

Non linear mechanical simulation of thin films on soft substrate in the FreeFem++ environment

P. Ventura, M. Potier-Ferry and F.Hecht*

**Laboratoire LEM3,
Université de
Lorraine, Metz,
France**

*** Laboratoire Jacques Louis
Lions, Université Pierre et
Marie Curie, Paris, France**

Outlines

- Introduction
- Asymptotic Numerical Method
- Application of the ANM to the non linear mechanical study of stiff thin films on soft substrates
- 3D implementation in the FreeFem++ environment
- Numerical results
- Conclusions

Introduction

- Wrinkles of stiff thin layers on soft materials
 - Wrinkles in nature:



leaf



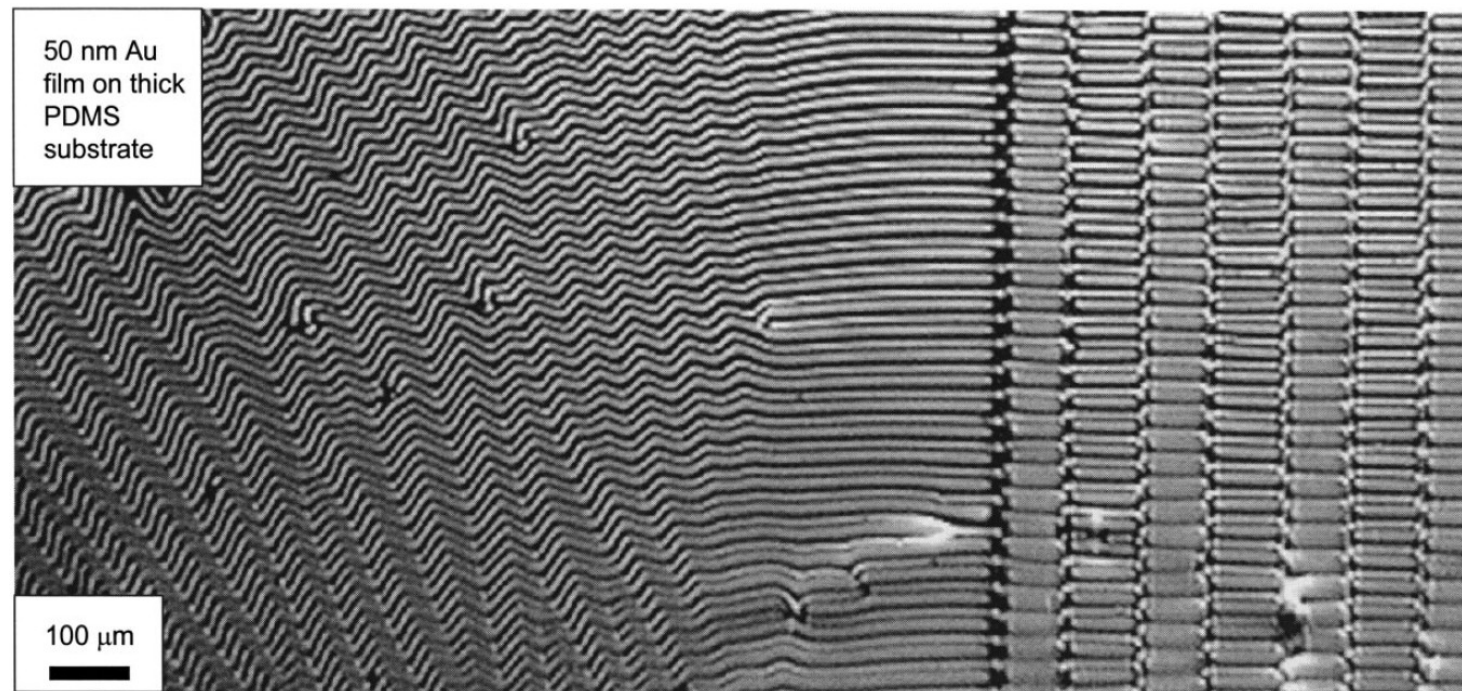
Human finger



Land form

Introduction

- Buckling of a 50 nm gold film on a thick PDMS substrate



Introduction

- Non linear mechanical problems are generally solved using predictor-corrector algorithms such as Newton Raphson scheme (Riks, 1972, 1984), (Ramm, 1981), ...
- A family of Asymptotic-Numerical-Method based on Taylor series and Finite Element Method has been developed for non linear elastic structures
 - Damil and Potier-Ferry (1990), compute perturbed bifurcations
 - Azrar, Cochelin, Damil, Potier-Ferry (1993), compute the post-buckling behavior of elastic plate
 - Cochelin, Damil, Potier-Ferry (1995), show the extension to any non linear elastic solutions

Asymptotic Numerical Method (ANM)

- Consider the non linear problem :

(1)

$$\mathbf{R}(\mathbf{U}, \lambda) = \mathbf{L}(\mathbf{U}) + \mathbf{Q}(\mathbf{U}, \mathbf{U}) - \lambda \mathbf{F} = \mathbf{0}$$

Diagram illustrating the components of the non-linear problem equation (1):

- \mathbf{U} : Unknown vector
- $\mathbf{L}(\mathbf{U})$: Linear operator
- $\mathbf{Q}(\mathbf{U}, \mathbf{U})$: Quadratic operator
- λ : Control parameter
- \mathbf{F} : Vector

- Principles of the ANM : from a known solution $(\mathbf{U}^j, \lambda^j)$, the new solution is expanded into truncated power serie of a perturbation parameter a :

(2)

$$\begin{cases} \mathbf{U}(a) = \mathbf{U}^j + \sum_{p=1}^N a^p \mathbf{U}_p \\ \lambda(a) = \lambda^j + \sum_{p=1}^N a^p \lambda_p \end{cases}$$

Asymptotic Numerical Method (ANM)

- A good choice for the parameter a is the linearized arc-length parameter defined by the projection of the pair $(\mathbf{U} - \mathbf{U}^j, \lambda - \lambda^j)$ on the tangent direction $(\mathbf{U}_1, \lambda_1)$

$$a = \langle \mathbf{U} - \mathbf{U}^j, \mathbf{U}_1 \rangle + (\lambda - \lambda^j) \lambda_1 \quad (3)$$

- By estimating the radius of convergence of the series, the validity range of a for each branch is:

$$a_{\max} = \left(\delta \frac{\|U_1\|}{\|U_N\|} \right)^{\frac{1}{N-1}} \quad (4)$$

- Truncation order: $15 \leq N \leq 50$ (5)

- tolerance δ (affects the residual): $10^{-6} \leq \delta \leq 10^{-3}$ (6)

Asymptotic Numerical Method (ANM)

- By substituting (2) into (1) and (3), and equating terms with the same power of a , we obtain the following sequence of linear problems:

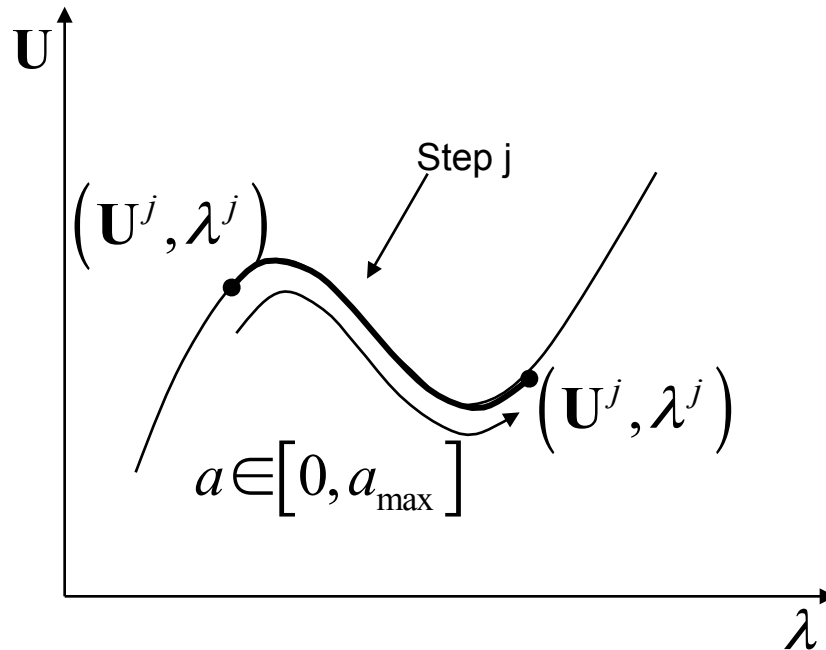
- order 1: $L_t(\mathbf{U}_1) = \lambda_1 \mathbf{F}$, and, $\langle \mathbf{U}_1, \mathbf{U}_1 \rangle + \lambda_1 \lambda_1 = 1$ (7)

- order 2: $L_t(\mathbf{U}_2) = \lambda_2 \mathbf{F} - \mathbf{Q}(\mathbf{U}_1, \mathbf{U}_1)$, and, $\langle \mathbf{U}_2, \mathbf{U}_1 \rangle + \lambda_2 \lambda_1 = 0$ (8)

- order p : $L_t(\mathbf{U}_p) = \lambda_p \mathbf{F} - \sum_{r=1}^{p-1} \mathbf{Q}(\mathbf{U}_r, \mathbf{U}_{p-r})$, and, $\langle \mathbf{U}_p, \mathbf{U}_1 \rangle + \lambda_p \lambda_1 = 0$ (9)

With, the tangent operator $\mathbf{L}_t(\cdot)$ defined by $\mathbf{L}_t(\cdot) = \mathbf{L}(\cdot) + 2\mathbf{Q}(\cdot, \mathbf{U}^j)$

Asymptotic Numerical Method (ANM)

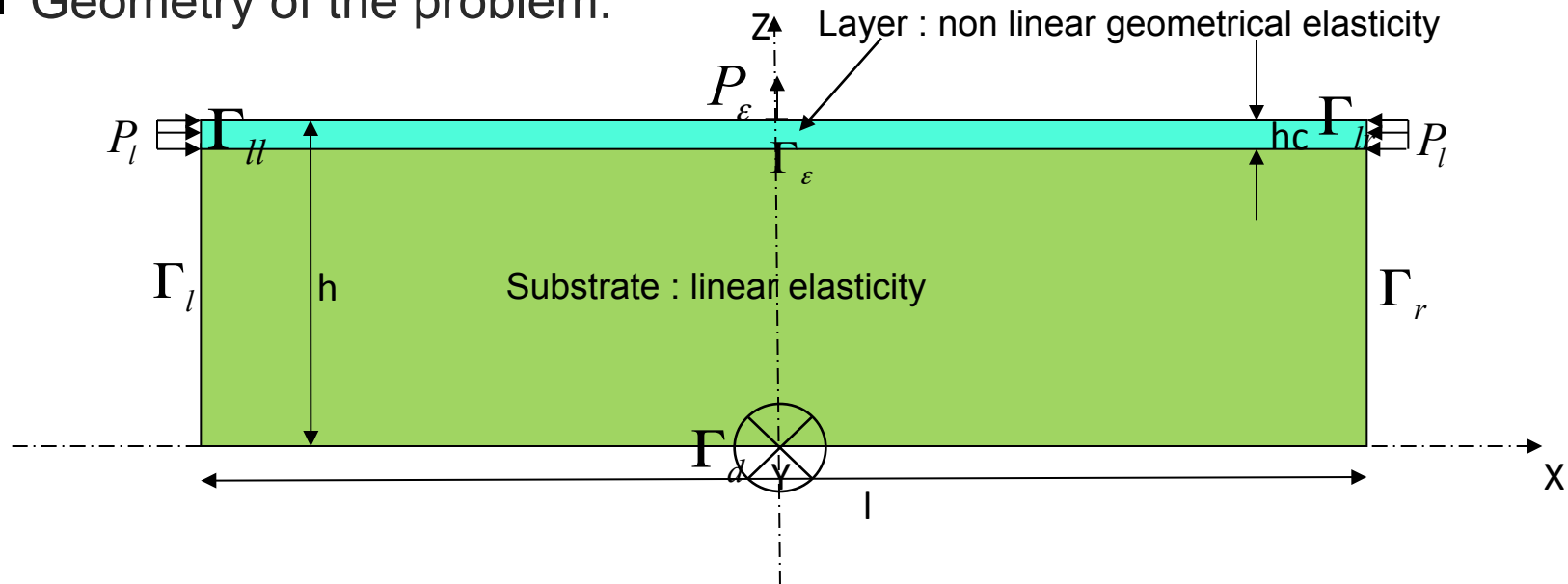


In case of bifurcation points:

► accumulation of small steps indicates the presence of a bifurcation

Application of ANM to the non linear mechanical study of thin films on soft substrate

■ Geometry of the problem:



■ Elastic coefficients:

- Substrate: $E_s = 1.8 \text{ MPa}$, $\nu_s = 0.48$
- Layer: $E_l = 1.3 \cdot 10^5 \text{ MPa}$, $\nu_l = 0.3$

- ## ■ Boundary conditions:
- on $\Gamma_l, \Gamma_{ll}, \Gamma_r, \Gamma_{rl}$, $u_Y = u_Z = 0$, on Γ_d $u_Z = 0$
 only model half structure, symmetry with respect to the ($x=0$) plane

Application of ANM to the non linear mechanical study of stiff thin films on soft substrate

- Assumptions for the mechanical model ($E_L \gg E_S$)
 - Non linear geometrical elasticity in the layer
 - Linear elasticity in the substrate
- Instabilities appear for small deformations
- Fan Xu's PhD thesis Dec 2014 : “numerical study of instability patterns of film substrate patterns”, based on a plate finite element formulation for the film.

Application of ANM to the non linear mechanical study of stiff thin films on soft substrate

- For elastic bodies, the governing equations can be stated from the mixed Hellinger-Reissner functional.

$$HR(\mathbf{u}, \mathbf{S}, \lambda) = \int_{\Omega} \left(\mathbf{S} : \underbrace{\boldsymbol{\gamma}}_{\text{Green-Lagrange strain tensor}} - \frac{1}{2} \mathbf{S} : \underbrace{\mathbf{D}^{-1}}_{\text{Elasticity matrix}} : \mathbf{S} \right) d\Omega - \lambda P_e(\mathbf{u}) \quad (10)$$

Piola-Kirchhoff stress tensor of the second kind

with,
$$P_e(\mathbf{u}) = - \int_{\Gamma_{lr}} \underbrace{P_l u_x}_{\text{Lateral surface forces}} + \int_{\Gamma_{ll}} P_l u_x + \int_{\Gamma_{\varepsilon}} P_{\varepsilon} \underbrace{u_z}_{\text{Small perturbed force}} \quad (11)$$

- Let us compute the variational formulation:

$$\int_{\Omega} \left(\mathbf{S} : \delta \boldsymbol{\gamma} + \delta \mathbf{S} : \boldsymbol{\gamma} - \mathbf{S} : \mathbf{D}^{-1} : \delta \mathbf{S} \right) d\Omega - \lambda P_e(\delta \mathbf{u}) = 0 \quad (12)$$

Application of ANM to the non linear mechanical study of stiff thin films on soft substrate

■ The Green Lagrange tensor is:

$$\gamma(\mathbf{u}) = \underbrace{\frac{1}{2}(\nabla \mathbf{u} + \nabla^T \mathbf{u})}_{\gamma_l(\mathbf{u})} + \underbrace{\frac{1}{2}(\nabla^T \mathbf{u} \cdot \nabla \mathbf{u})}_{\gamma_{nl}(\mathbf{u}, \mathbf{u})} = \gamma_l(\mathbf{u}) + \gamma_{nl}(\mathbf{u}, \mathbf{u}) \quad (13)$$

which gives:

$$\delta\gamma = \gamma_l(\delta\mathbf{u}) + \underbrace{2\gamma_{nl}(\mathbf{u}, \delta\mathbf{u})}_{\delta\gamma_{nl}(\mathbf{u}, \delta\mathbf{u})} = \gamma_l(\delta\mathbf{u}) + \delta\gamma_{nl}(\mathbf{u}, \delta\mathbf{u}) \quad (14)$$

■ The serial developments of the ANM leads to:

$$\begin{cases} \mathbf{u}(a) = \mathbf{u}^j + \sum_{p=1}^N a^p \mathbf{u}_p \\ \lambda(a) = \lambda^j + \sum_{p=1}^N a^p \lambda_p \end{cases} \quad (15)$$

Application of ANM to the non linear mechanical study of stiff thin films on soft substrate

- By introducing (15) into (12), by identifying the order p terms, we obtain the following variational formulation:

$$\begin{aligned}
 & \int_{\Omega} \delta \gamma^T(\mathbf{u}^j, \delta \mathbf{u}) \mathbf{D}(\gamma_l(\mathbf{u}_p) + 2\gamma_{nl}(\mathbf{u}^j, \mathbf{u}_p)) d\Omega + \int_{\Omega} \delta \gamma_{nl}^T(\mathbf{u}_p, \delta \mathbf{u}) \mathbf{D}(\gamma_l(\mathbf{u}^j) + 2\gamma_{nl}(\mathbf{u}^j, \mathbf{u}^j)) d\Omega \\
 & - \lambda_p P_e(\delta \mathbf{u}) + \sum_{r=1}^{p-1} \int_{\Omega} \delta \gamma_{nl}^T(\mathbf{u}_{p-r}, \delta \mathbf{u}) \mathbf{D} \left(\gamma_l(\mathbf{u}_r) + 2\gamma_{nl}(\mathbf{u}^j, \mathbf{u}_r) + \sum_{s=1}^{r-1} \gamma_{nl}(\mathbf{u}_{r-s}, \mathbf{u}_s) \right) \\
 & + \int_{\Omega} \delta \gamma^T(\mathbf{u}^j, \delta \mathbf{u}) \mathbf{D} \left(\sum_{r=1}^{p-1} \gamma_{nl}(\mathbf{u}_{p-r}, \mathbf{u}_r) \right) d\Omega = 0
 \end{aligned} \tag{16}$$

- For the first order, the resulting variational formulation is:

$$\begin{aligned}
 & \int_{\Omega} \delta \gamma^T(\mathbf{u}^j, \delta \mathbf{u}) \mathbf{D}[\gamma_l(\mathbf{u}_1) + 2\gamma_{nl}(\mathbf{u}^j, \mathbf{u}_1)] d\Omega \\
 & + \int_{\Omega} \delta \gamma_{nl}^T(\mathbf{u}_1, \delta \mathbf{u}) \mathbf{D}[\gamma_l(\mathbf{u}^j) + 2\gamma_{nl}(\mathbf{u}^j, \mathbf{u}^j)] d\Omega - \lambda_1 P_e(\delta \mathbf{u}) = 0
 \end{aligned} \tag{17}$$

Application of ANM to the non linear mechanical study of stiff thin films on soft substrate

■ P2 finite element model is used which leads to the linear systems:
(for each branch).

- Order 1:
$$\begin{cases} [\mathbf{K}_T] \hat{\mathbf{U}}_1 = \mathbf{F} \\ \lambda_1 = \frac{1}{\sqrt{1 + \hat{\mathbf{U}}_1^T \hat{\mathbf{U}}_1}} \\ \mathbf{U}_1 = \lambda_1 \hat{\mathbf{U}}_1 \end{cases}$$

- Order 2:
$$\begin{cases} [\mathbf{K}_T] \mathbf{U}_2 = \lambda_2 \mathbf{F} + \mathbf{F}_2^{nl} \quad (\mathbf{F}_2^{nl} \text{ computed using } \mathbf{U}_1) \\ \lambda_2 = -\lambda_1 (\mathbf{U}_2^{nl})^T \mathbf{U}_1 \\ \mathbf{U}_2 = \frac{\lambda_2}{\lambda_1} \mathbf{U}_1 + \mathbf{U}_2^{nl} \end{cases}$$

with, $\mathbf{U}_2^{nl} = [\mathbf{K}_T]^{-1} \mathbf{F}_2^{nl}$

Application of ANM to the non linear mechanical study of stiff thin films on soft substrate

- Order p: $[\mathbf{K}_T] \mathbf{U}_p = \lambda_p \mathbf{F} + \mathbf{F}_p^{nl}$ (\mathbf{F}_p^{nl} computed using $\mathbf{U}_1, \mathbf{U}_2, \mathbf{K}, \mathbf{U}_{p-1}$)
$$\begin{cases} \lambda_p = -\lambda_1 (\mathbf{U}_p^{nl})^T \mathbf{U}_1 \\ \mathbf{U}_p = \frac{\lambda_p}{\lambda_1} \mathbf{U}_1 + \mathbf{U}_p^{nl} \end{cases} \quad \text{with, } \mathbf{U}_p^{nl} = [\mathbf{K}_T]^{-1} \mathbf{F}_p^{nl}$$

The direction of the path in the branch is determined knowing the tangent of the displacement for the previous branch.

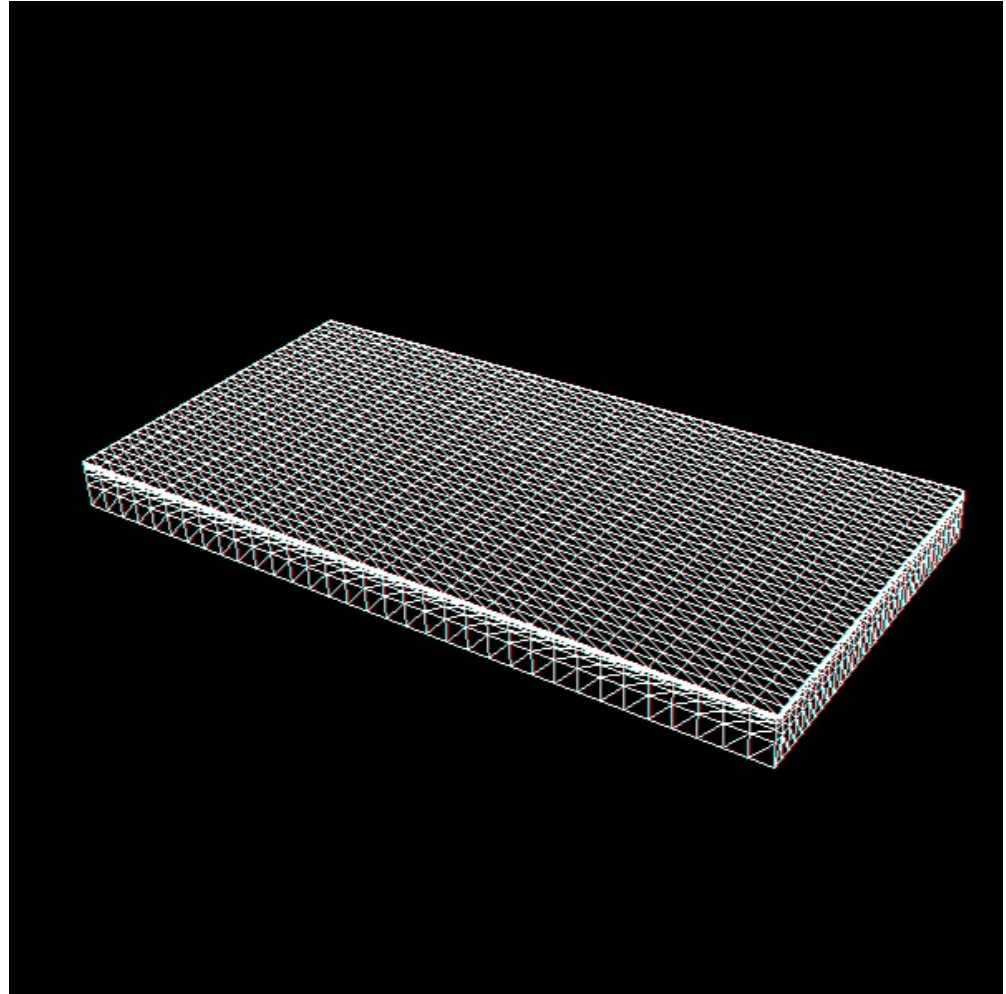
3D implementation in the FreeFem++ environment

■ Main advantages of using FreeFem++:

- use volume Finite Elements
- powerful open source mathematical libraries are available
- allows to compute problems with huge number of degrees of freedom by using parallel computing on HPC
- allows to check stability of solutions

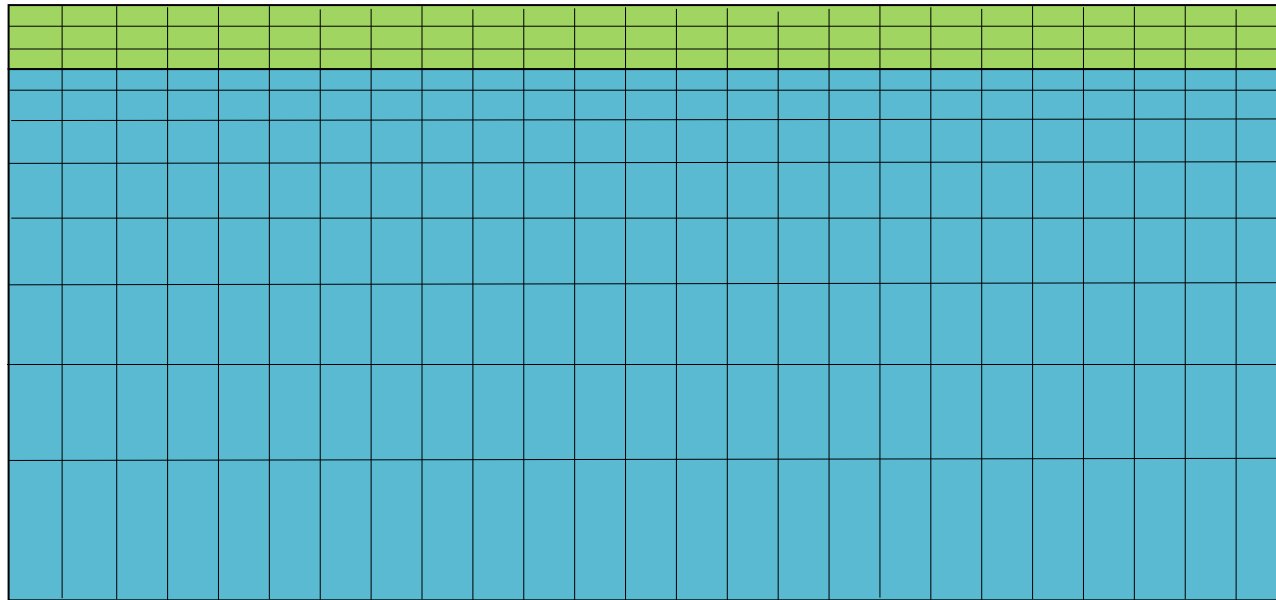
3D implementation in the FreeFem++ environment

- 3D Finite Element mesh
- Tetrahedral Finite Elements
- P2 quadratic Lagrangian interpolation
- Number of nodes: 187 005
- CPU time (almost 3 days)
- improvement with parallel programming



3D implementation in the FreeFem++ environment

- 3D mesh obtained from a 2D mesh
- 2D mesh: uniform mesh in the layer, geometrical rate in the substrate



3D implementation in the FreeFem++ environment

- Let us present the main features of the FreeFem++ code:
 - macro are used to define the Green Lagrange tensor and its differential:

```
macro GammaL(u,v,w) [dx(u),dy(v),dz(w),(dy(u)+dx(v)),(dz(u)+dx(w)),(dz(v)+dy(w)) ] // EOM
```

```
macro GammaNL(u1,v1,w1,u2,v2,w2) [ (dx(u1)*dx(u2)+dx(v1)*dx(v2)+dx(w1)*dx(w2))*0.5,  
                                     (dy(u1)*dy(u2)+dy(v1)*dy(v2)+dy(w1)*dy(w2))*0.5,  
                                     (dz(u1)*dz(u2)+dz(v1)*dz(v2)+dz(w1)*dz(w2))*0.5,  
                                     (dy(u1)*dx(u2)+dx(u1)*dy(u2)+dy(v1)*dx(v2)+dx(v1)*dy(v2)+dy(w1)*dx(w2)+dx(w1)*dy(w2))*0.5,  
                                     (dz(u1)*dx(u2)+dx(u1)*dz(u2)+dz(v1)*dx(v2)+dx(v1)*dz(v2)+dz(w1)*dx(w2)+dx(w1)*dz(w2))*0.5,  
                                     (dz(u1)*dy(u2)+dy(u1)*dz(u2)+dz(v1)*dy(v2)+dy(v1)*dz(v2)+dz(w1)*dy(w2)+dy(w1)*dz(w2))*0.5 ] // EOM
```

```
macro Gamma(u,v,w) (GammaL(u,v,w)+GammaNL(u,v,w,u,v,w)) // EOM
```

```
macro dGammaNL(u,v,w,uu,vv,ww) (2.0*GammaNL(u,v,w,uu,vv,ww)) // EOM
```

```
macro dGamma(u,v,w,uu,vv,ww) (GammaL(uu,vv,ww)+dGammaNL(u,v,w,uu,vv,ww)) // EOM
```

3D implementation in the FreeFem++ environment

- Definition of the finite element space

```
fespace Vh(Th3D,[P2,P2,P2]);
```

- Creation of the tangent matrix $\left[\mathbf{K}_T \right]$ and the second member \mathbf{F}

```
varf PbTg ([u1,v1,w1],[uu,vv,ww]) = int3d(Th3D,reg3DS) ( (GammaL(uu,vv,ww))*(DS*(GammaL(u1,v1,w1))) )
+ int3d(Th3D,reg3DL) (
    (dGamma(u[0],v[0],w[0],uu,vv,ww))*(DL*(GammaL(u1,v1,w1)+2*GammaNL(u[0],v[0],w[0],u1,v1,w1)))
    +
    (dGammaNL(u1,v1,w1,uu,vv,ww))*(DL*(GammaL(u[0],v[0],w[0])+GammaNL(u[0],v[0],w[0],u[0],v[0],w[0]))) )
+ int2d(Th3D,Irightlmid) ( Pa*uu ) + Force
+ on(Isymmid,u1=0.) + on(Irightmid,Irightlmid,v1=0.,w1=0.)+on(Idownmid,w1=0);
```

```
matrix Kt = PbTg(Vh,Vh,solver=sparse solver);
```

```
Fu[] = PbTg(0,Vh);
```

3D implementation in the FreeFem++ environment

- Computation of \mathbf{F}_2^{nl}

```
varf PbFnI2 ([utmp,vtmp,wtmp],[uuu,vvv,www]) = - int3d(Th3D,reg3DL)
( (dGammaNL(u[1],v[1],w[1],uuu,vvv,www))*(DL*(GammaL(u[1],v[1],w[1])+2*GammaNL(u[0],v[0],w[0],u[1],v[1],w[1])))
+ (dGamma(u[0],v[0],w[0],uuu,vvv,www))*(DL*(GammaNL(u[1],v[1],w[1],u[1],v[1],w[1]))) )
+ on(Isymmid,utmp=0.) + on(lrightmid,lrightlmid,vtmp=0.,wtmp=0.)+on(ldownmid,wtmp=0);
Fnlu[] = PbFnI2(0,Vh);
```

- Computation of \mathbf{F}_p^{nl} for $p > 2$: double loop sum is needed

3D implementation in the FreeFem++ environment

```
[Fnlv,Fnlv,Fnlw] = [0.,0.,0.];
```

```
for (int ir=1;ir<ipn;ir++)
```

```
{
```

```
  varf PbFnla ([utmp,vtmp,wtmp],[uuu,vvv,www]) = - int3d(Th3D,reg3DL) ( (dGammaNL(u[ipn-ir],v[ipn-ir],w[ipn-ir],uuu,vvv,www))*(DL*(GammaL(u[ir],v[ir],w[ir]) + 2*GammaNL(u[0],v[0],w[0],u[ir],v[ir],w[ir])))) );
```

```
  Fnlutmp[] = PbFnla(0,Vh);
```

```
  Fnlv[] = Fnlv[] + Fnlutmp[];
```

```
  for (int is=1;is<ir;is++)
```

```
  {
```

```
    varf PbFnlb([utmp,vtmp,wtmp],[uuu,vvv,www]) = - int3d(Th3D,reg3DL) ( (dGammaNL(u[ipn-ir],v[ipn-ir],w[ipn-ir],uuu,vvv,www))*(DL*(GammaNL(u[ir-is],v[ir-is],w[ir-is],u[is],v[is],w[is])))) );
```

```
    Fnlutmp[] = PbFnlb(0,Vh);
```

```
    Fnlv[] = Fnlv[] + Fnlutmp[];
```

```
  }
```

```
  varf PbFnlc ([utmp,vtmp,wtmp],[uuu,vvv,www]) = - int3d(Th3D,reg3DL) ( (dGamma(u[0],v[0],w[0],uuu,vvv,www))*(DL*(GammaNL(u[ipn-ir],v[ipn-ir],w[ipn-ir],u[ir],v[ir],w[ir])))) );
```

```
  Fnlutmp[] = PbFnlc(0,Vh);
```

```
  Fnlv[] = Fnlv[] + Fnlutmp[];
```

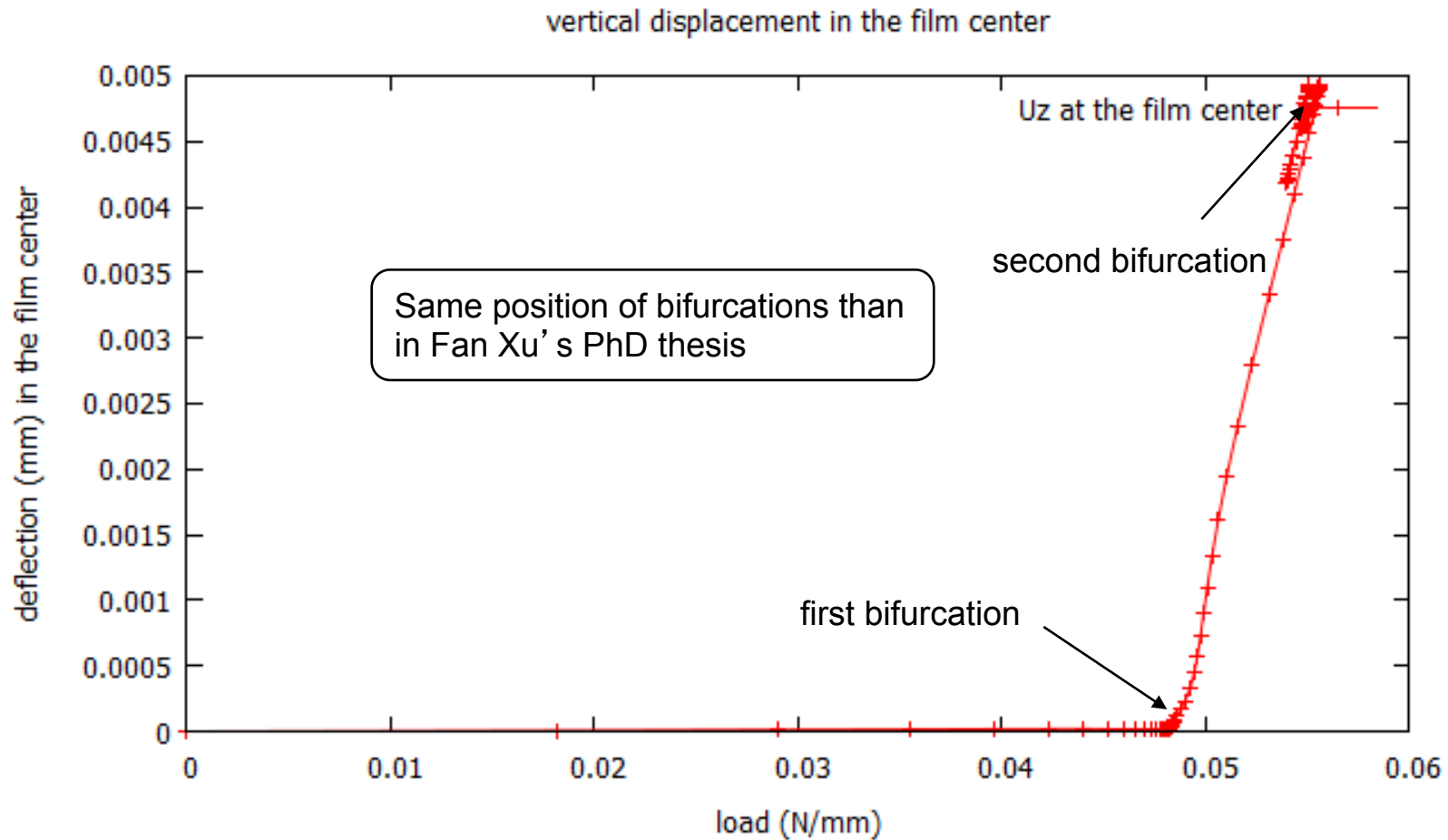
```
}
```

```
varf PbFnICL ([utmp,vtmp,wtmp],[uuu,vvv,www]) = on(Isymmid,utmp=0.) + on(Irightmid,Irightlmid,vtmp=0.,wtmp=0.) + on(Ildownmid,wtmp=0);
```

```
Fnlutmp[] = PbFnICL(0,Vh);
```

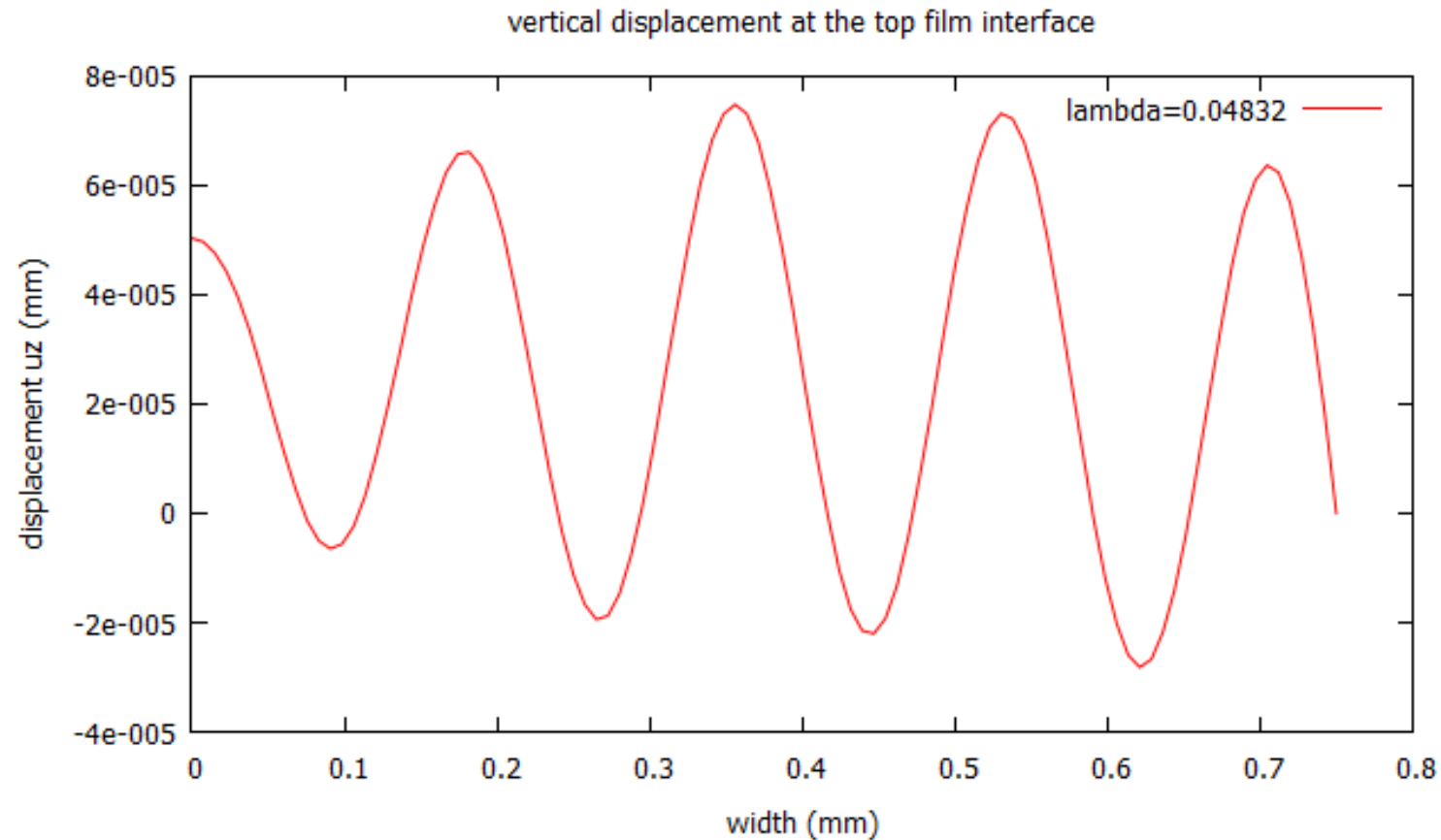
```
Fnlv[] = Fnlv[] + Fnlutmp[];
```

Numerical results



Bifurcation curve of the film / substrate under uniaxial compression

Numerical results



Vertical displacement for $\lambda = 0.04832$ at the top film interface

Conclusions

- it has been demonstrated that ANM can be used to study non linear problems
- the FreeFem++ numerical development tool is very efficient to implement the ANM algorithm of non linear mechanical problems
- it has been applied to simulate the non linear mechanical behavior of thin films on soft substrates
- both bifurcation curve and plot of the vertical displacement at the top interface have been shown
- the positions of the two first bifurcations are close to Fan Xu's results

Thank you for your attention