

# Adjoint representation

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Let  $G$  be a Lie group. For  $g \in G$  consider the automorphism

into  $g h g^{-1}$  of  $G$ .

Its differential at  $e$  is denoted by  $\text{Ad}_g$  or  $\text{Ad}_g$ . This way we get a homomorphism

$$\text{Ad}: G \rightarrow \text{GL}(\mathfrak{g})$$

called the adjoint representation.

The differential of  $\text{Ad}$  at  $e$  gives a Lie algebra homomorphism

$$\text{ad}: \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{g}),$$

also called the adjoint representation. Let's compute  $\text{ad}$  more explicitly.

Take  $X, Y \in \mathfrak{g}$ . Then by def  $(\text{ad } X)(Y) = \left. \frac{d}{dt} (\text{Ad} \exp(tX))(Y) \right|_{t=0}$

Take  $f \in C^\infty(G)$ . Then

$$(d_e f)(\text{ad}(X)(Y)) = \left. \frac{d}{dt} (d_e f) (\text{Ad} \exp(tX)(Y)) \right|_{t=0}$$

$$= \left. \frac{\partial^2}{\partial t \partial s} (f(\exp(tX) \exp(sY) \exp(-tX))) \right|_{s=t=0}$$

chain rule

$$= \left. \frac{\partial^2}{\partial s \partial t} (f(\exp(tX) \exp(sY) - f(\exp(sY) \exp(tX))) \right|_{s=t=0}$$

$$= (d_e f)([X, Y])$$

$$\text{Therefore } (\text{ad } X)(Y) = [X, Y].$$

of course the adjoint rep.  $\text{ad}: \mathfrak{g} \rightarrow \mathfrak{gl}(\mathfrak{g})$ ,  $\text{ad}(X)(Y) = [X, Y]$  is well-defined for any Lie algebra  $\mathfrak{g}$ . Note that the identity

(2)

$$\begin{aligned} \text{ad}[X, Y] &= [\text{ad}(X), \text{ad}(Y)] \\ &= \text{ad}(X)\text{ad}(Y) - \text{ad}(Y)\text{ad}(X) \end{aligned}$$

is exactly the Jacobi identity.

The kernel of  $\text{ad}$  is the center of  $\mathfrak{g}$ :

$$Z(\mathfrak{g}) = \{X \mid [X, Y] = 0 \ \forall Y \in \mathfrak{g}\}$$

We say that  $X, Y$  commute if  $[X, Y] = 0$

Prop Let  $G$  be a Lie group,  $X, Y \in \mathfrak{g}$ . TFAE

①  $[X, Y] = 0$

②  $\exp(tX)\exp(sY) = \exp(sY)\exp(tX) \quad \forall s, t \in \mathbb{R}$

Furthermore, if these conditions are satisfied then

$$\exp(X+Y) = \exp(X)\exp(Y)$$

pf  $\exp(tX)\exp(sY)\exp(-tX) \stackrel{\text{function}}{=} \exp(\text{Ad}(\exp(tX))(sY))$

$$= \exp(s e^{\text{ad} X} Y)$$

$\begin{array}{ccc} \text{used } G & \xrightarrow{\text{Ad}} & \mathfrak{gl}(\mathfrak{g}) \\ \text{exp} \uparrow & & \uparrow \text{exp} \\ \mathfrak{g} & \xrightarrow{\text{ad}} & \mathfrak{g} \end{array}$

$\begin{array}{ccc} G & \xrightarrow{\text{Ad}(s)} & G \\ \text{exp} \uparrow & & \uparrow \text{exp} \\ \mathfrak{g} & \xrightarrow{\text{ad}_g} & \mathfrak{g} \end{array}$

Issue ① holds, so  $(\text{ad} X)(Y) = 0$ , and hence

$$e^{\text{ad} X} Y = Y \text{ and } \exp(tX)\exp(sY)\exp(-tX) = \exp(sY) \quad \checkmark$$

Now assume ②. Then

$$\exp(s e^{\text{ad} X} Y) = \exp(s Y) \quad \forall s.$$

Applying  $\frac{d}{ds} \Big|_{s=0}$  we get  $e^{\text{ad} X} Y = Y$ . Applying  $\frac{d}{dt} \Big|_{t=0}$

we get  $\text{ad}(X)(Y) = 0$ .

Finally, if ① and ② hold, then

$$t \mapsto \exp(tX) \exp(tY)$$

is a 1-parameter subgroup of  $G$ . Hence  $\exp(tX) \exp(tY) = \exp(tZ)$  for some  $Z \in \mathfrak{g}$ . Applying  $\frac{d}{dt} \Big|_{t=0}$  we get  $X+Y=Z$ . □

Remark This also follows from the general fact that v-fields  $X|_U$ , on a manifold  $M$  commute iff the corresponding global flows (if defined) commute.

Prop Any connected abelian Lie group  $G$  is isomorphic to  $\mathbb{R}^k \times \mathbb{T}^l$  for some  $k, l \geq 0$ .

Pf Consider  $\mathfrak{g}$  as a Lie group under addition. By the previous result,  $\exp: \mathfrak{g} \rightarrow G$  is a Lie group homomorphism. Since the exponential map is  $\text{pd}$ . As  $d_0 \exp = \text{id}$ ,  $\exp: \mathfrak{g} \rightarrow G$  is a covering map. Hence  $\ker \exp$  is a discrete subgroup  $\Gamma \subset \mathfrak{g}$  and  $G \cong \mathfrak{g} / \Gamma$  as Lie groups, where on  $\mathfrak{g} / \Gamma$  we endow the smooth structure making  $\mathfrak{g} \rightarrow \mathfrak{g} / \Gamma$  a local diffeomorphism.

Ex Assume  $\Gamma \ni$  a discrete subgroup of  $V \subset \mathbb{R}^d$ . Then  $\exists$   
a basis  $e_1, \dots, e_l$  and  $l \leq d$  s.t.

$$\Gamma = \mathbb{Z}e_1 + \dots + \mathbb{Z}e_l$$

to follow that  $\mathbb{R}^d / \Gamma \cong \mathbb{R}^l / \mathbb{Z}^l \times \mathbb{R}^{d-l} = \mathbb{T}^l \times \mathbb{R}^{d-l}$ .

□

Structure and repr. theory of  $SU(2) = \{ A \in \mathbb{C}^{2 \times 2} \mid AA^* = I \}$

Recall that the Lie algebra of  $SU(2)$  is

$$\mathfrak{su}(2) = \{ X \in \mathfrak{gl}_2(\mathbb{C}) \mid X^* + X = 0, \text{Tr } X = 0 \}$$

The complex span spanned by  $\mathfrak{su}(2)$  in  $\mathfrak{gl}_2(\mathbb{C})$

is  $\mathfrak{sl}_2(\mathbb{C}) = \{ X \in \mathfrak{gl}_2(\mathbb{C}) \mid \text{Tr } X = 0 \}$

We define a basis in  $\mathfrak{sl}_2(\mathbb{C})$  by

$$E = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \quad F = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \quad H = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Then  $\{E, F, H\}$  is a basis in  $\mathfrak{su}(2)$  (over  $\mathbb{R}$ ) we can take

$$E - F, \quad i(E + F), \quad iH \quad \text{as a basis of } \mathfrak{su}(2).$$



Note that  $\mathbb{R}iI \subset su(2)$  is the Lie algebra of the torus  $T = \left\{ \begin{pmatrix} z & 0 \\ 0 & \bar{z} \end{pmatrix} \mid z \in \mathbb{C} \right\} \subset SU(2)$ .

The Lie algebra structure on  $sl_2(\mathbb{C})$  is described by the rules

$$[H, E] = 2E \quad [H, F] = -2F \quad [E, F] = H$$

We know that  $SU(2)$  is simply connected. In fact,  $SU(2)$

$$SU(2) = \left\{ \begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix} \mid \alpha, \beta \in \mathbb{C} \right. \\ \left. |\alpha|^2 + |\beta|^2 = 1 \right\}$$

So as a manifold,  $SU(2) \cong S^3$ , which has  $\pi_1 = 0$ .

Therefore, we have a 1-1 correspondence between the group homomorphisms  $SU(2) \rightarrow GL(V)$  and the Lie algebra homomorphisms

$$su(2) \rightarrow gl(V).$$

For a Lie algebra  $\mathfrak{g}$ , by a representation of  $\mathfrak{g}$  on  $V$  we mean a Lie algebra homomorphism  $\mathfrak{g} \rightarrow gl(V)$ . In this case we also say that  $V$  is a  $\mathfrak{g}$ -module.

A subspace  $W \subset V$  is called  $\mathfrak{g}$ -invariant if  $xW \subset W \quad \forall x \in \mathfrak{g}$ .

A representation  $\mathfrak{g} \rightarrow gl(V)$  is called reducible, or the  $\mathfrak{g}$ -module  $V$  is simple if there are no proper invariant subspaces.

Exc Assume  $\pi: G \rightarrow GL(V)$  is a repr. of a connected Lie grp  $G$  on a f.d. vector space  $V$ . Then a subspace  $W \subset V$  is  $G$ -invariant  $\iff$  it is  $\mathfrak{g}$ -invariant. In particular,  $\pi$  is irreducible  $\iff \pi_{\mathfrak{g}}$  is irreducible.

We want to classify irreducible reps of  $SU(2)$  on complex f.d. vector spaces. Equivalently, we want to classify irreps of  $\mathfrak{su}(2)$  on complex f.d. vector spaces.

$$\hookrightarrow \left( \begin{array}{c} \mathbb{C} \\ \otimes \\ \mathbb{R} \end{array} \right) \mathfrak{su}(2) \simeq \mathfrak{sl}_2(\mathbb{C}), \text{ as Lie algebras}$$

$$\lambda \otimes X \mapsto \lambda X.$$

Isomorphism  $\mathfrak{su}(2) \rightarrow \mathfrak{gl}(V)$  ( $V$  complex!) extends uniquely to an isomorphism  $\mathfrak{sl}_2(\mathbb{C}) \rightarrow \mathfrak{gl}(V)$  of complex Lie algebras.

Thus we want to understand irreps of  $\mathfrak{sl}_2(\mathbb{C})$  as a complex Lie algebra.

Assume  $V$  is a f.d.  $\mathfrak{sl}_2(\mathbb{C})$ -module. Since it integrates to a representation of  $SU(2)$  on  $V$ , the space  $V$  decomposes into a sum of one-dim spaces invariant under  $T = \left\{ \begin{pmatrix} z & 0 \\ 0 & \bar{z} \end{pmatrix} \mid |z|=1 \right\}$   
"maximal torus"  $\cap$   
 $SU(2)$

This means that the operator  $H$  on  $V$  is diagonalizable, and as  $e^{2\pi i H} = 1$  in  $SU(2)$ , all its eigenvalues are integers.

It is common to index the eigenvalues of  $H$  on  $V$  by half-integers. Thus for  $s \in \frac{1}{2}\mathbb{Z}$  we put

$$V(s) = \left\{ \zeta \in V \mid H\zeta = 2s\zeta \right\}.$$

Elements of  $V(s)$  are called vectors of weight  $s$ . This

$$V = \bigoplus_{s \in \frac{1}{2}\mathbb{Z}} V(s)$$

Recall that  $[H, E] = 2E$ ,  $[H, F] = -2F$ . This implies that

$$E V(s) \subset V(s+1) \quad F V(s) \subset V(s-1).$$

Indeed, if  $\zeta \in V(s)$ , then  $H E \zeta = (H E - E H) \zeta + E H \zeta$

$$= [H, E] \zeta + E H \zeta$$

$$= 2E \zeta + 2s E \zeta$$

$$= 2(s+1) E \zeta.$$

The second inclusion is similar.

In particular, if  $\zeta$  is a nonzero vector of highest weight, then  $E \zeta = 0$ .

Lemma Assume  $V$  is a fin. dim  $\mathfrak{sl}_2(\mathbb{C})$ -module,  $\zeta \in V(s) \setminus \{0\}$ , w/  $E \zeta = 0$ . Then

- ①  $s \geq 0$
- ②  $F^{2s+1} \zeta = 0$  and  $F^k \zeta \neq 0$  for  $k=0, \dots, 2s$
- ③  $E F^k \zeta = (2s-k+1)_k F^{k-1} \zeta$ .

