

Representation theory

Fredrik Meyer

Abstract

These are notes from the course MAT4270 on representation theory, autumn 2015. The lectures were held by Sergey Neshyevy. The notes are mine. The first half is about representations of finite groups, the second half about representations of compact Lie groups.

1 Lecture 1

From now on G is always a *finite group* and V a finite-dimensional vector space over the complex number. Most results will hold over any algebraically closed field of characteristic zero.

1.1 Motivating example

In 1896 Dedekind made the following observation. Let $\mathbb{C}[x_g \mid g \in G]$ be the free \mathbb{C} -algebra with basis the elements of G . Then one can form the following polynomial:

$$P_G(x_{\rho_1}, \dots, x_{\rho_n}) = \det \left((x_{\rho_i g_j})_{i,j=1}^n \right).$$

Note that the matrix is just the multiplication table for the group G . The problem is to decompose P_G into irreducible polynomials.

Example 1.1. Let $G = S_3$. Then G is generated by two elements r and s with the relation $srs = r^2$. If we write the elements of G as $\{e, r, r^2, s, sr, sr^2\}$, then the multiplication table looks like

$$\begin{pmatrix} e & r & r^2 & s & sr & sr^2 \\ r & r^2 & e & sr^2 & s & sr \\ r^2 & e & r & sr & sr^2 & s \\ s & sr & sr^2 & e & r & r^2 \\ sr & sr^2 & s & r^2 & e & r \\ sr^2 & s & sr & r & r^2 & e \end{pmatrix}.$$

The determinant is quite long, so I won't write it out. Suffice it to say it is a degree 6 polynomial with 146 terms. Using a computer algebra system such as `Macaulay2`, one can decompose it. It decomposes into three factors: one quadratic and two linear. They are the following (we change notation to avoid confusion about exponents):

$$x_e + x_r + x_{r^2} + x_s + x_{sr} + x_{sr^2}$$

and

$$x_e + x_r + x_{r^2} - x_s - x_{sr} - x_{sr^2}$$

and

$$x_e^2 - x_e x_r + x_{r^2} - x_e x_{r^2} - x_r x_{r^2} + x_{r^2}^2 - x_s^2 + x_s x_{sr} - x_{sr^2}^2 + x_s x_{sr^2} - x_{sr^2}^2 - x_{sr^2}^2.$$

We will see later that the first factor corresponds to the trivial representation, the second to the alternating representation, and the third is the so-called standard representation of G . ★

Frobenius proved the following theorem:

Theorem 1.2. *Let $P_G = \prod_{i=1}^r P_i^{m_i}$ be the decomposition of P_G into irreducibles. Then*

1. $m_i = \deg P_i$ for every i .
2. r is the number of conjugacy classes in G .

In particular, since $r = |G|$ if and only if G is abelian, P_G decomposes into linear factors if and only if G is abelian.

In trying to prove the above theorem, Frobenius had to develop representation theory.

1.2 Representations

A **representation of G on V** is a homomorphism $\pi : G \rightarrow \text{GL}(V)$. We will denote a representation interchangeably by π , (π, V) , V_π or V , depending upon the situation.

This means that a representation is a *linear* action of G on V .

Example 1.3. The trivial representation ϵ of any group is given by letting $V = \mathbb{C}$ and $\epsilon(g) = e$ for all $g \in G$. ★

Example 1.4 (Left regular representation). Let $\mathbb{C}[G]$ be the space of functions on G . It is a finite-dimensional vector space under pointwise addition. Define $\lambda : G \rightarrow \text{GL}(\mathbb{C}[G])$ by

$$g \mapsto (f \mapsto (h \mapsto f(g^{-1}h)))$$

This vector space have a basis consisting of the characteristic functions e_g for $g \in G$. On these elements one sees that the action is given by $g \cdot e_h = e_{gh}$. ★

Example 1.5. Similarly, one has the **permutation representation**. Let X be a G -set, i.e. a set on which G acts. Then one forms the space $\mathbb{C}[X]$ of X -valued functions. It has a basis e_x of characteristic functions, and the action of G on $\mathbb{C}[X]$ is given by $ge_x = e_{gx}$. ★

The notion of isomorphism is not surprising. An **equivalence** of representations (π, V) and (θ, W) is given by a vector space isomorphism $T : V \rightarrow W$ such that $T(g \cdot v) = g \cdot T(v)$ for all $g \in G$.

In case $T : V \rightarrow W$ is not an isomorphism, we say that T is an **intertwiner** of V and W . The set of intertwiners is denoted by $\text{Mor}(\pi, \theta)$ or $\text{Hom}_G(V, W)$.

A subspace $W \subset V$ is **invariant** if $g \cdot W \subset W$ for all $g \in G$. Letting $\theta(g) = \pi(g)|_W$, we get another representation of G , called a **subrepresentation** of G . We write $\pi|_W$ for θ .

If we have two representation (π, V) and (π', V') , we can form the **direct sum representation** by letting $g \in G$ act on $V \oplus V'$ componentwise. Note that π is a subrepresentation of $V \oplus V'$.

Proposition 1.6 (Mascke's theorem). *Let (π, V) be a representation of G and $W \subset V$ an invariant subspace. Then there exists a complementary invariant subspace W^\perp . That is, W is also invariant and such that $V = W \oplus W^\perp$.*

Proof. We prove this by “averaging”. Let $P : V \rightarrow W$ be any projection from V to W . Then define

$$\Pi(v) = \frac{1}{|G|} \sum_{g \in G} gP(g^{-1}v).$$

This is a G -linear morphism, because

$$\begin{aligned} \Pi(h \cdot v) &= \frac{1}{|G|} \sum_{g \in G} gP(g^{-1}h \cdot v) \\ &= \frac{1}{|G|} \sum_{g \in G} gP((h^{-1}g) \cdot v) \\ &= \frac{h}{|G|} \sum_{g \in G} h^{-1}gP((h^{-1}g) \cdot v). \end{aligned}$$

It is also surjective, since if $v \in W$, then clearly $\Pi(v) = v$. Hence Π is a G -linear surjection onto W . Then it is clear that $\ker \Pi$ is a G -invariant subspace of V complementary to W . □

We say that a representation is **irreducible** if it has no proper invariant subspaces. A representation is **completely reducible** if it decomposes into a direct sum of irreducible representations.

Example 1.7. Let $G = (\mathbb{R}, +)$ act on \mathbb{R}^2 by the matrices

$$\begin{pmatrix} 1 & a \\ 0 & 1 \end{pmatrix}.$$

This leaves the x -axis fixed, so the representation is not irreducible. But it does not split into irreducible representations, since there is no complementary subspaces. ★

However, if G is finite (or **compact**, as we shall see later), things are nicer:

Theorem 1.8. *Any finitely-dimensional representation of a finite group G is completely reducible.*

The proof follows directly from Maschke's theorem (1.6).

We next prove Schur's lemma, which although has a very simple proof, has great consequences.

Proposition 1.9 (Schur's lemma). *Let (V, π) and (W, θ) be irreducible representations. Then*

1. *If $\pi \not\sim \theta$, then $\text{Hom}_G(V, W) = 0$.*
2. *If $\pi \sim \theta$, then $\text{Hom}_G(V, W)$ is 1-dimensional.*

Proof. Both the kernel and the image of a morphism of representations is a representation. But since V, W are irreducible, it follows that $\ker \varphi = 0$ or $\ker \varphi = V$ for any $\varphi : V \rightarrow W$. This proves i).

Now suppose $\Pi : V \rightarrow W$ is an equivalence of representations. Let $\varphi \in \text{Hom}_G(V, W)$. Then φ must be an equivalence as well, since the neither the kernel nor image can be non-zero. Consider $T = \varphi^{-1} \circ \Pi : V \rightarrow V$. This is a linear map, and since we work over \mathbb{C} , it has an eigenvalue λ . Now consider $T - \lambda \text{id}_V$. This has non-zero invariant kernel, hence $T - \lambda \text{id}_V = 0$. □

Proposition 1.10. *If G is abelian, then any irreducible representation of G is 1-dimensional.*

Proof. Each $g \in G$ gives a map $\pi(g) : V \rightarrow V \in \text{End}(V)$. This is even an intertwining map, because $\pi(g)\pi(h) = \pi(gh) = \pi(hg) = \pi(h)\pi(g)$.

If π is not trivial, by Schur's lemma, this map is just multiplication by some constant. But any 1-dimensional subspace of V is invariant under this action, so V must be 1-dimensional in order to be irreducible. □

Thus, up to equivalence, every irreducible representation of a finite abelian group is just a homomorphism $\chi : G \rightarrow \mathbb{C}$. But since G is finite, this actually maps into $\mathbb{T} := \{z \in \mathbb{C} \mid |z| = 1\}$. Such maps are called **characters** of G . Denote by \hat{G} the set of irreducible representations of G .

We call the \hat{G} the **Pontryagin dual** of G . It is an abelian group under pointwise multiplication. See Exercise 2 for more on this.

Remark. *If G is non-abelian, there will always exist irreducible representations of dimension ≥ 2 . This follows because the regular representation $G \rightarrow \mathrm{GL}(\mathbb{C}[G])$ is injective.*

2 Lecture 2 - Density theorems

2.1 Density theorems

Let (V, π) be an irreducible representation. The set of operators $\pi(g)$ for $g \in G$ is quite large. By definition, if $x \neq 0$, then

$$V = \text{Span}\{\pi(g)x \mid g \in G\}.$$

By Schur's lemma, we also know that

$$\text{End}(\pi) = \{T \in \text{End}(V) \mid T\pi(g) = \pi(g)T \forall g \in G\} = \mathbb{C} \cdot \text{id}_V.$$

Theorem 2.1 (The density theorem). *Assume π_1, \dots, π_n are pairwise inequivalent irreducible representations, with $V_i = V_{\pi_i}$. Consider the direct sum representation $V_1 \oplus \dots \oplus V_n$.*

Then

$$\text{Span}\{\pi(G)\} = \text{End}(V_1) \oplus \dots \oplus \text{End}(V_n).$$

Proof/exercise: We deduce the first theorem from the second: First break (V, π) into irreducible representations V_i . Then it follows directly from Schur's lemma that $\pi(G)' = \mathbb{C}\text{id}_{V_1} \oplus \dots \oplus \mathbb{C}\text{id}_{V_n}$.

Now, the elements of $\mathbb{C}\text{id}_{V_1} \oplus \dots \oplus \mathbb{C}\text{id}_{V_n}$ are block diagonal matrices. It is an easy exercise with matrices to see that the commutator of this set is just

$$\text{End}(V_1) \oplus \dots \oplus \text{End}(V_n).$$

□

First we need some notation. Let V be some vector space and $X \subset \text{End}(V)$ a subset of the endomorphisms of V . Let

$$X' \triangleq \{T \in \text{End}(V) \mid TS = ST \text{ for all } S \in X\}.$$

We call X' the **commutant** of X . Thus if (V, π) is a representation, then by definition:

$$\text{End}(\pi) = \pi(G)'.$$

Theorem 2.2. *For any finite-dimensional representation (V, π) we have*

$$\pi(G)'' = \text{Span}\{\pi(G)\}.$$

Proof. Let $T \in \pi(G)''$. Let x_1, \dots, x_n be a basis of V . Consider the representation $\theta = \pi \oplus \dots \oplus \pi$ (n times) on $W = \oplus_{i=1}^n V$. Consider $x = (x_1, \dots, x_n) \in W$ and the operator $S = T \oplus \dots \oplus T$ on W .

It is an exercise to show that $S \in \pi(G)''$.

Now $\text{Span}\{\theta(G)x\}$ is an invariant subspace of W . Then there exists an invariant complementary subspace. Let $P : W \rightarrow \text{Span}\{\theta(G)x\}$ be the projection with kernel that invariant subspace, so that $P \in \Theta(G)'$ (that is, P is a G -morphism). Then

$$PSx = SPx = Sx$$

since $Px \in \text{Span}\{\theta(G)x\}$. Hence $Sx \in \text{Span}\{\theta(G)x\}$ as well. This means that there exist $\alpha_g \in \mathbb{C}$ such that

$$Sx = \sum_g \alpha_g \theta(g)x$$

This is the same as saying that

$$Tx_i = \sum_g \alpha_g \pi(g)x_i,$$

hence $T = \sum \alpha \pi(g)$. □

2.2 Orthogonality relations

Let (V, π) be a representation and let $\rho \in V^* = \text{Hom}(V, \mathbb{C})$. The functions $\alpha_{\rho, x}^\pi$ on G defined by $\alpha_{\rho, x}^\pi(g) = \rho(\pi(g)x)$ is called a **matrix coefficient** of π . If we fix a basis e_1, \dots, e_n of V and consider the dual basis e_1^*, \dots, e_n^* of V^* , then we write α_{ij}^π instead of $\alpha_{e_i^*, e_j}^\pi$.

In the basis e_1, \dots, e_n we have

$$\pi(g) = (\alpha_{ij}^\pi(g))_{ij}$$

Theorem 2.3. *We have:*

1. *If π and θ are inequivalent irreducible representations, then*

$$\frac{1}{|G|} \sum_g \alpha_{f, x}^\pi(g) \alpha_{\rho, y}^\theta(g^{-1}) = 0$$

for all $f \in V_\pi^$, $\rho \in V_\theta^*$, $x \in V_\pi$ and $y \in V_\theta$.*

2. *If π is irreducible, then*

$$\frac{1}{|G|} \sum_g \alpha_{f, x}^\pi(g) \alpha_{\rho, y}^\pi(g^{-1}) = \frac{f(x)\rho(y)}{\dim \pi}.$$

Proof. It is the averaging trick again. First observe that if $T : V_\theta \rightarrow V_\pi$ is any linear operator, then

$$S = \frac{1}{|G|} \sum_{g \in G} \pi(g) T \theta(g^{-1})$$

is in $\text{Hom}_G(\theta, \pi)$ by averaging. Thus, since π and θ are in-equivalent, it follows from Schur's lemma that this must be zero.

Now let $T(v) = \rho(v)x$. This is a linear operator. Then

$$0 = f(Sy) = \frac{1}{|G|} \sum_g \alpha_{f,x}^\pi(g) \alpha_{\rho,y}^\theta(g^{-1}).$$

This proves part 1.

Now suppose $\pi = \theta$. Then $S \in \text{End}(\pi) = \mathbb{C} \cdot \text{id}_V$. Thus $S = \alpha \cdot \text{id}_V$. Taking traces on both sides, we get $\alpha = \text{Tr} T / \dim \pi$ (note that T and S have the same trace).

Then

$$\frac{1}{|G|} \sum_g \alpha_{f,x}^\pi(g) \alpha_{\rho,y}^\pi(g^{-1}) = f(S(y)) = f(y) \frac{\text{Tr} T}{\dim \pi}$$

(make this nicer some time) □

Instead of writing expressions like $\sum_g \alpha_g \pi(g)$ it is convenient to introduce the following notation. Define the **convolution** of two functions $f_1, f_2 \in \mathbb{C}[G]$ by

$$(f_1 * f_2)(g) = \sum_{g=g_1 g_2} f_1(g_1) f_2(g_2) = \sum_{h \in G} f_1(h) f_2(h^{-1}g).$$

We have $\delta_{g_1} * \delta_{g_2} = \delta_{g_1 g_2}$ (easy check!). The convolution product is associative and makes $\mathbb{C}[G]$ into an algebra, called the **group algebra** of G .

Given a representation $\pi : G \rightarrow \text{GL}(V)$ we can define an algebra homomorphism $\mathbb{C}[G] \rightarrow \text{End}(V)$ by $\pi(f) = \sum_{g \in G} f(g) \pi(g)$. Thus V becomes a left $\mathbb{C}[G]$ -module. Conversely, given any unital algebra homomorphism $\pi : \mathbb{C}[G] \rightarrow \text{End}(V)$, we get a representation by $g \mapsto \pi(\delta_g)$. Thus we have a correspondence between representations of G and left $\mathbb{C}[G]$ -modules. Using these notions, the Density Theorem (Theorem 2.1) becomes $\pi(\mathbb{C}[G]) = \bigoplus_i \text{End}(V_i)$.

Theorem 2.4. *Let \hat{G} be the set of equivalence classes of irreducible representations of G . Then \hat{G} is finite and $\sum_{[\pi] \in \hat{G}} (\dim \pi)^2 = |G|$. Furthermore, we have*

$$\lambda \sim \bigoplus_{[\pi] \in \hat{G}} \pi^{\oplus \dim \pi}.$$

Here λ is the left regular representation of G .

Proof to come later.

3 Lecture 3 - More on orthogonality

Where does the name “orthogonality relations” come from? We’ll see now.

First of all, note that if V_π is a representation of a finite group G , and \langle, \rangle' is *any* Hermitian scalar product on V_π , then

$$\langle v, w \rangle := \frac{1}{|G|} \sum_{g \in G} \langle \pi(g)v, \pi(g)w \rangle'$$

is another Hermitian scalar product on V_π , making the representation **unitary**.

If π is any unitary representation, choose an orthonormal basis $e_1, \dots, e_n \in V$. Then the matrices $\pi(g) = (a_{ij}^\pi(g))$ are unitary matrices. Hence $\overline{a_{ij}^\pi} = a_{ji}^\pi(g^{-1})$.

There is a standard scalar product on $\mathbb{C}[G]$ defined by

$$(f_1, f_2) = \frac{1}{|G|} \sum_{g \in G} f_1(g) \overline{f_2(g)}.$$

Then the orthogonality relations take the form:

Theorem 3.1. *For every irreducible representation π choose an invariant scalar product and an orthonormal basis $\{e_1^\pi, \dots, e_n^{\dim \pi}\}$ and corresponding matrix coefficients a_{ij}^π . Then the functions a_{ij}^π are mutually orthogonal with*

$$(a_{ij}^\pi, a_{ij}^\pi) = \frac{1}{\dim \pi}.$$

3.1 Characters of a representation

Let (π, V) be a representation.

The function $\chi_\pi : G \rightarrow \mathbb{C}$ defined by $\text{Tr } \pi(g)$ is called the **character** of π .

We say that a function $f : G \rightarrow \mathbb{C}$ is **central** if $f(hgh^{-1}) = f(g)$ for all $h, g \in G$. Note that characters are central. Also note that $\chi_\pi(e) = \dim \pi$.

Theorem 3.2. *The characters χ_π (for $[\pi] \in \widehat{G}$) form an orthonormal basis for the space of central functions on G .*

Proof. We have

$$\chi_\pi(g) = \sum_{i=1}^{\dim \pi} a_{ii}^\pi(g),$$

and the orthogonality relations show that $\{\chi_\pi \mid [\pi] \in \widehat{G}\}$ is an orthonormal system:

$$(\chi_\pi, \chi_\pi) = \sum_{ij}^{\dim \pi} (a_{ii}^\pi, a_{jj}^\pi) = \sum_{i=1}^{\dim \pi} \frac{1}{\dim \pi} = 1.$$

Thus we need to show that the characters *span* the space of central functions. Consider the projection P from $\mathbb{C}[G]$ to the space of central functions defined by

$$f \mapsto (Pf)(g) = \frac{1}{|G|} \sum_{h \in G} f(hgh^{-1}).$$

It is obviously a projection. Now consider $P(a_{ij})(g)$ (we skip the upper index π). Then this is equal to

$$\frac{1}{|G|} \sum_h a_{ij}(hgh^{-1}) = \frac{1}{|G|} \sum_{h \in G} \sum_k \sum_l a_{ik}(h) a_{kl}(g) a_{lj}(h^{-1}).$$

But after using that the orthogonality relations, this simplifies to

$$\frac{1}{\dim \pi} \delta_{ij} \chi_\pi(g).$$

But the a_{ij} constitute a basis of $\mathbb{C}[G]$. [[HM!? TRUE??]] □

[[some comment about why the last claim is true...]]

Corollary 3.3. *Let $c(G)$ be the number of conjugacy classes in G . We have*

$$|\widehat{G}| = c(G).$$

Proof. The left hand side is equal to $\dim_{\mathbb{C}} \text{span}_{\pi \in \widehat{G}} \{\chi_\pi\}$. But this is, as just proved, equal to the dimension of the space of central functions. □

Corollary 3.4. *Two finite-dimensional representations π and θ are equivalent if and only if $\chi_\pi = \chi_\theta$.*

Proof. You can read off the multiplicities from the character. □

Corollary 3.5. *For any $[\pi] \in \widehat{G}$, the multiplicity of π in the regular representation λ equals $\dim \pi$.*

Proof. We are interested in (χ_λ, χ_π) . But note that

$$\chi_\lambda(g) = \sum_{h \in G} \text{Tr}(\delta_h \mapsto \delta_{hg}) = \begin{cases} 0 & \text{if } g \neq e \\ |G| & \text{if } g = e. \end{cases}$$

Then $(\chi_\lambda, \chi_\pi) = \frac{1}{|G|} \chi_\lambda(e) \cdot \overline{\chi_\pi(e)} = \dim \pi$. □

3.2 Isotypic component and can. decomposition of V

[[isotypic component ...]]

4 Lecture 4 - The Frobenius determinant problem

Let G be a finite group and $\mathbb{C}[x_g \mid g \in G]$ the algebra on generators indexed by $g \in G$. Then one can form the following determinant:

$$P_G = \det((x_{gh})_{gh}).$$

It is the determinant of the multiplication table of G . The problem is to decompose P_G into irreducible polynomials.

It is convenient to instead work with $\tilde{P}_G = \det((x_{gh^{-1}})_{gh})$. This has the same determinant as P_G up to multiplication by ± 1 since this just corresponds to permuting some of rows of the multiplication table.

Now here comes the *key* observation: the matrix $(x_{gh^{-1}})$ is the matrix of the operator

$$\sum_{g \in G} x_g \lambda(g)$$

in the basis $\delta_g \in \mathbb{C}[G]$. Here you are supposed to view elements of $\mathbb{C}[x_g \mid g \in G]$ as **functions** on G .

That this operator actually has matrix $(x_{gh^{-1}})$ can be seen by applying the operator to basis elements:

$$\left(\sum_{g \in G} x_g \lambda(g) \right) (\delta_h) = \sum_{g \in G} x_g \delta_{gh}$$

by definition of the left regular action. Reparametrizing this last sum by setting $g' = gh$ we get

$$\sum_{g \in G} x_g \delta_{gh} = \sum_{g' = gh} x_{gh^{-1}} \delta_g,$$

as wanted.

Now, the regular representation decomposes as

$$\lambda \sim \bigoplus_{[\pi] \in \widehat{G}} \pi^{\oplus \dim \pi}$$

Hence the determinant decomposes as well (since the operator is G -invariant) and we get

$$\widehat{P}_G = \prod_{[\pi] \in \widehat{G}} \det \left(\sum_{g \in G} x_g \pi(g) \right)^{\dim \pi}$$

The question is now of course if we can decompose further. The answer is no:

Theorem 4.1 (Frobenius). *The polynomials $\det\left(\sum_{g \in G} x_g \pi(g)\right)$ ($[\pi] \in \widehat{G}$) are irreducible and no two of them are associates.*

We begin with a lemma:

Lemma 4.2. *The polynomial $p = \det(x_{ij})$ is irreducible.*

Proof. To come. □

Proof of theorem. Suppose that $P_\pi = p_1 p_2$. The polynomials p_1, p_2 are homogeneous. Fix a basis e_1, \dots, e_n in V_π . Consider the corresponding matrix units m_{ij} defined by

$$m_{ij} e_k = \delta_{jk} e_i.$$

Since $\pi(\mathbb{C}[G]) = \text{End}(V_\pi)$ by the density theorem, we can find $a_{ij}(g) \in \mathbb{C}$ such that

$$m_{ij} = \sum_{g \in G} \alpha_{ij}(g) \pi(g).$$

Consider the ring map $\mathbb{C}[x_g \mid g \in G] \rightarrow \mathbb{C}[x_{ij}]$ defined by

$$x_g \mapsto \sum_{ij} \alpha_{ij}(g) x_{ij}.$$

Under this map the operator \widehat{P}_G becomes

$$\sum_{g \in G} x_g \pi(g) = \sum_{g \in G} \sum_{i,j} \alpha_{ij}(g) x_{ij} \pi(g) = \sum_{ij} m_{ij} x_{ij} = (x_{ij}).$$

Since the determinant is functorial with respect to ring maps, a decomposition $P_G = p_1 p_2$ would induce a decomposition of $\det(x_{ij})$, which was just proved to be impossible.

We still have to check that no two of the determinants are equal (up to associates). But note that $P_\pi|_{x_g=0, g \neq e} = x_e^{\dim \pi}$. So we can recover the dimension of π from the determinant. Also note that if we fix $g \in G$, then

$$P_\pi|_{x_e=1, x_h=0 \text{ for } h \neq g} = \det(1 + x_g \pi(g)) = 1 + \text{Tr } \pi(g) x_g + h.o.t.$$

, so we can recover the trace as well. But a representation is determined by its character, so if the polynomials are equal, then the representations are equivalent. The converse is similar. □

4.1 Two constructions on representations

Recall that the tensor product of V and W have a basis $v_i \otimes v_j$. Hence $\dim_{\mathbb{C}} V \otimes W = \dim_{\mathbb{C}} V \cdot \dim_{\mathbb{C}} W$.

Assume (V, π) is a finite-dimensional representation and consider $V^* = \text{Hom}_{\mathbb{C}}(V, \mathbb{C})$. Then we define the **contragredient representation** π^c to be the representation of the dual space defined by

$$(\pi(g)f)(v) = f(\pi(g^{-1})v).$$

If v_1, \dots, v_n is a basis for V and $\pi(g) = (a_{ij}(g))$, then in this basis

$$\pi^c(g) = (a_{ji}(g^{-1}))_{ij}.$$

In particular, the character $\chi_{\pi^c}(g) = \chi_{\pi}(g^{-1}) = \overline{\chi_{\pi}(g)}$.

Also, we can define the **tensor product of two representations** π and θ by $(\pi \otimes \theta)(g)(v \otimes w) = \pi(g)v \otimes \theta(g)w$.

See the exercises for some properties.

Also: $\text{Hom}(U, W \otimes V^*) = \text{Hom}(U \otimes V, W)$.

Frobenius reciprocity:

$$\text{Mor}(\pi, \eta \otimes \theta^c) \simeq \text{Mor}(\pi \otimes \theta, \eta).$$

Denote by $R(G)$ the abelian group generated by classes $[\pi] \in \widehat{G}$ of finite-dimensional representations and relations $[\pi] + [\pi'] = [\pi \oplus \pi']$. Then it is an exercise to show that $R(G)$ is a free abelian group with basis $[\pi] \in \widehat{G}$.

Via the tensor product we can form a product on $R(G)$, making it into a ring.

5 Lecture 5 - Dimension of irreps and the symmetric group

Recall that

$$\sum_{[\pi] \in \widehat{G}} (\dim \pi)^2 = |G|.$$

In this lecture we will prove the following theorem:

Theorem 5.1. *The dimension of any irreducible representation divides the number $|G/Z(G)|$, where $Z(G)$ is the center of G .*

Later we will strengthen this and show that $Z(G)$ can be replaced by any normal abelian subgroup of G .

In order to prove this, we need to introduce some results from commutative algebra. Let R be a unital commutative ring and $S \subset R$ a united subring. Then we say that an element $a \in R$ is **integral over**

S if it satisfies a monic polynomial $a^n + s_1 a^{n-1} + \dots + s_{n-1} = 0$ with coefficients in S .

We say that a complex number integral over \mathbb{Z} is an **algebraic integer**. An integral domain S is called **integrally closed** if any element in the fraction field of S integral over S is already in S . It is an easy exercise to see that \mathbb{Z} is integrally closed (and in fact any UFD).

Lemma 5.2. *Let $S \subset R$ be as above. Then $a \in R$ is integral over S if and only if the subring $S[a]$ is a finitely-generated S -module.*

Proof. This is Proposition 5.1 in Atiyah-MacDonald. \square

It is an exercise to see that the set of elements of R integral over S actually form a ring. Alternatively, consult Corollary 5.3 in Atiyah-MacDonald.

Proposition 5.3. *Assume that π is an irreducible representation. Let $g \in G$. Let $C(g)$ be the conjugacy class of G . Then*

1. *The number $\chi_\pi(g)$ is an algebraic integer.*
2. *The number $\frac{|C(g)|}{\dim \pi} \chi_\pi(g)$ is also an algebraic integer.*

Proof. i). Since G is finite, we have $g^n = e$ for some n . Hence all eigenvalues of g are n th roots of unity which are algebraic integers. But $\chi_\pi(g)$ is the sum of the eigenvalues, and the set of algebraic integers form a subring of \mathbb{C} , hence $\chi_\pi(g)$ is an algebraic integer as well.

The second part is more difficult. Let p be the characteristic function of $C(g)$. Then p lies in the center of $\mathbb{C}[G]$. Consider the subring $\mathbb{Z}[G] \subset \mathbb{C}[G]$ (the **group ring** of G). Let $R \subset \mathbb{Z}[G]$ be the subring of *central functions*. As R is a finitely generated abelian group, any element of R is integral over $\mathbb{Z} \cdot 1 \subset R$.

It follows that $\pi(p)$ is integral over $\mathbb{Z} \cdot \text{id}_{V_\pi} \subset \text{End}(V_\pi)$. Since p is central $\pi(p) \in \text{End}_G(V_\pi) = \mathbb{C} \cdot 1$. Hence $\pi(p) = \alpha \cdot 1$ for some complex number α . This α is an algebraic integer.

But now

$$\begin{aligned} \alpha \cdot \dim \pi &= \text{Tr}(\alpha \cdot 1) \\ &= \text{Tr} \pi(p) \\ &= \sum_{h \in C(g)} \text{Tr} \pi(h) \\ &= \sum_{h \in C(g)} \chi_\pi(h) \\ &= |C(g)| \chi_\pi(g). \end{aligned}$$

The last equality is because characters are constant on conjugacy classes. This proves the claim. \square

Lemma 5.4. *If π is irreducible, then $\dim \pi \mid |G|$.*

Proof. Recall that

$$(\chi_\pi, \chi_\pi) = 1.$$

This can be rewritten as

$$\frac{|G|}{\dim \pi} = \sum_{g \in G} \frac{\chi_\pi(g) \chi_\pi(g^{-1})}{\dim \pi}.$$

Now let $C(G)$ denote the set of conjugacy classes in G . C is then a partition of G . Then the above sum can be rewritten as

$$\sum_{C \in C(G)} \sum_{h \in C} \frac{\chi_\pi(h) \chi_\pi(h^{-1})}{\dim \pi} = \sum_{C \in C(G)} \frac{|C| \chi_\pi(g)}{\dim \pi} \chi_\pi(g^{-1}).$$

The right-hand-side is a sum of product that we know are algebraic integers. They form a ring, hence the sum is an algebraic integer as well.

But the left hand side is a fraction, so we must have $|G|/\dim \pi \in \mathbb{Z}$, which is equivalent to what was to be proven. \square

Now we can prove Theorem 5.1. Recall that we want to show that $\dim \pi$ divides $|G/Z(G)|$.

Proof. For every $n \in \mathbb{N}$, consider the representation of $G^n = G \times \cdots \times G$ on $V_\pi \otimes \cdots \otimes V_\pi$ defined by $\pi_n(g_1, \dots, g_n) = \pi_1(g_1) \otimes \cdots \otimes \pi_n(g_n)$. It is an **exercise** to see that this representation is irreducible as well.

Now consider the subgroup $Z_n = \{(g_1, \dots, g_n) \in Z(G)^n \mid \prod g_i = e\}$. It is isomorphic to $Z(G)^{n-1}$.

If $g \in Z(G)$, then by Schur's lemma, $\pi(g)$ is a scalar operator. So if $(g_1, \dots, g_n) \in Z_n$, then $\pi(g_i) = \alpha_i \cdot 1$, hence

$$\pi_n(g_1, \dots, g_n) = \alpha_1, \dots, \alpha_n \text{id}_{V^{\otimes n}} = \text{id}_{V^{\otimes n}}$$

since $g_1 \cdots g_n = e$. Therefore $Z_n \subset \ker \pi_n$. It follows that π_n induces a representation of G^n/Z_n . Then by the previous lemma

$$(\dim \pi)^n \mid \frac{|G|^n}{|Z(G)|^{n-1}}$$

That is:

$$\left(\frac{|G|}{\dim \pi |Z(G)|} \right)^n \in \mathbb{Z} \left[\frac{1}{|Z(G)|} \right]$$

for any n . But this implies that the left-hand-side is a finitely-generated \mathbb{Z} -module, hence what is inside the brackets is an algebraic integer. But is also a fraction, so it must be an integer. \square

6 Lecture 6 - Representation theory of S_n

It is easy to understand conjugacy classes in S_n . Every $\sigma \in S_n$ defines a partition of $\{1, \dots, n\}$ into orbits of σ . Let O_1, \dots, O_m be these orbits. Assume that they are decreasing in size. Let $n_i = |O_i|$. These numbers n_i sum to n .

We say that a **partition of n** is a decreasing sequence of integers $n_1 \geq n_2 \geq \dots \geq n_m \geq 1$ such that $n = \sum n_i$.

Thus every $\sigma \in S_n$ gives a partition of n . Two elements of S_n are conjugate if and only if they define the same partition. This is straightforward to see. First suppose that σ and τ are conjugate, that is, that $\sigma = g^{-1}\tau g$ for some $g \in S_n$. The orbit of 1 under σ is defined by $O(\sigma, 1) = \{\sigma^n(1) \mid n \geq 0\}$. But this is $g^{-1}O(\tau, g(1))$. This defines a bijection the orbit of 1 under σ and the orbit of 1 under τ . Hence their sizes are equal. Conversely, assume that the orbits of τ and σ have the same sizes. Let g be an arbitrary bijection $[n] \rightarrow [n]$ between sending orbits to orbits. [[HOW TO PROCEED????]]

Our goal is to produce an irreducible representation for every partition of n .

Recall that for any finite group G , we have

$$\mathbb{C}[G] \simeq \bigoplus_{[\pi] \in \hat{G}} \text{End}(V_\pi),$$

the isomorphism sending g to the corresponding endomorphism of $V = \bigoplus V_\pi$. Now one can ask if it is possible to recover the space V_π from its matrix algebra? (essentially, yes)

We need a few definitions. An idempotent e in an algebra A is called **minimal** if $e \neq 0$ and $eAe = \mathbb{C}e$.

Here's an exercise (to be proven in the appendix!):

Exercise 1. Let V be a finite-dimensional vector space. Show that $e \in \text{End}(V)$ is a minimal idempotent if and only if it is a projecting onto a 1-dimensional subspace $\mathbb{C}v \subset V$. Then we have an isomorphism

$$\text{End}(V)e \simeq V$$

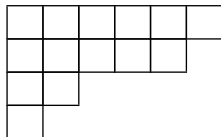
of $\text{End}(V)$ -modules given by $Te \mapsto Tv$. ♠

Therefore finding irreducible representations of G is the same as finding minimal idempotents in the group algebra $\mathbb{C}[G]$: if $e \in \mathbb{C}[G]$ is a minimal idempotent, then $\mathbb{C}[G]e$ defines an irreducible representation ([[WHY IS IT IRREDUCIBLE??]]).

Thus, returning to S_n , we want to construct minimal idempotents in $\mathbb{C}[S_n]$ for every partition.

It is convenient to present partitions as **Young diagrams**. Given a partition (n_1, \dots, n_m) of n , we draw a diagram having n_1 boxes in

the first row, n_2 boxes in the second, and so on. For example, for the partition $(6, 5, 2, 1)$ of 14, we draw the following diagram:



We can also fill these with numbers: a **Young tableau** (plural *tableaux*) is a Young diagram filled with numbers $i \in [n]$ without repetitions. For example:

3	1
2	

Two Young tableaux are said to be of the same **shape** if they arise from the same underlying Young diagram.

Note that the symmetric group acts on the set of Young tableaux of the same shape λ .

Fix a Young tableaux T . Let $R(T) \subset S_n$ be the subgroup of elements of S_n permuting numbers in the *rows* of T . Let $C(T)$ be the same group, but permuting columns instead. Define the following two elements of $\mathbb{C}[S_n]$:

$$a_T = \frac{1}{|R(T)|} \sum_{g \in R(T)} g$$

and

$$b_T = \frac{1}{|C(T)|} \sum_{g \in C(T)} \text{sgn}(g) \cdot g.$$

Then we define $c_T = a_T b_T$. The element c_T is called a **Young symmetrizer**. Our main theorem is this:

Theorem 6.1. *1. For any T , the element c_T is (up to a scalar) a minimal idempotent in $\mathbb{C}[S_n]$, so it defines an irreducible representation of S_n .*
2. If T_1, T_2 are two Young tableaux, then the representations corresponding to them are equivalent if and only if T_1 and T_2 have the same shape.

The modules $\mathbb{C}[S_n]c_T$ are called **Specht modules**.

Proof. TOO LONG FOR NOW. WILL PROB. COME LATER □

6.1 Tabloids

A bit more explicitly the Specht modules can be described as follows.

Fix a Young diagram λ . Introduce an equivalence relation on Young tableaux of shape λ :

$$T_1 \sim T_2$$

if $T_1 = r(T_2)$ for some $r \in R(T_2)$. The equivalence class of a Young tableau T is called a **tabloid** (of shape λ) and denoted by $\{T\}$.

Note that S_n act on the set of tabloids. Let (M_λ, S_n) be the corresponding permutation representation. Note also that action on the set of tabloids is transitive. Thus the basis of M_λ can be identified with $S_n/R(T)$ ¹.

Thus we get isomorphisms of $\mathbb{C}[S_n]$ -modules:

$$\mathbb{C}[S_n]a_T \simeq \mathbb{C}[S_n/R(T)] \simeq M_\lambda.$$

The first isomorphism is given by sending ga_T to $\partial_{gR(T)}$ (the delta function), and the second is given by sending a coset $\partial_{gR(T)}$ to $\{g(T)\}$.

Under these isomorphisms, the image of the submodule $\mathbb{C}[S_n]b_Ta_T \subset \mathbb{C}[S_n]a_T$ is spanned by the elements $b_{g(T)}\{g(T)\}$. In other words, V_λ is spanned by $e_{T'} := b_{T'}\{T'\}$ by all elements of shape λ . This gives us a description of $V_\lambda \simeq V_T$ only in terms of λ .

This is a spanning set. We would like a basis. We say that that tableau T is **standard** if the numbers in every row and column are increasing.

Here's a theorem that we wont prove:

Theorem 6.2. *For any Young diagram λ the elements e_T for all standard tableaux T of shape λ form a basis in V_λ .*

The complication is of course that $ge_T = c_{g(T)}$ is a combination of standard tableaux!

[[two examples]]

6.2 Characters and the Hook length formula

Here we prove two theorems.

Let $I = (i_1, i_2, \dots)$ consist of non-negative integers such that

$$\sum_{k=1}^{\infty} ki_k = n.$$

Denote by c_I the conjugacy class in S_n consisting of elements σ which decompose into i_1 orbits of length 1, i_2 orbits of length two and so on.

This corresponds to an obvious partition of n .

Let $\chi_{\pi_\lambda}(C_I)$ denote the value of the character of π_λ on any representing of the conjugacy class of C_I . Then

¹Every $\{T\}$ can be written as $\sigma\{T_0\}$ for some fixed T_0 . But the ambiguity lies in $R(T)$.

Theorem 6.3 (Frobenius character formula). Assume $\lambda = (\lambda_1, \dots, \lambda_r)$. Take any number $N \geq r$. Then $\chi_{\pi_\lambda}(C_I)$ is the coefficient of $\prod_{i=1}^N x_i^{\lambda_i + N - i}$ in the polynomial

$$\Delta(x) \prod_{i \geq 1} \sum_{k=1}^N (x_i^k)^{i_k}.$$

where $\Delta(x) = \prod (x_i - x_j)$ is the Vandermonde determinant.

This was not proved, but the idea of the proof was given.

Now we quote the **hook length** formula. Let λ be Young diagram and let (i, j) be the element in position row i and column j . Then the **hook length** $h(i, j)$ is the number of boxes below and to the right of (i, j) including (i, j) itself. Then:

Theorem 6.4. Let λ be partition and let π_λ be the corresponding irreducible representation of S_n . Then

$$\dim \pi_\lambda = \frac{n!}{\prod_{(i,j) \in \lambda} h(i,j)}.$$

Proof later.

7 Induced representations

Let G be a finite group and $H \subset G$ a subgroup. Assume (π, V) is a representation of H . We want to construct a representation of G out of this.

We define the **induced representation** $\text{Ind}_H^G \pi$ to be the $\mathbb{C}[G]$ -module defined by

$$\mathbb{C}[G] \otimes_{\mathbb{C}[H]} V.$$

It is very useful in constructing representations of larger groups from smaller ones. The idea is that if we know the representations of some subgroup H of a group G , then in nice situations all representations of G can be found as subrepresentations of $\text{Ind}_H^G \pi$ for various $[\pi] \in \hat{H}$.

Remark. *This is exactly the concept of extension of scalars from commutative algebra (see e.g. Atiyah-MacDonald page 28). Namely let $A = \mathbb{C}[H]$ and $B = \mathbb{C}[G]$ and let $M = V$ be an A -module. Then we can form the A -module $M_B = B \otimes_A M$, which carries a natural B -module structure as well: the action of B on M_B is given by $b(b' \otimes x) = bb' \otimes x$.*

We have three equivalent descriptions of the induced representation, some of the descriptions being easier to work with than others.

Theorem 7.1. *Let V be a representation of H . The following representations are isomorphic.*

1. $\mathbb{C}[G] \otimes_{\mathbb{C}[H]} V$ where G acts by $g \cdot (g' \otimes v) = gg' \otimes v$.
2. $\text{Hom}_H(\mathbb{C}[G], V) \simeq \{f : G \rightarrow V \mid f(hg) = hf(g) \forall h \in H, g \in G\}$, where g acts by $(g' \cdot f)(g) = f(gg')$.
3. $W = \bigoplus_{\sigma \in G/H} V_\sigma$, where each V_σ is a copy of V . Let $x_\sigma \in V_\sigma$. Then the action of G is defined as follows: Let $r_\sigma \in \sigma$ be a representative for the coset σ . Then g can be written as $g = r_\sigma h$ for some $h \in H$. Then we define $g \cdot x_\sigma = h \cdot x_{g\sigma}$.

Proof. Start with 1). We want to show that this is the same as number 3). We will do this in a non-canonical way. The algebra $\mathbb{C}[H]$ has a vector space basis $\{e_{h_1}, \dots, e_{h_r}\}$ where $r = |H|$. By properties of cosets, this implies that $\mathbb{C}[G]$ has a basis

$$\{e_{h_1}, \dots, e_{h_r}, e_{r_1 h_1}, \dots, e_{r_1 h_r}, \dots, e_{r_k h_1}, \dots, e_{r_k h_r}\}$$

where $k = [G : H]$ and the r_i 's are a set of fixed representatives for the cosets G/H . This means that we can write

$$\mathbb{C}[G] = \bigoplus_{i=1}^k r_i \mathbb{C}[H].$$

This implies that $\mathbb{C}[G] \otimes_{\mathbb{C}[H]} V$ decomposes as

$$\mathbb{C}[G] \otimes_{\mathbb{C}[H]} V = \left(\bigoplus_{i=1}^k r_i \mathbb{C}[H] \right) \otimes_{\mathbb{C}[H]} V \simeq \bigoplus_{i=1}^k (r_i \mathbb{C}[H] \otimes_{\mathbb{C}[H]} V)$$

This is exactly the description in 3), because each $r_i \mathbb{C}[H] \otimes_{\mathbb{C}[H]} V$ is isomorphic to V via the map $r_i h \otimes v \mapsto h^{-1} v$ (we need the inverse in order for this to be a map of representations). The representation V is endowed with a left action of H (this is what a representation *is*), but it also has a right action, defined by $v \cdot g := g^{-1} v$. In this way, V becomes a left-right- H -module.

One can check that the action in 3) and the natural G -action on $r_i \mathbb{C}[H] \otimes_{\mathbb{C}[H]} V$ are the same.

The equivalence of 1) and 2) can be seen by standard isomorphisms from module theory. Namely, note that

$$\mathrm{Hom}_H(\mathbb{C}[G], V) \simeq \mathrm{Hom}_H(\mathbb{C}[G], \mathbb{C}) \otimes_{\mathbb{C}[H]} V.$$

We also have an identification of representations $\mathbb{C}[G]$ with $\mathrm{Hom}(\mathbb{C}[G], \mathbb{C})$ where we let δ_g be a basis of $\mathbb{C}[G]$. Then the action of G on $\mathbb{C}[G]$ by left-multiplication is identified with the contragradient action of G on $\mathrm{Hom}(\mathbb{C}[G], \mathbb{C})$. But all functions $\mathbb{C}[G] \rightarrow \mathbb{C}$ are G -invariant (because $f(gx) = gf(x) = f(x)$ since we are considering the trivial action on \mathbb{C}). Hence $\mathrm{Hom}_H(\mathbb{C}[G], \mathbb{C}) = \mathbb{C}[G]$. So the two descriptions are equal. \square

We say that the collection $\{V_\sigma\} \subset W$ is called a **system of imprimitivity** of the representation V .

Example 7.2. Let λ_H be the regular representation of H . Then λ_H can be identified with $\mathbb{C}[H]$. In this case we have $\mathrm{Ind}_H^G \lambda_H = \lambda_G$ since $\mathbb{C}[G] \otimes_{\mathbb{C}[H]} \mathbb{C}[H] \simeq \mathbb{C}[G]$. \star

Here are some basic properties of induction. Most of them follow from basic properties of tensor products.

1. If $N \subset M \subset G$ are subgroups, then

$$\mathrm{Ind}_H^G \mathrm{Ind}_N^M \pi \sim \mathrm{Ind}_N^G \pi$$

2. If π is finitedimensional, then

$$(\mathrm{Ind}_H^G \pi)^\vee \simeq \mathrm{Ind}_H^G \pi^\vee.$$

Here π^\vee is the contragradient representation of π .

7.1 Frobenius reciprocity

Let $\text{Rep}(G)$ denote the category of finite-dimensional G -representations where G is a finite group and let $H \subset G$ be a subgroup of G . We have two functors in each direction: we have a functor Res_H^G sending a representation to its restriction to H , and we have a functor Ind_H^G in the other direction, sending a representation of H to the induced representation on G . The theorem of this section is that these two functors are adjoints to each other.

But this is a standard fact about tensor products: let $S \subset R$ be rings (commutative or not) and let V be an S -module and W an R - S -bimodule. In our case a representation W of G is both a $\mathbb{C}[G]$ -module and a $\mathbb{C}[H]$ -module by restriction. Then we always have

$$\text{Hom}_R(R \otimes_S V, W) \simeq \text{Hom}_S(V, W)$$

Note that as an S -module we have $W = \text{Res}_H^G W$.

If χ is the character of π (a representation of H), we denote by $\text{Ind}_H^G \chi$ the character of the induced representation.

Note that it follows by Schur's lemma and the orthogonality relations that for any two representations, we have

$$(\chi_{\pi_1}, \chi_{\pi_2}) = \dim_{\mathbb{C}} \text{Mor}(\pi_1, \pi_2).$$

Therefore, in terms of characters, Frobenius reciprocity can be stated as

$$(\text{Ind}_H^G \chi_{\pi}, \chi_{\theta}) = (\chi_{\theta}, \text{Res}_H^G \chi_{\theta}).$$

Thus:

Proposition 7.3. *Let V be an irreducible representation of H and W an irreducible representation of G . Then the number of times that W occurs in $\text{Ind}_H^G V$ is equal to the number of times that $\text{Res}_H^G W$ occurs in V .*

Proof. Recall that if V is an irreducible representation and U is any representation, then (χ_V, χ_U) is equal to the number of times that V occurs in U . Now use the above remarks. \square

7.2 Characters of induced representations

Proposition 7.4. *Assume $G \supset H$ and that (π, V) is a finite-dimensional representation of H and χ its character. Then the character $\text{Ind}_H^G \chi$ of $\text{Ind}_H^G \pi$ is given by*

$$(\text{Ind } \chi)(g) = \sum_{\bar{s} \in G/H, s^{-1}gs \in H} \chi(s^{-1}gs) = \frac{1}{|H|} \sum_{s \in G | s^{-1}gs \in H} \chi(s^{-1}gs),$$

where we extend χ to G by zero.

Proof. Consider the imprimitivity system $\{W_x\}_{x \in G/H}$ for the induced representation $\theta = \text{Ind}_H^G \pi$. Then

$$\begin{aligned}
\chi_\theta(g) &= \text{Tr}(g) &= \sum_{x \in G/H, gx=x} \text{Tr}(\theta(g)|_{W_x}) \\
&= \sum_{\bar{s} \in G/H, s^{-1}gs \in H} \text{Tr}(\theta(g)|_{W_{\bar{s}}}) &= \sum_{\bar{s} \in G/H, s^{-1}gs \in H} \text{Tr}(\theta(s^{-1})\theta(g)\theta(s)|_{W_{\bar{e}}}) \\
&= \sum_{\bar{s} \in G/H, s^{-1}gs \in H} \text{Tr}(\pi(s^{-1}gs)) &= \sum_{\bar{s} \in G/H, s^{-1}gs \in H} \chi(s^{-1}gs).
\end{aligned}$$

The second equality follows by noting that $\chi(s^{-1}gs)$ is constant on left cosets as s varies. \square

This makes it easy to compute characters of induced representations. In practice one often induces from a normal subgroup containing few conjugacy classes, so that many of the terms in the sum are zero.

8 The Frobenius subgroup theorem

In this section we will prove a theorem of group theory, the proof of which relies heavily upon representation theory. To this day, no “elementary” proof is known.

Theorem 8.1. *Assume a finite group G acts transitively on a set X such that every $g \neq e$ has at most one fixed point. Then there exists a unique normal subgroup K of G acting freely transitively on X .*

Proof. Put

$$K \triangleq \{e\} \cup \{g \in G \mid g \text{ has no fixed points}\}.$$

We have to show that K is a normal subgroup and that it acts freely transitively on X . Once this is done, we are finished, since K is clearly the largest possible subset of G satisfying the conclusion of the theorem.

To show that K acts freely transitively on X , it suffices to show that $\#K = \#X$. Let $x \in X$, and consider the stabilizer

$$H = G_x = \{g \in G \mid g \cdot x = x\}.$$

If $g \notin H$, by definition $g \cdot x \neq x$. Also note that

$$H \cap gHg^{-1} = G_x \cap G_{gx} = \{e\},$$

since otherwise h in the intersection would act trivially on both x and gx , but we assumed that every element acted with at most one fixpoint.

Hence we can write G as a disjoint union as follows:

$$G = K \coprod \left(\coprod_{y \in X} G_y \setminus \{e\} \right) = K \coprod \left(\coprod_{[g] \in G/H} gHg^{-1} \setminus \{e\} \right).$$

Therefore

$$\#G = \#K + \frac{\#G}{\#H}(\#H - 1)$$

so that $\#K = \#G/\#H = \#X$.

It remains to show that K is a normal subgroup. We will do this by showing that it is the kernel of some representation of G .

For an irreducible representation π of H , consider the function $\widetilde{\chi}_\pi$ on G defined by

$$\begin{aligned} \widetilde{\chi}_\pi &= \text{Ind}_H^G \chi_\pi - (\dim \pi) \text{Ind}_H^G \chi_{\epsilon_H} + (\dim \pi) \chi_{\epsilon_G} \\ &= \text{Ind}_H^G \chi_\pi - (\dim \pi) \text{Ind}_H^G 1 + (\dim \pi) 1. \end{aligned}$$

Recall that in general, if $f : H \rightarrow \mathbb{C}$ is any class function, we can induce a new class function on G by the formula

$$(\text{Ind}_H^G f)(h) = \sum_{[g] \in G/H, g^{-1}hg \in H} f(s^{-1}gs).$$

Here the sum chooses one representative from each coset. Now one sees easily that

$$\widetilde{\chi}_\pi(g) = \begin{cases} \dim \pi & \text{if } g \in K \\ \chi_\pi(h) & \text{if } g \text{ is conjugate to } h \in H \end{cases}$$

In the first case we get $0 - 0 + \dim \pi$ in the definition, and in the second case we get $\text{Ind}_H^G \chi_\pi(g) - \dim \pi + \dim \pi$. That this completely describes $\widetilde{\chi}_\pi(g)$ is clear because of our description of G as a disjoint union above.

Using this decomposition, we can calculate $(\widetilde{\chi}_\pi, \widetilde{\chi}_\pi)$:

$$(\widetilde{\chi}_\pi, \widetilde{\chi}_\pi) = \frac{1}{|G|} \sum_{g \in G} |\widetilde{\chi}_\pi(g)|^2 = \frac{1}{|G|} \frac{|G|}{|H|} \dim \pi^2 + \frac{1}{|G|} \frac{|G|}{|H|} \sum_{h \in H \setminus \{e\}} |\chi_\pi(h)|^2$$

But this last expression is equal to $(\chi_\pi, \chi_\pi) = 1$.

As $\widetilde{\chi}_\pi$ is a linear combination of characters with integer coefficients, we must have $\widetilde{\chi}_\pi = \pm \chi_{\widetilde{\pi}}$ for some irreducible representation $\widetilde{\pi}$.² But $\widetilde{\chi}_\pi(e) = \dim \pi > 0$, so that actually $\widetilde{\chi}_\pi = \chi_{\widetilde{\pi}}$.

Note that as $\chi_{\widetilde{\pi}}|_H = \chi_\pi$, we have $\text{Res}_H^G \widetilde{\pi} \sim \pi$.

Now we claim that

$$K = \bigcap_{[\pi] \in \hat{H}} \ker \widetilde{\pi}.$$

This implies that K is a normal subgroup. This would finishing the proof.

First we look at \subseteq : Let $g \in K$. Then $\chi_{\widetilde{\pi}}(g) = \dim \pi = \dim \widetilde{\pi}$. But $\widetilde{\pi}(g)^n = 1$ for some $n \geq 1$. Hence all the eigenvalues of $\widetilde{\pi}(g)$ are roots of unity. The matrix $\widetilde{\pi}(g)$ is diagonalizable, hence the sum of $\dim \widetilde{\pi}$ roots of unity is equal to $\dim \widetilde{\pi}$. This is only possible if all the eigenvalues are 1 by the triangle inequality, i.e. that $\widetilde{\pi}(g) = \text{id}$. Thus $g \in \ker \widetilde{\pi}$.

Now look at \supseteq . Let $g \in G \setminus K$. Then g is conjugate to an element $h \in H \setminus \{e\}$. Then we can find some irreducible representation $[\pi] \in \hat{H}$ such that $\pi(h) \neq 1$. Hence $\widetilde{\pi}(g) \neq 1$.

This finishes the proof. \square

²To see this, note that the norm of $\widetilde{\chi}_\pi$ is a sum of squares of integers, summing to 1.

Example 8.2. Let k be a finite field and let G be the translation group of \mathbb{A}^1 , or in other words the “ax+b”-group. It is isomorphic to the matrix group

$$G \simeq \left\{ \begin{pmatrix} a & b \\ 0 & 1 \end{pmatrix} \mid a \in k^\times, b \in k \right\}.$$

Then G satisfies the conditions of the theorem (we say that G is a **Frobenious group**). Then the group K in the theorem is the group of translations:

$$K = \left\{ \begin{pmatrix} 1 & b \\ 0 & 1 \end{pmatrix} \mid b \in k \right\}.$$

★

9 The theorems of Artin and Brauer and fields of definition

Theorem 9.1 (Artin). *Let G be a finite group and \mathcal{C} a collection of subgroups of G . Then the following two conditions are equivalent:*

1. *Any character of G is a rational combination of characters of representations induced from subgroups in \mathcal{C} .*
2. *Any $g \in G$ is conjugate to an element in a subgroup in \mathcal{C} .*

We will not prove Brauer's theorem, but we state it:

Theorem 9.2 (Brauer). *For any finite group G , the character of G can be written as a linear combination with integer coefficients of characters $\text{Ind}_H^G \chi_\pi$ for one-dimensional representations π of subgroups $H \subset G$.*

In fact we can let H range through products of cyclic and p -subgroups.

9.1 Field of definition

Theorem 9.3 (Brauer). *Let G be a finite group and let m be the exponent of G (the least common multiple of orders of elements in G). Then any complex representation of G is defined over $\mathbb{Q}(\zeta_m)$, where ζ_m is a primitive m -th root of unity.*

10 Mackey's irreducibility criterion

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11 Induction from normal subgroups

thu 22 and wed 23.

12 Part II - Compact groups

When one wants to develop a representation theory for infinite groups, one has to restrict the scope somewhat. Infinite groups are too wild in general, and they can have quite bad representation theory. For example, \mathbb{Z} acting on \mathbb{C}^2 by $(x, y) \mapsto (x + ny, y)$ has the y -axis as an irreducible subspace, but the representation does not split, because there is no complementary invariant subspace. Thus the property of complete reducibility fails.

We want to at least restrict to groups with a topology. But what made wonders for the theory of finite groups was the presence of an averaging operator. If we restrict to *compact* groups, we will see that we can mimic this operator in this setting as well.

Recall that a **topological group** is a group G equipped with a topology such that the group law and the inverse are continuous maps.

Here is a key fact:

Proposition 12.1 (Haar, von Neumann, André Weil). *For any locally compact group G there exists a nonzero left-invariant Radon measure on G which is unique up to scalar. We call such a measure a **Haar measure**.*

Recall that a **Radon measure** μ on a locally compact space is a Borel measure which is outer regular, inner regular on open subsets and $\mu(K) < \infty$ for all compacts K .

To be given a Radon measure on a locally compact space X is equivalent to be given a linear functional $F : C_c(X) \rightarrow \mathbb{C}$ such that $F(f) \geq 0$ if $f \geq 0$ (here $C_c(X)$ is the space of compactly supported functions on X). Thus we can think of a Radon measure as equivalent to having a way to integrate functions.

If G is compact, we usually normalize so that $\mu(G) = 1$. This makes the Haar measure unique.

Example 12.2. Let $G = (\mathbb{R}, +)$. The Haar measure is the usual Lebesgue measure. ★

There are also right-invariant measures. If the left- and right-invariant Haar measures coincide, then we say that the group G is **unimodular**.

Lemma 12.3. *Any compact group is unimodular.*

Proof. Let μ_l be the left-invariant measure. Then the measure $\mu'_l(U) = \mu_l(Ug)$ is left-invariant as well. Hence $\mu'_l = \alpha\mu_l$ for some $\alpha \in \mathbb{R}$. But $1 = \mu'_l(G) = \alpha\mu_l(G) = \alpha$. Hence $\mu'_l = \mu_l$. Thus $\mu_l(Ug) = \mu'_l(U) = \mu_l(U)$, so μ_l is right-invariant as well. □

Many of the results for finite groups carry over to compact groups: the proofs are the same except expressions like $\frac{1}{|G|}$ are replaced by $\int_G f d\mu$.

A **representation** of a compact group G is a continuous homomorphism $\pi : G \rightarrow \text{GL}(V)$.

Here are some results that holds for compact groups as well (with the same proofs):

- **Maschke's theorem:** Any finite-dimensional representation of G is completely reducible.
- Any finite-dimensional representation is unitarizable.
- The orthogonality relations. In particular, two finite-dimensional representations of a G are equivalent if and only if the characters coincide.

The notion of regular representation is however more complicated. We are forced to (briefly) introduce infinite-dimensional spaces.

A **unitary** representation of a topological group G on a Hilbert space \mathcal{H} is a homomorphism $\pi : G \rightarrow U(\mathcal{H})$, continuous in the **strong operator topology**, meaning the following: if $g_i \rightarrow g$ in G , then $\pi(g_i)\zeta \rightarrow \pi(g)\zeta$ for all $\zeta \in \mathcal{H}$. This can be rephrased as saying that the map $G \rightarrow \mathcal{H}$ given by $g \mapsto \pi(g)\zeta$ is continuous for all $\zeta \in \mathcal{H}$.

Example 12.4. Let G be a locally compact group with fixed Haar measure. Consider $L^2(G)$ (the vector space of square integrable functions on G) with respect to the given measure. Define

$$\begin{aligned} G &\longrightarrow U(L^2(G)) \\ g &\longmapsto (\lambda(g)f)(h) = f(g^{-1}h). \end{aligned}$$

Then λ is continuous in the above sense.

We call λ the **regular representation of the compact group** G . ★

Theorem 12.5 (Peter-Weyl). *Let G be a compact group and $\pi : G \rightarrow U(\mathcal{H})$ a unitary representation. Then π decomposes into a direct sum (in the sense of Hilbert spaces) of finite-dimensional irreducible representations.*

Proof. A sketch was given in the lecture. □

Corollary 12.6. *For any compact group G , the intersection of all kernels of irreducible representations on G is trivial.*

Proof. The regular representation decomposes into a sum of irreducibles, and is injective. □

Denote by $\mathbb{C}[G]$ the linear span of matrix coefficients of finite dimensional representations of G . This is an algebra under pointwise multiplication: the product of two matrix coefficients (from representations π_1, π_2 , say) is a matrix coefficient in $\pi_1 \otimes \pi_2$. This algebra is closed under complex conjugation, since the matrix coefficient of the dual representation is given by $\overline{\pi(g^{-1})_{ji}}$. Thus $\mathbb{C}[G]$ is a C^* -algebra.

Corollary 12.7. *The algebra $\mathbb{C}[G]$ is norm-dense in $C(G)$.*

Proof. Recall the Stone-Weierstrass theorem: if A is a subalgebra of $C(G)$ that separates points, then A is norm-dense in $C(G)$. So let $g_1, g_2 \in G$. By Theorem 12.5, there exist non-trivial representations of G . Then [[details later]] \square

The algebra $\mathbb{C}[G]$ is called the **algebra of regular/polynomial functions on G** .

Theorem 12.8 (Peter-Weyl). *For every compact group G , we have*

$$\lambda \sim \bigoplus_{[\pi] \in \widehat{G}} \pi^{\dim \pi_i},$$

where $\lambda : G \rightarrow U(L^2(G))$ is the regular representation.

Just as in the case of finite groups, it is shown that the characters of finite-dimensional representations form an orthonormal basis in the space

$$\{f \in L^2(G) \mid f(g - g^{-1}) = f(-)\forall g \in G\} \subseteq L^2(G).$$

In fact, for any compact group G , the characters of finite-dimensional representations of G span a *dense* subspace in the space of continuous central functions on G .

Theorem 12.9. *Suppose G is a compact subgroup of the unitary group $U(n) \subseteq \mathbb{R}^{n \times n}$. Then $\mathbb{C}[G]$ is the unital algebra generated by the matrix coefficients a_{ij} and \det^{-1} .*

Proof. LATER \square

13 Representation theory of compact Lie groups

A **Lie group** is a smooth manifold G equipped with smooth maps $\mu : G \times G \rightarrow G$ and $\iota : G \rightarrow G$ making (G, μ, ι) into a group.

Equivalently, a Lie group is a group object in the category of smooth manifolds.

Example 13.1. Let V be a finite-dimensional vector space. Then $\mathrm{GL}(V)$ is a Lie group. The smooth structure is inherited from $\mathrm{End}(V) \simeq \mathbb{R}^N$, since $\mathrm{GL}(V)$ is an open subset of $\mathrm{End}(V)$. ★

Before giving further examples, we will develop some general results.

13.1 The exponential map

We recall some results from manifold theory.

Let M be a smooth manifold and let $p \in M$. The tangent space $T_p M$ can be equivalently defined as

- Equivalence classes of smooth curves passing through p : let $\gamma_i : (a_i, b_i) \rightarrow M$, with $a_i < 0 < b_i$ and $\gamma_i(0) = p$ be two such curves ($i = 1, 2$). Then $\gamma_1 \sim \gamma_2$ if and only if

$$(x \circ \gamma_1)'(0) = (x \circ \gamma_2)'(0)$$

for some/any coordinate system (x, U) around p . We denote the equivalence class by $\gamma'(0)$.

- There is a more algebraic definition: the space of derivations of $C^\infty(M)$ at p . This is by definition a linear map $L : C^\infty(M) \rightarrow \mathbb{C}$ such that $L(fg) = f(p)L(g) + g(p)L(f)$.

The relation between these two definitions is that the derivation L defined by $\gamma'(0)$ is

$$L(f) = \frac{\partial}{\partial f}(f \circ \gamma) \Big|_{t=0}.$$

In local coordinates (x, U) , any tangent vector can be written as

$$\sum a^i(p) \frac{\partial}{\partial x^i} \Big|_p.$$

Recall that a smooth vector field is a smooth section of the tangent bundle. The space of vector fields can be identified with the space of derivations of $C^\infty(M)$, i.e. as linear maps $L : C^\infty(M) \rightarrow C^\infty(M)$ satisfying the Leibniz rule.

Given a vector field X , an **integral curve of X** is a smooth curve $\gamma : (a, b) \rightarrow M$ such that $\gamma'(t) = X_{\gamma(t)}$ for all $t \in (a, b)$. It is a standard fact of manifold theory that for any $p \in M$, there exists a unique maximal integral curve passing through p .

Recall also: if $f : M \rightarrow N$ is a smooth map, then the differential at p is the map $d_p f : T_p M \rightarrow T_{f(p)} N$ given by $\gamma'(0) \mapsto (f \circ \gamma)'(0)$.

Now let G be a Lie group. For each $g \in G$, we have diffeomorphism $l_g : G \rightarrow G$ defined by left-multiplication: $h \mapsto gh$. This induces a map on vector fields:

$$(l_g)_*(X)_p = (d_{g^{-1}(p)} l_g)(X_{g^{-1}p}).$$

We say that a vector field X on a Lie group G is **left-invariant** if $(l_g)_*(X) = X$ for all $g \in G$. Such a vector field is determined by its value at $e \in G$: $X_g = (d_e l_g)(X_e)$.

Thus we get a one to one correspondence between left-invariant vector fields and $v \in T_e G$.

Proposition 13.2. *Let G be a Lie group, $X \in T_e G$ and $\alpha_X : (a, b) \rightarrow G$ be the maximal integral curve of the corresponding left-invariant vector field such that $\alpha_X(0) = e$.*

Then $(a, b) = \mathbb{R}$ and $\alpha_X(s + t) = \alpha_X(s)\alpha_X(t)$ for all $s, t \in \mathbb{R}$.

A **1-parameter subgroup of G** is a smooth map $\gamma : \mathbb{R} \rightarrow G$ that is a group homomorphism.

Corollary 13.3. *The map $X \mapsto \alpha_X$ is a bijection between $T_e G$ and one-parameter subgroups of G .*

Proof. Assume $\gamma : \mathbb{R} \rightarrow G$ is a one-parameter subgroup of G . Put $X = \gamma'(0) \in T_e G$. Then $\gamma = \alpha_X$:

$$\gamma'(t) = (d_e \gamma(t))(\gamma'(0))$$

as $\gamma(t + s) = \gamma(t)\gamma(s)$. [[why does it follow??]] □

Remark. *In general $\gamma(\mathbb{R})$ is not a closed subgroup of G . Take for example $\mathbb{R} \rightarrow S^1 \times S^1$ given by $t \mapsto (e^{it}, e^{i\theta t})$ for some irrational θ . Then the image is dense in $S^1 \times S^1$.*

We define the **exponential map** as $\exp : T_e G \rightarrow G$ given by $X \mapsto \alpha_X(1)$.

Note that for any $s \in \mathbb{R}$

$$\frac{\partial}{\partial t} \alpha_X(st) = s \alpha'_X(st) = s X_{\alpha_X(st)}.$$

Thus $t \mapsto \alpha_X(st)$ is the integral curve of the vector field corresponding to sX , hence $\alpha_X(st) = \alpha_{sX}(t)$.

Therefore $\exp(tX) = \alpha_{tX}(1) = \alpha_X(t)$. So by the corollary, all 1-parameter subgroups of G have the form $t \mapsto \exp(tX)$.

We have

$$\left. \frac{\partial}{\partial t} \exp(tX) \right|_{t=0} = X.$$

In other words, if we identify $T_0(T_e G)$ with $T_e G$, we conclude that $d_0 \exp = \text{id}_{T_e G}$. Thus \exp gives us a diffeomorphism between a neighbourhood of $0 \in T_e G$ and a neighbourhood of the identity $e \in G$.

That \exp is smooth is a standard result on integral curves (see e.g. Spivak).

Theorem 13.4. *The exponential map is the unique smooth map $\exp : T_e G \rightarrow G$ such that $\exp((s+t)X) = \exp(sX)\exp(tX)$ and*

$$\left. \frac{\partial}{\partial t} \exp(tX) \right|_{t=0} = X$$

In general, the exponential map is neither injective nor surjective, even for connected groups.

Example 13.5. Let $G = \text{GL}(V)$. As $\text{GL}(V)$ is an open subset of $\text{End}(V)$, the tangent space at every $M \in \text{GL}(V)$ is identified with $\text{End}(V)$ for all $M \in \text{GL}(V)$. Then $\exp : \text{End}(V) \rightarrow \text{GL}(V)$ is given by

$$X \mapsto e^X = \sum_{n=0}^{\infty} \frac{X^n}{n!}.$$

★

A **homomorphism of Lie groups** is a homomorphism $\pi : G \rightarrow H$ which is also smooth.

Theorem 13.6. *Assume that $\pi : G \rightarrow H$ is a Lie group homomorphism. Then the diagram*

$$\begin{array}{ccc} G & \xrightarrow{\pi} & H \\ \exp \uparrow & & \uparrow \exp \\ T_e G & \xrightarrow{d_e \pi} & T_e H \end{array}$$

is commutative.

Example 13.7. Let $G = \text{GL}(V)$. Consider the map $\det : \text{GL}(V) \rightarrow K^\times = \text{GL}(K)$. Then $d_e \det = \text{trace}$. Then the theorem says that $\det(e^A) = e^{\text{trace}(A)}$. ★

13.2 The Lie algebra of a Lie group

Recall that for vector field X, Y on a manifold M , there is a bracket operation $[X, Y]$. If L_X, L_Y are the corresponding derivations, then $[X, Y]$ is defined as the vector field corresponding to the derivation $L_{[X, Y]} = L_X L_Y - L_Y L_X$.³ If X and Y are given in local coordinates as

$$X = \sum f^i \frac{\partial}{\partial x^i}, Y = \sum g^i \frac{\partial}{\partial x^i},$$

respectively, then

$$[X, Y] = \sum_{i,j} \left(f^i \frac{\partial g^j}{\partial x^i} - g^i \frac{\partial f^j}{\partial x^i} \right) \frac{\partial}{\partial x^j}.$$

The definition of a Lie algebra over a field k is then the following: a **Lie algebra** is a vector space \mathfrak{g} over k equipped with a bilinear form $[-, -]$ called the **Lie bracket** that is skew-symmetric and satisfies the **Jacobi identity**:

$$[X, [Y, Z]] + [Z, [X, Y]] + [Y, [Z, X]] = 0.$$

The Jacobi identity can be thought of as a "linearization of associativity".

We want to compute the commutator more explicitly. Let γ_X be a curve on G with $\gamma_X(0) = e$ and $\gamma'_X(0) = X$. Then for any $g \in G$, the curve $g\gamma_X$ satisfies $(g\gamma_X)(0) = g$ and $(g\gamma_X)'(0) = (d_e l_g)(X)$.

Hence we have

$$L_X(f)(g) = \left. \frac{d}{dt} f(g\gamma_X(t)) \right|_{t=0}$$

Then

$$\begin{aligned} (L_X L_Y)(f)(g) &= \left. \frac{d}{dt} L_Y(f)(g\gamma_X(t)) \right|_{t=0} \\ &= \left. \frac{\partial^2}{\partial s \partial t} f(g\gamma_X(t)\gamma_Y(s)) \right|_{s=t=0} \end{aligned}$$

Hence

$$\begin{aligned} (d_e f)([X, Y]) &= (L_X L_Y - L_Y L_X)(f)(e) \\ &= \left. \frac{\partial^2}{\partial s \partial t} (f(\gamma_X(t)\gamma_Y(s)) - f(\gamma_Y(s)\gamma_X(t))) \right|_{s=t=0} \end{aligned} \quad (1)$$

³It is not immediately obvious that this is a derivation, but it is easily checked.

This is reasonable explicit, but can be made more so by working with coordinates. Choose local coordinates (x, U) around the identity $e \in G$. We can identify the codomain of $x : U \rightarrow \mathbb{R}^n$ with $\mathfrak{g} = T_e G$. We require that $x(e) = 0$ and $d_e x = \text{id}$ (we can for example choose $x = \exp^{-1}$).

Now consider the map $m : V \times V \rightarrow \mathfrak{g}$ given by $(X, Y) \mapsto x(x^{-1}(X)x^{-1}(Y))$. This is well-defined for a small enough neighbourhood U of $0 \in \mathfrak{g}$.

Applying equation (1) to $f = \ell \circ x$ (where ℓ is a linear functional on \mathfrak{g}) we get

$$\begin{aligned} \ell([X, Y]) &= \frac{\partial^2}{\partial s \partial t} \ell(x(x^{-1}(tX)(x^{-1}(sY)) - x(x^{-1}(sY)x^{-1}(tX)))) \Big|_{t=s=0} \\ &= \ell \left(\frac{\partial^2}{\partial s \partial t} (m(tX, sY) - m(sY, tX)) \Big|_{t=s=0} \right) \end{aligned}$$

Therefore

$$[X, Y] = \frac{\partial^2}{\partial s \partial t} (m(tX, sY) - m(sY, tX)) \Big|_{t=s=0}$$

This can further be written as follows: as $m(0, 0) = 0$, $m(X, 0) = X$ and $m(0, Y) = Y$, the Taylor expansion of m at $(0, 0)$ has the form

$$m(X, Y) = X + Y + B(X, Y) + h.o.t$$

where $B : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ is a bilinear map [[WHY????]]

Hence in this description, we have that

$$[X, Y] = B(X, Y) - B(Y, X).$$

Example 13.8. Let $G = \text{GL}(V)$ for V a finite-dimensional real or complex vector space. Choose coordinates by setting $x(A) = A - I$. Then

$$m(X, Y) = (1 + X)(1 + Y) - 1 = XY + X + Y.$$

Hence in this case $[X, Y] = XY - YX$. ★

The space $\text{End } V = T_e \text{GL}(V)$ with this bracket is denoted by $\mathfrak{gl}(V)$.

With this done, here's a theorem:

Theorem 13.9. *If $\pi : G \rightarrow H$ is a Lie group homomorphism, then $\pi_* = d_e \pi : \mathfrak{g} \rightarrow \mathfrak{h}$ is a Lie algebra homomorphism. That is, the map π_* preserves the bracket:*

$$\pi_*([X, Y]) = [\pi_*(X), \pi_*(Y)].$$

Also, if G is connected, π is completely determined by π_ .*

Proof. Recall first that for all $X \in \mathfrak{g}$ we have $\pi(\exp(tX)) = \exp(t\pi_*(X))$. First off, we have, as above, that

$$L_X(f)(g) = \left. \frac{d}{dt}(f(g \exp(tX))) \right|_{t=0}$$

and one also verifies that

$$L_{\pi_*(X)}(f)(\pi(g)) = L_X(f \circ \pi)(g).$$

This follows more or less directly from the definitions.

[[[[rest of the proof here]]]]

□

14 Lie subgroups

By definition, a **closed Lie subgroup** of a Lie group G is a subgroup H which is also a closed submanifold.

Then H is itself a Lie group. We can identify $\mathfrak{h} = T_e H$ with a subspace of $\mathfrak{g} = T_e G$. As the embedding $H \hookrightarrow G$ is a Lie group homomorphism, this gives an identification of \mathfrak{h} with a Lie subalgebra of \mathfrak{g} .

In fact, the condition that H is a submanifold is redundant:

Theorem 14.1. *If G is a Lie group and H is a closed subgroup, then H is a closed submanifold.*

Proof. LONG PROOF HERE □

Here's a surprising theorem.

Theorem 14.2. *If $\pi : G \rightarrow H$ is a continuous homomorphism of Lie groups, then π is smooth.*

In particular, for Lie groups, there is no difference between finite-dimensional representations of locally compact groups and Lie groups.

15 Classical Lie groups

This section will give examples of Lie groups and their Lie algebras explicitly in terms of matrices. The **classical Lie groups** are groups of linear transformations preserving some symmetric/skew-symmetric/Hermitian form on a real/complex/quaternionic space, as well as their special versions.

15.1 The general linear group

Let V be a real or complex vector space of dimension n . Then $\mathrm{GL}(V)$ is the set of invertible linear operators $V \rightarrow V$. If a basis for V is given, then $\mathrm{GL}(V)$ is realized as the set of invertible $n \times n$ matrices with determinant non-zero.

If V is a real vector space, then the dimension of $\mathrm{GL}(V)$ is n^2 , and if V is complex, then the dimension is $2n^2$.

The Lie algebra of $\mathrm{GL}(V)$, denoted by $\mathfrak{gl}(V)$ is identified with $\mathrm{End}(V)$, or, if a basis is given, with $\mathrm{Mat}_{n,n}(V)$, since $\mathrm{GL}(V)$ is an open subset in $\mathrm{End}(V)$.

15.2 The special linear group

Again, let V be a real or a complex vector space. The **special linear group** $\mathrm{SL}(V)$ is by definition the subset of $\mathrm{GL}(V)$ consisting of operators of determinant 1. Since this is a closed condition, it follows from [[THEOREM]] that $\mathrm{SL}(V)$ is actually a closed Lie subgroup of $\mathrm{GL}(V)$. Note that $\dim \mathrm{SL}(V) = n^2 - 1$ if V is a real vector space.

I claim that the Lie algebra of $\mathrm{SL}(V)$ is the space of matrices in $\mathrm{End}(V)$ of trace zero. To prove this, let $\{A_t\}$ be an arc in $\mathrm{SL}(V)$ such that $A_0 = I_n$ and $\frac{d}{dt}\big|_{t=0} A_t = X$. Then $A_t e_1 \wedge \dots \wedge A_t e_n = e_1 \wedge \dots \wedge e_n$ for all t since the determinant of A_t is 1 for all t . Thus, taking derivatives of both sides, we get

$$\begin{aligned} 0 &= \frac{d}{dt}\bigg|_{t=0} A_t e_1 \wedge \dots \wedge A_t e_n \\ &= \sum_{i=1}^n e_1 \wedge \dots \wedge X e_i \wedge \dots \wedge e_n \\ &= \mathrm{Tr}(X) e_1 \wedge \dots \wedge e_n. \end{aligned}$$

In the second line we used the product rule for the derivative (which works just as well with exterior products (in fact, with any bilinear operator)). Hence $\mathrm{Tr}(X) = 0$. Counting dimensions, we see that the space of traceless matrices have the same dimension as $\mathrm{SL}(V)$, so that we can identify $\mathfrak{sl}(V)$ with the space of traceless matrices.

15.3 Groups defined by preservation of a bilinear form

Let V be as above and consider a bilinear B form on V . Let

$$G = \{g \in \mathrm{GL}(V) \mid B(gv, gw) = B(v, w) \text{ for all } v, w \in V\}.$$

Then G is a subgroup of $\mathrm{GL}(V)$. We shall verify that it is indeed a Lie subgroup.

Let W be the space of bilinear forms on V . Note that $W \simeq V^* \otimes V^*$. Define a representation π of $\mathrm{GL}(V)$ on W by

$$(\pi(g)B')(v, w) = B'(g^{-1}v, g^{-1}w).$$

Then G is exactly the set $\{g \in \mathrm{GL}(V) \mid \pi(g)B = B\}$, so that from [[Proposition 2]], it follows that G is a Lie group. with Lie algebra

$$\mathfrak{g} = \{X \in \mathfrak{gl}(V) \mid \pi_*(X)B = 0\}.$$

We want this a little more explicit. So note that we can write

$$\pi_*(X) = \left. \frac{d}{dt} \pi(\exp(tX)) \right|_{t=0}$$

This is a simple calculation using the functoriality of $\pi_a st$ and the definition of the exponential map. Hence we get

$$\begin{aligned} (\pi_*(X)B)(v, w) &= \left. \frac{d}{dt} (\pi(\exp(tX))B)(v, w) \right|_{t=0} \\ &= \left. \frac{d}{dt} B(e^{-tX}v, e^{-tX}w) \right|_{t=0} \\ &= -B(Xv, w) - B(v, Xw). \end{aligned}$$

We used the chain rule in the last line.

Thus

$$\mathfrak{g} = \{X \in \mathfrak{gl}(V) \mid B(Xv, w) + B(v, Xw) = 0\}.$$

The dimension of G will of course depend upon the choice of B .

15.4 The orthogonal group $O(n)$

Let $V = \mathbb{R}^n$ and let B be the usual scalar product

$$(v, w) = \sum_{i=1}^n v_i w_i.$$

Then the group G for B as above is called the **orthogonal group** and denoted by $O(n)$, $O_n(\mathbb{R})$ or $O(n; \mathbb{R})$.

Note that we have

$$(Xv, w) + (v, Xw) = (Xv, w) + (X^T v, w) = ((X + X^T)v, w).$$

This inner product should be zero for all v, w . Hence we have:

$$\mathfrak{o}(n) = \{X \in \mathfrak{gl}_n(\mathbb{R}) \mid X + X^T = 0\},$$

by the previous section. Thus the Lie algebra consists of all skew-symmetric matrices. We see that $O(n)$ have dimension $1 + 2 + \dots + (n-1) = n(n-1)/2$. The **special orthogonal group** $SO(n)$ is the subgroup of $O(n)$ whose determinants are 1. In other words: $SO(n) = O(n) \cap \mathrm{SL}_n(\mathbb{R})$. This is the connected component of the identity of $O_n(\mathbb{R})$. Then the Lie algebra is given by

$$\mathfrak{sl}_n(\mathbb{R}) = \{X \in \mathfrak{gl}_n(\mathbb{R}) \mid X^T = -X, \mathrm{Tr} X = 0\},$$

which is equal to $\mathfrak{o}(n)$ since the condition $X^T = -X$ implies that $\mathrm{Tr} X = 0$.

We can do the same for $V = \mathbb{C}^n$ with the same bilinear form. The corresponding groups are denoted by $O_n(\mathbb{C})$ and $SO_n(\mathbb{C})$. These are however not compact anymore, since $B \otimes \mathbb{C}$ is not positive definite.

15.5 Indefinite orthogonal groups $O(k, l)$

Let $V = \mathbb{R}^{k+l}$ for $k, l \geq 1$ and consider the bilinear form

$$\begin{aligned} B(v, w) &= \sum_{i=1}^k v_i w_i - \sum_{i=k+1}^{k+l} v_i w_i \\ &= (Av, w) \end{aligned}$$

where

$$A = \begin{pmatrix} I_k & 0 \\ 0 & -I_l \end{pmatrix}.$$

The group of transformations preserving this form is then by definition the indefinite orthogonal group $O(k, n)$. As above, we see that its Lie algebra is

$$\mathfrak{o}(k, l) = \{X \in \mathfrak{gl}_{k+l}(\mathbb{R}) \mid AX + X^T A = 0\}.$$

This can be made even more explicit. Let $X \in \mathfrak{o}(k, l)$. Write

$$X = \begin{pmatrix} P & Q \\ R & S \end{pmatrix},$$

where P is a $k \times k$ matrix, Q is a $l \times k$ matrix, R is a $k \times l$ matrix, and S is a $l \times l$ matrix. Then one can check that the condition for X to be in $\mathfrak{o}(k, l)$ is equivalent to $P = -P^T$, $S = -S^T$ and $R = Q$. Thus the dimension of $\mathfrak{o}(k, l)$ is

$$\frac{k(k-1)}{2} + \frac{l(l-1)}{2} + kl = \frac{n(n-1)}{2}.$$

We also have its special version: $SO(k, l) := O(k, l) \cap SL_{k+l}(\mathbb{R})$.

15.6 The unitary group $U(n)$

Let $V = \mathbb{C}^n$, and consider the Hermitian form

$$\langle v, w \rangle = \sum_{i=1}^n v_i \overline{w_i}.$$

The **unitary group** $U(n)$ is the group of \mathbb{C} -linear transformations preserving this form. The proof in the case of $O(n)$ goes through here as well, so that we see that

$$\mathfrak{u}(n) = \{X \in \mathfrak{gl}_n(\mathbb{C}) \mid X = -X^*\},$$

where the star means the conjugate transpose of X . We also have the **special unitary group** $SU(n) = U(n) \cap SL_n(\mathbb{C})$ with Lie algebra

$$\mathfrak{su}(n) = \{X \in \mathfrak{gl}_n(\mathbb{C}) \mid X = -X^*, \text{Tr } X = 0\}.$$

The dimension of $U(n)$ is n^2 . To see this, note that matrices in the Lie algebra consist of real entries along the diagonal, plus free entries above the diagonal (the entries below the diagonal are minus conjugate those above). Thus the total freedom is $n + 2 \cdot \frac{n(n-1)}{2} = n^2$.

15.7 The symplectic Lie groups $Sp(2n, \mathbb{R})$

Let $V = \mathbb{R}^{2n}$ or $V = \mathbb{C}^{2n}$ and consider

$$\begin{aligned} (v, w) &= \sum_{i=1}^{2n} (v_i w_{i+n} - v_{i+n} w_i) \\ &= (Jv, w) \end{aligned}$$

where

$$J = \begin{pmatrix} 0 & -I_n \\ -I_n & 0 \end{pmatrix}.$$

The group of transformations preserving this form are the **symplectic groups** $Sp(2n, \mathbb{R})$ or $Sp(2n, \mathbb{C})$. The Lie algebra is

$$\mathfrak{sp}(2n; k) = \{X \in \mathfrak{gl}_n(k) \mid JX + X^T J = 0\}.$$

In the same way is with the indefinite orthogonal group, one can compute the Lie algebra more explicitly. Namely, write X as

$$X = \begin{pmatrix} A & B \\ C & D \end{pmatrix}.$$

Here A, B, C and D are $n \times n$ matrices. Here the condition on X to be in the Lie algebra is equivalent to $D = -A^T$ and B and C being skew-symmetric matrices. Hence the dimension is $n^2 + 2 \cdot \frac{n^2 - n}{2} = 2n^2 - n$.

15.8 The compact symplectic group $Sp(n)$

This is the group defined by $Sp(n) = Sp(2n; \mathbb{C}) \cap U(2n)$ with Lie algebra

$$\mathfrak{sp}(n) = \{X \in \mathfrak{gl}_n(\mathbb{C}) \mid X + X^* = 0, JX + X^T J = 0\},$$

where J is as above. It can be shown that $Sp(n)$ is the subgroup of $GL_n(\mathbb{H})$ preserving $\sum_{i=1}^n v_i \bar{w}_i$.

16 Lie subgroups

A **Lie subgroup** of a Lie group G is a subgroup $H \subset G$ admitting the structure of a Lie group, making the embedding $H \rightarrow G$ smooth.

17 The adjoint representation

Let G be a Lie group. For any $g \in G$ consider the automorphism $h \mapsto ghg^{-1}$ of G . Thus we have a map $G \rightarrow \text{Aut}(G)$. Its differential at the identity is denoted by Ad , and we get a homomorphism $\text{Ad} : G \rightarrow \text{GL}(\mathfrak{g})$, called the **adjoint representation**.

18 Structure and representation theory of $SU(2)$

Recall that the Lie algebra of $SU(2)$ is

$$\mathfrak{su}(2) = \{X \in \mathfrak{gl}_2(\mathbb{C}) \mid X^* + X = 0, \quad \text{Tr}(X) = 0\}.$$

Recall also that

$$\mathfrak{sl}_2(\mathbb{C}) = \{X \in \mathfrak{gl}_2(\mathbb{C}) \mid \text{Tr}(X) = 0\}.$$

The latter is a complex vector space, and in fact we have $\mathfrak{su}(2) \otimes_{\mathbb{R}} \mathbb{C} = \mathfrak{sl}_2(\mathbb{C})$. Note that one inclusion is obvious. For the other, note that any $X \in \mathfrak{sl}_2(\mathbb{C})$ can be written as

$$X = \frac{X - X^*}{2} + i \frac{X + X^*}{2i},$$

namely as a sum of two matrices in $\mathfrak{su}(2)$.

There is a standard \mathbb{C} -basis for $\mathfrak{sl}_2(\mathbb{C})$ given by the following three matrices:

$$E = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad F = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \quad H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

A basis for $\mathfrak{su}(2)$ over \mathbb{R} is $E - F$, $i(E + F)$ and iH . Note that $\mathbb{R}iH \subset \mathfrak{su}(2)$ is the Lie algebra of the torus

$$T = \left\{ \begin{pmatrix} z & 0 \\ 0 & \bar{z} \end{pmatrix} \mid z \in S^1 \right\}.$$

The Lie algebra structure on $\mathfrak{sl}_2(\mathbb{C})$ is defined by the rules

$$[H, E] = 2E \quad [H, F] = -2F \quad [E, F] = H.$$

Lemma 18.1. *The group $SU(2)$ is simply-connected.*

Proof. One checks that

$$SU(2) = \left\{ \begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix} \mid \alpha, \beta \in \mathbb{C}, \quad |\alpha|^2 + |\beta|^2 = 1 \right\}$$

This is clearly homeomorphic to S^3 , which is simply-connected. \square

Therefore, from [[Prop]], we have a one to one correspondence between Lie group homomorphisms $SU(2) \rightarrow GL(V)$ and Lie algebra homomorphisms $\mathfrak{su}(2) \rightarrow \mathfrak{gl}(V)$.

Recall that if \mathfrak{g} is Lie algebra, then a **representation** of \mathfrak{g} on V is the same thing as a Lie algebra homomorphism $\mathfrak{g} \rightarrow \mathfrak{gl}(V)$. We also say that V is a **\mathfrak{g} -module**. We say that a subspace $W \subset V$ is **invariant** if $X \cdot W \subset W$ for all $X \in \mathfrak{g}$. A representation $\mathfrak{g} \rightarrow \mathfrak{gl}(V)$ is **irreducible** (or the \mathfrak{g} -module V is **simple**) if there are no proper invariant subspaces.

It is an exercise to see that if G is connected Lie group, then these notions coincide with those of representation of G (as opposed to representations of \mathfrak{g}).

We now want to classify irreducible representations of $SU(2)$ on *complex* finite-dimensional vector spaces V . Equivalently, we want to classify irreducible representations of $\mathfrak{su}(2)$ on complex finite-dimensional vectors spaces V .

Now, since $\mathfrak{su}(2) \otimes_{\mathbb{R}} \mathbb{C} \simeq \mathfrak{sl}_2(\mathbb{C})$, any Lie algebra homomorphism $\mathfrak{su}(2) \rightarrow \mathfrak{gl}(V)$ (where we consider V as a real vector space) extends uniquely to a Lie algebra homomorphism $\mathfrak{sl}_2(\mathbb{C}) \rightarrow \mathfrak{gl}(V)$ of complex vector spaces.

So classifying $\mathfrak{su}(2)$ -modules is the same as classifying $\mathfrak{sl}_2(\mathbb{C})$ -modules.

Assume now V is a finite-dimensional $\mathfrak{sl}_2(\mathbb{C})$ -module. Then this exponentiates to a representation of $SU(2)$:

$$\begin{array}{ccc}
 \mathfrak{su}(2) \hookrightarrow \mathfrak{sl}_2(\mathbb{C}) & & SU(2) \hookrightarrow SL_2(\mathbb{C}) \\
 \searrow \quad \downarrow & \xrightarrow{\text{exp}} & \searrow \quad \downarrow \\
 \mathfrak{gl}(V) & & GL(V)
 \end{array}$$

By restriction, the torus $T \subset SU(2)$ act on V as well, and by complete reducibility, V decomposes as a sum of T -invariant subspaces. Since $\{itH \mid t \in \mathbb{R}\}$ exponentiates to the torus \mathbb{T} , V decomposes in as a sum of H -invariant subspaces as well.

Lemma 18.2. *The eigenvalues of H are integers.*

Proof. Note that each irreducible eigenspace must be one-dimensional, since on each eigenspace, H is sent to a diagonal matrix. Thus on each one-dimensional irreducible representation, itH is sent to multiplication by $it\alpha$.

Also note that $\exp(itH) \in S^1$, so that the action of H on $(\mathbb{C}, +)$ lifts to a representation of S^1 . These are all of the form $\theta \mapsto e^{i\alpha\theta}$.

Exponentiating, we get that $e^{itH} = e^{it\alpha}$ for all $t \in \mathbb{R}$. Put $t = 2\pi$. Then we get that $1 = e^{2\pi i\alpha}$, which is possible only if $\alpha \in \mathbb{Z}$. \square

It is common to index the eigenvalues of H on V by half-integers. Thus for $s \in \frac{1}{2}\mathbb{Z}$, we put

$$V(s) = \{\xi \in V \mid H\xi = 2s\xi\}.$$

Elements of $V(s)$ are called vectors of **weight** s . Thus we write

$$V = \bigoplus_{s \in \frac{1}{2}\mathbb{Z}} V(s).$$

Now recall the commutation relations in $\mathfrak{sl}_2(\mathbb{C})$: $[H, E] = 2E$ and $[H, F] = -2F$.

Lemma 18.3. *We have*

$$EV(s) \subset V(s+1)$$

and

$$FV(s) \subset V(s-1).$$

In particular, if $v \neq 0$ is a vector of highest weight, then $Ev = 0$.

Proof. Let $v \in EV(s)$. Then $v = Ew$ for $w \in V(s)$. Then

$$\begin{aligned} Hv &= HEw \\ &= HEw - EHw + EHw \\ &= [H, E]w + EHw \\ &= 2Ew + 2sEw \\ &= 2v + 2sv \\ &= 2(v+1)v. \end{aligned}$$

So $v \in V(s+1)$. The calculation with F is similar. \square

These two observations are enough to prove quite a lot about representations of $\mathfrak{sl}_2(\mathbb{C})$.

Lemma 18.4. *Suppose V is a finite-dimensional $\mathfrak{sl}_2(\mathbb{C})$ -module and $\xi \in V(s) \setminus \{0\}$ satisfies $E\xi = 0$ (that is, ξ is of highest weight). Then*

1. $s \geq 0$.
2. $F^{2s+1}\xi = 0$ and $F^k\xi \neq 0$ for $k = 0, \dots, 2s$.
3. $EF^k\xi = (2s - k + 1)kF^{k-1}\xi$ for all $k \geq 0$.

Proof. We start by proving number 3 by induction. The base case $k = 0$ gives $E\xi = 0$, which is clear by assumption.

Note that $EF = [E, F] + FE = H + FE$. Note also that since $\xi \in V(s)$, we have $F^k\xi \in V(s - k)$ by the previous lemma. Then:

$$\begin{aligned} EF^{k+1}\xi &= EFF^k\xi \\ &= (H + FE)F^k\xi \\ &= H(F^k\xi) + F(EF^k\xi) \\ &= 2(s - k)F^k\xi + (2s - k + 1)kF^k\xi \\ &= (2s - k + 2sk - k^2)F^k\xi. \end{aligned}$$

Now note that this is what we want, because

$$(2s - (k + 1) + 1)(k + 1) = (2s - k)(k + 1) = 2sk + 2s - k^2 - k.$$

Thus number 3) is proved.

Now let n be the smallest number such that $F^n\xi = 0$ (the **smallest weight**). Then $F^n\xi = 0$. Then it follows from 3) that

$$0 = EF^n\xi = (2s - n + 1)nF^{n-1}\xi.$$

Hence $2s - n + 1 = 0$, so $n = 2s + 1$. This proves 2). This also proves 1) because $n \geq 1$. \square

In view of this lemma, for any $s \in \frac{1}{2}\mathbb{Z}_+ = \{0, \frac{1}{2}, 1, \dots\}$, define an $\mathfrak{sl}_2(\mathbb{C})$ -module V_s as follows: it is a vector space with basis elements denoted by

$$\{\xi_{-s}^s, \xi_{-s+1}^s, \dots, \xi_s^s\},$$

and where H, F and E act as follows:

$$H\xi_t^s = 2t\xi_t^s \quad F\xi_t^s = \xi_{t-1}^s \quad E\xi_{s-k}^s = (2s - k + 1)k\xi_{s-k+1}^s.$$

Then it is an (easy) exercise to see that this defines an $\mathfrak{sl}_2(\mathbb{C})$ -module. It is also easy to see that V_s is irreducible, since, starting from any basis vector ξ_t^s , we can use F and E to raise and lower the indices to generate all of V_s .

The number s in V_s is called the **highest weight** or **spin** of V_s .

The lemma tells us that if V is a finite-dimensional $\mathfrak{sl}_2(\mathbb{C})$ -module and $\xi \in V(s)$, $\xi \neq 0$ and $E\xi = 0$ (that is, ξ is a highest weight vector), then we get an embedding $V_s \hookrightarrow V$ given by $\xi_{s-k}^s \mapsto F^k\xi$.

Theorem 18.5. *The $\mathfrak{sl}_2(\mathbb{C})$ -modules V_s ($s \in \frac{1}{2}\mathbb{Z}$) are irreducible, pairwise non-isomorphic, and any finite-dimensional irreducible $\mathfrak{sl}_2(\mathbb{C})$ -module is isomorphic to some V_s .*

Proof. The first statement is clear, since all the V_s have different dimension. Now, if V is an irreducible $\mathfrak{sl}_2(\mathbb{C})$ -module, the observation above tells that we have an embedding $V_s \hookrightarrow V$.

Since $\mathfrak{sl}_2(\mathbb{C})$ is semisimple, it follows from Weyl's theorem ([ref??]), that every invariant subspace has a complementary invariant subspace. But V was irreducible, so $V_s = V$. \square

Example 18.6. Let $s = 0$. Then $\dim V_0 = 1$, and this corresponds to the trivial representation of $SU(2)$. \star

Example 18.7. Let $s = \frac{1}{2}$. Then $\dim V_{\frac{1}{2}} = 2$, and one sees that H, F and E act precisely as the canonical representation of $\mathfrak{sl}_2(\mathbb{C})$ on \mathbb{C}^2 . \star

Example 18.8. Let $s = 1$. Then $\dim V_1 = 3$, and V_1 is the adjoint representation of $\mathfrak{sl}_2(\mathbb{C})$ with highest weight vector $\xi_1^1 = E$. \star

19 **Tori**

20 Cartan's theorem on maximal tori

21 Roots

First we recall some notation from the representation theory of $SU(2)$. There we had a maximal torus, called T , which was given by

$$T = \left\{ \begin{pmatrix} z & 0 \\ 0 & \bar{z} \end{pmatrix} \mid z \in S^1 \subset \mathbb{C} \right\}.$$

The Lie algebra of $SU(2)$ is contained in the Lie algebra of $SL(2, \mathbb{C})$. We write $\mathfrak{su}(2) \subset \mathfrak{sl}_2(\mathbb{C})$. The Lie algebra is spanned by [[write basis here]]

21.1 Roots

Let G be a compact connected Lie group. Fix a maximal torus T . Consider $\mathfrak{g}_{\mathbb{C}} = \mathbb{C} \otimes_{\mathbb{R}} \mathfrak{g}$, the complexification of the Lie algebra of G . This is a complex Lie algebra, where we define $[c \otimes X, d \otimes Y] = cd \otimes [X, Y]$.

We can identify \mathfrak{g} with the elements of the form $1 \otimes X$ for $X \in \mathfrak{g}$. Sometimes we write elements of $\mathfrak{g}_{\mathbb{C}}$ as $X + iY$.

The adjoint representation $\text{Ad} : G \rightarrow \text{GL}(\mathfrak{g})$ extends to a representation $G \rightarrow \text{GL}(\mathfrak{g}_{\mathbb{C}})$, which we will also denote by Ad .

Consider $\text{Ad}|_T$. As T is a compact abelian group, we have a decomposition of $\text{Ad}|_T$ into isotypic components corresponding to characters $\chi \in \widehat{T}$. Thus we can write

$$\mathfrak{g}_{\mathbb{C}} = \bigoplus_{\chi \in \widehat{T}} \mathfrak{g}_{\mathbb{C}}(\chi)$$

where

$$\mathfrak{g}_{\mathbb{C}}(\chi) = \{X \in \mathfrak{g}_{\mathbb{C}} \mid (\text{Ad } g)X = \chi(g)X \text{ for all } g \in T\}$$

is the eigenspace of X .

We view $\mathbb{T} = S^1$ as a subgroup of $\mathbb{C}^* = \text{GL}_1(\mathbb{C})$. In this picture, the Lie algebra of \mathbb{T} is $i\mathbb{R} \subset \mathbb{C}$.

Let \mathfrak{t} be the Lie algebra of T . Any character $\chi \in \widehat{T}$ is determined by its differential $\chi_* : \mathfrak{t} \rightarrow i\mathbb{R}$, so we can think of $\chi_* \in i\mathfrak{t}^*$, where $\mathfrak{t}^* = \text{Hom}_{\mathbb{R}}(\mathfrak{t}, \mathbb{R})$.

Then the set of differentials χ_* ($\chi \in \widehat{T}$) form a subset $X^*(T) \subset i\mathfrak{t}^*$. It is a *lattice* in $i\mathfrak{t}^*$ (here by *lattice* we mean a discrete subgroup of maximal rank), called the **character lattice**.

Indeed, if $T = \mathbb{R}^n / \mathbb{Z}^n$, then $\mathfrak{t} = \mathbb{R}^n$, so $\mathfrak{t}^* = \mathbb{R}^n$, and an element $(it_1, \dots, it_n) \in i\mathfrak{t}^*$ defines a character $\mathbb{R}^n \rightarrow \mathbb{T}$ by

$$(a_1, \dots, a_n) \mapsto e^{ia_1 t_1} \cdots e^{ia_n t_n},$$

which factors through $\mathbb{R}^n/\mathbb{Z}^n$ if and only if all the $a_i \in 2\pi\mathbb{Z}$. Then $X^*(T) = 2\pi i\mathbb{Z}^n \subset i\mathbb{R}^n$.

Consider now the complexification $\mathfrak{t}_{\mathbb{C}}$ of the Lie algebra of T . We denote this complexification by \mathfrak{h} . It is called a **Cartan subalgebra** of $\mathfrak{g}_{\mathbb{C}}$. It is a “maximal toral subalgebra”.

Functionals $\mathfrak{t} \rightarrow \mathbb{R}$ can be extended by complex linearity to \mathfrak{h} , so $i\mathfrak{t}^* \subset \mathfrak{h}^* = \text{Hom}_{\mathbb{C}}(\mathfrak{h}, \mathbb{C})$. We then have

$$\begin{aligned}\mathfrak{g}_{\mathbb{C}}(\chi) &= \{X \in \mathfrak{g}_{\mathbb{C}} \mid (\text{Ad } g)X = \chi(g)X, \forall g \in T\} \\ &= \{X \in \mathfrak{g}_{\mathbb{C}} \mid [Y, X] = \chi_*(Y)X, \forall Y \in T\} \\ &= \{X \in \mathfrak{g}_{\mathbb{C}} \mid [Y, X] = \chi_*(Y)X, \forall Y \in \mathfrak{h}\}.\end{aligned}$$

For $\alpha \in \mathfrak{h}^*$, denote

$$\mathfrak{g}_{\alpha} = \{X \in \mathfrak{g}_{\mathbb{C}} \mid [H, X] = \alpha(H)X, \forall H \in \mathfrak{h}\}.$$

In our earlier notation, this says that $\mathfrak{g}_{\alpha} = \mathfrak{g}_{\mathbb{C}}(\chi)$, where we think of $\chi \in i\mathfrak{t}^* \subset \mathfrak{h}^*$.

Lemma 21.1. *We have that $\mathfrak{g}_0 = \mathfrak{h}$.*

Proof. This follows because \mathfrak{t} is a maximal abelian Lie subalgebra of \mathfrak{g} , so that

$$\mathfrak{t} = \{X \in \mathfrak{g} \mid [H, X] = 0 \quad \forall H \in \mathfrak{t}\}.$$

Now complexify both sides. □

The elements $\alpha \in X^*(T) \setminus \{0\}$ such that $\mathfrak{g}_{\alpha} \neq 0$ are called the **roots** of G or $\mathfrak{g}_{\mathbb{C}}$. We denote the set of roots by Δ .

To remember the position of \mathfrak{g} inside $\mathfrak{g}_{\mathbb{C}}$, it is convenient to introduce an involution on $\mathfrak{g}_{\mathbb{C}}$, defined by

$$(X + iY)^* = -X + iY,$$

so that $\mathfrak{g} = \{X \in \mathfrak{g}_{\mathbb{C}} \mid X = -X^*\}$.⁴

This induces an involution $\alpha \mapsto \bar{\alpha}$ in \mathfrak{h}^* as well. Namely, define

$$\bar{\alpha}(H) \triangleq \overline{\alpha(H^*)}.$$

This is actually an involution, because

$$\overline{\bar{\alpha}}(H) = \overline{\overline{\alpha(H^*)}} = \overline{\alpha(H^{**})} = \alpha(H).$$

In fact, this definition ensures that $\bar{\alpha}$ is *complex linear* as well: we have that $\bar{\alpha}(zH) = z\bar{\alpha}(H)$ (this is an easy but somewhat tedious exercise).

⁴Note that I have chosen to write X^* for the involution to distinguish it from taking duals.

This lets us recognise $i\mathfrak{t}^*$ inside \mathfrak{h}^* as well. Namely,

$$\begin{aligned} i\mathfrak{t}^* &= \{\alpha \in \mathfrak{h}^* \mid \alpha(\mathfrak{t}) \subset i\mathbb{R}\} \\ &= \{\alpha \in \mathfrak{h}^* \mid \bar{\alpha} = \alpha\}, \end{aligned}$$

as those functionals fixed by the involution.

21.2 Some lemmas

The rest of this lecture will consist of several small results.

Lemma 21.2. *We have a decomposition*

$$\mathfrak{g}_{\mathbb{C}} = \mathfrak{h} \oplus \bigoplus_{\alpha \in \Delta} \mathfrak{g}_{\alpha}.$$

Also:

1. $[\mathfrak{g}_{\alpha}, \mathfrak{g}_{\beta}] \subset \mathfrak{g}_{\alpha+\beta}$.
2. $\mathfrak{g}_{\alpha}^* = \mathfrak{g}_{-\alpha}$. Here $\mathfrak{g}_{\alpha}^* = \{X^* \mid X \in \mathfrak{g}_{\alpha}\}$.

Proof. The decomposition of $\mathfrak{g}_{\mathbb{C}}$ is just that of writing $\mathfrak{g}_{\mathbb{C}}$ into simultaneous eigenspaces for the action of \mathfrak{h} , where \mathfrak{h} has zero eigenvalues, as proved above.

We have that

$$\mathfrak{g}_{\alpha} = \{X \in \mathfrak{g}_{\mathbb{C}} \mid [H, X] = \alpha(H)X \text{ for all } H \in \mathfrak{h}\}.$$

Let $Y \in \mathfrak{g}_{\beta}$. Then we look at $[H, [X, Y]]$. By the Jacobi identity, this is equal to

$$\begin{aligned} [H, [X, Y]] &= -[Y, [H, X]] - [X, [Y, H]] \\ &= -\alpha(H)[Y, X] + [X, [H, Y]] \\ &= \alpha(H)[X, Y] + \beta(H)[X, Y] \\ &= (\alpha(H) + \beta(H))[X, Y]. \end{aligned}$$

Hence $[X, Y] \in \mathfrak{g}_{\alpha+\beta}$.

For ii), note that $\alpha(\mathfrak{t}) \subset i\mathbb{R}$. Hence for $H \in \mathfrak{t}$, we have

$$\bar{\alpha}(H) = \overline{\alpha(H^*)} = -\overline{\alpha(H)} = \alpha(H).$$

Hence we have

$$\begin{aligned} \mathfrak{g}_{\alpha} &= \{X \in \mathfrak{g}_{\mathbb{C}} \mid [H, X] = -\alpha(H)X \quad \forall H \in \mathfrak{h}\} \\ &= \{X \in \mathfrak{g} \mid [H, X] = -\alpha(H)X \quad \forall H \in i\mathfrak{t}^*\} \otimes_{\mathbb{R}} \mathbb{C} \\ &= \{X \in \mathfrak{g} \mid [H, X^*] = \alpha(H)X^* \quad \forall H \in i\mathfrak{t}^*\} \otimes_{\mathbb{R}} \mathbb{C}. \end{aligned}$$

In the last equality, we used the involution on both sides to get

$$[H^*, X^*] = -[H, X] = \alpha(H)X = \alpha(H)X^*,$$

since X is real (which gives $X^* = -X$) and $H^* = H$. □

21.3 An Ad-invariant inner product

To proceed, it is convenient to introduce an Ad-invariant scalar product on \mathfrak{g} . These exist:

Lemma 21.3. *Let G be compact Lie group. Then there is an Ad-invariant inner product $(-, -)$ on \mathfrak{g} , in the sense that*

$$(g \cdot X, g \cdot Y) = (X, Y)$$

for $X, Y \in \mathfrak{g}$, where $g \cdot X$ denotes the adjoint action $\text{Ad} : G \rightarrow \text{GL}(\mathfrak{g})$. This condition further implies that

$$([X, Y], Z) + (Y, [X, Z]) = 0.$$

Proof. Choose any scalar product $\langle -, - \rangle$ on \mathfrak{g} and a normalized Haar measure dg on G . Then

$$(X, Y) = \int_G (g \cdot X, g \cdot Y) dg$$

is an Ad-invariant scalar product on \mathfrak{g} . To see the other equality, let $\gamma : \mathbb{R} \rightarrow G$ be an arc with $\gamma(0) = e \in G$ and $\gamma'(0) = Z \in \mathfrak{g}$. Then

$$\begin{aligned} 0 &= \left. \frac{d}{dt} (\gamma(t) \cdot X, \gamma(t) \cdot Y) \right|_{t=0} \\ &= \lim_{t \rightarrow 0} \frac{1}{t} ((\gamma(t) \cdot X, \gamma(t) \cdot Y) - (X, \gamma(t) \cdot Y) + (X, \gamma(t) \cdot Y) - (X, Y)) \\ &= \lim_{t \rightarrow 0} \left(\frac{1}{t} (\gamma(t) \cdot X - X, Y) + \left(X, \frac{1}{t} (\gamma(t) \cdot Y - Y) \right) \right) \\ &= ([Z, X], Y) + (X, [Z, Y]) \end{aligned}$$

Renaming X, Y, Z appropriately gives the required identity. \square

It will be convenient to require that $(-, -)$ is *negative* definite on \mathfrak{g} . We can extend this form to $\mathfrak{g}_{\mathbb{C}}$ be complex linearity. It will no longer be definite (it doesn't make sense), but it will still be non-degenerate (easy exercise).

Lemma 21.4. *We have*

$$(\mathfrak{g}_{\alpha}, \mathfrak{g}_{\beta}) = 0$$

if $\alpha \neq -\beta$.

Proof. This follows from the invariance of Ad. Namely let $X_{\alpha} \in \mathfrak{g}_{\alpha}$ and $X_{\beta} \in \mathfrak{g}_{\beta}$. Then:

$$\begin{aligned} 0 &= ([H, X_{\alpha}], X_{\beta}) + (X_{\alpha}, [H, X_{\beta}]) \\ &= (\alpha(H)X_{\alpha}, X_{\beta}) + (X_{\alpha}, \beta(H)X_{\beta}) \\ &= (\alpha(H) + \beta(H))(X_{\alpha}, X_{\beta}) \end{aligned}$$

for all $H \in \mathfrak{h}$. \square

By duality we can define a symmetric bilinear form on \mathfrak{h}^* as well: let $\alpha \in \mathfrak{h}^*$. Define its **dual element** h_α by the equality

$$(h_\alpha, H) = \alpha(H)$$

for all $H \in \mathfrak{h}$. To see that this is well-defined, choose an orthogonal basis $\{e_i\}$ for \mathfrak{h} and let $\{e_i^*\}$ be the dual basis (with respect to the form $(-, -)$). Then the vector h_α is just the transpose of the vector α .

We define

$$(\alpha, \beta) = (h_\alpha, h_\beta).$$

Lemma 21.5. *We have*

$$h_\alpha^* = h_{\bar{\alpha}}$$

for every $\alpha \in \mathfrak{h}^*$.

Proof. First off, note that by definition $(X^*, Y) = \overline{(X, Y^*)}$. Then

$$(h_\alpha^*, H) = \overline{(h_\alpha, H^*)} = \overline{\alpha(H^*)} = \overline{\overline{\alpha(H)}} = \alpha(H) = (h_\alpha, H).$$

Here we used the definition of $\bar{\alpha}$ as $\bar{\alpha}(H) = \overline{\alpha(H^*)}$. \square

It follows that if for $\alpha \in \mathfrak{h}$ satisfies $\bar{\alpha} = \alpha$, then $h_\alpha^* = h_\alpha$, which implies that $h_\alpha \in i\mathfrak{t}$. Since $(-, -)$ was negative definite on \mathfrak{g} , it follows that $(-, -)$ is positive definite on $i\mathfrak{t}$.

Now let $\alpha \in \Delta$ be a root. Then define

$$H_\alpha = \frac{2h_\alpha}{(\alpha, \alpha)} \in i\mathfrak{t} \subset \mathfrak{h}.$$

Lemma 21.6. *Let $\alpha \in \Delta$, and $X \in \mathfrak{g}_\alpha$. Then*

$$[X, X^*] = (X, X^*)h_\alpha.$$

Proof. We know already from Lemma (21.2) that $[X, X^*] \in \mathfrak{h}$. Let $\beta \in \mathfrak{h}^*$. Then

$$\begin{aligned} \beta([X, X^*]) &= (h_\beta, [X, X^*]) \\ &= -(h_\beta, [X^*, X]) \\ &= ([X^*, h_\beta], X) \\ &= (\alpha(h_\beta)X^*, X) = (X^*, X)\beta(h_\alpha). \end{aligned}$$

This holds for all $\beta \in \mathfrak{h}^*$, which implies the statement. \square

Choose a non-zero $E_\alpha \in \mathfrak{g}_\alpha$, and normalize it so that $(E_\alpha, E_\alpha^*) = \frac{2}{(\alpha, \alpha)}$. Then

$$[E_\alpha, E_\alpha^*] = H_\alpha.$$

Put $F_\alpha = E_\alpha^*$. We thus get

$$[H_\alpha, E_\alpha] = 2E_\alpha \quad [H_\alpha, F_\alpha] = -2F_\alpha \quad [E_\alpha, F_\alpha] = H_\alpha.$$

This defines a sub-Lie-algebra isomorphic to $\mathfrak{sl}_2(\mathbb{C})$. Thus for every $\alpha \in \Delta$ we get an inclusion of Lie algebras

$$i_\alpha : \mathfrak{sl}_2(\mathbb{C}) \rightarrow \mathfrak{g}_\mathbb{C}.$$

Lemma 21.7. *a) The spaces \mathfrak{g}_α are one-dimensional.*

b) Suppose $\alpha \in \Delta$ and $c \in \mathbb{R}^$ and $c\alpha \in \Delta$. Then $c = \pm 1$.*

Proof. We can suppose α to be minimal, in the sense that $c\alpha \notin \Delta$ if $c \in (0, 1)$. Now consider the space

$$V = \mathbb{C}F_\alpha \oplus \mathfrak{h} \oplus \left(\bigoplus_{c>0, c\alpha \in \Delta} \mathfrak{g}_{c\alpha} \right).$$

This is a finite-dimensional $\mathfrak{sl}_2(\mathbb{C})$ -module. But we know from [[previous lecture]] that their spectra are symmetric about the origin, counted with multiplicities. Hence the big term must be isomorphic with the left term, which is one-dimensional, and we must have $c = 1$. \square

Remark. *The isomorphism $\mathfrak{h}^* \simeq \mathfrak{h}$ depends upon the choice of invariant form, but the elements H_α ($\alpha \in \Delta$) does not depend upon this choice: H_α is the unique element of the one-dimensional space $[\mathfrak{g}_\alpha, \mathfrak{g}_{-\alpha}] \subseteq \mathfrak{h}$ such that $\alpha(H_\alpha) = 2$. Then $E_\alpha \in \mathfrak{g}_\alpha$ is defined up to scalar of modulus 1, such that $[E_\alpha, E_\alpha^*] = H_\alpha$.*

22 Root systems

In this lecture, we study root systems in the abstract.

Let V be a finite-dimensional Euclidean vector space (that is, a real vector space equipped with a scalar product). A finite subset $\Delta \subset V \setminus \{0\}$ is a **root system** if:

1. For every $\alpha \in \Delta$, the reflection s_α with respect to the hyperplane α^\perp leaves Δ invariant.

Note that

$$s_\alpha(v) = v - \frac{2(\alpha, v)}{(\alpha, \alpha)} \alpha.$$

2. The number

$$\frac{2(\alpha, \beta)}{(\alpha, \alpha)}$$

is an integer for all $\alpha, \beta \in \Delta$.

A root system is called **reduced**, if in addition the following condition is satisfied:

3. If $\alpha, c\alpha \in \Delta$, where $c \in \mathbb{R}^\times$, then we must have $c = \pm 1$.

Remark. Number 3. is often assumed to be part of the definition of a root system. It is also often assumed that Δ span the whole space V , but for us it will be important not to assume this.

Example 22.1. Here's an example of a root system. It is denoted by A_2 (and is associated with $SU(3)$). It is a regular hexagon.

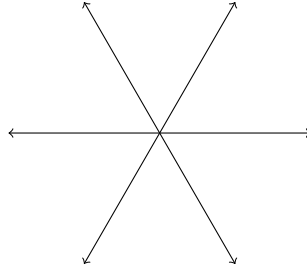


Figure 1: The root system A_2 .

To check the conditions, we can choose the vertices α_i to be given by $\alpha_i = (\cos \theta_i, \sin \theta_i)$ with $\theta_i = \frac{\pi}{3}i$ for $i = 0, \dots, 5$. Then we have that

$$(\cos \theta_i, \sin \theta_i) \cdot (\cos \theta_j, \sin \theta_j) = \cos(\theta_i - \theta_j) = \pm \frac{1}{2} \text{ or } \pm 1,$$

since $\theta_i - \theta_j$ is a multiple of $\pi/3$. In either case, the second condition is fulfilled. ★

We say that two root systems (V_1, Δ_1) and (V_2, Δ_2) are **isomorphic** if there exists a linear isomorphism $T : V_1 \rightarrow V_2$ such that $T(\Delta_1) = \Delta_2$ and $Ts_\alpha = s_{T(\alpha)}T$ for all $\alpha \in \Delta_1$. Note that we do not require the isomorphism to preserve the scalar product.

Theorem 22.2. *Let G be a compact connected Lie group and $T \subset G$ a maximal torus. Then (\mathfrak{t}^*, Δ) is a reduced root system. Up to isomorphism, this root system does not depend upon the choice of T and the choice of an invariant form on \mathfrak{g} .*

Proof. LONG PROOF HERE □

22.1 Simple roots, Weyl chambers, and the Weyl group

Let (V, Δ) be a root system and assume that $\text{Span} \Delta = V$. We say that a subset $\Pi \subset \Delta$ is a **system of simple roots** if (1) Π is a basis of V and (2) that if $\beta = \sum_{\alpha \in \Pi} c_\alpha \alpha \in \Delta$, then either all $c_\alpha \geq 0$ or all $c_\alpha \leq 0$.

Reflections s_α defined by simple roots are called **simple reflections**.

If we fix a set of simple roots Π , then the roots $\beta = \sum_{\alpha \in \Pi} c_\alpha \alpha \in \Delta$ with positive c_α are called **positive roots**. We denote the set of positive roots by Δ_+ . Thus $\Delta = \Delta_+ \cup -\Delta_+$.

It is a fact that every root system possesses systems of simple roots. In order to construct Π , we introduce the notion of a **Weyl chamber**: consider the set

$$V \setminus \bigcup_{\alpha \in \Delta} \alpha^\perp.$$

The connected components of this set are called the (open) *Weyl chambers* of Δ . Let C be such a Weyl chamber.

By definition, $(\alpha, \beta) \neq 0$ for all $\alpha \in \Delta$ and $\beta \in C$. Hence for any $\alpha \in \Delta$ we have either $(\alpha, \beta) > 0$ for all $\beta \in C$ or $(\alpha, \beta) < 0$ for all $\beta \in C$. In the first case, we say that α is **C -positive**. Let $\Pi(C) \subset \Delta$ be the set of C -positive roots α such that it is impossible to write α as $\beta + \gamma$ for C -positive roots $\beta, \gamma \in \Delta$.

Proposition 22.3. *The set $\Pi(C)$ is a system of simple roots. Furthermore, the assignment $C \mapsto \Pi(C)$ is a bijection between Weyl chambers and systems of simple roots.*

Proof. “quite long proof here” □

Given a Weyl chamber C , we say that a hyperplane $L \subset V$ is a **wall of C** if $L \cap \overline{C}$ has nonempty interior in L (in the subspace topology).

Here are some facts that were given as an exercise:

- For all $\alpha \in \Delta$, the hyperplane α^\perp is a wall of some Weyl chamber.
- For any Weyl chamber C , the walls of C are the hyperplanes α^\perp with $\alpha \in \Pi(C)$.
- This implies that any $\alpha \in \Delta$ lies in $\Pi(C)$ for some Weyl chamber C .

By definition, the **Weyl group** W of (V, Δ) is the subgroup of $O(V)$ generated by the reflections s_α for $\alpha \in \Delta$.

Since the reflections preserve the root system (which is a finite set), the Weyl group is itself finite. Note also that since the Weyl group act on the set of hyperplanes α^\perp for $\alpha \in \Delta$, it also act on the set C of Weyl chambers.

Theorem 22.4. *We have:*

1. W acts freely and transitively on the set of Weyl chambers.
2. For any Weyl chamber C , W is generated by the reflections s_α for $\alpha \in \Pi(C)$.

Half-proof: Let C be a Weyl chamber and let C' be an adjacent Weyl chamber, meaning that there exists a hyperplane L such that $L \cap \overline{C} \cap \overline{C}'$ has nonempty interior in L .

Then $L = \alpha^\perp$ for some $\alpha \in \Pi(C)$ and $C' = s_\alpha(C)$. Then $s_\alpha(\Pi(C)) = \Pi(C')$.

It follows that for any $\beta' = s_\alpha(\beta) \in \Pi(C')$ (with $\beta \in \Pi(C)$), we have

$$s_{\beta'} = s_{s_\alpha(\beta)} = s_\alpha s_\beta s_\alpha,$$

since for any orthogonal transformation we have $s_{T\alpha} = T s_\alpha T^{-1}$.

Thus reflections $s_{\beta'}$ for $\beta' \in \Pi(C')$ lie in the group generated by s_α , $\alpha \in \Pi(C)$.

Now, for any Weyl chamber C'' we can find a sequence of adjacent Weyl chambers $C = C_0, \dots, C_n = C''$. Using the above argument and induction on n , we conclude that there exists $w \in W$ such that $w(C) = C''$ and the reflections $s_{\beta''}$ for $\beta'' \in \Pi(C'')$ lie in the group generated by s_α for $\alpha \in \Pi(C)$.

As any root in Δ lies in some $\Pi(C'')$, we see that W is generated by s_α , $\alpha \in \Delta$.

This proves that the action of W on the set of Weyl chambers is transitive. We will not prove nor need the fact that the action is free. For root spaces coming from compact groups, this will follow from the proof of the next result. \square

Example 22.5. Again consider the root system A_2 . One computes that the Weyl chambers are the interiors of the rays generated by $(\cos(\frac{\pi}{6} + \frac{\pi}{3}k), \sin(\frac{\pi}{6} + \frac{\pi}{3}k))$ and $(\cos(\frac{\pi}{6} + \frac{\pi}{3}(k+1)), \sin(\frac{\pi}{6} + \frac{\pi}{3}(k+1)))$ for $k = 0, \dots, 5$.

Let C be the Weyl chamber generated by the first two rays. Then one computes that there are three C -positive roots: $\alpha_1, \alpha_2, \alpha_3$ (the first one of angle zero, next of angle 60° , and last of angle 120°). But $\alpha_2 = \alpha_1 + \alpha_3$, so we discard it. Thus the C -simple roots of A_2 are α_1 and α_3 .

We see that the Weyl group is the group D_6 of symmetries preserving the hexagon. ★

22.2 Root systems of compact Lie groups

Assume now that G is a compact connected Lie group and $T \subset G$ a maximal torus. Consider the corresponding root system Δ on $V = \mathfrak{t}^* \subset \mathfrak{h}^*$.

Let $V_0 = \text{Span}_{\mathbb{R}} \Delta$. Then for any $\alpha \in \Delta$, the reflection s_α act trivially on V_0^\perp . It follows that the group generated by s_α ($\alpha \in \Delta$) can be identified with the Weyl group W generated by $s_\alpha|_{V_0}$.

We have a homomorphism

$$r: N(T)/T \rightarrow O(V)$$

defined by $r(gT)(\alpha)\alpha \circ (\text{Ad } g^{-1})$.

Theorem 22.6. *The homomorphism r defines an isomorphism*

$$N(T)/T \simeq W,$$

so that the two definitions of the Weyl group are equivalent.

A Exercises

A.1 Lecture 1

Exercise 2. Suppose $V_1 \oplus \dots \oplus V_r \sim W_1 \oplus \dots \oplus W_s$ as representations and that the V_i, W_i are irreducible. Show that $n = m$ and there exists $\rho \in S_r$ such that $V_i \sim W_{\rho(i)}$ for all i . ♠

Solution 1. First note a lemma: If $V \oplus W \sim V' \oplus W'$ and $V \sim V'$, then $W \sim W'$. This follows from the five-lemma.

Now consider the composition $V_1 \hookrightarrow V_1 \oplus \dots \oplus V_r \rightarrow W_1 \oplus \dots \oplus W_s \rightarrow W_i$. This has to be non-zero for at least one i . Hence $V_1 \sim W_i$ for some i . By rearranging, we are in the situation of the lemma above. Hence, inductively, if $r \leq s$, we find $0 \sim W_{r+1} \oplus \dots \oplus W_s$, which is impossible. Similarly for $s \leq r$. Hence $r = s$ and we conclude. ♥

Exercise 3. Let \hat{G} denote the Pontryagin dual of G . Then, for any finite abelian group G , we have $G \simeq \hat{\hat{G}}$. ♠

Solution 2. We first do this when $G = \mathbb{Z}/n$ for some $n \geq 0$. Let $\varphi : \mathbb{Z}/n \rightarrow \mathbb{C}^*$ be a character. Then $\phi(1) = z$ for some z , but $\phi(n) = \phi(0) = z^n = 1$, so z must be a n 'th root of unity.

Realize \mathbb{Z}/n as the n th roots of unity. Then we can define a homomorphism $\widehat{\mathbb{Z}/n} \rightarrow \mathbb{Z}/n$ by $\varphi \mapsto \varphi(1)$. Similarly, we can define an inverse map by sending $e^{2\pi i/n}$ to the character $m \mapsto e^{2\pi i m/n}$. These are inverses.

Now, every finite abelian group is a product of these groups. So it remains to show (by induction) that if G, H are two finite abelian groups, then $\widehat{G \times H} \simeq \hat{G} \times \hat{H}$. The inclusion maps $G \rightarrow G \times H$ and $H \rightarrow G \times H$ induces a map $\hat{G} \times \hat{H} \rightarrow \widehat{G \times H}$ by $(\varphi_1, \varphi_2) \mapsto ((g, h) \mapsto \varphi_1(g)\varphi_2(h))$.

It is easy to see that this map is injective. To see that it is surjective, let $\varphi : G \times H \rightarrow \mathbb{C}$ be a character. Write φ as $gh \mapsto \varphi(gh)$. Then we can define characters on G, H by $g \mapsto \varphi(g \cdot 1)$ which maps to φ . Ok. ♥

A.2 Exercises 3

Exercise 4. Show that the S defined in the proof of Theorem (2.1) lies in $\Theta(G)''$. ♠

Solution 3. This is, I think, definition-hunting. DETAILS COME LATER ♥

Exercise 5. 1. Check that indeed

$$\langle v, w \rangle := \frac{1}{|G|} \sum_{g \in G} \langle \pi(g)v, \pi(g)w \rangle'$$

is an invariant Hermitian scalar product.

2. Show that if π is irreducible, then an invariant scalar product is unique up to a factor.



Solution 4. i). Invariant means that $\langle \pi(h)v, \pi(h)w \rangle = \langle v, w \rangle$. This is clear from the definitions, since if $g \in G$ ranges over all of G , then so does gh .

The only (slightly) nontrivial thing to check is that \langle, \rangle is positive definite. But this is so.

ii) If \langle, \rangle is invariant, then it is an element of $\text{Hom}_G(V \otimes V, \mathbb{C})$. This is canonically isomorphic to $\text{Hom}_G(V \otimes, V^*)$. If we can show that V and V^* are isomorphic as representations, then we are done by Schur's lemma.

But we are given an inner product \langle, \rangle . We can define a map $V \rightarrow V^*$ by sending $v \in V$ to the function $w \mapsto \langle v, w \rangle$. This is clearly a linear isomorphism, and it is also a map of representations. Recall that the action of G on V^* is defined by $\pi^*(g)\varphi(v) = \varphi(g^{-1}v)$. Then in the diagram

$$\begin{array}{ccc} V & \longrightarrow & V^* \\ \downarrow \cdot g & & \downarrow \cdot g \\ V & \longrightarrow & V^* \end{array}$$

we want $\langle gv, w \rangle$ to be equal to $\langle v, g^{-1}w \rangle$. But this is true since \langle, \rangle is invariant:

$$\langle gv, w \rangle = \langle gvgg^{-1}w \rangle = \langle v, g^{-1}w \rangle.$$

Hence V and V^* are isomorphic as representations and then $\text{Hom}_G(V, V^*)$ (space of bilinear forms) is one-dimensional. ♡

Exercise 6. Let (V, π) be an irreducible representation and (W, θ) a finite-dimensional representation. Let $W(\pi)$ be the isotypic component corresponding to π .

1. Show that the operator

$$P = \frac{\dim \pi}{|G|} \sum_{g \in G} \chi_\pi(g^{-1}) \theta(g)$$

on W is the projection onto $W(\pi)$ along $\sum_{\pi' \neq \pi} W(\pi')$. In particular:

$$W = \bigoplus_{[\pi] \in \hat{G}} W(\pi).$$

2. Show that $\theta|_{W(\pi)} \sim \pi^{n_\pi}$ where $n_\pi = \dim \text{Mor}(\pi, \theta)$.

Solution 5. dddd



A.3 Lecture 4

- Exercise 7.**
1. $\pi^{cc} = \pi$.
 2. $(\pi \otimes \theta)^c = \pi^c \otimes \theta^c$.
 3. π is irreducible if and only if π^c is.



A.4 Exercises 5

Exercise 8 (Exercise 1). Show that the ring \mathbb{Z} is integrally closed. ♠

Solution 6. Let $x = p/q \in \mathbb{Q}$ and suppose that we have an equation of integral dependence:

$$x^n + b_1 x^{n-1} + \dots + b_n = 0$$

with $b_i \in \mathbb{Z}$. We can suppose that p and q have no common factor. Multiply by q^n on both sides to get

$$p^n + b_1 q p^{n-1} + \dots + b_n q^n = 0.$$

Looking modulo q we see that $q \mid p^n$, which to avoid contradiction, must imply that $q = \pm 1$, hence $x \in \mathbb{Z}$. ♡

Exercise 9 (Exercise 2). Suppose R is a unital commutative ring and $S \subset R$ a subring with $1 \in S$. Show that the set of elements of R integral over S form a subring of R . ♠

Solution 7. Note that x is integral over S if and only if $S[x]$ is a finitely generated S -module. Hence if x and y are integral over S , it follows that $S[x] \otimes_S S[y] = S[x, y]$ is a finitely generated S -module. Hence $x \pm y$ and xy are integral over S . ♡

A.5 Exercises 11

A.6 Lecture 13

Exercise 10. Let $G = \mathrm{GL}_n(\mathbb{C})$. Show that $\exp : \mathfrak{g} \rightarrow G$ is surjective. Show also that it is not open. ♠

Solution 8. Note that for matrix groups, the exponential is given by

$$\exp(A) = I + A + \frac{1}{2}A^2 + \frac{1}{6}A^3 + \dots + \frac{1}{n!}A^n + \dots$$

Also note that

$$\exp(P^{-1}AP) = P^{-1}\exp(A)P$$

for invertible matrices $P \in \mathrm{GL}_n(\mathbb{C}) \subset \mathfrak{g} = \mathrm{End}(\mathbb{C}^n)$. Thus, if A is diagonalizable with eigenvalues λ_i , the matrix $P^{-1}\mathrm{diag}(\log \lambda_1, \dots, \log \lambda_n)P$ (with P diagonalizing A) is mapped to A . Here \log is of course the complex logarithm (which is multi-valued, so choose one value for each).

Now if A is not diagonalizable, the matrix $A + \epsilon I$ is invertible and diagonalizable for generic ϵ . Thus we can find a sequence A_n with all A_n diagonalizable and $A_n \rightarrow A$ with corresponding B_n with $\exp(B_n) = A_n$. I claim that the B_n can be chosen such that $\{B_n\}$ is a convergent sequence. This is because the eigenvalues of A_n are continuous with respect to ϵ , and as $\log : \mathbb{C}^* \rightarrow \mathbb{C}$ is continuous, we can choose the logs of close eigenvalues to be close. Thus we get a convergent sequence $B_n \rightarrow B$, and by continuity of \exp , $\exp(B) = A$.

Now we explain why \exp is not open. [[[HOW???\]]] ♡

A.7 Exercises 13

Exercise 11 (Exercise 1). Let G be a group that is also a compact space (that is, a compact Hausdorff topological space) such that the multiplication map $\mu : G \times G \rightarrow G$ is continuous. Show that G is a compact group, that is, that the inverse map $\iota : G \rightarrow G$ is continuous as well. ♠

Solution 9. Let $U \subset G$. Then

$$\begin{aligned}\iota^{-1}(U) &= \{g \in G \mid \iota(g) \in U\} \\ &= \{g \in G \mid g^{-1} \in U\} \\ &= \{g \in G \mid e \in gU\}\end{aligned}$$

[[[[[[[something about bijection between compact spaces is a homeomorphism]]]]]]] ♡

Exercise 12. 1. Find a Haar measure on $\mathrm{GL}_2(\mathbb{R})$ and check that this group is unimodular⁵.

2. Find left- and right-invariant Haar measures on the $ax + b$ group over \mathbb{R} , and check that this group is not unimodular. ♠

Solution 10. For the first part, we start with the usual measure on \mathbb{R}^4 , and see what happens when we translate by an element of $\mathrm{GL}_2(\mathbb{R})$.

We assume the Haar measure has the following form, for some yet unknown function f .

$$\mu(S) = \int_S f(A) |da_{11} da_{12} da_{21} da_{22}|.$$

⁵Recall that this means that the left and right invariant Haar measures coincide

Now consider the same formula on the set gS . Then the change of variable formula tells us that

$$\mu(gS) = \int_S f(gS) |\det D(g)| |da_{11} da_{12} da_{21} da_{22}|.$$

where $\det D(g)$ is the Jacobian matrix of the map $A \mapsto gA$. A computation shows that this map is row-equivalent to a block diagonal matrix with two copies of g . Thus $\det D(g) = (\det g)^2$. Hence a left-invariant Haar measure on $\mathrm{GL}_2(\mathbb{R})$ is given by

$$\mu(S) = \int_S \frac{1}{|\det A|^2} dA.$$

The same computation with $g \mapsto Ag$ gives the same result. Hence $\mathrm{GL}_2(\mathbb{R})$ is unimodular.

ii). For the second part, note that the $ax + b$ -group is topologically $\mathbb{R} \times \mathbb{R}^*$, so that we can use the measure $dx dy$ here. Then a similar computation gives that a left-invariant Haar measure is given by

$$\mu(S) = \int_S \frac{1}{a^2} da db$$

and a right-invariant Haar measure is given by

$$\mu(S) = \int_S \frac{1}{a} da db.$$

♡

A.8 Exercises 16

Exercise 13 (Exc 2). Let G be a topological group and $\Gamma \subset G$ a discrete normal subgroup. Show that $\Gamma \subset Z(G)$. ♠

Solution 11. Since $\Gamma \subset G$ is normal, we have that $h^{-1}gh \in \Gamma$ for all $g \in G$. So we get a continuous map $c : G \rightarrow \Gamma$ given by conjugation. But a continuous map from a connected topological space to a discrete space must be constant (let $\{g_1, g_2\} \subset c(G)$, which is open (in the discrete topology), hence $c^{-1}(\{g_1, g_2\})$ is open, which is only possible if the inverse image is \emptyset or all of G).

Since c is constant it must be constantly equal to e , since $c(e) = e$. ♡

A.9 Exercises 18

Exercise 14 (Exc 2). Let $\pi : G \rightarrow \mathrm{GL}(V)$ and $\eta : G \rightarrow \mathrm{GL}(W)$ be two finite-dimensional representations of a Lie group G . Show that

$$(\pi \otimes \eta)_*(X) = \pi_*(X) \otimes 1 + 1 \otimes \eta_*(X)$$

for all $X \in \mathfrak{g}$. ♠

Solution 12. We have that $\text{GL}(V \otimes W)$ is an open subset of $\text{End}(V \otimes W)$, so that we may use the additive structure when computing the derivative.

Thus, let $\gamma : \mathbb{R} \rightarrow \text{GL}(V \otimes W)$ be a continuous curve with $\gamma(0) = e$ and $\gamma'(0) = X$. Then

$$\begin{aligned}\pi_*(\pi \otimes \eta)(X) &= \frac{\partial}{\partial t}(\pi(\gamma(t)) \otimes \eta(\gamma(t))) \big|_{t=0} \\ &= \lim_{t \rightarrow 0} \frac{1}{t} (\pi(\gamma(t)) \otimes \eta(\gamma(t)) - \pi(\gamma(0)) \otimes \eta(\gamma(0))) \\ &= 1 \otimes X + X \otimes 1\end{aligned}$$

by the usual proof of the product rule. ♡

A.10 Exercises 19

Exercise 15 (Exercise 3). Let G be a closed subgroup of $U(n)$. Verify that the formula

$$\langle X, Y \rangle = -\text{Tr}(XY)$$

defines an Ad-invariant scalar product on $\mathfrak{g} \subset \mathfrak{u}(n)$. ♠

Solution 13. We first verify that the formula defines a scalar product. It is clearly symmetric and bilinear. We only need to check that it is positive definite. Note that every $X \in \mathfrak{g}$ satisfies $X = -X^*$. Hence $\langle X, X \rangle = -\text{Tr}(XX) = -\text{Tr}(-X^*X) = \text{Tr}(XX^*)$. An easy computation shows that the i th diagonal entry of XX^* is the sum of the moduli of the elements in the i th row of X . Hence $\text{tr}(XX^*)$ is the sum of the lengths of all the entries in X (with certain repetitions). But this is zero if and only if $X = 0$. Hence $\langle X, Y \rangle$ is positive definite.

Recall the adjoint action of G on \mathfrak{g} , given by $g \cdot X = gXg^{-1}$. Being Ad-invariant means that $\langle g \cdot X, g \cdot Y \rangle = \langle X, Y \rangle$ for all $X, Y \in \mathfrak{g}$. But the action on the Lie algebra is given by conjugating, and we have

$$\langle g \cdot X, g \cdot Y \rangle = \langle gXg^{-1}, gYg^{-1} \rangle = -\text{Tr}(gXg^{-1}gYg^{-1}) = -\text{Tr}(gXYg^{-1}) = -\text{tr}(XY).$$

And we are done. ♡

B Some worked examples

B.1 The representation ring of S_3

We want to explicitly compute the representation ring of S_3 .

First we find all irreducible representations. The first one is the trivial representation $\epsilon : S_3 \rightarrow \mathbb{C}$. We also have the *sign* representation given by $g \mapsto \text{sgn}(g) \in \mathbb{C}$. Both of these are one-dimensional representations.

S_3 have a natural action on \mathbb{R}^3 given by permuting the basis vectors. But it acts trivially on the subspace spanned by $e_1 + e_2 + e_3$, hence \mathbb{R}^3 decomposes as $\epsilon \oplus V$, where V is some 2-dimensional representation. It is irreducible: if not, any $v \in V$ would be sent to a scalar multiple of itself, but this is not the case. This representation is called the **standard representation** of S_3 . We have also now found all representations of S_3 , since $1^2 + 1^2 + 2^2 = 6$.

Thus the representation ring $R(S_3)$ is $\mathbb{Z}[A, S]$ modulo some relations to be found. Here A is the alternating representation and S is the standard representation. The trivial representation is 1. It is easy to see that $A \otimes A \sim \epsilon$, so $A^2 = 1 \in R(S_3)$. The representation $S \otimes S$ is 4-dimensional. To compute how it decomposes, we use character theory.

Recall that characters are class functions on G , that is, they only depend on the conjugacy classes of G . So we write a character table:

	e	τ	σ
ϵ	1	1	1
A	1	1	-1
S	2	-1	0

To compute the character of the standard representation, we first note that it is, as a vector space given by $\mathbb{R}^3/(1,1,1)$. A basis is then given by the images of e_1, e_2 . Let τ be the transposition (123), sending e_i to e_{i+1} . Let σ be reflection fixing e_1 and exchanging e_2 and e_3 . In this basis that means e_2 is sent to $-e_1 - e_2$. Writing up the corresponding matrices lets us find the value of the character.

Now one can compute by hand (or use a result on characters), that the character of $S \otimes S$ is given by $\chi_S \cdot \chi_S$, so that its entry in the character table is (4, 1, 0). If $S \otimes S = V_1 \oplus V_2$, then $\chi_S = \chi_{V_1} + \chi_{V_2}$. Using also that the characters are linearly independent, we see that the only option is $S \otimes S \sim \epsilon \oplus A \oplus S$.

Hence $S^2 = 1 + A + S$ in the representation ring. Similarly, we find that $AS = S$ in the representation ring. All in all

$$R(S_3) = \mathbb{Z}[A, S]/(A^2 - 1, S^2 - 1 - A - S, AS - S).$$

B.2 Explicit Specht modules

Again, we work with $G = S_3$. Consider the following Young-diagram:

$$T = \begin{array}{|c|c|} \hline 1 & 2 \\ \hline 3 & \\ \hline \end{array}$$

We want to use the theorem from Lecture 5 (?) to find the standard representation of S_3 . The elements of S_3 are generated by $\rho = (123)$ and $s = (23)$ with the relations $\rho^3 = e$ and $s\rho s = \rho^2$.

First off, the elements permuting the rows is the subgroup consisting of e and $(12) = s\rho^2$. The elements permuting the columns is the subgroup generated by $(13) = s\rho$. Then

$$a_T = \frac{1}{2}(e + (12))$$

and

$$b_T = \frac{1}{2}(e + (13)).$$

Thus

$$c_T = \frac{1}{4}(e - (13) + (12) - (132)).$$

This gives us as in the lecture a map

$$\mathbb{C}[S_3] \rightarrow V \subseteq \mathbb{C}[S_3]$$

given by $g \mapsto gc_T$, whose image is supposed to be an irreducible representation of S_3 . Let's find this. One computes the action of c_T on the basis elements of $\mathbb{C}[S_3]$ by direct computation:

$$\begin{aligned} c_T &= \frac{1}{4}(e - s\rho + s\rho^2 - \rho^2) \\ \rho c_T &= \frac{1}{4}(\rho - s + s\rho - e) \\ \rho^2 c_T &= \frac{1}{4}(\rho^2 - s\rho^2 + s - \rho) \\ s c_T &= \frac{1}{4}(s - \rho + \rho^2 - s\rho^2) \\ s\rho c_T &= \frac{1}{4}(s\rho - e + \rho - s) \\ s\rho^2 c_T &= \frac{1}{4}(s\rho^2 - \rho^2 + e - s\rho) \end{aligned}$$

We claim that c_T and ρc_T span the image. For we have $\rho^2 c_T = -c_T - \rho c_T$. And $s c_T = \rho^2 c_T$. And $s\rho c_T = \rho c_T$. And $s\rho^2 c_T = c_T$.

Thus we have some 2-dimensional representation of S_3 with basis $c_T, \rho c_T$. We compute the matrices of S_3 with respect to this basis:

$$\begin{aligned} e &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} & \rho &= \begin{pmatrix} 0 & -1 \\ 1 & -1 \end{pmatrix} & \rho^2 &= \begin{pmatrix} -1 & 1 \\ -1 & 0 \end{pmatrix} \\ s &= \begin{pmatrix} -1 & 0 \\ -1 & 1 \end{pmatrix} & s\rho &= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} & s\rho^2 &= \begin{pmatrix} 1 & -1 \\ 0 & -1 \end{pmatrix}. \end{aligned}$$

As expected, the character of this representation is exactly the character of the standard representation from the previous example (as is seen by computing traces). This is no coincidence.