

## Chapter 7

### Parameter estimation, Diagnostic Checking and Model Selection

Real data:  $y_1, y_2, \dots, y_n$ .

New data:  $Z_1, Z_2, \dots, Z_n$  follow a stationary and invertible **ARMA** model.

Let  $\dot{Z}_t = Z_t - \mu$ .

Suppose that  $\dot{Z}_t$  follows **ARMA** model:

$$\begin{aligned}\dot{Z}_t = & \phi_1 \dot{Z}_{t-1} + \phi_2 \dot{Z}_{t-2} + \dots + \phi_p \dot{Z}_{t-p} \\ & + a_t - \theta_1 a_{t-1} - \dots - \theta_q a_{t-q},\end{aligned}$$

where  $a_t \sim i.i.d.N(0, \sigma_a^2)$ . We need to find

$p, q, \phi_1, \dots, \phi_p, \theta_1, \dots, \theta_q, \mu$  and  $\sigma_a^2$ , which are called unknown parameters.

How to find?

## Procedure:

**Step 1.** Determine  $(p, q)$  by the method in Chapter 6. If it is not easy to find  $p$  and  $q$ , you can try some different  $(p, q)$ .

**Step 2.** Estimate  $\phi_1, \dots, \phi_p, \theta_1, \dots, \theta_q, \mu$  and  $\sigma_a^2$ .

**Step 3.** Checking whether or not  $(p, q)$  is correct.

If it is not correct, try some different  $(p, q)$  and then go to **Step 2**.

Even if it is correct, we still need to try some different  $(p, q)$  in practice.

**Step 4.** In general, the correct  $(p, q)$  is not unique. We can select the best one by **AIC** and **BIC** criteria.

The above procedure is called building a model, fit a model, model fitting, or modeling.

## Section 7.1 The method of moments.

**Model:**  $\dot{Z}_t = Z_t - \mu,$

$$\dot{Z}_t = \phi_1 \dot{Z}_{t-1} + \phi_2 \dot{Z}_{t-2} + \cdots + \phi_p \dot{Z}_{t-p} + a_t.$$

Yule-Walker equations:

$$\rho_1 = \phi_1 + \phi_2 \rho_1 + \phi_3 \rho_2 + \cdots + \phi_p \rho_{p-1}$$

$$\rho_2 = \phi_1 \rho_1 + \phi_2 + \phi_3 \rho_1 + \cdots + \phi_p \rho_{p-2}$$

$$\rho_3 = \phi_1 \rho_2 + \phi_2 \rho_1 + \phi_3 + \cdots + \phi_p \rho_{p-3}$$

$\vdots$

$$\rho_p = \phi_1 \rho_{p-1} + \phi_2 \rho_{p-2} + \cdots + \phi_{p-1} \rho_1 + \phi_p$$

Note that  $\rho_k$  can be estimated by  $\hat{\rho}_k$ . Solve the above equations:

$$\begin{bmatrix} \hat{\phi}_1 \\ \hat{\phi}_2 \\ \hat{\phi}_3 \\ \vdots \\ \hat{\phi}_p \end{bmatrix} = \begin{bmatrix} 1 & \hat{\rho}_1 & \hat{\rho}_2 & \cdots & \hat{\rho}_{p-2} & \hat{\rho}_{p-1} \\ \hat{\rho}_1 & 1 & \hat{\rho}_1 & \cdots & \hat{\rho}_{p-3} & \hat{\rho}_{p-2} \\ \hat{\rho}_2 & \hat{\rho}_1 & 1 & \cdots & \hat{\rho}_{p-4} & \hat{\rho}_{p-3} \\ \vdots & & & & \vdots & \\ \hat{\rho}_{p-1} & \hat{\rho}_{p-2} & \hat{\rho}_{p-3} & \cdots & \hat{\rho}_1 & 1 \end{bmatrix}^{-1} \begin{bmatrix} \hat{\rho}_1 \\ \hat{\rho}_2 \\ \hat{\rho}_3 \\ \vdots \\ \hat{\rho}_p \end{bmatrix}$$

$\hat{\phi}_i$ ,  $i = 1, 2, \dots, p$ , are called the moment or Yule-Walker estimators of  $\phi_i$ ,  $i = 1, 2, \dots, p$ .

The moment estimator of  $\sigma_a^2$  is

$$\hat{\sigma}_a^2 = \hat{\gamma}_0(1 - \hat{\phi}_1 \hat{\rho}_1 - \hat{\phi}_2 \hat{\rho}_2 - \cdots - \hat{\phi}_p \hat{\rho}_p).$$

**Example 7.1.** Model:

$$(Z_t - \mu) = \phi_1(Z_{t-1} - \mu) + a_t.$$

Given  $Z_t$ ,  $t = 1, \dots, n$ , find the Yule-Walker estimators of  $\mu$ ,  $\phi_1$  and  $\sigma_a^2$ .

The drawbacks of Yule-Walker estimation:

- (1). It is not robust if the  $a_t$  is not normal.
- (2). It is not easy to estimate the **MA**( $q$ ) or **ARMA**( $p, q$ ) model ( $q \neq 0$ ).

## Section 7.2.

### Maximum likelihood (ML) method

#### Section 7.2.1

#### Conditional ML estimation

**Model:**  $\dot{Z}_t = Z_t - \mu,$

$$\begin{aligned}\dot{Z}_t = & \phi_1 \dot{Z}_{t-1} + \phi_2 \dot{Z}_{t-1} + \cdots + \phi_p \dot{Z}_{t-p} \\ & + a_t - \theta_1 a_{t-1} - \cdots - \theta_q a_{t-q},\end{aligned}$$

where  $a_t \sim i.i.d.N(0, \sigma_a^2)$ .

Denote  $\phi = (\phi_1, \cdots, \phi_p)'$  and  $\theta = (\theta_1, \cdots, \theta_q)'$ .

Given  $Z_1, Z_2, \cdots, Z_n$ ,

the joint density  $f(Z_n, Z_{n-1}, \cdots, Z_1)$  is the likelihood function.

If the initial values  $Z_* = (Z_{1-p}, Z_{2-p}, \cdots, Z_0)'$ ,  
 $a_* = (a_{1-q}, a_{2-q}, \cdots, a_0)'$  are used,

$f(Z_n, Z_{n-1}, \cdots, Z_1 | Z_*, a_*)$  is called the conditional likelihood function.

$$f(Z_n, Z_{n-1}, \cdots, Z_1 | Z_*, a_*) = \prod_{i=1}^n f(Z_i | Z_{i-1}, \cdots, Z_1, Z_*, a_*)$$

$$\begin{aligned}\dot{Z}_1 &= \phi_1 \dot{Z}_0 + \phi_2 \dot{Z}_{-1} + \cdots + \phi_p \dot{Z}_{1-p} \\ &\quad + a_1 - \theta_1 a_0 - \cdots - \theta_q a_{1-q}, \\ a_1 &\sim i.i.d.N(0, \sigma_a^2).\end{aligned}$$

$$\dot{Z}_1 | (\dot{Z}_*, a_*) \sim N(M_1, \sigma_a^2), \text{ where}$$

$$\begin{aligned}M_1 &= \phi_1 \dot{Z}_0 + \phi_2 \dot{Z}_{-1} + \cdots + \phi_p \dot{Z}_{1-p} \\ &\quad - \theta_1 a_0 - \cdots - \theta_q a_{1-q},\end{aligned}$$

$$f(\dot{Z}_1 | Z_*, a_*) = \frac{1}{\sqrt{2\pi\sigma_a^2}} e^{-\frac{(\dot{Z}_1 - M_1)^2}{2\sigma_a^2}}.$$

$$\begin{aligned}a_1(\phi, \mu, \theta) &\equiv \dot{Z}_1 - M_1 \\ &= \dot{Z}_1 - \phi_1 \dot{Z}_0 - \phi_2 \dot{Z}_{-1} - \cdots - \phi_p \dot{Z}_{1-p} \\ &\quad + \theta_1 a_0 + \cdots + \theta_q a_{1-q}. \\ \dot{Z}_2 &= \phi_1 \dot{Z}_1 + \phi_2 \dot{Z}_0 + \cdots + \phi_p \dot{Z}_{2-p} \\ &\quad + a_2 - \theta_1 a_1 - \cdots - \theta_q a_{2-q}, \\ a_2 &\sim i.i.d.N(0, \sigma_a^2).\end{aligned}$$

$$\dot{Z}_2 | (\dot{Z}_1, \dot{Z}_*, a_*) \sim N(M_2, \sigma_a^2), \text{ where}$$

$$\begin{aligned}M_2 &= \phi_1 \dot{Z}_1 + \phi_2 \dot{Z}_0 + \cdots + \phi_p \dot{Z}_{2-p} \\ &\quad - \theta_1 a_1(\phi, \mu, \theta) - \cdots - \theta_q a_{2-q}.\end{aligned}$$

$$f(\dot{Z}_2 | \dot{Z}_1, Z_*, a_*) = \frac{1}{\sqrt{2\pi\sigma_a^2}} e^{-\frac{(\dot{Z}_2 - M_2)^2}{2\sigma_a^2}}.$$

$$\begin{aligned}
a_2(\phi, \mu, \theta) &\equiv \dot{Z}_2 - M_2 \\
&= \dot{Z}_2 - \phi_1 \dot{Z}_1 - \phi_2 \dot{Z}_0 - \cdots - \phi_p \dot{Z}_{2-p} \\
&\quad + \theta_1 a_1(\phi, \mu, \theta) + \cdots + \theta_q a_{2-q}.
\end{aligned}$$

$$\dot{Z}_n | (\dot{Z}_{n-1}, \cdots, \dot{Z}_1, \dot{Z}_*, a_*) \sim N(M_n, \sigma_a^2), \text{ where}$$

$$\begin{aligned}
M_n &= \phi_1 \dot{Z}_{n-1} + \phi_2 \dot{Z}_{n-2} + \cdots + \phi_p \dot{Z}_{n-p} \\
&\quad - \theta_1 a_{n-1}(\phi, \mu, \theta) - \cdots - \theta_q a_{n-q}(\phi, \mu, \theta).
\end{aligned}$$

$$f(\dot{Z}_n | \dot{Z}_{n-1}, \dot{Z}_1, Z_*, a_*) = \frac{1}{\sqrt{2\pi\sigma_a^2}} e^{-\frac{(\dot{Z}_n - M_n)^2}{2\sigma_a^2}}.$$

$\vdots$

$$\begin{aligned}
a_n(\phi, \mu, \theta) &\equiv \dot{Z}_n - M_n \\
&= \dot{Z}_n - \phi_1 \dot{Z}_{n-1} - \phi_2 \dot{Z}_{n-2} - \cdots - \phi_p \dot{Z}_{n-p} \\
&\quad + \theta_1 a_{n-1}(\phi, \mu, \theta) + \cdots + \theta_q a_{n-q}(\phi, \mu, \theta)
\end{aligned}$$

Let

$$L_*(\phi, \mu, \theta, \sigma_a^2) = f(Z_n, Z_{n-1}, \cdots, Z_1 | Z_*, a_*).$$

$$L_*(\phi, \mu, \theta, \sigma_a^2) = \prod_{i=1}^n (2\pi\sigma_a^2)^{-1/2} e^{-\frac{(\dot{Z}_i - M_i)^2}{2\sigma_a^2}}$$

$$\ln L_*(\phi, \mu, \theta, \sigma_a^2) = -\frac{n}{2} \ln(2\pi\sigma_a^2) - \frac{S_*(\phi, \mu, \theta)}{2\sigma_a^2}.$$

$$\text{where } S_*(\phi, \mu, \theta) = \sum_{t=1}^n a_t^2(\phi, \mu, \theta).$$

$\ln L_*(\phi, \mu, \theta, \sigma_a^2)$  is called the conditional log-likelihood function.

The maximizer of  $\ln L_*(\phi, \mu, \theta, \sigma_a^2)$  is called the conditional maximum likelihood estimator (CMLE) of  $(\phi, \mu, \theta, \sigma_a^2)$ , denoted by  $(\hat{\phi}, \hat{\mu}, \hat{\theta}, \hat{\sigma}_a^2)$ .

$(\hat{\phi}, \hat{\mu}, \hat{\theta})$  is also the minimizer of  $S_*(\phi, \mu, \theta)$ . So,  $(\hat{\phi}, \hat{\mu}, \hat{\theta})$  is called conditional least squares estimator (CLSE) of  $(\phi, \mu, \theta)$ .

In practice, we first find  $(\hat{\phi}, \hat{\mu}, \hat{\theta})$  by minimizing:

$$S_*(\phi, \mu, \theta) = \sum_{t=1}^n a_t^2(\phi, \mu, \theta)$$

Then calculate  $\hat{\sigma}_a^2$  by

$$\hat{\sigma}_a^2 = \frac{S_*(\hat{\phi}, \hat{\mu}, \hat{\theta})}{n - p - q - 1}.$$



How to minimize  $S_*(\phi, \mu, \theta)$ ?

**Example 7.2 Model:**

$$Z_t = \phi_1 Z_{t-1} + \phi_2 Z_{t-2} + \cdots + \phi_p Z_{t-p} + a_t$$

where  $a_t \sim i.i.d.N(0, \sigma_a^2)$ .

**Solution:**

$$\begin{aligned} a_t(\phi) &= Z_t - \phi_1 Z_{t-1} - \phi_2 Z_{t-2} - \cdots - \phi_p Z_{t-p} \\ &= Z_t - \tilde{Z}'_{t-1} \phi, \end{aligned}$$

where  $\tilde{Z}_{t-1} = (Z_{t-1}, Z_{t-2}, \cdots, Z_{t-p})'$ .

$$S_*(\phi) = \sum_{t=1}^n a_t^2(\phi)$$

$$\begin{aligned} \frac{\partial S_*(\phi)}{\partial \phi} &= 2 \sum_{t=1}^n \frac{\partial a_t(\phi)}{\partial \phi} a_t(\phi) \\ &= - \sum_{t=1}^n \tilde{Z}_{t-1} Z_t + \sum_{t=1}^n \tilde{Z}_{t-1} \tilde{Z}'_{t-1} \phi \end{aligned}$$

Note that  $\frac{\partial S_*(\phi)}{\partial \phi} \big|_{\phi=\hat{\phi}} = 0$ , we have

$$\hat{\phi} = \left( \sum_{t=1}^n \tilde{Z}_{t-1} \tilde{Z}'_{t-1} \right)^{-1} \left( \sum_{t=1}^n \tilde{Z}_{t-1} Z_t \right).$$

Since  $\frac{\partial^2 S_*(\phi)}{\partial \phi \partial \phi'} = \sum_{t=1}^n \tilde{Z}_{t-1} \tilde{Z}_{t-1}' > 0$ ,  $\hat{\phi}$  is the CMLE.

$$\hat{\sigma}_a^2 = \frac{1}{n-p} \sum_{t=1}^n [Z_t - \tilde{Z}_{t-1}' \hat{\phi}]^2.$$

### Remark:

(1).  $\hat{\phi}$  for **AR**( $p$ ) model is equivalent to Yule-Walker estimator and is called ordinary least squares estimator (**OLS**) in Section 7.4.

(2). for the **ARMA**( $p, q$ ) model with  $q \neq 0$ , how to minimize  $S_*(\phi, \mu, \theta)$  will be given in Section 7.3.

(3). In the **CMLE** or **CLSE**, we simply take the initial values:  $Z_* = 0$  or  $a_* = 0$ , or  $Z_* = \hat{\mu}$  and  $a_* = 0$ . These initial values do not affect on the estimators.

For example, in the **MA**(1) model:

$$\begin{aligned} a_{100}(\theta) &= Z_{100} + \theta a_{99}(\theta) \\ &= Z_{100} + \theta Z_{99} + \theta^2 Z_{98} + \dots + \theta^{100} Z_0 + \dots \end{aligned}$$

### Example 7.3.

exchange Rates: TEN/USA (1970-2000).

## 7.2.2. Unconditional ML Estimation

**Model:**  $\dot{Z}_t = Z_t - \mu$ ,

$$\begin{aligned}\dot{Z}_t = & \phi_1 \dot{Z}_{t-1} + \phi_2 \dot{Z}_{t-1} + \cdots + \phi_p \dot{Z}_{t-p} \\ & + a_t - \theta_1 a_{t-1} - \cdots - \theta_q a_{t-q},\end{aligned}$$

where  $a_t \sim i.i.d.N(0, \sigma_a^2)$ .

Given  $Z = (Z_n, Z_{n-1}, \cdots, Z_2, Z_1)'$ ,

Box and Jenkin (1976) suggested the unconditional log-likelihood function:

$$\ln L(\phi, \mu, \theta, \sigma_a^2) = -\frac{n}{2} \ln(2\pi\sigma_a^2) - \frac{S(\phi, \mu, \theta)}{2\sigma_a^2}$$

where  $S(\phi, \mu, \theta) = \sum_{t=-\infty}^n [E(a_t|\phi, \mu, \theta, Z)]^2$ ,

where  $Z = (Z_1, Z_2, \cdots, Z_n)$  and  $E(a_t|\phi, \mu, \theta, Z)$  is the conditional expectation of  $a_t$  given  $(\phi, \mu, \theta, Z)$ .

The maximizer of  $\ln L(\phi, \mu, \theta, \sigma_a^2)$  is called the unconditional ML estimator (UMLE) of  $(\phi, \mu, \theta, \sigma_a^2)$ , denoted by  $(\hat{\phi}, \hat{\mu}, \hat{\theta}, \hat{\sigma}_a^2)$ .

$(\hat{\phi}, \hat{\mu}, \hat{\theta})$  is also the minimizer of  $S(\phi, \mu, \theta)$ . So,  $(\hat{\phi}, \hat{\mu}, \hat{\theta})$  is called unconditional LS estimator (ULSE) of  $(\phi, \mu, \theta)$ .

$S(\phi, \mu, \theta)$  is approximated by

$$S(\phi, \mu, \theta) = \sum_{t=-M}^n [E(a_t|\phi, \mu, \theta, Z)]^2,$$

where  $M$  is an integer large enough so that, for any predetermined  $\epsilon > 0$ ,

$$|E(a_t|\phi, \mu, \theta, Z) - E(a_{t-1}|\phi, \mu, \theta, Z)| \leq \epsilon$$

for  $t \leq -M - 1$ .

How to find  $E(a_t|\phi, \mu, \theta, Z)$ ? Backcasting method.

$\sigma_a^2$  is estimated by

$$\hat{\sigma}_a^2 = \frac{S(\hat{\phi}, \hat{\mu}, \hat{\theta})}{n}.$$

SAS program:

```
proc arima data=yenusa;
```

```
identify var=log(1) noprint;
```

```
estimate q=1 noconstant method=uls;
```

```
run;
```

## Backcasting Method.

An ARMA model (forward form):

$$(1 - \phi_1 B - \dots - \phi_p B^p) \dot{Z}_t = (1 - \theta_1 B - \dots - \theta_q B^q) a_t$$

can be written by

An ARMA model (backward form):

$$(1 - \phi_1 F - \dots - \phi_p F^p) \dot{Z}_t = (1 - \theta_1 F - \dots - \theta_q F^q) e_t,$$

where  $e_t \sim N(0, \sigma_e^2)$  and  $F^j Z_t = Z_{t+j}$ .

### Example 7.4.

AR(1) model in forward form:  $(1 - \phi_1 B) Z_t = a_t$ .

AR(1) model in backward form:  $(1 - \phi_1 F) Z_t = e_t$ .

**Question:** how to find  $E(a_t | \phi, Z)$ ?

Solution:

$$E(a_n | \phi, Z) = E(Z_n | Z) - \phi E(Z_{n-1} | Z) = Z_n - \phi Z_{n-1}$$

$\vdots$

$$E(a_2 | \phi, Z) = E(Z_2 | Z) - \phi E(Z_1 | Z) = Z_2 - \phi Z_1,$$

$$E(a_1 | \phi, Z) = E(Z_1 | Z) - \phi E(Z_0 | Z) = Z_1 - \phi E(Z_0 | Z),$$

$$E(a_0 | \phi, Z) = E(Z_0 | Z) - \phi E(Z_{-1} | Z),$$

$$E(a_{-1} | \phi, Z) = E(Z_{-1} | Z) - \phi E(Z_{-2} | Z),$$

$\vdots$

$$E(a_{-M} | \phi, Z) = E(Z_{-M} | Z) - \phi E(Z_{-M-1} | Z)$$

**Further Question:** how to find  $E(Z_{-t}|Z)$ ?

By backward form:

$$Z_t = \sum_{i=0}^{\infty} \phi^i F^i e_t = e_t + \phi e_{t+1} + \phi^2 e_{t+2} + \cdots ,$$

$$E(Z_0|Z) = E(e_0|Z) + \phi E(Z_1|Z) = \phi Z_1 ,$$

$$E(Z_{-1}|Z) = E(e_{-1}|Z) + \phi E(Z_0|Z) = \phi^2 Z_1 ,$$

$\vdots$

$$E(Z_{-M}|Z) = E(e_{-M}|Z) + \phi E(Z_{-M+1}|Z) = \phi^{M+1} Z_1$$

$E(Z_{-t}|Z)$  is called the backcasting of  $Z_{-t}$ .

Thus

$$E(a_1|\phi, Z) = Z_1 - \phi^2 Z_1 = (1 - \phi^2) Z_1 ,$$

$$E(a_0|\phi, Z) = (1 - \phi^2) \phi Z_1 ,$$

$$E(a_{-1}|\phi, Z) = (1 - \phi^2) \phi^2 Z_1 ,$$

$\vdots$

$$E(a_{-M}|\phi, Z) = (1 - \phi^2) \phi^{M+1} Z_1 .$$

Now,

$$S(\phi) = \sum_{t=2}^n \left[ \dot{Z}_t - \phi Z_{t-1} \right]^2 + \sum_{i=-M}^1 \left[ (1 - \phi^2) \phi^{1-i} Z_1 \right]^2 .$$

### 7.2.3. Exact likelihood function

**Model:**  $\dot{Z}_t = Z_t - \mu$ ,

$$\begin{aligned}\dot{Z}_t = & \phi_1 \dot{Z}_{t-1} + \phi_2 \dot{Z}_{t-1} + \cdots + \phi_p \dot{Z}_{t-p} \\ & + a_t - \theta_1 a_{t-1} - \cdots - \theta_q a_{t-q},\end{aligned}$$

where  $a_t \sim i.i.d.N(0, \sigma_a^2)$ .

Given  $Z_1, Z_2, \cdots, Z_n$ ,

the joint probability  $f(Z_n, Z_{n-1}, \cdots, Z_1)$  is the exact likelihood function.

Let  $L(\phi, \mu, \theta, \sigma_a^2) = f(Z_n, Z_{n-1}, \cdots, Z_1)$ .

The maximizer of  $\ln L(\phi, \mu, \theta, \sigma_a^2)$  is called the (exact) ML estimator (MLE) of  $(\phi, \mu, \theta, \sigma_a^2)$ , denoted by  $(\hat{\phi}, \hat{\mu}, \hat{\theta}, \hat{\sigma}_a^2)$ .

How to find the exact likelihood function?

Answer: too complicated.

**Example 7.5.** AR(1) model:

$$Z_t = \phi_1 Z_{t-1} + a_t,$$

where  $|\phi| < 1$  and  $a_t \sim N(0, \sigma_a^2)$ .

**Solution:**

$$Z_t = \sum_{j=0}^{\infty} \phi^j a_{t-j}.$$

So,  $Z_t \sim N(0, \sigma_a^2/(1 - \phi^2))$ . Consider

$$e_1 = Z_1 = \sum_{j=0}^{\infty} \phi^j a_{1-j},$$

$a_2,$

$a_3,$

$\vdots$

$a_n.$

Since  $e_1, a_2, \dots, a_n$  are independent, their joint density is

$$f(e_1, a_2, \dots, a_n) = \left[ \frac{1 - \phi^2}{2\pi\sigma_a^2} \right]^{1/2} e^{-\frac{e_1^2(1-\phi^2)}{2\sigma_a^2}} \cdot \left[ \frac{1}{2\pi\sigma_a^2} \right]^{\frac{n-1}{2}} e^{-\frac{1}{2\sigma_a^2} \sum_{t=2}^n a_t^2}.$$



Using the transformation:

$$\begin{aligned} Z_1 &= e_1, \\ Z_2 &= \phi Z_1 + a_2, \\ Z_3 &= \phi Z_2 + a_3, \\ &\vdots \\ Z_n &= \phi Z_{n-1} + a_n. \end{aligned}$$

The Jacobian for the transformation is

$$J = \begin{vmatrix} 1 & 0 & \cdot & \cdot & \cdot & 0 & 0 & 0 \\ -\phi & 1 & 0 & \cdot & \cdot & 0 & 0 & 0 \\ 0 & -\phi & 1 & 0 & \cdot & 0 & 0 & 0 \\ \vdots & & & & & & & \\ 0 & \cdot & \cdot & \cdot & \cdot & 0 & -\phi & 1 \end{vmatrix} = 1.$$

Thus

$$\begin{aligned} f(Z_n, Z_{n-1}, \dots, Z_1) &= J f(e_1, a_2, \dots, a_n) \\ &= \left[ \frac{1 - \phi^2}{2\pi\sigma_a^2} \right]^{\frac{1}{2}} e^{-\frac{Z_1^2(1-\phi^2)}{2\sigma_a^2}} \\ &\quad \cdot \left[ \frac{1}{2\pi\sigma_a^2} \right]^{\frac{n-1}{2}} e^{-\frac{1}{2\sigma_a^2} \sum_{t=2}^n (Z_t - \phi Z_{t-1})^2} \end{aligned}$$

$$\begin{aligned} \ln L(\phi, \sigma_a^2) \\ = -\frac{n}{2} \ln(2\pi) + \frac{1}{2} \ln(1 - \phi^2) - \frac{n}{2} \ln \sigma_a^2 - \frac{S(\phi)}{2\sigma_a^2} \end{aligned}$$

where

$$S(\phi) = Z_1^2(1 - \phi^2) + \sum_{t=2}^n (Z_t - \phi Z_{t-1})^2.$$

## Section 7.3 Nonlinear Estimation

(1) In CLS, we need to find  $(\hat{\phi}, \hat{\mu}, \hat{\theta})$  so that

$$S_*(\phi, \mu, \theta) = \sum_{t=1}^n a_t^2(\phi, \mu, \theta)$$

achieves its minimum value.

(2) In ULS, for example, for the AR(1) model, we need to find  $\hat{\phi}$  so that

$$S(\phi) = \sum_{t=2}^n [\dot{Z}_t - \phi Z_{t-1}]^2 + \sum_{i=-M}^1 [(1 - \phi^2)\phi^{1-i} Z_1]^2.$$

achieves its minimum value.

(3) In ML, for example, for the AR(1) model, we need to find  $\hat{\phi}$  so that

$$S(\phi) = Z_1^2(1 - \phi^2) + \sum_{t=2}^n (Z_t - \phi Z_{t-1})^2.$$

achieves its minimum value.

**Question:** how to find?

**nonlinear estimation method.**

**Example 7.1** ARMA(1, 1) model

$$Z_t = \phi Z_{t-1} + a_t - \theta a_{t-1}.$$

Find  $(\hat{\phi}, \hat{\theta})$  so that

$$S_*(\phi, \theta) = \sum_{t=1}^n a_t^2(\phi, \theta)$$

achieves its minimum value.

## Properties of the Parameter Estimates:

Let  $\hat{\alpha} = (\hat{\phi}, \hat{\mu}, \hat{\theta})$  be the CLS, ULS, or ML estimator of  $\alpha = (\phi, \mu, \theta)$ . Then

$$\sqrt{n}(\hat{\alpha} - \alpha) \sim N(0, V(\hat{\alpha})),$$

where

$$V(\hat{\alpha}) = \hat{\sigma}_a^2 (\bar{X}'_{\hat{\alpha}} \bar{X}_{\hat{\alpha}})^{-1} = \begin{pmatrix} \hat{\sigma}_{\hat{\alpha}_i \hat{\alpha}_j}^2 \end{pmatrix}.$$

We can test the hypothesis  $H_0 : \alpha_i = \alpha_{i0}$  using the following  $t$  statistics:

$$t = \frac{\hat{\alpha}_i - \alpha_{i0}}{\hat{\sigma}_{\hat{\alpha}_i \hat{\alpha}_i}}$$

with the degrees of freedom equaling  $n - (p + q + 1)$  for the ARMA( $p, q$ ) model.

The estimated correlation matrix of these estimates is

$$\hat{R}(\alpha) = \begin{pmatrix} \hat{\rho}_{\hat{\alpha}_i \hat{\alpha}_j} \end{pmatrix}.$$

where

$$\hat{\rho}_{\hat{\alpha}_i \hat{\alpha}_j} = \frac{\hat{\sigma}_{\hat{\alpha}_i \hat{\alpha}_j}}{\sqrt{\hat{\sigma}_{\hat{\alpha}_i \hat{\alpha}_i}} \sqrt{\hat{\sigma}_{\hat{\alpha}_j \hat{\alpha}_j}}}$$

A high correlation among estimates indicates overparameterization (too many parameters).

## Section 7.4. Omitted

## Section 7.5. Diagnostic Checking

Given data:  $Z_1, \dots, Z_n$ . Assume the model is  $\text{ARMA}(p, q)$ :

$$Z_t = \mu + \phi_1 Z_{t-1} + \dots + \phi_p Z_{t-p} + a_t - \theta_1 a_{t-1} - \dots - \theta_q a_{t-q}.$$

Two problems need to be considered:

- (i). Is the **ARMA** model correct?
- (ii). Even if the **ARMA** model is correct, what is  $p$  and  $q$ ?

Suppose (i) and (ii) are correct. We can estimate  $\hat{\phi}_i$  and  $\hat{\theta}_j$ .

Let

$$\hat{a}_t = Z_t - \hat{\mu} - \hat{\phi}_1 Z_{t-1} - \dots - \hat{\phi}_p Z_{t-p} + \hat{\theta}_1 \hat{a}_{t-1} + \dots + \hat{\theta}_q \hat{a}_{t-q},$$

where  $t = 1, \dots, n$ .

$\hat{a}_t$ ,  $t = 1, \dots, n$ , are called residuals.

If (i) and (ii) are truly correct, then  $\hat{a}_t$  should be very close to  $a_t$ .

Since the ACF of  $a_t$  is zero, the ACF of  $\hat{a}_t$  should be very close to zero. That is, we need to check the null hypothesis:

$$H_0 : \rho_1 = \rho_2 = \cdots = \rho_K = 0.$$

$$H_1 : H_0 \text{ does not hold.}$$

Test statistics:

$$Q = n(n+2) \sum_{k=1}^K (n-k)^{-1} \hat{\rho}_k^2 \sim \chi^2(K-m),$$

$K$  is the lag of ACF specified by yourself and  $m$  is the number of the parameters estimated in the model,

$$\hat{\rho}_k = \frac{\sum_{t=1}^{n-k} \hat{a}_t \hat{a}_{t+k}}{\sum_{t=1}^n \hat{a}_t^2}.$$

## **Section 7.6. Empirical Examples for Series W1-W7**

## **Section 7.7. Model Selection Criteria**

### **1. Akaike's AIC and BIC Criteria**

Akaike (1973, 1974):

$$\text{AIC}(p, q) = \ln \hat{\sigma}_a^2 + 2(p + q)/n,$$

$$\text{AIC}(p, q) = -2 \ln L_*(\hat{\phi}, \hat{\mu}, \hat{\theta}, \hat{\sigma}_a^2) + 2(p + q)$$

**The optimal order  $(p, q)$  is the one so that  $\text{AIC}(p, q)$  is minimum.**——- called AIC [Akaike's information criterion ].

$$\text{BIC}(p, q) = \ln \hat{\sigma}_a^2 + 2(p + q) \ln n/n,$$

$$\text{BIC}(p, q) = -2 \ln L_*(\hat{\phi}, \hat{\mu}, \hat{\theta}, \sigma_a^2) + (p + q) \ln n$$

**The optimal order  $(p, q)$  is the one so that  $\text{BIC}(p, q)$  is minimum.**——- called BIC [Schwartz (1978) Bayesian Criterion ](SBC).