

Getting Started

Thank you for choosing Freenove products!

First, please read the **Read Me First.pdf** document in the unzipped folder you created.

If you have not yet downloaded the zip file, associated with this kit, please do so now and unzip it.

Get Support and Offer Input

Freenove provides free and responsive product and technical support, including but not limited to:

- Product quality issues
- Product use and build issues
- Questions regarding the technology employed in our products for learning and education
- Your input and opinions are always welcome
- We also encourage your ideas and suggestions for new products and product improvements

For any of the above, you may send us an email to:

support@freenove.com

Safety and Precautions

Please follow the following safety precautions when using or storing this product:

- Keep this product out of the reach of children under 6 years old.
- This product should be used only when there is adult supervision present as young children lack necessary judgment regarding safety and the consequences of product misuse.
- This product contains small parts and parts, which are sharp. This product contains electrically conductive parts. Use caution with electrically conductive parts near or around power supplies, batteries and powered (live) circuits.
- When the product is turned ON, activated or tested, some parts will move or rotate. To avoid injuries to hands and fingers, keep them away from any moving parts!
- It is possible that an improperly connected or shorted circuit may cause overheating. Should this happen, immediately disconnect the power supply or remove the batteries and do not touch anything until it cools down! When everything is safe and cool, review the product tutorial to identify the cause.
- Only operate the product in accordance with the instructions and guidelines of this tutorial, otherwise parts may be damaged or you could be injured.
- Store the product in a cool dry place and avoid exposing the product to direct sunlight.
- After use, always turn the power OFF and remove or unplug the batteries before storing.

Car and Robot for Raspberry Pi

We also have cars and robot kit for Raspberry Pi. If you are interesting in them, please visit our website for details.

<http://www.freenove.com/store.html>

FNK0043 Freenove 4WD Smart Car Kit for Raspberry Pi



<https://www.youtube.com/watch?v=4Zv0GZUQjZc>

FNK0050 Freenove Robot Dog Kit for Raspberry Pi



https://www.youtube.com/watch?v=7BmlZ8_R9d4&t=35s

About Freenove

Freenove provides open source electronic products and services worldwide.

Freenove is committed to assist customers in their education of robotics, programming and electronic circuits so that they may transform their creative ideas into prototypes and new and innovative products. To this end, our services include but are not limited to:

- Educational and Entertaining Project Kits for Robots, Smart Cars and Drones
- Educational Kits to Learn Robotic Software Systems for Arduino, Raspberry Pi and micro:bit
- Electronic Component Assortments, Electronic Modules and Specialized Tools
- **Product Development and Customization Services**

You can find more about Freenove and get our latest news and updates through our website:

<http://www.freenove.com>

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Raspberry Pi® is a trademark of Raspberry Pi Foundation (<https://www.raspberrypi.org/>).

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Preface

Raspberry Pi is a low cost, **credit card sized computer** that plugs into a computer monitor or TV, and uses a standard keyboard and mouse. It is an incredibly capable little device that enables people of all ages to explore computing, and to learn how to program in a variety of computer languages like Scratch and Python. It is capable of doing everything you would expect from a desktop computer, such as browsing the internet, playing high-definition video content, creating spreadsheets, performing word-processing, and playing video games. For more information, you can refer to Raspberry Pi official [website](#). For clarification, this tutorial will also reference Raspberry Pi as RPi, RPI and RasPi.

In this tutorial, most chapters consist of **Components List**, **Component Knowledge**, **Circuit**, and **Code (C code and Python code)**. We provide both C and Python code for each project in this tutorial. After completing this tutorial, you can learn Java by reading Processing.pdf.

This kit contains all the accessory electronic components and modules needed to complete the projects described in the index. You can also use these components and modules to create projects of your own design.

Additionally, if you encounter any issues or have questions about this tutorial or the contents of kit, you can always contact us for free technical support at:

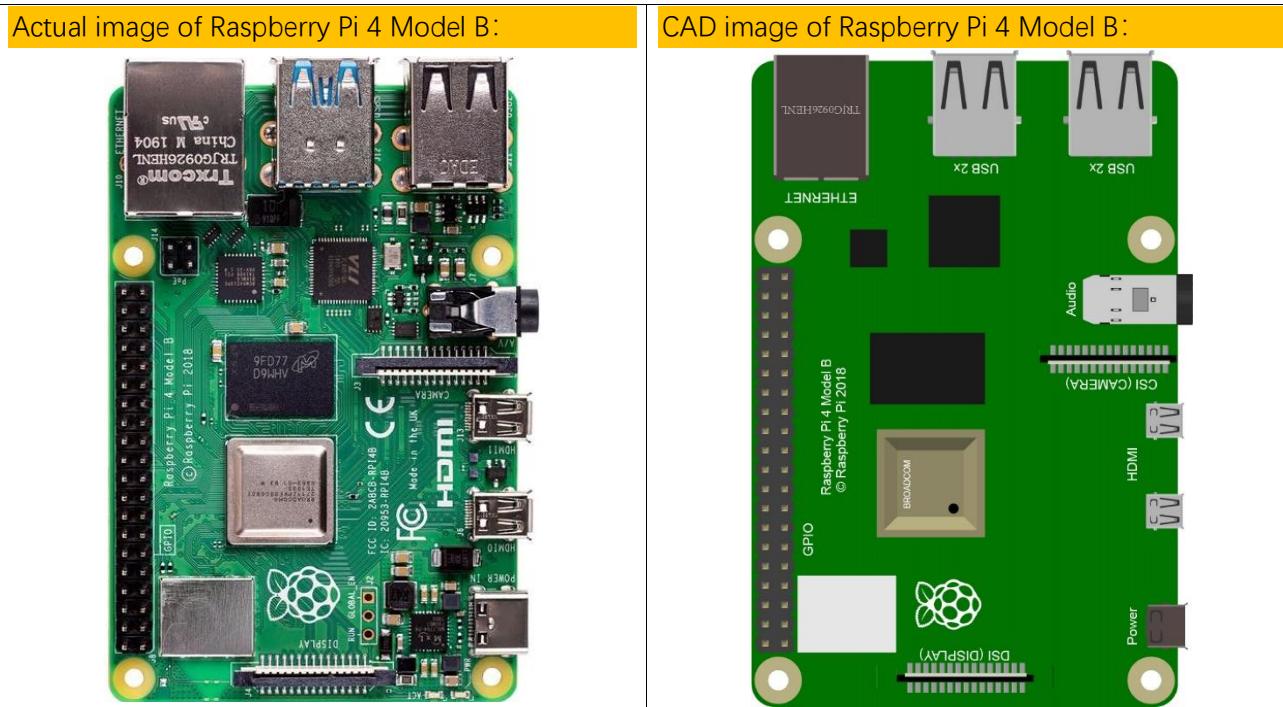
support@freenove.com

Raspberry Pi

So far, at this writing, Raspberry Pi has advanced to its fourth generation product offering. Version changes are accompanied by increases in upgrades in hardware and capabilities.

The A type and B type versions of the first generation products have been discontinued due to various reasons. What is most important is that other popular and currently available versions are consistent in the order and number of pins and their assigned designation of function, making compatibility of peripheral devices greatly enhanced between versions.

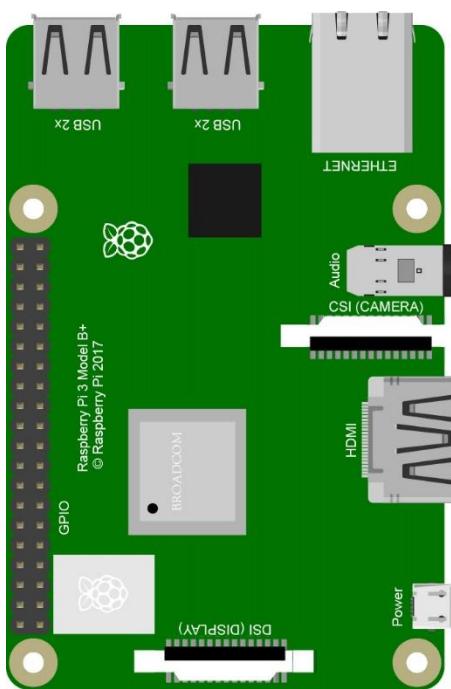
Below are the raspberry pi pictures and model pictures supported by this product. They have 40 pins.



Actual image of Raspberry Pi 3 Model B+:



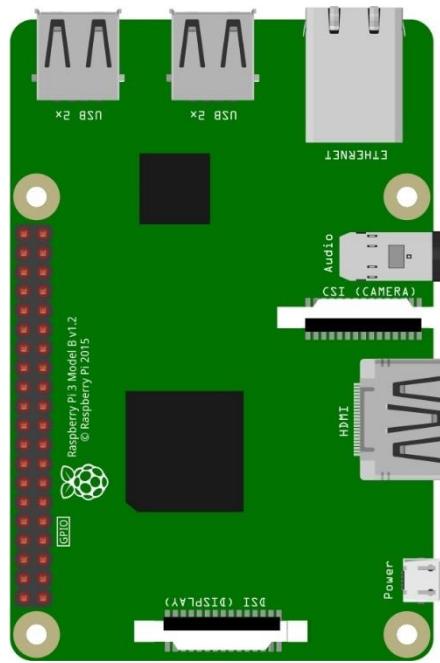
CAD image of Raspberry Pi 3 Model B+:



Actual image of Raspberry Pi 3 Model B:



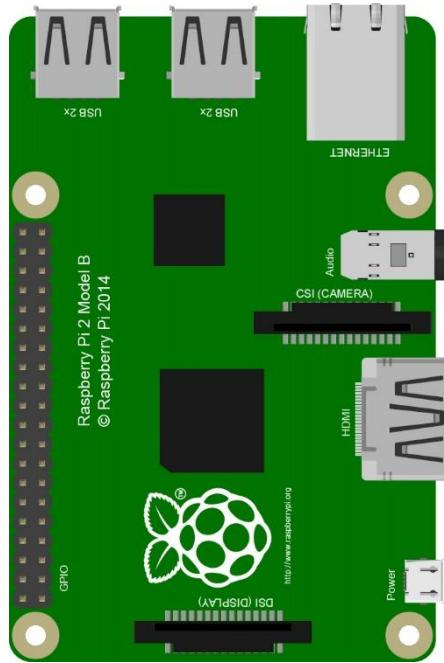
CAD image of Raspberry Pi 3 Model B:



Actual image of Raspberry Pi 2 Model B:



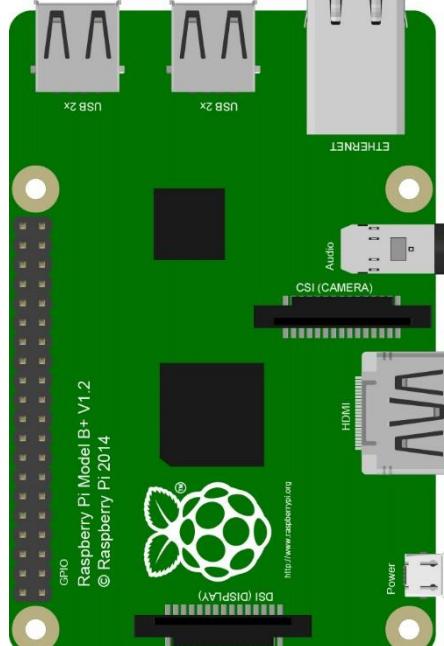
CAD image of Raspberry Pi 2 Model B:



Actual image of Raspberry Pi 1 Model B+:



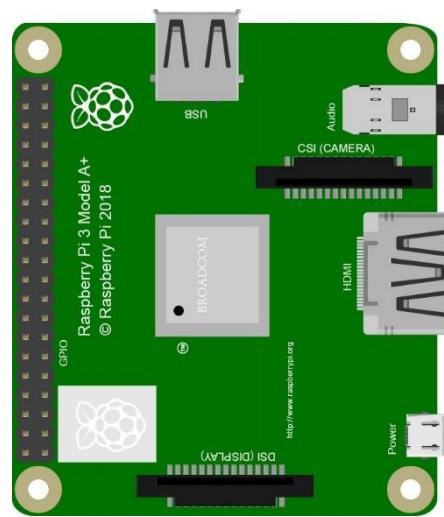
CAD image of Raspberry Pi 1 Model B+:



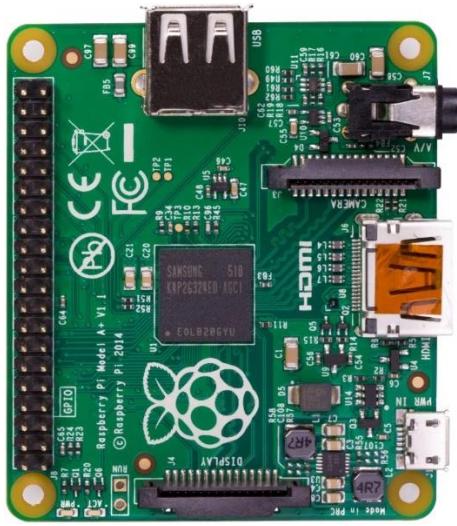
Actual image of Raspberry Pi 3 Model A+:



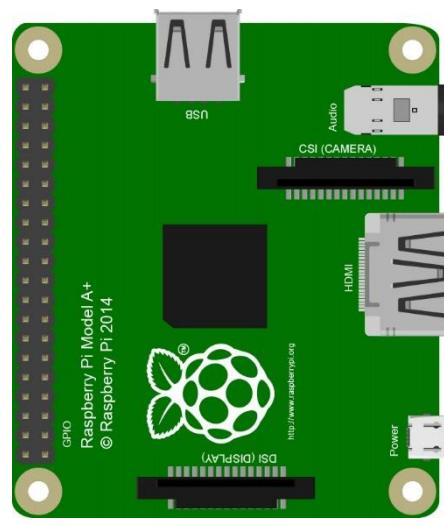
CAD image of Raspberry Pi 3 Model A+:



Actual image of Raspberry Pi 1 Model A+:



CAD image of Raspberry Pi 1 Model A+:



Actual image of Raspberry Pi Zero W:



CAD image of Raspberry Pi Zero W:



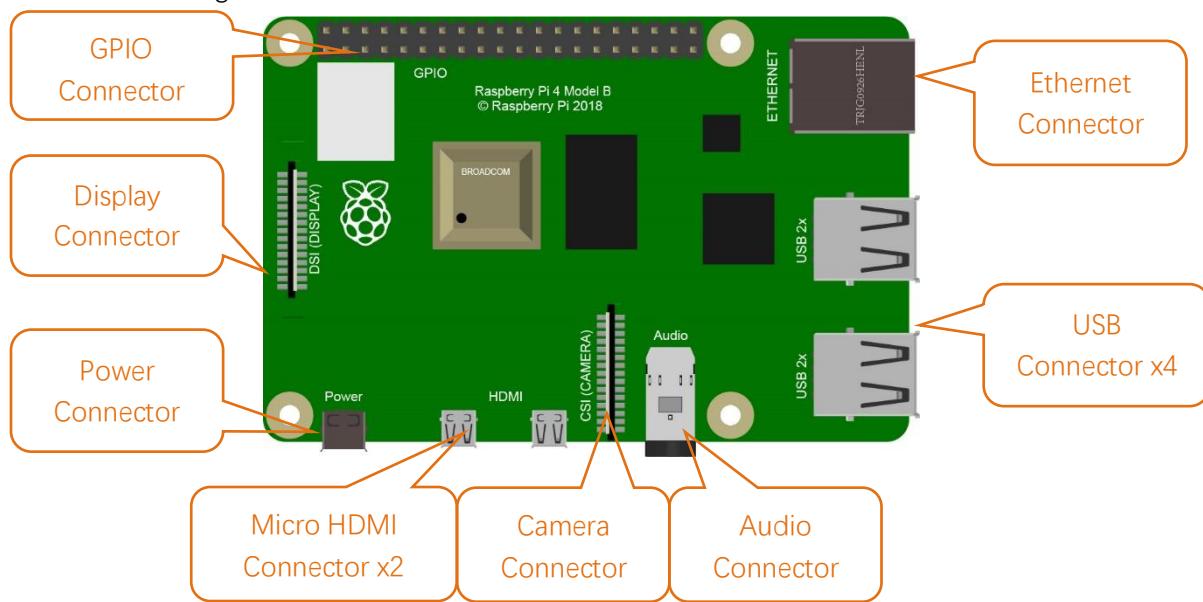
Actual image of Raspberry Pi Zero:



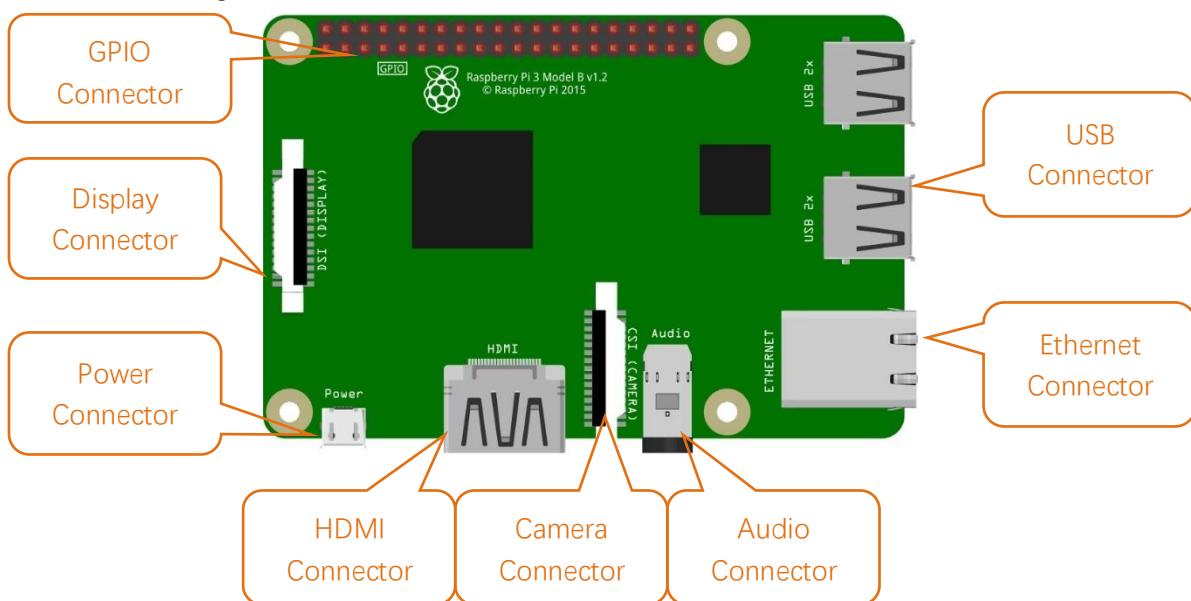
CAD image of Raspberry Pi Zero:



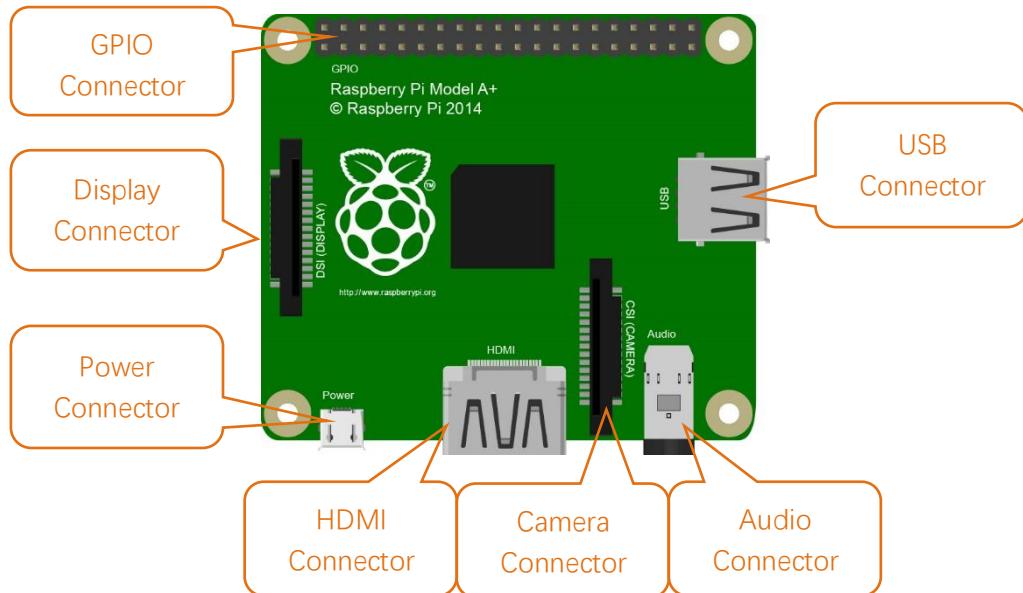
Hardware interface diagram of RPi 4B:



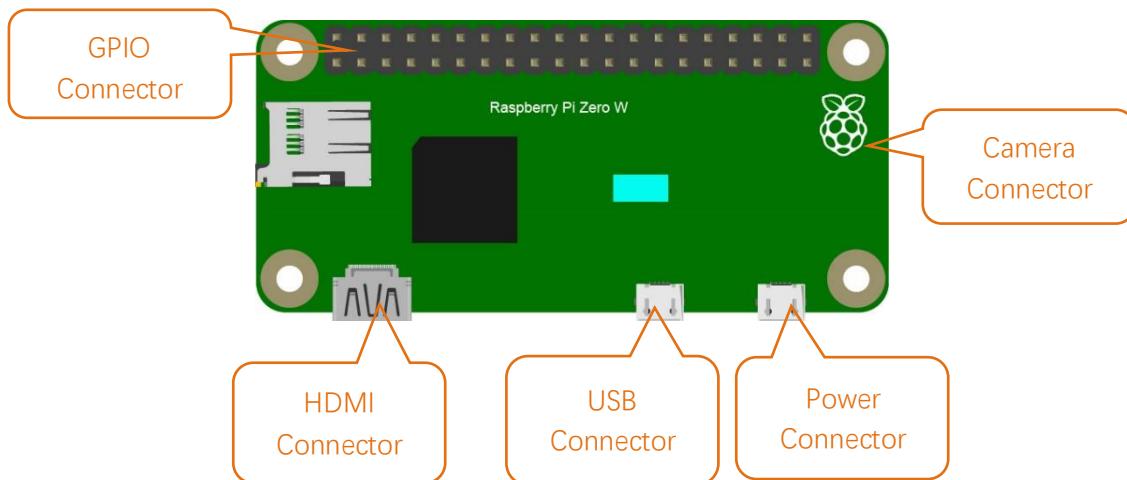
Hardware interface diagram of RPi 3B+/3B/2B/1B+:



Hardware interface diagram of RPi 3A+/A+:



Hardware interface diagram of RPi Zero/Zero W:



Installing an Operating System

The first step is to install an operating system on your RPi so that it can be programmed and function. If you have installed a system in your RPi, you can start from Chapter 0 Preparation.

Component List

Required Components

Following

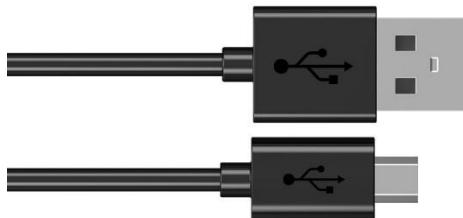
Any Raspberry Pi



5V/3A Power Adapter. Note: Different versions of Raspberry Pi have different power requirements (please check the power requirements for yours on the chart in the following page.)



Micro or Type-C USB Cable x1



Micro SD Card (TF Card) x1, Card Reader x1





Power requirements of various versions of Raspberry Pi are shown in following table:

Product	Recommended PSU current capacity	Maximum total USB peripheral current draw	Typical bare-board active current consumption
Raspberry Pi Model A	700mA	500mA	200mA
Raspberry Pi Model B	1.2A	500mA	500mA
Raspberry Pi Model A+	700mA	500mA	180mA
Raspberry Pi Model B+	1.8A	600mA/1.2A (switchable)	330mA
Raspberry Pi 2 Model B	1.8A	600mA/1.2A (switchable)	350mA
Raspberry Pi 3 Model B	2.5A	1.2A	400mA
Raspberry Pi 3 Model A+	2.5A	Limited by PSU, board, and connector ratings only.	350mA
Raspberry Pi 3 Model B+	2.5A	1.2A	500mA
Raspberry Pi 4 Model B	3.0A	1.2A	600mA
Raspberry Pi Zero W	1.2A	Limited by PSU, board, and connector ratings only.	150mA
Raspberry Pi Zero	1.2A	Limited by PSU, board, and connector ratings only	100mA

For more details, please refer to <https://www.raspberrypi.org/help/faqs/#powerReqs>

In addition, RPi also needs an Ethernet network cable used to connect it to a WAN (Wide Area Network).

All these components are necessary for any of your projects to work. Among them, the power supply of at least 5V/2.5A, because a lack of a sufficient power supply may lead to many functional issues and even damage your RPi, we STRONGLY RECOMMEND a 5V/2.5A power supply. We also recommend using a SD Micro Card with a capacity 16GB or more (which, functions as the RPi's "hard drive") and is used to store the operating system and necessary operational files.

Optional Components

Under normal circumstances, there are two ways to login to Raspberry Pi: 1) Using a stand-alone monitor. 2) Using a remote desktop or laptop computer monitor “sharing” the PC monitor with your RPi.

Required Accessories for Monitor

If you choose to use an independent monitor, mouse and keyboard, you also need the following accessories:

1. A display with a HDMI interface
2. A Mouse and a Keyboard with an USB interface

As to Pi Zero and Pi Zero W, you also need the following accessories:

1. A Mini-HDMI to HDMI Adapter and Cable.
2. A Micro-USB to USB-A Adapter and Cable (Micro USB OTG Cable).
3. A USB HUB.
4. USB to Ethernet Interface or USB Wi-Fi receiver.

For different Raspberry Pi Modules, the optional items may vary slightly but they all aim to convert the interfaces to Raspberry Pi standards.

	Pi Zero	Pi A+	Pi Zero W	Pi 3A+	Pi B+/2B	Pi 3B/3B+	Pi 4B
Monitor	Yes (All)						
Mouse	Yes (All)						
Keyboard	Yes (All)						
Micro-HDMI to HDMI Adapter & Cable	Yes	No	Yes	No	No	No	No
Micro-HDMI to HDMI Adapter & Cable	No					Yes	
Micro-USB to USB-A Adapter & Cable (Micro USB OTG Cable)	Yes	No	Yes	No			
USB HUB	Yes	Yes	Yes	Yes	No	No	
USB to Ethernet Interface	select one from two or select two from two		optional		Internal Integration	Internal Integration	
USB Wi-Fi Receiver			Internal Integration	optional			



Required Accessories for Remote Desktop

If you do not have an independent monitor, or if you want to use a remote desktop, you first need to login to Raspberry Pi through SSH, and then open the VNC or RDP service. This requires the following accessories.

	Pi Zero	Pi Zero W	Pi A+	Pi 3A+	Pi B+/2B	Pi 3B/3B+/4B
Micro-USB to USB-A Adapter & Cable (Micro USB OTG Cable)	Yes	Yes	No			NO
USB to Ethernet interface	Yes	Yes	Yes			

Raspberry Pi OS

Automatically Method (Recommended)

You can follow the official method to install the system for raspberry pi via visiting link below:

<https://projects.raspberrypi.org/en/projects/raspberry-pi-setting-up/2>

In this way, the system will be downloaded **automatically** via the application.

Manually Method

After installing the Imager Tool in the **link above**. You can **also** download the system **manually** first.

Visit <https://www.raspberrypi.org/downloads/>

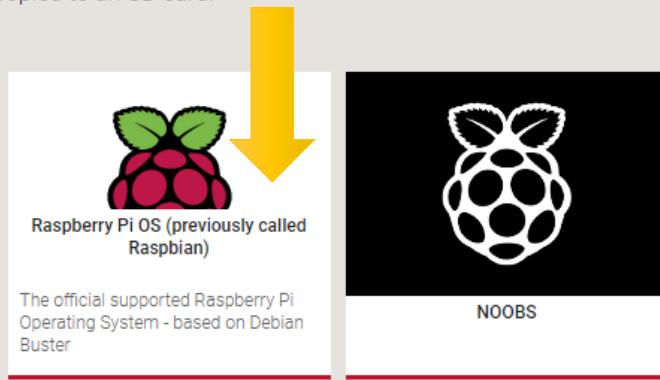
Downloads

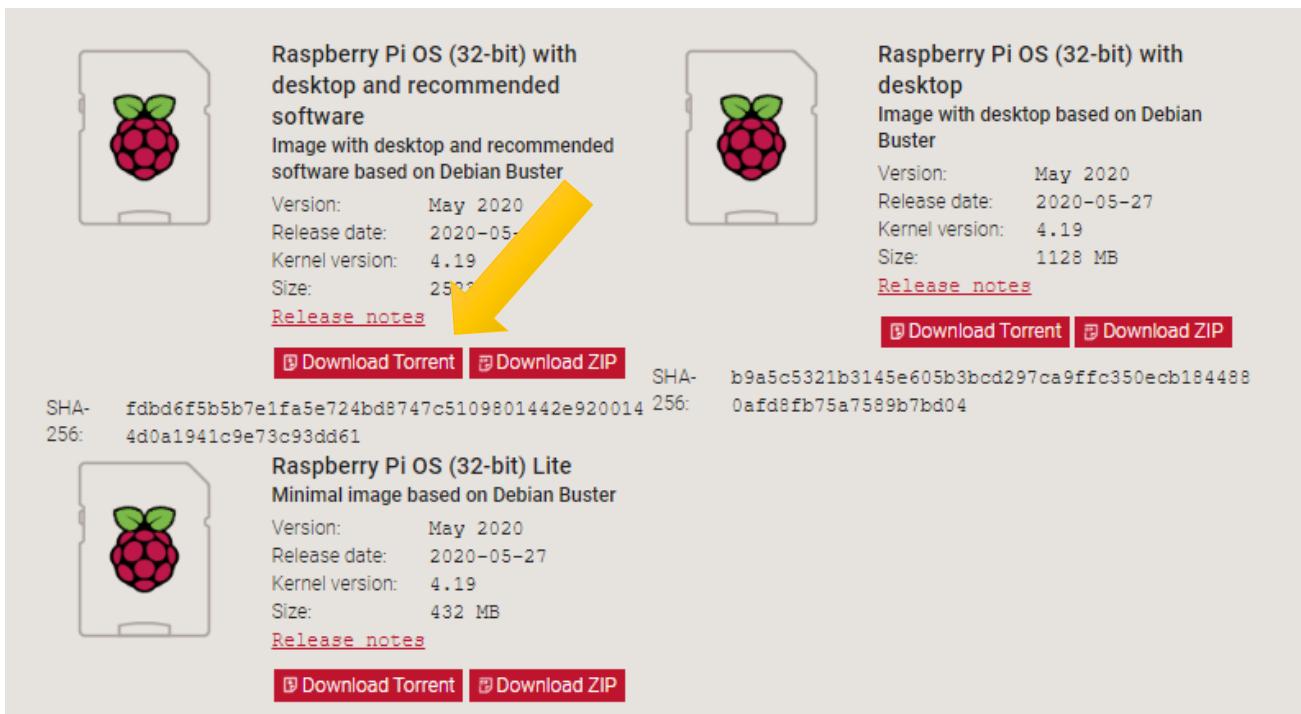
Raspberry Pi OS (previously called Raspbian) is our official operating system for **all** models of the Raspberry Pi.

Use **Raspberry Pi Imager** for an easy way to install Raspberry Pi OS and other operating systems to an SD card ready to use with your Raspberry Pi:

- [Raspberry Pi Imager for Windows](#)
- [Raspberry Pi Imager for macOS](#)
- [Raspberry Pi Imager for Ubuntu](#)

Alternatively, use the links below to download OS images which can be manually copied to an SD card.

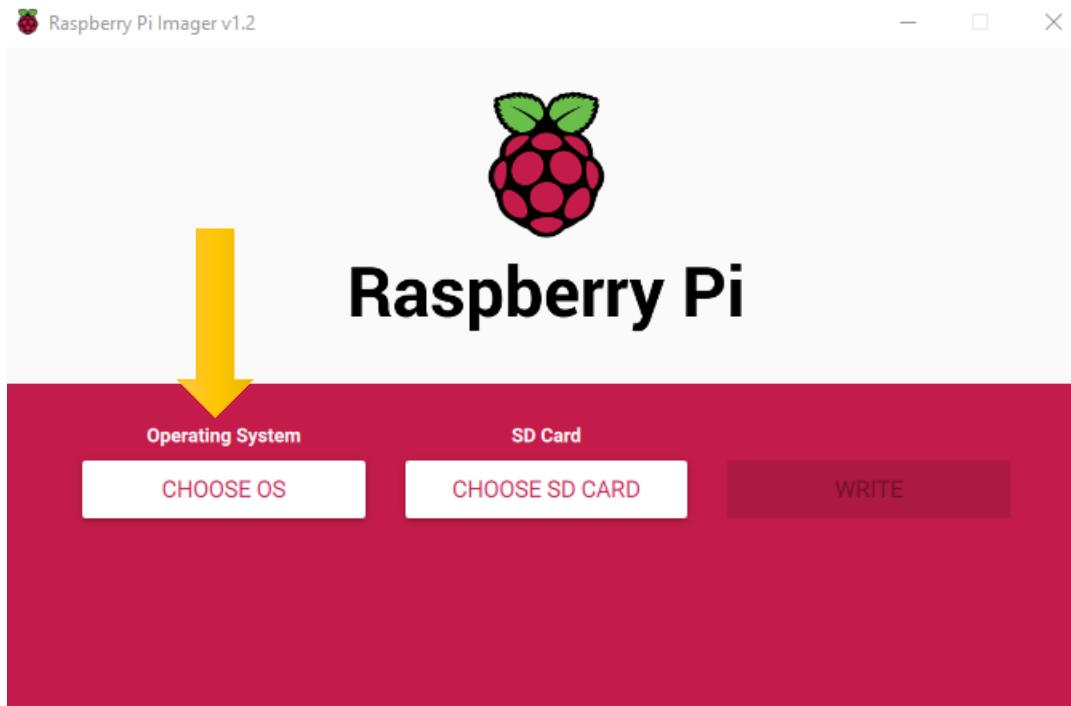


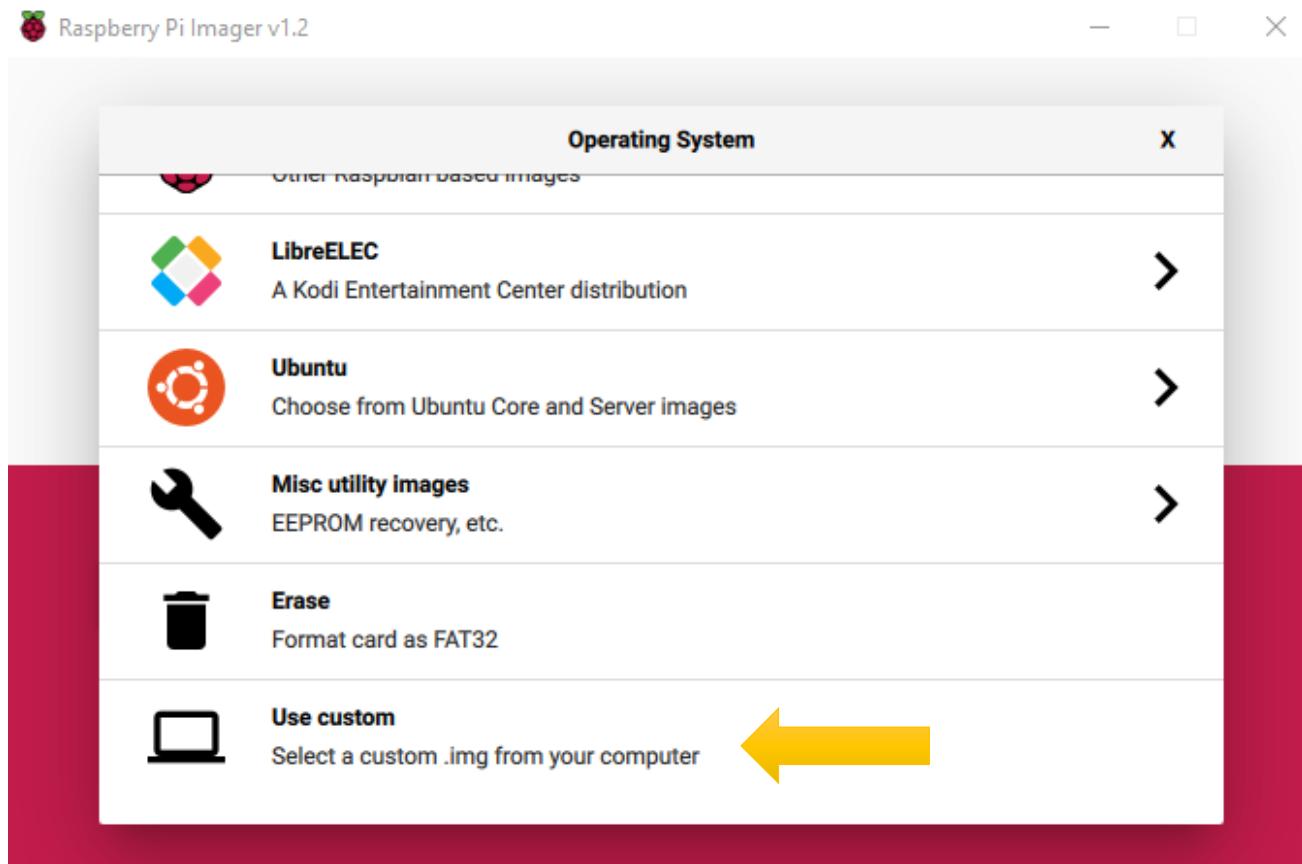


And then the zip file is downloaded.

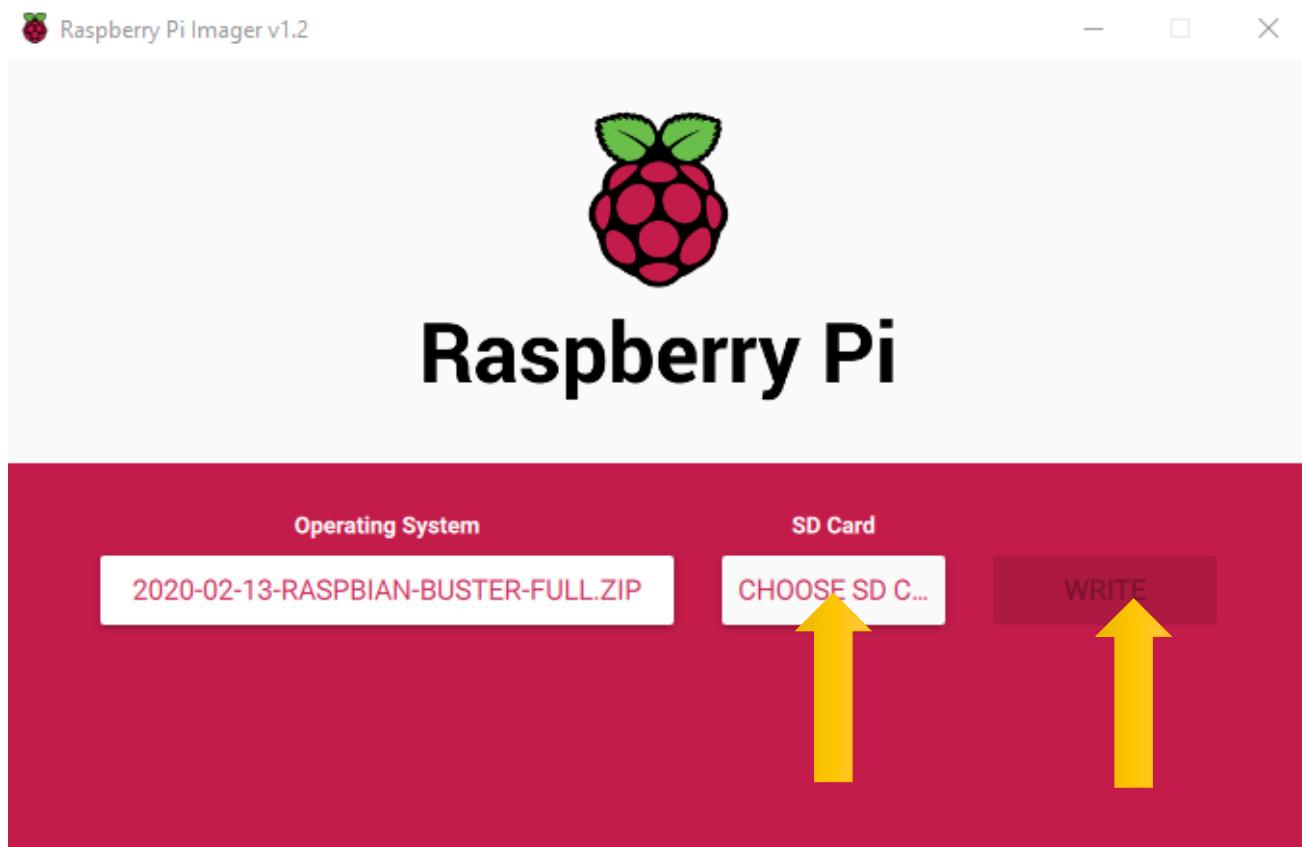
Write System to Micro SD Card

First, put your Micro **SD card** into card reader and connect it to USB port of PC. Then open imager toll, choose Choose system that you just downloaded in Use custom.





Choose the SD card. Then click "WRITE".



Getting Started with Raspberry Pi

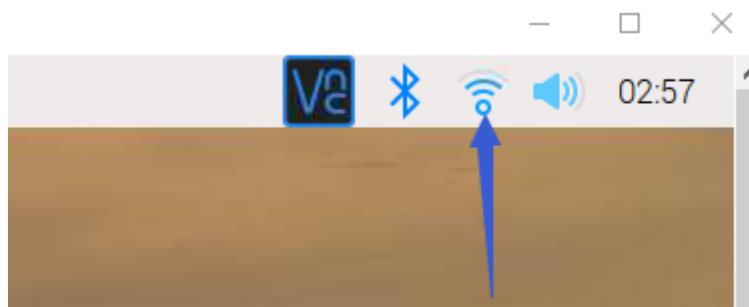
If you do not have a spare monitor, please skip to next section. If you have a spare monitor, please follow the steps in this section.

After the system is written successfully, take out Micro SD Card and put it into the SD card slot of RPi. Then connect your RPi to send video through the HDMI port, attach your mouse and keyboard through the USB ports, attach a network cable to the network card port and finally, connect your power supply (making sure that it meets the specifications required by your RPi Module Version). Your RPi should start (power up). Later, after setup, you will need to enter your user name and password to login. The default user name: pi; password: raspberry. After login, you should see the following screen.



Congratulations! You have successfully installed the RASPBERRY PI OS operating system on your RPi.

Raspberry Pi 4B, 3B+/3B integrates a Wi-Fi adaptor. You can use it to connect to your Wi-Fi. Then you can use the wireless remote desktop to control your RPi. This will be helpful for the following work. Raspberry Pi of other models can use wireless remote desktop through accessing an external USB wireless card.



Remote desktop & VNC

If you have logged in Raspberry Pi, you can skip to [VNC Viewer](#).

If you don't have a spare display, mouse and keyboard for your RPi, you can use a remote desktop to share a display, keyboard, and mouse with your PC. Below is how to use remote desktop under the Windows and MAC OS.

Enable SSH

Under the latest version of Raspberry Pi OS, SSH is closed by default. So you need to open it first. After write system, **create a folder named “ssh” under generated boot disk of Micro SD Card**, then the SSH connection will be opened.

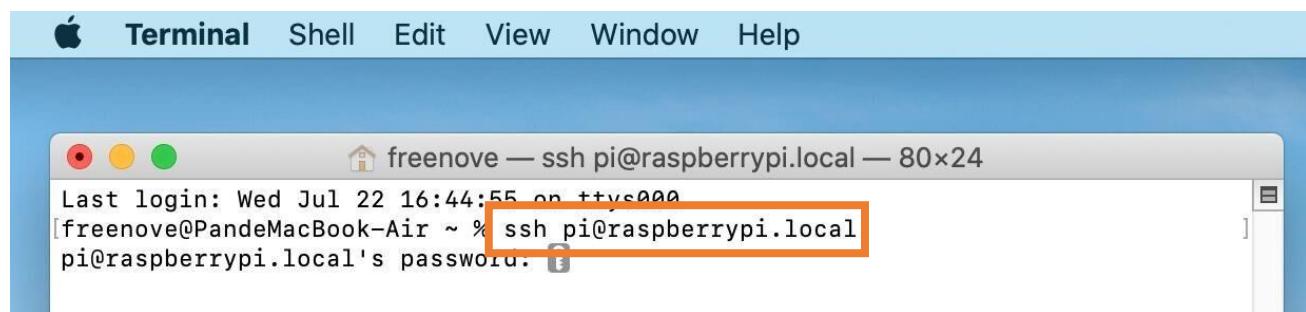
MAC OS Remote Desktop

Connect your pi to the router via a network cable.

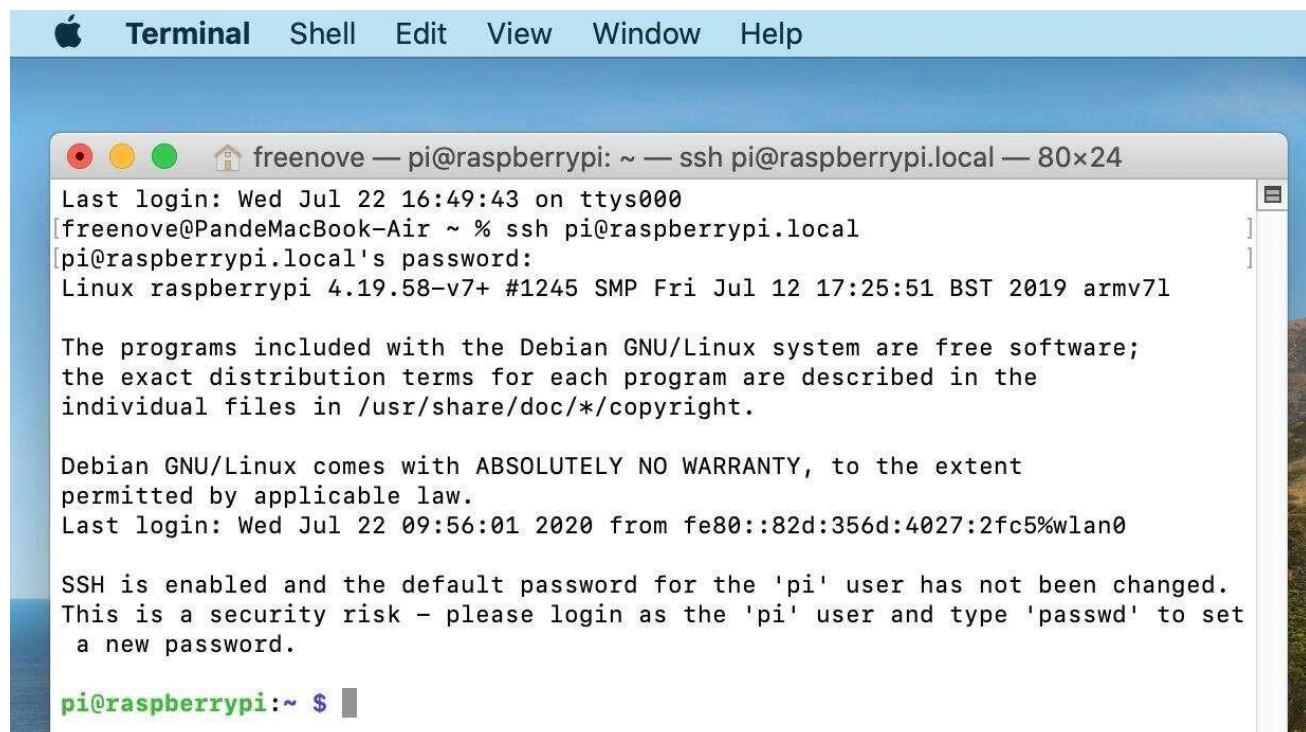
Open the terminal and type following command.

```
ssh pi@raspberrypi.local
```

The password is **raspberry** by default, case sensitive.



You may need to type **yes** during the process.



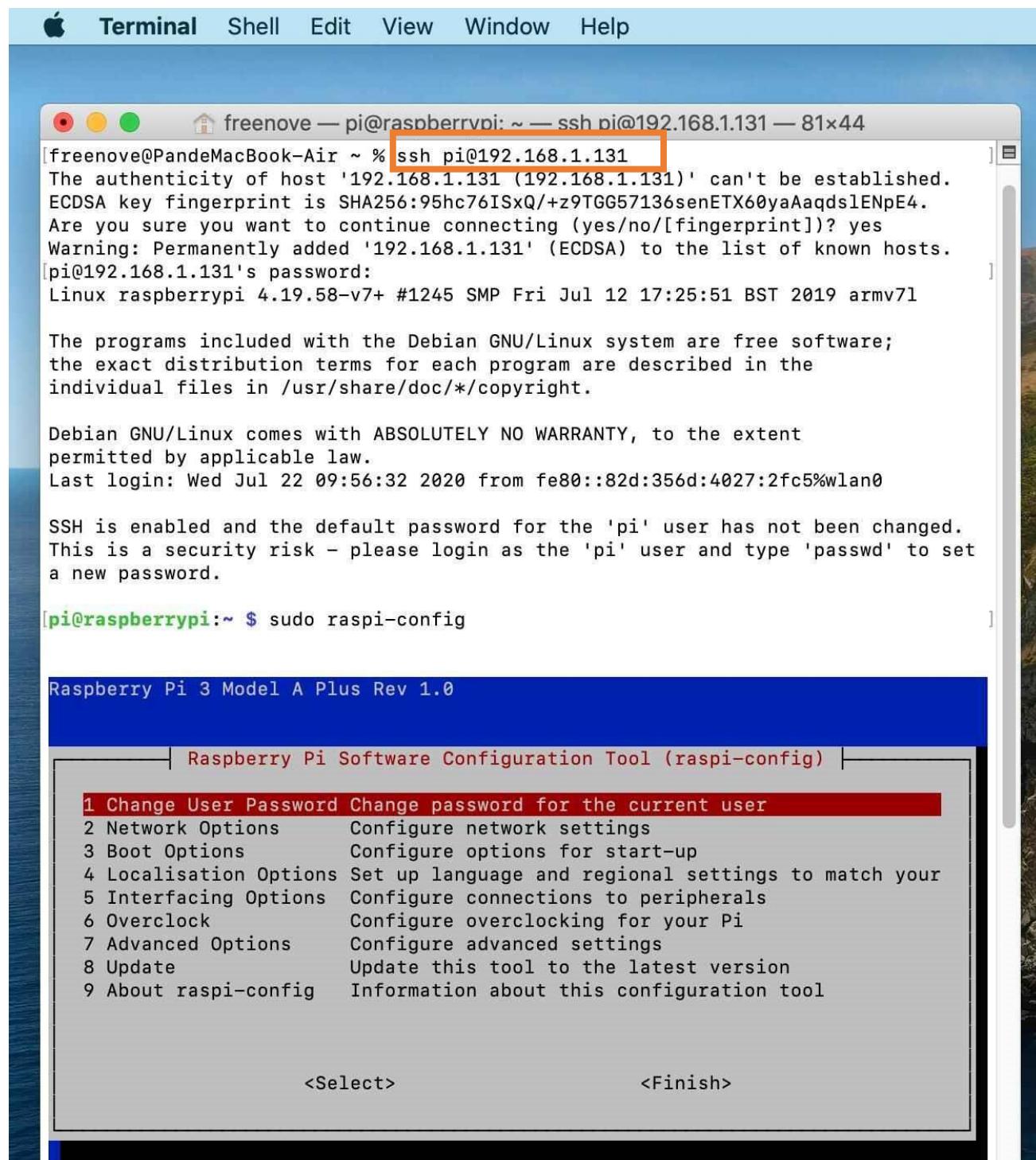
When you see **pi@raspberrypi:~ \$**, you have logged in Pi successfully. Then you can skip to next section.

You can also use the IP address to log in Pi.

Enter router client to inquiry IP address named "raspberry pi". For example, I have inquired to my RPi IP address, and it is "192.168.1.131".

Open the terminal and type following command.

```
ssh pi@192.168.1.131
```



```
freenove — pi@raspberrypi: ~ — ssh pi@192.168.1.131 — 81x44
[freenove@PandeMacBook-Air ~ % ssh pi@192.168.1.131
The authenticity of host '192.168.1.131 (192.168.1.131)' can't be established.
ECDSA key fingerprint is SHA256:95hc76ISxQ/+z9TGG57136senETX60yaAaqds1ENpE4.
Are you sure you want to continue connecting (yes/no/[fingerprint])? yes
Warning: Permanently added '192.168.1.131' (ECDSA) to the list of known hosts.
[pi@192.168.1.131's password:
Linux raspberrypi 4.19.58-v7+ #1245 SMP Fri Jul 12 17:25:51 BST 2019 armv7l

The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*copyright.

Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
Last login: Wed Jul 22 09:56:32 2020 from fe80::82d:356d:4027:2fc5%wlan0

SSH is enabled and the default password for the 'pi' user has not been changed.
This is a security risk - please login as the 'pi' user and type 'passwd' to set
a new password.

[pi@raspberrypi:~ $ sudo raspi-config

Raspberry Pi 3 Model A Plus Rev 1.0

Raspberry Pi Software Configuration Tool (raspi-config)

1 Change User Password Change password for the current user
2 Network Options Configure network settings
3 Boot Options Configure options for start-up
4 Localisation Options Set up language and regional settings to match your
5 Interfacing Options Configure connections to peripherals
6 Overclock Configure overclocking for your Pi
7 Advanced Options Configure advanced settings
8 Update Update this tool to the latest version
9 About raspi-config Information about this configuration tool

<Select> <Finish>
```

Then you can skip to [VNC Viewer](#).

Windows OS Remote Desktop

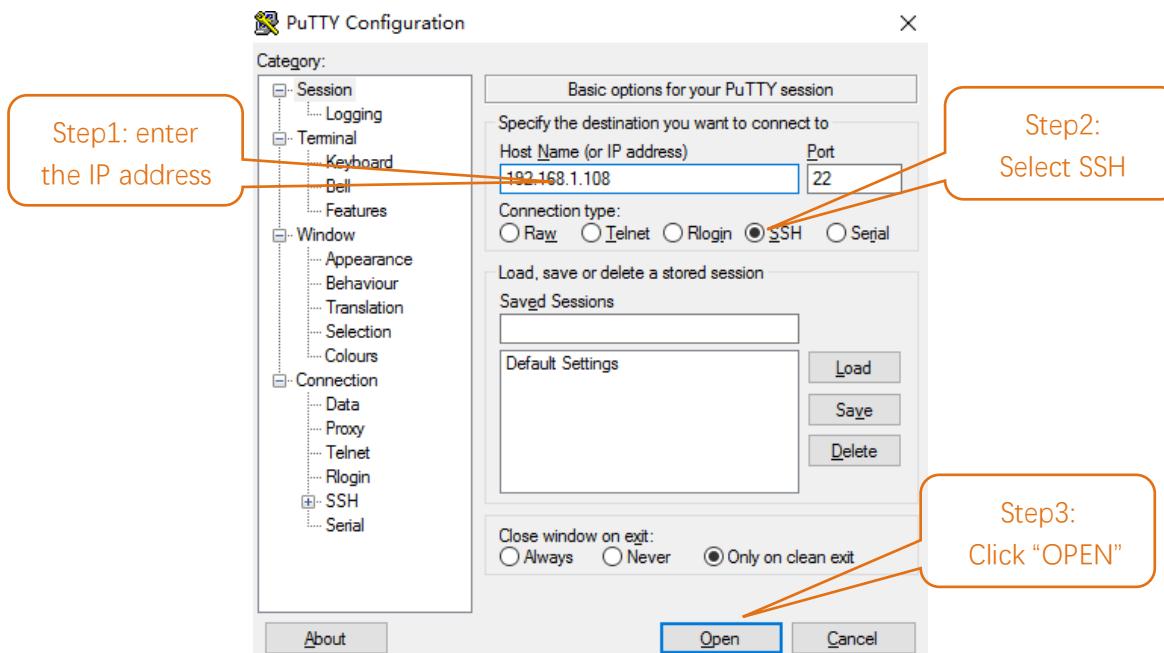
The windows built-in application remote desktop corresponds to the Raspberry Pi xrdp service.

Download the tool software Putty. Its official address: <http://www.putty.org/>

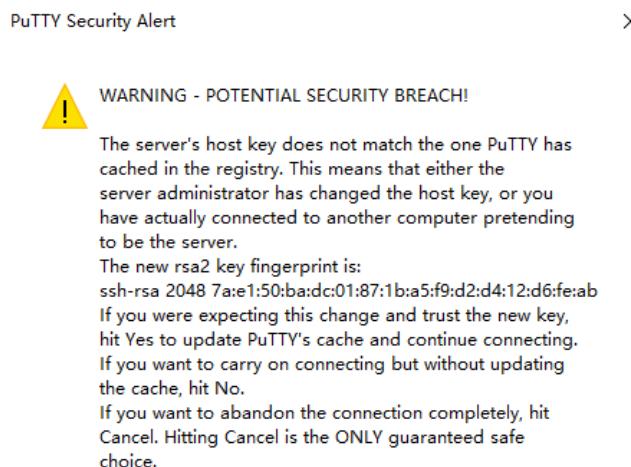
Or download it here: <http://www.chiark.greenend.org.uk/~sgtatham/putty/download.html>

Then use net cable to connect your RPi to the same router with your PC. Then put the system Micro SD Card prepared before into the slot of the RPi and turn on the power supply. Enter router client to inquiry IP address named "raspberry pi". For example, my RPi IP address is "192.168.1.108".

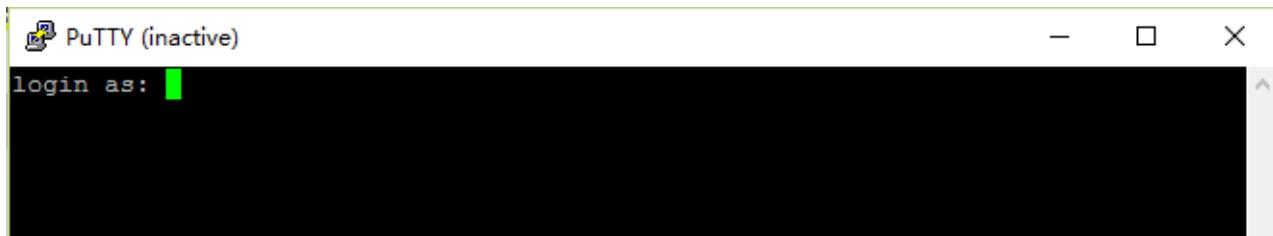
Then open Putty, enter the address, select SSH, and then click "OPEN", as shown below:



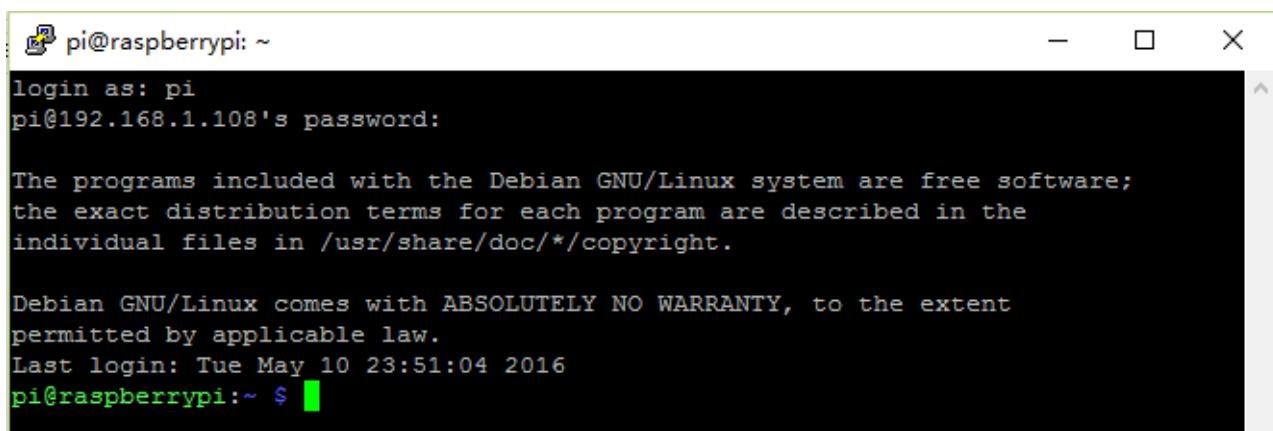
There will appear a security warning at first login. Just click "YES".



Then there will be a login interface (RPi default user name: **pi**; the password: **raspberry**). When you enter the password, there will be **no display** on the screen. This is normal. After the correct input, press “Enter” to confirm.



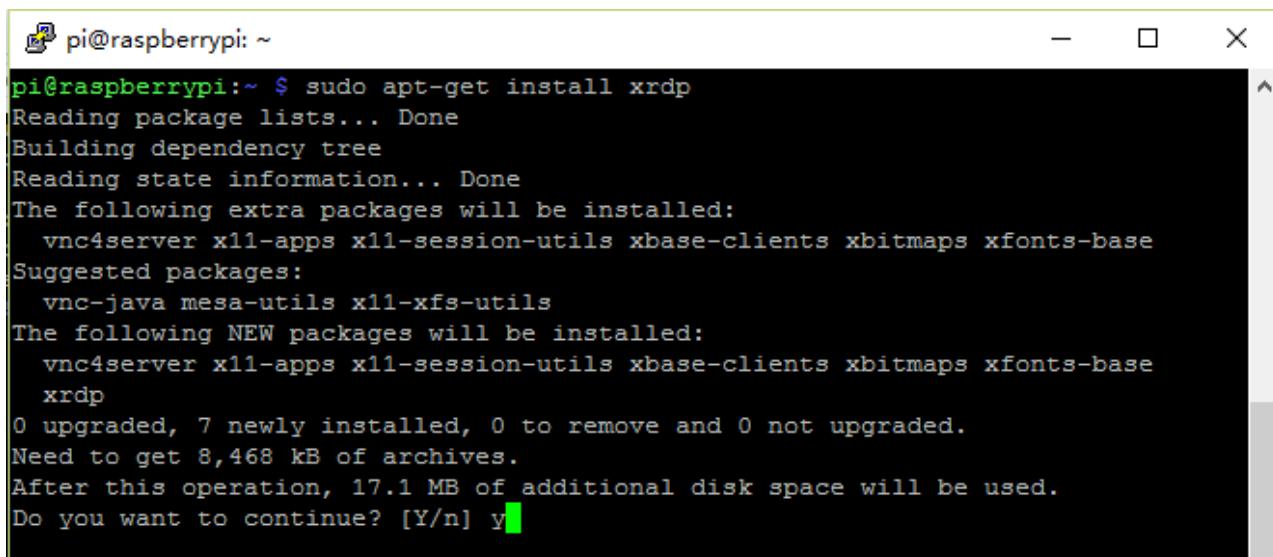
Then enter the command line of RPi, which means that you have successfully login to RPi command line mode.



If you want to use built-in Remote Desktop Connection under Windows, you need install xrdp service on Raspberry Pi.

Next, install a xrdp service, an open source remote desktop protocol(xrdp) server, for RPi. Type the following command, then press enter to confirm:

```
sudo apt-get install xrdp
```



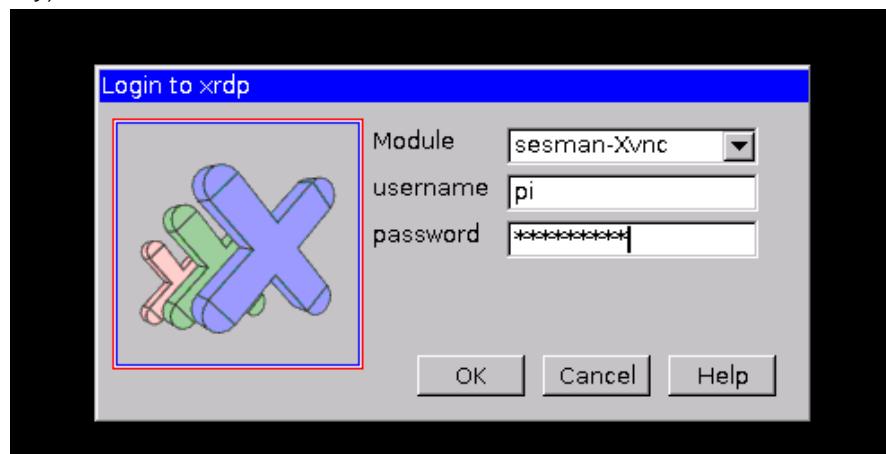
Enter "Y", press key "Enter" to confirm.

After the installation is completed, you can use Windows remote desktop applications to login to your RPi.

Use "WIN+R" or search function, open the remote desktop application "mstsc.exe" under Windows, enter the IP address of RPi and then click "Connect".



Later, there will be xrdp login screen. Enter the user name and password of RPi (RPi default user name: pi; password: raspberry) and click "OK".



Later, you can enter the RPi desktop system.



Here, you have successfully used the remote desktop login to RPi.

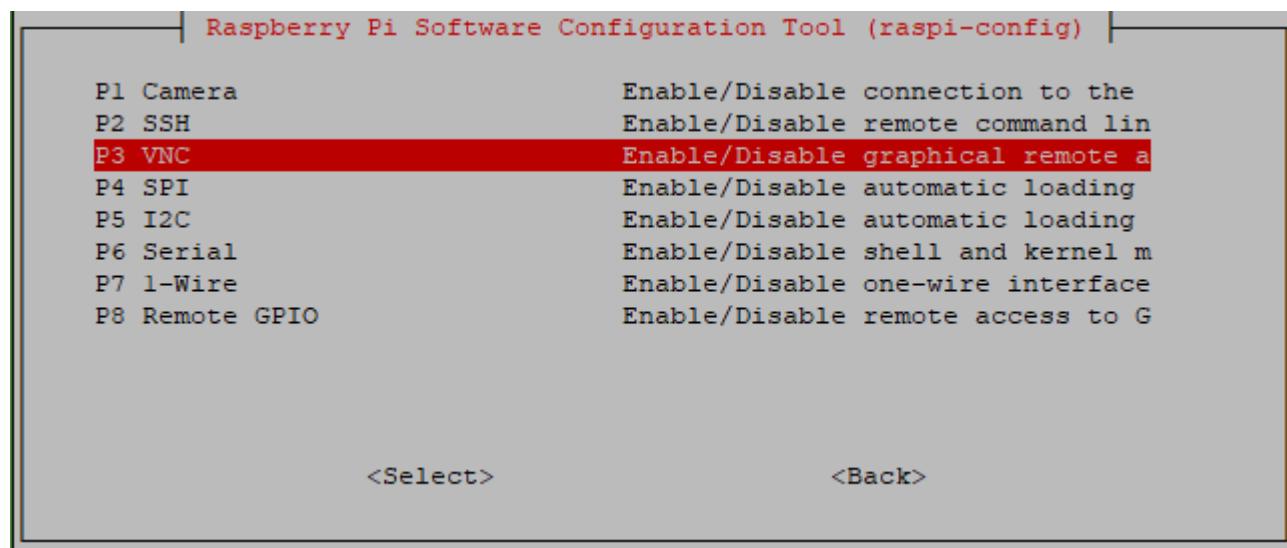
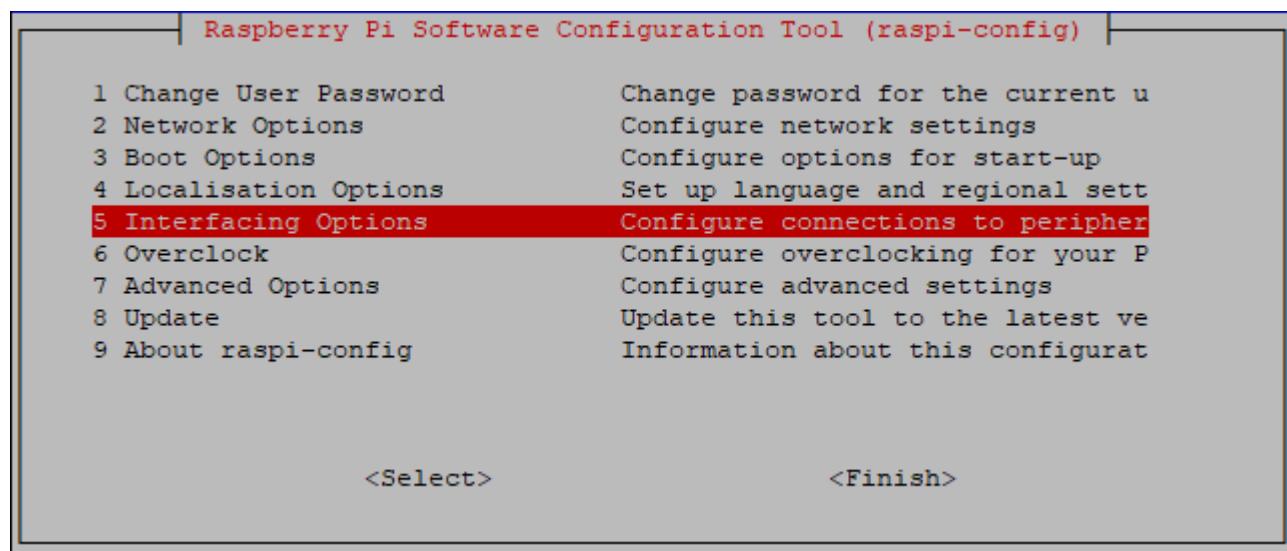
Raspberry Pi 4B/3B+/3B integrates a Wi-Fi adaptor. You can use it to connect to your Wi-Fi. Then you can use the wireless remote desktop to control your RPi.



VNC Viewer & VNC

Type the following command. And select 5 Interfacing Options → P3 VNC → Yes → OK → Finish. Here Raspberry Pi may need be restarted, and choose ok. Then open VNC interface.

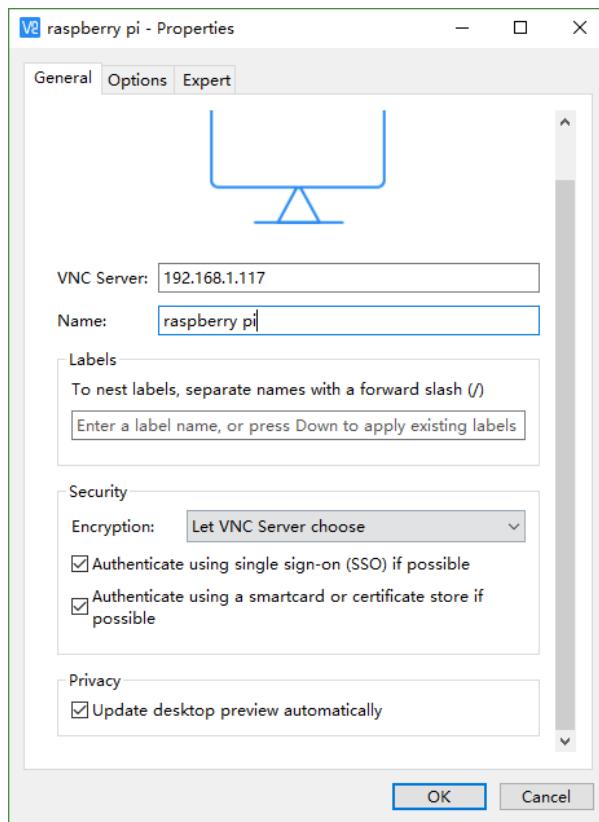
```
sudo raspi-config
```



Then download and install VNC Viewer according to your computer system by click following link:

<https://www.realvnc.com/en/connect/download/viewer/>

After installation is completed, open VNC Viewer. And click File → New Connection. Then the interface is shown below.

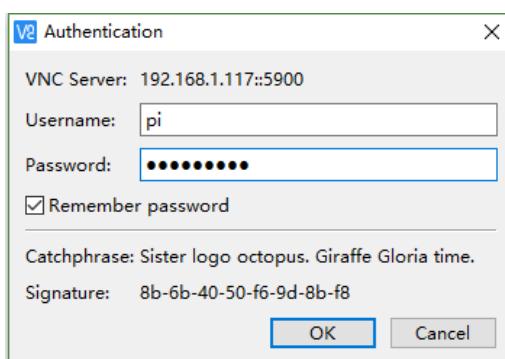


Enter ip address of your Raspberry Pi and fill in a name. Then click OK.

Then on the VNC Viewer panel, double-click new connection you just created,



and the following dialog box pops up.





Enter username: **pi** and Password: **raspberry**. And click OK.

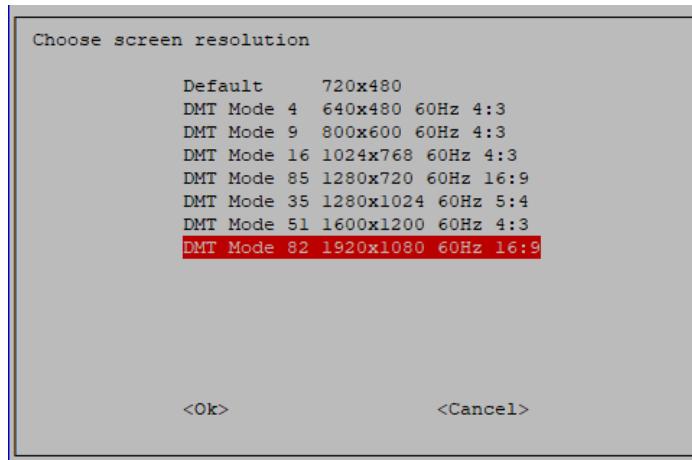


Here, you have logged in to Raspberry Pi successfully by using VNC Viewer

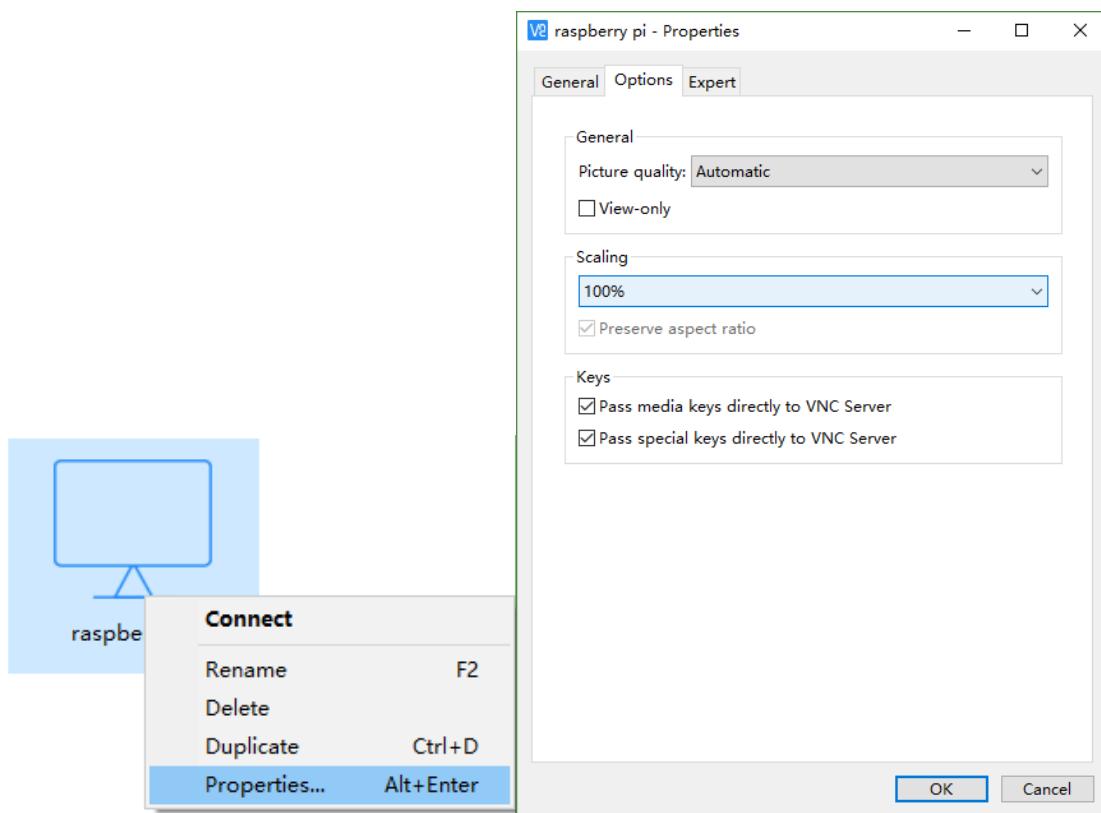
If the resolution ratio is not great or there is just a **little window**, you can set a proper resolution ratio via steps below.

`sudo raspi-config`

Select 7 Advanced Options → A5 Resolution → proper resolution ratio (set by yourself) → OK → Finish. And then reboot Raspberry Pi.

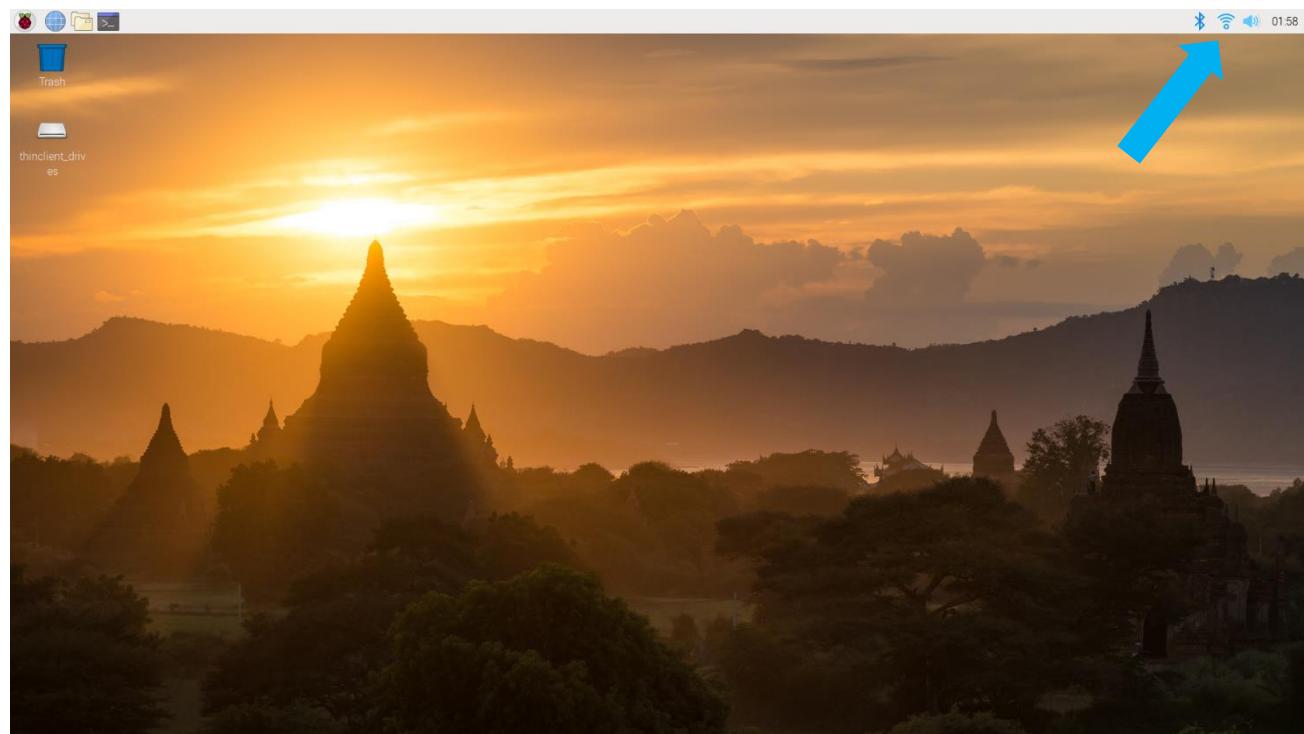


In addition, your VNC Viewer window may zoom your Raspberry Pi desktop. You can change it. On your VNC View control panel, click right key. And select Properties->Options label->Scaling. Then set proper scaling.



Here, you have logged in to Raspberry Pi successfully by using VNC Viewer and operated proper setting.

Raspberry Pi 4B/3B+/3B integrates a Wi-Fi adaptor. If you did not connect Pi to WiFi. You can connect it to wirelessly control the robot.



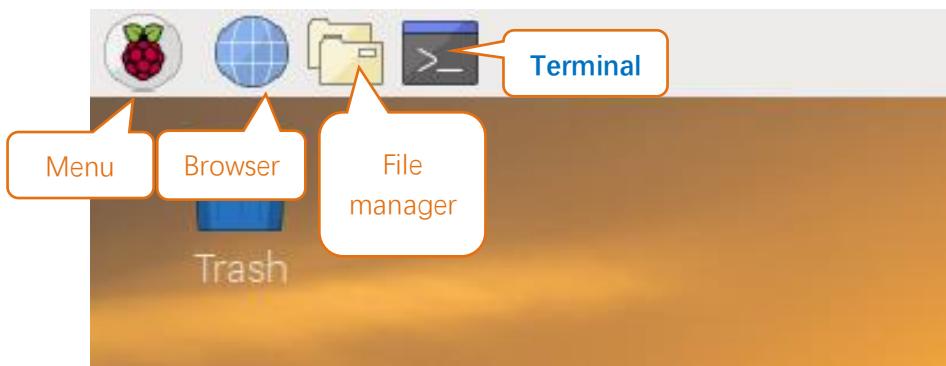
Chapter 0 Preparation

Why “Chapter 0”? Because in program code the first number is 0. We choose to follow this rule. In this chapter, we will do some necessary foundational preparation work: Start your Raspberry Pi and install some necessary libraries.

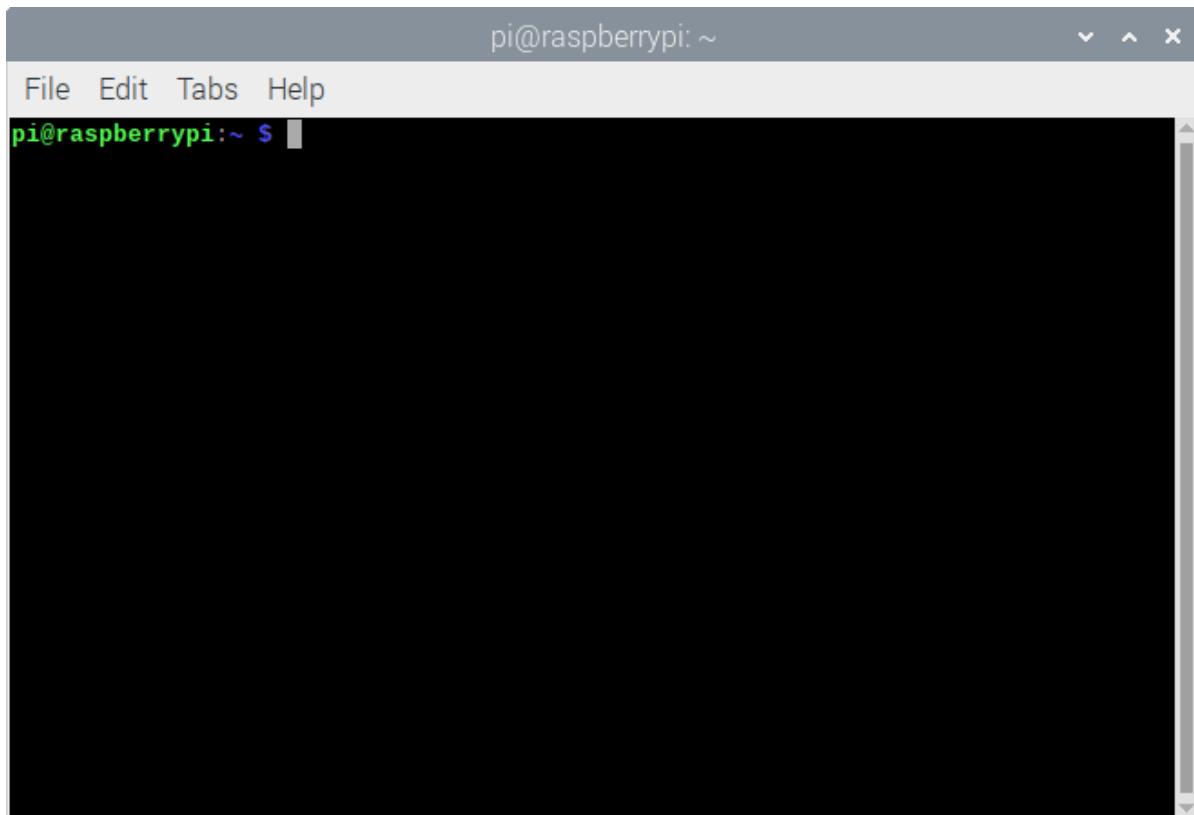
Linux Command

Raspberry Pi OS is based on the Linux Operation System. Now we will introduce you to some frequently used Linux commands and rules.

First, open the Terminal. All commands are executed in Terminal.



When you click the Terminal icon, following interface appears.



Note: The Linux is case sensitive.

First, type “ls” into the Terminal and press the “Enter” key. The result is shown below:

```
pi@raspberrypi:~ $ ls
Desktop
Documents
Downloads
Freenove_Three-wheeled_Smart_Car_Kit_for_Raspberry_Pi
Freenove_Ultimate_Starter_Kit_for_Raspberry_Pi
MagPi
mu_code
Music
Pictures
Public
Templates
thinclient_drives
Videos
```

The “ls” command lists information about the files (the current directory by default).

Content between “\$” and “pi@raspberrypi:” is the current working path. “~” represents the user directory, which refers to “/home/pi” here.

```
pi@raspberrypi:~ $ pwd
/home/pi
```

“cd” is used to change directory. “/” represents the root directory.

```
pi@raspberrypi:~ $ cd /usr
pi@raspberrypi:/usr $ ls
bin  games  include  lib  local  man  sbin  share  src
pi@raspberrypi:/usr $ cd ~
pi@raspberrypi:~ $
```

Later in this Tutorial, we will often change the working path. Typing commands under the wrong directory may cause errors and break the execution of further commands.

Many frequently used commands and instructions can be found in the following reference table.

Command	instruction
ls	Lists information about the FILEs (the current directory by default) and entries alphabetically.
cd	Changes directory
sudo + cmd	Executes cmd under root authority
./	Under current directory
gcc	GNU Compiler Collection
git clone URL	Use git tool to clone the contents of specified repository, and URL in the repository address.

There are many commands, which will come later. For more details about commands. You can refer to:

<http://www.linux-commands-examples.com>

Shortcut Key

Now, we will introduce several commonly used shortcuts that are very useful in Terminal.

1. **Up and Down Arrow Keys:** Pressing “↑” (the Up key) will go backwards through the command history and pressing “↓” (the Down Key) will go forwards through the command history.
2. **Tab Key:** The Tab key can automatically complete the command/path you want to type. When there is only one eligible option, the command/path will be completely typed as soon as you press the Tab key even you only type one character of the command/path.

As shown below, under the '~' directory, you enter the Documents directory with the "cd" command. After typing "cd D", pressing the Tab key (there is no response), pressing the Tab key again then all the files/folders that begin with "D" will be listed. Continue to type the letters "oc" and then pressing the Tab key, the "Documents" is typed automatically.

```
pi@raspberrypi:~ $ cd D
Desktop/  Documents/ Downloads/
pi@raspberrypi:~ $ cd Doc█
```

```
pi@raspberrypi:~ $ cd D
Desktop/  Documents/ Downloads/
pi@raspberrypi:~ $ cd Documents/
```

Install WiringPi

WiringPi is a GPIO access library written in C language for the BCM2835/BMC2836/BMC2837 used in the Raspberry Pi. It is released under the GNU LGPLv3 license and is usable from C, C++ and many other languages with suitable wrappers (See below). It is designed to be user friendly for those people who have had prior experience with the Arduino “wiring” system. (for more details, please refer to <http://wiringpi.com/>)

WiringPi Installation Steps

To install the WiringPi library, please open the Terminal and then follow the steps and commands below.

Note: For a command containing many lines, execute them one line at a time.

Enter the following command in the terminal to install WiringPi:

```
sudo apt-get update  
sudo apt-get upgrade  
sudo apt-get install wiringpi
```

And then the installation will be complete quickly as shown below.

```
pi@raspberrypi:~ $ sudo apt-get install wiringpi  
Reading package lists... Done  
Building dependency tree  
Reading state information... Done  
The following packages were automatically installed and are no longer required:  
  freetype2-doc rpi.gpio-common  
Use 'sudo apt autoremove' to remove them.  
The following NEW packages will be installed:  
  wiringpi  
0 upgraded, 1 newly installed, 0 to remove and 0 not upgraded.  
Need to get 0 B/52.9 kB of archives.  
After this operation, 0 B of additional disk space will be used.  
Selecting previously unselected package wiringpi.  
(Reading database ... 159071 files and directories currently installed.)  
Preparing to unpack .../wiringpi_2.50_armhf.deb ...  
Unpacking wiringpi (2.50) ...  
Setting up wiringpi (2.50) ...  
Processing triggers for man-db (2.8.5-2) ...
```

Run the gpio command to check the installation:

```
gpio -v
```

That should give you some confidence that the installation was a success.

```
pi@raspberrypi:~ $ gpio -v  
gpio version: 2.50  
Copyright (c) 2012-2018 Gordon Henderson  
This is free software with ABSOLUTELY NO WARRANTY.  
For details type: gpio -warranty  
  
Raspberry Pi Details:  
Type: Unknown17, Revision: 01, Memory: 1024MB, Maker: Sony  
* Device tree is enabled.  
*--> Raspberry Pi 4 Model B Rev 1.1  
* This Raspberry Pi supports user-level GPIO access.
```

Note: The new Raspberry Pi OS has integrated the WiringPi library. So when you enter the installing command, it may prompt that you have installed it as shown below. If so, you can skip the process of checking installation.

```
pi@raspberrypi:~ $ sudo apt-get install wiringpi
Reading package lists... Done
Building dependency tree
Reading state information... Done
wiringpi is already the newest version (2.50).
The following packages were automatically installed and are no longer required:
  rpi-eeprom-images vlc-l10n vlc-plugin-notify vlc-plugin-samba
  vlc-plugin-video-splitter vlc-plugin-visualization
Use 'sudo apt autoremove' to remove them.
0 upgraded, 0 newly installed, 0 to remove and 16 not upgraded.
pi@raspberrypi:~ $
```

Obtain the Project Code

After the above installation is complete, you can visit our official website (<http://www.freenove.com>) or our GitHub resources at (<https://github.com/freenove>) to download the latest available project code. We provide both **C** language and **Python** language code for each project to allow ease of use for those who are skilled in either language.

This is the method for obtaining the code:

In the pi directory of the RPi terminal, enter the following command.

```
cd ~
```

```
git clone --depth 1 https://github.com/freenove/Freenove_Basic_Starter_Kit_for_Raspberry_Pi
```

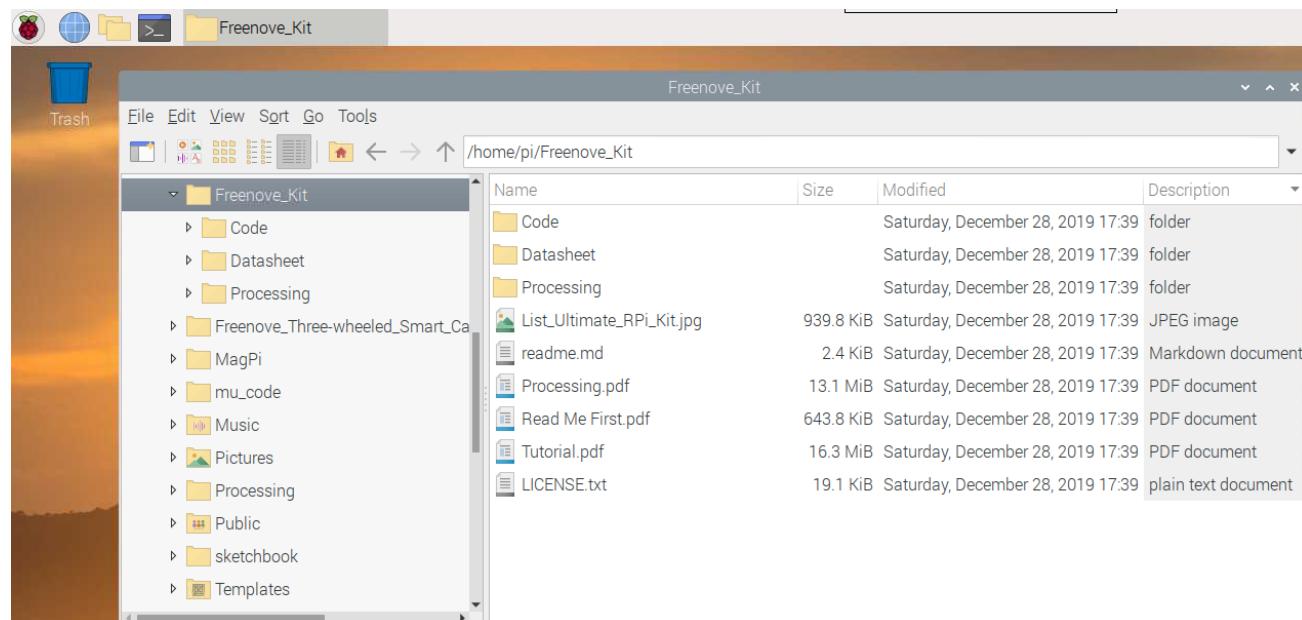
(There is no need for a password. If you get some errors, please check errors in your commands.)

After the download is completed a new folder "Freenove_Basic_Starter_Kit_for_Raspberry_Pi" is generated, which contains all of the tutorials and required code.

This folder name seems a little too long. We can simply rename it by using the following command.

```
mv Freenove_Basic_Starter_Kit_for_Raspberry_Pi/ Freenove_Kit/
```

"Freenove_Kit" is now the new and much shorter folder name.



If you have no experience with Python, we suggest that you refer to this website for basic information and knowledge.

<https://python.swaroopch.com/basics.html>

Python2 & Python3

If you only use C/C++, you can skip this section.

Python code, used in our kits, can now run on Python2 and Python3. **Python3 is recommend**. If you want to use Python2, please make sure your Python version is 2.7 or above. Python2 and Python3 are not fully compatible. However, Python2.6 and Python2.7 are transitional versions to python3, therefore you can also use Python2.6 and 2.7 to execute some Python3 code.

You can type “python2” or “python3” respectively into Terminal to check if python has been installed. Press Ctrl-Z to exit.

```
pi@raspberrypi:~ $ python2
Python 2.7.13 (default, Nov 24 2017, 17:33:09)
[GCC 6.3.0 20170516] on linux2
Type "help", "copyright", "credits" or "license" for more information.
>>>
[2]+  Stopped                  python2
pi@raspberrypi:~ $ python3
Python 3.5.3 (default, Jan 19 2017, 14:11:04)
[GCC 6.3.0 20170124] on linux
Type "help", "copyright", "credits" or "license" for more information.
>>> █
```

Type “python”, and Terminal shows that it links to python2.

```
pi@raspberrypi:~ $ python
Python 2.7.13 (default, Nov 24 2017, 17:33:09)
[GCC 6.3.0 20170516] on linux2
Type "help", "copyright", "credits" or "license" for more information.
>>> █
```

If you want to use Python3 in Raspberry Pi, it is recommended to set python3 as default Python by following the steps below.

1. Enter directory /usr/bin

```
cd /usr/bin
```

2. Delete the old python link.

```
sudo rm python
```

3. Create new python links to python3.

```
sudo ln -s python3 python
```

4. Execute python to check whether the link succeeds.

```
python
```

```
pi@raspberrypi:/usr/bin $ sudo rm python
pi@raspberrypi:/usr/bin $ sudo ln -s python3 python
pi@raspberrypi:/usr/bin $ python
Python 3.5.3 (default, Jan 19 2017, 14:11:04)
[GCC 6.3.0 20170124] on linux
Type "help", "copyright", "credits" or "license" for more information.
>>>
```

If you want to use Python2, repeat the steps above and just change the third command to the following:

```
sudo ln -s python2 python
```

```
pi@raspberrypi:/usr/bin $ sudo rm python
pi@raspberrypi:/usr/bin $ sudo ln -s python2 python
pi@raspberrypi:/usr/bin $ python
Python 2.7.13 (default, Nov 24 2017, 17:33:09)
[GCC 6.3.0 20170516] on linux2
Type "help", "copyright", "credits" or "license" for more information.
>>> █
```

We will only use the term “Python” without reference to Python2 or Python3. You can choose to use either Python version according to your preference.



Code Editor

vi, nano, Geany

vi

Here we will introduce three kinds of code editor: vi, nano and Geany. Among them, nano and vi are used to edit files directly in the terminal. And Geany is an independent editing software, which is recommended for beginner. We will use the three editors to open an example code "Hello.c" respectively. First we will show how to use vi and nano editor:

First, use cd command to enter the sample code folder.

```
cd ~
cd ~/Freenove_Kit/Code/C_Code/00.0.0_Hello
```

Use the vi editor to open the file "Hello.c", then press ": q" and "Enter" to exit.

```
vi Hello.c
```

As is shown below:

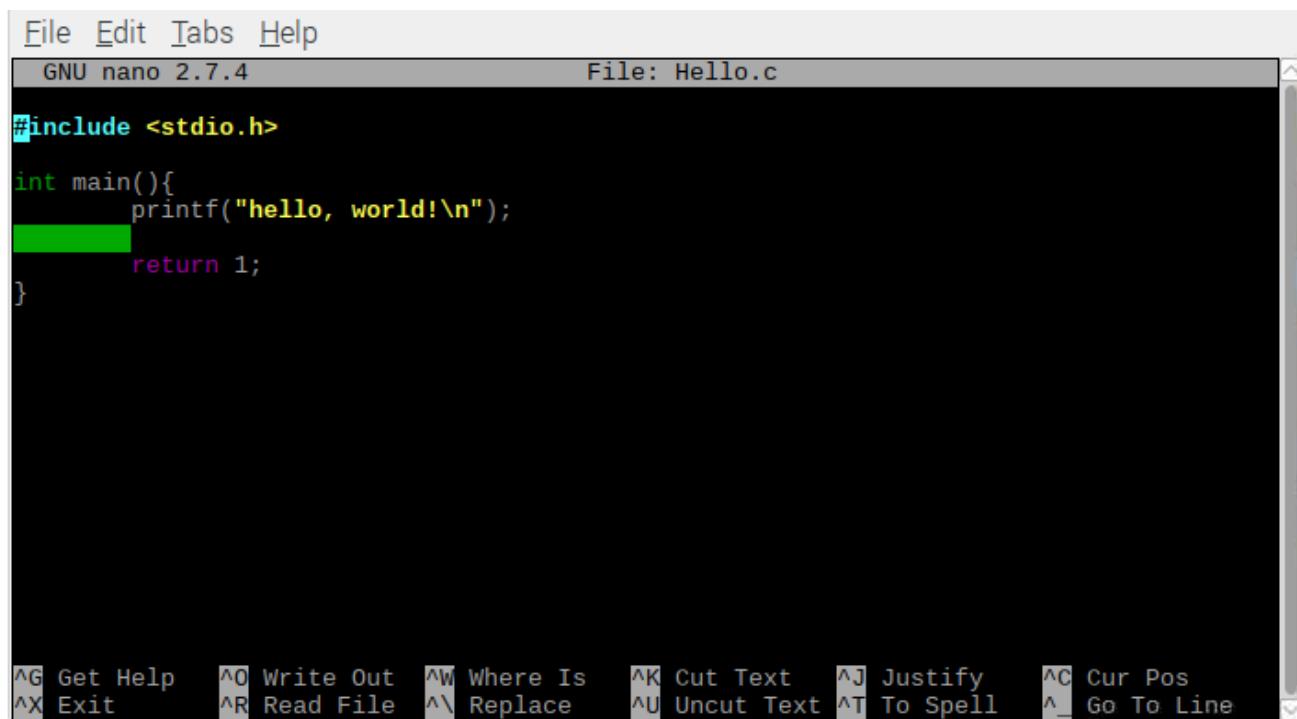
```
File Edit Tabs Help
#include <stdio.h>
int main(){
    printf("hello, world!\n");
    return 1;
}
"Hello.c" [Incomplete last line] 7 lines, 74 characters
```

nano

Use the nano editor to open the file "Hello.c", then press " Ctrl+X " to exit.

```
nano Hello.c
```

As is shown below:



```
File Edit Tabs Help
GNU nano 2.7.4 File: Hello.c
#include <stdio.h>
int main(){
    printf("Hello, world!\n");
    return 1;
}

^G Get Help ^O Write Out ^W Where Is ^K Cut Text ^J Justify ^C Cur Pos
^X Exit      ^R Read File ^\ Replace ^U Uncut Text ^T To Spell ^_ Go To Line
```

Use the following command to compile the code to generate the executable file "Hello".

```
gcc Hello.c -o Hello
```

Use the following command to run the executable file "Hello".

```
sudo ./Hello
```

After the execution, "Hello, World!" is printed out in terminal.

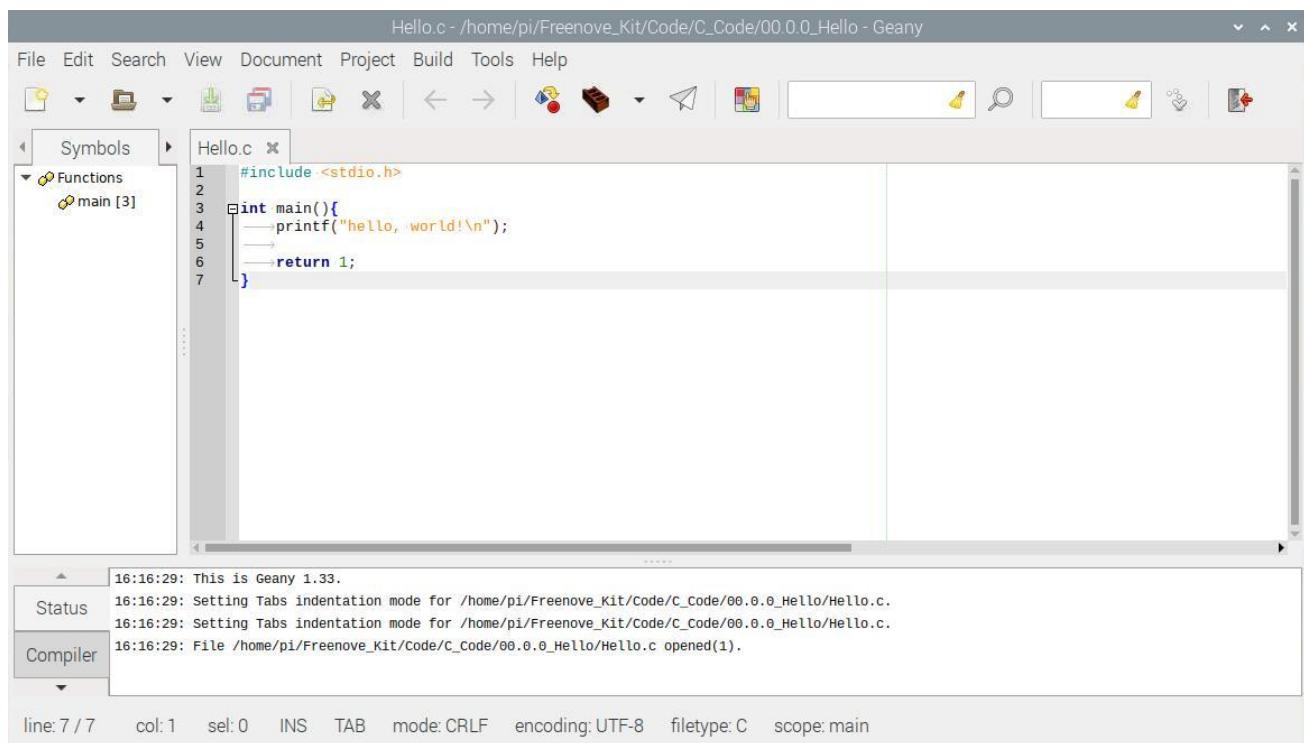
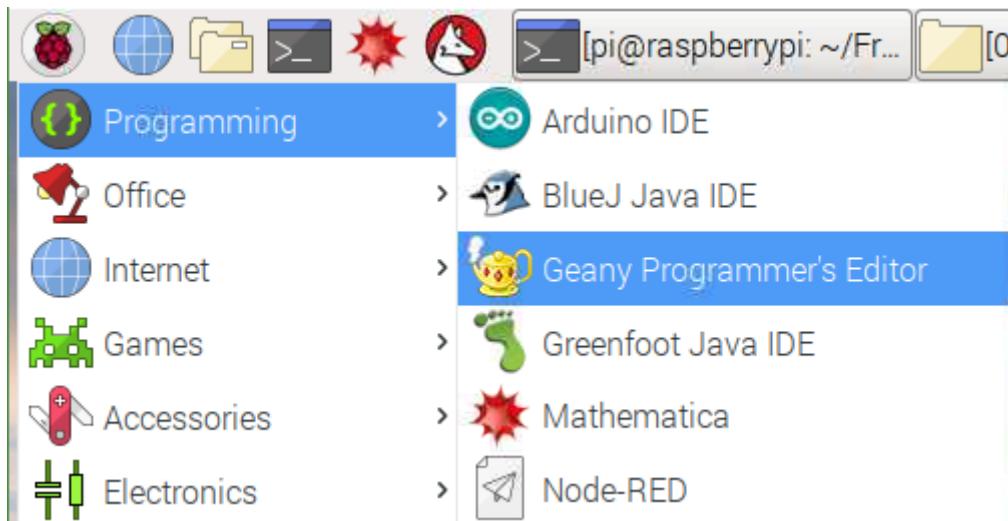
```
pi@raspberrypi:~/Freenove_Kit/Code/C_Code/00.0.0_Hello $ gcc Hello.c -o Hello
pi@raspberrypi:~/Freenove_Kit/Code/C_Code/00.0.0_Hello $ sudo ./Hello
Hello, world!
```

geany

Next, learn to use the Geany editor. Use the following command to open the Geany in the sample file "Hello.c" file directory path.

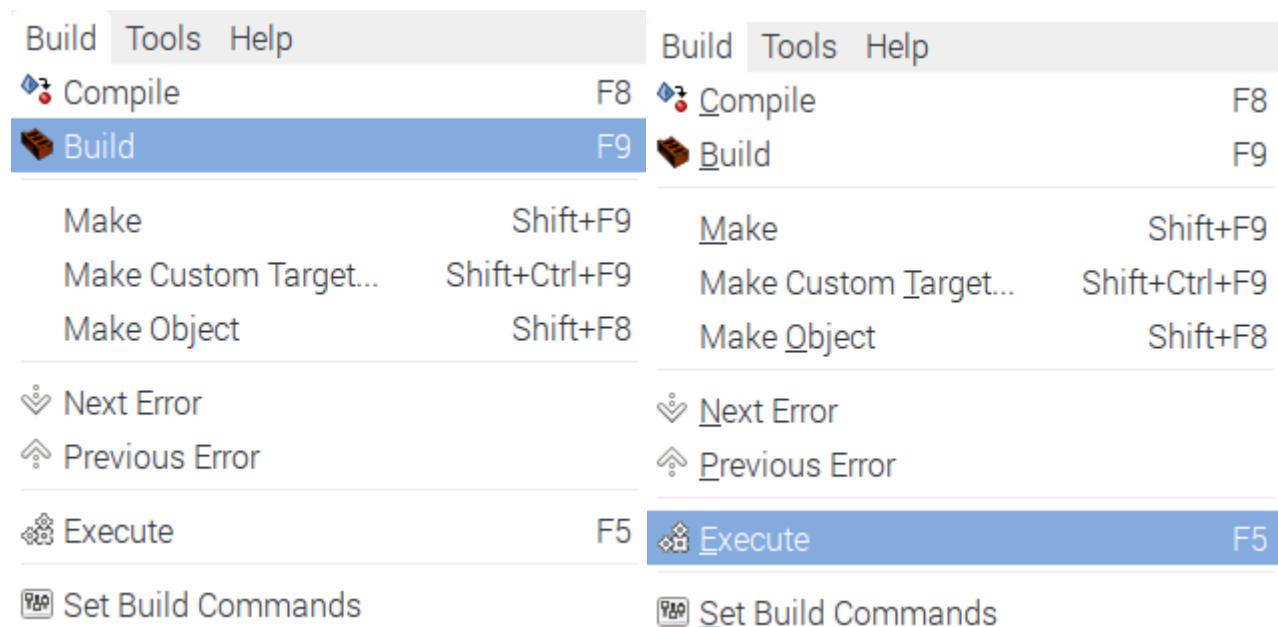
geany Hello.c

Or find and open Geany directly in the desktop main menu, and then click **File→Open** to open the "Hello.c", Or drag "Hello.c" to Geany directly.



If you want to create a new code, click **File→New→File→Save as (name.c or name.py)**. Then write the code.

Generate an executable file by clicking menu bar Build->Build, then execute the generated file by clicking menu bar Build->Execute.



After the execution, a new terminal window will output the characters "Hello, World!", as shown below:

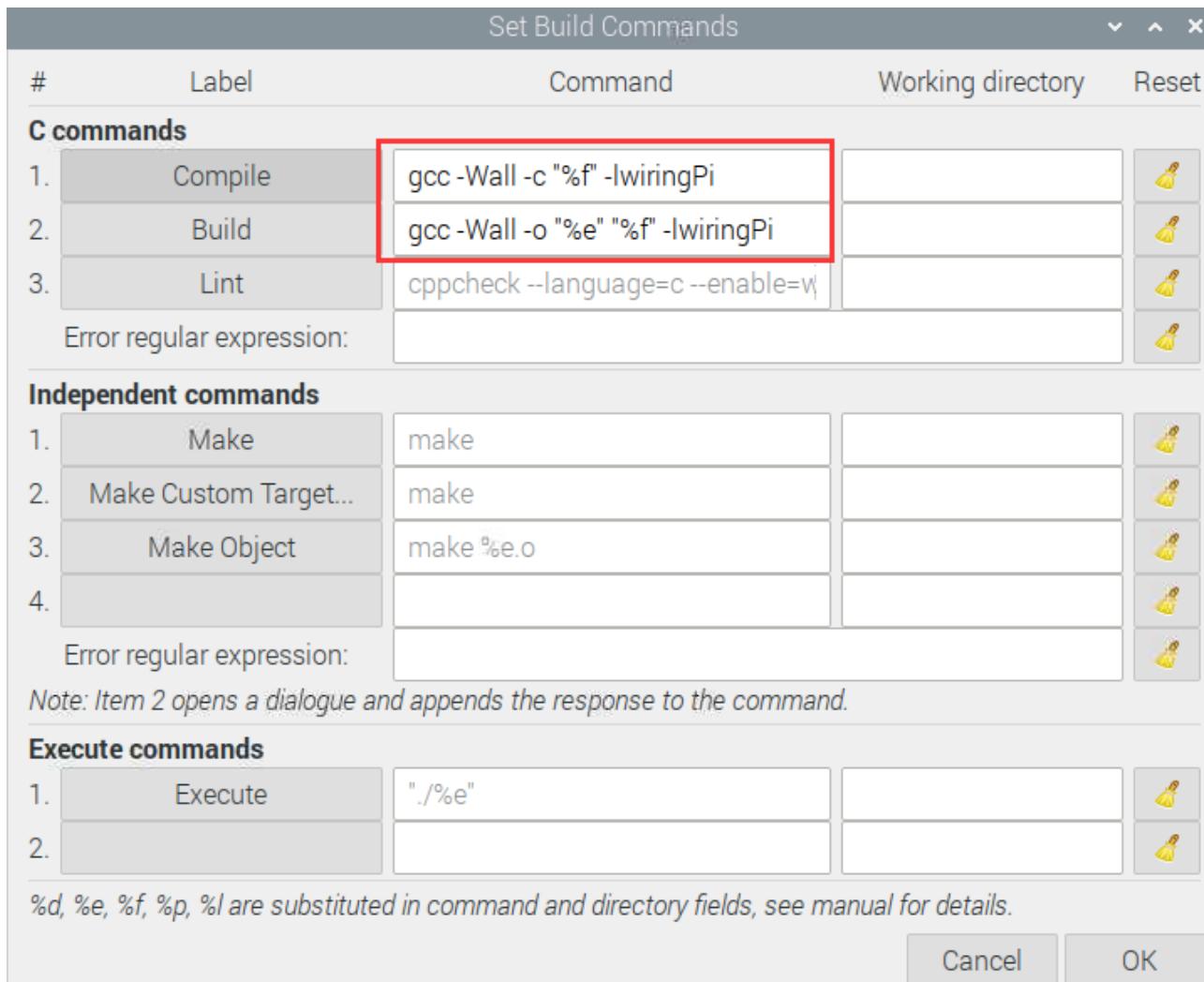
```
sh
File Edit Tabs Help
hello, world!

-----
(program exited with code: 1)
Press return to continue
```

A screenshot of a terminal window titled 'sh'. The window has a blue header bar with the title 'sh' and standard window controls. The main area is black with white text. It displays the output of a program: 'hello, world!', followed by a dashed line, '(program exited with code: 1)', and the instruction 'Press return to continue'. A vertical scroll bar is visible on the right side of the terminal window.



You can click Build->Set Build Commands to set compiler commands. In later projects, we will use various compiler command options. **If you choose to use Geany, you will need change the compiler command here.** As is shown below:



Summary

Here we have identified three code editors: vi, nano and Geany. There are also many other good code editors available to you, and you can choose whichever you prefer to use.

In later projects, we will only use terminal to execute the project code. This way will not modify the code by mistake.

GPIO

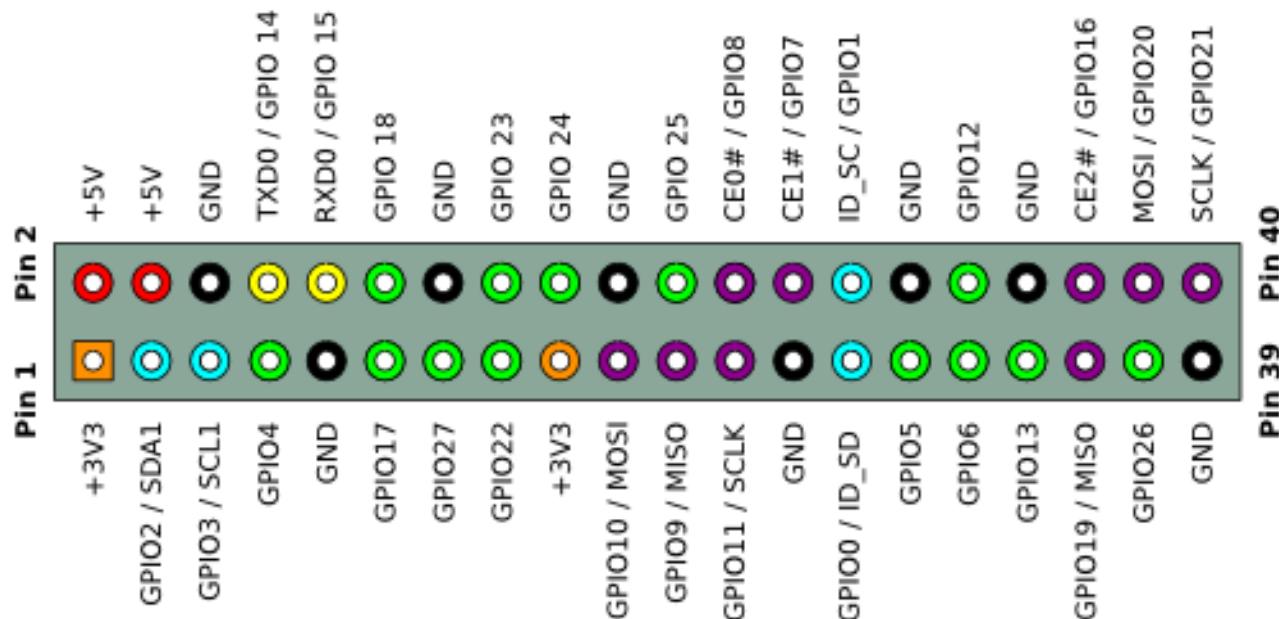
GPIO: General Purpose Input/Output. Here we will introduce the specific function of the pins on the Raspberry Pi and how you can utilize them in all sorts of ways in your projects. Most RPi Module pins can be used as either an input or output, depending on your program and its functions.

When programming GPIO pins there are 3 different ways to reference them: GPIO Numbering, Physical Numbering and WiringPi GPIO Numbering.

BCM GPIO Numbering

The Raspberry Pi CPU uses Broadcom (BCM) processing chips BCM2835, BCM2836 or BCM2837. GPIO pin numbers are assigned by the processing chip manufacturer and are how the computer recognizes each pin. The pin numbers themselves do not make sense or have meaning as they are only a form of identification. Since their numeric values and physical locations have no specific order, there is no way to remember them so you will need to have a printed reference or a reference board that fits over the pins.

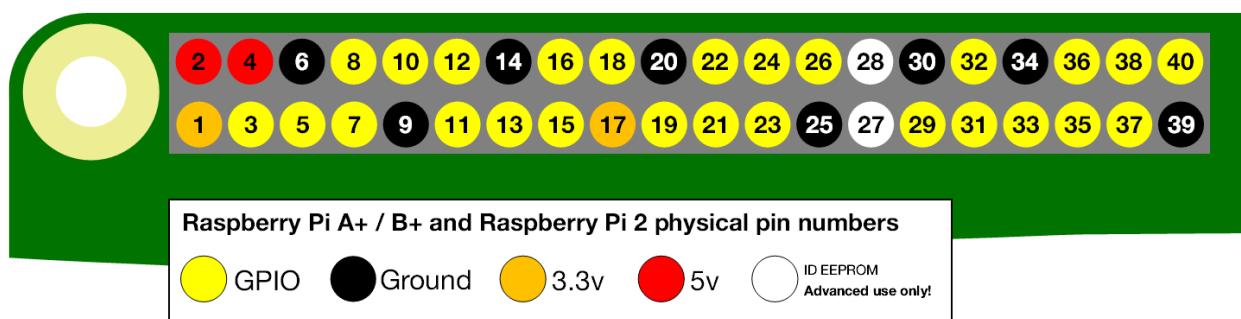
Each pin's functional assignment is defined in the image below:



For more details about pin definition of GPIO, please refer to <http://pinout.xyz/>

PHYSICAL Numbering

Another way to refer to the pins is by simply counting across and down from pin 1 at the top left (nearest to the SD card). This is 'Physical Numbering', as shown below:



WiringPi GPIO Numbering

Different from the previous two types of GPIO serial numbers, RPi GPIO serial number of the WiringPi are numbered according to the BCM chip use in RPi.

wiringPi Pin	BCM GPIO	Name	Header	Name	BCM GPIO	wiringPi Pin	
wiringPi Pin	BCM GPIO	Name	Header	Name	BCM GPIO	wiringPi Pin	
—	—	3.3v	1 2	5v	—	—	For A+, B+, 2B, 3B, 3B+, 4B, Zero
8	R1:0/R2:2	SDA	3 4	5v	—	—	
9	R1:1/R2:3	SCL	5 6	0v	—	—	
7	4	GPIO7	7 8	TxD	14	15	
—	—	0v	9 10	RxD	15	16	For Pi B
0	17	GPIO0	11 12	GPIO1	18	1	
2	R1:21/R2:27	GPIO2	13 14	0v	—	—	
3	22	GPIO3	15 16	GPIO4	23	4	
—	—	3.3v	17 18	GPIO5	24	5	
12	10	MOSI	19 20	0v	—	—	
13	9	MISO	21 22	GPIO6	25	6	
14	11	SCLK	23 24	CE0	8	10	
—	—	0v	25 26	CE1	7	11	
30	0	SDA.0	27 28	SCL.0	1	31	
21	5	GPIO.21	29 30	0V			
22	6	GPIO.22	31 32	GPIO.26	12	26	
23	13	GPIO.23	33 34	0V			
24	19	GPIO.24	35 36	GPIO.27	16	27	
25	26	GPIO.25	37 38	GPIO.28	20	28	
		0V	39 40	GPIO.29	21	29	
wiringPi Pin	BCM GPIO	Name	Header	Name	BCM GPIO	wiringPi Pin	

(For more details, please refer to <https://projects.drogon.net/raspberry-pi/wiringpi/pins/>)



You can also use the following command to view their correlation.

```
gpio readall
```

BCM	wPi	Name	Mode	V	Physical	V	Mode	Name	wPi	BCM
		3.3v			1 2			5v		
2	8	SDA.1	ALTO	1	3 4			5V		
3	9	SCL.1	ALTO	1	5 6			0v		
4	7	GPIO. 7	IN	1	7 8	1	ALT5	TxD	15	14
		0v			9 10	1	ALT5	RxD	16	15
17	0	GPIO. 0	IN	0	11 12	0	IN	GPIO. 1	1	18
27	2	GPIO. 2	IN	0	13 14			0v		
22	3	GPIO. 3	IN	0	15 16	0	IN	GPIO. 4	4	23
		3.3v			17 18	0	IN	GPIO. 5	5	24
10	12	MOSI	ALTO	0	19 20			0v		
9	13	MISO	ALTO	0	21 22	0	IN	GPIO. 6	6	25
11	14	SCLK	ALTO	0	23 24	1	OUT	CE0	10	8
		0v			25 26	1	OUT	CE1	11	7
0	30	SDA.0	IN	1	27 28	1	IN	SCL.0	31	1
5	21	GPIO.21	IN	1	29 30			0v		
6	22	GPIO.22	IN	1	31 32	0	IN	GPIO.26	26	12
13	23	GPIO.23	IN	0	33 34			0v		
19	24	GPIO.24	IN	0	35 36	0	IN	GPIO.27	27	16
26	25	GPIO.25	IN	0	37 38	0	IN	GPIO.28	28	20
		0v			39 40	0	IN	GPIO.29	29	21
BCM	wPi	Name	Mode	V	Physical	V	Mode	Name	wPi	BCM

Expect to have errors when executing the command "gpio readall" if you are using Raspberry Pi 4B (as shown below):

```
pi@raspberrypi:~ $ gpio readall
Oops - unable to determine board type... model: 17
```

This is because the official version of the library supporting RPI 4B, as of this writing, has not yet been released. This results in some commands not functioning properly. However, the following projects will not be affected. This problem can be solved by installing a patch. Just execute the commands below in the Terminal.

```
sudo apt-get update
sudo apt-get install git
git clone https://github.com/raspberrypi/wiringpi.git
cd wiringpi
make
sudo make install
```

After the installation is completed, Execute "gpio -v" and "gpio readall" commands again.

```
pi@raspberrypi:~ $ gpio -v
gpio version: 2.52
Copyright (c) 2012-2018 Gordon Henderson
This is free software with ABSOLUTELY NO WARRANTY.
For details type: gpio -warranty

Raspberry Pi Details:
  Type: Pi 4B, Revision: 01, Memory: 1024MB, Maker: Sony
  * Device tree is enabled.
  *--> Raspberry Pi 4 Model B Rev 1.1
  * This Raspberry Pi supports user-level GPIO access.

pi@raspberrypi:~ $ gpio readall
+-----+-----+-----+-----+-----+-----+-----+-----+-----+
| BCM | wPi |     Name | Mode | V | Physical | V | Mode | Name | wPi | BCM |
+-----+-----+-----+-----+-----+-----+-----+-----+-----+
|   |   | 3.3v |      |   |    |   |    |   | 5v |   |   |
| 2 | 8 | SDA.1 | ALT0 | 1 | 3 | 4 |   |   | 5v |   |   |
| 3 | 9 | SCL.1 | ALT0 | 1 | 5 | 6 |   |   | 0v |   |   |
| 4 | 7 | GPIO. 7 | IN | 1 | 7 | 8 | 1 | IN | TxD | 15 | 14 |
|   |   | 0v |      |   | 9 | 10 | 1 | IN | RxD | 16 | 15 |
| 17 | 0 | GPIO. 0 | IN | 0 | 11 | 12 | 0 | IN | GPIO. 1 | 1 | 18 |
| 27 | 2 | GPIO. 2 | IN | 0 | 13 | 14 |   |   | 0v |   |   |
| 22 | 3 | GPIO. 3 | IN | 0 | 15 | 16 | 0 | IN | GPIO. 4 | 4 | 23 |
|   |   | 3.3v |      |   | 17 | 18 | 0 | IN | GPIO. 5 | 5 | 24 |
| 10 | 12 | MOSI | IN | 0 | 19 | 20 |   |   | 0v |   |   |
| 9 | 13 | MISO | IN | 0 | 21 | 22 | 0 | IN | GPIO. 6 | 6 | 25 |
| 11 | 14 | SCLK | IN | 0 | 23 | 24 | 1 | IN | CE0 | 10 | 8 |
|   |   | 0v |      |   | 25 | 26 | 1 | IN | CE1 | 11 | 7 |
| 0 | 30 | SDA.0 | IN | 1 | 27 | 28 | 1 | IN | SCL.0 | 31 | 1 |
| 5 | 21 | GPIO.21 | IN | 1 | 29 | 30 |   |   | 0v |   |   |
| 6 | 22 | GPIO.22 | IN | 1 | 31 | 32 | 0 | IN | GPIO.26 | 26 | 12 |
| 13 | 23 | GPIO.23 | IN | 0 | 33 | 34 |   |   | 0v |   |   |
| 19 | 24 | GPIO.24 | IN | 0 | 35 | 36 | 0 | IN | GPIO.27 | 27 | 16 |
| 26 | 25 | GPIO.25 | IN | 0 | 37 | 38 | 0 | IN | GPIO.28 | 28 | 20 |
|   |   | 0v |      |   | 39 | 40 | 0 | IN | GPIO.29 | 29 | 21 |
+-----+-----+-----+-----+-----+-----+-----+-----+-----+
| BCM | wPi |     Name | Mode | V | Physical | V | Mode | Name | wPi | BCM |
+-----+-----+-----+-----+-----+-----+-----+-----+-----+
```

For more details about wiringPi, please refer to <http://wiringpi.com/>.



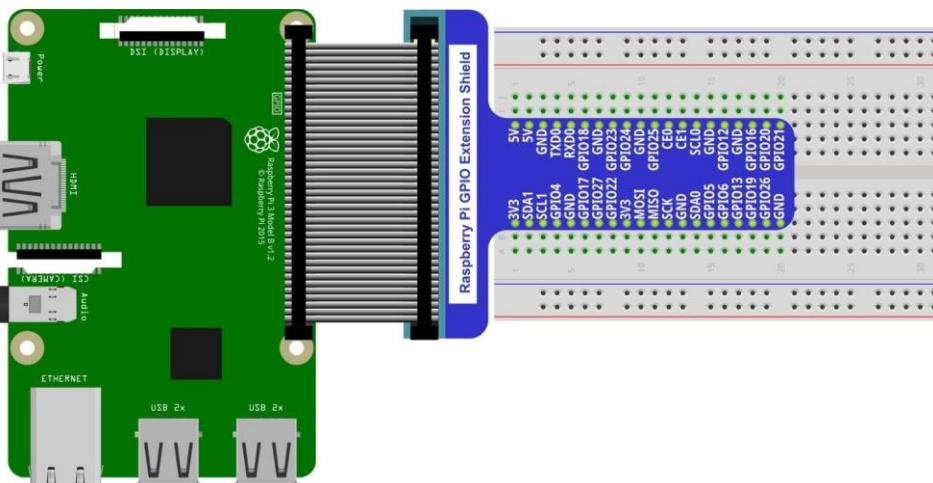
GPIO Numbering Relationship

Here we have three kinds of GPIO number modes: based on the BCM chip number used found in the Rpi Module, relating to the physical sequence number and based on wiringPi. The correlations between these three GPIO numbers are shown below:

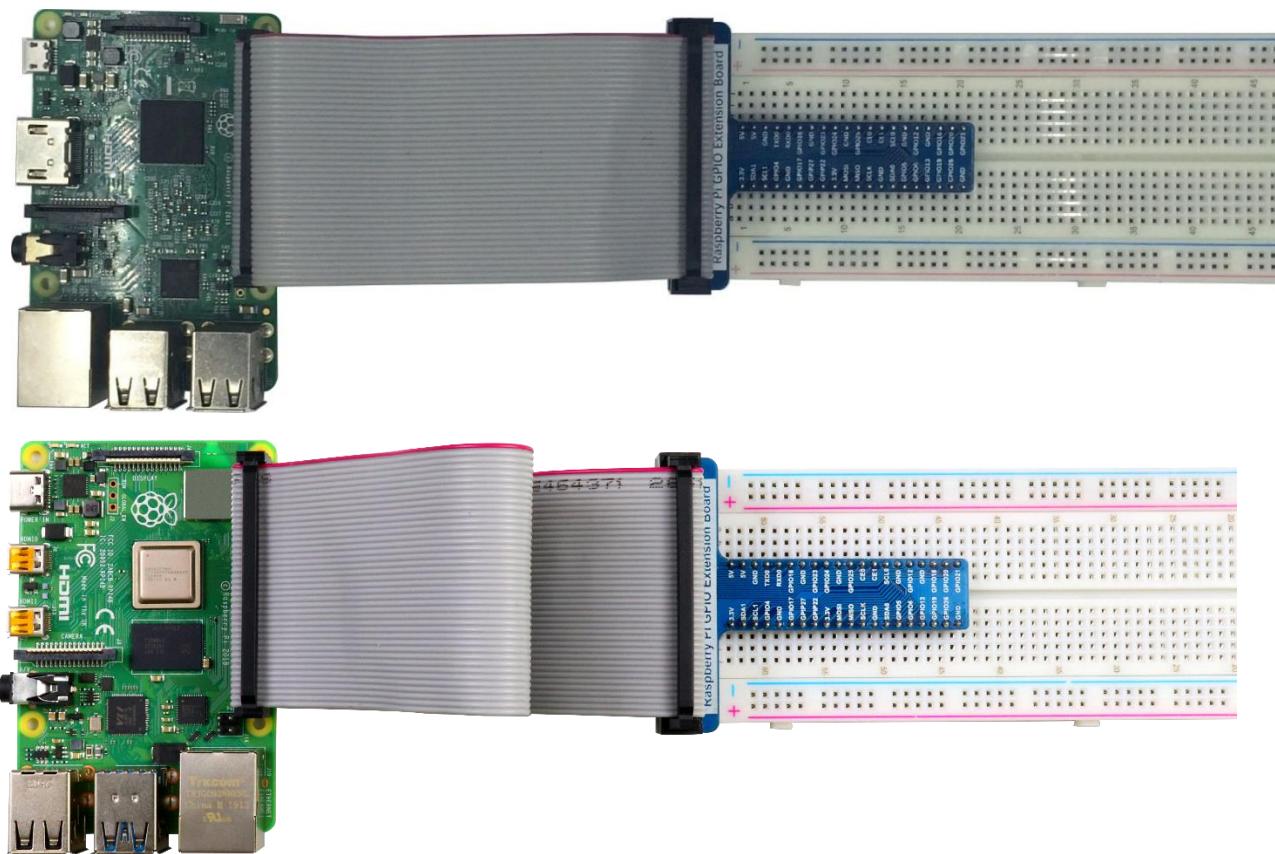
WingPi	BCM(Extension)	Physical		BCM(Extension)	WingPi
3.3V	3.3V	1	2	5V	5V
8	SDA1	3	4	5V	5V
9	SCL1	5	6	GND	GND
7	GPIO17	7	8	GPIO14/TXD0	15
GND	GND	9	10	GPIO15/RXD0	16
0	GPIO17	11	12	GPIO18	1
2	GPIO27	13	14	GND	GND
3	GPIO22	15	16	GPIO23	4
3.3V	3.3V	17	18	GPIO24	5
12	GPIO10/MOSI)	19	20	GND	GND
13	GPIO9/MOIS	21	22	GPIO25	6
14	GPIO11/SCLK	23	24	GPIO8 /CEO	10
GND	GND	25	26	GPIO7 CE1	11
30	GPIO0/SDA0	27	28	GPIO1 /SCLO	31
21	GPIO5	29	30	GND	GND
22	GPIO6	31	32	GPIO12	26
23	GPIO13	33	34	GND	GND
24	GPIO19	35	36	GPIO16	27
25	GPIO26	37	38	GPIO20	28
GND	GND	39	40	GPIO21	29

GPIO Extension Board

When using a RPi in a project, it is best to use the GPIO board, which is the most convenient way to connect the RPi I/O ports to the bread board directly. The GPIO pin sequence on Extension Board is identical to the GPIO pin sequence of RPi. Since the various versions of RPi Modules have different GPIO sequences, the corresponding extensions boards are also different. For example, a GPIO extensions board with 40 pins is connected to RPi as follows:

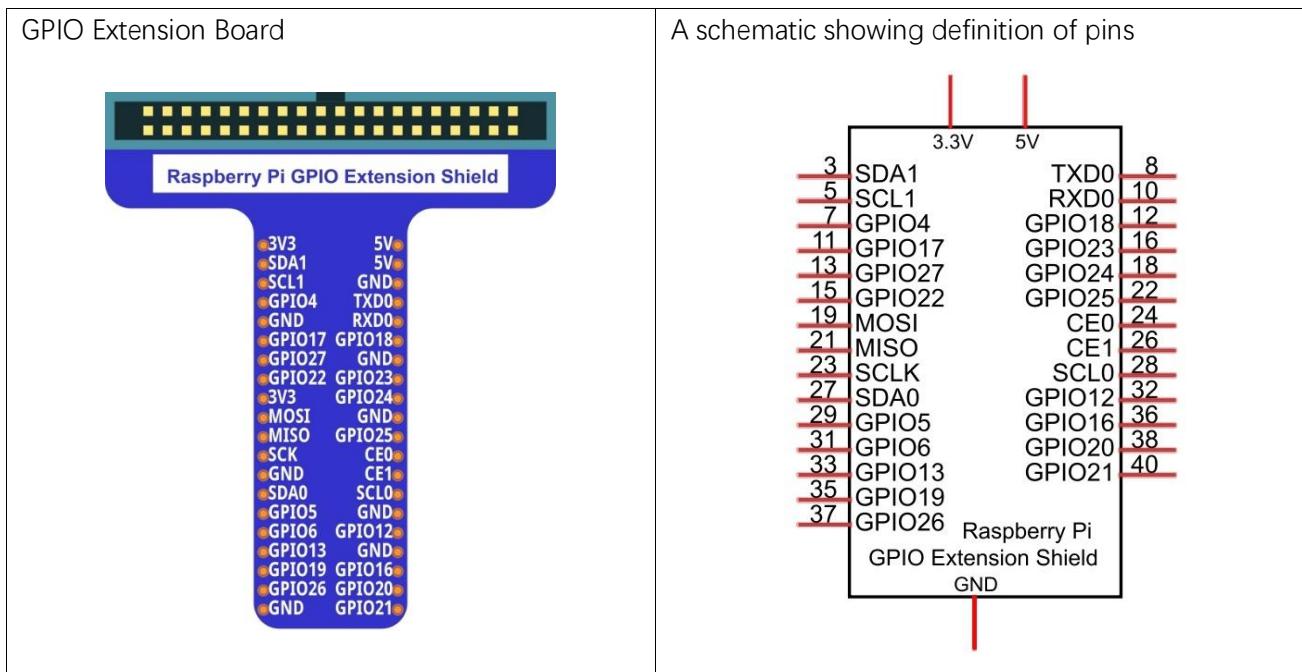


Actual picture of connection:



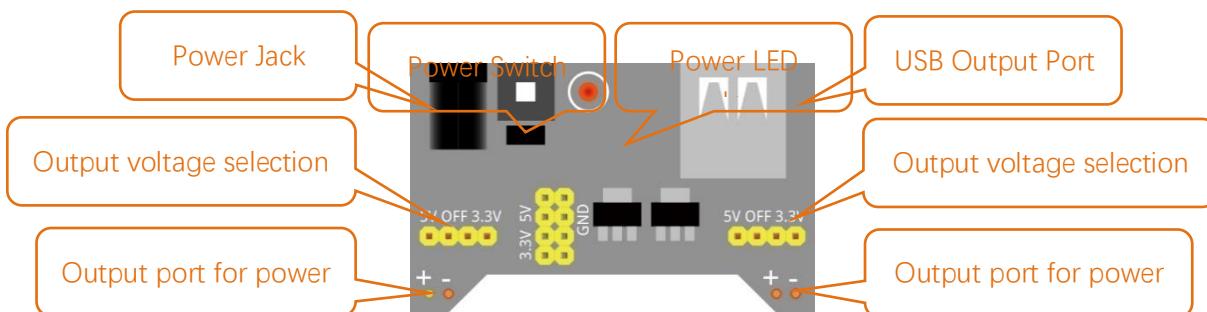


GPIO Extension Board and its schematic are shown below:

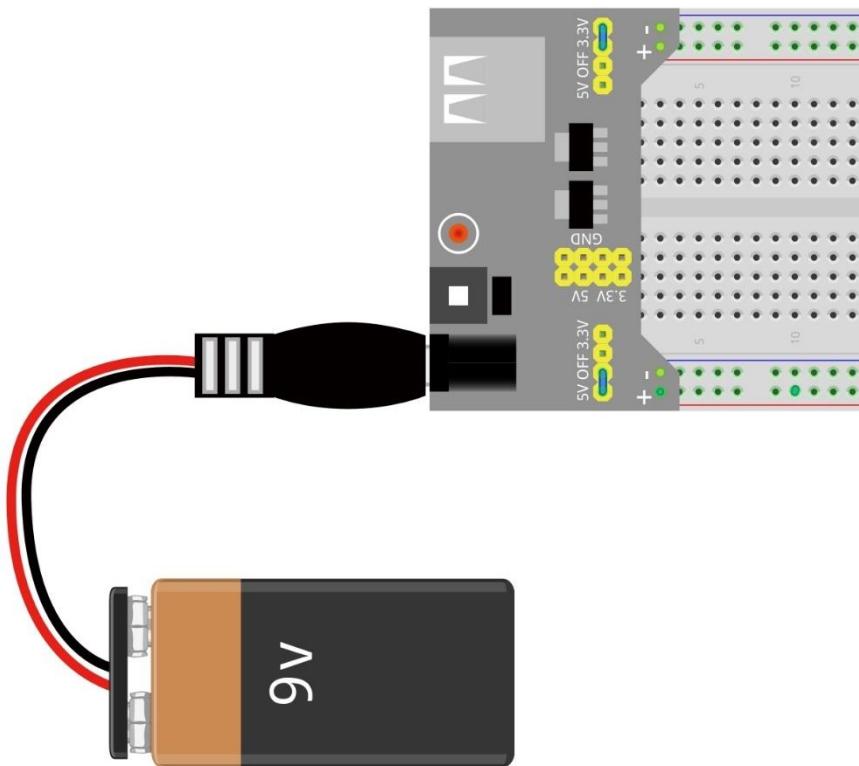


Breadboard Power Module

Breadboard Power Module is an independent circuit board, which can provide independent 5V or 3.3V power to the breadboard when building circuits. It also has built-in power protection to avoid damaging your RPi module. The schematic diagram below identifies the important features of this Power Module:



Here is an acceptable connection between Breadboard Power Module and Breadboard using a 9V battery and the provided power harness:



Next

Finally, all the necessary preparations have been completed! Next, we will combine the RPi and electronic components to build a series of projects from easy to the more challenging and difficult as we focus on learning the associated knowledge of each electronic circuit.



Chapter 1 LED

This chapter is the Start Point in the journey to build and explore RPi electronic projects. We will start with simple "Blink" project.

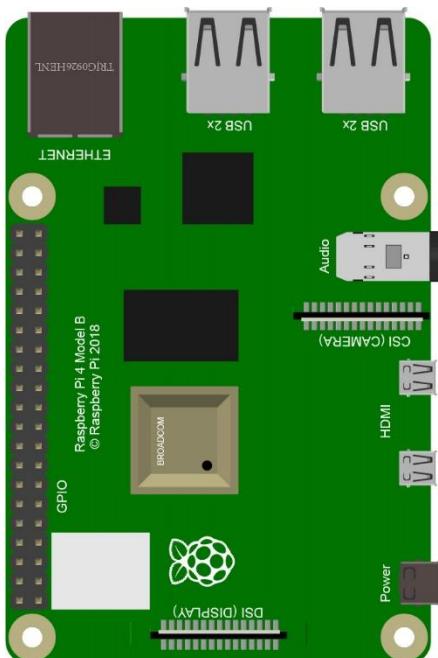
Project 1.1 Blink

In this project, we will use RPi to control blinking a common LED.

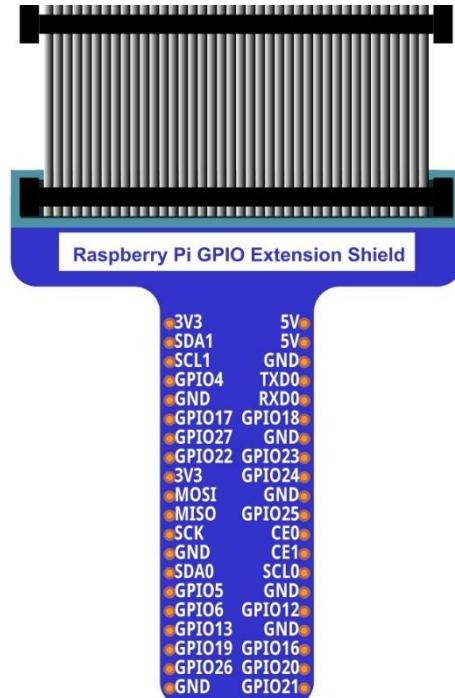
Component List

Raspberry Pi

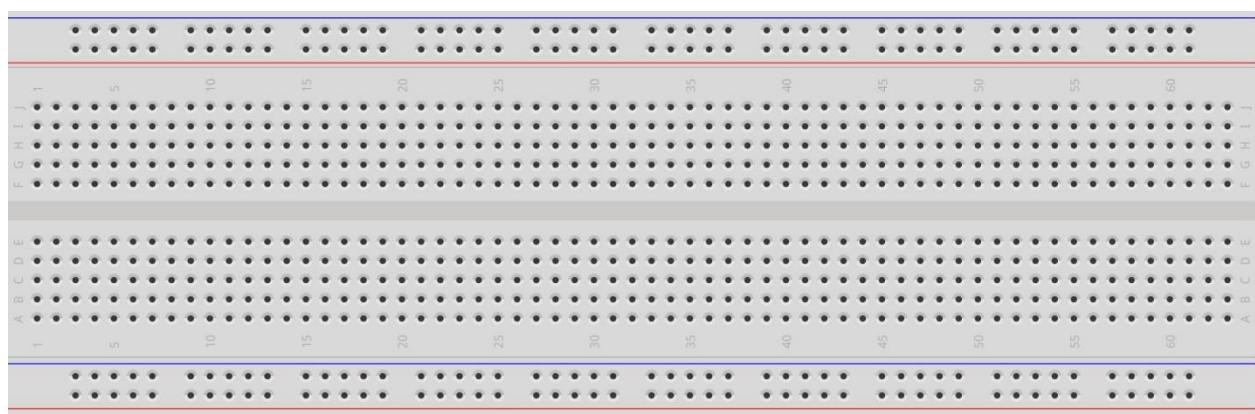
(Recommended: Raspberry Pi 4B / 3B+ / 3B
Compatible: 3A+ / 2B / 1B+ / 1A+ / Zero W / Zero)

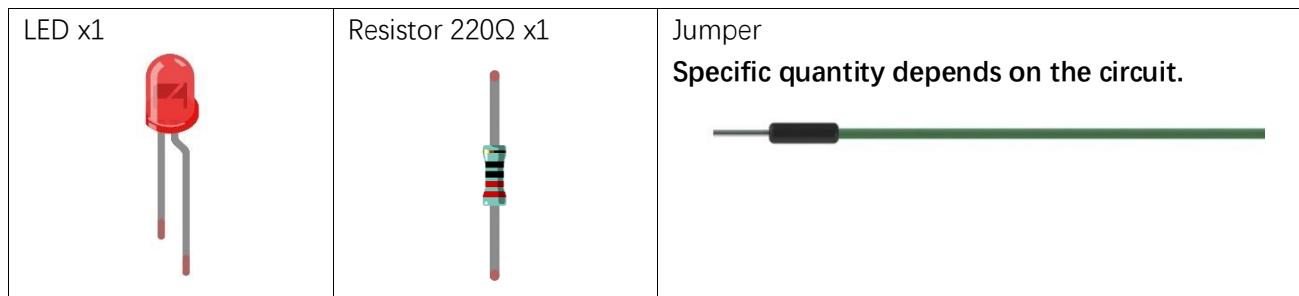


GPIO Extension Board & Ribbon Cable



Breadboard x1



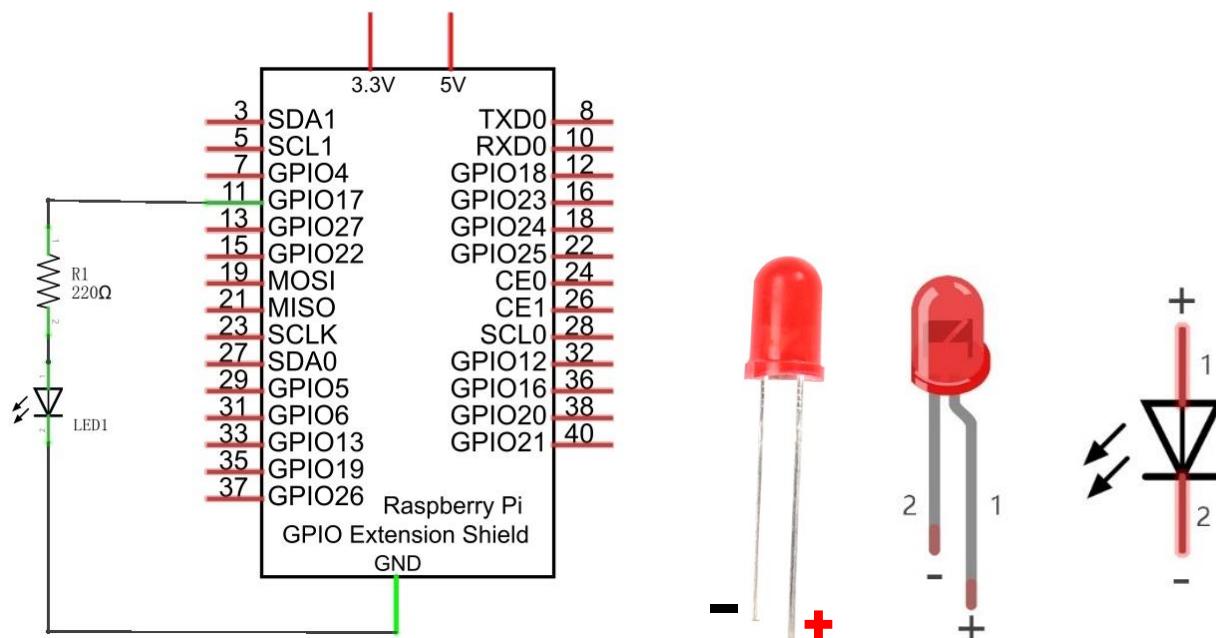


In the components list, 3B GPIO, Extension Shield Raspberry and Breadboard are necessary for each project. Later, they will be reference by text only (no images as in above).

Circuit

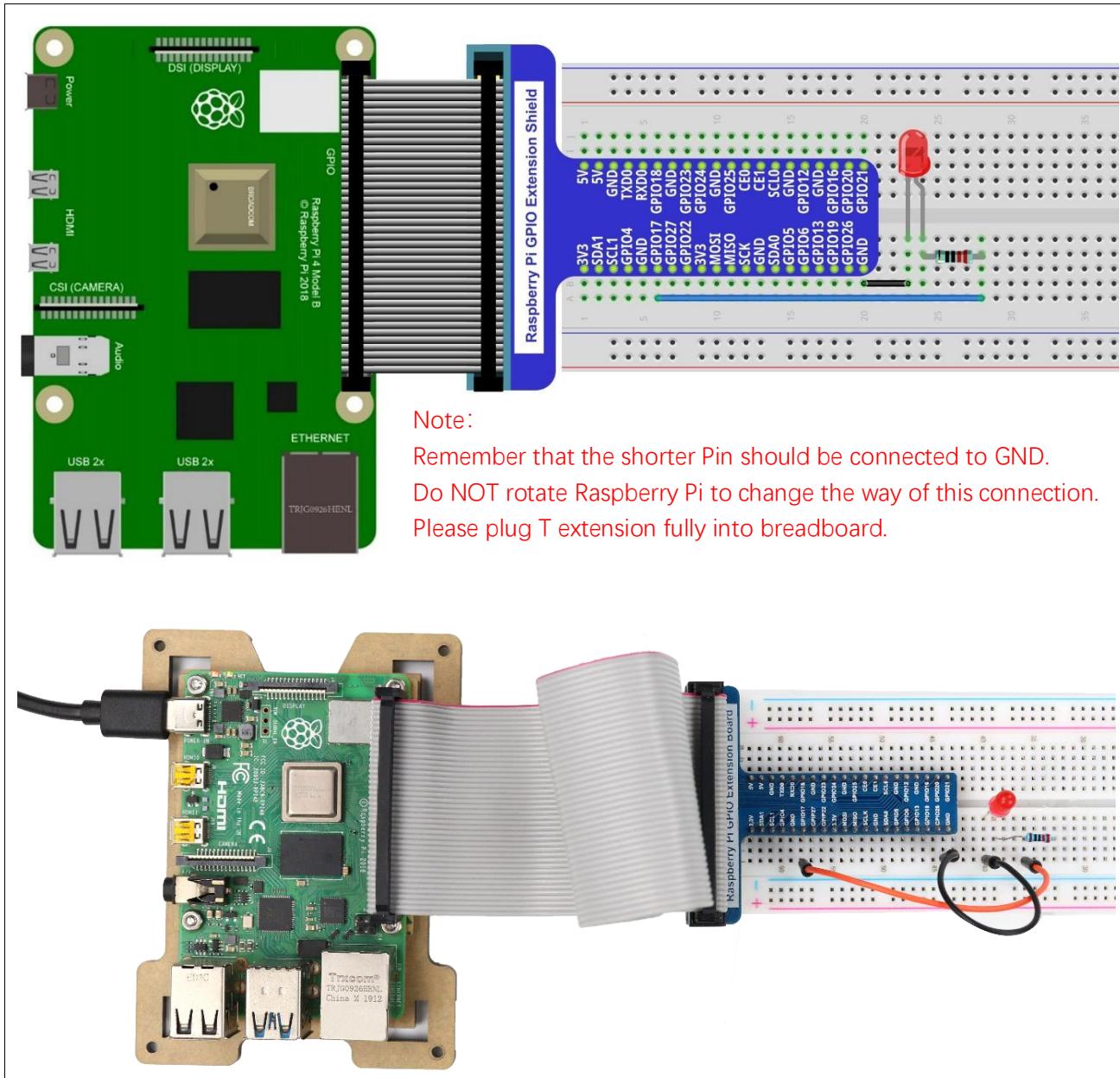
First, disconnect your RPi from the GPIO Extension Shield. Then build the circuit according to the circuit and hardware diagrams. After the circuit is built and verified correct, connect the RPi to GPIO Extension Shield.
CAUTION: Avoid any possible short circuits (especially connecting 5V or GND, 3.3V and GND)! **WARNING:** A short circuit can cause high current in your circuit, create excessive component heat and cause permanent damage to your RPi!

Schematic diagram



Hardware connection.

If you need any support, please contact us via: support@freenove.com



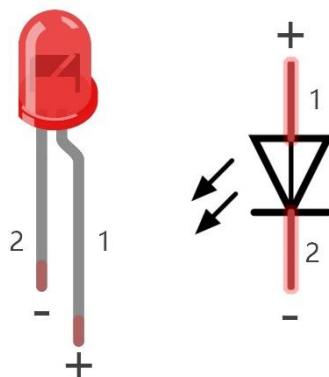
Future hardware connection diagrams will only show that part of breadboard and GPIO Extension Shield.

Component knowledge

LED

An LED is a type of diode. All diodes only work if current is flowing in the correct direction and have two Poles. An LED will only work (light up) if the longer pin (+) of LED is connected to the positive output from a power source and the shorter pin is connected to the negative (-) negative output also referred to as Ground (GND). This type of component is known as "Polar" (think One-Way Street).

All common 2 lead diodes are the same in this respect. Diodes work only if the voltage of its positive electrode is higher than its negative electrode and there is a narrow range of operating voltage for most all common diodes of 1.9 and 3.4V. If you use much more than 3.3V the LED will be damaged and burn out.



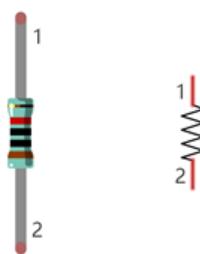
LED	Voltage	Maximum current	Recommended current
Red	1.9 - 2.2V	20mA	10mA
Green	2.9 - 3.4V	10mA	5mA
Blue	2.9 - 3.4V	10mA	5mA
Volt ampere characteristics conform to diode			

Note: LEDs cannot be directly connected to a power supply, which usually ends in a damaged component. A resistor with a specified resistance value must be connected in series to the LED you plan to use.

Resistor

Resistors use Ohms (Ω) as the unit of measurement of their resistance (R). $1M\Omega=1000k\Omega$, $1k\Omega=1000\Omega$.

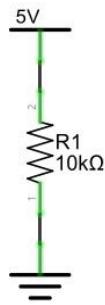
A resistor is a passive electrical component that limits or regulates the flow of current in an electronic circuit. On the left, we see a physical representation of a resistor, and the right is the symbol used to represent the presence of a resistor in a circuit diagram or schematic.



The bands of color on a resistor is a shorthand code used to identify its resistance value. For more details of resistor color codes, please refer to the card in the kit package.

With a fixed voltage, there will be less current output with greater resistance added to the circuit. The relationship between Current, Voltage and Resistance can be expressed by this formula: $I=V/R$ known as Ohm's Law where I = Current, V = Voltage and R = Resistance. Knowing the values of any two of these allows you to solve the value of the third.

In the following diagram, the current through R1 is: $I=U/R=5V/10k\Omega=0.0005A=0.5mA$.

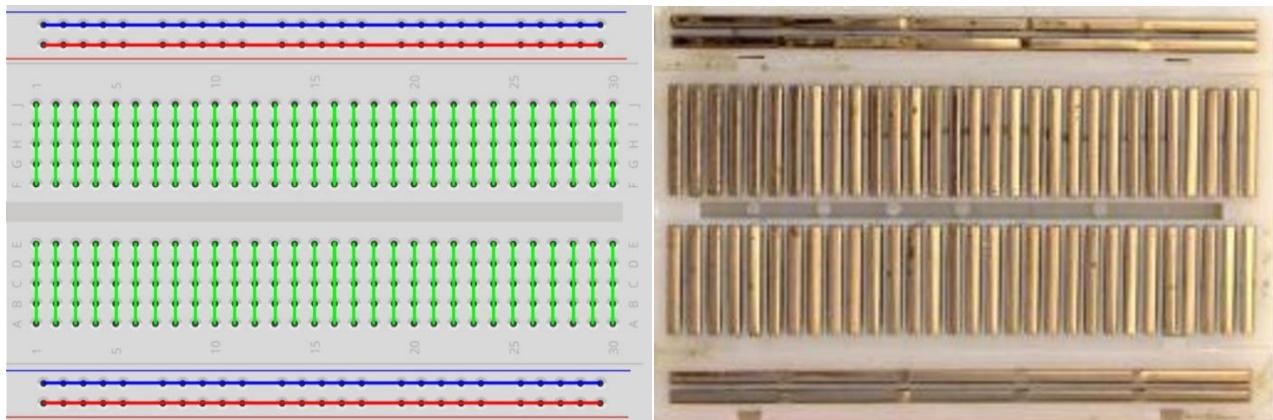


WARNING: Never connect the two poles of a power supply with anything of low resistance value (i.e. a metal object or bare wire) this is a Short and results in high current that may damage the power supply and electronic components.

Note: Unlike LEDs and Diodes, Resistors have no poles and are non-polar (it does not matter which direction you insert them into a circuit, it will work the same)

Breadboard

Here we have a small breadboard as an example of how the rows of holes (sockets) are electrically attached. The left picture shows the ways the pins have shared electrical connection and the right picture shows the actual internal metal, which connects these rows electrically.



Code

According to the circuit, when the GPIO17 of RPi output level is high, the LED turns ON. Conversely, when the GPIO17 RPi output level is low, the LED turns OFF. Therefore, we can let GPIO17 cycle output high and output low level to make the LED blink. We will use both C code and Python code to achieve the target.

C Code 1.1.1 Blink

First, enter this command into the Terminal one line at a time. Then observe the results it brings on your project, and learn about the code in detail.

If you want to execute it with editor, please refer to section [Code Editor](#) to configure.

If you have any concerns, please contact us via: support@freenove.com

It is recommended that to execute the code via command line.

1. Update wiring pi.

```
wget https://project-downloads.drogon.net/wiringpi-latest.deb
sudo dpkg -i wiringpi-latest.deb
```

2. Use cd command to enter 01.1.1_Blink directory of C code.

```
cd ~/Freenove_Kit/Code/C_Code/01.1.1_Blink
```

3. Use the following command to compile the code "Blink.c" and generate executable file "Blink".

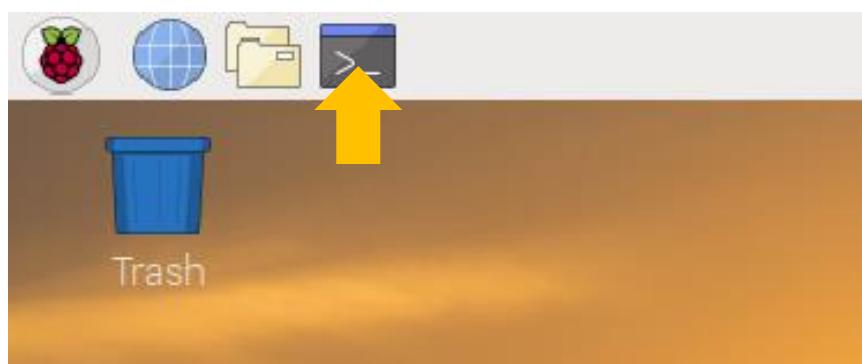
"I" of "lwiringPi" is low case of "L".

```
gcc Blink.c -o Blink -lwiringPi
```

4. Then run the generated file "blink".

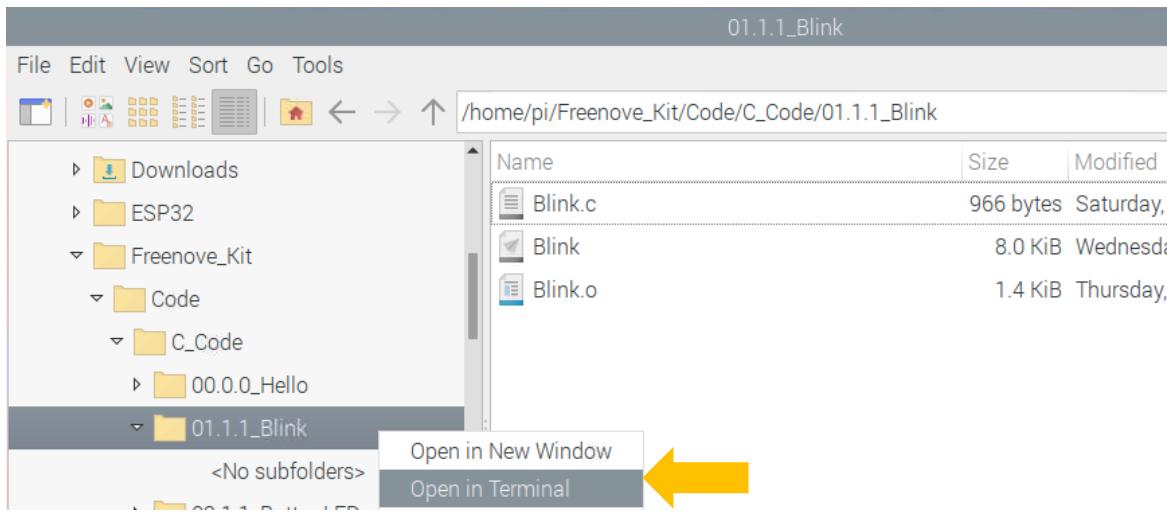
```
sudo ./Blink
```

Now your LED should start blinking! CONGRATULATIONS! You have successfully completed your first RPi circuit!



```
pi@raspberrypi:~ $ cd ~/Freenove_Kit/Code/C_Code/01.1.1_Blink/
pi@raspberrypi:~/Freenove_Kit/Code/C_Code/01.1.1_Blink $ gcc Blink.c -o Blink -lwiringPi
pi@raspberrypi:~/Freenove_Kit/Code/C_Code/01.1.1_Blink $ sudo ./Blink
Program is starting ...
Using pin0
led turned on >>>
led turned off <<<
```

You can also use the file browser. In the folder tree on the left, right-click the folder you want to enter, and click "Open in Terminal".



You can press "Ctrl+C" to end the program. The following is the program code:

```

1 #include <wiringPi.h>
2 #include <stdio.h>
3
4 #define ledPin    0 //define the led pin number
5
6 void main(void)
7 {
8     printf("Program is starting ... \n");
9
10    wiringPiSetup(); //Initialize wiringPi.
11
12    pinMode(ledPin, OUTPUT); //Set the pin mode
13    printf("Using pin%d\n", %ledPin); //Output information on terminal
14    while(1{
15        digitalWrite(ledPin, HIGH); //Make GPIO output HIGH level
16        printf("led turned on >>>\n"); //Output information on terminal
17        delay(1000); //Wait for 1 second
18        digitalWrite(ledPin, LOW); //Make GPIO output LOW level
19        printf("led turned off <<<\n"); //Output information on terminal
20        delay(1000); //Wait for 1 second
21    }
22 }
```

In the code above, the configuration function for GPIO is shown below as:

```
void pinMode(int pin, int mode);
```

This sets the mode of a pin to either INPUT, OUTPUT, PWM_OUTPUT or GPIO_CLOCK. Note that only wiringPi pin 1 (BCM_GPIO 18) supports PWM output and only wiringPi pin 7 (BCM_GPIO 4) supports CLOCK output modes.

This function has no effect when in Sys mode. If you need to change the pin mode, then you can do it with the gpio program in a script before you start your program

```
void digitalWrite (int pin, int value);
```

Writes the value HIGH or LOW (1 or 0) to the given pin, which must have been previously set as an output.

For more related wiringpi functions, please refer to <http://wiringpi.com/reference/>

GPIO connected to ledPin in the circuit is GPIO17 and GPIO17 is defined as 0 in the wiringPi numbering. So ledPin should be defined as 0 pin. You can refer to the corresponding table in Chapter 0.

```
#define ledPin 0 //define the led pin number
```

GPIO Numbering Relationship

WingPi	BCM(Extension)	Physical		BCM(Extension)	WingPi
3.3V	3.3V	1	2	5V	5V
8	SDA1	3	4	5V	5V
9	SCL1	5	6	GND	GND
7	GPIO17	7	8	GPIO14/TXD0	15
GND	GND	9	10	GPIO15/RXD0	16
0	GPIO17	11	12	GPIO18	1
2	GPIO27	13	14	GND	GND
3	GPIO22	15	16	GPIO23	4
3.3V	3.3V	17	18	GPIO24	5
12	GPIO10/MOSI	19	20	GND	GND
13	GPIO9/MOSI	21	22	GPIO25	6
14	GPIO11/SCLK	23	24	GPIO8 /CEO	10
GND	GND	25	26	GPIO7 CE1	11
30	GPIO0/SDA0	27	28	GPIO1 /SCL0	31
21	GPIO5	29	30	GND	GND
22	GPIO6	31	32	GPIO12	26
23	GPIO13	33	34	GND	GND
24	GPIO19	35	36	GPIO16	27
25	GPIO26	37	38	GPIO20	28
GND	GND	39	40	GPIO21	29

In the main function main(), initialize wiringPi first.

```
wiringPiSetup(); //Initialize wiringPi.
```

After the wiringPi is initialized successfully, you can set the ledPin to output mode and then enter the while loop, which is an endless loop (a while loop). That is, the program will always be executed in this cycle, unless it is ended because of external factors. In this loop, use digitalWrite (ledPin, HIGH) to make ledPin output high level, then LED turns ON. After a period of time delay, use digitalWrite(ledPin, LOW) to make ledPin output low

level, then LED turns OFF, which is followed by a delay. Repeat the loop, then LED will start blinking.

```
pinMode(ledPin, OUTPUT); //Set the pin mode
printf("Using pin%d\n", ledPin); //Output information on terminal
while(1) {
    digitalWrite(ledPin, HIGH); //Make GPIO output HIGH level
    printf("led turned on >>>\n"); //Output information on terminal
    delay(1000); //Wait for 1 second
    digitalWrite(ledPin, LOW); //Make GPIO output LOW level
    printf("led turned off <<<\n"); //Output information on terminal
    delay(1000); //Wait for 1 second
}
```

Python Code 1.1.1 Blink

Now, we will use Python language to make a LED blink.

First, observe the project result, and then learn about the code in detail.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 01.1.1_Blink directory of Python code.

```
cd ~/Freenove_Kit/Code/Python_Code/01.1.1_Blink
```

2. Use python command to execute python code blink.py.

```
python Blink.py
```

The LED starts blinking.

```
pi@raspberrypi:~ $ cd Freenove_Kit/Code/Python_Code/01.1.1_Blink/
pi@raspberrypi:~/Freenove_Kit/Code/Python_Code/01.1.1_Blink $ python Blink.py
Program is starting ...

using pin11
led turned on >>>
led turned off <<<
```

You can press “Ctrl+C” to end the program. The following is the program code:

```

1 import RPi.GPIO as GPIO
2 import time
3
4 ledPin = 11      # define ledPin
5
6 def setup():
7     GPIO.setmode(GPIO.BOARD)      # use PHYSICAL GPIO Numbering
8     GPIO.setup(ledPin, GPIO.OUT)   # set the ledPin to OUTPUT mode
9     GPIO.output(ledPin, GPIO.LOW)  # make ledPin output LOW level
10    print ('using pin%d' %ledPin)
11
12 def loop():
13     while True:
14         GPIO.output(ledPin, GPIO.HIGH) # make ledPin output HIGH level to turn on led
15         print ('led turned on >>>')      # print information on terminal
16         time.sleep(1)                  # Wait for 1 second
17         GPIO.output(ledPin, GPIO.LOW)   # make ledPin output LOW level to turn off led
18         print ('led turned off <<<')
19         time.sleep(1)                  # Wait for 1 second
20
21 def destroy():
22     GPIO.cleanup()                  # Release all GPIO
23
24 if __name__ == '__main__':      # Program entrance
```

```

25     print (' Program is starting ... \n')
26     setup()
27     try:
28         loop()
29     except KeyboardInterrupt: # Press ctrl-c to end the program.
30         destroy()

```

About RPi.GPIO:

RPi.GPIO

This is a Python module to control the GPIO on a Raspberry Pi. It includes basic output function and input function of GPIO, and functions used to generate PWM.

GPIO.setmode(mode)

Sets the mode for pin serial number of GPIO.

mode=GPIO.BCM, which represents the GPIO pin serial number based on physical location of RPi.
mode=GPIO.BOARD, which represents the pin serial number based on CPU of BCM chip.

GPIO.setup(pin, mode)

Sets pin to input mode or output mode, "pin" for the GPIO pin, "mode" for INPUT or OUTPUT.

GPIO.output(pin, mode)

Sets pin to output mode, "pin" for the GPIO pin, "mode" for HIGH (high level) or LOW (low level).

For more functions related to RPi.GPIO, please refer to:

<https://sourceforge.net/p/raspberry-gpio-python/wiki/Examples/>

"import time" time is a module of python.

<https://docs.python.org/2/library/time.html?highlight=time%20time#module-time>

In subfunction setup(), GPIO.setmode (GPIO.BCM) is used to set the serial number for GPIO based on physical location of the pin. GPIO17 uses pin 11 of the board, so define ledPin as 11 and set ledPin to output mode (output low level).

```

ledPin = 11      # define ledPin

def setup():
    GPIO.setmode(GPIO.BCM)      # use PHYSICAL GPIO Numbering
    GPIO.setup(ledPin, GPIO.OUT) # set the ledPin to OUTPUT mode
    GPIO.output(ledPin, GPIO.LOW) # make ledPin output LOW level
    print (' using pin%d' %ledPin)

```

GPIO Numbering Relationship

WingPi	BCM(Extension)	Physical		BCM(Extension)	WingPi
3.3V	3.3V	1	2	5V	5V
8	SDA1	3	4	5V	5V
9	SCL1	5	6	GND	GND
7	GPIO17	7	8	GPIO14/TXDO	15
GND	GND	9	10	GPIO15/RXDO	16
0	GPIO17	11	12	GPIO18	1
2	GPIO27	13	14	GND	GND
3	GPIO22	15	16	GPIO23	4
3.3V	3.3V	17	18	GPIO24	5
12	GPIO10/MOSI	19	20	GND	GND
13	GPIO9/MOIS	21	22	GPIO25	6
14	GPIO11/SCLK	23	24	GPIO8 /CEO	10
GND	GND	25	26	GPIO7 CE1	11
30	GPIO0/SDA0	27	28	GPIO1 /SCLO	31
21	GPIO5	29	30	GND	GND
22	GPIO6	31	32	GPIO12	26
23	GPIO13	33	34	GND	GND
24	GPIO19	35	36	GPIO16	27
25	GPIO26	37	38	GPIO20	28
GND	GND	39	40	GPIO21	29

In loop(), there is a while loop, which is an endless loop (a while loop). That is, the program will always be executed in this loop, unless it is ended because of external factors. In this loop, set ledPin output high level, then the LED turns ON. After a period of time delay, set ledPin output low level, then the LED turns OFF, which is followed by a delay. Repeat the loop, then LED will start blinking.

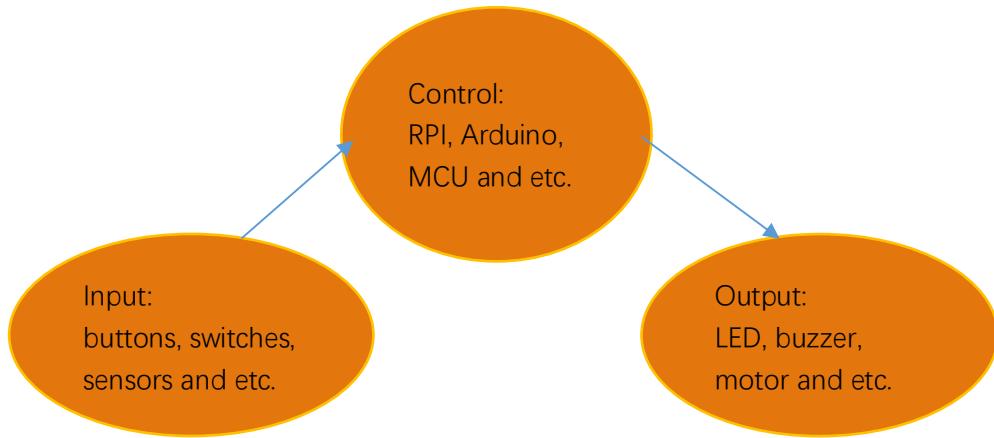
```
def loop():
    while True:
        GPIO.output(ledPin, GPIO.HIGH) # make ledPin output HIGH level to turn on led
        print ('led turned on >>>') # print information on terminal
        time.sleep(1) # Wait for 1 second
        GPIO.output(ledPin, GPIO.LOW) # make ledPin output LOW level to turn off led
        print ('led turned off <<<')
        time.sleep(1) # Wait for 1 second
```

Finally, when the program is terminated, subfunction (a function within the file) will be executed, the LED will be turned off and then the IO port will be released. If you close the program Terminal directly, the program will also be terminated but the finish() function will not be executed. Therefore, the GPIO resources will not be released which may cause a warning message to appear the next time you use GPIO. Therefore, do not get into the habit of closing Terminal directly.

```
def finish():
    GPIO.cleanup() # Release all GPIO
```

Chapter 2 Buttons & LEDs

Usually, there are three essential parts in a complete automatic control device: INPUT, OUTPUT, and CONTROL. In last section, the LED module was the output part and RPI was the control part. In practical applications, we not only make LEDs flash, but also make a device sense the surrounding environment, receive instructions and then take the appropriate action such as turn on LEDs, make a buzzer beep and so on.



Next, we will build a simple control system to control an LED through a push button switch.

Project 2.1 Push Button Switch & LED

In the project, we will control the LED state through a Push Button Switch. When the button is pressed, our LED will turn ON, and when it is released, the LED will turn OFF. This describes a Momentary Switch.

Component List

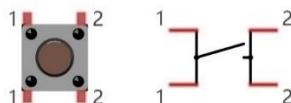
Raspberry Pi (with 40 GPIO) x1 GPIO Extension Board & Wire x1 Breadboard x1	LED x1 	Resistor 220Ω x1 	Resistor 10kΩ x2 	Push Button Switch x1 
Jumper Wire 				

Please Note: In the code “button” represents switch action.

Component knowledge

Push Button Switch

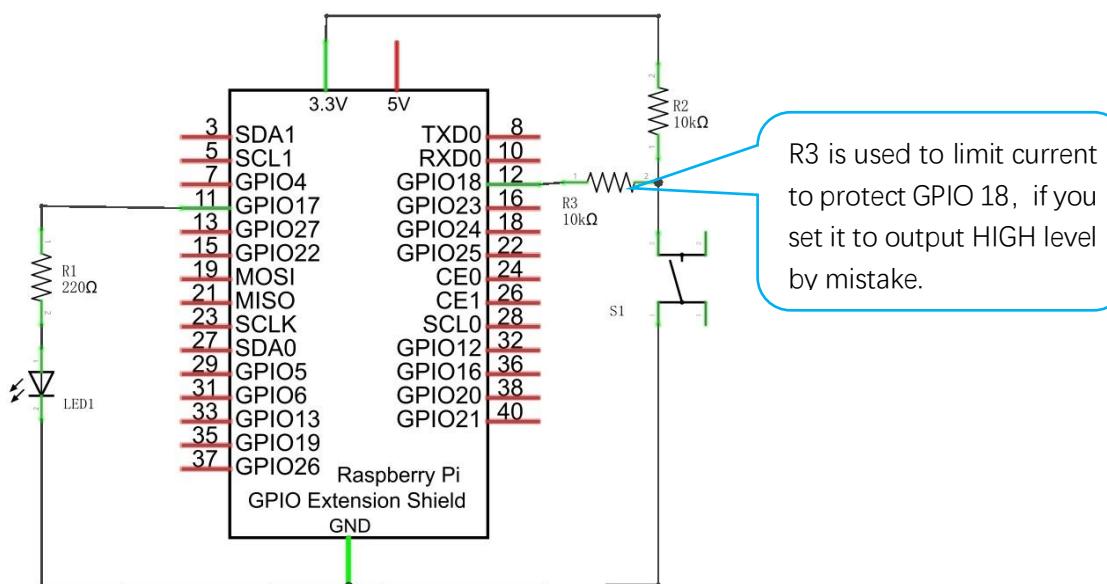
This type of Push Button Switch has 4 pins (2 Pole Switch). Two pins on the left are connected, and both left and right sides are the same per the illustration:



When the button on the switch is pressed, the circuit is completed (your project is Powered ON).

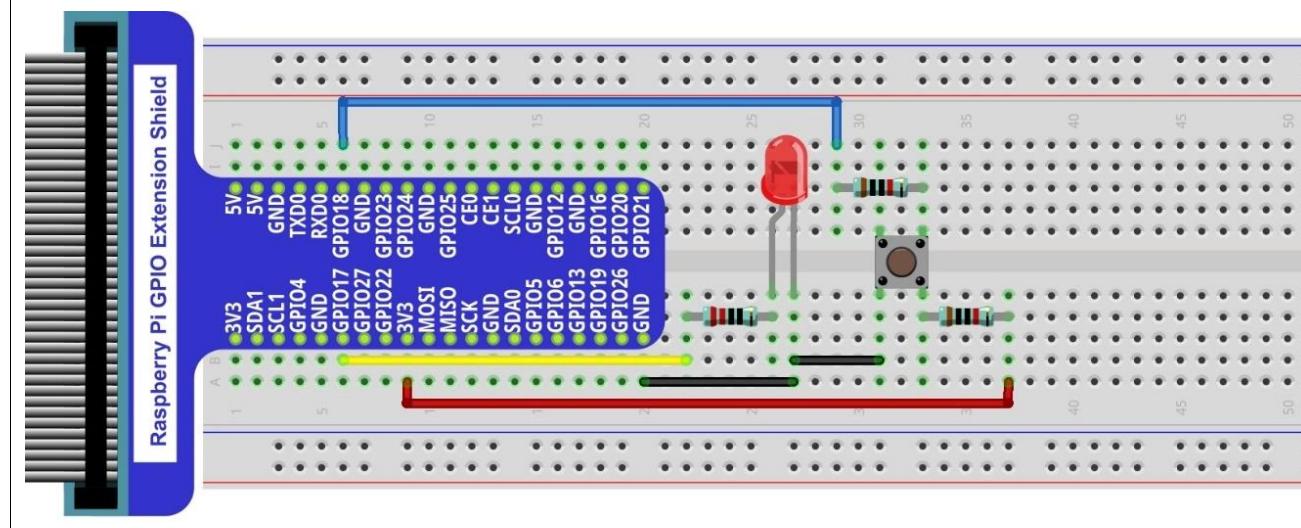
Circuit

Schematic diagram



Hardware connection. If you need any support, please feel free to contact us via:

support@freenove.com



There are two kinds of push button switch in this kit.

The smaller push button switches are contained in a plastic bag.

Code

This project is designed for learning how to use Push Button Switch to control an LED. We first need to read the state of switch, and then determine whether to turn the LED ON in accordance to the state of the switch.

C Code 2.1.1 ButtonLED

First, observe the project result, then learn about the code in detail.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 02.1.1_ButtonLED directory of C code.

```
cd ~/Freenove_Kit/Code/C_Code/02.1.1_ButtonLED
```

2. Use the following command to compile the code "ButtonLED.c" and generate executable file "ButtonLED"

```
gcc ButtonLED.c -o ButtonLED -lwiringPi
```

3. Then run the generated file "ButtonLED".

```
sudo ./ButtonLED
```

Later, the terminal window continues to print out the characters "led off...". Press the button, then LED is turned on and then terminal window prints out the "led on...". Release the button, then LED is turned off and then terminal window prints out the "led off...". You can press "Ctrl+C" to terminate the program.

The following is the program code:

```

1 #include <wiringPi.h>
2 #include <stdio.h>
3
4 #define ledPin    0 //define the ledPin
5 #define buttonPin 1 //define the buttonPin
6
7 void main(void)
8 {
9     printf("Program is starting ... \n");
10
11     wiringPiSetup(); //Initialize wiringPi.
12
13     pinMode(ledPin, OUTPUT); //Set ledPin to output
14     pinMode(buttonPin, INPUT); //Set buttonPin to input
15
16     pullUpDnControl(buttonPin, PUD_UP); //pull up to HIGH level
17     while(1) {
18         if(digitalRead(buttonPin) == LOW){ //button is pressed
19             digitalWrite(ledPin, HIGH); //Make GPIO output HIGH level
20             printf("Button is pressed, led turned on >>>\n"); //Output information on
21             terminal
22         }
23         else { //button is released
24             digitalWrite(ledPin, LOW); //Make GPIO output LOW level
25             printf("Button is released, led turned off >>>\n"); //Output information on
26             terminal
27         }
28     }
29 }
```

```
24         digitalWrite(ledPin, LOW); //Make GPIO output LOW level
25         printf("Button is released, led turned off <<<\n"); //Output information on
26 terminal
27     }
28 }
29 }
```

In the circuit connection, LED and Button are connected with GPIO17 and GPIO18 respectively, which correspond to 0 and 1 respectively in wiringPI. So define ledPin and buttonPin as 0 and 1 respectively.

```
#define ledPin 0 //define the ledPin
#define buttonPin 1 //define the buttonPin
```

In the while loop of main function, use digitalRead(buttonPin) to determine the state of Button. When the button is pressed, the function returns low level, the result of "if" is true, and then turn on LED. Or, turn off LED.

```
if(digitalRead(buttonPin) == LOW){ //button has pressed down
    digitalWrite(ledPin, HIGH); //led on
    printf("led on... \n");
}
else { //button has released
    digitalWrite(ledPin, LOW); //led off
    printf("...led off\n");
}
```

Reference:

```
int digitalRead (int pin);
```

This function returns the value read at the given pin. It will be "**HIGH**" or "**LOW**"(1 or 0) depending on the logic level at the pin.



Python Code 2.1.1 ButtonLED

First, observe the project result, then learn about the code in detail. Remember in code “button” = switch function

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 02.1.1_ButtonLED directory of Python code.

```
cd ~/Freenove_Kit/Code/Python_Code/02.1.1_ButtonLED
```

2. Use Python command to execute btnLED.py.

```
python ButtonLED.py
```

Then the Terminal window continues to show the characters “led off…”, press the switch button and the LED turns ON and then Terminal window shows “led on…”. Release the button, then LED turns OFF and then the terminal window text “led off…” appears. You can press “Ctrl+C” at any time to terminate the program.

The following is the program code:

```

1 import RPi.GPIO as GPIO
2
3 ledPin = 11      # define ledPin
4 buttonPin = 12    # define buttonPin
5
6 def setup():
7
8     GPIO.setmode(GPIO.BCM)      # use PHYSICAL GPIO Numbering
9     GPIO.setup(ledPin, GPIO.OUT)  # set ledPin to OUTPUT mode
10    GPIO.setup(buttonPin, GPIO.IN, pull_up_down=GPIO.PUD_UP)   # set buttonPin to PULL UP
11    INPUT mode
12
13 def loop():
14     while True:
15         if GPIO.input(buttonPin)==GPIO.LOW: # if button is pressed
16             GPIO.output(ledPin,GPIO.HIGH)  # turn on led
17             print (' led turned on >>>')  # print information on terminal
18         else : # if button is released
19             GPIO.output(ledPin,GPIO.LOW) # turn off led
20             print (' led turned off <<<')
21
22 def destroy():
23     GPIO.cleanup()                  # Release GPIO resource
24
25 if __name__ == '__main__':      # Program entrance
26     print ('Program is starting... ')
27     setup()
28     try:
29         loop()
30     except KeyboardInterrupt: # Press ctrl-c to end the program.
31         destroy()
```

In subfunction setup (), GPIO.setmode (GPIO.BOARD) is used to set the serial number of the GPIO, which is based on physical location of the pin. Therefore, GPIO17 and GPIO18 correspond to pin11 and pin12 respectively in the circuit. Then set ledPin to output mode, buttonPin to input mode with a pull resistor.

```
ledPin = 11      # define ledPin
buttonPin = 12    # define buttonPin

def setup():
    GPIO.setmode(GPIO.BOARD)      # use PHYSICAL GPIO Numbering
    GPIO.setup(ledPin, GPIO.OUT)   # set ledPin to OUTPUT mode
    GPIO.setup(buttonPin, GPIO.IN, pull_up_down=GPIO.PUD_UP)  # set buttonPin to PULL UP
    INPUT mode
```

The loop continues endlessly to judge whether the key is pressed. When the button is pressed, the GPIO.input(buttonPin) will return low level, then the result of "if" is true, ledPin outputs high level, LED is turned on. Otherwise, LED will be turned off.

```
def loop():
    while True:
        if GPIO.input(buttonPin)==GPIO.LOW: # if button is pressed
            GPIO.output(ledPin,GPIO.HIGH)  # turn on led
            print ('led turned on >>>') # print information on terminal
        else : # if button is released
            GPIO.output(ledPin,GPIO.LOW) # turn off led
            print ('led turned off <<<')
```

Execute the function destroy (), close the program and release the occupied GPIO pins.

About function GPIO.input ():

GPIO.input()

This function returns the value read at the given pin. It will be “**HIGH**” or “**LOW**”(1 or 0) depending on the logic level at the pin.



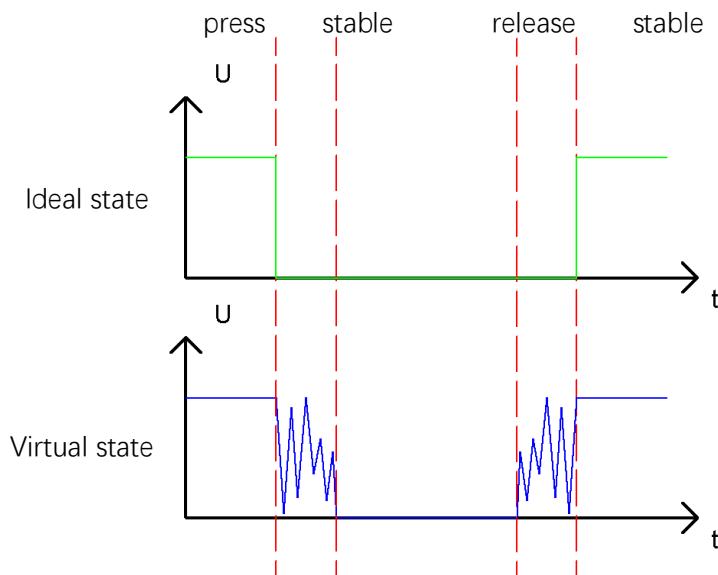
Project 2.2 MINI Table Lamp

We will also use a Push Button Switch, LED and RPi to make a MINI Table Lamp but this will function differently: Press the button, the LED will turn ON, and pressing the button again, the LED turns OFF. The ON switch action is no longer momentary (like a door bell) but remains ON without needing to continually press on the Button Switch.

First, let us learn something about the push button switch.

Debounce a Push Button Switch

When a Momentary Push Button Switch is pressed, it will not change from one state to another state immediately. Due to tiny mechanical vibrations, there will be a short period of continuous buffeting before it stabilizes in a new state too fast for Humans to detect but not for computer microcontrollers. The same is true when the push button switch is released. This unwanted phenomenon is known as “bounce”.



Therefore, if we can directly detect the state of the Push Button Switch, there are multiple pressing and releasing actions in one pressing cycle. This buffeting will mislead the high-speed operation of the microcontroller to cause many false decisions. Therefore, we need to eliminate the impact of buffeting. Our solution: to judge the state of the button multiple times. Only when the button state is stable (consistent) over a period of time, can it indicate that the button is actually in the ON state (being pressed).

This project needs the same components and circuits as we used in the previous section.

Code

In this project, we still detect the state of Push Button Switch to control an LED. Here we need to define a variable to define the state of LED. When the button switch is pressed once, the state of LED will be changed once. This will allow the circuit to act as a virtual table lamp.

C Code 2.2.1 Tablelamp

First, observe the project result, and then learn about the code in detail.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 02.2.1_Tablelamp directory of C code.

```
cd ~/Freenove_Kit/Code/C_Code/02.2.1_Tablelamp
```

2. Use the following command to compile “Tablelamp.c” and generate executable file “Tablelamp”.

```
gcc Tablelamp.c -o Tablelamp -lwiringPi
```

3. Tablelamp: Then run the generated file “Tablelamp”.

```
sudo ./Tablelamp
```

When the program is executed, press the Button Switch once, the LED turns ON. Pressing the Button Switch again turns the LED OFF.

```

1 #include <wiringPi.h>
2 #include <stdio.h>
3
4 #define ledPin    0 //define the ledPin
5 #define buttonPin 1 //define the buttonPin
6 int ledState=LOW; //store the State of led
7 int buttonState=HIGH; //store the State of button
8 int lastbuttonState=HIGH;//store the lastState of button
9 long lastChangeTime; //store the change time of button state
10 long captureTime=50; //set the stable time for button state
11 int reading;
12 int main(void)
13 {
14     printf("Program is starting...\n");
15
16     wiringPiSetup(); //Initialize wiringPi.
17
18     pinMode(ledPin, OUTPUT); Set ledPin to output
19     pinMode(buttonPin, INPUT); Set buttonPin to input
20
21     pullUpDnControl(buttonPin, PUD_UP); //pull up to high level
22     while(1) {
23         reading = digitalRead(buttonPin); //read the current state of button
24         if( reading != lastbuttonState){ //if the button state has changed, record the time
25             point
26             lastChangeTime = millis();
27         }

```





```

28     //if changing-state of the button last beyond the time we set, we consider that
29     //the current button state is an effective change rather than a buffeting
30     if(millis() - lastChangeTime > captureTime){
31         //if button state is changed, update the data.
32         if(reading != buttonState){
33             buttonState = reading;
34             //if the state is low, it means the action is pressing
35             if(buttonState == LOW){
36                 printf("Button is pressed!\n");
37                 ledState = !ledState; //Reverse the LED state
38                 if(ledState){
39                     printf("turn on LED ... \n");
40                 }
41                 else {
42                     printf("turn off LED ... \n");
43                 }
44             }
45             //if the state is high, it means the action is releasing
46             else {
47                 printf("Button is released!\n");
48             }
49         }
50     }
51     digitalWrite(ledPin, ledState);
52     lastbuttonState = reading;
53 }
54
55     return 0;
56 }
```

This code focuses on eliminating the buffeting (bounce) of the button switch. We define several variables to define the state of LED and button switch. Then read the button switch state constantly in while () to determine whether the state has changed. If it has, then this time point is recorded.

```

reading = digitalRead(buttonPin); //read the current state of button
if( reading != lastbuttonState){
    lastChangeTime = millis();
}
```

millis()

This returns a number representing the number of milliseconds since your program called one of the wiringPiSetup functions. It returns to an unsigned 32-bit number value after 49 days because it “wraps” around and restarts to value 0.

Then according to the recorded time point, evaluate the duration of the button switch state change. If the duration exceeds captureTime (buffeting time) we have set, it indicates that the state of the button switch has changed. During that time, the while () is still detecting the state of the button switch, so if there is a change, the time point of change will be updated. Then the duration will be evaluated again until the duration is determined to be a stable state because it exceeds the time value we set.

```
if(millis() - lastChangeTime > captureTime) {  
    //if button state is changed, update the data.  
    if(reading != buttonState) {  
        buttonState = reading;
```

Finally, we need to judge the state of Button Switch. If it is low level, the changing state indicates that the button Switch has been pressed, if the state is high level, then the button has been released. Here, we change the status of the LED variable, and then update the state of the LED.

```
if(buttonState == LOW) {  
    printf("Button is pressed!\n");  
    ledState = !ledState; //Reverse the LED state  
    if(ledState){  
        printf("turn on LED ... \n");  
    }  
    else {  
        printf("turn off LED ... \n");  
    }  
}  
//if the state is high, it means the action is releasing  
else {  
    printf("Button is released!\n");  
}
```



Python Code 2.2.1 Tablelamp

First, observe the project result, and then learn about the code in detail.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 02.2.1_Tablelamp directory of Python code

cd ~/Freenove_Kit/Code/Python_Code/02.2.1_Tablelamp

2. Use python command to execute python code "Tablelamp.py".

python Tablelamp.py

When the program is executed, pressing the Button Switch once turns the LED ON. Pressing the Button Switch again turns the LED OFF.

```
1 import RPi.GPIO as GPIO
2
3 ledPin = 11      # define ledPin
4 buttonPin = 12    # define buttonPin
5 ledState = False
6
7 def setup():
8     GPIO.setmode(GPIO.BOARD)      # use PHYSICAL GPIO Numbering
9     GPIO.setup(ledPin, GPIO.OUT)    # set ledPin to OUTPUT mode
10    GPIO.setup(buttonPin, GPIO.IN, pull_up_down=GPIO.PUD_UP)    # set buttonPin to PULL UP
11    INPUT mode
12
13 def buttonEvent(channel): # When button is pressed, this function will be executed
14     global ledState
15     print ('buttonEvent GPIO%d' %channel)
16     ledState = not ledState
17     if ledState :
18         print ('Led turned on >>>')
19     else :
20         print ('Led turned off <<<')
21     GPIO.output(ledPin, ledState)
22
23 def loop():
24     #Button detect
25     GPIO.add_event_detect(buttonPin,GPIO.FALLING,callback = buttonEvent,bouncetime=300)
26     while True:
27         pass
28
29 def destroy():
30     GPIO.cleanup()                  # Release GPIO resource
31
32 if __name__ == '__main__':      # Program entrance
33     print ('Program is starting...')
34     setup()
35     try:
```

```
36     loop()
37 except KeyboardInterrupt: # Press ctrl-c to end the program.
38     destroy()
```

RPi.GPIO provides us with a simple but effective function to eliminate “jitter”, that is GPIO.add_event_detect(). It uses the callback function. Once it detects that the buttonPin has a specified action FALLING, it executes a specified function buttonEvent(). In the function buttonEvent, each time the ledState is reversed, the state of the LED will be updated.

```
def buttonEvent(channel): # When button is pressed, this function will be executed
    global ledState
    print ('buttonEvent GPIO%d' %channel)
    ledState = not ledState
    if ledState :
        print ('Led turned on >>>')
    else :
        print ('Led turned off <<<')
    GPIO.output(ledPin, ledState)

def loop():
    #Button detect
    GPIO.add_event_detect(buttonPin, GPIO.FALLING, callback = buttonEvent, bouncetime=300)
    while True:
        pass
```

Of course, you can also use the same programming idea in C code above to achieve this target.

GPIO.add_event_detect(channel, GPIO.RISING, callback=my_callback, bouncetime=200)

This is an event detection function. The first parameter specifies the IO port to be detected. The second parameter specifies the action to be detected. The third parameter specifies a function name; the function will be executed when the specified action is detected. The fourth parameter is used to set the jitter time.



Chapter 3 LED Bar Graph

We have learned how to control one LED to blink. Next, we will learn how to control a number of LEDs.

Project 3.1 Flowing Water Light

In this project, we use a number of LEDs to make a flowing water light.

Component List

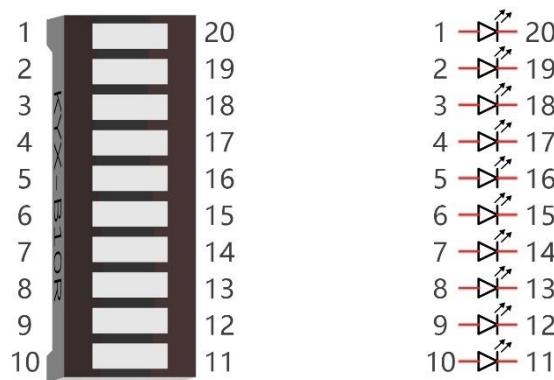
Raspberry Pi (with 40 GPIO) x1 GPIO Extension Board & Ribbon Cable x1 Breadboard x1	Bar Graph LED x1	Resistor 220Ω x10
Jumper Wire x 1 		

Component knowledge

Let us learn about the basic features of these components to use and understand them better.

Bar Graph LED

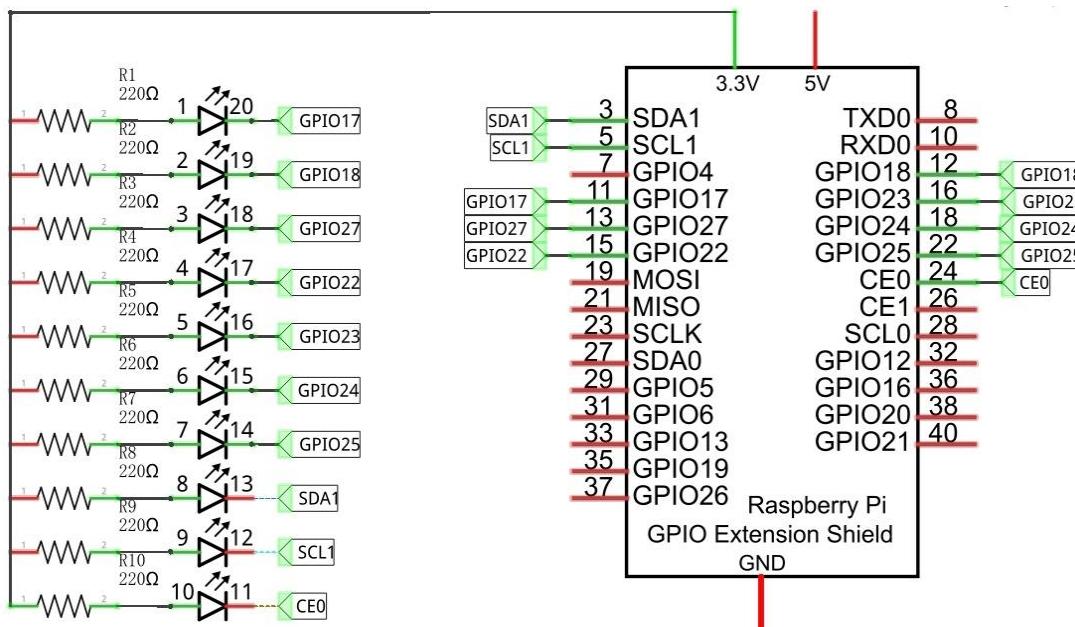
A Bar Graph LED has 10 LEDs integrated into one compact component. The two rows of pins at its bottom are paired to identify each LED like the single LED used earlier.



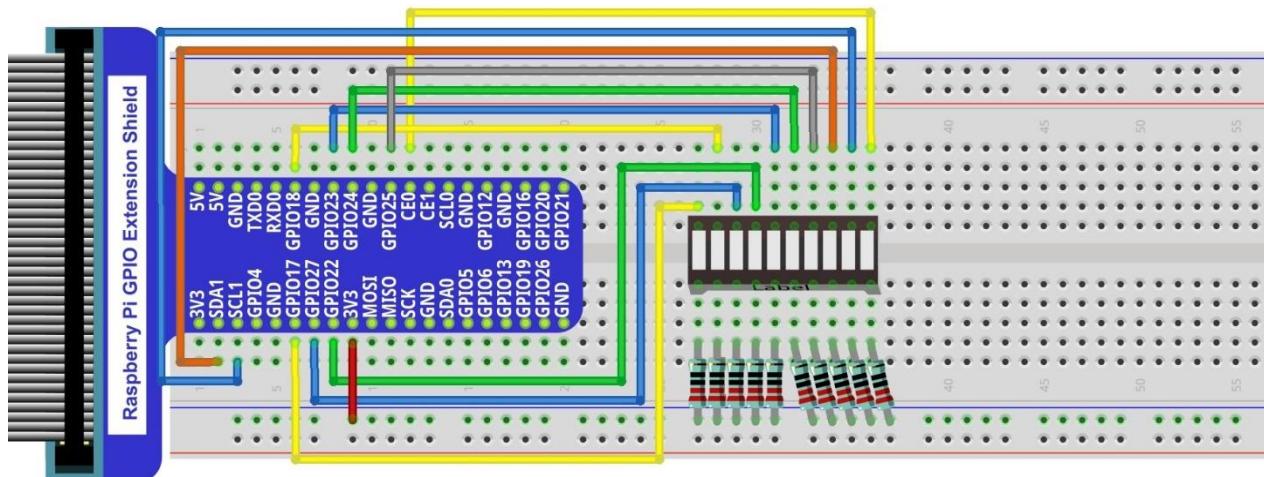
Circuit

A reference system of labels is used in the circuit diagram below. Pins with the same network label are connected together.

Schematic diagram



Hardware connection. If you need any support, please free to contact us via: support@freenove.com



In this circuit, the cathodes of the LEDs are connected to the GPIO, which is different from the previous circuit. The LEDs turn ON when the GPIO output is low level in the program.

Code

This project is designed to make a flowing water lamp, which are these actions: First turn LED #1 ON, then



turn it OFF. Then turn LED #2 ON, and then turn it OFF... and repeat the same to all 10 LEDs until the last LED is turns OFF. This process is repeated to achieve the “movements” of flowing water.

C Code 3.1.1 LightWater

First, observe the project result, and then learn about the code in detail.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 03.1.1_LightWater directory of C code.

```
cd ~/Freenove_Kit/Code/C_Code/03.1.1_LightWater
```

2. Use the following command to compile “LightWater.c” and generate executable file “LightWater”.

```
gcc LightWater.c -o LightWater -lwiringPi
```

3. Then run the generated file “LightWater”.

```
sudo ./LightWater
```

After the program is executed, you will see that Bar Graph LED starts with the flowing water pattern flashing from left to right and then back from right to left.

The following is the program code:

```

1  #include <wiringPi.h>
2  #include <stdio.h>
3
4  #define ledCounts 10
5  int pins[ledCounts] = {0, 1, 2, 3, 4, 5, 6, 8, 9, 10} ;
6
7  void main(void)
8  {
9      int i;
10     printf("Program is starting ... \n");
11
12     wiringPiSetup(); //Initialize wiringPi.
13
14     for(i=0;i<ledCounts;i++) {      //Set pinMode for all led pins to output
15         pinMode(pins[i], OUTPUT);
16     }
17     while(1) {
18         for(i=0;i<ledCounts;i++) {    // move led(on) from left to right
19             digitalWrite(pins[i], LOW);
20             delay(100);
21             digitalWrite(pins[i], HIGH);
22         }
23         for(i=ledCounts-1;i>-1;i--) { // move led(on) from right to left
24             digitalWrite(pins[i], LOW);
25             delay(100);
26             digitalWrite(pins[i], HIGH);
27         }
28     }
29 }
```

In the program, configure the GPIO0-GPIO9 to output mode. Then, in the endless “while” loop of main function, use two “for” loop to realize flowing water light from left to right and from right to left.

```
while(1) {  
    for(i=0;i<ledCounts;i++) { // move led(on) from left to right  
        digitalWrite(pins[i],LOW);  
        delay(100);  
        digitalWrite(pins[i],HIGH);  
    }  
    for(i=ledCounts-1;i>-1;i--) { // move led(on) from right to left  
        digitalWrite(pins[i],LOW);  
        delay(100);  
        digitalWrite(pins[i],HIGH);  
    }  
}
```

Python Code 3.1.1 LightWater

First observe the project result, and then view the code.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 03.1.1_LightWater directory of Python code.

cd ~/Freenove_Kit/Code/Python_Code/03.1.1_LightWater

2. Use Python command to execute Python code “LightWater.py”.

python LightWater.py

After the program is executed, you will see that LED Bar Graph starts with the flowing water way to be turned on from left to right, and then from right to left.

The following is the program code:

```

1 import RPi.GPIO as GPIO
2 import time
3
4 ledPins = [11, 12, 13, 15, 16, 18, 22, 3, 5, 24]
5
6 def setup():
7     GPIO.setmode(GPIO.BOARD)      # use Physical GPIO Numbering
8     GPIO.setup(ledPins, GPIO.OUT)  # set all ledPins to OUTPUT mode
9     GPIO.output(ledPins, GPIO.HIGH) # make all ledPins output HIGH level, turn off all led
10
11 def loop():
12     while True:
13         for pin in ledPins:      # make led(on) move from left to right
14             GPIO.output(pin, GPIO.LOW)
15             time.sleep(0.1)
16             GPIO.output(pin, GPIO.HIGH)
17         for pin in ledPins[::-1]: # make led(on) move from right to left
18             GPIO.output(pin, GPIO.LOW)
19             time.sleep(0.1)
20             GPIO.output(pin, GPIO.HIGH)
21
22 def destroy():
23     GPIO.cleanup()           # Release all GPIO
24
25 if __name__ == '__main__':    # Program entrance
26     print ('Program is starting...')
27     setup()
28     try:
29         loop()
30     except KeyboardInterrupt: # Press ctrl-c to end the program.
31         destroy()
```

In the program, first define 10 pins connected to LED, and set them to output mode in subfunction setup().

Then in the loop() function, use two “for” loops to realize flowing water light from right to left and from left to right. ledPins[::-1] is used to get elements of ledPins in reverse order.

```
def loop():
    while True:
        for pin in ledPins:      #make led on from left to right
            GPIO.output(pin, GPIO.LOW)
            time.sleep(0.1)
            GPIO.output(pin, GPIO.HIGH)
        for pin in ledPins[::-1]:      #make led on from right to left
            GPIO.output(pin, GPIO.LOW)
            time.sleep(0.1)
            GPIO.output(pin, GPIO.HIGH)
```

Chapter 4 Analog & PWM

In previous chapters, we learned that a Push Button Switch has two states: Pressed (ON) and Released (OFF), and an LED has a Light ON and OFF state. Is there a middle or intermediated state? We will next learn how to create an intermediate output state to achieve a partially bright (dim) LED.

First, let us learn how to control the brightness of an LED.

Project 4.1 Breathing LED

We describe this project as a Breathing Light. This means that an LED that is OFF will then turn ON gradually and then gradually turn OFF like "breathing". Okay, so how do we control the brightness of an LED to create a Breathing Light? We will use PWM to achieve this goal.

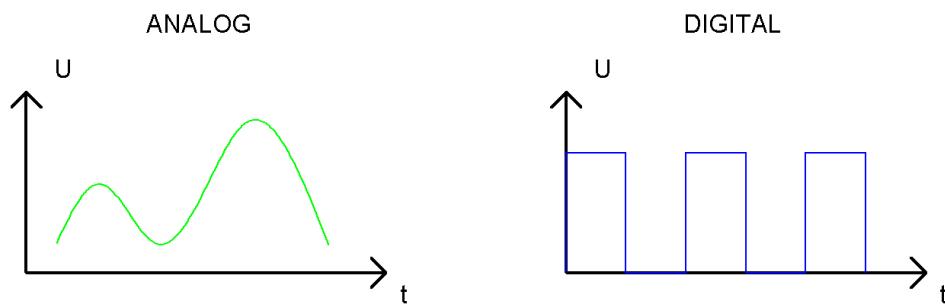
Component List

Raspberry Pi (with 40 GPIO) x1 GPIO Extension Board & Ribbon Cable x1 Breadboard x1	LED x1	Resistor 220Ω x1
Jumper Wire 		

Component Knowledge

Analog & Digital

An Analog Signal is a continuous signal in both time and value. On the contrary, a Digital Signal or discrete-time signal is a time series consisting of a sequence of quantities. Most signals in life are analog signals. A familiar example of an Analog Signal would be how the temperature throughout the day is continuously changing and could not suddenly change instantaneously from 0°C to 10°C. However, Digital Signals can instantaneously change in value. This change is expressed in numbers as 1 and 0 (the basis of binary code). Their differences can more easily be seen when compared when graphed as below.



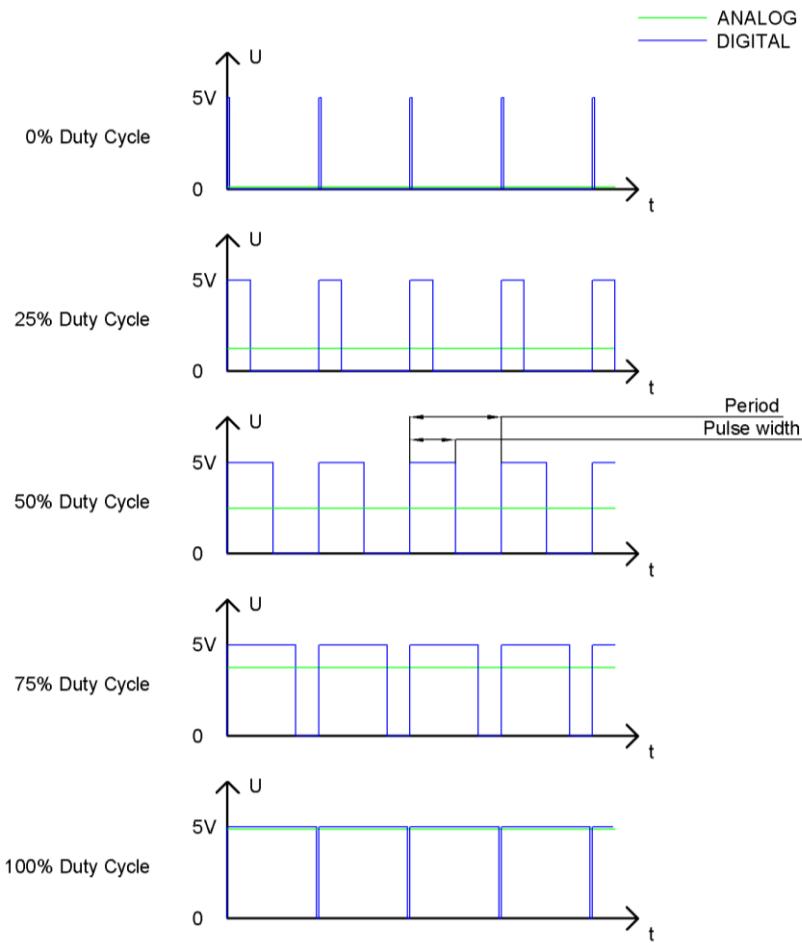
Note that the Analog signals are curved waves and the Digital signals are "Square Waves".

In practical applications, we often use binary as the digital signal, that is a series of 0's and 1's. Since a binary signal only has two values (0 or 1) it has great stability and reliability. Lastly, both analog and digital signals can be converted into the other.

PWM

PWM, Pulse-Width Modulation, is a very effective method for using digital signals to control analog circuits. Digital processors cannot directly output analog signals. PWM technology makes it very convenient to achieve this conversion (translation of digital to analog signals).

PWM technology uses digital pins to send certain frequencies of square waves, that is, the output of high levels and low levels, which alternately last for a while. The total time for each set of high levels and low levels is generally fixed, which is called the period (Note: the reciprocal of the period is frequency). The time of high level outputs are generally called "pulse width", and the duty cycle is the percentage of the ratio of pulse duration, or pulse width (PW) to the total period (T) of the waveform. The longer the output of high levels last, the longer the duty cycle and the higher the corresponding voltage in the analog signal will be. The following figures show how the analog signal voltages vary between 0V-5V (high level is 5V) corresponding to the pulse width 0%-100%:



The longer the PWM duty cycle is, the higher the output power will be. Now that we understand this relationship, we can use PWM to control the brightness of an LED or the speed of DC motor and so on.

It is evident, from the above, that PWM is not actually analog but the effective value of voltage is equivalent to the corresponding analog value. Therefore, by using PWM, we can control the output power of to an LED and control other devices and modules to achieve multiple effects and actions.

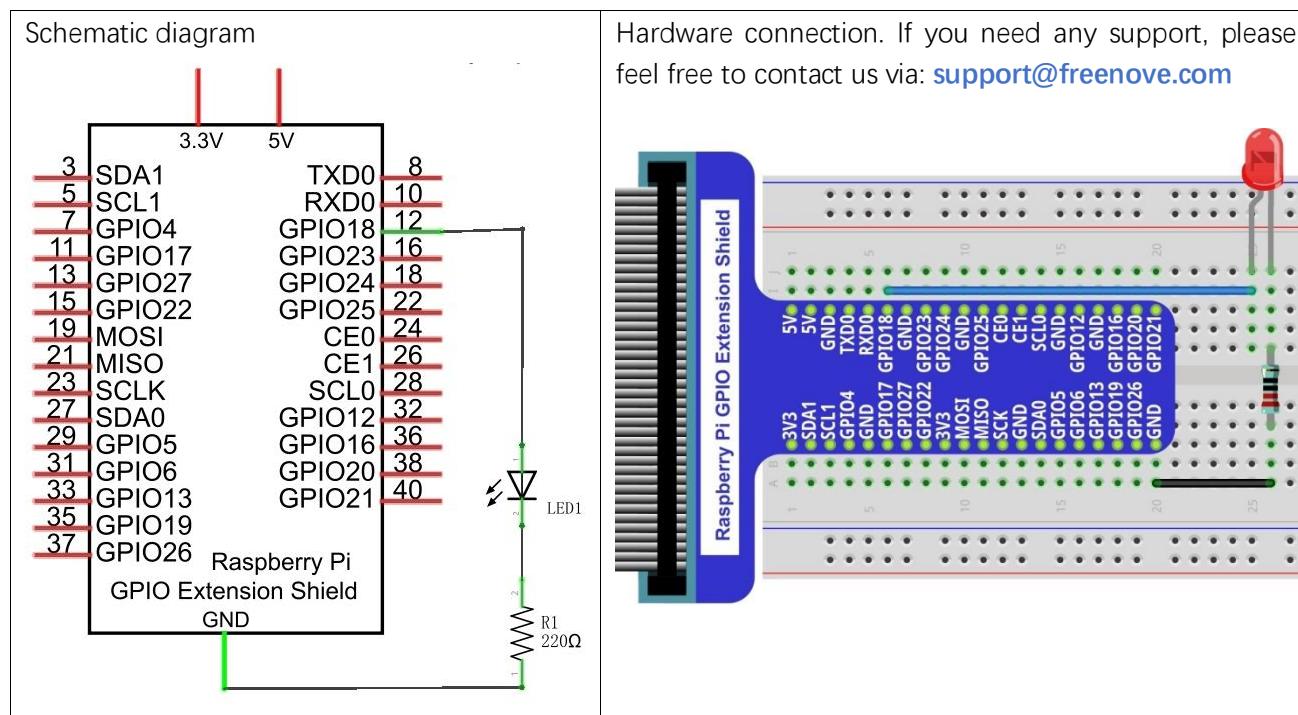
In RPi, GPIO18 pin has the ability to output to hardware via PWM with a 10-bit accuracy. This means that 100% of the pulse width can be divided into $2^{10}=1024$ equal parts.

The wiringPi library of C provides both a hardware PWM and a software PWM method, while the wiringPi library of Python does not provide a hardware PWM method. There is only a software PWM option for Python.

The hardware PWM only needs to be configured, does not require CPU resources and is more precise in time control. The software PWM requires the CPU to work continuously by using code to output high level and low level. This part of the code is carried out by multi-threading, and the accuracy is relatively not high enough.

In order to keep the results running consistently, we will use PWM.

Circuit



Code

This project uses the PWM output from the GPIO18 pin to make the pulse width gradually increase from 0% to 100% and then gradually decrease from 100% to 0% to make the LED glow brighter then dimmer.

C Code 4.1.1 BreathingLED

First, observe the project result, and then learn about the code in detail.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 04.1.1_BreathingLED directory of C code.

```
cd ~/Freenove_Kit/Code/C_Code/04.1.1_BreathingLED
```

2. Use following command to compile "BreathingLED.c" and generate executable file "BreathingLED".

```
gcc BreathingLED.c -o BreathingLED -lwiringPi
```

3. Then run the generated file "BreathingLED"

```
sudo ./BreathingLED
```

After the program is executed, you'll see that LED is turned from on to off and then from off to on gradually like breathing.

The following is the program code:

```

1 #include <wiringPi.h>
2 #include <stdio.h>
3 #include <softPwm.h>
4 #define ledPin 1
5 void main(void)
6 {
7     int i;
```

```

8      printf("Program is starting ... \n");
9
10     wiringPiSetup(); //Initialize wiringPi.
11
12     softPwmCreate(ledPin, 0, 100); //Create SoftPWM pin
13
14     while(1) {
15         for(i=0;i<100;i++) { //make the led brighter
16             softPwmWrite(ledPin, i);
17             delay(20);
18         }
19         delay(300);
20         for(i=100;i>=0;i--) { //make the led darker
21             softPwmWrite(ledPin, i);
22             delay(20);
23         }
24         delay(300);
25     }
26 }
27 }
```

First, create a software PWM pin.

```
softPwmCreate(ledPin, 0, 100); //Create SoftPWM pin
```

There are two “for” loops in the next endless “while” loop. The first loop outputs a power signal to the ledPin PWM from 0% to 100% and the second loop outputs a power signal to the ledPin PWM from 100% to 0%.

```

while(1) {
    for(i=0;i<100;i++) {
        softPwmWrite(ledPin, i);
        delay(20);
    }
    delay(300);
    for(i=100;i>=0;i--) {
        softPwmWrite(ledPin, i);
        delay(20);
    }
    delay(300);
}
```

You can also adjust the rate of the state change of LED by changing the parameter of the delay() function in the “for” loop.

```
int softPwmCreate (int pin, int initialValue, int pwmRange);
```

This creates a software controlled PWM pin.

```
void softPwmWrite (int pin, int value);
```

This updates the PWM value on the given pin.

For more details, please refer <http://wiringpi.com/reference/software-pwm-library/>

Python Code 4.1.1 BreathingLED

First, observe the project result, and then learn about the code in detail.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 04.1.1_BreathingLED directory of Python code.

```
cd ~/Freenove_Kit/Code/Python_Code/04.1.1_BreathingLED
```

2. Use the Python command to execute Python code "BreathingLED.py".

```
python BreathingLED.py
```

After the program is executed, you will see that the LED gradually turns ON and then gradually turns OFF similar to "breathing".

The following is the program code:

```
1 import RPi.GPIO as GPIO
2 import time
3
4 LedPin = 12      # define the LedPin
5
6 def setup():
7     global p
8     GPIO.setmode(GPIO.BOARD)      # use PHYSICAL GPIO Numbering
9     GPIO.setup(LedPin, GPIO.OUT)   # set LedPin to OUTPUT mode
10    GPIO.output(LedPin, GPIO.LOW) # make ledPin output LOW level to turn off LED
11
12    p = GPIO.PWM(LedPin, 500)    # set PWM Frequency to 500Hz
13    p.start(0)                  # set initial Duty Cycle to 0
14
15 def loop():
16     while True:
17         for dc in range(0, 101, 1): # make the led brighter
18             p.ChangeDutyCycle(dc)    # set dc value as the duty cycle
19             time.sleep(0.01)
20             time.sleep(1)
21         for dc in range(100, -1, -1): # make the led darker
22             p.ChangeDutyCycle(dc)    # set dc value as the duty cycle
23             time.sleep(0.01)
24             time.sleep(1)
25
26 def destroy():
27     p.stop() # stop PWM
28     GPIO.cleanup() # Release all GPIO
29
30 if __name__ == '__main__':      # Program entrance
31     print ('Program is starting ... ')
32     setup()
33     try:
34         loop()
```



```

35     except KeyboardInterrupt: # Press ctrl-c to end the program.
36         destroy()

```

The LED is connected to the IO port called GPIO18. The LedPin is defined as pin 12 and set to output mode according to the corresponding chart for pin designations. Then create a PWM instance and set the PWM frequency to 1000HZ and the initial duty cycle to 0%.

```

LedPin = 12      # define the LedPin

def setup():
    global p
    GPIO.setmode(GPIO.BOARD)      # use PHYSICAL GPIO Numbering
    GPIO.setup(LedPin, GPIO.OUT)   # set LedPin to OUTPUT mode
    GPIO.output(LedPin, GPIO.LOW)  # make ledPin output LOW level to turn off LED

    p = GPIO.PWM(LedPin, 500)    # set PWM Frequency to 500Hz
    p.start(0)                  # set initial Duty Cycle to 0

```

There are two “for” loops used to control the breathing LED in the next endless “while” loop. The first loop outputs a power signal to the ledPin PWM from 0% to 100% and the second loop outputs a power signal to the ledPin PWM from 100% to 0%.

```

def loop():
    while True:
        for dc in range(0, 101, 1): # make the led brighter
            p.ChangeDutyCycle(dc)   # set dc value as the duty cycle
            time.sleep(0.01)
        time.sleep(1)
        for dc in range(100, -1, -1): # make the led darker
            p.ChangeDutyCycle(dc)   # set dc value as the duty cycle
            time.sleep(0.01)
        time.sleep(1)

```

The related functions of PWM are described as follows:

p = GPIO.PWM(channel, frequency)

To create a PWM instance:

p.start(dc)

To start PWM, where dc is the duty cycle (0.0 <= dc <= 100.0)

p.ChangeFrequency(freq)

To change the frequency, where freq is the new frequency in Hz

p.ChangeDutyCycle(dc)

To change the duty cycle where 0.0 <= dc <= 100.0

p.stop()

To stop PWM.

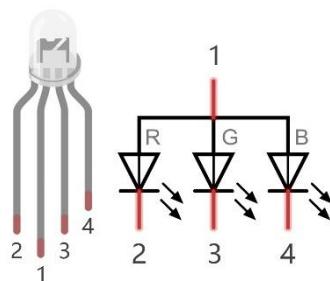
For more details regarding methods for using PWM with RPi.GPIO, please refer to:

<https://sourceforge.net/p/raspberry-gpio-python/wiki/PWM/>

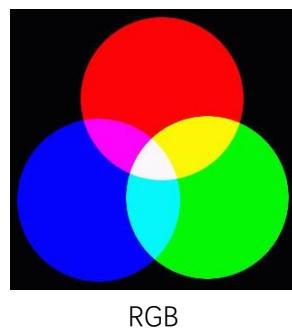
Chapter 5 RGB LED

In this chapter, we will learn how to control a RGB LED.

A RGB LED has 3 LEDs integrated into one LED component. It can respectively emit Red, Green and Blue light. In order to do this, it requires 4 pins (this is also how you identify it). The long pin (1) is the common which is the Cathode (+) or positive lead, the other 3 are the Anodes (-) or negative leads. A rendering of a RGB LED and its electronic symbol are shown below. We can make RGB LED emit various colors of light and brightness by controlling the 3 Anodes (2, 3 & 4) of the RGB LED



Red, Green, and Blue light are called 3 Primary Colors when discussing light (Note: for pigments such as paints, the 3 Primary Colors are Red, Blue and Yellow). When you combine these three Primary Colors of light with varied brightness, they can produce almost any color of visible light. Computer screens, single pixels of cell phone screens, neon lamps, etc. can all produce millions of colors due to phenomenon.



If we use a three 8 bit PWM to control the RGB LED, in theory, we can create $2^8 * 2^8 * 2^8 = 16777216$ (16 million) colors through different combinations of RGB light brightness.

Next, we will use RGB LED to make a multicolored LED.

Project 5.1 Multicolored LED

In this project, we will make a multicolored LED, which we can program the RGB LED to automatically change colors.

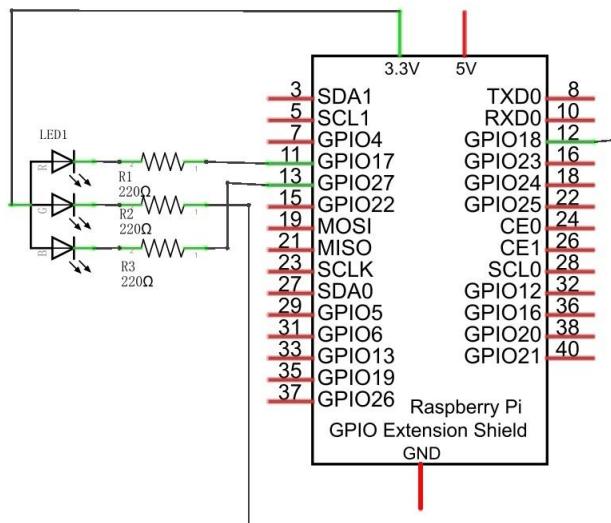
Component List

Raspberry Pi (with 40 GPIO) x1	RGB LED x1	Resistor 220Ω x3
GPIO Extension Board & Wire x1		
Breadboard x1		

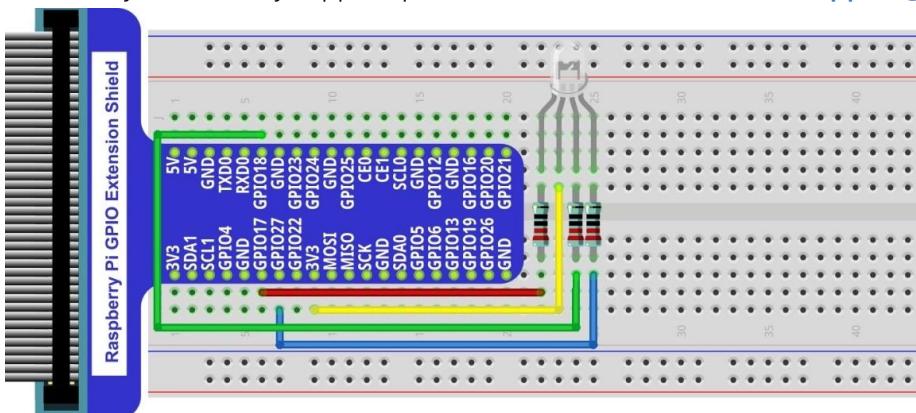
Jumper Wire		
		

Circuit

Schematic diagram



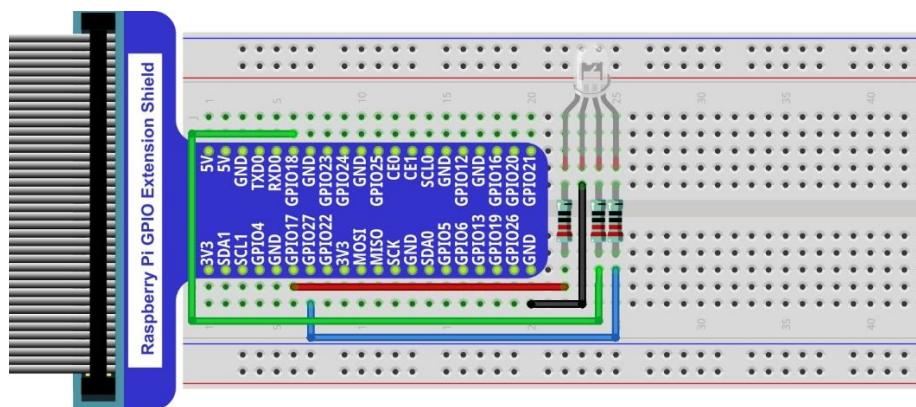
Hardware connection. If you need any support, please feel free to contact us via: support@freenove.com



In this kit, the RGB led is **Common anode**. The **voltage difference** between LED will make it work. There is no visible GND. The GPIO ports can also receive current while in output mode.

If circuit above doesn't work, the RGB LED may be common cathode. Please try following wiring.

There is no need to modify code for random color.



Code

We need to use the software to make the ordinary GPIO output PWM, since this project requires 3 PWM and in RPi only one GPIO has the hardware capability to output PWM,

C Code 5.1.1 Colorful LED

First, observe the project result, and then learn about the code in detail.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 05.1.1_ColorfulLED directory of C code.

```
cd ~/Freenove_Kit/Code/C_Code/05.1.1_ColorfulLED
```

2. Use following command to compile "ColorfulLED.c" and generate executable file "ColorfulLED". Note: in this project, the software PWM uses a multi-threading mechanism. So "-lpthread" option need to be add to the compiler.

```
gcc ColorfulLED.c -o ColorfulLED -lwiringPi -lpthread
```

3. And then run the generated file "ColorfulLED".

```
sudo ./ColorfulLED
```

After the program is executed, you will see that the RGB LED shows lights of different colors randomly.

The following is the program code:

```

1 #include <wiringPi.h>
2 #include <softPwm.h>
3 #include <stdio.h>
4 #include <stdlib.h>
5
6 #define ledPinRed    0
7 #define ledPinGreen   1
8 #define ledPinBlue    2
9
10 void setupLedPin(void)
11 {

```



```

12     softPwmCreate(ledPinRed, 0, 100); //Creat SoftPWM pin for red
13     softPwmCreate(ledPinGreen, 0, 100); //Creat SoftPWM pin for green
14     softPwmCreate(ledPinBlue, 0, 100); //Creat SoftPWM pin for blue
15 }
16
17 void setLedColor(int r, int g, int b)
18 {
19     softPwmWrite(ledPinRed, r); //Set the duty cycle
20     softPwmWrite(ledPinGreen, g); //Set the duty cycle
21     softPwmWrite(ledPinBlue, b); //Set the duty cycle
22 }
23
24 int main(void)
25 {
26     int r, g, b;
27
28     printf("Program is starting ... \n");
29
30     wiringPiSetup(); //Initialize wiringPi.
31
32     setupLedPin();
33     while(1) {
34         r=random()%100; //get a random in (0,100)
35         g=random()%100; //get a random in (0,100)
36         b=random()%100; //get a random in (0,100)
37         setLedColor(r, g, b); //set random as the duty cycle value
38         printf("r=%d, g=%d, b=%d \n", r, g, b);
39         delay(1000);
40     }
41     return 0;
42 }
```

First, in subfunction of ledInit(), create the software PWM control pins used to control the R, G, B pin respectively.

```

void setupLedPin(void)
{
    softPwmCreate(ledPinRed, 0, 100); //Creat SoftPWM pin for red
    softPwmCreate(ledPinGreen, 0, 100); //Creat SoftPWM pin for green
    softPwmCreate(ledPinBlue, 0, 100); //Creat SoftPWM pin for blue
}
```

Then create subfunction, and set the PWM of three pins.

```

void setLedColor(int r, int g, int b)
{
    softPwmWrite(ledPinRed, r); //Set the duty cycle
```

```
    softPwmWrite(ledPinGreen, g); //Set the duty cycle  
    softPwmWrite(ledPinBlue, b); //Set the duty cycle  
}
```

Finally, in the “while” loop of main function, get three random numbers and specify them as the PWM duty cycle, which will be assigned to the corresponding pins. So RGB LED can switch the color randomly all the time.

```
while(1) {  
    r=random()%100; //get a random in (0, 100)  
    g=random()%100; //get a random in (0, 100)  
    b=random()%100; //get a random in (0, 100)  
    setLedColor(r, g, b); //set random as the duty cycle value  
    printf("r=%d, g=%d, b=%d \n", r, g, b);  
    delay(1000);  
}
```

The related function of PWM Software can be described as follows:

long random();

This function will return a random number.

For more details about Software PWM, please refer to: <http://wiringpi.com/reference/software-pwm-library/>



Python Code 5.1.1 ColorfulLED

First, observe the project result, and then learn about the code in detail.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 05.1.1_ColorfulLED directory of Python code.

cd ~/Freenove_Kit/Code/Python_Code/05.1.1_ColorfulLED

2. Use python command to execute python code "ColorfullLED.py".

python ColorfullLED.py

After the program is executed, you will see that the RGB LED randomly lights up different colors.

The following is the program code:

```
1 import RPi.GPIO as GPIO
2
3 import time
4
5 import random
6
7
8 pins = {'pinRed':11, 'pinGreen':12, 'pinBlue':13} # define the pins for RGBLED
9
10
11
12
13
14
15
16
17
18
19
20
21
22
23
24
25
26
27
28
29
30
31
32
33
34
35
```

```
import RPi.GPIO as GPIO
import time
import random

pins = {'pinRed':11, 'pinGreen':12, 'pinBlue':13} # define the pins for RGBLED

def setup():
    global pwmRed, pwmGreen, pwmBlue
    GPIO.setmode(GPIO.BOARD)      # use PHYSICAL GPIO Numbering
    GPIO.setup(pins, GPIO.OUT)     # set RGBLED pins to OUTPUT mode
    GPIO.output(pins, GPIO.HIGH)   # make RGBLED pins output HIGH level
    pwmRed = GPIO.PWM(pins['pinRed'], 2000)    # set PWM Frequnce to 2kHz
    pwmGreen = GPIO.PWM(pins['pinGreen'], 2000)  # set PWM Frequnce to 2kHz
    pwmBlue = GPIO.PWM(pins['pinBlue'], 2000)    # set PWM Frequnce to 2kHz
    pwmRed.start(0)      # set initial Duty Cycle to 0
    pwmGreen.start(0)
    pwmBlue.start(0)

def setColor(r_val,g_val,b_val):      # change duty cycle for three pins to r_val,g_val,b_val
    pwmRed.ChangeDutyCycle(r_val)      # change pwmRed duty cycle to r_val
    pwmGreen.ChangeDutyCycle(g_val)
    pwmBlue.ChangeDutyCycle(b_val)

def loop():
    while True :
        r=random.randint(0,100)  #get a random in (0,100)
        g=random.randint(0,100)
        b=random.randint(0,100)
        setColor(r,g,b)          #set random as a duty cycle value
        print ('r=%d, g=%d, b=%d' %(r ,g, b))
        time.sleep(1)

def destroy():
    pwmRed.stop()
    pwmGreen.stop()
```



```
36     pwmBlue.stop()
37     GPIO.cleanup()
38
39 if __name__ == '__main__':      # Program entrance
40     print ('Program is starting ... ')
41     setup()
42     try:
43         loop()
44     except KeyboardInterrupt: # Press ctrl-c to end the program.
45         destroy()
```

In last chapter, we learned how to use Python language to make a pin output PWM. In this project, we output to three pins via PWM and the method is exactly the same as we used in the last chapter. In the “while” loop of “loop” function, we first generate three random numbers, and then specify these three random numbers as the PWM values for the three pins, which will make the RGB LED produce multiple colors randomly.

```
def loop():
    while True :
        r=random.randint(0,100)  #get a random in (0,100)
        g=random.randint(0,100)
        b=random.randint(0,100)
        setColor(r,g,b)          #set random as a duty cycle value
        print (' r=%d, g=%d, b=%d ' %(r ,g, b))
        time.sleep(1)
```

About the randint() function :

random.randint(a, b)

This function can return a random integer (a whole number value) within the specified range (a, b).

Chapter 6 Buzzer

In this chapter, we will learn about buzzers and the sounds they make. And in our next project, we will use an active buzzer to make a doorbell and a passive buzzer to make an alarm.

Project 6.1 Doorbell

We will make a doorbell with this functionality: when the Push Button Switch is pressed the buzzer sounds and when the button is released, the buzzer stops. This is a momentary switch function.

Component List

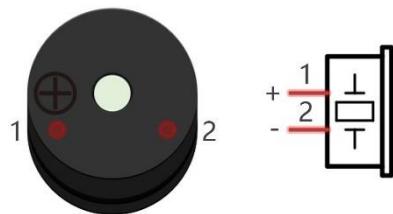
Raspberry Pi (with 40 GPIO) x1 GPIO Extension Board & Ribbon Cable x1 Breadboard x1	Jumper Wire 			
NPN transistor x1 (S8050) 	Active buzzer x1 	Push Button Switch x1 	Resistor 1kΩ x1 	Resistor 10kΩ x2 

Component knowledge

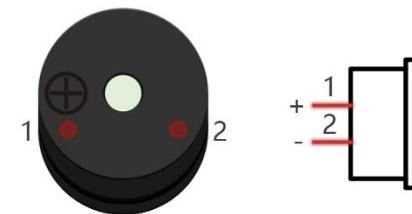
Buzzer

A buzzer is an audio component. They are widely used in electronic devices such as calculators, electronic alarm clocks, automobile fault indicators, etc. There are both active and passive types of buzzers. Active buzzers have oscillator inside, these will sound as long as power is supplied. Passive buzzers require an external oscillator signal (generally using PWM with different frequencies) to make a sound.

Active buzzer



Passive buzzer



Active buzzers are easier to use. Generally, they only make a specific sound frequency. Passive buzzers require an external circuit to make sounds, but passive buzzers can be controlled to make sounds of various frequencies. The resonant frequency of the passive buzzer in this Kit is 2kHz, which means the passive buzzer is the loudest when its resonant frequency is 2kHz.

How to identify active and passive buzzer?

1. As a rule, there is a label on an active buzzer covering the hole where sound is emitted, but there are exceptions to this rule.
2. Active buzzers are more complex than passive buzzers in their manufacture. There are many circuits and crystal oscillator elements inside active buzzers; all of this is usually protected with a waterproof coating (and a housing) exposing only its pins from the underside. On the other hand, passive buzzers do not have protective coatings on their underside. From the pin holes, view of a passive buzzer, you can see the circuit board, coils, and a permanent magnet (all or any combination of these components depending on the model).



Active buzzer bottom



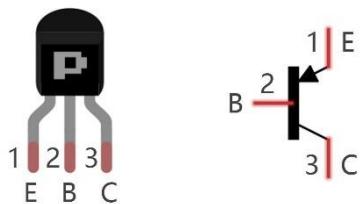
Passive buzzer bottom

Transistors

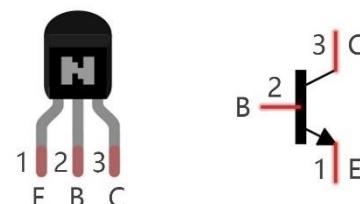
A transistor is required in this project due to the buzzer's current being so great that GPIO of RPi's output capability cannot meet the power requirement necessary for operation. A NPN transistor is needed here to amplify the current.

Transistors, full name: semiconductor transistor, is a semiconductor device that controls current (think of a transistor as an electronic "amplifying or switching device"). Transistors can be used to amplify weak signals, or to work as a switch. Transistors have three electrodes (PINs): base (b), collector (c) and emitter (e). When there is current passing between "be" then "ce" will have a several-fold current increase (transistor magnification), in this configuration the transistor acts as an amplifier. When current produced by "be" exceeds a certain value, "ce" will limit the current output. at this point the transistor is working in its saturation region and acts like a switch. Transistors are available as two types as shown below: PNP and NPN,

PNP transistor



NPN transistor

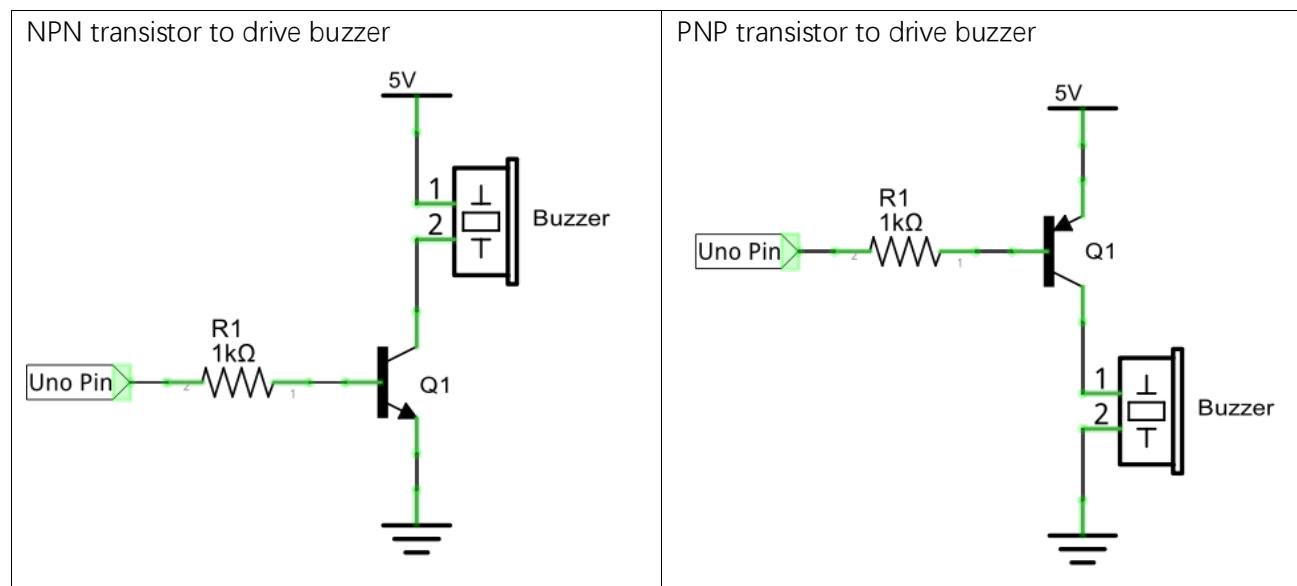


In our kit, the PNP transistor is marked with 8550, and the NPN transistor is marked with 8050.

Thanks to the transistor's characteristics, they are often used as switches in digital circuits. As micro-controllers output current capacity is very weak, we will use a transistor to amplify its current in order to drive components requiring higher current.

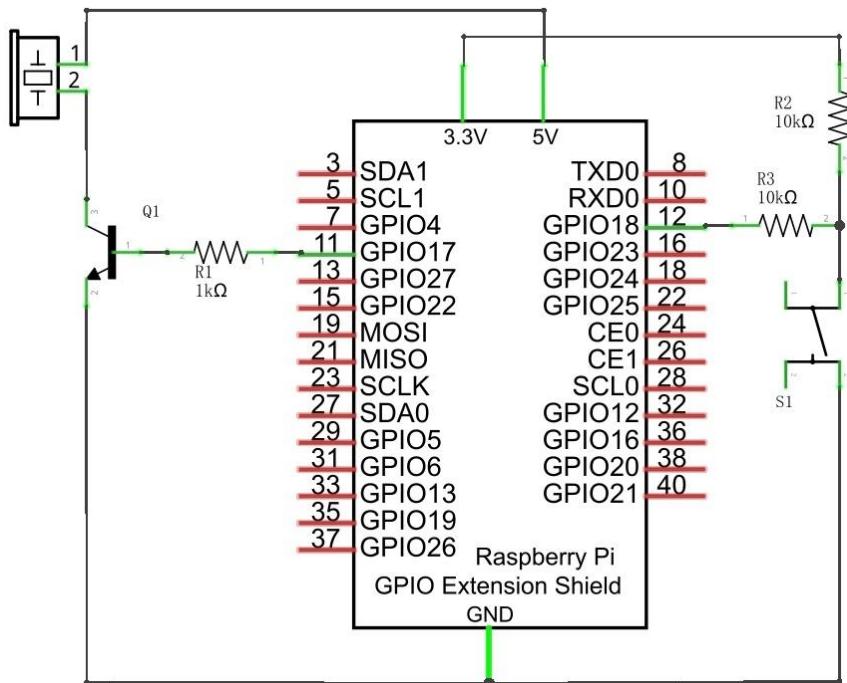
When we use a NPN transistor to drive a buzzer, we often use the following method. If GPIO outputs high level, current will flow through R1 (Resistor 1), the transistor conducts current and the buzzer will make sounds. If GPIO outputs low level, no current will flow through R1, the transistor will not conduct current and buzzer will remain silent (no sounds).

When we use a PNP transistor to drive a buzzer, we often use the following method. If GPIO outputs low level, current will flow through R1. The transistor conducts current and the buzzer will make sounds. If GPIO outputs high level, no current flows through R1, the transistor will not conduct current and buzzer will remain silent (no sounds). Below are the circuit schematics for both a NPN and PNP transistor to power a buzzer.

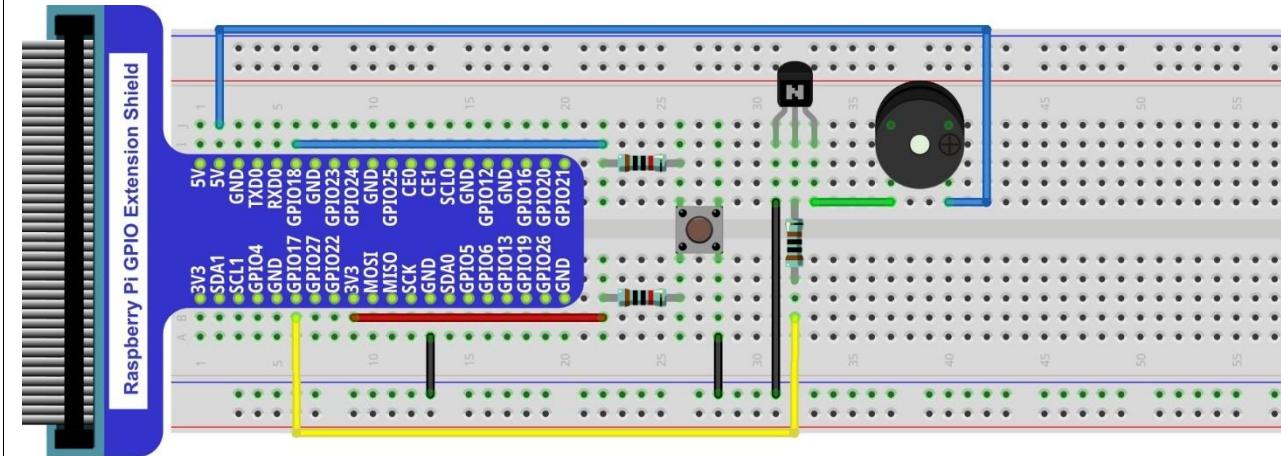


Circuit

Schematic diagram with RPi GPIO Extension Shield



Hardware connection. If you need any support, please feel free to contact us via: support@freenove.com



Note: in this circuit, the power supply for the buzzer is 5V, and pull-up resistor of the push button switch is connected to the 3.3V power feed. Actually, the buzzer can work when connected to the 3.3V power feed but this will produce a weak sound from the buzzer (not very loud).

Code

In this project, a buzzer will be controlled by a push button switch. When the button switch is pressed, the buzzer sounds and when the button is released, the buzzer stops. It is analogous to our earlier project that controlled an LED ON and OFF.

C Code 6.1.1 Doorbell

First, observe the project result, and then learn about the code in detail.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 06.1.1_Doorbell directory of C code.

```
cd ~/Freenove_Kit/Code/C_Code/06.1.1_Doorbell
```

2. Use following command to compile "Doorbell.c" and generate executable file "Doorbell.c".

```
gcc Doorbell.c -o Doorbell -lwiringPi
```

3. Then run the generated file "Doorbell".

```
sudo ./Doorbell
```

After the program is executed, press the push button switch and the will buzzer sound. Release the push button switch and the buzzer will stop.

The following is the program code:

```
1 #include <wiringPi.h>
2 #include <stdio.h>
3
4 #define buzzerPin 0 //define the buzzerPin
5 #define buttonPin 1 //define the buttonPin
6
7 void main(void)
8 {
9     printf("Program is starting ... \n");
10    wiringPiSetup();
11
12    pinMode(buzzerPin, OUTPUT);
13    pinMode(buttonPin, INPUT);
14
15    pullUpDnControl(buttonPin, PUD_UP); //pull up to HIGH level
16    while(1) {
17
18        if(digitalRead(buttonPin) == LOW){ //button is pressed
19            digitalWrite(buzzerPin, HIGH); //Turn on buzzer
20            printf("buzzer turned on >>> \n");
21        }
22        else { //button is released
23            digitalWrite(buzzerPin, LOW); //Turn off buzzer
24            printf("buzzer turned off <<< \n");
25        }
26    }
27 }
28 }
```

The code is exactly the same as when we used a push button switch to control an LED. You can also try using the PNP transistor to achieve the same results.



Python Code 6.1.1 Doorbell

First, observe the project result, then learn about the code in detail.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 06.1.1_Doorbell directory of Python code.

```
cd ~/Freenove_Kit/Code/Python_Code/06.1.1_Doorbell
```

2. Use python command to execute python code "Doorbell.py".

```
python Doorbell.py
```

After the program is executed, press the push button switch and the buzzer will sound. Release the push button switch and the buzzer will stop.

The following is the program code:

```
1 import RPi.GPIO as GPIO
2
3 buzzerPin = 11      # define buzzerPin
4 buttonPin = 12      # define buttonPin
5
6 def setup():
7     GPIO.setmode(GPIO.BOARD)          # use PHYSICAL GPIO Numbering
8     GPIO.setup(buzzerPin, GPIO.OUT)    # set buzzerPin to OUTPUT mode
9     GPIO.setup(buttonPin, GPIO.IN, pull_up_down=GPIO.PUD_UP)    # set buttonPin to PULL UP
10    INPUT mode
11
12 def loop():
13     while True:
14         if GPIO.input(buttonPin)==GPIO.LOW: # if button is pressed
15             GPIO.output(buzzerPin,GPIO.HIGH) # turn on buzzer
16             print ('buzzer turned on >>>')
17         else : # if button is released
18             GPIO.output(buzzerPin,GPIO.LOW) # turn off buzzer
19             print ('buzzer turned off <<<')
20
21 def destroy():
22     GPIO.cleanup()                  # Release all GPIO
23
24 if __name__ == '__main__':      # Program entrance
25     print ('Program is starting...')
26     setup()
27     try:
28         loop()
29     except KeyboardInterrupt: # Press ctrl-c to end the program.
30         destroy()
```

The code is exactly the same as when we used a push button switch to control an LED. You can also try using the PNP transistor to achieve the same results.

Project 6.2 Alertor

Next, we will use a passive buzzer to make an alarm.

The list of components and the circuit is similar to the doorbell project. We only need to take the Doorbell circuit and replace the active buzzer with a passive buzzer.

Code

In this project, our buzzer alarm is controlled by the push button switch. Press the push button switch and the buzzer will sound. Release the push button switch and the buzzer will stop.

As stated before, it is analogous to our earlier project that controlled an LED ON and OFF.

To control a passive buzzer requires PWM of certain sound frequency.

C Code 6.2.1 Alertor

First, observe the project result, and then learn about the code in detail.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 06.2.1_Alertor directory of C code.

```
cd ~/Freenove_Kit/Code/C_Code/06.2.1_Alertor
```

2. Use following command to compile "Alertor.c" and generate executable file "Alertor". "-lm" and "-lpthread" compiler options need to added here.

```
gcc Alertor.c -o Alertor -lwiringPi -lm -lpthread
```

3. Then run the generated file "Alertor".

```
sudo ./Alertor
```

After the program is executed, press the push button switch and the buzzer will sound. Release the push button switch and the buzzer will stop.

The following is the program code:

```

1 #include <wiringPi.h>
2 #include <stdio.h>
3 #include <softTone.h>
4 #include <math.h>
5
6 #define buzzerPin    0      //define the buzzerPin
7 #define buttonPin     1      //define the buttonPin
8
9 void alertor(int pin) {
10     int x;
11     double sinVal, toneVal;
12     for(x=0;x<360;x++) { // frequency of the alertor is consistent with the sine wave
13         sinVal = sin(x * (M_PI / 180));           //Calculate the sine value
14         toneVal = 2000 + sinVal * 500;           //Add the resonant frequency and weighted sine
15         value
16         softToneWrite(pin, toneVal);           //output corresponding PWM
17         delay(1);

```





```

18 }
19 }
20 void stopAlertor(int pin){
21     softToneWrite(pin, 0);
22 }
23 int main(void)
24 {
25     printf("Program is starting ... \n");
26
27     wiringPiSetup();
28
29     pinMode(buzzerPin, OUTPUT);
30     pinMode(buttonPin, INPUT);
31     softToneCreate(buzzerPin); //set buzzerPin
32     pullUpDnControl(buttonPin, PUD_UP); //pull up to HIGH level
33     while(1) {
34         if(digitalRead(buttonPin) == LOW){ //button is pressed
35             alertor(buzzerPin); // turn on buzzer
36             printf("alertor turned on >>> \n");
37         }
38         else { //button is released
39             stopAlertor(buzzerPin); // turn off buzzer
40             printf("alertor turned off <<< \n");
41         }
42     }
43     return 0;
44 }
```

The code is the same to the active buzzer but the method is different. A passive buzzer requires PWM of a certain frequency, so you need to create a software PWM pin though softToneCreate (buzzerPin). Here softTone is designed to generate square waves with variable frequency and a duty cycle fixed to 50%, which is a better choice for controlling the buzzer.

	softToneCreate (buzzerPin);
--	-----------------------------

In the while loop of the main function, when the push button switch is pressed the subfunction alertor() will be called and the alarm will issue a warning sound. The frequency curve of the alarm is based on a sine curve. We need to calculate the sine value from 0 to 360 degrees and multiplied by a certain value (here this value is 500) plus the resonant frequency of buzzer. We can set the PWM frequency through softToneWrite (pin, toneVal).

	void alertor(int pin){ int x; double sinVal, toneVal; for(x=0;x<360;x++){ //The frequency is based on the sine curve. sinVal = sin(x * (M_PI / 180)); toneVal = 2000 + sinVal * 500;
--	---

```
    softToneWrite(pin, toneVal) ;  
    delay(1) ;  
}  
}
```

If you want to stop the buzzer, just set PWM frequency of the buzzer pin to 0.

```
void stopAlertor(int pin) {  
    softToneWrite(pin, 0) ;  
}
```

The related functions of softTone are described as follows:

int softToneCreate (int pin) ;

This creates a software controlled tone pin.

void softToneWrite (int pin, int freq) ;

This updates the tone frequency value on the given pin.

For more details about softTone, please refer to :<http://wiringpi.com/reference/software-tone-library/>

Python Code 6.2.1 Alertor

First observe the project result, and then learn about the code in detail.

If you have any concerns, please contact us via: support@freenove.com

1. Use cd command to enter 06.2.1_Alertor directory of Python code.

```
cd ~/Freenove_Kit/Code/Python_Code/06.2.1_Alertor
```

2. Use the python command to execute the Python code "Alertor.py".

```
python Alertor.py
```

After the program is executed, press the push button switch and the buzzer will sound. Release the push button switch and the buzzer will stop.

The following is the program code:

```

1 import RPi.GPIO as GPIO
2 import time
3 import math
4
5 buzzerPin = 11      # define the buzzerPin
6 buttonPin = 12      # define the buttonPin
7
8 def setup():
9     global p
10    GPIO.setmode(GPIO.BOARD)          # Use PHYSICAL GPIO Numbering
11    GPIO.setup(buzzerPin, GPIO.OUT)    # set RGBLED pins to OUTPUT mode
12    GPIO.setup(buttonPin, GPIO.IN, pull_up_down=GPIO.PUD_UP)    # Set buttonPin to INPUT
13 mode, and pull up to HIGH level, 3.3V
14    p = GPIO.PWM(buzzerPin, 1)
15    p.start(0);
16
17 def loop():
18     while True:
19         if GPIO.input(buttonPin)==GPIO.LOW:
20             alertor()
21             print ('alertor turned on >>> ')
22         else :
23             stopAlertor()
24             print ('alertor turned off <<< ')
25 def alertor():
26     p.start(50)
27     for x in range(0,361):      # Make frequency of the alertor consistent with the sine wave
28         sinVal = math.sin(x * (math.pi / 180.0))          # calculate the sine value
29         toneVal = 2000 + sinVal * 500 # Add to the resonant frequency with a Weighted
30         p.ChangeFrequency(toneVal)      # Change Frequency of PWM to toneVal
31         time.sleep(0.001)
32
33 def stopAlertor():

```

```

34     p.stop()
35
36     def destroy():
37         GPIO.output(buzzerPin, GPIO.LOW)      # Turn off buzzer
38         GPIO.cleanup()                      # Release GPIO resource
39
40     if __name__ == '__main__':    # Program entrance
41         print ('Program is starting...')
42         setup()
43         try:
44             loop()
45         except KeyboardInterrupt: # Press ctrl-c to end the program.
46             destroy()

```

The code is the same to the active buzzer but the method is different. A passive buzzer requires PWM of a certain frequency, so you need to create a software PWM pin though softToneCreate (buzzerRPin). The way to create a PWM was introduced earlier in the BreathingLED and RGB LED projects.

```

def setup():
    global p
    GPIO.setmode(GPIO.BOARD)          # Use PHYSICAL GPIO Numbering
    GPIO.setup(buzzerPin, GPIO.OUT)    # set RGBLED pins to OUTPUT mode
    GPIO.setup(buttonPin, GPIO.IN, pull_up_down=GPIO.PUD_UP)  # Set buttonPin to INPUT
    mode, and pull up to HIGH level, 3.3V
    p = GPIO.PWM(buzzerPin, 1)
    p.start(0);

```

In the while loop loop of the main function, when the push button switch is pressed the subfunction alertor() will be called and the alarm will issue a warning sound. The frequency curve of the alarm is based on a sine curve. We need to calculate the sine value from 0 to 360 degrees and multiplied by a certain value (here this value is 500) plus the resonant frequency of buzzer. We can set the PWM frequency through softToneWrite (pin, toneVal).

```

def alertor():
    p.start(50)
    for x in range(0, 361):
        sinVal = math.sin(x * (math.pi / 180.0))
        toneVal = 2000 + sinVal * 500
        p.ChangeFrequency(toneVal)
        time.sleep(0.001)

```

When the push button switch is released, the buzzer (in this case our Alarm) will stop.

```

def stopAlertor():
    p.stop()

```



Chapter 7 WebIOPi & IoT

In this chapter, we will learn how to use GPIO to control the RPi remotely via a network and how to build a WebIOPi service on the RPi.

This concept is known as “IoT” or Internet of Things. The development of IoT will greatly change our habits and make our lives more convenient and efficient.

“WebIOPi” is the Raspberry Pi Internet of Things Framework. After configuring WebIOPi on your RPi is completed, you can use a web browser on a mobile phone, computers and other equipment to control, debug and use RPi GPIO conveniently. It also supports many commonly used communication protocols, such as serial, I2C, SPI, etc., and many equipment, like AD/DA converter pcf8591 we used earlier and so on. By adding some peripheral circuits, you can create your own Smart Home environment.

For more details about WebIOPi, please refer to: <http://webiopi.trouch.com/>

Project 7.1 Remote LED

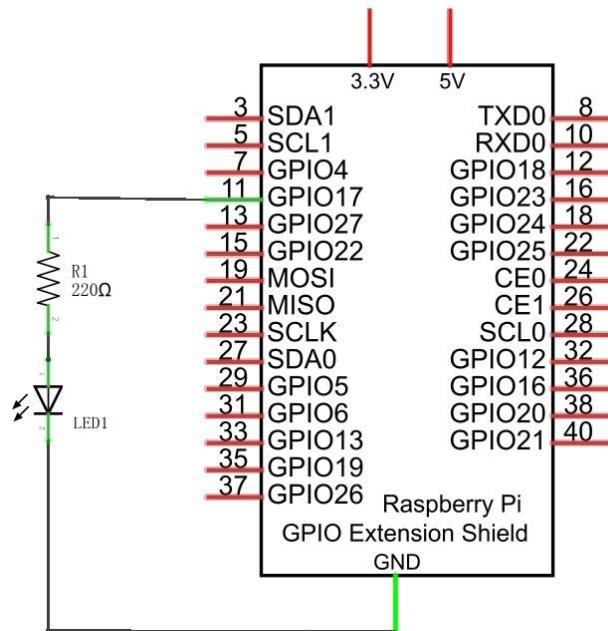
In this project, we need to build a WebIOPi service, and then use the RPi GPIO to control an LED through the web browser of phone or PC.

Component List

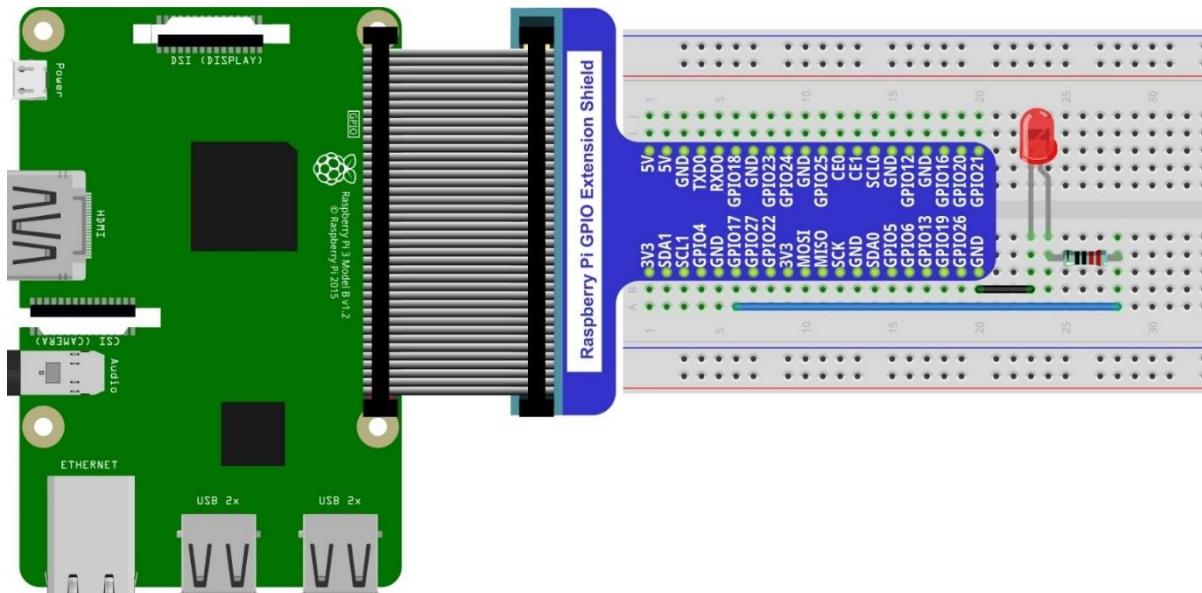
Raspberry Pi (with 40 GPIO) x1 GPIO Extension Board & Ribbon Cable x1 Breadboard x1	LED x1	Resistor 220Ω x1
Jumper M/M x2		

Circuit

Schematic diagram



Hardware connection. If you need any support, please feel free to contact us via: support@freenove.com



Building a WebIOPi Service Framework

The following is the key part of this chapter. The installation steps refer to WebIOPi official. And you also can directly refer to the official installation steps. The latest version (in 2016-6-27) of WebIOPi is 0.7.1. So, you may encounter some issues in using it. We will explain these issues and provide the solution in the following installation steps.

Here are the steps to build a WebIOPi:

Installation

1. Get the installation package. You can use the following command to obtain.

```
wget https://github.com/Freenove/WebIOPi/archive/master.zip -O WebIOPi.zip
```

2. Extract the package and generate a folder named "WebIOPi-master". Then enter the folder.

```
unzip WebIOPi.zip
```

```
cd WebIOPi-master/WebIOPi-0.7.1
```

3. Patch for Raspberry Pi B+, 2B, 3B, 3B+.

```
patch -p1 -i webiopi-pi2bplus.patch
```

4. Run setup.sh to start the installation, the process takes a while and you will need to be patient.

```
sudo ./setup.sh
```

5. If setup.sh does not have permission to execute, execute the following command

```
sudo sh ./setup.sh
```

Run

After the installation is completed, you can use the webiopi command to start running.

```
$ sudo webiopi [-h] [-c config] [-l log] [-s script] [-d] [port]
```

Options:

-h, --help	Display this help
-c, --config file	Load config from file
-l, --log file	Log to file
-s, --script file	Load script from file
-d, --debug	Enable DEBUG

Arguments:

port	Port to bind the HTTP Server
-------------	------------------------------

Run webiopi with verbose output and the default config file:

```
sudo webiopi -d -c /etc/webiopi/config
```

The Port is 8000 in default. Now WebIOPi has been launched. Keep it running.

Access WebIOPi over local network

Under the same network, use a mobile phone or PC browser to open your RPi IP address, and add a port number like 8000. For example, my personal Raspberry Pi IP address is 192.168.1.109. Then, in the browser, I then should input: <http://192.168.1.109:8000/>

Default user is "webiopi" and password is "raspberry".

Then, enter the main control interface:

WebIOPi Main Menu

GPIO Header

Control and Debug the Raspberry Pi GPIO with a display which looks like the physical header.

GPIO List

Control and Debug the Raspberry Pi GPIO ordered in a single column.

Serial Monitor

Use the browser to play with Serial interfaces configured in WebIOPi.

Devices Monitor

Control and Debug devices and circuits wired to your Pi and configured in WebIOPi.

Click on GPIO Header to enter the GPIO control interface.

	3.3V	1	2	5.0V	
	I2C SDA	3	4	5.0V	
	I2C SCL	5	6	GROUND	
	ONEWIRE	7	8	UART TX	
	GROUND	9	10	UART RX	
OUT	GPIO 17	11	12	GPIO 18	IN
IN	GPIO 27	13	14	GROUND	
IN	GPIO 22	15	16	GPIO 23	IN
	3.3V	17	18	GPIO 24	IN
ALTO	GPIO 10	19	20	GROUND	
ALTO	GPIO 9	21	22	GPIO 25	IN
ALTO	GPIO 11	23	24	GPIO 8	OUT
	GROUND	25	26	GPIO 7	OUT
	--	27	28	--	
IN	GPIO 5	29	30	GROUND	
IN	GPIO 6	31	32	GPIO 12	IN
IN	GPIO 13	33	34	GROUND	
IN	GPIO 19	35	36	GPIO 16	IN
IN	GPIO 26	37	38	GPIO 20	IN
	GROUND	39	40	GPIO 21	IN



Control methods:

- Click/Tap the OUT/IN button to change GPIO direction.
- Click/Tap pins to change the GPIO output state.

Completed

According to the circuit we build, set GPIO17 to OUT, then click Header11 to control the LED.

You can end the webioPi in the terminal by “Ctr+C”.

About WebIOPi

Note: If you have a Raspberry Pi 4B, you may have some trouble. We are currently working to complete the WebIOPi for adaptation to a Raspberry Pi 4B as soon as possible, and will issue updates ASAP.

The reason for changing the file in the configuration process is that the newer generation models of the RPi CPUs are different from the older ones. These issues may arise during some projects.

WebIOPi has not provided a corresponding installation package for the latest RPi Models in timely fashion. Therefore, there are two configuration options and some “bugs” may exist, which could cause some functionality problems with WebIOPi project. We have requested the author of WebIOPi to provide a complete set of the latest version of installation package for RPi. However, at this writing there is nothing more that we can provide you. Please note that WebIOPi can achieve far more than we can demonstrate at this time, so we look forward to learning and exploring this functionality with many fun aspects in the future when there is more up to date installation package available.

What's Next?

THANK YOU for participating in this learning experience! If you have completed all of the projects successfully you can consider yourself a Raspberry Pi Master.

We have reached the end of this Tutorial. If you find errors, omissions or you have suggestions and/or questions about the Tutorial or component contents of this Kit, please feel free to contact us:
support@freenove.com

We will make every effort to make changes and correct errors as soon as feasibly possible and publish a revised version.

If you are interesting in processing, you can study the Processing.pdf in the unzipped folder.

If you want to learn more about Arduino, Raspberry Pi, Smart Cars, Robotics and other interesting products in science and technology, please continue to visit our website. We will continue to launch fun, cost-effective, innovative and exciting products.

<http://www.freenove.com/>

Thank you again for choosing Freenove products.