A Data-Driven Model for COVID-19 Propagation in Honduras

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Abstract—In this document, an application of universal algebraic controllers (in the sense of [1]) to the computation of predictive models for COVID-19 propagation in Honduras, is presented.

Some data-driven numerical predictive simulations for the COVID-19 propagation in Honduras, are outlined.

Index Terms—System identification, state transition matrix, structured matrices.

I. Introduction

The purpose of this document is to present some theoretical and computational techniques for constrained approximation of data-driven predictive models for the propagation of COVID-19 in Honduras during the first quarter of 2020. These models can be interpreted as discrete-time systems that can be partially described using the transition block diagram (I.1) as a black-box device \mathfrak{S} , that needs to be determined in such a way that it can be used to transform the present state x_t into the next state x_{t+1} , according to (I.2).

In this study each entry $x_{t,j}$ of the state vector x_t corresponds to the known/predicted number of infected people in Department j, where the index j coincides with the Department's identification number, for instance $x_{t,1}$ is the estimated number of infected people in Atlántida at stage t. We will approach the computation of the state-transition maps corresponding to the device (I.1), applying the algebraic methods developed in [1] and [2] to compute the state-transition matrices that correspond to matrix solvents of difference equations of the form

$$\Sigma : \begin{cases} x_{t+1} = T_t x_t, & t \ge 1 \\ x_1 \in \Sigma \subseteq \mathbb{R}^{18n} \end{cases}$$
 (I.2)

where $\Sigma \subseteq \mathbb{R}^{18n}$ is the set of *valid* propagation states for the system with $n \in \mathbb{Z}$ fixed, and where the matrices $T_t \in \mathbb{R}^{18n \times 18n}$ are to be determined by the relations (I.2),

and in addition need to satisfy the following structural constraints.

$$\begin{cases}
T_t = \prod_{j=1}^{18n} \left(I + \hat{e}_j (\tau_{(t,j)} - \hat{e}_j)^\top \right) \\
K_j \circ \tau_{(t,j)}^\top = \tau_{t,j}, \quad 1 \le j \le 18n
\end{cases}$$
(I.3)

where \circ denotes the Hadamard product, K_j is the jthrow of a connectivity matrix determined by the geographic
configuration of Honduras territory under consideration,
the matrices $\tau_{(t,j)} \in \mathbb{R}^{18n \times 1}$ are to be determined by (I.2)
and I.3, and where $\hat{e}_{j,n}$ denotes the matrices in $\mathbb{C}^{n \times 1}$ representing the canonical basis of \mathbb{C}^n (the j-column of
the $n \times n$ identity matrix I), that are determined by the
expression

$$\hat{e}_{j,n} = \begin{bmatrix} \delta_{1,j} & \delta_{2,j} & \cdots & \delta_{n-1,j} & \delta_{n,j} \end{bmatrix}^{\top}$$
 (I.4)

for each $1 \leq j \leq n$, where $\delta_{k,j}$ is the Kronecker delta determined by the expression.

$$\delta_{k,j} = \begin{cases} 1, & k = j \\ 0, & k \neq j \end{cases}$$
 (I.5)

II. UNIVERSAL ALGEBRAIC CONTROLLERS FOR THE PROPAGATION MODEL

A. Connectivity Matrices

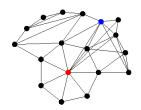
Based on the COVID-19 propagation behavior data available thus far. Let us consider the connectivity matrix $K \in \mathbb{R}^{18 \times 18}$ determined by the expression.

$$K = I + adj(G) (II.1)$$

Where $adj(G) = [a_{jk}]$ denotes the adjacency matrix of a graph $G = (V_G, E_G)$ determined by the rules.

$$a_{jk} = \begin{cases} 1, & \text{if } [v_j, v_k] \in E_G, \ v_j, v_k \in V_G \\ 0, & \text{otherwise} \end{cases}$$
 (II.2)

The graph G is determined by the geographical configuration of the Honduras territory, and belongs to the class represented by graphs like the ones in fig. 1.



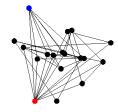


Figure 1. Homomorphic connectivity graphs corresponding to Honduras departments geographical confuguration. The red dot represents Francisco Morazán, the blue dot represents Cortés.

B. UAC Computation

Lemma II.1. Let us consider two propagation states $x_t, x_{t+1} \in \Sigma$ and the connectivity matrix $K \in \mathbb{R}^{18n \times 18n}$ determined by (II.1). There is a matrix $T_t \in \mathbb{R}^{18n \times 18n}$ that satisfies (I.2) and (I.3), if and only if for each $1 \le j \le 18n$, there is $\tau_{(t,j)} \in \mathbb{R}^{18n \times 1}$ such that $\tau_{(t,j)}^{\top} x_t = x_{t+1,j}$ and $K_i \circ \tau_{(t,i)} = \tau_{(t,i)}, \text{ with } x_{t+1} = [x_{t+1,i}].$

Proof. Let us consider the matrix.

$$E_{\tau_{(t,j)}} = I + \hat{e}_j (\tau_{(t,j)} - \hat{e}_j)^{\top}$$
 (II.3)

Given $x = [x_j] \in \mathbb{R}^{18n \times 1}$, we will have that.

$$E_{\tau_{(t,j)}} x = (I + \hat{e}_j (\tau_{(t,j)} - \hat{e}_j)^\top x = \begin{cases} \tau_{(t,j)}^\top x, & k = j \\ x_k, & k \neq j \end{cases}$$
(II.4)

Let us set $T_t = \prod_{j=1}^{18n} E_{\tau_{(t,j)}}$ by (I.3). By (II.3) and (II.4), we will have that the matrix $T_t \in \mathbb{R}^{18n \times 18n}$ that satisfies (I.2) and (I.3), if and only if for each $1 \leq j \leq 18n$, there is $\tau_{(t,j)} \in \mathbb{R}^{18n \times 1}$ such that $\tau_{(t,j)}^{\top} x_t = x_{t+1,j}$ and $K_j \circ \tau_{(t,j)} = x_{t+1,j}$ $\tau_{(t,i)}$. This completes the proof.

III. Algorithm

We can combine lemma II.1 combined with the techniques developed in [1] and [2], in order to derive two prototypical data-driven approximation algorithms for the propagation model that are described by algorithm 1 and algorithm 2.

IV. Numerical Experiments

have created two spreadsheets named COVID19History.xlsx and HNConnect.xlsx, we have collected the data corresponding to observed COVID-19 propagation history in Honduras thus far and to the geographical configuration of Honduran Departments, respectively.

We have written a GNU Octave program named COVID19.m that implements algorithm 1 based on the data in COVID19History.xlsx and HNConnect.xlsx. The GNU Octave code of COVID19.m is presented below.

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Algorithm 1 First Data-driven (descriptor-corrector) approximation algorithm

Data: Real number $\varepsilon > 0$, State data history: $\{x_t\}_{1 < t < T}, T \in \mathbb{Z}^+$ Connectivity matrix: $K \in$

APPROXIMATE MATRIX REALIZATIONS: Result: $\{T_t\}_{t=1}^{T-1} \subset \mathbb{R}^{18n \times 18n} \text{ of } \tilde{\Sigma}$

- 1) For each $1 \le t \le T 1$
 - a) Compute $\tau_{(t,j)} \in \mathbb{R}^{18n \times 1}$ such that $K_j \circ \tau_{(t,j)}^\top =$ $\begin{array}{c} \tau_{(t,j)}^{\intercal} \text{ and } |x_{t+1,j} - \tau_{(t,j)}^{\intercal} x_t| \leq \varepsilon \text{ for each } 1 \leq j \leq \\ 18n \text{ and , with } x_t, x_{t+1} \in \Sigma \\ \text{b) Set } T_t = \prod_{j=1}^{18n} E_{\tau_{(t,j)}}, \text{ with } E_{\tau_{(t,j)}} \text{ defined by} \end{array}$
 - (II.3).

return $\{T_t\}_{t=1}^{T-1}$

Algorithm 2 Second Data-driven (predictor) approximation algorithm

Data: Real number $\varepsilon > 0$, State data history: $\{x_t\}_{1\leq t\leq T},\ T\in\mathbb{Z}^+$

Result: APPROXIMATE STATE TRANSITION MATRIX: $\mathbf{T} \in \mathbb{R}^{18n \times 18n} \text{ of } \tilde{\Sigma}$

- 1) Set $H = [x_{t_1} \cdots x_{t_1+S}]$ with $t_1 \ge 1$ and $t_1 + S \le 1$
- 2) Compute the reduced singular value decomposition H = USV
- 3) Compute the perturbation $H_{\varepsilon} = US_{\varepsilon}V$ of Haccording to $[1, \S 3.2: (3.38)]$.
- 4) Compute the state-transition matrix **T** determined by [1, Corollary 3.8.] according to [1, §3.2: (3.44)].

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return T

```
## and/or modify it under the terms of the GNU General
## Public License as published by the Free Software
## Foundation, either version 3 of the License, or
## (at your option) any later version.
##
## This program is distributed in the hope that it will be
## useful, but WITHOUT ANY WARRANTY; without even the
## implied warranty of MERCHANTABILITY or FITNESS FOR A
## PARTICULAR PURPOSE.
                       See the
## GNU General Public License for more details.
##
## You should have received a copy of the GNU General
## Public License
## along with this program. If not, see
## <https://www.gnu.org/licenses/>.
##
## function [K,T,x0,x]=COVID19(m,n,tol,graph)
##
## Example:
## [K,T01,x0,x1]=COVID19(0,1,eps);
```

```
## [K,T12,x1,x2]=COVID19(1,2,eps);
                                                    x(f1)=0;
## [K,T23,x2,x3] = COVID19(2,3,eps);
                                                    T=E;
## [K,T03,x0,x3]=COVID19(0,3,eps);
                                                    for k=f2
## norm(x3-T03*x0,1)+norm((T23*T12*T01-T03)*x0,1) T0=E;
                                                    TO(k,:)=K(k,:).*(x(k)/x0);
## Author: fredy <fredy@HPCLAB>
                                                    T=TO*T;
## Created: 2020-03-17
                                                    end
                                                    T0=ones(M,1);
function [K,T,x0,x]=COVID19(m,n,tol,graph)
                                                    y0=T*x0;
                                                    TO(f2)=x(f2)./yO(f2);
n=n+1;
                                                    T=diag(T0)*T;
                                                    K=A+E;
pkg load io;
COVIDHist=xlsread ('COVID19History.xlsx');
                                                    end
HNConnect=xlsread ('HNConnect.xlsx');
                                                      One can run program COVID19.m using the following
A=HNConnect (1:18,1:18);
                                                    command lines in GNU Octave.
[M,N]=size(A);
E=eye(M,N);
                                                    >> [K,T01,x0,x1]=COVID19(0,1,eps);
                                                    >> [K,T12,x1,x2]=COVID19(1,2,eps);
K=A+E;
if nargin<=3
                                                    >> [K,T23,x2,x3]=COVID19(2,3,eps);
graph=1;
                                                    >> [K,T03,x0,x3]=COVID19(0,3,eps);
end
                                                    >> norm(x3-T03*x0,1)+norm((T23*T12*T01-T03)*x0,1)
if graph==1
                                                             3.0531e-15
r=.5;
                                                      We have written a GNU Octave program named
z1=(r*exp(2*pi*i*(0:6)/7)).';
                                                    UACPredictor.m that implements algorithm 2 based on
z2=(2.0*r*exp(20*pi*i*(0:8)/(9*21))).';
                                                    the data in COVID19History.xlsx. The GNU Octave code
z3=2.4*r*exp((pi+.1)*i/4);
                                                    of UACPredictor.m is presented below.
xy=zeros(M,2);
xy([15 18 4 12 17 2 7],:)=[real(z1),imag(z1)];
                                                    ## Copyright (C) 2020 Fredy Vides
xy([9 3 1 6 16 5 14 13 10],:)=[real(z2),imag(z2)];##
                                                    ## This program is free software: you can redistribute it
xy(11,:)=[real(z3),imag(z3)];
                                                    ## and/or modify it under the terms of the GNU General
subplot(211);
gplot (A,xy,'k-');
                                                    ## Public License as published by the Free Software
hold on;
                                                    ## Foundation, either version 3 of the License, or
plot(xy(:,1),xy(:,2),'k.','markersize',20,...
                                                    ## (at your option) any later version.
xy(8,1), xy(8,2), 'r.', 'markersize', 20, xy(6,1)...
,xy(6,2),'b.','markersize',20);
                                                    ## This program is distributed in the hope that it will be
hold off;
                                                    ## useful, but WITHOUT ANY WARRANTY; without even the
axis off;
                                                    ## implied warranty of MERCHANTABILITY or FITNESS FOR A
                                                    ## PARTICULAR PURPOSE. See the
axis square;
                                                    ## GNU General Public License for more details.
subplot(212);
XY=randn(M,2);
gplot (A,XY,'k-');
                                                    ## You should have received a copy of the GNU General
hold on;
                                                    ## Public License
plot(XY(:,1),XY(:,2),'k.','markersize',20,XY(8,1),\# along with this program. If not, see
XY(8,2), 'r.', 'markersize',20,XY(6,1),XY(6,2),...
                                                    ## <https://www.gnu.org/licenses/>.
'b.', 'markersize', 20);
                                                    ## function [Xh,T,EIHUB,EIHLB,EGHUB,EGHLB] =
hold off;
axis off;
                                                    # UACPredictor(n,r,tol)
                                                    ##
axis square;
                                                    ## Example:
                                                    ## [Xh,T,EIHUB,EIHLB,EGHUB,EGHLB] = . . .
x0=COVIDHist (1:18,m);
f0=find(abs(x0)<=tol);</pre>
                                                    UACPredictor(9,12,1e-12);
x=COVIDHist (1:18,n);
f1=find(abs(x)<=tol);</pre>
                                                    ## Author: fredy <fredy@HPCLAB>
f2=find(abs(x)>tol);
                                                    ## Created: 2020-03-28
x0(f0)=0;
```

```
function [Xh,T,EIHUB,EIHLB,EGHUB,EGHLB] = ...
UACPredictor(n,r,tol)
pkg load io;
Xh=xlsread ('COVID19History.xlsx');
[p,m]=size(Xh);
Xh=Xh(1:(p-1),(n+1):(r+1));
[p,m]=size(Xh);
Xh0=Xh(:,1:(m-1));
[uh, sh, vh] = svd(Xh0, 0);
sh0=diag(sh);
f=find(sh0<=tol);
sh0(f)=tol;
sh0=diag(sh0);
T=Xh0\Xh(:,m);
T=[[zeros(1,m-2);eye(m-2)] T];
T=uh*sh0*vh'*T*(vh/sh0)*uh';
EIHUB=Xh(:,1);
EGHUB=Xh(:,1);
EIHLB=EIHUB;
EGHLB=EGHUB;
for k=1:(m-1)
EIHUB = [EIHUB (Xh(:,k+1)>0).*ceil(T*Xh(:,k))];
EIHLB = [EIHLB (Xh(:,k+1)>0).*floor(T*Xh(:,k))];
EGHUB = [EGHUB (Xh(:,k+1)>0).*ceil(T*EGHUB(:,k))]; program COVID19.m are available at [3].
EGHLB = [EGHLB (Xh(:,k+1)>0).*floor(T*EGHLB(:,k))];
end
end
```

One can run program UACPredictor.m using the following command lines in GNU Octave.

```
>> s=9;R=12;
>> [Xh,T,EIHUB,EIHLB,EGHUB,EGHLB] = ...
UACPredictor(s,R,1e-12);
>> t=1:(R-s+1);
>> subplot(221),plot(t,Xh(8,:),'k.-',...
'linewidth',6,t,EIHLB(8,:),'r.-',...
'linewidth',2,t,EIHUB(8,:),'b.-',...
'linewidth',2)
>> subplot(222),plot(t,Xh(8,:),'k.-',...
'linewidth',6,t,EGHLB(8,:),'r.-',...
'linewidth',2,t,EGHUB(8,:),'b.-',...
'linewidth',2)
>> subplot(223),plot(t,Xh(6,:),'k.-',...
'linewidth',6,t,EIHLB(6,:),'r.-',...
'linewidth',2,t,EIHUB(6,:),'b.-',...
'linewidth',2)
>> subplot(224),plot(t,Xh(6,:),'k.-',...
'linewidth',6,t,EGHLB(6,:),'r.-',...
'linewidth',2,t,EGHUB(6,:),'b.-',...
'linewidth',2)
```

The previous lines produce the graphical outputs illustrated in fig. 2.

The spreadsheet data files together with a copy of the

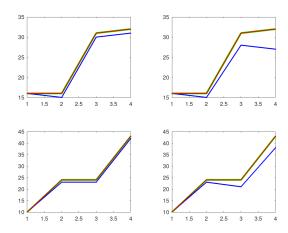


Figure 2. Four stages forcast for Francisco Morazán (top): Local time estimates (left) and Global time estimates (right). Four stages forcast for Cortés (bottom): Local time estimates (left) and Global time estimates (right). Green dotted lines represent observed values, blue dotted lines represent lower bounds for expected-predicted values, and red dotted lines represent upper bounds for expected-predicted values

V. Conclusion and Future Directions

The results in §II can be used to derive predictive numerical simulation algorithms like algorithm 1 and algorithm 2.

Once more COVID-19 behavior data becomes available, we plan to extend algorithm 1 and algorithm 2. to describe other aspects of the COVID-19 propagation in Honduras. An extension of the ideas presented in this document to more complex geographical configuration graphs will be the subject of future communications.

ACKNOWLEDGMENT

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References

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