

ALGORITHMS PROJECT 5

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- Original Problem: Dr. Cooper would like to know the minimum number of legs required to fly from one city to another city, given the map of SheldonAir flights map.
- **Problem behind:** Given two vertices u and v of an undirected, unweighted graph (with n vertices and m edges), compute the length of a shortest path between u and v.
- In our python3 codes, a graph is a dictionary which keys are vertices and values are list of vertices connected to corresponding key.
- Language: Python 3
- Libraries: math, random, time, dequeue, numpy, matplotlib
- Test Environment: PC

Naive Approach

Floyd & Warshall (All Pairs Shortest Paths)

- Application of dynamic programming
- Idea: Starting from the *adjacency matrix*(1 means an edge, math.inf means no edge), build a three-dimensional minimum distance matrix
- Can reduce space to $O(n^2)$ (we use n^3 in our codes)

Time Complexity: O(n³)

Space Complexity: $O(n^2) - n \times n \ array \ (matrix)$

Bread First Search

Can we do better than APSP?

Since the graph in unweighted, actually *Bread First Search* provides a solution to the problem!

Time Complexity: O(n + m)

Space Complexity: O(n + m) - The graph itself

Python Codes - Algorithms - User Guide

BFS_Shortest_Path: implementation of BFS (Solution1)

✓ Insert your own sample graph
implemented as an adjacency matrix
✓ Call the «short» function, passing as
parameters the graph and the two nodes

• DP_Shortest_Path: implementation of APSP (Solution2)

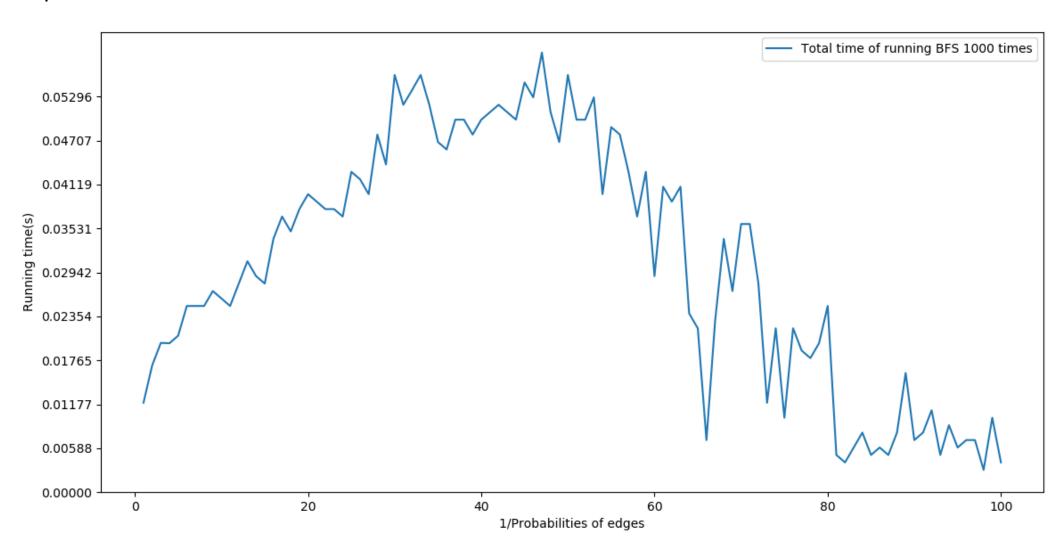
- ✓ Insert your own sample graph implemented as an adjacency matrix
- ✓ Call the «cube» function, passing as parameter the graph
- ✓ Call the «nodes» function, passing as parameter the graph
- ✓ Call the «short» function, passing as parameters the graph and the two nodes

Other Python Codes - Tests

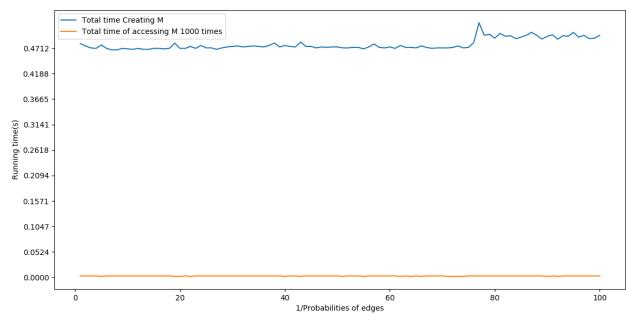
- test_BFS: implementation of BFS. Test on inputs with different probability of having an edge between two nodes.
- test_DP1: implementation of APSP. Test on inputs with different probability of having an edge between two nodes.
- test_DP2: implementation of APSP. Test on input graphs with different number of nodes.
- test_stress: implementation of a Stress Test to check correcteness.
- •graph_random: to generate a random graph.

Algorithm Implementation: Plots - BFS

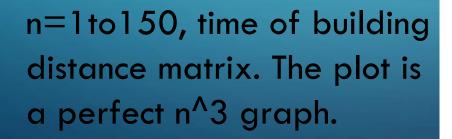
Graph info: n=100

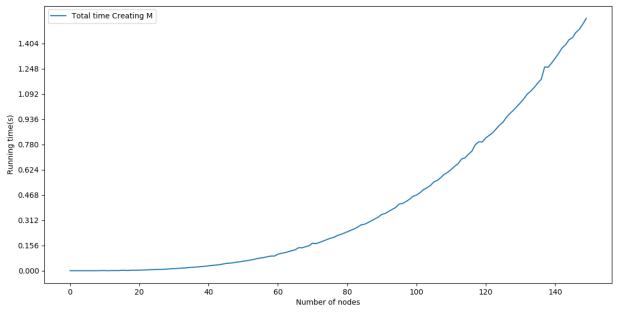


Algorithm Implementation: Plots - DP1&DP2



n=100, time of creating matrix(blue line), and time of accessing(orange line, almost 0).





ANALYSIS OF PLOTS

- Why BFS test plot has a peak around 40?
 - The x axis represents the reciprocal of probability of having an edge between two vertices. In both high and low probabilities, BFS can perform very fast, while a middle amount of probability slow it down.
- Why DP cost almost same time whatever the probability is?
 - DP is always creating the distance matrix in $O(n^3)$, so m doesn't matter the total time.

Which algorithm is better?

From our Time Complexity Analysis, <u>BFS turns out to be faster</u> - O(n + m)

Actually, practical implementation matters!

In the Dynamic Programming approach, the demanding step in terms of computational resources is building the matrix, while accessing it is extremely fast!

An Amortized Analysis for a huge number of accesses might prove better bounds

In practice, SheldonAir could follow the DP approach by:

- Building the table just once and storing it (Time O(n³) needed)
- All the future accesses will then be possible in constant time (Close to 0, as shown in the Plot!)
- Or just uses BFS if he wants only one pair of u and v.
- You're welcome, Sheldon!