

Wiederholung  $c \mid \frac{A}{b^T}$

$$g_j = y_0 + h \sum_{i=1}^s a_{ij} f(x_0 + c_i h, g_j)$$

$$y_1 = y_0 + h \sum_{i=1}^s b_i f(x_0 + c_i h, g_i)$$

### § 1 Beispiel Prothero & Robinson

$$y' = \lambda(y - \varphi(x)) + \varphi'(x), \quad y(x_0) = \varphi(x_0), \quad \operatorname{Re} \lambda < 0 \quad (\text{PR})$$

Lös:  $y(x) = \varphi(x)$

$$g_j = y_0 + h \sum_{i=1}^s a_{ij} \left( \lambda \underbrace{(g_j - \varphi(x_0 + c_j h))}_{=0} + \varphi'(x_0 + c_j h) \right)$$

$$y_1 = y_0 + h \sum_{i=1}^s b_i \left( \lambda \underbrace{(g_i - \varphi(x_0 + c_i h))}_{=0} + \varphi'(x_0 + c_i h) \right)$$

$g_j$	$\varphi(x_0 + c_j h)$
$y_0$	$\varphi(x_0)$
$y_1$	$\varphi(x_0 + h)$

$$\varphi(x_0 + c_j h) = \varphi(x_0) + h \sum_{i=1}^s a_{ij} \varphi'(x_0 + c_i h) + \Delta_{i,j,h}(x_0) \quad \text{Taylor} \quad \mathcal{O}(h^{p+1})$$

$$\varphi(x_0 + h) = \varphi(x_0) + h \sum_{i=1}^s b_i \varphi'(x_0 + c_i h) + \Delta_{0,h}(x_0) \quad \mathcal{O}(h^{q+1})$$

$\min(p, q)$  Stage order

Notation:  $\varphi_i := \varphi(x_0 + c_i h)$   $\varphi_0 := \varphi(x_0), y_0 = y(x_0)$

$$\varphi = \begin{pmatrix} \varphi_1 \\ \vdots \\ \varphi_s \end{pmatrix} \quad g = \begin{pmatrix} g_1 \\ \vdots \\ g_s \end{pmatrix} \quad \Delta_h(x) = \begin{pmatrix} \Delta_{1,h}(x) \\ \vdots \\ \Delta_{s,h}(x) \end{pmatrix}, \quad z = \lambda \cdot h$$

$$g - \varphi = (y_0 - \varphi_0) \mathbb{1} + z \cdot A (g - \varphi) - \Delta_h(x_0) \rightsquigarrow g - \varphi = (I - zA)^{-1} \mathbb{1} (y_0 - \varphi_0) - (I - zA)^{-1} \Delta_h(x_0)$$

$$\mathbb{1} + zB(I - zA)^{-1} \mathbb{1}$$

$$\Rightarrow y_1 - \varphi(x_0 + h) = (y_0 - \varphi_0) + z b^T (g - \varphi) - \Delta_{0,h}(x_0) = R(z) \underbrace{(y_0 - \varphi_0)}_{=0} - \underbrace{b^T (I - zA)^{-1} \Delta_h(x_0) - \Delta_{0,h}(x_0)}_{:= \delta_h(x_0) \text{ Lokaler Fehler}}$$

$$x_0 \rightsquigarrow x_n: \quad y_{n+1} - \varphi(x_{n+1}) = R(z) (y_n - \varphi(x_n)) + \delta_h(x_n)$$

Globaler Fehler:

$$y_{n+1} - \varphi(x_{n+1}) = R(z)^{n+1} (y_0 - \varphi_0) + \sum_{j=0}^n R(z)^{n-j} \delta_h(x_j)$$

Radau IIA  $a_{si} = b_i \quad \forall i \in \{1, \dots, s\}$

$$e_s^T (g - \varphi) = e_s^T (I - zA)^{-1} \underbrace{\Delta_h(x)}_{O(h^{s+1})} \rightsquigarrow O(z^{-1} h^{s+1})$$

$$h \rightarrow 0 \quad h \gg \frac{1}{|\lambda|} \quad \& \quad \lambda h = z \rightarrow \infty$$

$$R(z) \rightarrow 0 \text{ f\"ur } z \rightarrow \infty$$

Verfahren	klassische Ordnung	lokaler Fehler	globaler Fehler	stiffly accurate	$\beta$ -Konv.
Gauss	$2s$	$h^{s+1}$	$h^s$		$S \subset S-1$
Radau IA	$2s-1$	$h^s$	$h^s$		$S$
Radau IIA	$2s-1$	$z^{-1} h^{s+1}$	$z^{-1} h^{s+1}$	✓	✓
Lobatto IIIA	$2s-2$	$z^{-1} h^{s+1}$	$z^{-1} h^s$	✓	✓
Lobatto IIIB	$2s-2$	$z h^{s-1}$	$z h^{s-2}$		✓
Lobatto IIIC	$2s-2$	$z^{-1} h^{s+1}$	$z^{-1} h^s$	✓	$S-1 (\gamma \leq 0)$

## § 2. Lokaler Fehler

2.1 Definition Für  $y' = f(x, y)$ :  $\langle f(x, y) - f(x, z), y - z \rangle \leq \nu \|y - z\|^2$  (ELS)

### 2.2 Theorem (Dekker)

$$g_i \longrightarrow \hat{g}_i = g_i + \delta_i \quad \curvearrowright \quad y_n \longrightarrow \hat{y}_n$$

$$\Rightarrow \|g - \hat{g}\| \leq C \|\delta\| \quad \curvearrowright \quad \|y_n - \hat{y}_n\| \leq C' \|\delta\|$$

für  $A$  inv., (ELS) und  $h\nu < \alpha$  ( $\curvearrowright$  Verfahren, berechenbar)

2.3 Prop. (ELS),  $A$  inv., stage order  $p$

Falls  $\alpha \geq 0$ :

$$\|\delta_h(x)\| \leq \underset{\substack{\uparrow \\ \text{nur vom Verf.} \\ \text{abh.}}}{C} h^{p+1} \max_{\xi \in [x, x+h]} \|y^{(p+1)}(\xi)\| \quad \text{für } h\nu < \alpha$$

Beweis (Idee): Betrachte  $y(x+h) = \hat{y}_1 = y_1 + \delta_1 \leadsto y_n \rightarrow \hat{y}_n$

$$\|\delta_n(x)\| = \|y_n - y(x+h)\| \leq \underbrace{\|y_n - \hat{y}_n\|}_{2.2} + \underbrace{\|\hat{y}_n - y(x+h)\|}_{\text{Taylor}} \quad \square$$

### § 3. Fehlerfortpflanzung

#### 3.1 Definition (Butcher 1975): B-Stabil

$$\langle f(x, y) - f(x, z), y - z \rangle \leq 0$$

$$\Rightarrow \|y_1 - \hat{y}_1\| \leq \|y_0 - \hat{y}_0\| \quad \text{f.a. } h \geq 0$$

$y_1, \hat{y}_1$  num. LÖS. zu  $y' = f(x, y)$  mit AW  $y_0, \hat{y}_0$

#### 3.2. Definition Algebraisch Stabil:

i)  $b_i \geq 0 \quad \forall i \in \{1, \dots, s\},$

ii)  $M = (m_{ij}) = (b_i a_{ij} + b_j a_{ji} - b_i b_j)_{i,j=1}^s$  positiv semi definit.

### 3.3 Theorem:    Algebraisch stabil $\Leftrightarrow$ B-stabil

Beweis: Notation:  $\Delta y_0 = y_0 - \hat{y}_0$ ,  $\Delta y_1 = y_1 - \hat{y}_1$ ,  $\Delta g_i = g_i - \hat{g}_i$ ,  $\Delta f_i = h(f(x_0 + C_i h, g_i) - f(x_0 + C_i h, \hat{g}_i))$

$$\Delta y_1 = \Delta y_0 + \sum_{i=1}^s b_i \Delta f_i \Rightarrow \|\Delta y_1\|^2 = \|\Delta y_0\|^2 + 2 \sum_{i=1}^s b_i \langle \Delta f_i, \Delta y_0 \rangle + \sum_{i,j=1}^s b_i b_j \langle \Delta f_i, \Delta f_j \rangle$$

$$\Delta g_i = \Delta y_0 + \sum_{j=1}^s a_{ij} \Delta f_j$$

$$\Rightarrow \|\Delta y_1\|^2 = \|\Delta y_0\|^2 + 2 \sum_{i=1}^s \underbrace{b_i}_{\geq 0} \underbrace{\langle \Delta f_i, \Delta g_i \rangle}_{\leq 0} - \sum_{i,j=1}^s \underbrace{m_{ij}}_{\geq 0 \rightarrow \text{Aufgabe}} \langle \Delta f_i, \Delta f_j \rangle \Rightarrow \|\Delta y_1\| \leq \|\Delta y_0\| \quad (*)$$

### 3.4 Theorem    (ELS), Alg. stabil, A inv. $\Rightarrow \exists C$ :

$$\|y_1 - \hat{y}_1\| \leq (1 + C h^\nu) \|y_0 - \hat{y}_0\| \quad \text{für } 0 \leq h^\nu \leq \alpha$$

Beweis:

$$(*) \quad 2 \sum_{i=1}^s b_i \langle \Delta f_i, \Delta g_i \rangle \leq 2 h^\nu \sum_{i=1}^s b_i \underbrace{\|\Delta g_i\|}_{\leq C \|y_0 - \hat{y}_0\|} \leq C h^\nu \|y_0 - \hat{y}_0\| \quad \text{in } (*)$$



# § 4. B-Konvergenz

## 4.1 Theorem

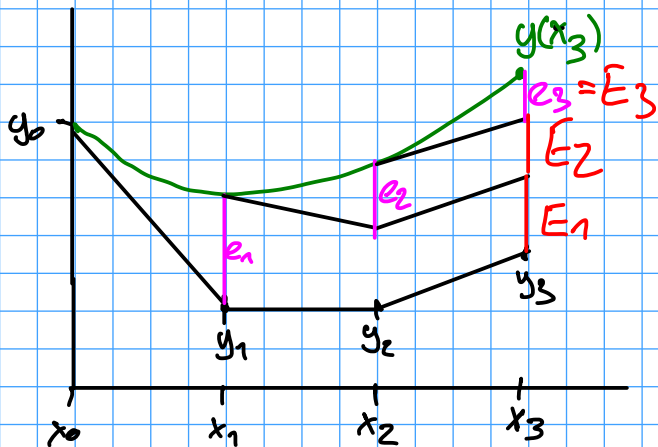
Alg. Stab., A inv., stage order  $p$ , (ELS)

$(h = \max_i h_i)$

$$\|y_n - y(x_n)\| \leq h^p \gamma(x_n - x_0, \gamma) \max_{x \in [x_0, x_n]} \|y^{(p+1)}(x)\| \text{ f\"ur } h^\gamma < \alpha$$

$$\|y_n - y(x_n)\| \leq h^p \underbrace{e^{L(x_n - x_0)}}_{\rightarrow \infty \text{ f\"ur gro\ss e Steifheit}} \max_{x \in [x_0, x_n]} \|y^{(p+1)}(x)\|$$

Beweis (Idee):



$$\|y_n - y(x_n)\| \leq \sum_{i=1}^n \|E_i\|$$

$$\|E_i\| \leq (1 + C(x_n - x_i)) \|y_{j-1}^{(p)}(x_{j-1})\|$$

$$\leq e^{C(x_n - x_j)} \|y_{j-1}^{(p)}(x_{j-1})\|$$

$$\leq C h^{p+1} \max \dots$$

B-Konvergenz: der Ord.  $r$   
(ELS) erfüllt

$$\|y_n - y(x_n)\| \leq h^r \gamma(x_n - x_0, \gamma) \max_{\ell} \max_x \|y^{(\ell)}(x)\| \text{ f\"ur } h^r < \alpha$$