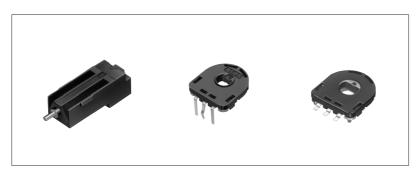


Compact, high precision, high heat resistant rotary sensors, meet various needs in position detection.

Magnetic Sensor Resistive Sensor







Features

- Uses potentiometer system.
- Analog output facilitates signal processing.
- Provides stable output characteristics against external noise and temperature changes.

Applications

- Rotation detecting sensors in car air conditioners, projectors, digital cameras and photo copiers
- Joint angle detections in robots
- Digital video cameras
- Car navigation systems

Typical Specifications

| Items | Specifications | | |
|----------------------------|---------------------------------------|--|--|
| Rating voltage | 5V DC | | |
| Rotational torque | 2mN∙m max. | | |
| Operating life | 1,000,000cycles (RDC40:100,000cycles) | | |
| Total resistance | 10kΩ | | |
| Total resistance tolerance | ±30% | | |

Recommended Product List

| Mounting method | Effective variable range | Linearity | Hollow shaft variation | Operating life (cycles) | Model No. | Minimum packing unit (pcs.) * | Drawing No. |
|---------------------------|--------------------------|-----------|----------------------------|-------------------------|------------|-------------------------------|-------------|
| Connector type | 13rotations | ±1% | _ | 100,000 | RDC401D07A | 770 | 1 |
| Horizontal type | | 320° ±2% | φ 3.5 dia | | RDC501015A | 1,500 | 2 |
| nonzontai type | | | ϕ 3.5 dia with radius | | RDC501011A | 1,500 | 3 |
| Vertical type | 220° | | φ 3.5 dia | 1,000,000 | RDC502006A | 1,600 | 4 |
| Reflow type | 320 | | | | RDC503013A | 1,300 | 5 |
| hellow type | | | ϕ 3.5 dia with radius | | RDC503015A | 1,300 | 6 |
| Reflow type (Low-profile) | | | ø 4 dia | | RDC506002A | 1,200 | 7 |

Notes

- 1. Additional product specifications in response to those not included in the above recommended products are also available.
- 2. **The minimum package content means the basic unit quantity for your order. Kindly determine your purchase order quantity to the "minimum package content" X N (an integral number). Please note that we will inform you separately for export packaging (content) quantity.

Dimensions Unit:mm No. Photo Style RDC40 (Multiple turns type) 28 CCW 1 RDC501 (Horizontal type) 2 RDC501 (Horizontal type, ϕ 3.5 dia with radius) 3 RDC502 (Vertical type) Mounting face 4

Magnetic Sensor

Resistive Sensor Photo

No.

■ Dimensions Unit:mm

Style

Agnetic Sensor

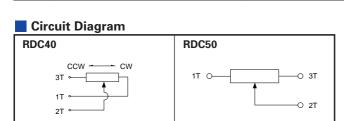
Resistive Sensor

RDC503 (Reflow type)

RDC503 (Reflow type, \$3.5 dia with radius)

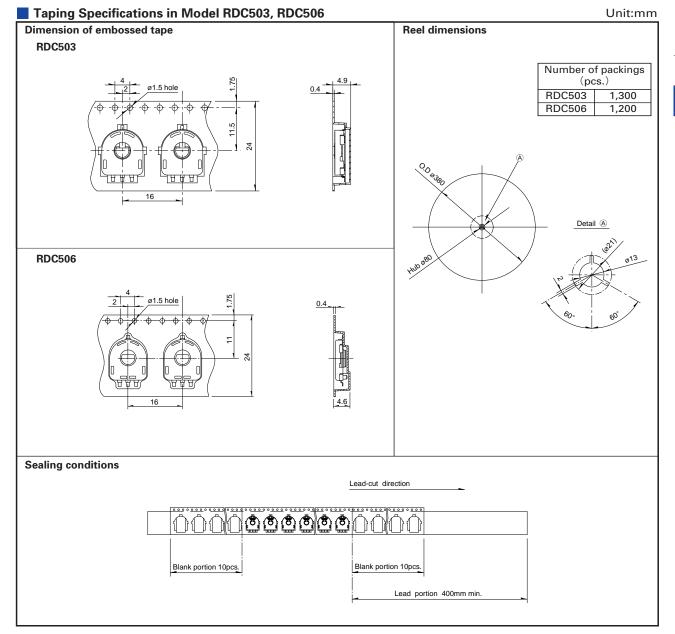
RDC506 (Reflow type, low-profile)

R1.5



7

Taping Specifications



Magnetic Sensor

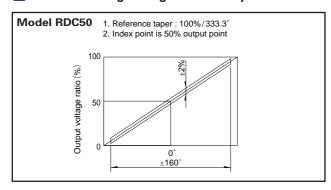
Resistive Sensor

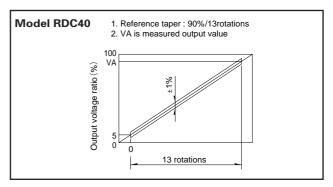
Product Specifications

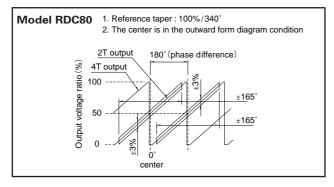
Magnetic Sensor Resistive Sensor

| | Style | | Rotary type | Linear type | | |
|-----------------------------|----------------------------|------------------------|---------------------------------|----------------------------------|------------------|-----------------|
| Item | Model | RDC40 | RDC501/RDC502/ RDC503/RDC506 | RDC80 | RDC10 | RD7 |
| Operating temperature range | | -30°C to +80°C | −40°C to +120°C | | -30°C to +85°C | -40°C to +105°C |
| | Total resistance tolerance | | ±3 | | ±20% | |
| | Resistance taper | | | | | |
| Electric performance | Rated voltage | | | 12V DC | | |
| | Max. operating voltage | 18V DC | 16V | DC | 5V DC | 18V DC |
| | Linearity | ±1% | ±2% | ±3% | ±0.5% | ±1% |
| | Effective variable range | 13rotations | 320° | 330° (1-phase) 360° (2-phase) | S (travel) – 2mm | S (travel) |
| Mechanical | Rotational angle | | (Without stopper) | | | |
| performance | Rotational torque | 2mN⋅m max. 10mN⋅m max. | | | | |
| | Operating force | , | | 0.25N max. | 2N less. | |
| Durability | 100,000cycles | • | | • | | |
| | 200,000cycles | | | | • | |
| | 1,000,000cycles | | • | | | |

Method for Regulating the Linearity







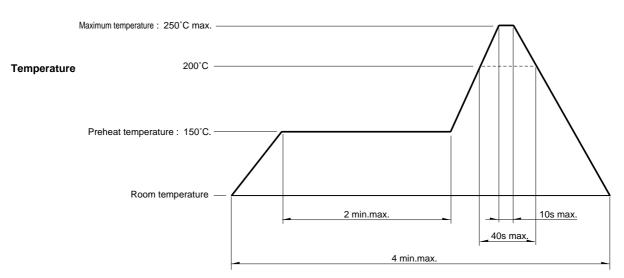
With rated voltage applied between terminals 1 and 3, the straight line which connects the measured output values VB and VA at specified reference positions B and A is assumed to be an ideal straight line, so that deviation against the ideal straight line when the voltage applied between terminals 1 and 3 is assumed to be 100% can be expressed as a percentage.

Soldering Conditions

Soldering Conditions

1. Recommended reflow conditions

Magnetic Sensor Resistive Sensor



- 2. Cleaning Cleaning should not be attempted.
- 3. Type of solder to be used Use cream solder that contains 10 15 % wt flux.
- 4. Number of solder applications apply solder only once

Notes

- 1. When using an infrared reflow oven, solder may not always be applied as intended. Be sure to use a hot air reflow oven or a type that uses infrared rays in combination with hot air.
- 2. The temperatures given above are the maximum temperatures at the terminals of the potentiometer when employing a hot air reflow method. The temperature of the PC board and the surface temperature of the potentiometer may vary greatly depending on the PC board material, its size and thickness. Ensure that the surface temperature of the potentiometer does not rise to 240°C or greater.
- 3. Conditions vary to some extent depending on the type of reflow bath used. Be sure to give due consideration to this prior to use.

Measurement and Test Methods

Analog Output Contact Type Sensor _

[Total Resistance]

The total resistance, with the shaft (lever) placed at the end of terminal 1 or 3, shall be determined by measuring the resistance between the resistor terminals 1 and 3 unless otherwise specified.

(Rating Voltage)

The rating voltage corresponding to the rated power shall be determined by the following equation. When the resulting rated voltage exceeds the maximum operating voltage of a specific resistor, the maximum operating voltage shall be taken as the rated voltage.

| E=√P•R |
|---|
| $\begin{array}{l} \texttt{E} : \texttt{Rated voltage} (\texttt{V}) \\ \texttt{P} : \texttt{Rated power} (\texttt{W}) \\ \texttt{R} : \texttt{Total nominal resistance} (\Omega) \end{array}$ |