



**FREE YOUR INNOVATION**

Freenove is an open-source electronics platform.  
[www.freenove.com](http://www.freenove.com)

## Warning

When you purchase or use this product, please note the following:

- This product contains small parts. Swallowing or improper operation them can cause serious infections and death. Seek immediate medical attention when the accident happened.
- Do not allow children under 3 years old to play with or near this product. Please place this product in where children under 3 years of age cannot reach.
- Do not allow children lack of ability of safe to use this product alone without parental care.
- Never use this product and its parts near any AC electrical outlet or other circuits to avoid the potential risk of electric shock.
- Never use this product near any liquid and fire.
- Keep conductive materials away from this product.
- Never store or use this product in any extreme environments such as extreme hot or cold, high humidity and etc.
- Remember to turn off circuits when not in use this product or when left.
- Do not touch any moving and rotating parts of this product while they are operating.
- Some parts of this product may become warm to touch when used in certain circuit designs. This is normal. Improper operation may cause excessively overheating.
- Using this product not in accordance with the specification may cause damage to the product.

## About

Freenove is an open-source electronics platform. Freenove is committed to helping customer quickly realize the creative idea and product prototypes, making it easy to get started for enthusiasts of programing and electronics and launching innovative open source products. Our services include:

- Electronic components and modules
- Learning kits for Arduino
- Learning kits for Raspberry Pi
- Learning kits for Technology
- Robot kits
- Auxiliary tools for creations

Our code and circuit are open source. You can obtain the details and the latest information through visiting the following web sites:

<http://www.freenove.com>

<https://github.com/freenove>

Your comments and suggestions are warmly welcomed, please send them to the following email address:

[support@freenove.com](mailto:support@freenove.com)

## Support

Freenove provides free and quick technical support, including but not limited to:

- Quality problems of products
- Problems in using products
- Questions for learning and technology
- Opinions and suggestions
- Ideas and thoughts

Please send email to:

[support@freenove.com](mailto:support@freenove.com)

On working day, we usually reply to you within 24 hours.

## Copyright

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The code and circuit involved in this product are released as Creative Commons Attribution ShareAlike 3.0. This means you can use them on your own derived works, in part or completely, as long as you also adopt the same license. Freenove brand and Freenove logo are copyright of Freenove Creative Technology Co., Ltd and cannot be used without formal permission.



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## Preface

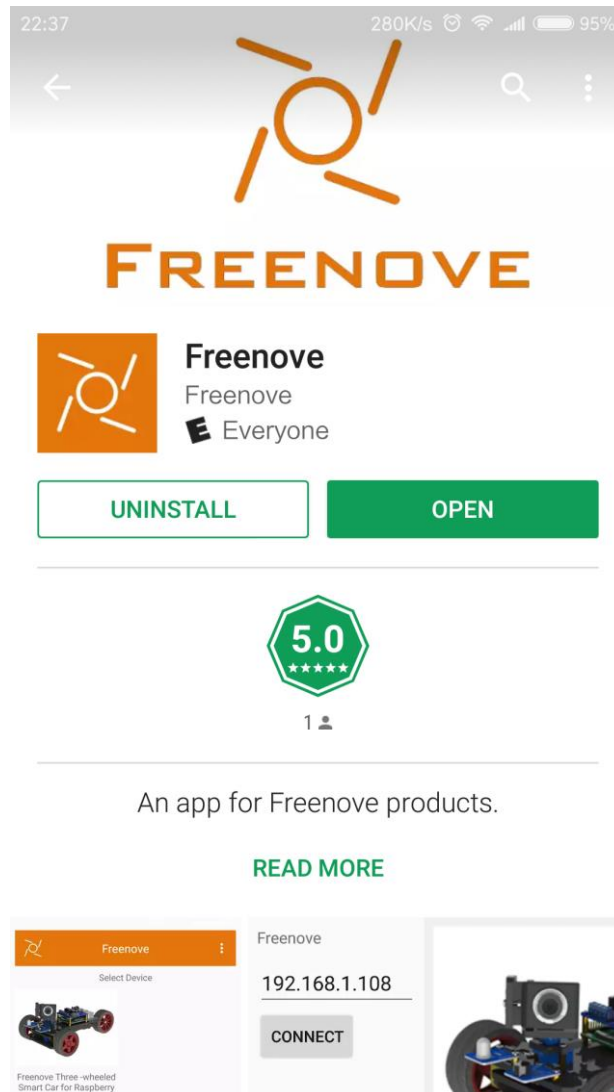
Welcome to use Freenove products. Freenove app for Freenove is the controller of Freenove official device (robot /car/aircraft, etc.), which will make you to enjoy using Android devices to control the the robot device.

# Install Freenove app

We have provided three ways to install app, you can choose any one.

## Method 1

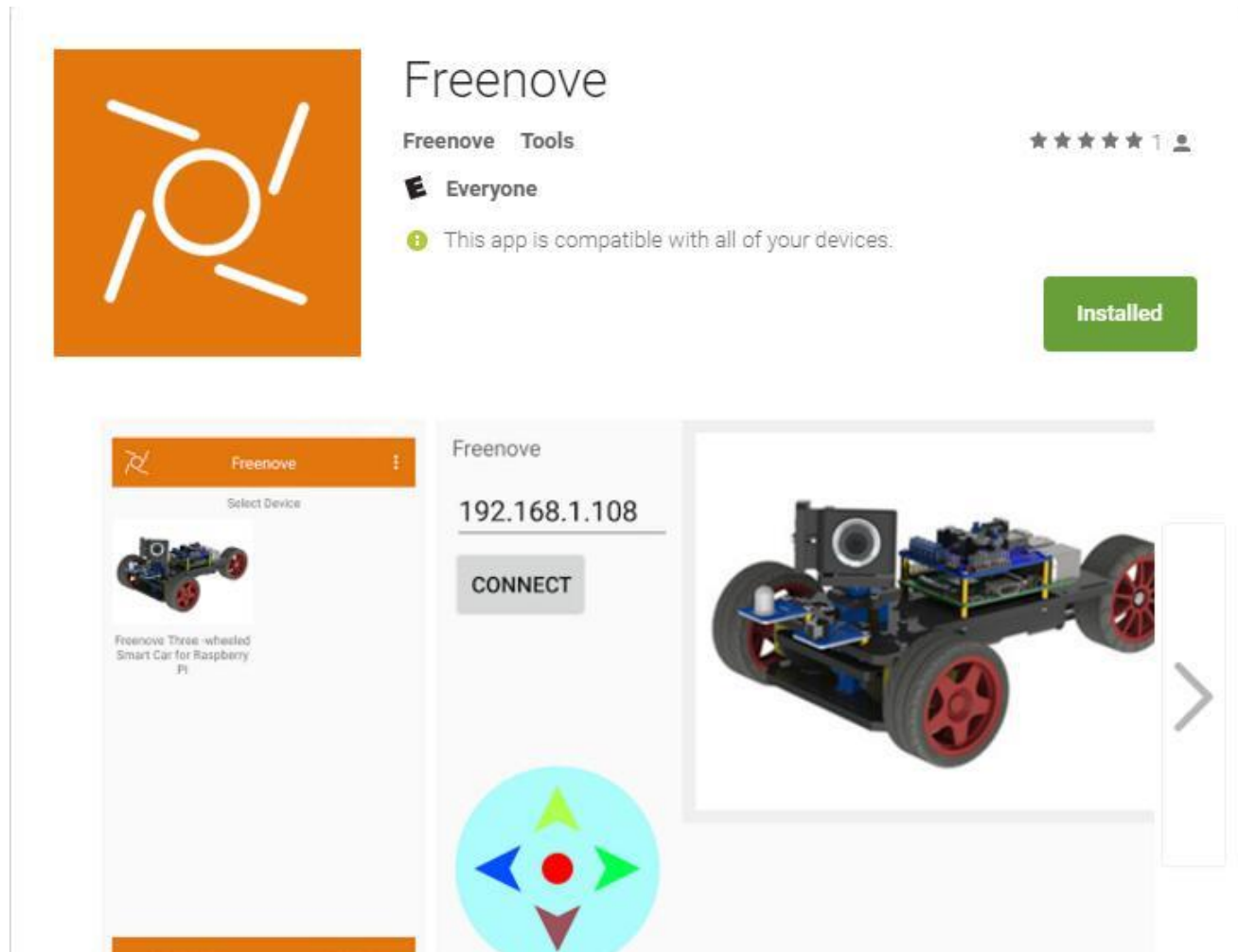
Use Google play to search “freenove”, download and install.





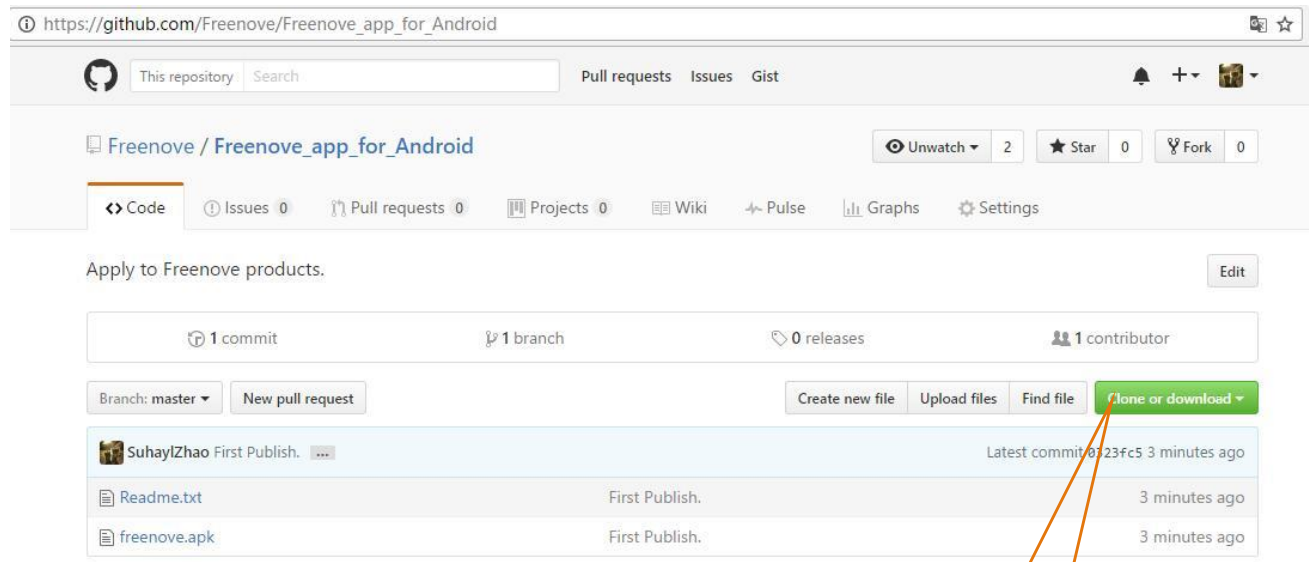
## Method 2

Visit <https://play.google.com/store/apps/details?id=com.freenove.suhayl.Freenove>, and click install.



## Method 3

Visit [https://github.com/Freenove/Freenove\\_app\\_for\\_Android](https://github.com/Freenove/Freenove_app_for_Android), download the files in this library, and install freenove.apk to your Android phone manually.



https://github.com/Freenove/Freenove\_app\_for\_Android

This repository Search Pull requests Issues Gist

Freenove / Freenove\_app\_for\_Android Unwatch 2 Star 0 Fork 0

Code Issues 0 Pull requests 0 Projects 0 Wiki Pulse Graphs Settings

Apply to Freenove products. Edit

1 commit 1 branch 0 releases 1 contributor

Branch: master New pull request Create new file Upload files Find file Clone or download

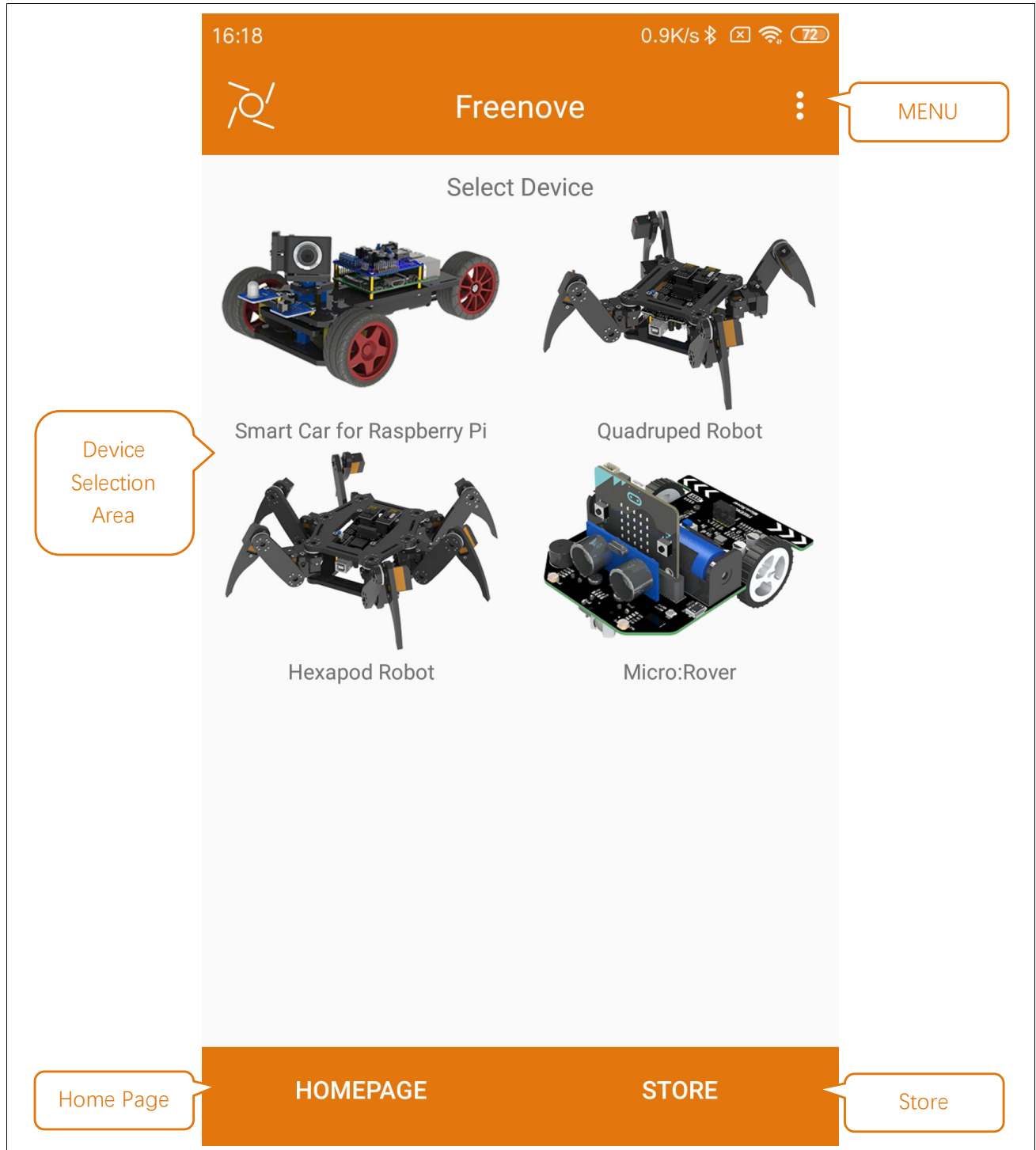
SuhaylZhao First Publish. Latest commit: 23fc5 3 minutes ago

Readme.txt	First Publish.	3 minutes ago
freenove.apk	First Publish.	3 minutes ago

Click here to download.

# Using

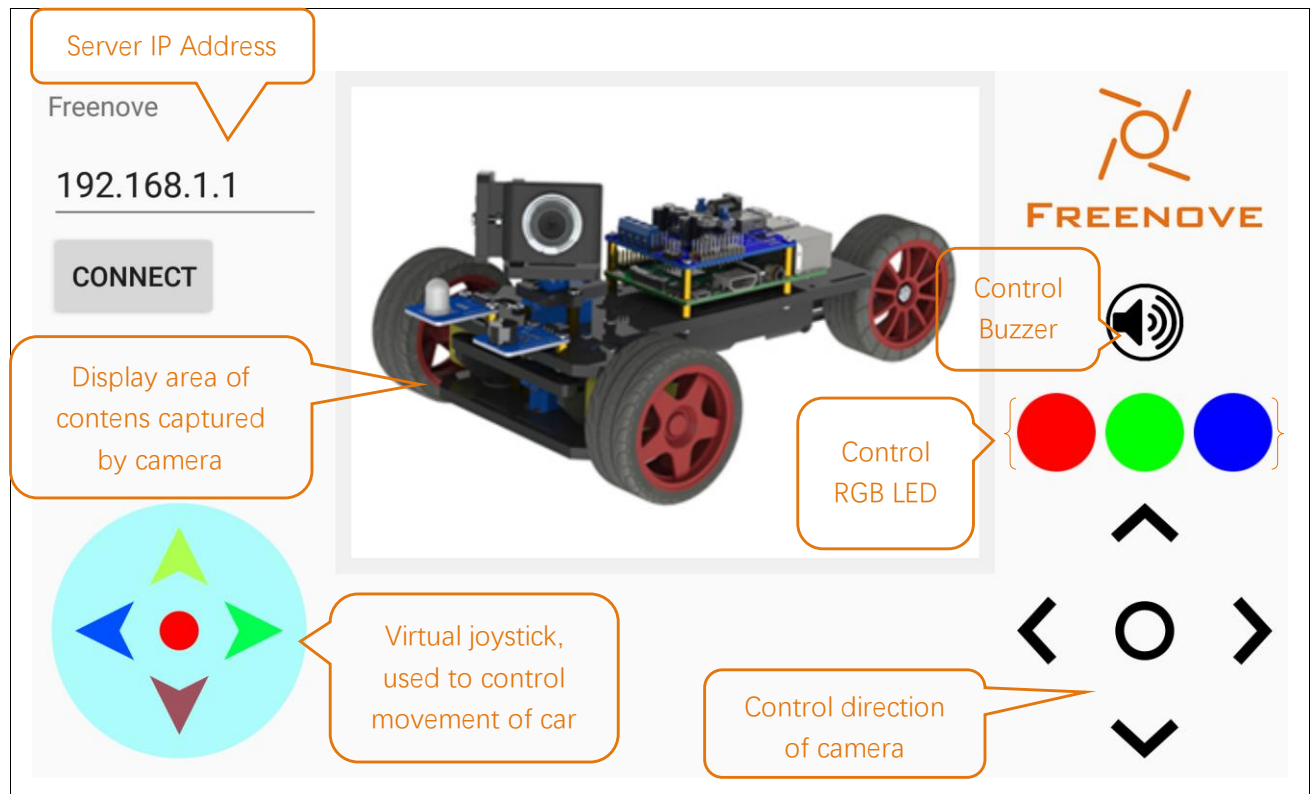
Open application "Freenove", as shown below:



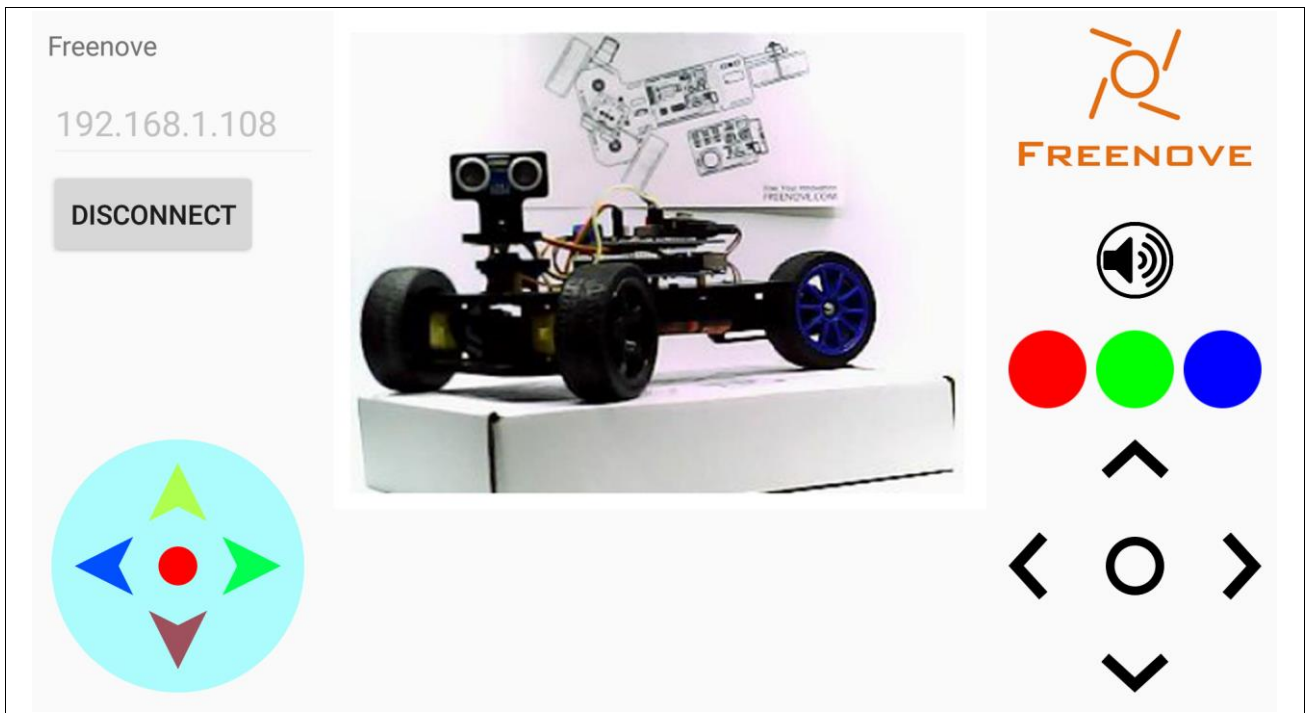
There will be more Freenove products added to the device selection area in the future.

# Freenove Three-wheeled Smart Car Kit for Raspberry Pi

Click "Smart Car for Raspberry Pi". then application jump to following interface.



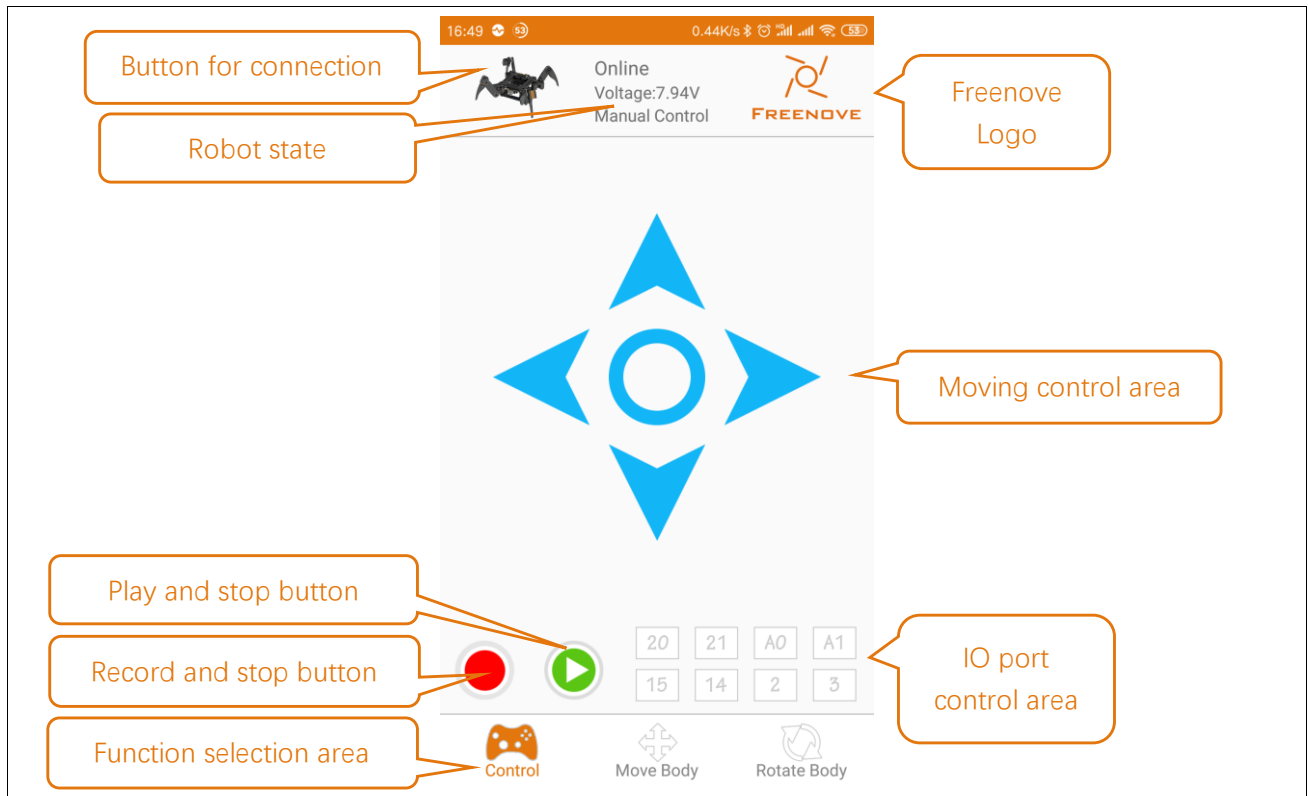
Make sure camera and TCP services of the RPi have been opened. Then enter your RPi IP address in the column Server IP Address, click the button CONNECT. Then the connection succeeds later. RPi IP address is 192.168.1.108. after a successful connection, the interface is shown below.



The IP address will be stored after correct connection, so that it can be used multiple times without having to output the IP address every time. Then you can control the car.

# Freenove Quadruped Robot Kit

Click Freenove Freenove Quadruped Robot Kit, then app jumps to the following interface.



If your Android device has been connected to the robot via WiFi, then the app will connect the robot automatically.

Under this page:

In moving control area, you can control robot to move back or forth and left or right, through touching arrow control button.

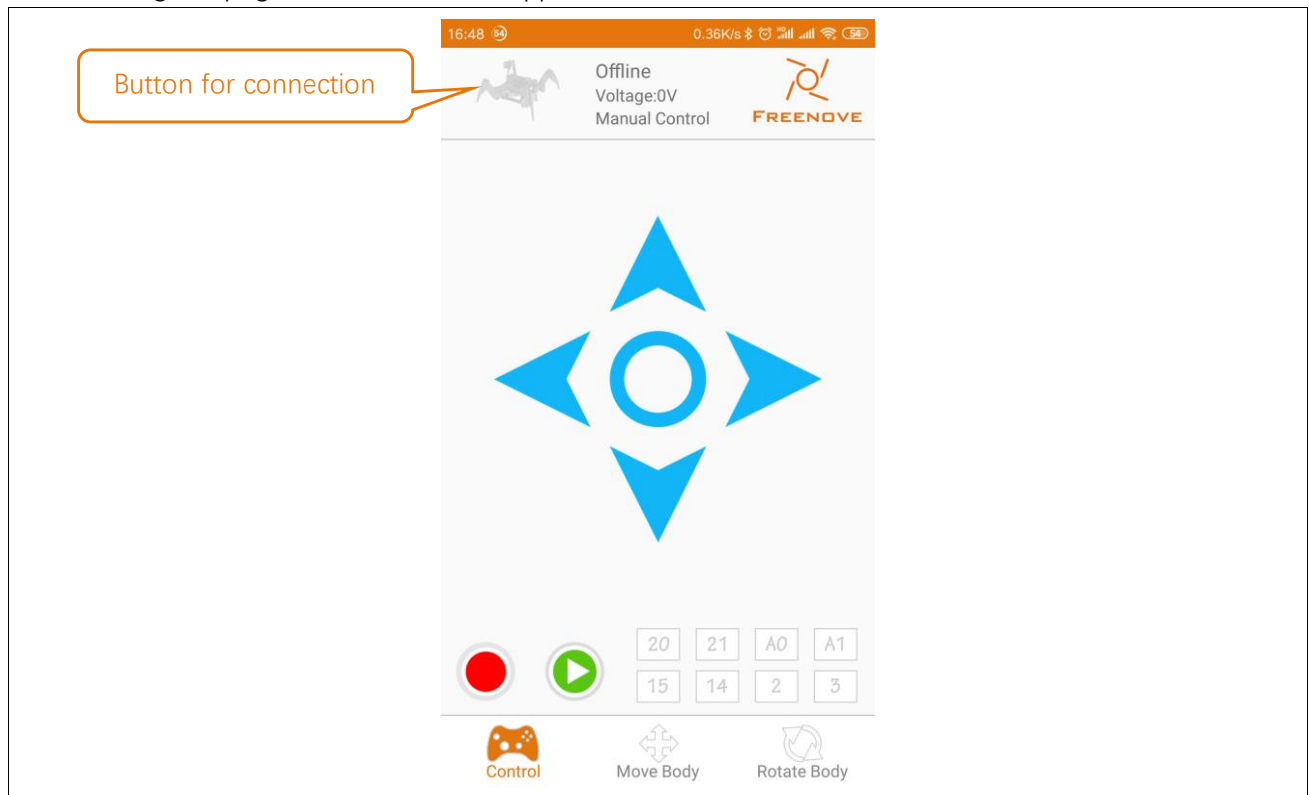
When you click the center, robot will sit down or stand up.

In IO port control area, you can also control different IO ports of robot to output high or low level, through touching different buttons.

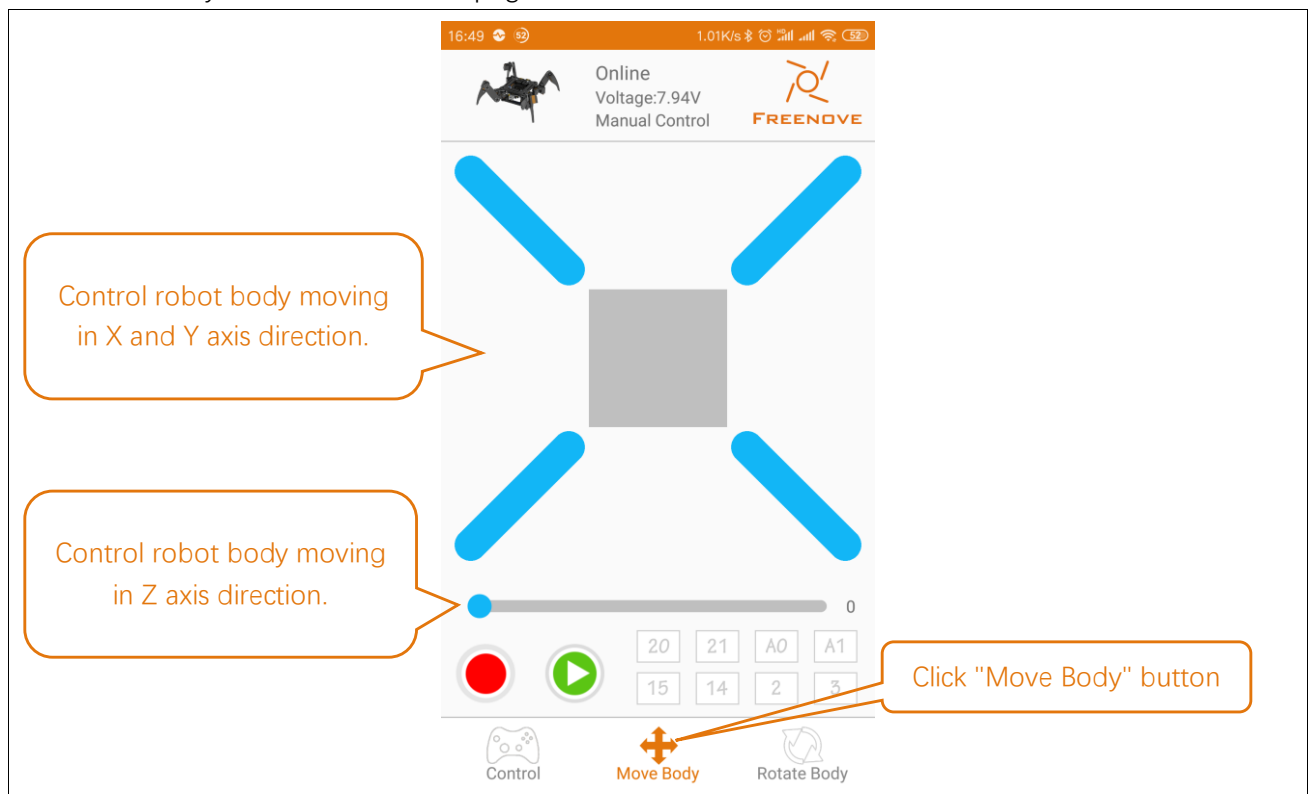
We will introduce the rest red and green button latter.

If the WiFi of your Android device is not connected to the robot, you will not be able to control the robot directly. If the connection succeeds, you can touch the robot indication icon to connect on the top left, or reopen Freenove app connection.

The following is a page screenshot of the app under offline.

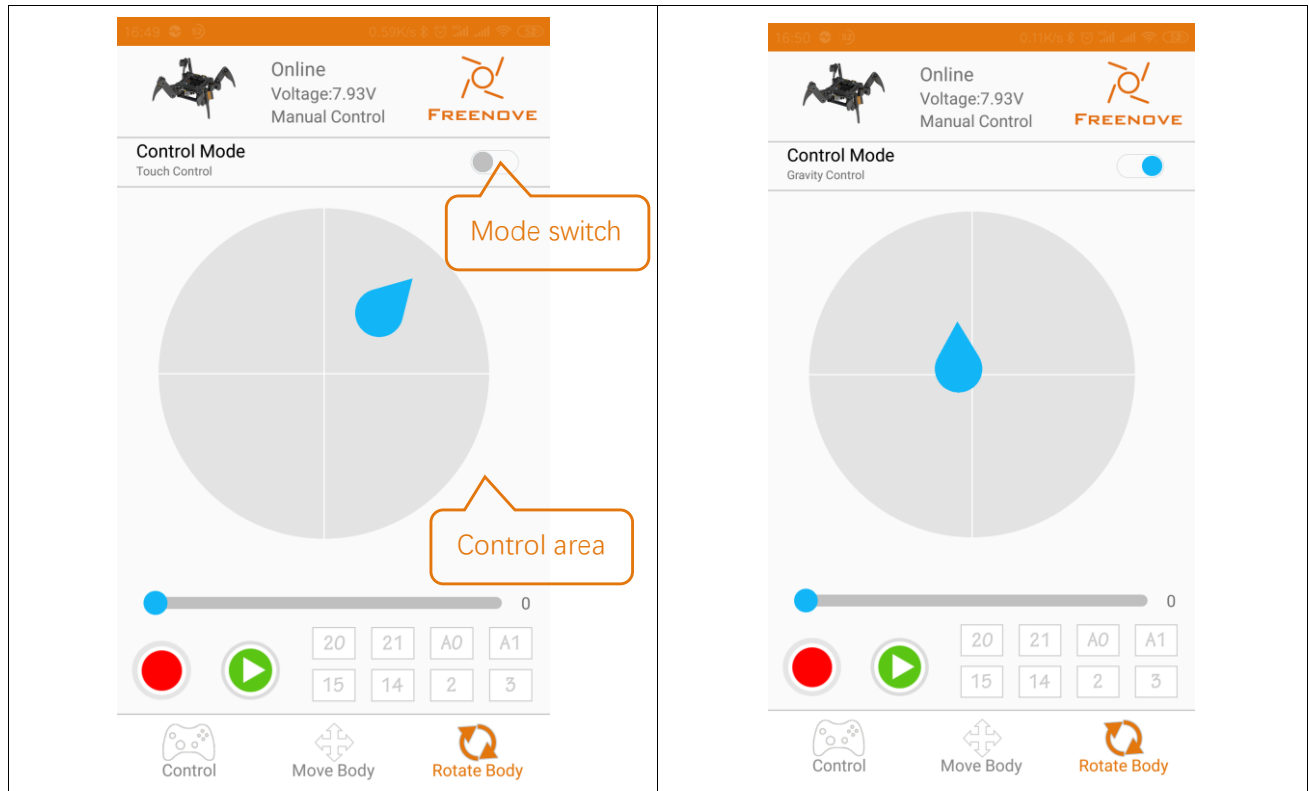


Click "Move Body" button to enter the page below.



In this page, you can control the robot body moving in three-dimensional space and with its feet no moving.

Click "Rotate Body" button to enter the page below.



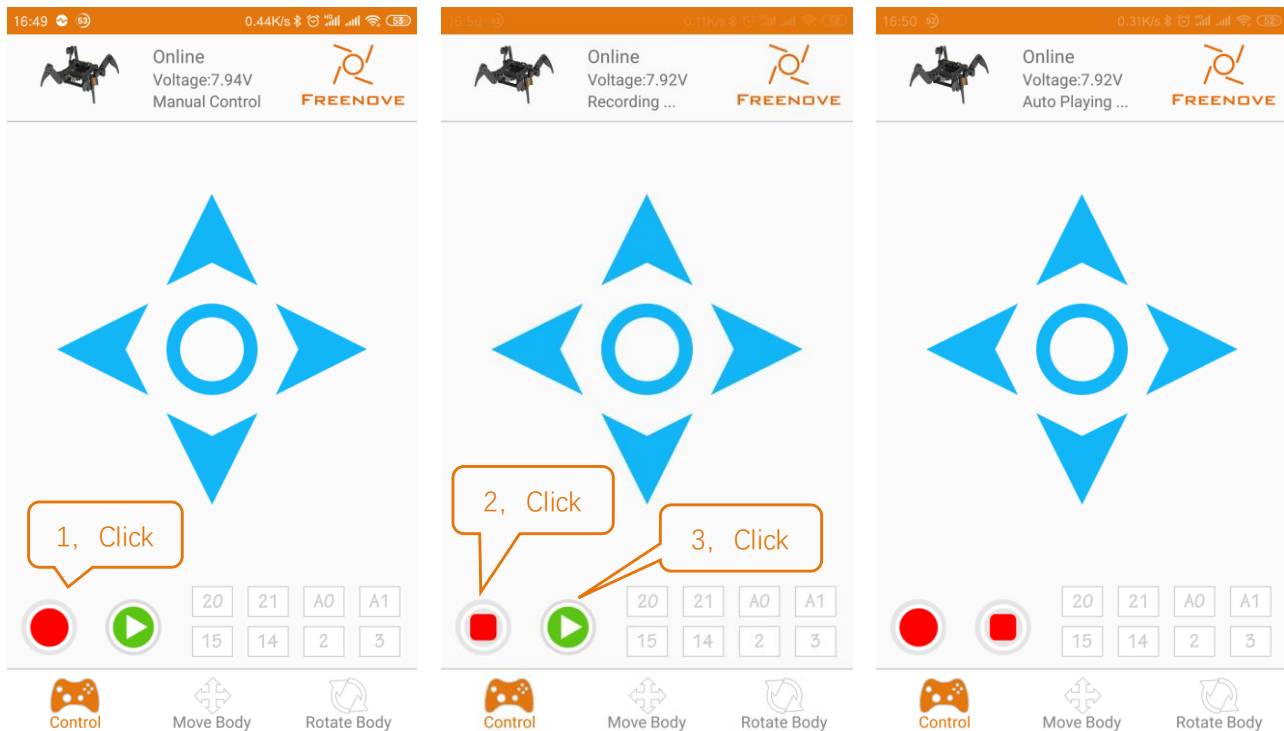
In this page, you can control robot body to rotate along the X, Y, Z axis. You can use one finger to drag the blue drip or use two fingers to rotate the blue drip.

Mode switch is used to switch control mode. Left is touch control mode and right is gravity control mode.

Under gravity control mode, tilt your cell phone to control.



Now we will introduce the record function.



Nomatter which interface the app is in, you can use this function.

First, press red circular button. Then it become red square button. The app starts to record your operation. Under this process, you can switch different fuction selections and do whatever operation you want. When you want to end recording, just press red square button, nomatter which page you are in.

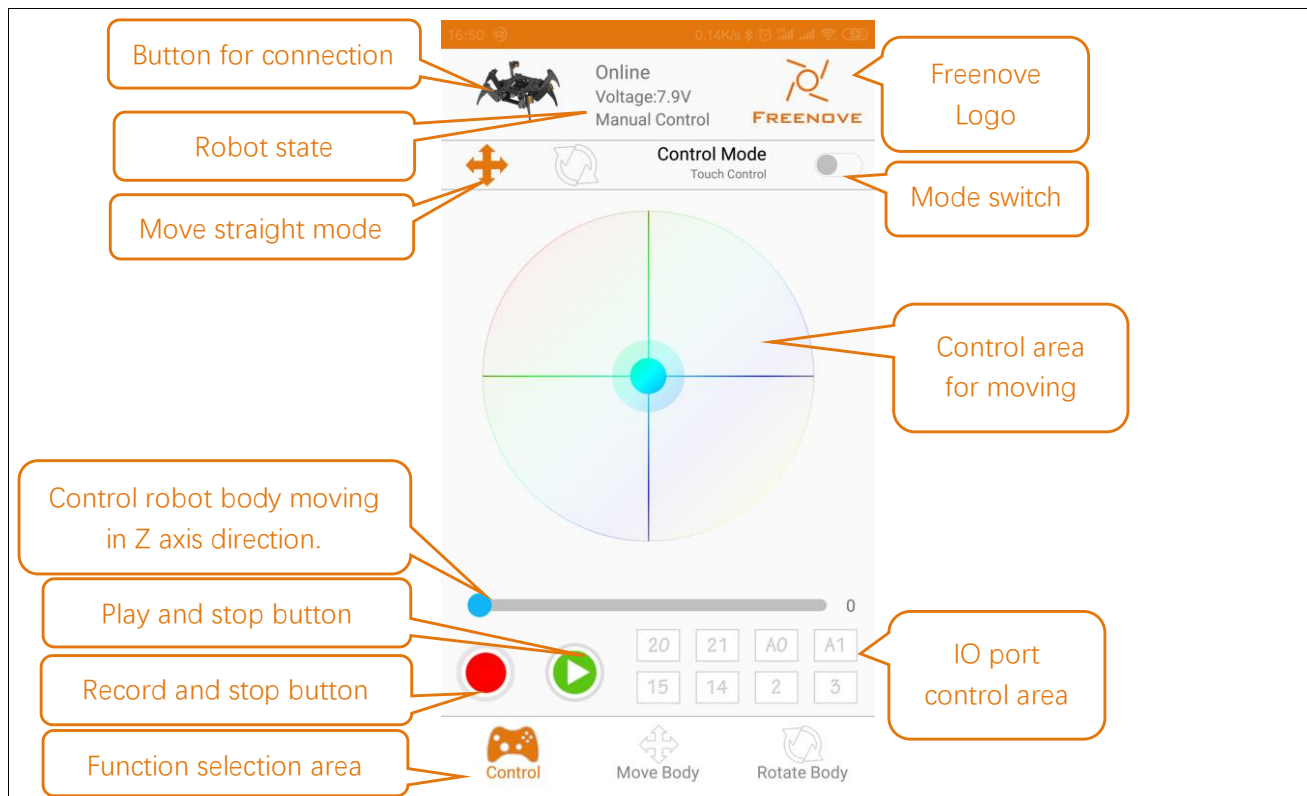
Second, press green circular button to play. Then it become red square button. You can press it to end the playing or wait for automatic end.

And the app will save only one record until you record another set of operations. So you can play a record many times.

You can also press green circular button to play without ending recording.

# Freenove Hexapod Robot Kit

Click Freenove Hexapod Robot Kit, then it jumps to the following interface.



If your Android device has been connected to the robot via WiFi, then the app will connect the robot automatically.

Under this page. Click move straight mode:

In control area, you can control robot to move in any direction. First you can click any position in Ring area. And you can drag the circular button to any position. The moving speed is depend on the distance to center. And When you click the center, robot will sit down or stand up.

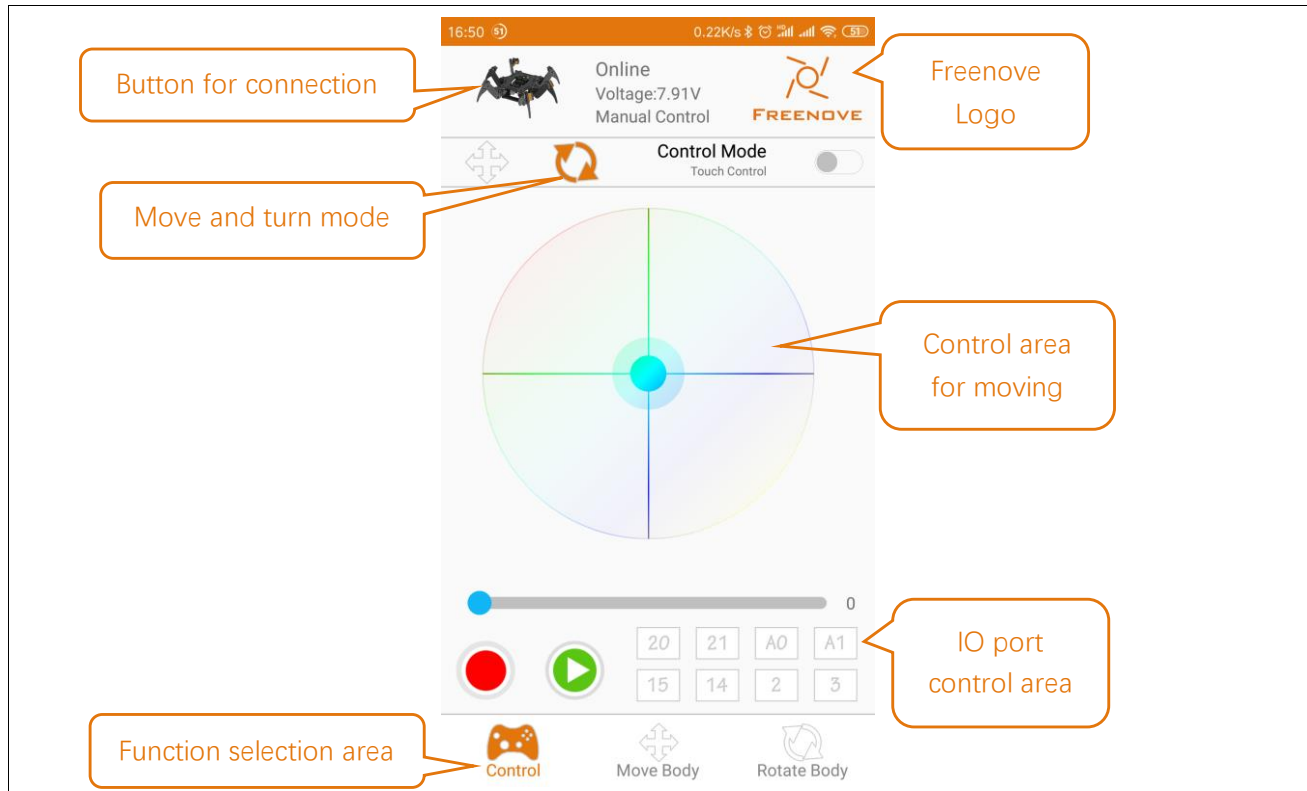
In IO port control area, you can also control different IO ports of robot to output high or low level, through touching different buttons.

Slider is used to Control robot body moving in Z axis direction.

Mode switch is used to switch control mode. Left is touch control mode and right is gravity control mode. Under gravity control mode, tilt your cell phone to control.

We will introduce the rest red and green button latter.

Under this page. Click move straight mode



In control area:

When circular button is in Y axis, the robot will move forth or back. When circular button is in x axis, the robot will turn in original place.

If circular button is in other positons, the robot will turn with certain turning radius.

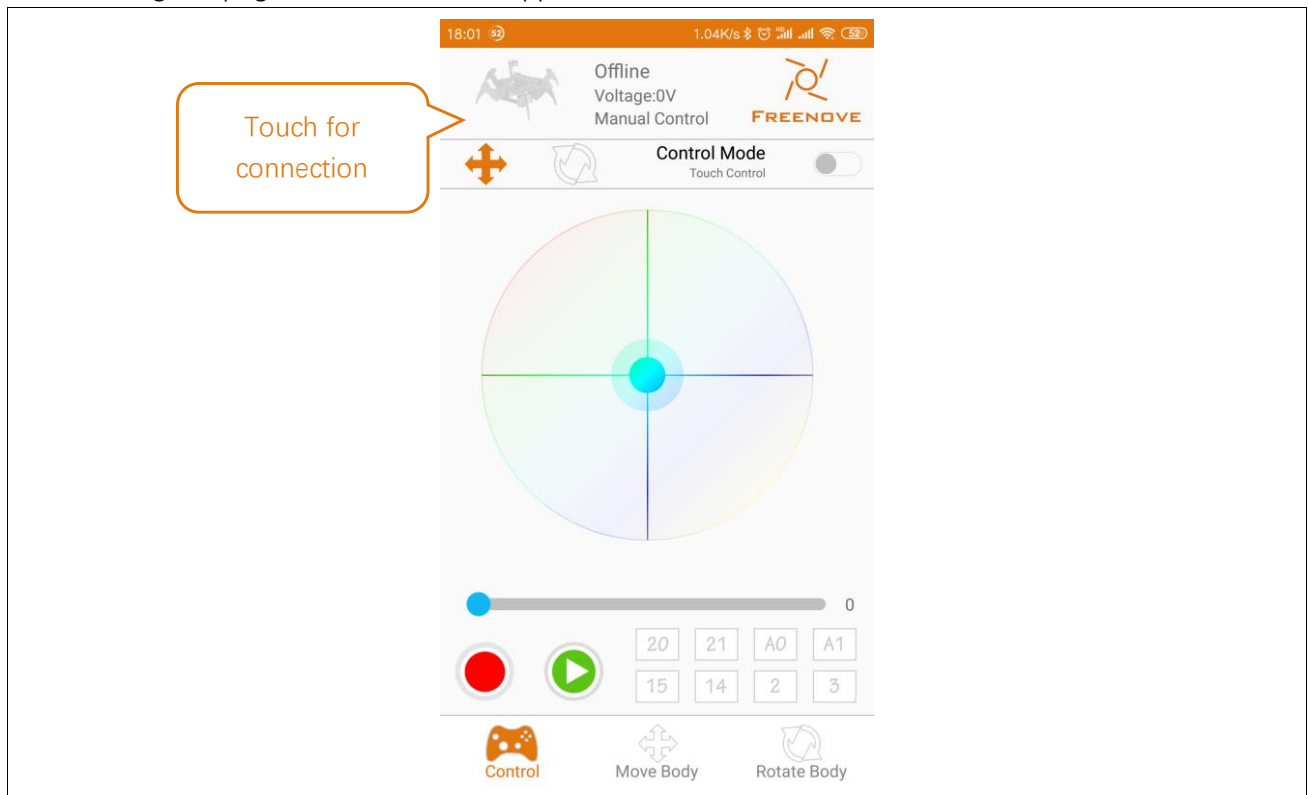
The closer the distance to the x-axis, the smaller the turning radius.

Mode switch is used to switch control mode. Left is touch control mode and right is gravity control mode.

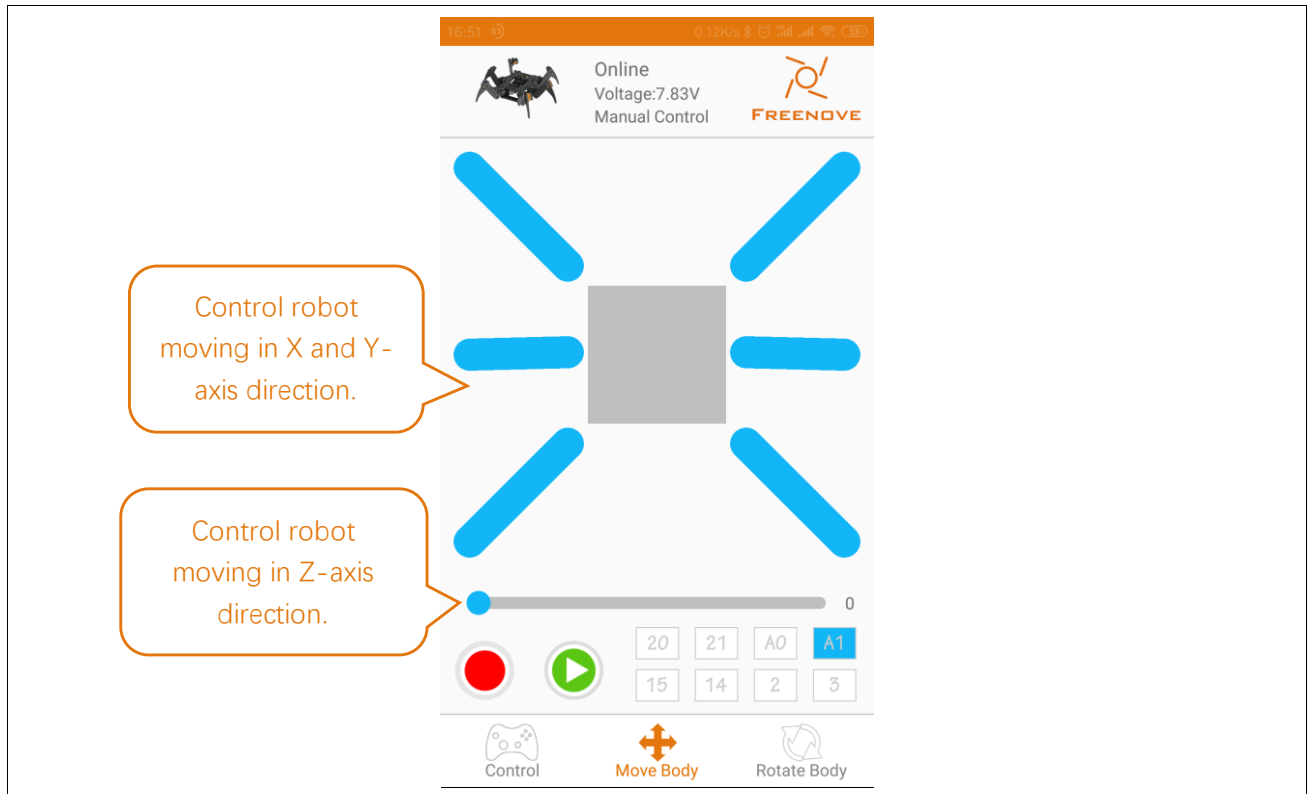
Under gravity control mode, tilt your cell phone to control.

If the WiFi of your Android device is not connected to the robot, you will not be able to control the robot directly. If the connection succeeds, you can touch the robot indication icon to connect on the top left, or reopen Freenove app connection.

The following is a page screenshot of the app under offline.

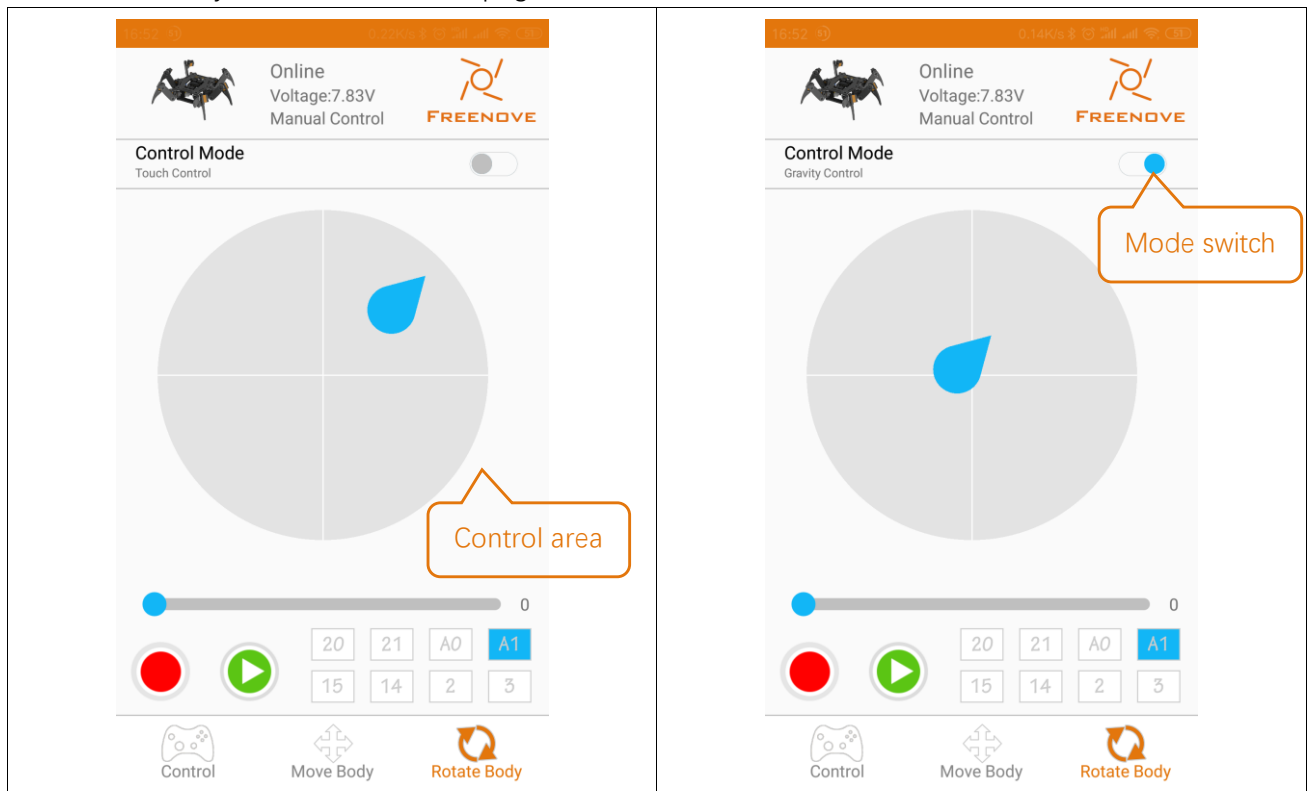


Click "Move Body" button to enter the page below.



In this page, you can control the robot body moving in three-dimensional space and with its feet no moving. Here, controlling robot to move in Z axis direction will not influence the robot position in X axis under control function selection. And A1 button is pressed in this page, so IO port A1 outputs high level.

Click "Rotate Body" button to enter the page below.



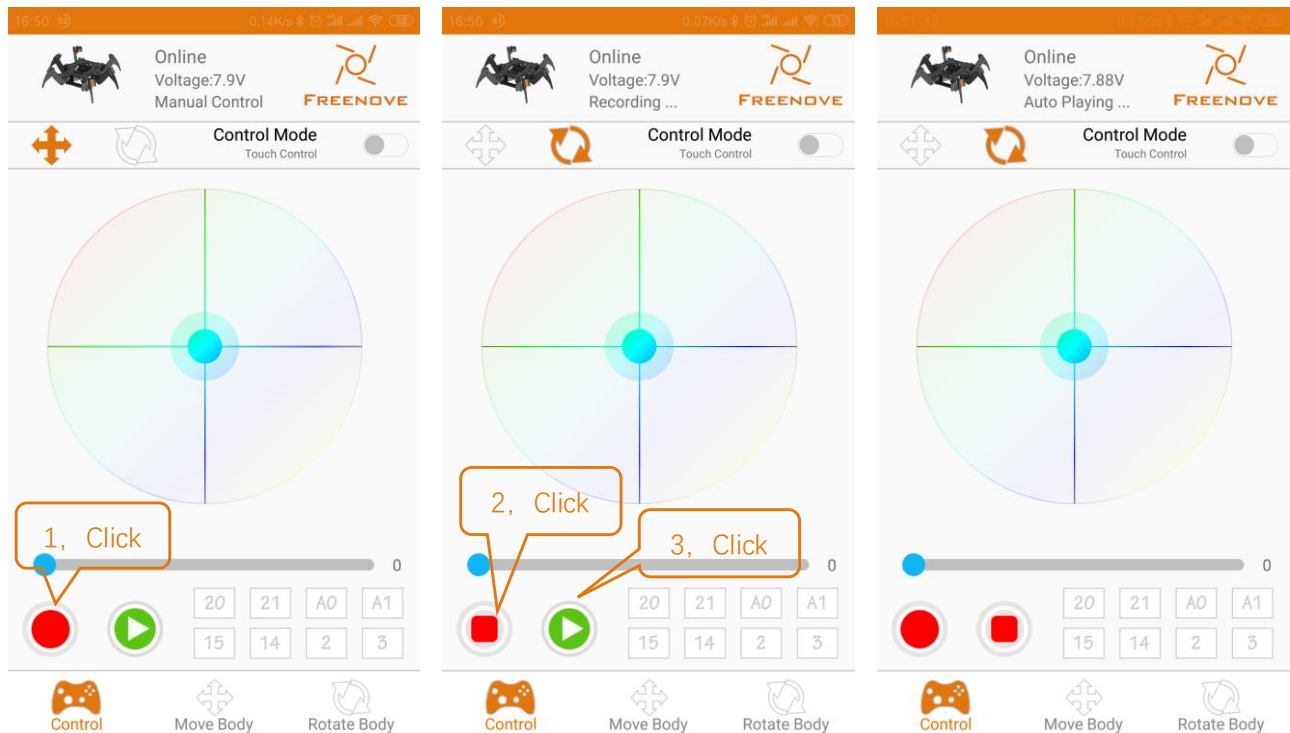
In this page, you can control robot body to rotate along the X, Y, Z axis. You can use one finger to drag the blue drip or use two fingers to rotate the blue drip.

Mode switch is used to switch control mode. Left is touch control mode and right is gravity control mode.

Under gravity control mode, tilt your cell phone to control.

Here, controlling robot to move in Z axis direction will not influence the robot position in X and Y axis under control function selection.

Now we will introduce the record function.



Nomatter which interface the app is in, you can use this function.

First, press red circular button. Then it become red square button. The app starts to record your operation. Under this process, you can switch different fuction selections and do whatever operation you want. When you want to end recording, just press red square button, nomatter which page you are in.

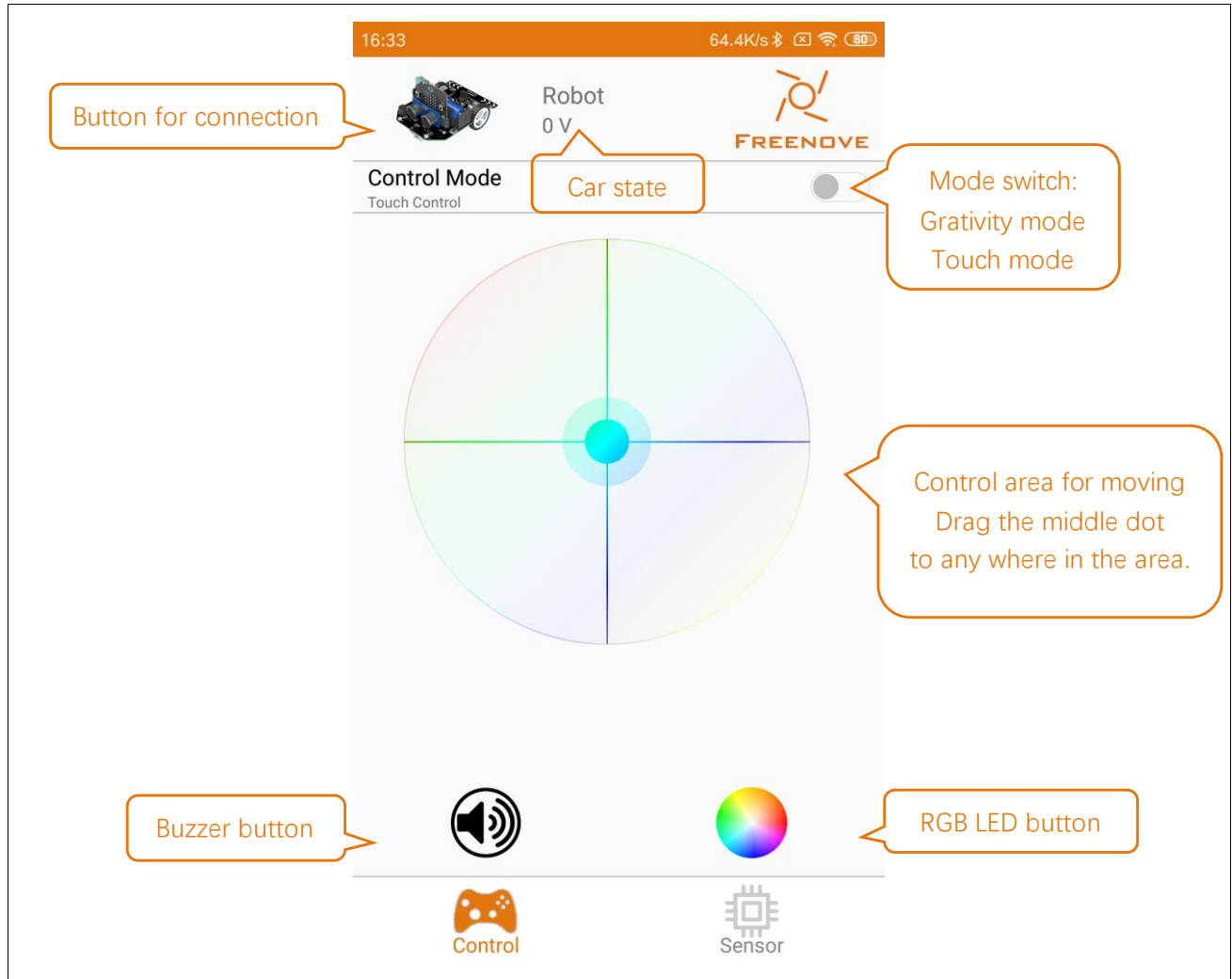
Second, press green circular button to play. Then it become red square button. You can press it to end the playing or wait for automatic end.

And the app will save only one record until you record another set of operations. So you can play a record many times.

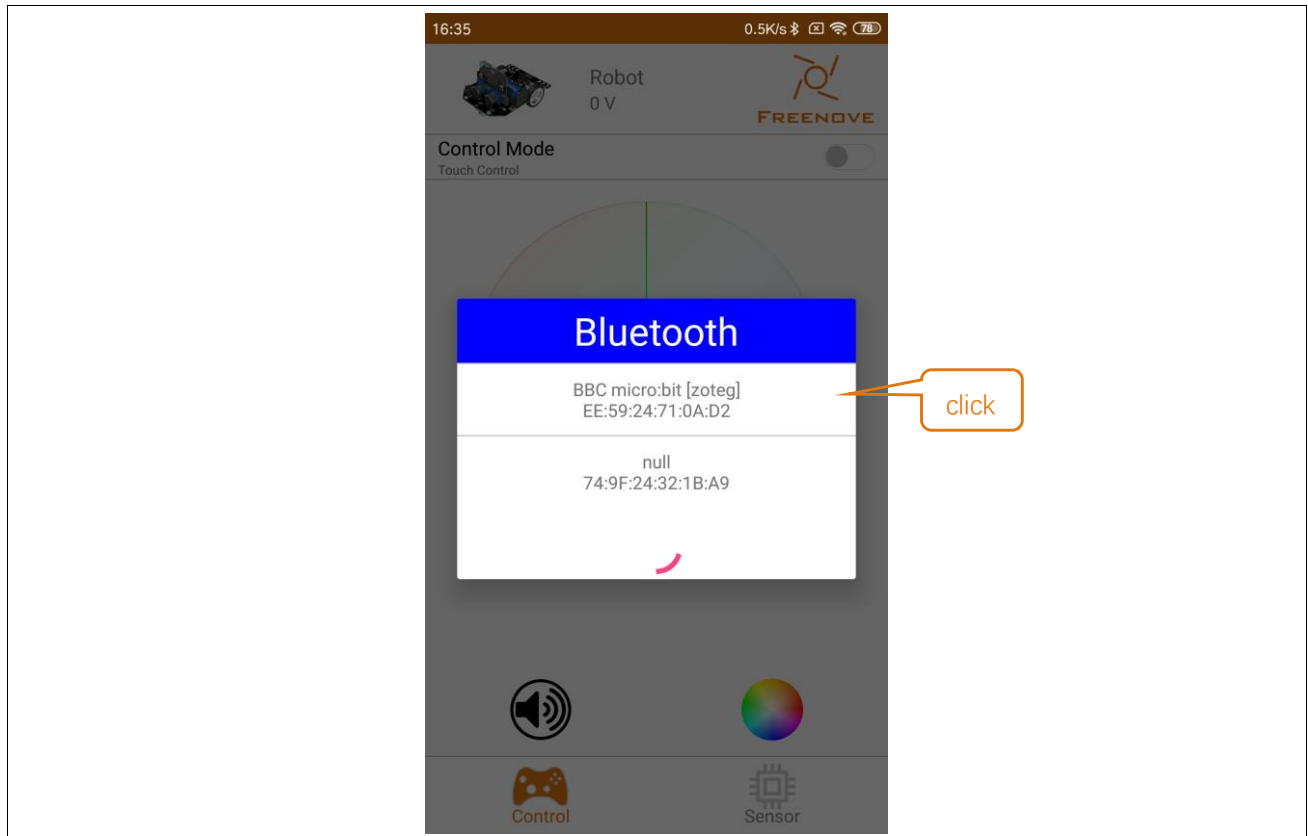
You can also press green circular button to play without ending recording.

# Freenove Micro:Rover

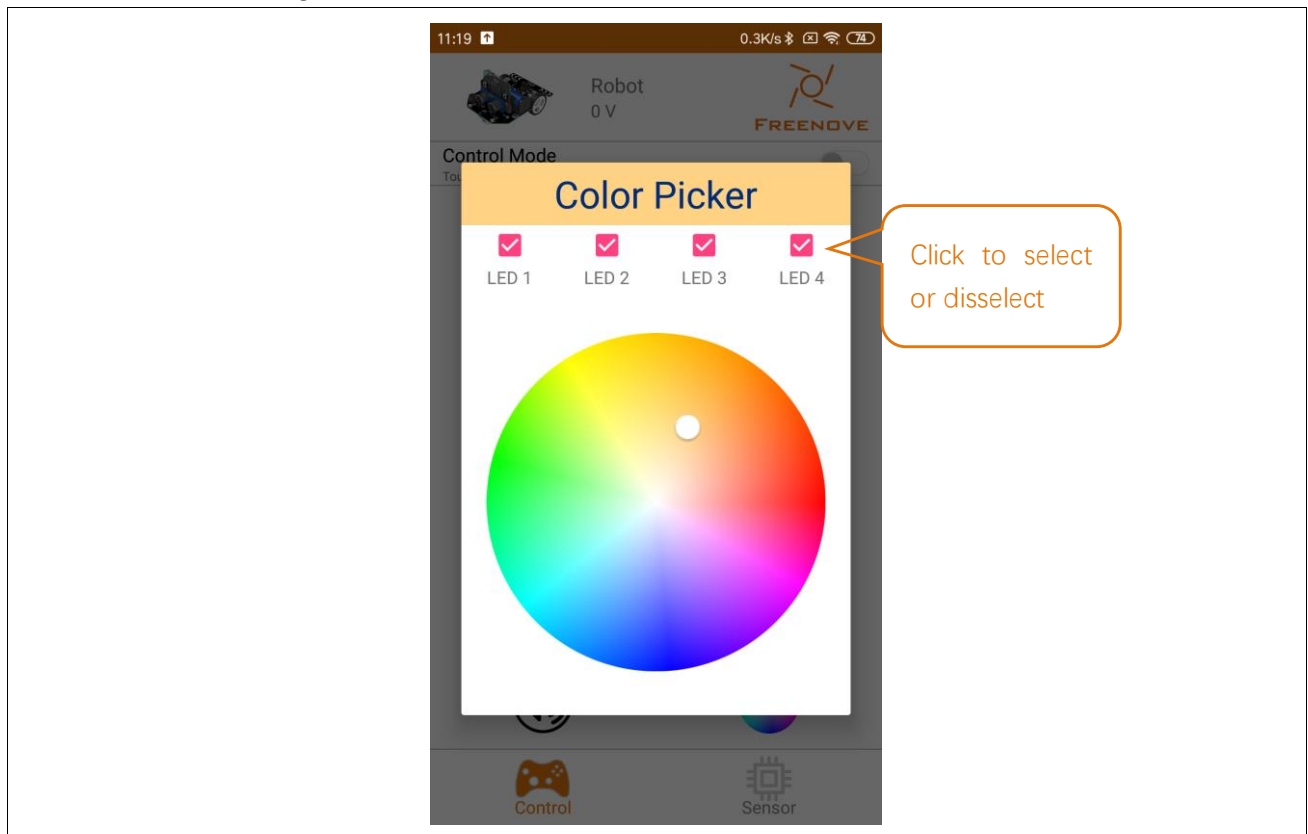
Click Micro:Rover on home page, then it jumps to the following interface.



First, click connection button to contact Mico:Rover with phone.

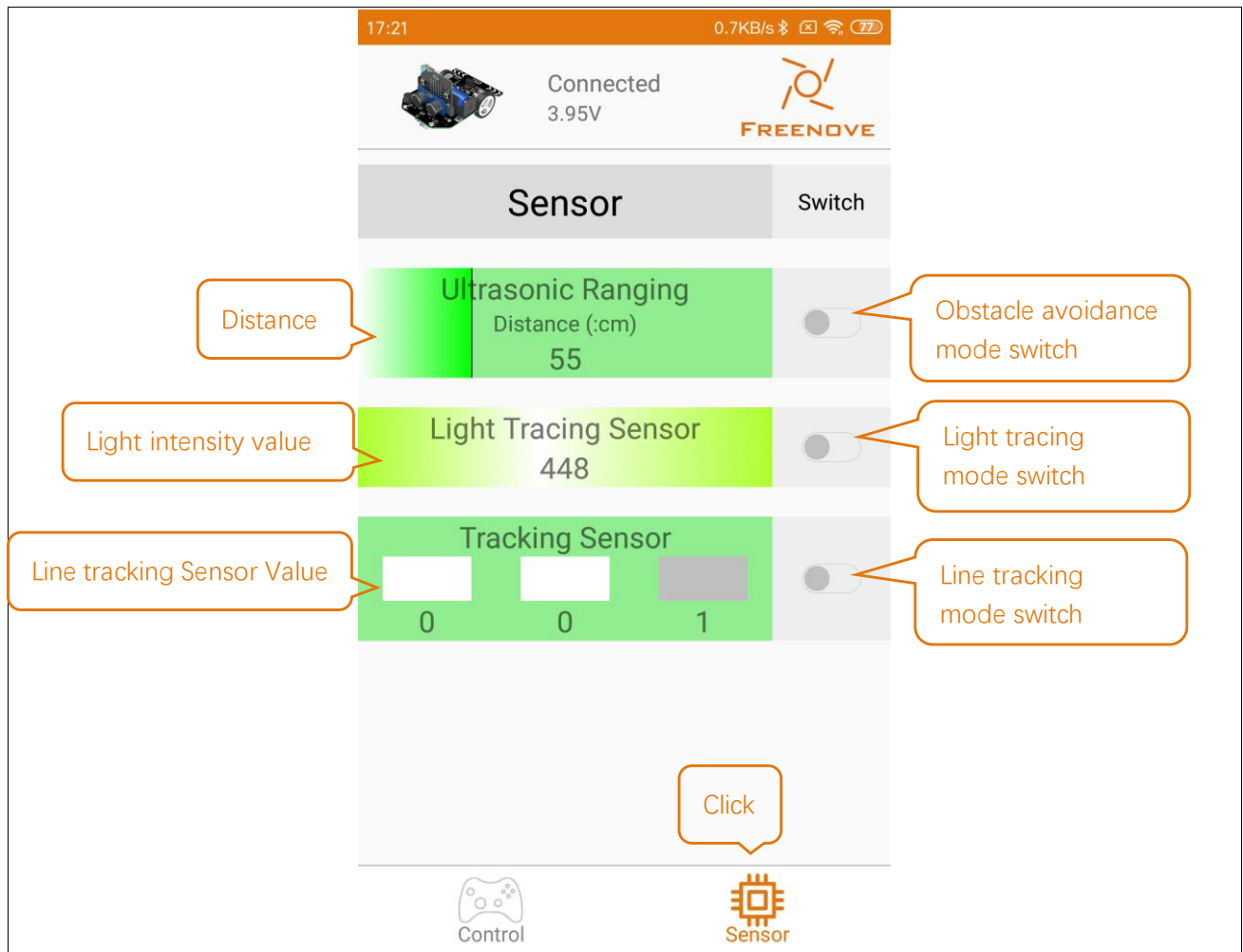


Click RGB LED button. Then following interface will appear.  
You can choose to change the color of certain LEDs selected.





In sensor interface, there are three control modes based on sensors.



## What's next?

Thanks for your reading.

This book is all over here. If you find any mistakes, missions or you have other ideas and questions about contents of this book or the kit and ect, please feel free to contact us, and we will check and correct it as soon as possible.

We will continue to update the application, add more devices, and optimize the software to make it with a better user experience in the future.

If you want to learn more about Arduino, Raspberry Pi, smart cars, robots and other interesting products in science and technology, please continue to focus on our website. We will continue to launch cost-effective, innovative and exciting products.

Thank you again for choosing Freenove products.