

Rao FU | Ph.D. Candidate

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Research Interest

My research is on capturing, analyzing, generating, and high-fiving with static and dynamic 3D from intuitive language instructions!

Education

Brown University | Computer Sciences **Providence, RI, USA**
Computer Science Ph.D. Candidate *Sept. 2021 – Present.*

Advisor: Srinath Sridhar. Committee: Daniel Ritchie, Stefanie Tellex, and George Konidaris.

Max Planck Institute for Informatics **Saarbrücken, German**
Visiting Scholar *May. 2025 – Sept. 2025*

Host: Christian Theobalt & Rishabh Dabral.

Brown University | Computer Sciences **Providence, RI, USA**
Master of Science in Computer Science *Sept. 2021 – May. 2024*

University of Chinese Academy of Sciences | Computer Sciences and Engineering **Beijing, China**
Bachelor of Computer Engineering *Sept. 2017 – Jun. 2021*

National Inspirational Scholarship & Outstanding Thesis Awards.

University of California, San Diego | Jacobs School of Engineering **San Diego, CA, USA**
Visiting Scholar *May. 2020 – Nov. 2020*

Host: Hao Su.

University of Southern California | Viterbi School of Engineering **Los Angeles, CA, USA**
Visiting Student *Jan. 2020 – May. 2020*

Beijing National Day School **Beijing, China**
Student *Sept. 2011 – Jul. 2017*

Employment

Meta Inc. | GenAI, Llama Team **Menlo Park, CA, US.**
Research Scientist Intern *June. 2023 – Oct. 2023*

Manager: Wenhan Xiong.

Autodesk Inc. | AI Lab **San Francisco, CA, USA.**
Research Scientist Intern *May. 2022 – Dec. 2022*

Manager: Aditya Sanghi.

Microsoft Research, Asia | Vision Group & Speech Group **Beijing, China.**
Research Intern *Mar. 2021 – Jul. 2021*

Manager: JingDong Wang, Yuhui Yuan, Weihong Lin.

Invited Talk

MIT, Multisensory Intelligence Group: Title: Capturing Dexterity *Host: Prof. Paul Liang (April 2025)*

University of California, Berkeley, Computer Vision Group: Title: Capturing Dexterity *(March 2025)*

Columbia University, RoboPIL: Title: Capturing Dexterity *Host: Prof. Yunzhu Li (March 2025)*

New York University, Immersive Computing Lab: Title: Capturing Dexterity *Host: Prof. Qi Sun (March 2025)*

NYC Vision Day 2025: GigaHands: A Massive Annotated Dataset of Bimanual Hand Activities.

New England Computer Vision Workshop, 2023: AnyHome: Open-Vocabulary Generation of Structured and Textured 3D Homes.

New England Computer Vision Workshop, 2022: ShapeCrafter: A Recursive Text-Conditioned 3D Shape Generation Model.

ICT Turing Seminar, 2022 : Text-conditioned 3D Shape Generation.

Publications

[1]: GigaHands: A Massive Annotated Dataset of Bimanual Hand Activities. **Rao Fu***, D. Zhang*, A. Jiang, W. Fu, A. Funk, D. Ritchie, S. Sridhar

The IEEE/CVF Conference on Computer Vision and Pattern Recognition 2025 (CVPR 2025, highlight) [paper link](#)

[2]: Scene-LLM: Extending Language Model for 3D Visual Understanding and Reasoning. **Rao Fu**, Jingyu Liu, Yixin Nie, Xilun Chen, Wenhan Xiong

The Winter Conference on Applications of Computer Vision (WACV 2025) [paper link](#)

[3]: AnyHome: Open-Vocabulary Generation of Structured and Textured 3D Homes. **Rao Fu***, Zehao Wen*, Zichen Liu*, Srinath Sridhar.

The European Conference on Computer Vision 2024(ECCV 2024) [paper link](#)

[4]: CharacterMixer: Rig-Aware Interpolation of 3D Characters. X. Zhan, **Rao Fu**, D. Ritchie

Annual Conference of the European Association for Computer Graphics 2024(Eurographics 2024) [paper link](#)

[5]: CLIPSculptor: Zero-shot Generation of High Fidelity and Diversity Shapes from Text. A. Sanghi, **Rao Fu**, V. Liu, K. Willis, H. Shayani, A. H. Khasahmadi, S. Sridhar, D. Ritchie

Conference on Computer Vision and Pattern Recognition.(CVPR 2023) [paper link](#)

[6]: ShapeCrafter: A Recursive Text-Conditioned 3D Shape Generation Model. **Rao Fu**, X. Zhan, Y.W. Chen, D. Ritchie, S. Sridhar.

Conference on Neural Information Processing Systems.(NeurIPS 2022) [paper link](#)

[7]: HRformer: High-resolution vision transformer for dense predict. Yuhui Yuan, **Rao Fu**, Lang Huang, Weihong Lin, Xilin Chen, Jingdong Wang.

Conference on Neural Information Processing Systems.(NeurIPS 2021) [paper link](#)

[8]: ROSA-Net: Rotation-Robust Structure-Aware Network for Fine-Grained 3D Shape Retrieval. **Rao Fu**, Jie Yang, Jiawei Sun, Fanglue Zhang, Yu-Kun Lai, Lin Gao.

Computational Visual Media Conference.(CVM 2024) [paperlink](#)

Manuscripts

[1]: DynaCon: Dynamic Contact Capture in Bimanual Hand-Object Manipulation. X.Y. Cong, A. Xing, C. Pokhariya, **Rao Fu**, S. Sridhar

In Submission to appear

[2]: NeuralODF: Learning Omnidirectional Distance Fields for 3D Shape Representation. T. Houchens, C.Y. Lu, S. Duggal, **Rao Fu**, S. Sridhar

Technical Report [paper link](#)

Workshops

ICCV 2025 HANDS: (To be announced)

Teaching Experience

CSCI 2952-K: Topics in 3D Computer Vision and Machine Learning:

Role: GTA and Co-Instructor

Grants

08.2024 - 08.2025: OpenAI Research Program Access Grant(\$5,000).

Awards and Honors

07.2021: UCAS Outstanding Undergrad Thesis Awards(Advisor: Prof. Xilin Chen).

09.2019: National Inspirational Scholarship.

09.2017: National College Entrance Exam: Top 1‰

Professional Service

Conference/Journal Reviewer: Siggraph 2025(2), Siggraph Asia 2024(2)/2023(1), ICML 2025(5)/2024(6), ICLR 2024(3)/2023(4), NeurIPS 2025/2023(3)/2022(2), ICCV 2025(4)/2023(2), ECCV 2024(4), CVPR 2025(4)/2024(5)/2023(4), IJCV(1), RSS 2023(2), TVCJ(2)

Google explore CSR: Ph.D. mentor 2022, 2023

Department PhD Admissions Committee Member: 2024, 2023

Research Mentoring

Xiao (Sean) Zhan Next position: PhD Student, MIT	Brown CS Undergrad 2023
Yiwen Chen Next position: PhD Student, NEU	Brown CS Master 2023
Dingxi Zhang Next position: CS Master, ETH Zurich	UCAS CS Undergrad 2024
Zehao Wen Next position: CS undergrad, JHU	Shenzhen International School
Zichen Liu Next position: Robotics undergrad, UCL	Shenzhen International School
Melvin He Next position: Software, Meta	Brown CS Undergrad 2025
Alex Jiang Current	Brown CS Undergrad 2028
Fiona Fan Current	Brown CS Undergrad 2028
Wanjia (Juia) Fu Current	Brown CS Undergrad 2026
Jiayi Shen Current	Brown CS Master 2026

Research Lead Experience

3D Hand Object Manipulation.....	
Research on 3D Hand Object Motion Synthesis.	MPI, Informatics; Brown University
<i>Research Group: 3D Visual Intelligence, MPI Informatics</i>	<i>May. 2025 – Now.</i>
◦ Generating hand-object deformation during interaction.	
Research on Force and Haptic Capturing during HOI.	Brown University
<i>Research Group: Brown IVL, Columbia RoboPIL, NYU ICL, MIT MMLab</i>	<i>March. 2025 – Now.</i>
◦ Capture force information during HOI.	
Research on In-Hand Manipulation Taxonomy.	Yale Grab; Brown University
<i>Research Group: Brown IVL, Yale Grab</i>	<i>Feb. 2025 – Now.</i>
◦ Building taxonomy for uni-manual in-hand dexterous manipulation.	
Research on 3D Hand Motion Dataset Construction.	Brown University
<i>Research Group: Brown IVL</i>	<i>Jan. 2023 – April. 2025</i>
◦ Constructing Large-Scale 3D Hand Motion Dataset with Marker-less Motion Capturing System.	
◦ Showcasing diverse applications including 3D hand motion generation, hand motion captioning for both 3D sequences and videos, motion retargeting to robotic grippers, dynamic semantic scene reconstruction, and multitasking capabilities.	
3D Scene Understanding and Generation	
Research on 3D-Visual-Language Model.	Meta Research
<i>Research Group: GenAI</i>	<i>May. 2023 – Nov. 2023</i>
◦ Extending Llama-2 for a 3D-Visual-Language Model for interactive 3D scene understanding and reasoning.	

Research on Text-to-Scene Generation.

Research Lead

Brown University

May. 2023 – Nov. 2023

- Propose a text-to house-scale scene generation method.
- The generation is structured and textured. Featuring control-ability with text and user inputs.

Language and 3D Shapes.....

Research on Zero-shot Text-conditioned 3D Shape Generation.

Brown University

Guide: Prof. Aditya Sanghi

May. 2023 – Dec. 2023

- Develop zero-shot text-conditioned shape generation method using 3D diffusion-based model.
- The generated shape set if of high diversity and quality.

Research on Text-conditioned 3D Shape Generation.

Brown University

Guide: Prof. Srinath Sridhar

Sept. 2022 – Present.

- Proposed a NLP-based method that augment one-to-one text-shape pairs to many-to-many correspondence.
- Propose a method that generates and edits high-quality 3D shapes with language.

Machine Perception.....

Research on High-Resolution Transformer.

Microsoft Research, Asia

Research Group: Visual Computing

March. 2021 – July. 2021

- Proposed a transformer-based neural network for dense prediction tasks.
- Achieved state-of-the-art performance on COCO human pose estimation benchmark.

Learning Based Robotics.....

Research on Articulation Grasping for Fast Exploration.

University of California, San Diego

Guide: Prof. Hao Su

May. 2020 – Nov. 2020

- Studied the problem of geometric based manipulation for efficient exploration.
- Proposed a novel neural network architecture that predicts grasp proposals efficiently and effectively.

Learning Based Graphics, Vision and Geometry Processing.....

Research on Emotional Talking Head Generation.

Institute of Computing Technology, CAS

Guide: Prof. Dinesh Manocha; Prof. Yu-Kun Lai; Prof. Lin Gao

Sept. 2020 – Nov. 2020

- Designed a pipeline that generates high-quality speech-driven talking head video with expressive emotion.
- Contributed to TAL Education Group Online School project.

Research on Fine-grained 3D Shape Retrieval.

Institute of Computing Technology, CAS

Guide: Prof. Fanglue Zhang; Prof. Yu-Kun Lai; Prof. Lin Gao

Sept. 2019 – May. 2020

- Proposed a deep architecture for rotation-invariant fine-grained 3D shape retrieval.
- Constructed and released a fine-grained 3D shape retrieval dataset.

Mathematics.....

A Geometric Solution to Multi-person Meeting Problem.

Beijing National Day School

Guide: Tiehan Li

Jan. 2017 – Feb. 2017

- Solved the multi-person meeting problem by formulating a dynamic programming problem into a high-dimensional geometric problem.

A Concise Discriminant of Cubic Real Coefficient Equations.

Beijing National Day School

Guide: Tiehan Li

Sept. 2016 – Dec. 2016

- Proposed a concise discriminant of cubic real coefficient equations. The method is applicable when the equation has one real root and two imaginary roots, more applicable than Cardano formula.

Reference

Dr. Srinath Sridhar

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PhD Advisor, Assistant Prof. at Brown University

Dr. Daniel Ritchie

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Collaborator, Associate Prof. at Brown University

Dr. Hao Su

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Collaborator, Associate Prof. at UCSD