

# Learning Algorithms for Gaussian Mixture Models

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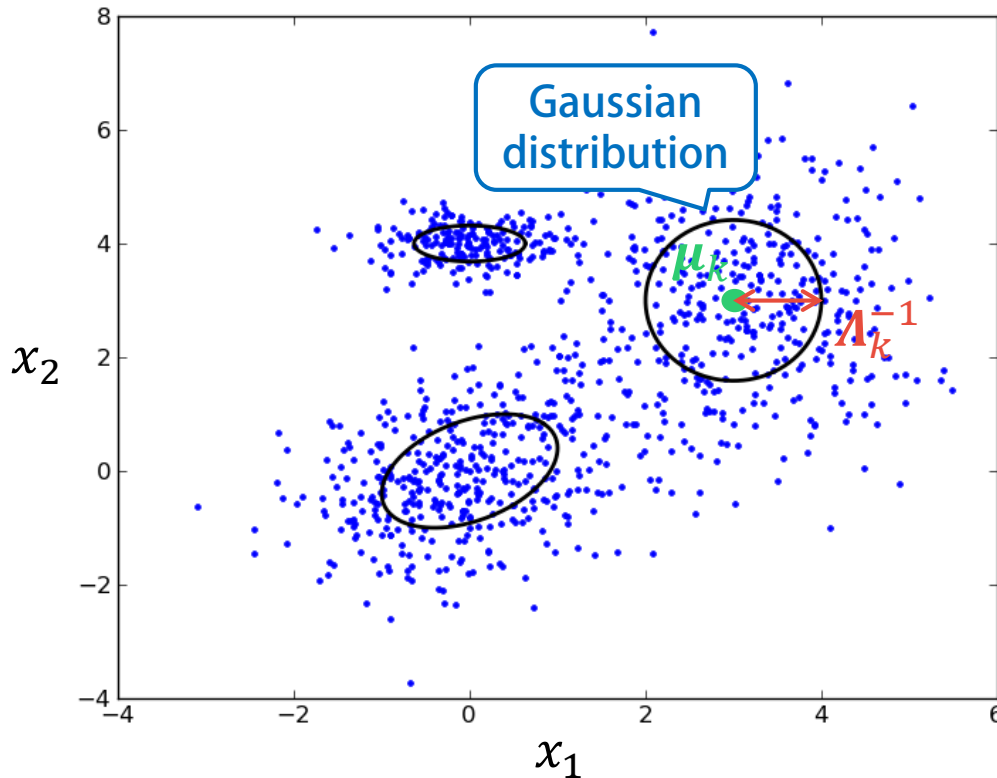
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# The Gaussian Mixture Model

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- The GMM is used for representing how multi-dimensional vectors (e.g., feature vectors) are distributed stochastically



Probability distribution:

$$p(\mathbf{x}) = \sum_{k=1}^K \pi_k N(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1})$$

Parameters to be estimated:

Mixing ratios

$$\boldsymbol{\pi} = [\pi_1, \dots, \pi_K]$$

Mean vectors

$$\boldsymbol{\mu} = [\boldsymbol{\mu}_1, \dots, \boldsymbol{\mu}_K]$$

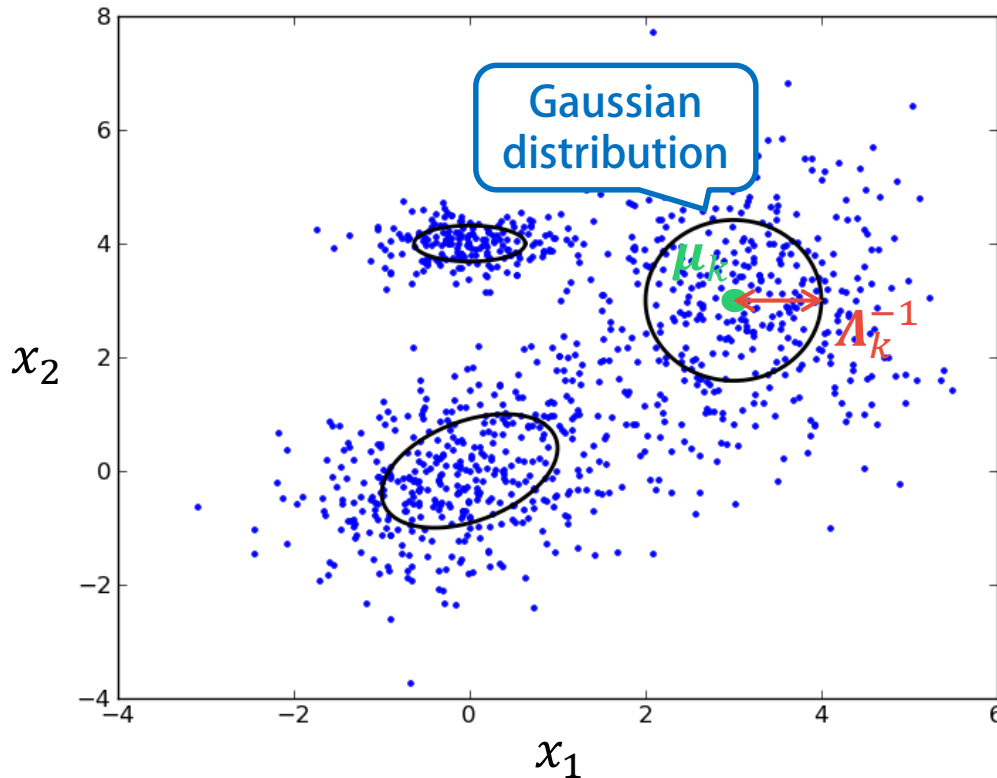
Precision matrices

$$\boldsymbol{\Lambda} = [\boldsymbol{\Lambda}_1, \dots, \boldsymbol{\Lambda}_K]$$

# Generative Story of GMM

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- The GMM is a probabilistic model for **clustering**
  - Each vector (sample) exclusively belongs to one of  $K$  classes



Probability distribution:

$$p(\mathbf{x}) = \sum_{k=1}^K \pi_k N(\mathbf{x} | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1})$$

Generative story:

Draw a latent variable

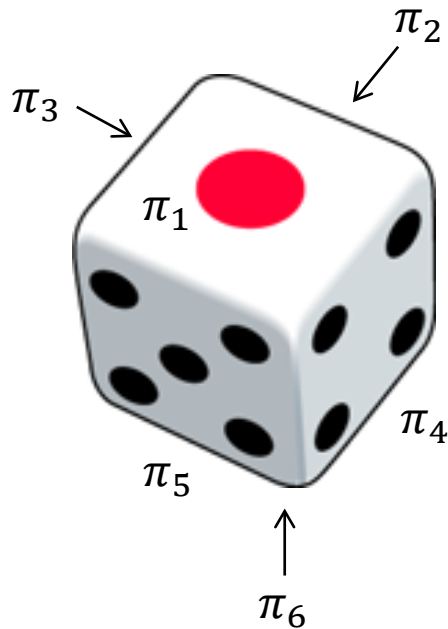
$$\mathbf{z}_n \sim \text{Categorical}(\mathbf{z}_n | \boldsymbol{\pi})$$

Draw an observed variable

$$\mathbf{x}_n \sim \prod_{k=1}^K N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1})^{z_{nk}}$$

Class  
indicator

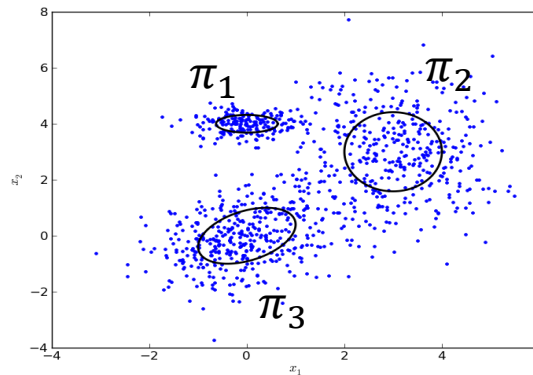
- Latent variables are **categorical** distributed
  - Draw each latent variable:  $\mathbf{z}_n \sim \text{Categorical}(\mathbf{z}_n | \boldsymbol{\pi})$  ( $\boldsymbol{\pi} = [\pi_1, \dots, \pi_K]$ )
  - Use an **one-of- $K$  representation**:  $\mathbf{z}_n = [z_{n1}, z_{n2}, z_{n3}, \dots, z_{nK}]$



Suppose we cast a  $K$ -sided die defined by  $\boldsymbol{\pi}$

If we get "3" for the  $n^{\text{th}}$  trial,  
we say  $\mathbf{z}_n = [0, 0, 1, 0, 0, 0]$

Only one of the elements  
takes the value of 1

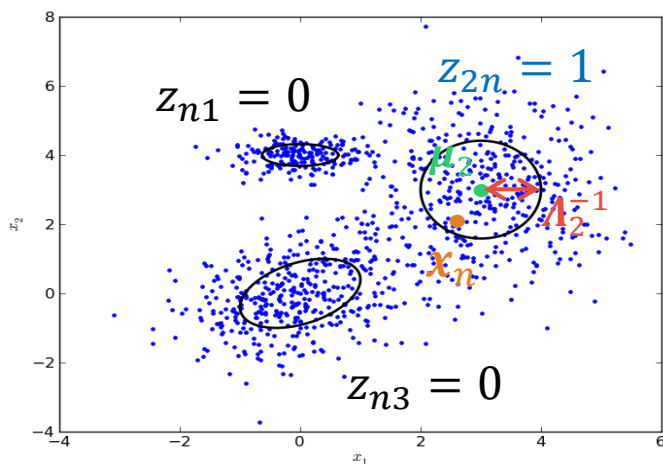


In the generative story of GMM,  
a class to which each sample  
belongs is stochastically  
determined by casting the die

- Observed variables are **Gaussian** distributed
  - Draw each observed variable:  $\mathbf{x}_n \sim \prod_{k=1}^K N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1})^{z_{nk}}$
  - Use the  $k^{th}$  Gaussian distribution when  $z_{nk} = 1$

Expand the product:

$$\mathbf{x}_n \sim \prod_{k=1}^3 N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1})^{z_{nk}} = N(\mathbf{x}_n | \boldsymbol{\mu}_1, \boldsymbol{\Lambda}_1^{-1})^{z_{n1}} N(\mathbf{x}_n | \boldsymbol{\mu}_2, \boldsymbol{\Lambda}_2^{-1})^{z_{n2}} N(\mathbf{x}_n | \boldsymbol{\mu}_3, \boldsymbol{\Lambda}_3^{-1})^{z_{n3}}$$



Suppose  $\mathbf{z}_n = [0, 1, 0]$

$$\mathbf{x}_n \sim N(\mathbf{x}_n | \boldsymbol{\mu}_2, \boldsymbol{\Lambda}_2^{-1})$$

The one-of- $K$  representation can be used as a class indicator (selector)

This makes the derivation of learning algorithms easy (explained later)

- There are several kinds of  **$K$ -dimensional** values
  - Random variables
    - ♦ Mixing ratios:  $\boldsymbol{\pi} = [\pi_1, \pi_2, \dots, \pi_k, \dots, \pi_K]$
    - ♦ Latent variables:  $\mathbf{z}_n = [z_{n1}, z_{n2}, \dots, z_{nk}, \dots, z_{nK}]$
  - Categorical probabilities
    - ♦ Posteriors:  $\boldsymbol{\gamma}_n = [\gamma_{n1}, \gamma_{n2}, \dots, \gamma_{nk}, \dots, \gamma_{nK}]$

The values sum to unity

$$\sum_{k=1}^K \pi_k = 1$$

$$0 < \pi_k < 1$$

$$\sum_{k=1}^K z_{nk} = 1$$

Only one of the values is 1  
The other values are 0

$$\sum_{k=1}^K \gamma_{nk} = 1$$

$$0 < \gamma_{nk} < 1$$

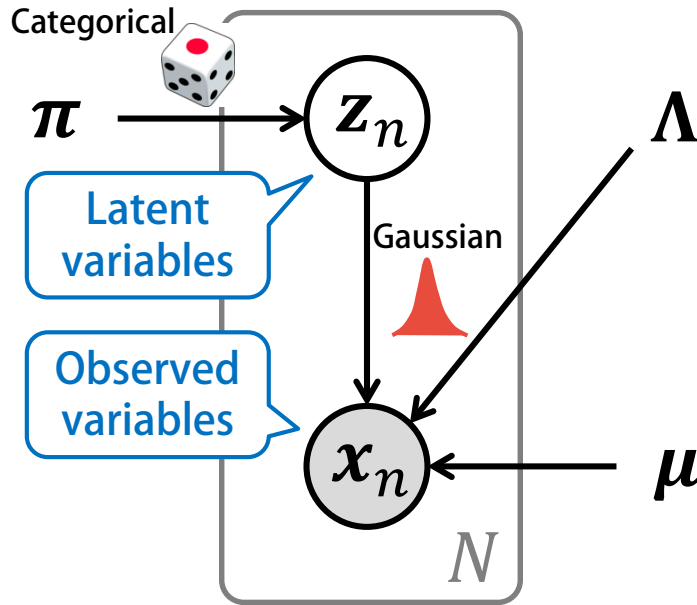
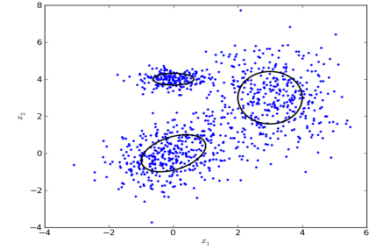
- Generative story of the GMM
  - Draw each latent variable:  $z_n \sim \text{Categorical}(z_n | \pi)$
  - Draw each observed variable:  $x_n \sim \prod_{k=1}^K N(x_n | \mu_k, \Lambda_k^{-1})^{z_{nk}}$
- Two major approaches

	Maximum likelihood (ML) estimation	Bayesian estimation
Probabilistic model	$p(X, Z; \mu, \Lambda)$ $= p(X Z; \mu, \Lambda)p(Z; \pi)$	$p(X, Z, \mu, \Lambda)$ $= p(X Z, \mu, \Lambda)p(Z, \pi)p(\pi, \mu, \Lambda)$
Latent variables $Z$	Posterior calculation $p(Z X; \pi, \mu, \Lambda)$	Posterior calculation $p(Z, \pi, \mu, \Lambda X)$
Parameters $\pi, \mu, \Lambda$	Point estimation $\pi^*, \mu^*, \Lambda^* = \text{argmax } p(X; \pi, \mu, \Lambda)$	

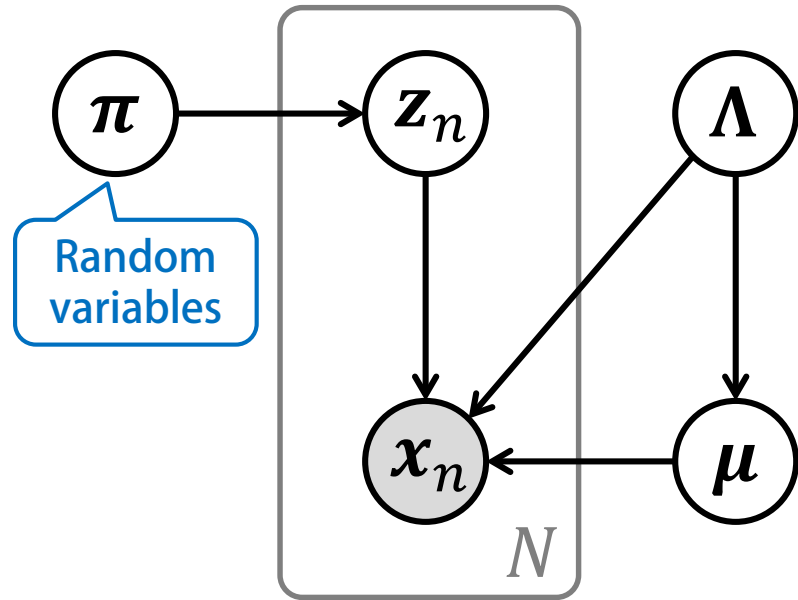
# Graphical Representation

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- Visualize dependency structures
  - Nodes: random variables (shaded = observable)
  - Edges: conditional dependencies



Likelihood model



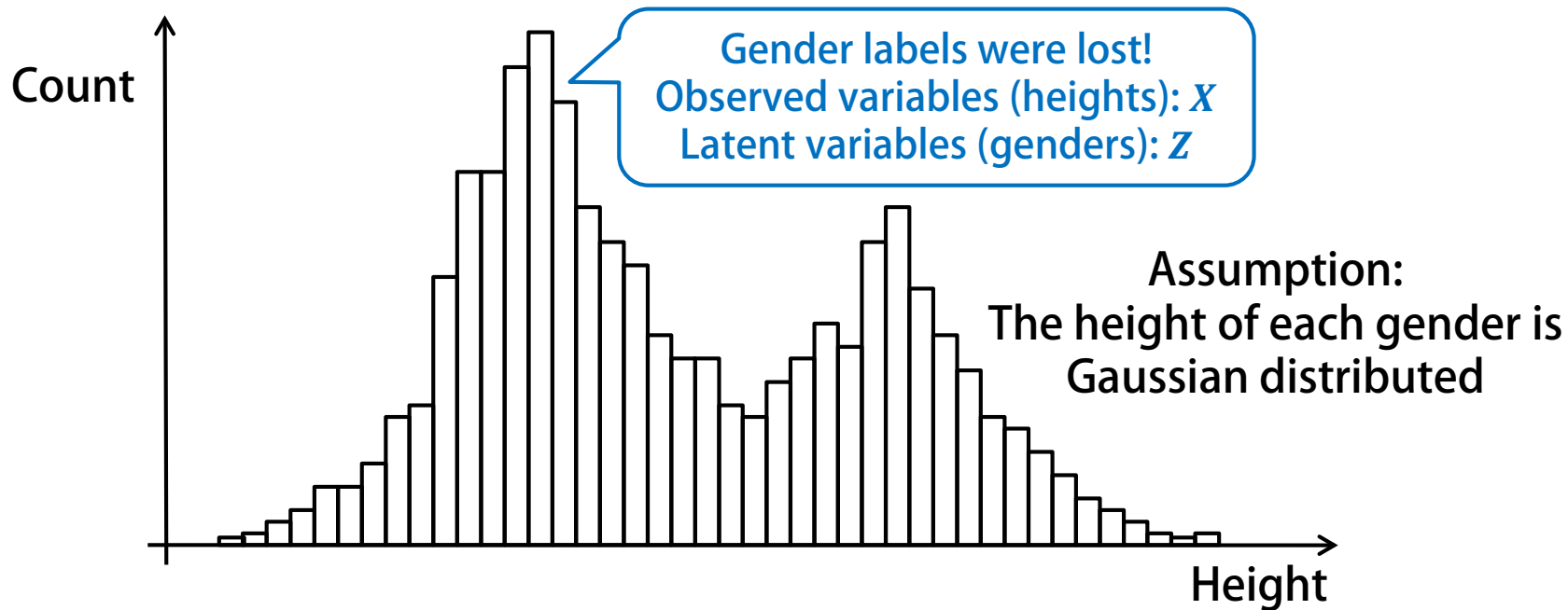
Bayesian model



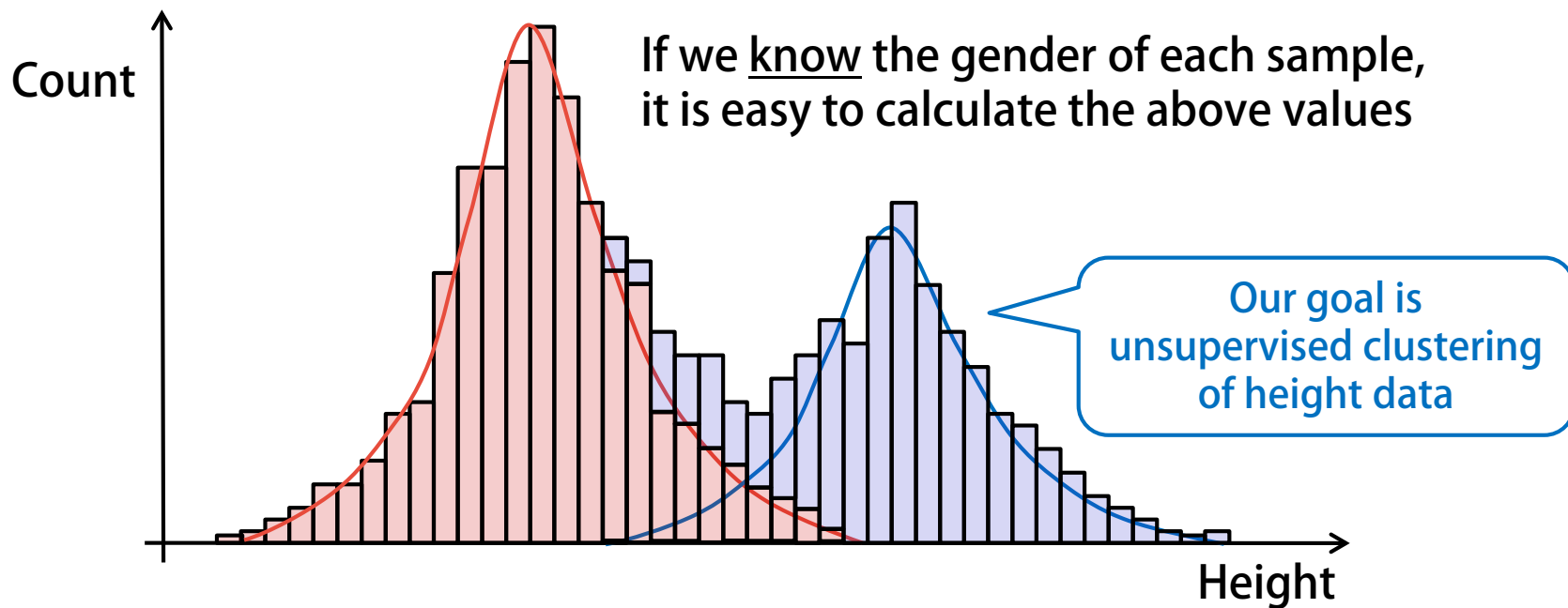
# Maximum Likelihood Estimation of **Finite** Gaussian Mixture Models

Expectation-Maximization Algorithm  
*K*-means Algorithm (Hard EM)

- Suppose we have unlabeled height data
  - We want to estimate
    - ♦ the **averages**  $\mu$  and **precisions**  $\Lambda$  of the heights of male and female
    - ♦ the **ratios**  $\pi$  of male and female



- Suppose we have unlabeled height data
  - We want to estimate
    - ♦ the **averages**  $\mu$  and **variances**  $\Lambda$  of the heights of male and female
    - ♦ the **ratios**  $\pi$  of male and female



- Generative story of the GMM
  - Draw each latent variable:  $\mathbf{z}_n \sim \text{Categorical}(\mathbf{z}_n | \boldsymbol{\pi})$
  - Draw each observed variable:  $\mathbf{x}_n \sim \prod_{k=1}^K N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1})^{z_{nk}}$
- Two major approaches

	Maximum likelihood (ML) estimation	Bayesian estimation
Probabilistic model	$p(\mathbf{X}, \mathbf{Z}; \boldsymbol{\mu}, \boldsymbol{\Lambda})$ $= p(\mathbf{X}   \mathbf{Z}; \boldsymbol{\mu}, \boldsymbol{\Lambda}) p(\mathbf{Z}; \boldsymbol{\pi})$	$p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda})$ $= p(\mathbf{X}   \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) p(\mathbf{Z}, \boldsymbol{\pi}) p(\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})$
Latent variables $\mathbf{Z}$	Posterior calculation $p(\mathbf{Z}   \mathbf{X}; \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})$	Posterior calculation $p(\mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}   \mathbf{X})$
Parameters $\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}$	Point estimation $\boldsymbol{\pi}^*, \boldsymbol{\mu}^*, \boldsymbol{\Lambda}^* = \text{argmax } p(\mathbf{X}; \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})$	

- Estimate the ratios, averages, and variances

	$k = 1$	$k = 2$
$x_1 = 180cm$	$z_1 = [1, 0]$	
$x_2 = 170cm$	$z_2 = [0, 1]$	
$x_3 = 166cm$	$z_3 = [1, 0]$	
$x_4 = 175cm$	$z_4 = [1, 0]$	
$x_5 = 160cm$	$z_5 = [1, 0]$	
$x_6 = 155cm$	$z_6 = [0, 1]$	
$x_7 = 165cm$	$z_7 = [0, 1]$	
$x_8 = 162cm$	$z_8 = [1, 0]$	
$x_9 = 150cm$	$z_9 = [0, 1]$	

Sufficient statistics for each class  $k$  (male or female)

$$S_k[1] = \sum_{n=1}^N z_{nk}$$

Count

$$S_k[x] = \sum_{n=1}^N z_{nk} x_n$$

Sum

$$S_k[xx^T] = \sum_{n=1}^N z_{nk} x_n x_n^T$$

Ratio:  $\pi_k = \frac{S_k[1]}{S[1]}$

Average:  $\mu_k = \frac{S_k[x]}{S_k[1]}$

Variance:  $\Lambda_k^{-1} = \frac{S_k[xx]}{S_k[1]} - \mu_k \mu_k^T$

- Use posteriors instead of latent variables

	$k = 1$	$k = 2$		$k = 1$	$k = 2$
$x_1 = 180cm$	$z_1 = [?, ?]$			$p(z_1 X) = [0.99, 0.01]$	
$x_2 = 170cm$	$z_2 = [?, ?]$			$p(z_2 X) = [0.90, 0.10]$	
$x_3 = 166cm$	$z_3 = [?, ?]$			$p(z_3 X) = [0.60, 0.40]$	
$x_4 = 175cm$	$z_4 = [?, ?]$			$p(z_4 X) = [0.95, 0.05]$	
$x_5 = 160cm$	$z_5 = [?, ?]$			$p(z_5 X) = [0.10, 0.90]$	
$x_6 = 155cm$	$z_6 = [?, ?]$			$p(z_6 X) = [0.05, 0.95]$	
$x_7 = 165cm$	$z_7 = [?, ?]$			$p(z_7 X) = [0.50, 0.50]$	
$x_8 = 162cm$	$z_8 = [?, ?]$			$p(z_8 X) = [0.30, 0.70]$	
$x_9 = 150cm$	$z_9 = [?, ?]$			$p(z_9 X) = [0.01, 0.99]$	

Responsibility

$\gamma_n = [\gamma_{n1}, \gamma_{n2}]$

We cannot say  $z_{nk} = 1$  for some  $k$  with absolute certainty

To deal with uncertainty, we estimate the **posterior** of  $z_{nk} = 1$

- Use posteriors instead of latent variables
  - Take into account the uncertainty of latent variables (genders)

Genders known

$$S_k[1] = \sum_{n=1}^N z_{nk} \quad S_k[\mathbf{x}] = \sum_{n=1}^N z_{nk} \mathbf{x}_n$$
$$S_k[\mathbf{x}\mathbf{x}^T] = \sum_{n=1}^N z_{nk} \mathbf{x}_n \mathbf{x}_n^T$$



Genders unknown

$$S_k[1] = \sum_{n=1}^N \gamma_{nk} \quad S_k[\mathbf{x}] = \sum_{n=1}^N \gamma_{nk} \mathbf{x}_n$$
$$S_k[\mathbf{x}\mathbf{x}^T] = \sum_{n=1}^N \gamma_{nk} \mathbf{x}_n \mathbf{x}_n^T$$

Ratio:  $\pi_k^* = \frac{S_k[1]}{S[1]}$     Average:  $\mu_k^* = \frac{S_k[\mathbf{x}]}{S_k[1]}$     Variance:  $\Lambda_k^{-1*} = \frac{S_k[\mathbf{x}\mathbf{x}]}{S_k[1]} - \mu_k \mu_k^T$

How to estimate  $z$  or  $\gamma$

$K$ -means algorithm (hard EM)  
(deterministic hard assignment)

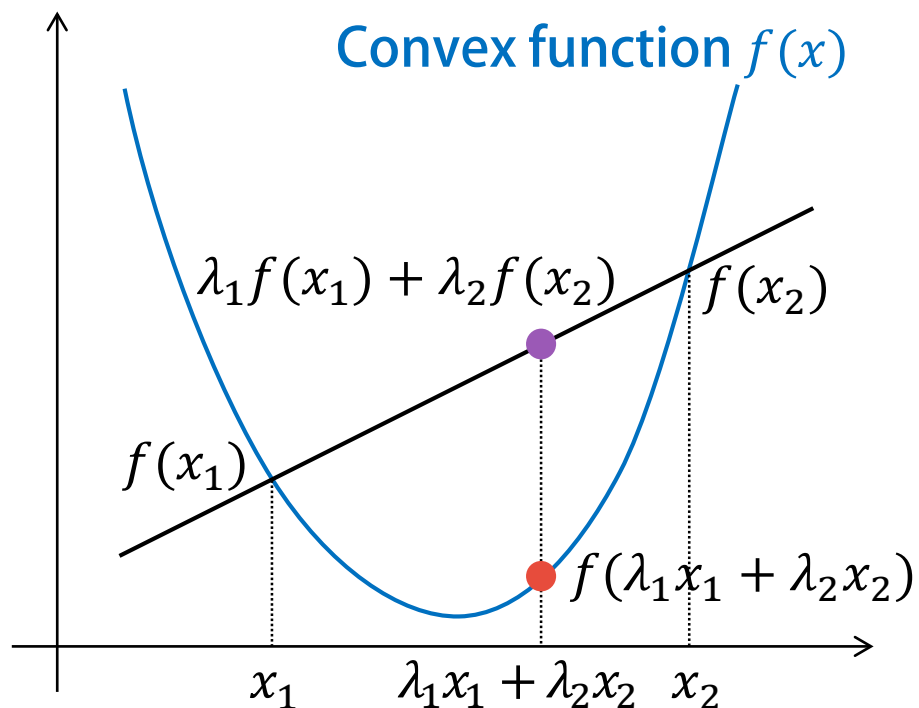
EM algorithm  
(deterministic soft assignment)

- Generative story of the GMM
  - Draw each latent variable:  $z_n \sim \text{Categorical}(z_n | \pi)$
  - Draw each observed variable:  $x_n \sim \prod_{k=1}^K N(x_n | \mu_k, \Lambda_k^{-1})^{z_{nk}}$
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Latent variables $Z$	Posterior calculation $p(Z X; \pi, \mu, \Lambda)$	Posterior calculation $p(Z, \pi, \mu, \Lambda X)$
Parameters $\pi, \mu, \Lambda$	Point estimation $\pi^*, \mu^*, \Lambda^* = \text{argmax } p(X; \pi, \mu, \Lambda)$	



- A basic inequality for convex functions
  - Forms the basis of the EM and VB algorithms



$$f\left(\sum_{k=1}^K \lambda_k x_k\right) \leq \sum_{k=1}^K \lambda_k f(x_k)$$

for auxiliary variables  $\lambda$   
such that  $\sum_{k=1}^K \lambda_k = 1$

$$f\left(\int q(x) x dx\right) \leq \int q(x) f(x) dx$$

for auxiliary distribution  $q(x)$   
such that  $\int q(x) dx = 1$

# How to Use Jensen's Inequality

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- Change the order of “sum” and “convex function”
  - Example: negative log of sum  $\rightarrow$  sum of negative log

$$-\log\left(\sum_{k=1}^K x_k\right) = -\log\left(\sum_{k=1}^K \lambda_k \frac{x_k}{\lambda_k}\right) \leq -\sum_{k=1}^K \lambda_k \log\left(\frac{x_k}{\lambda_k}\right) \stackrel{\text{def}}{=} U(\lambda)$$

Upper bound

When does the equality holds true (when is  $U(x, \lambda)$  minimized)?

$\rightarrow$  Optimization problem with a constraint

$\rightarrow$  Method of Lagrange multipliers

$$F(\lambda) \stackrel{\text{def}}{=} U(\lambda) + \omega \left(1 - \sum_{k=1}^K \lambda_k\right) \longrightarrow \frac{\partial F(\lambda)}{\partial \lambda_k} = -\log x_k + \log \lambda_k + 1 - \omega$$

Equality condition

Solving  $\frac{\partial F(\lambda)}{\partial \lambda_k} = 0$ , we get  $\lambda_k = x_k e^{\omega-1} \rightarrow e^{\omega-1} = \frac{1}{\sum_{k=1}^K x_k} \rightarrow \lambda_k = \frac{x_k}{\sum_{k=1}^K x_k}$

# How to Use Jensen's Inequality

19

- Change the order of “sum” and “convex function”
  - Example: negative log of sum  $\rightarrow$  sum of negative log

$$-\log \int p(x, z) dz = -\log \int q(z) \frac{p(x, z)}{q(z)} dz \leq - \int q(z) \log \frac{p(x, z)}{q(z)} \stackrel{\text{def}}{=} U(q(x))$$

Upper bound

When does the equality holds true (when is  $U(q(x))$  minimized)?

$\rightarrow$  Optimization problem with a constraint

$\rightarrow$  Method of Lagrange multipliers

$$\sum_{k=1}^K q(x) = 1$$

$F(q(x)) \stackrel{\text{def}}{=} U(q(x)) + \omega \left( 1 - \int q(x) dx \right) \rightarrow$  Minimize as in the previous slide

Equality condition

$$q(z) = \frac{p(x, z)}{\int p(x, z) dz} = \frac{p(x, z)}{p(x)} = p(z|x)$$

# The Expectation-Maximization Algorithm

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- A deterministic algorithm for ML estimation
  - Suppose a probabilistic model  $p(\mathbf{X}, \mathbf{Z}; \boldsymbol{\theta}) = p(\mathbf{X}|\mathbf{Z}; \boldsymbol{\theta})p(\mathbf{Z}; \boldsymbol{\theta})$ 
    - $\mathbf{X}$ : observed variables    $\mathbf{Z}$ : latent variables    $\boldsymbol{\theta}$ : parameters
  - We aim to get ML estimates  $\boldsymbol{\theta}^* = \operatorname{argmax} p(\mathbf{X}; \boldsymbol{\theta})$  Intractable!

$$\log p(\mathbf{X}; \boldsymbol{\theta}) = \log \int p(\mathbf{X}, \mathbf{Z}; \boldsymbol{\theta}) d\mathbf{Z}$$

$$= \log \int q(\mathbf{Z}) \frac{p(\mathbf{X}, \mathbf{Z}; \boldsymbol{\theta})}{q(\mathbf{Z})} d\mathbf{Z}$$

Introduce an arbitrary distribution  $q(\mathbf{Z})$   
called a variational distribution

$$\geq \int q(\mathbf{Z}) \log \frac{p(\mathbf{X}, \mathbf{Z}; \boldsymbol{\theta})}{q(\mathbf{Z})} d\mathbf{Z}$$

Jensen's  
inequality

The equality holds true  
when  $q^*(\mathbf{Z}) = p(\mathbf{Z}|\mathbf{X}; \boldsymbol{\theta})$

$$= \int q(\mathbf{Z}) \log p(\mathbf{X}, \mathbf{Z}; \boldsymbol{\theta}) d\mathbf{Z} - \int q(\mathbf{Z}) \log q(\mathbf{Z})$$

E-step

M-step

→ Maximize lower bound  
with respect to  $\boldsymbol{\theta}$

Hard EM:  $q^*(\mathbf{Z}) = \delta_{\mathbf{Z}^*}(\mathbf{Z})$   
 $\mathbf{Z}^* = \operatorname{argmax} p(\mathbf{Z}|\mathbf{X}; \boldsymbol{\theta})$

- Iterate **E-step** and **M-step** alternately

- E-step:** Calculate a posterior distribution over latent variables  $\mathbf{Z}$

$$\begin{array}{lll} \mathbf{x}_1 = 180\text{cm} & \mathbf{z}_1 = [?, ?] & \boldsymbol{\gamma}_1 = p(\mathbf{z}_1 | \mathbf{X}) = [0.99, 0.01] \\ \mathbf{x}_2 = 170\text{cm} & \mathbf{z}_2 = [?, ?] & \boldsymbol{\gamma}_2 = p(\mathbf{z}_2 | \mathbf{X}) = [0.90, 0.10] \\ \mathbf{x}_3 = 166\text{cm} & \mathbf{z}_3 = [?, ?] & \boldsymbol{\gamma}_3 = p(\mathbf{z}_3 | \mathbf{X}) = [0.60, 0.40] \end{array}$$

$$q^*(\mathbf{Z}) = p(\mathbf{Z} | \mathbf{X}; \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = \prod_{n=1}^N p(\mathbf{z}_n | \mathbf{x}_n; \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = \prod_{n=1}^N \prod_{k=1}^K \gamma_{nk}^{z_{nk}}$$

Responsibility

$$q^*(z_{nk} = 1) = p(z_{nk} = 1 | \mathbf{x}_n; \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})$$

$$\begin{aligned} &= \frac{p(\mathbf{x}_n, z_{nk} = 1; \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})}{\sum_{k'=1}^K p(\mathbf{x}_n, z_{nk'} = 1; \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})} \\ &= \frac{\pi_k N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1})}{\sum_{k'=1}^K \pi_{k'} N(\mathbf{x}_n | \boldsymbol{\mu}_{k'}, \boldsymbol{\Lambda}_{k'}^{-1})} = \gamma_{nk} \end{aligned}$$

How well the sample  $\mathbf{x}_n$  is explained by each cluster

||

How likely the sample  $\mathbf{x}_n$  was to be generated from each cluster

- Iterate **E-step** and **M-step** alternately

- M-step**: Update parameters  $\pi, \mu, \Lambda$

- Calculate sufficient statistics

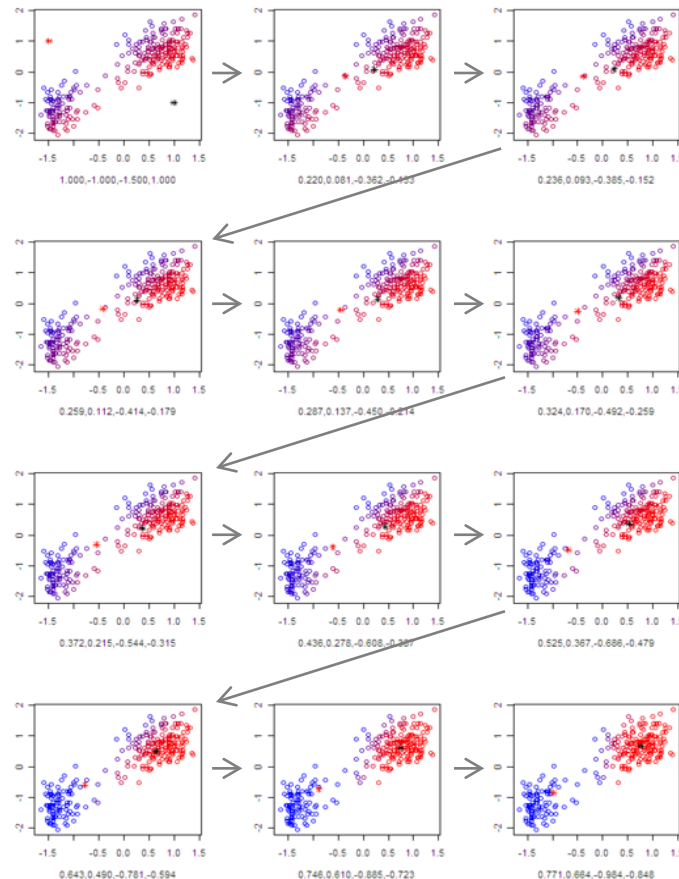
$$S_k[1] = \sum_{n=1}^N \gamma_{nk} \quad S_k[\mathbf{x}] = \sum_{n=1}^N \gamma_{nk} \mathbf{x}_n$$

$$S_k[\mathbf{x}\mathbf{x}^T] = \sum_{n=1}^N \gamma_{nk} \mathbf{x}_n \mathbf{x}_n^T$$

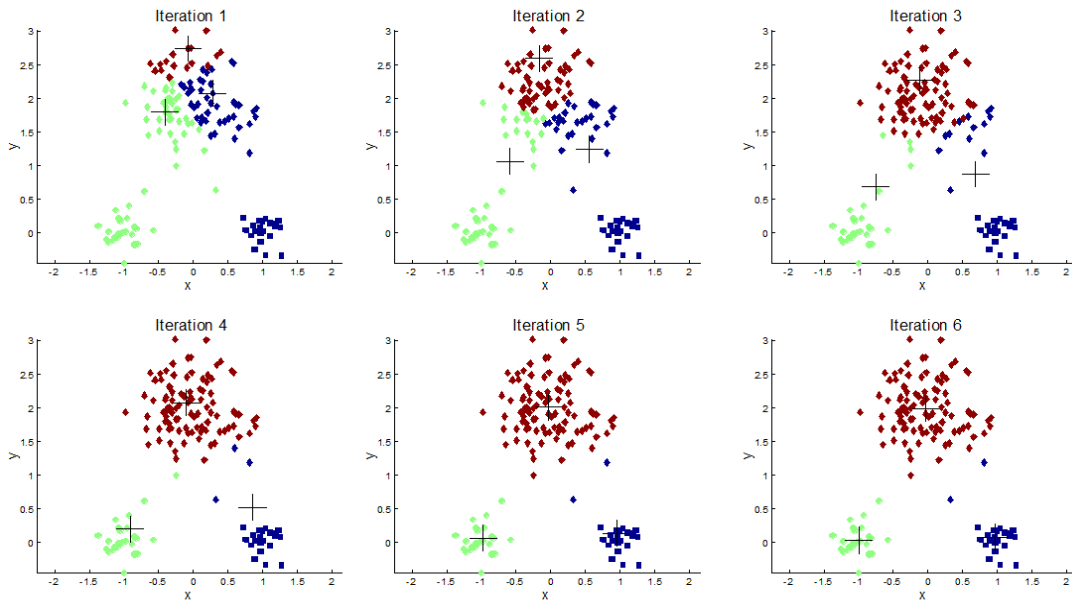
- Estimate parameters

$$\text{Ratio: } \pi_k^* = \frac{S_k[1]}{S.[1]} \quad \text{Mean: } \mu_k^* = \frac{S_k[\mathbf{x}]}{S_k[1]}$$

$$\text{Variance: } \Lambda_k^{-1*} = \frac{S_k[\mathbf{x}\mathbf{x}]}{S_k[1]} - \mu_k \mu_k^T$$



- Iterate M-step and M-step alternately
  - **M-step:** Update latent variables  $Z$  Hard assignment
    - ♦  $Z^* = \operatorname{argmax} p(Z|X; \pi, \mu, \Lambda) = \operatorname{argmax} p(X, Z; \pi, \mu, \Lambda)$
  - **M-step:** Update parameters  $\pi, \mu, \Lambda$ 
    - ♦  $\pi^*, \mu^*, \Lambda^* = \operatorname{argmax} p(X|Z; \pi, \mu, \Lambda) = \operatorname{argmax} p(X, Z; \pi, \mu, \Lambda)$



If the all  $\Lambda_k$ 's are same,  
the hard EM for GMM  
reduces to the  
*k*-means algorithm

- A key difference lies in how to deal with **uncertainty**

	<i>K</i> -means algorithm	EM algorithm
Latent variables $Z$	Optimizing	Marginalizing out
Parameters $\pi, \mu, \Lambda$	Optimizing	Optimizing

$$\begin{aligned}
 S_k[1] &= \sum_{n=1}^N z_{nk} & S_k[\mathbf{x}] &= \sum_{n=1}^N z_{nk} \mathbf{x}_n & \Rightarrow & S_k[1] = \sum_{n=1}^N \gamma_{nk} & S_k[\mathbf{x}] &= \sum_{n=1}^N \gamma_{nk} \mathbf{x}_n \\
 S_k[\mathbf{x}\mathbf{x}^T] &= \sum_{n=1}^N z_{nk} \mathbf{x}_n \mathbf{x}_n^T & & & & S_k[\mathbf{x}\mathbf{x}^T] &= \sum_{n=1}^N \gamma_{nk} \mathbf{x}_n \mathbf{x}_n^T
 \end{aligned}$$

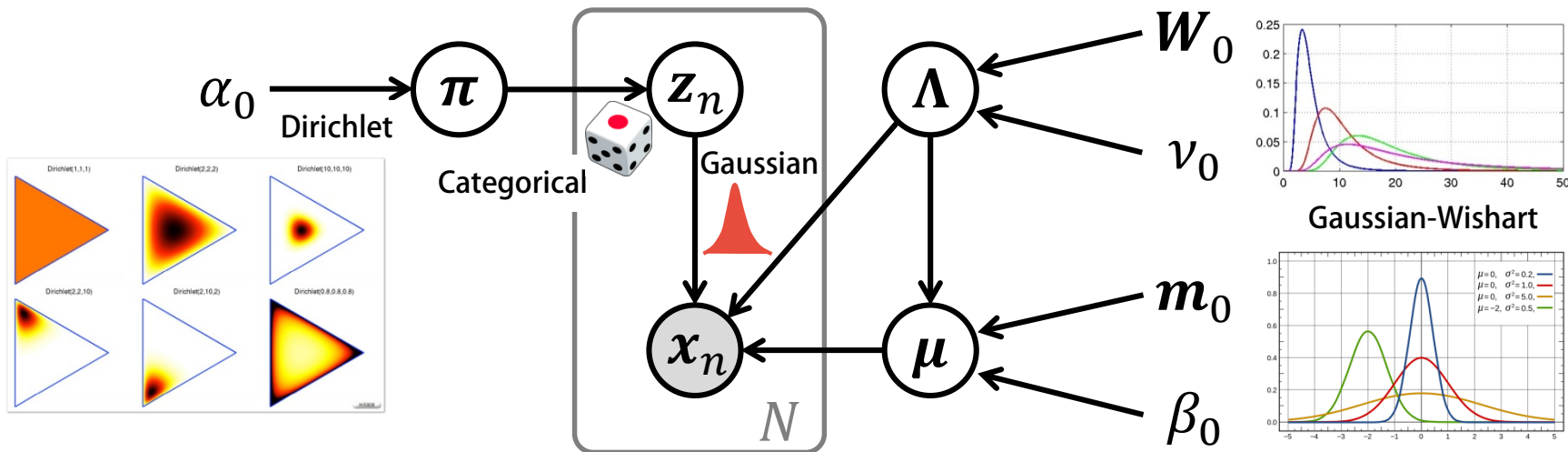
$$\text{Ratio: } \pi_k^* = \frac{S_k[1]}{S.[1]} \quad \text{Mean: } \mu_k^* = \frac{S_k[\mathbf{x}]}{S_k[1]} \quad \text{Variance: } \Lambda_k^{-1*} = \frac{S_k[\mathbf{x}\mathbf{x}]}{S_k[1]} - \mu_k \mu_k^T$$



# Bayesian Estimation of **Finite** Gaussian Mixture Models

(Collapsed) Gibbs Sampling  
(Collapsed) Variational Bayes

- Regard parameters as random variables
  - Introduce **prior distributions** on parameters
    - The Dirichlet distribution
      - A conjugate prior on categorical distributions
    - The Gaussian-Wishart distribution
      - A conjugate prior on Gaussian distributions



- Regard parameters as random variables
  - Introduce prior distributions on parameters
  - Calculate **posterior distributions** on random variables

## Maximum likelihood estimation

Latent variables:  $p(Z|X; \pi, \mu, \Lambda)$

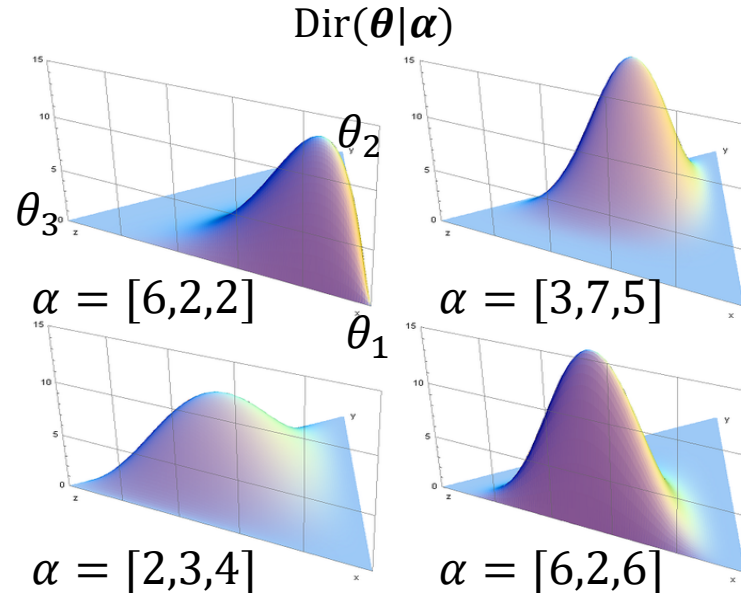
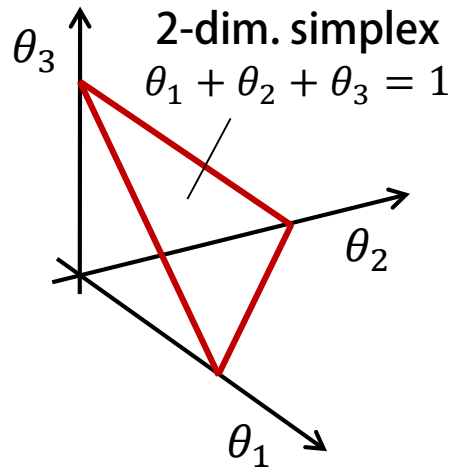
$$\text{Ratio: } \pi_k^* = \frac{S_k[1]}{S.[1]} \quad \text{Mean: } \mu_k^* = \frac{S_k[x]}{S_k[1]} \quad \text{Variance: } \Lambda_k^{-1*} = \frac{S_k[xx]}{S_k[1]} - \mu_k \mu_k^T$$

## Bayesian estimation

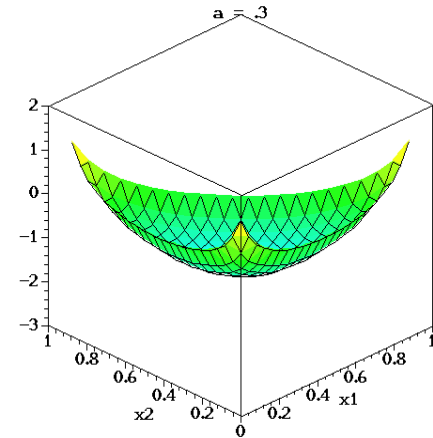
$$\underbrace{p(X|Z, \mu, \Lambda)}_{\text{Likelihood}} p(Z|\pi) \times \underbrace{p(\pi)p(\mu, \Lambda)}_{\text{Prior}} \longrightarrow \underbrace{p(Z, \pi, \mu, \Lambda|X)}_{\text{Posterior}}$$

$$\text{Bayes' theorem: } p(Z, \pi, \mu, \Lambda|X) = \frac{p(X|Z, \mu, \Lambda)p(Z|\pi)p(\pi)p(\mu, \Lambda)}{p(X)}$$

- Widely used for mathematical convenience
  - The posterior  $p(\theta|X)$  takes the same form of the prior  $p(\theta)$  for a particular type of the likelihood  $p(X|\theta)$ 
    - $p(\pi), p(\pi|Z)$ : Dirichlet  $p(Z|\pi)$ : Categorical
    - $p(\mu, \Lambda), p(\mu, \Lambda|X, Z)$ : Gaussian-Wishart  $p(X|Z, \mu, \Lambda)$ : Gaussian



Changing  $\alpha$  from 0 to 2



- Generative story of the GMM
  - Draw each latent variable:  $z_n \sim \text{Categorical}(z_n|\pi)$
  - Draw each observed variable:  $x_n \sim \prod_{k=1}^K N(x_n|\mu_k, \Lambda_k^{-1})^{z_{nk}}$
- Two major approaches

	Maximum likelihood (ML) estimation	Bayesian estimation
Probabilistic model	$p(X, Z; \mu, \Lambda)$ $= p(X Z; \mu, \Lambda)p(Z; \pi)$	$p(X, Z, \mu, \Lambda)$ $= p(X Z, \mu, \Lambda)p(Z, \pi)p(\pi, \mu, \Lambda)$
Latent variables $Z$	Posterior calculation $p(Z X; \pi, \mu, \Lambda)$	Posterior calculation $p(Z, \pi, \mu, \Lambda X)$
Parameters $\pi, \mu, \Lambda$	Point estimation $\pi^*, \mu^*, \Lambda^* = \text{argmax } p(X; \pi, \mu, \Lambda)$	

- Estimate the ratios, averages, and variances

	$k = 1$	$k = 2$
$x_1 = 180cm$	$z_1 = [1, 0]$	
$x_2 = 170cm$	$z_2 = [0, 1]$	
$x_3 = 166cm$	$z_3 = [1, 0]$	
$x_4 = 175cm$	$z_4 = [1, 0]$	
$x_5 = 160cm$	$z_5 = [1, 0]$	
$x_6 = 155cm$	$z_6 = [0, 1]$	
$x_7 = 165cm$	$z_7 = [0, 1]$	
$x_8 = 162cm$	$z_8 = [1, 0]$	
$x_9 = 150cm$	$z_9 = [0, 1]$	

Sufficient statistics for each cluster  $k$  (male or female)

$$S_k[1] = \sum_{n=1}^N z_{nk} \quad \text{Count}$$

$$S_k[x] = \sum_{n=1}^N z_{nk} x_n \quad \text{Sum}$$

$$S_k[xx^T] = \sum_{n=1}^N z_{nk} x_n x_n^T$$

How to calculate the posterior distribution  $p(\pi, \mu, \Lambda | X, Z)$  ?

- Calculate a posterior distribution on parameters  $\pi$

- The generative story

- Prior:  $\pi \sim \text{Dir}(\alpha_0)$
- Likelihood:  $\mathbf{z}_n \sim \text{Categorical}(\mathbf{z}_n|\pi)$

$$p(\pi) = \text{Dir}(\pi|\alpha_0) = \frac{\Gamma(\sum_{k=1}^K \alpha_{0k})}{\prod_{k=1}^K \Gamma(\alpha_{0k})} \prod_{k=1}^K \pi_k^{\alpha_{0k}-1}$$

$$p(\mathbf{Z}|\pi) = \prod_{n=1}^N \text{Categorical}(\mathbf{z}_n|\pi) = \prod_{n=1}^N \prod_{k=1}^K \pi_k^{z_{nk}}$$

$$p(\pi|\mathbf{Z}) = \text{Dir}(\pi|\alpha) \propto \frac{\Gamma(\sum_{k=1}^K \alpha_{0k})}{\prod_{k=1}^K \Gamma(\alpha_{0k})} \prod_{k=1}^K \pi_k^{\alpha_{0k} + S_k[1] - 1}$$

Posterior  
count

Prior  
count

Actual  
count

$$\alpha_k = \alpha_{0k} + S_k[1]$$

Bayes' theorem:

$$\begin{aligned} p(\pi|\mathbf{Z}) &= \frac{p(\mathbf{Z}|\pi)p(\pi)}{p(\mathbf{Z})} \\ &\propto p(\mathbf{Z}|\pi)p(\pi) \end{aligned}$$

We do not need to  
directly calculate  
the normalizing factor

- Calculate a posterior distribution on parameters  $\mu, \Lambda$ 
  - The generative story
    - Prior:  $\mu_k, \Lambda_k \sim N(\mu_k | \mathbf{m}_0, (\beta_0 \Lambda_k)^{-1}) W(\Lambda_k | \mathbf{W}_0, \nu_0)$
    - Likelihood:  $\mathbf{x}_n \sim \prod_{k=1}^K N(\mathbf{x}_n | \mu_k, \Lambda_k^{-1})^{z_{nk}}$

$$p(\mu, \Lambda) = \prod_{k=1}^K N(\mu_k | \mathbf{m}_0, (\beta_0 \Lambda_k)^{-1}) W(\Lambda_k | \mathbf{W}_0, \nu_0)$$

$$p(\mathbf{X} | \mathbf{Z}, \mu, \Lambda) = \prod_{n=1}^N \prod_{k=1}^K N(\mathbf{x}_n | \mu_k, \Lambda_k^{-1})^{z_{nk}}$$

$$p(\mu, \Lambda | \mathbf{X}, \mathbf{Z}) = \prod_{k=1}^K N(\mu_k | \mathbf{m}_k, (\beta_k \Lambda_k)^{-1}) W(\Lambda_k | \mathbf{W}_k, \nu_k)$$

Bayes'  
theorem

Posterior  
count

Prior  
count

Actual  
count

$$\beta_k = \beta_0 + S_k[1]$$

$$\mathbf{m}_k = \frac{\beta_0 \mathbf{m}_0 + S_k[\mathbf{x}]}{\beta_0 + S_k[1]}$$

$$\nu_k = \nu_0 + S_k[1]$$

$$\mathbf{W}_k^{-1} = \mathbf{W}_0^{-1} + \beta_0 \mathbf{m}_0 \mathbf{m}_0^T + S_k[\mathbf{x} \mathbf{x}^T] - \beta_k \mathbf{m}_k \mathbf{m}_k^T$$



- Use posteriors instead of latent variables

	$k = 1$	$k = 2$		$k = 1$	$k = 2$
$x_1 = 180cm$	$z_1 = [?, ?]$			$p(z_1 X) = [0.99, 0.01]$	
$x_2 = 170cm$	$z_2 = [?, ?]$			$p(z_2 X) = [0.90, 0.10]$	
$x_3 = 166cm$	$z_3 = [?, ?]$			$p(z_3 X) = [0.60, 0.40]$	
$x_4 = 175cm$	$z_4 = [?, ?]$			$p(z_4 X) = [0.95, 0.05]$	
$x_5 = 160cm$	$z_5 = [?, ?]$			$p(z_5 X) = [0.10, 0.90]$	
$x_6 = 155cm$	$z_6 = [?, ?]$			$p(z_6 X) = [0.05, 0.95]$	
$x_7 = 165cm$	$z_7 = [?, ?]$			$p(z_7 X) = [0.50, 0.50]$	
$x_8 = 162cm$	$z_8 = [?, ?]$			$p(z_8 X) = [0.30, 0.70]$	
$x_9 = 150cm$	$z_9 = [?, ?]$			$p(z_9 X) = [0.01, 0.99]$	

Responsibility

$\gamma_n = [\gamma_{n1}, \gamma_{n2}]$

We cannot say  $z_{nk} = 1$  for some  $k$  with absolute certainty

To deal with uncertainty, we estimate the **posterior** of  $z_{nk} = 1$

- Use posteriors instead of latent variables
  - Take into account the uncertainty of latent variables (genders)

## Hard assignment

$$S_k[1] = \sum_{n=1}^N z_{nk} \quad S_k[\mathbf{x}] = \sum_{n=1}^N z_{nk} \mathbf{x}_n$$
$$S_k[\mathbf{x}\mathbf{x}^T] = \sum_{n=1}^N z_{nk} \mathbf{x}_n \mathbf{x}_n^T$$



## Soft assignment

$$S_k[1] = \sum_{n=1}^N \gamma_{nk} \quad S_k[\mathbf{x}] = \sum_{n=1}^N \gamma_{nk} \mathbf{x}_n$$
$$S_k[\mathbf{x}\mathbf{x}^T] = \sum_{n=1}^N \gamma_{nk} \mathbf{x}_n \mathbf{x}_n^T$$

How to estimate  $z$  or  $\gamma$

Gibbs sampling  
(stochastic algorithm)

Variational Bayes  
(deterministic algorithm)

- Generative story of the GMM
  - Draw each latent variable:  $z_n \sim \text{Categorical}(z_n|\pi)$
  - Draw each observed variable:  $x_n \sim \prod_{k=1}^K N(x_n|\mu_k, \Lambda_k^{-1})^{z_{nk}}$
- Two major approaches

	Maximum likelihood (ML) estimation	Bayesian estimation
Probabilistic model	$p(X, Z; \mu, \Lambda)$ $= p(X Z; \mu, \Lambda)p(Z; \pi)$	$p(X, Z, \mu, \Lambda)$ $= p(X Z, \mu, \Lambda)p(Z, \pi)p(\pi, \mu, \Lambda)$
Latent variables $Z$	Posterior calculation $p(Z X; \pi, \mu, \Lambda)$	Posterior calculation $p(Z, \pi, \mu, \Lambda X)$
Parameters $\pi, \mu, \Lambda$	Point estimation $\pi^*, \mu^*, \Lambda^* = \text{argmax } p(X; \pi, \mu, \Lambda)$	

# Gibbs Sampling vs. Variational Bayes

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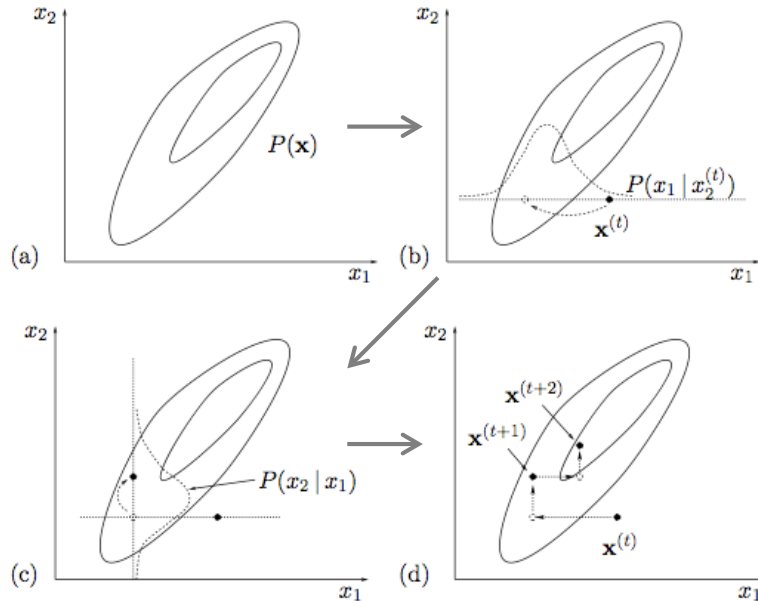
- Choose an appropriate approach according to situations
  - Each approach has pros and cons
  - In general, Gibbs sampling is easy to implement

	Gibbs sampling	Variational Bayes
Convergence to true posterior	Yes	No
Judgment of convergence	Difficult	Easy
Convergence speed	Slow	Fast
Quality of estimation results	High	Moderate

# The Gibbs Sampling

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- A popular variant of Markov chain Monte Carlo (MCMC)
  - Generate random samples from a probability distribution
$$p(\mathbf{X}) = \frac{f(\mathbf{X})}{Z}$$
even if the normalizing factor  $Z$  is intractable
  - The acceptance ratio is 100%



Objective: Generate independent samples from a probability distribution  $p(\mathbf{X})$

1. Divide  $\mathbf{X}$  into several groups  $\mathbf{X}_1, \dots, \mathbf{X}_M$

2. for  $t = 1:T$

for  $m = 1:M$

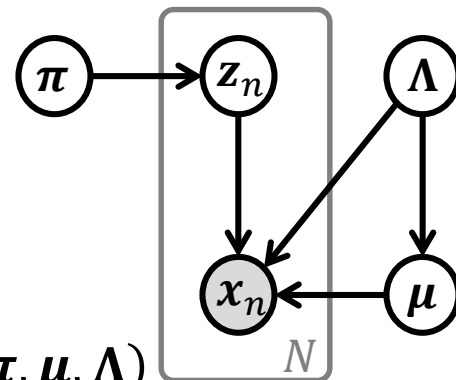
Sample  $\mathbf{X}_m^{(t+1)}$

$\sim p(\mathbf{X}_m^{(t+1)} | \mathbf{X}_1^{(t+1)}, \dots, \mathbf{X}_{m-1}^{(t+1)}, \mathbf{X}_{m+1}^{(t)}, \dots, \mathbf{X}_M^{(t)})$

3. Pick up  $\mathbf{X}^{(t)}$  with a certain interval

This sampling needs to be done easily

- Generate samples from  $p(\mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda} | \mathbf{X})$ 
  - Divide  $\{\mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}\}$  into  $\{\mathbf{z}_1\}, \{\mathbf{z}_2\}, \dots, \{\mathbf{z}_N\}, \{\boldsymbol{\pi}\}, \{\boldsymbol{\mu}, \boldsymbol{\Lambda}\}$
  - Iterate until convergence
    - for  $n = 1:N$ 
      - Sample  $\mathbf{z}_n \sim p(\mathbf{z}_n | \mathbf{X}, \mathbf{Z}_{-n}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = p(\mathbf{z}_n | \mathbf{x}_n, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})$
      - Sample  $\boldsymbol{\pi} \sim p(\boldsymbol{\pi} | \mathbf{X}, \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = p(\boldsymbol{\pi} | \mathbf{Z})$
      - Sample  $\boldsymbol{\mu}, \boldsymbol{\Lambda} \sim p(\boldsymbol{\mu}, \boldsymbol{\Lambda} | \mathbf{X}, \mathbf{Z}, \boldsymbol{\pi}) = p(\boldsymbol{\mu}, \boldsymbol{\Lambda} | \mathbf{X}, \mathbf{Z})$



$$p(z_{nk} = 1 | \mathbf{x}_n, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = \frac{\pi_k N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)}{\sum_{k'=1}^K \pi_{k'} N(\mathbf{x}_n | \boldsymbol{\mu}_{k'}, \boldsymbol{\Lambda}_{k'})}$$

$$p(\boldsymbol{\pi} | \mathbf{Z}) = \text{Dir}(\boldsymbol{\pi} | \boldsymbol{\alpha})$$

$$p(\boldsymbol{\mu}, \boldsymbol{\Lambda} | \mathbf{X}, \mathbf{Z}) = \prod_{k=1}^K N(\boldsymbol{\mu}_k | \mathbf{m}_k, (\beta_k \boldsymbol{\Lambda}_k)^{-1}) W(\boldsymbol{\Lambda}_k | \mathbf{W}_k, \nu_k)$$

EM algorithm:  
soft assignment

Gibbs sampling:  
hard assignment

See "Posterior Calculation: Genders Known"

- A Bayesian extension of the EM algorithm
  - We aim to approximate a true posterior  $p(\mathbf{Z}|\mathbf{X}) = p(\mathbf{Z}|\mathbf{X})/p(\mathbf{X})$  as a factorizable distribution  $q(\mathbf{Z}) = \prod_{m=1}^M q(\mathbf{Z}_m)$

Intractable!

$$\log p(\mathbf{X}) = \log \int p(\mathbf{X}, \mathbf{Z}) d\mathbf{Z} = \log \int q(\mathbf{Z}) \frac{p(\mathbf{X}, \mathbf{Z})}{q(\mathbf{Z})} d\mathbf{Z} \geq \int q(\mathbf{Z}) \log \frac{p(\mathbf{X}, \mathbf{Z})}{q(\mathbf{Z})} d\mathbf{Z}$$

Jensen's inequality

$$= \int \left( \prod_{m=1}^M q(\mathbf{Z}_m) \right) \left( \log p(\mathbf{X}, \mathbf{Z}) - \sum_{m=1}^M \log q(\mathbf{Z}_m) \right) d\mathbf{Z}_1 d\mathbf{Z}_2 \cdots d\mathbf{Z}_M$$

$$= \sum_{m=1}^M \left( \int q(\mathbf{Z}_m) \left( \int q(\mathbf{Z}_{-m}) \log p(\mathbf{X}, \mathbf{Z}) d\mathbf{Z}_{-m} \right) d\mathbf{Z}_m - \int q(\mathbf{Z}_m) \log q(\mathbf{Z}_m) d\mathbf{Z}_m \right)$$

The lower bound is maximized when  $\log q^*(\mathbf{Z}_m) = \langle \log p(\mathbf{X}, \mathbf{Z}) \rangle_{q(\mathbf{Z}_{-m})} + \text{const.}$

The equality does NOT hold true!

VB-E step

VB-M step

- VB just **approximates** a true posterior  $p(\mathbf{Z}|\mathbf{X})$ 
  - The accuracy depends on how to factorize a variational posterior  $q(\mathbf{Z})$

$$\log p(\mathbf{X}) = \int q(\mathbf{Z}) \log p(\mathbf{X}) d\mathbf{Z} = \int q(\mathbf{Z}) \log \frac{q(\mathbf{Z})p(\mathbf{X}, \mathbf{Z})}{q(\mathbf{Z})p(\mathbf{Z}|\mathbf{X})} d\mathbf{Z}$$

$$= \int q(\mathbf{Z}) \log \frac{p(\mathbf{X}, \mathbf{Z})}{q(\mathbf{Z})} d\mathbf{Z} + \int q(\mathbf{Z}) \log \frac{q(\mathbf{Z})}{p(\mathbf{Z}|\mathbf{X})} d\mathbf{Z}$$

$$= \text{LowerBound}(q) + \text{KL}(q||p)$$

$\downarrow$   
**Maximize** = **Minimize**

**Kullback-Leibler (KL) divergence**  
between  
a variational posterior  $q(\mathbf{Z})$   
and a true posterior  $p(\mathbf{Z}|\mathbf{X})$

The KD divergence is 0 when  $q(\mathbf{Z}) = p(\mathbf{Z}|\mathbf{X})$  (intractable!)

If  $q(\mathbf{Z})$  is assumed to be factorized, the KD divergence cannot be 0!



- Approximate a true posterior  $p(\mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda} | \mathbf{X})$ 
  - Assume a variational distribution  $q(\mathbf{Z})q(\boldsymbol{\pi})q(\boldsymbol{\mu}, \boldsymbol{\Lambda}) \approx p(\mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda} | \mathbf{X})$
  - Iteratively update (optimize) each factor
    - ♦ VB-E step
      - $-\log q^*(\mathbf{Z}) = \langle \log p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})} + \text{const.}$   
–  $= \langle \log p(\mathbf{X} | \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) p(\mathbf{Z} | \boldsymbol{\pi}) \rangle_{q(\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})} + \text{const.}$
    - ♦ VB-M step
      - $-\log q^*(\boldsymbol{\pi}) = \langle \log p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda})} + \text{const.}$   
–  $= \langle \log p(\mathbf{Z} | \boldsymbol{\pi}) p(\boldsymbol{\pi}) \rangle_{q(\mathbf{Z})} + \text{const.}$
      - $-\log q^*(\boldsymbol{\mu}, \boldsymbol{\Lambda}) = \langle \log p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z}, \boldsymbol{\pi})} + \text{const.}$   
–  $= \langle \log p(\mathbf{X} | \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z})} + \text{const.}$

Tractable posteriors: Use responsibilities instead of latent variables

- Formulate a full joint distribution

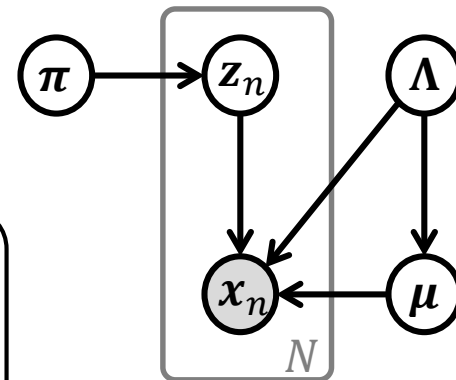
$$p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda})p(\mathbf{Z}|\boldsymbol{\pi})p(\boldsymbol{\pi})p(\boldsymbol{\mu}, \boldsymbol{\Lambda})$$

$$p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = \prod_{n=1}^N \prod_{k=1}^K N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1})^{z_{nk}}$$

$$p(\mathbf{Z}|\boldsymbol{\pi}) = \prod_{n=1}^N \text{Categorical}(\mathbf{z}_n | \boldsymbol{\pi}) = \prod_{n=1}^N \prod_{k=1}^K \pi_k^{z_{nk}}$$

$$p(\boldsymbol{\pi}) = \text{Dir}(\boldsymbol{\pi} | \boldsymbol{\alpha}_0) = \frac{\Gamma(\sum_{k=1}^K \alpha_{0k})}{\prod_{k=1}^K \Gamma(\alpha_{0k})} \prod_{k=1}^K \pi_k^{\alpha_{0k}-1}$$

$$p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) = \prod_{k=1}^K N(\boldsymbol{\mu}_k | \mathbf{m}_0, (\beta_0 \boldsymbol{\Lambda}_k)^{-1}) W(\boldsymbol{\Lambda}_k | \mathbf{W}_0, \nu_0)$$



Likelihood functions

Prior distributions

- Invoke the updating formula of VB
  - Take the expectation of the full joint probability distribution under “factorized” variational posteriors over other variables
  - Focus on only terms including  $\mathbf{Z}$   
(other terms can be absorbed into the normalization factor)

$$\begin{aligned}\log q^*(\mathbf{Z}) &= \langle \log p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})} + \text{const.} \\ &= \langle \log p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) p(\mathbf{Z}|\boldsymbol{\pi}) p(\boldsymbol{\pi}) p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})} + \text{const.} \\ &= \langle \log p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) p(\mathbf{Z}|\boldsymbol{\pi}) \rangle_{q(\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda})} + \text{const.}\end{aligned}$$

$$p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = \prod_{n=1}^N \prod_{k=1}^K N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1})^{z_{nk}}$$

$$p(\mathbf{Z}|\boldsymbol{\pi}) = \prod_{n=1}^N \text{Categorical}(\mathbf{z}_n | \boldsymbol{\pi}) = \prod_{n=1}^N \prod_{k=1}^K \pi_k^{z_{nk}}$$

- Proceed the calculation according the updating rule

$$\langle \log p(\mathbf{Z}|\boldsymbol{\pi}) \rangle_{q(\boldsymbol{\pi})} = \sum_{n=1}^N \sum_{k=1}^K z_{nk} \langle \log \pi_k \rangle_{q(\boldsymbol{\pi})}$$

$$\langle \log p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\boldsymbol{\mu}, \boldsymbol{\Lambda})} = \sum_{n=1}^N \sum_{k=1}^K z_{nk} \langle \log N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1}) \rangle_{q(\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)}$$



$$\log q^*(\mathbf{Z}) = \langle \log p(\mathbf{Z}|\boldsymbol{\pi}) \rangle_{q(\boldsymbol{\pi})} + \langle \log p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\boldsymbol{\mu}, \boldsymbol{\Lambda})} + \text{const.}$$


$$= \sum_{n=1}^N \sum_{k=1}^K z_{nk} \left( \langle \log \pi_k \rangle_{q(\boldsymbol{\pi})} + \langle \log N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1}) \rangle_{q(\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)} \right) + \text{const.}$$

$$= \sum_{n=1}^N \sum_{k=1}^K z_{nk} \log \rho_{nk} + \text{const.}$$

- Calculate the variational posterior over latent variables  $\mathbf{Z}$ 
  - The normalization factor is automatically determined

$$\log q^*(\mathbf{Z}) = \sum_{n=1}^N \sum_{k=1}^K z_{nk} \log \rho_{nk} + \text{const.}$$

The distribution should be appropriately normalized


$$\gamma_{nk} = \frac{\rho_{nk}}{\sum_{k'=1}^K \rho_{nk'}}$$

$$\log q^*(\mathbf{Z}) = \sum_{n=1}^N \sum_{k=1}^K z_{nk} \log \gamma_{nk}$$



$$q^*(\mathbf{Z}) = \prod_{n=1}^N \prod_{k=1}^K \gamma_{nk}^{z_{nk}} = \prod_{n=1}^N \text{Categorical}(\mathbf{z}_n | \boldsymbol{\gamma}_n)$$

Latent variables are categorical distributed!

- Invoke the updating formula of VB
  - Take the expectation of the full joint probability distribution under “factorized” variational posteriors over other variables
  - Focus on only terms including  $\mathbf{Z}$   
(other terms can be absorbed into the normalization factor)

$$\begin{aligned}\log q^*(\boldsymbol{\pi}) &= \langle \log p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda})} + \text{const.} \\ &= \langle \log p(\mathbf{Z} | \boldsymbol{\pi}) p(\boldsymbol{\pi}) \rangle_{q(\mathbf{Z})} + \text{const.} \\ &= \log p(\boldsymbol{\pi}) + \langle \log p(\mathbf{Z} | \boldsymbol{\pi}) \rangle_{q(\mathbf{Z})} + \text{const.}\end{aligned}$$

$$\begin{aligned}\log q^*(\boldsymbol{\mu}, \boldsymbol{\Lambda}) &= \langle \log p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z}, \boldsymbol{\pi})} + \text{const.} \\ &= \langle \log p(\mathbf{X} | \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z})} + \text{const.} \\ &= \log p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) + \langle \log p(\mathbf{X} | \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z})} + \text{const.}\end{aligned}$$

Bayesian estimation in simple conjugate models!  
(Use responsibilities  $q(\mathbf{Z})$  instead of latent variables  $\mathbf{Z}$ )

- Calculate the variational posteriors over parameters  $\pi, \mu, \Lambda$ 
  - The posteriors take the same forms of the priors

$$S_k[1] = \sum_{n=1}^N \gamma_{nk} \quad S_k[\mathbf{x}] = \sum_{n=1}^N \gamma_{nk} \mathbf{x}_n \quad S_k[\mathbf{x}\mathbf{x}^T] = \sum_{n=1}^N \gamma_{nk} \mathbf{x}_n \mathbf{x}_n^T$$

Sufficient statistics

$$p(\pi) = \text{Dir}(\pi | \alpha_0)$$



$$q^*(\pi) = \text{Dir}(\pi | \alpha)$$

$$\alpha_k = \alpha_{0k} + S_k[1]$$

Posterior  
count

Prior  
count

Actual  
count

$$\beta_k = \beta_0 + S_k[1]$$

$$\mathbf{m}_k = \frac{\beta_0 \mathbf{m}_0 + S_k[\mathbf{x}]}{\beta_0 + S_k[1]}$$

$$\nu_k = \nu_0 + S_k[1]$$

$$p(\mu, \Lambda) = \prod_{k=1}^K N(\mu_k | \mathbf{m}_0, (\beta_0 \Lambda_k)^{-1}) W(\Lambda_k | \mathbf{W}_0, \nu_0)$$



$$q^*(\mu, \Lambda) = \prod_{k=1}^K N(\mu_k | \mathbf{m}_k, (\beta_k \Lambda_k)^{-1}) W(\Lambda_k | \mathbf{W}_k, \nu_k)$$

$$\mathbf{W}_k^{-1} = \mathbf{W}_0^{-1} + \beta_0 \mathbf{m}_0 \mathbf{m}_0^T + S_k[\mathbf{x}\mathbf{x}^T] - \beta_k \mathbf{m}_k \mathbf{m}_k^T$$

- Both methods have similar updating formulas
  - EM: Using the **values** of parameters

$$\log p(\mathbf{Z}|\mathbf{X}; \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = \sum_{n=1}^N \sum_{k=1}^K z_{nk} \left( \log \pi_k + \log N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1}) \right) + \text{const.}$$

- VB: Using the **geometric means** of parameters

$$\log q^*(\mathbf{Z}) = \sum_{n=1}^N \sum_{k=1}^K z_{nk} \left( \langle \log \pi_k \rangle_{q(\boldsymbol{\pi})} + \langle \log N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1}) \rangle_{q(\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)} \right) + \text{const.}$$

$$\langle \log N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1}) \rangle_{q(\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)} = -\frac{D}{2} \log(2\pi) + \frac{1}{2} \langle \log \boldsymbol{\Lambda}_k \rangle - \frac{1}{2} \left( \frac{D}{\beta_k^{-1}} + v_k(\mathbf{x}_n - \mathbf{m}_k)^T \mathbf{W}_k (\mathbf{x}_n - \mathbf{m}_k) \right)$$

$$\langle \log |\boldsymbol{\Lambda}_k| \rangle_{q(\boldsymbol{\pi})} = \sum_{d=1}^D \psi \left( \frac{c_k + 1 - d}{2} \right) + D \log 2 + \log |\mathbf{W}_k|$$



# Log Function vs. Digamma Function

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- The digamma function results in sparsifying effect

- Example: Dirichlet distribution

- Mean  $\pi \sim \text{Dir}(\alpha)$

$$\begin{aligned} E[\pi_k] &= \frac{\alpha_k}{\sum_{k'=1}^K \alpha_{k'}} \\ &= \exp(\log(\alpha_k) - \log(\sum_{k'=1}^K \alpha_{k'})) \end{aligned}$$

- Geometric mean

$$\begin{aligned} G[\pi_k] &= \exp(E[\log \pi_k]) \\ &= \exp(\psi(\alpha_k) - \psi(\sum_{k'=1}^K \alpha_{k'})) \end{aligned}$$

$$\exp(\psi(0.1)) = 0.00003$$

$$\exp(\psi(0.5)) = 0.140$$

$$\exp(\psi(0.9)) = 0.470$$

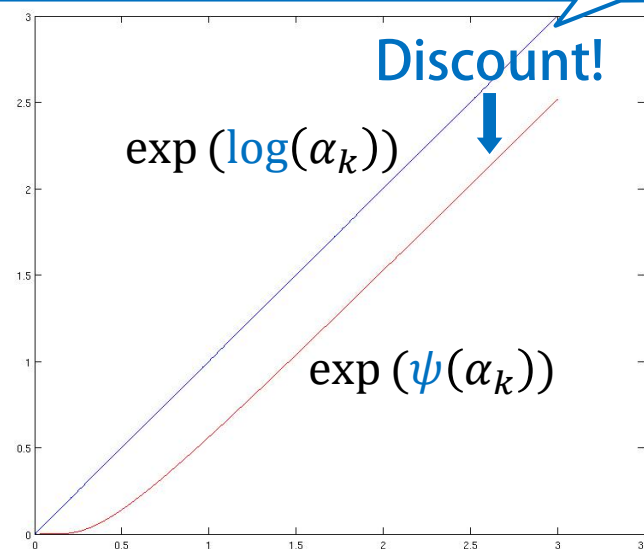
$$\exp(\psi(1)) = 0.561$$

$$\exp(\psi(10)) = 9.504$$

$$\exp(\psi(100)) = 99.5004$$

$$\exp(\psi(1000)) = 999.500$$

Small components tend to be degenerated in Bayesian mixture modeling



- Both methods are based on similar updating formulas

- GS: **Stochastic hard** assignment

$$p(z_{nk} = 1 | \mathbf{x}_n, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = \frac{\pi_k N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)}{\sum_{k'=1}^K \pi_{k'} N(\mathbf{x}_n | \boldsymbol{\mu}_{k'}, \boldsymbol{\Lambda}_{k'})}$$

- EM: **Deterministic soft** assignment

$$q^*(z_{nk} = 1 | \mathbf{x}_n, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = \frac{\pi_k N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)}{\sum_{k'=1}^K \pi_{k'} N(\mathbf{x}_n | \boldsymbol{\mu}_{k'}, \boldsymbol{\Lambda}_{k'})}$$

- VB: **Deterministic soft** assignment

$$q^*(z_{nk} = 1) = \frac{G[\pi_k] G[N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)]}{\sum_{k'=1}^K G[\pi_{k'}] G[N(\mathbf{x}_n | \boldsymbol{\mu}_{k'}, \boldsymbol{\Lambda}_{k'})]}$$

$$\left. \begin{aligned} S_k[1] &= \sum_{n=1}^N z_{nk} \\ S_k[\mathbf{x}] &= \sum_{n=1}^N z_{nk} \mathbf{x}_n \\ S_k[\mathbf{x}\mathbf{x}^T] &= \sum_{n=1}^N z_{nk} \mathbf{x}_n \mathbf{x}_n^T \end{aligned} \right\}$$

Replace  $z_{nk}$   
with  $\gamma_{nk}$

- Reduce the number of variables for **fast/better** estimation
  - The parameters can be **marginalized out** due to conjugacy

$$p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda})p(\mathbf{Z}|\boldsymbol{\pi})p(\boldsymbol{\pi})p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) \rightarrow p(\mathbf{X}|\mathbf{Z}) = p(\mathbf{X}|\mathbf{Z})p(\mathbf{Z})$$

$$p(\mathbf{Z}|\boldsymbol{\pi}) = \prod_{n=1}^N \text{Categorical}(\mathbf{z}_n|\boldsymbol{\pi}) = \prod_{n=1}^N \prod_{k=1}^K \pi_k^{z_{nk}}$$

$$p(\boldsymbol{\pi}) = \text{Dir}(\boldsymbol{\pi}|\boldsymbol{\alpha}_0)$$

Conjugacy holds true  
(Dirichlet-Categorical)

$$p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = \prod_{n=1}^N \prod_{k=1}^K N(\mathbf{x}_n|\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1})^{z_{nk}}$$

Marginalization over  $\boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}$   
is analytically tractable!

$$p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) = \prod_{k=1}^K N(\boldsymbol{\mu}_k|\mathbf{m}_0, (\beta_0 \boldsymbol{\Lambda}_k)^{-1})W(\boldsymbol{\Lambda}_k|\mathbf{W}_0, \nu_0)$$

Conjugacy holds true  
(Gaussian-Wishart-Gaussian)

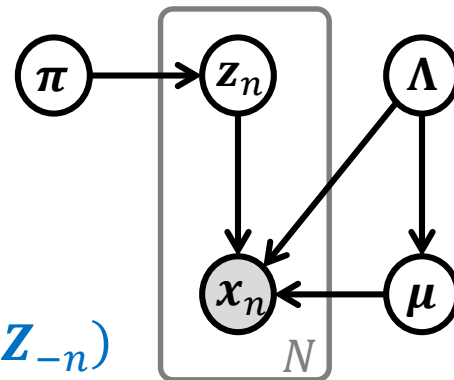
- Generate samples from  $p(\mathbf{Z}|\mathbf{X})$

- Divide  $\{\mathbf{Z}\}$  into  $\{\mathbf{z}_1\}, \{\mathbf{z}_2\}, \dots, \{\mathbf{z}_N\}$

- for  $t = 1:T$

- for  $n = 1:N$

- Sample  $\mathbf{z}_n \sim p(\mathbf{z}_n|\mathbf{X}, \mathbf{Z}_{-n}) = p(\mathbf{z}_n|\mathbf{x}_n, \mathbf{X}_{-n}, \mathbf{Z}_{-n})$



$$p(z_{nk} = 1|\mathbf{x}_n, \mathbf{X}_{-n}, \mathbf{Z}_{-n}) \propto p(z_{nk} = 1, \mathbf{x}_n|\mathbf{X}_{-n}, \mathbf{Z}_{-n})$$

$$= p(z_{nk} = 1|\mathbf{Z}_{-n})p(\mathbf{x}_n|z_{nk} = 1, \mathbf{X}_{-n}, \mathbf{Z}_{-n})$$

$$= \int p(z_{nk} = 1|\pi)p(\pi|\mathbf{Z}_{-n})d\pi \int p(\mathbf{x}_n|\mu_k, \Lambda_k)p(\mu_k, \Lambda_k|\mathbf{X}_{-n}, \mathbf{Z}_{-n}) d\mu_k d\Lambda_k$$

$$= \frac{\alpha_k^{(-n)}}{\sum_{k'=1}^K \alpha_{k'}^{(-n)}} \text{St}\left(\mathbf{x}_n \middle| \mathbf{m}_k^{(-n)}, \mathbf{L}_k^{(-n)}, \nu_k^{(-n)} + 1 - D\right)$$

Product of two predictive distributions

- Calculate predictive distributions
  - Marginalize likelihood functions under posteriors

$$\int \underbrace{p(z_{nk} = 1 | \boldsymbol{\pi})}_{\text{Likelihood}} \underbrace{p(\boldsymbol{\pi} | \mathbf{Z}_{-n})}_{\text{Posterior}} d\boldsymbol{\pi} = \int \pi_k \text{Dir}(\boldsymbol{\pi}_k | \boldsymbol{\alpha}^{(-n)}) d\boldsymbol{\pi} = \frac{\alpha_k^{(-n)}}{\sum_{k'=1}^K \alpha_{k'}^{(-n)}}$$

$$\int \underbrace{p(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)}_{\text{Likelihood}} \underbrace{p(\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k | \mathbf{X}_{-n}, \mathbf{Z}_{-n})}_{\text{Posterior}} d\boldsymbol{\mu}_k d\boldsymbol{\Lambda}_k$$

$$= \int N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1}) N(\boldsymbol{\mu}_k | \mathbf{m}_k^{(-n)}, (\boldsymbol{\beta}_k^{(-n)} \boldsymbol{\Lambda}_k)^{-1}) W(\boldsymbol{\Lambda}_k | \mathbf{W}_k^{(-n)}, \nu_k^{(-n)}) d\boldsymbol{\mu}_k d\boldsymbol{\Lambda}_k$$

$$= \text{St}(\mathbf{x}_n | \mathbf{m}_k^{(-n)}, \mathbf{L}_k^{(-n)}, \nu_k^{(-n)} + 1 - D)$$

$$\mathbf{L}_k^{(-n)} = \frac{\nu_k^{(-n)} + 1 - D}{1 + \beta_k^{(-n)}} \mathbf{W}_k^{(-n)}$$

$$S_k[1] = \sum_{n' \neq n} z_{n'k} \quad S_k[\mathbf{x}] = \sum_{n' \neq n} z_{n'k} \mathbf{x}_{n'}$$

$$S_k[\mathbf{x}\mathbf{x}^T] = \sum_{n' \neq n} z_{n'k} \mathbf{x}_{n'} \mathbf{x}_{n'}^T$$

- Approximate a posterior  $p(\mathbf{Z}|\mathbf{X})$ 
  - Assume a variational distribution  $\prod_{n=1}^N q(\mathbf{z}_n) \approx p(\mathbf{Z}|\mathbf{X})$
  - Iteratively update (optimize) each factor

• **CVB-E step**: Invoke the updating formula of VB

$$\begin{aligned}\log q^*(\mathbf{z}_n) &= \langle \log p(\mathbf{X}, \mathbf{Z}) \rangle_{q(\mathbf{z}_{-n})} + \text{const.} \\ &= \langle \log p(\mathbf{z}_n | \mathbf{X}, \mathbf{Z}_{-n}) p(\mathbf{X} | \mathbf{Z}_{-n}) p(\mathbf{Z}_{-n}) \rangle_{q(\mathbf{z}_{-n})} + \text{const.} \\ &= \langle \log p(\mathbf{z}_n | \mathbf{X}, \mathbf{Z}_{-n}) \rangle_{q(\mathbf{z}_{-n})} + \text{const.}\end{aligned}$$

$$\begin{aligned}p(z_{nk} = 1 | \mathbf{X}, \mathbf{Z}_{-n}) &\propto p(z_{nk} = 1, \mathbf{x}_n | \mathbf{X}_{-n}, \mathbf{Z}_{-n}) \\ &= \frac{\alpha_k^{(-n)}}{\sum_{k'=1}^K \alpha_{k'}^{(-n)}} \text{St} \left( \mathbf{x}_n | \mathbf{m}_k^{(-n)}, \mathbf{L}_k^{(-n)}, \nu_k^{(-n)} + 1 - D \right)\end{aligned}$$

Same as collapsed Gibbs sampling

- Calculate the variational posterior over latent variables  $\mathbf{Z}$ 
  - The normalization factor is automatically determined

$$\log q^*(z_{nk} = 1) = \langle \log p(\mathbf{z}_n | \mathbf{X}, \mathbf{Z}_{-n}) \rangle_{q(\mathbf{Z}_{-n})} + \text{const.}$$

$$= \left\langle \log \frac{\alpha_k^{(-n)}}{\sum_{k'=1}^K \alpha_{k'}^{(-n)}} + \log \text{St}(\mathbf{x}_n | \mathbf{m}_k^{(-n)}, \mathbf{L}_k^{(-n)}, v_k^{(-n)} + 1 - D) \right\rangle + \text{const.}$$

$$\approx \log \langle \alpha_k^{(-n)} \rangle - \log \sum_{k'=1}^K \langle \alpha_{k'}^{(-n)} \rangle$$

0-th order approximation (CVB0)  
 $E[\log x] \approx \log E[x]$

$$+ \log \text{St}(\mathbf{x}_n | \langle \mathbf{m}_k^{(-n)} \rangle, \langle \mathbf{L}_k^{(-n)} \rangle, \langle v_k^{(-n)} \rangle + 1 - D) + \text{const.}$$

$$S_k[1] = \sum_{n' \neq n} \gamma_{n'k} \quad S_k[\mathbf{x}] = \sum_{n' \neq n} \gamma_{n'k} \mathbf{x}_{n'} \quad S_k[\mathbf{x} \mathbf{x}^T] = \sum_{n' \neq n} \gamma_{n'k} \mathbf{x}_{n'} \mathbf{x}_{n'}^T$$

- Both methods are based on similar updating formulas
  - CGS: Stochastic **hard** assignment

$$p(z_{nk} = 1 | \mathbf{x}_n, \mathbf{X}_{-n}, \mathbf{Z}_{-n}) = \frac{\alpha_k^{(-n)}}{\sum_{k'=1}^K \alpha_{k'}^{(-n)}} \text{St} \left( \mathbf{x}_n \middle| \mathbf{m}_k^{(-n)}, \mathbf{L}_k^{(-n)}, \nu_k^{(-n)} + 1 - D \right)$$

$$S_k[1] = \sum_{n' \neq N} z_{n'k} \quad S_k[\mathbf{x}] = \sum_{n' \neq n} z_{n'k} \mathbf{x}_{n'} \quad S_k[\mathbf{x}\mathbf{x}^T] = \sum_{n' \neq n} z_{n'k} \mathbf{x}_{n'} \mathbf{x}_{n'}^T$$

- CVB: Deterministic **soft** assignment

$$q(z_{nk} = 1) = \frac{\langle \alpha_k^{(-n)} \rangle}{\sum_{k'=1}^K \langle \alpha_{k'}^{(-n)} \rangle} \text{St} \left( \mathbf{x}_n \middle| \langle \mathbf{m}_k^{(-n)} \rangle, \langle \mathbf{L}_k^{(-n)} \rangle, \langle \nu_k^{(-n)} \rangle + 1 - D \right)$$

$$S_k[1] = \sum_{n' \neq N} \gamma_{n'k} \quad S_k[\mathbf{x}] = \sum_{n' \neq n} \gamma_{n'k} \mathbf{x}_{n'} \quad S_k[\mathbf{x}\mathbf{x}^T] = \sum_{n' \neq n} \gamma_{n'k} \mathbf{x}_{n'} \mathbf{x}_{n'}^T$$



- All methods are based on similar updating formulas

- GS: **Stochastic hard** assignment

- $p(z_{nk} = 1 | \mathbf{x}_n, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \propto \pi_k N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)$

- CGS: **Stochastic hard** assignment

- $p(z_{nk} = 1 | \mathbf{x}_n, \mathbf{X}_{-n}, \mathbf{Z}_{-n}) = \frac{\alpha_k^{(-n)}}{\sum_{k'=1}^K \alpha_{k'}^{(-n)}} \text{St} \left( \mathbf{x}_n \middle| \mathbf{m}_k^{(-n)}, \mathbf{L}_k^{(-n)}, \nu_k^{(-n)} + 1 - D \right)$

- EM: **Deterministic soft** assignment

- $q^*(z_{nk} = 1 | \mathbf{x}_n, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \propto \pi_k N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)$

- VB: **Deterministic soft** assignment

- $q^*(z_{nk} = 1) \propto G[\pi_k] G[N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)]$

- CVB: **Deterministic soft** assignment

- $q(z_{nk} = 1) = \frac{\langle \alpha_k^{(-n)} \rangle}{\sum_{k'=1}^K \langle \alpha_{k'}^{(-n)} \rangle} \text{St} \left( \mathbf{x}_n \middle| \langle \mathbf{m}_k^{(-n)} \rangle, \langle \mathbf{L}_k^{(-n)} \rangle, \langle \nu_k^{(-n)} \rangle + 1 - D \right)$

All formulas are like:  
Mixing ratio  
×  
Component  
distribution

- Learning algorithm can be categorized with respect to how to deal with uncertainty

		Latent variables $Z$		
		Point estimates	Posteriors	Sampled values
Parameters $\pi, \mu, \Lambda$	Point estimates	$K$ -means+ (maximization-maximization)	EM (expectation-maximization)	
	Posteriors	Bayesian $K$ -means (maximization-expectation)	VB (expectation-expectation)	
	Sampled values			Gibbs sampling (sampling-sampling)

- Implement basic functions for updating posteriors
  - Input: **prior** + **statistics**    Output: **posterior**

posterior.h

```
void update_dirichlet  
(mcl::Dirichlet& dirichlet,  
 mcl::Dirichlet& dirichlet0,  
 const std::vector<double>& s);
```

```
void update_gaussian_wishart  
(mcl::Gaussian& gaussian,  
 mcl::Wishart& wishart,  
 const mcl::Gaussian& gaussian0,  
 const mcl::Wishart& wishart0,  
 double s,  
 const std::vector<double>& sx,  
 const std::vector<double>& sxx);
```

```
void update_student  
(mcl::Student& student,  
 const mcl::Gaussian& gaussian,  
 const mcl::Wishart& wishart);
```

Predictive distribution  
(used for collapsed inference)

# Implementation Example in C++

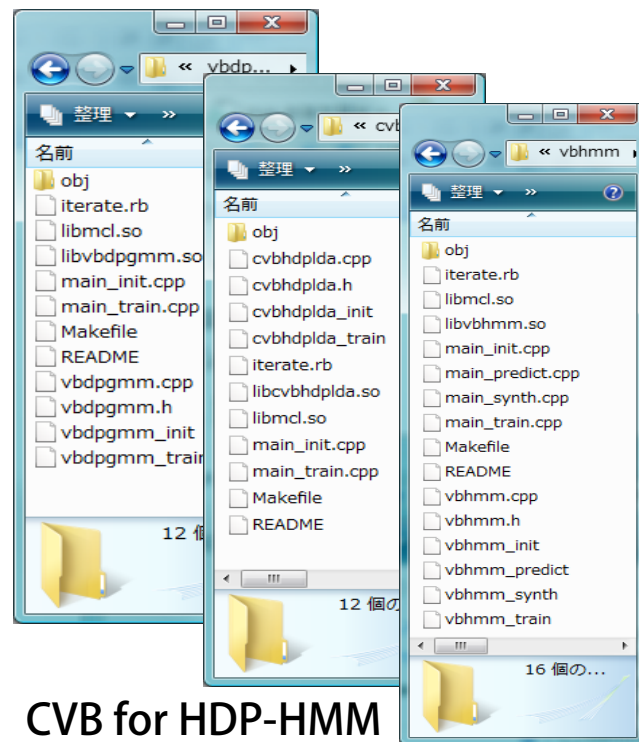
60

- Combine appropriate functions for your model
  - Use conjugate priors as much as possible



Library

VB for DP-GMM



CVB for HDP-HMM

VB for HMM

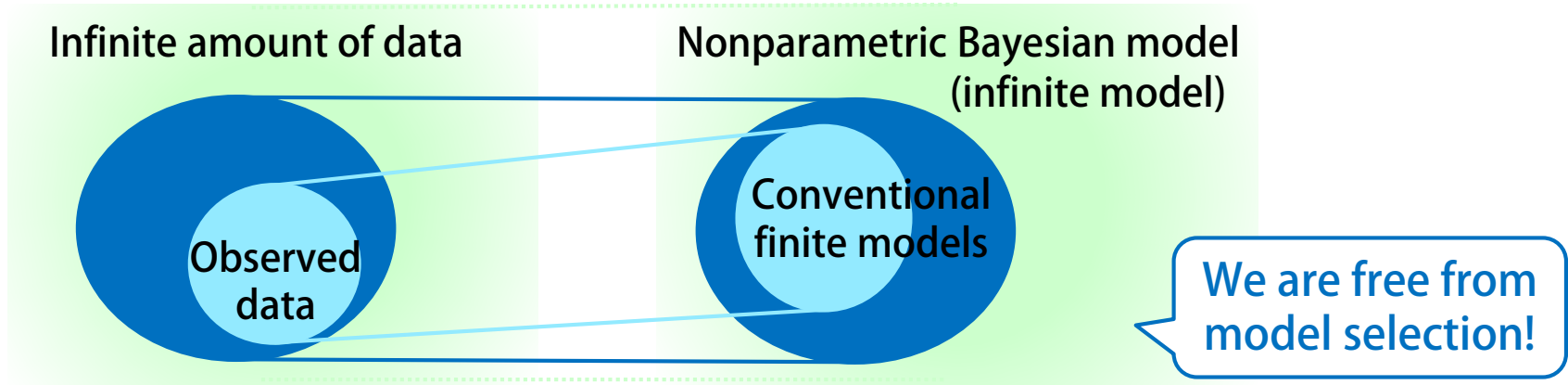
MapReduce-type parallelization is easy

- Implement HTK-like commands
  - `vbgmm_init [model.xml] [K]`
    - ♦ Make an initial model with K components
  - `vbgmm_train [model.xml] [data.csv] ([#iterations])`
    - ♦ Update the model using the data
    - ♦ Overwrite the model file
- Parallelization based on `boost::mpi`
  - MapReducing EM algorithm for Master-Slave architecture
    - ♦ E-step: *Master* distributes the data to *Slaves*
      - Each *Slave* calculates the responsibilities for the given data
    - ♦ M-step: *Master* gathers the responsibilities from *Slaves*
      - *Master* updates the posteriors

# Bayesian Estimation of **Infinite** Gaussian Mixture Models

Collapsed Gibbs Sampling  
Variational Bayes

- Bayesian models with infinite complexity
  - “Nonparametric” means having an **infinite** number of parameters
  - **Excellent generalization capability**
    - If we have an **infinite** amount of data, **all an infinite number** of parameters are required
    - If we have a **finite** amount of data, only **a finite subset** is required



# Dirichlet Process $G \sim \text{DP}(\alpha, G_0)$

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- An **infinite**-dimensional prior distribution
  - Capable of generating **infinite**-dimensional distributions

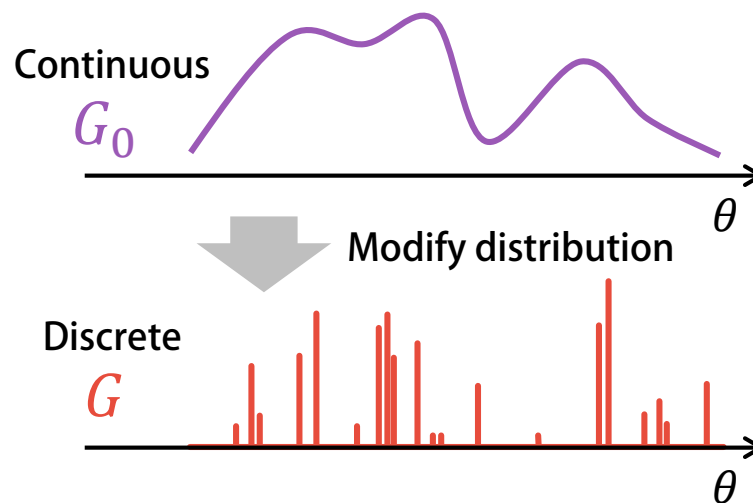
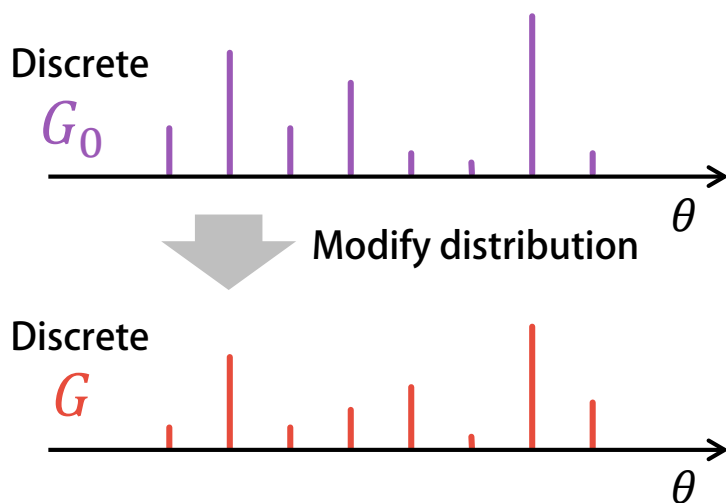
$$G \sim \text{DP}(\alpha, G_0)$$

Concentration  
parameter

Base  
measure

The DP can be explicitly rewritten as

$$G(\theta) = \sum_{k=1}^{\infty} \pi_k \delta_{\theta_k}(\theta) \quad \theta_k \sim G_0$$

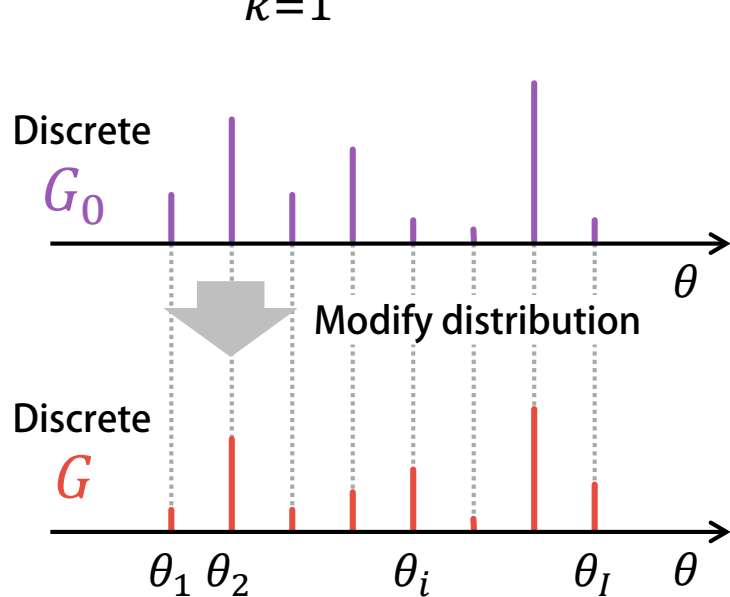




- The DP **always** generates discrete distributions
  - The positions of “atoms” are shared with the discrete base measure

$$G(\theta) = \sum_{k=1}^{\infty} \pi_k \delta_{\theta_k}(\theta) \quad \theta_k \sim G_0$$

Each  $\theta_k$  is one of  $\{\theta_1, \theta_2, \dots, \theta_I\}$



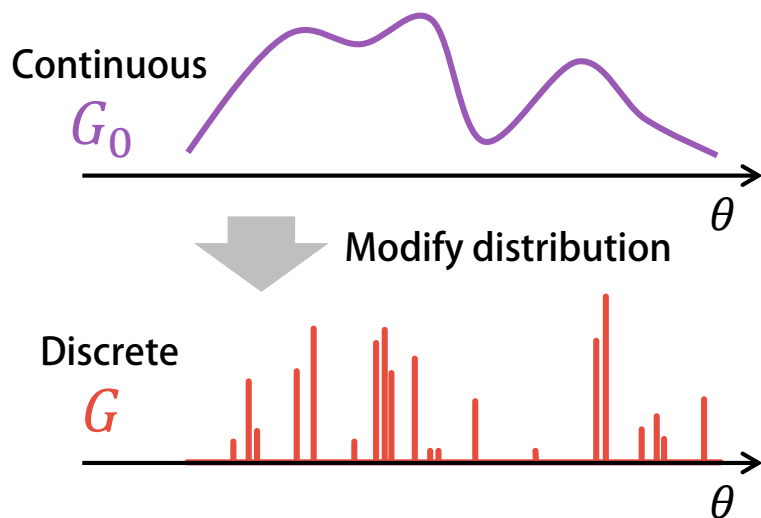
$$\begin{aligned} G(\theta) &= \sum_{k=1}^{\infty} \pi_k \delta_{\theta_k}(\theta) \\ &= \sum_{i=1}^I \left( \sum_{k: \theta_k = \theta_i} \pi_k \right) \delta_{\theta_i}(\theta) \end{aligned}$$

$I$ -dimensional  
discrete distribution

- The DP **always** generates discrete distributions
  - The number of “atoms” are countably infinite

$$G(\theta) = \sum_{k=1}^{\infty} \pi_k \delta_{\theta_k}(\theta) \quad \theta_k \sim G_0$$

$\theta_k$ 's are almost surely disjoint



If we use a continuous prior distribution as a base measure  $G_0$ , we can generate an infinite-dim. discrete distribution!

If  $G_0$  is a Gaussian-Wishart distribution (the probability space is over  $\theta = \{\mu, \Lambda\}$ )



$G$  consists of infinitely many Gaussians  $\{\theta_1, \dots, \theta_\infty\}$  with weights  $\{\pi_1, \dots, \pi_\infty\}$

# Stick Breaking Process

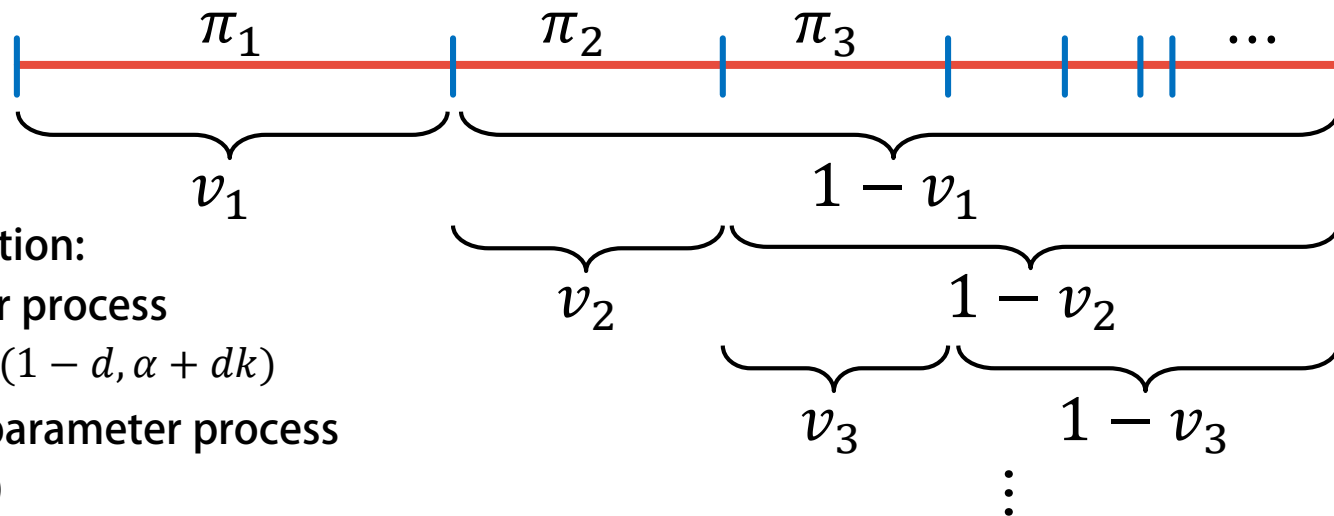
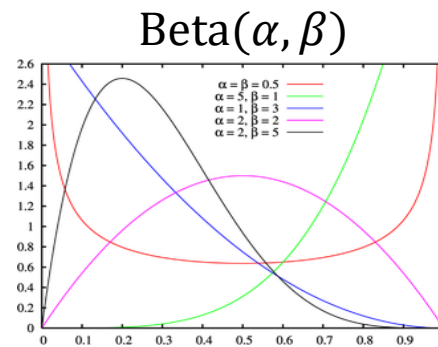
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- Stochastically generate the weights  $\{\pi_1, \dots, \pi_\infty\}$ 
  - a.k.a. Griffiths-Engen-McCloskey distribution

$$\boldsymbol{\pi} \sim \text{SBP}(\alpha) \text{ or } \text{GEM}(\alpha)$$

$$\downarrow$$

$$v_k \sim \text{Beta}(1, \alpha) \quad \pi_k = v_k \prod_{k'=1}^{k-1} (1 - v_{k'})$$



Generalization:

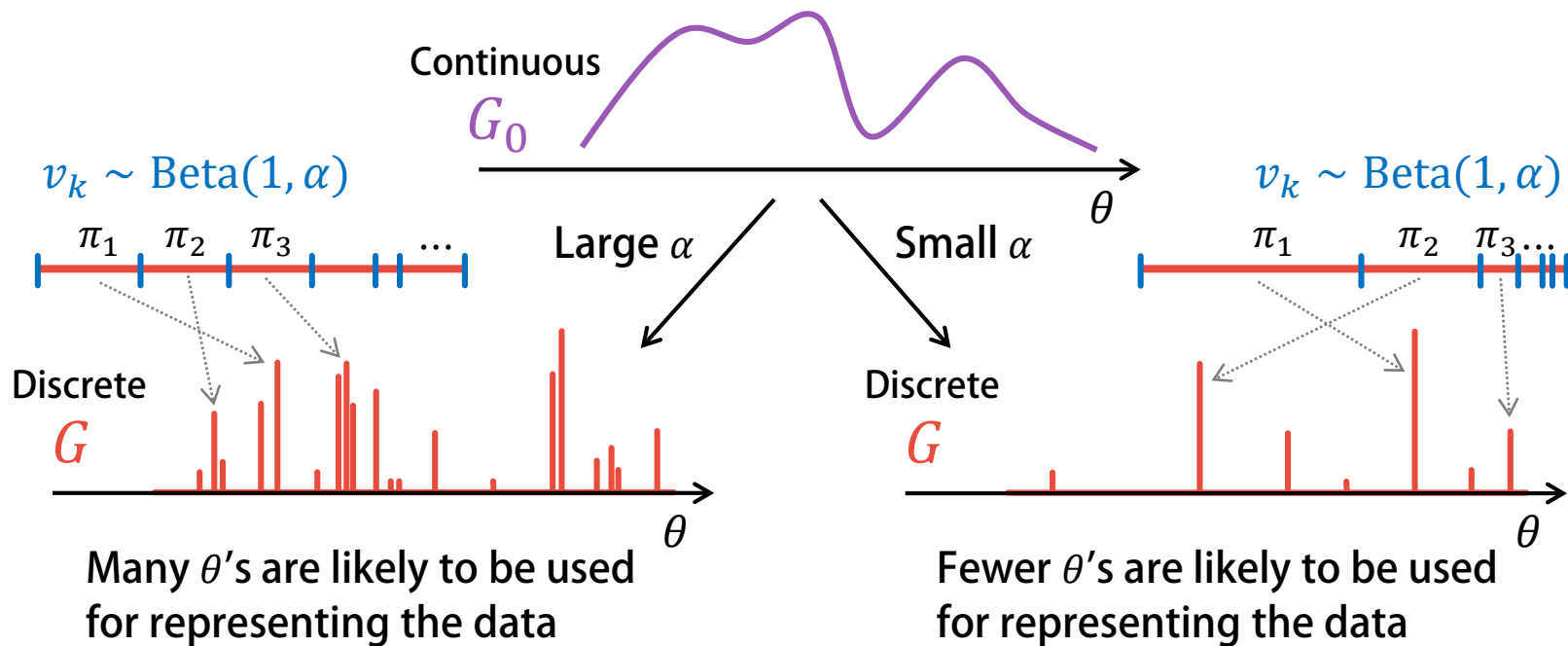
Pitman-Yor process

$$v_k \sim \text{Beta}(1 - d, \alpha + dk)$$

Beta two-parameter process

$$\text{Beta}(\alpha, \beta)$$

- The concentration parameter controls the **sparseness**
  - The value of  $\alpha$  is unknown  $\rightarrow$  Introduce a hyper prior on  $\alpha$



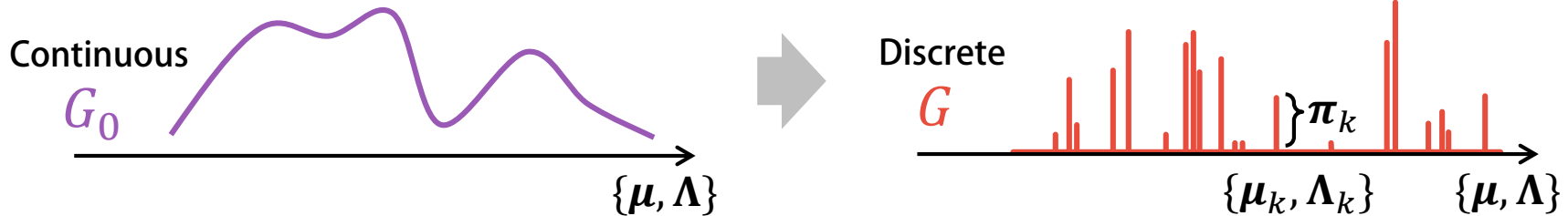
Assume  $\alpha \sim \text{Gamma}(a, b)$  for taking into account uncertainty

- Generate infinitely many Gaussians using a DP

$$G(\boldsymbol{\mu}, \boldsymbol{\Lambda}) = \sum_{k=1}^{\infty} \pi_k \delta_{\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k}(\boldsymbol{\mu}, \boldsymbol{\Lambda})$$

$$\boldsymbol{\pi} \sim \text{SBP}(\alpha) \quad \text{SBP prior}$$

$$\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k \sim G_0(\boldsymbol{\mu}, \boldsymbol{\Lambda}) \quad \text{Gaussian-Wishart prior}$$



- Generate samples independently

for  $n = 1:N$

$$\boldsymbol{\mu}_n, \boldsymbol{\Lambda}_n \sim G(\boldsymbol{\mu}, \boldsymbol{\Lambda})$$

$$\mathbf{x}_n \sim N(\mathbf{x}_n | \boldsymbol{\mu}_n, \boldsymbol{\Lambda}_n^{-1})$$

end

Equivalent representation

$$\mathbf{z}_n \sim \text{Categorical}(\mathbf{z}_n | \boldsymbol{\pi})$$

$$\mathbf{x}_n \sim \prod_{k=1}^{\infty} N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)^{z_{nk}}$$

Infinite  
GMM!

- Formulate a full joint distribution

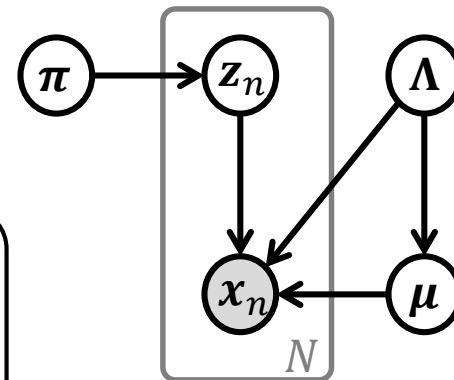
$$p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda})p(\mathbf{Z}|\boldsymbol{\pi})p(\boldsymbol{\pi})p(\boldsymbol{\mu}, \boldsymbol{\Lambda})$$

$$p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = \prod_{n=1}^N \prod_{k=1}^K N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1})^{z_{nk}}$$

$$p(\mathbf{Z}|\boldsymbol{\pi}) = \prod_{n=1}^N \text{Categorical}(\mathbf{z}_n | \boldsymbol{\pi}) = \prod_{n=1}^N \prod_{k=1}^K \pi_k^{z_{nk}}$$

$$p(\boldsymbol{\pi}) = \text{Dir}(\boldsymbol{\pi} | \boldsymbol{\alpha}_0) = \frac{\Gamma(\sum_{k=1}^K \alpha_{0k})}{\prod_{k=1}^K \Gamma(\alpha_{0k})} \prod_{k=1}^K \pi_k^{\alpha_{0k}-1}$$

$$p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) = \prod_{k=1}^K N(\boldsymbol{\mu}_k | \mathbf{m}_0, (\beta_0 \boldsymbol{\Lambda}_k)^{-1}) W(\boldsymbol{\Lambda}_k | \mathbf{W}_0, \nu_0)$$



Likelihood functions

Prior distributions

- Use a SBP prior instead of a Dirichlet prior

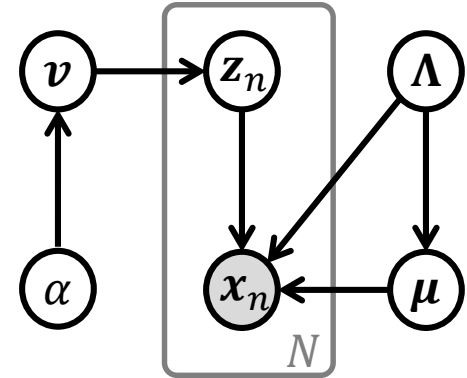
$$p(X, Z, \pi, \mu, \Lambda, \alpha) = p(X|Z, \mu, \Lambda)p(Z|v)p(v|\alpha)p(\alpha)p(\mu, \Lambda)$$

$$p(X|Z, \mu, \Lambda) = \prod_{n=1}^N \prod_{k=1}^{\infty} N(x_n | \mu_k, \Lambda_k^{-1})^{z_{nk}}$$

$$p(Z|v) = \prod_{n=1}^N \prod_{k=1}^{\infty} \left( v_k \prod_{k'=1}^{k-1} (1 - v_{k'}) \right)^{z_{nk}}$$

$$p(v|\alpha) = \prod_{k=1}^{\infty} \text{Beta}(v_k | 1, \alpha) \quad p(\alpha) = \text{Gamma}(\alpha | a_0, b_0)$$

$$p(\mu, \Lambda) = \prod_{k=1}^{\infty} N(\mu_k | m_0, (\beta_0 \Lambda_k)^{-1}) W(\Lambda_k | W_0, \nu_0)$$



Likelihood functions

Prior distributions

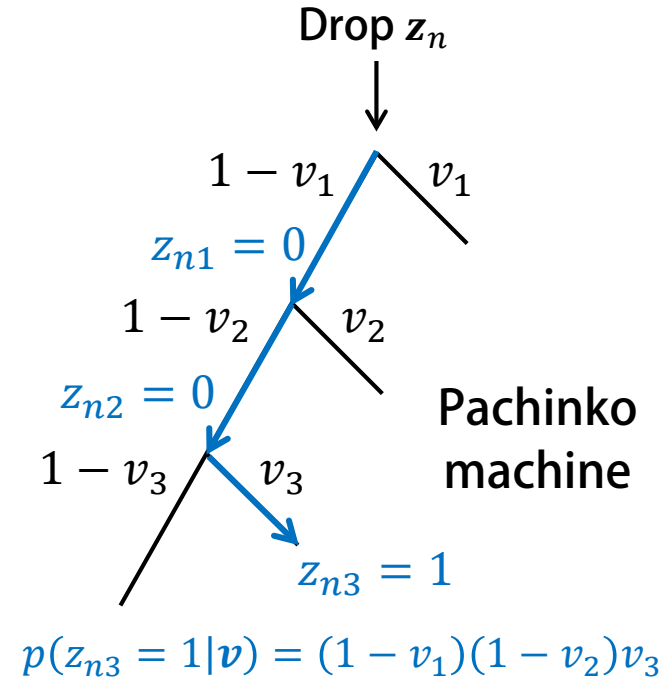
- Beta-Bernoulli & Gamma-Exponential conjugacy
  - The VB is applicable for learning an iGMM

$$p(\mathbf{Z}|\mathbf{v}) = \prod_{n=1}^N \prod_{k=1}^{\infty} \left( v_k \prod_{k'=1}^{k-1} (1 - v_{k'}) \right)^{z_{nk}}$$

$$= \prod_{n=1}^N \prod_{k=1}^{\infty} v_k^{z_{nk}} (1 - v_k)^{\sum_{k'=k+1}^{\infty} z_{nk'}}$$

$$= \prod_{k=1}^{\infty} v_k^{\sum_{n=1}^N z_{nk}} (1 - v_k)^{\sum_{n=1}^N \sum_{k'>k} z_{nk'}}$$

$$p(\mathbf{v}|\alpha) = \prod_{k=1}^{\infty} \alpha v_k^{1-1} (1 - v_k)^{\alpha-1} \longleftrightarrow p(\alpha) = \frac{b_0^{a_0}}{\Gamma(a_0)} \alpha^{a_0-1} e^{-b_0 \alpha}$$





- Approximate a posterior  $p(\mathbf{Z}, \mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda}, \alpha | \mathbf{X})$ 
  - Use a variational distribution  $q(\mathbf{Z})q(\mathbf{v})q(\boldsymbol{\mu}, \boldsymbol{\Lambda})q(\alpha) \approx p(\mathbf{Z}, \mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda}, \alpha | \mathbf{X})$
  - Iteratively update (optimize) each factor
    - ♦ VB-E step
      - $-\log q^*(\mathbf{Z}) = \langle \log p(\mathbf{X}, \mathbf{Z}, \mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda}, \alpha) \rangle_{q(\mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda}, \alpha)} + \text{const.}$   
 $= \langle \log p(\mathbf{X} | \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) p(\mathbf{Z} | \mathbf{v}) \rangle_{q(\mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda})} + \text{const.}$
    - ♦ VB-M step
      - $-\log q^*(\mathbf{v}) = \langle \log p(\mathbf{X}, \mathbf{Z}, \mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}, \alpha)} + \text{const.}$   
 $= \langle \log p(\mathbf{Z} | \mathbf{v}) p(\mathbf{v} | \alpha) \rangle_{q(\mathbf{Z}, \alpha)} + \text{const.}$
      - $-\log q^*(\boldsymbol{\mu}, \boldsymbol{\Lambda}) = \langle \log p(\mathbf{X}, \mathbf{Z}, \mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z}, \mathbf{v}, \alpha)} + \text{const.}$   
 $= \langle \log p(\mathbf{X} | \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z})} + \text{const.}$
      - $-\log q^*(\alpha) = \langle \log p(\mathbf{X}, \mathbf{Z}, \mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z}, \mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda})} + \text{const.}$   
 $= \langle \log p(\mathbf{v} | \alpha) p(\alpha) \rangle_{q(\mathbf{v})} + \text{const.}$

- Invoke the updating formula of VB
  - Take the expectation of the full joint probability distribution under variational posteriors over other variables
  - Focus on only terms including  $\mathbf{Z}$   
(other terms can be absorbed into the normalization factor)

$$\begin{aligned}\log q^*(\mathbf{Z}) &= \langle \log p(\mathbf{X}, \mathbf{Z}, \mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda}, \alpha) \rangle_{q(\mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda}, \alpha)} + \text{const.} \\ &= \langle \log p(\mathbf{X} | \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) p(\mathbf{Z} | \mathbf{v}) p(\mathbf{v} | \alpha) p(\alpha) p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda}, \alpha)} + \text{const.} \\ &= \langle \log p(\mathbf{X} | \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) p(\mathbf{Z} | \mathbf{v}) \rangle_{q(\mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda})} + \text{const.}\end{aligned}$$

$$p(\mathbf{X} | \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = \prod_{n=1}^N \prod_{k=1}^{\infty} N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1})^{z_{nk}}$$

$$p(\mathbf{Z} | \mathbf{v}) = \prod_{n=1}^N \prod_{k=1}^{\infty} \left( v_k \prod_{k'=1}^{k-1} (1 - v_{k'}) \right)^{z_{nk}}$$

- Proceed the calculation according the updating rule

$$\langle \log p(\mathbf{Z}|\mathbf{v}) \rangle_{q(\mathbf{v})} = \sum_{n=1}^N \sum_{k=1}^{\infty} z_{nk} \left( \langle \log v_k \rangle_{q(v_k)} + \sum_{k'=1}^{k-1} \langle \log(1 - v_{k'}) \rangle_{q(v_{k'})} \right)$$

$$\langle \log p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\boldsymbol{\mu}, \boldsymbol{\Lambda})} = \sum_{n=1}^N \sum_{k=1}^{\infty} z_{nk} \langle \log N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1}) \rangle_{q(\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)}$$



$$\log q^*(\mathbf{Z}) = \langle \log p(\mathbf{Z}|\mathbf{v}) \rangle_{q(\mathbf{v})} + \langle \log p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\boldsymbol{\mu}, \boldsymbol{\Lambda})} + \text{const.}$$

$$= \sum_{n=1}^N \sum_{k=1}^{\infty} z_{nk} \left( \underbrace{\langle \log v_k \rangle_{q(v_k)} + \sum_{k'=1}^{k-1} \langle \log(1 - v_{k'}) \rangle_{q(v_{k'})}}_{\text{Infinite GMM}} + \langle \log N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1}) \rangle_{q(\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k)} \right) + \text{const.}$$


$$= \sum_{n=1}^N \sum_{k=1}^{\infty} z_{nk} \log \rho_{nk} + \text{const.}$$

Finite GMM

$$\langle \log \pi_k \rangle_{q(\pi)}$$

- Calculate the variational posterior over latent variables  $\mathbf{Z}$ 
  - The normalization factor is automatically determined

$$\log q^*(\mathbf{Z}) = \sum_{n=1}^N \sum_{k=1}^{\infty} z_{nk} \log \rho_{nk} + \text{const.}$$


$$\gamma_{nk} = \frac{\rho_{nk}}{\sum_{k'=1}^K \rho_{nk'}}$$

$$\log q^*(\mathbf{Z}) = \sum_{n=1}^N \sum_{k=1}^{\infty} z_{nk} \log \gamma_{nk}$$



$$q^*(\mathbf{Z}) = \prod_{n=1}^N \prod_{k=1}^{\infty} \gamma_{nk}^{z_{nk}} = \prod_{n=1}^N \text{Categorical}(\mathbf{z}_n | \boldsymbol{\gamma}_n)$$

Truncate the variational posterior at the level  $K$  i.e.,  $q(z_{nk>K}) = 0$   
The larger  $K$  becomes, the more accurate the approximation is

Latent variables are categorical distributed!

- Invoke the updating formula of VB
  - Take the expectation of the full joint probability distribution under variational posteriors over other variables
  - Focus on only terms including  $\mathbf{Z}$   
(other terms can be absorbed into the normalization factor)

$$\begin{aligned}\log q^*(\mathbf{v}) &= \langle \log p(\mathbf{X}, \mathbf{Z}, \mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}, \alpha)} + \text{const.} \\ &= \log p(\mathbf{v} | \alpha) + \langle \log p(\mathbf{Z} | \mathbf{v}) \rangle_{q(\mathbf{Z})} + \text{const.}\end{aligned}$$

$$\begin{aligned}\log q^*(\boldsymbol{\mu}, \boldsymbol{\Lambda}) &= \langle \log p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z}, \boldsymbol{\pi}, \alpha)} + \text{const.} \\ &= \log p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) + \langle \log p(\mathbf{X} | \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z})} + \text{const.}\end{aligned}$$

Same as finite GMM

$$\begin{aligned}\log q^*(\alpha) &= \langle \log p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\pi}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) \rangle_{q(\mathbf{Z}, \mathbf{v}, \boldsymbol{\mu}, \boldsymbol{\Lambda})} + \text{const.} \\ &= \log p(\alpha) + \langle \log p(\mathbf{v} | \alpha) \rangle_{q(\mathbf{v})} + \text{const.}\end{aligned}$$

Bayesian estimation in simple conjugate models!  
(Use responsibilities  $q(\mathbf{Z})$  instead of latent variables  $\mathbf{Z}$ )

- Calculate the variational posterior over parameters  $\mathbf{v}$ 
  - The posteriors take the same forms of the priors

$$S_k[1] = \sum_{n=1}^N \gamma_{nk} \quad S_k[\mathbf{x}] = \sum_{n=1}^N \gamma_{nk} \mathbf{x}_n \quad S_k[\mathbf{x}\mathbf{x}^T] = \sum_{n=1}^N \gamma_{nk} \mathbf{x}_n \mathbf{x}_n^T$$

Sufficient statistics

$$\left\{ \begin{array}{l} p(\mathbf{v}|\alpha) = \prod_{k=1}^{\infty} \text{Beta}(v_k|1, \alpha) = \prod_{k=1}^{\infty} \alpha v_k^{1-1} (1 - v_k)^{\alpha-1} \\ p(\mathbf{Z}|\mathbf{v}) = \prod_{k=1}^{\infty} v_k^{\sum_{n=1}^N z_{nk}} (1 - v_k)^{\sum_{n=1}^N \sum_{k'=k+1}^{\infty} z_{nk'}} \end{array} \right.$$

Bayes' theorem

$$p(\mathbf{v}|\mathbf{Z}, \alpha) = \prod_{k=1}^{\infty} \text{Beta}(v_k | 1 + \sum_{n=1}^N z_{nk}, \alpha + \sum_{n=1}^N \sum_{k'=k+1}^{\infty} z_{nk'})$$

Replace  $z_{nk}$  with  $\gamma_{nk}$

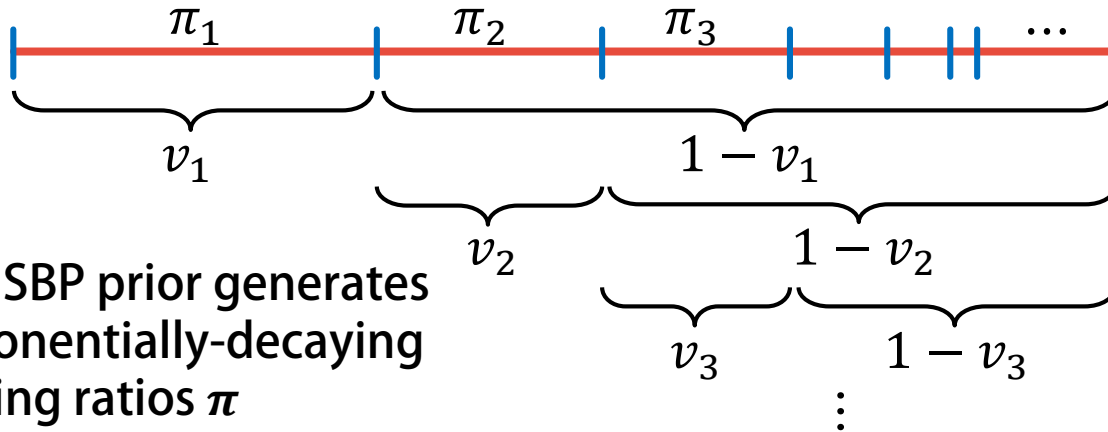
$$\Rightarrow q^*(\mathbf{v})$$

- Calculate the variational posterior over parameter  $\alpha$ 
  - The posterior takes the same forms of the prior
  - Use that fact that if  $x \sim \text{Beta}(1, \alpha)$ , then  $-\log(1 - x) \sim \text{Exponential}(\alpha)$
  - $q^*(\alpha)$  is analytically tractable in case of iGMM

$$\left\{ \begin{array}{l} p(\alpha) = \text{Gamma}(\alpha | a_0, b_0) = \frac{b_0^{a_0}}{\Gamma(a_0)} \alpha^{a_0-1} e^{-b_0 \alpha} \\ p(\mathbf{v} | \alpha) = \prod_{k=1}^{\infty} \text{Beta}(v_k | 1, \alpha) = \alpha^K \prod_{k=1}^{\infty} (1 - v_k)^{\alpha-1} \\ p(\alpha | \mathbf{v}) = \text{Gamma}(\alpha | a_0 + K, b_0 - \sum_{k=1}^K \log(1 - v_k)) \end{array} \right.$$

Bayes' theorem  
 Replace  $\log(1 - v_k)$  with  $\langle \log(1 - v_k) \rangle_{q(v_k)}$   
 $\Rightarrow q^*(\alpha)$

- Truncate the variational poster  $q(\mathbf{Z})$ 
  - The infinite-dimensional true posterior  $p(\mathbf{Z}|\mathbf{X})$  is NOT truncated!
  - $q(\mathbf{z}_n)$  is truncated at a sufficiently large level  $K$  *i.e.*,  $q(z_{nk} > K) = 0$
  - $K$  corresponds to how accurately  $q(\mathbf{Z})$  approximates  $p(\mathbf{Z}|\mathbf{X})$
- Sort  $K$  clusters in descending order before VB-M step
  - Remove unnecessary cluster  $k$  with  $S_k[1] \approx 0$

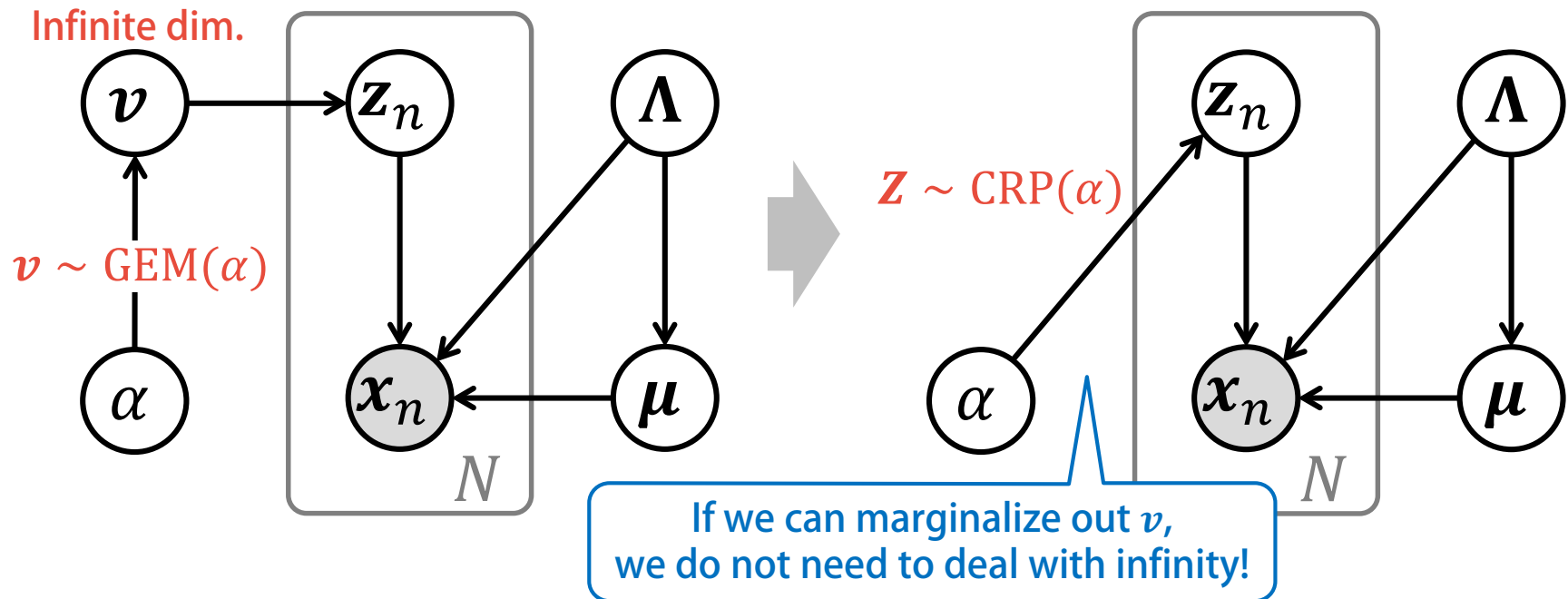


This is effective for:

1. accelerating the convergence
2. avoiding poor local maxima



- Finite truncation at a certain level  $K$  is required for VB
  - A large amount of computational power is wasted
  - $K$  should be sufficiently large even if only a few clusters are required for representing the data



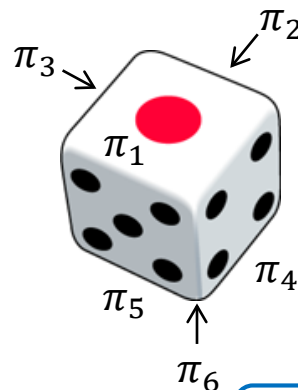
- Marginalize out infinite-dimensional parameters  $\pi$  or  $\nu$ 
  - Take the infinite limit of a Dirichlet-Categorical model

$K$ -dimensional Dirichlet prior

$$\boldsymbol{\pi} \sim \text{Dir}(\boldsymbol{\pi} | \alpha \boldsymbol{\beta}_K) \quad \boldsymbol{\beta}_K = \underbrace{\left[ \frac{1}{K}, \frac{1}{K}, \dots, \frac{1}{K} \right]}_K$$

Likelihood

$$\mathbf{z}_{1:N} \sim \text{Categorical}(\mathbf{z} | \boldsymbol{\pi})$$



Infinite-sided  
die

Given  $\mathbf{Z}_{-n}$  as observed data,  $z_n$  is **predicted** as:

$$p(z_{nk} = 1 | \mathbf{Z}_{-n}) = \int \underbrace{p(z_{nk} = 1 | \boldsymbol{\pi})}_{\text{Likelihood}} \underbrace{p(\boldsymbol{\pi} | \mathbf{Z}_{-n})}_{\text{Posterior}} d\mathbf{Z}_{-n}$$

$$= \int \pi_k \text{Dir}(\boldsymbol{\pi} | \alpha \boldsymbol{\beta}_K + \sum_{n' \neq n} \mathbf{z}_{n'}) d\mathbf{Z}_{-n} = \frac{\frac{\alpha}{K} + \sum_{n' \neq n} z_{n'k}}{\sum_{k'=1}^K \left( \frac{\alpha}{K} + \sum_{n' \neq n} z_{n'k'} \right)} \xrightarrow{K \rightarrow \infty} \frac{n_k^{(-n)}}{(N-1) + \alpha}$$

The number of samples  
belonging to cluster  $k$   
among  $N - 1$  samples

$n_k^{(-n)}$

$K \rightarrow \infty$

$n_{k'}^{(-n)}$

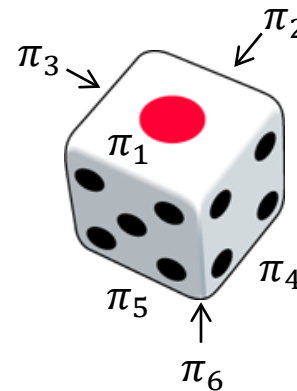
- Focus on the probability that a new cluster is selected
  - Accumulate the probabilities that existing clusters are selected

$K$ -dimensional Dirichlet prior

$$\boldsymbol{\pi} \sim \text{Dir}(\boldsymbol{\pi} | \alpha \boldsymbol{\beta}_K) \quad \boldsymbol{\beta}_K = \underbrace{\left[ \frac{1}{K}, \frac{1}{K}, \dots, \frac{1}{K} \right]}_K$$

Likelihood

$$\mathbf{z}_{1:N} \sim \text{Categorical}(\mathbf{z} | \boldsymbol{\pi})$$



Infinite-sided  
die

Given  $\mathbf{Z}_{-n}$  consisting of  $K$  clusters,  $z_n$  is predicted as:

$$p(z_{nk} = 1 | \mathbf{Z}_{-n}) = \begin{cases} \frac{n_k^{(-n)}}{(N-1) + \alpha} \\ \frac{\alpha}{(N-1) + \alpha} \end{cases}$$

Existing cluster  $k$  ( $1 \leq k \leq K$ ) is selected

New cluster  $k$  ( $k > K$ ) is created

Sum:  $\frac{N-1}{N-1+\alpha}$

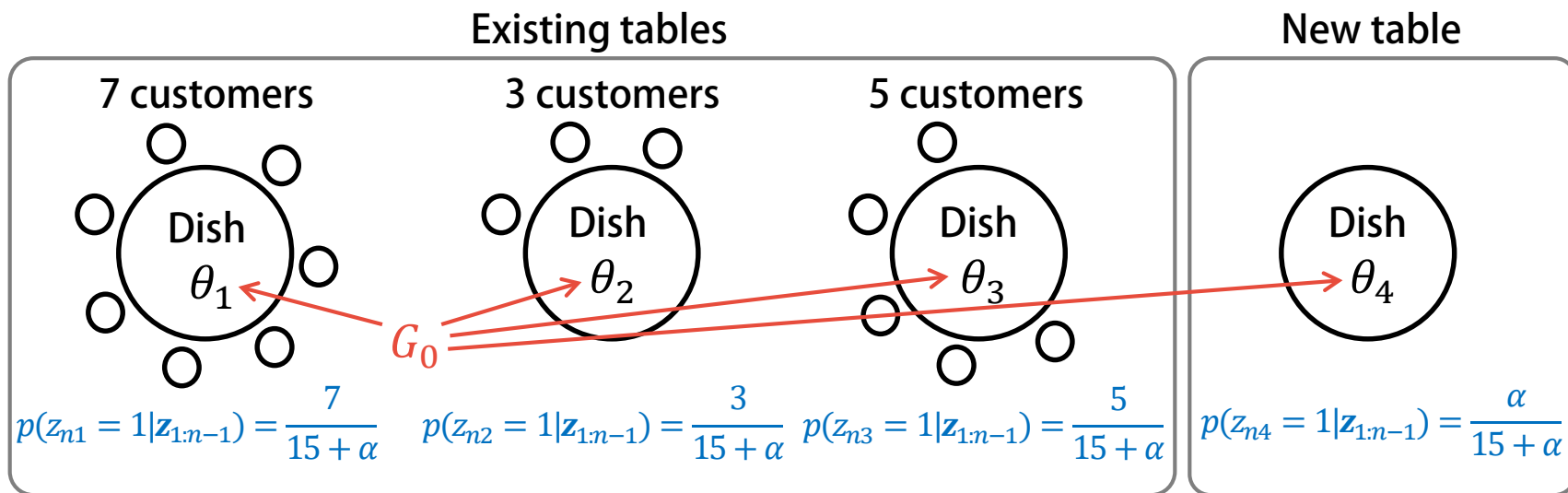
We index the new cluster as  $K + 1$

- Sequentially generate samples s.t. “the rich get richer”
  - Used as a prior on latent variables  $Z$  ( $= z_{1:N}$ )

$$z_{1:N} \sim \text{CRP}(\alpha) \quad \theta_k \sim G_0(\theta) \text{ if a new cluster is created}$$

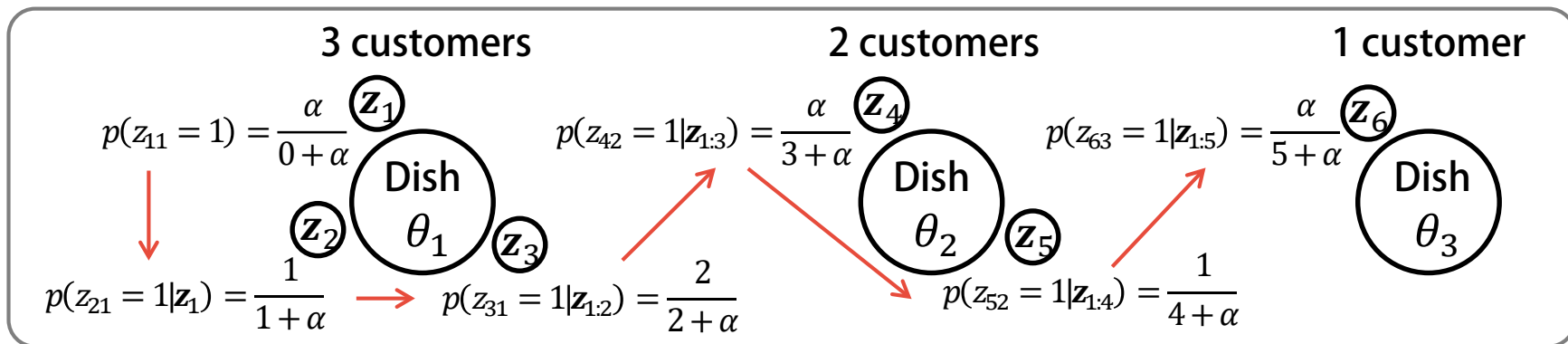
Suppose  $n - 1$  customers  $z_{1:n-1}$  are already seated in restaurant  $G_0$

The next customer  $z_n$  stochastically selects a table as follows:

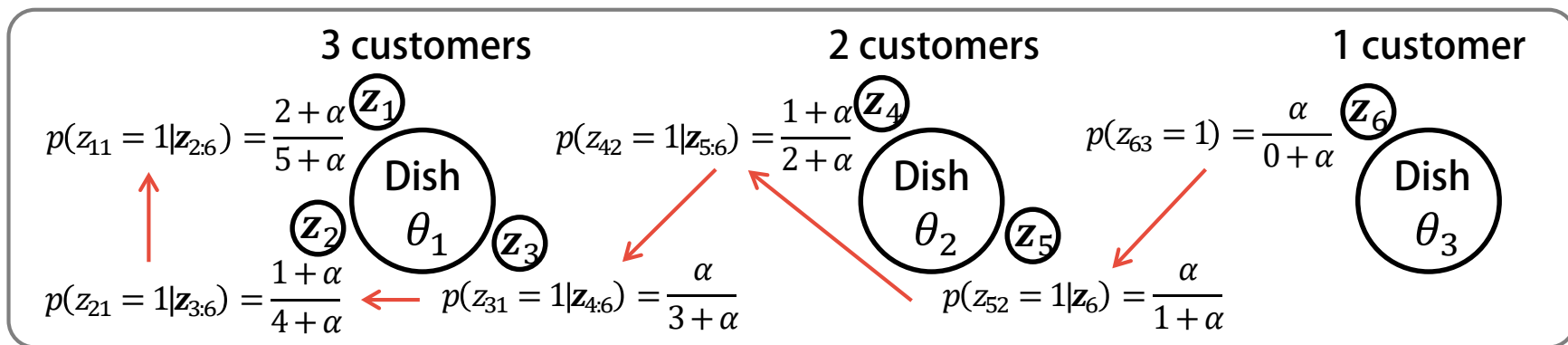


- The **customer order** does not change the CRP probability

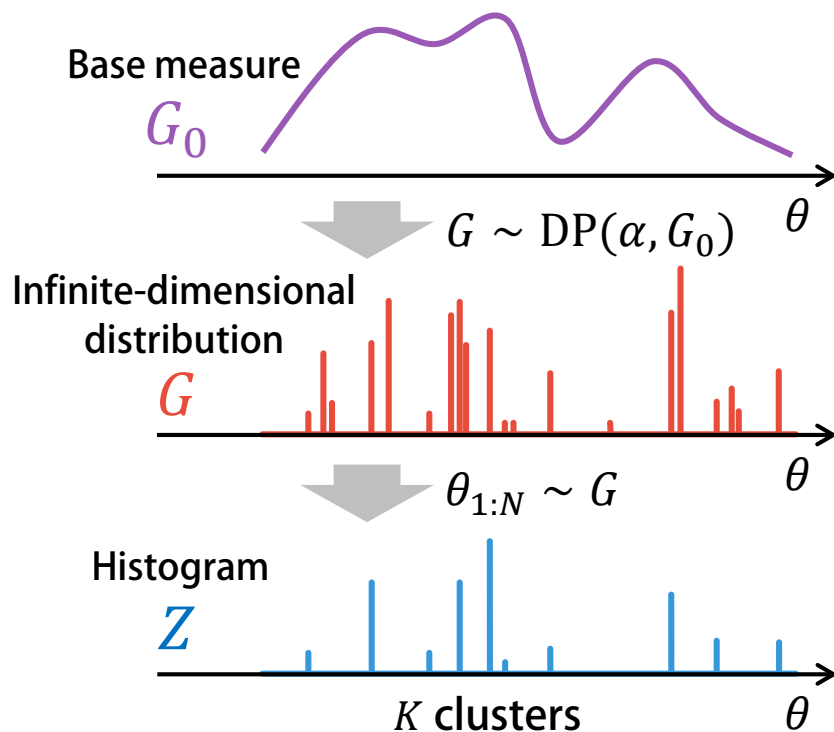
$$\text{CRP}(\mathbf{Z}|\alpha) = p(\mathbf{z}_1)p(\mathbf{z}_2|\mathbf{z}_1)p(\mathbf{z}_3|\mathbf{z}_{1:2})p(\mathbf{z}_4|\mathbf{z}_{1:3})p(\mathbf{z}_5|\mathbf{z}_{1:4})p(\mathbf{z}_6|\mathbf{z}_{1:5})$$



$$\text{CRP}(\mathbf{Z}|\alpha) = p(\mathbf{z}_6)p(\mathbf{z}_5|\mathbf{z}_6)p(\mathbf{z}_4|\mathbf{z}_{5:6})p(\mathbf{z}_3|\mathbf{z}_{4:6})p(\mathbf{z}_2|\mathbf{z}_{3:6})p(\mathbf{z}_1|\mathbf{z}_{2:6})$$



- Two major approaches to representing the DP
  - SBP: Represent **how a distribution  $G$  is drawn from the DP**
  - CRP: Represent **how samples  $Z$  are drawn from the DP**



$$G(\theta) = \sum_{k=1}^{\infty} \pi_k \delta_{\theta_k}(\theta)$$

$$\pi_{1:\infty} \sim \text{SBP}(\alpha) \quad \theta_{1:\infty} \sim G_0(\theta)$$

$$\mathbf{z}_{1:N} \sim \text{CRP}(\alpha) \quad \theta_{1:K} \sim G_0(\theta)$$

- Reduce the number of variables for **fast/better** estimation
  - The parameters can be **marginalized out** because of conjugacy

$$p(\mathbf{X}, \mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}, \alpha) = p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda})p(\mathbf{Z}|\alpha)p(\alpha)p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) \Rightarrow p(\mathbf{X}|\mathbf{Z}) = p(\mathbf{X}|\mathbf{Z})p(\mathbf{Z}|\alpha)p(\alpha)$$

$$p(\mathbf{Z}|\alpha) = \text{CRP}(\mathbf{Z}|\alpha) \quad \text{Marginal likelihood for } \mathbf{Z} \text{ (mixing ratios are marginalized out)}$$

$$p(\mathbf{Z}|\alpha) \propto \lim_{K \rightarrow \infty} \int p(\mathbf{Z}|\boldsymbol{\pi}) \text{Dir}(\boldsymbol{\pi}|\alpha \boldsymbol{\beta}_K) d\boldsymbol{\pi}$$

$$p(\alpha) = \text{Gamma}(\alpha|a_0, b_0) \quad \text{Hyper prior on } \alpha$$

$$p(\mathbf{X}|\mathbf{Z}, \boldsymbol{\mu}, \boldsymbol{\Lambda}) = \prod_{n=1}^N \prod_{k=1}^K N(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k^{-1})^{z_{nk}}$$

$$p(\boldsymbol{\mu}, \boldsymbol{\Lambda}) = \prod_{k=1}^K N(\boldsymbol{\mu}_k | \mathbf{m}_0, (\beta_0 \boldsymbol{\Lambda}_k)^{-1}) W(\boldsymbol{\Lambda}_k | \mathbf{W}_0, \nu_0)$$

Marginalization over  $\boldsymbol{\mu}, \boldsymbol{\Lambda}$   
is analytically tractable!

Conjugacy holds true  
(Gaussian-Wishart-Gaussian)

- Generate samples from  $p(\mathbf{Z}, \alpha | \mathbf{X})$ 
  - Divide  $\{\mathbf{Z}, \alpha\}$  into  $\{\mathbf{z}_1\}, \{\mathbf{z}_2\}, \dots, \{\mathbf{z}_N\}, \{\alpha\}$
  - for  $n = 1:N$ 
    - Sample  $\mathbf{z}_n \sim p(\mathbf{z}_n | \mathbf{X}, \mathbf{Z}_{-n}, \alpha) = p(\mathbf{z}_n | \mathbf{x}_n, \mathbf{X}_{-n}, \mathbf{Z}_{-n}, \alpha)$

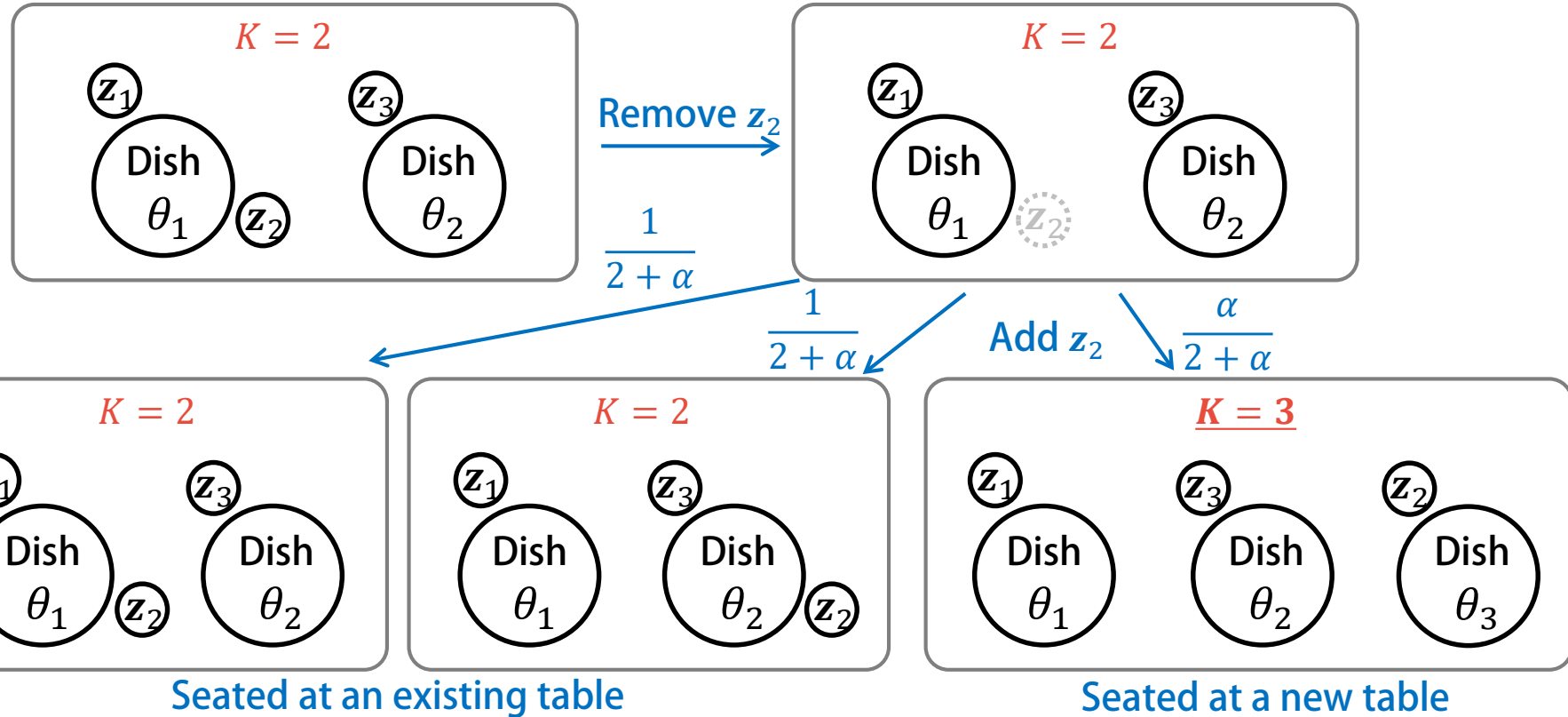
$$\begin{aligned}
 p(z_{nk} = 1 | \mathbf{x}_n, \mathbf{X}_{-n}, \mathbf{Z}_{-n}, \alpha) &\propto p(z_{nk} = 1, \mathbf{x}_n | \mathbf{X}_{-n}, \mathbf{Z}_{-n}, \alpha) \\
 &= p(z_{nk} = 1 | \mathbf{Z}_{-n}, \alpha) p(\mathbf{x}_n | z_{nk} = 1, \mathbf{X}_{-n}, \mathbf{Z}_{-n}) \\
 &= \text{CRP}(z_{nk} = 1 | \mathbf{Z}_{-n}, \alpha) \int p(\mathbf{x}_n | \boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k) p(\boldsymbol{\mu}_k, \boldsymbol{\Lambda}_k | \mathbf{X}_{-n}, \mathbf{Z}_{-n}) d\boldsymbol{\mu}_k d\boldsymbol{\Lambda}_k \\
 &= \begin{cases} \frac{n_k^{(-n)}}{N - 1 + \alpha} \text{St}(\mathbf{x}_n | \mathbf{m}_k^{(-n)}, \mathbf{L}_k^{(-n)}, \nu_k^{(-n)} + 1 - D) & \text{for existing cluster } k \ (1 \leq k \leq K) \\ \frac{\alpha}{N - 1 + \alpha} \text{St}(\mathbf{x}_n | \mathbf{m}_0, \mathbf{L}_0, \nu_0 + 1 - D) & \text{for new cluster } K + 1 \end{cases}
 \end{aligned}$$



# Remove-and-Add Scheme

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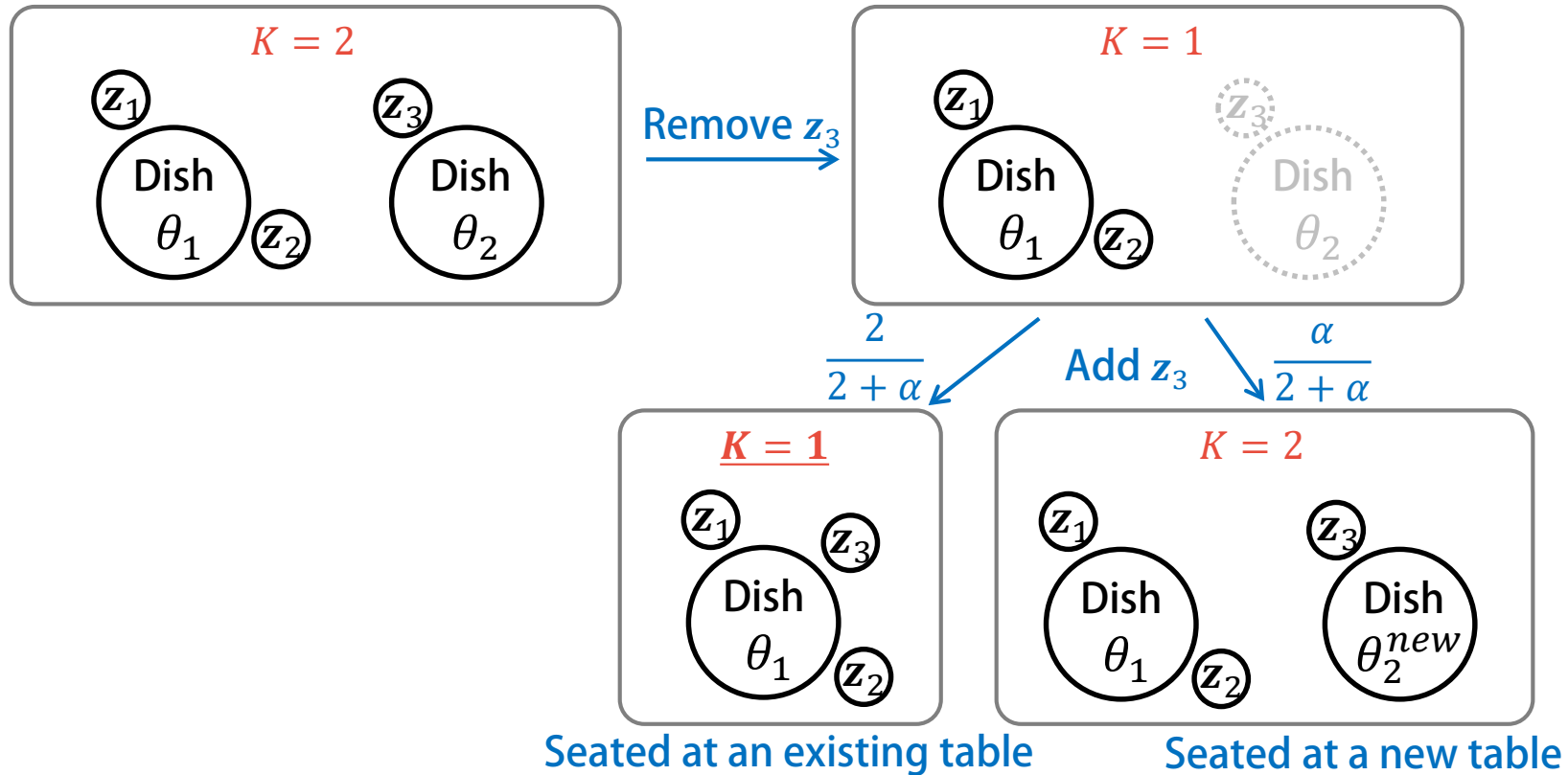
- Update  $z_n$  using the remove-and-add scheme
  - The number of tables  $K$  **can be increased**



# Remove-and-Add Scheme

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- Update  $z_n$  using the remove-and-add scheme
  - The number of tables  $K$  **can be decreased**



- Calculate the probability of seating arrangement

$$p(\mathbf{Z}|\alpha) = \frac{1}{\sum_{i=1}^N (i-1+\alpha)} \prod_{k=1}^K \alpha(n_k-1)! = \alpha^K \frac{\Gamma(\alpha)}{\Gamma(\alpha+N)} \prod_{k=1}^K (n_k-1)!$$

Data augmentation

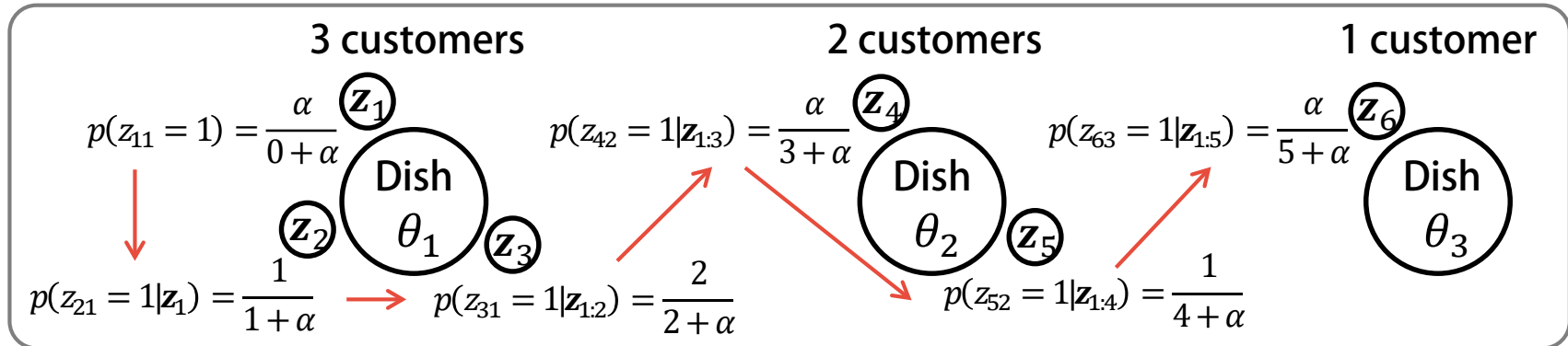
$$p(\mathbf{Z}, \eta|\alpha) = \frac{\alpha^{K-1}(\alpha+n)}{\Gamma(N)} \eta^\alpha (1-\eta)^{N-1} \prod_{k=1}^K (n_k-1)!$$

$\uparrow$ 
 $p(\mathbf{Z}|\alpha) = \int p(\mathbf{Z}, \eta|\alpha) d\eta$

$$1 = \int \text{Beta}(\eta|\alpha+1, N) d\eta$$

$$= \frac{\Gamma(\alpha+N+1)}{\Gamma(\alpha+1)\Gamma(N)} \int \eta^\alpha (1-\eta)^{N-1} d\eta$$

$$\Gamma(x+1) = x\Gamma(x)$$



- Generate samples from  $p(\mathbf{Z}, \alpha, \eta | \mathbf{X})$ 
  - Sample  $\alpha \sim p(\alpha | \mathbf{X}, \mathbf{Z}, \eta) \propto p(\mathbf{Z}, \eta | \alpha) p(\alpha)$
  - Sample  $\eta \sim p(\eta | \mathbf{X}, \mathbf{Z}, \alpha) \propto p(\mathbf{Z}, \eta | \alpha)$

$$p(\alpha) = \text{Gamma}(\alpha | a_0, b_0) = \frac{b_0^{a_0}}{\Gamma(a_0)} \alpha^{a_0-1} e^{-b_0 \alpha}$$

$$p(\mathbf{Z}, \eta | \alpha) = \frac{\alpha^{K-1} (\alpha + n)}{\Gamma(N)} \eta^\alpha (1 - \eta)^{N-1} \prod_{k=1}^K (n_k - 1)! \propto \alpha^K \eta^\alpha + n \alpha^{K-1} \eta^\alpha$$

Bayes' theorem

$$p(\alpha | \mathbf{Z}, \eta) \propto \alpha^{a_0+K-1} e^{-(b_0 - \log \eta) \alpha} + n \alpha^{a_0+K-2} e^{-(b_0 - \log \eta) \alpha}$$

$$\propto \omega \text{Gamma}(a_0 + K, b_0 - \log \eta) + (1 - \omega) \text{Gamma}(a_0 + K - 1, b_0 - \log \eta)$$

$$\frac{\omega}{1 - \omega} = \frac{a_0 + K - 1}{N(b_0 - \log \eta)}$$

Sampling from beta

$$p(\eta | \mathbf{Z}, \alpha) = \text{Beta}(\alpha + 1, N)$$

Sampling from gamma mixture

- **Maximum likelihood estimation for finite GMM**
  - EM algorithm and hard EM (k-means)
- **Bayesian estimation for finite GMM**
  - (Collapsed) Gibbs sampling
  - (Collapsed) variational Bayes
- **Bayesian estimation for infinite GMM**
  - Collapsed Gibbs sampling with Chinese restaurant process
  - Variational Bayes with stick breaking process
- **Other topics**
  - Hierarchical Dirichlet process
    - ♦ HMM, PCFG (sequential data), LDA (grouped data)
  - Beta process, gamma process, Gaussian process
    - ♦ (Nonnegative) matrix factorization

GS is feasible with SBP

CVB is feasible with CRP

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  - T. Stepleton: Understanding the Antoniak equation, 2008.  
<http://www.cs.cmu.edu/~tss/antoniak.pdf>

- ML estimation
  - Derive the update formulas of the parameters  $\pi, \mu, \Lambda$  (p. 22) by letting the partial derivative of the lower bound (p. 20) w.r.t. each parameter equal to zero.
  - Implement the EM algorithm by using your favorite language.
- Bayesian estimation
  - Derive the variational posteriors of the parameters  $\pi, \mu, \Lambda$  (p. 47) by using the formulas (p. 46)
  - Try one of the following at least:
    - ♦ Implement the VB algorithm
    - ♦ Implement the GS algorithm
  - Optional:
    - ♦ Implement the other algorithms for finite/infinite GMMs.

- Report submission

- Deadline: 7/21 (Fri.)
- “Assignments” → “Assignments 6/7 (Yoshii)”
- Upload two files
  - ♦ PDF file: Report document
  - ♦ Zip file: Codes and instructions (README)

- Program specification

- *your\_program\_or\_script* x.csv z.csv params.dat
- Show the value of the likelihood or lower bound at each iteration
- Output z.csv and params.dat
  - ♦ z.csv: Posterior probabilities of  $z_n$

0.2, 0.3, 0.5
0.5, 0.1, 0.4
0.1, 0.8, 0.1
. . .