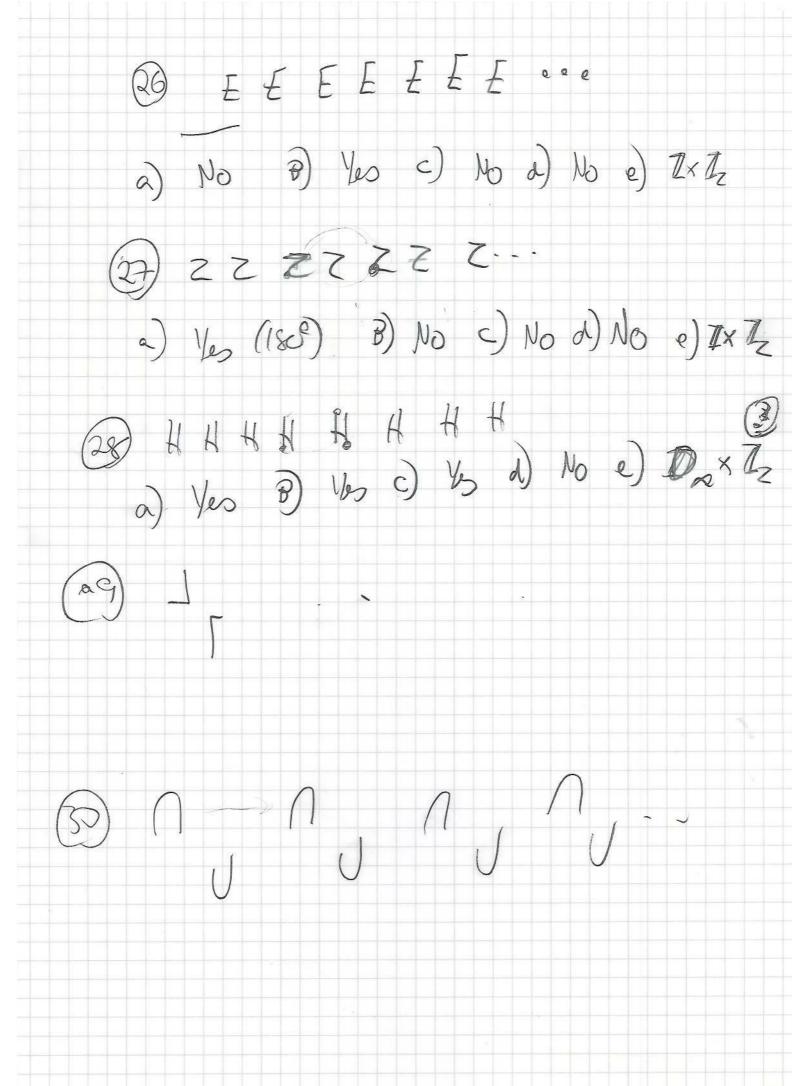
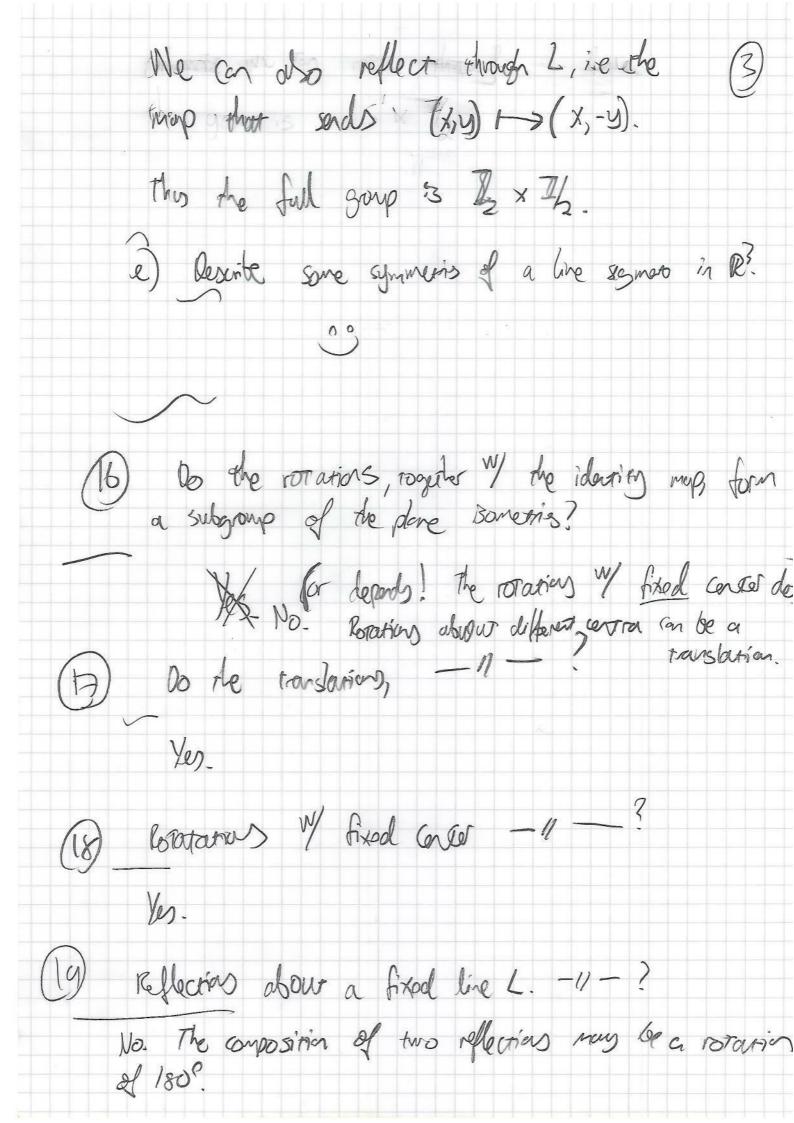
ecrian 12 I lescibe all symmetries of a point in IR. That is, all isometries of IR their leave are point fixed. We can without loss of generality assume that the point is OER. Let X be any other point  $\in \mathbb{R}$  and let  $\alpha: \mathbb{R} \to \mathbb{R}$  be an isometry. Then by definition,  $|\alpha(x)-0|=|\alpha(x)|=|x|$ . But then  $\alpha(x)=\pm x$ . Thus I sends x either to itself or to its negative. Suppose  $\alpha(x) = x$ . Then I claim that  $\alpha = id_R$ . Let  $y \in R$ . Then we must have  $|\alpha(y)| = |y|$  as before, so  $\alpha(y) = \pm y$ . On the other hand, we also have |a(x) - a(y)| = |x - y|Suppose first y >0, and x >0. If x(y) = -4, then | x(y) - a(x) > | ax-y|, current to a being an isometry. Suppose now 470 and ×10. If aly) = -4), the laly) - x(x) < (x-vs), coverang to & being on isomerny. The other two cases one similar. Have the only automorphisms of a point in R one It







B) All symmetries of a point in the plane R. We want to find all isometries fixing (0,0) ER.
Suppose first that a preserve orientation. Then
since lengths are preserved, a muso be different a station about the origin. Now suppose that a reverses orientation. Then  $\alpha \circ (0)$  preserves orientation, so  $d = \begin{cases} 0 \\ 1 \\ 0 \end{cases} = \begin{cases} 0 \end{cases} = \begin{cases} 0 \\ 0 \end{cases} = \begin{cases} 0 \\ 0 \end{cases} = \begin{cases} 0 \end{cases} = \begin{cases} 0 \\ 0 \end{cases} = \begin{cases} 0 \end{cases} = \begin{cases} 0 \\ 0 \end{cases} = \begin{cases} 0 \end{cases} = \begin{cases} 0 \\ 0 \end{cases} = \begin{cases} 0 \end{cases} = \begin{cases} 0 \end{cases} = \begin{cases} 0 \\ 0 \end{cases} = \begin{cases} 0 \\ 0 \end{cases} = \begin{cases} 0 \end{cases} = (0 \end{cases}$ But then  $d = P_{\Theta} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$ . Hree the group of isomens fixing a point is 5° R Z. c) All symmetries of a line segment.  $\subseteq R$ Arsnot Pelecian down the midpoint + identity. d) All symmetris of a line segment & R3. Suppose whose that  $L = [0,1] \times \{0\} \subseteq \mathbb{R}^{1}$ . We an reflect about the midpoint  $(\frac{1}{2},0)$  of  $L_{1}$  reversing orientation.