

# Align Rotation to Vector Node



The *Align Rotation to Vector* node rotates an Euler rotation into the given direction.

## Inputs

### Rotation

The [Euler](#) rotation to align.

#### Important

This input has to be a rotation input. Be careful not to connect a direction vector like the [normal](#).

### Factor

Determines how much the points are rotated towards the vector. Zero effectively disables the node and one means that the points are aligned with the vector perfectly.

### Vector

The direction vector that points should be rotated to. The vector is in the local space of the object that is being modified. When it is all zeros for a point, it is not rotated at all.

## Properties

### Axis

Local axis of the object that is to be rotated towards the vector input.

### Pivot

The local axis to rotate around.

#### Auto:

The best rotation angle is computed automatically. This minimizes the angle of rotation.

#### X, Y, Z:

Rotate around a specific local axis.

## Outputs

### Rotation

The rotated Euler rotation.