

(1)

III. Rep. th. of compact Lie groups

Def A Lie group is a grp G which is also a smooth manifold s.t. $G \times G \xrightarrow{\text{smooth}} G$ and $G \xrightarrow{\text{smooth}}$ are smooth maps. (Smooth = C^∞)

Ex i) Let V be a fin dim. be a fin dim. real v.spc. Then $GL(V)$ is a Lie Group.

Smooth structure inherited from $End(V)$.

ii) $(\mathbb{R}^n, +)$, $(\mathbb{C}^n, +)$

First develop some general results on Lie groups. Later discuss how to write down the group.

Exponential map

Let M be a smooth manifold, p.m. The tangent space $T_p M$ can be equivalently defined as

- Equivalence classes of smooth curves passing through p
 $\gamma_i : (a_i, b_i) \rightarrow M, a_i < 0 < b_i, \gamma_i(0) = p$
 $\gamma_1 \sim \gamma_2 \Leftrightarrow (\gamma_1 \circ \chi)'(0) = (\gamma_2 \circ \chi)'(0)$ for
 some/any coordinate system (χ, U) around p

We denote by $\delta'(0)$ the equiv. class of γ . ②

- More algebraic definition: Space of derivations of $C^\infty(M)$

at p .

A derivation at p is a linear map L :

$$L: C^\infty(M) \rightarrow \mathbb{R}$$

$$L(fg) = f(p)L(g) + L(f)g(p)$$

The relation between the two def's is that the derivation L defined by $\delta'(0)$ is $L(f) = \frac{d}{dt} (f \circ \gamma)|_{t=0}$

In local coord's x any right vector can be written as

$$\sum d_i(0) \frac{dx^i}{dt}|_p$$

- Recall A (smooth) v. field is a smooth section of the tangent bundle.

- The space of v. fields can be identified

~~An integral curve~~ \cong the space of derivations of $C^\infty(M)$, that is maps $L: C^\infty(M) \rightarrow C^\infty(M)$ satisfying -

- Given a v. field X on M , an integral curve of X is a smooth map $\gamma: (a, b) \rightarrow M$ s.t. $\gamma'(t) = X_{\gamma(t)}$ $\forall t \in (a, b)$.

For any $p \in M$, there exists an integral curve γ passing through p . And if γ, γ' are two integral curves with $\gamma(t_0) = \gamma'(t_0)$ for some t_0 , then $\gamma = \gamma'$ on the m.s. of their sources.

Hence for any $p \in M$ \exists a maximal integral curve

③

through p .

If $f: M \rightarrow N$ is a smooth map, then the differential of f at $p \in M$ is the linear map $T_p M \xrightarrow{\text{def}} T_{f(p)} N$ defined by

$$x'(0) \mapsto (f \circ x)'(0)$$

Let now G be on Lie grp. before diffeomorphism

$$\begin{aligned} g: G &\longrightarrow G \\ g \mapsto &gh \end{aligned}$$

The g induces a map $(l_g)_*$ on v.fields. by

$$(l_g)_*(X)_p = (d_{g^{-1}(p)} l_g)(X_{g^{-1}(p)})$$

Def A v.field X is called left-invariant if $(l_g)_*(X) = X \forall g \in G$.

Such a v.field is denoted by its value at $e \in G$. $X_e = (d_e l_g)(X_e)$

This way we get a 1-1 correspondence between left-invariant v.fields and $v \in T_e G$.

(4)

"Almost tautological exercise" Show that X is left-inv.

iff. the corresponding derivation L_X commutes

$$\text{by the rps} \quad \text{eg}: C^*(G) \xrightarrow{\alpha_X} C^*(G) \\ f \mapsto f(g^{-1})$$

Proof let G be any group, $x \in G$, and

$$\alpha_X: (g, b) \rightarrow G$$

be the maximal integral curve of the cusp. left-inv. v-field.

$$\text{s.t. } \alpha_X(0) = e$$

$$\text{phy. } \alpha_X(a, b) = R \quad \text{and} \quad \alpha_X(s+t) = \alpha_X(s)\alpha_X(t)$$

Pf Fix $s \in (a, b)$. Consider two curves: $\gamma_1: (a/b) \rightarrow G$ $+ s, t \in \mathbb{R}$
 $\gamma_1(t) = \alpha_X(s)\alpha_X(t)$

$$\gamma_2: (a-s, b-s) \rightarrow G$$

$$\gamma_2(t) = \alpha_X(s+t)$$

phy. $\gamma_1(0) = \alpha_X(s) = \gamma_2(0)$. Both curves are integral curves of
an v.field. Clear for γ_2 , while for γ_1 , we have

$$\begin{aligned} \gamma_1'(t) &= (\ell_{\alpha_X(s)} \circ \alpha_X)'(t) = \frac{d}{dt} \alpha_X(\alpha_X'(t)) \\ &= (d_{\alpha_X(t)} \ell_{\alpha_X(s)}) \left(\tilde{X}_{\alpha_X(t)} \right) = \tilde{X}_{\alpha_X(s)\alpha_X(t)} = \tilde{X}_{\gamma_1(t)} \end{aligned}$$

Hence $\delta_1 = \delta_2$ on their domain of def.

(5)

As δ_2 is maximal it follows that $(a, b) \in (a \circ s, f \circ s)$.

Only possible for $(a, b) = R$.



(6) A 1-param subgp of G is a smooth map

$$\gamma: \mathbb{R} \rightarrow G$$

that is a group homomorphism $(\mathbb{R}, +) \rightarrow (G, \mu)$.

Finally the map $X \mapsto \alpha_X$ is a bijection between $T_e G$ and one-parameter subgroups of G .

(7) Assume $\gamma: \mathbb{R} \rightarrow G$ is a one-param subgp. Put

$$X = \gamma'(0) \in T_e G. \text{ Then } \gamma = \alpha_X.$$

$$\gamma'(t) = (d_{\alpha_X} \gamma(t))(\gamma'(0)) \text{ as } \partial(t+s) = \gamma(s)\gamma'(s)$$

□

Remark In general, $\gamma(\mathbb{R})$ is not a closed subgroup of G .

Example $\mathbb{R} \rightarrow T \times T \ni t \mapsto (e^{it}, e^{it})$
is close in $T \times T$

(8) The exponential map is the map

$$\exp: T_e G \longrightarrow G$$

$$X \mapsto \alpha_X(1)$$

$$\text{Note that for any } s \in \mathbb{R} \quad \frac{d}{dt} \alpha_x(s t) = s \alpha'_x(st) \\ = s \underset{\sim}{\alpha}_x(st)$$

⑥

This $t \mapsto \alpha_x(st)$ is the integral curve of v -field
corresponding to sX , hence $\alpha'_x(st) = d_{sx}(t)$.

$$\text{Therefore } \exp(tX) = \alpha_x(t) = \alpha'_x(1).$$

Therefore all 1-param subgrps of G have the form
 $t \mapsto \exp(tX)$

$$\text{We have } \left. \frac{d}{dt} \exp(tX) \right|_{t=0} = X$$

In other words, if we identify $T_e(G) \leftrightarrow T_eG$, we
conclude that $d \exp = \text{id}_{T_eG}$.

Note that the map $\exp: T_eG \rightarrow G$ is smooth, so the map

$$T_eG \times \mathbb{R} \rightarrow G \quad (\text{by smooth dependence})$$

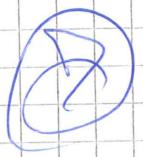
$(X, t) \mapsto \alpha_X(t)$

(solutions of ODE or initial cond's and param's)

thus we have proved the following theorem:

Then the exp. map is the 1 smooth map $\exp: T_eG \rightarrow G$
s.t. $\exp((s+t)X) = \exp(sX) \exp(tX)$ and

$$\left. \frac{d}{dt} (\exp(tX)) \right|_{t=0} = X.$$

As $d\exp = \text{id}_e$, the map \exp 

defines a diffeomorphism between a neighborhood of $0 \in T_e G$ and a neighborhood of $e \in G$.

Ingen \exp is neither inj. nor surjective, even for connected groups.

Example $G = GL(V)$

As $GL(V) \subset End(V)$ is open the regular space of any $A \in GL(V)$ is identical w/ $End(V) \cap MEG(V)$

Then $\exp: End(V) \rightarrow GL(V)$ is given by

$$X \mapsto e^X = \sum_{n=0}^{\infty} \frac{A^n}{n!}$$

Def A homomorphism of Lie groups is a homomorphism $\pi: G \rightarrow H$ which is also smooth.

Thm Assume $\pi: G \rightarrow H$ is a Lie grp homomorphism. Then the diagram

$$\begin{array}{ccc} G & \xrightarrow{\pi} & H \\ \exp \downarrow & & \downarrow \exp \\ T_e G & \xrightarrow{\text{d}\pi} & T_{\pi(e)} H \end{array}$$

commutes.



Example $h = GL(V)$, consider the map

$$\det: GL(V) \rightarrow K^* = GL(K)$$

(8)

The $\frac{d}{dt} \det = \text{Trace}$

Therefore the theorem gives us that

$$\det(e^A) = e^{\text{Trace } A} \quad \forall A \in \text{End}(V)$$

Still some time to go w/ main construction.

The Lie algebra of a Lie group

Recall that for v-fields on a manifold M we have a commutator, or lie bracket.

If $x_i y$ are v-fields, and L_x, L_y are the corresponding derivations, then the bracket is defined as

$$[L_x, L_y] = L_x L_y - L_y L_x.$$

In local coords, if $x = \sum f^i \frac{\partial}{\partial x^i}$ and $y = \sum g^i \frac{\partial}{\partial x^i}$

$$\text{then } [x, y] = \sum_{i,j} \left(f^i \frac{\partial g^j}{\partial x^i} - g^i \frac{\partial f^j}{\partial x^i} \right) \frac{\partial}{\partial x^j}$$

A lie algebra over a field K is a subspace \mathfrak{g} over K equipped

with a bilinear map $[\cdot, \cdot]$ called the lie bracket s.t. it

is skew symmetric, and satisfies the Jacobi identity.

$$[[A, B], C] + [[C, A], B] + [[B, C], A] = 0$$

V-fields Tech form a lie algebra.