#### Maximum Likelihood Estimation

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#### Inference Problem for a Model

- Model prediction:
  - A model  $M(\mathbf{x}; \boldsymbol{\theta})$  usually predicts the  $\mathbf{y}_M$  associated with a given  $\mathbf{x}$  under a given model parameter  $\boldsymbol{\theta}$ .
- However, the observed/labelled  $\mathbf{y}_O$  usually do not always agree with  $\mathbf{y}_M$  for any  $\theta$ .<sup>1</sup>
  - We need a principled way to choose the best  $\theta$  (within its domain). This is the inference problem. 推理问题
- Candidate inference principles:
  - Least squared: find the most accurate model 找出最有可能的模型
  - Maximum likelihood (MLE): find the most likely model
  - Maximum a posterior (MAP): find the model that appears most often in the posterior distribution (i.e., achieving the maximum  $P(\mathbf{x}, \boldsymbol{\theta})$ .
  - Based on a loss function: find the most accurate model

 $<sup>^1</sup>$ We do talk about a special case where there are many  $\theta$  that will fit perfectly with the  $yy_0$  for every training data.

#### **MLE**

- Proposed by R. A. Fisher in the 1920s.
  - Write out the **likelihood function**  $L(\mathbf{y} \mid \boldsymbol{\theta}) = P(\mathbf{y} \mid \boldsymbol{\theta})$ .
  - Find  $\theta_{MLE} = \arg \max_{\theta} L(\mathbf{y} \mid \theta)$ .
- MLE has a few nice statistical properties: sufficiency, consistency, efficiency, and parameter invariance.
  - Consistency: when the number of samples grows to  $\infty$ ,  $\theta_{MLE}$  converges to the true parameter.
  - Won't go into the formal technical details.
- Common tricks:
  - Almost always work in the log space: log-likelihood function  $\ell()$ .
    - (1) log here is In. Base does not matter.
    - Also taking log still gives the same arg max solutions.
  - (Assume) all training instances are i.i.d., hence  $\ell(\mathbf{y}_1, \dots, \mathbf{y}_n \mid \boldsymbol{\theta}) = \sum_{i=1}^n \log P(\mathbf{y}_i \mid \boldsymbol{\theta}).$



## MLE Example 1 /1

- Biased coin with head probability of  $p_M$ . Toss n times, and observed the empirical head probability as  $p_O$ .
- Understanding first:
  - $p_M$  could be any number in  $(0,1) \Longrightarrow$  even  $p_M = 0.000001$  is possible, c.f., Murphy's law.
  - Yet, in the absence of any other source of information/belief, a sensible choice is to choose  $p_M$  such that the probability of observing  $p_O \cdot n$  heads are the maximum  $\Longrightarrow$  MLE
- e.g.,  $p_M = 0.1$ ,  $p_O = 0.6$ , n = 10.

$$P(p_O = 0.6 \mid p_M = 0.1, n = 10) = {10 \choose 6} \cdot (0.1)^6 \cdot (1 - 0.1)^4$$

## MLE Example 1 /2

- Biased coin with head probability of  $p_M$ . Toss n times, and observed the empirical head probability as  $p_O$ .
- Write out the log-likelihood function:  $\ell(\mathbf{y} \mid \boldsymbol{\theta}) = \log P(\mathbf{y} \mid \boldsymbol{\theta})$ .

$$\log P(p_O \mid p_M) = \log \left( \binom{n}{p_O n} \cdot p_M^{p_O n} \cdot (1 - p_M)^{(1 - p_O) n} \right)$$

Note:  $p_M$  is the only variable (i.e., view others as constants)

- Finding the maximum
  - For such a simple case, we can obtain the analytical solution by requiring:
    - $\frac{\partial \ell}{\partial \theta_i} = 0 \Longrightarrow \frac{p_O n}{p_M} + \frac{-(1-p_O)n}{1-p_M} = 0$  (note: n does not matter)
    - $\frac{\partial^2 \ell}{\partial^2 \theta_i} < 0$
  - Otherwise, find the arg max solution numerically. (Might not be global maximum or non-unique/non-deterministic, esp. in the non-linear or high-dimensional cases).

## MLE Example 2 /1

• Memory retention model based on power law. y=1 means one still remember a given fact. It is a function over time t. (Z is the normalizing constant)

$$P(y=1 \mid t; \mathbf{w}) = \frac{1}{Z} \cdot \mathbf{w}_1 \cdot t^{-\mathbf{w}_2}$$

- At each timestamp  $t_i$ , we recruit some volunteers to conduct the experiments, and obtain the corresponding empirical retention probability  $p_O$ .
- MLE:
  - Write out the log-likelihood function
  - Do the arg max

# MLE Example 2 /2

- $p_M(y = 1 \mid t; \mathbf{w}) = \frac{1}{Z} \cdot \mathbf{w}_1 \cdot t^{-\mathbf{w}_2}$
- Data:  $(t^{(i)}, p_O^{(i)})$
- MLE:
  - Write out the log-likelihood function for a given  $t^{(i)}$

$$\ell^{(i)} = \log \left( \binom{n}{p_O n} \cdot p_M^{p_O n} \cdot (1 - p_M)^{(1 - p_O) n} \right)$$

$$\ell = \sum_{i} \ell^{(i)}$$

Note: the  $p_M$  and  $p_O$  (and n) in  $\ell^{(i)}$  are all conditioned on i.

- Do the arg max
  - In general, there is no analytical solution. Why?

## MLE Example 2 /3

- The big picture:
  - Model predicted distribution  $(t^{(i)}, p_M^{(i)})$
  - Observed distribution:  $(t^{(i)}, p_O^{(i)})$
- MLE will give its best w
- In general, a different  $\mathbf{w}$  will be obtained if we define a loss function,  $\sum_i J(p_M^{(i)}, p_O^{(i)})$ , and find its best  $\mathbf{w}$  that minimizes the loss
- In general, MAP will give a different w as well, as it considers not only the likelihood function, but also the prior on w.
  - Could be useful in some cases, e.g., one already obtained a
    posterior distribution of w based on samples from volunteers in
    one state, and now doing the inference on volunteers from
    another state.

# MLE Example 3: Linear Regression

- Model:  $y_M = \mathbf{w}^\top \mathbf{x}$
- Observed: y<sub>O</sub>
- Log-likelihood function:
  - As both y<sub>M</sub> and y<sub>O</sub> are numerical measurents, we need to come up with a different model to derive the likelihood function.
  - Without any other knowledge/info, we can assume  $P(y_O \mid y_M)$  follows a fixed Guassian distribution  $\mathcal{N}(0, \sigma^2)$  (i.e.,  $\sigma$  is fixed for all  $(\mathbf{x}^{(i)}, y^{(i)})$ s.

$$\ell = \sum_{i} \log P(y_O \mid y_M; \sigma^2) = \sum_{i} \log \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(y_O - y_M)^2}{2\sigma^2}\right)$$
$$= \sum_{i} \left(\log\left(\frac{1}{\sqrt{2\pi\sigma^2}}\right) - \frac{(y_O - y_M)^2}{2\sigma^2}\right)$$

- Note that maximiming  $\ell$  above means minimizing  $(y_O y_M)^2$ ! Hence, MLE inference is equivalent to Least Squared inference (or inference based on SSE as the loss function).
- In many case, this is interpreted as  $y_O = y_M + \epsilon$ , where  $\epsilon$  is a Guassian noise. This is the additive Gaussian noise model, but there are many cases where such modelling does not work, yet MLE (and other inference methods) still works.

#### Final Remarks on MLE

- It is just one of the model selection criteria.
  - Not always applicable
  - Could easily overfit the data (c.f., smoothing)
  - Should not be used to perform model selection (i.e., choose between two models based on their log-likelihood values on a given training data). Think why?
    - Instead, generalization (impossible to measure) is the right criteria).
    - In ML/DL, the usually approaches are based on Bayesian models or structured risk minimization
    - In pratice, typically done via a separate validation/development set.