GPU Computing

Patterns for massively parallel programming (part 2)

Histograms

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Lab reminder

Mandelbrot practice session

During the practice session, you will have had to compute the cumulated histogram of the image.

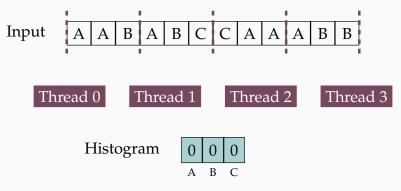
There are two major steps:

- 1. Compute the histogram H: count the number of occurrences of each value within the image.
- 2. Compute the cumulated histogram C: sum histogram values such that $C[i] = \sum_{k=0}^{i} H[k]$.

We will see how to compute those elements with efficient parallel algorithms.

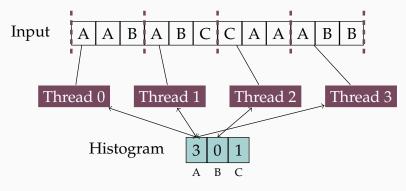
Simple parallel histogram

A wrong approach consists in **sectioning** the input, i.e. assigning a chunk of the input to each thread.



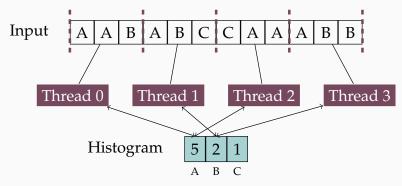
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What is the issue?

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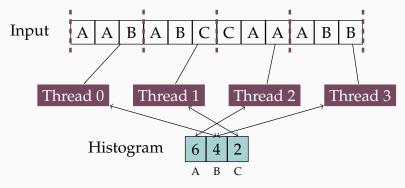


What is the issue?

Inefficient, non-coalesced memory access.

- · Does not leverage cache
- · Does not make use of full RAM burst

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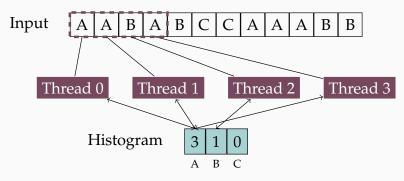
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Interleaved partitioning of input

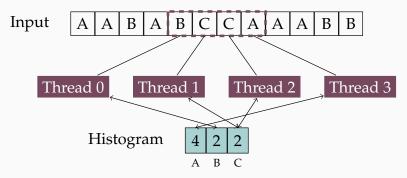
This enables coalesced memory accesses.



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Interleaved partitioning of input

This enables coalesced memory accesses.



Much more efficient, coalesced memory access.

- · All threads process a contiguous secion of elements
- They all move to the next section and repeat

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First code sample

```
__global__ void histo(int* buf, int w, int h, int pitch, int hist_size, int* hist)
{
  int x = blockDim.x * blockIdx.x + threadIdx.x;
  int y = blockDim.y * blockIdx.y + threadIdx.y;
  if (x >= w || y >= h) return;
  int cellValue = getValue(buf, x, y, pitch);
  hist[cellValue]++; // This is wrong!
}
```

What is the issue?

First code sample

Data racel

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}
What is the issue?
```

A correct naive version

```
__global__ void histo(int* buf, int w, int h, int pitch, int hist_size, int* hist)
{
  int x = blockDim.x * blockIdx.x + threadIdx.x;
  int y = blockDim.y * blockIdx.y + threadIdx.y;
  if (x >= w || y >= h) return;
  int cellValue = getValue(buf, x, y, pitch);
  atomicAdd(&(hist[cellValue]), 1);
}
```

Parallel algorithm using output privatization

Reminder about output privatization

A simple solution called **"output privatization"** works by proceeding in two steps:

- 1. compute a local histogram for each block in shared memory cost to read and write: 1 cycle each
- 2. at the end of the block, flush each local histogram to global memory

Local histogram: initialization

Shared memory must be initialized.

This can be done with the "comb-like" pattern.

```
__global__ void histo(int* buf, int w, int h, int pitch, int hist_size, int* hist)
 extern shared int localHist[];
 // linear thread id and block dim to init the 1D histogram
 int i = blockDim.x * threadIdx.y + threadIdx.x;
 int bs = blockDim.x * blockDim.y;
 for (; i < hist_size; i+=bs)</pre>
   localHist[i] = 0:
 // Wait for all block's threads before next stage
 __syncthreads();
```

Warning: we need synchronization after this stage.

Local histogram: computation

Like previous code, but with local atomics!

```
__global__ void histo(int* buf, int w, int h, int pitch, int hist_size, int* hist)
 // ...
  int x = blockDim.x * blockIdx.x + threadIdx.x;
  int y = blockDim.y * blockIdx.y + threadIdx.y;
  if (x \ge w \mid | y \ge h) return;
  int cellValue = getValue(buf, x, y, pitch);
  atomicAdd(δ(localHist[cellValue]), 1);
  // Wait for all block's threads before next stage
  __syncthreads();
```

Warning: we need synchronization after this stage.

Local histogram: commit to global memory

It is the same pattern as for the initialization.

We use a global atomic here.

```
__global__ void histo(int* buf, int w, int h, int pitch, int hist_size, int* hist)
{
    // ...

    // linear thread id and block dim to copy the 1D histogram
    int i = blockDim.x * threadIdx.y + threadIdx.x;
    int bs = blockDim.x * blockDim.y;
    for (; i < hist_size; i+=bs)
        atomicAdd(&(hist[i]), localHist[i]);
}</pre>
```

Summary

Histogram summary

Performance boosters:

- · coalesced accesses
- · output privatization
- · (not seen here: cascading)

Requirements:

- · atomics
- synchronization

Limitations:

- · histograms smaller than the size of the shared memory
- \cdot overhead to allocate and initialize private copies, then commit them to global memory