# Microcontroller programming

02 – The basic toolset



## Reading tips

- The keyboard symbol means it's practice time
- Colored text usually carries a meaning:
  - Blue text highlights a new concept or an important lesson to take away
  - Red text highlights a tricky part or a risk of mistake
  - Green text highlights good practices and stuff that is now done
- At the end of each slide deck, you'll find a recap of technologies and concepts



## Agenda

- What's in STM32 Cube?
- Blinking LED
- Hardware corner: GPIO
- The code behind a blinking LED
- Hardware corner: interrupt
- Configuring pins with STM32 CubeMX
- Software corner: C weak symbol





Butterfly sold separately





- What is a development environment for embedded?
- Slightly different than programming for a PC!
- Our needs:
  - Writing code
  - o Compiling code to a program
  - o Storing program on the target hardware
  - Debugging program from the target hardware

- Our needs:
  - Writing code → Text editor on console / GUI
  - Compiling code to a program → Cross-compiler
  - Storing program on the target hardware -> Flasher (for "flashing")
  - Debugging program from the target hardware → Cross-debugger
- Some new terms for you!



- The cross-compiler runs on hardware architecture A, and produces code for hardware architecture B
- A → host
- B → target
  - x86-64 → ARM
  - PowerPC → aarch64 [64-bits ARM]
  - •
- "gcc" is actually a native compiler (A == B)



- Native compilers are not practical for MCUs
- Compiling is very CPU intensive
  - You would wait forever
- Compilers are big
  - You can't even store them on the board!
  - On Alpine Linux gcc binary is 1.7MB large (without dependencies)
  - STM32F429ZIT internal flash is 2MB large



- Compiler examples!
- gcc
  - Implicitly native for your arch (e.g. x86-64 → x86-64)
- arm-none-eabi-gcc
  - Host: your arch
  - Libc: none
  - ABI : Extended ABI
  - Target: ARM (32-bits)
- (The compiler's full name is called a tuple)



#### mips32-musl-eabi-gcc

- Host: your arch
- Libc: musb libc (official website)
- ABI: Extended ABI
- Target: ARM (32-bits)

#### riscv64-glibc-gnueabi-gcc

- Host: your arch
- Libc: GNU C library (the most common one)
- ABI: GNU Extended ABI
- Target: Risc-V 64-bits



- This logic works with gcc but also clang, Keil, Microchip etc.
- You may be asking yourself:
  - Why are there multiple C libraries?
  - What is an ABI?
  - How to choose a cross-compiler?
- We'll answer those questions later ;-)



- The simplest toolset for the ARM course could be:
  - Writing → vim
  - Compiling → arm-none-eabi-gcc
  - Flashing → openocd
  - Debugging → openocd
- All are command-line tools
- All are open-source are require no license



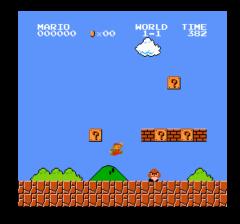
- For ARM course let's use the beginner-friendly STmicro IDE
- The IDE allows not thinking about :
  - Where to get libraries, and which ones? (they require configuration)
  - How to handle board-specific code? (it would requires directly diving into the SMT32F429 reference manual)
  - How to boot my MCU? (specific initialization code would again require precautious study of the STM32F429)
- Let's launch STM32 Cube IDE!



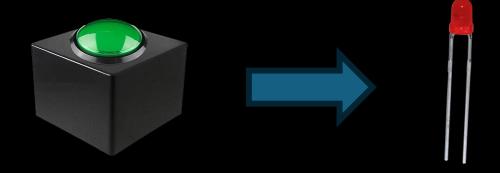
- STM32 Cube IDE is an Eclipse-based IDE, and offers:
  - Text editor
  - C/C++ Compiler
  - Flasher
  - Debugger
  - Board-specific graphical configurator
  - Board-specific code generator
  - Hardware Abstraction Layer (think "library" for now)
  - o Example programs



- Today we'll be doing the "Hello World" of embedded systems...switching a LED when you press a button
- This simple application will require understanding:
  - How STM32 Cube generates code for us
  - What is the generated code's structure
  - o Figuring out why the main loop looks weird







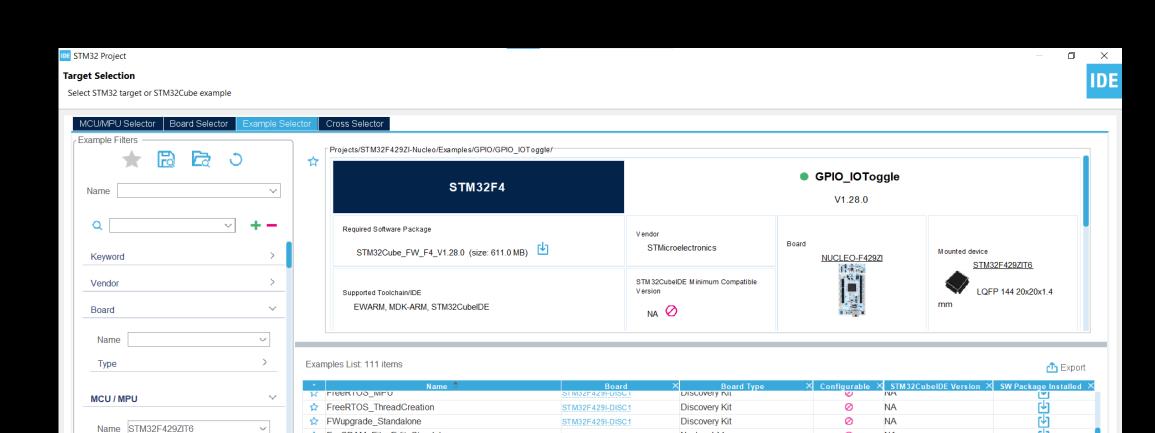
# Blinking LED

Gotta start somewhere

## Blinking LED

- Please open the GPIO\_EXTI project
  - You should already have downloaded it before the course
  - Open gistre26-arm-setup.pdf on Moodle if not!
- Please compile and run the program on the devkit
- Let's take a moment to make sure everyone is up and running
- The following slides offer tips for debugging





☆ Fx\_SRAM\_File\_Edit\_Standalone

☆ HAL\_TimeBase\_RTC\_ALARM

☆ HAL\_TimeBase\_RTC\_ALARM

☆ GPIO\_EXTI

☆ GPIO EXTI

☆ GPIO\_IOToggle

Series

□ Device Configuration Tool capable

P Taper ici pour rechercher

Project

?



NUCLEO-F429ZI

NUCLEO-F429ZI

STM32F429I-DISC1

STM32F429I-DISC1

NUCLEO-F429ZI

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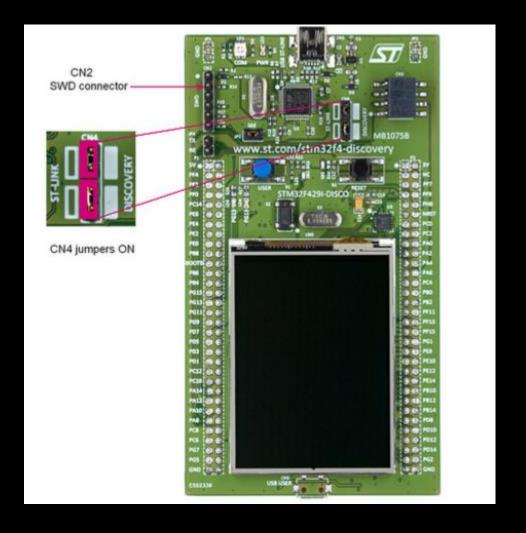
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## Blinking LED

Make sure you've put on jumpers

on *JP3* (1 jumper) and *CN4* (2 jumpers) in order to be able to connect to the board using USB

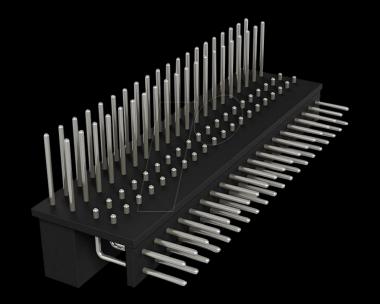




## Blinking LED

- Make sure to upgrade the ST link firmware if asked
- The prompt looks like this:





General Purpose Input/Output

#### **New Hardware: GPIO**

- GPIOs are digital, 1-wire signals
- 1 GPIO means 1 pin
- Can generally be in one of 3 states:
  - Input (reading)
  - Output (writing)
  - Floating (detached)



- GPIOs are used for controlling devices with binary logic
  - Buttons (pressed / not pressed)
  - Lights (on / off)
  - Relays (current flows / current does not flow)
- GPIOs can also be used for manual signal generation







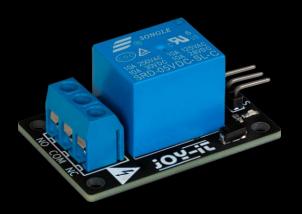


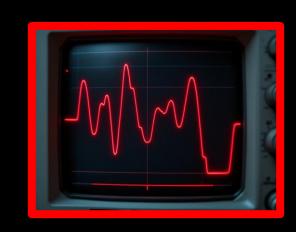


???











- Merci Le Chat (Mistral AI) 😊
- Ceci est un signal analogique qu'il est bien sûr impossible de générer avec une GPIO!





- Programming the GPIO is possible thanks to registers
  - Some register bank is associated with the GPIO
  - The register bank is linked to the CPU through the I/O bus
- As input...
  - Default value can be set (push/pull : pull-up == VREF, pull-down == GND)
  - Default value can also be left floating/tristate which can be required by the facing component's datasheet
  - CPU reads value from register
- As output...
  - CPU writes value to register



- Finally, GPIOs are usually organized in GPIO banks
- "Pin A-3" means GPIO bank A, pin number 3
  - Beware 0-based counting;-)
- Banks are usually powered separately
  - This opens the way to power-efficient designs
- Each GPIO bank has got its register bank
  - Thus each GPIO bank is operated independently



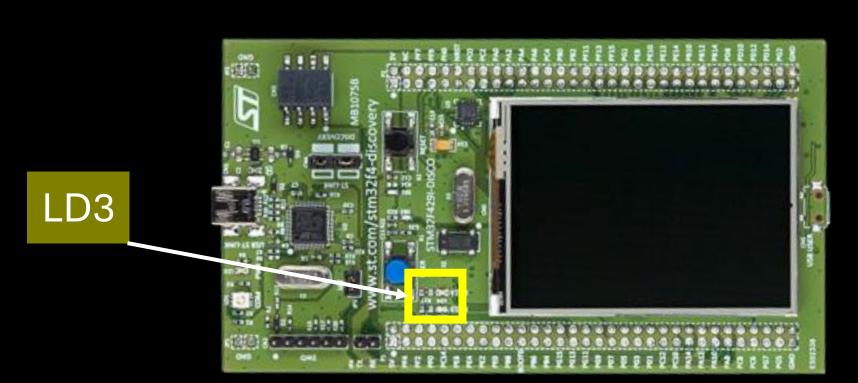
- Let us build an hardware architecture model for the STM32F429I-DISC1 development kit
- During the course, we shall enrich that model
- We begin our architecture study with the green LED
- You will now need to master the documentation needed to get correct information on a microcontroller system
- We begin with the development kit's user manual!



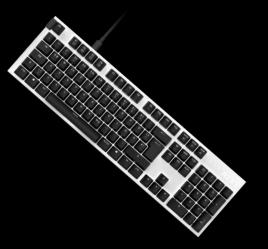
- Find the STM32F429I-DISC1's user manual on st.com
  - Official name: UM1670
  - Target document revision: 5







Find LD3 in the STM32F429I-DISC1 user manual.



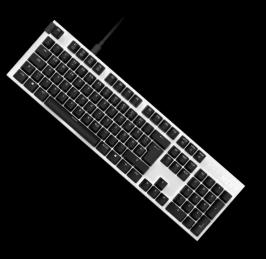
- The development kit's user manual describes hardware information specific to the board
  - LD3 is routed to some GPIO of the MCU
  - Documented by EE (Electronics Engineers) who built the devkit...
  - ...who are not the EE who built the MCU!
- Information specific to the MCU will be found elsewhere
- Different levels of hardware  $\rightarrow$  different documents
- Our low-level treasure trove: the MCU reference manual!



- Find the STM32F429 MCU reference manual on st.com
  - Official name: RM0090
  - Target document revision: 20



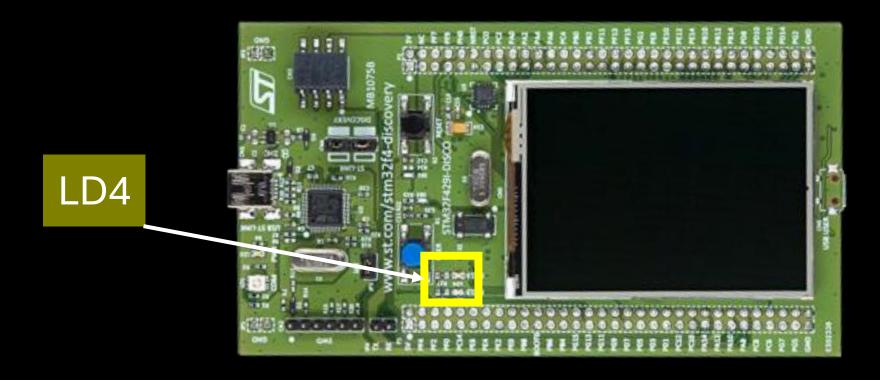
STM32F405/415, STM32F407/417, STM32F427/437 and STM32F429/439 advanced Arm®-based 32-bit MCUs



- Using the two documents in your hands:
  - Find which GPIO bank + pin number is routed to LD3
  - Find which the address in memory of the associated register bank, in the STM32F429 MCU memory system

- Using the two documents in your hands:
  - Find which GPIO bank + pin number is routed to LD3
  - GPIO PG13 → bank G, pin 13 (UM1670 § 6.5)
  - Find which the address in memory of the associated register bank, in the STM32F429 MCU memory system
  - 0x4002\_1800 (RM0090 table 1 "STM32F4xx register boundary addresses")





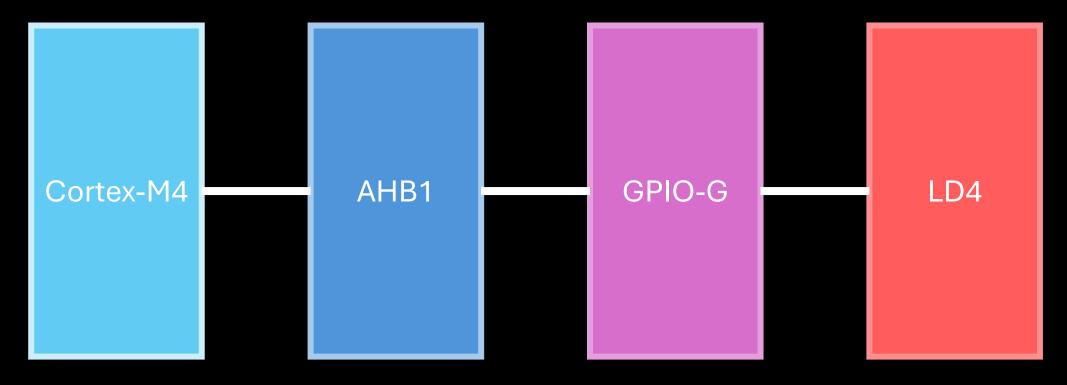
LD3 is actually named PG13 in the STM32F429 documentation So GPIO bank G, pin number 13



- Let us build an architecture model for the STM32F429I-DISC1 development kit
- During the course, we shall enrich that model
- We begin our architecture study with how CPU connects with LD4
- You will now discover the documentation needed to get correct information on a microcontroller system



#### Hardware corner: GPIO



In this data flow diagram, the CPU (Cortex-M4) is connected to the high-speed AHB bus.

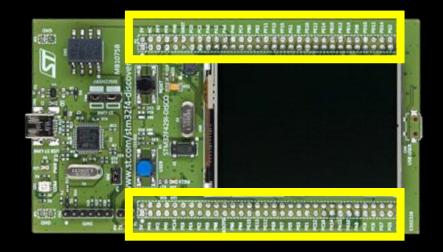
The AHB bus gives access to many peripherals, including GPIO banks.

The GPIO bank G controls several pins.

Pin 13 is physically soldered to LD4.

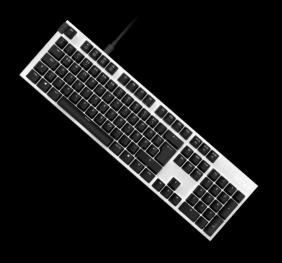


- The pins headers on your devkit are not necessarily GPIOs
- In fact, each pin of the MCU has a fixed set of functions it can be dynamically associated to ("GPIO" is one function)
- To know which pin can do what, you have to figure it the pin number in the general pin numbering scheme





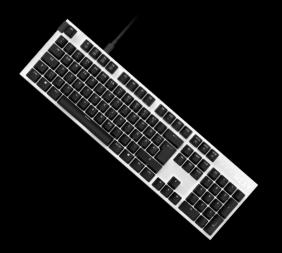
- What document can explain MCU pin numbering?
- What is the pin number of PG13?





- What document can explain MCU pin numbering?
- What is the pin number of PG13?
- UM1670 table 7 (repeats pin # information)

Table 7. STM32 pin description versus board functions (continued)																					
	STM32 pin		Board functions																		
	Main function	LQFP144	System	VCP	SDRAM	LCD-TFT	LCD-RGB	ICD-SPI	13G4250D	USB	ΓED	Push-button	I <sup>2</sup> C Ext	Touch panel	Free I/O	Power supply	CN2	CN3	CN6	2	P2
-	PG13	128	-	-	-	-	-	-	-	-	Green	-	-	-	-	-	-	-	-	29	-





Like a layered cake



- As software developers, we should consider each piece of hardware as a new library to learn
- In fact, hardware manufacturers provide libraries to make our life easier → the Hardware Abstraction Layer
- The HAL is, by definition, specific to the target hardware
- In this course we're studying STM32F429 HAL

- Let's read the GPIO\_EXTI project structure...
- Application code :
  - Main function in Example/User/main.c (feel free to modify!)
- MCU initialization :
  - Hardware initialization code in Example/Startup/\* (shouldn't touch)
- Libraries & drivers :
  - Hardware Abstraction Layer in *Drivers/STMF4xx\_HAL\_Driver/* (vendor API)
  - CMSIS layer in *Drivers/CMSIS/\** (you can ignore)
  - STM32F429-Disco high-level layer in *Drivers/BSP/\** (vendor API)

- - > 🐉 Binaries
  - → 🔊 Includes
  - > 🗁 Debug
  - > 🗁 Doc
  - Drivers
    - > 🗁 BSP
    - > 🗁 CMSIS
    - - > kstm32f4xx\_hal\_cortex.c
      - > 🗟 stm32f4xx\_hal\_dma.c
      - > 🗟 stm32f4xx\_hal\_flash\_ex.c
      - k stm32f4xx\_hal\_flash.c
      - > kg stm32f4xx\_hal\_gpio.c
      - > k stm32f4xx\_hal\_i2c\_ex.c
      - > k stm32f4xx\_hal\_i2c.c
      - > 🗟 stm32f4xx\_hal\_pwr\_ex.c
      - > 🖟 stm32f4xx\_hal\_pwr.c
      - > R stm32f4xx\_hal\_rcc\_ex.c
      - > k stm32f4xx\_hal\_rcc.c
      - > 🖟 stm32f4xx\_hal\_spi.c
      - > 🖟 stm32f4xx hal.c
  - 🗸 🗁 Example
    - Startup
      - startup\_stm32f429zitx.s
    - User
      - > 🖳 main.c
      - > 🖳 stm32f4xx\_it.c
      - > 🖻 syscalls.c
      - > 🖻 sysmem.c
    - GPIO\_EXTI Debug.launch
    - STM32F429ZITX\_FLASH.Id



- All this code has been generated for us...why?
- This is a good occasion to build a software architecture model
- Here, we'll draw a layer diagram to focus on dependencies
- This will not be a . h include tree

GPIO\_EXTI app

STM32F429I Discovery BSP

STM32F429 HAL GPIO

GPIO\_EXTI software architecture, layered view. This simplified view focuses on GPIO control.

The app (the main() function) sits on a vendor "BSP" library.

The BSP sits on the STM32F429 HAL.

The HAL knows what registers to control, and their addresses.



GPIO\_EXTI app

```
/* Toggle LED3 */
BSP_LED_Toggle(LED3);
```

#### STM32F429I Discovery BSP

```
226 void BSP_LED_Toggle(Led_TypeDef Led)
227 {
228 HAL_GPIO_TogglePin(GPIO_PORT[Led], GPIO_PIN[Led]);
229 }
```

#### STM32F429 HAL GPIO

IIM32F429 HAL GPIO

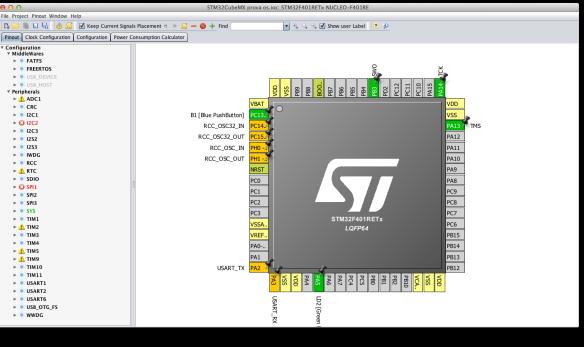
Only the HAL knows about registers (ODR, BSRR...)

```
433@ void HAL_GPIO_TogglePin(GPIO_TypeDef* GPIOx, uint16_t GPIO_Pin)
434
      uint32 t odr;
435
436
      /* Check the parameters */
437
438
      assert param(IS GPIO PIN(GPIO Pin));
439
      /* get current Output Data Register value */
440
441
      odr = GPIOx -> ODR;
442
443
      /* Set selected pins that were at low level, and reset ones that were high */
444
      GPIOx->BSRR = ((odr & GPIO_Pin) << GPIO_NUMBER) | (~odr & GPIO_Pin);
445 }
```

- Looks like the BSP layer just adds symbolic names
  - We should throw it away!
- The HAL is really useful
  - Practical software engineering for MCUs use the HAL
  - Developers build hardware-agnostic libraries on top of that
- Could we have controlled the GPIO by hand?
- Let's recode this app ourselves

# Configuring pins Config

Graphical bonanza

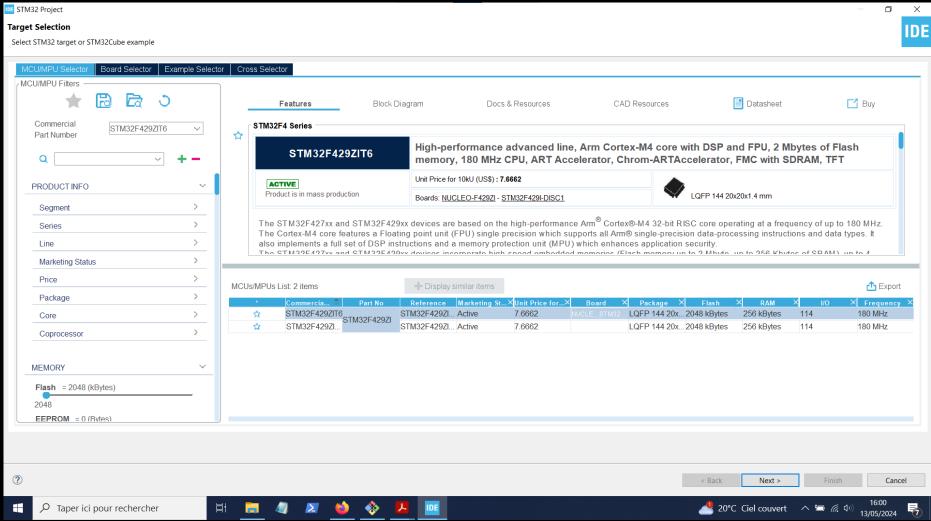


- We're going to do the same blinking code but ourselves, without premade code
- Let's create a new STM32 project again, but this time go to the MCU Selector and find our STM32F429 reference
- Don't go to example projects

- You'll find the following variants:
  - STM32F429ZIT6
  - STM32F429ZIT6TR
  - STM32F429ZIT7
- We wanted "STM32F429ZIT6U"...
  - Can we still use one of these variants?

- You'll find the following variants:
  - STM32F429ZIT6
  - STM32F429ZIT6TR
  - STM32F429ZIT7
- Any one of these is fine!
  - Recall MCU datasheet § 8 "Part numbering": 6 is chip temperature range, and "TR" indicate chip is packaged in tape and reel format
  - Let's pick STM32F429ZIT6





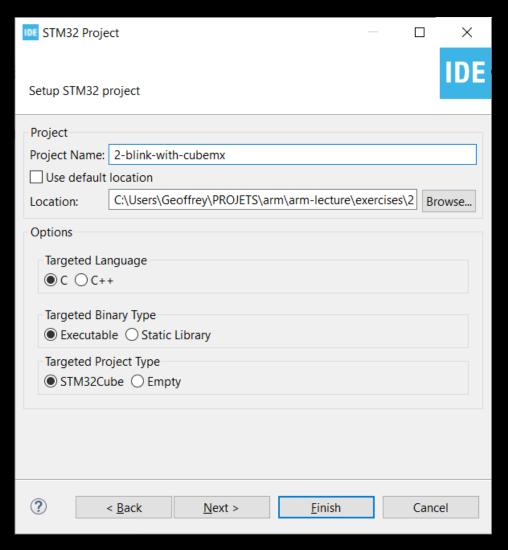
Create a new STM32 project.

Make sure to check

"STM32Cube" as Target Project

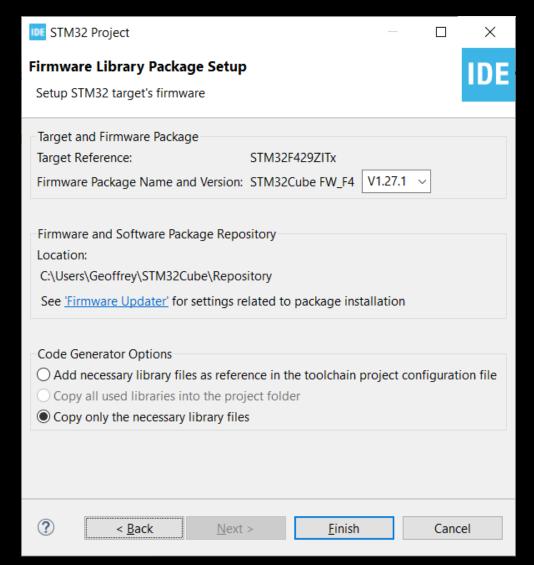
Type to get the CubeMX
environment.

We'll use it to configure GPIOs using a GUI.

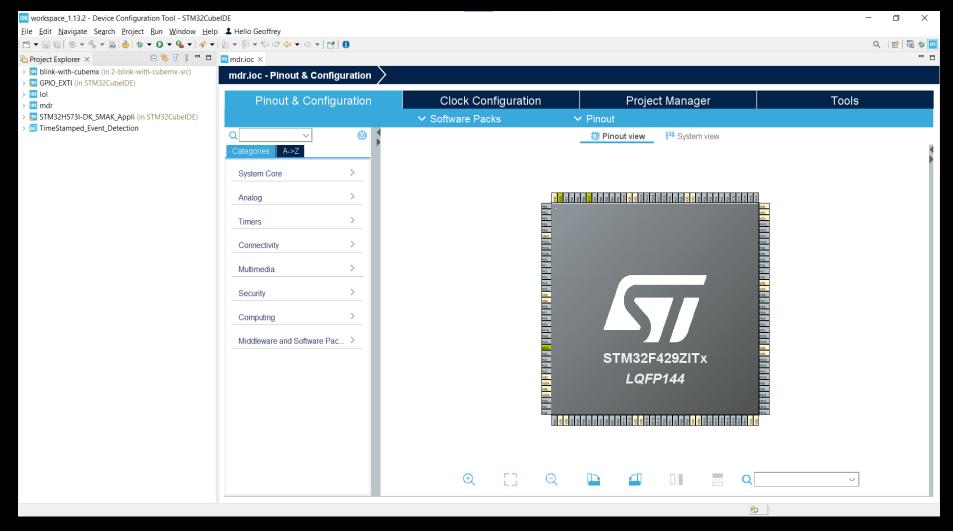


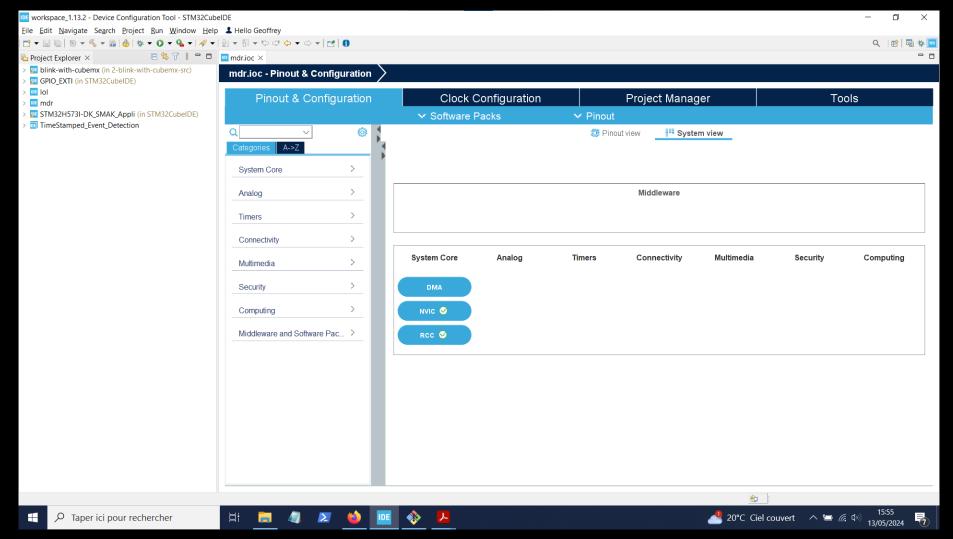


"Initialize peripherals to default?" ==> Yes





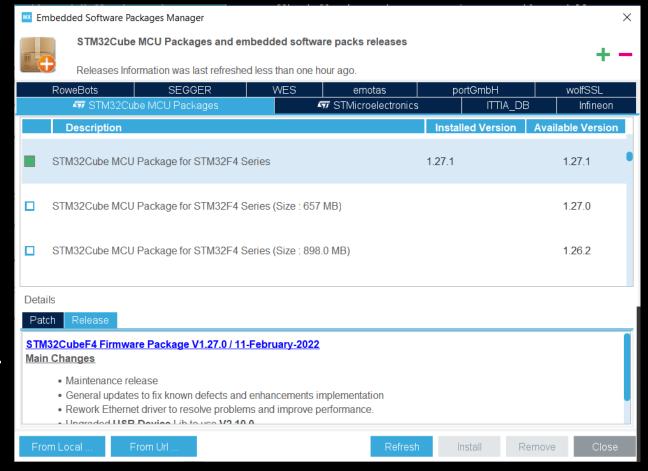




Clicking on « Software Packs » shows that we have installed STM32CubeF4 package.

#### It contains:

- HAL
- Code generator
- Some of the GUI's « backend »





- Build and run default code
- LED does not react to button press: this project only initializes (prepare use of) peripherals but does not change their state
- Compare the code to the previous example
  - What has been added? Removed?
  - O What missing logic do we need to code?

- We have to code two things:
  - 1. Lighting on/off the LED (LED3)
  - 2. Reacting to button press (USER)
- You can get inspiration from previous code
- Don't forget the STM32F4 HAL reference manual for details



EPITA LED blinking app

STM32F429 HAL GPIO

Manual LED blinking target software architecture

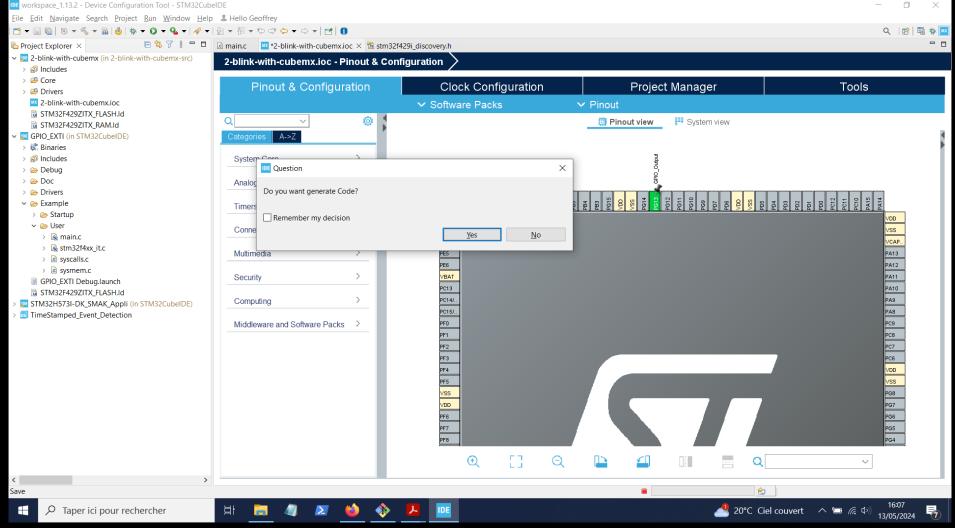




Let's start with the LED

- Go to "Pinout & Configuration" (if needed, reopen .ioc file) and configure the pin behind LED3 as a GPIO output
- 2. Regenerate code
- 3. Code gistre\_led\_turnon() and gistre\_led\_turnoff() functions
- 4. Turn on the LED at program startup





- Cool, we can light up a LED!
- And we got rid of ST's BSP code...
- Find the exercise with commented code on Moodle
- Now we need to program the button
- We'll see that in the next chapter!

#### In the next chapter

- New hardware feature: interrupts
- Input GPIO configuration using STM32 CubeIDE
- More about the STM32 HAL, and C weak symbols!

- Until then:
  - Read full code of GPIO\_EXTI
  - Read § 2.1 / 2.2 / 2.3 of RM0090 (global system architecture)
  - Read § 8.1 / 8.2 / 8.4 of RM0090 (GPIO features + registers)



#### Quick recap



#### <u>Technologies:</u>

- arm-none-eabi-gcc
- openocd

#### **Concepts:**

- Cross-compiler
- Cross-debugger
- Flasher
- Hardware Abstraction Layer
- Host (when compiling)
- Native compiler
- Reference manual (for a MCU)
- Register bank



## Quick recap





#### Concepts:

- Target (when compiling)
- Tuple (full compiler name)
- User manual (for a devkit)

