2. **Derivatives of Log-Likelihood:** In logistic regression, the log-likelihood is given by

$$L = \sum_{i=1}^{I} y_i log \left( \frac{1}{1 + exp(-w^T x_i)} \right) + \sum_{i=1}^{I} (1 - y_i) log \left( \frac{exp(-w^T x_i)}{1 + exp(-w^T x_i)} \right)$$

Show the gradient to be

$$\frac{\partial L}{\partial w} = -\sum_{i=1}^{I} \left( \frac{1}{1 + exp(-w^T x_i)} - y_i \right) x_i \tag{2}$$

Provide a comprehensible solution. (4 Points)

$$\frac{\partial L}{\partial \omega} = \sum_{i=1}^{L} \left( V_{i} \frac{\partial \omega}{\partial \omega} \left( \log \frac{1}{1 + \exp(-\omega^{T} \kappa_{i})} \right) + \left( 1 - \gamma_{i} \right) \frac{\partial}{\partial \omega} \left( \log \left( \frac{\exp(-\omega^{T} \kappa_{i})}{1 + \exp(-\omega^{T} \kappa_{i})} \right) \right) \right)$$

$$\frac{\partial L}{\partial \omega} = \sum_{i=1}^{L} \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \frac{\partial}{\partial \omega} \left( \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right)^{2} \cdot \frac{\partial}{\partial \omega} \left( \exp\left( -\omega^{T} \kappa_{i} \right) \right) \right)$$

$$\frac{\partial L}{\partial \omega} = \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \frac{\partial}{\partial \omega} \left( \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right)^{2} \cdot \frac{\partial}{\partial \omega} \left( \exp\left( -\omega^{T} \kappa_{i} \right) \right) \right)$$

$$= \frac{\partial L}{\partial \omega} \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \frac{\partial}{\partial \omega} \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \frac{\partial}{\partial \omega} \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right)$$

$$= \frac{\partial L}{\partial \omega} \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \frac{\partial}{\partial \omega} \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left( 1 + \exp\left( -\omega^{T} \kappa_{i} \right) \right) \cdot \left$$

## Exercise for MA-INF 2213 Computer Vision SS23

12.04.2023

Submission deadline: 26.04.2023 Exercise: 28.04.2023

Important: Please use Python 3.8 for your solutions. You are **not** allowed to use any additional python modules beyond the ones imported in the template. Otherwise you won't get any points.

**Grading:** Submissions that generate runtime errors or produce obviously rubbish results (e.g. nans, inf or meaningless visual output in future exercises) will receive at most 50% of the points.

**Plagiarism:** Plagiarism in any form is prohibited. If your solution contains code copied from any source (e.g. other students, or solutions from the web. This includes ChatGPT!), you will receive **0 points** for the entire exersice sheet.

**Submission:** You can complete the exercise in groups of two, but only one submission per group is allowed. Include a *README.txt* file with your group members into each solution. Points for solutions without readme file will only be given to the uploader.

## 1 Regression

We consider the problem of object pose regression. For every frame of an rotating object you are given 510 dimensional PHoG  $\boxed{1}$  features  $\mathbf{x} = [x_0, x_1...x_{509}]$  and world variables  $\mathbf{y} = [y_0, y_1]$ . These observations are provided in respective  $regression_*.txt$  files. Each row holds the concatenation  $[y_i, x_i]_{1\times 512}$  for image  $I_i$ .

In the following sub-tasks use the maximum likelihood rule for learning. To evaluate the performance, take the maximum likelihood parameters to predict the values  $\hat{y_i} \in \{0,1\}$  on the val and test sets. As a performance metric, report the MSE relative to variance of  $\mathbf{y}$ :  $\frac{MSE(\hat{y_i}, y_i)}{Var(y_i)}$  for  $i \in \{0,1\}$ .

- 1. **Linear Regression:** Learn a linear regressor using the training data for both world variables  $y_i, i \in \{0, 1\}$  independently and evaluate its performance on the test data. (3 Points)
- 2. **Dual Model Regression**: Learn a dual-model regressor for both variables independently using RBF function as the kernel. Do not use regularization, i.e. simply perform linear regression in the feature space you map  $\mathbf{x}$  to. Split the training data into a train and a val split of equal size. Estimate the right value for  $\sigma$  (standard deviation in the RBF kernel) using the val set. Also evaluate regressor's performance on the test data. What do you think about the val set proposed in the template? What does the regressor become equivalent to if  $\sigma$  approaches 0? What happens to the regression if  $\sigma$  approaches infinity? (6 Points)

3. Non Linear Regression: Learn a non-linear regressor for both variables independently using RBF kernels. The centers for RBF kernels will be learnt by reducing the observed features into codebooks. Do not use regularization, i.e. simply perform linear regression in the feature space you map  $\mathbf{x}$  to. Use the same train and val split as for dual regression. Estimate the optimal number of clusters and  $\sigma$  on the val set. Also evaluate regressor's performance on the test data. (2 Points)

## 2 Classification

We consider the problem of binary classification (bottles and horses). Given are the 510 dimensional PHoG features for each class, separated for training and testing. The data is arranged in a similar manner as above.

1. Logistic Regression: Using the bottles as positive and the horses as negative examples, learn a linear classifier based on logistic regression. The loss function is the negative log-likelihood. You may choose a simple gradient descent or the Newton's method for optimization. Train your classifier for 10000 iterations printing the loss and the accuracy every 1000 iterations. You should reach 90% accuracy on the test set. Can your model get stuck in a local minimum and why?

$$Accuracy = \frac{TP + TN}{TP + FP + TN + FN} \tag{1}$$

where TP and FN stand for true positive and false negative respectively. (5 Points)

2. **Derivatives of Log-Likelihood:** In logistic regression, the log-likelihood is given by

$$L = \sum_{i=1}^{I} y_i log \left( \frac{1}{1 + exp(-w^T x_i)} \right) + \sum_{i=1}^{I} (1 - y_i) log \left( \frac{exp(-w^T x_i)}{1 + exp(-w^T x_i)} \right)$$

Show the gradient to be

$$\frac{\partial L}{\partial w} = -\sum_{i=1}^{I} \left( \frac{1}{1 + exp(-w^T x_i)} - y_i \right) x_i \tag{2}$$

Provide a comprehensible solution. (4 Points)

## References

[1] Bosch, A. and Zisserman, A. and Munoz, X. Representing shape with a spatial pyramid kernel. In Proceedings of the International Conference on Image and Video Retrieval, pp 401-408, 2007