

Node-Aligned Graph-to-Graph: Elevating Template-free Deep Learning Approaches in Single-Step Retrosynthesis

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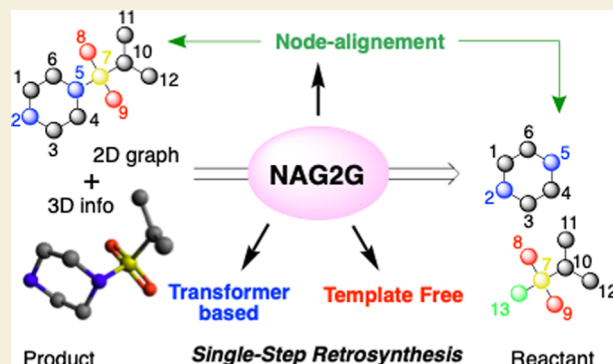
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ABSTRACT: Single-step retrosynthesis in organic chemistry increasingly benefits from deep learning (DL) techniques in computer-aided synthesis design. While template-free DL models are flexible and promising for retrosynthesis prediction, they often ignore vital 2D molecular information and struggle with atom alignment for node generation, resulting in lower performance compared to the template-based and semi-template-based methods. To address these issues, we introduce node-aligned graph-to-graph (NAG2G), a transformer-based template-free DL model. NAG2G combines 2D molecular graphs and 3D conformations to retain comprehensive molecular details and incorporates product-reactant atom mapping through node alignment, which determines the order of the node-by-node graph outputs process in an autoregressive manner. Through rigorous benchmarking and detailed case studies, we have demonstrated that NAG2G stands out with its remarkable predictive accuracy on the expansive data sets of USPTO-50k and USPTO-FULL. Moreover, the model's practical utility is underscored by its successful prediction of synthesis pathways for multiple drug candidate molecules. This proves not only NAG2G's robustness but also its potential to revolutionize the prediction of complex chemical synthesis processes for future synthetic route design tasks.

KEYWORDS: Template-Free Retrosynthesis, Deep Learning, Chemical Reactions, Graph Generation, Single-Step Retrosynthesis Prediction



INTRODUCTION

The single-step retrosynthesis (SSR)¹ is an essential operation in organic chemistry involving the reversed synthesis of a target product or intermediate in a single step. To achieve automatic multistep synthesis route design, SSR plays a critical role in building the blocks for each separated stage. Typically, the design of retrosynthesis strategies demands a thorough understanding and knowledge of organic chemistry principles, such as reaction mechanisms and reactive sites. With the emergence of computer-aided synthetic planning tools, researchers are now harnessing deep learning (DL) techniques to address this task and recognize their immense potential.

Various DL architectures have been developed and refined to suit the purpose of learning reactions for SSR tasks.² Even though there are notable variations in their network structures and data representation formats, they mainly fall into two primary groups: template-dependent and template-independent. In the following section, we will provide a concise overview of recent DL-based methods, highlighting their model designs as well as their strengths and weaknesses.

Template or Non-template?

The chemical intuition of organic synthetic chemists is accumulated from knowledge of reaction rules. Naturally, a dictionary or so-called template of existing reactions (such as an organic synthesis textbook) will serve as a bible for SSR design.

Therefore, the initial generation of retrosynthesis tools was trained to search for the most likely reaction templates in the library that could be used for generating the desired product. For instance, the program *Synthia* (previously named as *Chemtica*)³ employs over 80,000 rules crafted by synthetic experts to determine the appropriate reaction step based on a huge decision tree. DL strategies, like *RetroSim*⁴ and *NeuralSym*,⁵ use traditional molecular similarity metrics, such as fingerprints and Tanimoto similarity, to look for the templates that match well with products. Other contemporary approaches include *Local-Retro*,⁶ *GLN*,⁷ and *RetroComposer*.⁸ The limitations of template-based methods are inherent in the library on which they rely on. The library may not cover all potential reactions, and there is a risk of incorrect associations between the intricate products and template structures. To avoid being overly dependent on dictionaries, semi-template approaches emerged. This method breaks down the SSR prediction process into two stages—synthons⁹ or intermediate detection followed by reactant

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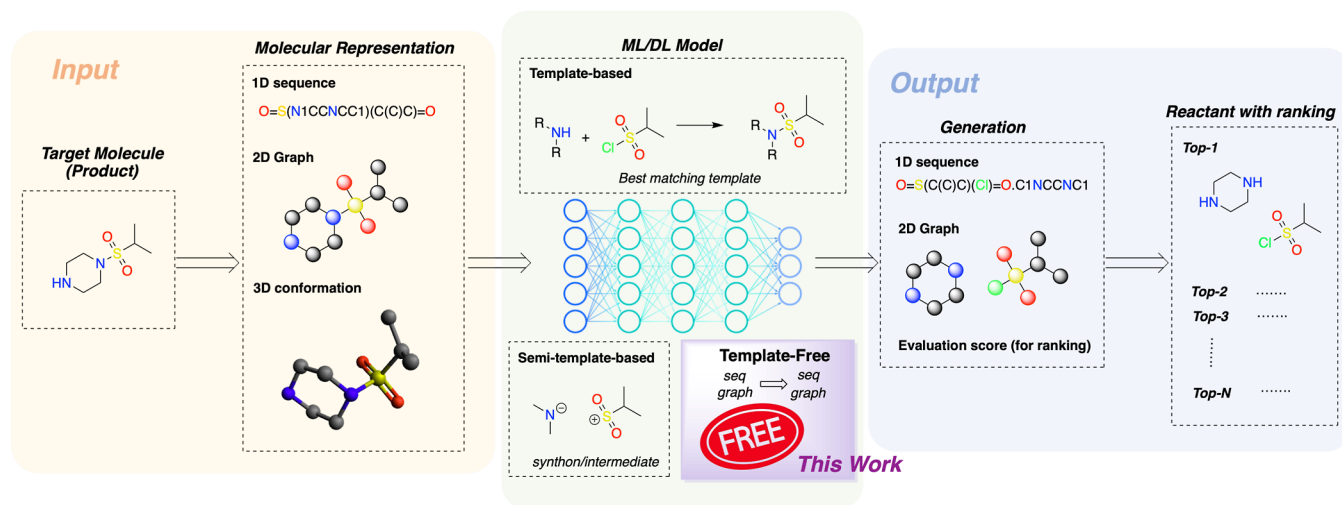


Figure 1. Overview of computer-aided SSR workflow based on template-based, semitemplate-based, and template-free design.

generation. Both steps are critical, as the preprocessing and identification of synthon are directly associated with the reactant prediction. The advantage of the two-stage methodology includes synthon understanding, searching capabilities expansion, and reaction scheme exploration. Meantime, errors can be easily passed from the first step to the second. As the technique of semi-template approaches grows, several models include *G2G*,¹⁰ *RetroXpert*,¹¹ *RetroPrime*,¹² *GraphRetro*,¹³ *SemiRetro*,¹⁴ *G2Retro*,¹⁵ and *Graph2Edits*¹⁶ have emerged, highlighting the compatibility of graph-to-graph models with molecular topology edits, which we will discuss later.

Can a DL model learn chemistry without any prerequisite knowledge (including dictionaries, templates, synthons, intermediates, and editing strategies) given by scientists? The answer is YES. Template-free models, such as pioneering *seq2seq*,¹⁷ *SCROP*,¹⁸ *Tied Transformer*,¹⁹ *Augmented Transformer*,²⁰ and *RetroDCVAE*²¹ all consider retrosynthesis as a prediction problem. The foundational idea posits that molecules can be analyzed in a manner akin to that for natural language processing (NLP) tasks. In this framework, product molecules are broken down into tokens based on their one-dimensional (1D) string representations, like the Simplified Molecular Input Line Entry System (SMILES). This tokenization allows us to treat the transformation of products into reactants, drawing parallels between chemical reactions and language translation processes. Recent studies have achieved marked improvements by applying the advanced NLP *Transformer*²² model, which employs a multihead attention mechanism. This mechanism enables the model to assign varying degrees of importance to different segments of input data, enhancing its ability to manage the message-passing process between each pair of atoms within a molecule and between pairs of product and reactant.

Choices of Molecular Representation

To help computers think like chemists, it is crucial to translate reaction information, specifically, molecular-level reactants and products, into in silico “language” or so-called molecular representation. One popular approach of DL-based SSR models^{18–21} is to employ 1D sequences, such as SMILES. Despite its simplicity, the 1D sequence-based model exhibits several limitations: (1) The sequence disregards the extensive molecular topological information;^{23–25} (2) Legal SMILES follow intricate syntax rules, which magnify the difficulty of valid

SMILES generation; (3) Effectively utilizing atom mapping information between products and reactants is challenging for 1D representation. Without alignment, model performance may decline due to lost atom correlations between products and reactants. (4) Due to the fact that a single molecule can have multiple SMILES representations when generating multiple candidate reactants for a product, it is possible to generate multiple reactant SMILES representing the same reaction, which may reduce the diversity of the candidates.²⁰

To overcome the limitations of 1D sequences, models involving 2D molecular graphs, which encompass atom (node) and bond (edge) topology, have been proposed for molecular representation in SSR tasks.^{10,15,16,26,27} 2D graphs encapsulate a wealth of information about the atomic environment, such as neighboring atoms and their connections. The graph topology offers an optimal solution for two-step tasks involving the modification of synthons and intermediates under the context of semi-template models. In order to effectively utilize the natural mapping information between atoms in products and reactants, prior approaches have employed a repeated graph edit strategy,²⁶ wherein the input graph of the product is iteratively modified by taking edit actions (such as adding nodes, removing nodes, updating nodes or edges) until it reaches an end—the reactant. Semi-template models such as *G2Retro*,¹⁵ *MARS*,²⁷ and *Graph2Edits*¹⁶ employ graph edit strategies²⁶ for graph generation. However, the 2D graph edition requires a delicate arrangement of edit actions and editing types forehead. Despite the advanced generation processes reducing computational expenses, the iterative action–prediction cycles, which require graph input and output at each editing step, continue to add to the computational burden.

Boundaries and Pushing Boundaries

Models have improved by combining different methods with the latest machine learning designs, as we have discussed before. Even though there are still some challenges, we see great potential in the new transformer-based models that can make predictions without using templates.^{17,28} Despite template-dependent models taking the upper hand, we have observed that template-free methods not only demonstrate remarkable performance with neat and concise structures but are also capable of capturing the nuances of chemical reasoning themselves. Molecular representation and attention mechanism

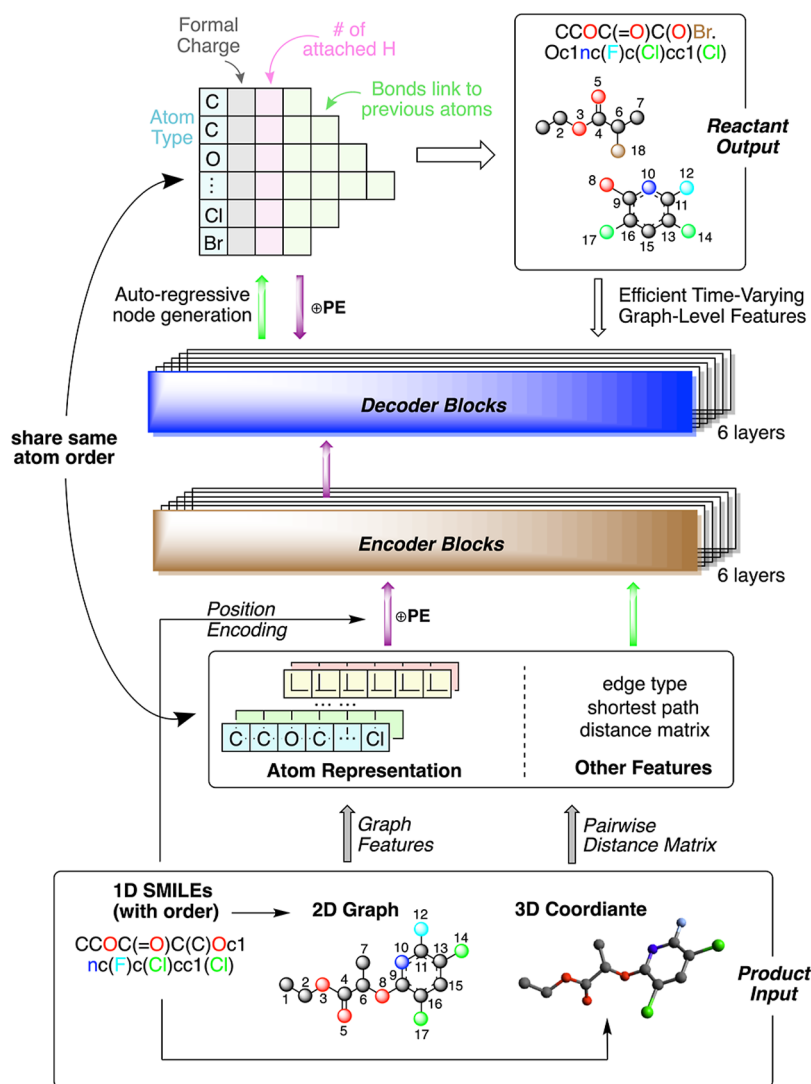


Figure 2. Network architecture of NAG2G.

(consideration of long-range dependencies between atoms) adaption are required to introduce more information. For example, *GET*²⁴ merges both graphs and SMILES encoders. *GTA*²⁵ integrates topological data into attention bias. Specifically, *Retroformer*,²⁹ using 1D sequence for the encoder, incorporates product-reactant atom alignments for better results.³⁰ Graph-based template-free methods, including G2GT,³¹ have advanced in exploiting graph topology. Nevertheless, they have yet to leverage node-alignment strategies for enhanced performance.

To take the advantage of a template-free approach and address the above limitations, we developed NAG2G that utilizes both 2D graph and 3D coordinates, with improved efficiency of graph generation and node alignment according to proper atom mappings, as shown in Figure 1. Moreover, we implement an autoregressive approach that generates graphs node-by-node according to the aligned order, drawing inspiration from language generation techniques. NAG2G is trained using two widely recognized data sets, USPTO-50k³² and USPTO-Full^{7,20} with augmented data, showing great capacity compared to existing models. Additionally, our model demonstrates its proficiency in tackling real-world problems by iteratively generating step-by-step synthesis pathways for drug

candidates. To gain deeper insights into the significance of each component within our methodology, we conducted ablation studies, systematically omitting certain parts of the model to evaluate their impact on performance.

METHOD

Model Construction

Encoders are the components of a neural network that process and compress input product into a compact representation and play the critical role of learning molecular representation in the NAG2G transformer-based encoder-decoder architecture. Competent models, such as *Graphormer*³³ and *Uni-Mol*,³⁴ have demonstrated the efficiency of encoder representation learning strategies. Thus, we adopt the encoder from *Uni-Mol* +,³⁵ which incorporates both 2D graph and 3D conformation for molecular representation as shown in Figure 2. The 1D positional encoding is also taken into account, serving as the node order encoder. Formally, we can denote the process of the encoder as the following in eq 1

$$\mathbf{O}^{\text{enc}} = f_{\text{enc}}(\mathbf{X}, \mathbf{P}^{\text{enc}}, \mathbf{E}, \mathbf{R}; \theta^{\text{enc}}) \quad (1)$$

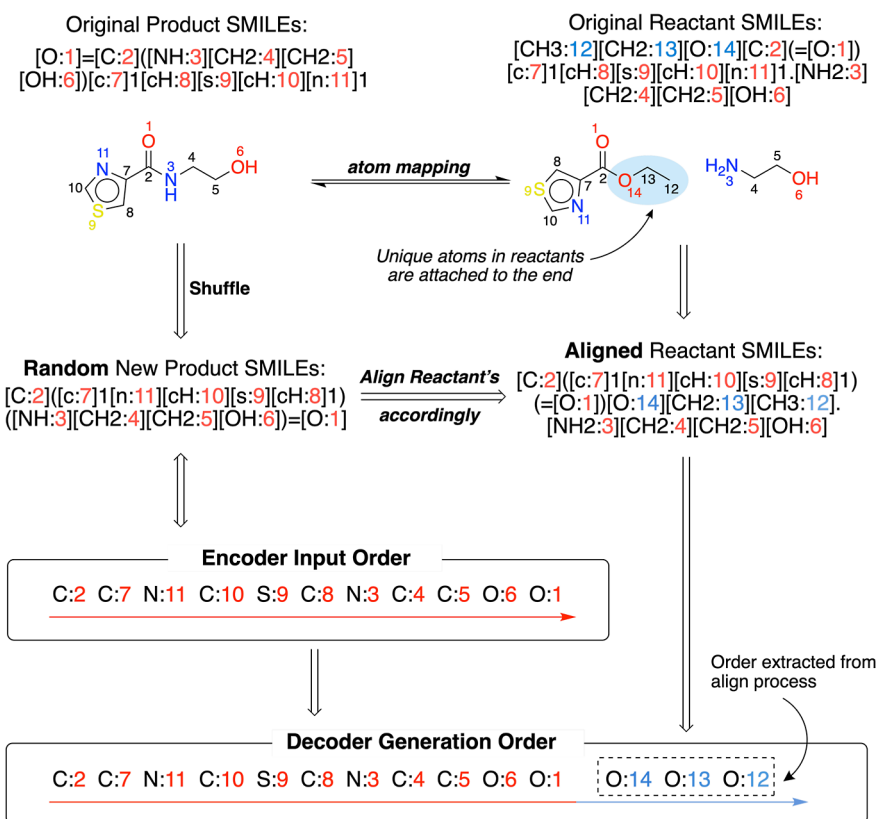


Figure 3. An example to illustrate the process of data augmentation and product-reactant alignment. The red numbers indicate the atoms present in both the product and reactants, while the blue ones represent the atoms found only in the reactants.

In the proposed formulation, \mathbf{X} denotes the atom features; \mathbf{P}^{enc} represents the 1D positional encoding, which is supplementary to the atomic embeddings; \mathbf{E} signifies the edge features inherent to the 2D graph structure; \mathbf{R} corresponds to the atomic coordinates in the 3D conformation; θ^{enc} encapsulates the encoder's learnable parameters, and \mathbf{O}^{enc} is the derived molecular representation result from the encoder.

Decoders primarily operate to generate the reactant graph node-by-node through an autoregressive approach. At the i -th time step, which also corresponds to the i -th generated node (atom), the decoder receives three distinct inputs:

- (1) The encoder's output, including keys and values that help in the interaction between the encoder and decoder.
- (2) The decoder outputs from prior steps (from 1 to $i - 1$), which is typical of autoregressive models in that the prediction of a new value is based on its preceding values. During the iterative process, 1D positional encoding is added, which is essential for NAG2G to align atom order between the encoder (product) inputs and decoder (reactant) outputs.
- (3) The graph-level features of the current output graph, such as node degrees and shortest paths between nodes. Incorporating these graph-level features directly into the model presents an efficiency challenge, as the graph features vary across time steps. To address this issue, we propose an efficient method for integrating graph-level features.

Given the above inputs, the decoder generates a new node at the i -th time step autoregressively, starting from atomic type, and then associated formal charge, the number of connected hydrogen atoms, and finally its edges (types of bond) linked to

prior nodes (atoms). The information for each node is produced sequentially given its above predictions. For instance, the formal charge is predicted based on the prior atomic type prediction. The process is denoted as

$$\begin{aligned}
 t_i &= f_{\text{dec}}(\mathbf{P}_{1:i}^{\text{dec}}, \mathbf{N}_{1:i-1}, \mathbf{G}_{1:i-1}, \mathbf{O}^{\text{enc}}; \theta^{\text{dec}}), \\
 c_i &= f_{\text{dec}}(t_i, \mathbf{P}_{1:i}^{\text{dec}}, \mathbf{N}_{1:i-1}, \mathbf{G}_{1:i-1}, \mathbf{O}^{\text{enc}}; \theta^{\text{dec}}), \\
 h_i &= f_{\text{dec}}(c_i, t_i, \mathbf{P}_{1:i}^{\text{dec}}, \mathbf{N}_{1:i-1}, \mathbf{G}_{1:i-1}, \mathbf{O}^{\text{enc}}; \theta^{\text{dec}}), \\
 e_{i,1} &= f_{\text{dec}}(h_i, c_i, t_i, \mathbf{P}_{1:i}^{\text{dec}}, \mathbf{N}_{1:i-1}, \mathbf{G}_{1:i-1}, \mathbf{O}^{\text{enc}}; \theta^{\text{dec}}), \\
 &\dots \\
 e_{i,k} &= f_{\text{dec}}(e_{i,k-1}, \dots, e_{i,1}, h_i, c_i, t_i, \mathbf{P}_{1:i}^{\text{dec}}, \mathbf{N}_{1:i-1}, \mathbf{G}_{1:i-1}, \mathbf{O}^{\text{enc}}; \theta^{\text{dec}})
 \end{aligned} \quad (2)$$

where $\mathbf{N}_{1:i-1}$ represents the set of nodes generated from the previous $i - 1$ time steps, $\mathbf{P}_{1:i}^{\text{dec}}$ denotes the 1D positional encoding of the current i nodes, $\mathbf{G}_{1:i-1}$ represents the graph feature extracted from previous outputs, and θ^{dec} denotes the parameters of the decoder. The atomic type, associated formal charge, and number of connected hydrogen atoms for the i -th node are represented by t_i , c_i , and h_i , respectively. The d -th edge, denoted by $e_{i,d} = (j, b)$, connects the i -th node and the j -th node with the bond type b . To define an edge's generative order, edges linked to nodes with larger 1D positions are prioritized. Generation of c_i and h_i is skipped if a node has zero charges or no linked hydrogen atoms to reduce the number of generative

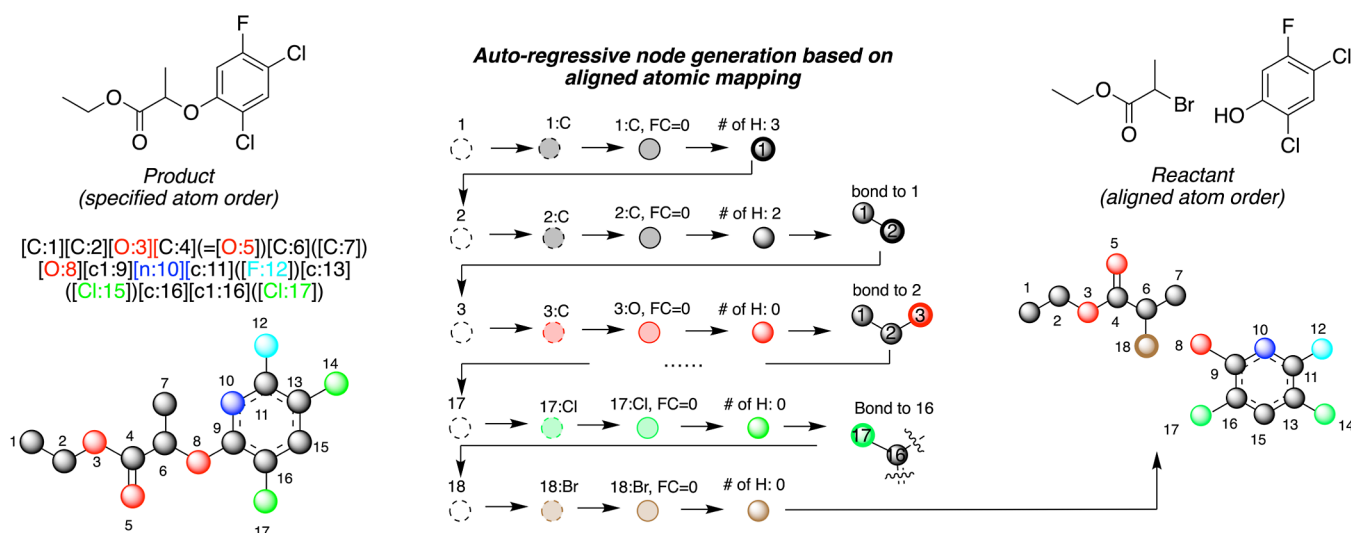


Figure 4. Illustration of the NAG2G generation.

steps. The overview of NAG2G's architecture is depicted in Figure 2.

Node Alignment and Data Augmentation

Molecular graphs, unlike sentences, lack an inherent sequence as atoms within a molecule do not have a natural order until assigned. In order to circumvent the need to consider the order of nodes in graph generation, several methods transform the graph generation task into indirect approaches, such as graph edit action prediction or SMILES prediction tasks, as discussed earlier. Alternatively, some methods utilize a one-in-all scheme, generating the entire graph output in a single step. Although this scheme avoids considering generation order, it lacks flexibility and is unsuitable for multisolution tasks such as retrosynthesis. To adopt a more flexible and autoregressive method, the output node order must be determined. A simple solution is using the canonical SMILES atom order; however, this fixed order restricts output data augmentation and limits the model's performance. Consequently, devising a robust and flexible strategy to tackle the unordered nature of graph nodes remains a formidable challenge in graph generation tasks. The unordered nodes challenge not only the graph generation but also the encoder input data augmentation. As input graphs inherently lack sequence, graph data augmentation must rely on alternative strategies such as omitting certain node or edge information. These approaches may be unsuitable for retrosynthesis, as the omission of critical information such as different reaction sites could result in vastly different outputs. Utilizing a reactant from the training set under these circumstances may introduce inaccuracies. Therefore, we choose a more appropriate encoder input data augmentation strategy based on node order, ensuring a more accurate and reliable outcome.

To address the challenges in input and output data augmentation and enable a flexible node-by-node autoregressive generation, we propose a novel method based on product-reactant node alignment. Our method begins with the random generation of the product's SMILES sequence by RDKit,³⁶ as shown in Figure 3. By following the new order in the SMILES sequence, we obtain the data-augmented input graph's node sequence order. Subsequently, the graph node order is marked by using position embedding. For the product graph with a determined order, we establish a unique and unambiguous rule that corresponds to the reactant node order for node-by-node

output, as demonstrated in Figures 3 and 4. In the reactant, atoms can be classified into two types: those shared with the product and those exclusive with the reactant. The assignment of atomic order should consider both these aspects. First, in generating the order, we stipulate that the shared atoms' order in the reactant should precede the order of nonshared atoms. For a specific ordered product input, there should exist a unique corresponding ordered reactant. This unique correlation refers to the order of shared atoms in the reactant follow the order in the product. Subsequently, the reactant SMILES is aligned with the product SMILES using RDKit to obtain the most similar SMILES. Finally, the order of nonshared atoms is extracted from the aligned reactant SMILES, ensuring the uniqueness of the nonshared atoms' order. This approach utilizes the product-reactant alignment information by ensuring that the node generation order mirrors the input graph's order in the training process and allows for consistent and equivariant data augmentation in both input and output. To conclude, we provide a robust and adaptable autoregressive generation procedure that can effectively handle the complexities of molecular graphs and enhance the performance of graph-to-graph generation models. NAG2G offers a concise, profound, and persuasive solution for input–output data augmentation, ensuring logical and efficient node-by-node autoregressive generation.

Efficient Time-Varying Graph-Level Features

During the generation process through decoder, the implementation of teacher forcing during training allows for the true output from a previous time step to be used as input for the current step, rather than the model's own prediction. This technique not only aligns the model's learning with the correct sequence of outputs but also enables parallel processing of data at various time steps. The interaction between the current and previous time steps is addressed within the decoder's attention layer. To avoid the inadvertent incorporation of future information, the attention matrix in a transformer model is masked with an upper triangular matrix. This ensures that a given output at a specific time step can only be influenced by preceding elements in the sequence, preserving the autoregressive property, where the prediction for each step is conditioned only on the known past information. Formally, we denote this process as

$$\text{attention}(\mathbf{Q}, \mathbf{K}, \mathbf{V}) = \text{softmax}\left(\frac{\mathbf{Q}\mathbf{K}^T}{\sqrt{d_h}} + \mathbf{M}\right)\mathbf{V} \quad (3)$$

where $\mathbf{Q}, \mathbf{K}, \mathbf{V} \in \mathbb{R}^{n \times d_h}$ represent the query, key, and value matrices, respectively. d_h is the dimension of one head. n is the number of time steps. \mathbf{M} is an additive mask matrix that ensures that only the relevant information from the current and previous time steps is considered during the attention computation. For the sake of simplicity, we present the calculation for only one head. The multihead attention process executes the above single-head calculation in parallel. During the calculation of one head, the computational complexity is $O(n \times n \times d_h)$, and the peak memory consumption is $O(n \times n)$.

As previously mentioned, graph-level features vary across time steps, and their direct utilization poses an efficiency challenge during model training. Specifically, to maintain the time-varying graph features, a matrix with shape $n \times n \times d_h$ is required.⁴ These time-varying graph features are then employed as additive positional encodings. As a result, the attention layer can be represented as

$$\begin{aligned} \text{attention}(\mathbf{Q}, \mathbf{K}, \mathbf{V}, \mathbf{D}) \\ = \text{softmax}\left(\frac{\mathbf{Q}(\mathbf{K} + \mathbf{D})^T}{\sqrt{d_h}} + \mathbf{M}\right)(\mathbf{V} + \mathbf{D}) \end{aligned} \quad (4)$$

where $\mathbf{D} \in \mathbb{R}^{n \times n \times d_h}$ denotes the time-varying graph features and the shape of $\mathbf{Q}, \mathbf{K}, \mathbf{V}$ is reshaped to $n \times 1 \times d_h$ for broadcasting. In this process, although the computational complexity remains unchanged, the peak memory consumption increases to $O(n \times n \times d_h)$. Considering that d_h is typically 32 or even larger, this significant increase in peak memory consumption is considered impractical for real-world applications.

To reduce the cost, we first remove \mathbf{D} from the $\mathbf{V} + \mathbf{D}$ term. Then, the cost is bottlenecked at $\mathbf{Q}\mathbf{D}^T$ due to the $\mathbf{Q}(\mathbf{K} + \mathbf{D})^T = \mathbf{Q}\mathbf{K}^T + \mathbf{Q}\mathbf{D}^T$ term. Furthermore, we can reduce the size of the last dimension by substituting \mathbf{D} . Thus, the attention can be transformed to

$$\begin{aligned} \text{attention}(\mathbf{Q}, \mathbf{K}, \mathbf{V}, \mathbf{D}_2) \\ = \text{softmax}\left(\frac{\mathbf{Q}\mathbf{K}^T}{\sqrt{d_h}} + \frac{\mathbf{Q}\mathbf{U}\mathbf{D}_2^T}{\sqrt{d_{h2}}} + \mathbf{M}\right)\mathbf{V} \end{aligned} \quad (5)$$

where $\mathbf{U} \in \mathbb{R}^{d_h \times d_{h2}}$ is employed to reduce the dimension of \mathbf{Q} and $\mathbf{D}_2 \in \mathbb{R}^{n \times n \times d_{h2}}$ represents the time-varying graph features with a much smaller dimension d_{h2} . With this configuration, the peak memory is reduced to $O(n \times n \times d_{h2})$. Figure 5 illustrates the design of a self-aware layer for time-varying graph features.

Data Preparation

The NAG2G is trained and tested on two broadly acknowledged data sets, USPTO-50k³² and USPTO-Full.^{7,20} USPTO-50k comprises 50,016 atom-mapped reactions, categorized into 10 reaction classes. The USPTO-50K data set was split into 40,008, 5,001, and 5007 reactions for the training, validation, and test sets, respectively. We also used the filtered USPTO-Full data set with approximately 1 million atom-mapped reactions as described by Tetko et al.²⁰ instead of the original USPTO-Full data set.⁷ After filtering out incorrect reactions, which leads to an approximate 4% size reduction, training, validation, and test sets contain approximately 769,000, 96,000, and 96,000 reactions.

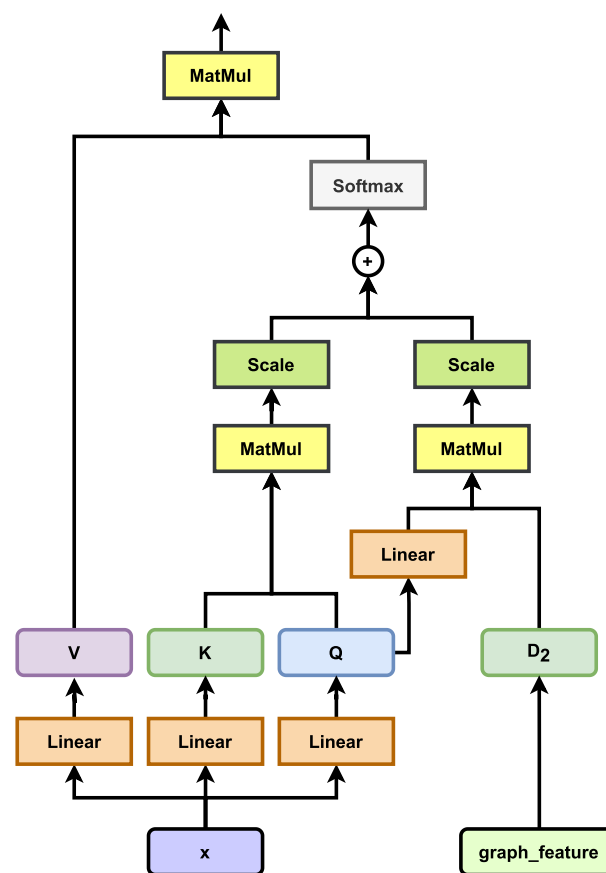


Figure 5. Illustration of decoder attention mechanism.

The distribution of reaction classes in the training, valid, and test sets of USPTO-50k are the same, displayed in Figure 6. Consistent with previous works, we did not benchmark the USPTO-Full results with the aid of reaction class information.

RESULTS

NAG2G Setup

The setup of NAG2G contains a 6-layer encoder and a 6-layer decoder. The input embedding dimension was set to 768, and the number of attention heads was set to 24. We employed the Adam optimizer³⁷ with $(\beta_1, \beta_2) = (0.9, 0.999)$, and linear warmup and decay with a peak learning rate of 2.5×10^{-4} . The training process took a total of 12,000 steps with a batch size of 16, requiring 6 h to finish on a single NVIDIA A100 GPU. For the training on the USPTO-Full data set, NAG2G ran 48,000 training steps with a batch size of 64, taking approximately 30 h to complete on eight NVIDIA A100 GPUs.

Results on the USPTO Data Set

To evaluate the performance of NAG2G during inference, we utilized the commonly adopted beam search method for top candidate predictions. We configure the beam size at 10, using a length penalty of 0 and a temperature of 1. Notably, data augmentation is not applied during the inference phase. Additionally, NAG2G relies on RDChiral³⁸ to assign the atomic chirality of reactants, drawing from the product's stereochemistry.

The definition of prediction accuracy follows the approach proposed by Liu et al.,¹⁷ which considers a prediction to be accurate only if it completely identifies all reactants for a specific

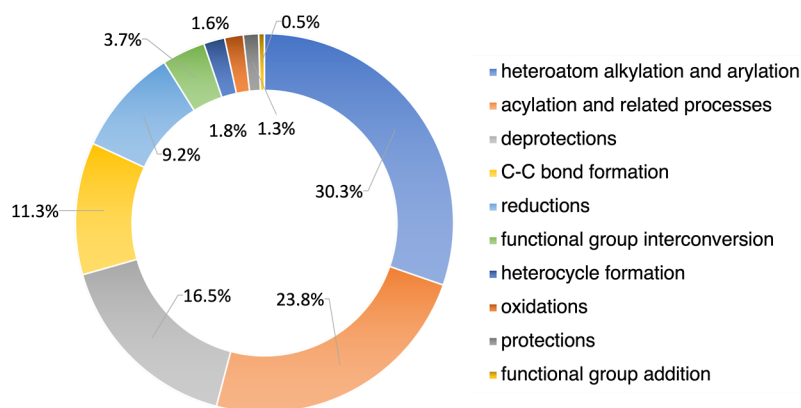


Figure 6. Distribution of 10 types of reactions in the USPTO-50k data set. The reaction's legends are ranked based on their fraction from largest to smallest.

Table 1. Top-*k* Accuracy for Retrosynthesis Prediction on USPTO-50k^a

model	Top- <i>k</i> accuracy (%)							
	USPTO-50k							
	reaction class known				reaction class unknown			
	1	3	5	10	1	3	5	10
Template-Based								
RetroSim ⁴	52.9	73.8	81.2	88.1	37.3	54.7	63.3	74.1
NeuralSym ⁵	55.3	76.0	81.4	85.1	44.4	65.3	72.4	78.9
GLN ⁷	64.2	79.1	85.2	90.0	52.5	69.0	75.6	83.7
MHNreact ³⁹	-	-	-	-	50.5	73.9	81.0	<u>87.9</u>
RetroComposer ⁸	<u>65.9</u>	<u>85.8</u>	<u>89.5</u>	<u>91.5</u>	<u>54.5</u>	<u>77.2</u>	<u>83.2</u>	87.7
Semi-Template-Based								
G2G ¹⁰	61.0	81.3	86.0	88.7	48.9	67.6	72.5	75.5
RetroXpert ¹¹	62.1	75.8	78.5	80.9	50.4	61.1	62.3	63.4
RetroPrime ¹²	64.8	81.6	85.0	86.9	51.4	70.8	74.0	76.1
GraphRetro ¹³	63.9	81.5	85.2	88.1	53.7	68.3	72.2	75.5
SemiRetro ¹⁴	65.8	85.7	89.8	92.8	<u>54.9</u>	75.3	80.4	84.1
G2Retro ¹⁵	63.6	83.6	88.4	91.5	54.1	74.1	81.2	86.7
MARS ²⁷	<u>66.2</u>	<u>85.8</u>	<u>90.2</u>	<u>92.9</u>	54.6	<u>76.4</u>	<u>83.3</u>	<u>88.5</u>
Template-Free								
LV-transformer ⁴⁰	-	-	-	-	40.5	65.1	72.8	79.4
SCROP ¹⁸	59.0	74.8	78.1	81.1	43.7	60.0	65.2	68.7
GET ²⁴	57.4	71.3	74.8	77.4	44.9	58.8	62.4	65.9
tied transformer ¹⁹	-	-	-	-	47.1	67.1	73.1	76.3
MEGAN ²⁶	60.7	82.0	87.5	91.6	48.1	70.7	78.4	86.1
aug. transformer ²⁰	-	-	-	-	48.3	-	73.4	77.4
aug. transformer* ²⁰	-	-	-	-	53.5	69.4	81	85.7
GTA ²⁵	-	-	-	-	51.1	67.6	74.8	81.6
Graph2SMILES ²³	-	-	-	-	52.9	66.5	70.0	72.9
RetroDCVAE ²¹	-	-	-	-	53.1	68.1	71.6	74.3
DualTF ⁴¹	65.7	81.9	84.7	85.9	53.6	70.7	74.6	77.0
Retroformer ²	64.0	82.5	86.7	90.2	53.2	71.1	76.6	82.1
G2GT ³¹	-	-	-	-	48.0	57.0	64.0	64.5
G2GT* ³¹	-	-	-	-	54.1	69.9	74.5	77.7
NAG2G (ours)	<u>67.2</u>	<u>86.4</u>	<u>90.5</u>	<u>93.8</u>	<u>55.1</u>	<u>76.9</u>	<u>83.4</u>	<u>89.9</u>

^aThe best performance is in **bold**, and the best results for each method type are underlined. Models denoted by an asterisk (*) employed supplementary datasets for training or incorporated techniques to enhance the accuracy during inference. In order to maintain a fair comparison, we also present their results without implementation of these additional techniques.

chemical reaction. We measure the top-*k* accuracy of the predictions, defined as the proportion of test cases in which the correct answer appears among the top *k* candidates of the beam search results.

USTPO-50k

In Table 1, NAG2G demonstrates superior performance on the USPTO-50k data set compared to recent baseline approaches, including template-based, semi-template-based, and template-free models. (1) No supplementary techniques were imple-

Table 2. Top-*k* Accuracy for Retrosynthesis Prediction on the USPTO-Full Data Set^a

model		Top- <i>k</i> accuracy (%)			
model type	methods	1	3	5	10
template-based	RetroSim ⁴	32.8	-	-	56.1
	NeuralSym ⁵	35.8	-	-	60.8
	GLN ⁷	39.3	-	-	63.7
semi-template-based	RetroPrime ¹²	44.1	59.1	62.8	68.5
template-free	MEGAN ²⁶	33.6	-	-	63.9
	aug. transformer*	44.4	-	-	70.4
	NAG2G (ours)	47.7	62.0	66.6	71.0
	aug. transformer*o ²⁰	46.2	-	-	73.3
	G2GT*o ²⁵	49.3	-	68.9	72.7
	NAG2G (ours)o	49.7	64.6	69.3	74.0

^aModels denoted by an asterisk (*) used supplementary data sets for training or incorporated techniques to improve accuracy during inference. For models denoted by a circle (o), the invalid reactions are excluded from the test set, following the setting of the augmented transformer.²⁰ To align our methods with the previous baselines, we adopted the approach from the augmented transformer,²⁰ assuming that the methods failed on the removed test data, as evidenced by the results of our methods without a circle (o).

mented to aid the inference procedure in NAG2G to ensure a fair comparison. Within the template-free domain, NAG2G markedly surpasses all benchmarks across every metric. Even though certain baselines leverage extra data or methods to bolster their results (indicated by *), NAG2G continues to excel without any such enhancements. Despite the additional use of predefined rules in template-based and semitemplate-based methods, NAG2G outperforms them without prerequisite information. This marks NAG2G achieves competent results among both template-based and semi-template-based approaches, which earlier template-free benchmarks never achieved. Besides, NAG2G gives SOTA results based on MaxFrag metric proposed by *Augmented Transformer*,²⁰ see the [Supporting Information](#) for details. Detailed results include testing of each reaction class on the USPTO-50k data set when trained with the class known are summarized in the [Supporting Information](#) as well.

USTPO-FULL

Table 2 presents the performance metrics of various models evaluated on the USPTO-Full data set. As the data set size increases, the performance of all models declines due to the heightened complexity of the task. Notably, while template-based methods have shown impressive results on the USPTO-50k data set, their performance falters considerably on the larger USPTO-Full data set. This trend indicates that the reliance on template-based methods from pre-established rules becomes a limitation when confronting larger and more complex data sets. In contrast, though weakened as well, template-free methods demonstrate a more versatile and adaptive capability, particularly more suited for expansive data sets. Still, it is evident that NAG2G consistently outperforms preceding baselines across all evaluative criteria.

Result Interpretation (Ablation Study)

To identify the importance of each component that has been designed for NAG2G, we performed ablation studies by studying the impact of its removal. This aids in understanding the NAG2G structure and how node alignment, data augmentation, and the incorporation of time-varying graph features can benefit the model.

Table 3 presents a comprehensive quantitative breakdown of the impact of each strategy on the model's performance on the USPTO-50k data set, focusing specifically on Top-*k* accuracy percentages. When all three techniques—node alignment, data

Table 3. Ablation Study on USPTO-50k with Reaction Class Unknown

strategies			Top- <i>k</i> accuracy (%)			
node alignment	data augmentation	graph features	1	3	5	10
✓	✓	✓	55.1	76.9	83.4	89.9
✓	✓	×	54.1	75.9	82.6	88.8
✓	×	✓	49.2	69.2	75.3	80.4
×	✓	✓	46.1	47.6	48.5	49.9
×	×	✓	40.3	54.9	58.9	62.6

augmentation, and graph features—are utilized, the model hits a peak Top-1 accuracy of 55.1% and maintains high performance across Top-3 (76.9%), Top-5 (83.4%), and Top-10 (89.9%), emphasizing the synergistic effect of this combination. Eliminating graph features results in a marginal decrease in the accuracy of each Top-*k* accuracy metric. However, incorporating these graph features contributes to an approximately 1% improvement in the metrics under challenging scenarios where further progress is difficult to achieve. Omitting data augmentation leads to a more pronounced decline, with the top-1 accuracy decreasing by 5.9% and the top-10 accuracy experiencing a reduction of 9.5%, underscoring its role in enhancing model robustness and generalizability to unseen data. The performance deteriorates dramatically without node alignment, with the accuracy dropping by 50% for Top-10. This highlights the importance of node alignment in capturing the structural information of the graphs and enabling the model to make more accurate predictions. It is evident that the difference between top-1 and top-10 accuracy significantly reduces from 34.8% (when both data augmentation and node alignment are employed) to merely 3.8% (when data augmentation is used without node alignment). This illustrates that using data augmentation without node alignment leads to a lower diversity of candidate predictions compared to when both techniques are employed. However, it is worth noting that the gap remains at 22.3% when neither node alignment nor data augmentation is utilized, which is not particularly high. Consequently, this highlights that node alignment and data augmentation are complementary techniques that, when jointly employed, can enhance the performance metrics. In conclusion, our ablation study shows that node alignment, data augmentation, and graph features are all crucial components

of our model, with each strategy playing a vital role in enhancing prediction accuracy. The combination of these strategies yields the best overall performance, emphasizing the importance of incorporating them in future work on graph-based reaction prediction models.

Table 4 illustrates the Top-*k* validity of various models on the USPTO-50k data set, focusing on the autoregressive node

Table 4. Top-*k* Validity of the Generated Molecules on USPTO-50k with the Reaction Class Unknown

model	Top- <i>k</i> validity (%)			
	1	3	5	10
NAG2G (ours)	99.7	98.6	97.1	92.9
NAG2G w/o charge	89.9	90.2	86.1	75.9
NAG2G w/o hydrogen	89.6	88.4	87.6	83.4
NAG2G w/o charge or hydrogen	80.8	82.5	81.5	77.6
GET ²⁴	97.8	86.6	80.5	70.7
Graph2SMILES ²³	99.4	90.9	84.9	74.9
RetroPrime ¹²	98.9	98.2	97.1	92.5

generation approach adopted by the NAG2G model. When all atomic features (type, formal charge, and number of hydrogens) are utilized, NAG2G delivers a Top-1 validity of 99.7%, with strong performances also observed in Top-3 (98.6%), Top-5 (97.1%), and Top-10 (92.9%) predictions. The exclusion of certain molecular properties during node generation reveals the importance of each feature in generating SMILES. Omitting just the formal charge results in a Top-1 validity of 89.9%, while the disregard of the hydrogens brings it to 89.6%. The most pronounced decrease is observed when both of these features are excluded, dropping the Top-1 validity to 80.8%. The results with respect to the accuracy are also studied, see the [Supporting Information](#) for details. When juxtaposed with other models such as GET, Graph2SMILES, and RetroPrime, NAG2G consistently outperforms.

Furthermore, our ablation studies of the encoder reveal that the performance of our model is robust and not overly dependent on its encoder configuration. For detailed findings, please refer to the [Supporting Information](#) provided.

Case Studies

To assess the capability of designing synthetic routes for organic molecules, we picked four drug candidates as the target product and performed sequentially SSR using NAG2G trained with the USPTO-50k data set. The performance of template-free NAG2G successfully outperforms the previous model¹⁶ according to its inference results as shown in [Figure 7a](#). All six synthetic steps documented in the original literature for Nirmatrelvir⁴² are accurately predicted by NAG2G, achieving all predictions within the top three ranks. The initial step involving the dehydration of the amide to form the cyano group was ranked first, while the rank-2 result predicted condensation reaction aligns with a recent advanced one-pot synthesis strategy for Nirmatrelvir.⁴³ The exact step-2 and step-6 condensations are pulled out by NAG2G with both answers standing out among the other candidates. In the third step, the trifluoroacetylation of the amine in **6** was predicted as the third-ranked reaction by our model, an improvement over its sixth-ranked prediction in Graph2Edits. For step-4 and step-5, our model's first- and second-ranked predictions effectively serve the protective function using different, yet common, reagents.⁴⁴ The second test case, osimertinib, known by its

research name AZD9291, gained approval in 2014 as a clinical treatment for patients with nonsmall cell lung cancer.⁴⁵ As shown in [Figure 7b](#), NAG2G successfully delineates a five-step synthesis, as described in the literature, tracing the synthetic pathway from commercially available pyrimidines to the final product AZD9291. The initial step of the reverse synthesis is an acylation reaction, ranking the first in order of likelihood, followed by another rank-1 reduction of the nitro group. Subsequently, it correctly identified two consecutive nucleophilic aromatic substitution steps as the top choices. In the final step, the model's highest probability prediction was a Suzuki coupling, which was also the rank-2 reaction inferred by the Graph2Edits model.¹⁶ Although the original strategy involving a Grignard reaction was not predicted, the rank-6 result suggests the alternative pathway. For the third case, we selected salmeterol, a long-acting bronchodilator, which has been tested in the former template-based model by Coley,⁴ LocalRetro,⁶ and root-aligned strategy by Zhong.³⁰ With the presence of amine and phenol functional groups in compound **21**, NAG2G recommends protecting the reactive sites, ranking these steps as first and second.^{46,47} The subsequent reaction is the production of compound **22** through a Williamson ether-type reaction, identified as the rank-5 choice. Moreover, rank-6 for the fourth step successfully predicts the transformation of **26** into **25** via an asymmetric Henry reaction, as described in Guo's synthesis.⁴⁷ It is noteworthy that while the original synthesis protects two hydroxyl groups in compound **27** simultaneously using 2,2-dimethoxypropane, NAG2G opts to protect only the more reactive phenol group, which aligns with the requirements of the complete synthetic scheme.

The last example, lenalidomide, which is also involved in the work of LocalRetro⁶ and Graph2Edit¹⁶ turns out to be a more challenging task.⁴⁸ NAG2G accurately predicted the first and last steps involving nitro reduction and NBS (*N*-bromosuccinimide) substitution as the top-1 reactions. For the cyclization step involving the formation of two C–N bonds, NAG2G proposed a precursor, compound **31**, with a chlorine substituent instead of bromine. Nonetheless, NAG2G is capable of suggesting a stepwise ring closure mechanism, mirroring the results reported by LocalRetro.

Error Analysis

In the sequence-to-sequence (seq2seq) model¹⁷ context, the generation of reactants in the SMILES format can result in three outcomes: (1) Generated SMILES strings generated are invalid, corresponding to a nonchemically feasible structure. (2) The SMILES strings are chemically valid but do not represent suitable reactants capable of producing the desired product under given reaction conditions. (3) The SMILES strings represent reactive compounds that can lead to the products as common reactions, even though they may not match the ground truth reactants exactly. In evaluating the first type of error for our model on the USPTO-50k data set, we focused on validity, which gauges the percentage of valid SMILES strings generated among the top-*k* predictions. Our model boasts a top-1 validity of 99.7%, outperforming other advanced models.^{12,23,24} This superior validity is due to the autoregressive generation process, as we have discussed in the ablation study section. If the model randomly omits predictions for charge and hydrogen attachments, then the top-1 validity significantly decreases to 80.8%. The identification of the second and third types of errors involves expert evaluation by organic chemists. To impartially review the inference results without preassigned reaction classes,

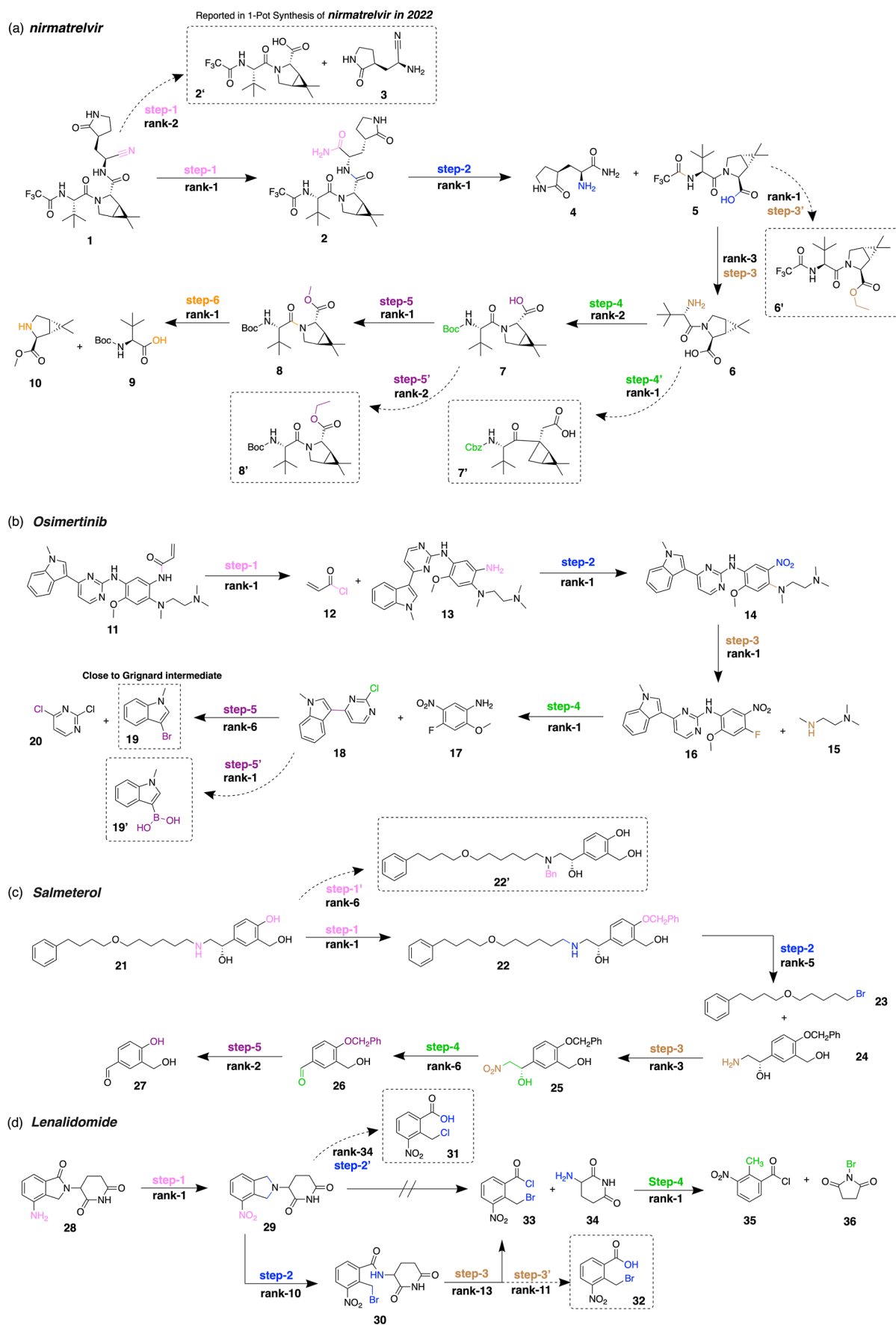


Figure 7. Synthesis route of four drug molecules and the predicted ranks given by NAG2G.

we selected three representatives to examine the variety of reactants that can be predicted by our model, referred to here as NAG2G. In all cases, the ground truth falls within the top 10 predictions, alongside a variety of other reaction types, showcasing the model's extensive predictive range. The rich diversity of suggested synthetic solutions enhances the retrosynthetic route design by providing a wide array of chemical reactions to consider, thus offering alternatives for subsequent route selection and evaluation. For a detailed summary table and analysis, please refer to the [Supporting Information](#).

Another limitation stemming from the origins of the USPTO data set is the lack of detailed reaction information, such as conditions, yields, and selectivity. With this information, the NAG2G model could provide more accurate and reliable rankings for its predictions. Additionally, single-step prediction models, including ours, might overlook interactions between consecutive steps. For example, in case 3, the selective phenolic benzylation, while an efficient protecting step, could significantly impact the subsequent asymmetric Henry reaction. This scenario illustrates that effective single-step predictions require not just accuracy but also a thorough evaluation of route complexity and yield trade-offs. In response to these challenges, we are actively developing advanced scoring methods to facilitate multistep process decisions based on the results provided by NAG2G.

CONCLUSIONS

In this study, we present the NAG2G model—a graph-based SSR method free from templates. This model employs the transformer encoder–decoder framework, generating reactant molecule graphs in an autoregressive fashion. Testing on well-established data sets, USPTO-50k and USPTO-Full, indicates that NAG2G offers competent performance against prevailing SOTA models. Ablation studies shed light on the contributions of various components, underlining the potential of our approach. The replication of case studies and error analysis highlight the promising performance of NAG2G in specific SSR tasks, suggesting that further advancements could enhance its capabilities even more.

While many SSR models, detailed in our introduction, show promise, NAG2G marks a notable stride in applying DL to single-step retrosynthesis—especially when considering a template-independent approach. Our methodology opens the door that intricate neural networks are not the sole route to achieve high quality results; careful and detailed model design, combined with precise task definitions, can yield competitive results. Our current design is tailored for single-step retrosynthesis predictions, where input and output graphs bear close resemblance. For broader graph-to-graph generation tasks, especially with considerable input–output disparities, refinements may be needed. Moving forward, our ultimate goal is to develop this method, delving into multistep synthesis planning for more intricate chemical synthesis scenarios.

ASSOCIATED CONTENT

Supporting Information

The Supporting Information is available free of charge at <https://pubs.acs.org/doi/10.1021/jacsau.3c00737>.

The NAG2G is available at <https://github.com/dptech-corp/NAG2G>. Experimental results related to NAG2G's

performance, auxiliary ablation studies, and prediction examples ([PDF](#))

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Notes

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ADDITIONAL NOTE

^aHere, we consider node-wise graph features, such as node degrees. Pair-wise graph features, such as the shortest path, will consume significantly more memory.

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