Rao FU | Ph.D. Student

†Homepage: https://freddierao.github.io ⊠Address: 115 Waterman Street, Providence, RI 02912

Education

Brown University | Dept. Computer Sciences

Providence, RI, USA

Computer Science Ph.D. Student

Sept. 2021 – Present.

Concentration: Vision, Graphics and Robotics

Beijing, China

Bachelor of Computer Science

Sept. 2017 - Jun. 2021

Overall GPA: 3.72/4.00. Core GPA: 3.82/4.00.

Outstanding Thesis Awards.

Los Angeles, CA, USA

University of Southern California | Viterbi School of Engineering

University of Chinese Academy of Sciences | Dept. Computer Sciences

Jan. 2020 – May. 2020

Visiting Student GPA: **4.00** / 4.00

Beijing National Day School

Beijing, China

Student

Sept.. 2011 – Jul.. 2017

INTERNSHIP

Microsoft Research, Asia | Speech Group, Visual Computing Group

Beijing, China

Award of Excellence at Star of Tomorrow Internship

Mar. 2021 – July. 2021

University of California, San Diego | SU Lab

San Diego, CA, USA

Visiting Scholar

May. 2020 – Nov. 2020

Publication and Submission

[1]: Yuhui Yuan, Rao Fu, Lang Huang, Weihong Lin, Xilin Chen, Jingdong Wang. HRT: High-Resolution Vision Transformer for Dense Prediction.

Conference on Neural Information Processing Systems. (NIPS2021)

[2]: Rao Fu, Jie Yang, Jiawei Sun, Fanglue Zhang, Yu-Kun Lai, Lin Gao. RISA-Net: Rotation-Invariant Structure-Aware Network for Fine-Grained 3D Shape Retrieval.

Submit to IEEE Transactions on Pattern Analysis and Machine Intelligences.(TPAMI)

Professional Service

Conference Reviewer: Computational Visual Media Conference 2021 (CVM2021)

Research Experience

Computer Vision.....

Research on High-Resolution Transformer.

Microsoft Research, Asia

Research Group: Visual Computing

March. 2021 – July. 2021

- Proposed a transformer-based neural network for dense prediction tasks.
- Achieved state-of-the-art performance on COCO human pose estimation benchmark.

Research on Humanoid Gripper Grasping.

University of California, San Diego

Guide: Prof. Hao Su

Aug. 2020 – Nov. 2020

• Proposed a network mapping object action space to robot configuration space, facilitating robot grasping.

- o Proposed a motion planning algorithm that effectively boost the efficiency of grasp execution.
- o Finished a paper as a co-author and the paper was submitted to NIPS2021.

Research on Articulation Grasping for Fast Exploration.

University of California, San Diego May. 2020 - Nov. 2020

Guide: Prof. Hao Su • Studied the problem of geometric based manipulation for efficient exploration.

o Proposed a novel neural network architecture that predicts grasp proposals efficiently and effectively.

• Finished a technical paper as a co-author and the paper was submitted to CVPR2021.

Learning Based Graphics, Vision and Geometry Processing.....

Research on Emotional Talking Head Generation. TAL Education; Institute of Computing Technology, CAS Guide: Prof. Dinesh Manocha; Prof. Yu-Kun Lai; Prof. Lin Gao Sept. 2020 – Nov. 2020

• Designed a pipeline that generates high-quality speech-driven talking head video with expressive emotion.

- o Contributed to TAL Education Group Online School project.
- o Finished a technical paper as first author and the manuscript was submitted to CVPR2021.

Research on Fine-grained 3D Shape Retrieval.

Alibaba; Institute of Computing Technology, CAS

Guide: Prof. Fanglue Zhang; Prof. Yu-Kun Lai; Prof. Lin Gao

Sept. 2019 – May. 2020

- Proposed a deep architecture for rotation-invariant fine-grained 3D shape retrieval.
- o Constructed and released a fine-grained 3D shape retrieval dataset.
- o Contributed to *Alibaba* 3D Online Shopping system.
- o Completed an academic paper as first author and the manuscript was submitted to IEEE TPAMI.

Research on Single Image Reconstruction.

Institute of Computing Technology, CAS

Guide: Prof. Lin Gao.

Jul. 2019 - Sept. 2020

 Combined parameterized modelling methods in traditional graphics algorithms with neural networks to reconstruct outdoor scene from a single image.

A Geometric Solution to Multi-person Meeting Problem.

Beijing National Day School

Guide: Tiehan Li

Jan. 2017 - Feb. 2017

- Solved the multi-person meeting problem by formulating a dynamic programming problem into a high-dimensional geometric problem.
- o Finished a math thesis.

A Concise Discriminant of Cubic Real Coefficient Equations.

Beijing National Day School

Guide: Tiehan Li

Sept. 2016 - Dec. 2016

- Proposed a concise discriminant of cubic real coefficient equations. The method is applicable when the equation has one real root and two imaginary roots, more applicable than Cardano formula.
- o Finished a math thesis.

Volunteer Experience

Starry Sky Program 2019.

o Organizer of popularizing STEM knowledge to left-behind female students in Mianyang, Sichuan Province.

Starry Sky Program 2018.

o Organizer and teacher of popularizing STEM knowledge to left-behind female students in Huaihua, Hunan Province.

Awards and Honors

07.2021: Award of Excellence at Star of Tomorrow Internship.

07.2021: Outstanding Thesis Awards at UCAS.

09.2020: Excellent Comprehensive Performance Scholarship(top **15**% in the Dept. of CS).

12.2019: First Prize in CCF Big Data & Computing Intelligence Contest. Ranking:1%

09.2019: National Inspirational Scholarship(top 5% among all competitors at UCAS).

09.2019: Excellent Comprehensive Performance Scholarship(top 15% in the Dept. of CS).

Skills

Standard Tests: TOFEL 108, GRE 330

Programming: C/C++, Python, Matlab, Latex, HTML, CSS, VHDL

Tools: PyTorch, TensorFlow, OpenGL, Sapien, Vim, Git, Docker, Kubenetes

Software: Autodesk Maya, Adobe Illustrator, Adobe Photoshop, Bugzilla, Vivado

Extracurricular Activities

03.2019: The 93rd place in the 38th Beijing Open Half Marathon Park Run.

01.2019-05.2019: Writer, actor and vice president of UCAS *Dreamer* drama club.

09.2018-07.2019: President of UCAS Swimming Club (Excellent Student's Club of UCAS).