# Skip to content Generic Constraint

Reference

Panel:

Physics • Rigid Body Constraint

Type:

Generic

The generic constraint has a lot of available parameters.

The X, Y, and Z axis constraints can be used to limit the amount of translation between the objects. Clamping the min/max to zero has the same effect as the Point constraint.

Clamping the relative rotation to zero keeps the objects in alignment. Combining an absolute rotation and translation clamp would behave much like the Fixed constraint.

Using a nonzero spread on any parameter allows it to oscillate in that range throughout the course of the simulation.

## **Options**

#### Limits

#### Angular

### X Angle, Y Angle, Z Angle

Enables/disables limit rotation around X, Y or Z axis respectively.

Lower

Lower limit of rotation for X, Y or Z axis respectively.

Upper

Upper limit of rotation for X, Y or Z axis respectively.

#### Linear

#### X Axis, Y Axis, Z Axis

Enables/disables limit translation on X, Y or Z axis respectively.

Lower

Lower limit of translation for X, Y or Z axis respectively.

Upper

Upper limit of translation for X, Y or Z axis respectively.

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