

# Welcome

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## How to Start

When reading this, you should have downloaded the ZIP file for this product.

Unzip it and you will get a folder containing tutorials and related files. Please start with this PDF tutorial.

- ! Unzip the ZIP file instead of opening the file in the ZIP file directly.
- ! Do not move, delete or rename files in the folder just unzipped.

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Encounter problems? Don't worry! Refer to "TroubleShooting.pdf" or contact us.

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## Attention

Pay attention to safety when using and storing this product:

- This product is not suitable for children under 12 years of age because of small parts and sharp parts.
- Minors should use this product under the supervision and guidance of adults.
- This product contains small and sharp parts. Do not swallow, prick and scratch to avoid injury.
- This product contains conductive parts. Do not hold them to touch power supply and other circuits.
- To avoid personal injury, do not touch parts rotating or moving while working.
- The wrong operation may cause overheat. Do not touch and disconnect the power supply immediately.
- Operate in accordance with the requirements of the tutorial. Fail to do so may damage the parts.
- Store this product in a dry and dark environment. Keep away from children.
- Turn off the power of the circuit before leaving.

Any concerns?  [support@freenove.com](mailto:support@freenove.com)

## About

Freenove provides open source electronic products and services.

Freenove is committed to helping customers learn programming and electronic knowledge, quickly implement product prototypes, realize their creativity and launch innovative products. Our services include:

- Kits for learning programming and electronics
- Kits compatible with Arduino®, Raspberry Pi®, micro:bit®, ESP32®, etc.
- Kits for robots, smart cars, drones, etc.
- Components, modules and tools
- Design and customization

To learn more about us or get our latest information, please visit our website:

<http://www.freenove.com>

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# Prepare

ESP32 is a micro control unit with integrated Wi-Fi launched by Espressif, which features strong properties and integrates rich peripherals. It can be designed and studied as an ordinary Single Chip Microcontroller(SCM) chip, or connected to the Internet and used as an Internet of Things device.

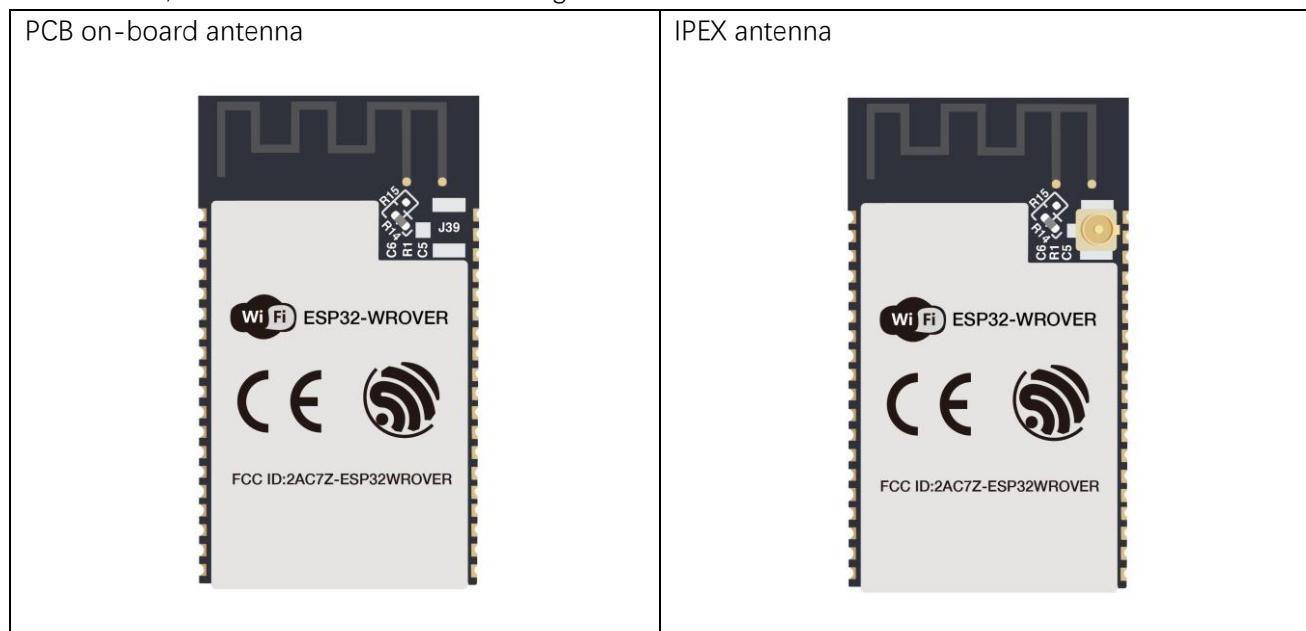
ESP32 can be developed both either with C/C++ language or micropython language. In this tutorial, we use micropython. With Micropython is as easy to learn as Python with little code, making it ideal for beginners. Moreover, the code of ESP32 is completely open-source, so beginners can quickly learn how to develop and design IOT smart household products including smart curtains, fans, lamps and clocks.

We divide each project into four parts, namely Component List, Component Knowledge, Circuit and Code. Component List helps you to prepare material for the experiment more quickly. Component Knowledge allows you to quickly understand new electronic modules or components, while Circuit helps you understand the operating principle of the circuit. And Code allows you to easily master the use of ESP32 and its accessory kit. After finishing all the projects in this tutorial, you can also use these components and modules to make products such as smart household, smart cars and robots to transform your creative ideas into prototypes and new and innovative products.

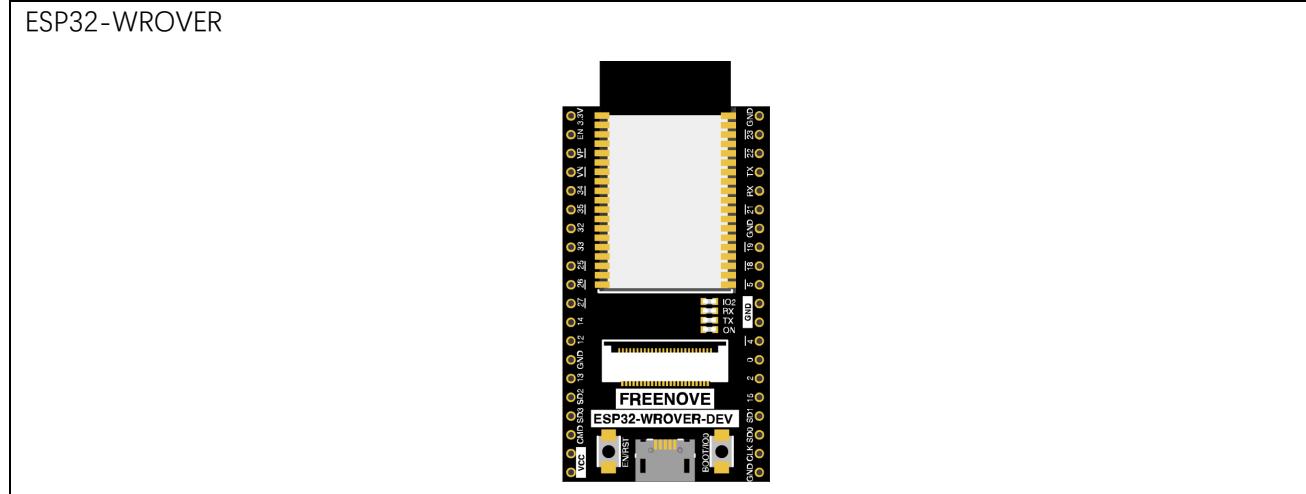
In addition, if you have any difficulties or questions with this tutorial or toolkit, feel free to ask for our quick and free technical support through [support@freenove.com](mailto:support@freenove.com)

## ESP32-WROVER

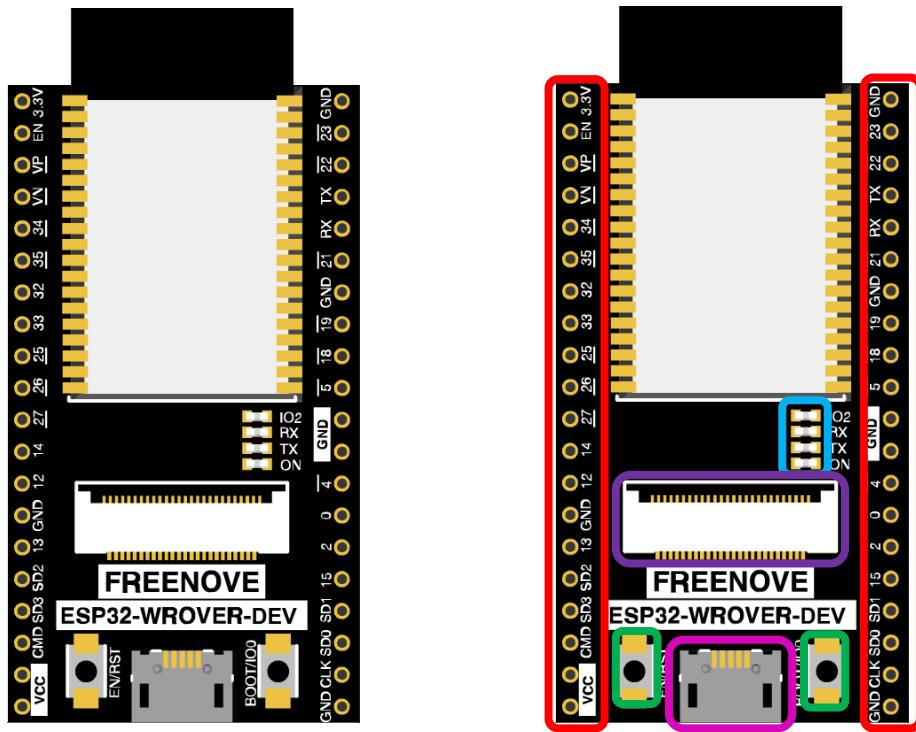
ESP32-WROVER has launched a total of two antenna packages, PCB on-board antenna and IPEX antenna respectively. The PCB on-board antenna is an integrated antenna in the chip module itself, so it is convenient to carry and design. The IPEX antenna is a metal antenna derived from the integrated antenna of the chip module itself, which is used to enhance the signal of the module.



In this tutorial, the ESP32-WROVER is designed based on the PCB on-board antenna package.



The hardware interfaces of ESP32-WROVER are distributed as follows:



Compare the left and right images. We've boxed off the resources on the ESP32-WROVER in different colors to facilitate your understanding of the ESP32-WROVER.

| Box color | Corresponding resources introduction            |
|-----------|---|
|           | <b>GPIO pin</b>                                 |
|           | <b>LED indicator</b>                            |
|           | <b>Camera interface</b>                         |
|           | <b>Reset button, Boot mode selection button</b> |
|           | <b>USB port</b>                                 |

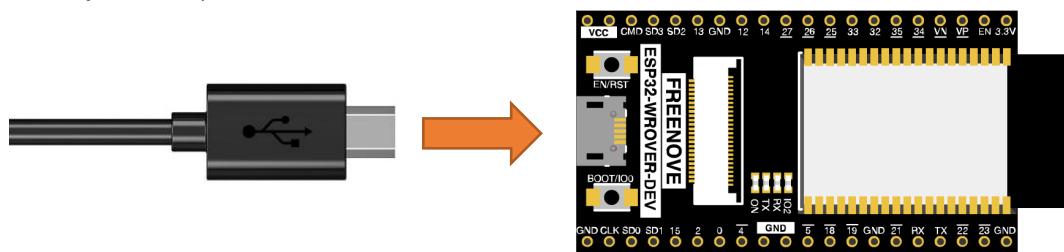
## 0.3 Installing CH340 (Important)

ESP32 uses CH340 to download codes. So before using it, we need to install CH340 driver in our computers.

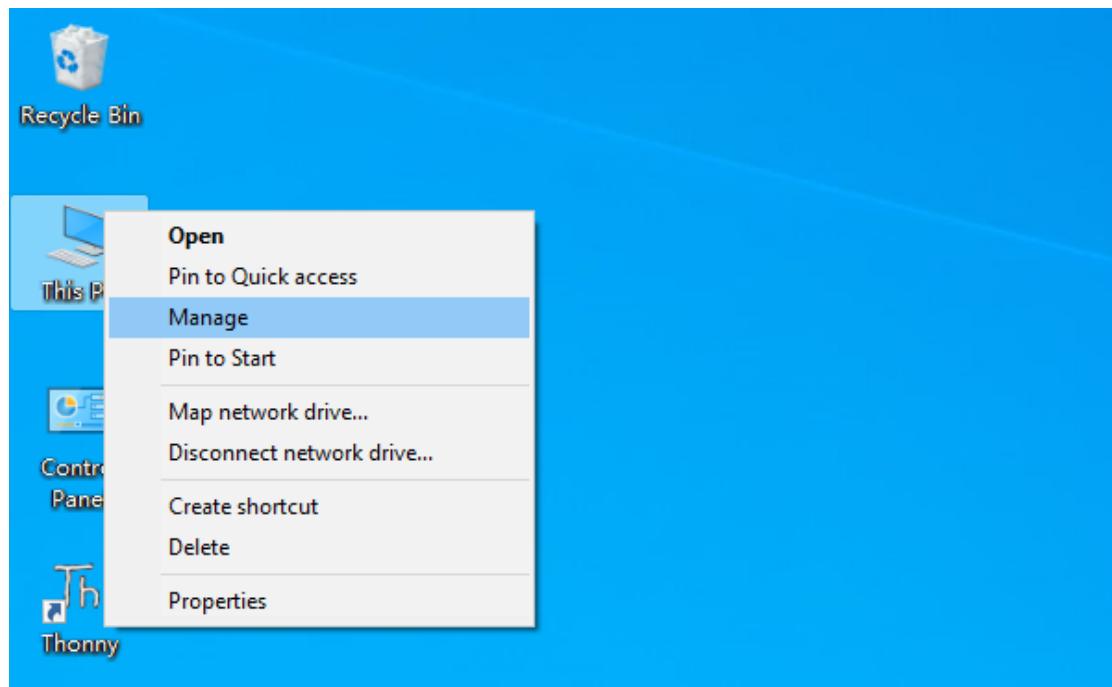
### Windows

Check whether CH340 has been installed

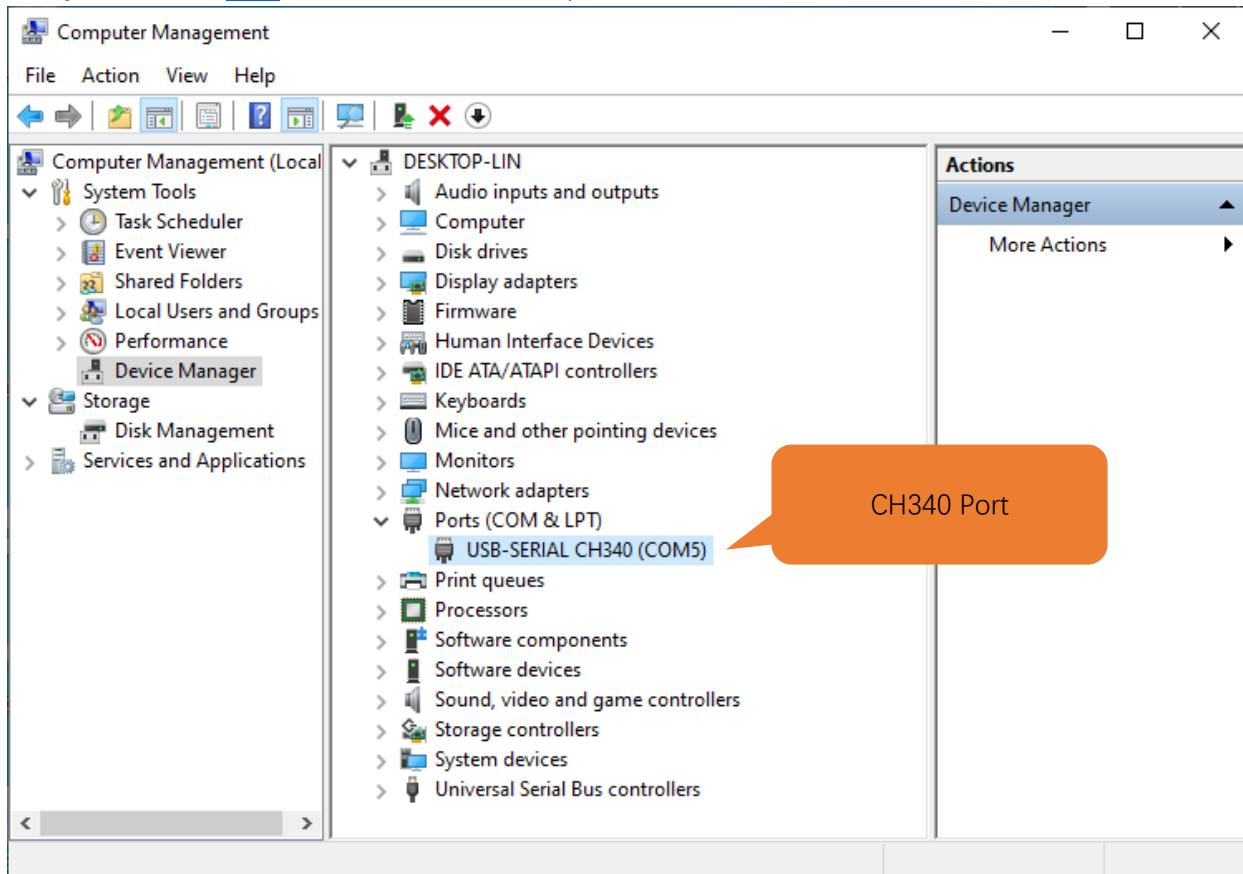
1. Connect your computer and ESP32 with a USB cable.



2. Turn to the main interface of your computer, select “This PC” and right-click to select “Manage”.



3. Click “Device Manager”. If your computer has installed CH340, you can see “USB-SERIAL CH340 (COMx)”. And you can click [here](#) to move to the next step.



## Installing CH340

- First, download CH340 driver, click <http://www.wch-ic.com/search?q=CH340&t=downloads> to download the appropriate one based on your operating system.

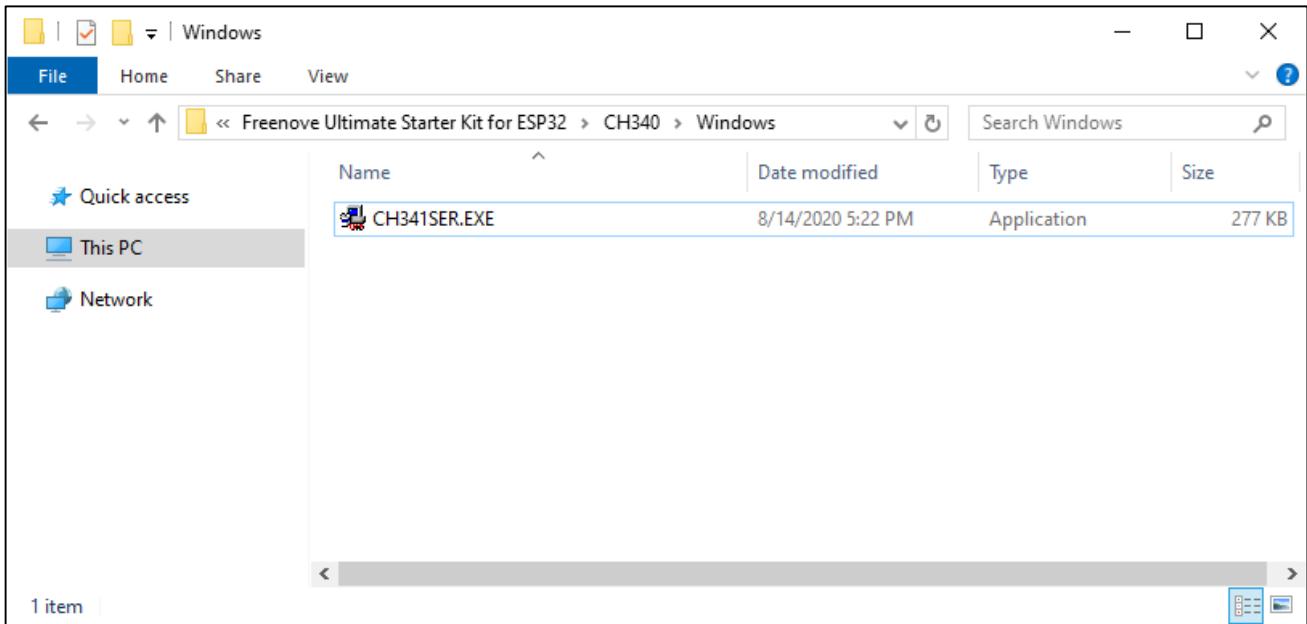
The screenshot shows a search results page for 'CH340' on a website. The left sidebar has categories: All (14), Downloads (7) [highlighted in blue], Products (4), Application (2), Video (1), and News (0). The main area is titled 'keyword CH340' and shows 'Downloads( 7 )'. A table lists the files:

| file category       | file content  | version | upload time |
|---------------------|---|---------|-------------|
| Driver&Tools        | <b>Windows</b>  |         |             |
| CH341SER.EXE        | CH340/CH341 USB to serial port Windows driver, supports 32/64-bit Windows 10/8.1/8/7/VISTA/XP, Server 2016/2012/2008/2003, 2000/ME/98   | 3.5     | 2019-03-18  |
| CH341SER.ZIP        | CH340/CH341 USB to serial port Windows driver, includes DLL dynamic library and non-standard baud rate settings and other instructions. Supports 32/64-bit Windows 10/8.1/8/7/VISTA/XP, Server 2016/2012/2008/2003, 2000/ME/98  | 3.5     | 2019-03-05  |
| CH341SER_ANDROID... | CH340/CH341 USB to serial port Android free drive application library, for Android OS 3.1 and above version which supports USB Host mode already, no need to load Android kernel driver, no root privileges. Contains apk, lib library file (Linux Driver), App Demo Example (USB to UART Device) | 1.6     | 2019-04-19  |
| CH341SER_LINUX...   | CH340/CH341 USB to serial port LINUX driver   | 1.5     | 2018-03-18  |
| CH341SER_MAC.ZI...  | CH340/CH341 USB to serial port MAC OS driver  | 1.5     | 2018-07-05  |
| Others              |   |         |             |
| PRODUCT_GUIDE.P...  | Electronic selection of product selection manual, please refer to related product technical manual for more technical information.  | 1.4     | 2018-12-29  |
| InstallNoteOn64...  | Instructions for the driver after 18 years of August cannot be installed under some 64-bit WIN7 (English)   | 1.0     | 2019-01-10  |

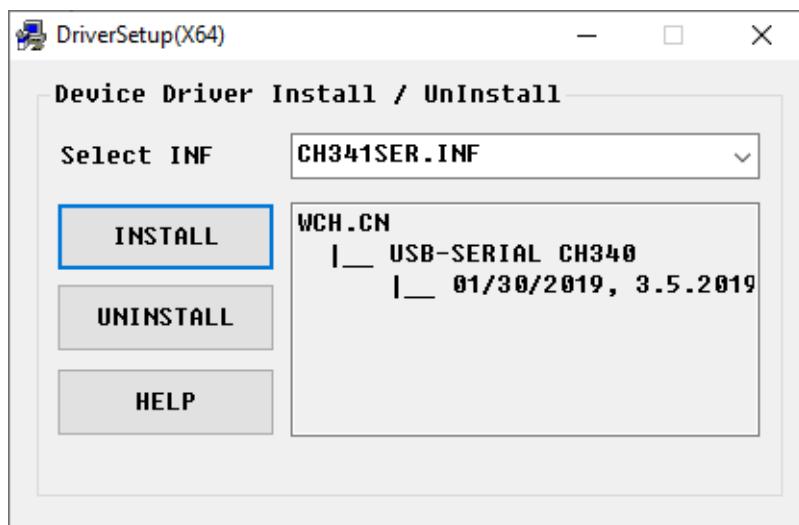
You can also open “Freenove\_ESP32\_WROVER\_Board/CH340”, we have prepared the installation package.

| Name    | Date modified     | Type        | Size |
|---------|-------------------|-------------|------|
| Linux   | 8/14/2020 5:24 PM | File folder |      |
| MAC     | 8/14/2020 5:23 PM | File folder |      |
| Windows | 8/14/2020 5:23 PM | File folder |      |

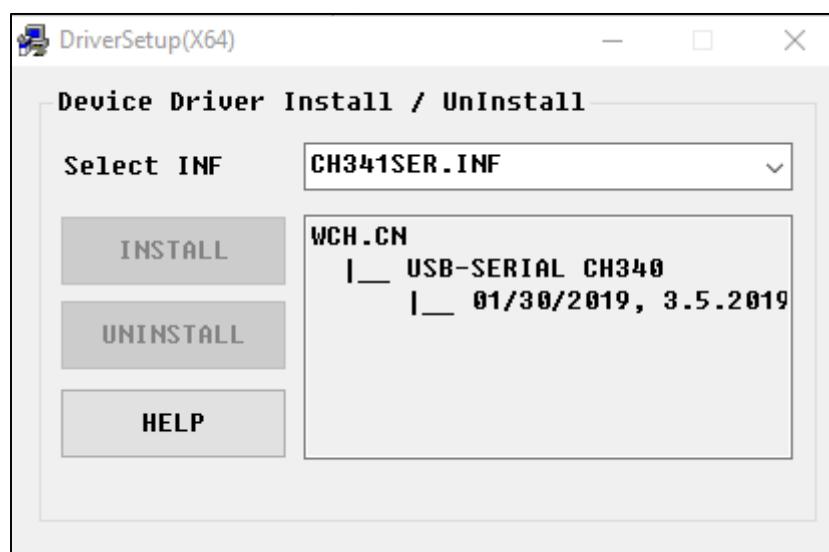
2. Open the folder “Freenove\_ESP32\_WROVER\_Board/CH340/Windows/ch341ser”



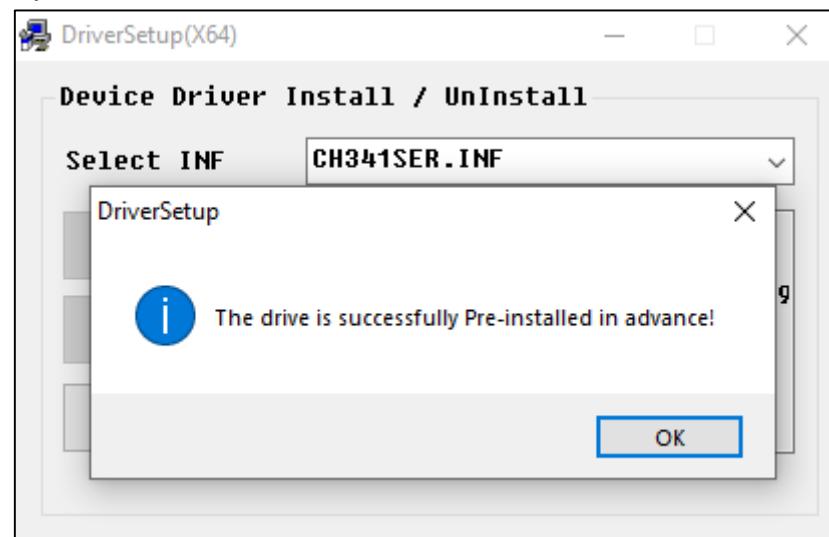
3. Double click “CH341SER.EXE”.



4. Click “INSTALL” and wait for the installation to complete.

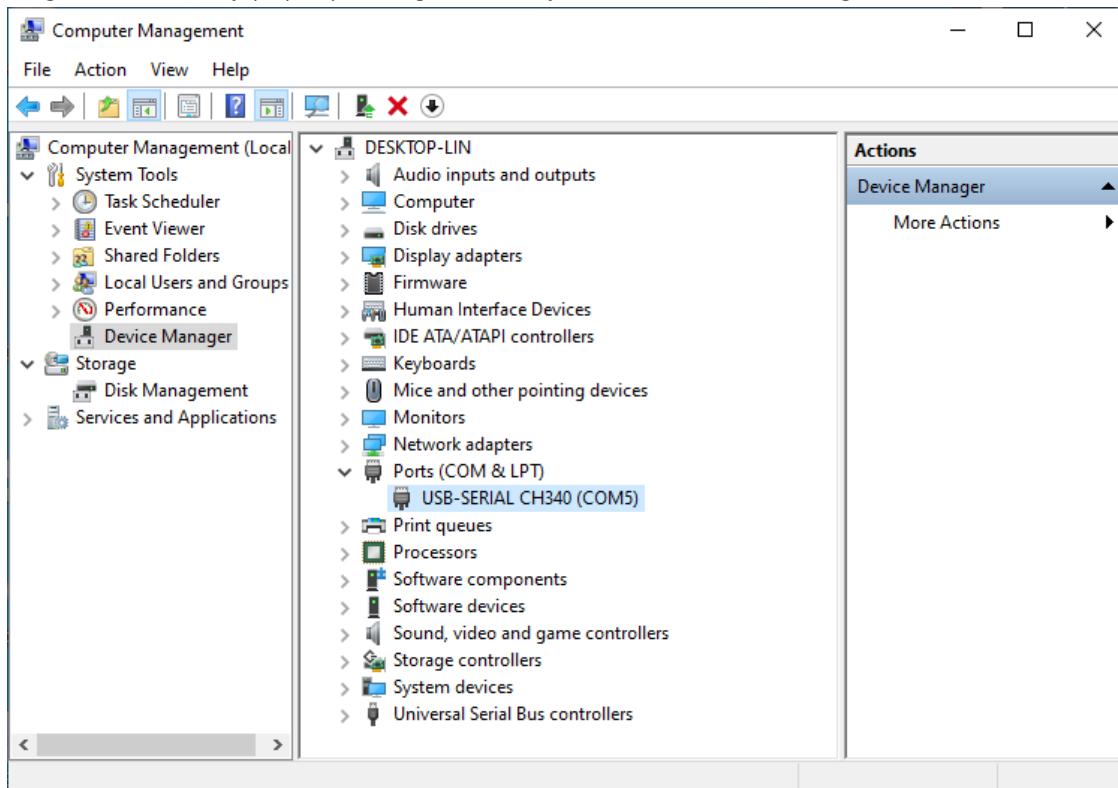


5. Install successfully. Close all interfaces.





6. When ESP32 is connected to computer, select "This PC", right-click to select "Manage" and click "Device Manager" in the newly pop-up dialog box, and you can see the following interface.



7. So far, CH340 has been installed successfully. Close all dialog boxes.

## MAC

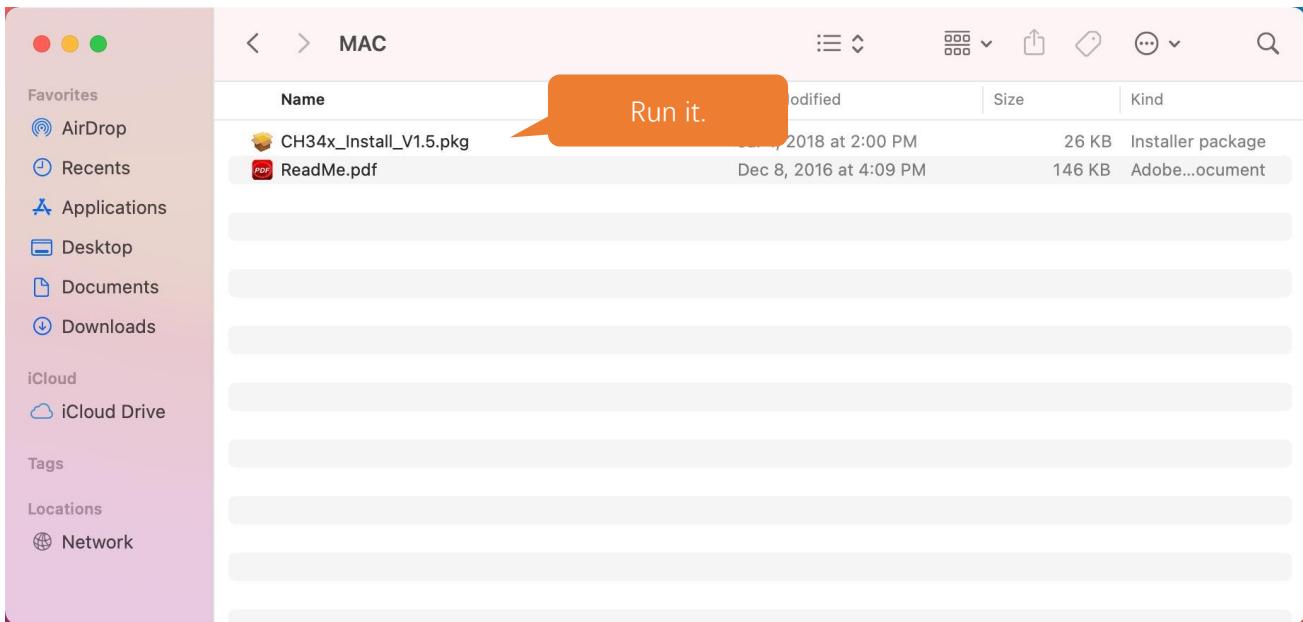
First, download CH340 driver, click <http://www.wch-ic.com/search?q=CH340&t=downloads> to download the appropriate one based on your operating system.

The screenshot shows a search results page for 'ch340' on the WCH website. The left sidebar has categories: All (14), Downloads (7), Products (4), Application (2), Video (1), and News (0). The main area shows a search bar with 'keyword ch340' and a table of results under 'Downloads( 7 )'. The table columns are file category, file content, version, and upload time. Three specific files are highlighted with orange callouts: 'CH341SER.EXE' is labeled 'Windows', 'CH341SER\_LINUX...' is labeled 'Linux', and 'CH341SER\_MAC.ZIP' is labeled 'MAC'.

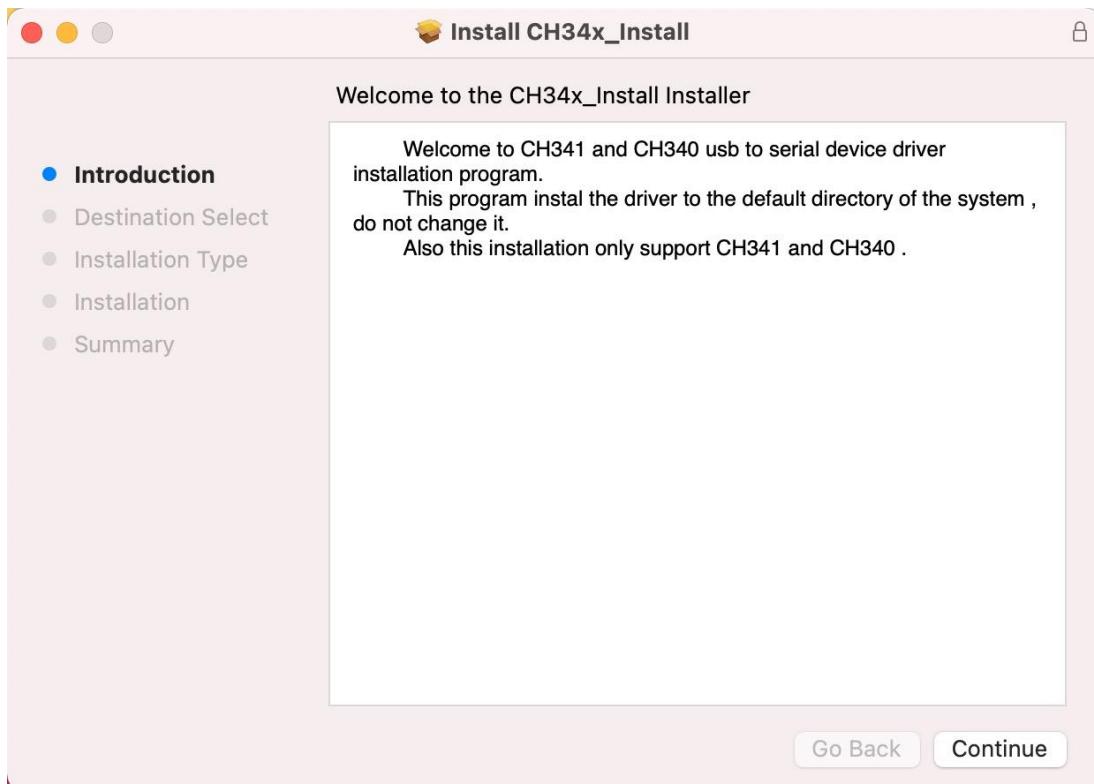
| file category                       | file content   | version | upload time |
|-------------------------------------|--|---------|-------------|
| Driver&Tools                        |  |         |             |
| <a href="#">CH341SER.EXE</a>        | CH340/CH341 USB to serial port Windows driver, supports 32/64-bit Windows 10/8.1/8/7/VISTA/XP, Server 2016/2012/2008/2003, 2000/ME/98  | 3.5     | 2019-03-18  |
| <a href="#">CH341SER.ZIP</a>        | CH340/CH341 USB to serial port Windows driver, includes DLL dynamic library and non-standard baud rate settings and other instructions. Supports 32/64-bit Windows 10/8.1/8/7/VISTA/XP, Server 2016/2012/2008/2003, 2000/ME/98   | 3.5     | 2019-03-05  |
| <a href="#">CH341SER_ANDROID...</a> | CH340/CH341 USB to serial port Android free drive application library, for Android OS 3.1 and above version which supports USB Host mode already, no need to load Android kernel driver, no root privileges. Contains apk, lib library file (Java Driver), App Demo Examples, and CH340/CH341 USB to serial port Demo SDK. | 1.6     | 2019-04-19  |
| <a href="#">CH341SER_LINUX...</a>   | CH340/CH341 USB to serial port LINUX driver  | 1.5     | 2018-03-18  |
| <a href="#">CH341SER_MAC.ZI...</a>  | CH340/CH341 USB to serial port MAC OS driver   | 1.5     | 2018-07-05  |
| Others                              |  |         |             |

If you would not like to download the installation package, you can open "Freenove\_ESP32\_WROVER\_Board/CH340", we have prepared the installation package.

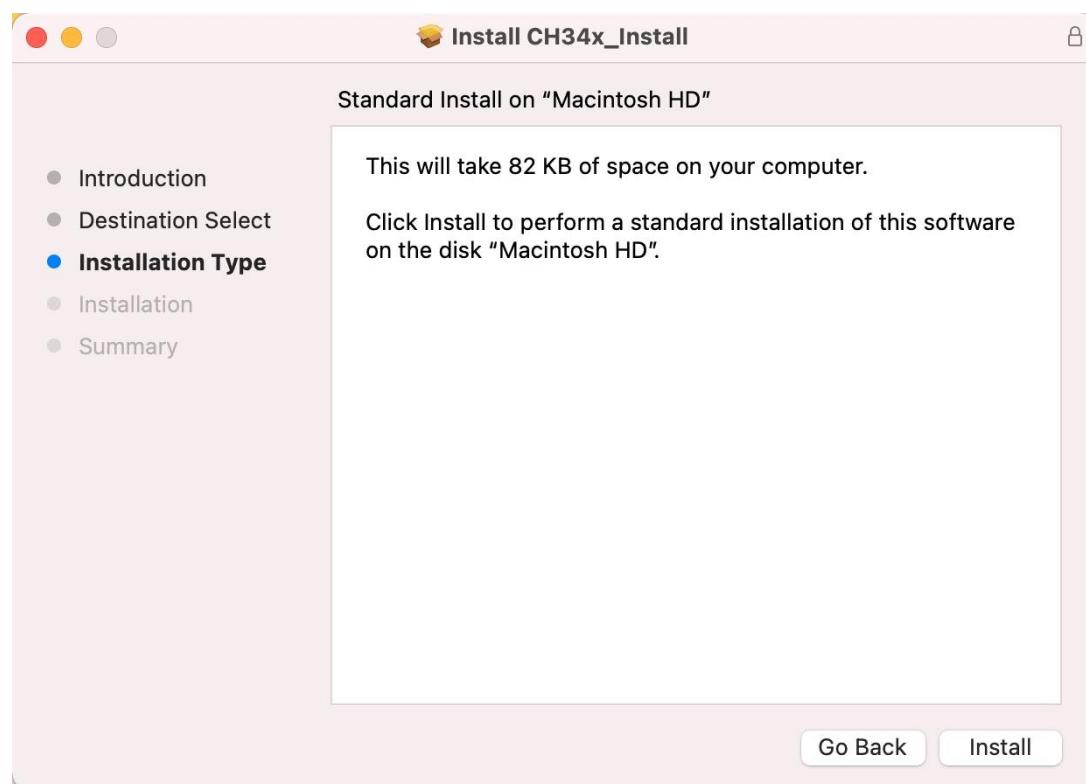
Second, open the folder "Freenove\_ESP32\_WROVER\_Board/CH340/MAC/"



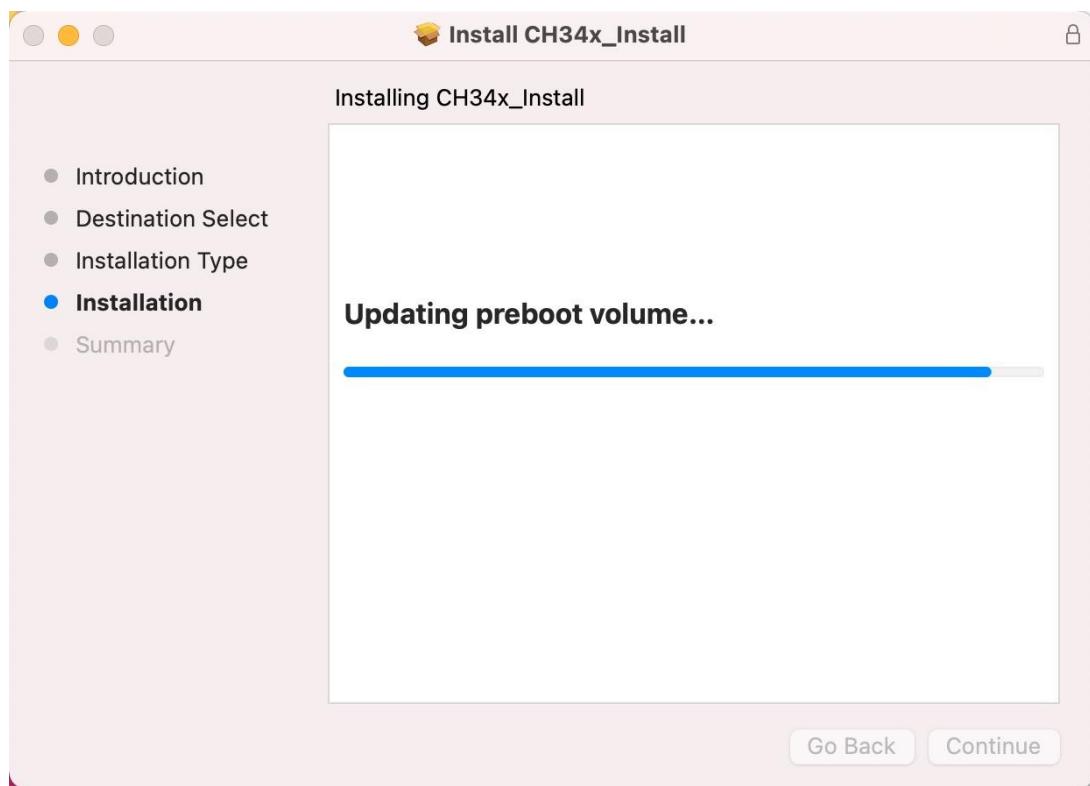
Third, click Continue.



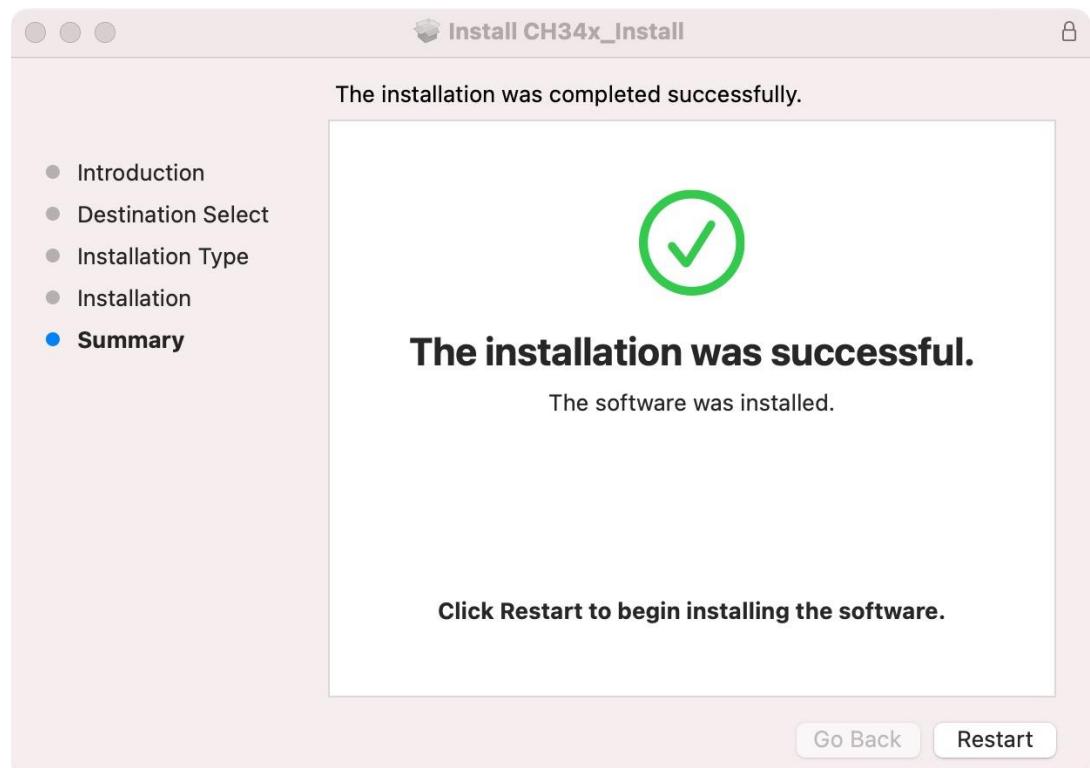
Fourth, click Install.



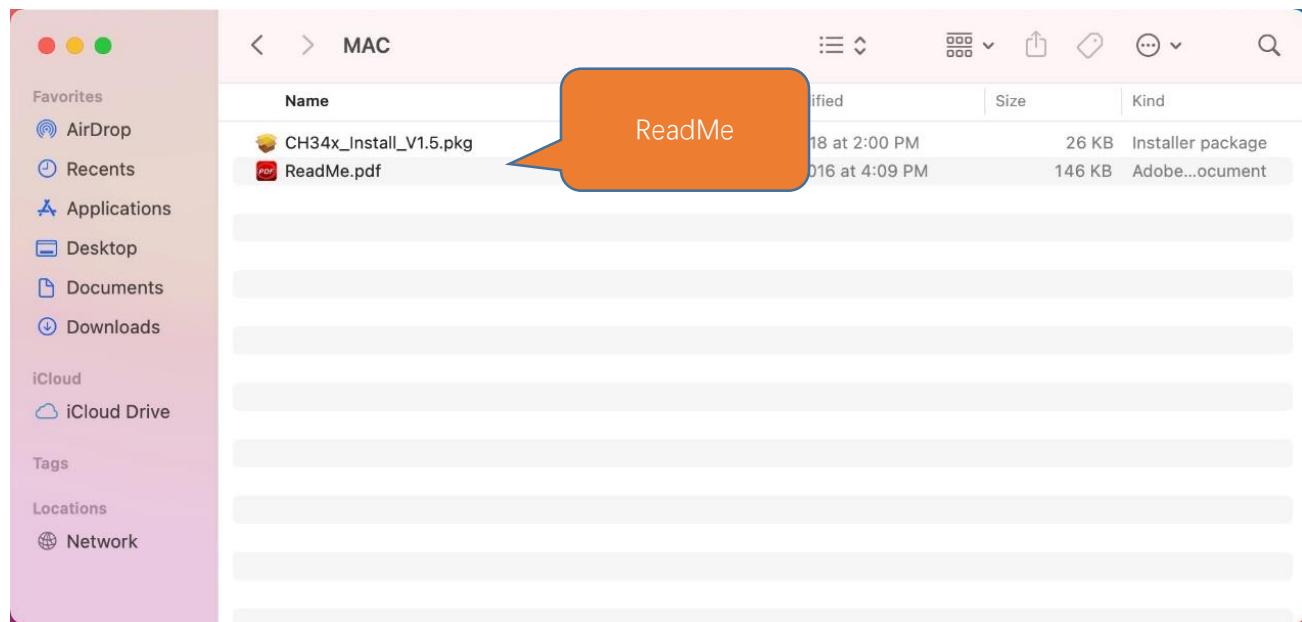
Then, waiting Finsh.



Finally, restart your PC.



If you still haven't installed the CH340 by following the steps above, you can view `readme.pdf` to install it.





## 0.4 Burning Micropython Firmware (Important)

To run Python programs on ESP32, we need to burn a firmware to ESP32 first.

### Downloading Micropython Firmware

Official website of microPython: <http://micropython.org/>

Webpage listing firmware of microPython for ESP32: <https://micropython.org/download/esp32spiram/>

#### Firmware

##### Releases

**v1.18 (2022-01-17) .bin [.elf] [.map] [Release notes] (latest)**

v1.17 (2021-09-02) .bin [.elf] [.map] [Release notes]

v1.16 (2021-06-23) .bin [.elf] [.map] [Release notes]

v1.15 (2021-04-18) .bin [.elf] [.map] [Release notes]

v1.14 (2021-02-02) .bin [.elf] [.map] [Release notes]

v1.13 (2020-09-02) .bin [.elf] [.map] [Release notes]

v1.12 (2019-12-20) .bin [.elf] [.map] [Release notes]

##### Nightly builds

v1.18-382-g014912daa (2022-04-27) .bin [.elf] [.map]

v1.18-377-geb9674822 (2022-04-26) .bin [.elf] [.map]

v1.18-370-g28e7e15c0 (2022-04-22) .bin [.elf] [.map]

v1.18-366-gef1c2cdab (2022-04-21) .bin [.elf] [.map]

#### Firmware (Compiled with IDF 3.x)

##### Releases

**v1.14 (2021-02-02) .bin [.elf] [.map] [Release notes] (latest)**

v1.13 (2020-09-02) .bin [.elf] [.map] [Release notes]

v1.12 (2019-12-20) .bin [.elf] [.map] [Release notes]

v1.11 (2019-05-29) .bin [.elf] [.map] [Release notes]

v1.10 (2019-01-25) .bin [.elf] [.map] [Release notes]

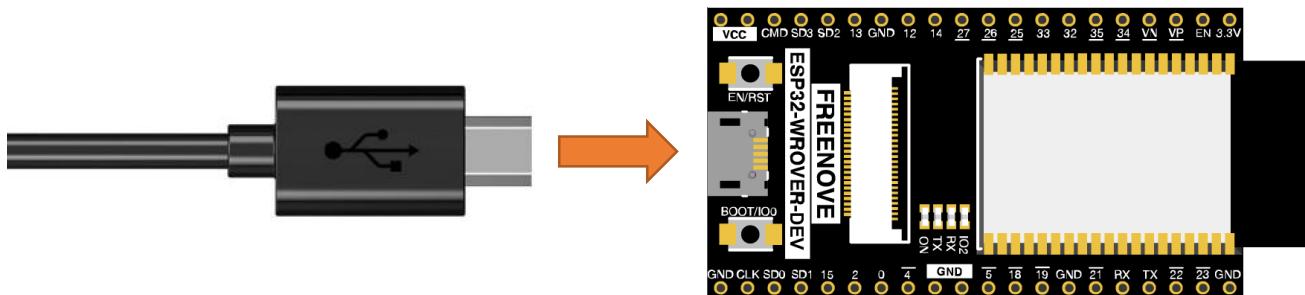
v1.9.4 (2018-05-11) .bin [.elf] [.map] [Release notes]

Firmware used in this tutorial is **esp32spiram-20220117-v1.18.bin**

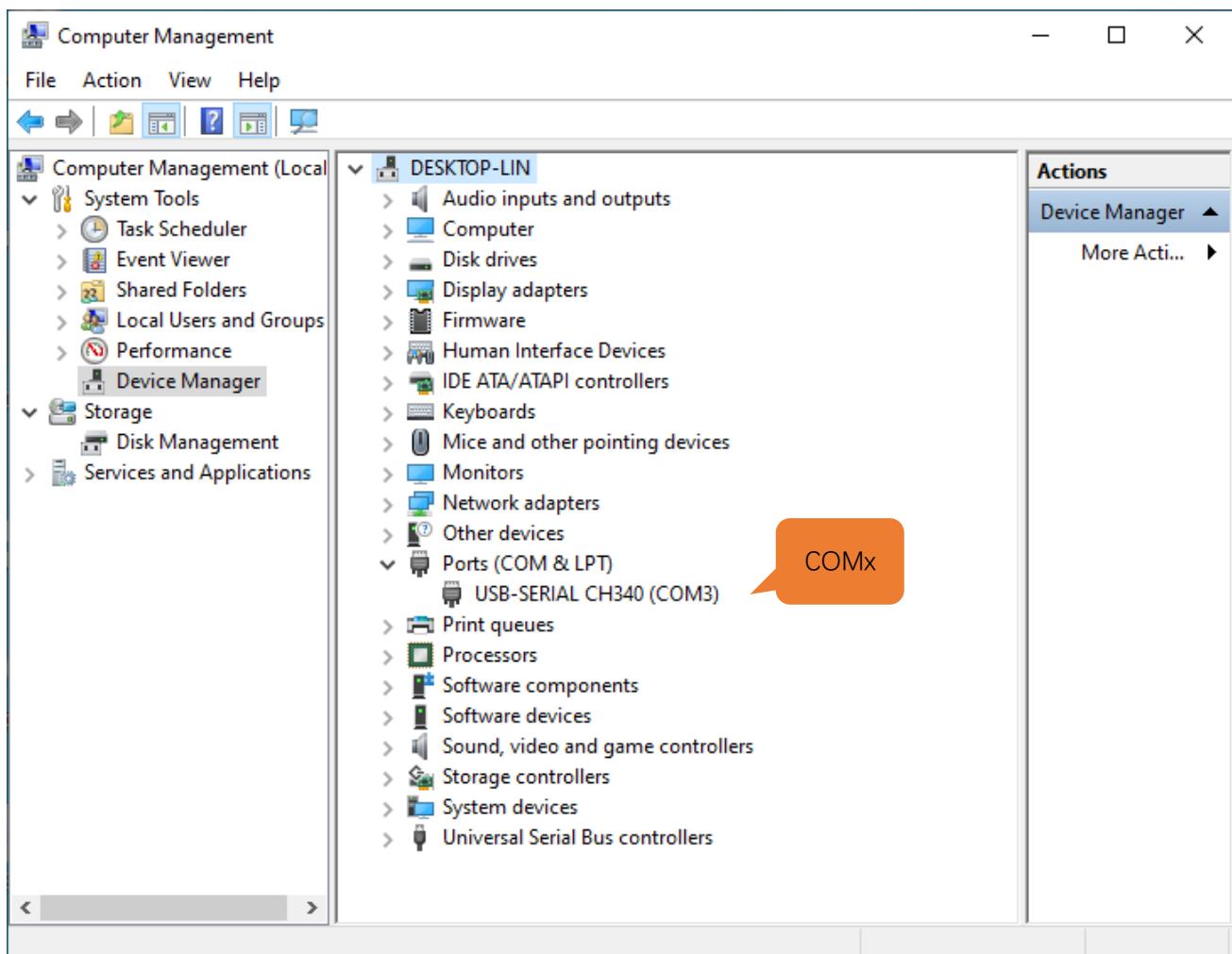
This file is also provided in our data folder "**Freenove\_ESP32\_WROVER\_Board /Python/Python\_Firmware**".

# Burning a Micropython Firmware

Connect your computer and ESP32 with a USB cable.

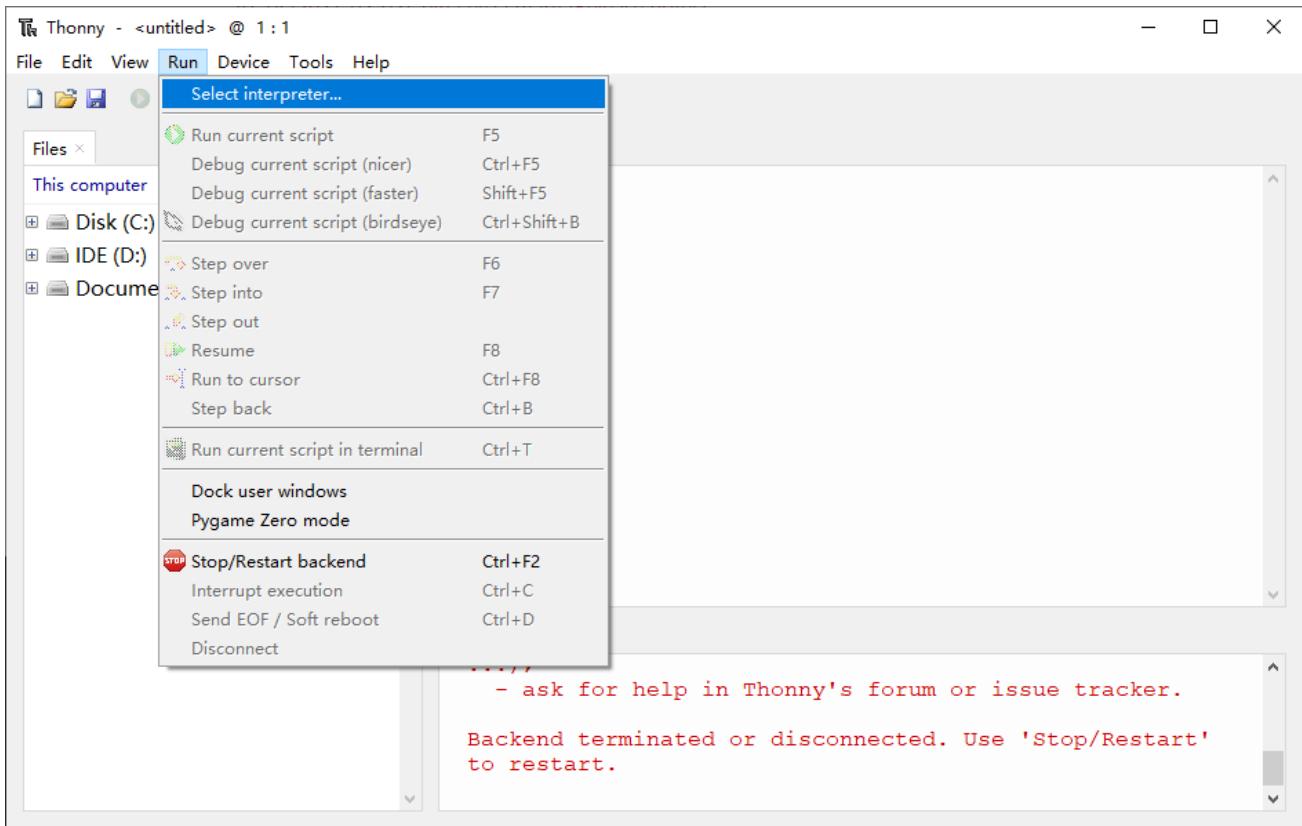


Make sure that the driver has been installed successfully and that it can recognize COM port correctly. Open device manager and expand "Ports".

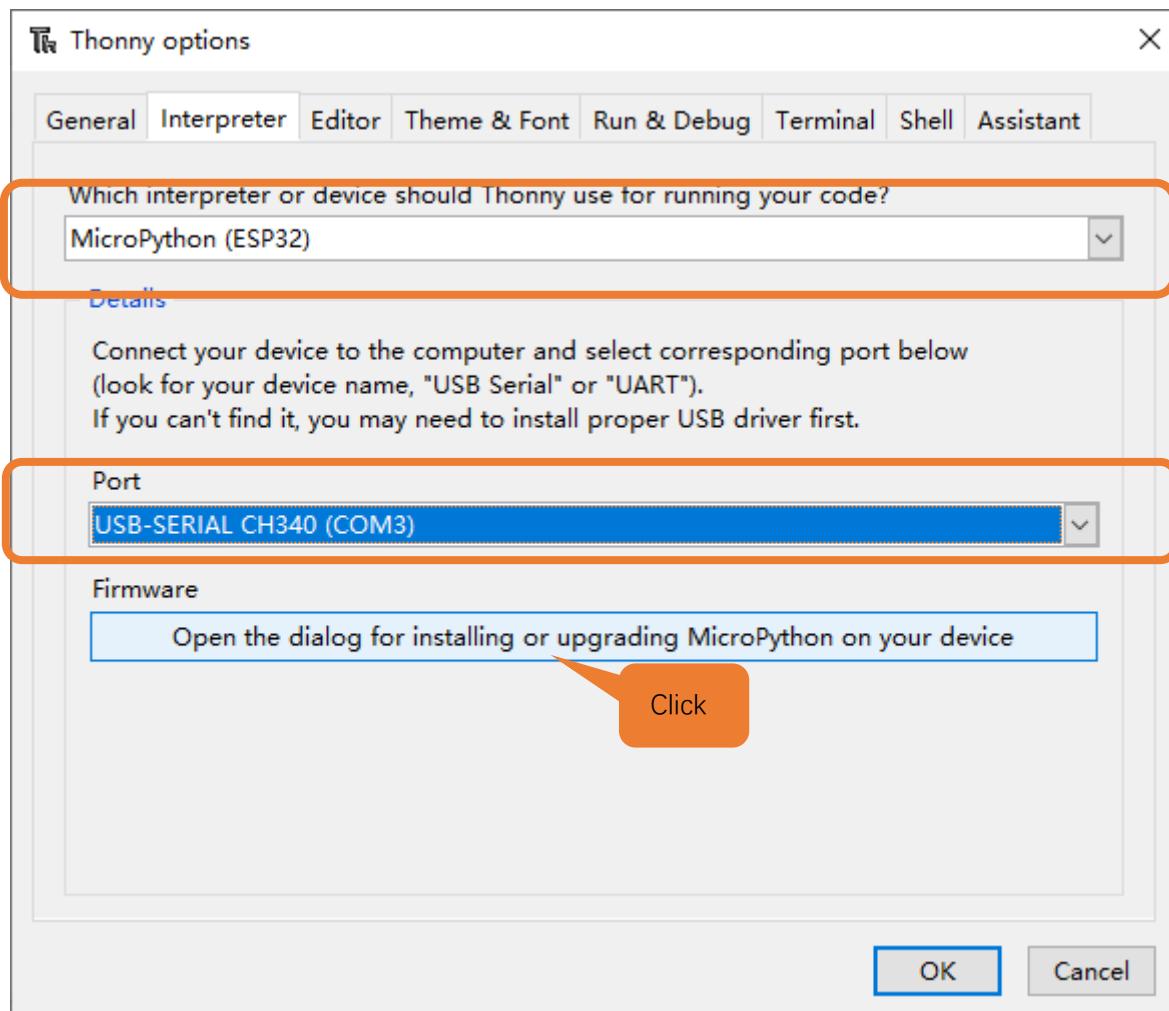


Note: the port of different people may be different, which is a normal situation.

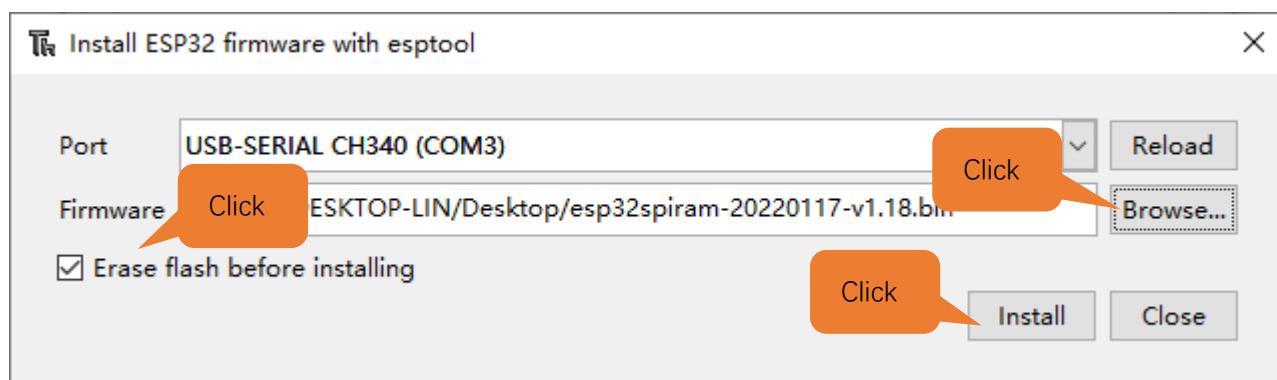
1. Open Thonny, click "run" and select "Select interpreter..."



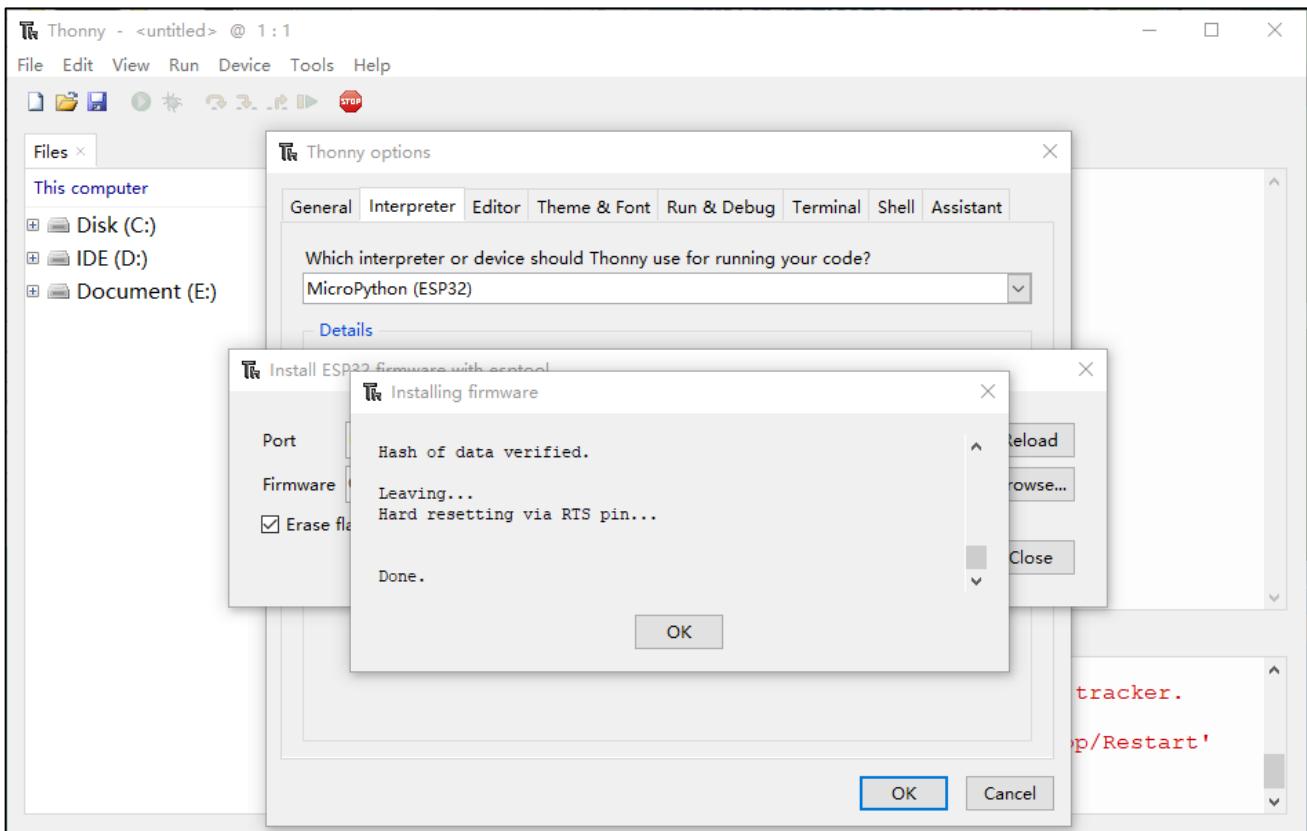
2. Select “Micropython (ESP32)”, select “USB-SERIAL CH340 (COM4)”, and then click the long button under “Firmware”.



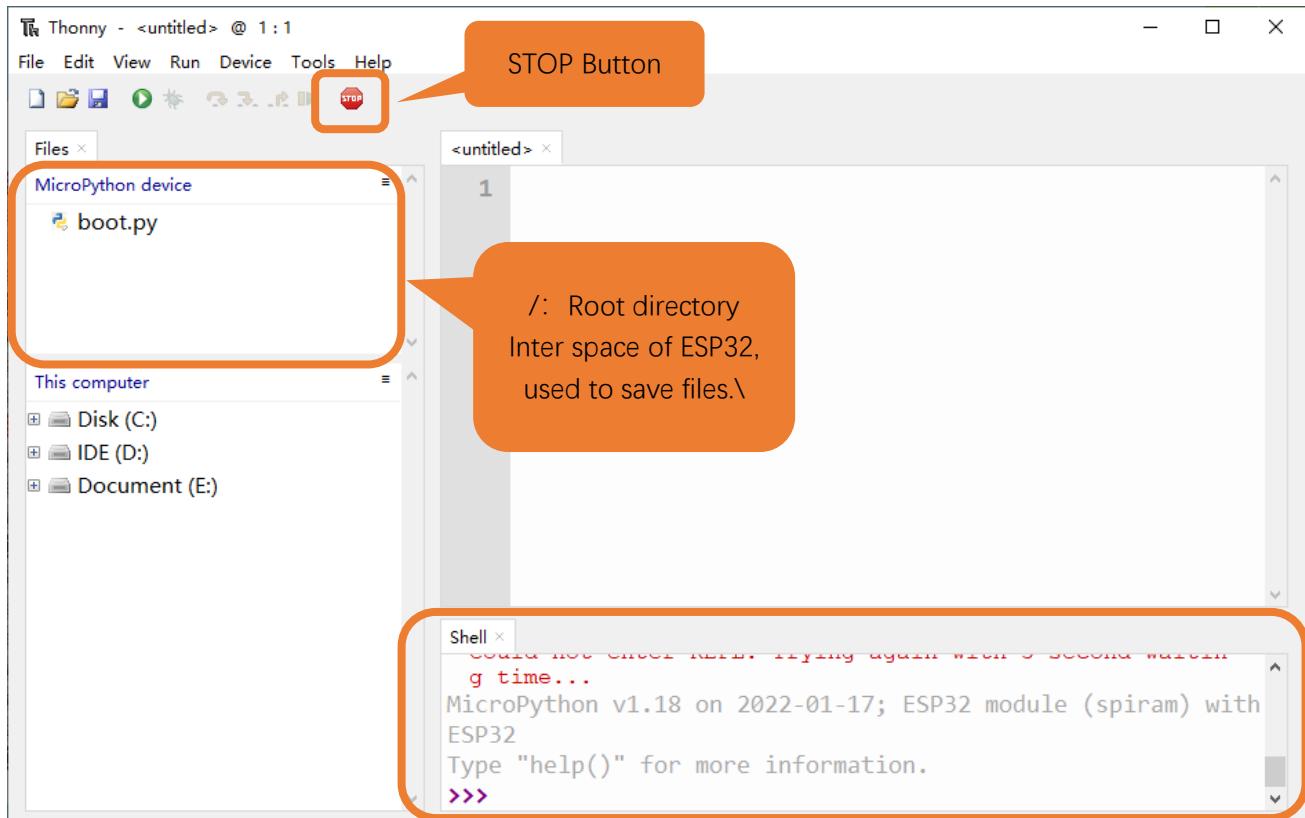
3. The following dialog box pops up. Select “USB-SERIAL CH340 (COM3)” for “Port” and then click “Browse...”. Select the previous prepared microPython firmware “**esp32spiram-20220117-v1.18.bin**”. Check “Erase flash before installing” and click “install” to wait for the prompt of finishing installation.



4. Wait for the installation to be done.



5. Close all dialog boxes, turn to main interface and click “STOP”. As shown in the illustration below



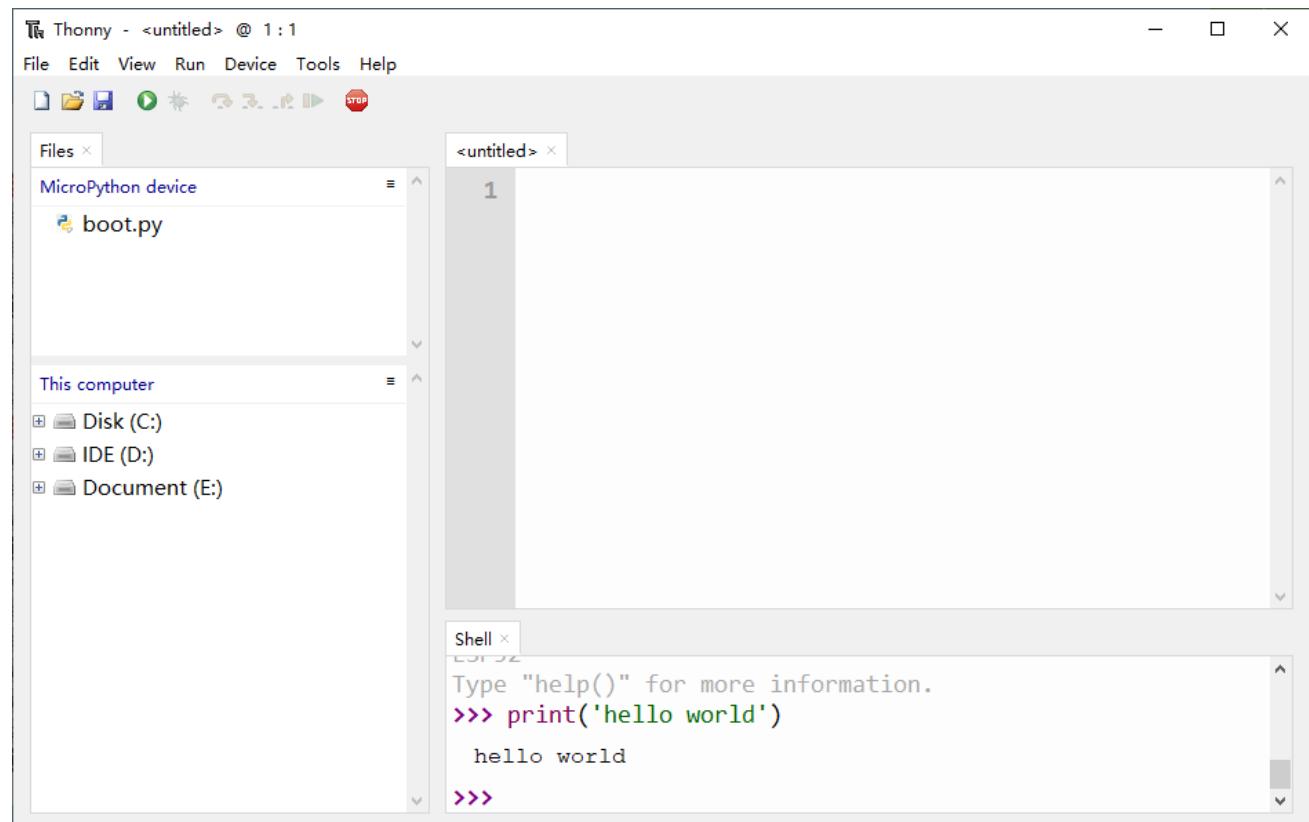
6. So far, all the preparations have been made.

Any concerns? ✉ support@freenove.com

## 0.5 Testing codes (Important)

### Testing Shell Command

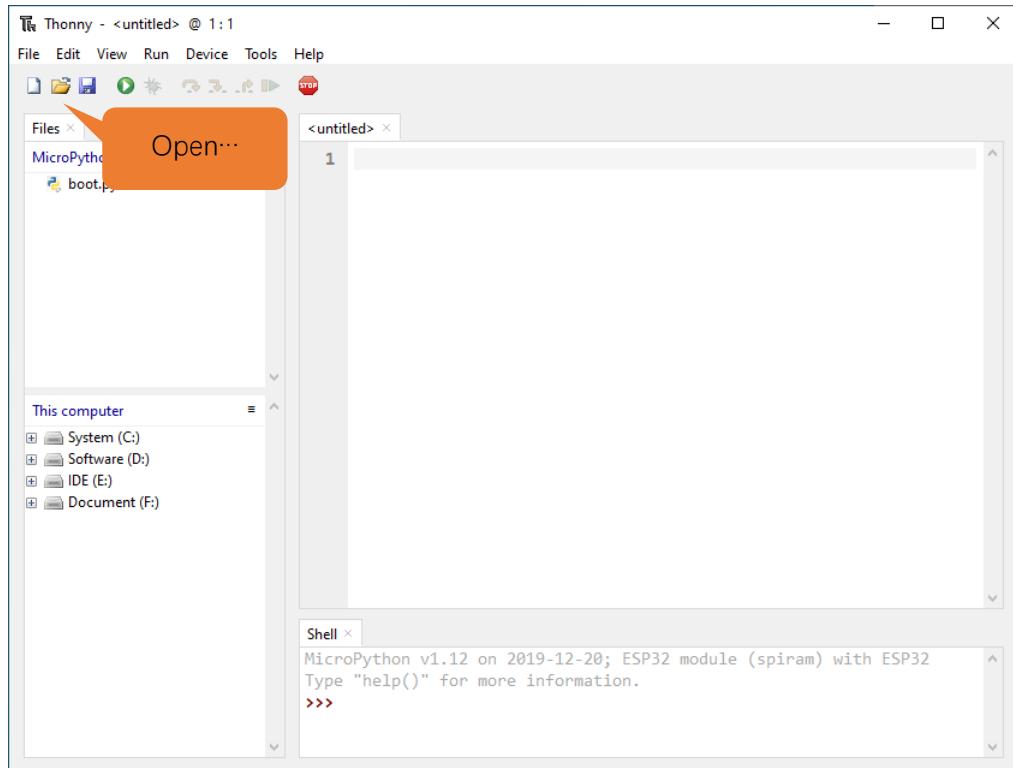
Enter "print('hello world')" in "Shell" and press Enter.



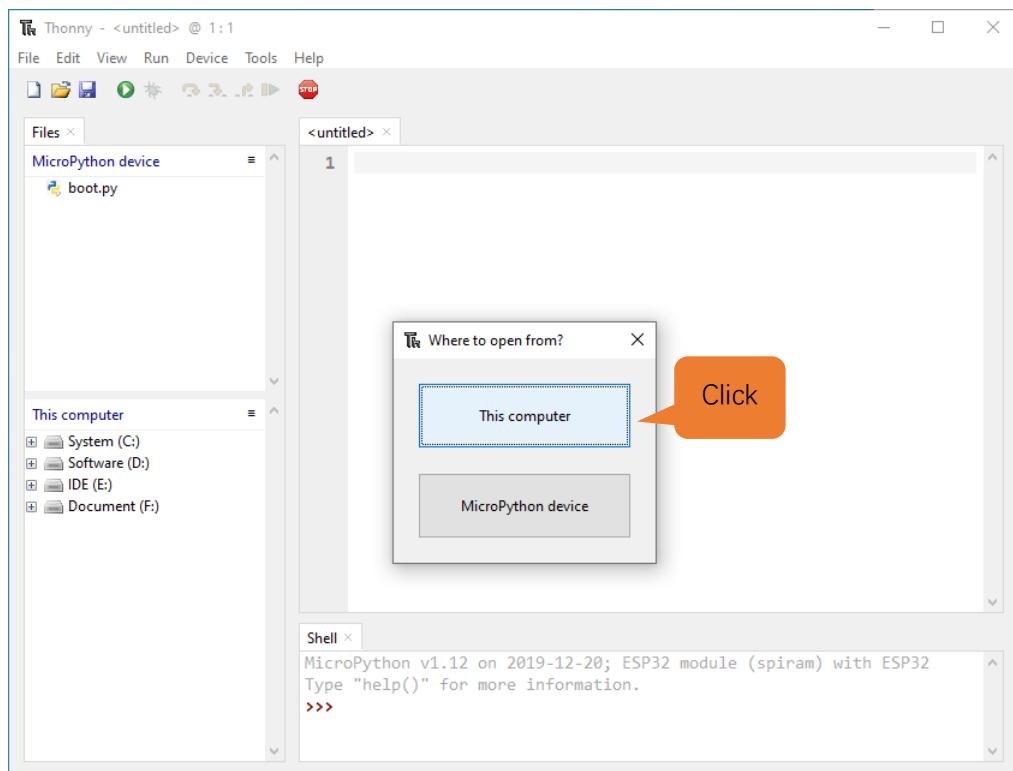
## Running Online

ESP32 needs to be connected to a computer when it is run online. Users can use Thonny to write and debug programs.

1. Open Thonny and click “Open…”.

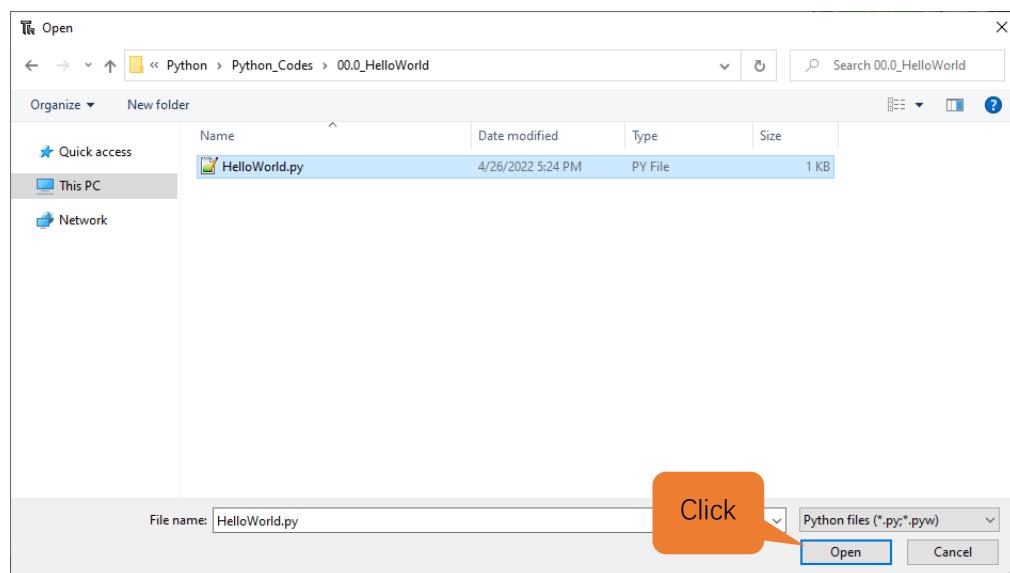


2. On the newly pop-up window, click “This computer”.

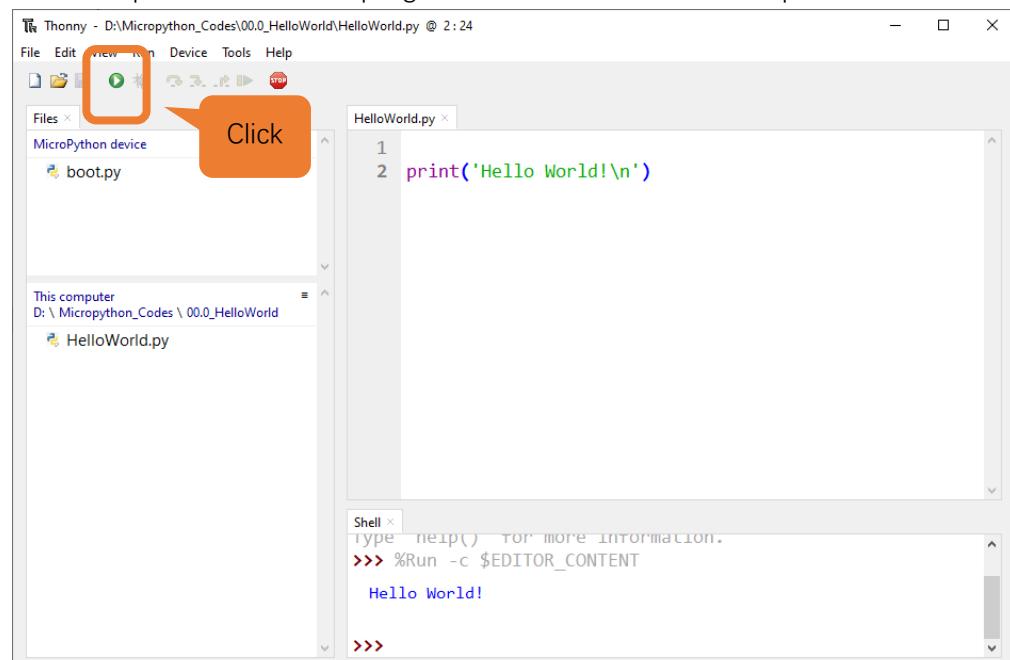


Any concerns? ✉ support@freenove.com

In the new dialog box, select “**HelloWorld.py**” in “**Freenove\_ESP32\_WROVER\_Board/Python/Python\_Codes/00.0\_HelloWorld**” folder.



Click “Run current script” to execute the program and “Hello World” will be printed in “Shell”.

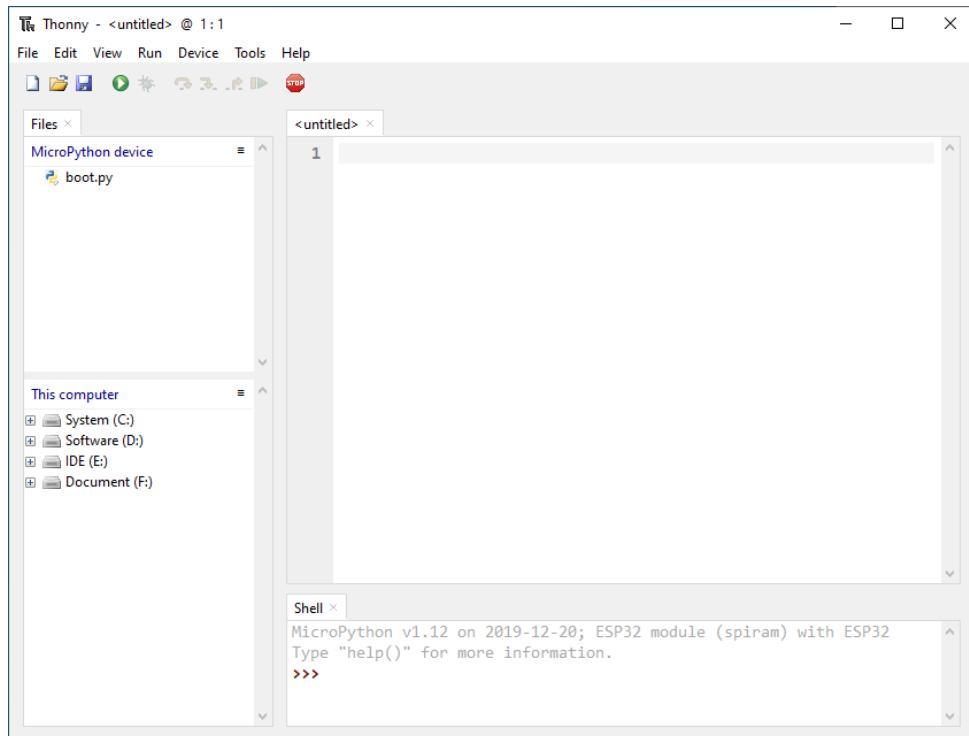


Note: When running online, if you press the reset key of ESP32, user's code will not be executed again. If you wish to run the code automatically after resetting the code, please refer to the following [Running Offline](#).

## Running Offline (Importance)

After ESP32 is reset, it runs the file boot.py in root directory first and then runs file main.py, and finally, it enters "Shell". Therefore, to make ESP32 execute user's programs after resetting, we need to add a guiding program in boot.py to execute user's code.

1. Move the program folder "**Freenove\_ESP32\_WROVER\_Board/Python/Python\_Codes**" to disk(D) in advance with the path of "**D:/Micropython\_Codes**". Open "Thonny".



2. Expand "00.1\_Boot" in the "Micropython\_Codes" in the directory of disk(D), and double-click boot.py, which is provided by us to enable programs in "MicroPython device" to run offline.

The screenshot shows the Thonny IDE interface. In the top menu, 'File' is selected. The main area displays the contents of 'boot.py' with syntax highlighting. The code is as follows:

```

1  #!/opt/bin/lv_micropython
2  import uos as os
3  import errno as errno
4  iter = os.ilistdir()
5  IS_DIR = 0x4000
6  IS_REGULAR = 0x8000
7
8  while True:
9      try:
10         entry = next(iter)
11         filename = entry[0]
12         file_type = entry[1]
13         if filename == 'boot.py':
14             continue
15         else:
16             print("====")
17             print(filename,end="")
18             if file_type == IS_DIR:
19                 print(", File is a directory")
20                 print("====")
21             else:
22                 print("\n====")
23                 #print("Contents:")
24                 #with open(filename) as f:
25                 #    for line in enumerate(f):
26                 #        print("{}\n".format(line[1]),end="")
27                 #print("")
28                 exec(open(filename).read(),globals())
29     except StopIteration:
30         break

```

In the bottom right corner of the code editor, there is a small orange speech bubble containing the text "No code has been uploaded." This is likely a placeholder or a message from the IDE.

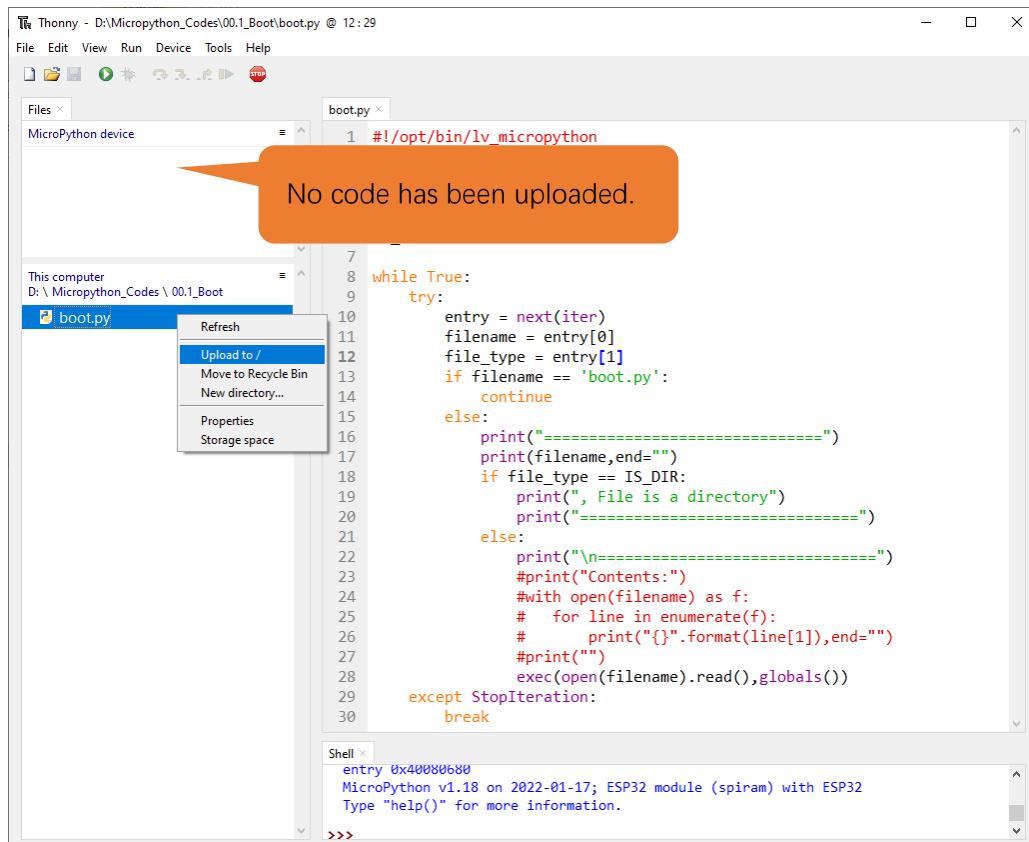
The bottom panel shows the MicroPython shell with the following output:

```

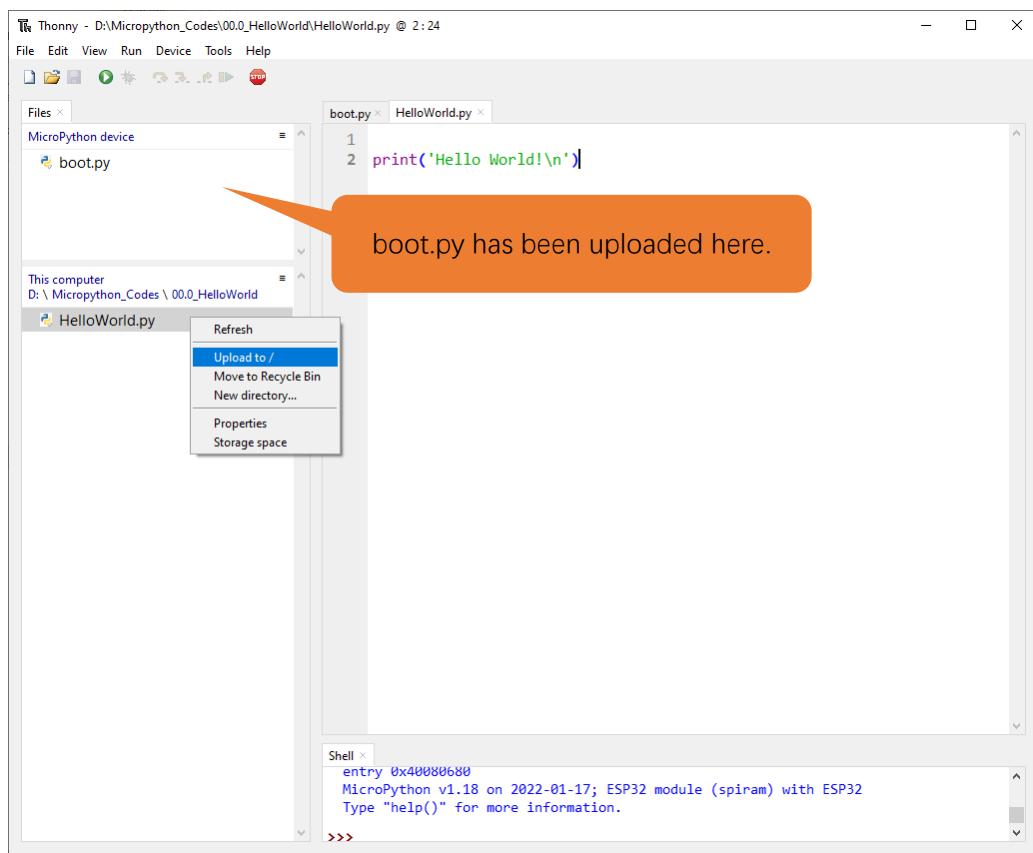
entry 0x40080680
MicroPython v1.18 on 2022-01-17; ESP32 module (spiram) with ESP32
Type "help()" for more information.
>>>

```

If you want your written programs to run offline, you need to upload boot.py we provided and all your codes to “MicroPython device” and press ESP32’s reset key. Here we use programs 00.0 and 00.1 as examples. Select “boot.py”, right-click to select “Upload to /”.



Similarly, upload “HelloWorld.py” to “MicroPython device”.



3. Press the reset key and in the box of the illustration below, you can see the code is executed.

The screenshot shows the Thonny IDE interface. In the top menu bar, it says "Thonny - D:\Micropython\_Codes\00.0\_HelloWorld\HelloWorld.py @ 2:24". The "File" menu is open. Below the menu is a toolbar with icons for file operations like Open, Save, Run, and Stop. On the left, there's a "Files" sidebar showing a "MicroPython device" folder containing "boot.py" and "HelloWorld.py", and a "This computer" section showing a "D:\ Micropython\_Codes \ 00.0\_HelloWorld" folder also containing "HelloWorld.py". The main workspace has two tabs: "boot.py" and "HelloWorld.py". The "HelloWorld.py" tab contains the following code:

```
1 print('Hello World!\n')
```

To the right of the workspace is a "Shell" window with a red border around its output area. The shell output shows:

```
=====
HelloWorld.py
=====
Hello World!
```

Below the shell output, the MicroPython version information is displayed:

```
MicroPython v1.18 on 2022-01-17; ESP32 module (spiram) with ESP32
Type "help()" for more information.
```

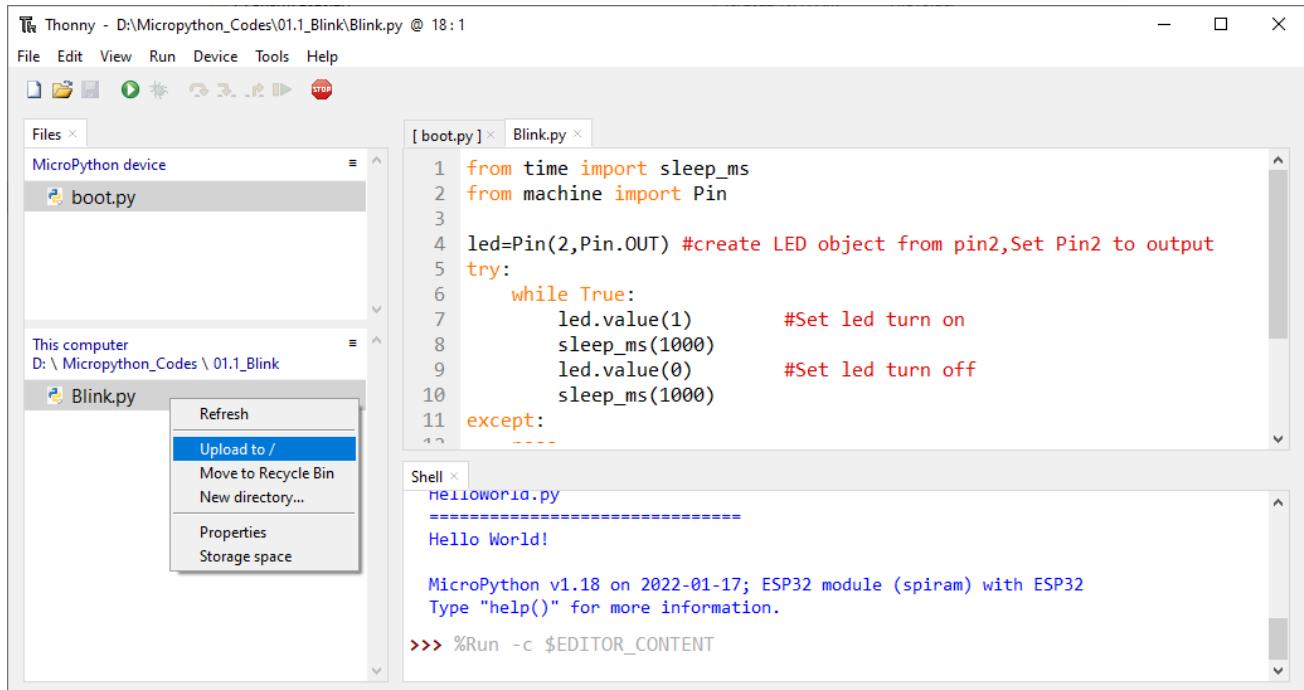
## 0.6 Thonny Common Operation

### Uploading Code to ESP32

Each time when ESP32 restarts, if there is a “boot.py” in the root directory, it will execute this code first.

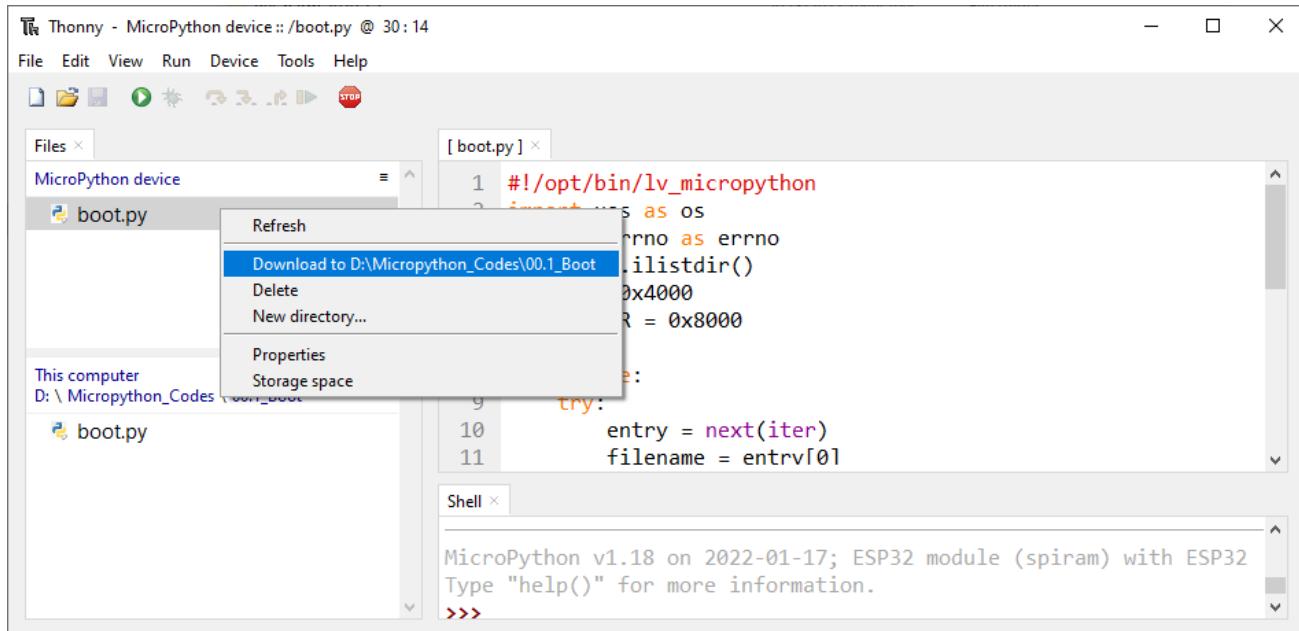


Select “Blink.py” in “01.1\_Blink”, right-click your mouse and select “Upload to /” to upload code to ESP32’s root directory.



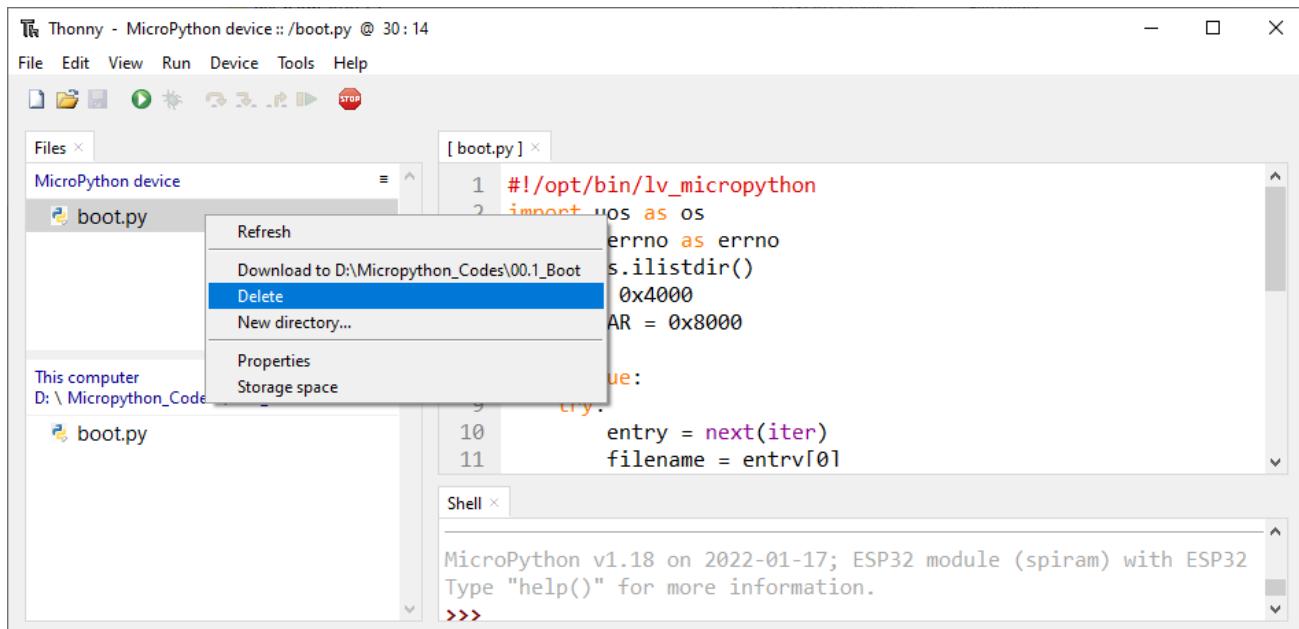
## Downloading Code to Computer

Select “boot.py” in “MicroPython device”, right-click to select “Download to ...” to download the code to your computer.



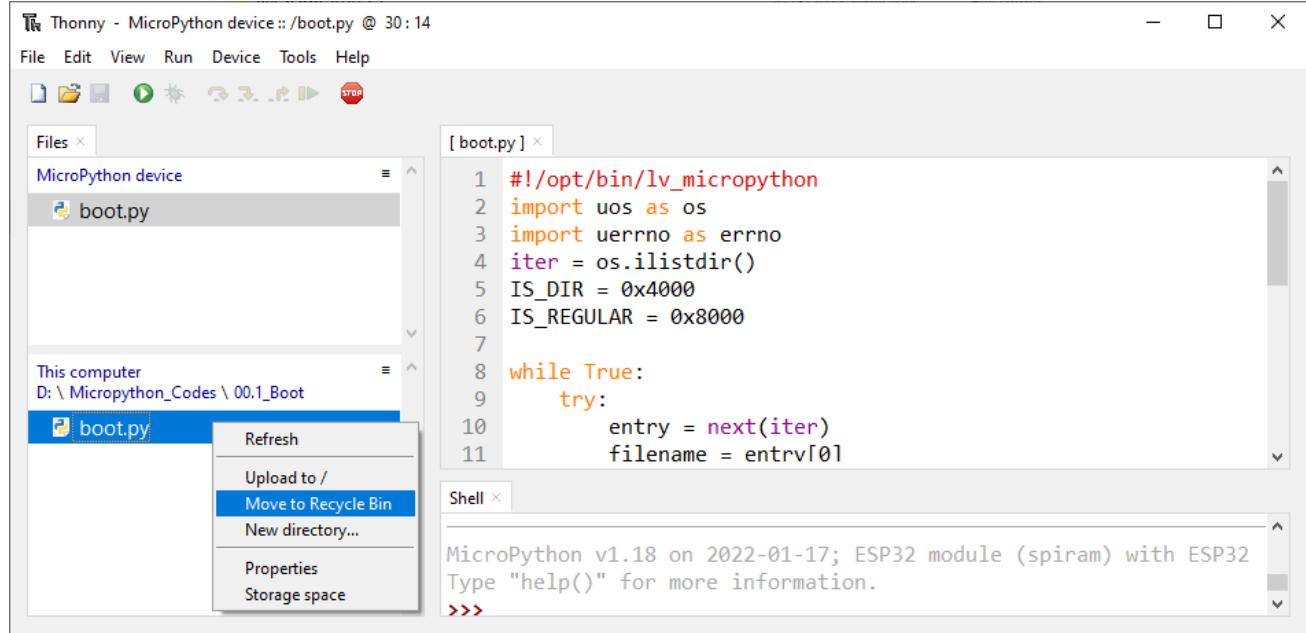
## Deleting Files from ESP32's Root Directory

Select “boot.py” in “MicroPython device”, right-click it and select “Delete” to delete “boot.py” from ESP32's root directory.



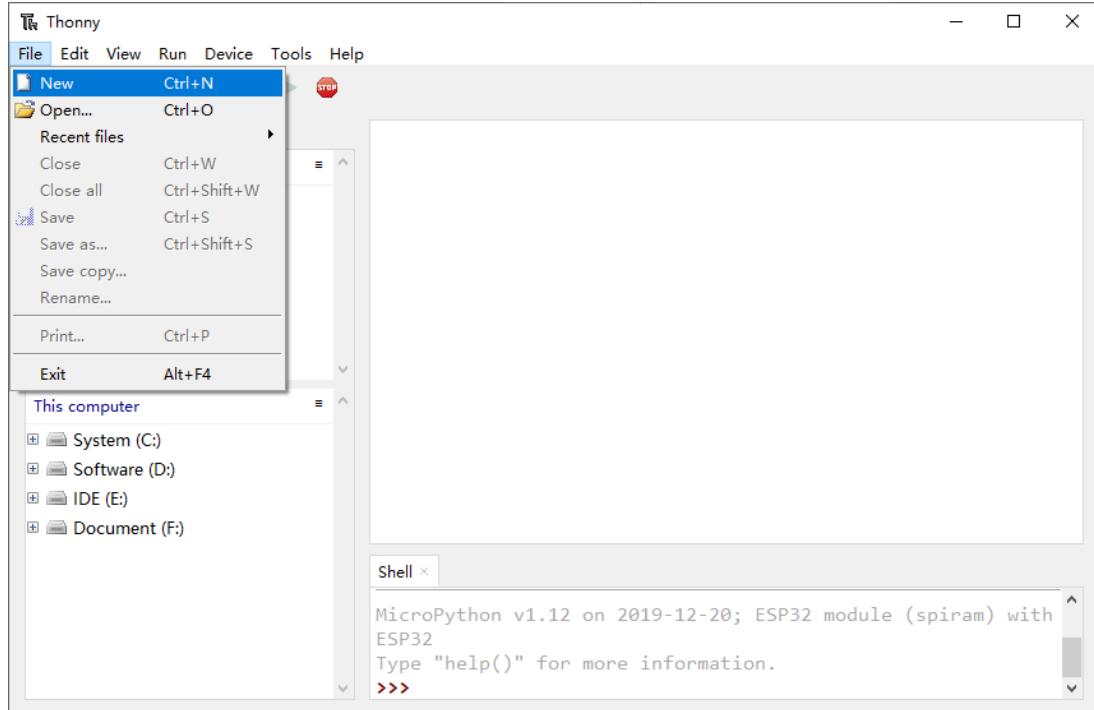
## Deleting Files from your Computer Directory

Select “boot.py” in “00.1\_Boot”, right-click it and select “Move to Recycle Bin” to delete it from “00.1\_Boot”.



## Creating and Saving the code

Click “File”→“New” to create and write codes.

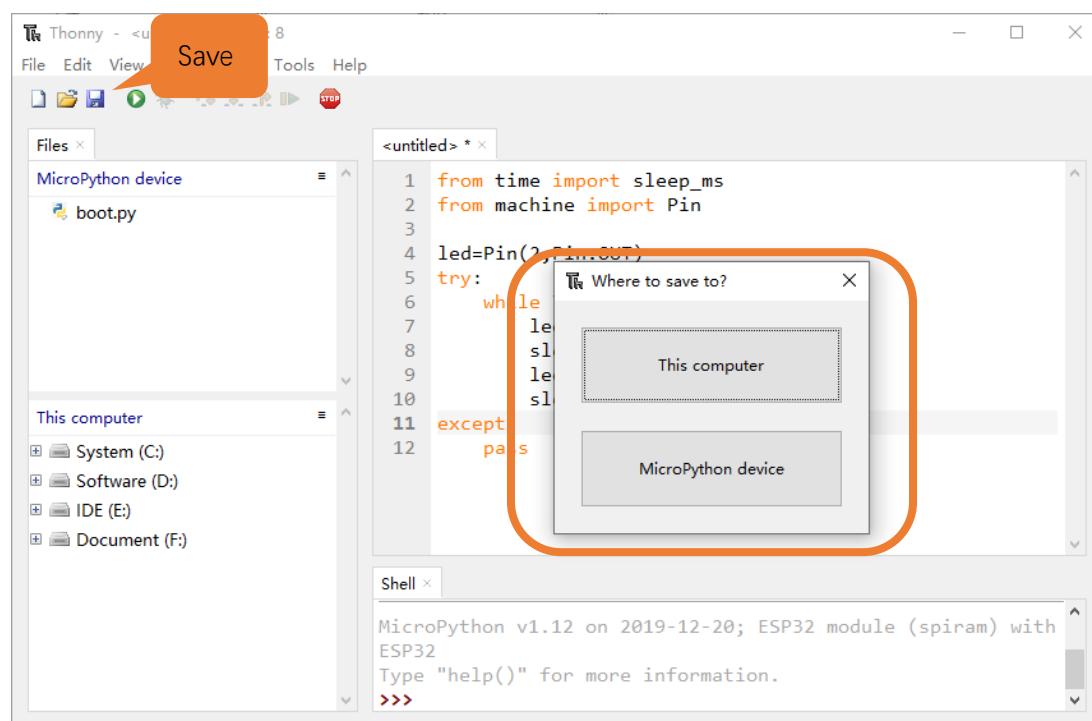


Enter codes in the newly opened file. Here we use codes of “01.1\_Blink.py” as an example.

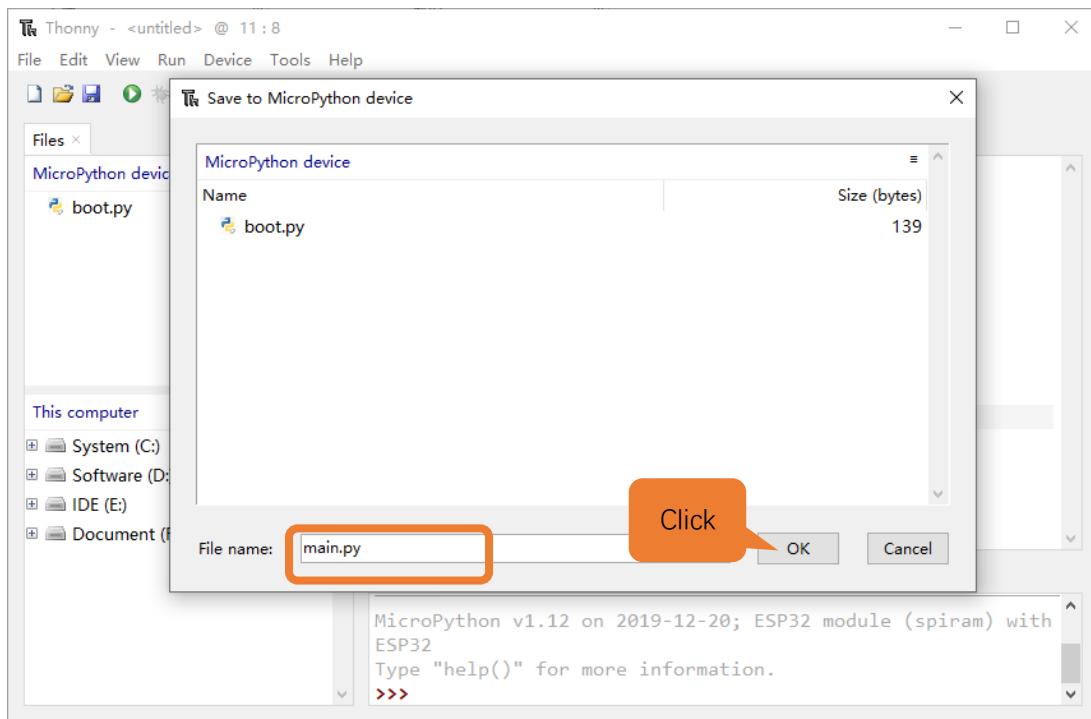
The screenshot shows the Thonny IDE interface. The menu bar includes File, Edit, View, Run, Device, Tools, and Help. The left sidebar shows a 'Files' tree with 'MicroPython device' expanded, containing a file named 'boot.py'. Below it is a 'This computer' section listing drives: System (C:), Software (D:), IDE (E:), and Document (F:). The main code editor window displays the following Python code:

```
1 from time import sleep_ms
2 from machine import Pin
3
4 led=Pin(2,Pin.OUT)
5 try:
6     while True:
7         led.value(1)
8         sleep_ms(1000)
9         led.value(0)
10        sleep_ms(1000)
11 except:
12     pass
```

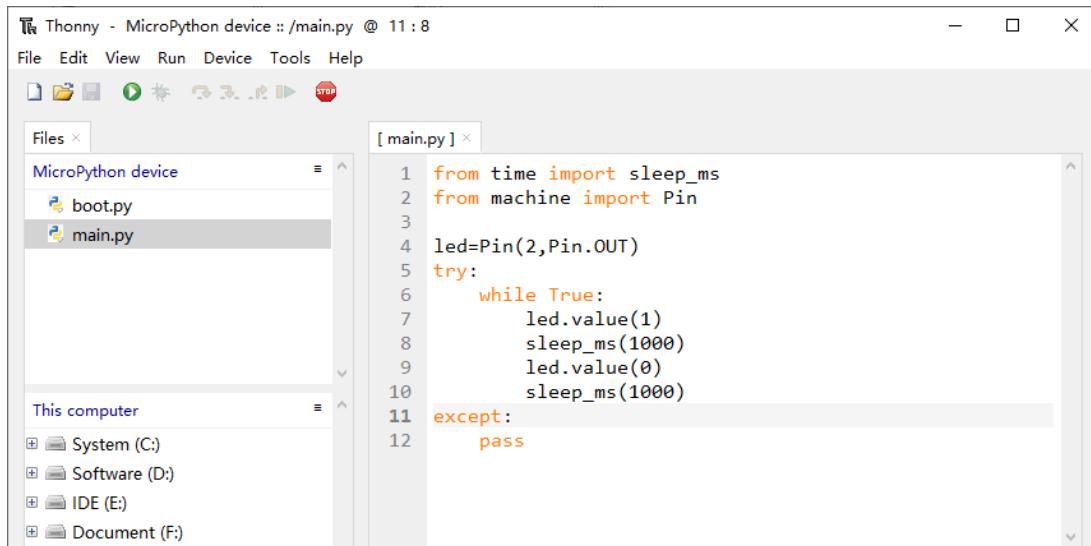
Click “Save” on the menu bar. You can save the codes either to your computer or to ESP32-WROVER.



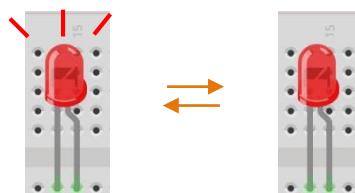
Select “MicroPython device”, enter “main.py” in the newly pop-up window and click “OK”.



You can see that codes have been uploaded to ESP32-WROVER.



Disconnect and reconnect USB cable, and you can see that LED is ON for one second and then OFF for one second, which repeats in an endless loop.



## 0.7 Note

Though there are many pins available on ESP32, some of them have been connected to peripheral equipment, so we should avoid using such pins to prevent pin conflicts. For example, when downloading programs, make sure that the pin state of Strapping Pin, when resetting, is consistent with the default level; do NOT use Flash Pin; Do NOT use Cam Pin when using Camera function.

### Strapping Pin

The state of Strapping Pin can affect the functions of ESP32 after it is reset, as shown in the table below.

| Voltage of Internal LDO (VDD_SDIO)                               |           |  |   |  |
|--|-----------|--|---|--|
| Pin  | Default   | 3.3 V  | 1.8 V                                       |  |
| MTDI   | Pull-down | 0  | 1   |  |
| Booting Mode   |           |  |   |  |
| Pin  | Default   | SPI Boot                                     | Download Boot                               |  |
| GPIO0  | Pull-up   | 1  | 0   |  |
| GPIO2  | Pull-down | Don't-care                                   | 0   |  |
| Enabling/Disabling Debugging Log Print over U0TXD During Booting |           |  |   |  |
| Pin  | Default   | U0TXD Active                                 | U0TXD Silent                                |  |
| MTDO   | Pull-up   | 1  | 0   |  |
| Timing of SDIO Slave   |           |  |   |  |
| Pin  | Default   | Falling-edge Sampling<br>Falling-edge Output | Rising-edge Sampling<br>Falling-edge Output | Rising-edge Sampling<br>Rising-edge Output |
| MTDO   | Pull-up   | 0  | 0   | 1  |
| GPIO5  | Pull-up   | 0  | 1   | 0  |

If you have any difficulties or questions with this tutorial or toolkit, feel free to ask for our quick and free technical support through support@freenove.com at any time.

or check: [https://www.espressif.com/sites/default/files/documentation/esp32-wrover\\_datasheet\\_en.pdf](https://www.espressif.com/sites/default/files/documentation/esp32-wrover_datasheet_en.pdf)

### Flash Pin

GPIO6-11 has been used to connect the integrated SPI flash on the module, and is used when GPIO 0 is power on and at high level. Flash is related to the operation of the whole chip, so the external pin GPIO6-11 cannot be used as an experimental pin for external circuits, otherwise it may cause errors in the operation of the program.

GPIO16-17 has been used to connect the integrated PSRAM on the module.

Because of external pull-up, MTDI pin is not suggested to be used as a touch sensor. For details, please refer to Peripheral Interface and Sensor chapter in "[ESP32 Data Sheet](#)".

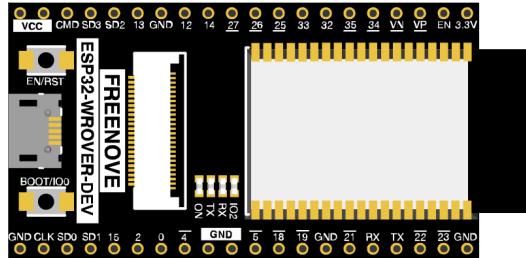
For more relevant information, please click:

[https://www.espressif.com/sites/default/files/documentation/esp32-wrover\\_datasheet\\_en.pdf](https://www.espressif.com/sites/default/files/documentation/esp32-wrover_datasheet_en.pdf).

Any concerns? ✉ [support@freenove.com](mailto:support@freenove.com)

## Cam Pin

When using the cam camera of our ESP32-WROVER, please check the pins of it. Pins with underlined numbers are used by the cam camera function, if you want to use other functions besides it, please avoid using them.



| CAM_Pin   | GPIO_pin |
|-----------|----------|
| I2C_SDA   | GPIO26   |
| I2C_SCL   | GPIO27   |
| CSI_VSYNC | GPIO25   |
| CSI_HREF  | GPIO23   |
| CSI_Y9    | GPIO35   |
| XCLK      | GPIO21   |
| CSI_Y8    | GPIO34   |
| CSI_Y7    | GPIO39   |
| CSI_PCLK  | GPIO22   |
| CSI_Y6    | GPIO36   |
| CSI_Y2    | GPIO4    |
| CSI_Y5    | GPIO19   |
| CSI_Y3    | GPIO5    |
| CSI_Y4    | GPIO18   |

If you have any questions about the information of GPIO, you can click [here](#) to go back to ESP32-WROVER to view specific information about GPIO.

Or check: [https://www.espressif.com/sites/default/files/documentation/esp32-wrover\\_datasheet\\_en.pdf](https://www.espressif.com/sites/default/files/documentation/esp32-wrover_datasheet_en.pdf).

# Chapter 1 LED (Important)

This chapter is the Start Point in the journey to build and explore ESP32 electronic projects. We will start with simple “Blink” project.

## Project 1.1 Blink

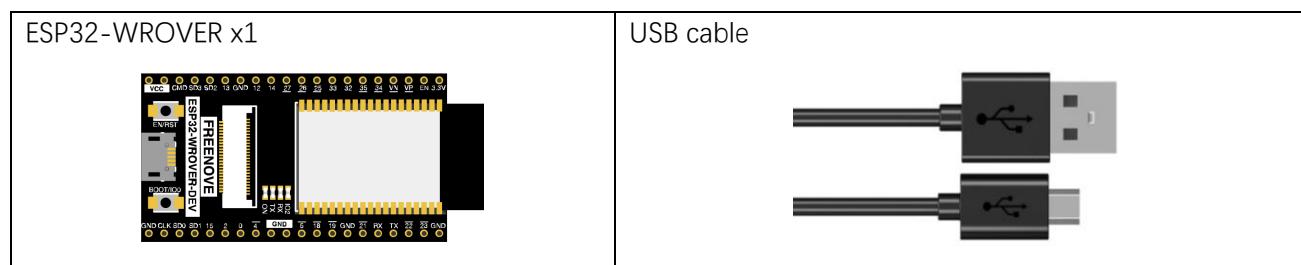
In this project, we will use ESP32 to control blinking a common LED.

If you have not yet installed Thonny, click [here](#).

If you have not yet downloaded Micropython Firmware, click [here](#).

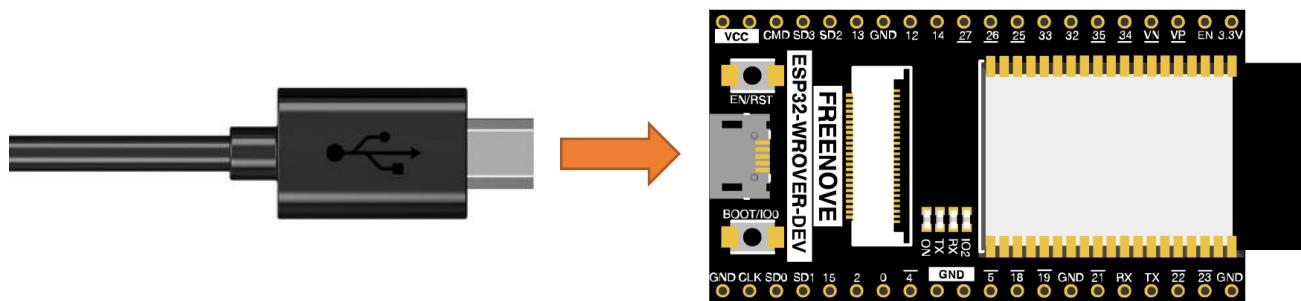
If you have not yet loaded Micropython Firmware, click [here](#).

## Component List



### Power

ESP32-WROVER needs 5v power supply. In this tutorial, we need connect ESP32-WROVER to computer via USB cable to power it and program it. We can also use other 5v power source to power it.



In the following projects, we only use USB cable to power ESP32-WROVER by default.

In the whole tutorial, we don't use T extension to power ESP32-WROVER. So 5V and 3.3V (including EXT 3.3V) on the extension board are provided by ESP32-WROVER.

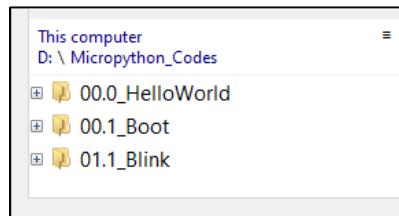
We can also use DC jack of extension board to power ESP32-WROVER. In this way, 5v and EXT 3.3v on extension board are provided by external power resource.

Code

Codes used in this tutorial are saved in “**Freenove\_ESP32\_WROVER\_Board/Python/Python\_Codes**”. You can move the codes to any location. For example, we save the codes in Disk(D) with the path of “**D:/Micropython\_Codes**”.

## 01.1\_Blink

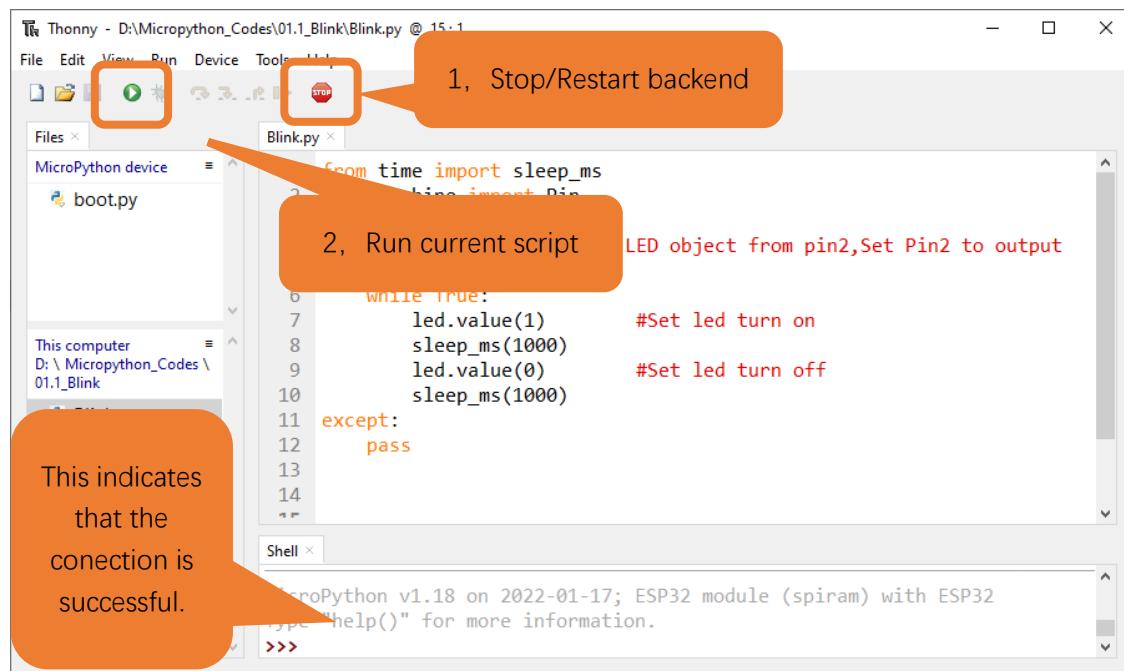
Open “Thonny”, click “This computer”→“D:”→“Micropython\_Codes”.



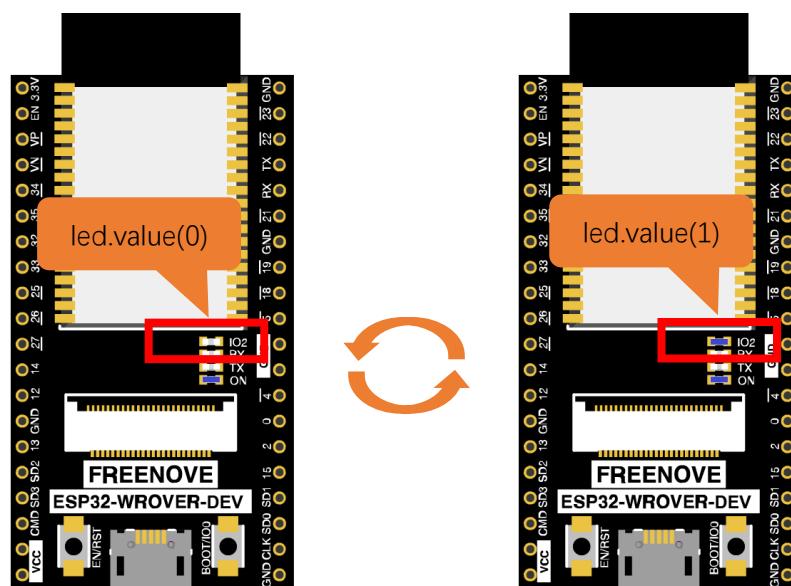
Expand folder "01.1\_Blink" and double click "Blink.py" to open it. As shown in the illustration below.



Make sure ESP32 has been connected with the computer with ESP32 correctly. Click “Stop/Restart backend” or press the reset button, and then wait to see what interface will show up.

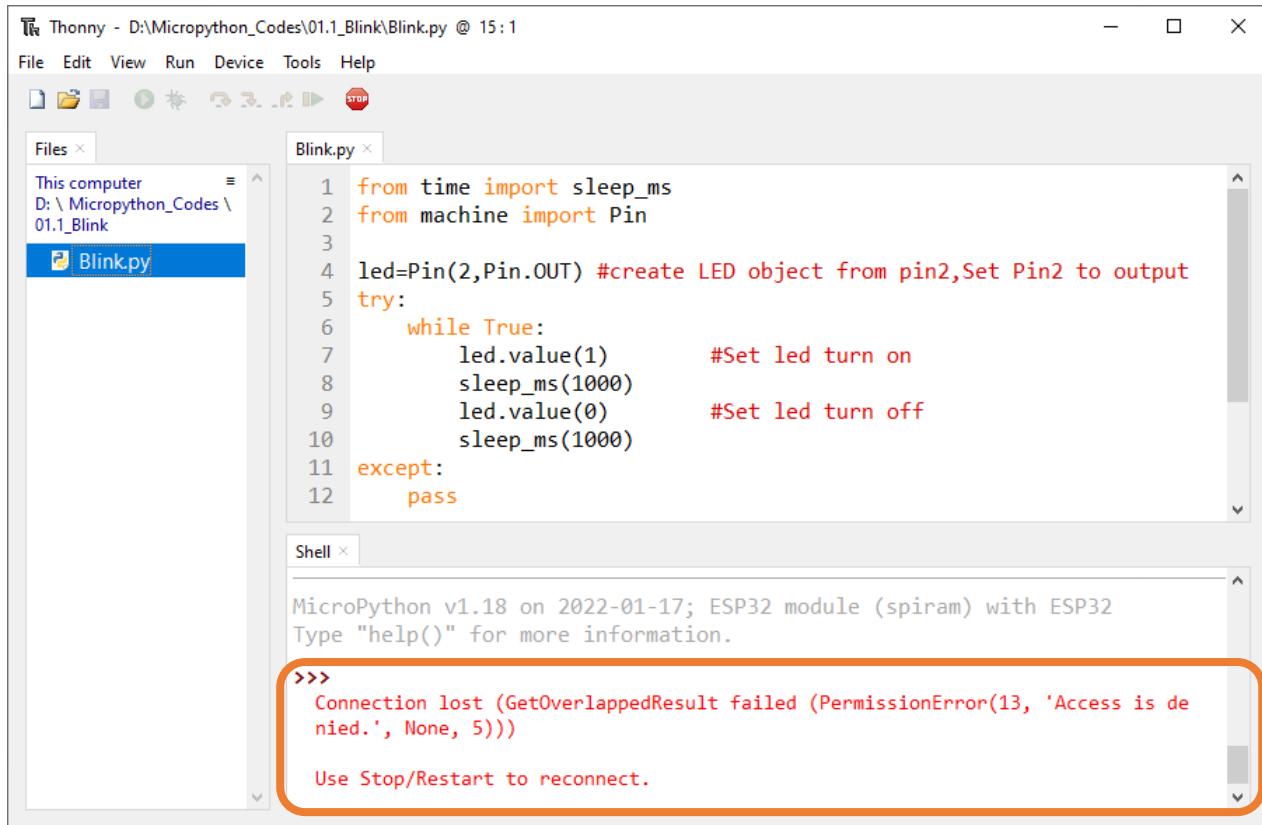


Click “Run current script” shown in the box above, the code starts to be executed and the LED in the circuit starts to blink.



### Note:

This is the code [running online](#). If you disconnect USB cable and repower ESP32 or press its reset key, LED stops blinking and the following messages will be displayed in Thonny.



The screenshot shows the Thonny IDE interface. The top menu bar includes File, Edit, View, Run, Device, Tools, and Help. The main window has a 'Files' tab on the left containing 'Blink.py' and a 'Blink.py' tab on the right displaying the following Python code:

```

1 from time import sleep_ms
2 from machine import Pin
3
4 led=Pin(2,Pin.OUT) #create LED object from pin2,Set Pin2 to output
5 try:
6     while True:
7         led.value(1)      #Set led turn on
8         sleep_ms(1000)
9         led.value(0)      #Set led turn off
10        sleep_ms(1000)
11 except:
12     pass

```

The bottom pane is a 'Shell' window showing MicroPython v1.18 running on an ESP32 module. It displays a connection error message:

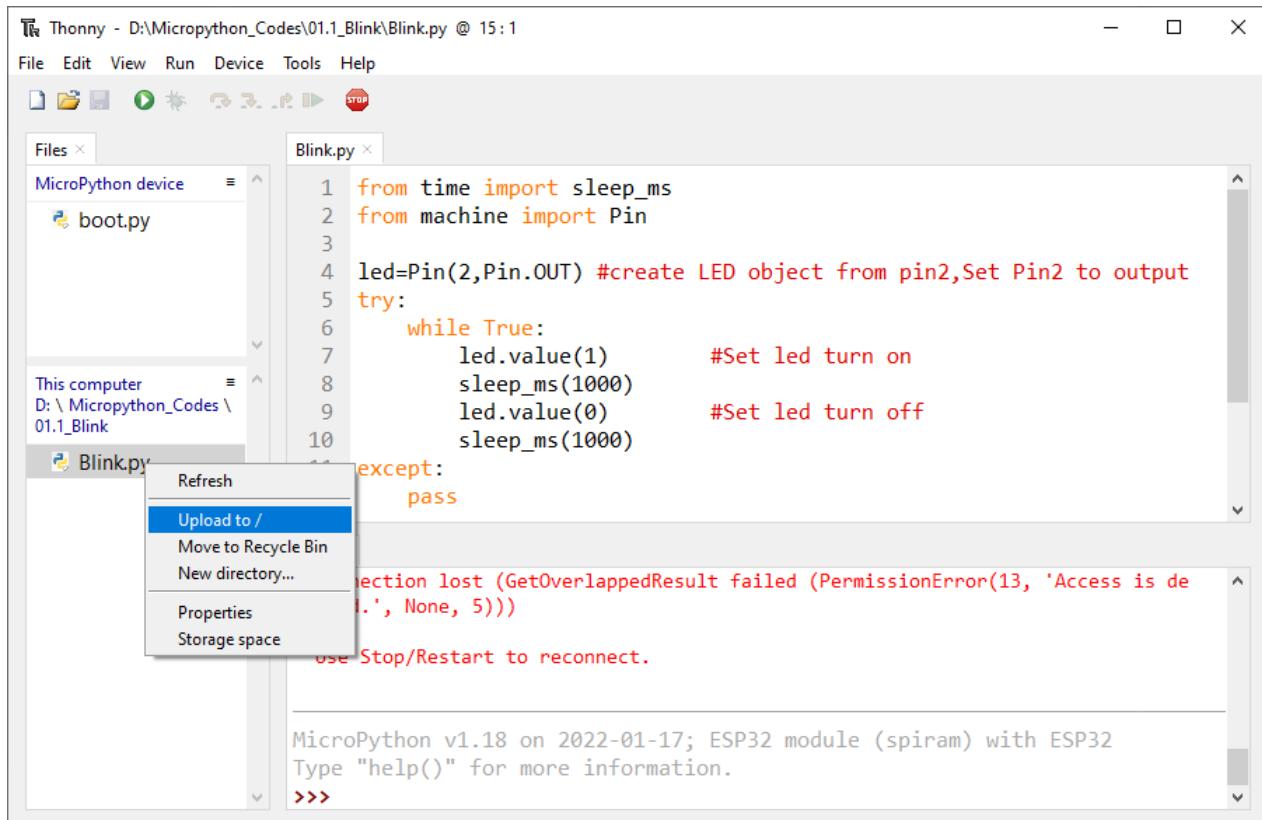
```

>>> Connection lost (GetOverlappedResult failed (PermissionError(13, 'Access is denied.', None, 5)))
Use Stop/Restart to reconnect.

```

### Uploading code to ESP32

As shown in the following illustration, right-click the file Blink.py and select “Upload to /” to upload code to ESP32.



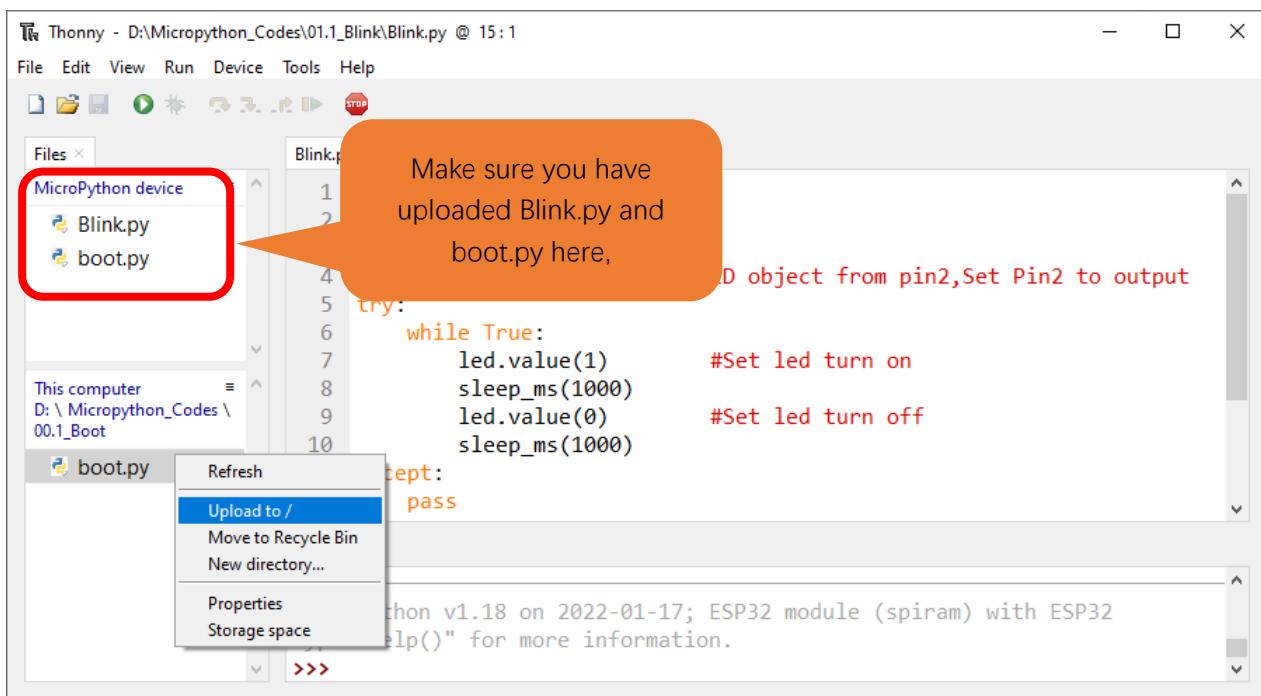
The screenshot shows the Thonny IDE interface with a different file structure in the 'Files' tab. The 'Blink.py' file is selected, and a context menu is open, with 'Upload to /' highlighted. The main code area is identical to the previous screenshot. The 'Shell' window at the bottom shows the same connection error message:

```

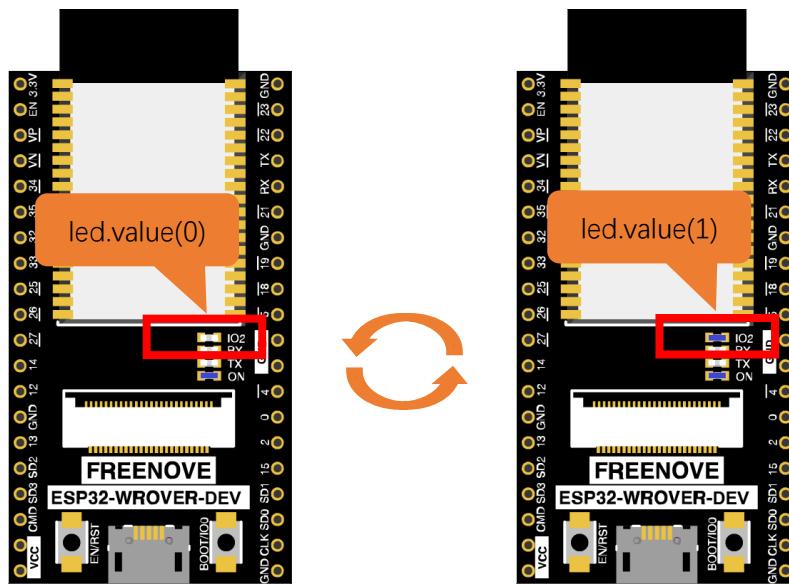
>>> Connection lost (GetOverlappedResult failed (PermissionError(13, 'Access is denied.', None, 5)))
Use Stop/Restart to reconnect.

```

Upload boot.py in the same way.

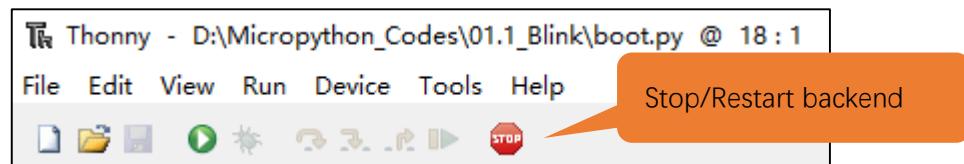


Press the reset key of ESP32 and you can see LED is ON for one second and then OFF for one second, which repeats in an endless loop.



Note:

Codes here is run offline. If you want to stop running offline and enter Shell, just click "Stop" in Thonny.



If you have any concerns, please contact us via: [support@freenove.com](mailto:support@freenove.com)

Any concerns? [✉ support@freenove.com](mailto:support@freenove.com)

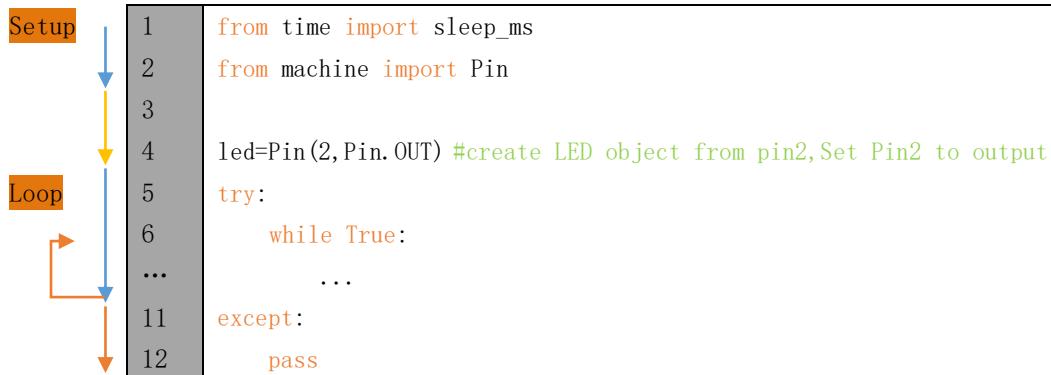
The following is the program code:

```

1  from time import sleep_ms
2  from machine import Pin
3
4  led=Pin(2,Pin.OUT) #create LED object from pin2, Set Pin2 to output
5  try:
6      while True:
7          led.value(1) #Set led turn on
8          sleep_ms(1000)
9          led.value(0) #Set led turn off
10         sleep_ms(1000)
11     except:
12         pass

```

Each time a new file is opened, the program will be executed from top to bottom. When encountering a loop construction, it will execute the loop statement according to the loop condition.



`Print()` function is used to print data to Terminal. It can be executed in Terminal directly or be written in a Python file and executed by running the file.

```
print("Hello world!")
```

Each time when using the functions of ESP32, you need to import modules corresponding to those functions:  
Import `sleep_ms` module of `time` module and `Pin` module of `machine` module.

```

1  from time import sleep_ms
2  from machine import Pin

```

Configure GPIO2 of ESP32-WROVER to output mode and assign it to an object named "led".

```
4  led=Pin(2,Pin.OUT) #create LED object from pin2, Set Pin2 to output
```

It means that from now on, LED represents GPIO2 that is in output mode.

Set the value of LED to 1 and GPIO2 will output high level.

```
7  led.value(1) #Set led turn on
```

Set the value of LED to 0 and GPIO2 will output low level.

```
9  led.value(0) #Set led turn on
```

Execute codes in a while loop.

```

6  while True:
...

```

Put statements that may cause an error in “try” block and the executing statements when an error occurs in “except” block. In general, when the program executes statements, it will execute those in “try” block.

However, when an error occurs to ESP32 due to some interference or other reasons, it will execute statements in “except” block.

“Pass” is an empty statement. When it is executed, nothing happens. It is useful as a placeholder to make the structure of a program look better.

```
5   try:  
...  
11  ...  
12  except:  
    pass
```

The single-line comment of Micropython starts with a “#” and continues to the end of the line. Comments help us to understand code. When programs are running, Thonny will ignore comments.

```
9 #Set led turn on
```

MicroPython uses indentations to distinguish different blocks of code instead of braces. The number of indentations is changeable, but it must be consistent throughout one block. If the indentation of the same code block is inconsistent, it will cause errors when the program runs.

```
6   while True:  
7       led.value(1) #Set led turn on  
8       sleep_ms(1000)  
9       led.value(0) #Set led turn off  
10      sleep_ms(1000)
```

### How to import python files

Whether to import the built-in python module or to import that written by users, the command “import” is needed.

If you import the module directly you should indicate the module to which the function or attribute belongs when using the function or attribute (constant, variable) in the module. The format should be: <module name>.<function or attribute>, otherwise an error will occur.

```
import random  
  
num = random.randint(1, 100)  
print(num)
```

If you only want to import a certain function or attribute in the module, use the from...import statement. The format is as follows

```
from random import randint  
num = randint(1, 100)  
print(num)
```

When using “from...import” statement to import function, to avoid conflicts and for easy understanding, you can use “as” statement to rename the imported function, as follows

```
from random import randint as rand  
num = rand(1, 100)  
print(num)
```



## Reference

### Class machine

Before each use of the **machine** module, please add the statement “**import machine**” to the top of python file.

**machine.freq(freq\_val):** When freq\_val is not specified, it is to return to the current CPU frequency; Otherwise, it is to set the current CPU frequency.

**freq\_val:** 80000000(80MHz)、160000000(160MHz)、240000000(240MHz)

**machine.reset():** A reset function. When it is called, the program will be reset.

**machine.unique\_id():** Obtains MAC address of the device.

**machine.idle():** Turns off any temporarily unused functions on the chip and its clock, which is useful to reduce power consumption at any time during short or long periods.

**machine.disable\_irq():** Disables interrupt requests and return the previous IRQ state. The disable\_irq () function and enable\_irq () function need to be used together; Otherwise the machine will crash and restart.

**machine.enable\_irq(state):** To re-enable interrupt requests. The parameter **state** should be the value that was returned from the most recent call to the disable\_irq() function

**machine.time\_pulse\_us(pin, pulse\_level, timeout\_us=1000000):**

Tests the duration of the external pulse level on the given pin and returns the duration of the external pulse level in microseconds. When pulse level = 1, it tests the high level duration; When pulse level = 0, it tests the low level duration.

If the setting level is not consistent with the current pulse level, it will wait until they are consistent, and then start timing. If the set level is consistent with the current pulse level, it will start timing immediately.

When the pin level is opposite to the set level, it will wait for timeout and return “-2”. When the pin level and the set level is the same, it will also wait timeout but return “-1”. **timeout\_us** is the duration of timeout.

**Class Pin(id[, mode, pull, value])**

Before each use of the **Pin** module, please add the statement “**from machine import Pin**” to the top of python file.

**id:** Arbitrary pin number

**mode:** Mode of pins

**Pin.IN:** Input Mode

**Pin.OUT:** Output Mode

**Pin.OPEN\_DRAIN:** Open-drain Mode

**Pull:** Whether to enable the internal pull up and down mode

**None:** No pull up or pull down resistors

**Pin.PULL\_UP:** Pull-up Mode, outputting high level by default

**Pin.PULL\_DOWN:** Pull-down Mode, outputting low level by default

**Value:** State of the pin level, 0/1

**Pin.init(mode, pull):** Initialize pins

**Pin.value([value]):** Obtain or set state of the pin level, return 0 or 1 according to the logic level of pins.

Without parameter, it reads input level. With parameter given, it is to set output level.

**value:** It can be either True/False or 1/0.

**Pin.irq(trigger, handler):** Configures an interrupt handler to be called when the pin level meets a condition.

**trigger:**

**Pin.IRQ\_FALLING:** interrupt on falling edge

**Pin.IRQ\_RISING:** interrupt on rising edge

**3:** interrupt on both edges

**Handler:** callback function

**Class time**

Before each use of the **time** module, please add the statement “**import time**” to the top of python file

**time.sleep(sec):** Sleeps for the given number of seconds

**sec:** This argument should be either an int or a float.

**time.sleep\_ms(ms):** Sleeps for the given number of milliseconds, ms should be an int.

**time.sleep\_us(us):** Sleeps for the given number of microseconds, us should be an int.

**time.time():** Obtains the timestamp of CPU, with second as its unit.

**time.ticks\_ms():** Returns the incrementing millisecond counter value, which recounts after some values.

**time.ticks\_us():** Returns microsecond

**time.ticks\_cpu():** Similar to ticks\_ms() and ticks\_us(), but it is more accurate(return clock of CPU).

**time.ticks\_add(ticks, delta):** Gets the timestamp after the offset.

**ticks:** ticks\_ms()、 ticks\_us()、 ticks\_cpu()

**delta:** Delta can be an arbitrary integer number or numeric expression

**time.ticks\_diff(old\_t, new\_t):** Calculates the interval between two timestamps, such as ticks\_ms(), ticks\_us() or ticks\_cpu().

**old\_t:** Starting time

**new\_t:** Ending time

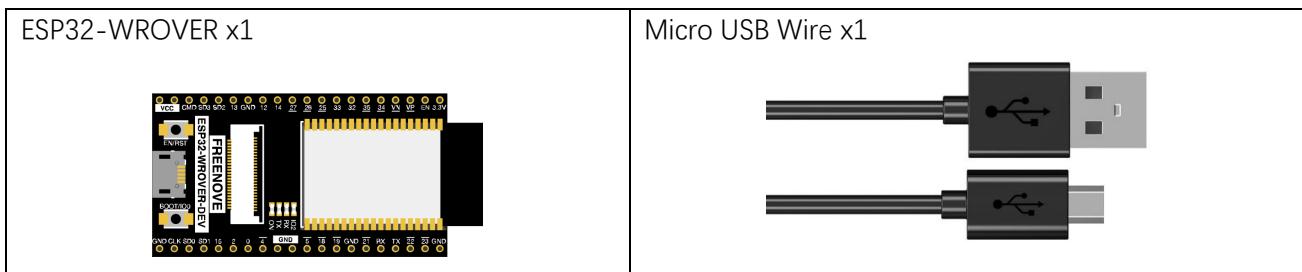


# Chapter 2 Bluetooth

This chapter mainly introduces how to make simple data transmission through Bluetooth of ESP32-WROVER and mobile phones.

## Project 2.1 Bluetooth Low Energy Data Passthrough

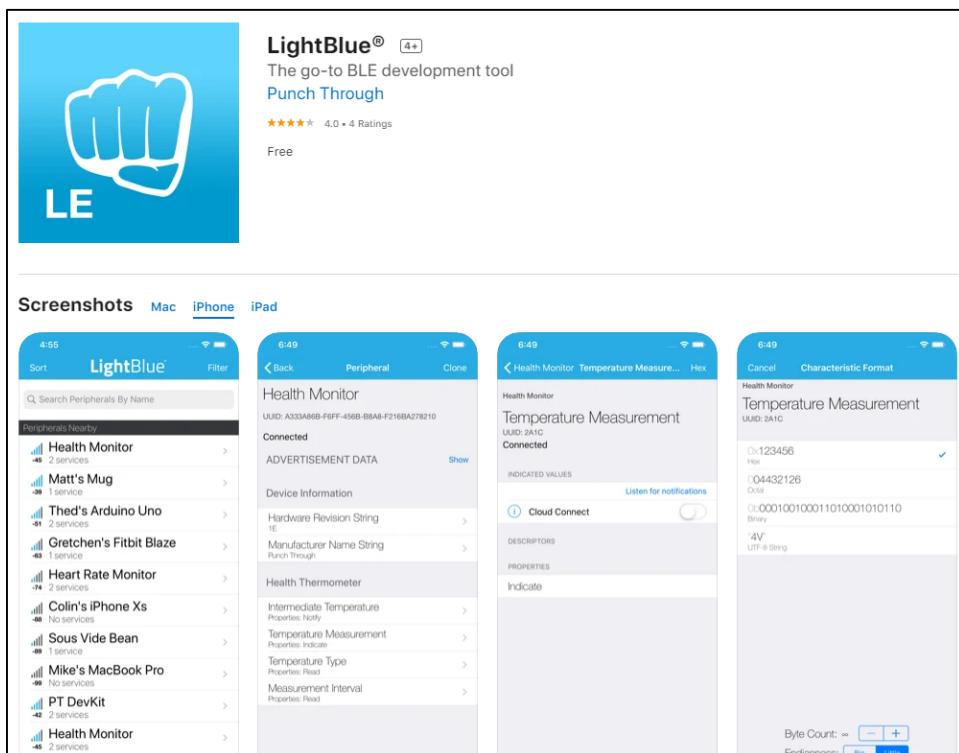
### Component List



### Lightblue

If you can't install Serial Bluetooth on your phone, try LightBlue. If you do not have this software installed on your phone, you can refer to this link:

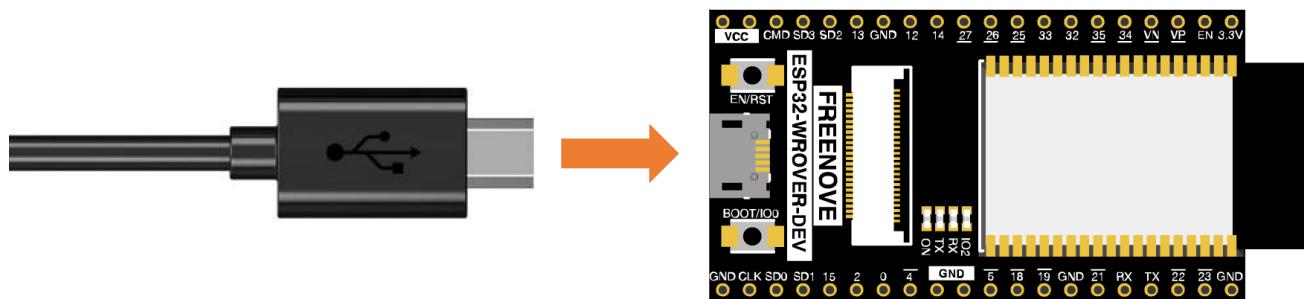
<https://apps.apple.com/us/app/lightblue/id557428110#?platform=iphone>



Any concerns?  [support@freenove.com](mailto:support@freenove.com)

## Circuit

Connect Freenove ESP32 to the computer using the USB cable.

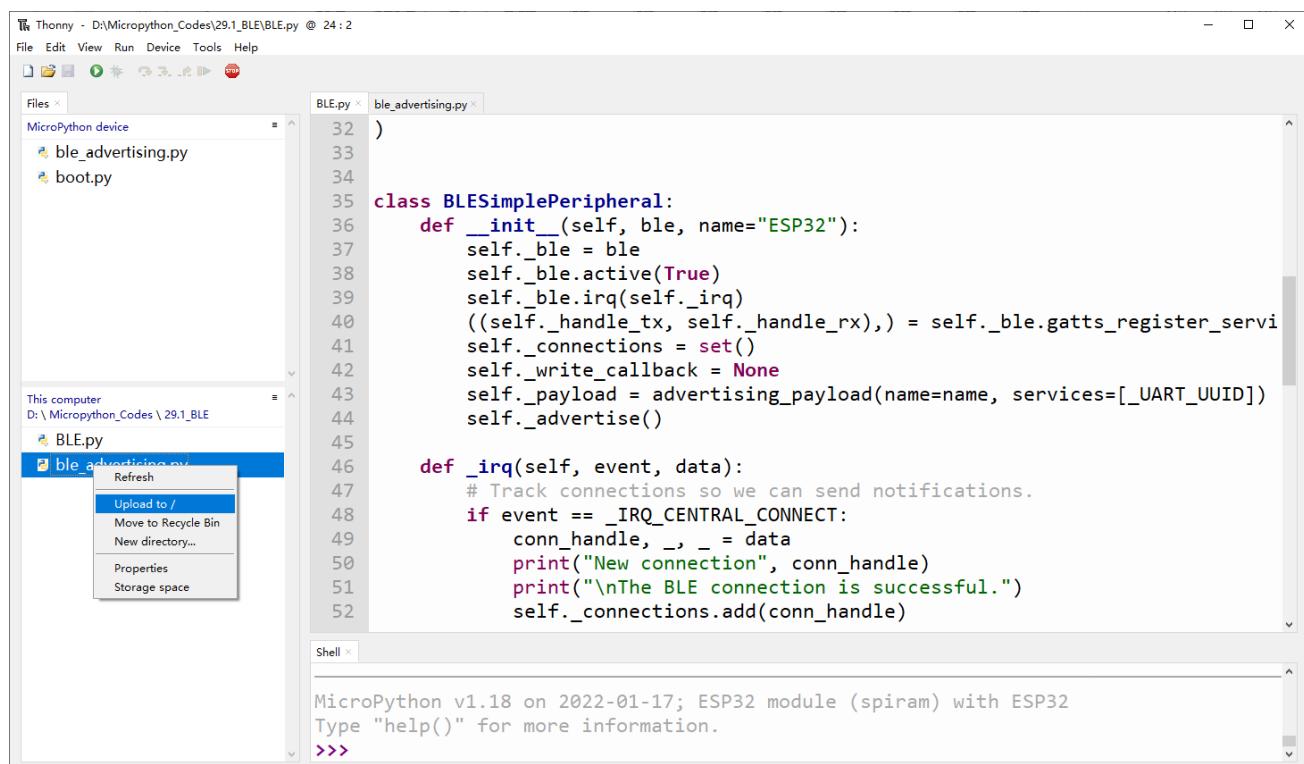


## Code

Move the program folder “**Freenove\_ESP32\_WROVER\_Board/Python/Python\_Codes**” to disk(D) in advance with the path of “**D:/Micropython\_Codes**”.

Open “Thonny”, click “This computer” → “D:” → “Micropython\_Codes” → “02.1\_BLE”. Select “ble\_advertising.py”, right click your mouse to select “Upload to /”, wait for “ble\_advertising.py” to be uploaded to ESP32-WROVER and then double click “BLE.py”.

### 02.1\_BLE





Click run for BLE.py.

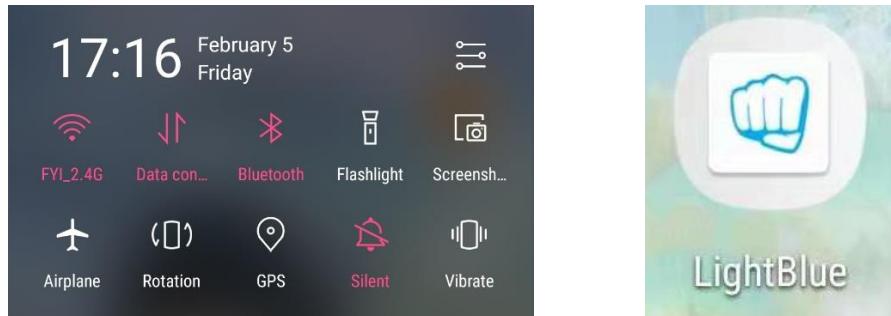
```

Thonny - D:\Micropython_Codes\29.1_BLE\BLE.py @ 43 : 10
File Edit View Run Device Tools Help
BLE.py x ble_advertising.py x
Files x
MicroPython device
ble_advertising.py
boot.py
34
35 class BLESimplePeripheral:
36     def __init__(self, ble, name="ESP32"):
37         self._ble = ble
38         self._ble.active(True)
39         self.ble.irq(self.irq)
Shell x
Please use LightBlue to connect to ESP32.
New connection 0

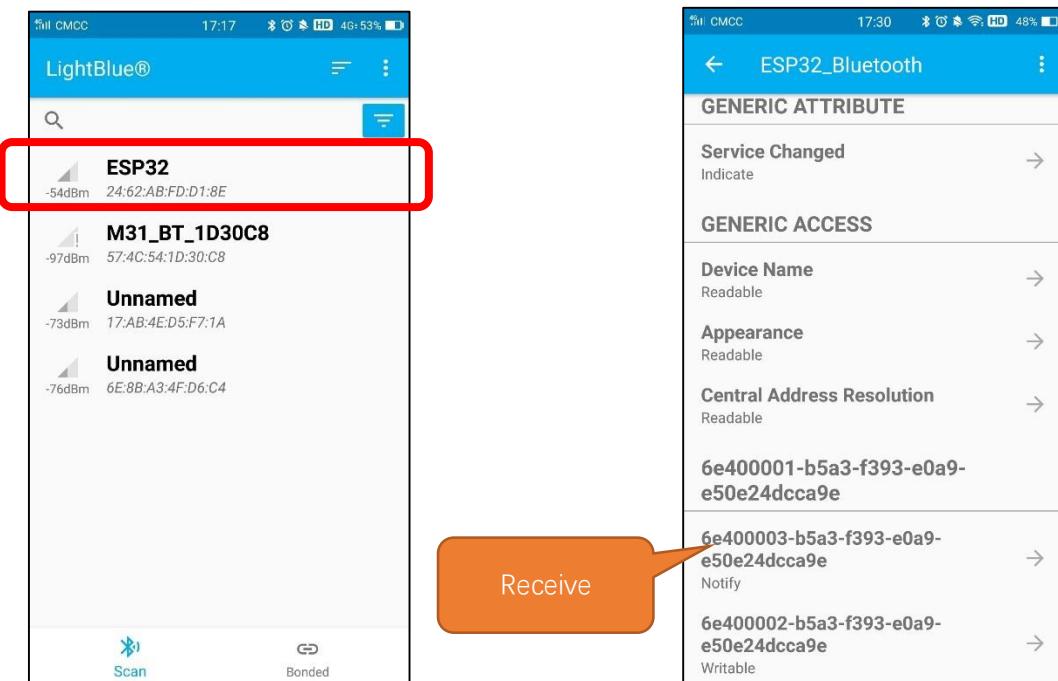
The BLE connection is successful.
Enter anything: 11112
Send: 11112
Enter anything: 2121
Send: 2121
Enter anything:

MicroPython v1.18 on 2022-01-17; ESP32 module (spiram) with ESP32
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT
Disconnected 0
Starting advertising
Traceback (most recent call last):
  File "<stdin>", line 58, in _irq
    File "<stdin>", line 74, in _advertise
  OSError: [Errno 19] ENODEV
Starting advertising
Please use LightBlue to connect to ESP32.
  
```

Turn ON Bluetooth on your phone, and open the Lightblue APP.



In the Scan page, swipe down to refresh the name of Bluetooth that the phone searches for. Click ESP32.

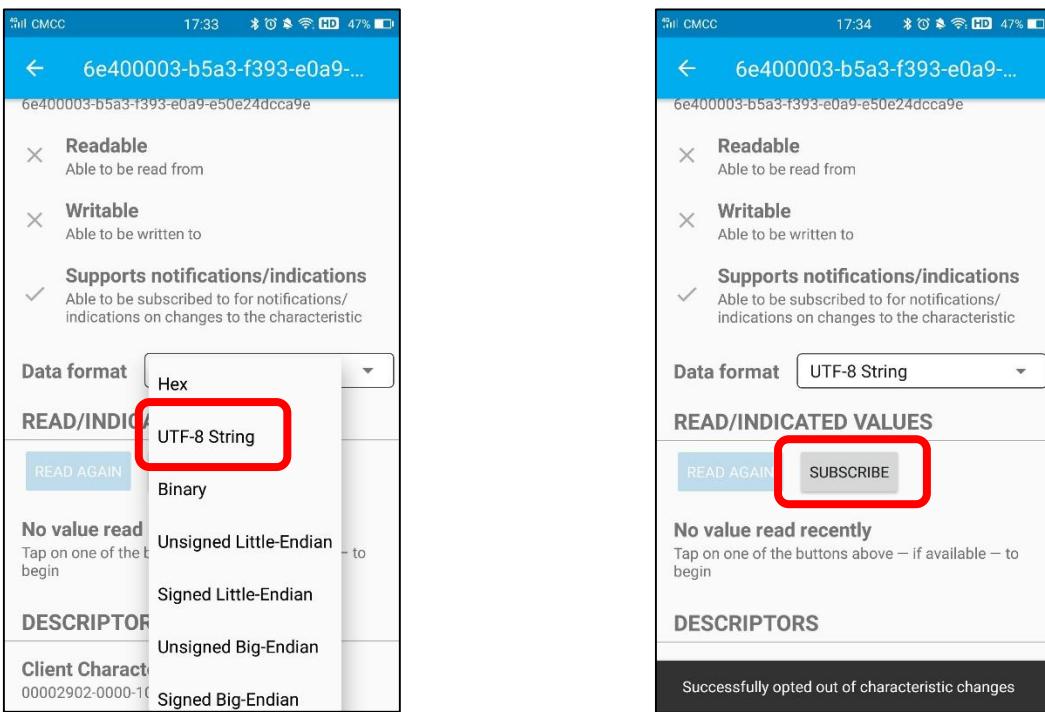


After Bluetooth is connect successfully, Shell will printer the information.

```
MicroPython v1.18 on 2022-01-17; ESP32 module (spiram) with ESP32
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT
Disconnected 0
Starting advertising
Traceback (most recent call last):
  File "<stdin>", line 58, in _irq
  File "<stdin>", line 74, in _advertise
OSError: [Errno 19] ENODEV
Starting advertising
Please use LightBlue to connect to ESP32.
New connection 0

The BLE connection is successful.
Enter anything:
```

Click “Receive”. Select the appropriate Data format in the box to the right of Data Format. For example, HEX for hexadecimal, utf-string for character, Binary for Binary, etc. Then click SUBSCRIBE.



You can type “Hello” in Shell and press “Enter” to send.

```

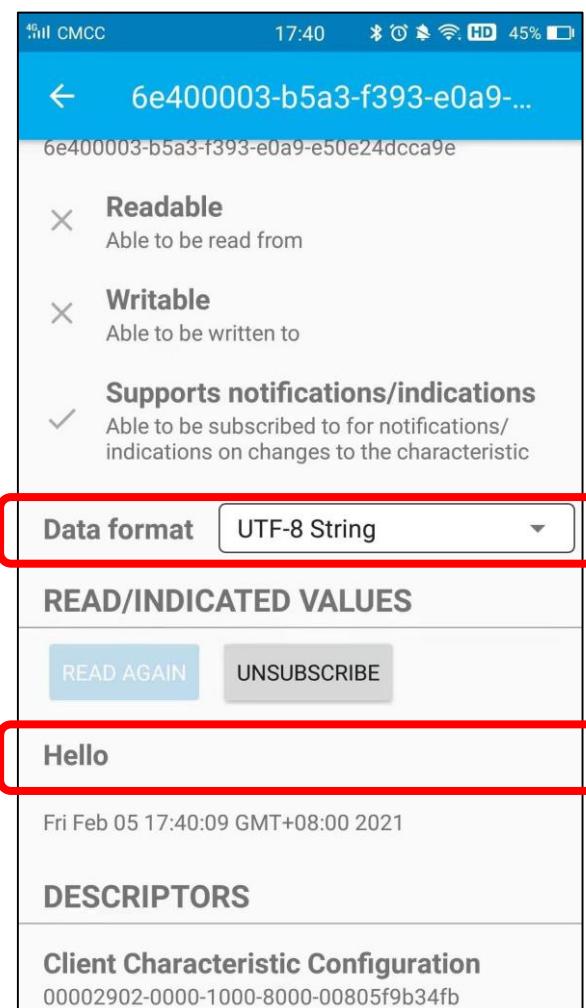
MicroPython v1.18 on 2022-01-17; ESP32 module (spiram) with ESP32
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT

Disconnected 0
Starting advertising
Traceback (most recent call last):
  File "<stdin>", line 58, in _irq
  File "<stdin>", line 74, in _advertise
OSErr: [Errno 19] ENODEV
Starting advertising
Please use LightBlue to connect to ESP32.
New connection 0

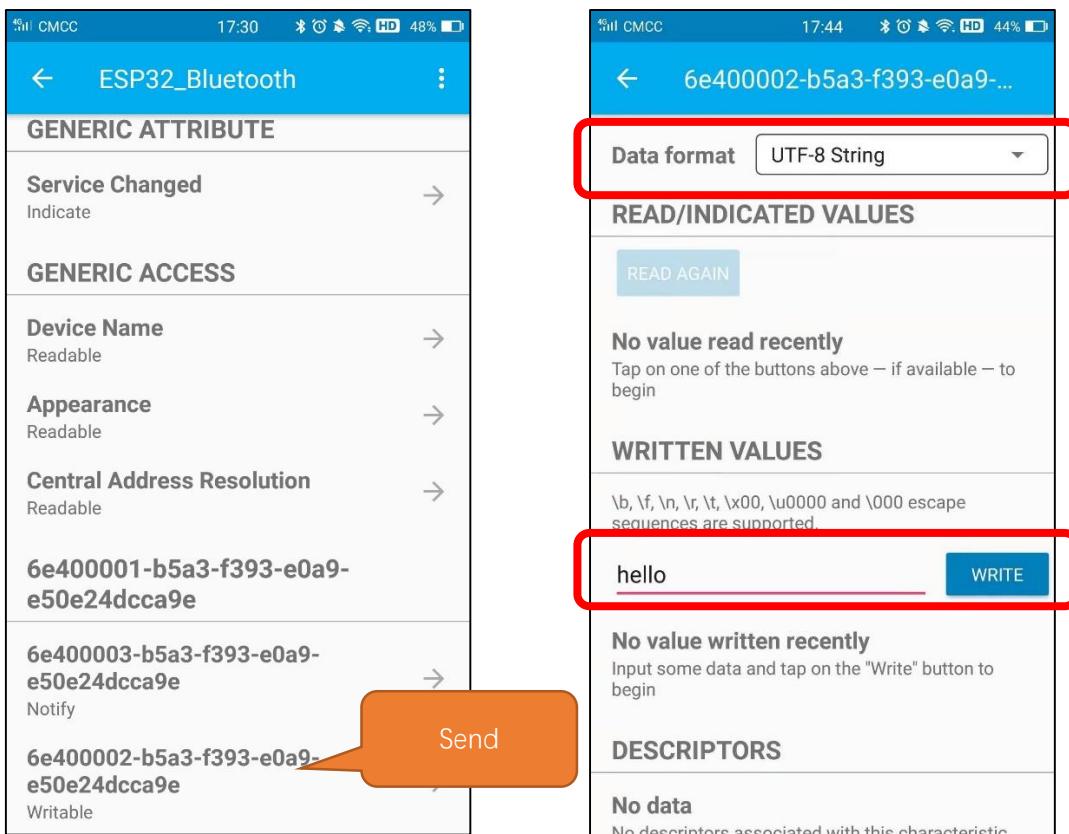
The BLE connection is successful.
Enter anything: Hello
Send: Hello
Enter anything:

```

And then you can see the mobile Bluetooth has received the message.



Similarly, you can select “Send” on your phone. Set Data format, and then enter anything in the sending box and click Write to send.



You can check the message from Bluetooth in “Shell”.

```
MicroPython v1.18 on 2022-01-17; ESP32 module (spiram) with ESP32
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT
Disconnected 0
Starting advertising
Traceback (most recent call last):
  File "<stdin>", line 58, in _irq
  File "<stdin>", line 74, in _advertise
OSError: [Errno 19] ENODEV
Starting advertising
Please use LightBlue to connect to ESP32.
New connection 0

The BLE connection is successful.
Enter anything: Hello
Send: Hello
Enter anything: RX b'hello'
```

And now data can be transferred between your mobile phone and computer via ESP32-WROVER.

The following is the program code:

```
1 import bluetooth
2 import random
3 import struct
4 import time
5 from ble_advertising import advertising_payload
6 from micropython import const
7
8 _IRQ_CENTRAL_CONNECT = const(1)
9 _IRQ_CENTRAL_DISCONNECT = const(2)
10 _IRQ_GATTS_WRITE = const(3)
11 _FLAG_READ = const(0x0002)
12 _FLAG_WRITE_NO_RESPONSE = const(0x0004)
13 _FLAG_WRITE = const(0x0008)
14 _FLAG_NOTIFY = const(0x0010)
15
16 _UART_UUID = bluetooth.UUID("6E400001-B5A3-F393-E0A9-E50E24DCCA9E")
17 _UART_TX = (
18     bluetooth.UUID("6E400003-B5A3-F393-E0A9-E50E24DCCA9E"),
19     _FLAG_READ | _FLAG_NOTIFY,
20 )
21 _UART_RX = (
22     bluetooth.UUID("6E400002-B5A3-F393-E0A9-E50E24DCCA9E"),
23     _FLAG_WRITE | _FLAG_WRITE_NO_RESPONSE,
24 )
25 _UART_SERVICE = (
26     _UART_UUID,
27     (_UART_TX, _UART_RX),
28 )
29 class BLESimplePeripheral:
30     def __init__(self, ble, name="ESP32"):
31         self._ble = ble
32         self._ble.active(True)
33         self._ble.irq(self._irq)
34         ((self._handle_tx, self._handle_rx),) =
35         self._ble.gatts_register_services((_UART_SERVICE,))
36         self._connections = set()
37         self._write_callback = None
38         self._payload = advertising_payload(name=name, services=[_UART_UUID])
39         self._advertise()
40     def _irq(self, event, data):
41         # Track connections so we can send notifications.
42         if event == _IRQ_CENTRAL_CONNECT:
```

```

43         conn_handle, _, _ = data
44         print("New connection", conn_handle)
45         print("\nThe BLE connection is successful.")
46         self._connections.add(conn_handle)
47     elif event == _IRQ_CENTRAL_DISCONNECT:
48         conn_handle, _, _ = data
49         print("Disconnected", conn_handle)
50         self._connections.remove(conn_handle)
51         # Start advertising again to allow a new connection.
52         self._advertise()
53     elif event == _IRQ_GATTS_WRITE:
54         conn_handle, value_handle = data
55         value = self._ble.gatts_read(value_handle)
56         if value_handle == self._handle_rx and self._write_callback:
57             self._write_callback(value)
58     def send(self, data):
59         for conn_handle in self._connections:
60             self._ble.gatts_notify(conn_handle, self._handle_tx, data)
61     def is_connected(self):
62         return len(self._connections) > 0
63     def _advertise(self, interval_us=500000):
64         print("Starting advertising")
65         self._ble.gap_advertise(interval_us, adv_data=self._payload)
66     def on_write(self, callback):
67         self._write_callback = callback
68     def demo():
69         ble = bluetooth.BLE()
70         p = BLESimplePeripheral(ble)
71         def on_rx(rx_data):
72             print("RX", rx_data)
73         p.on_write(on_rx)
74         print("Please use LightBlue to connect to ESP32.")
75         while True:
76             if p.is_connected():
77                 # Short burst of queued notifications.
78                 tx_data = input("Enter anything: ")
79                 print("Send: ", tx_data)
80                 p.send(tx_data)
81             if __name__ == "__main__":
82                 demo()

```

Define the specified UUID number for BLE vendor.

```

18     _UART_UUID = bluetooth.UUID("6E400001-B5A3-F393-E0A9-E50E24DCCA9E")
19     _UART_TX = (
20         bluetooth.UUID("6E400003-B5A3-F393-E0A9-E50E24DCCA9E"),

```

**Any concerns? ✉ support@freenove.com**

```

21     _FLAG_READ | _FLAG_NOTIFY,
22 )
23 _UART_RX = (
24     bluetooth.UUID("6E400002-B5A3-F393-E0A9-E50E24DCCA9E"),
25     _FLAG_WRITE | _FLAG_WRITE_NO_RESPONSE,
26 )

```

Write an \_irq function to manage BLE interrupt events.

```

42 def _irq(self, event, data):
43     # Track connections so we can send notifications.
44     if event == _IRQ_CENTRAL_CONNECT:
45         conn_handle, _, _ = data
46         print("New connection", conn_handle)
47         print("\nThe BLE connection is successful.")
48         self._connections.add(conn_handle)
49     elif event == _IRQ_CENTRAL_DISCONNECT:
50         conn_handle, _, _ = data
51         print("Disconnected", conn_handle)
52         self._connections.remove(conn_handle)
53         # Start advertising again to allow a new connection.
54         self._advertise()
55     elif event == _IRQ_GATTS_WRITE:
56         conn_handle, value_handle = data
57         value = self._ble.gatts_read(value_handle)
58         if value_handle == self._handle_rx and self._write_callback:
59             self._write_callback(value)

```

Initialize the BLE function and name it.

```

33 def __init__(self, ble, name="ESP32"):

```

When the mobile phone send data to ESP32 via BLE Bluetooth, it will print them out with serial port; When the serial port of ESP32 receive data, it will send them to mobile via BLE Bluetooth.

```

70 def demo():
71     ble = bluetooth.BLE()
72     p = BLESimplePeripheral(ble)
73     def on_rx(rx_data):
74         print("RX", rx_data)
75         p.on_write(on_rx)
76     print("Please use LightBlue to connect to ESP32.")
77     while True:
78         if p.is_connected():
79             # Short burst of queued notifications.
80             tx_data = input("Enter anything: ")
81             print("Send: ", tx_data)
82             p.send(tx_data)
83         lastMsg = now;
84     }

```

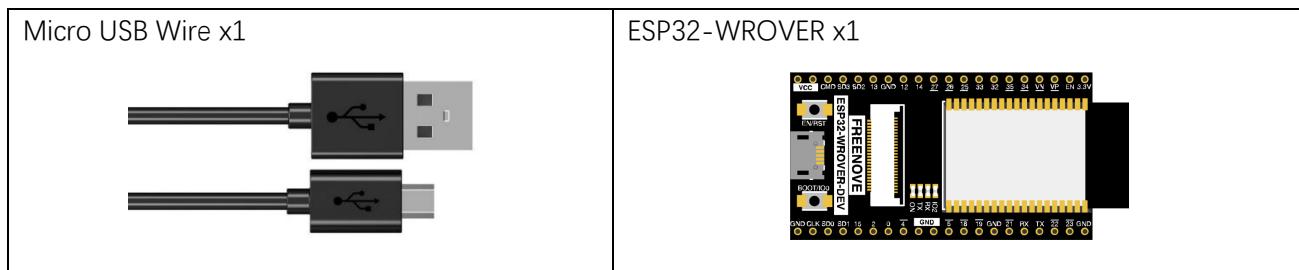
# Chapter 3 WiFi Working Modes

In this chapter, we'll focus on the WiFi infrastructure for ESP32-WROVER.

ESP32-WROVER has 3 different WiFi operating modes: Station mode, AP mode and AP+Station mode. All WiFi programming projects must be configured with WiFi operating mode before using WiFi, otherwise WiFi cannot be used.

## Project 3.1 Station mode

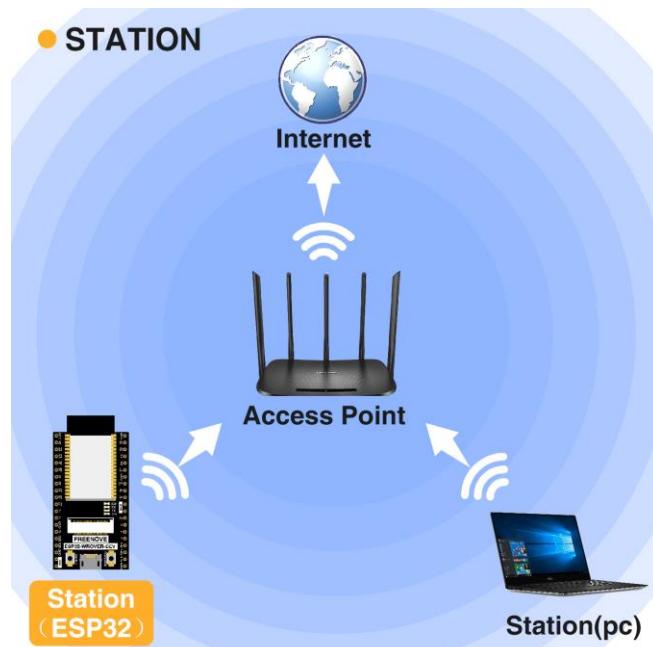
### Component List



### Component knowledge

#### Station mode

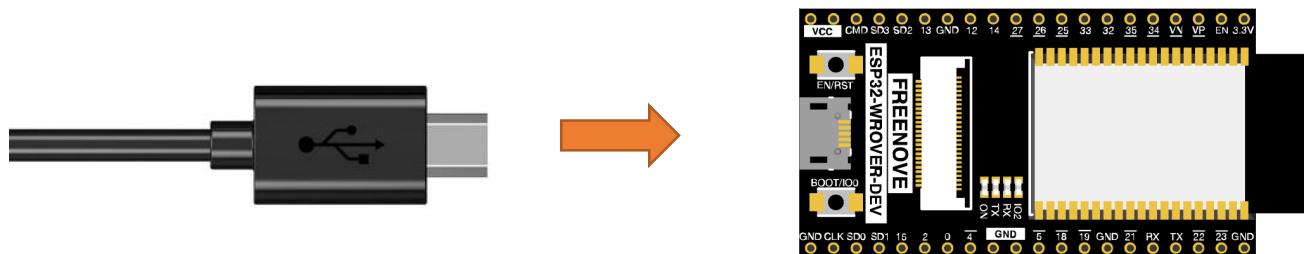
When ESP32 selects Station mode, it acts as a WiFi client. It can connect to the router network and communicate with other devices on the router via WiFi connection. As shown below, the PC is connected to the router, and if ESP32 wants to communicate with the PC, it needs to be connected to the router.



Any concerns? [✉ support@freenove.com](mailto:support@freenove.com)

## Circuit

Connect Freenove ESP32 to the computer using the USB cable.



## Code

Move the program folder “**Freenove\_ESP32\_WROVER\_Board/Python/Python\_Codes**” to disk(D) in advance with the path of “**D:/Micropython\_Codes**”.

Open “Thonny”, click “This computer” → “D:” → “Micropython\_Codes” → “03.1\_Station\_mode” and double click “Station\_mode.py”.

### 03.1\_Station\_mode

The screenshot shows the Thonny IDE interface with the following details:

- File menu:** File, Edit, View, Run, Device, Tools, Help.
- Toolbar:** Standard file operations (New, Open, Save, Run, Stop).
- Left sidebar:** Files (MicroPython device: boot.py), This computer (D:\ Micropython\_Codes\27.1\_Station\_mode, Station\_mode.py selected).
- Code editor:** Station\_mode.py content:

```

1 import time
2 import network
3
4 ssidRouter      = '*****' #Enter the router name
5 passwordRouter = '*****' #Enter the router password
6
7 def STA_Setup(ssidRouter,passwordRouter):
8     print("Setup start")
9     sta_if = network.WLAN(network.STA_IF)
10    if not sta_if.isconnected():
11        print('connecting to',ssidRouter)
12        sta_if.active(True)
13        sta_if.connect(ssidRouter,passwordRouter)
14        while not sta_if.isconnected():
15            pass
16    print('Connected, IP address:', sta_if.ifconfig())
17    print("Setup End")
18
19 try:
20     STA_Setup(ssidRouter,passwordRouter)
21 except:

```
- Shell:** MicroPython v1.18 on 2022-01-17; ESP32 module (spiram) with ESP32  
Type "help()" for more information.

A callout bubble highlights the lines `ssidRouter = '*****'` and `passwordRouter = '*****'` with the text "Enter the correct Router name and password."



Because the names and passwords of routers in various places are different, before the Code runs, users need to enter the correct router's name and password in the box as shown in the illustration above.

After making sure the router name and password are entered correctly, compile and upload codes to ESP32-WROVER, wait for ESP32 to connect to your router and print the IP address assigned by the router to ESP32 in "Shell".

```
MicroPython v1.12 on 2019-12-20; ESP32 module (spiram) with ESP32
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT

  Setup start
  connecting to FYI_2.4G
I (4155528) phy: phy_version: 4102, 2fa7a43, Jul 15 2019, 13:06:06,
0, 2
Connected, IP address: ('192.168.1.102', '255.255.255.0', '192.168.
1.1', '192.168.1.1')
  Setup End

>>>
```

The following is the program code:

```
1 import time
2 import network
3
4 ssidRouter      = '*****' #Enter the router name
5 passwordRouter = '*****' #Enter the router password
6
7 def STA_Setup(ssidRouter,passwordRouter):
8     print("Setup start")
9     sta_if = network.WLAN(network.STA_IF)
10    if not sta_if.isconnected():
11        print(' connecting to',ssidRouter)
12        sta_if.active(True)
13        sta_if.connect(ssidRouter,passwordRouter)
14        while not sta_if.isconnected():
15            pass
16        print(' Connected, IP address:', sta_if.ifconfig())
17        print("Setup End")
18
19 try:
20     STA_Setup(ssidRouter,passwordRouter)
21 except:
22     sta_if.disconnect()
```

Import network module.

```
2 import network
```

Enter correct router name and password.

```
3 const char *ssid_Router      = "*****"; //Enter the router name
4 const char *password_Router = "*****"; //Enter the router password
```

Set ESP32 in Station mode.

```
9 sta_if = network.WLAN(network.STA_IF)
```

**Any concerns? ✉ support@freenove.com**

Activate ESP32's Station mode, initiate a connection request to the router and enter the password to connect.

```
12     sta_if.active(True)
13     sta_if.connect(ssidRouter, passwordRouter)
```

Wait for ESP32 to connect to router until they connect to each other successfully.

```
14     while not sta_if.isconnected():
15         pass
```

Print the IP address assigned to ESP32-WROVER in "Shell".

```
16     print('Connected, IP address:', sta_if.ifconfig())
```

## Reference

### Class network

Before each use of **network**, please add the statement "**import network**" to the top of the python file.

**WLAN(interface\_id)**: Set to WiFi mode.

**network.STA\_IF**: Client, connecting to other WiFi access points.

**network.AP\_IF**: Access points, allowing other WiFi clients to connect.

**active(is\_active)**: With parameters, it is to check whether to activate the network interface; Without parameters, it is to query the current state of the network interface.

**scan(ssid, bssid, channel, RSSI, authmode, hidden)**: Scan for wireless networks available nearby (only scan on STA interface), return a tuple list of information about the WiFi access point.

**bssid**: The hardware address of the access point, returned in binary form as a byte object. You can use `ubinascii.hexlify()` to convert it to ASCII format.

**authmode**: Access type

|                   |     |
|-------------------|-----|
| AUTH_OPEN         | = 0 |
| AUTH_WEP          | = 1 |
| AUTH_WPA_PSK      | = 2 |
| AUTH_WPA2_PSK     | = 3 |
| AUTH_WPA_WPA2_PSK | = 4 |
| AUTH_MAX          | = 6 |

**Hidden**: Whether to scan for hidden access points

**False**: Only scanning for visible access points

**True**: Scanning for all access points including the hidden ones.

**isconnected()**: Check whether ESP32 is connected to AP in Station mode. In STA mode, it returns True if it is connected to a WiFi access point and has a valid IP address; Otherwise it returns False.

**connect(ssid, password)**: Connecting to wireless network.

**ssid**: WiFi name

**password**: WiFi password

**disconnect()**: Disconnect from the currently connected wireless network.



## Project 3.2 AP mode

### Component List & Circuit

Component List & Circuit are the same as in Section 03.1.

### Component knowledge

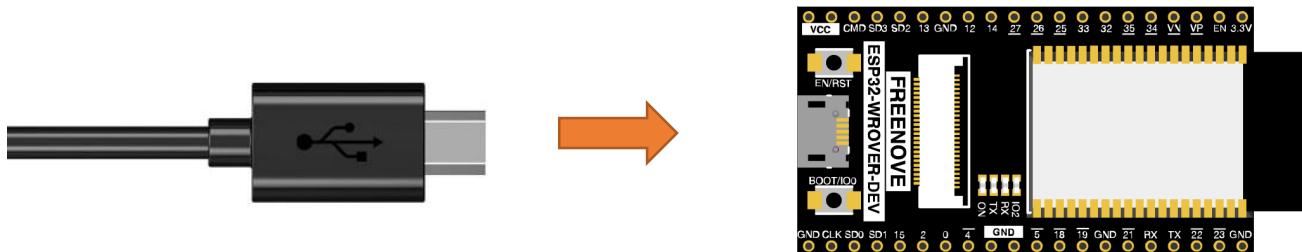
#### AP mode

When ESP32 selects AP mode, it creates a hotspot network that is separated from the Internet and waits for other WiFi devices to connect. As shown in the figure below, ESP32 is used as a hotspot. If a mobile phone or PC wants to communicate with ESP32, it must be connected to the hotspot of ESP32. Only after a connection is established with ESP32 can they communicate.



### Circuit

Connect Freenove ESP32 to the computer using the USB cable.



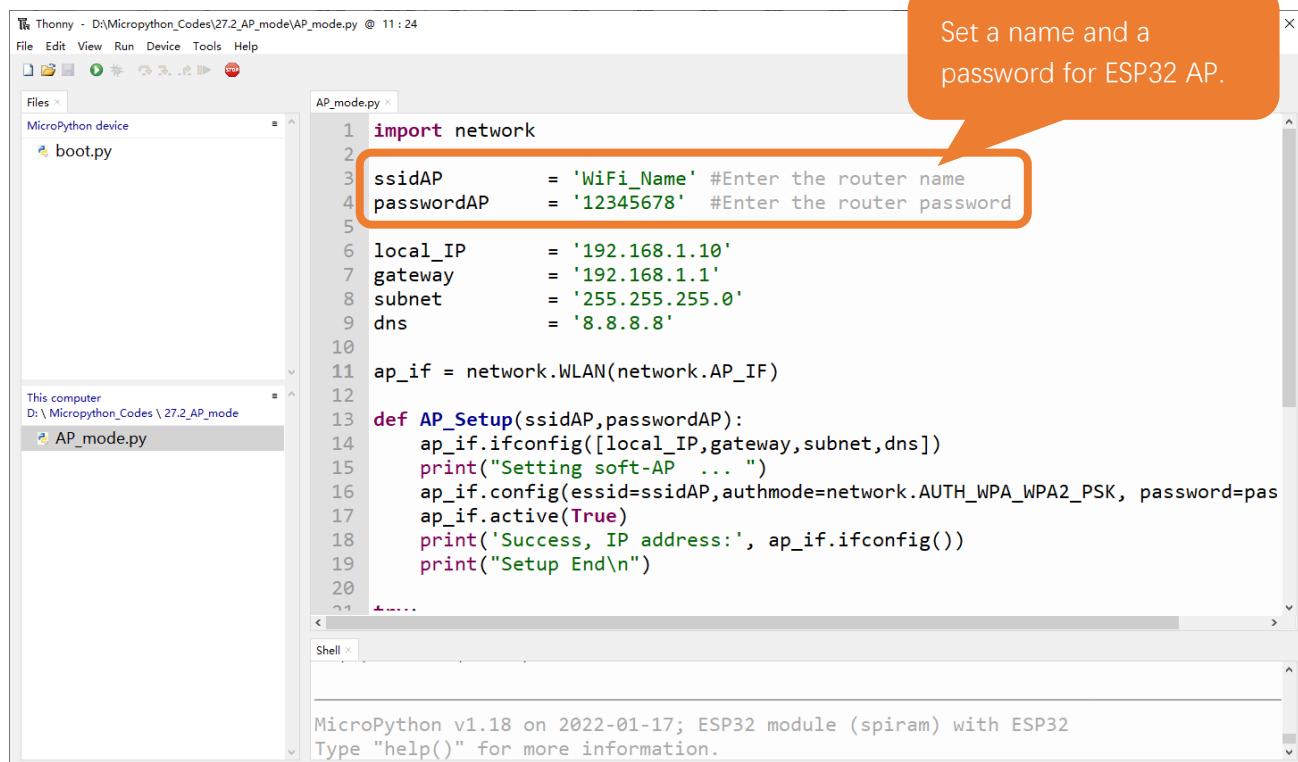
Any concerns? ✉ [support@freenove.com](mailto:support@freenove.com)

## Code

Move the program folder “**Freenove\_ESP32\_WROVER\_Board/Python/Python\_Codes**” to disk(D) in advance with the path of “**D:/Micropython\_Codes**”.

Open “Thonny”, click “This computer” → “D:” → “Micropython\_Codes” → “03.2\_AP\_mode”. and double click “AP\_mode.py”.

### 03.2\_AP\_mode



The screenshot shows the Thonny IDE interface with the file `AP_mode.py` open. The code defines a function `AP_Setup` which configures the WiFi access point settings. A callout bubble highlights the lines where the AP name and password are set:

```

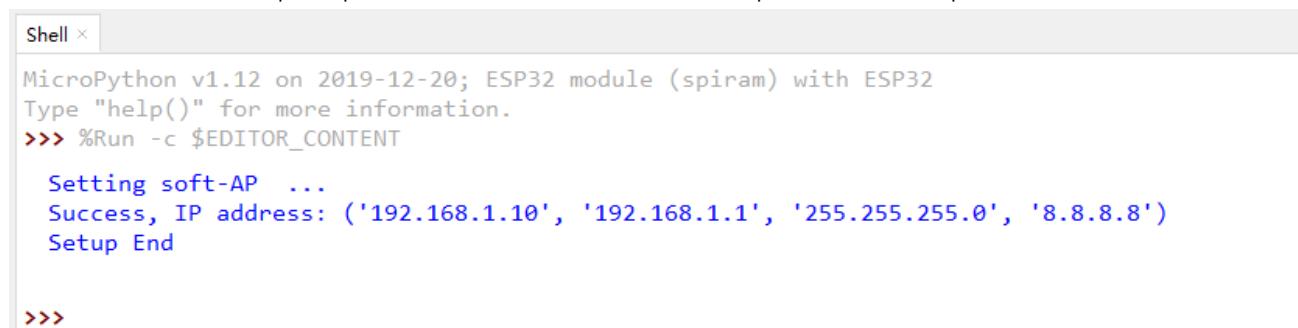
1 import network
2
3 ssidAP      = 'WiFi_Name' #Enter the router name
4 passwordAP  = '12345678' #Enter the router password
5
6 local_IP    = '192.168.1.10'
7 gateway     = '192.168.1.1'
8 subnet      = '255.255.255.0'
9 dns         = '8.8.8.8'
10
11 ap_if = network.WLAN(network.AP_IF)
12
13 def AP_Setup(ssidAP,passwordAP):
14     ap_if.ifconfig([local_IP,gateway,subnet,dns])
15     print("Setting soft-AP ... ")
16     ap_if.config(essid=ssidAP,authmode=network.AUTH_WPA_WPA2_PSK, password=passwordAP)
17     ap_if.active(True)
18     print('Success, IP address:', ap_if.ifconfig())
19     print("Setup End\n")
20
21 ...

```

Set a name and a password for ESP32 AP.

Before the Code runs, you can make any changes to the AP name and password for ESP32 in the box as shown in the illustration above. Of course, you can leave it alone by default.

Click “Run current script”, open the AP function of ESP32 and print the access point information.



The screenshot shows the Thonny Shell window displaying the output of running the `AP_mode.py` script. The output shows the WiFi access point has been successfully configured with the specified IP, gateway, subnet, and DNS settings.

```

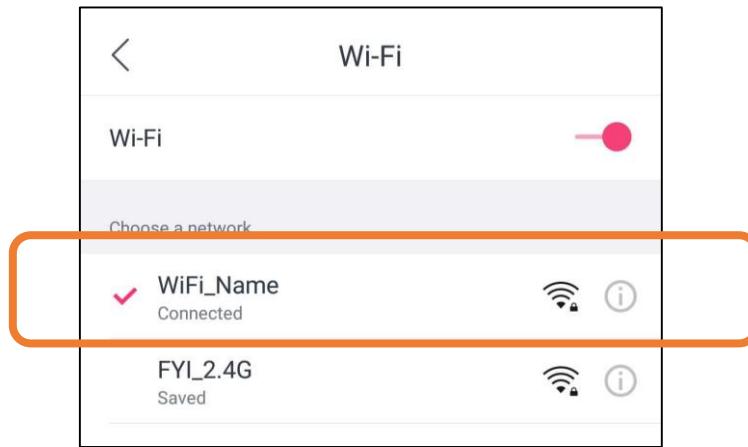
Shell x
MicroPython v1.12 on 2019-12-20; ESP32 module (spiram) with ESP32
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT
Setting soft-AP ...
Success, IP address: ('192.168.1.10', '192.168.1.1', '255.255.255.0', '8.8.8.8')
Setup End

>>>

```



Turn on the WiFi scanning function of your phone, and you can see the ssid\_AP on ESP32, which is called "WiFi\_Name" in this Code. You can enter the password "12345678" to connect it or change its AP name and password by modifying Code.



The following is the program code:

```

1 import network
2
3 ssidAP      = 'WiFi_Name' #Enter the router name
4 passwordAP  = '12345678' #Enter the router password
5
6 local_IP    = '192.168.1.10'
7 gateway     = '192.168.1.1'
8 subnet      = '255.255.255.0'
9 dns         = '8.8.8.8'
10
11 ap_if = network.WLAN(network.AP_IF)
12
13 def AP_Setup(ssidAP, passwordAP):
14     ap_if.ifconfig([local_IP, gateway, subnet, dns])
15     print("Setting soft-AP ... ")
16     ap_if.config(essid=ssidAP, authmode=network.AUTH_WPA_WPA2_PSK, password=passwordAP)
17     ap_if.active(True)
18     print(' Success, IP address:', ap_if.ifconfig())
19     print("Setup End\n")
20
21 try:
22     AP_Setup(ssidAP, passwordAP)
23 except:
24     ap_if.disconnect()

```

Import network module.

|   |                |
|---|----------------|
| 1 | import network |
|---|----------------|

Enter correct AP name and password.

```
3   ssidAP      = 'WiFi_Name' #Enter the router name
4   passwordAP  = '12345678' #Enter the router password
```

Set ESP32 in AP mode.

```
11  ap_if = network.WLAN(network.AP_IF)
```

Configure IP address, gateway and subnet mask for ESP32.

```
14  ap_if.ifconfig([local_IP, gateway, subnet, dns])
```

Turn on an AP in ESP32, whose name is set by ssid\_AP and password is set by password\_AP.

```
16  ap_if.config(essid=ssidAP, authmode=network.AUTH_WPA_WPA2_PSK, password=passwordAP)
17  ap_if.active(True)
```

If the program is running abnormally, the AP disconnection function will be called.

```
14  ap_if.disconnect()
```

## Reference

### Class network

Before each use of **network**, please add the statement “**import network**” to the top of the python file.

**WLAN(interface\_id):** Set to WiFi mode.

**network.STA\_IF:** Client, connecting to other WiFi access points

**network.AP\_IF:** Access points, allowing other WiFi clients to connect

**active(is\_active):** With parameters, it is to check whether to activate the network interface; Without parameters, it is to query the current state of the network interface

**isconnected():** In AP mode, it returns True if it is connected to the station; otherwise it returns False.

**connect(ssid, password):** Connecting to wireless network

**ssid:** WiFi name

**password:** WiFi password

**config(essid, channel):** To obtain the MAC address of the access point or to set the WiFi channel and the name of the WiFi access point.

**ssid:** WiFi account name

**channel:** WiFi channel

**ifconfig([(ip, subnet, gateway, dns)]):** Without parameters, it returns a 4-tuple (ip, subnet\_mask, gateway, DNS\_server); With parameters, it configures static IP.

**ip:** IP address

**subnet\_mask:** subnet mask

**gateway:** gateway

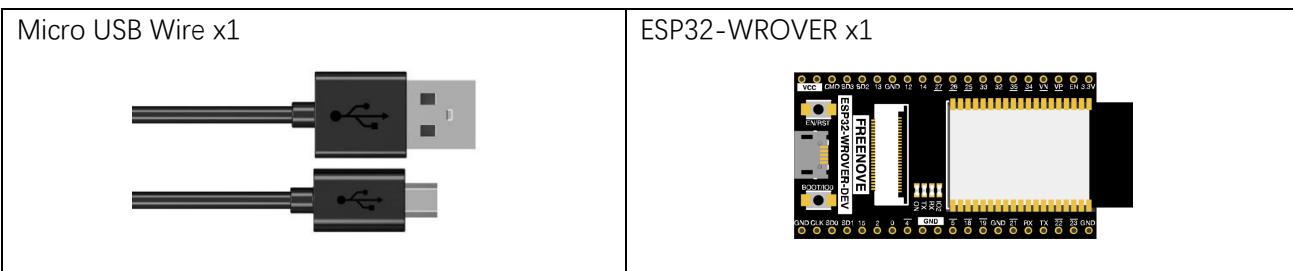
**DNS\_server:** DNS server

**disconnect():** Disconnect from the currently connected wireless network

**status():** Return the current status of the wireless connection

## Project 3.3 AP+Station mode

### Component List



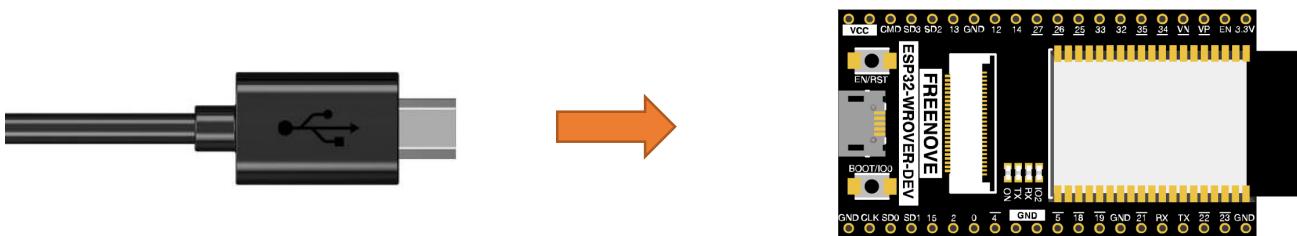
### Component knowledge

#### AP+Station mode

In addition to AP mode and Station mode, ESP32 can also use AP mode and Station mode at the same time. This mode contains the functions of the previous two modes. Turn on ESP32's Station mode, connect it to the router network, and it can communicate with the Internet via the router. At the same time, turn on its AP mode to create a hotspot network. Other WiFi devices can choose to connect to the router network or the hotspot network to communicate with ESP32.

### Circuit

Connect Freenove ESP32 to the computer using the USB cable.



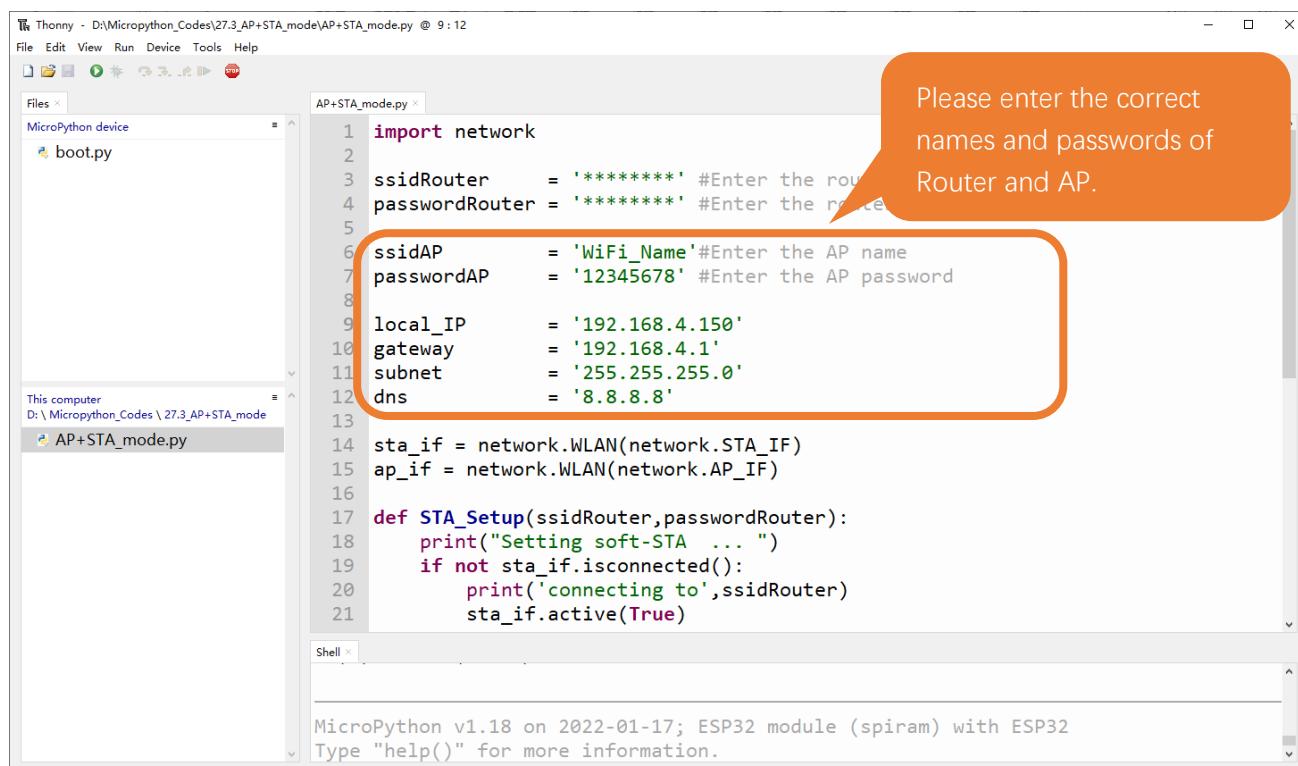
### Code

Move the program folder “**Freenove\_ESP32\_WROVER\_Board/Python/Python\_Codes**” to disk(D) in advance with the path of “**D:/Micropython\_Codes**”.

Open “Thonny”, click “This computer” → “D:” → “Micropython\_Codes” → “03.3\_AP+STA\_mode” and double click “AP+STA\_mode.py”.

**Any concerns? ✉ support@freenove.com**

### 03.3\_AP+STA\_mode



The screenshot shows the Thonny IDE interface with the file `AP+STA_mode.py` open. The code defines network parameters for both AP and STA modes. A callout bubble highlights the AP configuration section (lines 6-21) with the text: "Please enter the correct names and passwords of Router and AP".

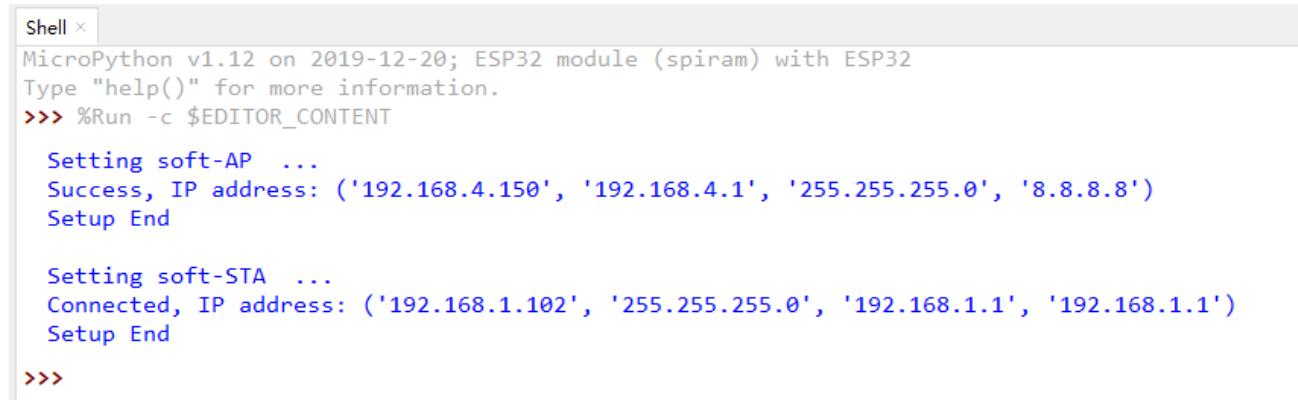
```

1 import network
2
3 ssidRouter = '*****' #Enter the router name
4 passwordRouter = '*****' #Enter the router password
5
6 ssidAP = 'WiFi_Name'#Enter the AP name
7 passwordAP = '12345678' #Enter the AP password
8
9 local_IP = '192.168.4.150'
10 gateway = '192.168.4.1'
11 subnet = '255.255.255.0'
12 dns = '8.8.8.8'
13
14 sta_if = network.WLAN(network.STA_IF)
15 ap_if = network.WLAN(network.AP_IF)
16
17 def STA_Setup(ssidRouter,passwordRouter):
18     print("Setting soft-STA ... ")
19     if not sta_if.isconnected():
20         print('connecting to',ssidRouter)
21         sta_if.active(True)

```

It is analogous to Project 3.1 and Project 3.2. Before running the Code, you need to modify `ssidRouter`, `passwordRouter`, `ssidAP` and `passwordAP` shown in the box of the illustration above.

After making sure that the code is modified correctly, click “Run current script” and the “Shell” will display as follows:



The screenshot shows the Thonny Shell window displaying the output of the code execution. It shows the setup of the soft-AP and soft-STA, including IP addresses assigned by the DHCP server.

```

Shell < 
MicroPython v1.18 on 2022-01-17; ESP32 module (spiram) with ESP32
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT

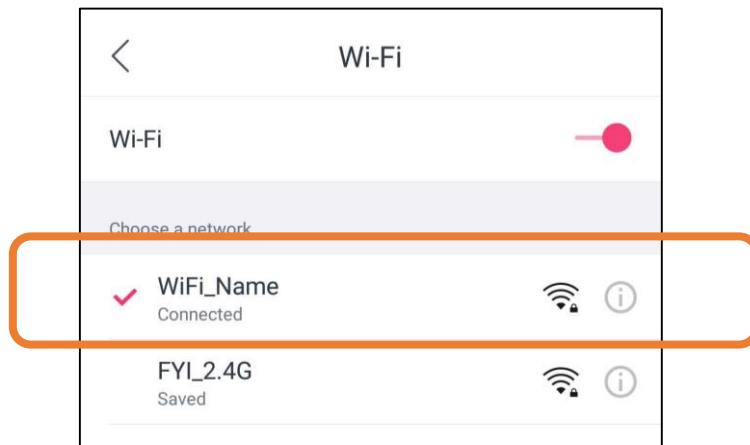
Setting soft-AP ...
Success, IP address: ('192.168.4.150', '192.168.4.1', '255.255.255.0', '8.8.8.8')
Setup End

Setting soft-STA ...
Connected, IP address: ('192.168.1.102', '255.255.255.0', '192.168.1.1', '192.168.1.1')
Setup End

>>>

```

Turn on the WiFi scanning function of your phone, and you can see the ssidAP on ESP32.



The following is the program code:

```

1 import network
2
3 ssidRouter      = '*****' #Enter the router name
4 passwordRouter = '*****' #Enter the router password
5
6 ssidAP         = 'WiFi_Name'#Enter the AP name
7 passwordAP     = '12345678' #Enter the AP password
8
9 local_IP       = '192.168.4.150'
10 gateway        = '192.168.4.1'
11 subnet         = '255.255.255.0'
12 dns            = '8.8.8.8'
13
14 sta_if = network.WLAN(network.STA_IF)
15 ap_if = network.WLAN(network.AP_IF)
16
17 def STA_Setup(ssidRouter, passwordRouter):
18     print("Setting soft-STA ... ")
19     if not sta_if.isconnected():
20         print(' connecting to',ssidRouter)
21         sta_if.active(True)
22         sta_if.connect(ssidRouter, passwordRouter)
23         while not sta_if.isconnected():
24             pass
25     print('Connected, IP address:', sta_if.ifconfig())
26     print("Setup End")
27
28 def AP_Setup(ssidAP, passwordAP):
29     ap_if.ifconfig([local_IP, gateway, subnet, dns])
30     print("Setting soft-AP ... ")

```

Any concerns? ✉ support@freenove.com

```
31     ap_if.config(essid=ssidAP, authmode=network.AUTH_WPA_WPA2_PSK, password=passwordAP)
32     ap_if.active(True)
33     print(' Success, IP address:', ap_if.ifconfig())
34     print("Setup End\n")
35
36 try:
37     AP_Setup(ssidAP, passwordAP)
38     STA_Setup(ssidRouter, passwordRouter)
39 except:
40     sta_if.disconnect()
41     ap_if.disconnect()
```

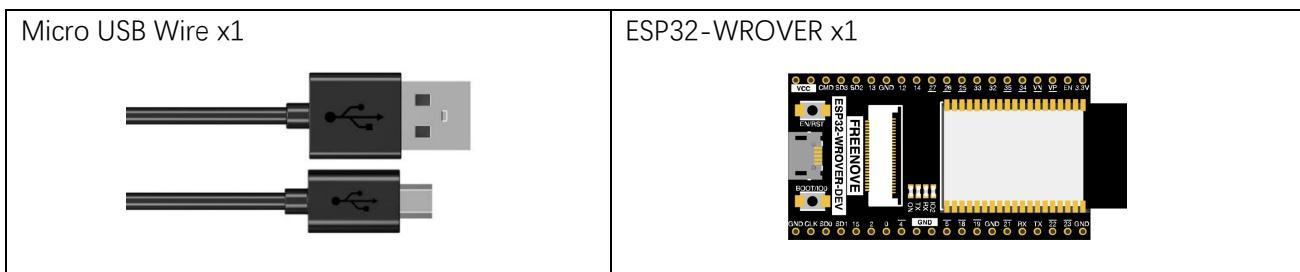
# Chapter 4 TCP/IP

In this chapter, we will introduce how ESP32 implements network communications based on TCP/IP protocol. There are two roles in TCP/IP communication, namely Server and Client, which will be implemented respectively with two projects in this chapter.

## Project 4.1 As Client

In this section, ESP32 is used as Client to connect Server on the same LAN and communicate with it.

## Component List



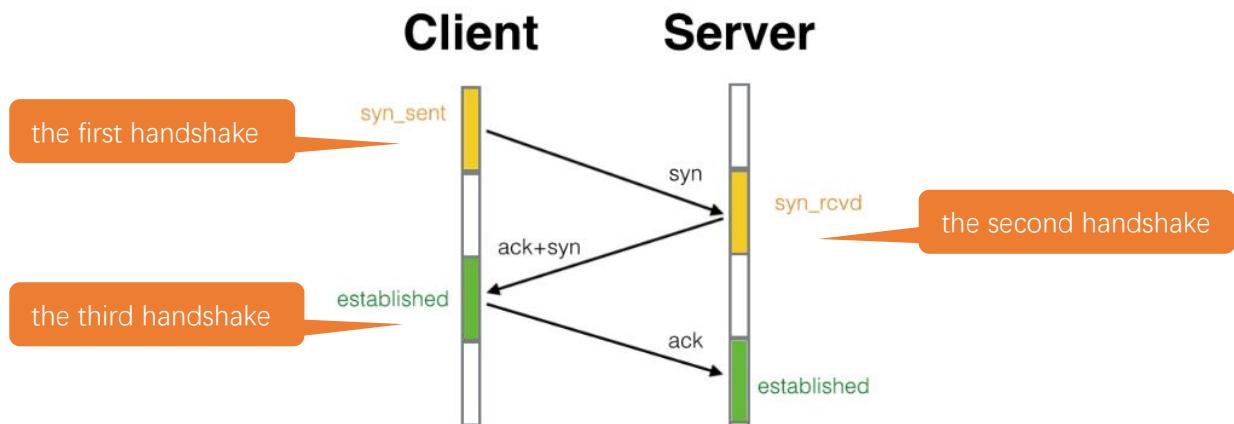
# Component knowledge

## TCP connection

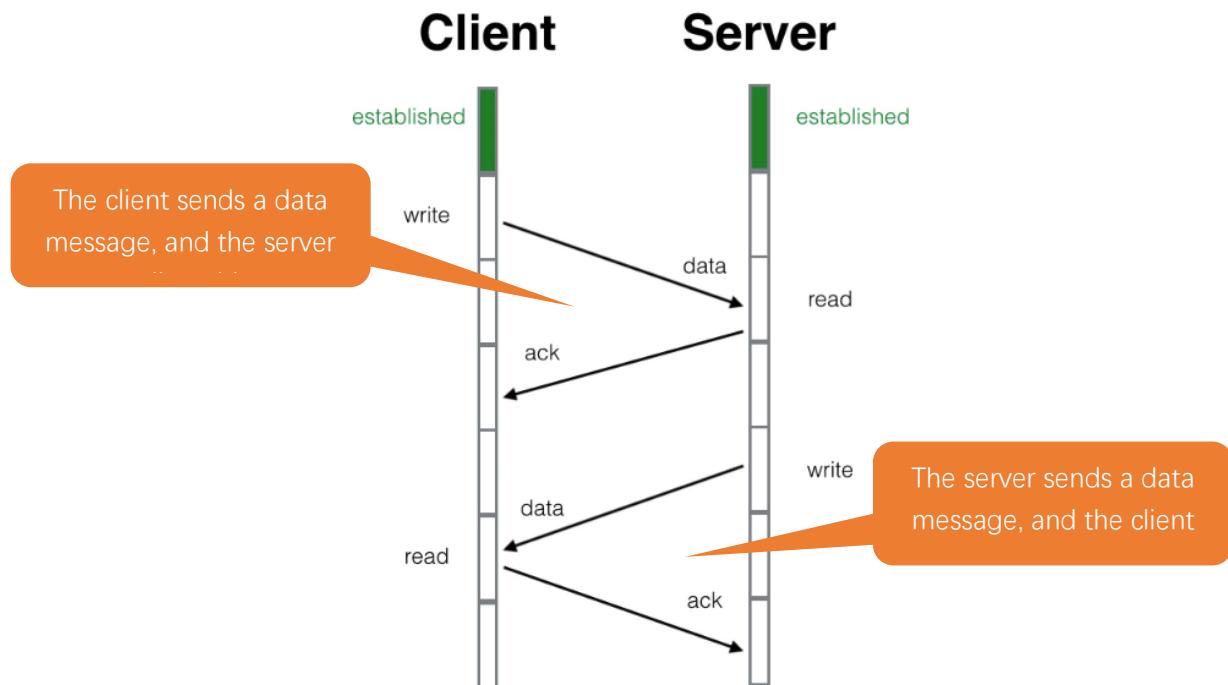
Before transmitting data, TCP needs to establish a logical connection between the sending end and the receiving end. It provides reliable and error-free data transmission between the two computers. In the TCP connection, the client and the server must be clarified. The client sends a connection request to the server, and each time such a request is proposed, a "three-times handshake" is required.

**Three-times handshake:** In the TCP protocol, during the preparation phase of sending data, the client and the server interact three times to ensure the reliability of the connection, which is called "three-times handshake". The first handshake, the client sends a connection request to the server and waits for the server to confirm. The second handshake, the server sends a response back to the client informing that it has received the connection request.

The third handshake, the client sends a confirmation message to the server again to confirm the connection.



TCP is a connection-oriented, low-level transmission control protocol. After TCP establishes a connection, the client and server can send and receive messages to each other, and the connection will always exist as long as the client or server does not initiate disconnection. Each time one party sends a message, the other party will reply with an ack signal.





## Install Processing

In this tutorial, we use Processing to build a simple TCP/IP communication platform.

If you've not installed Processing, you can download it by clicking <https://processing.org/download/>. You can choose an appropriate version to download according to your PC system.

The screenshot shows the official Processing website's download section. At the top, there's a navigation bar with links for "Processing", "p5.js", "Processing.py", "Processing for Android", "Processing for Pi", and "Processing Foundation". Below the navigation is a large "Processing" logo with a geometric background. To the right is a search bar. On the left, there's a sidebar with links: "Cover", "Download", "Donate", "Exhibition", "Reference", "Libraries", "Tools", "Environment", "Tutorials", "Examples", "Books", "Overview", and "People". The main content area features a large "3.5.4 (17 January 2020)" release note. It includes download links for "Windows 64-bit", "Windows 32-bit", "Linux 64-bit", and "Mac OS X". Below the release note, there are links to "» Github", "» Report Bugs", "» Wiki", "» Supported Platforms", and a link to "Read about the changes in 3.0. The list of revisions covers the differences between releases in detail."

Unzip the downloaded file to your computer. Click "processing.exe" as the figure below to run this software.

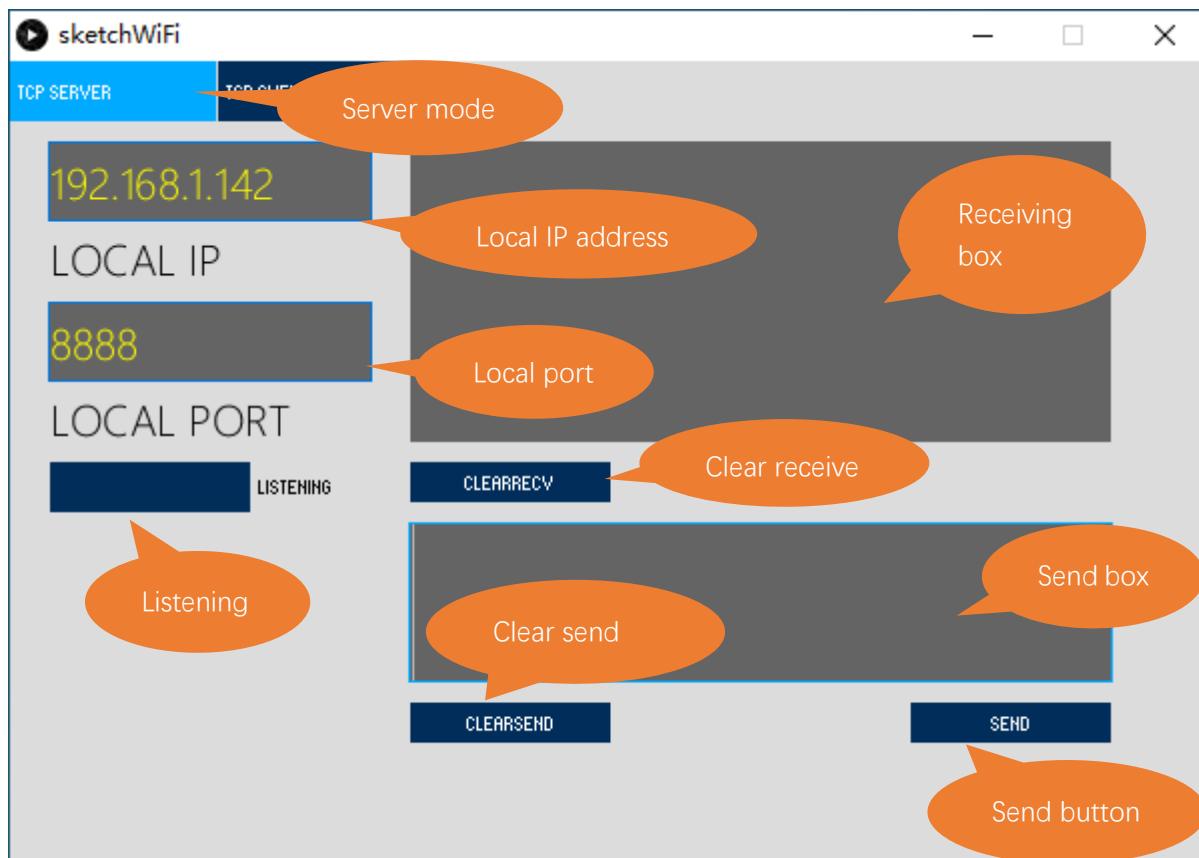
|                     |                 |
|---------------------|-----------------|
| core                | 2020/1/17 12:16 |
| java                | 2020/1/17 12:17 |
| lib                 | 2020/1/17 12:16 |
| modes               | 2020/1/17 12:16 |
| tools               | 2020/1/17 12:16 |
| processing.exe      | 2020/1/17 12:16 |
| processing-java.exe | 2020/1/17 12:16 |
| revisions.txt       | 2020/1/17 12:16 |

Use Server mode for communication

Open the “Freenove\_ESP32\_WROVER\_Board/Codes/Micropython\_Codes/04.1\_TCP\_as\_Client/sketchWiFi/sketchWiFi.pde”. Click “Run”.

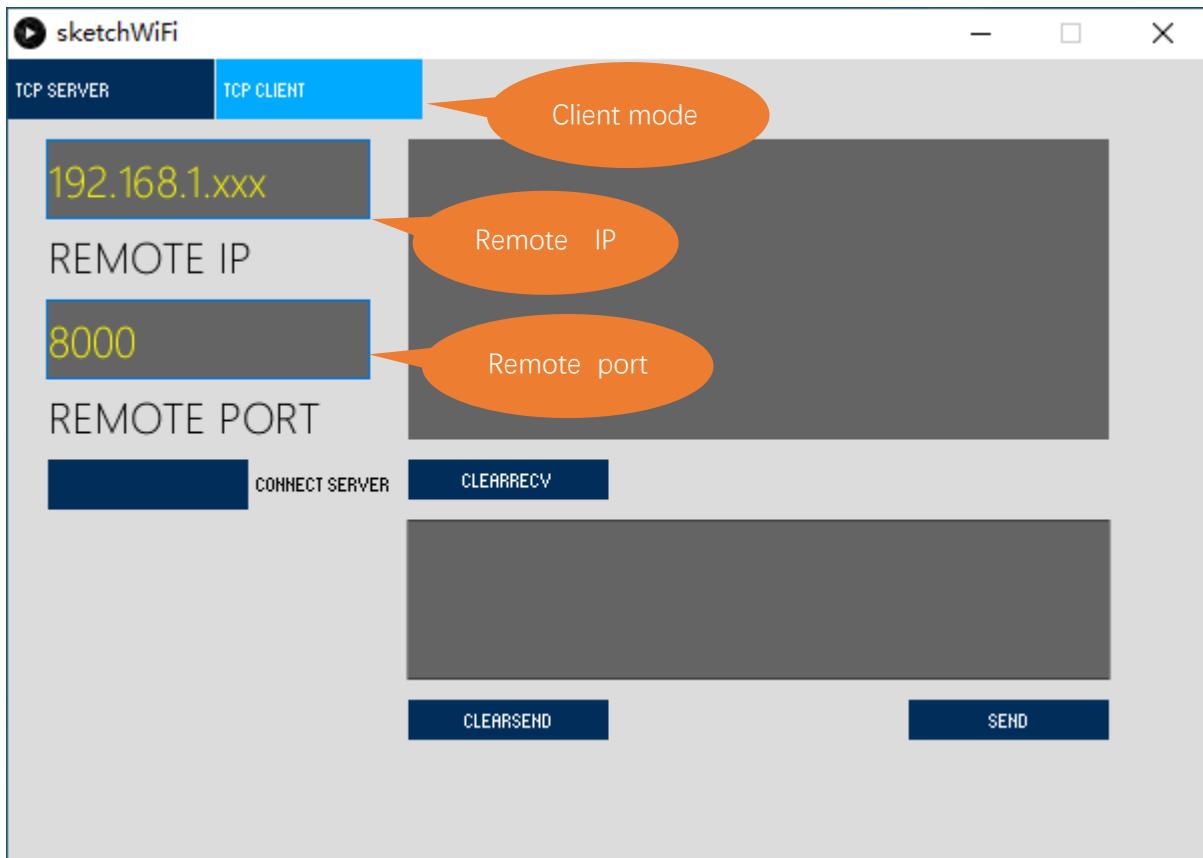


The new pop-up interface is as follows. If ESP32 is used as Client, select TCP SERVER mode for sketchWiFi.



When sketchWiFi selects TCP SERVER mode, ESP32 Code needs to be changed according to sketchWiFi's displaying of LOCAL IP or LOCAL PORT.

If ESP32 serves as Server, select TCP CLIENT mode for sketchWiFi.



When sketchWiFi selects TCP CLIENT mode, the LOCAL IP and LOCAL PORT of sketchWiFi need to be changed according to the IP address and port number printed by the serial monitor.

**Mode selection:** select **Server mode/Client mode**.

**IP address:** In Server mode, this option does not need to be filled in, and the computer will automatically obtain the IP address.

In Client mode, fill in the remote IP address to be connected.

**Port number:** In Server mode, fill in a port number for client devices to make an access connection.

In client mode, fill in port number given by the Server devices to make an access connection.

**Start button:** In server mode, push the button, and then the computer will serve as Server and open a port number for Client to make access connection. During this period, the computer will keep monitoring.

In client mode, before pushing the button, please make sure the server is on, remote IP address and remote port number is correct; push the button, and the computer will make access connection to the remote port number of the remote IP as a Client.

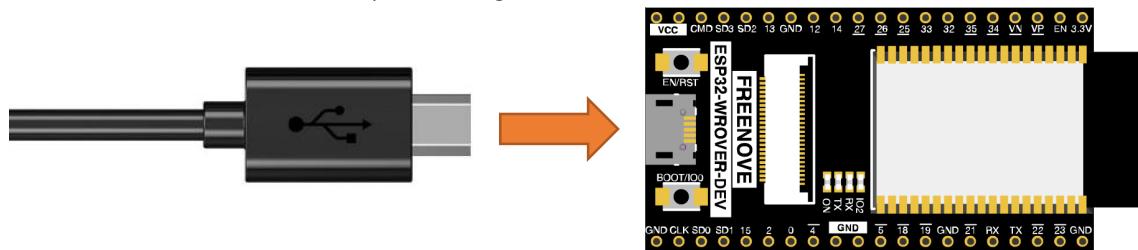
**clear receive:** clear out the content in the receiving text box

**clear send:** clear out the content in the sending text box

**Sending button:** push the sending button, the computer will send the content in the text box to others.

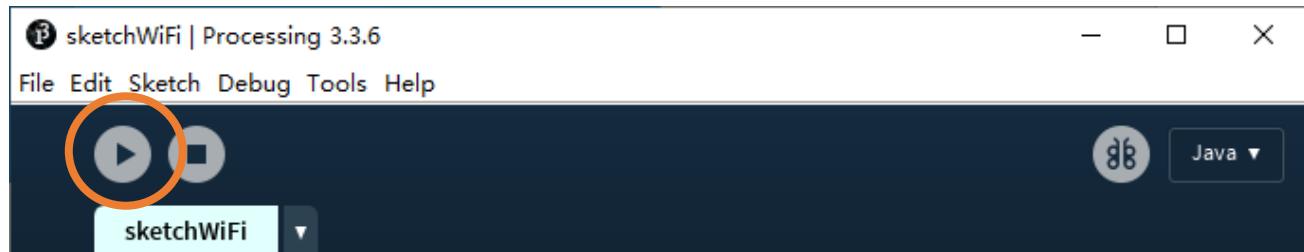
## Circuit

Connect Freenove ESP32 to the computer using USB cable.

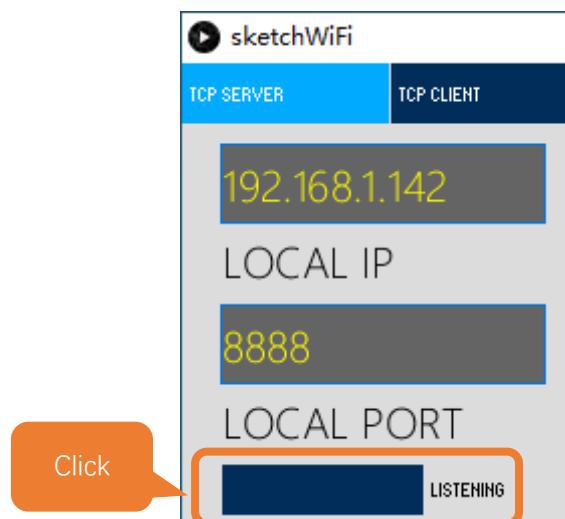


## Code

Before running the Code, please open “sketchWiFi.pde.” first, and click “Run”.



The newly pop up window will use the computer's IP address by default and open a data monitor port. Click “Listening”.



Move the program folder "Freenove\_ESP32\_WROVER\_Board/Python/Python\_Codes" to disk(D) in advance with the path of "D:/Micropython\_Codes".

Open “Thonny”, click “This computer” → “D:” → “Micropython\_Codes” → “04.1\_TCP\_as\_Client” and double click “TCP\_as\_Client.py”.

Before clicking “Run current script”, please modify the name and password of your router and fill in the “host” and “port” according to the IP information shown in the box below:

## 04.1\_TCP\_as\_Client

The screenshot shows the Thonny IDE interface with the following details:

- Title Bar:** Thonny - D:\Micropython\_Codes\28.1\_TCP\_as\_Client\TCP\_as\_Client.py @ 43 : 21
- Menu Bar:** File, Edit, View, Run, Device, Tools, Help
- Toolbar:** Includes icons for file operations like Open, Save, Run, Stop, and Help.
- Left Sidebar:** Shows the project structure:
  - MicroPython device
  - boot.py
  - This computer
  - D:\ Micropython\_Codes \ 28.1\_TCP\_as\_Client
    - sketchWiFi
    - TCP\_as\_Client.py (selected)
- Code Editor:** The main window displays the code for `TCP_as_Client.py`. A red box highlights the configuration section:

```
1 import network
2 import socket
3 import time
4
5 ssidRouter      = "*****"          #Enter the router name
6 passwordRouter = "*****"          #Enter the router password
7 host           = "192.168.1.142"    #input the remote server
8 port           = 8888              #input the remote port
9
10 wlan=None
11 s=None
12
13 def connectWifi(ssid,password):
14     global wlan
15     wlan=network.WLAN(network.STA_IF)
16     wlan.active(True)
17     wlan.disconnect()
18     wlan.connect(ssid,password)
19     while(wlan.ifconfig()[0]=='0.0.0.0'):
20         time.sleep(1)
21     return True
```
- Shell:** At the bottom, it shows the MicroPython prompt:

```
MicroPython v1.18 on 2022-01-17; ESP32 module (spiram) with ESP32
Type "help()" for more information.
```

Click “Run current script” and in “Shell”, you can see ESP32-WROVER automatically connects to sketchWiFi.

```
Shell x

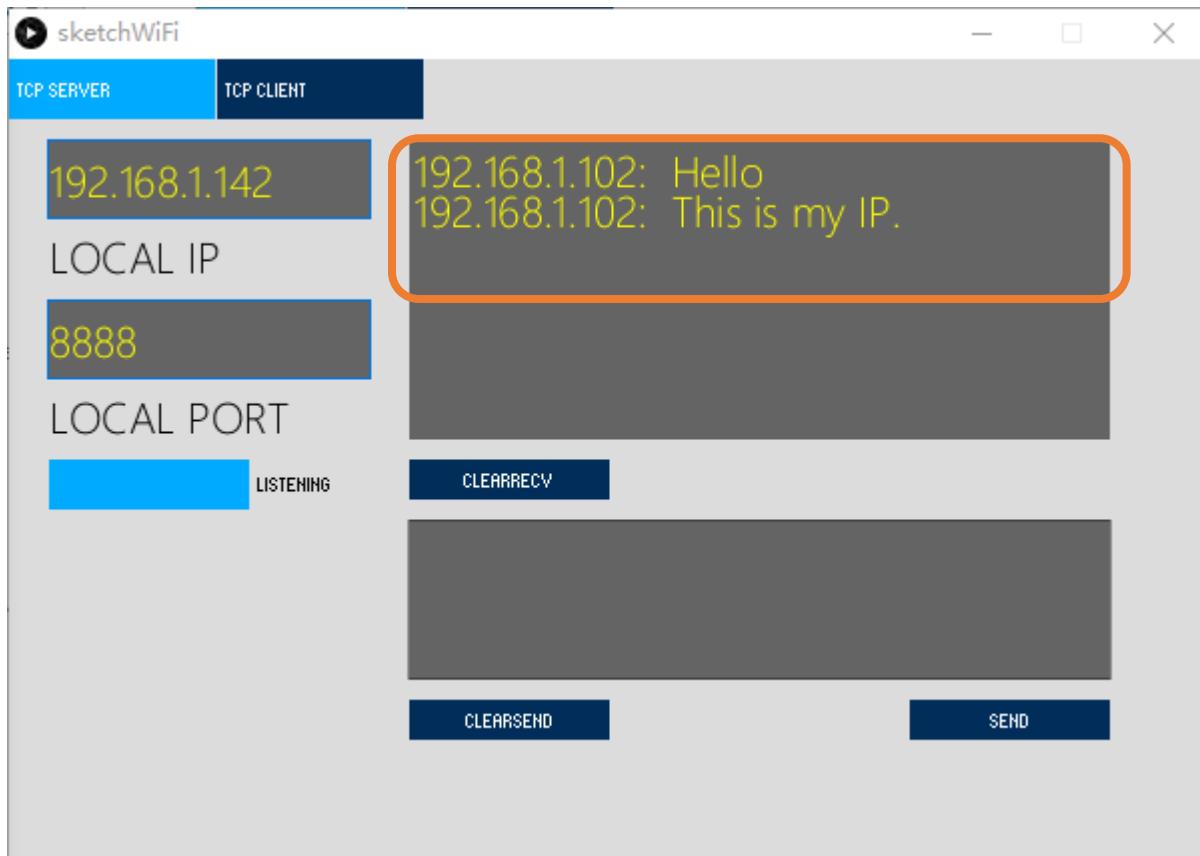
MicroPython v1.12 on 2019-12-20; ESP32 module with ESP32
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT

TCP Connected to: 192.168.1.142 : 8888
```

If you don't click "Listening" for sketchWiFi, ESP32-WROVER will fail to connect and will print information as follows:

```
Shell x
for connected to: 192.168.1.142 : 8888
Close socket
>>> %Run -c $EDITOR_CONTENT
TCP close, please reset!
>>>
```

ESP32 connects with TCP SERVER, and TCP SERVER receives messages from ESP32, as shown in the figure below.



The following is the program code:

```
1 import network
2 import socket
3 import time
4
5 ssidRouter      = "*****"          #Enter the router name
6 passwordRouter = "*****"          #Enter the router password
7 host           = "*****"          #input the remote server
8 port           = 8888              #input the remote port
9
10 wlan=None
11 s=None
```

```

12
13 def connectWifi(ssid,passwd):
14     global wlan
15     wlan= network.WLAN(network.STA_IF)
16     wlan.active(True)
17     wlan.disconnect()
18     wlan.connect(ssid,passwd)
19     while(wlan.ifconfig()[0]=='0.0.0.0'):
20         time.sleep(1)
21     return True
22 try:
23     connectWifi(ssidRouter,passwordRouter)
24     s = socket.socket()
25     s.setsockopt(socket.SOL_SOCKET, socket.SO_REUSEADDR, 1)
26     s.connect((host,port))
27     print("TCP Connected to:", host, ":", port)
28     s.send('Hello')
29     s.send('This is my IP.')
30     while True:
31         data = s.recv(1024)
32         if(len(data) == 0):
33             print("Close socket")
34             s.close()
35             break
36         print(data)
37         ret=s.send(data)
38 except:
39     print("TCP close, please reset!")
40     if (s):
41         s.close()
42     wlan.disconnect()
43     wlan.active(False)

```

Import network、socket、time modules.

```

1 import network
2 import socket
3 import time

```

Enter the actual router name, password, remote server IP address, and port number.

```

5 ssidRouter      = "*****"      #Enter the router name
6 passwordRouter = "*****"      #Enter the router password
7 host           = "*****"      #input the remote server
8 port           = 8888          #input the remote port

```

Connect specified Router until it is successful.

```
13 def connectWifi(ssid,passwd):  
14     global wlan  
15     wlan= network.WLAN(network.STA_IF)  
16     wlan.active(True)  
17     wlan.disconnect()  
18     wlan.connect(ssid,passwd)  
19     while(wlan.ifconfig()[0]=='0.0.0.0'):  
20         time.sleep(1)  
21     return True
```

Connect router and then connect it to remote server.

```
23     connectWifi(ssidRouter,passwordRouter)  
24     s = socket.socket()  
25     s.setsockopt(socket.SOL_SOCKET, socket.SO_REUSEADDR, 1)  
26     s.connect((host,port))  
27     print("TCP Connected to:", host, ":", port)
```

Send messages to the remote server, receive the messages from it and print them out, and then send the messages back to the server.

```
28     s.send('Hello')  
29     s.send('This is my IP.')  
30     while True:  
31         data = s.recv(1024)  
32         if(len(data) == 0):  
33             print("Close socket")  
34             s.close()  
35             break  
36         print(data)  
37         ret=s.send(data)
```

If an exception occurs in the program, for example, the remote server is shut down, execute the following program, turn off the socket function, and disconnect the WiFi.

```
39     print("TCP close, please reset!")  
40     if (s):  
41         s.close()  
42         wlan.disconnect()  
43         wlan.active(False)
```

## Reference

### Class socket

Before each use of **socket**, please add the statement “**import socket**” to the top of the python file.

**socket([af, type, proto]):** Create a socket.

**af:** address

**socket.AF\_INET:** IPv4

**socket.AF\_INET6:** IPv6

**type:** type

**socket.SOCK\_STREAM** : TCP stream

**socket.SOCK\_DGRAM** : UDP datagram

**socket.SOCK\_RAW** : Original socket

**socket.SO\_REUSEADDR** : socket reusable

**proto:** protocol number

**socket.IPPROTO\_TCP**: TCPmode

**socket.IPPROTO\_UDP**: UDPmode

**socket.setsockopt(level, optname, value):** Set the socket according to the options.

**Level:** Level of socket option

**socket.SOL\_SOCKET**: Level of socket option. By default, it is 4095.

**optname:** Options of socket

**socket.SO\_REUSEADDR**: Allowing a socket interface to be tied to an address that is already in use.

**value:** The value can be an integer or a bytes-like object representing a buffer.

**socket.connect(address):** To connect to server.

**Address:** Tuple or list of the server's address and port number

**send(bytes):** Send data and return the bytes sent.

**recv(bufsize):** Receive data and return a bytes object representing the data received.

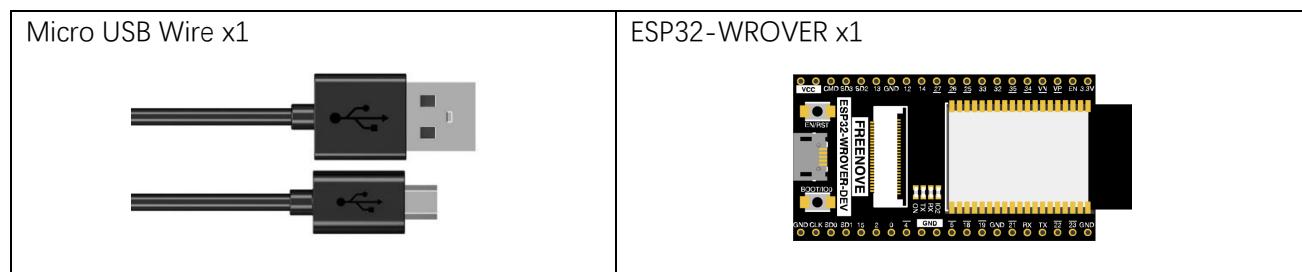
**close():** Close socket.

To learn more please visit: <http://docs.micropython.org/en/latest/>

## Project 4.2 As Server

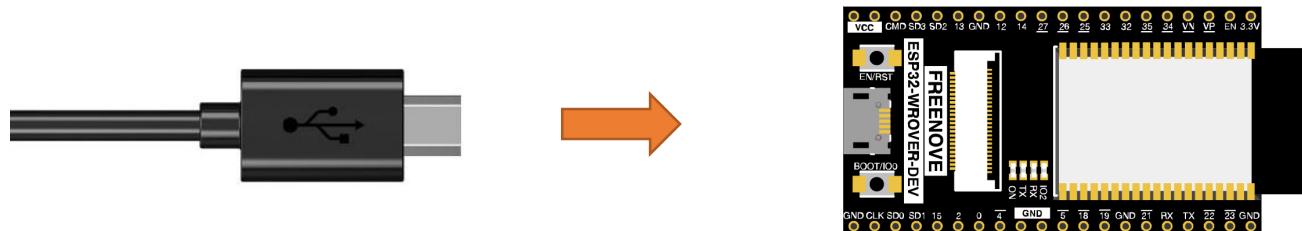
In this section, ESP32 is used as a Server to wait for the connection and communication with Client on the same LAN.

### Component List



### Circuit

Connect Freenove ESP32 to the computer using the USB cable.



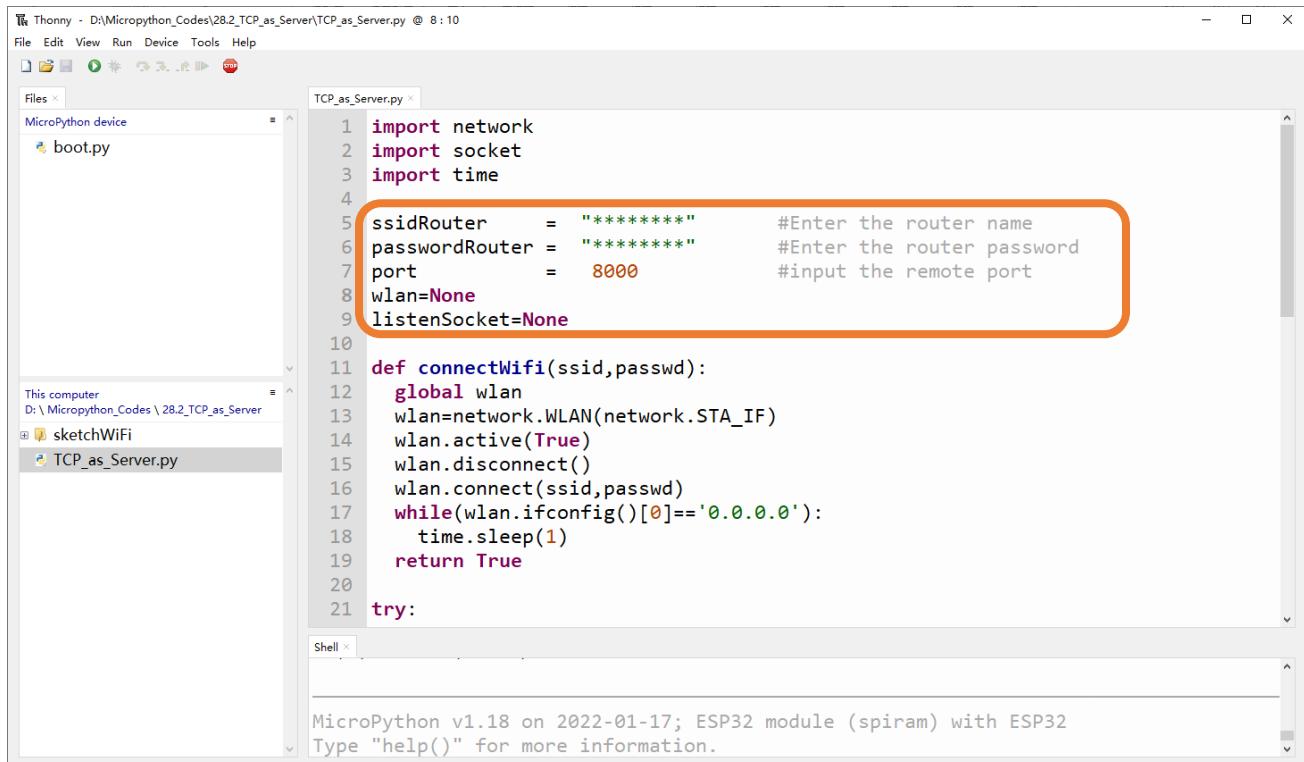
## Code

Move the program folder “**Freenove\_ESP32\_WROVER\_Board/Python/Python\_Codes**” to disk(D) in advance with the path of “**D:/Micropython\_Codes**”.

Open “Thonny”, click “This computer” → “D:” → “Micropython\_Codes” → “04.2\_TCP\_as\_Server” and double click “TCP\_as\_Server.py”.

Before clicking “Run current script”, please modify the name and password of your router shown in the box below.

### 04.2\_TCP\_as\_Server



```

import network
import socket
import time

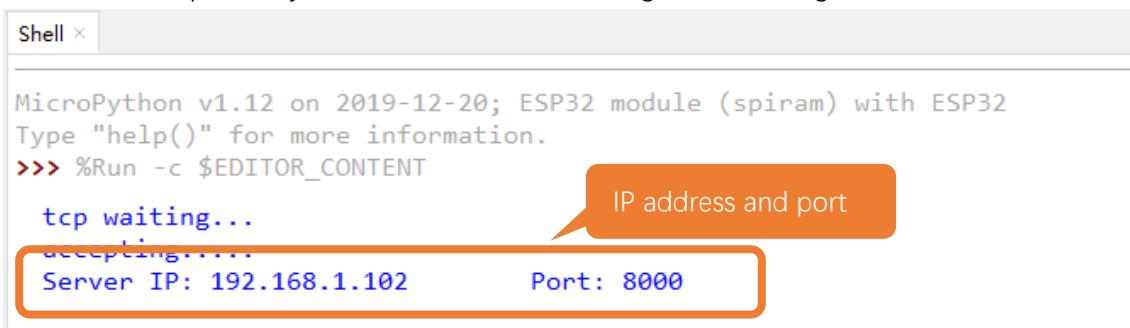
ssidRouter = "*****" #Enter the router name
passwordRouter = "*****" #Enter the router password
port = 8000 #input the remote port
wlan=None
listenSocket=None

def connectWifi(ssid,passwd):
    global wlan
    wlan=network.WLAN(network.STA_IF)
    wlan.active(True)
    wlan.disconnect()
    wlan.connect(ssid,passwd)
    while(wlan.ifconfig()[0]=='0.0.0.0'):
        time.sleep(1)
    return True

try:

```

After making sure that the router's name and password are correct, click “Run current script” and in “Shell”, you can see a server opened by the ESP32- WROVER waiting to connecting to other network devices.



```

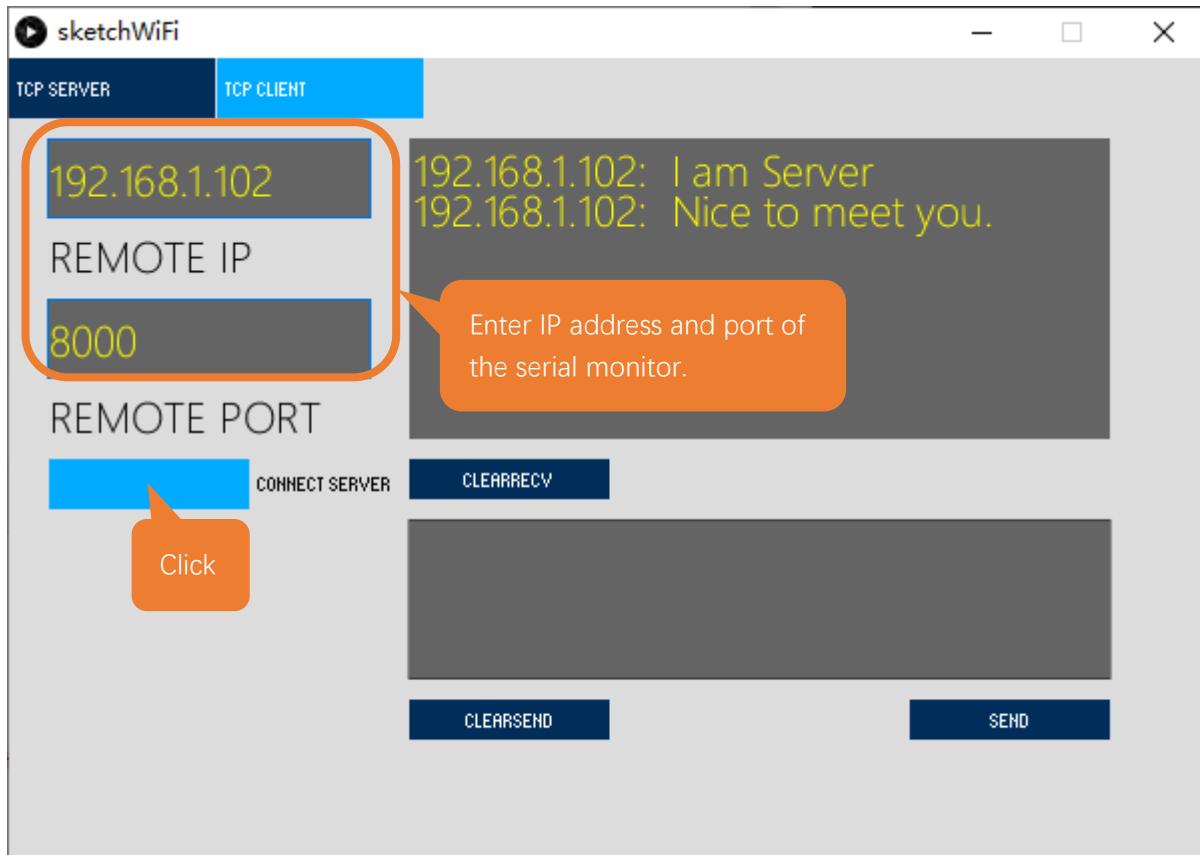
MicroPython v1.12 on 2019-12-20; ESP32 module (spiram) with ESP32
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT
tcp waiting...
accepting...
Server IP: 192.168.1.102
Port: 8000

```

Processing:

Open the “Freenove\_ESP32\_WROVER\_Board/Codes/MicroPython\_Codes/04.2\_TCP\_as\_Server/sketchWiFi/sketchWiFi.pde”.

Based on the message printed in "Shell", enter the correct IP address and port when processing, and click to establish a connection with ESP32 to communicate.



You can enter any information in the “Send Box” of sketchWiFi. Click “Send” and ESP32 will print the received messages to “Shell” and send them back to sketchWiFi.

```
Shell <input>
MicroPython v1.12 on 2019-12-20; ESP32 module (spiram) with ESP32
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT
tcp waiting...
accepting.....
Server IP: 192.168.1.102      Port: 8000
('192.168.1.142', 51326) connected
b'Nice to meet you.'
```

The following is the program code:

```
1 import network
2 import socket
3 import time
4
5 ssidRouter      = "*****"          #Enter the router name
6 passwordRouter = "*****"          #Enter the router password
7 port           = 8000             #input the remote port
8 wlan            = None
9 listenSocket    = None
10
11 def connectWifi(ssid,passwd):
12     global wlan
13     wlan=network.WLAN(network.STA_IF)
14     wlan.active(True)
15     wlan.disconnect()
16     wlan.connect(ssid,passwd)
17     while(wlan.ifconfig()[0]=='0.0.0.0'):
18         time.sleep(1)
19     return True
20
21 try:
22     connectWifi(ssidRouter,passwordRouter)
23     ip=wlan.ifconfig()[0]
24     listenSocket = socket.socket()
25     listenSocket.bind((ip,port))
26     listenSocket.listen(1)
27     listenSocket.setsockopt(socket.SOL_SOCKET, socket.SO_REUSEADDR, 1)
28     print('tcp waiting...')
29     while True:
30         print("Server IP:",ip,"\tPort:",port)
31         print("accepting.....")
32         conn,addr = listenSocket.accept()
33         print(addr, "connected")
34         break
35     conn.send('I am Server')
36     while True:
37         data = conn.recv(1024)
38         if(len(data) == 0):
39             print("close socket")
40             listenSocket.close()
41             wlan.disconnect()
42             wlan.active(False)
43             break
```

```

44     else:
45         print(data)
46         ret = conn.send(data)
47     except:
48         print("Close TCP-Server, please reset.")
49         if(listenSocket):
50             listenSocket.close()
51             wlan.disconnect()
52             wlan.active(False)

```

Call function `connectWifi()` to connect to router and obtain the dynamic IP that it assigns to ESP32.

```

22     connectWifi(ssidRouter, passwordRouter)
23     ip=wlan.ifconfig()[0]

```

Open the socket server, bind the server to the dynamic IP, and open a data monitoring port.

```

24     listenSocket = socket.socket()
25     listenSocket.bind((ip, port))
26     listenSocket.listen(1)
27     listenSocket.setsockopt(socket.SOL_SOCKET, socket.SO_REUSEADDR, 1)

```

Print the server's IP address and port, monitor the port and wait for the connection of other network devices.

```

29     while True:
30         print("Server IP:", ip, "\tPort:", port)
31         print("accepting.....")
32         conn, addr = listenSocket.accept()
33         print(addr, "connected")
34         break

```

Each time receiving data, print them in “Shell” and send them back to the client.

```

36     while True:
37         data = conn.recv(1024)
38         if(len(data) == 0):
39             print("close socket")
40             listenSocket.close()
41             wlan.disconnect()
42             wlan.active(False)
43             break
44         else:
45             print(data)
46             ret = conn.send(data)

```

If the client is disconnected, close the server and disconnect WiFi.

```

47     except:
48         print("Close TCP-Server, please reset.")
49         if(listenSocket):
50             listenSocket.close()
51             wlan.disconnect()
52             wlan.active(False)

```



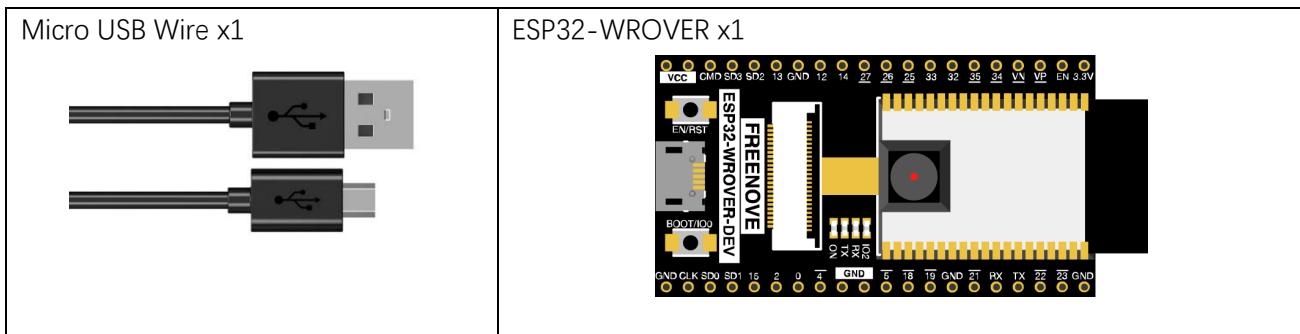
# Chapter 5 Camera Web Server

In this section, we'll use ESP32's video function as an example to study.

## Project 5.1 Camera Web Server

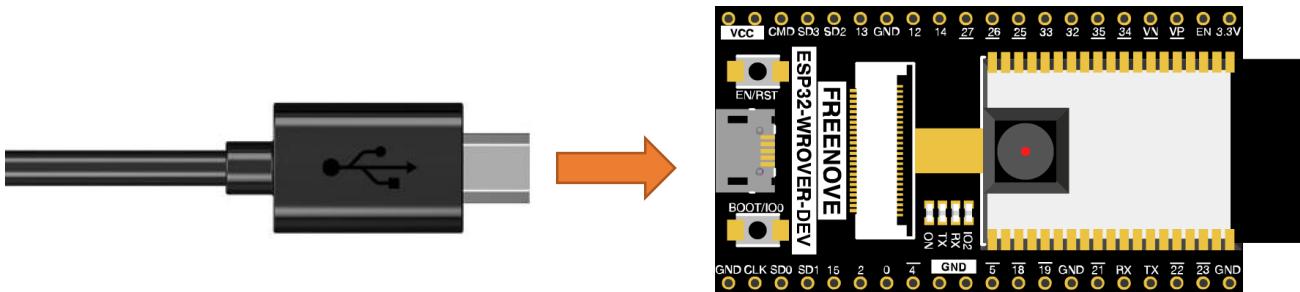
Connect ESP32 using USB and check its IP address through serial monitor. Use web page to access IP address to obtain video and image data.

### Component List



### Circuit

Connect Freenove ESP32 to the computer using USB cable.



## Code

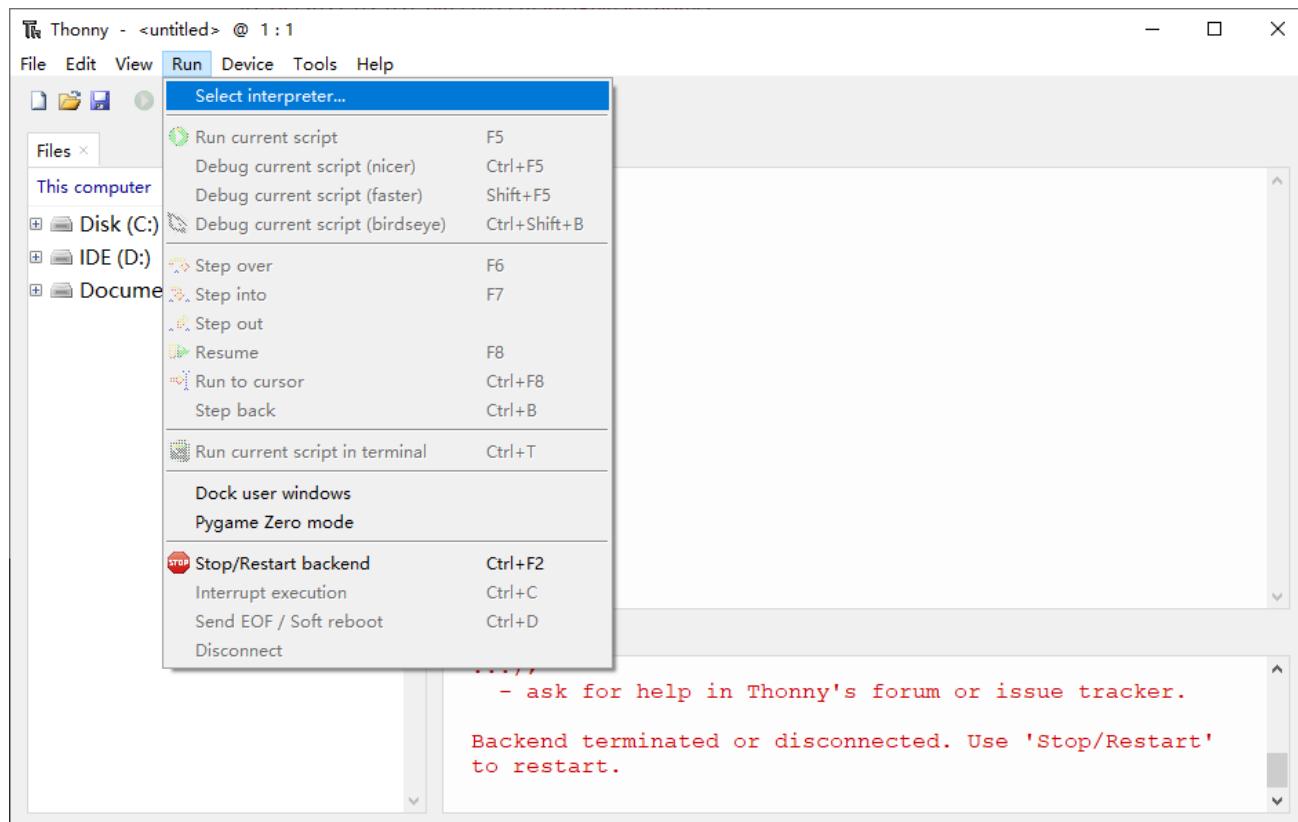
Move the program folder “**Freenove\_ESP32\_WROVER\_Board/Python/Python\_Codes**” to disk(D) in advance with the path of “**D:/Micropython\_Codes**”.

Since Micropython does not provide firmware including camera module, in this chapter, we will use the camera based on the firmware in lemariva's Github project, micropython-camera-driver.

Project link: <https://github.com/lemariva/micropython-camera-driver>

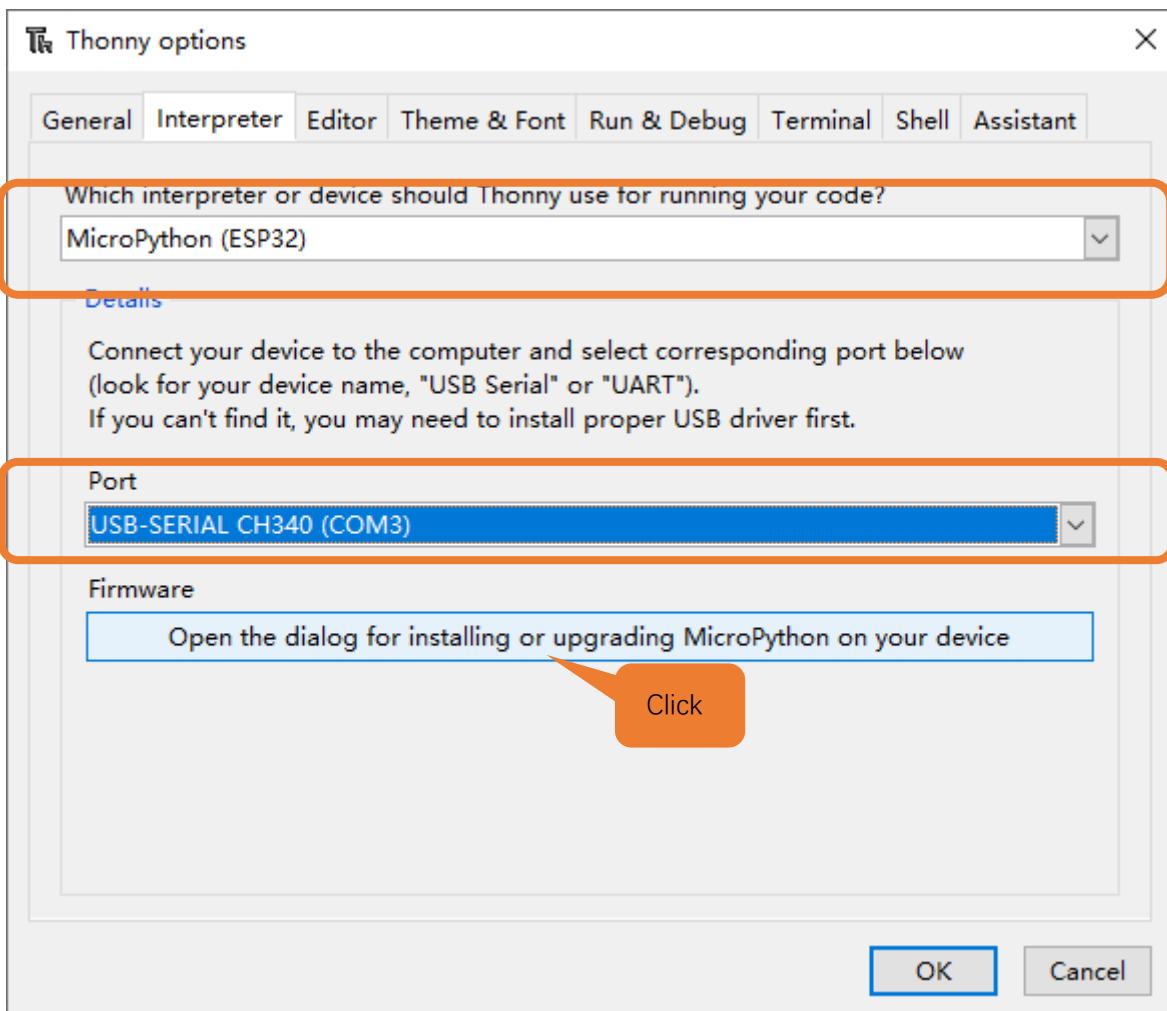
Before starting the project, we need to re-upload the firmware with the camera module via steps below.

Open Thonny, click “run” and select “Select interpreter...”



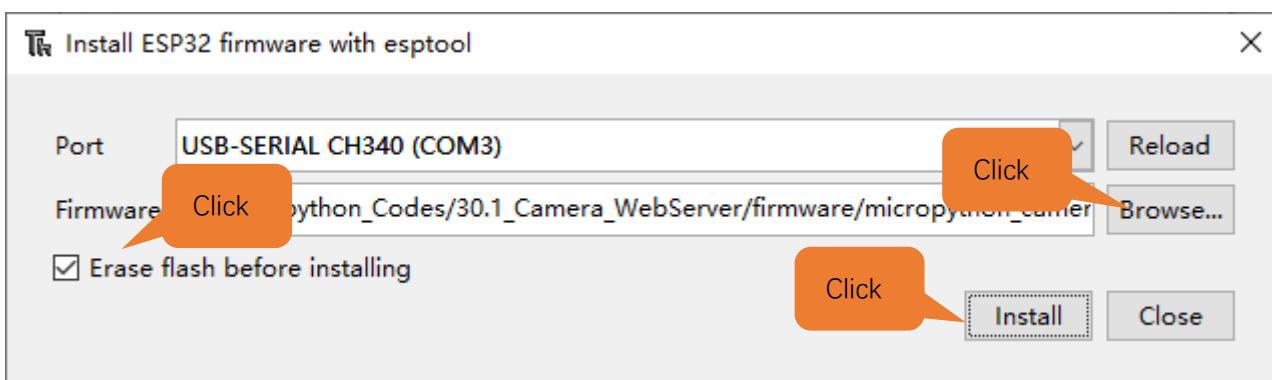


Select “Micropython (ESP32)”, select “USB-SERIAL CH340 (COM4)”, and then click the long button under “Firmware”.



In the new popup window, select corresponding “USB-SERIAL CH340 (COM3)” for port. Click “Browse”, select “05.1\_Camera\_WebServer\firmware\micropython\_camera\_feeeb5ea3\_esp32\_idf4\_4.bin”.

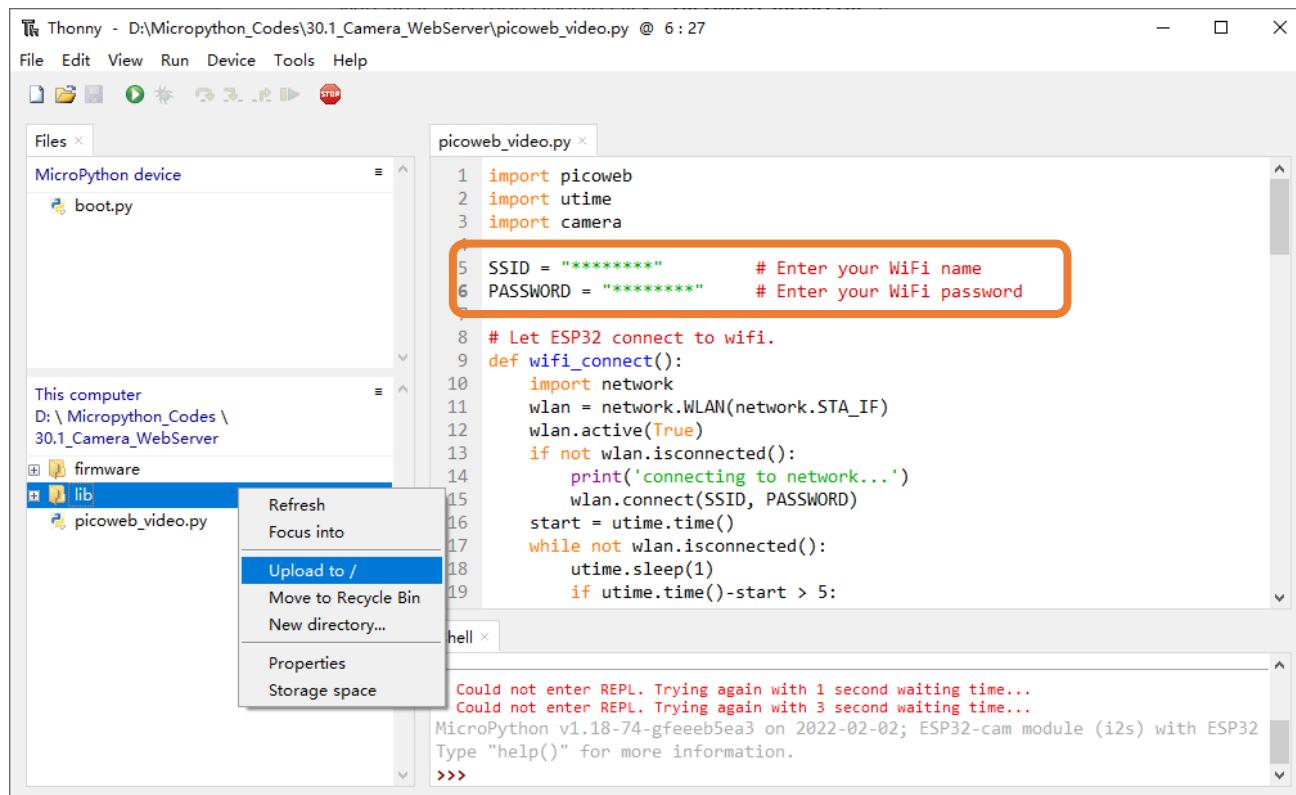
Select “Erase…” and click “Install”.



Wait for completion.

Open “Thonny”, click “This computer” → “D:” → “Micropython\_Codes” → “05.1\_Camera\_WebServer”. Select folder “lib”, right click your mouse to select “Upload to /”, wait for “lib” to be uploaded to ESP32-WROVER and then double click “picoweb\_video.py”.

### 05.1\_Camera\_WebServer



Before running the program, please modify your router's name and password in the box shown in the illustration above to make sure that your code can compile and work successfully.

Click "run" to run the code "picoweb\_video.py", then you can see the following content in the shell area.

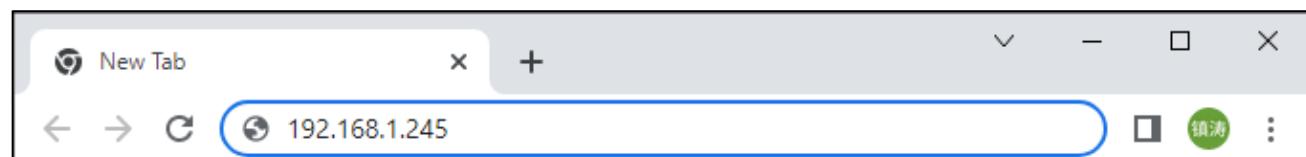
```

Shell >>> %Run -c $EDITOR_CONTENT
connecting to network...
network config: ('192.168.1.245', '255.255.255.0', '192.168.1.1', '192.168.1.1')
* Running on http://0.0.0.0:80
  
```

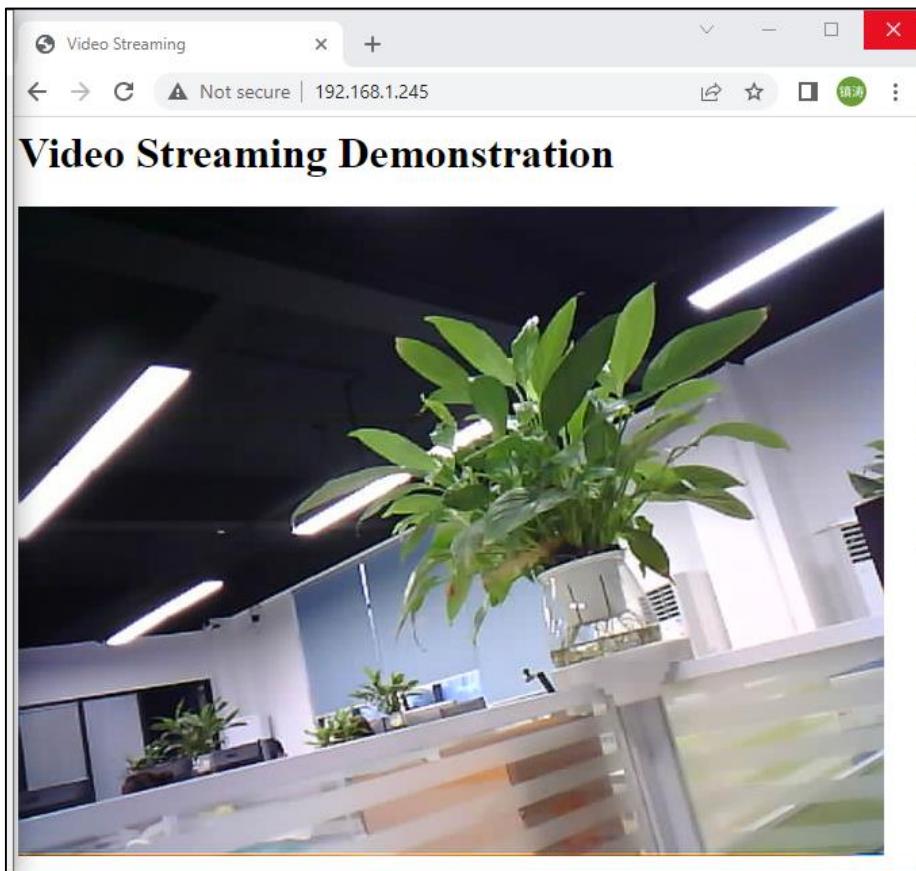
If your ESP32 has been in the process of connecting to router, but the information above has not been printed out, please re-check whether the router name and password have been entered correctly and press the reset key on ESP32-WROVER to wait for a successful connection prompt.

Open a web browser, enter the IP address printed by the serial monitor in the address bar, and access it.

Taking the Google browser as an example, here's what the browser prints out after successful access to ESP32's IP.



The effect is shown in the image below.



Please note:

If the shell area prompts an error when you click to run the code, please press the rst button on the esp32, wait for the system reset to complete, and then re-run the code.

The following is the program code.

```
1 import picoweb
2 import utime
3 import camera
4 import gc
5
6 SSID = "*****"          # Enter your WiFi name
7 PASSWORD = "*****"      # Enter your WiFi password
8
9 # Let ESP32 connect to wifi.
10 def wifi_connect():
11     import network
12     wlan = network.WLAN(network.STA_IF)
13     wlan.active(True)
14     if not wlan.isconnected():
15         print('connecting to network... ')
16         wlan.connect(SSID, PASSWORD)
17         start = utime.time()
18         while not wlan.isconnected():
```

Any concerns? ✉ support@freenove.com

```
19     utime.sleep(1)
20     if utime.time()-start > 5:
21         print("connect timeout!")
22         break
23     if wlan.isconnected():
24         print(' network config:', wlan.ifconfig())
25
26 # Initializing the Camera
27 def camera_init():
28     # Disable camera initialization
29     camera.deinit()
30     # Enable camera initialization
31     camera.init(0, d0=4, d1=5, d2=18, d3=19, d4=36, d5=39, d6=34, d7=35,
32                 format=camera.JPEG, framesize=camera.FRAME_VGA,
33                 xclk_freq=camera.XCLK_20MHz,
34                 href=23, vsync=25, reset=-1, pwdn=-1,
35                 sioc=27, siod=26, xclk=21, pclk=22, fb_location=camera.PSRAM)
36
37     camera.framesize(camera.FRAME_VGA) # Set the camera resolution
38     # The options are the following:
39     # FRAME_96X96 FRAME_QQVGA FRAME_QCIF FRAME_HQVGA FRAME_240X240
40     # FRAME_QVGA FRAME_CIF FRAME_HVGA FRAME_VGA FRAME_SVGA
41     # FRAME_XGA FRAME_HD FRAME_SXGA FRAME_UXGA
42     # Note: The higher the resolution, the more memory is used.
43     # Note: And too much memory may cause the program to fail.
44
45     camera.flip(1)                      # Flip up and down window: 0-1
46     camera.mirror(1)                    # Flip window left and right: 0-1
47     camera.saturation(0)               # saturation: -2,2 (default 0). -2 grayscale
48     camera.brightness(0)                # brightness: -2,2 (default 0). 2 brightness
49     camera.contrast(0)                  # contrast: -2,2 (default 0). 2 highcontrast
50     camera.quality(10)                 # quality: # 10-63 lower number means higher quality
51     # Note: The smaller the number, the sharper the image. The larger the number, the more
52     # blurry the image
53
54     camera.speffect(camera.EFFECT_NONE) # special effects:
55     # EFFECT_NONE (default) EFFECT_NEG EFFECT_BW EFFECT_RED EFFECT_GREEN EFFECT_BLUE
56     # EFFECT_RETRO
57
58     camera.whitebalance(camera.WB_NONE) # white balance
59     # WB_NONE (default) WB_SUNNY WB_CLOUDY WB_OFFICE WB_HOME
60
61     # HTTP Response Content
62     index_web="""HTTP/1.0 200 OK\r\n
```

```
61 <html>
62   <head>
63     <title>Video Streaming</title>
64   </head>
65   <body>
66     <h1>Video Streaming Demonstration</h1>
67     
68   </body>
69 </html>
70 """
71
72 # HTTP Response
73 def index(req, resp):
74     # You can construct an HTTP response completely yourself, having
75     yield from resp.awrite(index_web)
76
77 # Send camera pictures
78 def send_frame():
79     buf = camera.capture()
80     yield (b'--frame\r\n'
81             b'Content-Type: image/jpeg\r\n\r\n'
82             + buf + b'\r\n')
83     del buf
84     gc.collect()
85
86 # Video transmission
87 def video(req, resp):
88     yield from picoweb.start_response(resp, content_type="multipart/x-mixed-replace;
89 boundary=frame")
90     while True:
91         yield from resp.awrite(next(send_frame()))
92         gc.collect()
93
94 ROUTES = [
95     # You can specify exact URI string matches...
96     ("/", index),
97     ("/video", video),
98 ]
99
100 if __name__ == '__main__':
101
102     import ulogging as logging
103     logging.basicConfig(level=logging.INFO)
104     camera_init()
```

```

105     wifi_connect()
106
107     #Create an app object that contains two decorators
108     app = picoweb.WebApp(__name__, ROUTES)
109
110     app.run(debug=1, port=80, host="0.0.0.0")
111     # debug values:
112     # -1 disable all logging
113     # 0 (False) normal logging: requests and errors
114     # 1 (True) debug logging
115     # 2 extra debug logging

```

Import picoweb、utime、camera、gc modules.

```

1 import picoweb
2 import utime
3 import camera
4 import gc

```

Before running the code, please modify the WiFi name and password in the code to ensure that the ESP32 can connect to the network.

```

6 SSID = "*****"          # Enter your WiFi name
7 PASSWORD = "*****"      # Enter your WiFi password

```

Define the WiFi connection function, set the ESP32 to STA mode, and let the ESP32 connect to the nearby WiFi. If the connection is successful, the WiFi configuration information of the ESP32 will be printed; if the connection fails, the connection timeout will be printed.

```

10 def wifi_connect():
11     import network
12     wlan = network.WLAN(network.STA_IF)
13     wlan.active(True)
14     if not wlan.isconnected():
15         print('connecting to network...')
16         wlan.connect(SSID, PASSWORD)
17     start = utime.time()
18     while not wlan.isconnected():
19         utime.sleep(1)
20         if utime.time()-start > 5:
21             print("connect timeout!")
22             break
23     if wlan.isconnected():
24         print('network config:', wlan.ifconfig())

```

The deinit() is used to disable the configuration of the camera to prevent the previous configuration from interfering with the following configuration.

The init() is used to configure the camera's pin driver, image data format, resolution and other information.



By default, please do not modify this function, otherwise the camera initialization fails and the image cannot be obtained.

```

29     camera.deinit()
30     # Enable camera initialization
31     camera.init(0, d0=4, d1=5, d2=18, d3=19, d4=36, d5=39, d6=34, d7=35,
32                     format=camera.JPEG, framesize=camera.FRAME_VGA,
33                     xclk_freq=camera.XCLK_20MHz,
34                     href=23, vsync=25, reset=-1, pwn=1,
35                     sioc=27, siod=26, xclk=21, pclk=22, fb_location=camera.PSRAM)

```

This function can set the resolution of the camera individually, you can refer to the notes below to select the appropriate resolution size.

```

37     camera.framesize(camera.FRAME_VGA) # Set the camera resolution
38     # The options are the following:
39     # FRAME_96X96 FRAME_QQVGA FRAME_QCIF FRAME_HQVGA FRAME_240X240
40     # FRAME_QVGA FRAME_CIF FRAME_HVGA FRAME_VGA FRAME_SVGA
41     # FRAME_XGA FRAME_HD FRAME_SXGA FRAME_UXGA
42     # Note: The higher the resolution, the more memory is used.
43     # Note: And too much memory may cause the program to fail.

```

The following functions can modify the image information obtained by the camera.

```

45     camera.flip(1)                      # Flip up and down window: 0-1
46     camera.mirror(1)                    # Flip window left and right: 0-1
47     camera.saturation(0)                # saturation: -2, 2 (default 0). -2 grayscale
48     camera.brightness(0)                # brightness: -2, 2 (default 0). 2 brightness
49     camera.contrast(0)                 # contrast: -2, 2 (default 0). 2 highcontrast
50     camera.quality(10)                 # quality: # 10-63 lower number means higher quality
51     # Note: The smaller the number, the sharper the image. The larger the number, the more
      blurry the image
52
53     camera.speffect(camera.EFFECT_NONE) # special effects:
54     # EFFECT_NONE (default) EFFECT_NEG EFFECT_BW EFFECT_RED EFFECT_GREEN EFFECT_BLUE
      EFFECT_RETRO
55     camera.whitebalance(camera.WB_NONE) # white balance
56     # WB_NONE (default) WB_SUNNY WB_CLOUDY WB_OFFICE WB_HOME

```

This is the code for a simple web interface, used here as an example.

```

59     index_web"""
60     HTTP/1.0 200 OK\r\n
61     <html>
62       <head>
63         <title>Video Streaming</title>
64       </head>
65       <body>
66         <h1>Video Streaming Demonstration</h1>
67         
68     </body>

```

```
69 </html>
70 """
```

Web page response function. When a user visits the webpage "/" built by ESP32, ESP32 calls this function, allowing the user to observe a display interface in the browser.

```
73 def index(req, resp):
74     # You can construct an HTTP response completely yourself, having
75     yield from resp.awrite(index_web)
```

`send_frame()` can send the image obtained by ESP32 in web page format. When someone visits the webpage "/video" built by the ESP32, the `video(req, resp)` function is used to continuously fetch images and send them to the browser.

```
77 # Send camera pictures
78 def send_frame():
79     buf = camera.capture()
80     yield (b'--frame\r\n'
81             b'Content-Type: image/jpeg\r\n\r\n'
82             + buf + b'\r\n')
83     del buf
84     gc.collect()
85
86 # Video transmission
87 def video(req, resp):
88     yield from picoweb.start_response(resp, content_type="multipart/x-mixed-replace;
89 boundary=frame")
90     while True:
91         yield from resp.awrite(next(send_frame()))
92         gc.collect()
```

Create two route decorators and declare their listening strings and corresponding response handlers respectively.

```
94 ROUTES = [
95     # You can specify exact URI string matches...
96     ("/", index),
97     ("/video", video),
98 ]
```

This is the main part of the program. First initialize the ESP32 camera, and then configure WiFi to connect the ESP32 to the network. Call the `picoweb` library, build a webserver, and run it.

```
103 import ulogging as logging
104 logging.basicConfig(level=logging.INFO)
105 camera_init()
106 wifi_connect()
107
108 #Create an app object that contains two decorators
109 app = picoweb.WebApp(__name__, ROUTES)
110
111 app.run(debug=1, port=80, host="0.0.0.0")
```



## Reference

| Image resolution | Sharpness | Image resolution | Sharpness |
|------------------|-----------|------------------|-----------|
| FRAME_96X96      | 96x96     | FRAME_HVGA       | 480x320   |
| FRAME_QQVGA      | 160x120   | FRAME_VGA        | 640x480   |
| FRAME_QCIF       | 176x144   | FRAME_SVGA       | 800x600   |
| FRAME_HQVGA      | 240x176   | FRAME_XGA        | 1024x768  |
| FRAME_240X240    | 240x240   | FRAME_HD         | 1280x720  |
| FRAME_QVGA       | 320x240   | FRAME_SXGA       | 1280x1024 |
| FRAME_CIF        | 400x296   | FRAME_UXGA       | 1600x1200 |

## What's next?

Thanks for your reading. This tutorial is all over here. If you find any mistakes, omissions or you have other ideas and questions about contents of this tutorial or the kit and etc., please feel free to contact us:

[support@freenove.com](mailto:support@freenove.com)

We will check and correct it as soon as possible.

If you want learn more about ESP32, you view our ultimate tutorial:

[https://github.com/Freenove/Freenove\\_ESP32\\_WROVER\\_Board/archive/master.zip](https://github.com/Freenove/Freenove_ESP32_WROVER_Board/archive/master.zip)

If you want to learn more about Arduino, Raspberry Pi, smart cars, robots and other interesting products in science and technology, please continue to focus on our website. We will continue to launch cost-effective, innovative and exciting products.

<http://www.freenove.com/>

## End of the Tutorial

Thank you again for choosing Freenove products.