# A Data-Driven Model for COVID-19 Propagation in Honduras

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Abstract—In this document, an application of universal algebraic controllers (in the sense of [1]) to the computation of predictive models for COVID-19 propagation in Honduras, is presented.

Some data-driven numerical predictive simulations for the COVID-19 propagation in Honduras, are outlined.

Index Terms—System identification, state transition matrix, structured matrices.

#### I. Introduction

The purpose of this document is to present some theoretical and computational techniques for constrained approximation of data-driven predictive models for the propagation of COVID-19 in Honduras during the first quarter of 2020. These models can be interpreted as discrete-time systems that can be partially described using the transition block diagram (I.1) as a black-box device  $\mathfrak{S}$ , that needs to be determined in such a way that it can be used to transform the present state  $x_t$  into the next state  $x_{t+1}$ , according to (I.2).

In this study each entry  $x_{t,j}$  of the state vector  $x_t$  corresponds to the known/predicted number of infected people in Department j, where the index j coincides with the Department's identification number, for instance  $x_{t,1}$  is the estimated number of infected people in Atlántida at stage t. We will approach the computation of the state-transition maps corresponding to the device (I.1), applying the algebraic methods developed in [1] and [2] to compute the state-transition matrices that correspond to matrix solvents of difference equations of the form

$$\Sigma : \begin{cases} x_{t+1} = T_t x_t, & t \ge 1 \\ x_1 \in \Sigma \subseteq \mathbb{R}^{18n} \end{cases}$$
 (I.2)

where  $\Sigma \subseteq \mathbb{R}^{18n}$  is the set of *valid* propagation states for the system with  $n \in \mathbb{Z}$  fixed, and where the matrices  $T_t \in \mathbb{R}^{18n \times 18n}$  are to be determined by the relations (I.2),

and in addition need to satisfy the following structural constraints.

$$\begin{cases}
T_t = \prod_{j=1}^{18n} \left( I + \hat{e}_j (\tau_{(t,j)} - \hat{e}_j)^\top \right) \\
K_j \circ \tau_{(t,j)}^\top = \tau_{t,j}, \quad 1 \le j \le 18n
\end{cases}$$
(I.3)

where  $\circ$  denotes the Hadamard product,  $K_j$  is the jthrow of a connectivity matrix determined by the geographic
configuration of Honduras territory under consideration,
the matrices  $\tau_{(t,j)} \in \mathbb{R}^{18n\times 1}$  are to be determined by (I.2)
and I.3, and where  $\hat{e}_{j,n}$  denotes the matrices in  $\mathbb{C}^{n\times 1}$ representing the canonical basis of  $\mathbb{C}^n$  (the j-column of
the  $n\times n$  identity matrix I), that are determined by the
expression

$$\hat{e}_{j,n} = \begin{bmatrix} \delta_{1,j} & \delta_{2,j} & \cdots & \delta_{n-1,j} & \delta_{n,j} \end{bmatrix}^{\top}$$
 (I.4)

for each  $1 \leq j \leq n$ , where  $\delta_{k,j}$  is the Kronecker delta determined by the expression.

$$\delta_{k,j} = \begin{cases} 1, & k = j \\ 0, & k \neq j \end{cases}$$
 (I.5)

# II. UNIVERSAL ALGEBRAIC CONTROLLERS FOR THE PROPAGATION MODEL

#### A. Connectivity Matrices

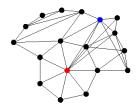
Based on the COVID-19 propagation behavior data available thus far. Let us consider the connectivity matrix  $K \in \mathbb{R}^{18 \times 18}$  determined by the expression.

$$K = I + adj(G) (II.1)$$

Where  $adj(G) = [a_{jk}]$  denotes the adjacency matrix of a graph  $G = (V_G, E_G)$  determined by the rules.

$$a_{jk} = \begin{cases} 1, & \text{if } [v_j, v_k] \in E_G, \ v_j, v_k \in V_G \\ 0, & \text{otherwise} \end{cases}$$
 (II.2)

The graph G is determined by the geographical configuration of the Honduras territory, and belongs to the class represented by graphs like the ones in fig. 1.



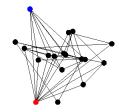


Figure 1. Homomorphic connectivity graphs corresponding to Honduras departments geographical confuguration. The red dot represents Francisco Morazán, the blue dot represents Cortés.

# B. UAC Computation

**Lemma II.1.** Let us consider two propagation states  $x_t, x_{t+1} \in \Sigma$  and the connectivity matrix  $K \in \mathbb{R}^{18n \times 18n}$ determined by (II.1). There is a matrix  $T_t \in \mathbb{R}^{18n \times 18n}$  that satisfies (I.2) and (I.3), if and only if for each  $1 \le j \le 18n$ , there is  $\tau_{(t,j)} \in \mathbb{R}^{18n \times 1}$  such that  $\tau_{(t,j)}^{\top} x_t = x_{t+1,j}$  and  $K_j \circ \tau_{(t,j)} = \tau_{(t,j)}, \text{ with } x_{t+1} = [x_{t+1,j}].$ 

*Proof.* Let us consider the matrix.

$$E_{\tau_{(t,j)}} = I + \hat{e}_j (\tau_{(t,j)} - \hat{e}_j)^{\top}$$
 (II.3)

Given  $x = [x_i] \in \mathbb{R}^{18n \times 1}$ , we will have that.

$$E_{\tau_{(t,j)}} x = (I + \hat{e}_j (\tau_{(t,j)} - \hat{e}_j)^\top x = \begin{cases} \tau_{(t,j)}^\top x, & k = j \\ x_k, & k \neq j \end{cases}$$
(II.4)

Let us set  $T_t = \prod_{j=1}^{18n} E_{\tau_{(t,j)}}$  by (I.3). By (II.3) and (II.4), we will have that the matrix  $T_t \in \mathbb{R}^{18n \times 18n}$  that satisfies (I.2) and (I.3), if and only if for each  $1 \le j \le 18n$ , there is  $\tau_{(t,j)} \in \mathbb{R}^{18n \times 1}$  such that  $\tau_{(t,j)}^{\top} x_t = x_{t+1,j}$  and  $K_j \circ \tau_{(t,j)} = T_j$  $\tau_{(t,j)}$ . This completes the proof.

# III. Algorithm

We can combine lemma II.1 combined with the techniques developed in [1] and [2], in order to derive a prototypical data-driven approximation algorithm for the propagation model that is described by algorithm 1.

# Algorithm 1 Data-driven approximation algorithm

**Data:** Real number  $\varepsilon > 0$ , State data history:  $\{x_t\}_{1 \le t \le T}, T \in \mathbb{Z}^+$ Connectivity matrix:  $K \in$ 

MATRIX Result: APPROXIMATE REALIZATIONS:  $\{T_t\}_{t=1}^{T-1} \subset \mathbb{R}^{18n \times 18n} \text{ of } \tilde{\Sigma}$ 

- 1) For each  $1 \le t \le T 1$ 
  - a) Compute  $\tau_{(t,j)} \in \mathbb{R}^{18n \times 1}$  such that  $K_j \circ \tau_{(t,j)}^{\top} =$  $au_{(t,j)}^{\top}$  and  $|x_{t+1,j} - \tau_{(t,j)}^{\top} x_t| \leq \varepsilon$  for each  $1 \leq j \leq 18n$  and , with  $x_t, x_{t+1} \in \Sigma$ b) Set  $T_t = \prod_{j=1}^{18n} E_{\tau_{(t,j)}}$ , with  $E_{\tau_{(t,j)}}$  defined by

 $\mathbf{return} \quad \{T_t\}_{t=1}^{T-1}$ 

#### IV. Numerical Experiments

We have createdtwospreadsheets COVID19History.xlsx and HNConnect.xlsx, we have collected the data corresponding to observed COVID-19 propagation history in Honduras thus far and to the geographical configuration of Honduran Departments, respectively.

We have written a GNU Octave program named COVID19.m that implements algorithm 1 based on the data in COVID19History.xlsx and HNConnect.xlsx. The GNU Octave code of COVID19.m is presented above.

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```
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##
##
   [K,T,x0,x]=COVID19(m,n,tol)
##
## Example:
## [K,T01,x0,x1]=COVID19(0,1,eps);
## [K,T12,x1,x2]=COVID19(1,2,eps);
## [K,T23,x2,x3] = COVID19(2,3,eps);
## [K,T03,x0,x3] = COVID19(0,3,eps);
## norm(x3-T03*x0,1)+norm((T23*T12*T01-T03)*x0,1)
## Author: fredy <fredy@HPCLAB>
## Created: 2020-03-17
function [K,T,x0,x]=COVID19(m,n,tol)
m=m+1;
n=n+1;
pkg load io;
COVIDHist=xlsread ('COVID19History.xlsx');
HNConnect=xlsread ('HNConnect.xlsx');
A=HNConnect (1:18,1:18);
[M,N]=size(A);
```

```
E=eye(M,N);
K=A+E;
r=.5;
z1=(r*exp(2*pi*i*(0:6)/7)).';
z2=(2.0*r*exp(20*pi*i*(0:8)/(9*21))).';
z3=2.4*r*exp((pi+.1)*i/4);
xy=zeros(M,2);
xy([15 \ 18 \ 4 \ 12 \ 17 \ 2 \ 7],:)=[real(z1),imag(z1)];
xy([9 3 1 6 16 5 14 13 10],:)=[real(z2),imag(z2)]; we plan to extend algorithm 1 to describe other aspects
xy(11,:)=[real(z3),imag(z3)];
subplot(211);
gplot (A,xy,'k-');
hold on;
plot(xy(:,1),xy(:,2),'k.','markersize',20,...
xy(8,1),xy(8,2),'r.','markersize',20,...
xy(6,1), xy(6,2), 'b.', 'markersize', 20);
hold off;
axis off;
axis square;
subplot(212);
XY=randn(M,2);
gplot (A,XY,'k-');
hold on;
plot(XY(:,1),XY(:,2),'k.','markersize',...
20, XY(8,1), XY(8,2), 'r.', 'markersize',...
20, XY(6,1), XY(6,2), 'b.', 'markersize',20);
hold off;
axis off;
axis square;
x0=COVIDHist (1:18,m);
f0=find(abs(x0) \le tol):
x=COVIDHist (1:18,n);
f1=find(abs(x)<=tol);
f2=find(abs(x)>tol);
x0(f0)=0;
x(f1)=0;
T=E;
for k=f2
T0=E;
TO(k,:)=K(k,:).*(x(k)/x0);
T=T0*T;
end
T0=ones(M,1);
y0=T*x0;
TO(f2)=x(f2)./yO(f2);
T=diag(T0)*T;
K=A+E;
end
  One can run program COVID19.m using the following
command lines in GNU Octave.
>> [K,T01,x0,x1]=COVID19(0,1,eps);
>> [K,T12,x1,x2]=COVID19(1,2,eps);
>> [K,T23,x2,x3]=COVID19(2,3,eps);
>> [K,T03,x0,x3]=COVID19(0,3,eps);
>> norm(x3-T03*x0,1)+norm((T23*T12*T01-T03)*x0,1)
```

```
ans =
         3.0531e-15
```

The spreadsheet data files together with a copy of the program COVID19.m are available at [3].

### V. Conclusion and Future Directions

The results in \( \) II can be used to derive predictive numerical simulation algorithms like algorithm 1.

Once more COVID-19 behavior data becomes available, of the COVID-19 propagation in Honduras. An extension of the ideas presented in this document to more complex geographical configuration graphs will be the subject of future communications.

#### Acknowledgment

The structure preserving matrix computations needed to implement algorithm 1, were performed with the technology of universal algebraic controllers developed in the Scientific Computing Innovation Center (CICC-UNAH) of the National Autonomous University of Honduras.

#### References

- [1] F. Vides, "Universal algebraic controllers and system identification," Submitted, 2020.
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