

# The Interaction Dataset

Probabilistic Prediction and Comprehensible Motion Planning for Automated Vehicles Workshop  
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# Dataset Creators

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**Not a comprehensive list!**

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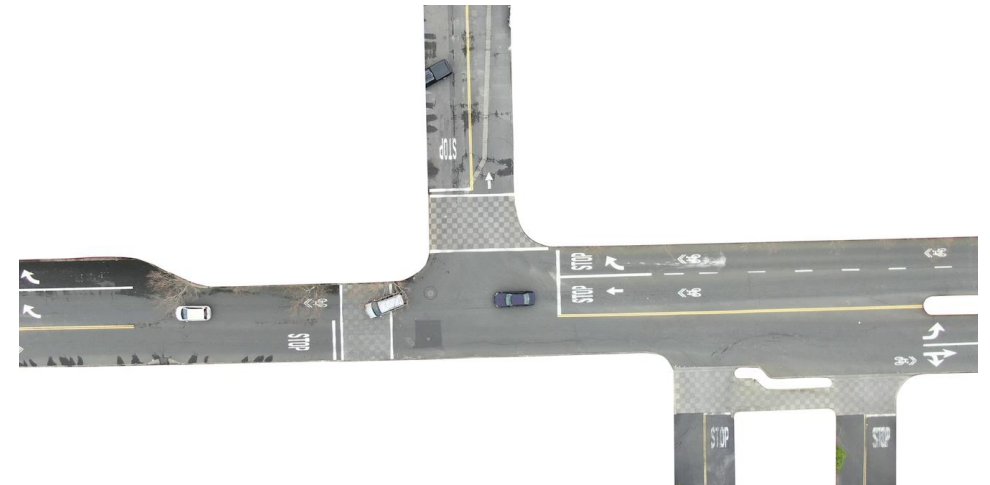
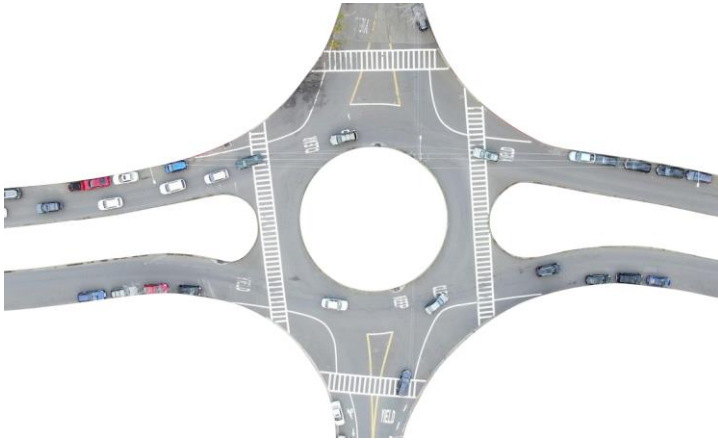
4 MINES Paris Tech, Paris, France

# The Interaction Dataset



11 recording locations

# The Interaction Dataset



11 recording locations

# Use cases



<https://interaction-dataset.com/>

# The Interaction Dataset

For the 11 recording locations, three files for each location are included:

1. High definition (HD) map (xxx.osm)
2. Recorded vehicle track files (vehicle\_tracks\_xxx.csv)
3. Recorded pedestrian track files (pedestrian\_tracks\_xxx.csv)

track_id	frame_id	timestamp_ms	agent_type	x	y	vx	vy	psi_rad	length	width
1	1	100	car	13.856	38.136	0.098	-0.583	-1.405	4.67	1.98
1	2	200	car	13.865	38.079	0.088	-0.566	-1.417	4.67	1.98
1	3	300	car	13.874	38.023	0.078	-0.547	-1.429	4.67	1.98
1	4	400	car	13.881	37.97	0.07	-0.527	-1.439	4.67	1.98
1	5	500	car	13.888	37.918	0.063	-0.505	-1.448	4.67	1.98
1	6	600	car	13.894	37.869	0.056	-0.483	-1.455	4.67	1.98
1	7	700	car	13.899	37.821	0.051	-0.462	-1.461	4.67	1.98
1	8	800	car	13.904	37.776	0.048	-0.445	1.775	4.67	1.98

# The Interaction Dataset

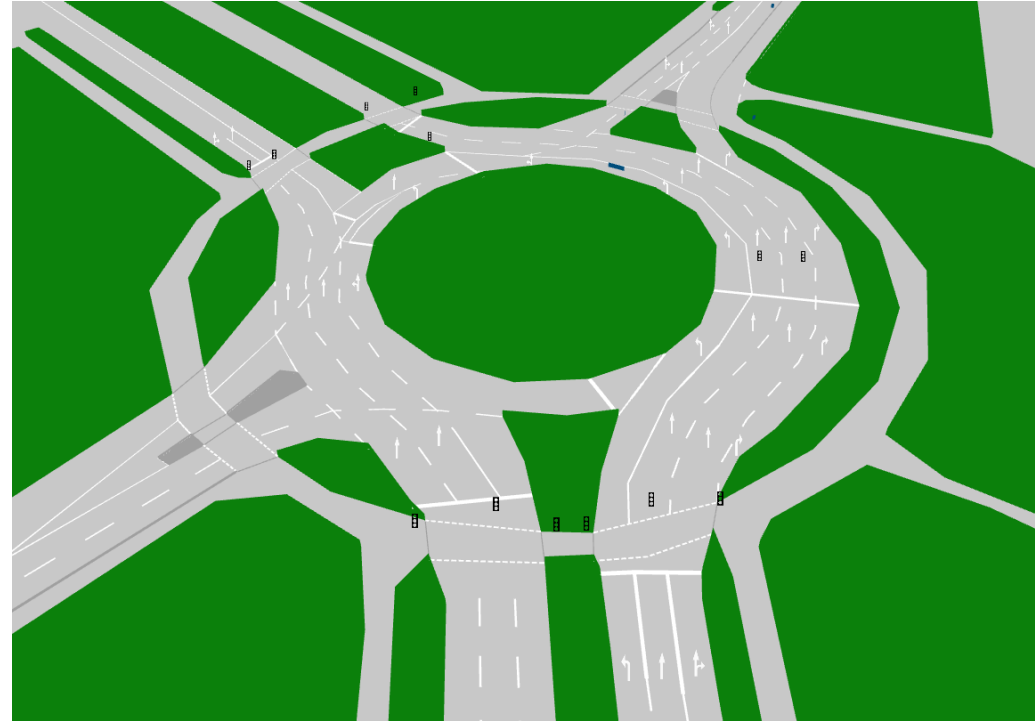
The dataset can serve for many behavior-related research areas, such as

- 1) intention/behavior/motion prediction,
- 2) behavior cloning and imitation learning,
- 3) behavior analysis and modeling,
- 4) motion pattern and representation learning,
- 5) interactive behavior extraction and categorization,
- 6) social and human-like behavior generation,
- 7) decision-making and planning algorithm development and verification,
- 8) driving scenario/case generation, etc

# The Interaction Dataset

## Lanelet2 maps

- High-definition maps
- Traffic rules & routing graph features
- Bindings to ROS
- BSD 3-clause Licence





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THANK  
YOU