

Stochastic Gradient Methods

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Solving the Finite Sum Training Problem

Recap

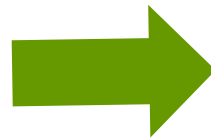
Training Problem

$$\min_{w \in \mathbf{R}^d} \underbrace{\frac{1}{n} \sum_{i=1}^n \ell(h_w(x^i), y^i)}_{L(w)} + \lambda R(w) =: f(w)$$

$L(w)$

General methods

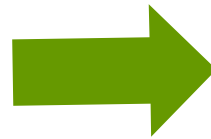
$$\min f(w)$$



- Gradient Descent
- Quasi-Newton
- Conjugate Gradients

Two parts

$$\min L(w) + \lambda R(w)$$



- ISTA
- FISTA

Optimization Sum of Terms

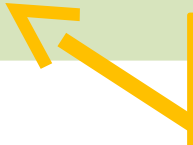
A Datum Function

$$f_i(w) := \ell(h_w(x^i), y^i) + \lambda R(w)$$

$$\begin{aligned} \frac{1}{n} \sum_{i=1}^n \ell(h_w(x^i), y^i) + \lambda R(w) &= \frac{1}{n} \sum_{i=1}^n (\ell(h_w(x^i), y^i) + \lambda R(w)) \\ &= \frac{1}{n} \sum_{i=1}^n f_i(w) \end{aligned}$$

Finite Sum Training Problem

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w) =: f(w)$$



Can we use this
sum structure?

The Training Problem

Solving the *training problem*:

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w)$$

Reference method: Gradient descent

$$\nabla \left(\frac{1}{n} \sum_{i=1}^n f_i(w) \right) = \frac{1}{n} \sum_{i=1}^n \nabla f_i(w)$$

Gradient Descent Algorithm

Set $w^0 = 0$, choose $\alpha > 0$.

for $t = 0, 1, 2, \dots, T - 1$

$$w^{t+1} = w^t - \frac{\alpha}{n} \sum_{i=1}^n \nabla f_i(w^t)$$

Output w^T

The Training Problem

Solving the *training problem*:

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n f_i(w)$$

Problem with Gradient Descent:

Each iteration requires computing a gradient $\nabla f_i(w)$ for each data point. One gradient for each cat on the internet!

Gradient Descent Algorithm

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Stochastic Gradient Descent

Is it possible to design a method that uses only the gradient of a **single** data function $f_i(w)$ at each iteration?

Stochastic Gradient Descent

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Unbiased Estimate

Let j be a random index sampled from $\{1, \dots, n\}$ selected uniformly at random. Then

$$\mathbb{E}_j[\nabla f_j(w)] = \frac{1}{n} \sum_{i=1}^n \nabla f_i(w) = \nabla f(w)$$

Stochastic Gradient Descent

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Use $\nabla f_j(w) \approx \nabla f(w)$



Stochastic Gradient Descent

SGD 0.0 Constant stepsize

Set $w^0 = 0$, choose $\alpha > 0$

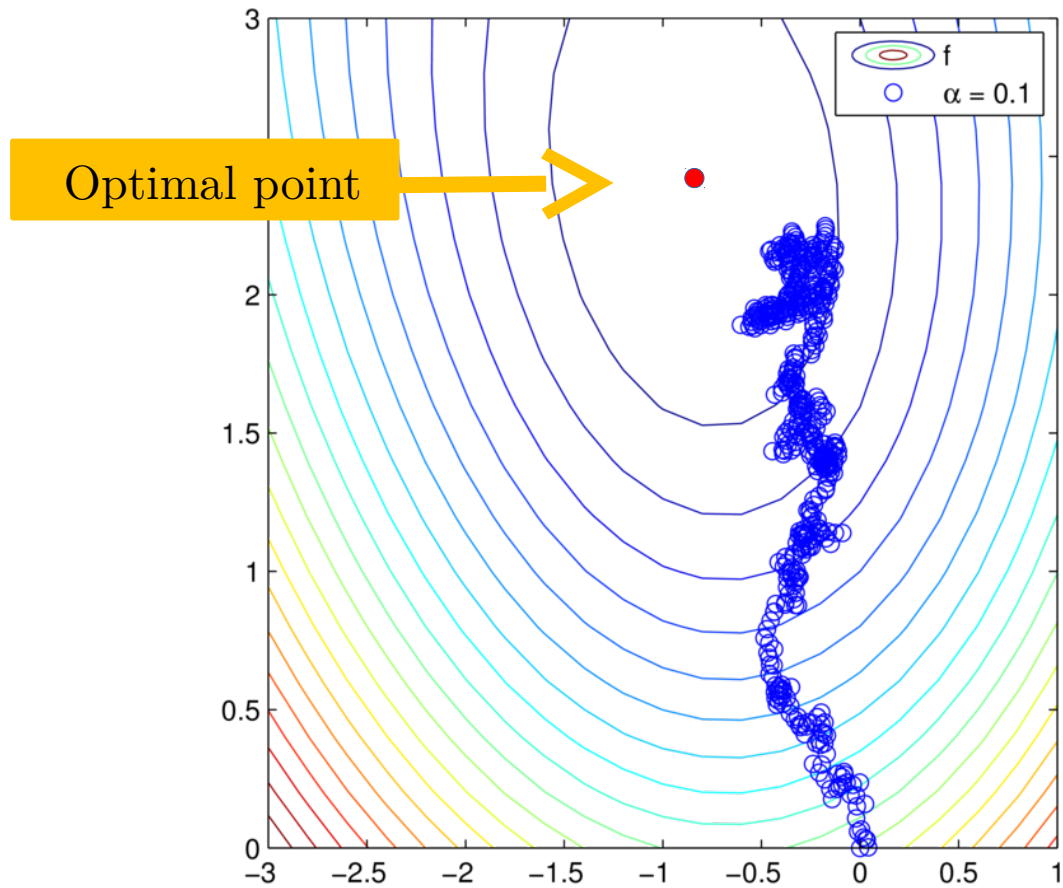
for $t = 0, 1, 2, \dots, T - 1$

 sample $j \in \{1, \dots, n\}$

$$w^{t+1} = w^t - \alpha \nabla f_j(w^t)$$

Output w^T

Stochastic Gradient Descent



Assumptions for Convergence

Strong Convexity

$$f(w) \geq f(y) + \langle \nabla f(y), w - y \rangle + \frac{\lambda}{2} \|w - y\|_2^2$$

$$2\langle \nabla f(w), w - w^* \rangle \geq \lambda \|w - w^*\|_2^2$$

EXE: Using that

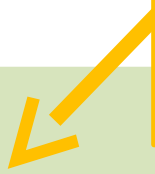
$$\frac{\sigma_{\min}(A)^2}{2} \|w - y\|_2^2 \leq \frac{1}{2} \|A(w - y)\|_2^2$$

Show that

$$\frac{1}{2} \|Aw - b\|_2^2 \geq \frac{1}{2} \|Ay - b\|_2^2 + \langle A^\top (Ay - b), w - y \rangle + \frac{\sigma_{\min}(A)^2}{2} \|w - y\|_2^2$$

Assumptions for Convergence

Often the same as
the regularization
parameter



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Strong convexity
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Strong convexity
parameter!

Expected Bounded Stochastic Gradients

$$\mathbb{E}_j[\|\nabla f_j(w)\|_2^2] \leq B^2, \text{ for all iterates } w^t \text{ of SGD}$$

Complexity / Convergence

Theorem

If $\frac{1}{\lambda} \geq \alpha > 0$ then the iterates of the SGD method satisfy

$$\mathbb{E} [\|w^t - w^*\|_2^2] \leq (1 - \alpha\lambda)^t \|w^0 - w^*\|_2^2 + \frac{\alpha}{\lambda} B^2$$

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Shows that $\alpha \approx \frac{1}{\lambda}$

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Shows that $\alpha \approx \frac{1}{\lambda}$



Shows that $\alpha \approx 0$

Proof:

$$\begin{aligned}\|w^{t+1} - w^*\|_2^2 &= \|w^t - w^* - \alpha \nabla f_j(w^t)\|_2^2 \\ &= \|w^t - w^*\|_2^2 - 2\alpha \langle \nabla f_j(w^t), w^t - w^* \rangle + \alpha^2 \|\nabla f_j(w^t)\|_2^2.\end{aligned}$$

Taking expectation with respect to j

Unbiased estimator

$$\begin{aligned}\mathbb{E}_j [\|w^{t+1} - w^*\|_2^2] &= \|w^t - w^*\|_2^2 - 2\alpha \langle \nabla f(w^t), w^t - w^* \rangle + \alpha^2 \mathbb{E}_j [\|\nabla f_j(w^t)\|_2^2] \\ &\leq \|w^t - w^*\|_2^2 - 2\alpha \langle \nabla f(w^t), w^t - w^* \rangle + \alpha^2 B^2\end{aligned}$$

Strong conv.



$$\leq (1 - \alpha\lambda) \|w^t - w^*\|_2^2 + \alpha^2 B^2$$

Taking total expectation

Bounded
Stoch grad

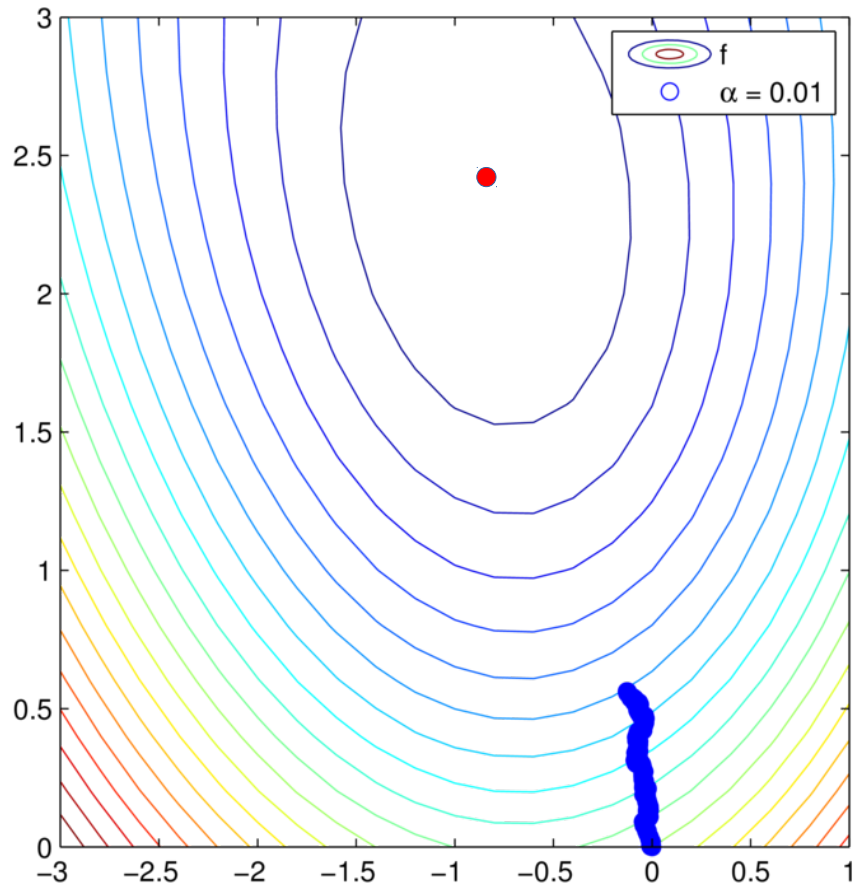
$$\begin{aligned}\mathbb{E} [\|w^{t+1} - w^*\|_2^2] &\leq (1 - \alpha\lambda) \mathbb{E} [\|w^t - w^*\|_2^2] + \alpha^2 B^2 \\ &= (1 - \alpha\lambda)^{t+1} \|w^0 - w^*\|_2^2 + \sum_{i=0}^t (1 - \alpha\lambda)^i \alpha^2 B^2\end{aligned}$$

Using the geometric series sum $\sum_{i=0}^t (1 - \alpha\lambda)^i = \frac{1 - (1 - \alpha\lambda)^{t+1}}{\alpha\lambda} \leq \frac{1}{\alpha\lambda}$

$$\mathbb{E} [\|w^{t+1} - w^*\|_2^2] \leq (1 - \alpha\lambda)^{t+1} \|w^0 - w^*\|_2^2 + \frac{\alpha}{\lambda} B^2$$

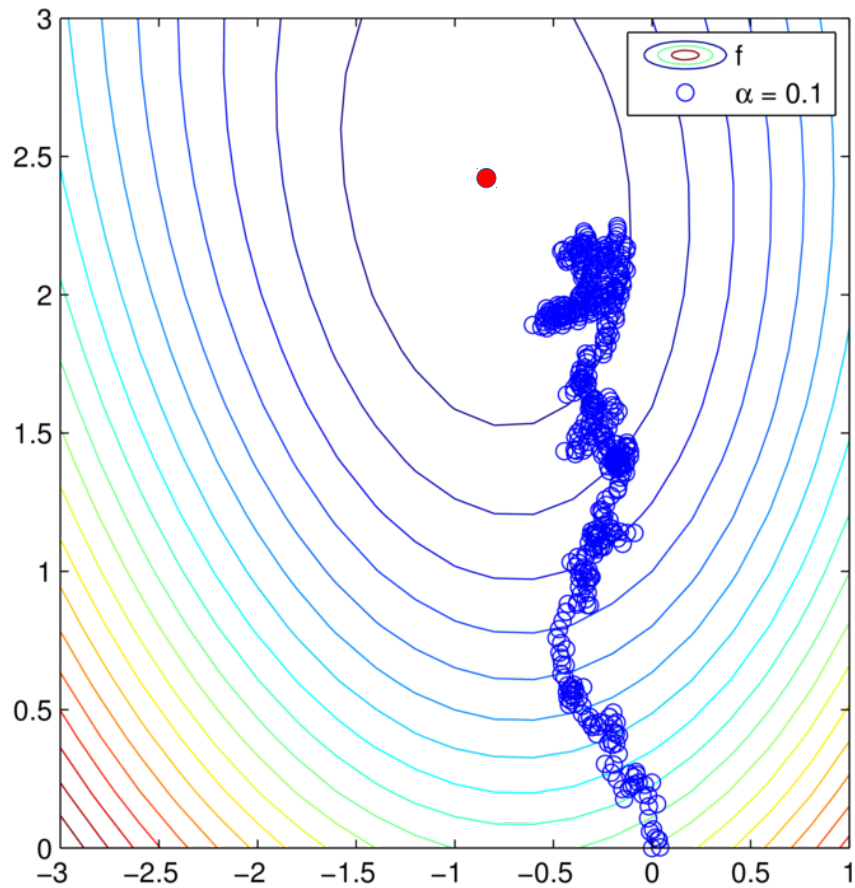
Stochastic Gradient Descent

$\alpha = 0.01$



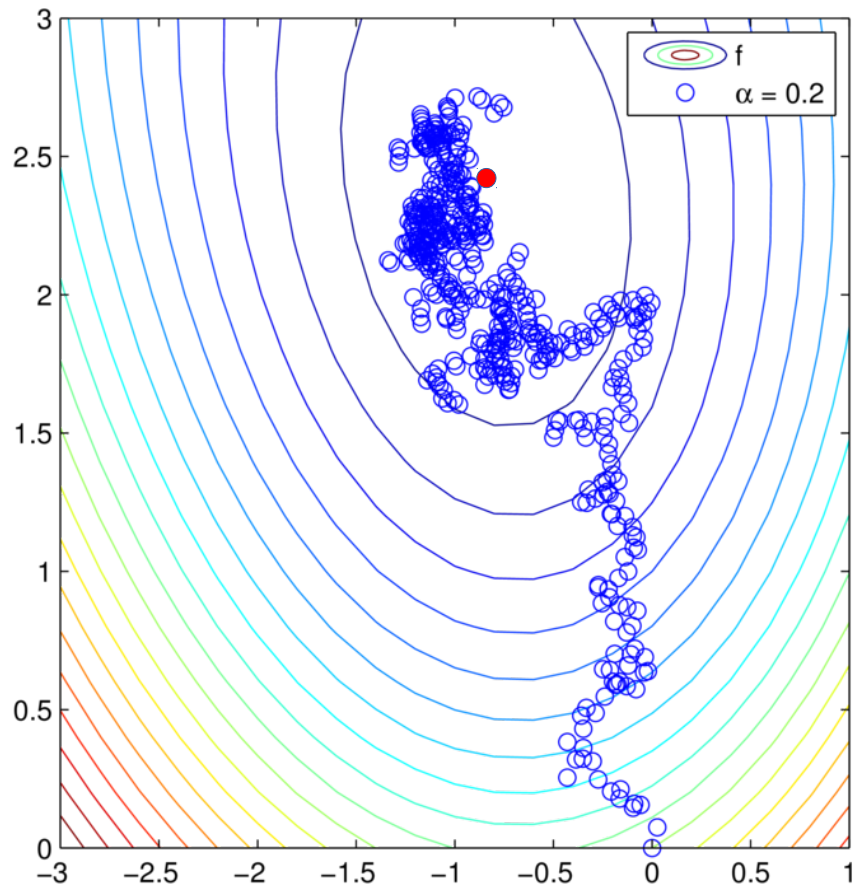
Stochastic Gradient Descent

$\alpha = 0.1$



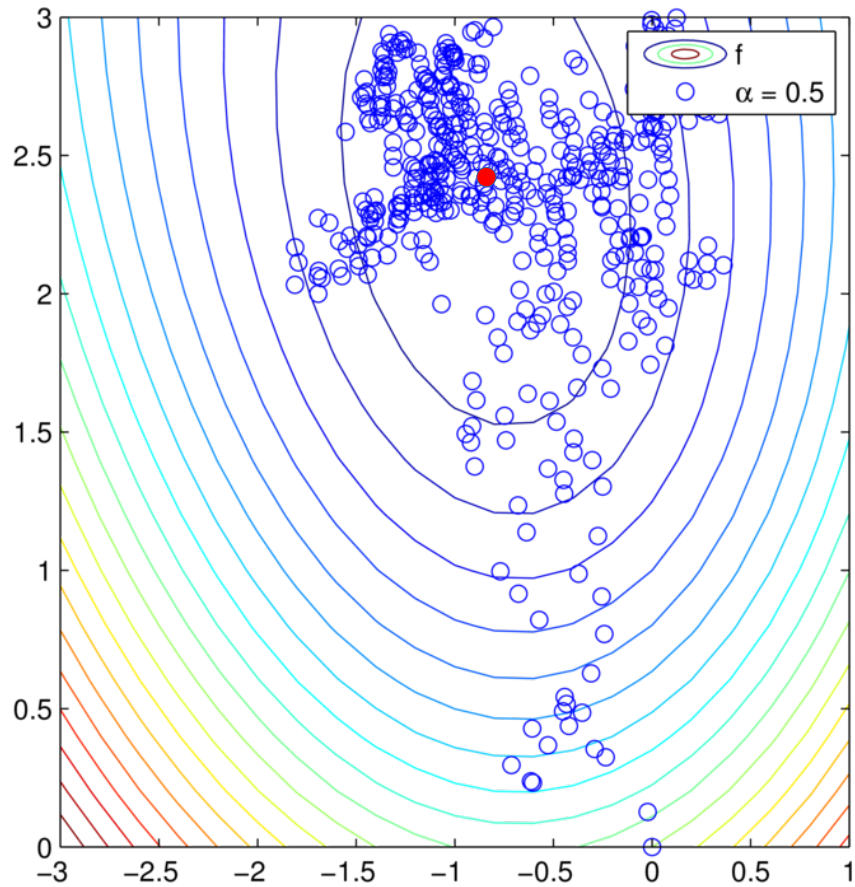
Stochastic Gradient Descent

$\alpha = 0.2$



Stochastic Gradient Descent

$\alpha = 0.5$



SGD shrinking stepsize

SGD 1.0: Decreasing stepsize


Set $w^0 = 0$, choose $\alpha > 0$, $\alpha_t = \frac{\alpha}{\sqrt{t+1}}$,

for $t = 0, 1, 2, \dots, T - 1$

sample $j \in \{1, \dots, n\}$

$$w^{t+1} = w^t - \alpha_t \nabla f_j(w^t)$$

Output w^T



Shrinking
Stepsize

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Shrinking
Stepsize

Shrinking
Stepsize

How should we
sample j ?

Why is $\alpha_t \sim \frac{1}{\sqrt{t}}$?

Does this converge?

SGD Theoretical Properties

Convergence for Convex

- $f(w)$ is convex
- Subgradients bounded

$$\alpha_t = O\left(\frac{1}{\sqrt{t}}\right) \Rightarrow \mathbb{E}[f(w^T)] - f(w^*) = O\left(\frac{1}{\sqrt{T}}\right)$$

Convergence for Strongly Convex

- $f(w)$ is λ - strongly convex
- Subgradients bounded

$$\alpha_t = O\left(\frac{1}{\lambda t}\right) \Rightarrow \mathbb{E}[f(w^T)] - f(w^*) = O\left(\frac{1}{\lambda T}\right)$$

Complexity for Convex

Theorem for SGD 1.1 (Shrinking stepsize)

Let $D = \{x : \|x\| \leq r\}$ and $r \in \mathbb{R}_+$

such that $\|w^*\|_2 \leq r$. If $\alpha_t = \frac{\alpha}{\sqrt{t+1}}$ for $\alpha > 0$ then

$$\mathbb{E}[f(w^T)] - f(w^*) = O\left(\frac{1}{\sqrt{T}}\right)$$

SGD 1.1 for Convex

Set $w^0 = 0$, $\alpha > 0$, $\alpha_t = \frac{\alpha}{\sqrt{t+1}}$,

for $t = 0, 1, 2, \dots, T-1$

sample $j \in \{1, \dots, n\}$

$w^{t+1} = \text{proj}_D(w^t - \alpha_t \nabla f_j(w^t))$

Output w^T

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Let $D = \{x : \|x\| \leq r\}$ and $r \in \mathbb{R}_+$

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$$\mathbb{E}[f(w^T)] - f(w^*) = O\left(\frac{1}{\sqrt{T}}\right) \leftarrow \text{Sublinear convergence}$$

SGD 1.1 for Convex

Set $w^0 = 0$, $\alpha > 0$, $\alpha_t = \frac{\alpha}{\sqrt{t+1}}$,

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sample $j \in \{1, \dots, n\}$

$$w^{t+1} = \text{proj}_D(w^t - \alpha_t \nabla f_j(w^t))$$

Output w^T

Complexity for Strong. Convex

Theorem (Shrinking stepsize)

If $f(w)$ is λ -strongly convex,

and $\alpha_t = \frac{\alpha}{\lambda(t+1)}$ then SGD1.1 satisfies

$$\mathbb{E}[f(w^T)] - f(w^*) = O\left(\frac{1}{\lambda T}\right)$$



Ohad Shamir and Tong Zhang (2013)

International Conference on Machine Learning

**Stochastic Gradient Descent for Non-smooth Optimization:
Convergence Results and Optimal Averaging Schemes.**

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$$\mathbb{E}[f(w^T)] - f(w^*) = O\left(\frac{1}{\lambda T}\right) \quad \leftarrow \text{Faster Sublinear convergence}$$



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Comparison GD and SGD for strongly convex

Approximate solution

$$\mathbb{E}[f(w^T)] - f(w^*) \leq \epsilon$$

SGD

$$O\left(\frac{1}{\lambda\epsilon}\right)$$

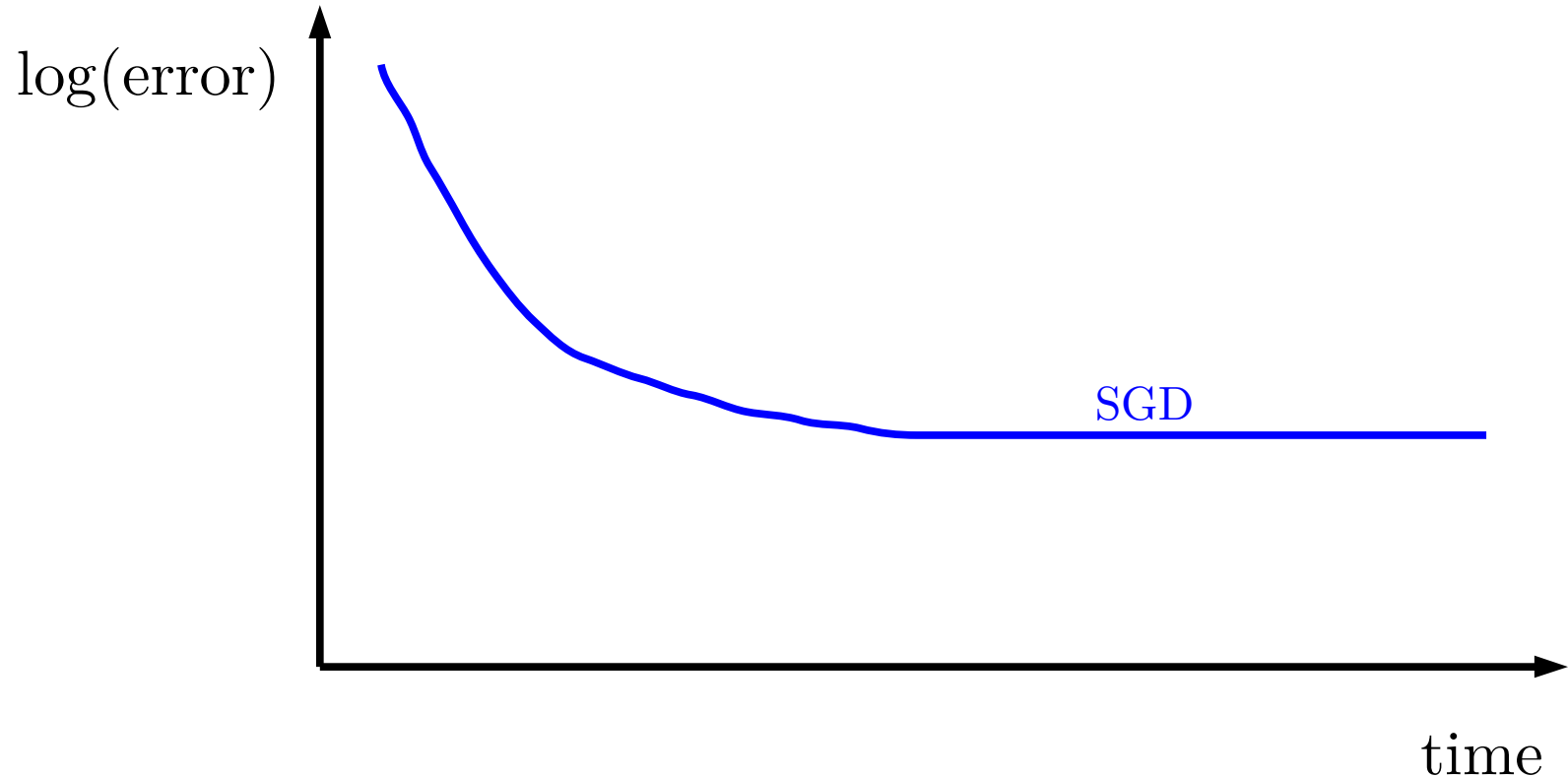
Gradient descent

$$O\left(\frac{nL}{\lambda} \log\left(\frac{1}{\epsilon}\right)\right)$$

What happens
if ϵ is small?

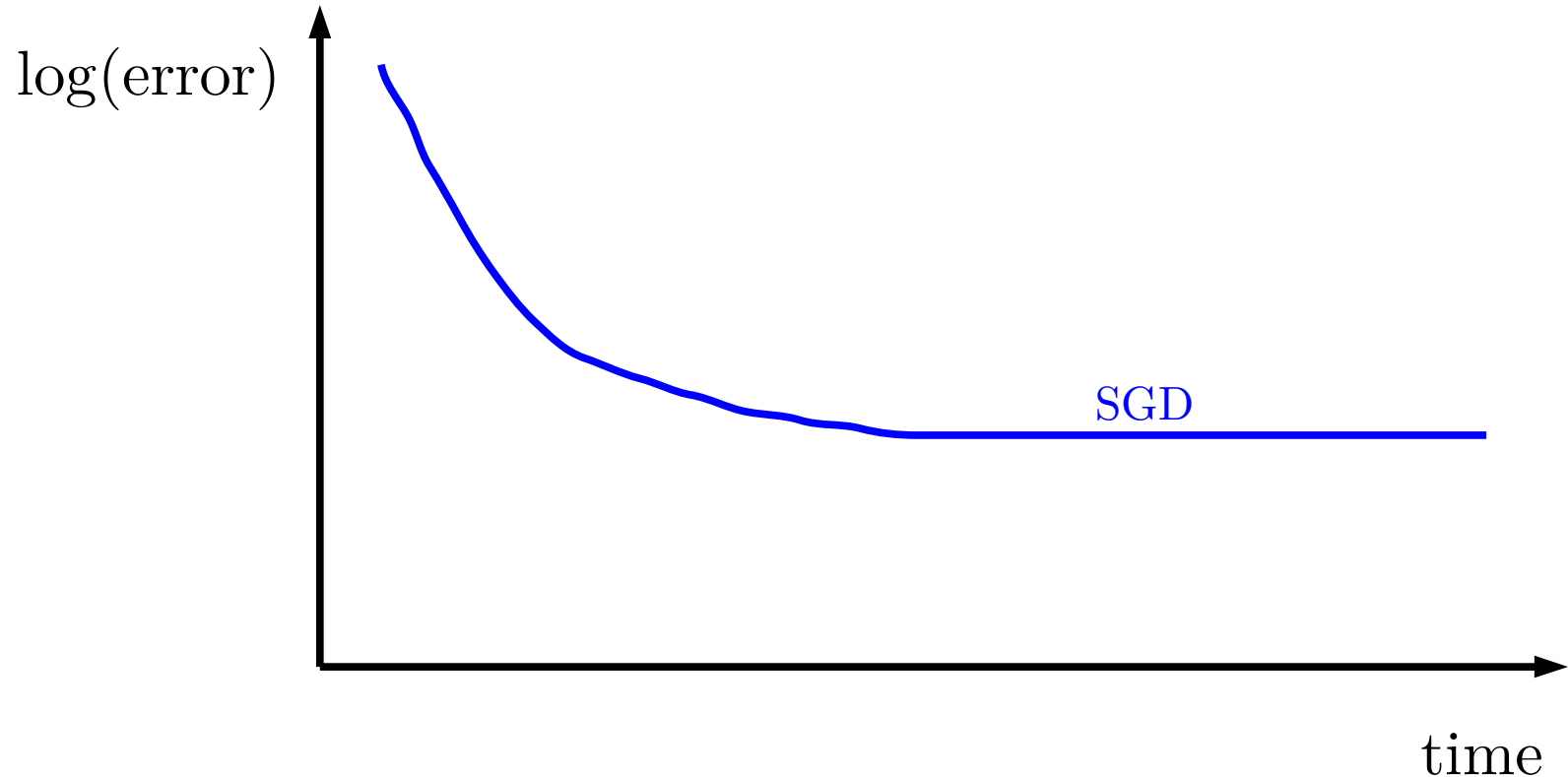
What happens
if n is big?

Comparison SGD vs GD



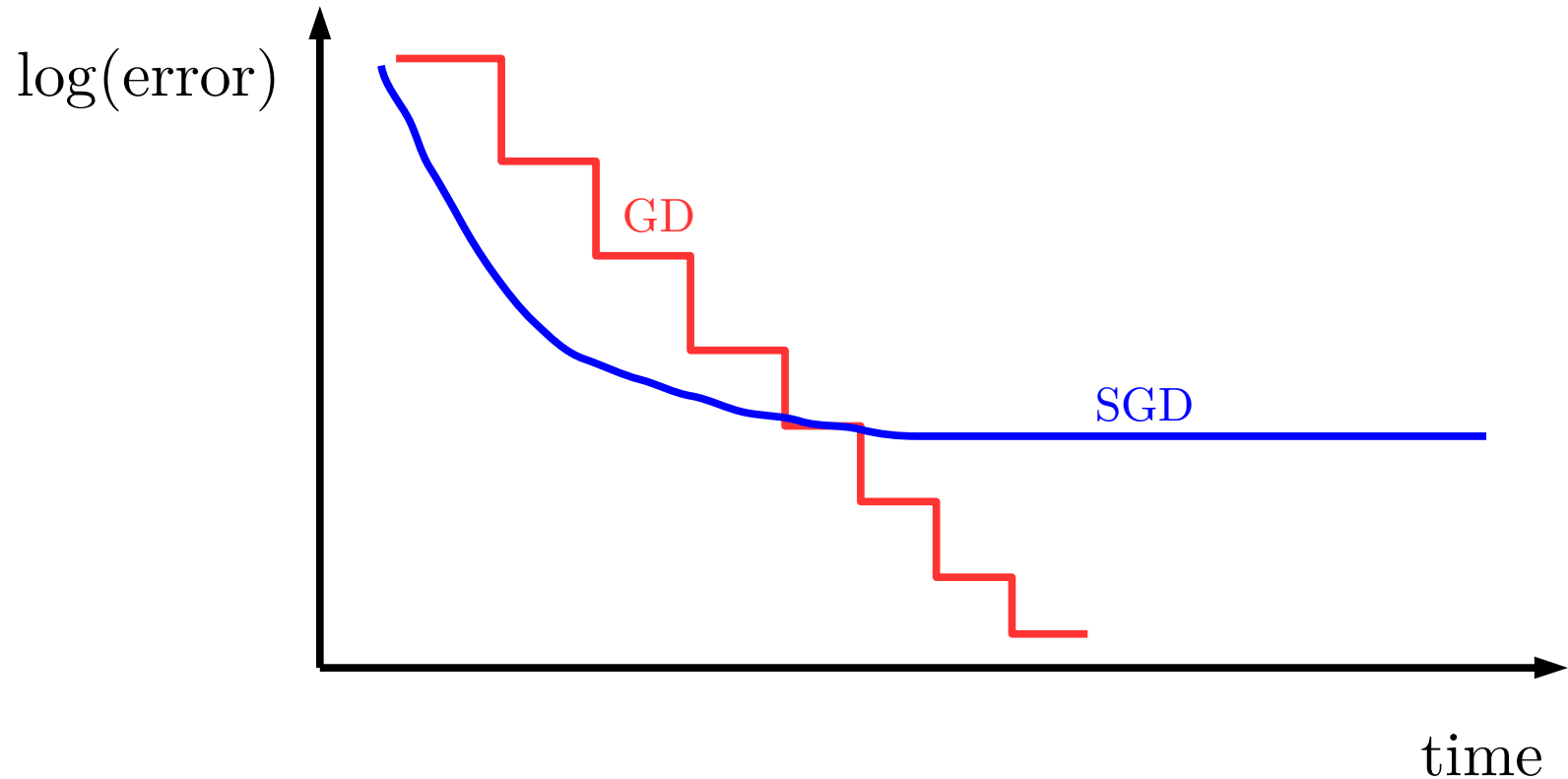
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Mathematical Programming
**Minimizing Finite Sums with the Stochastic Average
Gradient.**

Comparison SGD vs GD



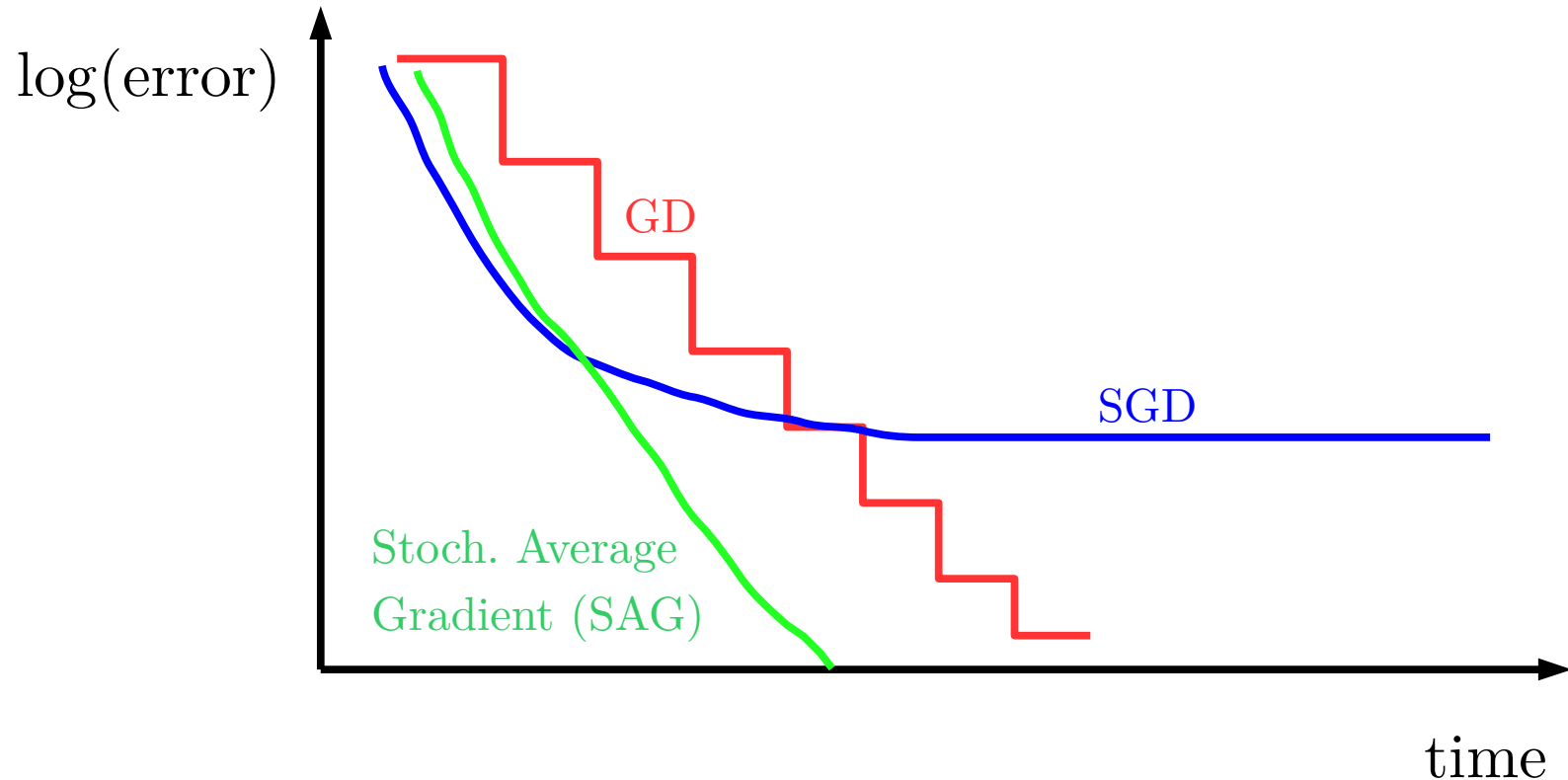
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Why Machine Learners like SGD

Though we solve:

$$\min_{w \in \mathbf{R}^d} \frac{1}{n} \sum_{i=1}^n \ell(h_w(x^i), y^i) + \lambda R(w)$$

We want to solve:

The statistical learning problem:

Minimize the expected loss over an *unknown* expectation

$$\min_{w \in \mathbf{R}^d} \mathbb{E}_{(x,y) \sim \mathcal{D}} [\ell(h_w(x), y)]$$

SGD can solve the
statistical learning problem!

Why Machine Learners like SGD

The statistical learning problem:

Minimize the expected loss over an *unknown* expectation

$$\min_{w \in \mathbf{R}^d} \mathbb{E}_{(x,y) \sim \mathcal{D}} [\ell(h_w(x), y)]$$

SGD $\infty.0$ for learning

Set $w^0 = 0$, $\alpha > 0$

for $t = 0, 1, 2, \dots, T - 1$

sample $(x, y) \sim \mathcal{D}$

calculate $v_t \in \partial \ell(h_{w^t}(x), y)$

$$w^{t+1} = w^t - \alpha v_t$$

$$\text{Output } \bar{w}^T = \frac{1}{T} \sum_{t=1}^T w^t$$

Coding time!

Complexity for Convex SGDA

Theorem for SGD 1.1 (Shrinking stepsize)

Let $\bar{w}^T = \frac{1}{T} \sum_{t=0}^{T-1} w^t$, $D = \{x : \|x\| \leq r\}$ and $r \in \mathbb{R}_+$

such that $\|w^*\|_2 \leq r$. If $\alpha_t = \frac{2r}{B\sqrt{t+1}}$ then

$$\mathbb{E}[f(\bar{w}^T)] - f(w^*) \leq \frac{3rB}{\sqrt{T+1}}$$

SGD 1.1 for Convex

Set $w^0 = 0$, $\alpha_t = \frac{2r}{B\sqrt{t+1}}$,

for $t = 0, 1, 2, \dots, T-1$

sample $j \in \{1, \dots, n\}$

$w^{t+1} = \text{proj}_D(w^t - \alpha_t \nabla f_j(w^t))$

Output \bar{w}^T

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Sublinear
convergence

SGD 1.1 for Convex

Set $w^0 = 0$, $\alpha_t = \frac{2r}{B\sqrt{t+1}}$,

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Output \bar{w}^T

Complexity for Convex SGDA

Theorem (Shrinking stepsize)

If $f(w)$ is λ -strongly convex, $\bar{w}^T = \frac{2}{T(T+1)} \sum_{t=0}^{T-1} tw^t$

and $\alpha_t = \frac{2}{\lambda(t+1)}$ then SGD1.2 satisfies

$$\mathbb{E}[f(\bar{w}^T)] - f(w^*) \leq \frac{2B^2}{\lambda(T+1)}$$

SGD 1.2 for Strongly Convex

Set $w^0 = 0$, $\alpha_t = \frac{2}{\lambda(t+1)}$,

for $t = 0, 1, 2, \dots, T-1$

sample $j \in \{1, \dots, n\}$

$$w^{t+1} = \text{proj}_D (w^t - \alpha_t \nabla f_j(w^t))$$

Output \bar{w}^T

Complexity for Convex SGDA

Theorem (Shrinking stepsize)

If $f(w)$ is λ -strongly convex, $\bar{w}^T = \frac{2}{T(T+1)} \sum_{t=0}^{T-1} tw^t$

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$$\mathbb{E}[f(\bar{w}^T)] - f(w^*) \leq \frac{2B^2}{\lambda(T+1)} < \text{Faster Sublinear convergence}$$

SGD 1.2 for Strongly Convex

Set $w^0 = 0$, $\alpha_t = \frac{2}{\lambda(t+1)}$,

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sample $j \in \{1, \dots, n\}$

$$w^{t+1} = \text{proj}_D(w^t - \alpha_t \nabla f_j(w^t))$$

Output \bar{w}^T