Resolution of PDE using domain decomposition methods on TeraFLOPic architectures

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Outline

- Introduction
- 2 Clusters
- Domain decomposition methods
 - One-level methods
 - Two-level methods
 - Numerical results
- 4 Conclusion

Context

We want to solve large systems arising from the finite element method.

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 \implies high-performance algorithms on massively parallel distributed memory multiprocessor architectures.

Within FreeFem++

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C++ plus load function within FreeFem++:

⇒ OpenMP (shared memory architectures), C for CUDA (GPGPU).

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FreeFem++ is working on the following parallel architectures (amongst others):

	N° of cores	Memory	Peak performance	Compilers
hpc1@LJLL	64@2.00 Ghz	252 Go	< 1 TFLOP/s	Intel
titane@CEA	12192*@2.93 Ghz	37 To	140 TFLOP/s	Intel
babel@IDRIS	40960@850 Mhz	20 To	139 TFLOP/s	IBM+GNU

^{* + 46080} CUDA cores

http://www-ccrt.cea.fr, Bruyères-le-Châtel, France.

http://www.idris.fr, Orsay, France.

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The original Schwarz method for a 2-way decomposition

Consider the following BVP in \mathbb{R}^d (d=2, 3):

$$\nabla \cdot \kappa \nabla u = F(u) \quad \text{in } \Omega$$
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Then, solve in parallel:

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ullet Highly heterogeneous coefficient κ in the BVP, \Longrightarrow long plateaux in the convergence of the algorithm.

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Construction of E

- build a coarse mesh $\mathcal{T}_{\text{coarse}}$, then a new fespace and a new varf on $\mathcal{T}_{\text{coarse}}$ (available under examples++-mpi/MPIGMRES*D.edp).
- ② use the low-frequency modes of the *Dirichlet-to-Neumann* operator of the BVP at the interface of each neighboring domains (Nataf *et al.*, 2011).

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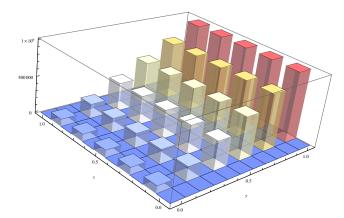
Two-level methods

- solve the global coarse problem Ex = b on one node,
- ② use the solution of the coarse problem on each local fine problem.

This is used to precondition a Krylov method (CG, GMRES) (Tang et al., 2009).

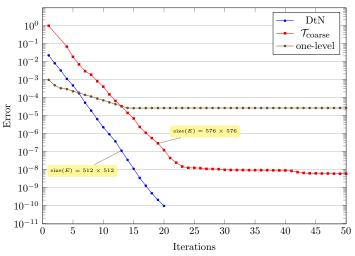
Test case in \mathbb{R}^2

with a *skyscrapper* viscosity $\kappa(x, y)$:



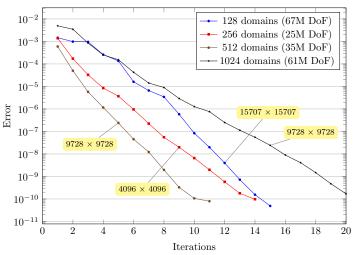
Convergence curves





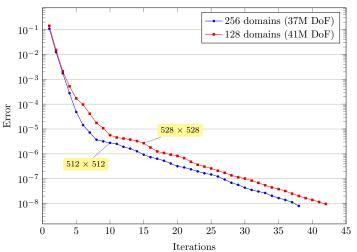
Some more 2D results

2D test case running on various number of processors using \mathbb{P}_1 FE ($\varepsilon=10^{-10}$)



And some 3D results

3D test case running on various number of processors using \mathbb{P}_2 FE ($\varepsilon=10^{-8}$)



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Final words

Concerning FreeFem++:

- efficient parallel algorithms (memory and CPU overhead with the FreeFem++ - MPI bindings),
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Concerning domain decomposition methods:

- add another level,
- 4 do parallel computations on more complex systems (e.g. elasticity).

Introduction Clusters Domain decomposition methods Conclusion

Thanks for your attention.

Nataf, F., Xiang, H., Dolean, V., & Spillane, N. 2011.

A coarse space construction based on local Dirichlet to Neumann maps, to appear.

SIAM Journal on Scientific Computing.

TANG, J.M., NABBEN, R., VUIK, C., & ERLANGGA, Y.A. 2009.

Comparison of two-level preconditioners derived from deflation, domain decomposition and multigrid methods.

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