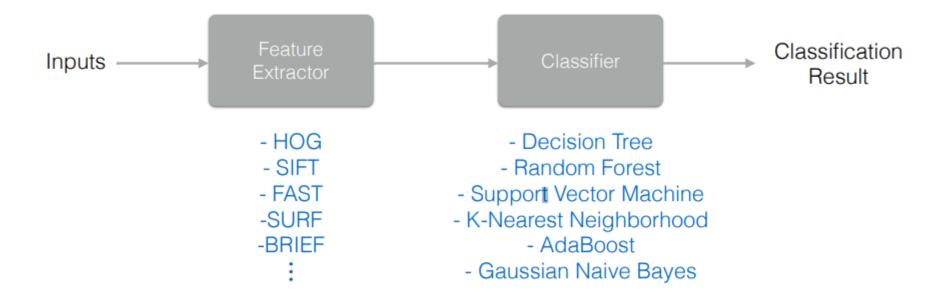
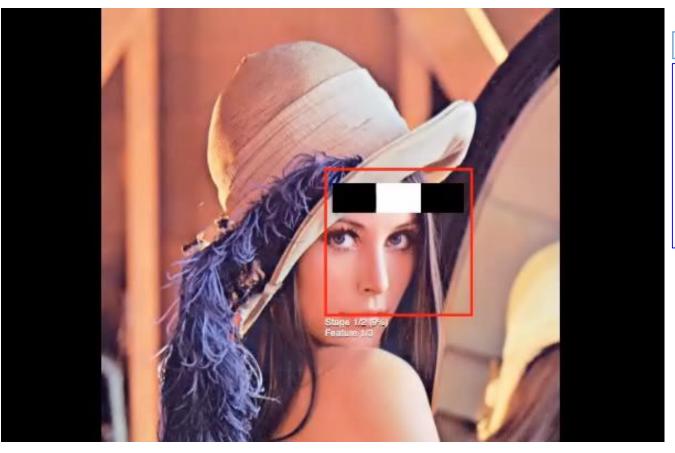
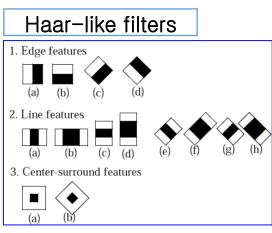
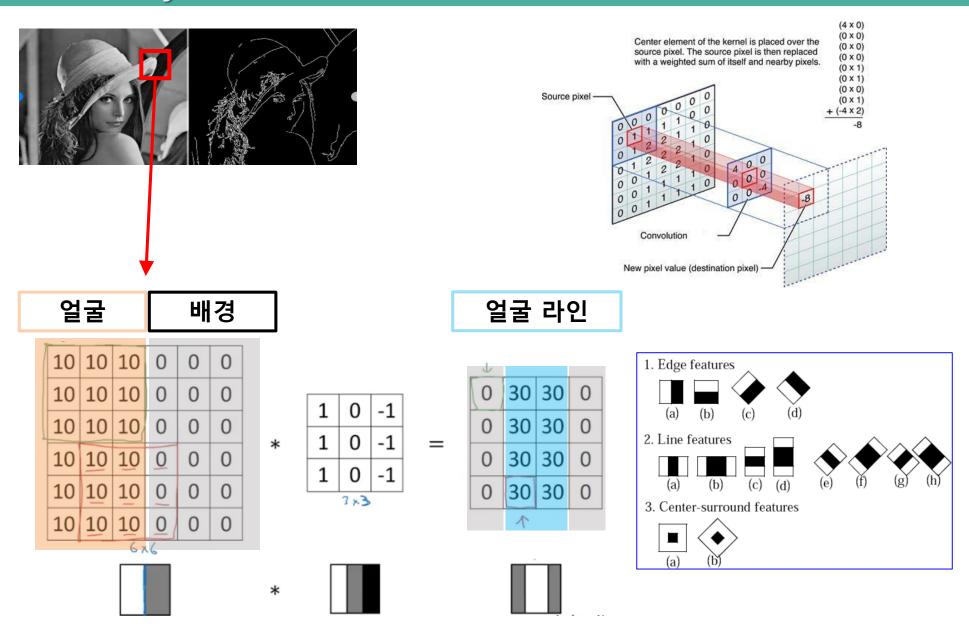
04 CNN

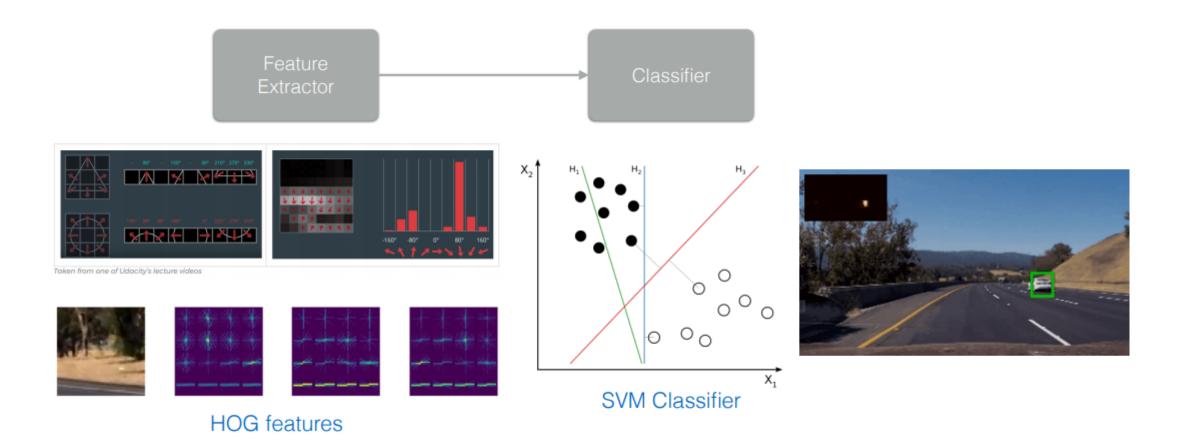


Adaptive boosting(Adaboost)



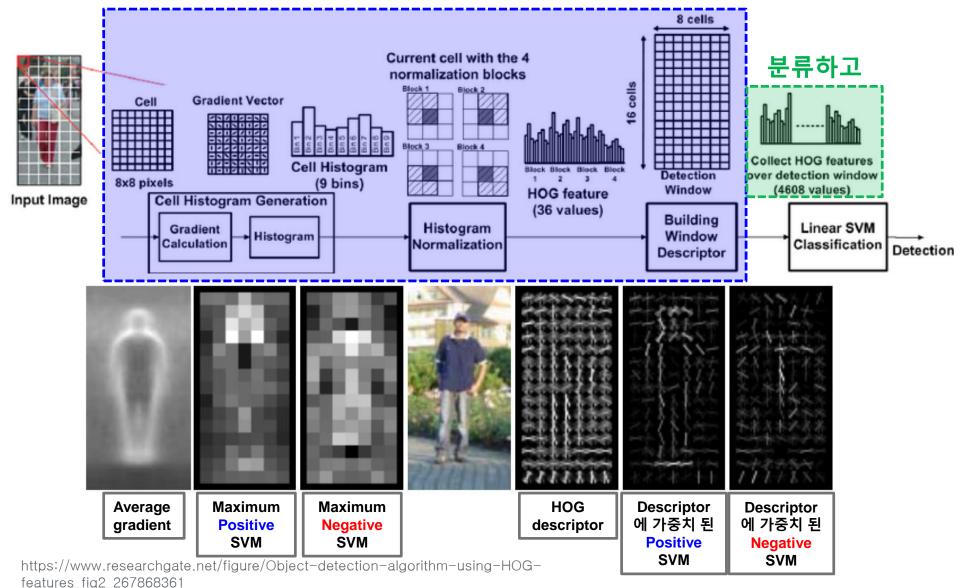






Histograms of Oriented Gradients (HoG) Detector





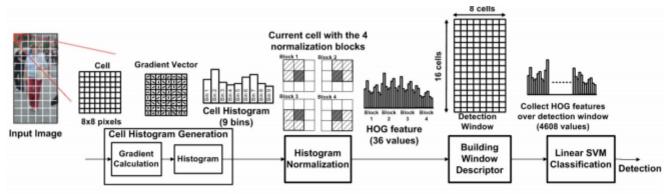


Fig. 2: Object detection algorithm using HOG features.

SVM Classifier

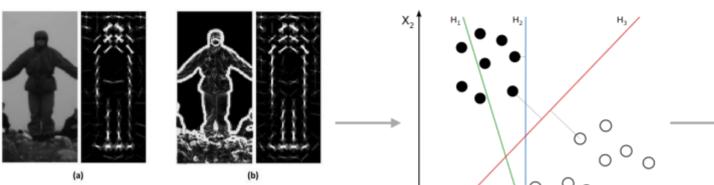
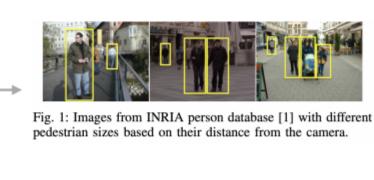
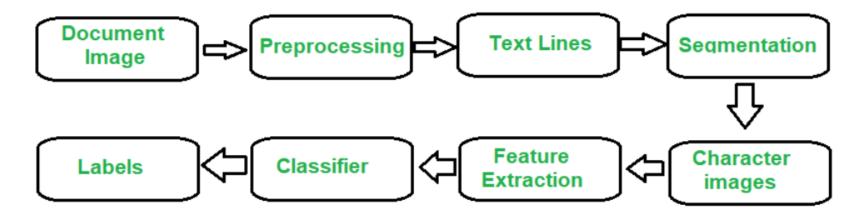


Fig. 9: Pedestrian image in (a) original and (b) gradient representations. Image is taken from INRIA person dataset [1].

HOG features





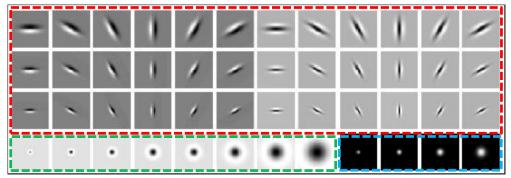
Flow Diagram of OCR

alternative interpretation of the input string. Typically, each module is manually optimized, or sometimes trained, outside of its context. For example, the character recognizer would be trained on labeled images of pre-segmented characters. Then the complete system is assembled, and a subset of the parameters of the modules is manually adjusted to maximize the overall performance. This last step is extremely tedious, time-consuming, and almost certainly suboptimal.

Classic Classifier Systems vs Neural Network

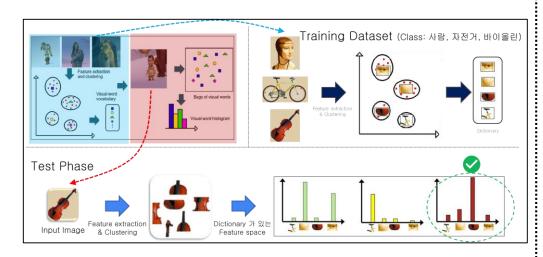
Traditional feature extraction approach

Gaussian derivative filters

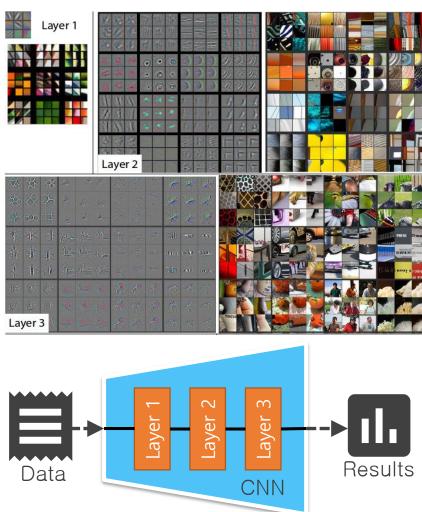


Laplacian of Gaussian filters

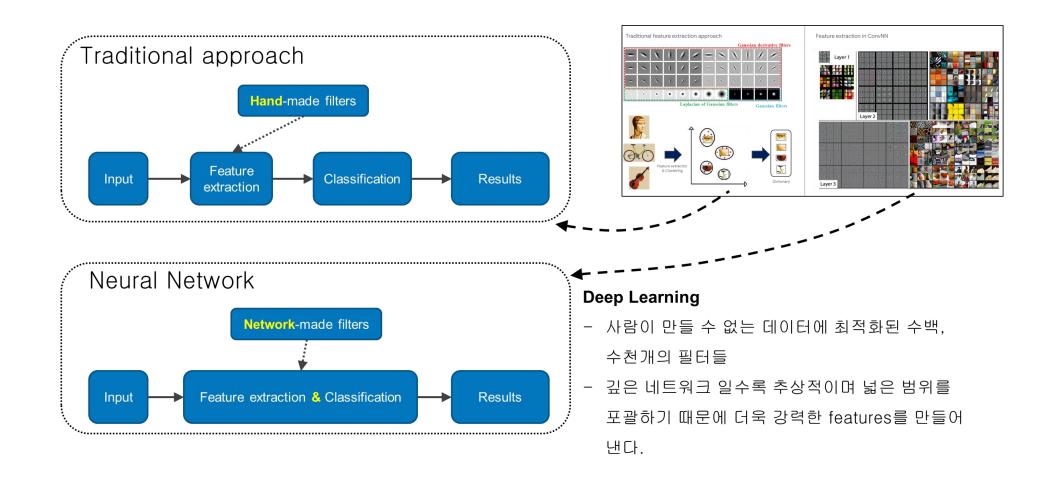
Gaussian filters

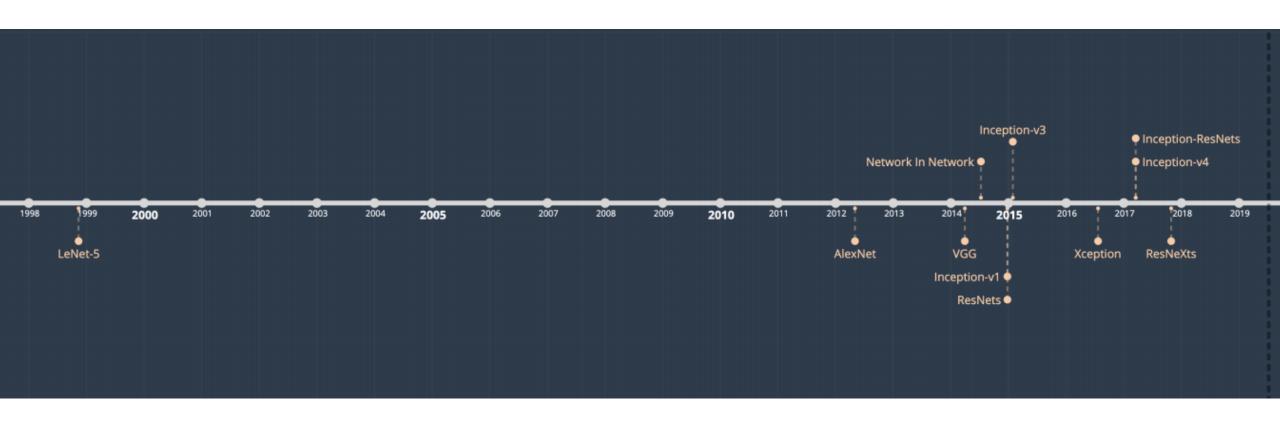


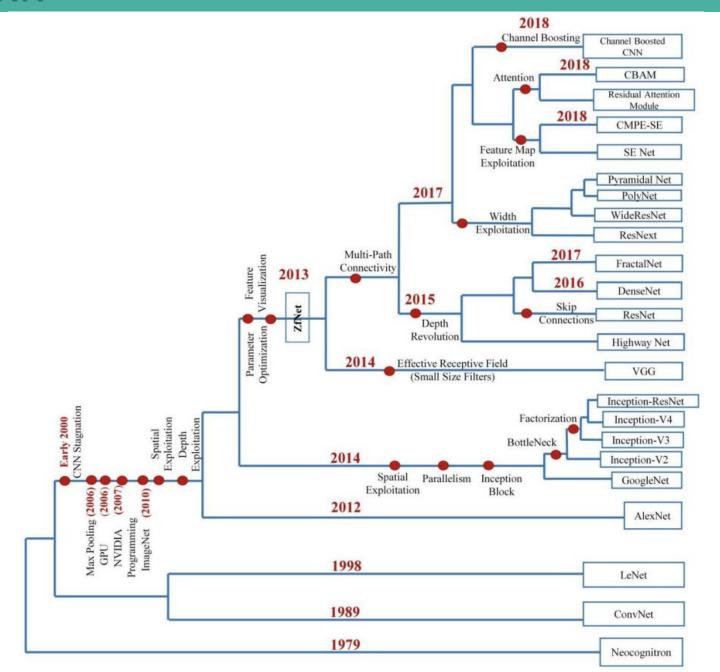
Feature extraction in CNN



Classic Classifier Systems vs Neural Network







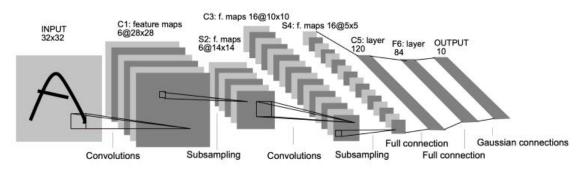
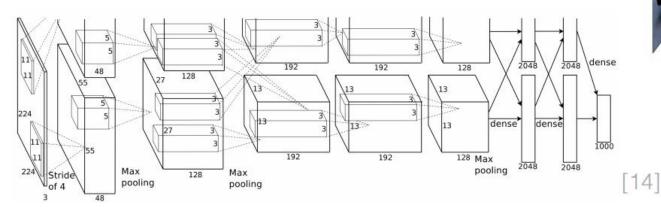
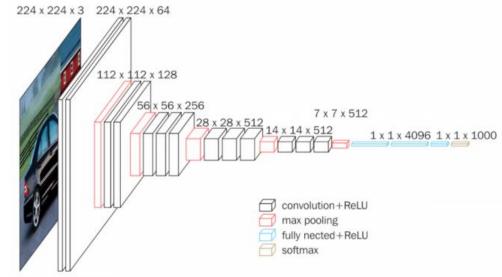


Fig. 2. Architecture of LeNet-5, a Convolutional Neural Network, here for digits recognition. Each plane is a feature map, i.e. a set of units whose weights are constrained to be identical.





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