

FUNCTION OF SEVERAL VARIABLES

SESSION 1

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Themes :

- SURFACES AND LEVEL SETS
- LIMITS AND CONTINUITY
- THE PARTIAL DERIVATIVE
- TANGENT PLANE AND LINEAR APPROXIMATIONS

SURFACES AND LEVEL SETS

- We can define a **2D surface** within a (euclidian) 3D space by an equation of the form

$$z = f(x, y) \quad \text{or} \quad 0 = F(x, y, z)$$

- To study more finely and systematically such surface we can use the concept of **level set** defined by the equation

$$c = f(x, y)$$

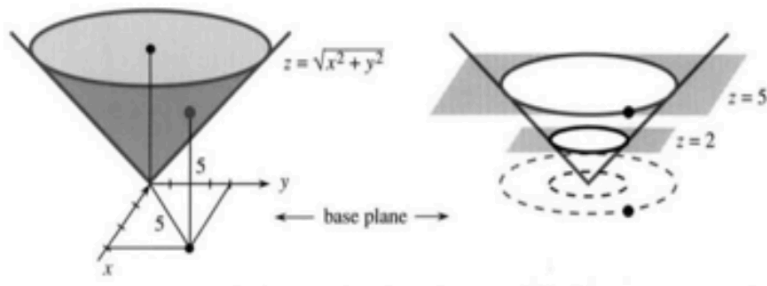


Figure – The surface for $z = f(x, y) = \sqrt{x^2 + y^2}$ is a cone. The level lines (or curves) are circles.

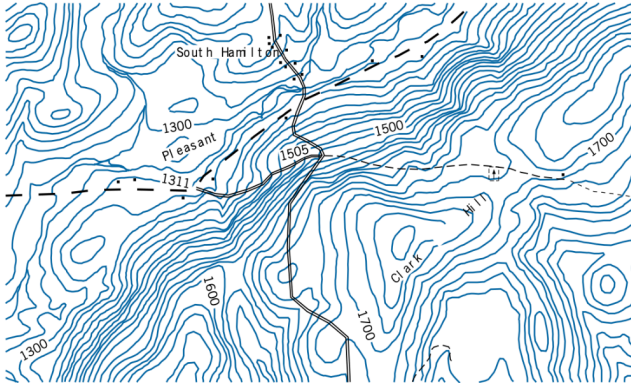


Figure – Topological map of the region located around the town of South Hamilton in New York state (US).

LIMITS AND CONTINUITY

- Limit of a two variables functions

- New : We use the notion of **disk** δ to define the *neighbourhood* of a point $\mathbf{a} = (a, b)$ corresponding to the set

$$\{\mathbf{x} \in \mathbb{R}^2 \mid \|\mathbf{x} - \mathbf{a}\| < \delta\}$$

- From that we can establish a **first definition** of the limit allowing to build fundamental (expected) **properties** (sum, multiplication, etc..).
- A important difference, with respect to the 1D case, is that you can now approach a point via **several directions** (an infinity in fact...)

- Interior points and boundary points

- Problem : the notion of disk is not **not adapted** when we evaluate the limit of a function on its boundary...
- Indeed, some points of the disk might not belong to the **domain** of the function $f(x, y)$.
- In this case, we propose an **improved definition** so that all the points of the disk belong to the domain of $f(x, y)$.

- Continuity for functions of two variables

- Once the notion of limit properly defined, we can easily **generalise** the definition of continuity to higher dimensions, to wit, if $f(\mathbf{x})$ is continuous at \mathbf{x}_0 :

(1) $f(\mathbf{x}_0)$ exists

(2) $\lim_{\mathbf{x} \rightarrow \mathbf{x}_0} f(\mathbf{x})$ exists

(3) $\lim_{\mathbf{x} \rightarrow \mathbf{x}_0} f(\mathbf{x}) = f(\mathbf{x}_0)$

- Following this, the usual (expected) **properties** (sum, product, composition) are insured.

- Functions of three variables and more

- The passage to higher dimensions \mathbb{R}^n is easily done by generalising the concept of disk to a **ball** :

$$\{\mathbf{x} \in \mathbb{R}^n \mid \|\mathbf{x} - \mathbf{a}\| < \delta\}$$

with a euclidean norm (for instance) given by

$$\|\mathbf{x} - \mathbf{a}\| = \sqrt{\sum_{i=1}^n (x_i - a_i)^2}$$

- Several **norms** exist and allow to define a «distance» between two elements belonging to a given space depending on our needs...
- The definitions and concepts that follow stay unchanged !

THE PARTIAL DERIVATIVE

- The essential : for a function $f(x, y)$, we compute

$$\frac{\partial f}{\partial x} = f_x \quad \text{or} \quad \frac{\partial f}{\partial y} = f_y$$

by considering the other variables, with respect to which we do not differentiate, as **constants**.

- Similarly to the on variable case, partial derivatives give informations on **variations** on the surface

$$z = f(x, y)$$

in directions parallel to the axes Ox and Oy .

- We can also simply use the **partial functions**

$$f(x, y_0) \quad \text{or} \quad f(x_0, y)$$

to study the surface $z = f(x, y)$ in a given direction, parallel to $x = x_0$ or $y = y_0$.

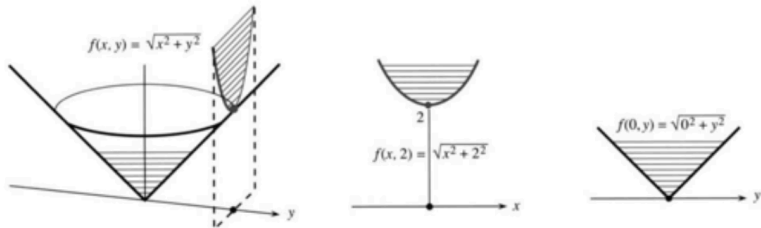


Figure – Partial functions $\sqrt{x^2 + 2^2}$ et $\sqrt{0^2 + y^2}$ of the distance function $f = \sqrt{x^2 + y^2}$.

- New : A **saddle point** configuration is possible if

$$f_x = f_y = 0$$

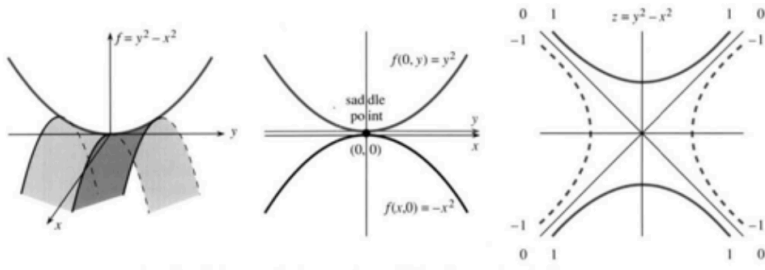


Figure – The function $f = y^2 - x^2$ showing a saddle point, its partial functions and its level sets.

- For a function of two variables $f(x, y)$ we compute four(!) partial **second derivatives**

$$f_{xx} = \frac{\partial^2 f}{\partial x^2} \quad , \quad f_{xy} = \frac{\partial^2 f}{\partial x \partial y} \quad , \quad f_{yx} = \frac{\partial^2 f}{\partial y \partial x} \quad , \quad f_{yy} = \frac{\partial^2 f}{\partial y^2}$$

- Luckily, if these second derivatives are **continuous** (true most of the time in usual applications) we have

$$f_{xy} = f_{yx}$$

also called the **Schwarz theorem**.

- The matrix of second derivatives is called the **Hessian**

$$\mathbf{H} = \begin{pmatrix} f_{xx} & f_{xy} \\ f_{yx} & f_{yy} \end{pmatrix}$$

TANGENT PLANE AND LINEAR APPROXIMATIONS

- We can approximate an arbitrary surface, of equation $z = f(x, y)$, **locally** by a plane, at the base point (x_0, y_0) , given by

$$z - z_0 = \left(\frac{\partial f}{\partial x} \right)_0 (x - x_0) + \left(\frac{\partial f}{\partial y} \right)_0 (y - y_0)$$

- We can define a **normal vector** to this plane (and to the surface at the point (x_0, y_0)) by

$$\mathbf{N} = \begin{pmatrix} (f_x)_0 \\ (f_y)_0 \\ -1 \end{pmatrix}$$

It is oriented **towards the exterior** for a closed surface.

- If the surface is given by an equation of the form $c = F(x, y, z)$, where c is a constant, then the equation of the **tangent plane** becomes

$$\left(\frac{\partial F}{\partial x}\right)_0 (x - x_0) + \left(\frac{\partial F}{\partial y}\right)_0 (y - y_0) + \left(\frac{\partial F}{\partial z}\right)_0 (z - z_0) = 0$$

- The **normal vector** becomes then

$$\mathbf{N} = \begin{pmatrix} (F_x)_0 \\ (F_y)_0 \\ (F_z)_0 \end{pmatrix}$$

- We remark that by setting $f = F - z$ we can recover the previous formula.

- If we write the following equivalences (for small variations)

$$z - z_0 \approx dz = df \quad , \quad y - y_0 \approx dy \quad , \quad x - x_0 \approx dx$$

in the equation of the tangent plane $z = f(x, y)$, we recover the **differential** of f , to wit

$$df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy$$

- Here an **infinitesimal variation** of f is expressed (linearly) in terms of the (infinitesimal) variations of its parameters x et y .

- By resetting $df = f(x, y) - f(x_0, y_0)$, we can construct the **linear approximation** of f at the point (x_0, y_0)

$$f(x, y) \approx f(x_0, y_0) + \left(\frac{\partial f}{\partial x} \right)_0 (x - x_0) + \left(\frac{\partial f}{\partial y} \right)_0 (y - y_0)$$

- The quadratic terms, i.e proportional to $(x - x_0)^2$ and $(y - y_0)^2$ are here **neglected** because (a priori) **smaller** than $(x - x_0)$ and $(y - y_0)$ not far from (x_0, y_0) .
- The approximation becomes more and more **incorrect** as we are getting further from (x_0, y_0) .