```
/* Example of problem solving in parallel */
 1
 2
 3
    // Usage:
     // ff-mpirun -np 12 LaplacianParallel.edp (here 12 is the number of threads (command nproc to know that)
 4
    // Need FreeFem++ with PETSc
 5
 6
 7
    // Parallel stuff
 8
    load "PETSc"
9
    macro partitioner()metis//
10
    macro dimension()2/
11
    include "./macro ddm.idp"
12
13
    macro def(i)[i]//
14
   macro init(i)[i]
15
    //macro meshN()mesh// //these macro are defined in macro ddm.idp
    //macro intN()int2d//
16
17
    // Parameters
18
19
    int nn = 500;
20
    real L = 1.;
21
    real H = 1.;
22
23
    func f = 1.;
24
    func Pk = P1;
25
26
27
    // Mesh
28
    border b1(t=0, L)\{x=t; y=0; label=1;\}
29
    border b2(t=0, H)\{x=L; y=t; label=2;\}
30
    border b3(t=L, 0){x=t; y=H; label=3;}
31
    border b4(t=H, 0)\{x=0; y=t; label=4;\}
32
    meshN Th = buildmesh(b1(1) + b2(1) + b3(1) + b4(1)); //build a really coarse mesh (just to build the fespace later)
33
34
    //\text{meshN Th} = \text{square}(1, 1, [L*x, H*y]);
35
36
    int[int] Wall = [1, 2, 3, 4];
37
38
    // Fespace
39
    fespace Uh(Th, Pk);
40
    // Mesh partition
41
42
    int[int] ArrayIntersection;
43
    int[int][int] RestrictionIntersection(0);
44
    real[int] D;
45
46
    meshN ThBorder;
    meshN ThGlobal = buildmesh(b1(nn*L) + b2(nn*H) + b3(nn*L) + b4(nn*H)); //build the mesh to partition
47
    //\text{meshN ThGlobal} = \text{square}(\text{nn*L}, \text{nn*H}, [\text{L*x}, \text{H*y}]);
48
49
    int InterfaceLabel = 10;
50
    int Split = 1;
51
    int Overlap = 1;
52
    build (Th, ThBorder, ThGlobal, Interface Label, Split, Overlap, D, ArrayIntersection, RestrictionIntersection, Uh, Pk,
         → mpiCommWorld, false); //see macro ddm.idp for detailed parameters
53
54
    // Macro
55
    macro grad(u) [dx(u), dy(u)] //
56
57
   // Problem
58
    varf vLaplacian (u, uh) //Problem in varf formulation mandatory
59
             = intN(Th)(
```

```
grad(u)' * grad(uh)
60
61
             -\inf N(Th)
62
63
                      f * uh
64
65
            + on(Wall, u=0)
66
67
68
    matrix<real> Laplacian = vLaplacian(Uh, Uh); //build the sequential matrix
69
    real[int] LaplacianBoundary = vLaplacian(0, Uh);// and right hand side
70
71
    /// In sequential, you normally do that:
    //// Solve
72
73
    //Uh \ def(u) = init(0);
74
    |\cdot|/u| = \text{Laplacian} -1 * \text{LaplacianBoundary};
75
76
    //// Plot
    //plot(u);
77
78
79
    // In parallel:
    // Matrix construction
80
81
    dmatrix PLaplacian (Laplacian, ArrayIntersection, RestrictionIntersection, D, bs=1); //build the parallel matrix
    set(PLaplacian, sparams="-pc type_lu_-pc factor mat solver package_mumps"); //preconditioner LU and MUMPS
         → solver (see PETSc doc for detailed parameters)
83
    // Solve
84
    Uh def(u)=init(0); //define the unknown (must be defined after mesh partitioning)
85
    \mathbf{u}[] = PLaplacian^-1 * LaplacianBoundary;
86
87
88
    // Export results to vtk (there is not plot in parallel)
89
            fespace PV(Th, P1);
90
91
            PV uu=u;
92
            int[int] Order = [1];
            export("Result", Th, uu, Order, mpiCommWorld);
93
94
```