

A TRAJECTORIAL INTERPRETATION OF DOOB'S MARTINGALE INEQUALITIES¹

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We present a unified approach to Doob's L^p maximal inequalities for $1 \leq p < \infty$. The novelty of our method is that these martingale inequalities are obtained as consequences of elementary *deterministic* counterparts. The latter have a natural interpretation in terms of robust hedging. Moreover, our deterministic inequalities lead to new versions of Doob's maximal inequalities. These are best possible in the sense that equality is attained by properly chosen martingales.

1. Introduction. In this paper we derive estimates for the running maximum of a martingale or nonnegative submartingale in terms of its terminal value. Given a function f we write $\tilde{f}(t) = \sup_{u \leq t} f(u)$. Among other results, we establish the following martingale inequalities.

THEOREM 1.1. *Let $(S_n)_{n=0}^T$ be a nonnegative submartingale. Then*

$$(\text{Doob-}L^p) \quad \mathbb{E}[\tilde{S}_T^p] \leq \left(\frac{p}{p-1}\right)^p \mathbb{E}[S_T^p], \quad 1 < p < \infty,$$

$$(\text{Doob-}L^1) \quad \mathbb{E}[\tilde{S}_T] \leq \frac{e}{e-1} [\mathbb{E}[S_T \log(S_T)] + \mathbb{E}[S_0(1 - \log(S_0))]].$$

Here (Doob- L^p) is the classical Doob L^p -inequality, $p \in (1, \infty)$ [8], Theorem 3.4. The second result (Doob- L^1) represents the Doob L^1 -inequality in the sharp form derived by Gilat [10] from the $L \log L$ Hardy–Littlewood inequality.

Trajectorial inequalities. The novelty of this note is that the above martingale inequalities are established as consequences of *deterministic* counterparts. We postpone the general statements (Proposition 2.1) and illustrate the spirit of our approach by a simple result that may be seen as the *trajectorial version* of Doob's L^2 -inequality.

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Let s_0, \dots, s_T be real numbers. Then

$$(\text{Path-}L^2) \quad \bar{s}_T^2 + 4 \left[\sum_{n=0}^{T-1} \bar{s}_n (s_{n+1} - s_n) \right] \leq 4s_T^2.$$

Inequality (Path- L^2) is completely elementary and the proof is straightforward: it suffices to rearrange terms and to complete squares. The significance of (Path- L^2) lies rather in the fact that it implies (Doob- L^2). Indeed, if $S = (S_n)_{n=1}^T$ is a nonnegative submartingale, we may apply (Path- L^2) to each trajectory of S . The decisive observation is that, by the submartingale property,

$$(1.1) \quad \mathbb{E} \left[\sum_{n=0}^{T-1} \bar{S}_n (S_{n+1} - S_n) \right] \geq 0,$$

hence, (Doob- L^2) follows from (Path- L^2) by taking expectations.

Inequalities in continuous time—sharpness. Passing to the continuous time setting, it is clear that (Doob- L^p) and (Doob- L^1) carry over verbatim to the case where $S = (S_t)_{t \in [0, T]}$ is a nonnegative càdlàg submartingale, by the usual limiting argument. It is also not surprising that in continuous time one has trajectorial counterparts of those inequalities, the sum in (Path- L^2) being replaced by a (carefully defined) integral. Moreover, in the case $p = 1$, the inequality can be attained by a martingale in continuous time; cf. [10] and [11]. Notably, this does not hold for $1 < p < \infty$. We discuss this for the case $p = 2$ in the L^2 -norm formulation. Given a nonnegative càdlàg submartingale $S = (S_t)_{t \in [0, T]}$, we have

$$(\text{Doob-}L^2) \quad \|\bar{S}_T\|_2 \leq 2\|S_T\|_2.$$

Dubins and Gilat [9] showed that the constant 2 in (Doob- L^2) is optimal, that is, cannot be replaced by a strictly smaller constant. It is also natural to ask whether equality can be attained in (Doob- L^2). It turns out that this happens only in the trivial case $S \equiv 0$; otherwise, the inequality is strict. Keeping in mind that equality in (Doob- L^1) is attained, one may also try to improve on (Doob- L^2) by incorporating the starting value of the martingale. Indeed, we obtain the following result.

THEOREM 1.2. *For every nonnegative càdlàg submartingale $S = (S_t)_{t \in [0, T]}$,*

$$(1.2) \quad \|\bar{S}_T\|_2 \leq \|S_T\|_2 + \|S_T - S_0\|_2.$$

Inequality (1.2) is sharp. More precisely, given $x_0, x_1 \in \mathbb{R}$, $0 < x_0 \leq x_1$, there exists a positive, continuous martingale $S = (S_t)_{t \in [0, T]}$ such that $\|S_0\|_2 = x_0$, $\|S_T\|_2 = x_1$ and equality holds in (1.2).

In Theorem 3.1 we formulate the result of Theorem 1.2 for $1 < p < \infty$, thus establishing an optimal a priori estimate on $\|\bar{S}_T\|_p$.

We emphasize that the idea that (Doob- L^p) can be improved by incorporating the starting value S_0 into the inequality is not new. Cox [7], Burkholder [5] and Peskir [18] show that

$$(1.3) \quad \mathbb{E}[\bar{S}_T^2] \leq 4\mathbb{E}[S_T^2] - 2\mathbb{E}[S_0^2].$$

Here the constants 4 (resp., 2) are sharp (cf. [18]) with equality in (1.3) holding iff $S \equiv 0$.¹

Financial interpretation. We want to stress that (Path- L^2) has a natural interpretation in terms of mathematical finance.

Financial intuition suggests that we consider the positive martingale $S = (S_n)_{n=0}^T$ as the process describing the price evolution of an asset under the so-called “risk-neutral measure,” so that $\Phi(S_0, \dots, S_T) = (\bar{S}_T)^2$ [resp., $\varphi(S_T) = S_T^2$] have the natural interpretation of a so-called *exotic* option (resp., a *European* option) written on S . In finance, a European option φ (resp., exotic option Φ) is a function that depends on the final value S_T of S (resp., on its whole path S_0, \dots, S_T). The seller of the option Φ pays the buyer the random amount $\Phi(S_0, \dots, S_T)$ after its expiration at time T . Following [2] we may interpret $\mathbb{E}[\Phi]$ as the price that the buyer pays for this option at time 0; cf. [19], Chapter 5, for an introductory survey on risk-neutral pricing.

Here we take the point of view of an economic agent who sells the option Φ and wants to protect herself in all possible scenarios $\omega \in \Omega$, that is, against all possible values $\Phi(S_0(\omega), \dots, S_T(\omega))$, which she has to pay to the buyer of Φ . This means that she will trade in the market in order to arrive at time T with a portfolio value which is at least as high as the value of Φ . By buying a European option $\varphi(S_T) = S_T^2$, she can clearly protect herself in case the asset reaches its maximal value at maturity T . However, she still faces the risk of S having its highest value at some time n before T . To protect against that possibility, one way for her is to “go short” in the underlying asset (i.e., to hold negative positions in S). By scaling, her protecting strategy should be proportional to the running maximum \bar{S}_n . At this point our educated guess is to follow the strategy $H_n = -4\bar{S}_n$, meaning that from time n to time $n+1$ we keep an amount H_n of units of the asset S in our portfolio. The portfolio strategy produces the following value at time T :

$$(1.4) \quad \sum_{n=0}^{T-1} H_n(S_{n+1} - S_n) = -4 \sum_{n=0}^{T-1} \bar{S}_n(S_{n+1} - S_n).$$

The reason why we have chosen the special form $H_n = -4\bar{S}_n$ now becomes apparent when considering (Path- L^2) and (1.1). In our “financial mind experiment” this may be interpreted as follows: by buying 4 European options S_T^2 and following the

¹That (1.2) implies (1.3) follows from a simple calculation. Alternatively, the sharpness of (1.3) is a consequence of the fact that equality in (1.2) can be attained for all possible values of $\|S_0\|_2, \|S_T\|_2$.

self-financing trading strategy $H = (H_n)_{n=0}^{T-1}$, the seller of the option $\Phi = (\bar{S}_T)^2$ covers her position at maturity T , whatever the outcome $(S_0(\omega), \dots, S_T(\omega))$ of the price evolution is. Thus an upper bound for the price of the exotic option Φ in terms of the European option φ is given by

$$\mathbb{E}[(\bar{S}_T)^2] \leq 4\mathbb{E}[S_T^2].$$

We note that Henry-Labordère [12] derived (Doob- L^p) in a related fashion.

The idea of robust pricing and pathwise hedging of exotic options seemingly goes back to Hobson [13] (see also [4, 6, 15]). We refer the reader to [14] for a thorough introduction to the topic.

Organization of the paper. In Section 2 we prove Doob's inequalities (Doob- L^p) and (Doob- L^1) after establishing the trajectorial counterparts (Path- L^p) and (Path- L^1). We prove Theorem 3.1 and its L^p version in Section 3.

2. Proof of Theorem 1.1. The aim of this section is to prove Doob's maximal inequalities in Theorem 1.1 by means of deterministic inequalities, which are established in Proposition 2.1 below. The proof of Theorem 1.1 is given at the end of this section. Regarding (Doob- L^p), we prove the stronger result

$$(2.1) \quad \mathbb{E}[\bar{S}_T^p] \leq \left(\frac{p}{p-1}\right)^p \mathbb{E}[S_T^p] - \frac{p}{p-1} \mathbb{E}[S_0^p], \quad 1 < p < \infty,$$

which was obtained in [7, 18].

PROPOSITION 2.1. *Let s_0, \dots, s_T be nonnegative numbers.*

(I) *For $1 < p < \infty$ and $h(x) := -\frac{p^2}{p-1}x^{p-1}$, we have*

$$(\text{Path-}L^p) \quad \bar{s}_T^p \leq \sum_{i=0}^{T-1} h(\bar{s}_i)(s_{i+1} - s_i) - \frac{p}{p-1} s_0^p + \left(\frac{p}{p-1}\right)^p s_T^p.$$

(II) *For $h(x) := -\log(x)$, we have*

$$(\text{Path-}L^1) \quad \bar{s}_T \leq \frac{e}{e-1} \left(\sum_{i=0}^{T-1} h(\bar{s}_i)(s_{i+1} - s_i) + s_T \log(s_T) + s_0(1 - \log(s_0)) \right).$$

We note that for $p = 2$, inequality (Path- L^p) is valid also in the case where s_0, \dots, s_T are real (possibly negative) numbers. A continuous time counterpart of (Path- L^p) is given in Remark 3.5 below.

In the proof of Proposition 2.1, we need the following identity.

LEMMA 2.2. *Let s_0, \dots, s_T be real numbers and $h: \mathbb{R} \rightarrow \mathbb{R}$ any function. Then*

$$(2.2) \quad \sum_{i=0}^{T-1} h(\bar{s}_i)(s_{i+1} - s_i) = \sum_{i=0}^{T-1} h(\bar{s}_i)(\bar{s}_{i+1} - \bar{s}_i) + h(\bar{s}_T)(s_T - \bar{s}_T).$$

PROOF. This follows by properly rearranging the summands. Indeed, observe that for a term on the right-hand side there are two possibilities: if $\bar{s}_{i+1} = \bar{s}_i$ (resp., $s_T = \bar{s}_T$) it simply vanishes. Otherwise, it equals a sum $h(\bar{s}_k)(s_{k+1} - s_k) + \cdots + h(\bar{s}_m)(s_{m+1} - s_m)$ where $\bar{s}_k = \cdots = \bar{s}_m$. In total, every summand on the left-hand side of (2.2) is accounted exactly once on the right. \square

We note that Lemma 2.2 is a special case of [17], Lemma 3.1.

PROOF OF PROPOSITION 2.1. (I) By convexity, $x^p + px^{p-1}(y - x) \leq y^p$, $x, y \geq 0$. Hence, Lemma 2.2 yields

$$\begin{aligned}
 \sum_{i=0}^{T-1} h(\bar{s}_i)(s_{i+1} - s_i) &= -\frac{p^2}{p-1} \sum_{i=0}^{T-1} \bar{s}_i^{p-1}(\bar{s}_{i+1} - \bar{s}_i) - \frac{p^2}{p-1} \bar{s}_T^{p-1}(s_T - \bar{s}_T) \\
 (2.3) \qquad &\geq -\frac{p}{p-1} \sum_{i=0}^{T-1} \bar{s}_{i+1}^p - \bar{s}_i^p - \frac{p^2}{p-1} \bar{s}_T^{p-1}(s_T - \bar{s}_T) \\
 &= p\bar{s}_T^p - \frac{p^2}{p-1} \bar{s}_T^{p-1} s_T + \frac{p}{p-1} \bar{s}_0^p.
 \end{aligned}$$

We therefore have

$$\begin{aligned}
 \sum_{i=0}^{T-1} h(\bar{s}_i)(s_{i+1} - s_i) &+ \left(\frac{p}{p-1}\right)^p s_T^p - \frac{p}{p-1} \bar{s}_0^p - \bar{s}_T^p \\
 (2.4) \qquad &\geq (p-1)\bar{s}_T^p - \frac{p^2}{p-1} \bar{s}_T^{p-1} s_T + \left(\frac{p}{p-1}\right)^p s_T^p.
 \end{aligned}$$

To establish (Path- L^p) it is thus sufficient to show that the rhs of (2.4) ≥ 0 . Defining c such that $S_n = cS_n^-$ amounts to showing that

$$(2.5) \qquad g(c) = (p-1) - \frac{p^2}{p-1}c + \left(\frac{p}{p-1}\right)^p c^p \geq 0.$$

Using standard calculus we obtain that g reaches its minimum at $\hat{c} = \frac{p-1}{p}$ where $g(\hat{c}) = 0$.

(II) By Lemma 2.2 we have

$$\begin{aligned}
 &\sum_{i=0}^{T-1} h(\bar{s}_i)(s_{i+1} - s_i) \\
 &= -\sum_{i=0}^{T-1} \log(\bar{s}_i)(\bar{s}_{i+1} - \bar{s}_i) - \log(\bar{s}_T)(s_T - \bar{s}_T) \\
 &\geq \sum_{i=0}^{T-1} (\bar{s}_{i+1} - \bar{s}_i - \bar{s}_{i+1} \log(\bar{s}_{i+1}) + \bar{s}_i \log(\bar{s}_i)) - \log(\bar{s}_T)(s_T - \bar{s}_T) \\
 &= \bar{s}_T - s_0 + s_0 \log(s_0) - s_T \log(\bar{s}_T),
 \end{aligned}$$

where the inequality follows from the convexity of $x \mapsto -x + x \log(x)$, $x > 0$. If $s_T = 0$ then the above inequality shows that (Path- L^1) holds true. Otherwise, we have

$$\bar{s}_T \leq \sum_{i=0}^{T-1} h(\bar{s}_i)(s_{i+1} - s_i) + s_0 - s_0 \log(s_0) + s_T \log(s_T) + s_T \log\left(\frac{\bar{s}_T}{s_T}\right).$$

Note that the function $x \mapsto x \log(y/x)$ on $(0, \infty)$, for any fixed $y > 0$, has a maximum in $\hat{x} = y/e$, where it takes the value y/e . This means that $s_T \log(\bar{s}_T/s_T) \leq \bar{s}_T/e$ which concludes the proof. \square

We are now in the position to prove Theorem 1.1.

PROOF OF THEOREM 1.1. By Proposition 2.1(I), for $h(x) := -\frac{p^2}{p-1}x^{p-1}$ we have

$$(2.6) \quad \bar{S}_T^p \leq \sum_{i=0}^{T-1} h(\bar{S}_i)(S_{i+1} - S_i) - \frac{p}{p-1}S_0^p + \left(\frac{p}{p-1}\right)^p S_T^p.$$

Since S is a submartingale and h is negative, $\mathbb{E}[\sum_{i=0}^{T-1} h(\bar{S}_i)(S_{i+1} - S_i)] \leq 0$ and thus (2.1) [and consequently (Doob- L^p)] follows from (2.6) by taking expectations.

Inequality (Doob- L^1) follows from Proposition 2.1(II) in the same fashion. \square

REMARK 2.3. Given the terminal law μ of a martingale S , Hobson [14], Section 3.7, also provides pathwise hedging strategies for lookback options on S . As opposed to the strategies given in Proposition 2.1, we emphasize that the strategies in [14] depend on μ .

3. Qualitative Doob L^p -inequality—Proof of Theorem 1.2. In this section we prove Theorem 1.2 as well as the following result which pertains to $p \in (1, \infty)$.

THEOREM 3.1. Let $(S_t)_{t \in [0, T]}$ be a nonnegative submartingale, $S \neq 0$ and $1 < p < \infty$. Then

$$(3.1) \quad \|\bar{S}_T\|_p \leq \frac{p}{p-1}\|S_T\|_p - \frac{1}{p-1} \frac{\|S_0\|_p^p}{\|\bar{S}_T\|_p^{p-1}}.$$

Given the values $\|S_0\|_p$ and $\|S_T\|_p$, inequality (3.1) is best possible. More precisely, given $x_0, x_1 \in \mathbb{R}$, $0 < x_0 \leq x_1$, there exists a positive, continuous martingale $S = (S_t)_{t \in [0, T]}$ such that $\|S_0\|_p = x_0$, $\|S_T\|_p = x_1$ and equality holds in (3.1).

Moreover, equality in (3.1) holds iff S is a nonnegative martingale such that \bar{S} is continuous and $\bar{S}_T = \alpha S_T$, where $\alpha \in [1, \frac{p}{p-1})$.

REMARK 3.2. We prove Theorem 3.1 by introducing a pathwise integral in continuous time. Note that inequality (3.1) can also be obtained without defining such an integral. However, the definition of the pathwise integral will allow us to characterize all submartingales for which equality in (3.1) holds.

Connection between Theorems 1.2 and 3.1. We now discuss under which conditions Theorem 1.2 and Theorem 3.1 are equivalent for $p = 2$. Recall that Theorem 1.2 asserts that

$$(3.2) \quad \|\bar{S}_T\|_2 \leq \|S_T\|_2 + \|S_T - S_0\|_2$$

and Theorem 3.1 reads, in the case of $p = 2$, as

$$(3.3) \quad \|\bar{S}_T\|_2 \leq 2\|S_T\|_2 - \frac{\|S_0\|_2^2}{\|\bar{S}_T\|_2}.$$

- If S is a martingale, then (3.2) and (3.3) are equivalent. Indeed, rearranging (3.3) yields

$$(3.4) \quad \psi(\|\bar{S}_T\|_2) := \frac{1}{2}\|\bar{S}_T\|_2 + \frac{\|S_0\|_2^2}{2\|\bar{S}_T\|_2} \leq \|S_T\|_2,$$

and by inverting the strictly monotone function ψ on $[\|S_0\|_2, \infty)$, we obtain

$$\|\bar{S}_T\|_2 \leq \psi^{-1}(\|S_T\|_2) = \|S_T\|_2 + \sqrt{\|S_T\|_2^2 - \|S_0\|_2^2}.$$

Since S is a martingale, $\sqrt{\|S_T\|_2^2 - \|S_0\|_2^2} = \|S_T - S_0\|_2$, which gives (3.2).

- If S is a true submartingale, then the estimate in (3.2) is in fact stronger than (3.3). This follows from the above reasoning and the fact that for a true submartingale, we have $\sqrt{\|S_T\|_2^2 - \|S_0\|_2^2} > \|S_T - S_0\|_2$.
- Clearly, it would be desirable to also obtain for general p an inequality of the type (3.2), which is in the case of a martingale S equivalent to (3.1), and where \bar{S}_T only appears on the left-hand side. By similar reasoning as for $p = 2$, finding such an inequality is tantamount to inverting the function

$$\psi(x) = \frac{p-1}{p}x + \frac{\|S_0\|_p^p}{px^{p-1}},$$

which is strictly monotone on $[\|S_0\|_p, \infty)$. Since finding ψ^{-1} amounts to solving an algebraic equation, there is, in general, no closed form representation of ψ^{-1} unless $p \in \{2, 3, 4\}$.

Definition of the continuous-time integral. For a general account on the theory of pathwise stochastic integration we refer to Bichteler [3] and Karandikar [16]. Here we are interested in the particular case where the integrand is of the form

$h(\bar{S})$ and h is monotone and continuous. In this setup a rather naive and ad hoc approach is sufficient (see Lemma 3.3 below).

Fix càdlàg functions $f, g: [0, T] \rightarrow [0, \infty)$ and assume that g is monotone. We set

$$(3.5) \quad \int_0^T g_t \, df_t := \lim_{n \rightarrow \infty} \sum_{t_i \in \pi_n} g_{t_i-} (f_{t_{i+1}} - f_{t_i})$$

if the limit exists for *every* sequence of finite partitions π_n with mesh converging to 0. The standard argument of mixing sequences then implies uniqueness. We stress that (3.5) exists if and only if the “nonpredictable version” $\int_0^T g_t \, df_t = \lim_{n \rightarrow \infty} \sum_{t_i \in \pi_n} g_{t_i} (f_{t_{i+1}} - f_{t_i})$ exists; in this case the two values coincide.

By rearranging terms, one obtains the identity

$$(3.6) \quad \begin{aligned} \sum_{t_i \in \pi} g_{t_i} (f_{t_{i+1}} - f_{t_i}) &= - \sum_{t_i \in \pi} f_{t_i} (g_{t_{i+1}} - g_{t_i}) + g_T f_T - g_0 f_0 \\ &\quad - \overbrace{\sum_{t_i \in \pi} (g_{t_{i+1}} - g_{t_i}) (f_{t_{i+1}} - f_{t_i})}^{(*)}. \end{aligned}$$

If it is possible to pass to a limit on either of the two sides, one can do so on the other. Hence, $\int_0^T g_t \, df_t$ is defined whenever $\int_0^T f_t \, dg_t$ is defined and vice versa, since the monotonicity of g implies that $(*)$ converges. In this case we obtain the integration-by-parts formula

$$(3.7) \quad \int_0^T g_t \, df_t = - \int_0^T f_t \, dg_t + g_T f_T - g_0 f_0 - \sum_{0 \leq t \leq T} (g_t - g_{t-}) (f_t - f_{t-}).$$

Below we will need that the integrals $\int_0^T h(\bar{f}_t) \, df_t$ and $\int_0^T f_t \, dh(\bar{f}_t)$ are well-defined whenever h is continuous, monotone and f is càdlàg. In the case of $\int_0^T f_t \, dh(\bar{f}_t)$, this can be seen by splitting f in its continuous and its jump part. Existence of $\int_0^T h(\bar{f}_t) \, df_t$ is then a consequence of (3.7).

The following lemma establishes the connection of the just defined pathwise integral with the standard Itô integral.

LEMMA 3.3. *Let S be a martingale on $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbb{P})$ and h be a monotone and continuous function. Then*

$$(3.8) \quad (h(\bar{S}) \bullet S)_T(\omega) = \int_0^T h(\bar{S}_{t-}(\omega)) \, dS_t(\omega) \quad \mathbb{P}\text{-a.s.},$$

where the lhs refers to the Itô integral while the rhs appeals to the pathwise integral defined in (3.5).

PROOF. Karandikar [16], Theorem 2, proves that

$$(h(\bar{S}) \bullet S)_T(\omega) = \lim_{n \rightarrow \infty} \sum_{t_i \in \pi_n} h(\bar{S}_{t_i-}(\omega))(S_{t_{i+1}}(\omega) - S_{t_i}(\omega))$$

for a suitably chosen sequence of random partitions $\pi_n, n \geq 1$. According to the above discussion, $\int_0^T h(\bar{S}_{t-}(\omega)) dS_t(\omega) = \lim_{n \rightarrow \infty} \sum_{t_i \in \pi_n} h(\bar{S}_{t_i-}(\omega))(S_{t_{i+1}}(\omega) - S_{t_i}(\omega))$ for any choice of partitions $\pi_n(\omega), n \geq 1$, with mesh converging to 0. \square

We are now able to establish a continuous-time version of Proposition 2.1.

PROPOSITION 3.4. *Let $f : [0, T] \rightarrow [0, \infty)$ be càdlàg. Then for $h(x) := -\frac{p^2}{p-1}x^{p-1}$, we have*

$$(3.9) \quad \bar{f}_T^p \leq \int_0^T p^{-1} h(\bar{f}_t) df_t + \frac{p}{p-1} \bar{f}_T^{p-1} f_T - \frac{1}{p-1} f_0^p.$$

Equality in (3.9) holds true if and only if \bar{f} is continuous. Similarly, a continuous-time version of (Path- L^1) also holds true.

PROOF. Inequality (3.9) follows from (2.3) by passing to limits. We now show that equality in (3.9) holds iff \bar{f} is continuous. To simplify notation, we consider the case $p = 2$. Formula (3.7) implies

$$(3.10) \quad \begin{aligned} \int_0^T h(\bar{f}_t) df_t &= 4 \int_0^T f_t d\bar{f}_t - 4\bar{f}_T f_T + 4f_0^2 \\ &\quad + 4 \sum_{0 \leq t \leq T} (\bar{f}_t - \bar{f}_{t-})(f_t - f_{t-}), \\ &\geq 2\bar{f}_T^2 - 4\bar{f}_T f_T + 2f_0^2, \end{aligned}$$

where equality in (3.10) holds iff \bar{f} is continuous. Hence, equality in (3.9) holds true iff \bar{f} is continuous. \square

If we choose f to be the path of a continuous martingale, the integral in (3.9) is a pathwise version of an Azéma–Yor process; cf. [17], Theorem 3.

REMARK 3.5. Passing to limits in (Path- L^p) in Section 2 we obtain that for every càdlàg function $f : [0, T] \rightarrow [0, \infty)$

$$\bar{f}_T^p \leq - \int_0^T \frac{p^2}{p-1} \bar{f}_t^{p-1} df_t + \left(\frac{p}{p-1} \right)^p f_T^p - \frac{p}{p-1} f_0^p, \quad 1 < p < \infty.$$

Alternatively, this can be seen as a consequence of (3.9).

LEMMA 3.6. *Let $(S_t)_{t \in [0, T]}$ be a nonnegative submartingale and $1 < p < \infty$. Set $S = M + A$, where M is a martingale and A is an increasing, predictable process with $A_0 = 0$. Then*

$$(3.11) \quad \mathbb{E}[\bar{S}_T^p] \leq -\frac{p}{p-1} \mathbb{E}[S_0^{p-1} A_T] + \frac{p}{p-1} \mathbb{E}[\bar{S}_T^{p-1} S_T] - \frac{1}{p-1} \mathbb{E}[S_0^p].$$

Equality holds in (3.11) if and only if S is a martingale such that \bar{S} is a.s. continuous.

PROOF. By Proposition 3.4 we find for $h(x) = -\frac{p^2}{p-1}x^{p-1}$,

$$(3.12) \quad \bar{S}_T^p \leq \int_0^T p^{-1} h(\bar{S}_t) dS_t + \frac{p}{p-1} \bar{S}_T^{p-1} S_T - \frac{1}{p-1} S_0^p,$$

where equality holds iff \bar{S} is continuous. Since

$$(3.13) \quad \mathbb{E}\left[\int_0^T p^{-1} h(\bar{S}_t) dA_t\right] \leq -\frac{p}{p-1} \mathbb{E}[S_0^{p-1} A_T],$$

(3.11) follows by taking expectations in (3.12). As the estimate in (3.13) is an equality iff $A = 0$, we conclude that equality in (3.11) holds iff S is a martingale such that \bar{S} is continuous. \square

We note that in the case of $p = 2$, [1], Corollary 2.2.2, also implies that equality in (3.11) holds for every continuous martingale S .

PROOF OF THEOREMS 3.1 AND 1.2. By Lemma 3.6 and Hölder's inequality we have

$$(3.14) \quad \|\bar{S}_T\|_p^p \leq -\frac{p}{p-1} \mathbb{E}[S_0^{p-1} A_T] + \frac{p}{p-1} \|\bar{S}_T^{p-1} S_T\|_1 - \frac{1}{p-1} \|S_0\|_p^p$$

$$(3.15) \quad \leq -\frac{p}{p-1} \mathbb{E}[S_0^{p-1} A_T] + \frac{p}{p-1} \|\bar{S}_T\|_p^{p-1} \|S_T\|_p - \frac{1}{p-1} \|S_0\|_p^p,$$

where equality in (3.14) holds for every martingale S such that \bar{S} is continuous, and equality in (3.15) holds whenever S_T is a constant multiple of \bar{S}_T . Since $\mathbb{E}[S_0^{p-1} A_T] \geq 0$, we obtain (3.1) after dividing by $\|\bar{S}_T\|_p^{p-1}$.

In order to establish (1.2) in Theorem 1.2 for $p = 2$, we rearrange terms in (3.15) to obtain

$$\psi(\|\bar{S}_T\|_2) := \frac{1}{2} \|\bar{S}_T\|_2 + \frac{2\mathbb{E}[S_0 A_T] + \|S_0\|_2^2}{2\|\bar{S}_T\|_2} \leq \|S_T\|_2.$$

Similarly, as in the discussion after Remark 3.2 above, inverting ψ on $[\|S_0\|_2, \infty)$ implies

$$\|\bar{S}_T\|_2 \leq \|S_T\|_2 + \sqrt{\|S_T\|_2^2 - 2\mathbb{E}[S_0 A_T] - \|S_0\|_2^2}.$$

Since for every submartingale S we have $\sqrt{\|S_T\|_2^2 - 2\mathbb{E}[S_0 A_T]} - \|S_0\|_2^2 = \|S_T - S_0\|_2$, this proves (1.2).

In order to prove that (3.1) [resp., (1.2)] is attained, we have to ensure the existence of a p -integrable martingale S such that \tilde{S} is continuous and S_T is a constant multiple of \tilde{S}_T . To this end, we may clearly assume that $x_0 = 1$. Fix $\alpha \in (1, \frac{p}{p-1})$ and let $B = (B_t)_{t \geq 0}$ be a Brownian motion starting at $B_0 = 1$. Consider the process $B^{\tau_\alpha} = (B_{t \wedge \tau_\alpha})_{t \geq 0}$ obtained by stopping B at the stopping time

$$\tau_\alpha := \inf\{t > 0 : B_t \leq \tilde{B}_t/\alpha\}.$$

This stopping rule corresponds to the Azéma–Yor solution of the Skorokhod embedding problem (B, μ) (cf. [1]) where the probability measure μ is given by

$$\frac{d\mu}{dx} = \frac{\alpha^{-1/(\alpha-1)}}{(\alpha-1)} x^{-(2\alpha-1)/(\alpha-1)} 1_{[\alpha^{-1}, \infty)}(x).$$

Clearly B^{τ_α} is a uniformly integrable martingale. Therefore the process $(S_t)_{t \in [0, T]}$ defined as $S_t := B_{t/(T-t) \wedge \tau_\alpha}$ is a nonnegative martingale satisfying $S_T = \tilde{S}_T/\alpha$. S_T is p -integrable for $\alpha \in (1, \frac{p}{p-1})$ and $\|S_T\|_p$ runs through the interval $(1, \infty)$ while α runs in $(1, \frac{p}{p-1})$. This concludes the proof.

In fact, note that the proof shows that equality in (3.1) holds if and only if S is a nonnegative martingale such that \tilde{S} is continuous and $\tilde{S}_T = \alpha S_T$, where $\alpha \in [1, \frac{p}{p-1})$. \square

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