Finance Data Science Lecture 4: PCA and and Factor Models

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Finance Data Scien 4. PCA and Factor Models MFE 230P, Summodel 2017
Eigenvalues
Singular values
Overview
Deflation
Example
Problem
Link with PCA
Explained variance
Factor models
Robust PCA
Sparse PCA

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Outline

Motivation

Linear Algebra Recap Eigenvalues Singular values

Principal Component Analysis Overview Deflation: iterated variance maximization Example

Low-rank approximations Problem Link with PCA Explained variance and approximation error Factor models

Extensions Robust PCA Sparse PCA

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MFE 230P, Summer 2017

Linear Algebra Re Eigenvalues Singular values

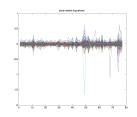
PCA Overview Deflation

approximations
Problem
Link with PCA
Explained variance

Robust PCA Sparse PCA

Notes			
-			
-			

Motivation



Daily log-returns of 77 Fortune 500 companies, 1/2/2007—12/31/2008

High-dimensional data does not make any sense! (Other than tell us: returns are approximately zero $\dots)$

In this lecture:

- ▶ start with a classical unsupervised learning to obtain insights
- examine a newer method that improves interpretability

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Motivation

Eigenvalues Singular values

PCA Overview

Deflation Example

approximations Problem

Explained variance Factor models

Robust PCA

Eigenvalue decomposition for symmetric matrices

Theorem (EVD of symmetric matrices)

We can decompose any symmetric $p \times p$ matrix S as

$$S = U\Lambda U^T = \sum_{i=1}^p \lambda_i u_i u_i^T,$$

where $\Lambda = \operatorname{diag}(\lambda_1,\dots,\lambda_p)$, with $\lambda_1 \geq \dots \geq \lambda_p$ the eigenvalues, and $U = [u_1,\dots,u_p]$ is a $p \times p$ orthogonal matrix ($U^T U = I_p$) that contains the eigenvectors u_i of S, that is:

$$Su_i = \lambda_i u_i, \ i = 1, \dots, p.$$

Corollary: If S is square, symmetric:

$$\lambda_{\max}(S) = \max_{x: \|x\|_2 = 1} x^T S x. \tag{1}$$

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4. PCA and Factor
Models
MFE 230P, Summer

Motivation

Linear Algebra Recap

Eigenvalues Singular values

PCA Overview

Deflation

proximations oblem

ink with PCA

xtensions

Robust PCA Sparse PCA

Notes

Positive semi-definite (PSD) matrices

A (square) symmetric matrix S is said to be $\ensuremath{\textit{positive semi-definite}}$ (PSD) if

$$\forall x, x^T Sx \geq 0.$$

In this case, we write $S \succeq 0$.

From EVD theorem: for any square, symmetric matrix S:

 $S \succeq 0 \iff$ every eigenvalue of S is non-negative.

Hence we can numerically (via EVD) check positive semi-definiteness.

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Eigenvalues
Singular values
Overview
Deflation
Example
Problem
Link with PCA
Explained variance
Factor models
Robust PCA

Notes

Singular Value Decomposition (SVD)

Theorem (SVD of general matrices)

We can decompose any non-zero $p \times m$ matrix A as

$$A = \sum_{i=1}^r \sigma_i u_i v_i^\intercal = U \Sigma V^\intercal, \ \ \Sigma = \text{diag}(\sigma_1, \dots, \sigma_r, 0, \dots, 0) \in \textbf{R}^{p \times m}$$

where $\sigma_1 \geq \ldots \geq \sigma_r > 0$ are the singular values, and

$$U = [u_1, \ldots, u_m], \quad V = [v_1, \ldots, v_p]$$

are square, orthogonal matrices ($U^TU=I_p$, $V^TV=I_m$). The number $r \leq \min(p,m)$ (the number of non-zero singular values) is called the rank of A.

The first r columns of U, V contains the left- and right singular vectors of A, respectively, that is:

$$Av_i = \sigma_i u_i, \quad A^T u_i = \sigma_i v_i, \quad i = 1, \ldots, r.$$

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Linear Algebra Reca

PCA

reflation

oroximations oblem

ink with PCA

Extensions
Robust PCA

Notes			

Links between EVD and SVD

The SVD of a $p \times m$ matrix A is related to the EVD of a (PSD) matrix related to A.

If $A = U\Sigma V^T$ is the SVD of A, then

- ▶ The EVD of AA^T is $U \wedge U^T$, with $\Lambda = \Sigma^2$.
- ► The EVD of $A^T A$ is $V \wedge V^T$.

Hence the left (resp. right) singular vectors of A are the eigenvectors of the PSD matrix AA^T (resp. A^TA).

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Eigenvalues
Singular values
Overview
Deflation
Example
Problem
Link with PCA
Explained variance
Factor models
Robust PCA
Sparse PCA

Notes

Computing SVD Power iteration algorithm

For a large, sparse matrix M, we can find left and right singular vectors corresponding to the largest singular value of M with the power iteration algorithm:

$$u \rightarrow \frac{Mv}{\|Mv\|_2}, \ v \rightarrow \frac{M^Tu}{\|M^Tu\|_2}.$$

This converges (for arbitrary initial u, v) under mild conditions on M.

Similar efficient algorithm when M is centered (thus, not necessarily sparse, even if data is).

Google's page rank is based on this kind of algorithm . . .

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Notes			

Principal Component Analysis

Principal Component Analysis (PCA) originated in psychometrics in the 1930's. It is now widely used in

- Exploratory data analysis.
- ▶ Simulation.
- Visualization.

Application fields include

- ► Finance, marketing, economics.
- ▶ Biology, medecine.
- ▶ Engineering design, signal compression and image processing.
- Search engines, data mining.



Solution principle of PCA

PCA finds "principal components" (PCs), i.e. orthogonal directions of $\it maximal\ variance$.

- ▶ PCs are computed via EVD of covariance matrix.
- Alternatively, PCs can be found directly via SVD of (centered) data matrix.
- ► Can be interpreted as a "factor model" of original data matrix.

Applications in finance:

- General understanding of market data.
- ▶ Underlies many theoretical models (such as CAPM).
- ▶ Modeling of term structure of interest rates.
- ► Portfolio hedging and immunization.
- ► Risk analysis, scenario generation.
- ▶ Obtain speed-ups in some portfolio optimization problems.

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Eigenvalues
Singular values
Overview
Deflation
Example
Problem
Link with PCA
Explained variance
Factor models
Robust PCA
Sparse PCA

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Notes		

Variance maximization problem

Let S be the (empirical) covariance matrix. Variance maximization

$$\max_{x} x^{T} S x : ||x||_{2} = 1.$$

Assume the EVD of S is given:

$$S = \sum_{i=1}^{p} \lambda_i u_i u_i^T,$$

with $\lambda_1 \geq \dots \lambda_p$, and $U = [u_1, \dots, u_p]$ is orthogonal ($U^T U = I$). Then a solution to

$$\max_{x: \|x\|_2=1} \ x^T S x$$

is $x^* = u_1$, with u_1 an eigenvector of S that corresponds to its largest eigenvalue λ_1 .

Alternatively, u_1 can be found directly via SVD of (centered) data matrix (see later).

Finding orthogonal directions

A deflation method

Once we've found a direction with high variance, can we repeat the process and find other ones?

Deflation method:

- Project data points on the subspace orthogonal to the direction we found.
- Find a direction of maximal variance for projected data.

The process stops after ρ steps (ρ is the dimension of the whole space), but can be stopped earlier (to find only k directions, with $k << \rho$).

Notes

Finding orthogonal directions Result

It turns out that the direction that solves

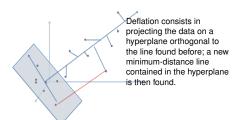
 $\max_{\mathbf{v}} \mathbf{var}(\mathbf{x}) : \mathbf{x}^T \mathbf{u}_1 = \mathbf{0}$

is $\ensuremath{\textit{u}}_2,$ an eigenvector corresponding to the second-to-largest eigenvalue.

After k steps of the deflation process, the directions returned are u_1, \ldots, u_k . Thus we can compute k directions of largest variance in one eigenvalue decomposition of the covariance matrix.

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Eigenvalues
Singular values
Overview
Deflation
Example
Problem
Link with PCA
Explained variance
Factor models
Robust PCA
Sparse PCA

Geometry of deflation



Models
MFE 230P, Summe 2017
Eigenvalues
Singular values
Overview
Deflation
Example
Problem
Link with PCA
Explained variance
Factor models
Robust PCA
Sparse PCA

Finance Data Science

Notes			

Measuring quality

How well is data approximated by its projections on the successive subspaces?

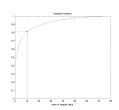
 $\ensuremath{\textit{Approach:}}\xspace$ compare sum of variances contained in the k directions found, with total variance.

Explained variance: measured by the ratio

$$\frac{\lambda_1 + \ldots + \lambda_k}{\lambda_1 + \ldots + \lambda_p} = \frac{\sigma_1^2 + \ldots + \sigma_k^2}{\sigma_1^2 + \ldots + \sigma_p^2},$$

where $\lambda_1 \geq \ldots \geq \lambda_p$ are the eigenvalues of the covariance matrix, and $\sigma_1 \geq \ldots \geq \sigma_p$ are the singular values of the (centered) data matrix.

Example PCA of market data



Data: Daily log-returns of 77 Fortune 500 companies, 1/2/2007—12/31/2008.

- Plot shows the eigenvalues of covariance matrix in decreasing order.
- First ten components explain 80% of the variance.
- Largest magnitude of eigenvector for 1st component correspond to financial sector (FABC, FTU, MER, AIG, MS).

Notes			

Low-rank approximation of a matrix

For a given $p \times m$ matrix A, and integer $k \leq m, p$, the k-rank approximation problem is

$$A^{(k)} := \arg\min_X \ \|X - A\|_F \ : \ \mathbf{Rank}(X) \le k,$$

where $\|\cdot\|_F$ is the Frobenius norm (Euclidean norm of the vector formed with all the entries of the matrix). The solution is

$$A^{(k)} = \sum_{i=1}^{k} \sigma_i u_i v_i^T,$$

where

$$A^{(k)} = \sum_{i=1}^{k} \sigma_i u_i v_i^T,$$

$$A = U \Sigma V^T = \sum_{i=1}^{r} \sigma_i u_i v_i^T$$

is an SVD of the matrix A.

Notes

Low-rank approximation

Assume data matrix $A \in \mathbf{R}^{\rho \times m}$ represents time-series data (each row is a time-series). Assume also that A is rank-one, that is, $A = uv^T \in \mathbf{R}^{\rho \times m}$, where u, v are vectors. Then

$$A = \begin{pmatrix} a_1^T \\ \vdots \\ a_m^T \end{pmatrix}, \ a_j(t) = \sigma_1 u(j) v(t), \ 1 \le j \le p, \ 1 \le t \le m.$$

Thus, each time-series is a "scaled" copy of the time-series represented by ν , with scaling factors given in u. We can think of ν as a "factor" that drives all the time-series.

Geometry: if a data matrix is rank-one, then all the data points are on a single line.

Notes		

Low-rank approximation

Interpretation: low-rank case

When A is rank k, that is,

$$\boldsymbol{A} = \boldsymbol{U}\boldsymbol{S}\boldsymbol{V}^T, \ \boldsymbol{U} \in \boldsymbol{R}^{p \times k}, \ \boldsymbol{S} = \boldsymbol{diag}(\sigma_1, \dots, \sigma_k) \in \boldsymbol{R}^{k \times k}, \ \boldsymbol{V} \in \boldsymbol{R}^{m \times k},$$

we can express the j-th row of A as

$$a_j(t) = \sum_{i=1}^k \sigma_i u_i(j) v_i(t), \ 1 \le j \le p, \ 1 \le t \le m.$$

Thus, each time-series is the sum of scaled copies of k time-series represented by v_1,\ldots,v_k , with scaling factors given in u_1,\ldots,u_k .

We can think of v_i 's as the few "factors" that drive all the time-series.

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Notes

Motivation
Linear Algebra Recap

PCA Overview Deflation

> Low-rank approximations Problem

Factor models

Extensions

Robust PCA

PCA and low-rank approximations

PCA can be obtained directly (without forming the covariance matrix) via a *low-rank approximation* to the centered data matrix A_c :

$$A_c \approx \hat{A}_c^{(k)} := \sum_{i=1}^k \sigma_i u_i v_i^T$$

Each v_i is a particular factor, and u_i 's contain scalings.

That is, $\hat{A}_{c}^{(k)}$ solves the problem

$$arg \min_{X} ||X - A_c||_F : \mathbf{Rank}(X) \le k,$$

where $\|X\|_F^2$ is the sum of the squares of the entries of X.

Finance Data Science
4. PCA and Factor
Models

MFE 230P, Summer
2017

Motivation
Linear Algebra Re

PCA

Deflation Example

> proximations roblem

ink with PCA explained variance

Extensions Robust PCA

Notes			

Link with power iteration algorithm

For a large, sparse matrix M, we can find left and right singular vectors corresponding to the largest singular value of M with the power iteration algorithm:

$$u \rightarrow \frac{Mv}{\|Mv\|_2}, \ v \rightarrow \frac{M^Tu}{\|M^Tu\|_2}$$

This converges (for arbitrary initial u, v) under mild conditions on M.

Interpretation: power iteration can be obtained by solving

$$\min_{p,q} \|M - pq^T\|_F$$

alternatively over p, q (in the P.I. algorithm above, u, v are just normalized versions of p, q).

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Linear Algebra Recap

Singular values

Overview

Deflation

Low-rank

Problem Link with PCA

Extensions

Robust PCA Sparse PCA

Low-rank approximation of covariance matrix

PCA also (implicitly) forms a low-rank approximation of the empirical covariance matrix.

The corresponding approximate covariance matrix is rank k:

$$S \approx S^{(k)} := U \Lambda^{(k)} U^T = F F^T$$

where $\Lambda^{(k)}=\mbox{diag}(\lambda_1,\dots,\lambda_k,0,\dots,0),$ with $\lambda_i=\sigma_i^2,$ and

$$F = U^{(k)} \operatorname{diag}(\sigma_1, \dots, \sigma_k),$$

where $U^{(k)}$ contains the first k columns of U.

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iotivation near Algebra Rec

.inear Algebra Hi Eigenvalues

CA Overview

Deflation Example

pproximations

Link with PCA Explained variance

Extensions
Robust PCA

Notes		

Explained variance and approximation error

Recall the explained variance ratio

$$\frac{\lambda_1 + \ldots + \lambda_k}{\lambda_1 + \ldots + \lambda_\rho} = \frac{\sigma_1^2 + \ldots + \sigma_k^2}{\sigma_1^2 + \ldots + \sigma_\rho^2},$$

The (square-root) of the explained variance ratio is the relative approximation error:

$$\frac{\|\hat{A}_{c}^{(k)} - A_{c}\|_{F}^{2}}{\|A_{c}\|_{F}^{2}} = \frac{\sigma_{1}^{2} + \ldots + \sigma_{k}^{2}}{\sigma_{1}^{2} + \ldots + \sigma_{p}^{2}}.$$

We can also express the above as

$$\frac{\text{Tr}(\mathcal{S} - \mathcal{S}^{(k)})}{\text{Tr }\mathcal{S}} = \frac{\lambda_1 + \ldots + \lambda_k}{\lambda_1 + \ldots + \lambda_p}.$$

Stochastic interpretation of low-rank approximations

Assume that the (e.g., price) observations y are the generated by stochastic model (here $F \in \mathbf{R}^{n \times k}$)

$$y = F\xi$$

where $\xi \in \mathbf{R}^k$ are independent random variables ($k \leq p$), with zero mean and identity covariance matrix. Here, $F \in \mathbf{R}^{p \times k}$ is the *loading* matrix.

Then the covariance matrix of y is

$$S = \mathbf{E}(F\xi\xi^TF^T) = FF^T.$$

In effect we are postulating that a few factors drive the market observations. This is the <code>same</code> as the PCA seen before!

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Models
MFE 230P, Summe

Notes		

Factor models

More generally we can assume that market observations are of the

$$y = F\xi + \sigma e$$
,

with (ξ, e) a zero-mean, random variable with identity covariance matrix, and $\sigma > 0$ is a parameter.

- ightharpoonup ξ contains the market factors;
- e is a noise term that affect each observation independently ("idiosyncratic noise").

The covariance matrix of y is of the form

$$S = FF^T + D^2$$

with $D^2 = \sigma^2 I$. We can fit this model (i.e., find F, σ) via SVD.

More general factor models allow for idiosyncratic noises with different variances (see lecture 4). However SVD cannot be used directly and the fitting problem is more challenging.

Finance Data Science
4. PCA and Factor
Models

MFE 230P, Sun 2017

Robust PCA

PCA is based on the assumption that the data matrix can be (approximately) written as a low-rank matrix:

$$A = LR^T$$

with $L \in \mathbf{R}^{p \times k}$, $R \in \mathbf{R}^{m \times k}$, with k << m, p.

Robust PCA [2] assumes that A has a "low-rank plus sparse" structure:

$$A = N + LR^T$$

where "noise" matrix N is sparse (has many zero entries).

How do we discover N, L, R based on A?

Notes

Robust PCA model

In robust PCA, we solve the convex problem

$$\min_{N} \|A - N\|_* + \lambda \|N\|_1$$

where $\|\cdot\|_*$ is the so-called nuclear norm (sum of singular values) of its matrix argument. At optimum, A-N has usually low-rank.

Motivation: the nuclear norm is akin to the l_1 -norm of the vector of singular values, and l_1 -norm minimization encourages sparsity of its argument.

4. PCA and Factor Models
MFE 230P, Summer 2017
Linear Algebra Recap Elgenvalues Singular values
PCA Overview Deflation Example
Link with PCA Explained variance Factor models
Extensions Robust PCA Sparse PCA

Notes

CVX syntax

Here is a matlab snippet that solves a robust PCA problem via CVX, given integers n,m, a $n\times m$ matrix A and non-negative scalar λ exist in the workspace:

cvx_begin
variable X(n,m);
minimize(norm_nuc(A-X)+ lambda*norm(X(:),1))
cvx_end

- ▶ Note the use of norm_nuc, which stands for the nuclear norm.
- In practice, this CVX code does not run on large matrices, for memory limitations.
- ► Efficient specialized algorithms exist [2].

Alternatively, we can use a power iteration-like algorithm [6], alternating over L,R

$$\min_{l,R} \|X - LR^T\|_1 : L \in \mathbf{R}^{n \times k}, \ R \in \mathbf{R}^{m \times k},$$

Each step is a convex problem.

Models
MFE 230P, Summe 2017
Eigenvalues
Singular values
Overview
Deflation
Example
Problem
Link with PCA
Explained variance
Factor models
Robust PCA
Sparse PCA

Finance Data Science

Notes			

Motivation

One of the issues with PCA is that it does not yield principal directions that are easily interpretable:

- ► The principal directions are really combinations of all the relevant features (say, assets).
- Hence we cannot interpret them easily.
- ► The previous thresholding approach (select features with large components, zero out the others) can lead to much degraded explained variance.

4. PGA and Factor Models
MFE 230P, Summe 2017
Linear Algebra Reca Eigenvalues Singular values
PCA Overview Deflation Example
Low-rank approximations Problem Link with PCA
Explained variance Factor models Extensions
Robust PCA

Finance Data Science

Sparse PCA

Problem definition

Modify the variance maximization problem:

$$\max_{\mathbf{x}} \ \mathbf{x}^T \mathbf{S} \mathbf{x} - \lambda \operatorname{Card}(\mathbf{x}) \ : \ \|\mathbf{x}\|_2 = 1,$$

where penalty parameter $\lambda \geq 0$ is given, and $\mathbf{Card}(x)$ is the cardinality (number of non-zero elements) in x.

The problem is hard but can be approximated via convex relaxation.

Notes			

Safe feature elimination

Express S as $S = R^T R$, with $R = [r_1, \dots, r_p]$ (each r_i corresponds to one feature, e.g. asset).

Theorem (Safe feature elimination)

We have

$$\begin{aligned} \max_{x: \, ||x||_2=1} \, & x^T S x - \lambda \, \mathbf{Card}(x) = \\ \max_{z: \, ||z||_2=1} \, & \sum_{i=1}^p \, \max(0, (r_i^T z)^2 - \lambda). \end{aligned}$$

- ▶ Reduces to ordinary formula when $\lambda = 0$.
- \blacktriangleright When $\lambda >$ 0 problem is hard, not amenable to SVD methods.

Notes

SAFE

Corollary

If $\lambda > \|r_i\|_2^2 = S_{ii}$, we can safely remove the i-th feature (row/column of S).

Proof.

If
$$||z||_2 = 1$$
, then $|r_i^T z| \le ||r_i||_2$.

- ▶ The presence of the penalty parameter allows to prune out dimensions in the problem.
- ► Criterion simply based on variance of each feature (i.e., directional variance along unit vectors).
- ▶ In practice, we want λ high as to allow better interpretability.
- ► Hence, interpretability requirement makes the problem easier in some sense!

Notes			

Sparse PCA Algorithms

- The Sparse PCA problem remains challenging due to the huge number of variables.
- SAFE technique does allow big reduction in problem size.
- ▶ Still area of active research. (Like SVD in the 70's-90's...)

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Notes

Notes

inear Algebra Recap

PCA Overview Deflation

approximations
Problem

Extensions
Robust PCA

Sparse PCA

Thresholded power iteration

Efficient heuristic to solve, for given $n \times m$ matrix M:

$$\min_{p,q} \ \| \mathbf{M} - pq^T \|_F \ : \ \mathbf{Card}(p) \le k, \ \ \mathbf{Card}(q) \le h.$$

Initialize p, q to be random and

$$p \to P(T_k(Mq)), \ q \to P(T_h(M^Tp)),$$

where

- ► *M* is the (centered) data matrix,
- ▶ *P* is the I_2 normalization operator (for $z \neq 0$, $P(z) = z/\|z\|_2$),
- $\,\blacktriangleright\,$ operator ${\cal T}_k$ removes all but the k largest-magnitude components of its input.
- \blacktriangleright Reduces to a standard method for PCA (power iteration) when $k=n,\,h=m.$

For sparse data, can be used in very high dimensions.

Finance Data Science 4. PCA and Factor Models
MFE 230P, Summer 2017

Linear Algebra Re Eigenvalues Singular values

PCA Overview

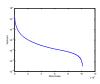
Problem
Link with PCA

Robust PCA Sparse PCA

Example
Sparse PCA of New York Times headlines

 $\it Data: \,$ NYTtimes text collection contains 300,000 articles and has a dictionary of 102,660 unique words.

The variance of the features (words) decreases very fast:



Sorted variances of 102,660 words in NYTimes data.

With a target number of words less than 10, SAFE allows to reduce the number of features from $n\approx$ 100, 000 to n=500.

Notes			

Example
Sparse PCA of New York Times headlines

Words associated with the top 5 sparse principal components in NYTimes

1st PC	2nd PC	3rd PC	4th PC	5th PC
(6 words)	(5 words)	(5 words)	(4 words)	(4 words)
million	point	official	president	school
percent	play	government	campaign	program
business	team	united_states	bush	children
company	season	u_s	administration	student
market	game	attack		
companies				

Note: the algorithm found those terms without any information on the subject headings of the corresponding articles (unsupervised problem).

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MFE 230P, Summer 2017

Notes			

NYT Dataset

Comparison with thresholded PCA

Thresholded PCA involves simply thresholding the principal components.

k = 2	k = 3	k = 9	k = 14
even	even	even	would
like	like	we	new
	states	like	even
		now	we
		this	like
		will	now
		united	this
		states	will
		if	united
			states
			world
			so
			some
			if

1st PC from Thresholded PCA for various cardinality $\it k$. The results contain a lot of non-informative words.

4. PCA and Factor Models
MFE 230P, Summer 2017
Eigenvalues
Singular values
Overview
Deflation
Example
Problem
Link with PCA
Explained variance
Factor models
Robust PCA
Sparse PCA

References













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Models							
MFE 230P, Summer 2017							
Eigenvalues							

Finance Data Science 4. PCA and Factor

Notes			