

①

Recall

$$\exp: T_e G \rightarrow G$$

$$(t+s)X \mapsto \exp(sX) \exp(tX) \quad \left. \frac{d}{dt} \exp(tX) \right|_{t=0} = X$$

Left-invariant v.fields on G are closed under the commutator. Identifying left-inv. v.fields w/ tangent vectors at e , we get the structure of a real lie algebra on $T_e G$. This lie algebra is denoted by \mathfrak{g} .

In other words, if $L_X: C^\infty(G) \rightarrow C^\infty(G)$ is the derivation corresponding to the left-invariant vfield defined by $X \in \mathfrak{g}$ then the lie bracket is def by $[L_X, L_Y] = L_X L_Y - L_Y L_X$.

A lie algebra has the properties

$$\textcircled{1} \quad [x, x] = 0$$

$$\textcircled{2} \quad \text{Jacobi identity} \quad \sum_{\text{cyclic}} [x, [x_1, x_2]] = 0$$

"replacement of associativity"

How to compute $[x, y]$ more explicitly?

Take a curve γ s.t. $\gamma(0) = e$ and $\gamma'(0) = y$.

Then for any $g \in G$, the curve $g\gamma_x$ satisfies

$$(g\gamma_x)(0) = g \quad \text{and} \quad (g\gamma_x)'(0) = (dg)(\gamma_x)$$

$$\text{Hence } L_x(f)(g) = \frac{d}{dt} f(g\chi(t))|_{t=0}. \quad \textcircled{2}$$

$$\begin{aligned} \text{Then } (L_x L_y)(f)(g) &= \frac{d}{dt} L_y(t)(g\chi_x(t))|_{t=0} \\ &= \frac{\partial^2}{\partial s \partial t} f(g\chi_x(t))|_{\substack{s=t \\ \chi_y(s)}} = 0 \end{aligned}$$

$$\text{thus } (d_e f)([x,y]) = (L_x L_y - L_y L_x)(f)(e)$$

$$\begin{aligned} \textcircled{3} &= \frac{\partial^2}{\partial s \partial t} \left(f(\chi_x(t) \chi_y(s)) \right. \\ &\quad \left. - f(\chi_y(s) \chi_x(t)) \right)|_{s=t=0} \end{aligned}$$

Divide explicit.

Choose local coord's x around e by take values on $g = T_E G$

s.t. $\chi(e) = 0$ and $d_e \chi = \text{id}$.
(e.g. $\chi = \exp^{-1}$)

$$\begin{aligned} \text{Consider the map } m: V \times V &\rightarrow g \\ (x, y) &\mapsto x(\bar{x}(x)^{-1}(y)) \end{aligned}$$

is well-def for small neighborhoods V of ∂E .

$$\begin{aligned} \text{Take } \bar{x}_x(t) &= x(t+x) & \bar{x}_y(s) &= x(s+y) \end{aligned}$$

apply $\textcircled{3}$ to $f = \ell \circ x$ where ℓ is a linear functional on g

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We set

$$l([x,y]) = \frac{\partial^2}{\partial s \partial t} \cancel{I}$$

$$l(x(\bar{x}(+x)\bar{x}(sy))) - x(\bar{x}(s))\bar{x}(+x)) \Big|_{\substack{t=s \\ s=0}}$$

$$= l\left(\frac{\partial^2}{\partial s \partial t} (m(+x, sy) - m(sy, +x)) \Big|_{\substack{t=s=0}} \right)$$

Therefore

$$[x,y] = \frac{\partial^2}{\partial s \partial t} (m(+x, sy) - m(sy, +x)) \Big|_{\substack{s=t=0}}$$

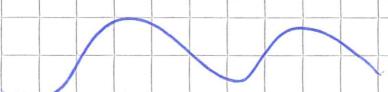
This can also be written as follows:

As $m(0,0) = 0$, $m(x,0) = x$, $m(0,y) = y$
 the Taylor expansion of m at $(0,0)$ has the form

$$m(x,y) = x + y + B(x)y + \text{h.o.t.}$$

where ~~B~~ $B: \mathbb{R}^{x,y} \rightarrow \mathbb{R}$ is a bilinear map.

$$\text{Therefore } [x,y] = B(x,y) - B(y,x).$$



Example Let $G = GL(V)$ for a fin-dim real/comp
space V .

choose words by setting $\star(A) = A - 1$.

$$\text{Then } m(X, Y) = (1+X)(1+Y) - 1 \\ = XY + X + Y$$

Therefore $[X, Y] = XY - YX$.

The space $T_e V = T_e GL(V)$ w/ this bracket is denoted $gl(V)$.

(More precisely, if V is complex, then $gl(V)$ is viewed as a $g\ell(V)$ algebra.)

If $\pi: G \rightarrow H$ is a Lie group homomorphism,
then $\pi_* = d\pi \circ \mathfrak{g} \rightarrow \mathfrak{h}$ is a Lie algebra
homomorphism. (ie preserves the bracket)

$$\pi_*([X, Y]) = [\pi_*(X), \pi_*(Y)]$$

pf, ok, so why this is the case?

Recall that $\forall x \in \mathfrak{g}$ we have

$$\pi(\exp(rX)) = \exp(r\pi_*(X))$$

As $L_X(f)(g) = \frac{d}{dt} (f(g \exp(tX)))|_{t=0}$

we have

$$L_{\pi_*(X)}(f)(\pi(g)) = L_X(f \circ \pi)(g).$$

Possibly commutators $L_{[\pi(X), \pi(Y)]}(f)(\pi(g)) = L_{[X, Y]}(f \circ \pi)(g)$

$$\text{Hence } [\pi_*(x), \pi_*(y)] = (\partial_e \pi)([x, y]) \\ = \pi_*([x, y]) - \text{III}$$

Lie subgroups

[a] A closed lie subgroup of a lie group G is a subgroup H which is also a closed submanifold.

Then H is itself a lie group. We can identify $H = T_e H$ the subspace of $\mathfrak{g} = T_e G$

As the embedding $H \hookrightarrow G$ is a lie group homomorphism, this gives an identification of H as a lie subalgebra (a subspace closed under lie bracket).

[b] If G is a lie group and H is a closed subgroup, then H is a closed submanifold.

[c] Consider $V \subset \mathfrak{g}$ consisting of v's X s.t. there exists $x_n \in g$ and $\alpha_n \in \mathbb{R}$ s.t. $\exp(x_n) \in H$

and $\alpha_n X_n \rightarrow 0$ and $|\alpha_n| \rightarrow \infty$ as $n \rightarrow \infty$

Claim 1 If $x \in V$ then $\exp(tx) \in H$ ~~H.F.R.~~. ⑥

Take $t \in \mathbb{R}$. As $|x_n| \rightarrow \infty$ we can find $m_n \in \mathbb{Z}$

s.t. $\frac{m_n}{a_n} \rightarrow t$ as $n \rightarrow \infty$ (e.g. let $m_n = [a_n t]$)

Then

$$H \ni \exp(x_n) = \exp(m_n x_n)$$

$$= \exp\left(\frac{m_n}{a_n} a_n x_n\right)$$

$$\xrightarrow{n \rightarrow \infty} \exp(tx) \in H$$

since H closed.

Claim 2 $V \subset g$ is a V -space

By claim 1, V is closed under multi. by scalars.

Therefore, we have to show that if $X, Y \in V$, then $X+Y \in V$.

Consider $\gamma(t) = \exp(tX) \exp(tY)$.

Then $\gamma'(0) = X+Y$

For small $|t|$ we can write $\gamma(t) = \exp(f(t))$ where f is

a smooth \mathbb{R} -valued function.

Then $f'(0) = X+Y$ so

$$\frac{f(t)}{t} \rightarrow X+Y \text{ as } t \rightarrow 0.$$

In particular, $n f(\frac{1}{n}) \rightarrow X+Y$ as $n \rightarrow \infty$.

and $\exp(f(\frac{1}{n})) \in H$. By definition $X, X+Y \in V$.

Claim 3 If H is a closed manifold w/ $T_0 H = V$.

(2)

Let V' be a complementary subspace to V in g ,

i.e. $g = V \oplus V'$.

Consider the map $\phi: V \times V' \rightarrow g$ $\phi(x,y) = \exp(X)\exp(Y)$

then $d_{(0,0)}\phi = id$, so we can find neighborhoods Ω of 0 in V

and Ω' of 0 in V' s.t. ϕ is a diffeomorphism of
 $\Omega \times \Omega'$ onto $\phi(\Omega \times \Omega')$.

We will show that for n large enough

$$\phi(-\Omega \times \frac{1}{n}\Omega') \cap H = \exp(\Omega)$$

$$\phi(\Omega \times \frac{1}{n}\Omega')$$

Suppose this is not true. Then we can find $(x_n, x_n') \in \Omega \times \Omega'$

s.t. $\exp(x_n)\exp(\frac{x_n'}{n}) \in H$ and $x_n' \neq 0$.

Take any limit point x' of the sequence $\frac{x_n'}{\|x_n'\|}$

Then $x' \neq 0$, $x' \in V'$, $\exp(\frac{x_n'}{\|x_n'\|}) \in H$ and $\frac{n}{\|x_n'\|} \cdot \frac{x_n'}{\|x_n'\|} \xrightarrow[n \rightarrow \infty]{} x'$

Th by def, $x' \in V$, which is

a contradiction.

Thus in the neighborhood $\phi(\Omega \times \frac{1}{n}\Omega')$ of $e \in G$,
we can take the coordinate system $\tilde{x} \in \tilde{G}'$ s.t. $\cup H = \{gH\}$ the word's ~~are~~ are good

For obiting left, we can take the neighborhood
hU of hG(G) and coor's

$$x_h = x(\bar{e}^{-1} -) \quad \text{s.t.} \quad U_h \cap H = \{g \in G \mid \text{the coord's of } x_h(g) \text{ in } V \text{ is good}\}$$

(tomorrow! can't to discuss this.)

Propriety a curve's tangent of hte sys
is automatically smooth