Welcome

Thank you for choosing Freenove products!

How to Start

When reading this, you should have downloaded the ZIP file for this product.
Unzip it and you will get a folder containing tutorials and related files. Please start with this PDF tutorial.

! Unzip the ZIP file instead of opening the file in the ZIP file directly.
! Do not move, delete or rename files in the folder just unzipped.

Get Support

Encounter problems? Don't worry! Refer to “TroubleShooting.pdf” or contact us.

When there are packaging damage, quality problems, questions encountering in use, etc., just send us an email. We will reply to you within one working day and provide a solution.

support@freenove.com

Attention

Pay attention to safety when using and storing this product:

- This product is not suitable for children under 12 years of age because of small parts and sharp parts.
- Minors should use this product under the supervision and guidance of adults.
- This product contains small and sharp parts. Do not swallow, prick and scratch to avoid injury.
- This product contains conductive parts. Do not hold them to touch power supply and other circuits.
- To avoid personal injury, do not touch parts rotating or moving while working.
- The wrong operation may cause overheat. Do not touch and disconnect the power supply immediately.
- Operate in accordance with the requirements of the tutorial. Fail to do so may damage the parts.
- Store this product in a dry and dark environment. Keep away from children.
- Turn off the power of the circuit before leaving.

About

Freenove provides open source electronic products and services.

Freenove is committed to helping customers learn programming and electronic knowledge, quickly implement product prototypes, realize their creativity and launch innovative products. Our services include:

- Kits for learning programming and electronics
- Kits compatible with Arduino®, Raspberry Pi®, micro:bit®, ESP8266®, etc.
- Kits for robots, smart cars, drones, etc.
- Components, modules and tools
- Design and customization

To learn more about us or get our latest information, please visit our website:

http://www.freenove.com

Copyright

FREENOVE™

Any concerns? ✉ support@freenove.com

Contents

Prepare

ESP8266 is a micro control unit with integrated Wi-Fi launched by Espressif, which features strong properties and integrates rich peripherals. It can be designed and studied as an ordinary Single Chip Micyoco(SCM) chip, or connected to the Internet and used as an Internet of Things device.

ESP8266 can be developed both either with C/C++ language or micropython language. In this tutorial, we use micropython. With Micropython is as easy to learn as Python with little code, making it ideal for beginners. Moreover, the code of ESP8266 is completely open-source, so beginners can quickly learn how to develop and design IOT smart household products including smart curtains, fans, lamps and clocks.

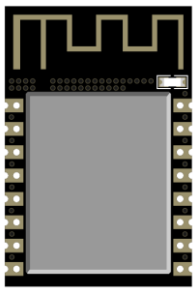
We divide each project into four parts, namely Component List, Component Knowledge, Circuit and Code. Component List helps you to prepare material for the experiment more quickly. Component Knowledge allows you to quickly understand new electronic modules or components, while Circuit helps you understand the operating principle of the circuit. And Code allows you to easily master the use of ESP8266 and its accessory kit. After finishing all the projects in this tutorial, you can also use these components and modules to make products such as smart household, smart cars and robots to transform your creative ideas into prototypes and new and innovative products.

In addition, if you have any difficulties or questions with this tutorial or toolkit, feel free to ask for our quick and free technical support through support@freenove.com

ESP8266

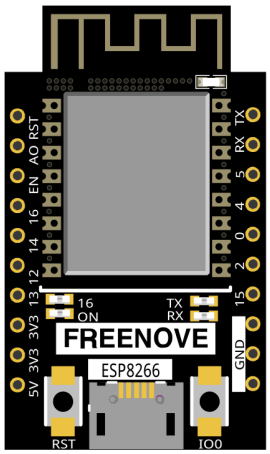
ESP8266 has PCB on-board antenna. The PCB on-board antenna is an integrated antenna in the chip module itself, so it is convenient to carry and design.

PCB on-board antenna

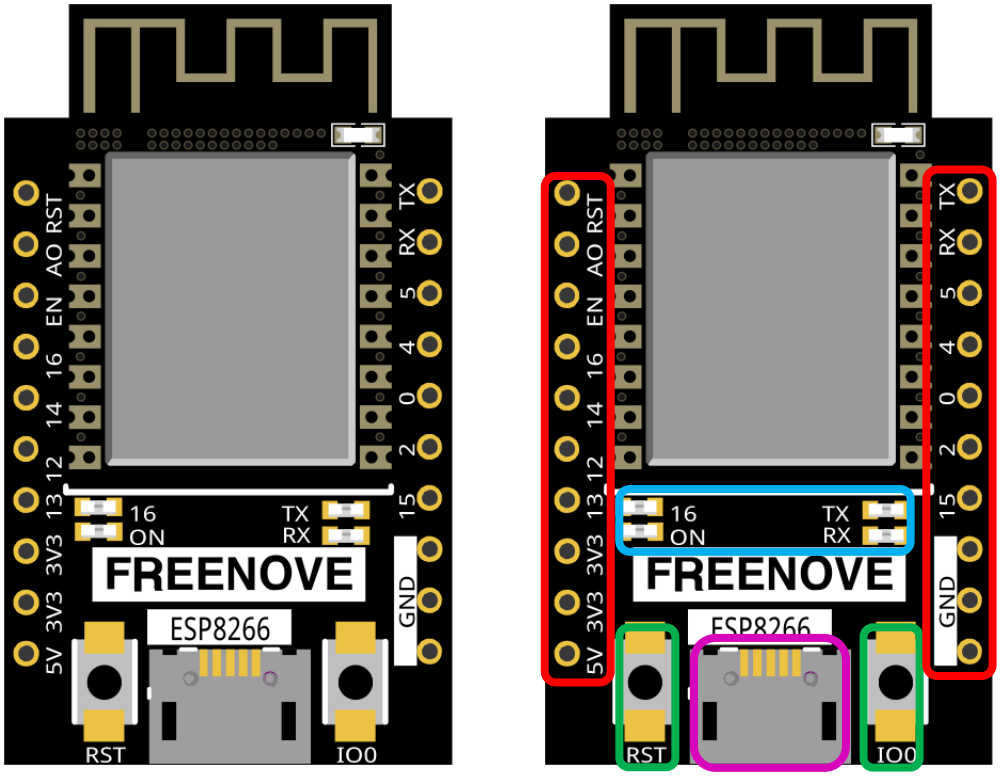


In this tutorial, the ESP8266 development board is designed based on the PCB on-board antenna-packaged ESP8266 module. The following tutorials will be based on the ESP8266 development board.

ESP8266 development board



The hardware interfaces of ESP8266 are distributed as follows:



Compare the left and right images. We've boxed off the resources on the ESP8266 in different colors to facilitate your understanding of the ESP8266 development board.

Box color	Corresponding resources introduction
	GPIO pin
	LED indicator
	Reset button, Boot mode selection button
	USB port

NO.	Pin Name	Functional Description
1	RST	Reset Pin, Active Low
2	ADC	AD conversion, Input voltage range 0~3.3V, the value range is 0~1024.
3	EN	Chip Enabled Pin, Active High
4	IO16	Connect with RST pin to wake up Deep Slee
5	IO14	GPIO14; HSPI_CLK
6	IO12	GPIO12; HSPI_MISO
7	IO13	GPIO13; HSPI_MOSI; UART0_CTS
8	VCC	Module power supply pin, Voltage 3.0V ~ 3.6V
9	GND	GND
10	IO15	GPIO15; MTDO; HSPICS; UART0_RTS
11	IO2	GPIO2; UART1_TXD
12	IO0	GPIO0;HSPI_MISO;I2SI_DATA
13	IO4	GPIO4
14	IO5	GPIO5;IR_R
15	RXD	UART0_RXD; GPIO3
16	TXD	UART0_TXD; GPIO1

Description of the ESP8266 series module boot mode:

Mode	CH_PD(EN)	RST	GPIO15	GPIO0	GPIO2	TXD0
Download mode	high	high	low	low	high	high
Running mode	high	high	low	high	high	high

Notes: Some of the pins inside the module have been pulled or pulled down.

If you want to learn more about this, you can read the following files:

“Freenove_ESP8266_Board/Datasheet/esp-12s_datasheet_en.pdf”

Chapter 0 Ready (Important)

Before starting building the projects, you need to make some preparation first, which is so crucial that you must not skip.

0.1 Installing Thonny (Important)

Thonny is a free, open-source software platform with compact size, simple interface, simple operation and rich functions, making it a Python IDE for beginners. In this tutorial, we use this IDE to develop ESP6266 during the whole process.
Thonny supports various operating system, including Windows、Mac OS、Linux.

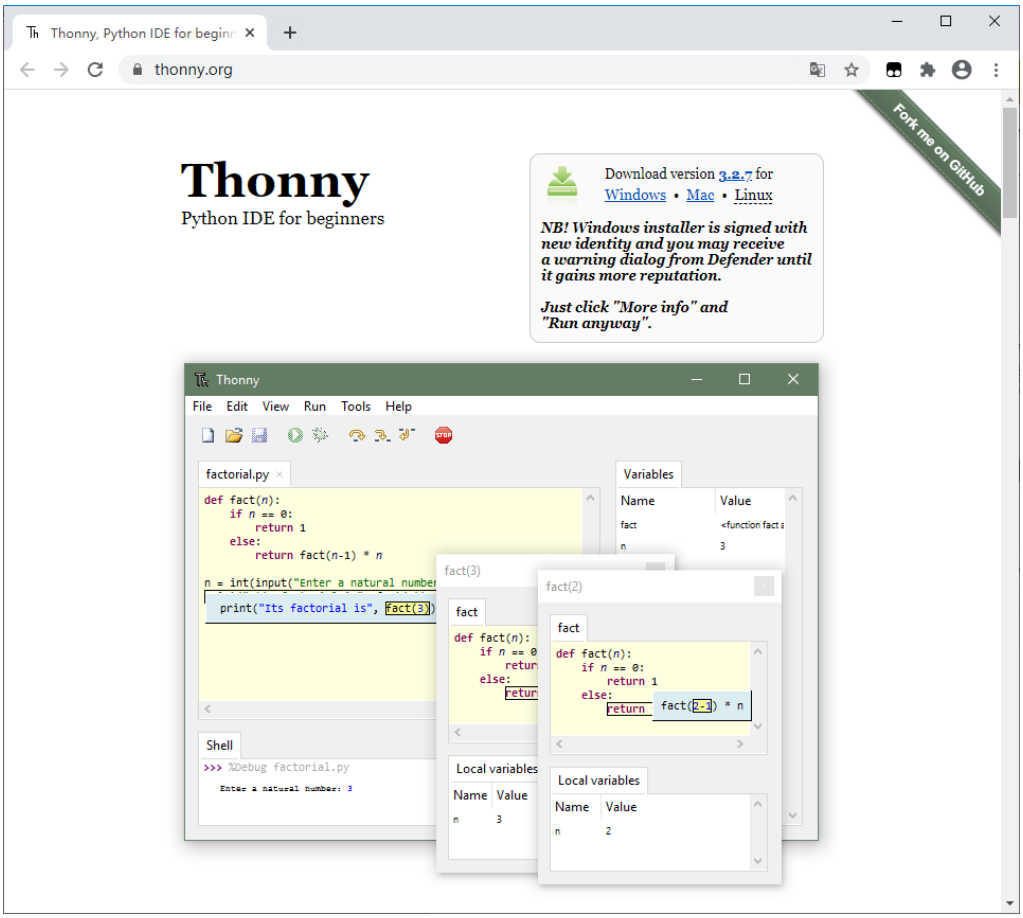
Downloading Thonny

Official website of Thonny: https://thonny.org
Open-source code repositories of Thonny: https://github.com/thonny/thonny

Follow the instruction of official website to install Thonny or click the links below to download and install. (Select the appropriate one based on your operating system.)

Operating System	Download links/methods
Windows	https://github.com/thonny/thonny/releases/download/v3.2.7/thonny-3.2.7.exe
Mac OS	https://github.com/thonny/thonny/releases/download/v3.2.7/thonny-3.2.7.pkg
Linux	**The latest version:** **Binary bundle for PC (Thonny+Python):** bash <(wget -O - https://thonny.org/installer-for-linux) **With pip:** pip3 install thonny **Distro packages (may not be the latest version):** **Debian, Rasbian, Ubuntu, Mint and others:** sudo apt install thonny **Fedora:** sudo dnf install thonny

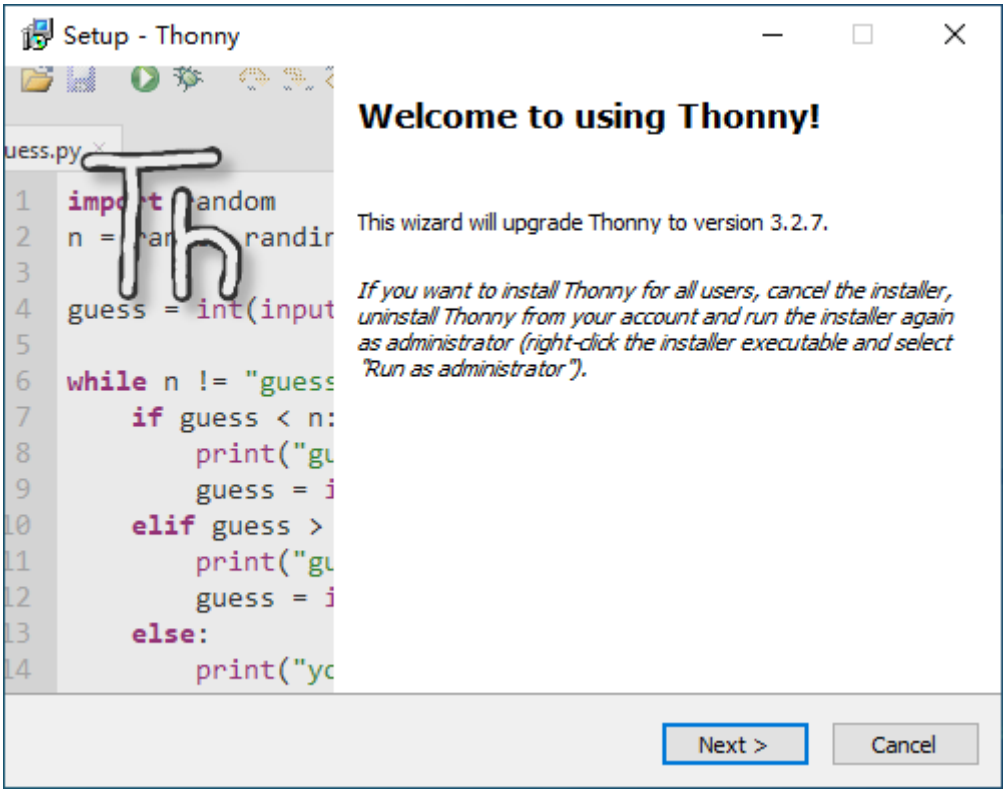
You can also open "**Freenove_ESP8266_Board/Python/Python_Software**", we have prepared it in advance.



Installing on Windows

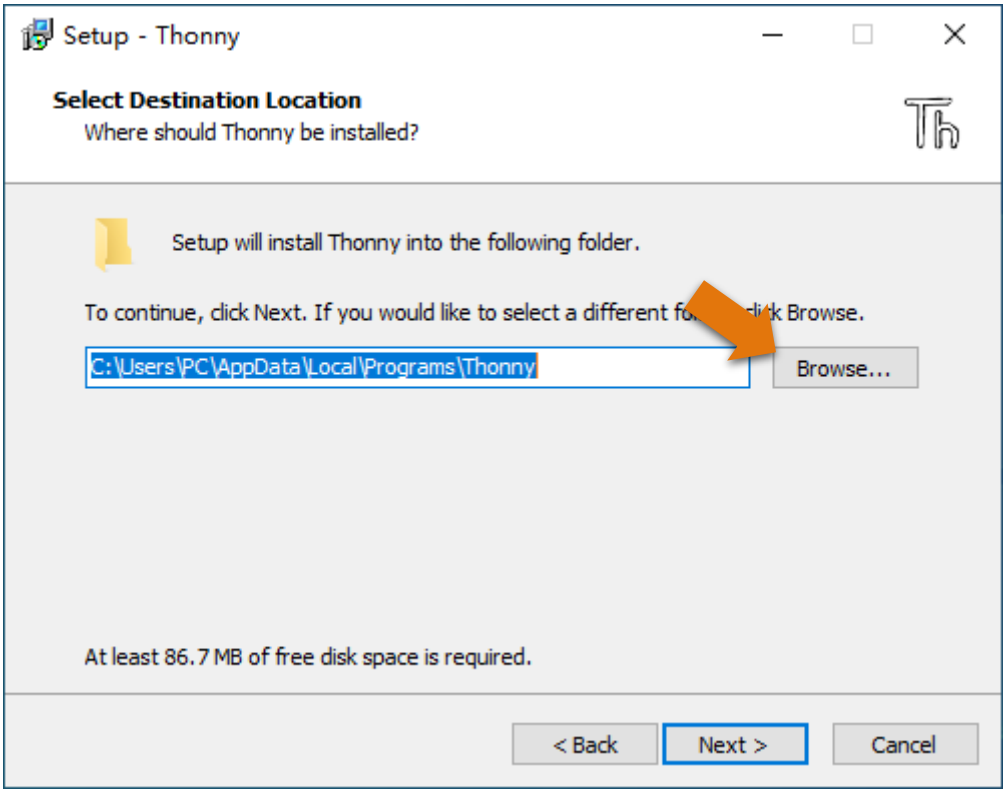
The icon of Thonny after downloading is as below. Double click “thonny-3.2.7.exe”.

If you're not familiar with computer software installation, you can simply keep clicking "Next" until the installation completes.

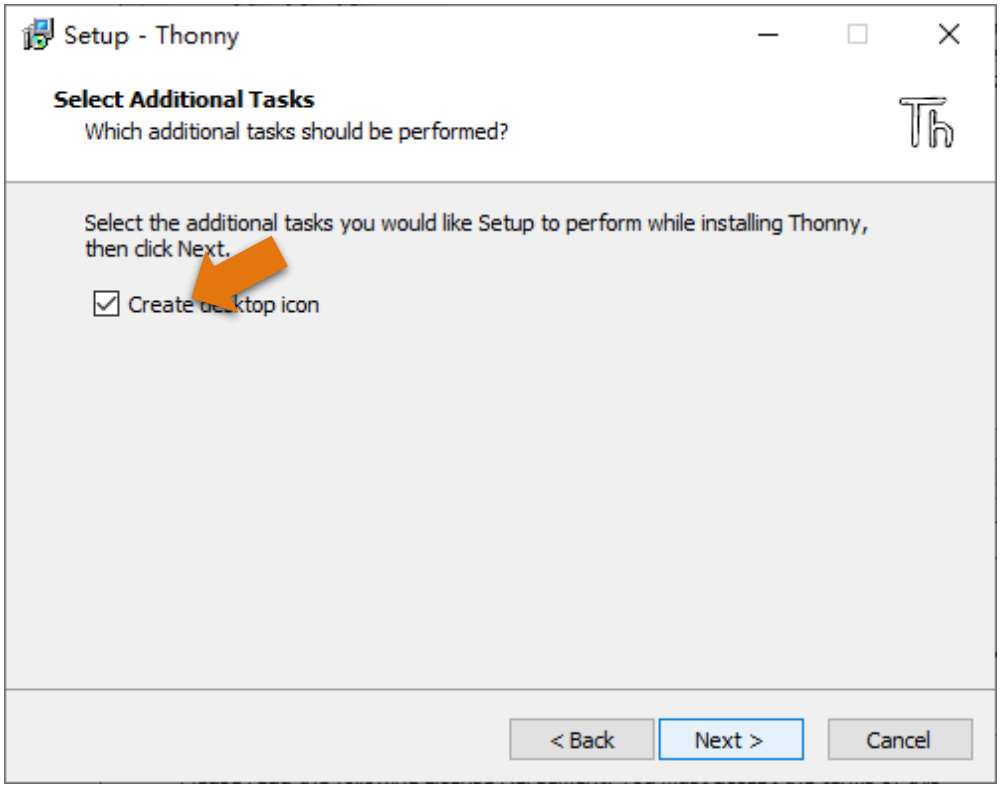


If you want to change Thonny's installation path, you can click "Browse" to modify it. After selecting installation path, click "OK".

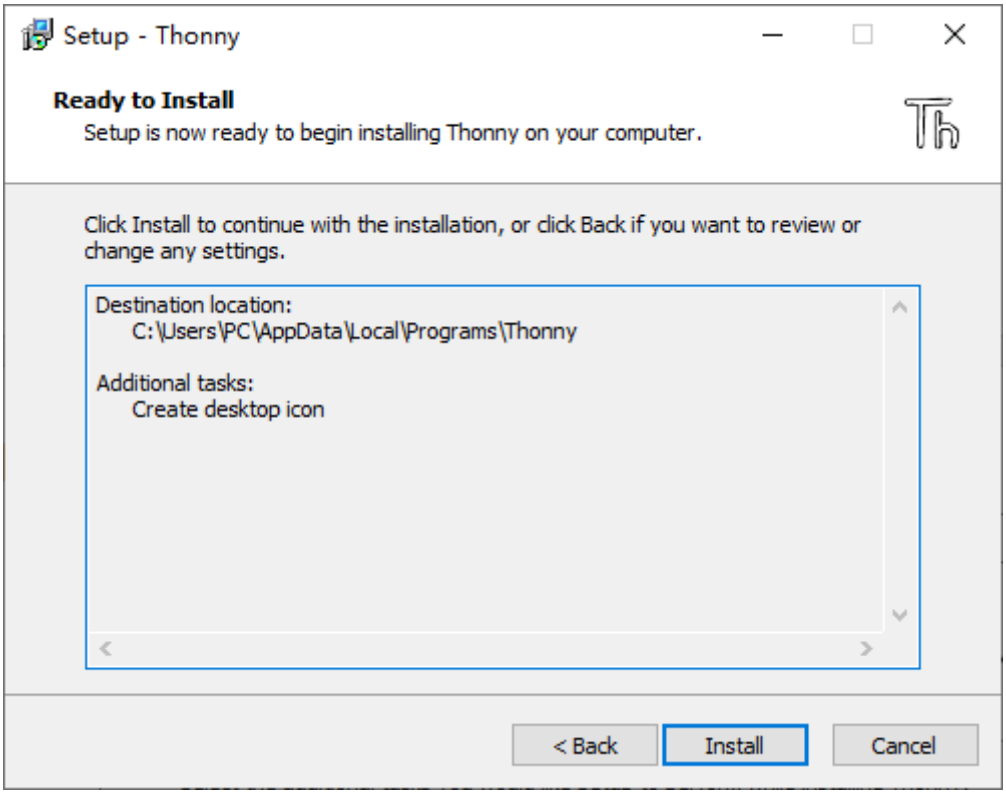
If you do not want to change it, just click "Next".



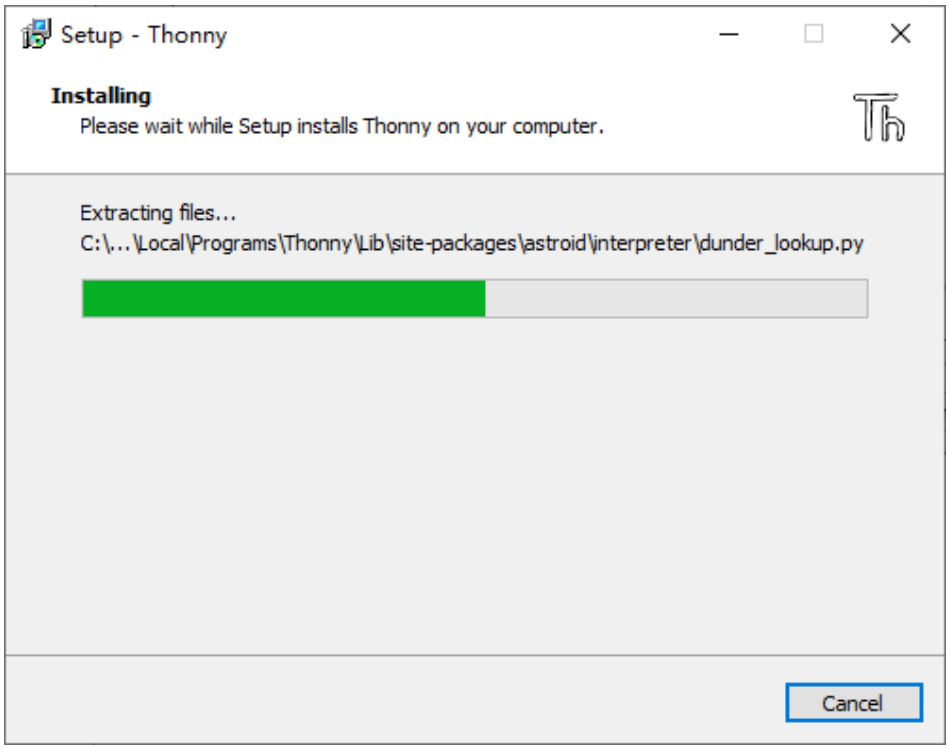
Check "Create desktop icon" and then it will generate a shortcut on your desktop to facilitate you to open Thonny later.



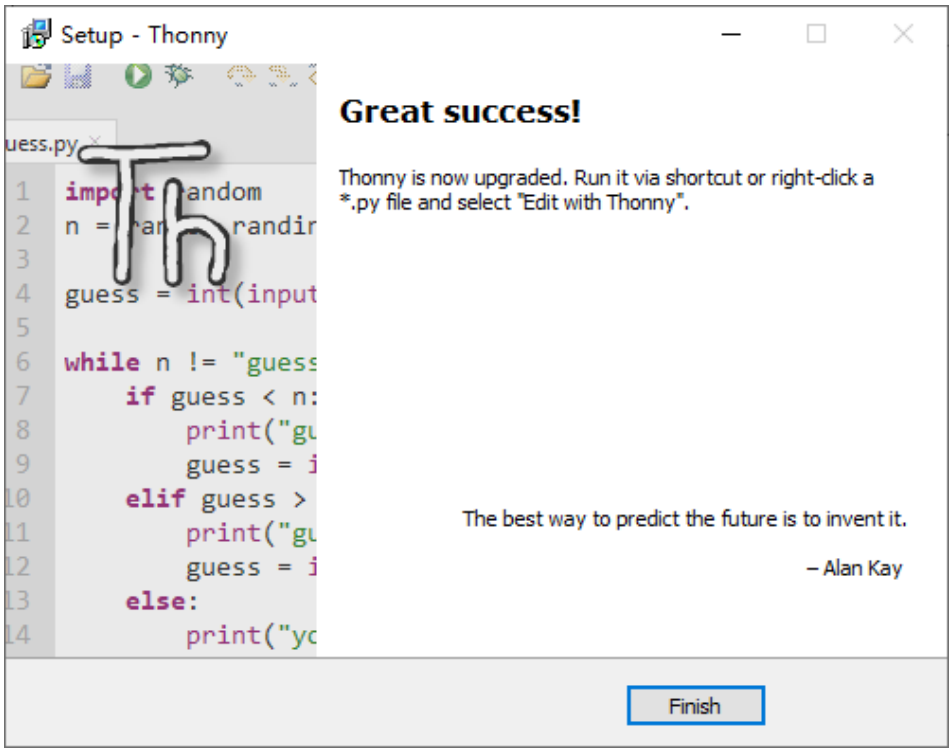
Click "install" to install the software.



During the installation process, you only need to wait for the installation to complete, and you msut not click "Cancel", otherwise Thonny will fail to be installed.



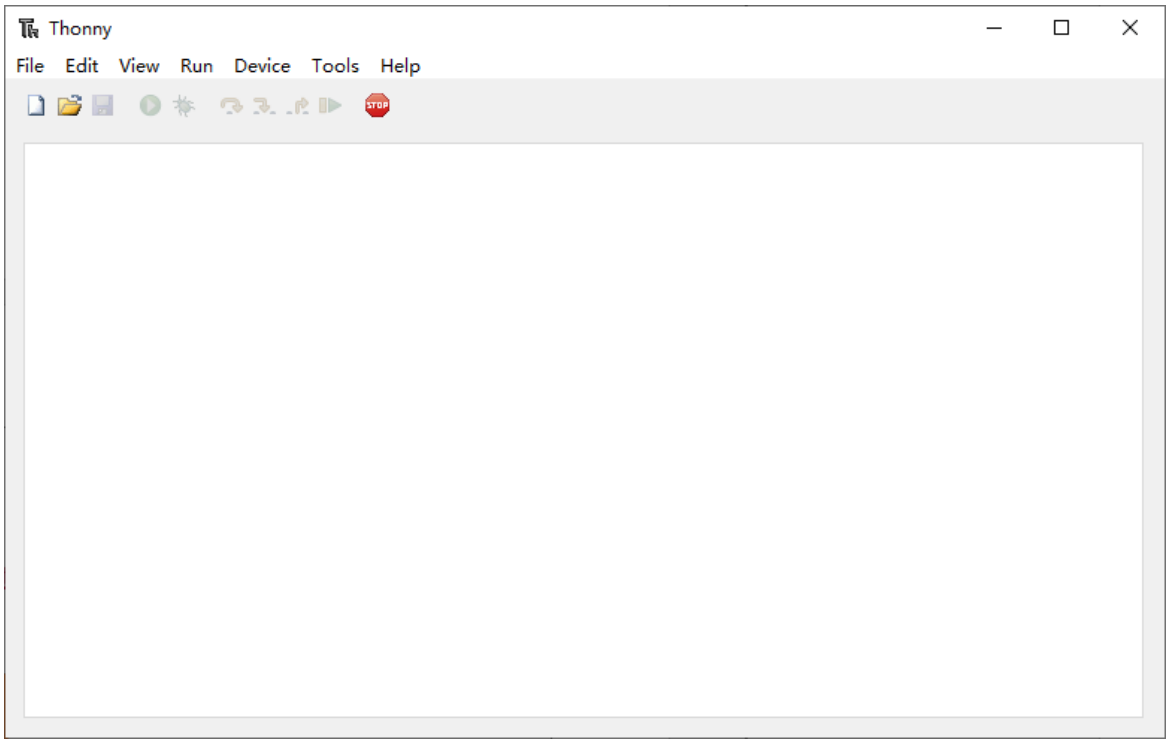
Once you see the interface as below, Thonny has been installed successfully.



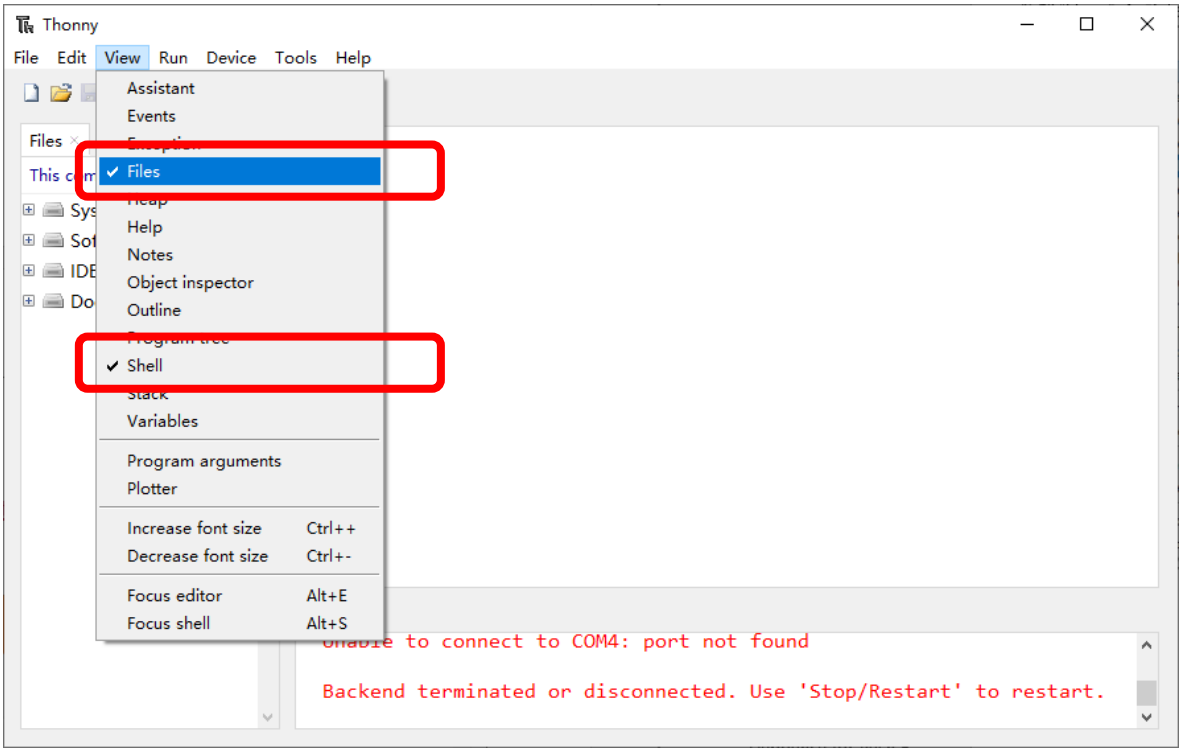
If you've check "Create desktop icon" during the installation process, you can see the below icon on your desktop.

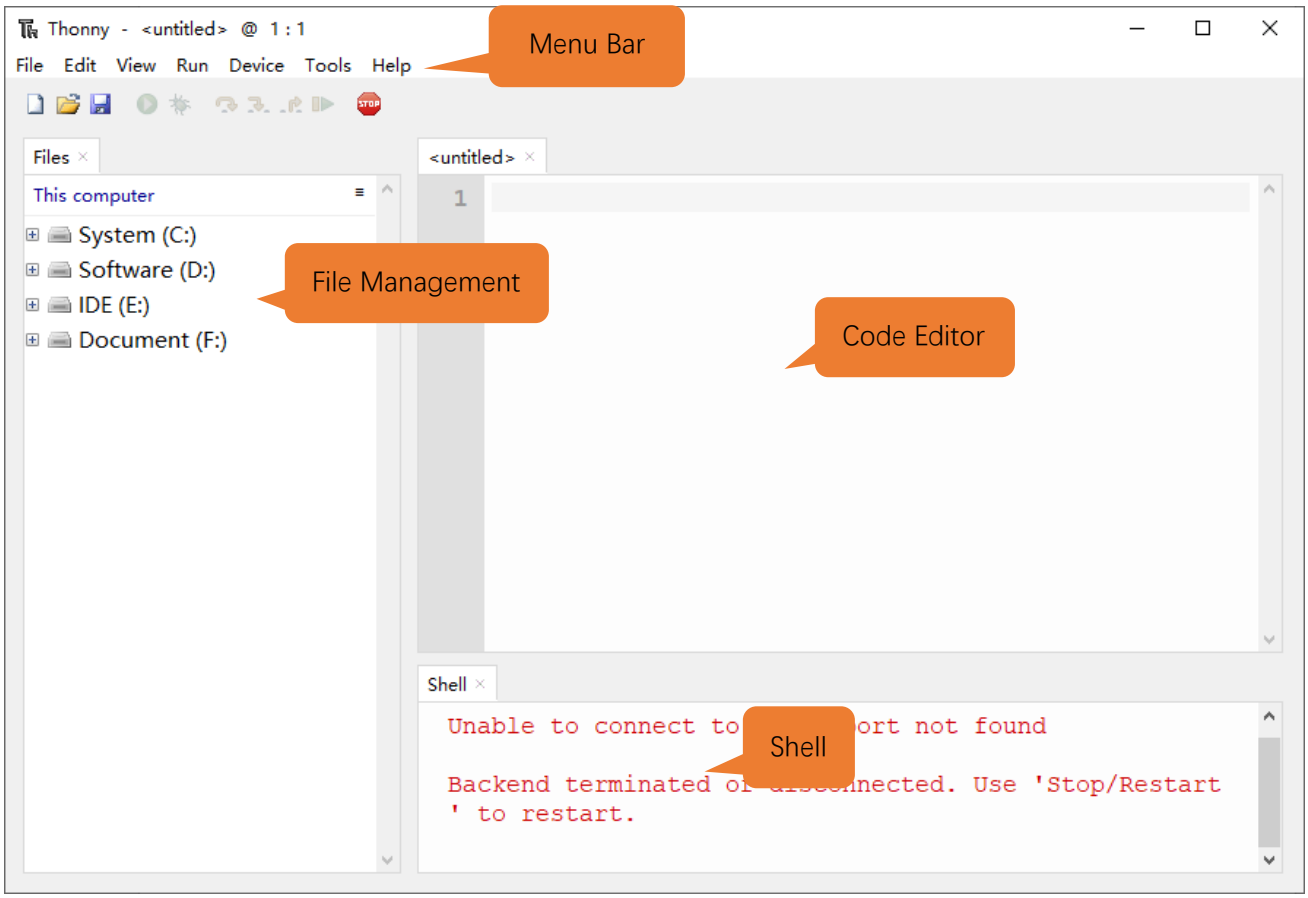
0.2 Basic Configuration of Thonny

Click the desktop icon of Thonny and you can see the interface of it as follows:



Select "View"→ "Files" and "Shell".




Thonny - <untitled> @ 1 : 1
File Edit View Run Device Tools Help
Menu Bar
Files
This computer
System (C:)
Software (D:)
IDE (E:)
Document (F:)
File Management
<untitled>
1
Code Editor
Shell
Unable to connect to
ort not found
Backend terminated or disconnected. Use 'Stop/Restart
' to restart.
Shell

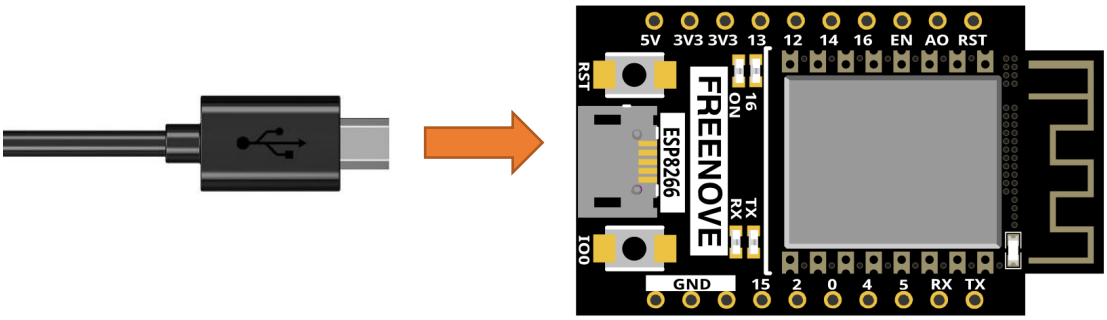
0.3 Installing CH340 (Important)

ESP8266 uses CH340 to download codes. So before using it, we need to install CH340 driver in our computers.

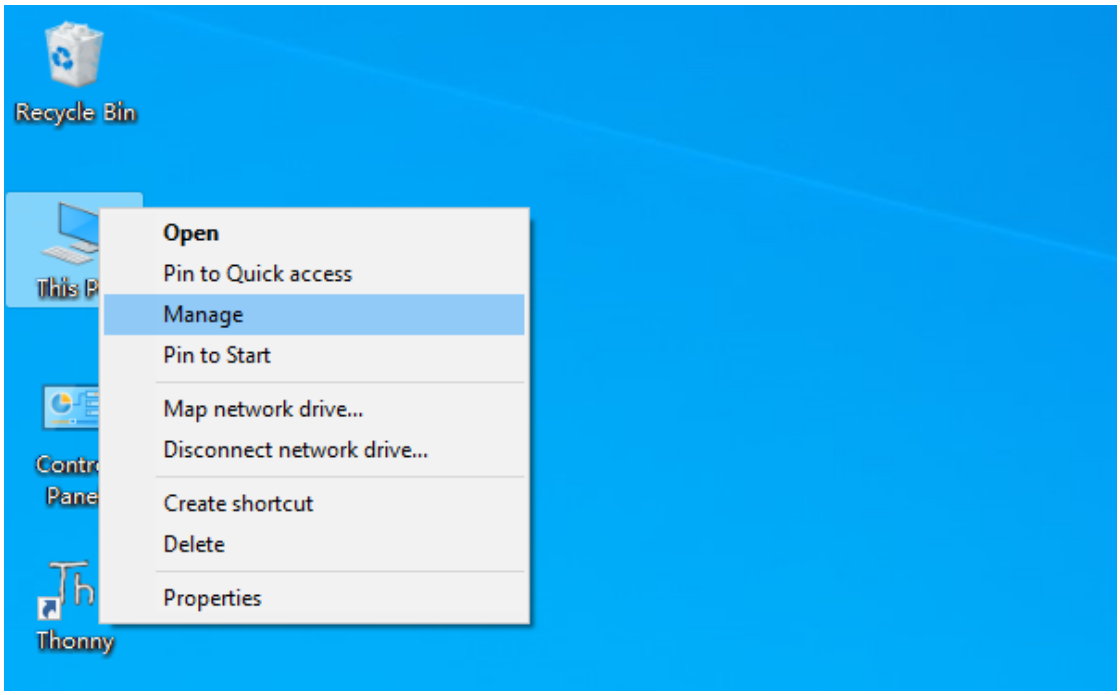
Windows

Check whether CH340 has been installed

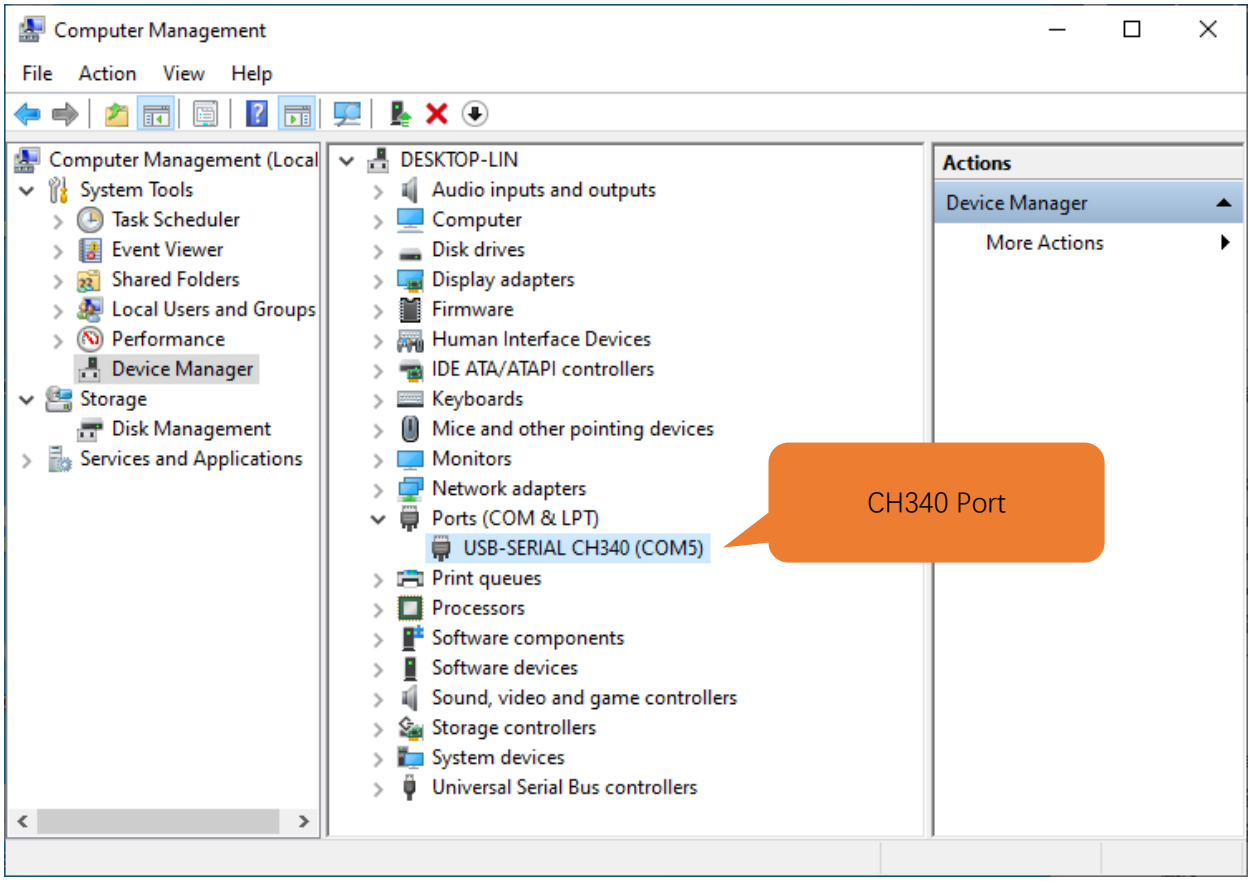
1. Connect your computer and ESP8266 with a USB cable.



2. Turn to the main interface of your computer, select "This PC" and right-click to select "Manage".

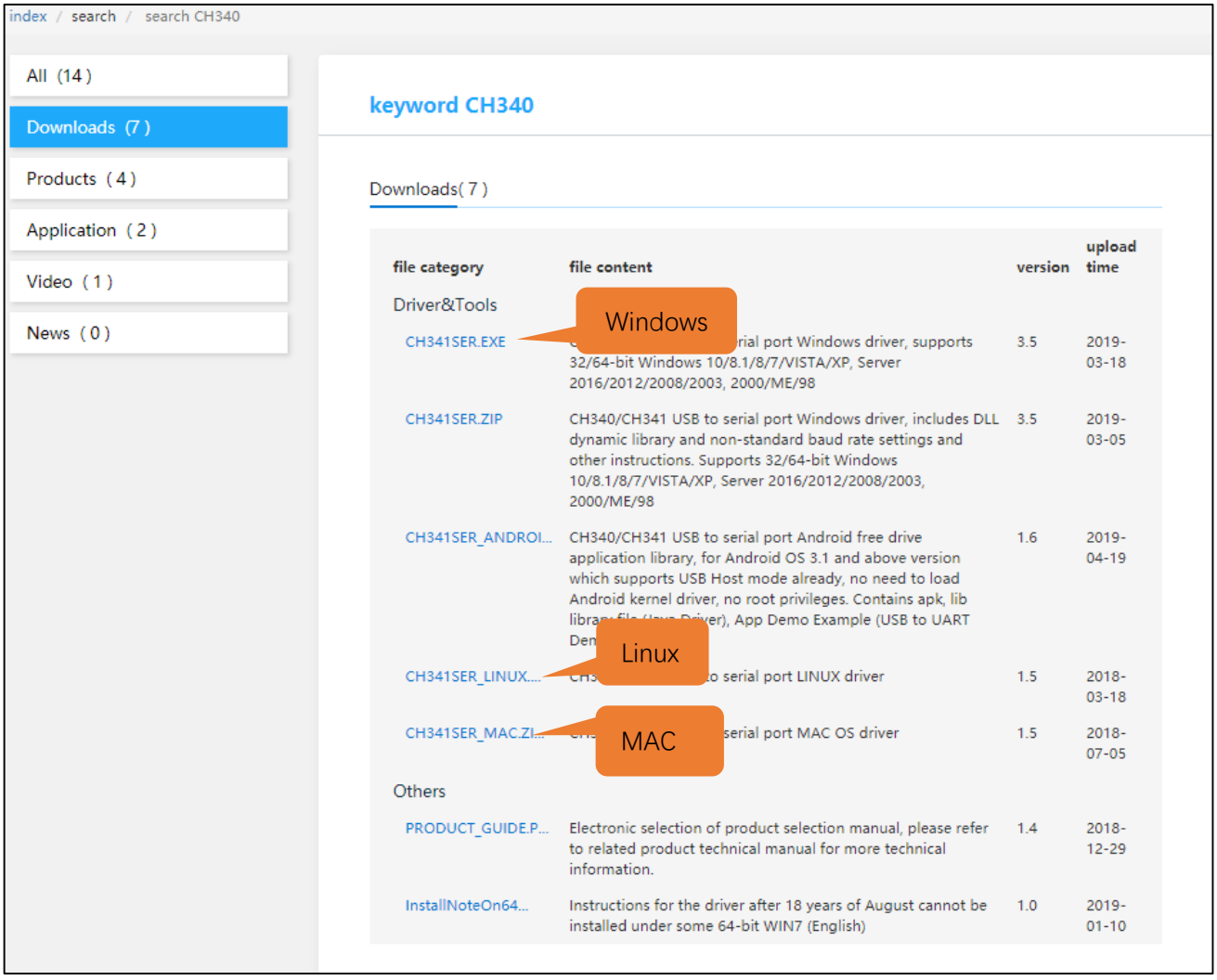


3. Click "Device Manager". If your computer has installed CH340, you can see"USB-SERIAL CH340 (COMx)". And you can click here to move to the next step.

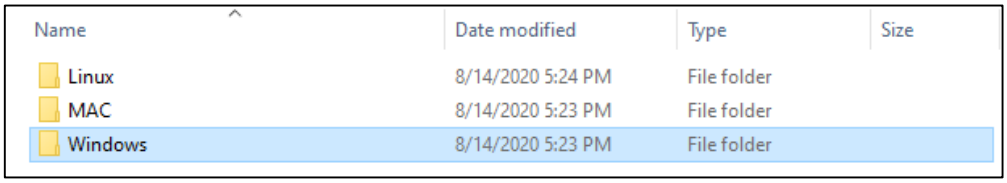


Installing CH340

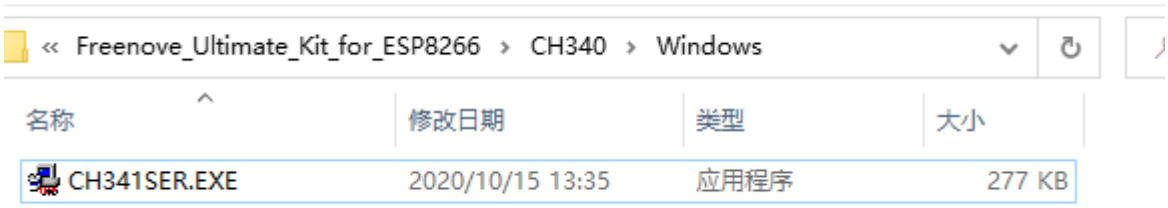
1. First, download CH340 driver, click http://www.wch-ic.com/search?q=CH340&t=downloads to download the appropriate one based on your operating system.



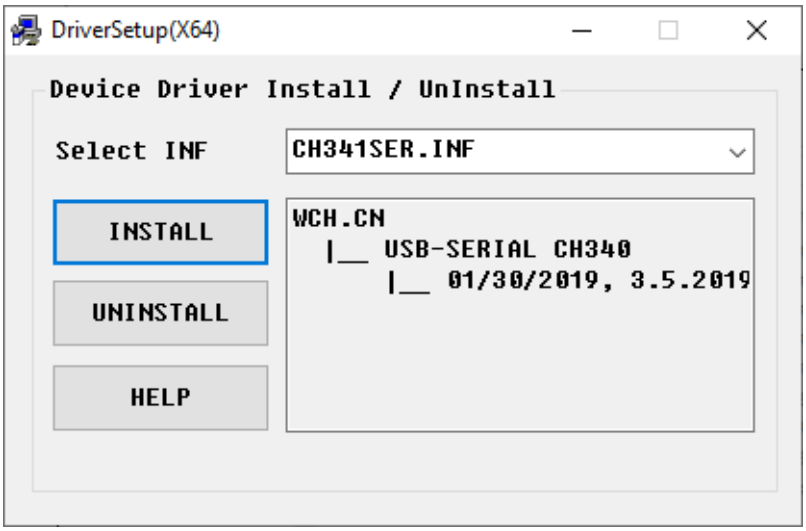
You can also open **"Freenove_ESP8266_Board/CH340"**, we have prepared the installation package.



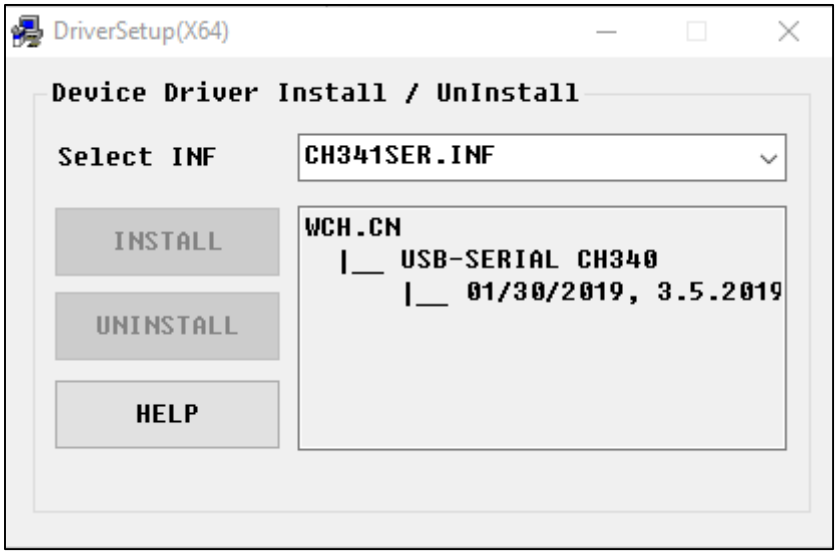
2. Open the folder "**Freenove_ESP8266_Board/CH340/Windows/ch341ser**"



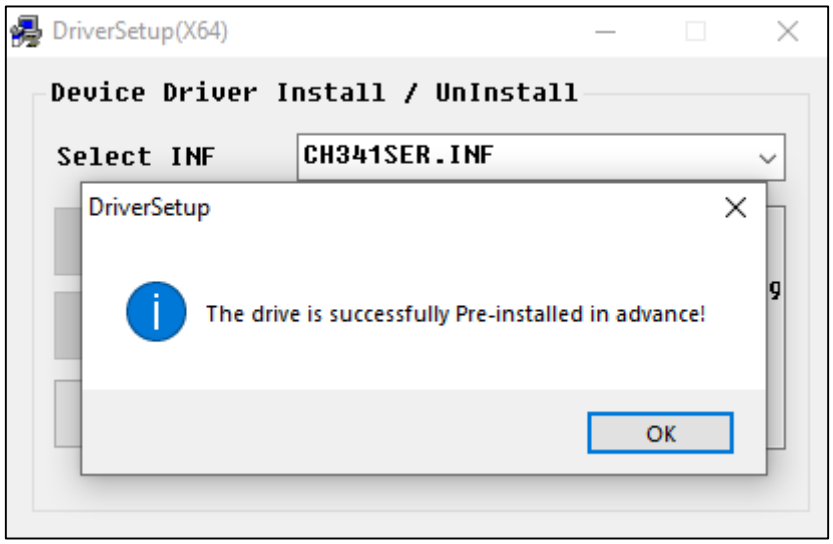
3. Double click "CH341SER.EXE".



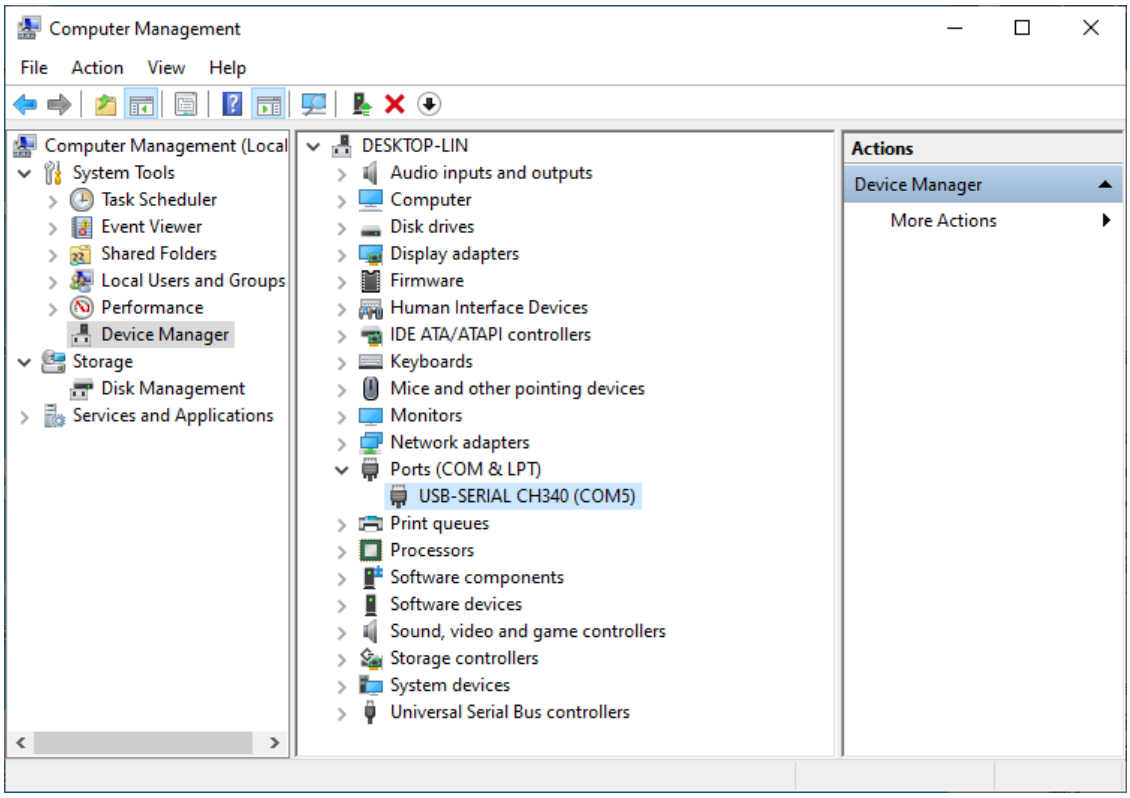
4. Click “INSTALL” and wait for the installation to complete.



5. Install successfully. Close all interfaces.



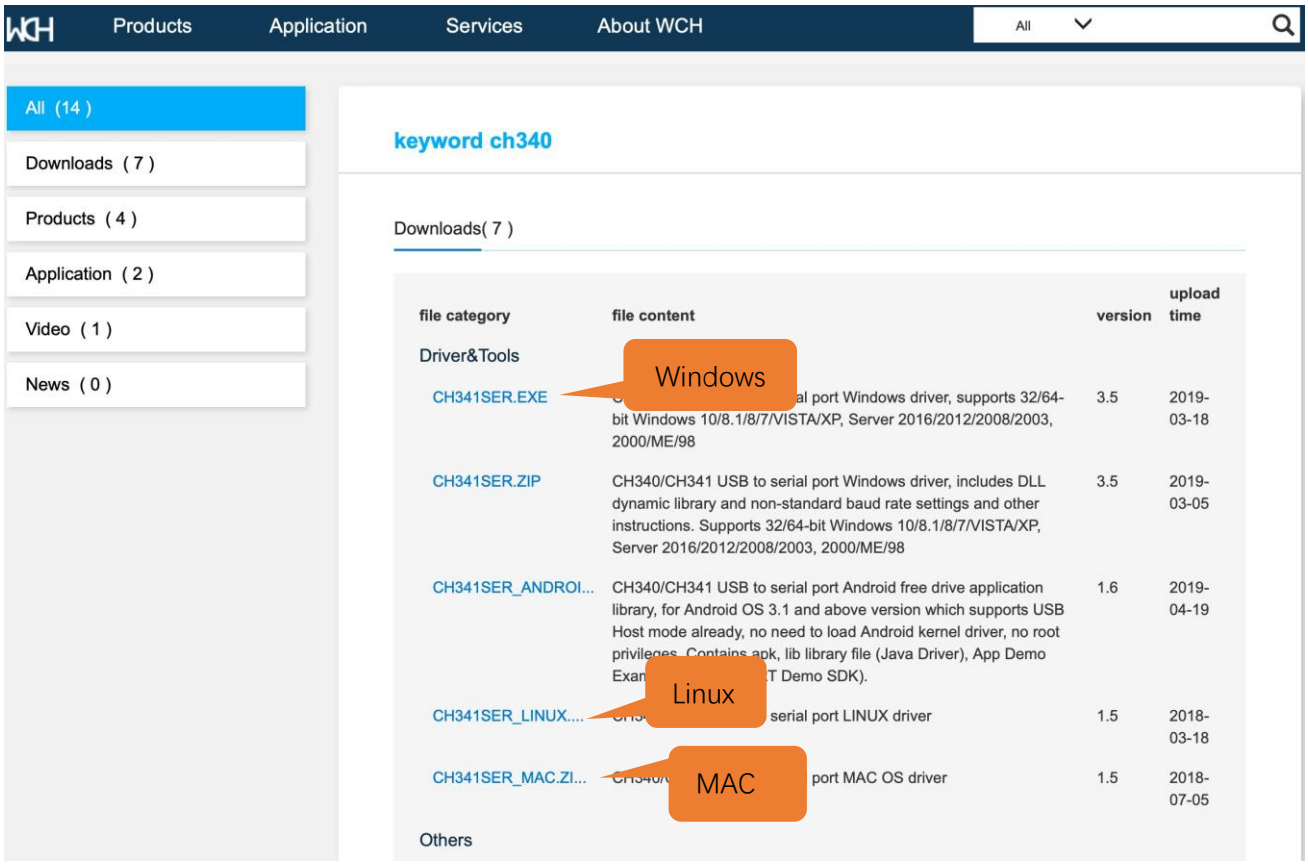
6. When ESP8266 is connected to computer, select “This PC”, right-click to select “Manage” and click “Device Manager” in the newly pop-up dialog box, and you can see the following interface.



7. So far, CH340 has been installed successfully. Close all dialog boxes.

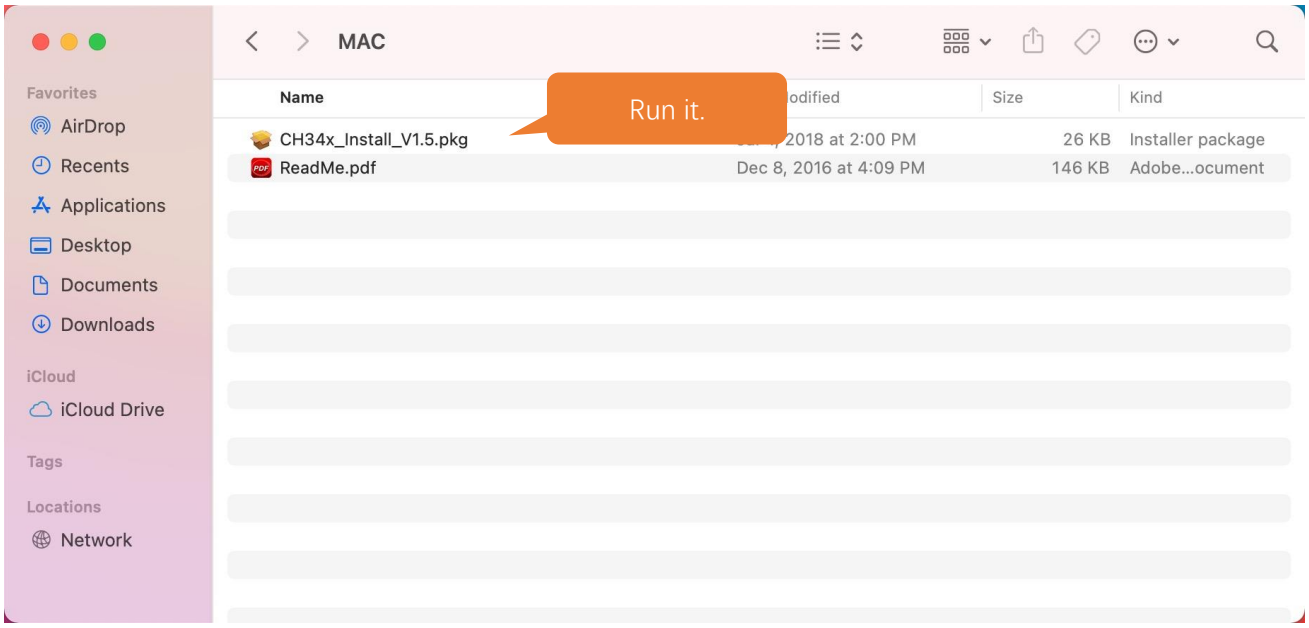
MAC

First, download CH340 driver, click http://www.wch-ic.com/search?q=CH340&t=downloads to download the appropriate one based on your operating system.

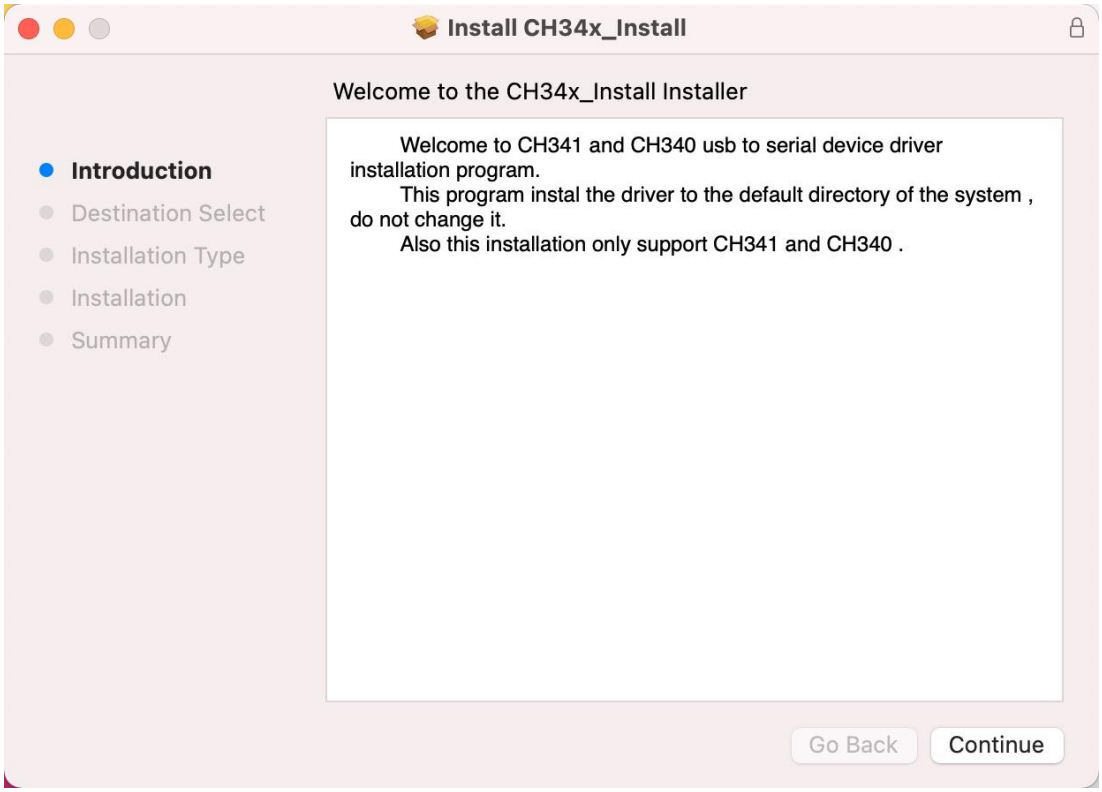


If you would not like to download the installation package, you can open **"Freenove_ESP8266_Board/CH340"**, we have prepared the installation package.

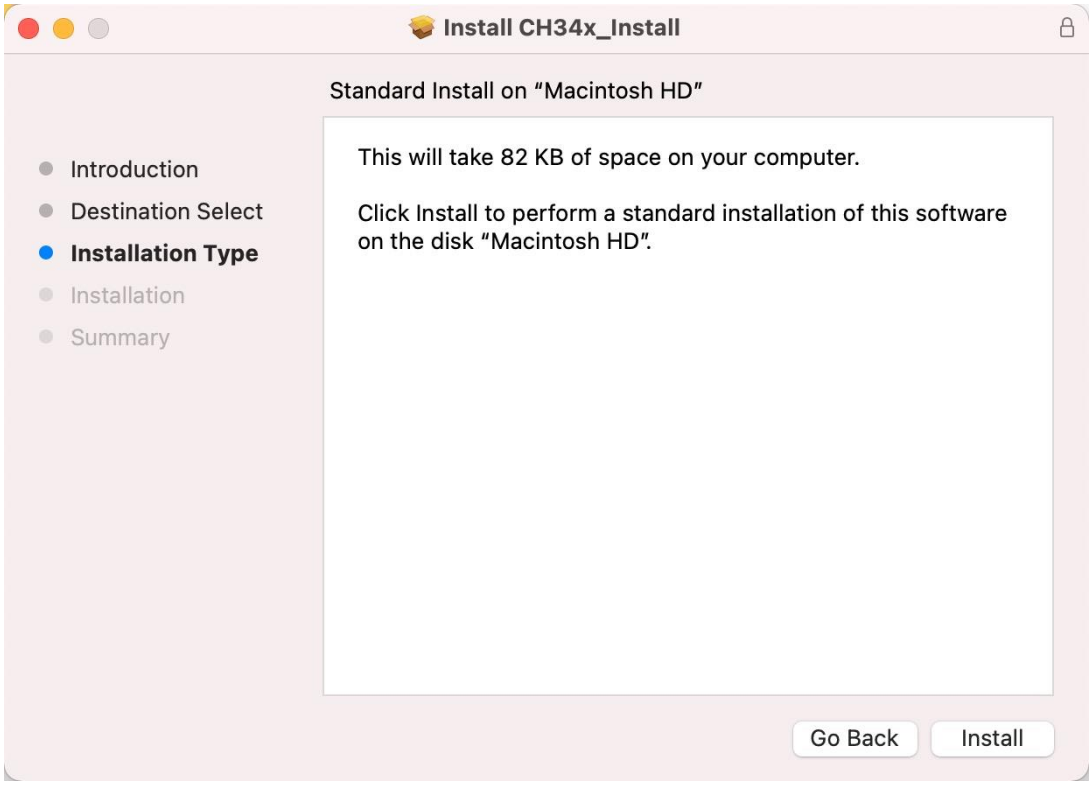
Second, open the folder "**Freenove_ESP8266_Board/CH340/MAC/**"



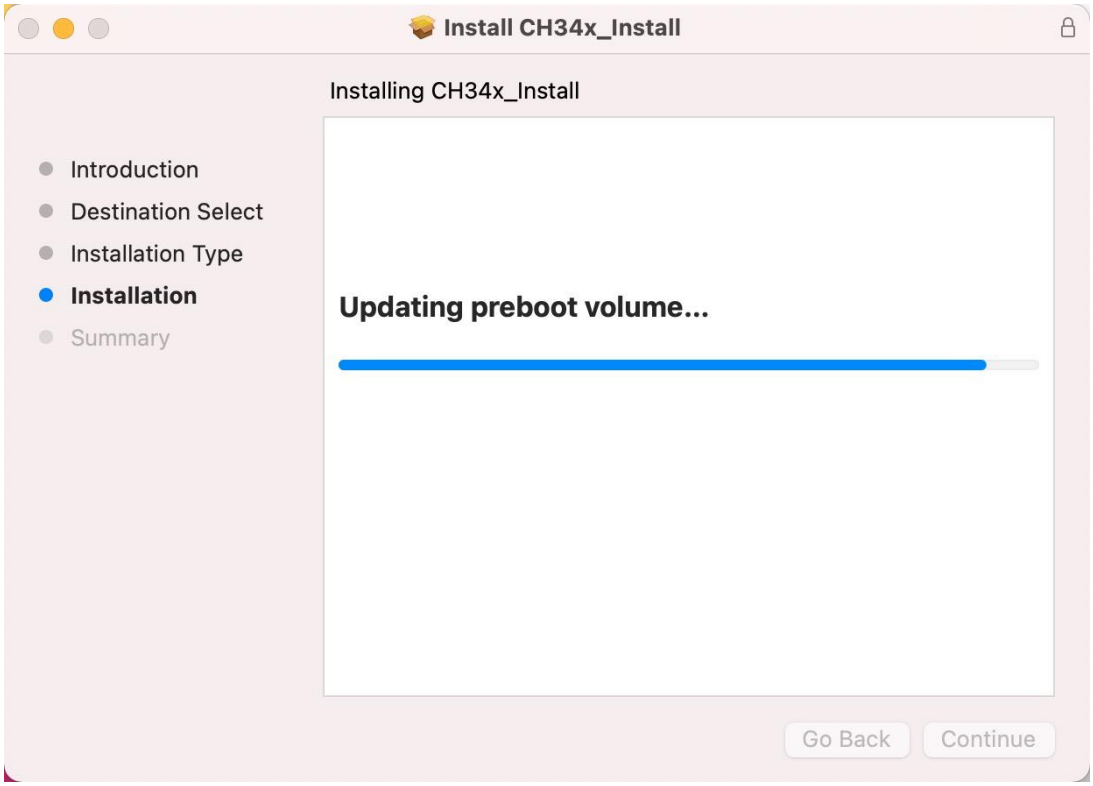
Third, click Continue.



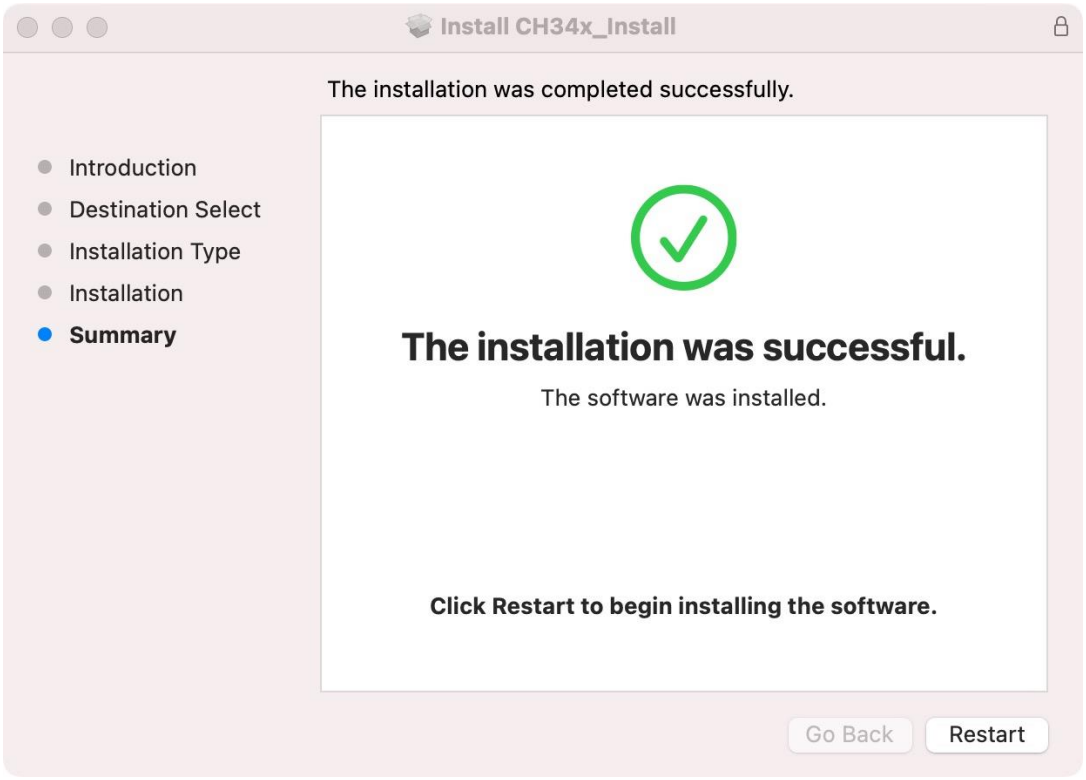
Fourth, click Install.


Install CH34x_Install
Standard Install on "Macintosh HD"
Introduction
Destination Select
Installation Type
Installation
Summary
This will take 82 KB of space on your computer.
Click Install to perform a standard installation of this software on the disk "Macintosh HD".
Go Back
Install

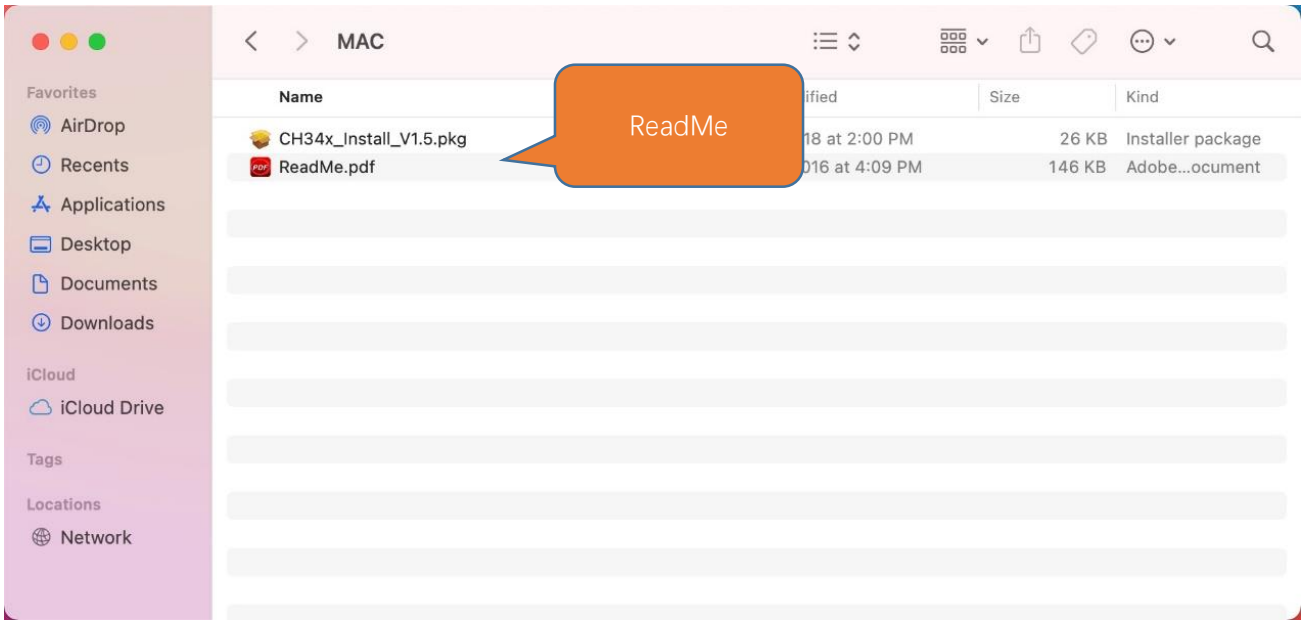
Then, waiting Finsh.



Finally, restart your PC.



If you still haven't installed the CH340 by following the steps above, you can view readme.pdf to install it.

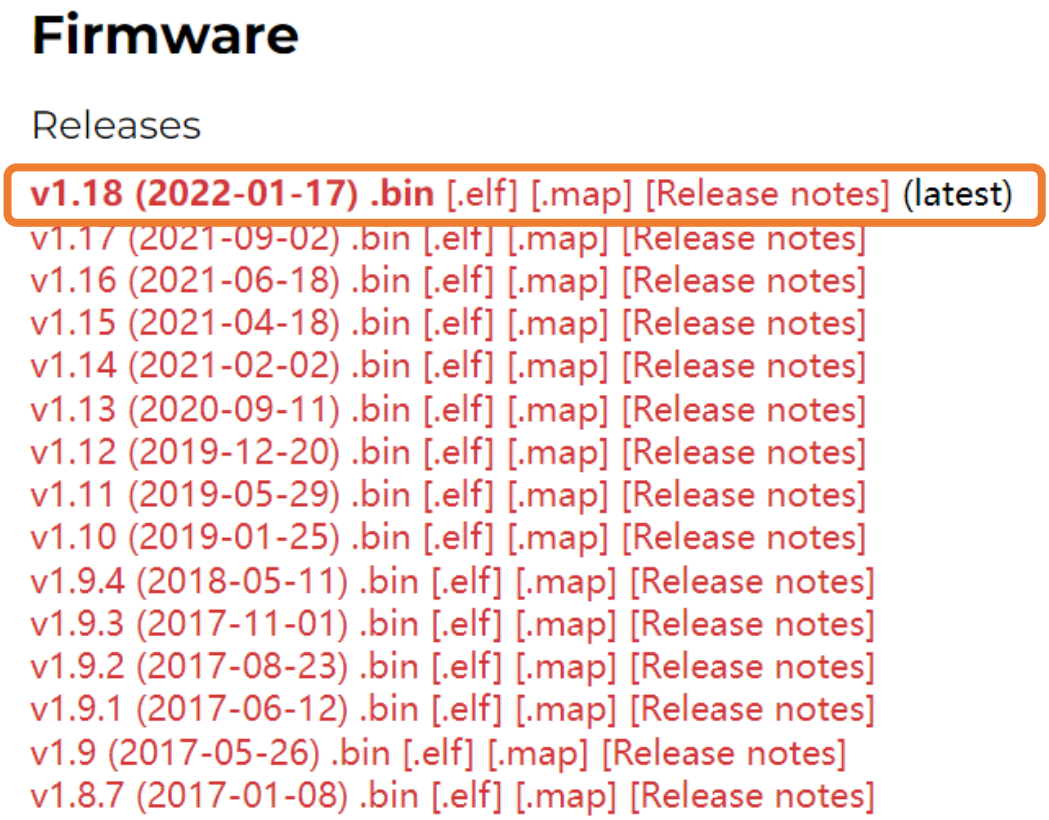


0.4 Burning Micropython Firmware (Important)

To run Python programs on ESP8266, we need to burn a firmware to ESP8266 first.

Downloading Micropython Firmware

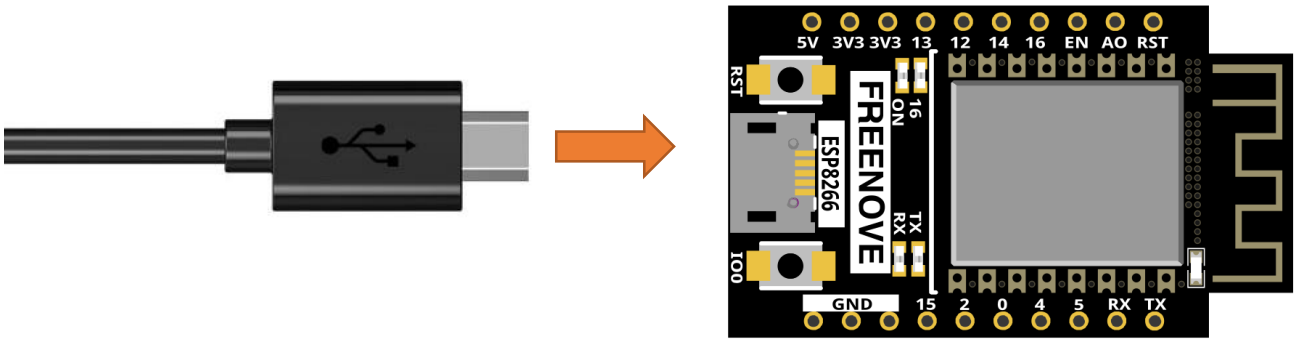
Official website of microPython: http://micropython.org/
Webpage listing firmware of microPython for ESP8266: https://micropython.org/download/esp8266/



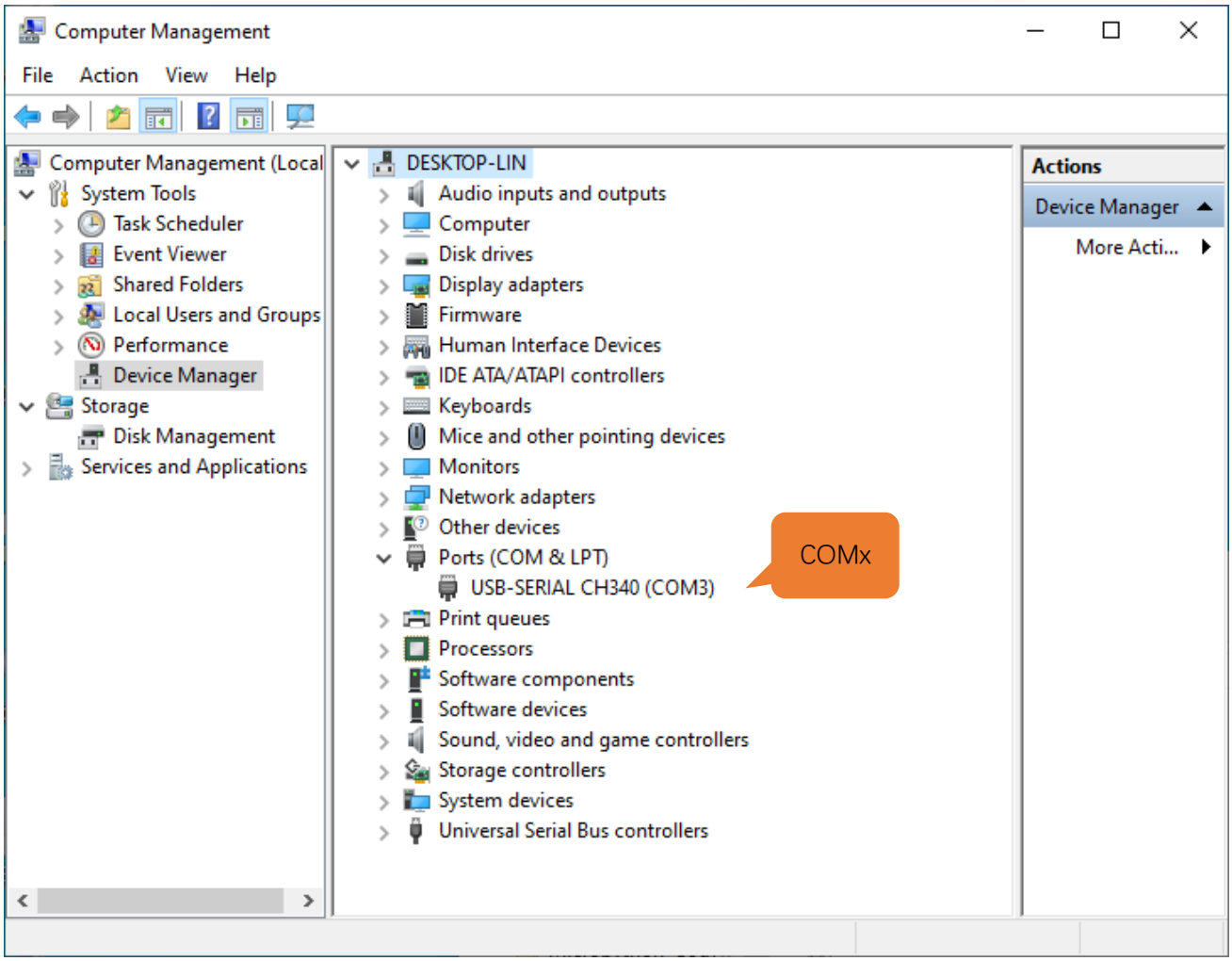
Firmware used in this tutorial is **esp8266-20220117-v1.18.bin**
Click the following link to download directly:
https://micropython.org/resources/firmware/esp8266-20220117-v1.18.bin
This file is also provided in our data folder "**Freenove_ESP8266_Board /Python/Python_Firmware**".

Burning a Micropython Firmware

Connect your computer and ESP8266 with a USB cable.

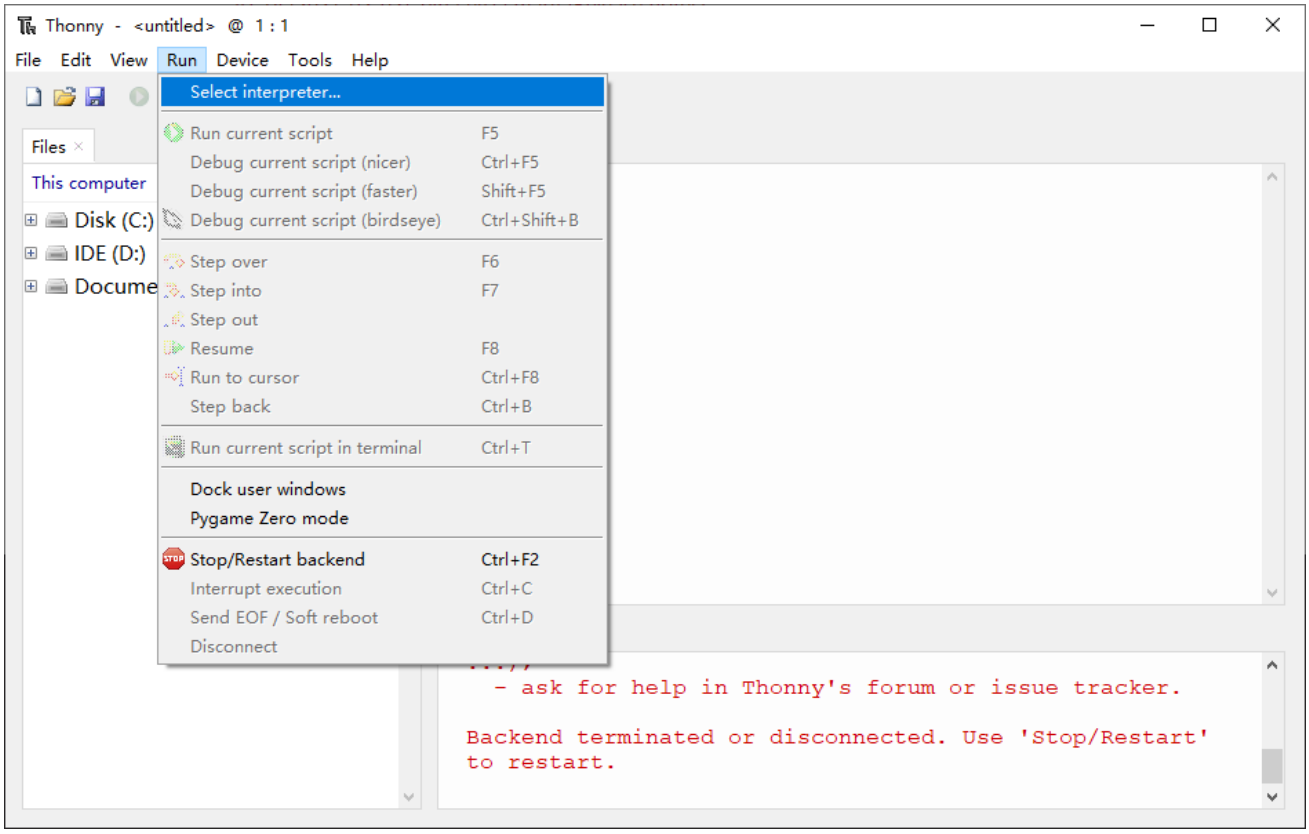


Make sure that the driver has been installed successfully and that it can recognize COM port correctly. Open device manager and expand "Ports".

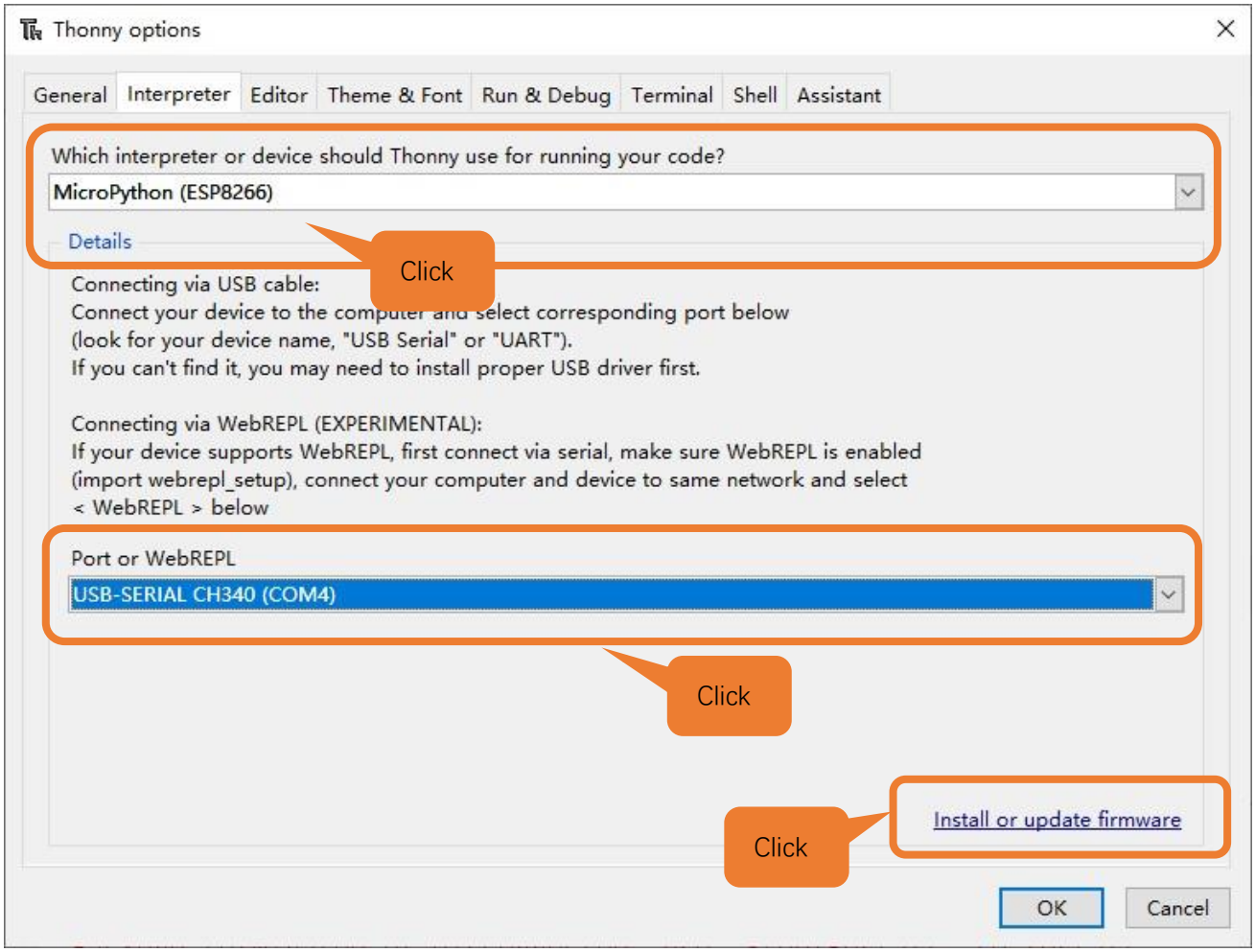


Note: the port of different people may be different, which is a normal situation.

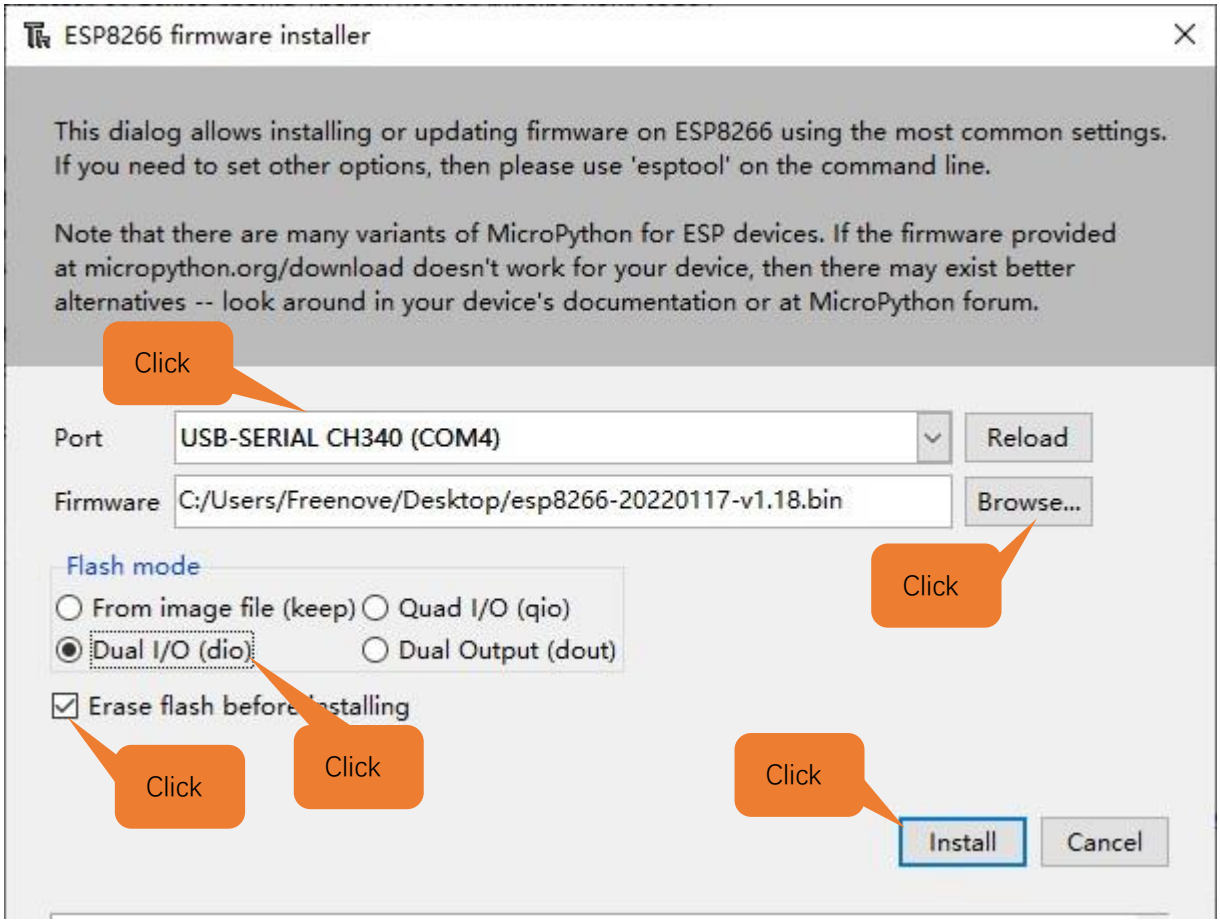
1. Open Thonny, click “run” and select “Select interpreter...””



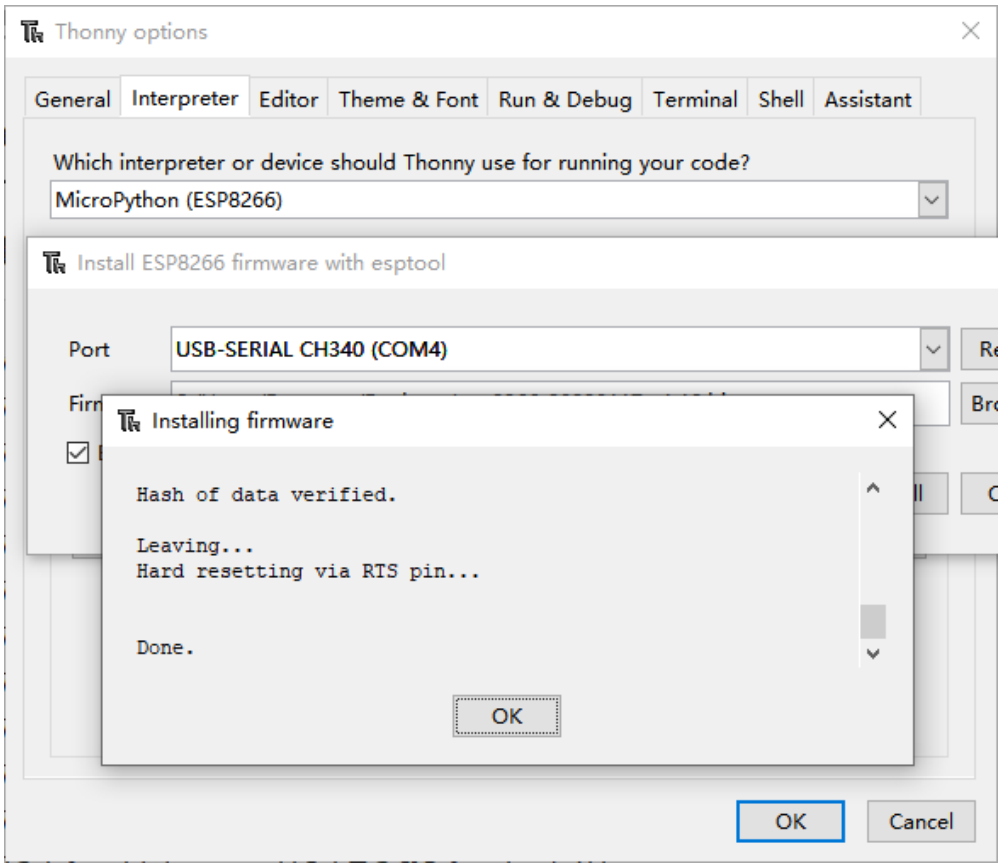
2. Select "Micropython (ESP8266)", select "USB-SERIAL CH340 (COM4)", and then click the long button under "Firmware".

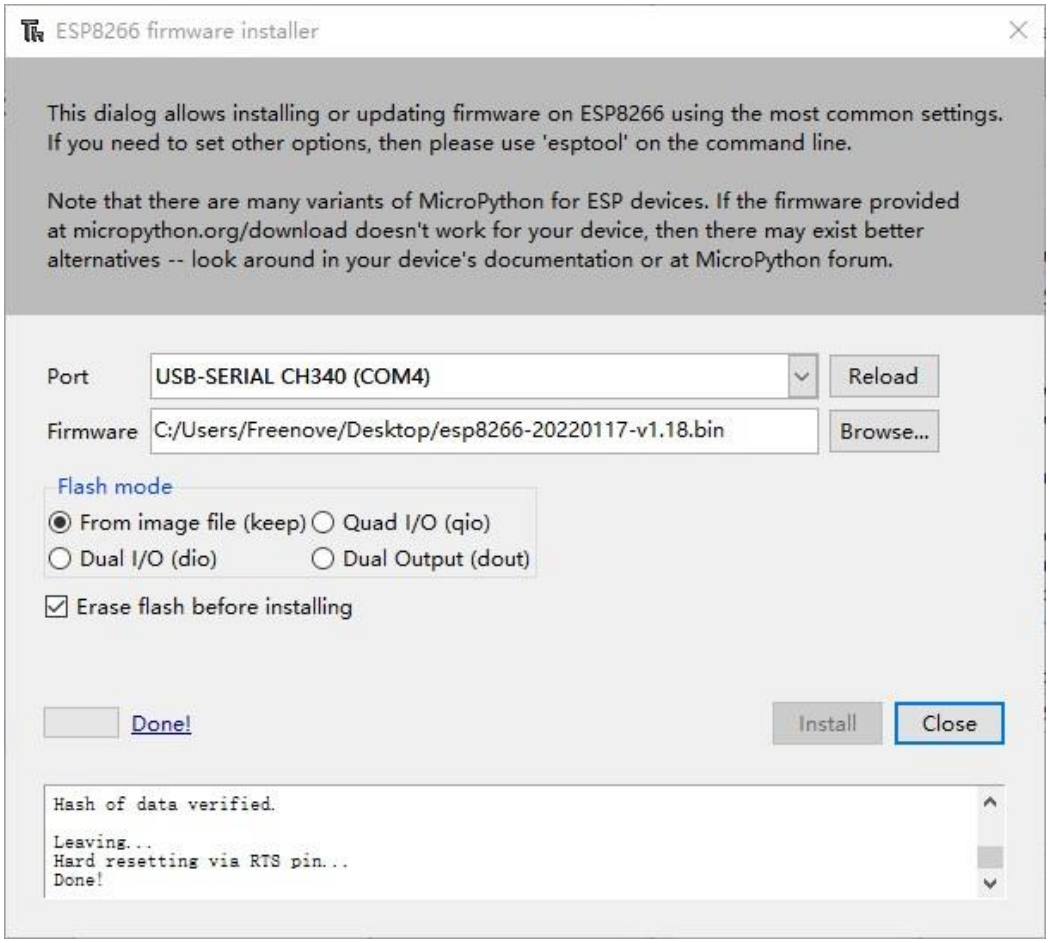


3. The following dialog box pops up. Select "USB-SERIAL CH340 (COM4)" for "Port" and then click "Browse...". Select the previous prepared microPython firmware "**esp8266-20220117-v1.18.bin**". Check "Erase flash before installing" and click "install" to wait for the prompt of finishing installation.
Here we need to select Flash mode.On our ESP8266 development board, choose "DIO" mode or "DOUT" mode for better compatibility.If the ESP8266 module is abnormal, check whether the ESP8266 module works in the two modes.
Flash works in DOUT, DIO, QOUT, and QIO modes.
1.DOUT: Address is input in 1-line mode and data is output in 2-line mode.
2.DIO: Address is input in 2-line mode and data is output in 2-line mode.
3.QOUT: Address is input in 1-line mode and data is output in 4-line mode.
4.QIO: Address is input in 4-line mode and data is output in 4-line mode.
If you need to use the QIO mode, ensure that the Flash supports the QIO mode.

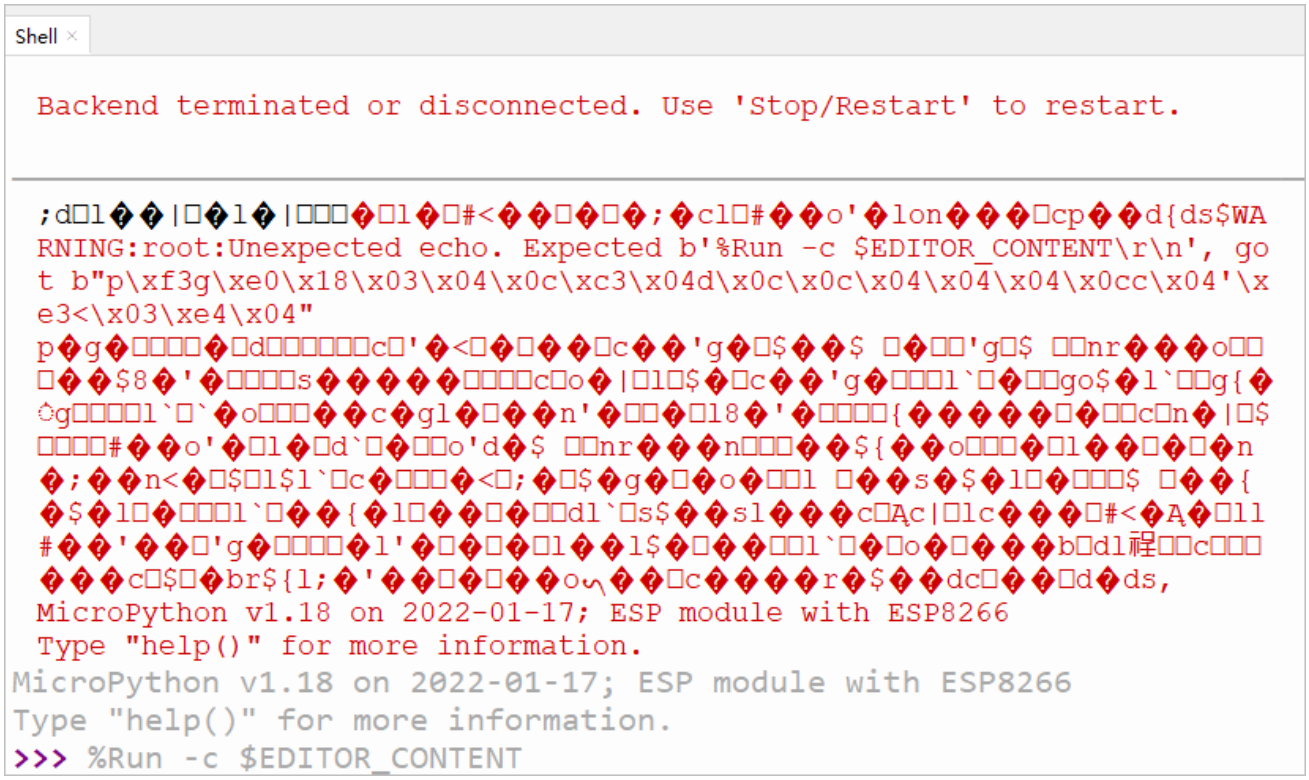


4. Wait for the installation to be done.

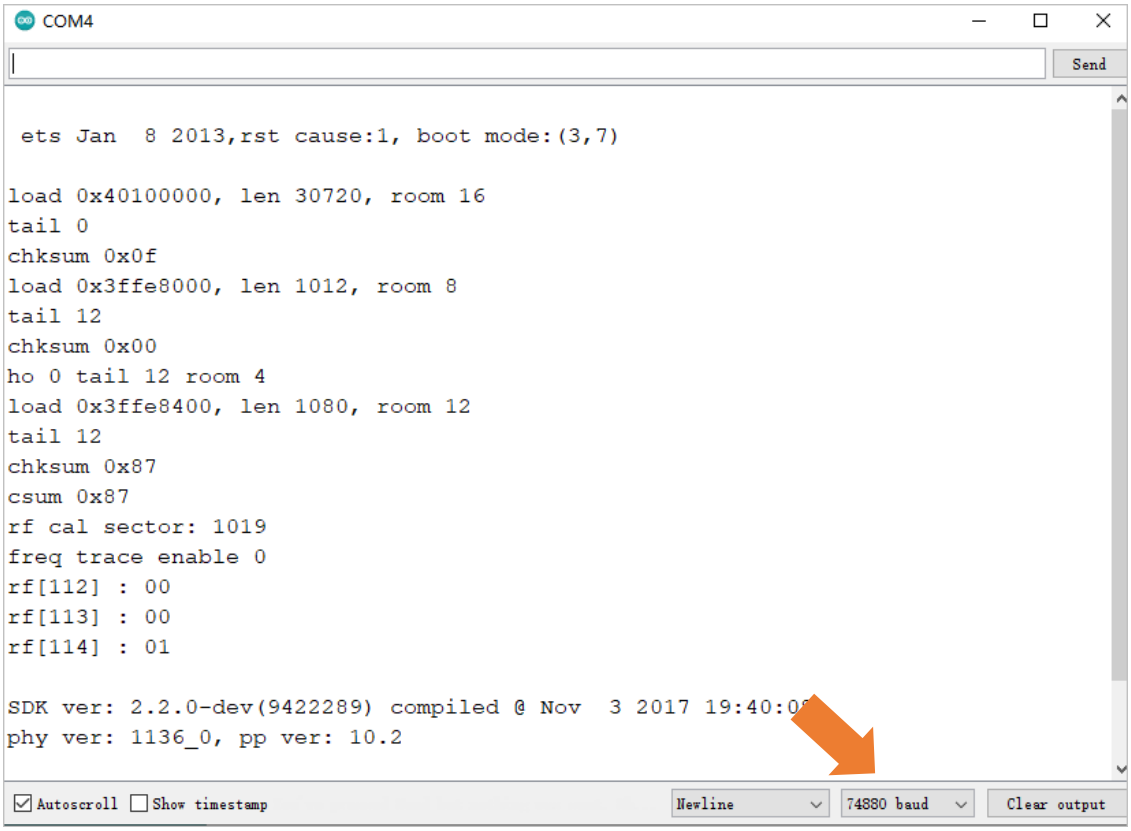




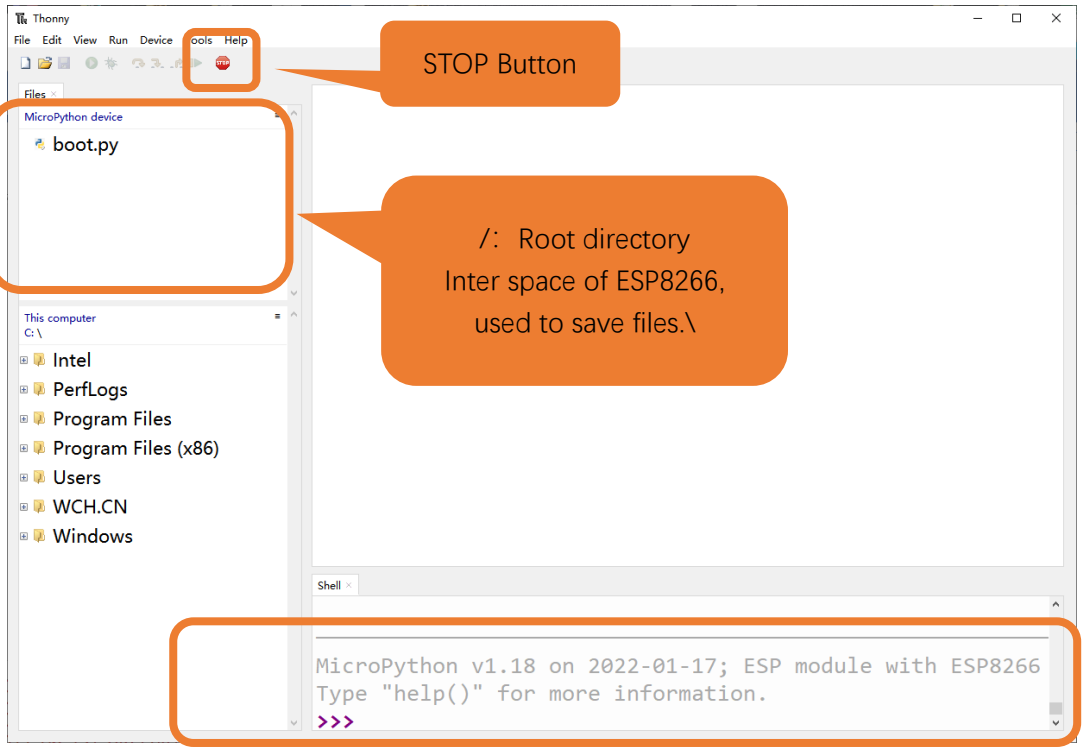
After burning the Micropython firmware, "shell" will display some garbled characters, please do not worry, the garbled characters are displayed as follows:



When the ESP8266 is powered on, the default baud rate is 74880. The default communication and serial port in the ESP8266 firmware is 115200. So if you set the serial port to 74880, this time can be displayed normally. Here, we use The Arduino IDE serial port tool for output and display. The details are as follows:



5. Close all dialog boxes, turn to main interface and click “STOP”. As shown in the illustration below. Ignore the garbled part here.

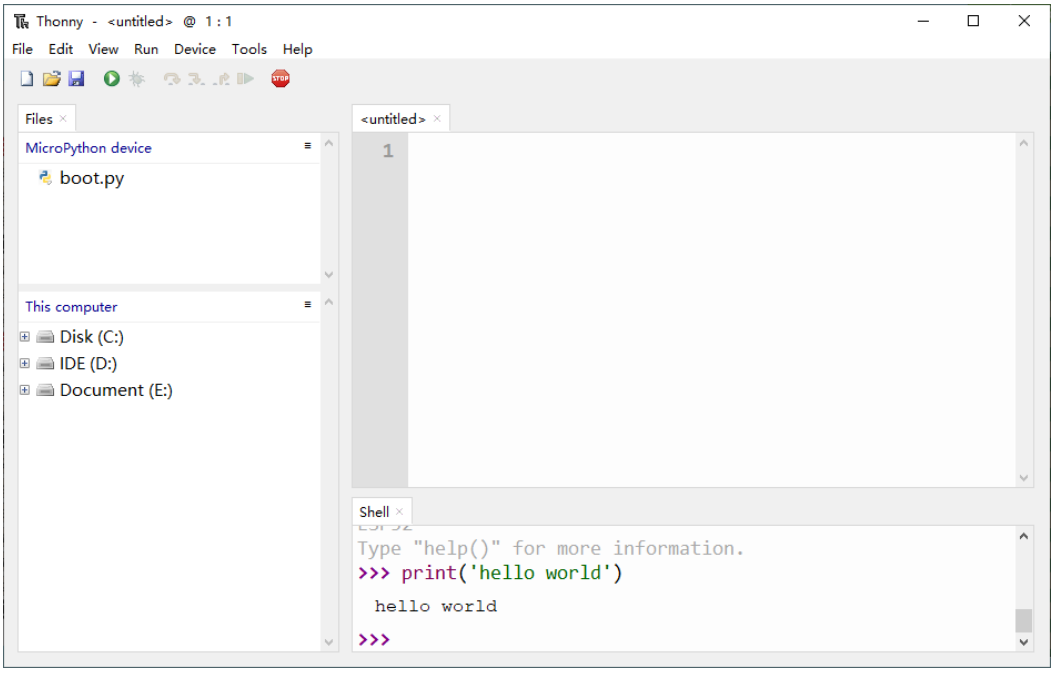


6. So far, all the preparations have been made.

0.5 Testing codes (Important)

Testing Shell Command

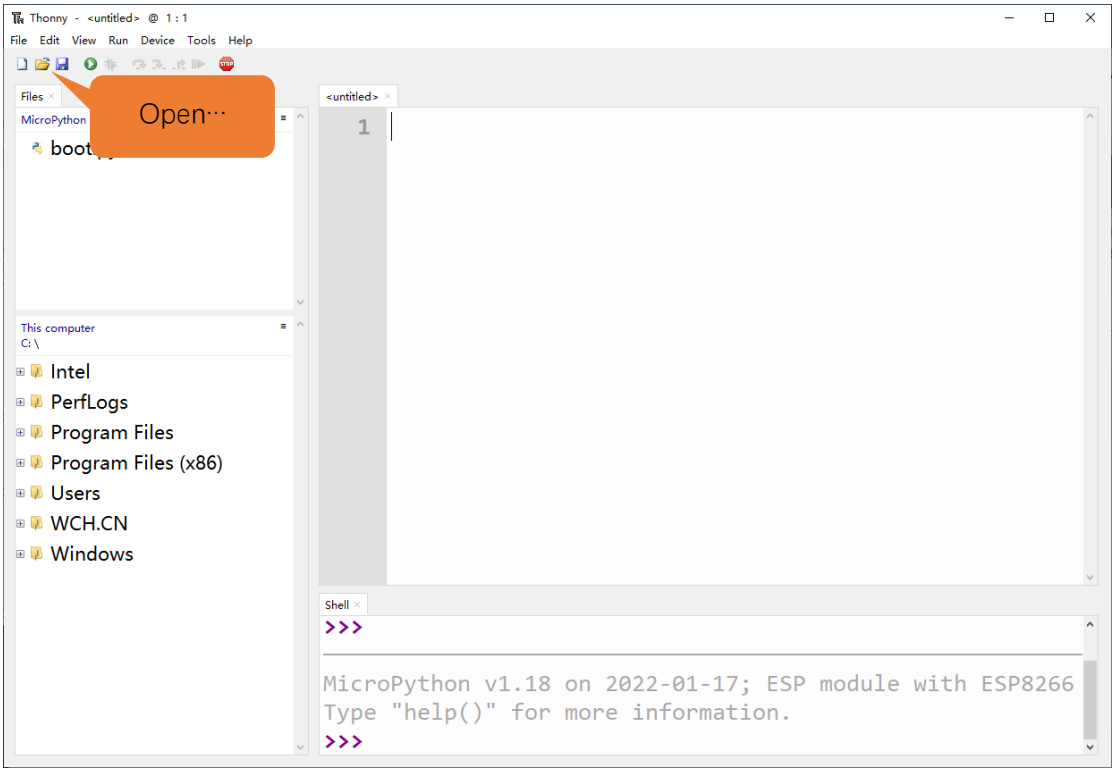
Enter "print('hello world')" in "Shell" and press Enter.



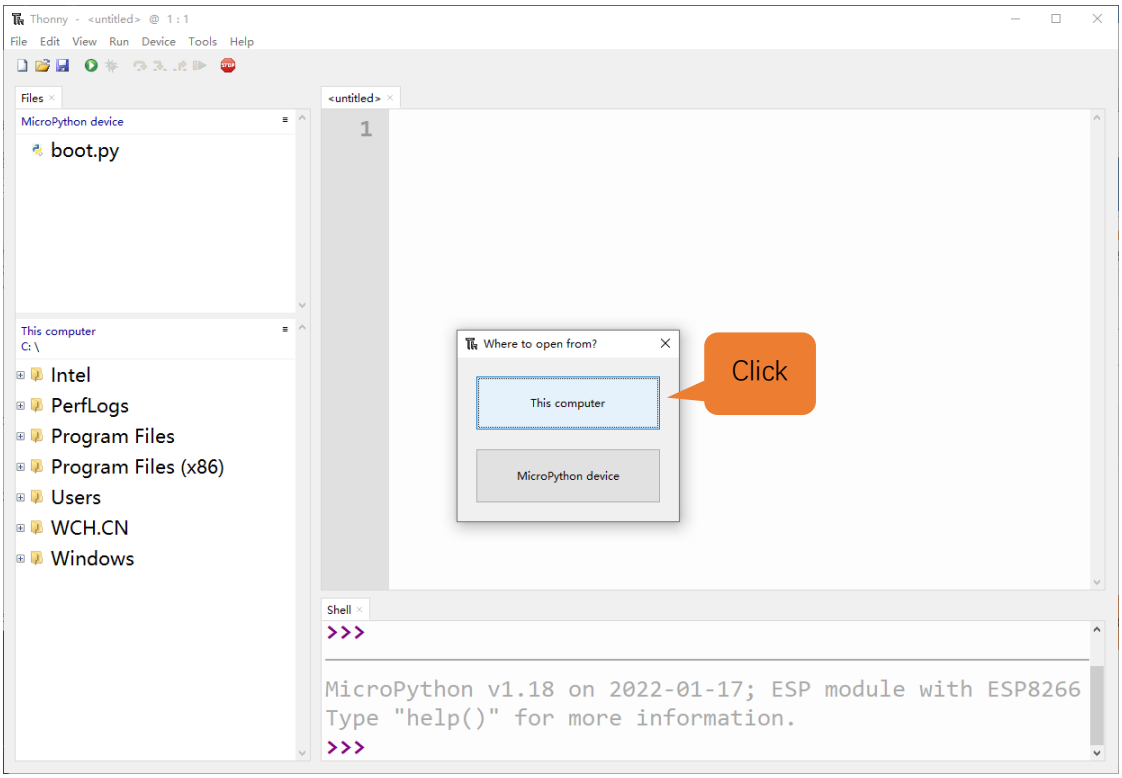
Running Online

ESP8266 needs to be connected to a computer when it is run online. Users can use Thonny to writer and debug programs.

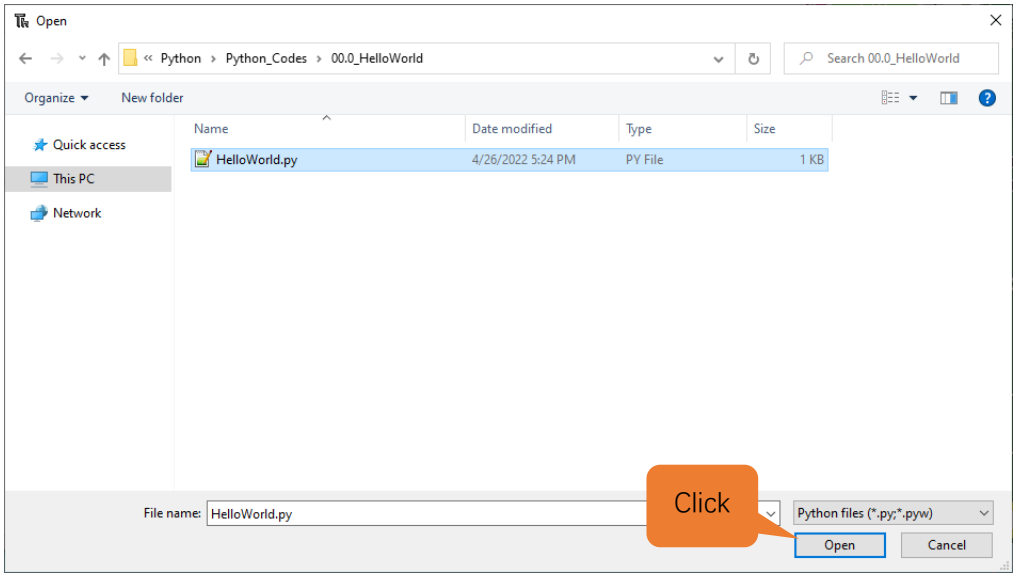
1. Open Thonny and click “Open···”.



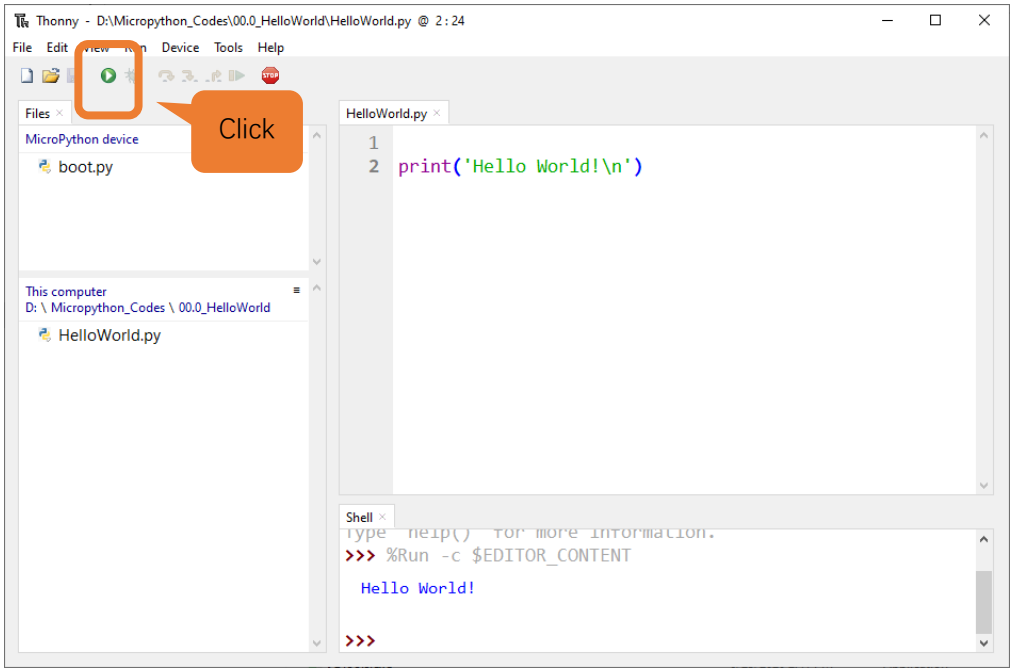
2. On the newly pop-up window, click “This computer”.



In the new dialog box, select "**HelloWorld.py**" in "**Freenove_ESP8266_Board/Python/Python_Codes/00.0_HelloWorld**" folder.



Click "Run current script" to execute the program and "Hello World" will be printed in "Shell".

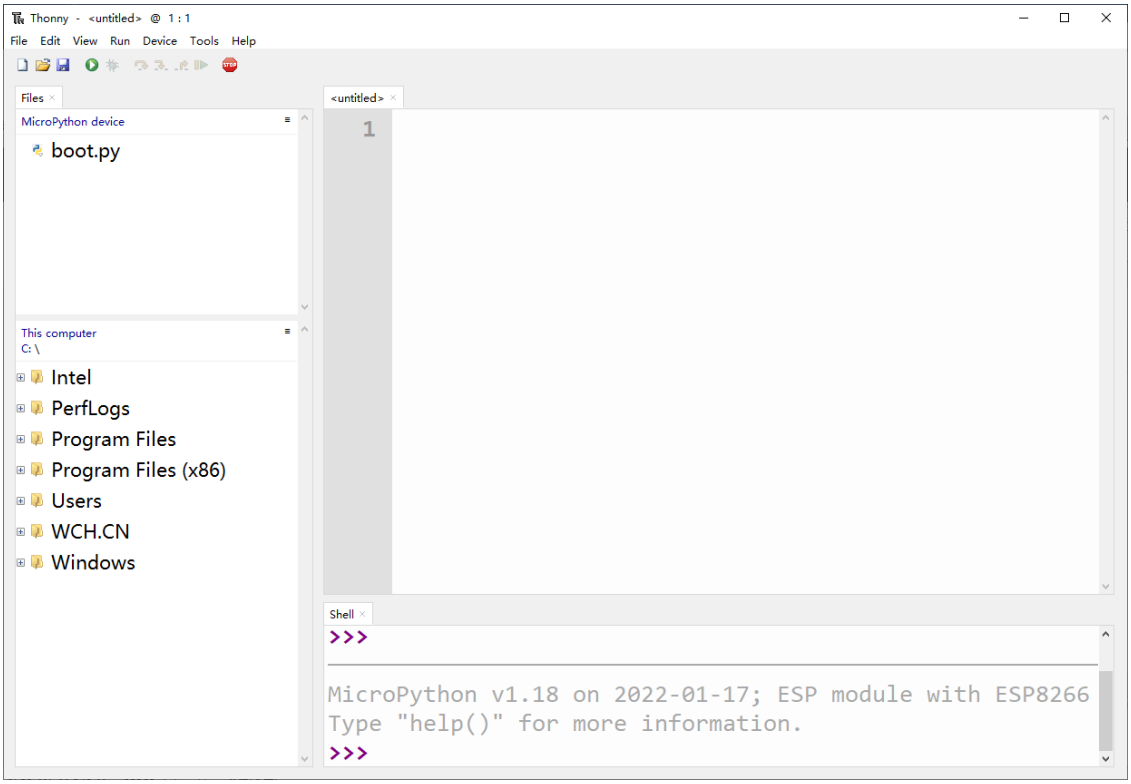


Note: When running online, if you press the reset key of ESP8266, user's code will not be executed again. If you wish to run the code automatically after resetting the code, please refer to the following Running Offline.

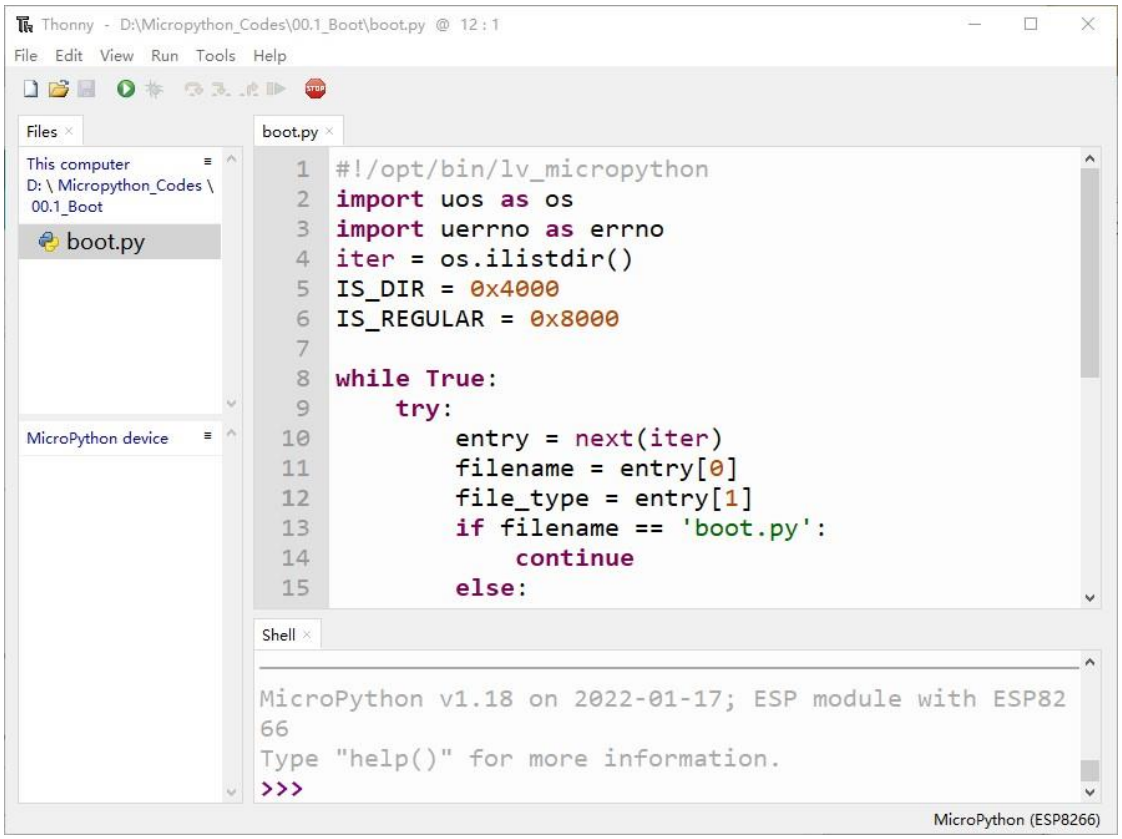
Running Offline (Important)

After ESP8266 is reset, it runs the file boot.py in root directory first and then runs file main.py, and finally, it enters "Shell". Therefore, to make ESP8266 execute user's programs after resetting, we need to add a guiding program in boot.py to execute user's code.

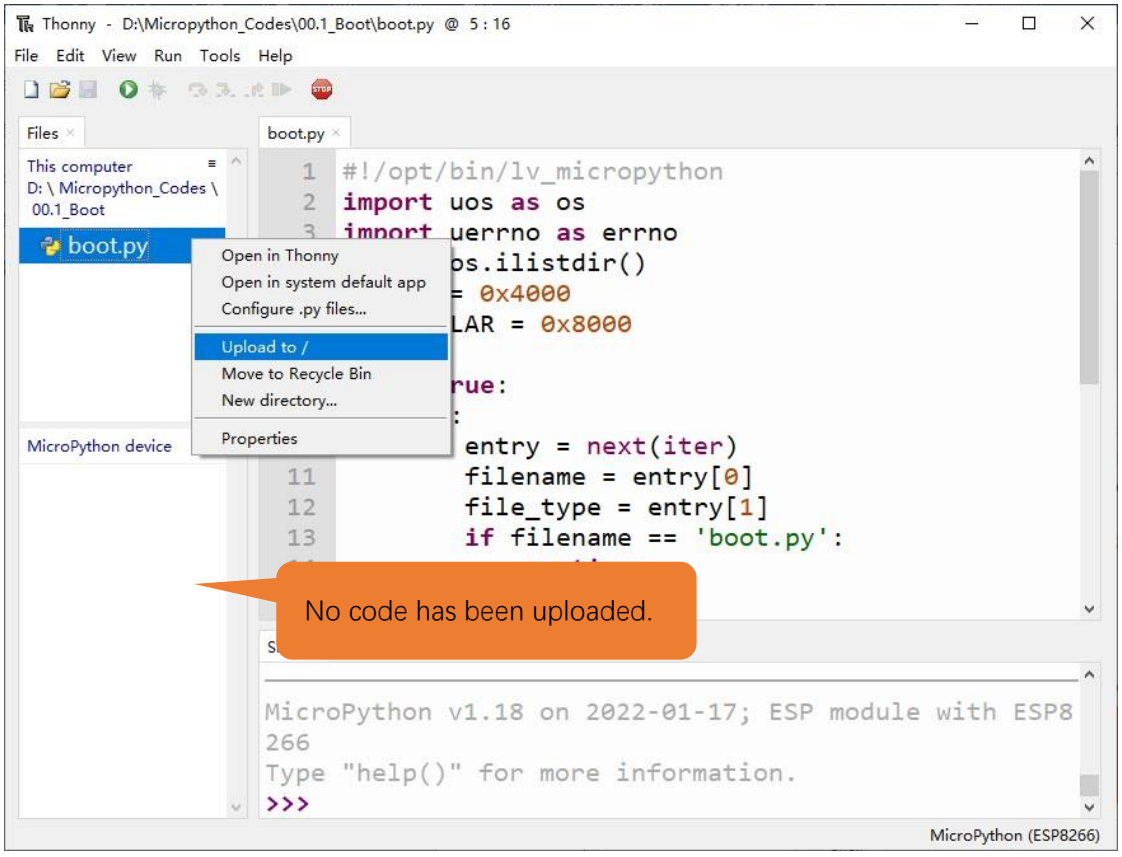
1. Move the program folder "**Freenove_ESP8266_Board/Python/Python_Codes**" to disk(D) in advance with the path of "**D:/Micropython_Codes**". Open "Thonny".



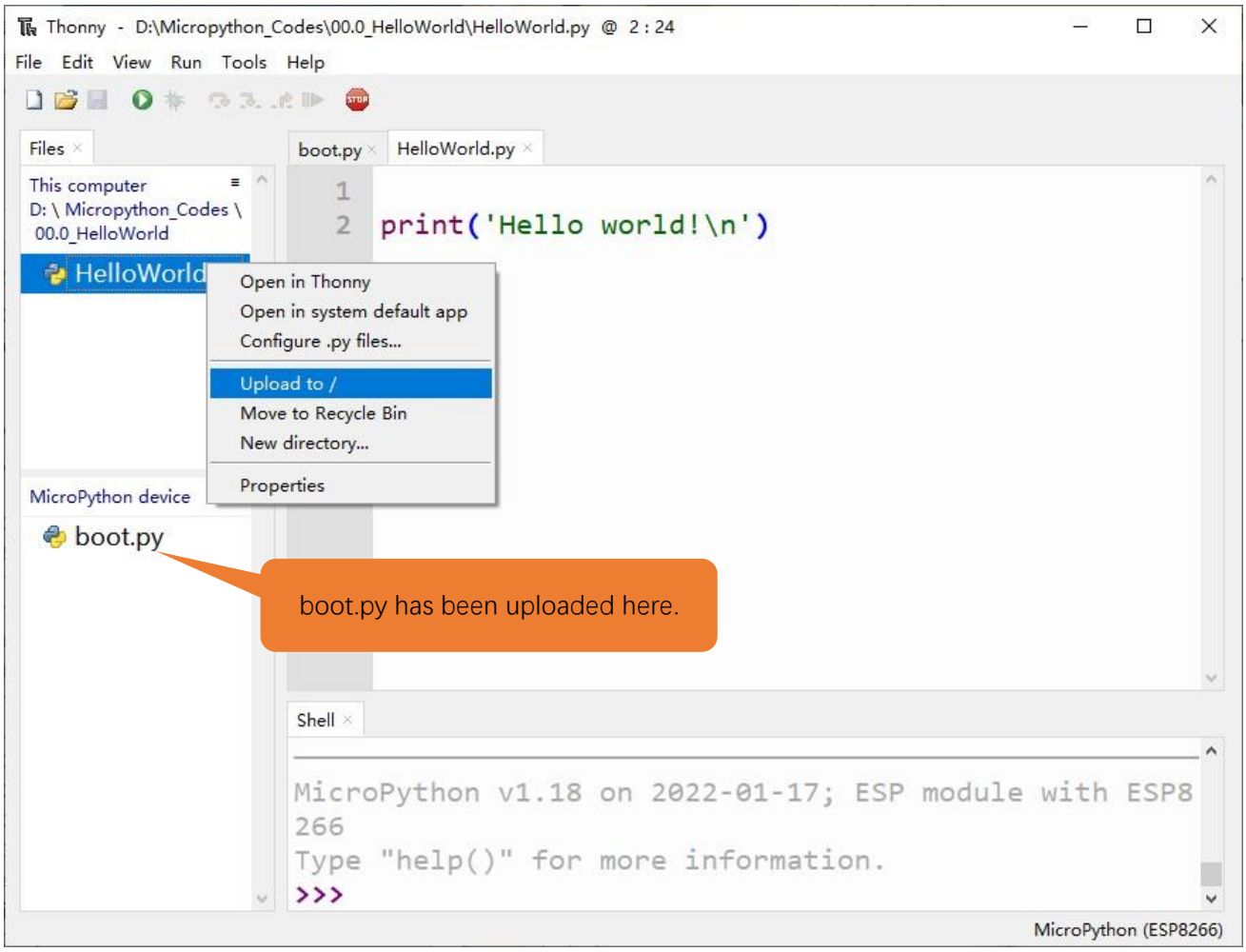
2. Expand "00.1_Boot" in the "Micropython_Codes" in the directory of disk(D), and double-click boot.py, which is provided by us to enable programs in "MicroPython device" to run offline.



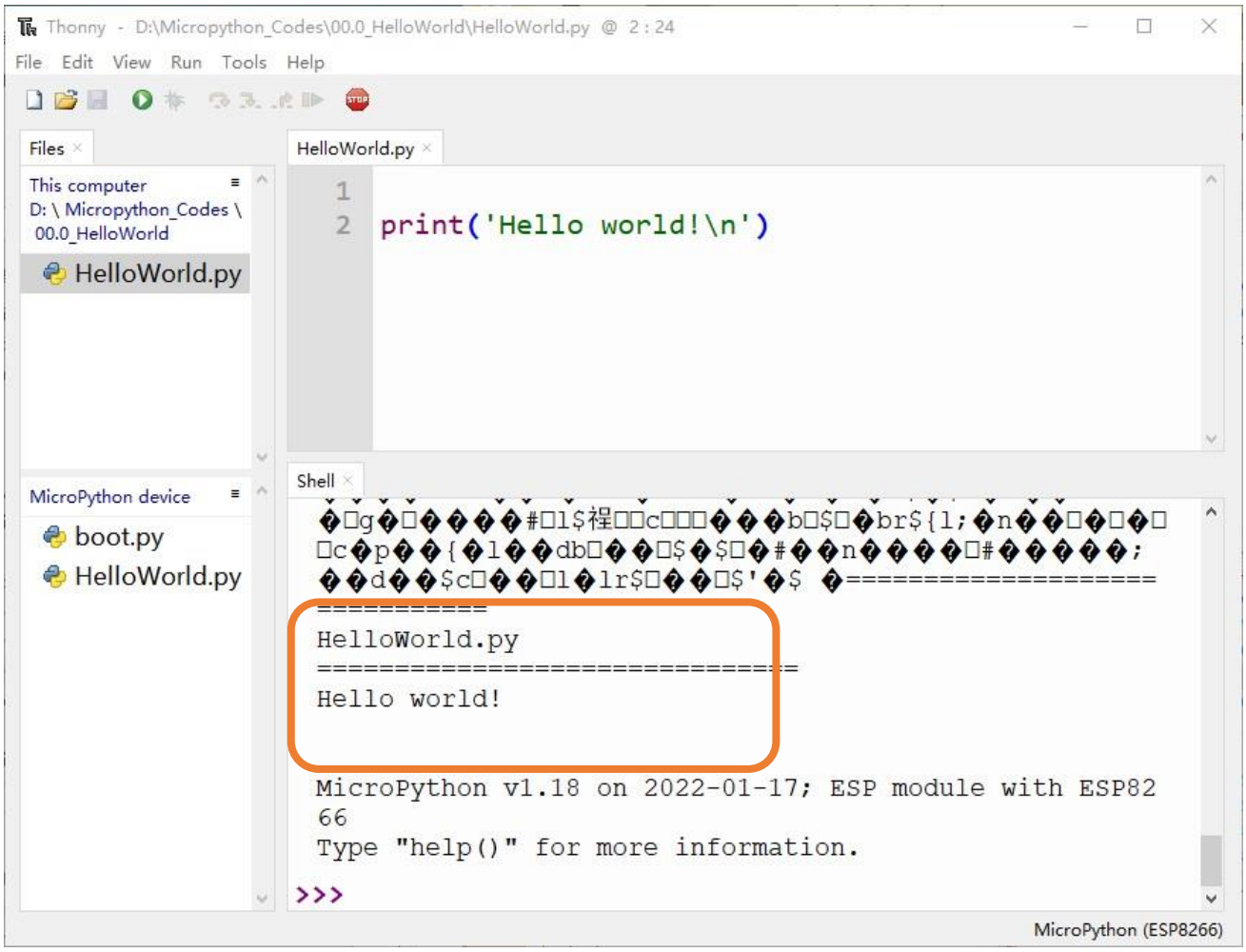
If you want your written programs to run offline, you need to upload boot.py we provided and all your codes to "MicroPython device" and press ESP8266's reset key. Here we use programs 00.0 and 00.1 as examples. Select "boot.py", right-click to select "Upload to /".



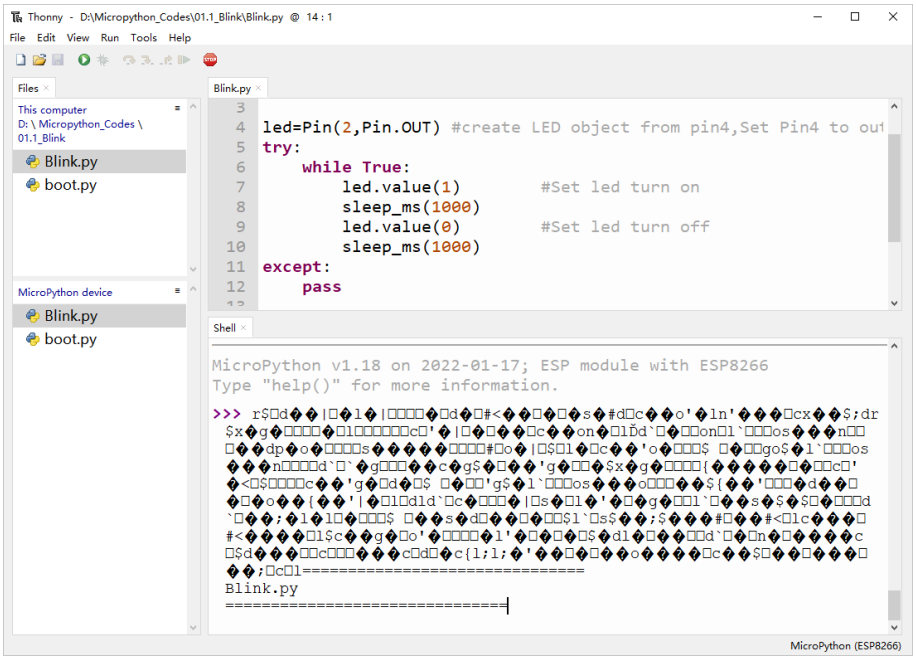
Similarly, upload “HelloWorld.py” to “MicroPython device”.



3. Press the reset key and in the box of the illustration below, you can see the code is executed.

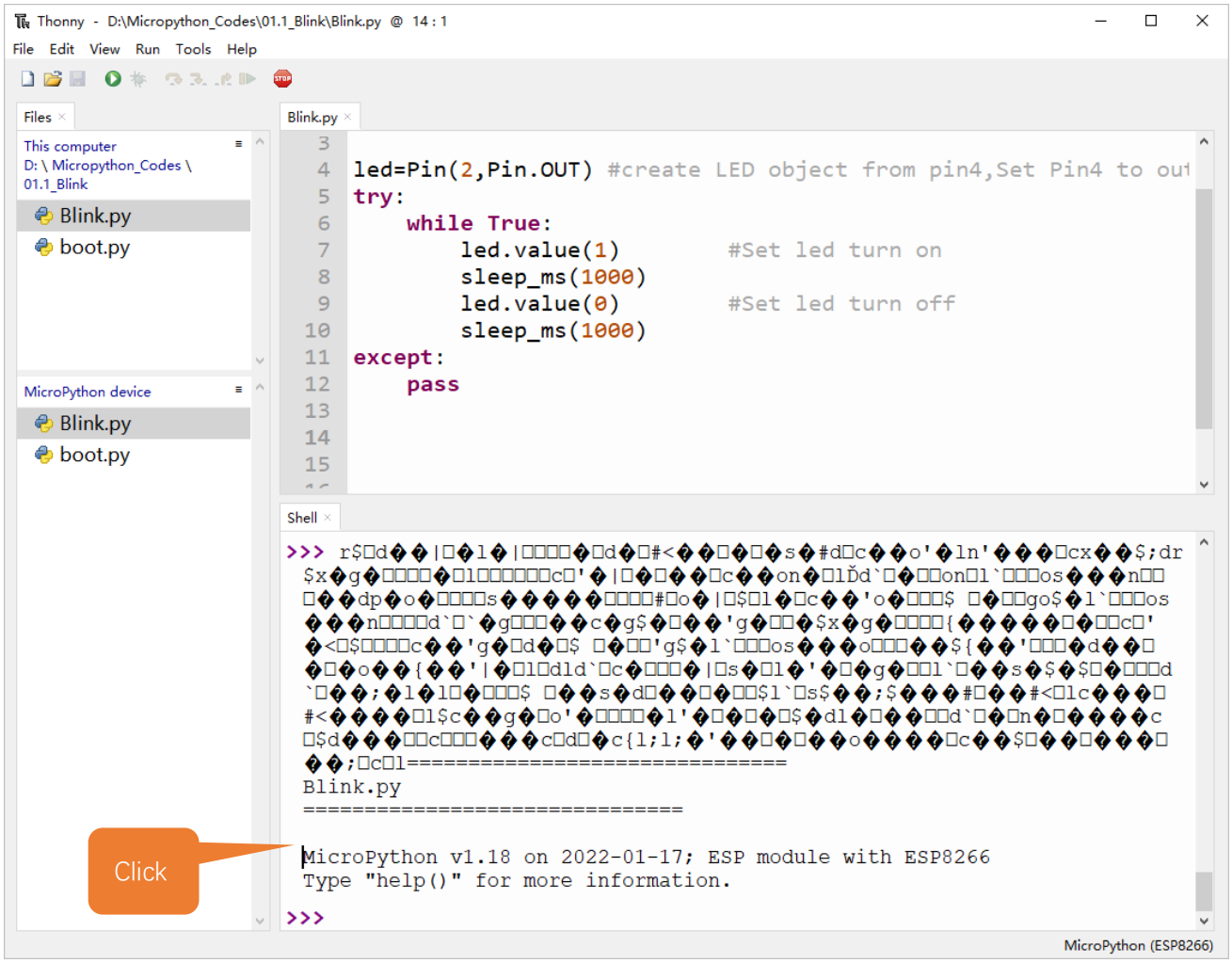


When you press the Reset key to run the offline code, the program will continue to execute while the ESP8266 is powered on.

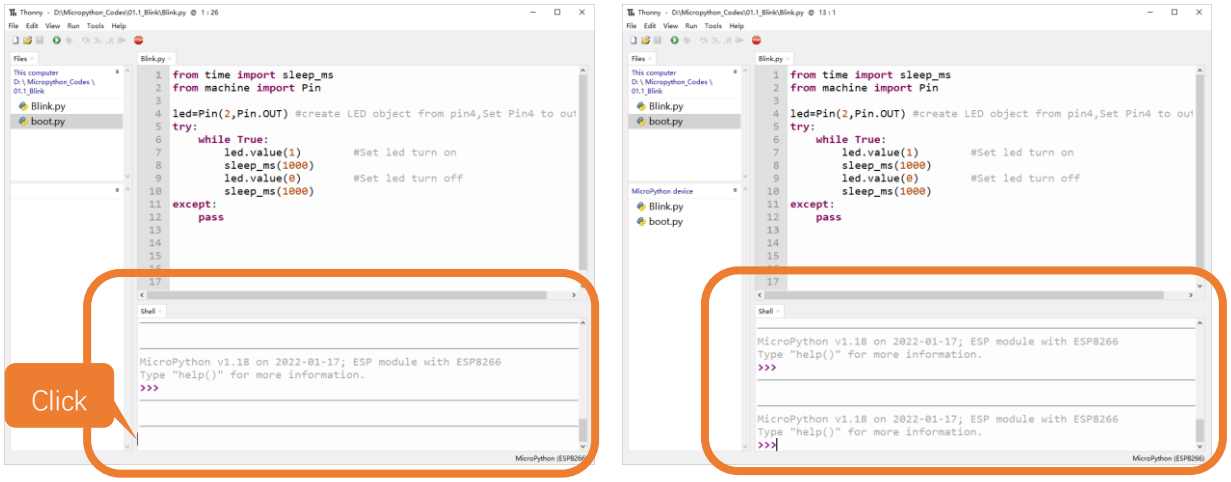


When you run offline code, you can exit the running program by pressing "CTRL" and "C" at the same time.

Before pressing the keyboard, click "Shell" with the mouse, and then press the keyboard key.



When your "Shell" is unresponsive or abnormal, you can exit the running program by pressing "CTRL" and "C" simultaneously.

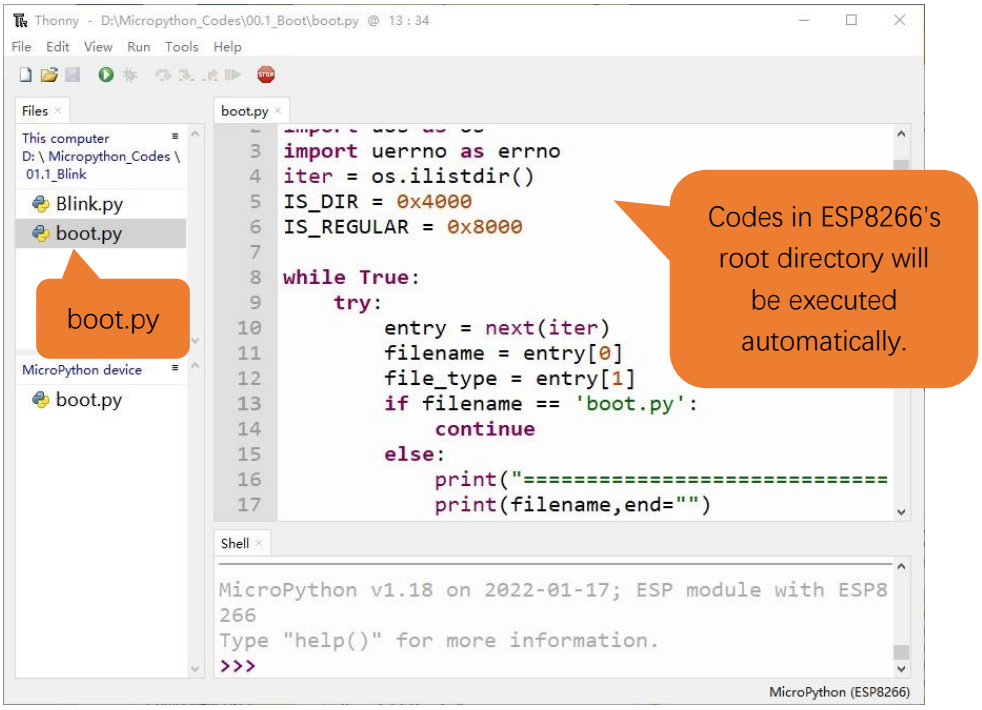


If the ESP8266 does not work properly, you can press CTRL and C at the same time to observe whether the Shell responds. If the ESP8266 still does not work properly, you can also rewrite the Micropython firmware and perform related operations again.

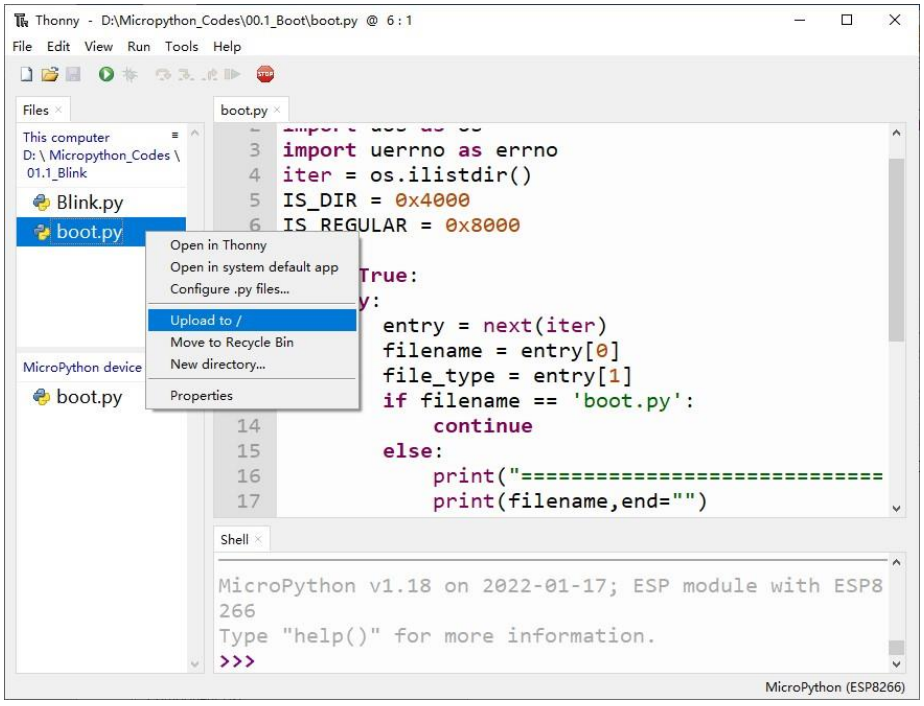
0.6 Thonny Common Operation

Uploading Code to ESP8266

For convenience, we take the opertation on “boot.py” as an example here. We have added “boot.py” to every code directory. Each time when ESP8266 restarts, if there is a “boot.py” in the root directory, it will execute this code first.

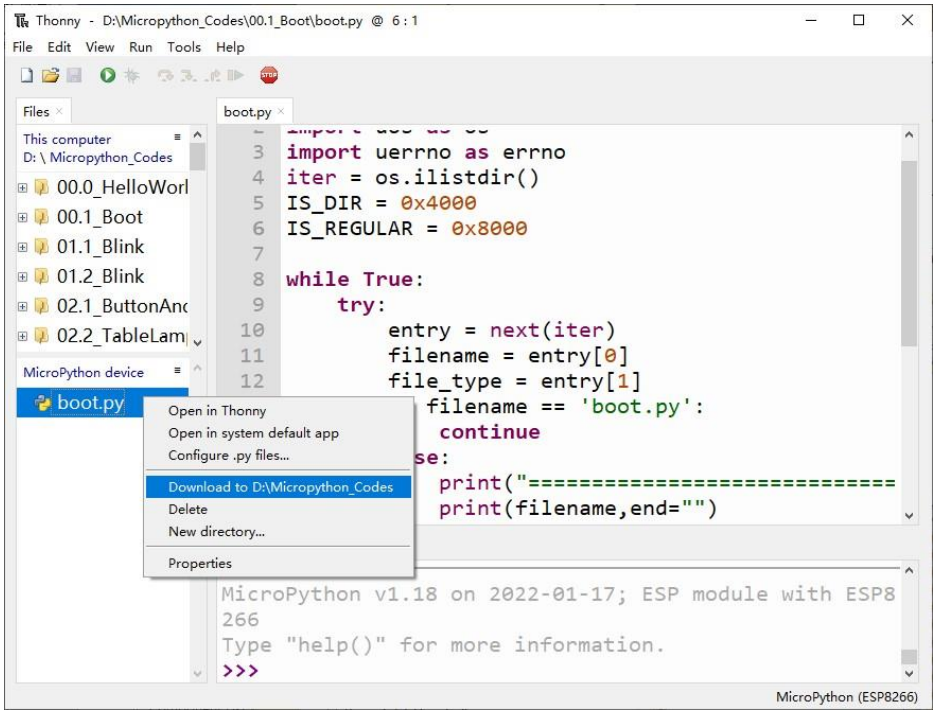


Select “Blink.py” in “01.1_Blink”, right-click your mouse and select “Upload to /” to upload code to ESP8266’s root directory.



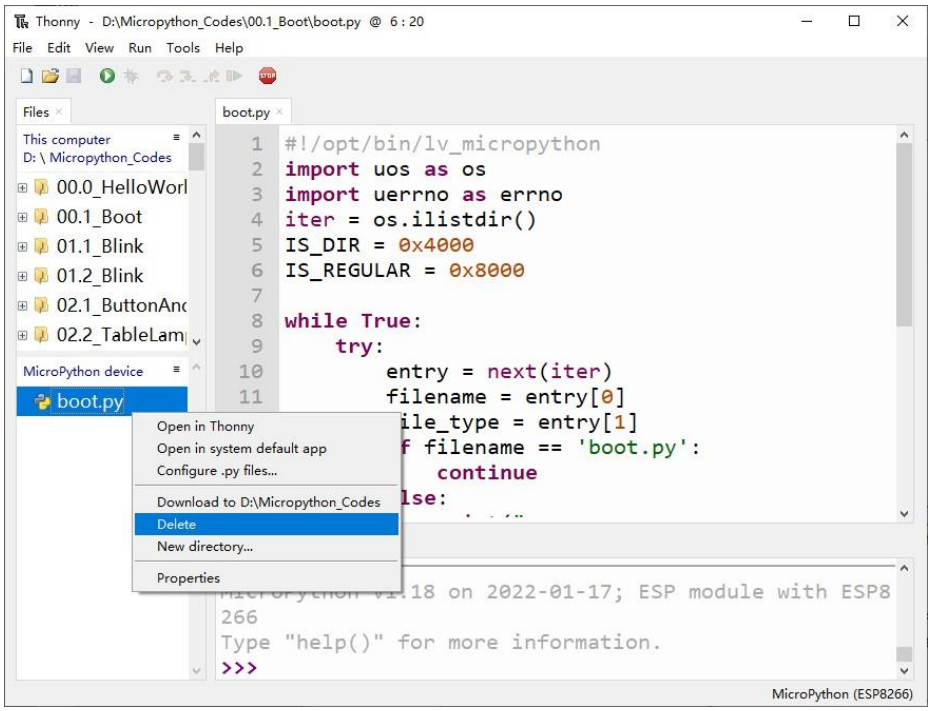
Downloading Code to Computer

Select “boot.py” in “MicroPython device”, right-click to select “Download to ...” to download the code to your computer.



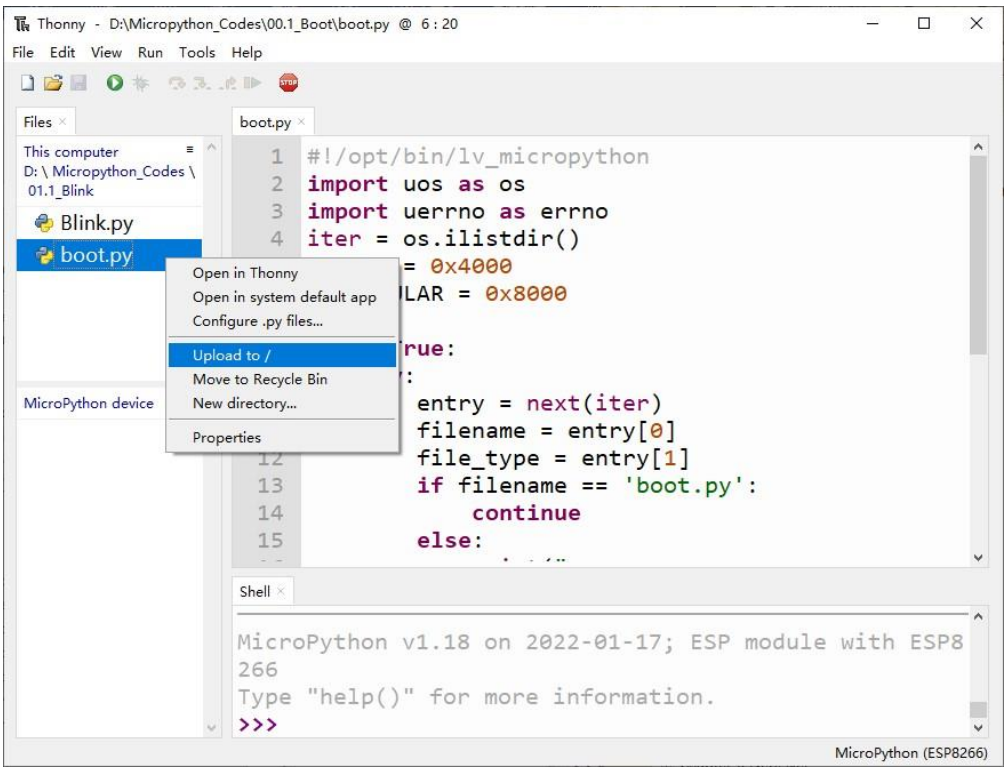
Deleting Files from ESP8266’s Root Directory

Select “boot.py” in “MicroPython device”, right-click it and select “Delete” to delete “boot.py” from ESP8266’s root directory.



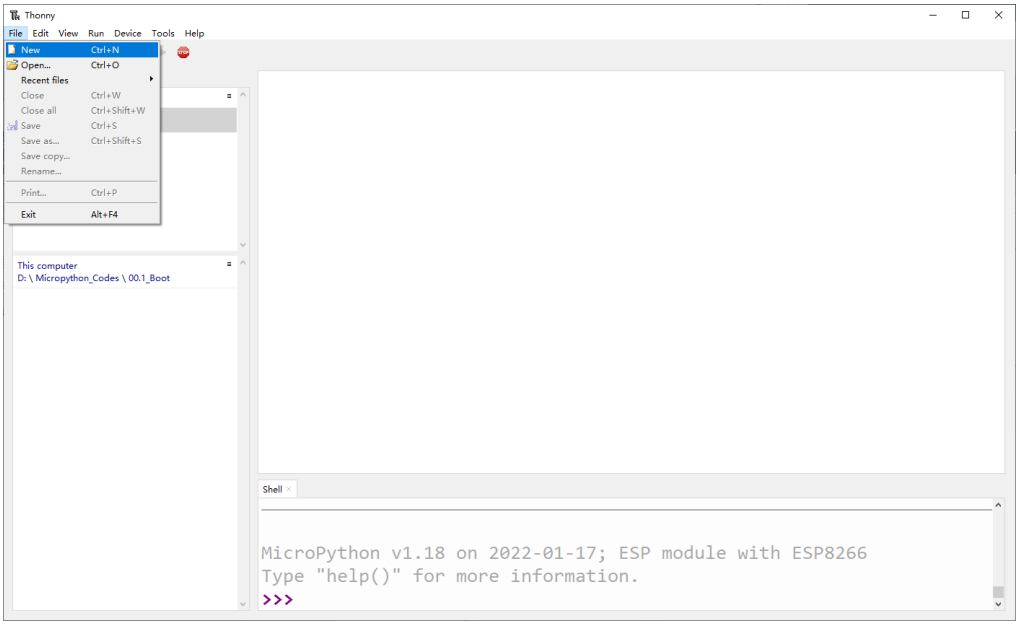
Deleting Files from your Computer Directory

Select "boot.py" in "00.1_Boot", right-click it and select "Move to Recycle Bin" to delete it from "00.1_Boot".

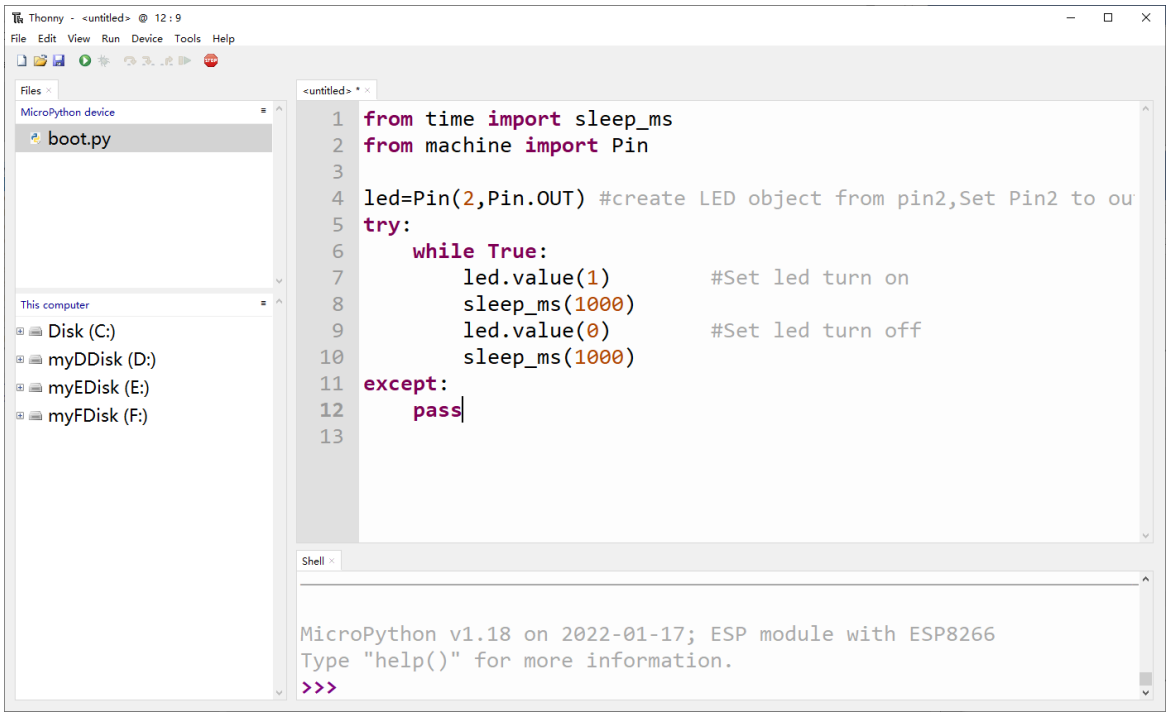


Creating and Saving the code

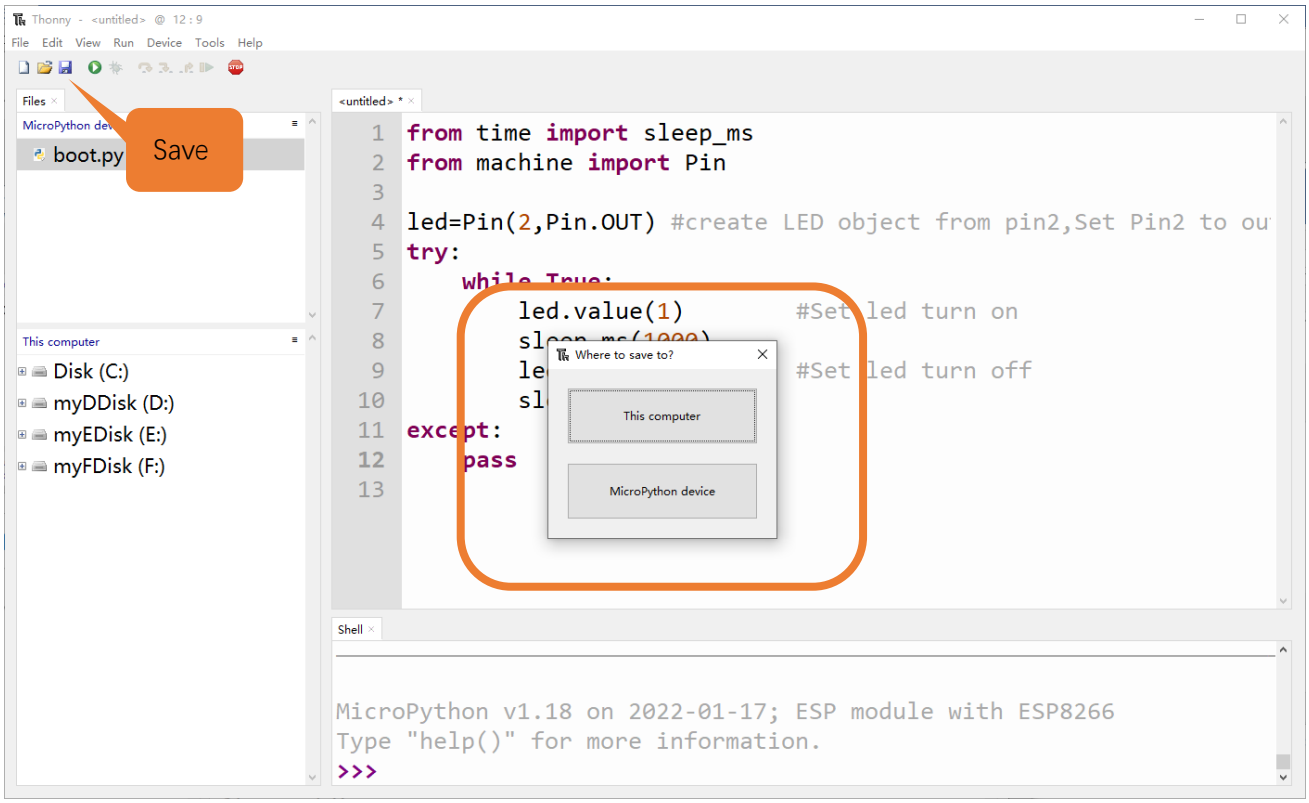
Click "File"→"New" to create and write codes.



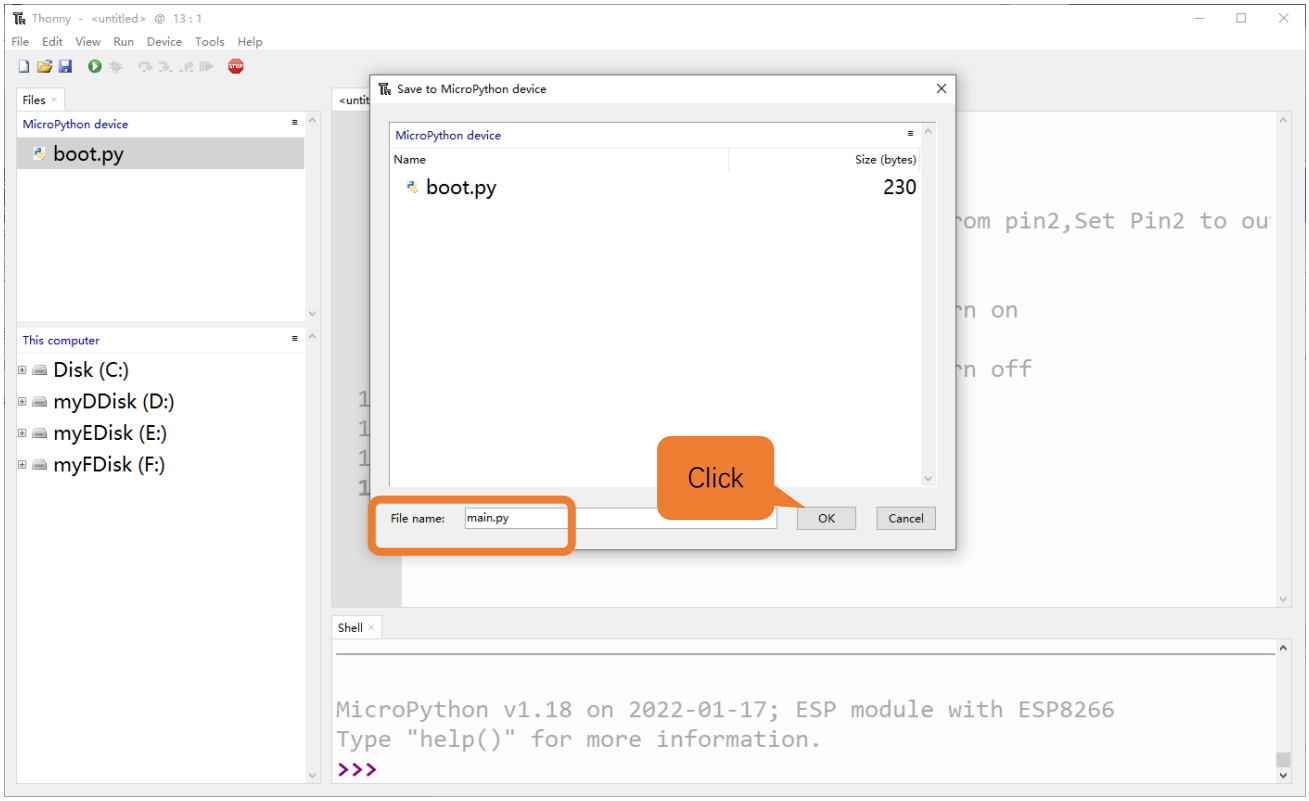
Enter codes in the newly opened file. Here we use codes of "01.1_Blink.py" as an example.



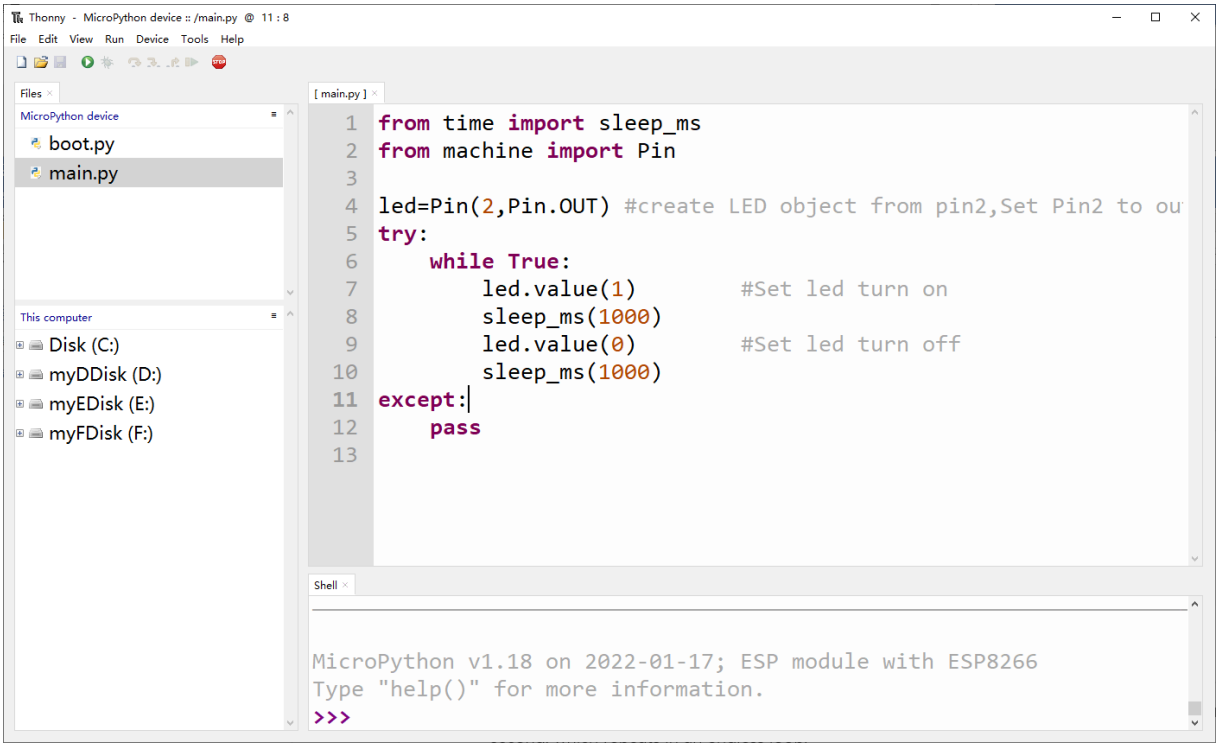
Click "Save" on the menu bar. You can save the codes either to your computer or to ESP8266.

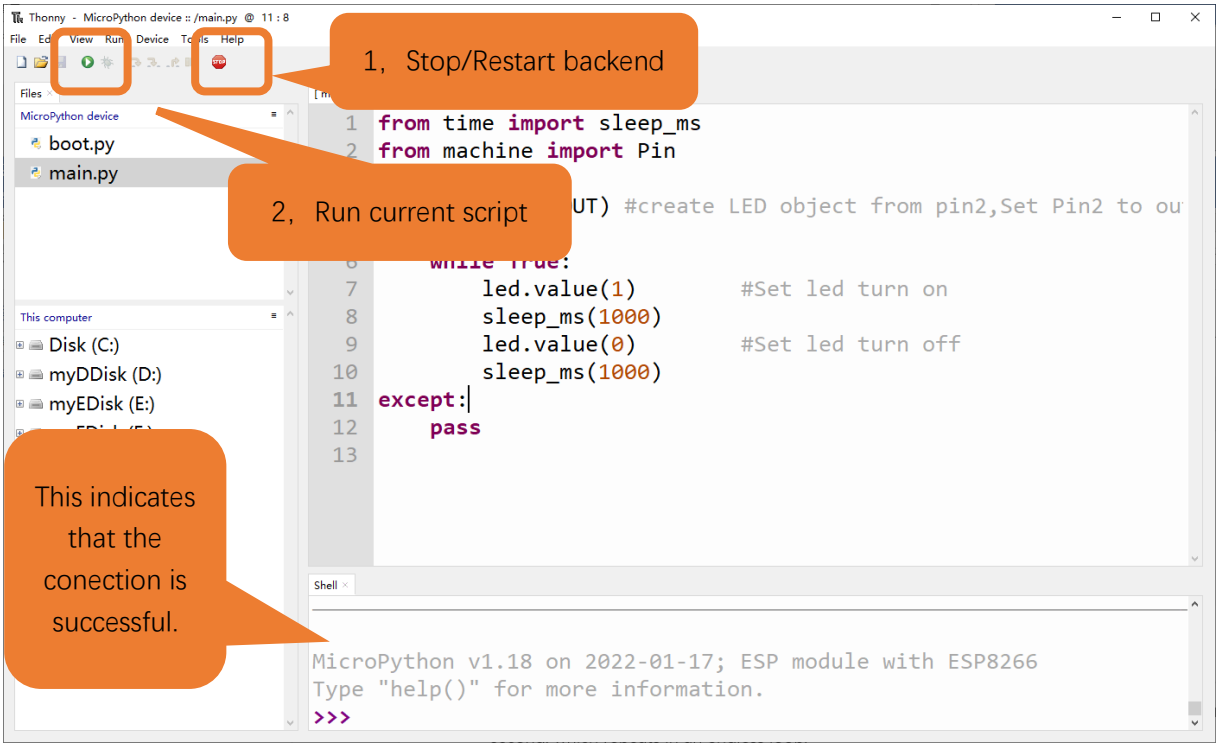


Select "MicroPython device", enter "main.py" in the newly pop-up window and click "OK".

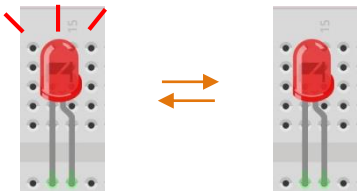


You can see that codes have been uploaded to ESP8266.





Disconnect and reconnect USB cable, and you can see that LED is ON for one second and then OFF for one second, which repeats in an endless loop.



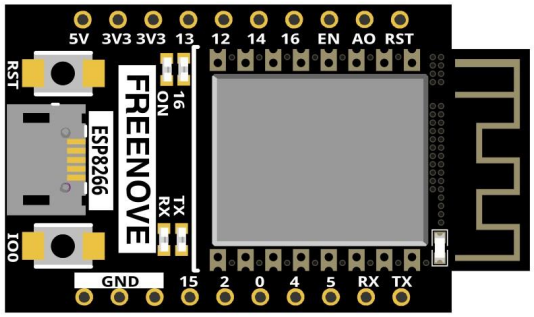
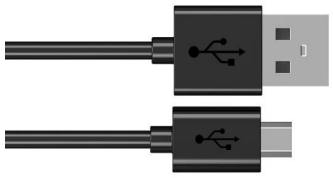
Chapter 1 LED (Important)

This chapter is the Start Point in the journey to build and explore ESP8266 electronic projects. We will start with simple “Blink” project.

Project 1.1 Blink

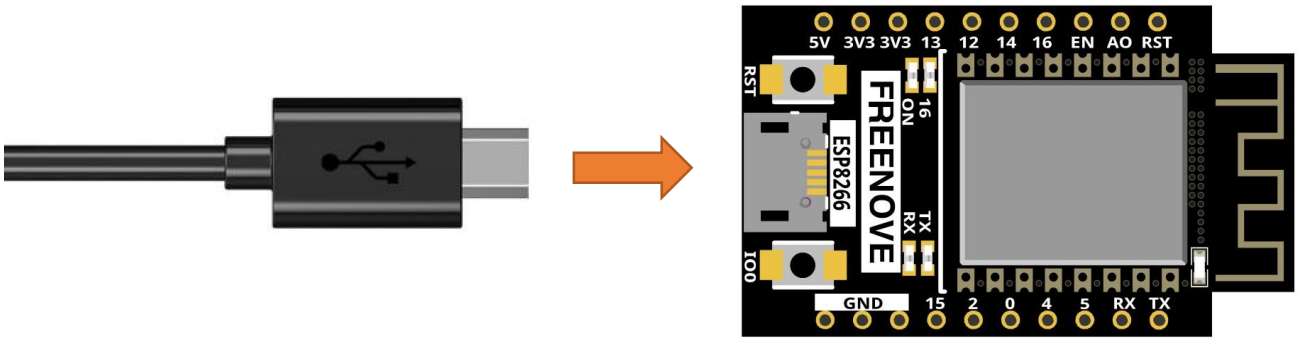
In this project, we will use ESP8266 to control blinking a common LED.
If you have not yet installed Thonny, click here.
If you have not yet downloaded Micropython Firmware, click here.
If you have not yet loaded Micropython Firmware, click here.

Component List

ESP8266 x1 	USB cable 

Power

ESP8266 needs 5v power supply. In this tutorial, we need connect ESP8266 development board to computer via USB cable to power it and program it. We can also use other 5v power source to power it.



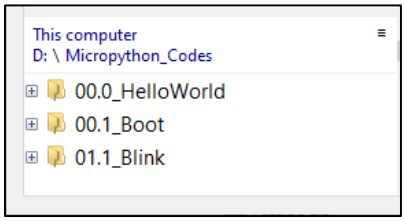
In the following projects, we only use USB cable to power ESP8266 development board by default.

Code

Codes used in this tutorial are saved in "**Freenove_ESP8266_Board/Python/Python_Codes**". You can move the codes to any location. For example, we save the codes in Disk(D) with the path of "**D:/Micropython_Codes**".

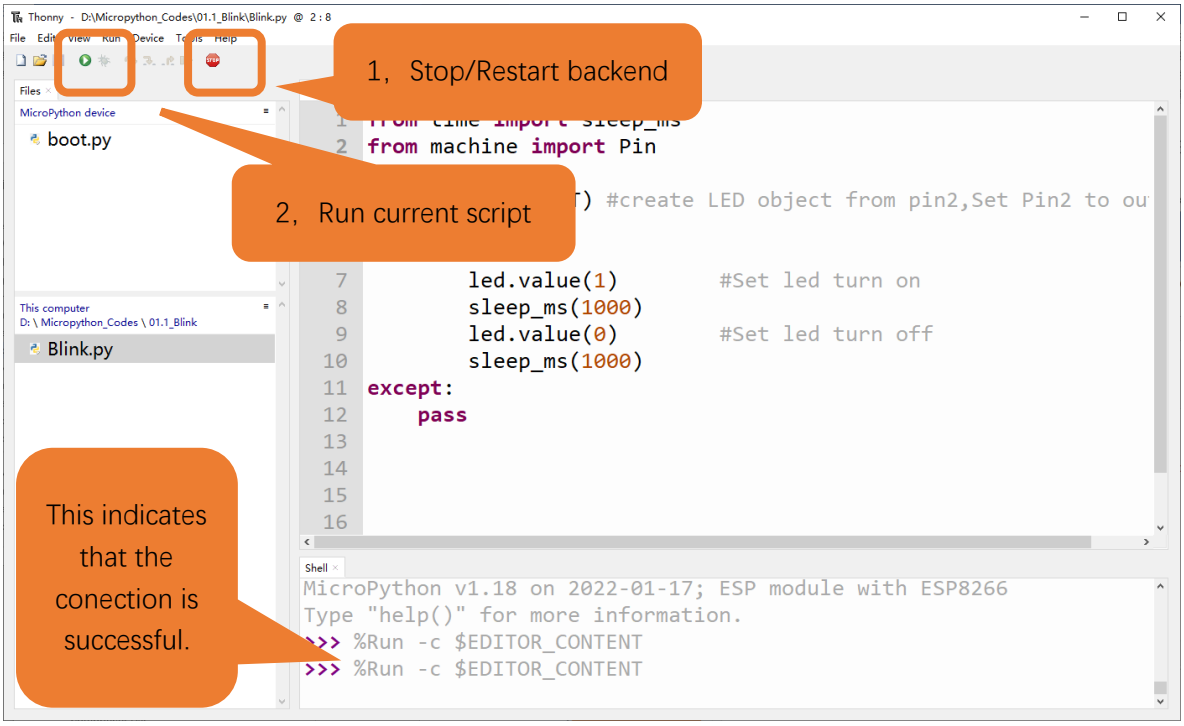
01.1_Blink

Open "Thonny", click "This computer"→"D:"→"Micropython_Codes".

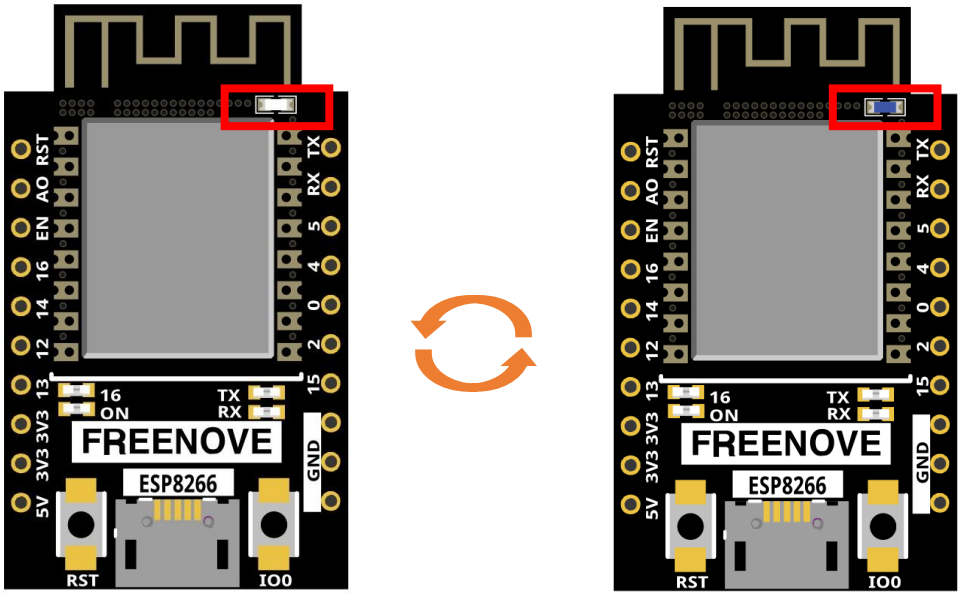


Expand folder "01.1_Blink" and double click "Blink.py" to open it. As shown in the illustration below.

Make sure ESP8266 is properly connected to your computer. Click "Stop/Restart backend" or press the reset button, and then wait to see what interface will show up.

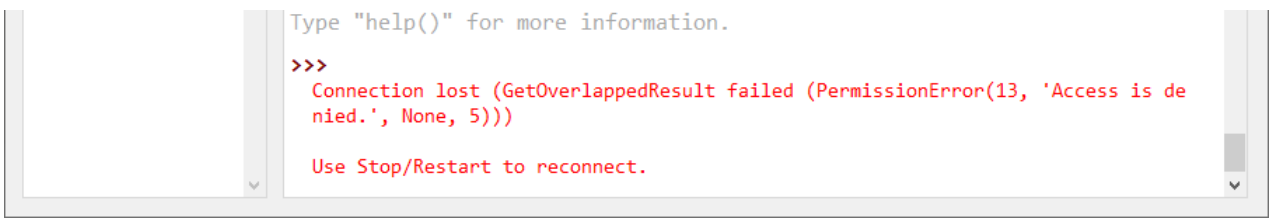


Click "Run current script" shown in the box above, the code starts to be executed and the LED in the circuit starts to blink.



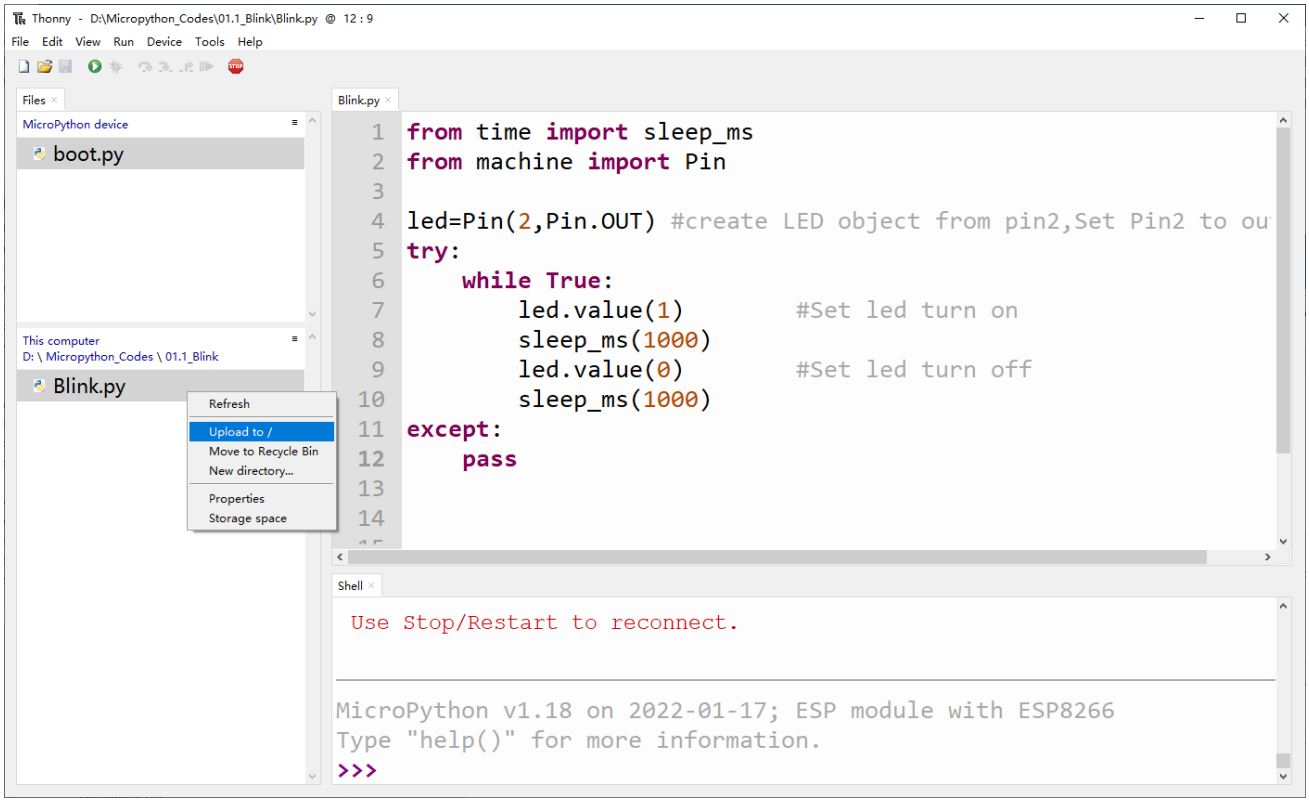
Note:

This is the code running online. If you disconnect USB cable and repower ESP8266 or press its reset key, LED stops blinking and the following messages will be displayed in Thonny.

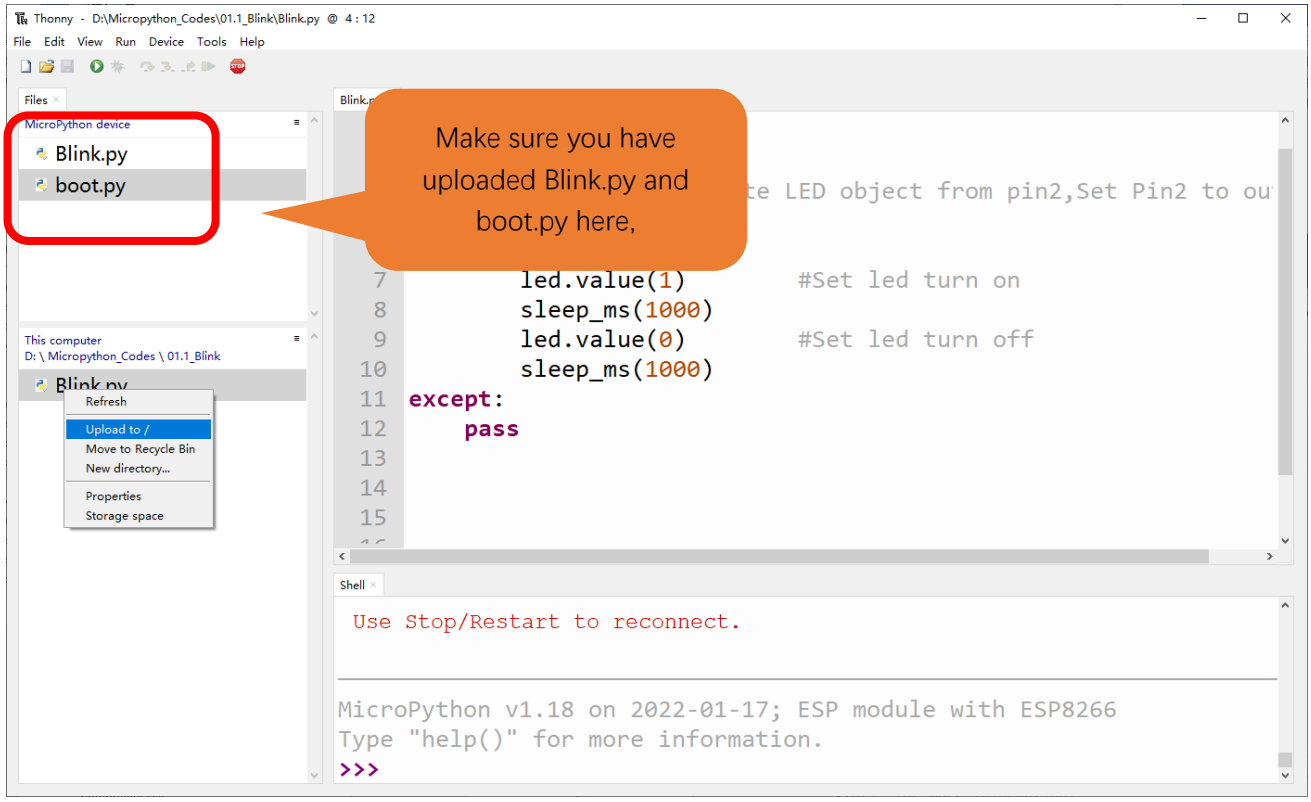


Uploading code to ESP8266

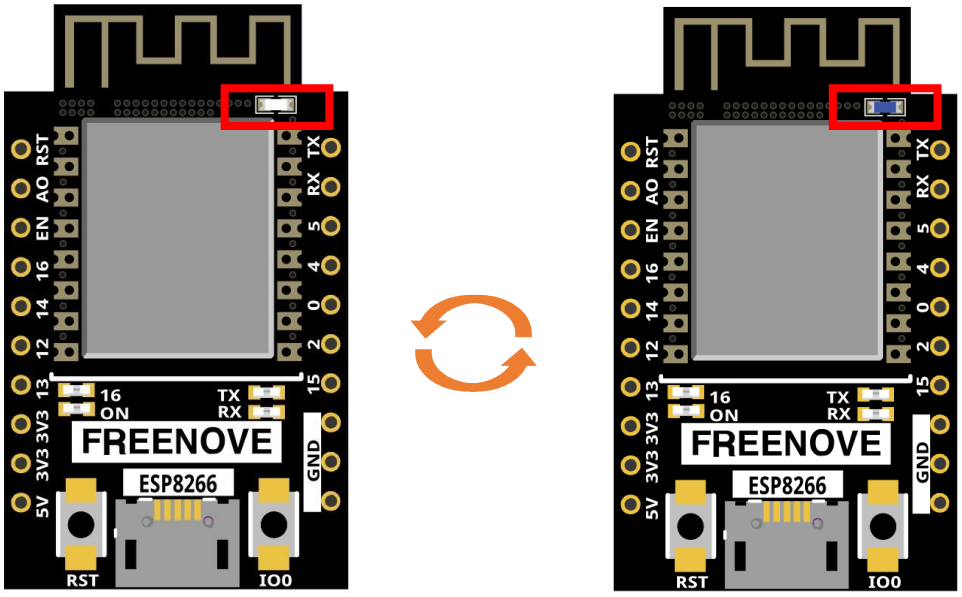
As shown in the following illustration, right-click the file Blink.py and select "Upload to /" to upload code to ESP8266.



Upload boot.py in the same way.

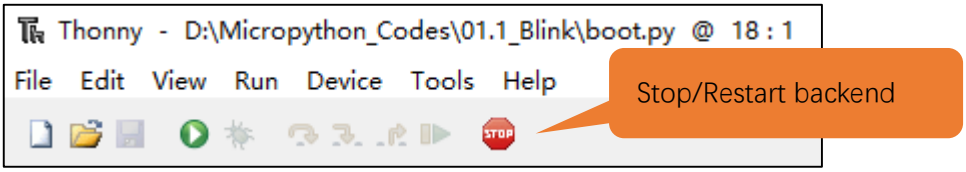


Press the reset key of ESP8266 and you can see LED is ON for one second and then OFF for one second, which repeats in an endless loop.



Note:

Codes here is run offline. If you want to stop running offline and enter Shell, just click "Stop" in Thonny.

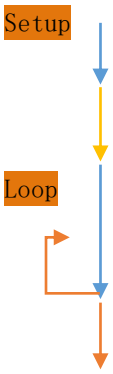


If you have any concerns, please contact us via: support@freenove.com

The following is the program code:

```
1  from time import sleep_ms
2  from machine import Pin
3
4  led=Pin(2,Pin.OUT) #create LED object from pin2,Set Pin2 to output
5  try:
6      while True:
7          led.value(1) #Set led turn on
8          sleep_ms(1000)
9          led.value(0) #Set led turn off
10         sleep_ms(1000)
11 except:
12     pass
```

Each time a new file is opened, the program will be executed from top to bottom. When encountering a loop construction, it will execute the loop statement according to the loop condition.




```
1  from time import sleep_ms
2  from machine import Pin
3
4  led=Pin(2,Pin.OUT) #create LED object from pin2,Set Pin2 to output
5  try:
6      while True:
…          ...
11 except:
12     pass
```

Print() function is used to print data to Terminal. It can be executed in Terminal directly or be written in a Python file and executed by running the file.

```
   print("Hello world!")
```

Each time when using the functions of ESP8266, you need to import modules corresponding to those functions: Import sleep_ms module of time module and Pin module of machine module.

```
1  from time import sleep_ms
2  from machine import Pin
```

Configure GPIO2 of ESP8266 to output mode and assign it to an object named "led".

```
4  led=Pin(2,Pin.OUT) #create LED object from pin2,Set Pin2 to output
```

It means that from now on, LED represents GPIO2 that is in output mode.

Set the value of LED to 1 and GPIO2 will output high level.

```
7  led.value(1) #Set led turn on
```

Set the value of LED to 0 and GPIO2 will output low level.

```
9  led.value(0) #Set led turn on
```

Execute codes in a while loop.

```
6      while True:
…          ...
```

Put statements that may cause an error in “try” block and the executing statements when an error occurs in “except” block. In general, when the program executes statements, it will execute those in “try” block. However, when an error occurs to ESP8266 due to some interference or other reasons, it will execute statements in “except” block.

“Pass” is an empty statement. When it is executed, nothing happens. It is useful as a placeholder to make the structure of a program look better.

```
5    try:
...      ...
11   except:
12       pass
```

The single-line comment of Micropython starts with a “#” and continues to the end of the line. Comments help us to understand code. When programs are running, Thonny will ignore comments.

```
9    #Set led turn on
```

MicroPython uses indentations to distinguish different blocks of code instead of braces. The number of indentations is changeable, but it must be consistent throughout one block. If the indentation of the same code block is inconsistent, it will cause errors when the program runs.

```
6        while True:
7            led.value(1) #Set led turn on
8            sleep_ms(1000)
9            led.value(0) #Set led turn off
10           sleep_ms(1000)
```

How to import python files

Whether to import the built-in python module or to import that written by users, the command “import” is needed.

If you import the module directly you should indicate the module to which the function or attribute belongs when using the function or attribute (constant, variable) in the module. The format should be: <module name>.<function or attribute>, otherwise an error will occur.

```
import random

num = random.randint(1, 100)
print(num)
```

If you only want to import a certain function or attribute in the module, use the from…import statement. The format is as follows.

```

from random import randint
num = randint(1, 100)
print(num)
```

When using “from…import” statement to import function, to avoid conflicts and for easy understanding, you can use “as” statement to rename the imported function, as follows.

```
from random import randint as rand
num = rand(1, 100)
print(num)
```

Reference

Class machine

Before each use of the **machine** module, please add the statement "**import machine**" to the top of python file.

machine.freq(freq_val): When freq_val is not specified, it is to return to the current CPU frequency; Otherwise, it is to set the current CPU frequency.

freq_val: 80000000(80MHz)、160000000(160MHz)、240000000(240MHz)

machine.reset(): A reset function. When it is called, the program will be reset.

machine.unique_id(): Obtains MAC address of the device.

machine.idle(): Turns off any temporarily unused functions on the chip and its clock, which is useful to reduce power consumption at any time during short or long periods.

machine.disable_irq(): Disables interrupt requests and return the previous IRQ state. The disable_irq () function and enable_irq () function need to be used together; Otherwise the machine will crash and restart.

machine.enable_irq(state): To re-enable interrupt requests. The parameter **state** should be the value that was returned from the most recent call to the disable_irq() function

machine.time_pulse_us(pin, pulse_level, timeout_us=1000000):

Tests the duration of the external pulse level on the given pin and returns the duration of the external pulse level in microseconds. When pulse level = 1, it tests the high level duration; When pulse level = 0, it tests the low level duration.

If the setting level is not consistent with the current pulse level, it will wait until they are consistent, and then start timing. If the set level is consistent with the current pulse level, it will start timing immediately.

When the pin level is opposite to the set level, it will wait for timeout and return "-2". When the pin level and the set level is the same, it will also wait timeout but return "-1". **timeout_us** is the duration of timeout.

Class Pin(id[, mode, pull, value])

Before each use of the **Pin** module, please add the statement "**from machine import Pin**" to the top of python file.

id: Arbitrary pin number

mode: Mode of pins

Pin.IN: Input Mode

Pin.OUT: Output Mode

Pin.OPEN_DRAIN: Open-drain Mode

Pull: Whether to enable the internal pull up and down mode

None: No pull up or pull down resistors

Pin.PULL_UP: Pull-up Mode, outputting high level by default

Pin.PULL_DOWN: Pull-down Mode, outputting low level by default

Value: State of the pin level, 0/1

Pin.init(mode, pull): Initialize pins

Pin.value([value]): Obtain or set state of the pin level, return 0 or 1 according to the logic level of pins. Without parameter, it reads input level. With parameter given, it is to set output level.

value: It can be either True/False or 1/0.

Pin.irq(trigger, handler): Configures an interrupt handler to be called when the pin level meets a condition.

trigger:

Pin.IRQ_FALLING: interrupt on falling edge

Pin.IRQ_RISING: interrupt on rising edge

3: interrupt on both edges

Handler: callback function

Class time

Before each use of the **time** module, please add the statement "**import time**" to the top of python file

time.sleep(sec): Sleeps for the given number of seconds

sec: This argument should be either an int or a float.

time.sleep_ms(ms): Sleeps for the given number of milliseconds, ms should be an int.

time.sleep_us(us): Sleeps for the given number of microseconds, us should be an int.

time.time(): Obtains the timestamp of CPU, with second as its unit.

time.ticks_ms(): Returns the incrementing millisecond counter value, which recounts after some values.

time.ticks_us(): Returns microsecond

time.ticks_cpu(): Similar to ticks_ms() and ticks_us(), but it is more accurate(return clock of CPU).

time.ticks_add(ticks, delta): Gets the timestamp after the offset.

ticks: ticks_ms()、ticks_us()、ticks_cpu()

delta: Delta can be an arbitrary integer number or numeric expression

time.ticks_diff(old_t, new_t): Calculates the interval between two timestamps, such as ticks_ms(), ticks_us() or ticks_cpu().

old_t: Starting time

new_t: Ending time

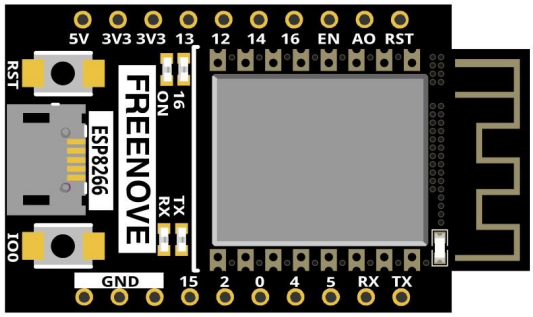
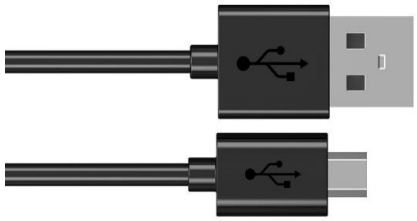
Chapter 2 Serial Communication

Serial Communication is a means of Communication between different devices/devices. This section describes ESP8266's Serial Communication.

Project 2.1 Serial Print

This project uses ESP8266's serial communicator to send data to the computer and print it on the serial monitor.

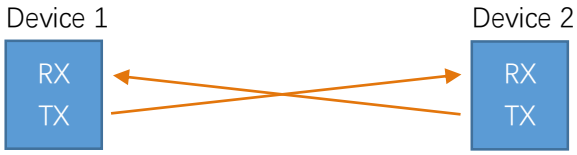
Component List

ESP8266 x1 	USB cable 

Related knowledge

Serial communication

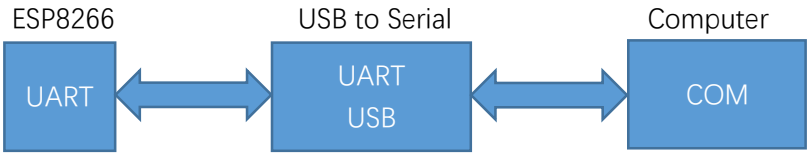
Serial communication generally refers to the Universal Asynchronous Receiver/Transmitter (UART), which is commonly used in electronic circuit communication. It has two communication lines, one is responsible for sending data (TX line) and the other for receiving data (RX line). The serial communication connections two devices use is as follows:



Before serial communication starts, the baud rate of both sides must be the same. Communication between devices can work only if the same baud rate is used. The baud rates commonly used is 9600 and 115200.

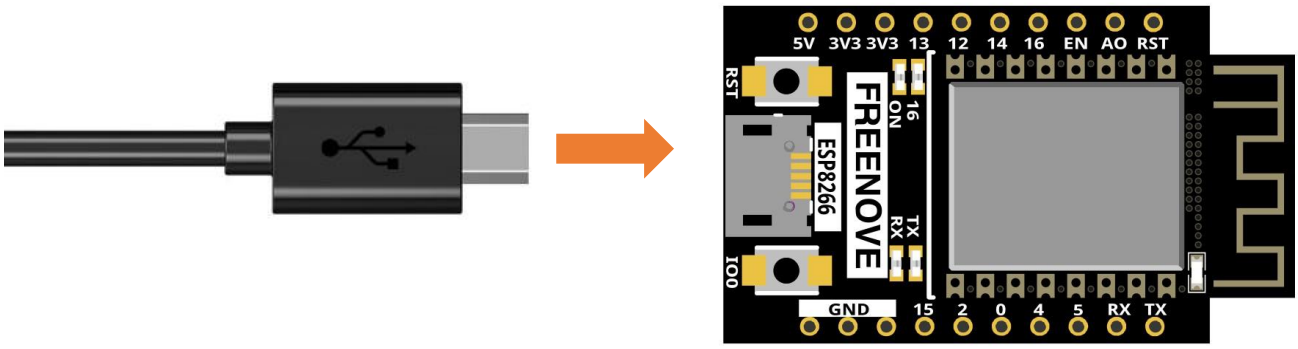
Serial port on ESP8266

Freenove ESP8266 has integrated USB to serial transfer, so it could communicate with computer connecting to USB cable.



Circuit

Connect Freenove ESP8266 to the computer with USB cable.



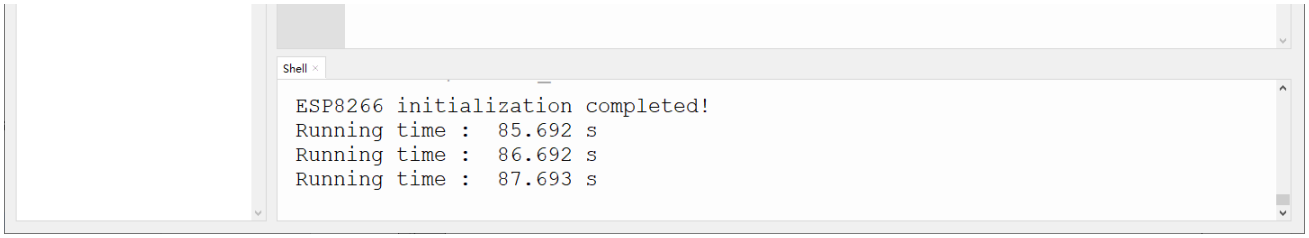
Code

Move the program folder "**Freenove_ESP8266_Board/Python/Python_Codes**" to disk(D) in advance with the path of "**D:/Micropython_Codes**".

Open "Thonny", click "This computer" → "D:" → "Micropython_Codes" → "08.1_Serial_Print" and double "Serial_Print.py".

08.1_Serial_Print

Click "Run current script" and observe the changes of "Shell", which will display the time when ESP8266 is powered on once per second.



The following is the program code:

```
1  import time
2
3  print("ESP8266 initialization completed!")
4
5  while True:
6      print("Running time : ", time.ticks_ms()/1000, "s")
7      time.sleep(1)
```

Reference

Class UART

Before each use of **UART** module, please add the statement "**from machine import UART**" to the top of python file.

UART(id, baudrate, bits, parity, rx, tx, stop, timeout): Define serial ports and configure parameters for them.

id: Serial Number. The available serial port number is 1 or 2

baudrate: Baud rate

bits: The number of each character.

parity: Check even or odd, with 0 for even checking and 1 for odd checking.

rx, tx: UAPT's reading and writing pins

Pin(0)、Pin(2)、Pin(4)、Pin(5)、Pin(9)、Pin(10)、Pin(12~19)、Pin(21~23)、Pin(25)、Pin(26)、Pin(34~36)、Pin(39)

Note: Pin(1) and Pin(3) are occupied and not recommend to be used as tx,rx.

stop: The number of stop bits, and the stop bit is 1 or 2.

timeout: timeout period (Unit: millisecond)

0 < timeout ≤ 0x7FFF FFFF (decimal: 0 < timeout ≤ 2147483647)

UART.init(baudrate, bits, parity, stop, tx, rx, rts, cts)): Initialize serial ports

tx: writing pins of uart

rx: reading pins of uart

rts: rts pins of uart

cts: cts pins of uart

UART.read(nbytes): Read nbytes bytes

UART.read(): Read data

UART.write(buf): Write byte buffer to UART bus

UART.readline(): Read a line of data, ending with a newline character.

UART.readinto(buf): Read and write data into buffer.

UART.readinto(buf, nbytes): Read and write data into buffer.

UART.any(): Determine whether there is data in serial ports. If yes, return the number of bytes; Otherwise, return 0.

Project 2.2 Serial Read and Write

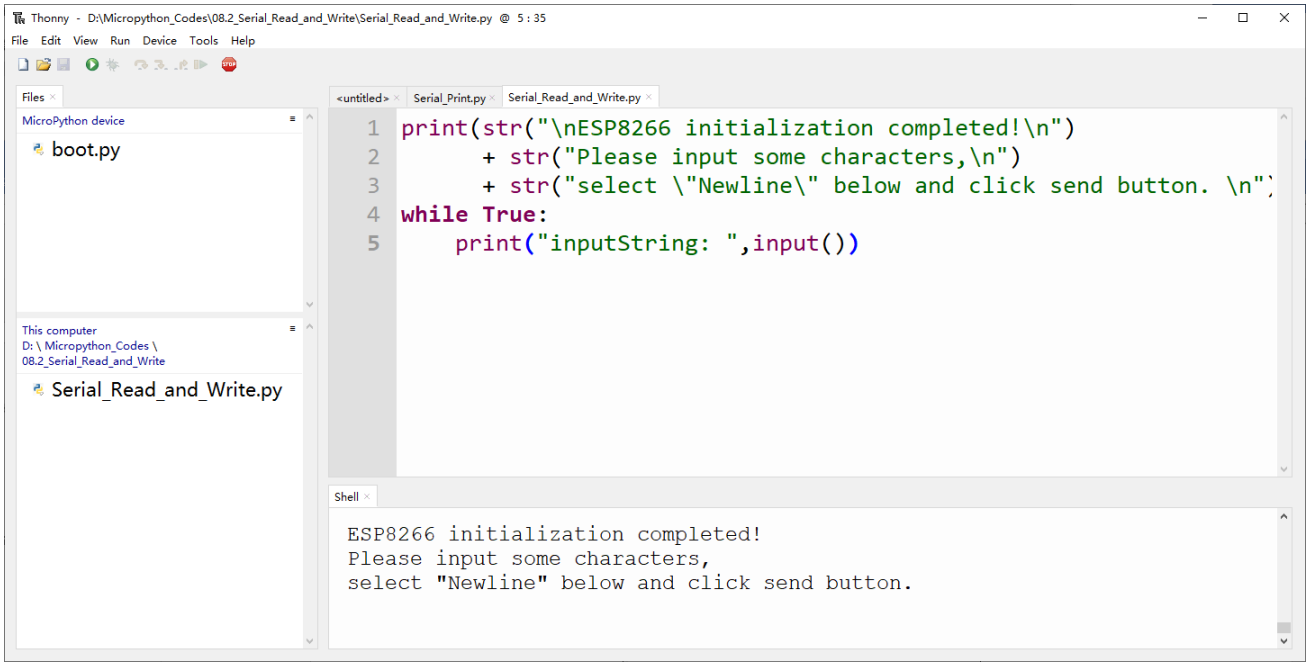
From last section, we use Serial port on Freenove ESP8266 to send data to a computer, now we will use that to receive data from computer.

Component and Circuit are the same as in the previous project.

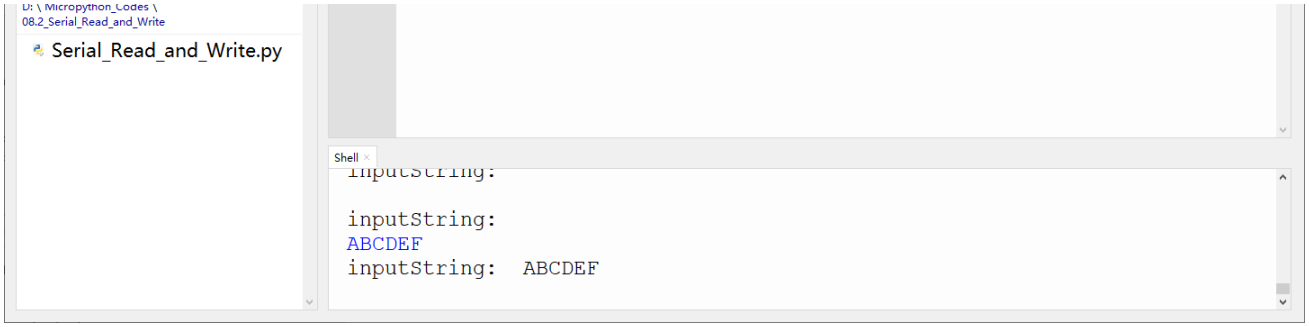
Code

Open "Thonny", click "This computer" → "D:" → "Micropython_Codes" → "08.2_Serial_Read_and_Write" and double click "Serial_Read_and_Write.py".

08.2_Serial_Read_and_Write



Click "Run current script" and ESP8266 will print out data at "Shell" and wait for users to enter any messages. Press Enter to end the input, and "Shell" will print out data that the user entered. If you want to use other serial ports, you can use other python files in the same directory.



The following is the program code:

```
print(str("\nESP8266 initialization completed!\n")
      + str("Please input some characters,\n")
      + str("select \"Newline\" below and click send button. \n"))
while True:
    print("inputString: ",input())
```

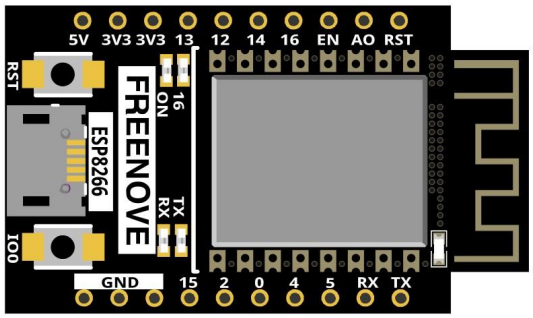
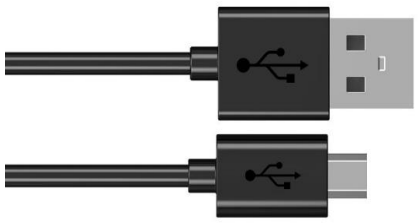
Chapter 3 WiFi Working Modes

In this chapter, we'll focus on the WiFi infrastructure for ESP8266.

ESP8266 has 3 different WiFi operating modes: Station mode, AP mode and AP+Station mode. All WiFi programming projects must be configured with WiFi operating mode before using WiFi, otherwise WiFi cannot be used.

Project 3.1 Station mode

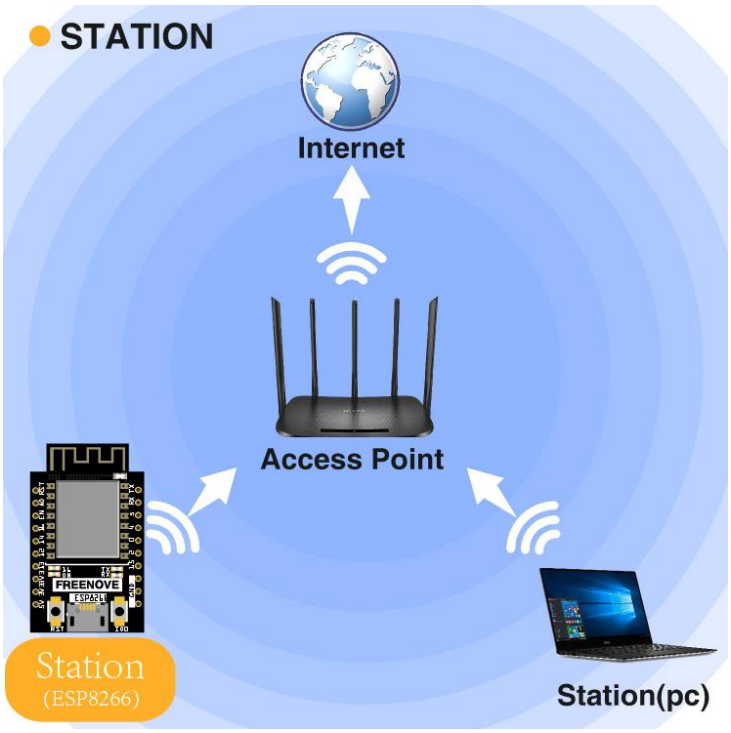
Component List

ESP8266 x1 	USB cable 

Component knowledge

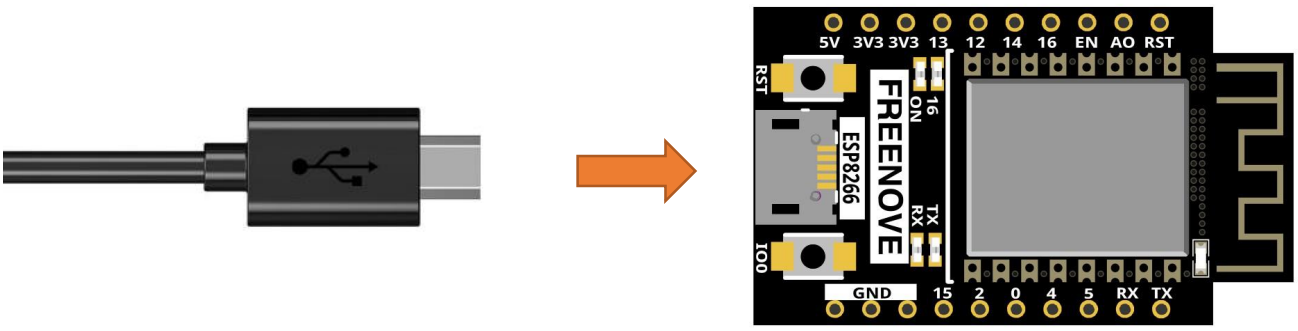
Station mode

When ESP8266 selects Station mode, it acts as a WiFi client. It can connect to the router network and communicate with other devices on the router via WiFi connection. As shown below, the PC is connected to the router, and if ESP8266 wants to communicate with the PC, it needs to be connected to the router.



Circuit

Connect Freenove ESP8266 to the computer using the USB cable.

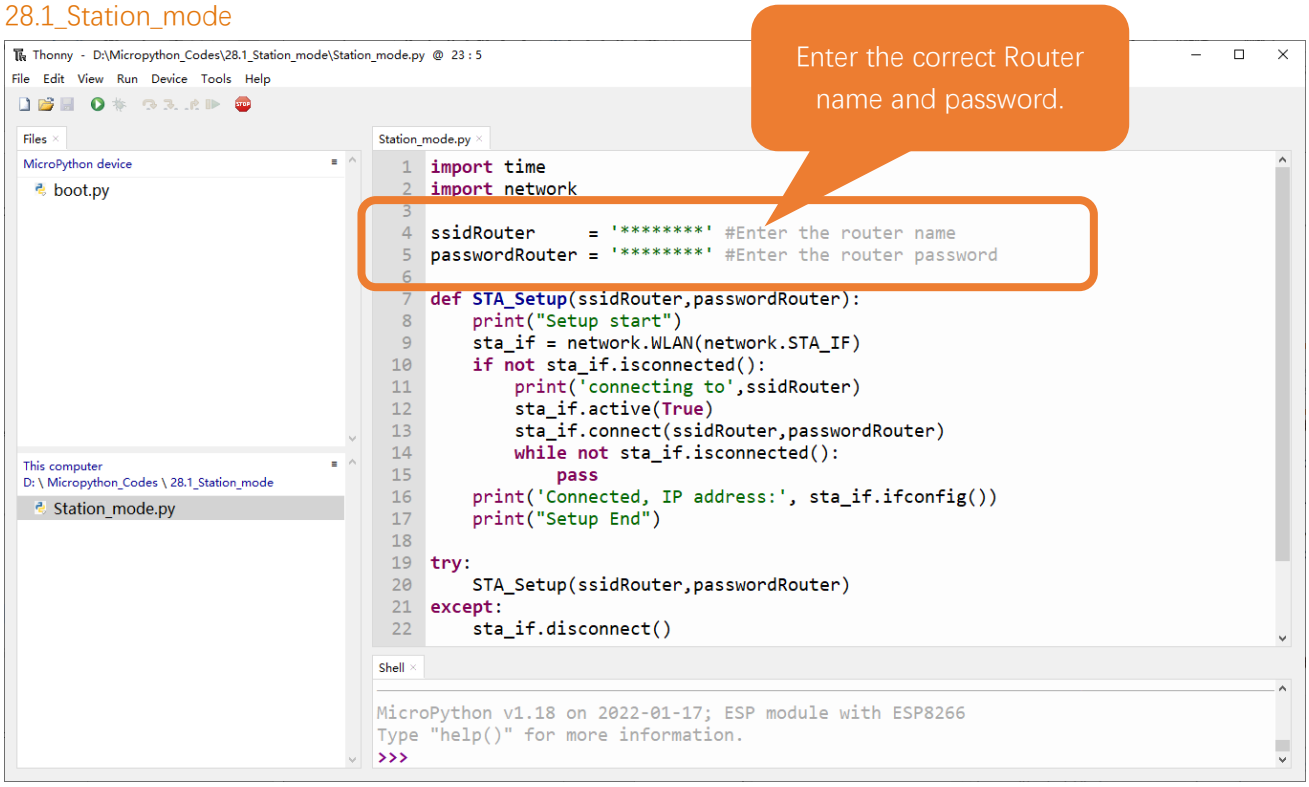


Code

Move the program folder "**Freenove_ESP8266_Board/Python/Python_Codes**" to disk(D) in advance with the path of "**D:/Micropython_Codes**".

Open "Thonny", click "This computer" → "D:" → "Micropython_Codes" → "28.1_Station_mode" and double click "Station_mode.py".

28.1_Station_mode



Because the names and passwords of routers in various places are different, before the Code runs, users need to enter the correct router's name and password in the box as shown in the illustration above.
After making sure the router name and password are entered correctly, compile and upload codes to ESP8266, wait for ESP8266 to connect to your router and print the IP address assigned by the router to ESP8266 in "Shell".

```
Shell
MicroPython v1.18 on 2022-01-17; ESP module with ESP8266
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT
  Setup start
  Connected, IP address: ('192.168.1.113', '255.255.255.0', '192.168.1.1', '8.8.8.8')
  Setup End

>>>
```

The following is the program code:

```
1  import time
2  import network
3
4  ssidRouter     = '********' #Enter the router name
5  passwordRouter = '********' #Enter the router password
6
7  def STA_Setup(ssidRouter,passwordRouter):
8      print("Setup start")
9      sta_if = network.WLAN(network.STA_IF)
10     if not sta_if.isconnected():
11         print('connecting to',ssidRouter)
12         sta_if.active(True)
13         sta_if.connect(ssidRouter,passwordRouter)
14         while not sta_if.isconnected():
15             pass
16     print('Connected, IP address:', sta_if.ifconfig())
17     print("Setup End")
18
19 try:
20     STA_Setup(ssidRouter,passwordRouter)
21 except:
22     sta_if.disconnect()
```

Import network module.

```
2  import network
```

Enter correct router name and password.

```
4  const char *ssid_Router     = "********"; //Enter the router name
5  const char *password_Router = "********"; //Enter the router password
```

Set ESP8266 in Station mode.

```
9    sta_if = network.WLAN(network.STA_IF)
```

Activate ESP8288 Station mode, initiate a connection request to the router and enter the password to connect.

```
12          sta_if.active(True)
13          sta_if.connect(ssidRouter,passwordRouter)
```

Wait for ESP8266 to connect to router until they connect to each other successfully.

```
14          while not sta_if.isconnected():
15              pass
```

Print the IP address assigned to ESP8266 in “Shell”.

```
16    Print('Connected, IP address:', sta_if.ifconfig())
```

Reference

Class network

Before each use of **network**, please add the statement “**import network**” to the top of the python file.

WLAN(interface_id): Set to WiFi mode.

network.STA_IF: Client, connecting to other WiFi access points.

network.AP_IF: Access points, allowing other WiFi clients to connect.

active(is_active): With parameters, it is to check whether to activate the network interface; Without parameters, it is to query the current state of the network interface.

scan(ssid, bssid, channel, RSSI, authmode, hidden): Scan for wireless networks available nearby (only scan on STA interface), return a tuple list of information about the WiFi access point.

bssid: The hardware address of the access point, returned in binary form as a byte object. You can use ubinascii.hexlify() to convert it to ASCII format.

authmode: Access type

AUTH_OPEN = 0

AUTH_WEP = 1

AUTH_WPA_PSK = 2

AUTH_WPA2_PSK = 3

AUTH_WPA_WPA2_PSK = 4

AUTH_MAX = 6

Hidden: Whether to scan for hidden access points

False: Only scanning for visible access points

True: Scanning for all access points including the hidden ones.

isconnected(): Check whether ESP8266 is connected to AP in Station mode. In STA mode, it returns True if it is connected to a WiFi access point and has a valid IP address; Otherwise it returns False.

connect(ssid, password): Connecting to wireless network.

ssid: WiFiname

password: WiFipassword

disconnect(): Disconnect from the currently connected wireless network.

Project 3.2 AP mode

Component List & Circuit

Component List & Circuit are the same as in Section 28.1.

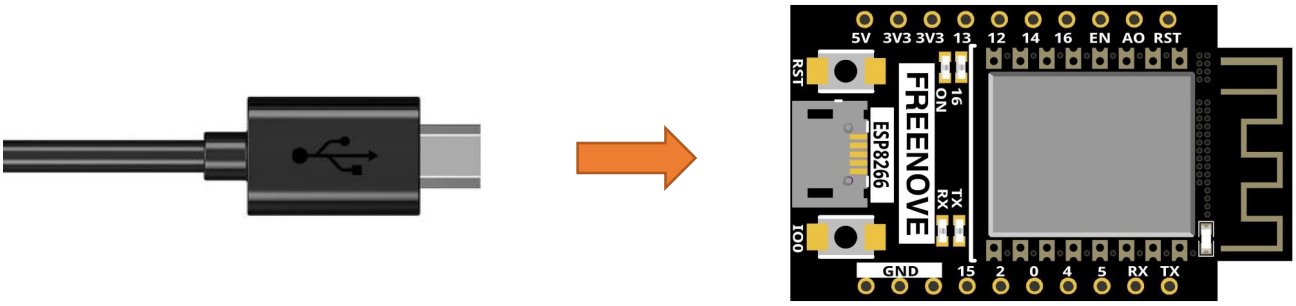
Component knowledge

AP mode

When ESP8266 selects AP mode, it creates a hotspot network that is separated from the Internet and waits for other WiFi devices to connect. As shown in the figure below, ESP8266 is used as a hotspot. If a mobile phone or PC wants to communicate with ESP8266, it must be connected to the hotspot of ESP8266. Only after a connection is established with ESP8266 can they communicate.

Circuit

Connect Freenove ESP8266 to the computer using the USB cable.

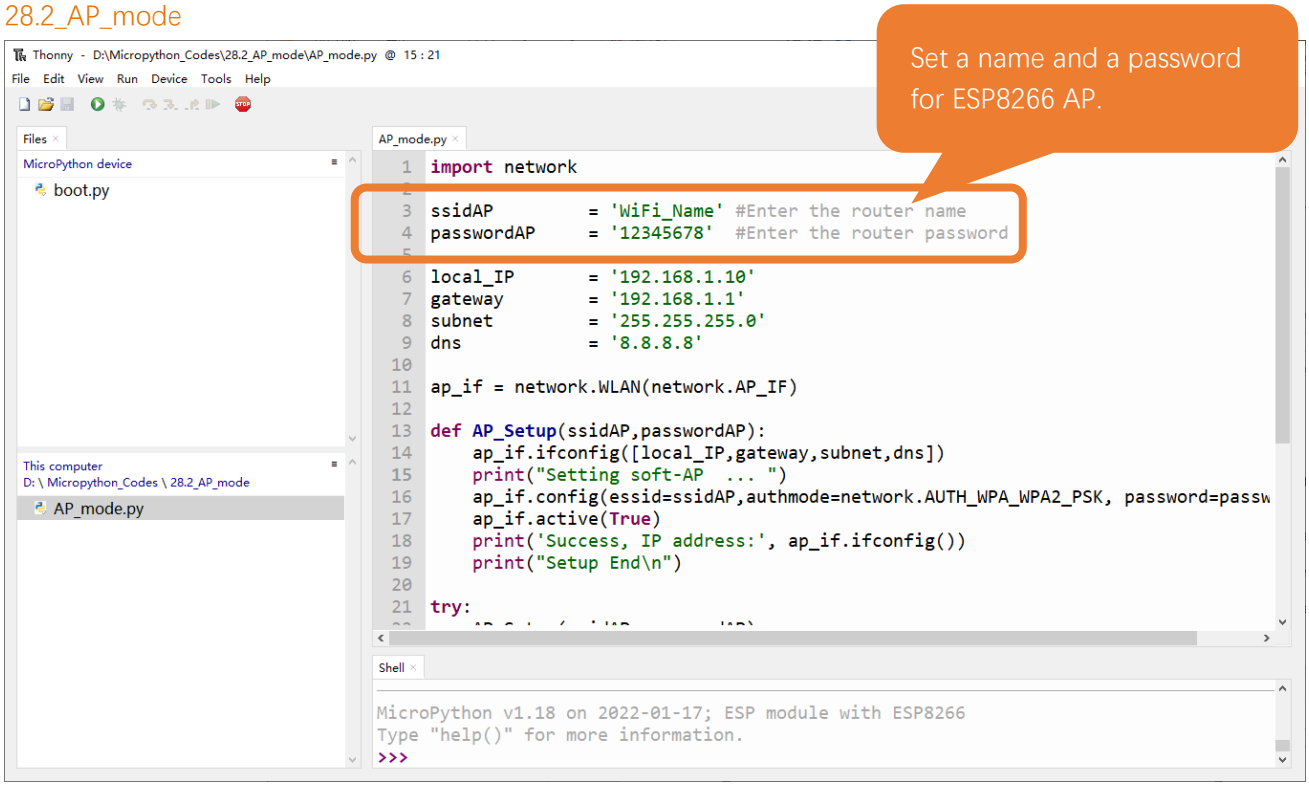


Code

Move the program folder "**Freenove_ESP8266_Board/Python/Python_Codes**" to disk(D) in advance with the path of "**D:/Micropython_Codes**".

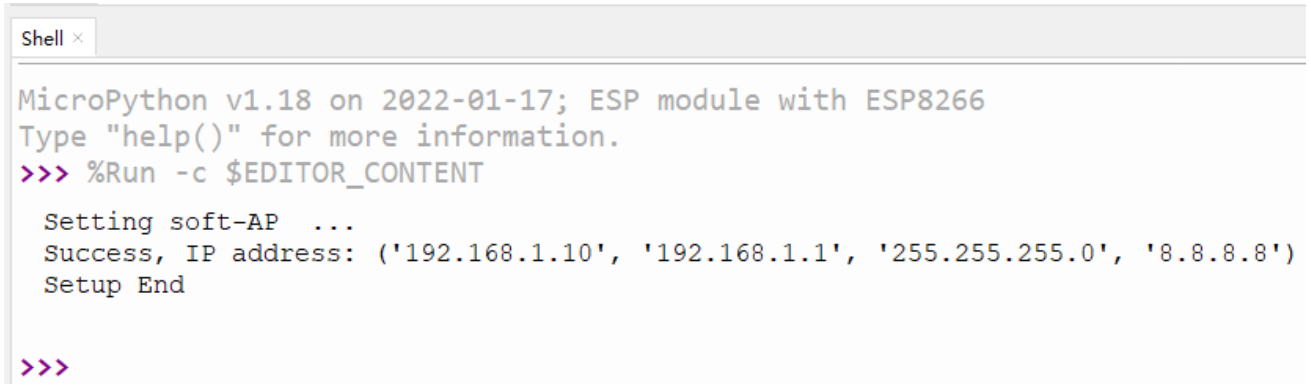
Open "Thonny", click "This computer" → "D:" → "Micropython_Codes" → "28.2_AP_mode". and double click "AP_mode.py".

28.2_AP_mode

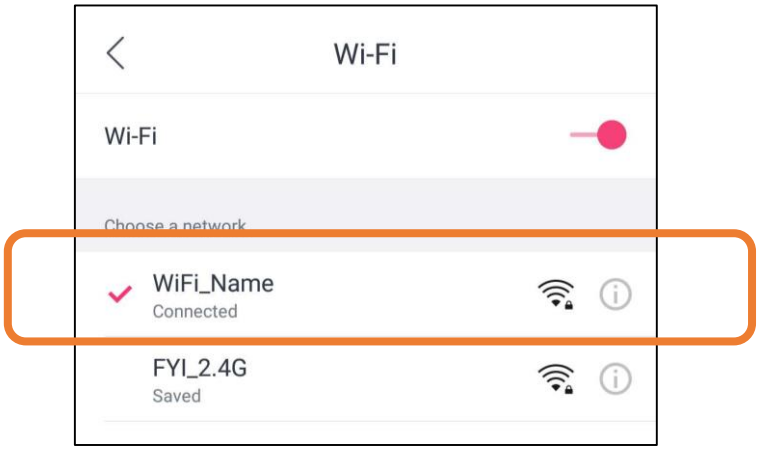


Before the Code runs, you can make any changes to the AP name and password for ESP8266 in the box as shown in the illustration above. Of course, you can leave it alone by default.

Click "Run current script", open the AP function of ESP8266 and print the access point information.



Turn on the WiFi scanning function of your phone, and you can see the ssid_AP on ESP8266, which is called "WiFi_Name" in this Code. You can enter the password "12345678" to connect it or change its AP name and password by modifying Code.



The following is the program code:

```
import network

ssidAP          = 'WiFi_Name' #Enter the router name
passwordAP      = '12345678'  #Enter the router password

local_IP        = '192.168.1.10'
gateway         = '192.168.1.1'
subnet          = '255.255.255.0'
dns             = '8.8.8.8'

ap_if = network.WLAN(network.AP_IF)

def AP_Setup(ssidAP, passwordAP):
    ap_if.ifconfig([local_IP,gateway,subnet,dns])
    print("Setting soft-AP  ... ")
    ap_if.config(essid=ssidAP,authmode=network.AUTH_WPA_WPA2_PSK, password=passwordAP)
    ap_if.active(True)
    print('Success, IP address:', ap_if.ifconfig())
    print("Setup End\n")

try:
    AP_Setup(ssidAP,passwordAP)
except:
    ap_if.disconnect()
```

Import network module.

```
import network
```

Enter correct AP name and password.

```
3  ssidAP        = 'WiFi_Name' #Enter the router name
4  passwordAP    = '12345678'  #Enter the router password
```

Set ESP8266 in AP mode.

```
11 ap_if = network.WLAN(network.AP_IF)
```

Configure IP address, gateway and subnet mask for ESP8266.

```
14 ap_if.ifconfig([local_IP,gateway,subnet,dns])
```

Turn on an AP in ESP8266, whose name is set by ssid_AP and password is set by password_AP.

```
16     ap_if.config(essid=ssidAP,authmode=network.AUTH_WPA_WPA2_PSK, password=passwordAP)
17     ap_if.active(True)
```

If the program is running abnormally, the AP disconnection function will be called.

```
14     ap_if.disconnect()
```

Reference

Class network

Before each use of **network**, please add the statement "**import network**" to the top of the python file.

WLAN(interface_id): Set to WiFi mode.

network.STA_IF: Client, connecting to other WiFi access points

network.AP_IF: Access points, allowing other WiFi clients to connect

active(is_active): With parameters, it is to check whether to activate the network interface; Without parameters, it is to query the current state of the network interface

isconnected(): In AP mode, it returns True if it is connected to the station; otherwise it returns False.

connect(ssid, password): Connecting to wireless network

ssid: WiFiname

password: WiFipassword

config(essid, channel): To obtain the MAC address of the access point or to set the WiFi channel and the name of the WiFi access point.

ssid: WiFi account name

channel: WiFichannel

ifconfig([(ip, subnet, gateway, dns)]): Without parameters, it returns a 4-tuple (ip, subnet_mask, gateway, DNS_server); With parameters, it configures static IP.

ip: IPaddress

subnet_mask: subnet mask

gateway: gateway

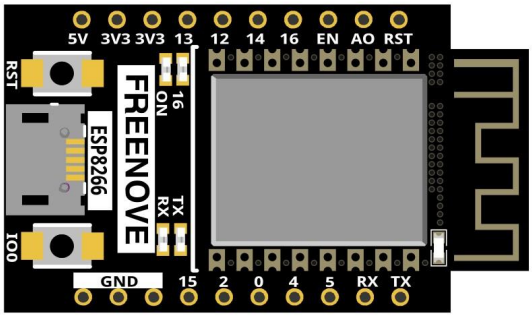
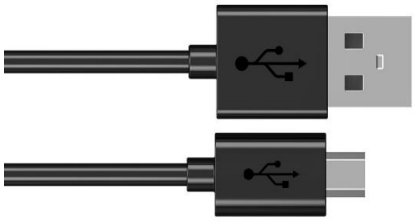
DNS_server: DNSserver

disconnect(): Disconnect from the currently connected wireless network

status(): Return the current status of the wireless connection

Project 3.3 AP+Station mode

Component List

ESP8266 x1	Micro USB Wire x1
	

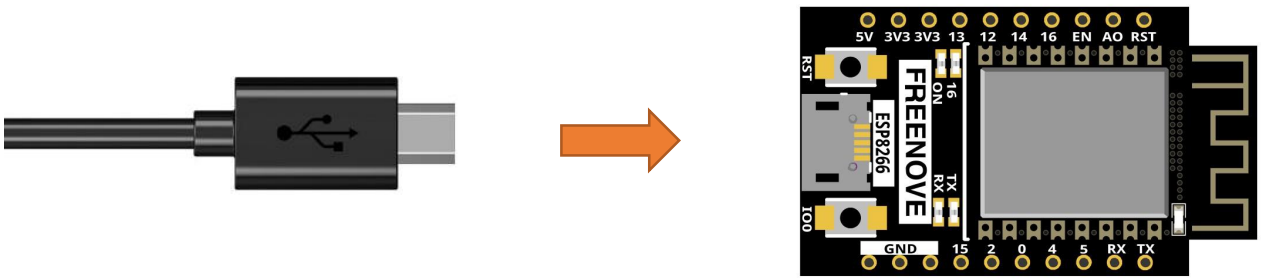
Component knowledge

AP+Station mode

In addition to AP mode and Station mode, ESP8266 can also use AP mode and Station mode at the same time. This mode contains the functions of the previous two modes. Turn on ESP8266's Station mode, connect it to the router network, and it can communicate with the Internet via the router. At the same time, turn on its AP mode to create a hotspot network. Other WiFi devices can choose to connect to the router network or the hotspot network to communicate with ESP8266.

Circuit

Connect Freenove ESP8266 to the computer using the USB cable.

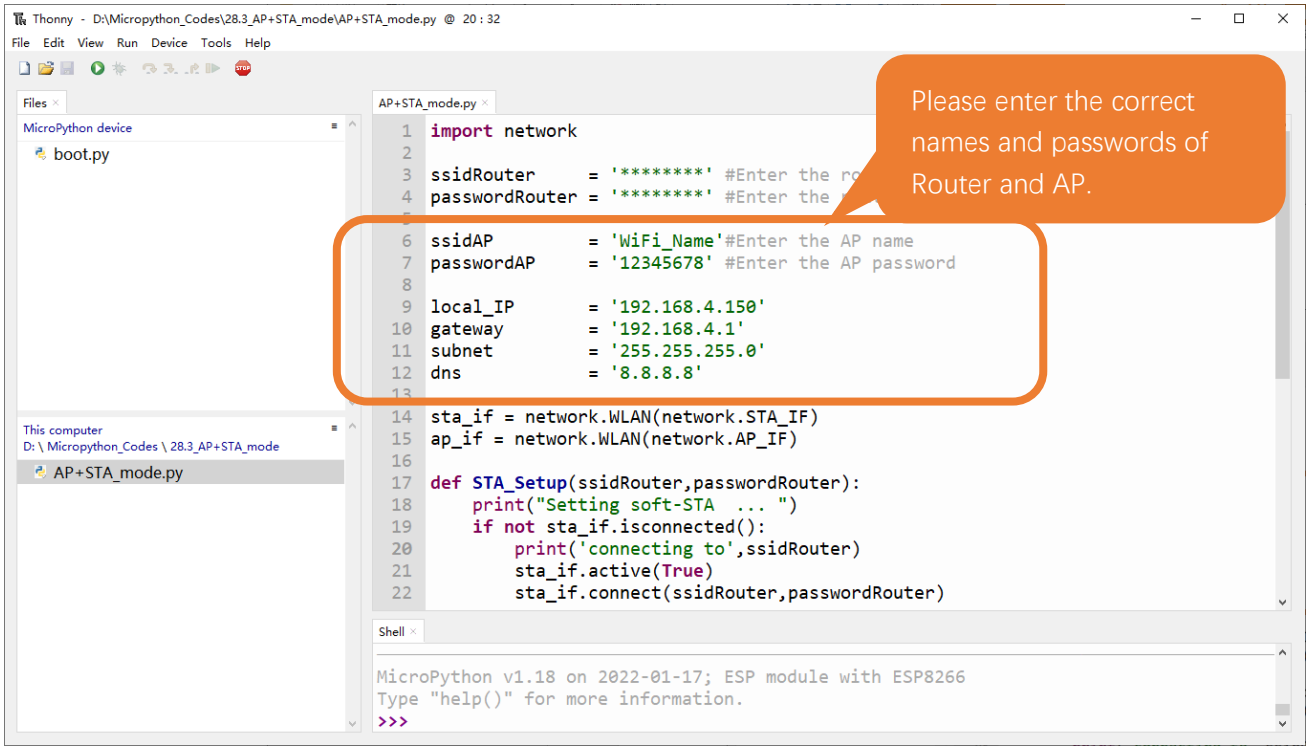


Code

Move the program folder "**Freenove_ESP8266_Board/Python/Python_Codes**" to disk(D) in advance with the path of "**D:/Micropython_Codes**".

Open "Thonny", click "This computer" → "D:" → "Micropython_Codes" → "28.3_AP+STA_mode"and double click "AP+STA_mode.py".

28.3_AP+STA_mode



It is analogous to Project 3.1 and Project 3.2. Before running the Code, you need to modify ssidRouter, passwordRouter, ssidAP and passwordAP shown in the box of the illustration above.

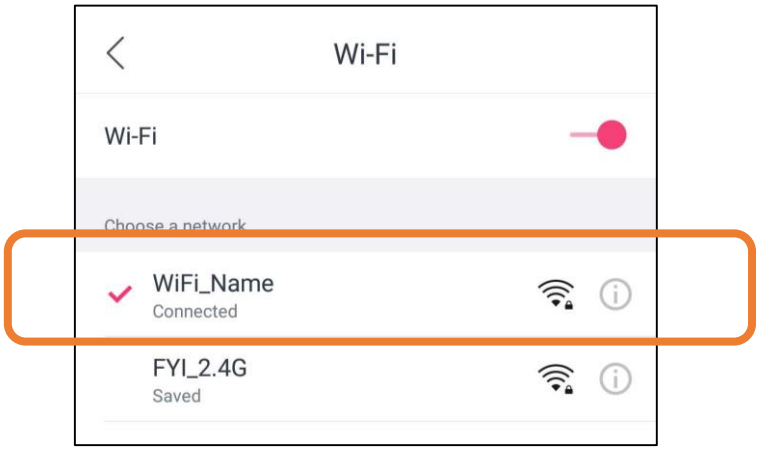
After making sure that the code is modified correctly, click "Run current script" and the "Shell" will display as follows:

```
Shell
MicroPython v1.18 on 2022-01-17; ESP module with ESP8266
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT
  Setting soft-AP  ...
  Success, IP address: ('192.168.4.150', '192.168.4.1', '255.255.255.0', '8.8.8.8')
  Setup End

  Setting soft-STA  ...
  Connected, IP address: ('192.168.1.113', '255.255.255.0', '192.168.1.1', '8.8.8.8')
  Setup End

>>>
```

Turn on the WiFi scanning function of your phone, and you can see the ssidAP on ESP8266.



The following is the program code:

```
import network

ssidRouter     = '********' #Enter the router name
passwordRouter = '********' #Enter the router password

ssidAP         = 'WiFi_Name'#Enter the AP name
passwordAP     = '12345678' #Enter the AP password

local_IP       = '192.168.4.150'
gateway        = '192.168.4.1'
subnet         = '255.255.255.0'
dns            = '8.8.8.8'

sta_if = network.WLAN(network.STA_IF)
ap_if = network.WLAN(network.AP_IF)

def STA_Setup(ssidRouter,passwordRouter):
    print("Setting soft-STA  ... ")
    if not sta_if.isconnected():
        print('connecting to',ssidRouter)
        sta_if.active(True)
        sta_if.connect(ssidRouter,passwordRouter)
        while not sta_if.isconnected():
            pass
    print('Connected, IP address:', sta_if.ifconfig())
    print("Setup End")

def AP_Setup(ssidAP,passwordAP):
    ap_if.ifconfig([local_IP,gateway,subnet,dns])
    print("Setting soft-AP  ... ")
```

```
31      ap_if.config(essid=ssidAP,authmode=network.AUTH_WPA_WPA2_PSK, password=passwordAP)
32      ap_if.active(True)
33      print('Success, IP address:', ap_if.ifconfig())
34      print("Setup End\n")
35
36  try:
37      AP_Setup(ssidAP,passwordAP)
38      STA_Setup(ssidRouter,passwordRouter)
39  except:
40      sta_if.disconnect()
41      ap_if.idsconnect()
```

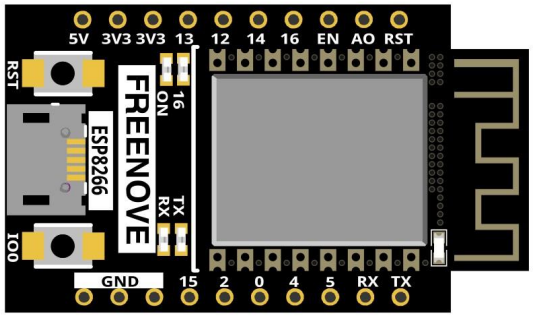
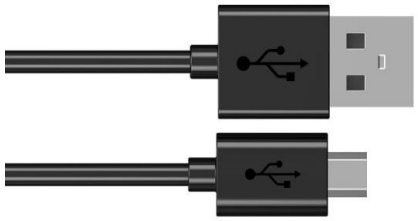
Chapter 4 TCP/IP

In this chapter, we wil introduce how ESP8266 implements network communications based on TCP/IP protocol. There are two roles in TCP/IP communication, namely Server and Client, which will be implemented respectively with two projects in this chaper.

Project 4.1 As Client

In this section, ESP8266 is used as Client to connect Server on the same LAN and communicate with it.

Component List

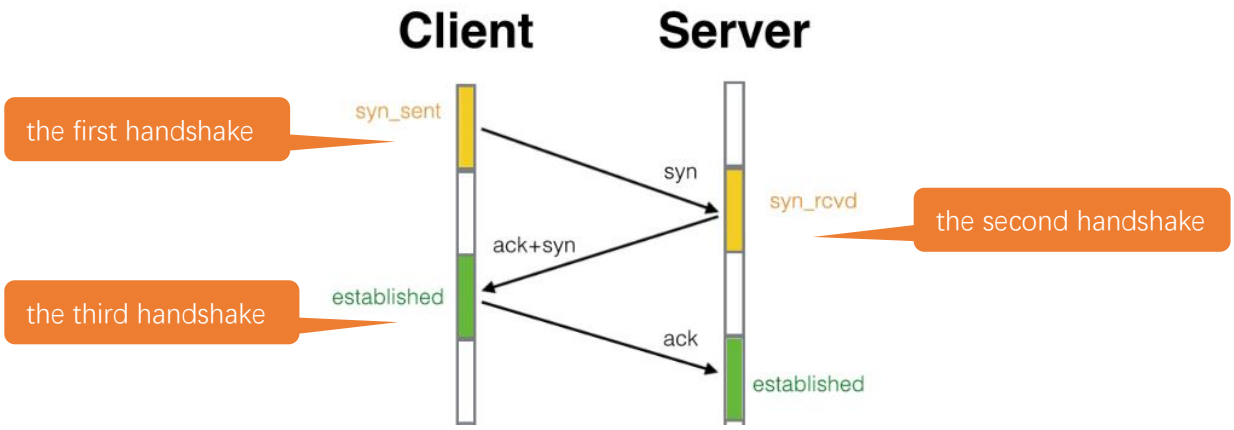
ESP8266 x1 	USB cable 

Component knowledge

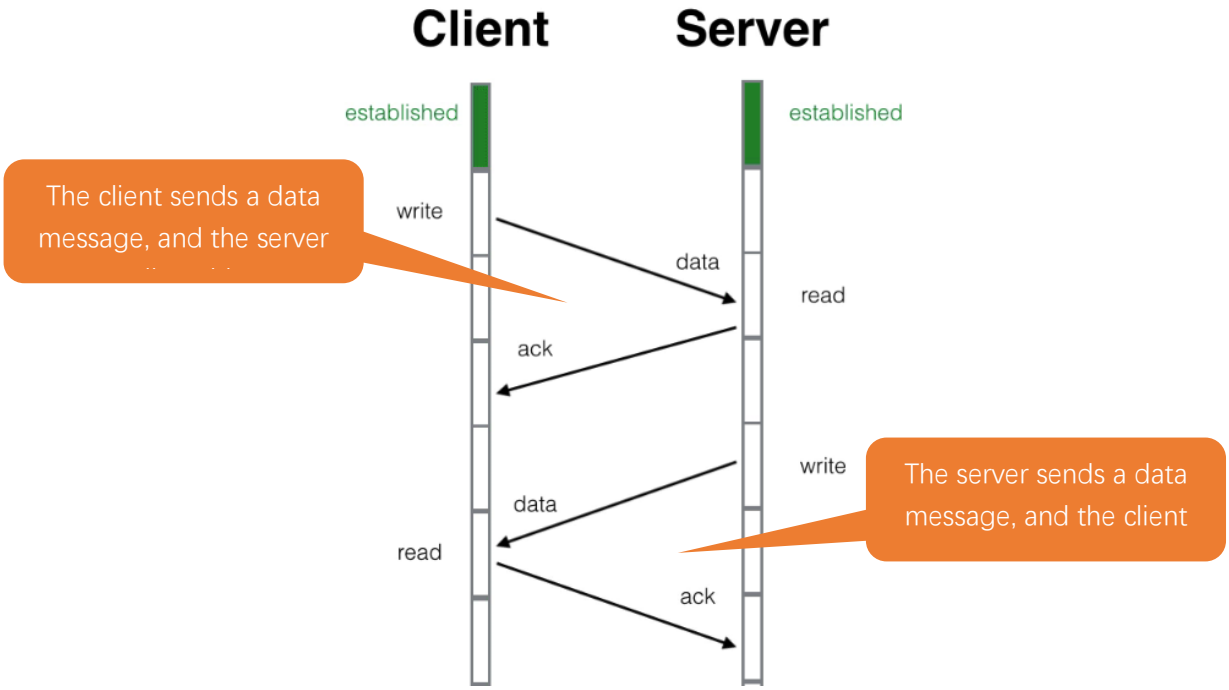
TCP connection

Before transmitting data, TCP needs to establish a logical connection between the sending end and the receiving end. It provides reliable and error-free data transmission between the two computers. In the TCP connection, the client and the server must be clarified. The client sends a connection request to the server, and each time such a request is proposed, a "three-times handshake" is required.

Three-times handshake: In the TCP protocol, during the preparation phase of sending data, the client and the server interact three times to ensure the reliability of the connection, which is called "three-times handshake".
The first handshake, the client sends a connection request to the server and waits for the server to confirm.
The second handshake, the server sends a response back to the client informing that it has received the connection request.
The third handshake, the client sends a confirmation message to the server again to confirm the connection.



TCP is a connection-oriented, low-level transmission control protocol. After TCP establishes a connection, the client and server can send and receive messages to each other, and the connection will always exist as long as the client or server does not initiate disconnection. Each time one party sends a message, the other party will reply with an ack signal.



Install Processing

In this tutorial, we use Processing to build a simple TCP/IP communication platform.

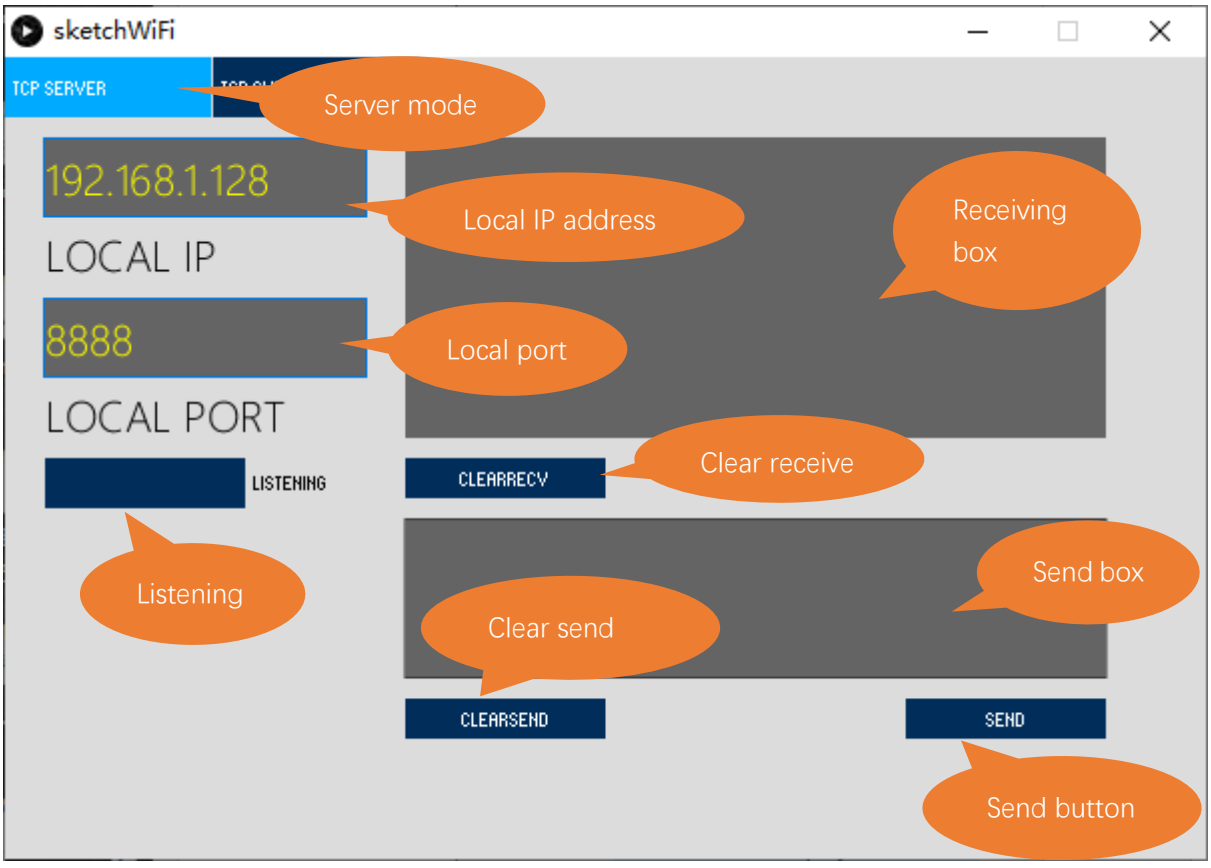
If you've not installed Processing, you can download it by clicking https://processing.org/download/. You can choose an appropriate version to download according to your PC system.

Unzip the downloaded file to your computer. Click "processing.exe" as the figure below to run this software.

Use Server mode for communication

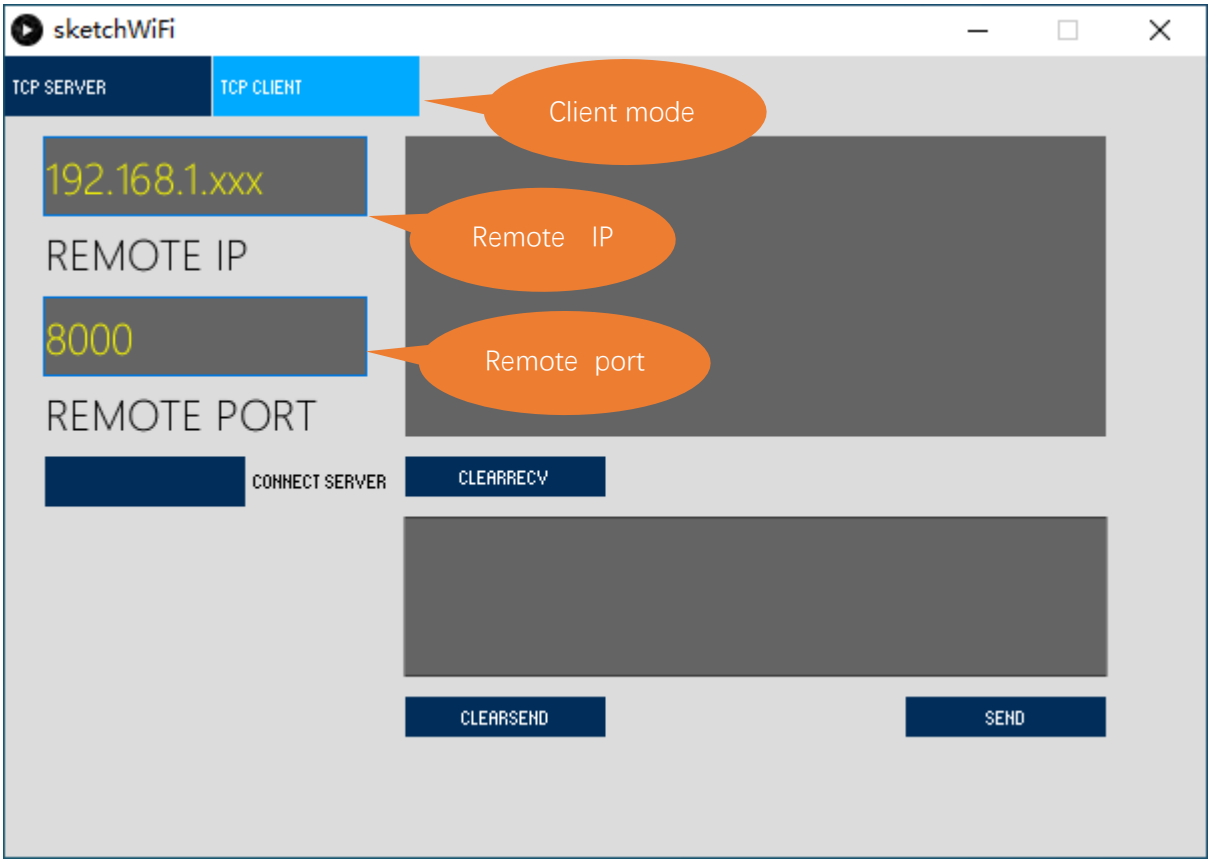
Open the "**Freenove_ESP8266_Board/Codes/Micropython_Codes/29.1_TCP_as_Client/sketchWiFi/sketchWiFi.pde**". Click "Run".

The new pop-up interface is as follows. If ESP8266 is used as Client, select TCP SERVER mode for sketchWiFi.



When sketchWiFi selects TCP SERVER mode, ESP8266 Code needs to be changed according to sketchWiFi's displaying of LOCAL IP or LOCAL PORT.

If ESP8266 serves as Server, select TCP CLIENT mode for sketchWiFi.



When sketchWiFi selects TCP CLIENT mode, the LOCAL IP and LOCAL PORT of sketchWiFi need to be changed according to the IP address and port number printed by the serial monitor.

Mode selection: select **Server mode/Client mode**.

IP address: In Server mode, this option does not need to be filled in, and the computer will automatically obtain the IP address.

In Client mode, fill in the remote IP address to be connected.

Port number: In Server mode, fill in a port number for client devices to make an access connection.

In client mode, fill in port number given by the Server devices to make an access connection.

Start button: In server mode, push the button, and then the computer will serve as Server and open a port number for Client to make access connection. During this period, the computer will keep monitoring.

In client mode, before pushing the button, please make sure the server is on, remote IP address and remote port number is correct; push the button, and the computer will make access connection to the remote port number of the remote IP as a Client.

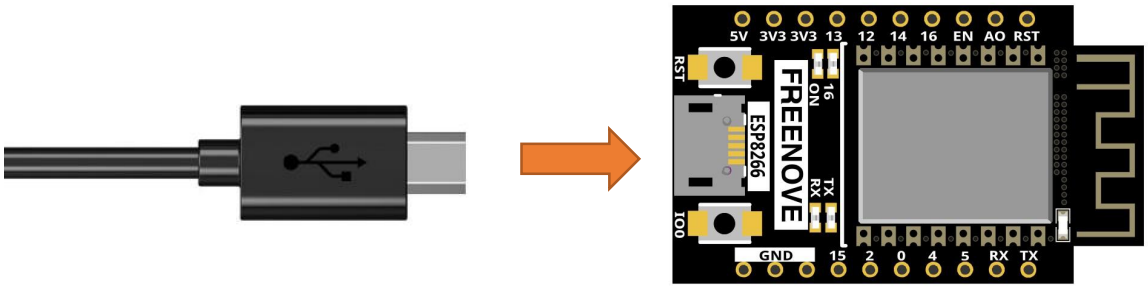
clear receive: clear out the content in the receiving text box

clear send: clear out the content in the sending text box

Sending button: push the sending button, the computer will send the content in the text box to others.

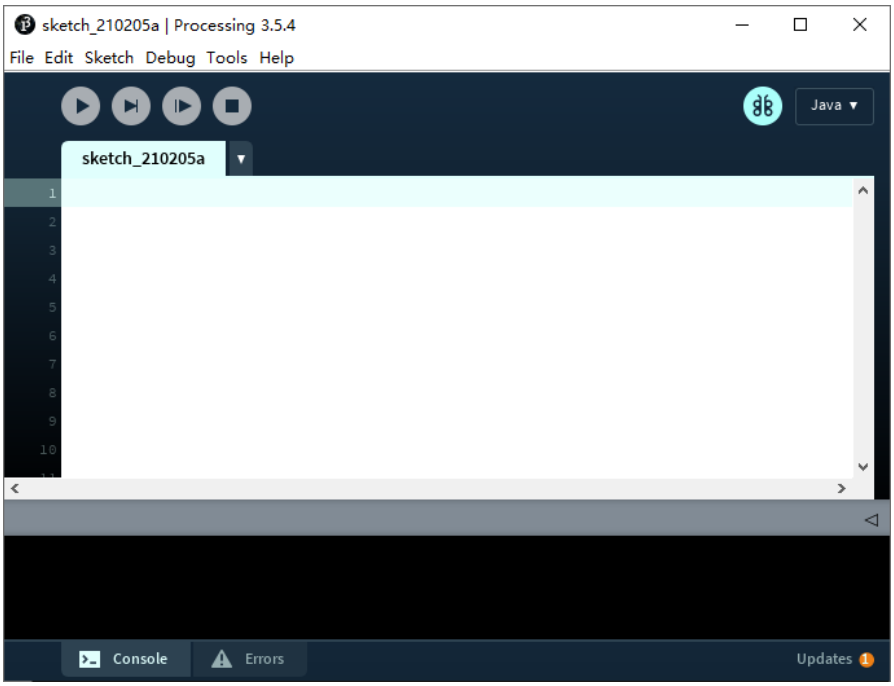
Circuit

Connect Freenove ESP8266 to the computer using USB cable.

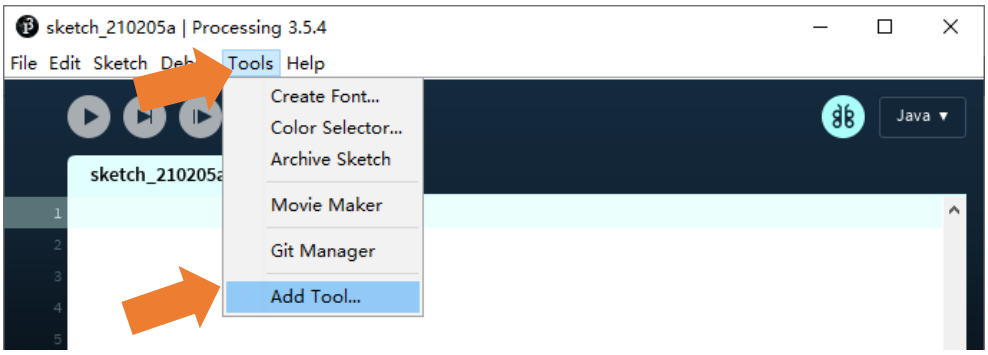


Code

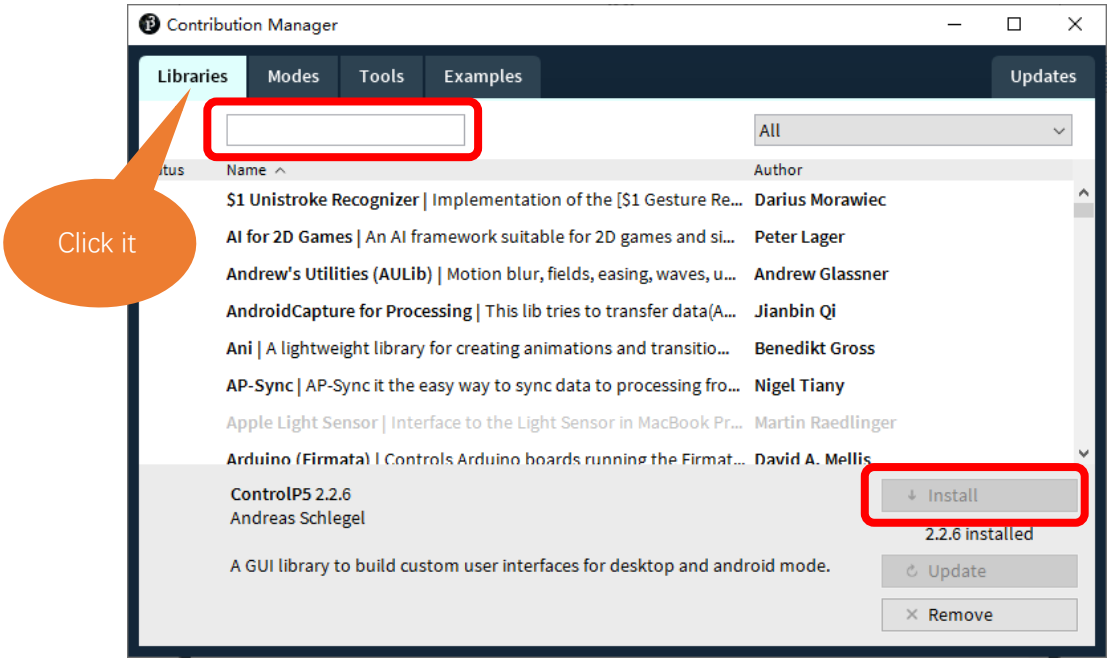
If you have not installed "ControlP5", please follow the following steps to continue the installation, if you have installed, please skip this section.
Open Processing.



Click Add Tool under Tools.

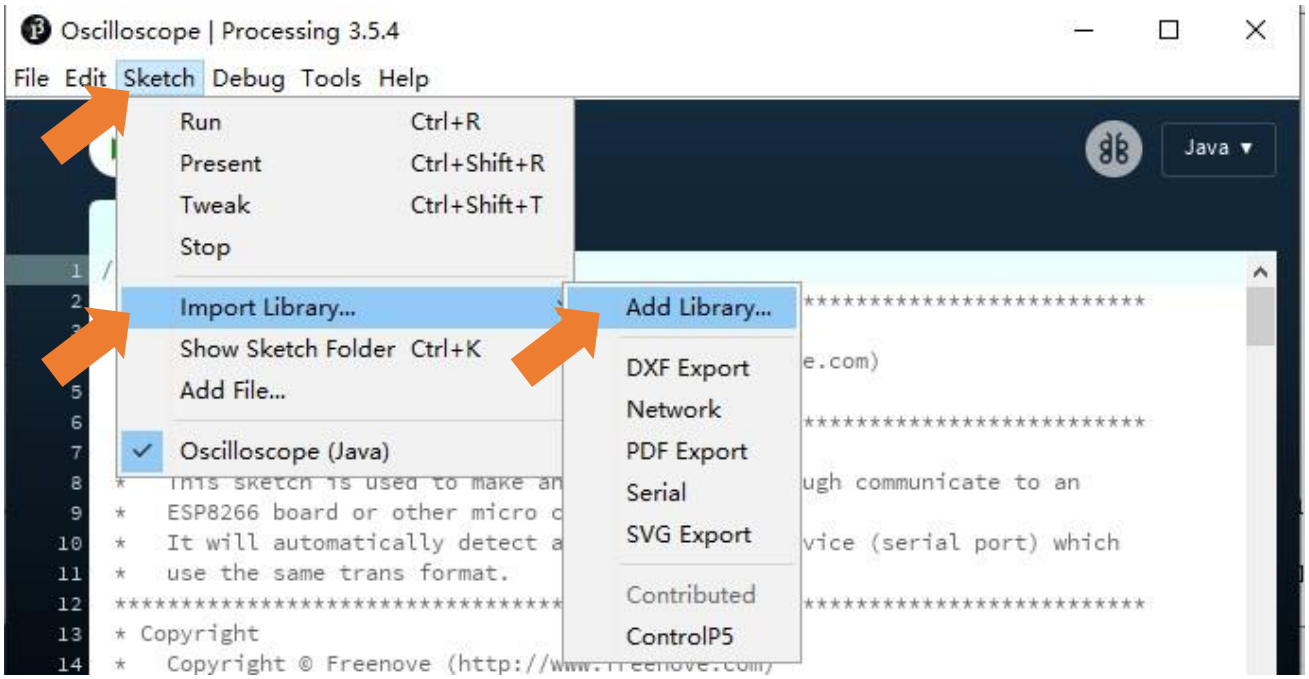


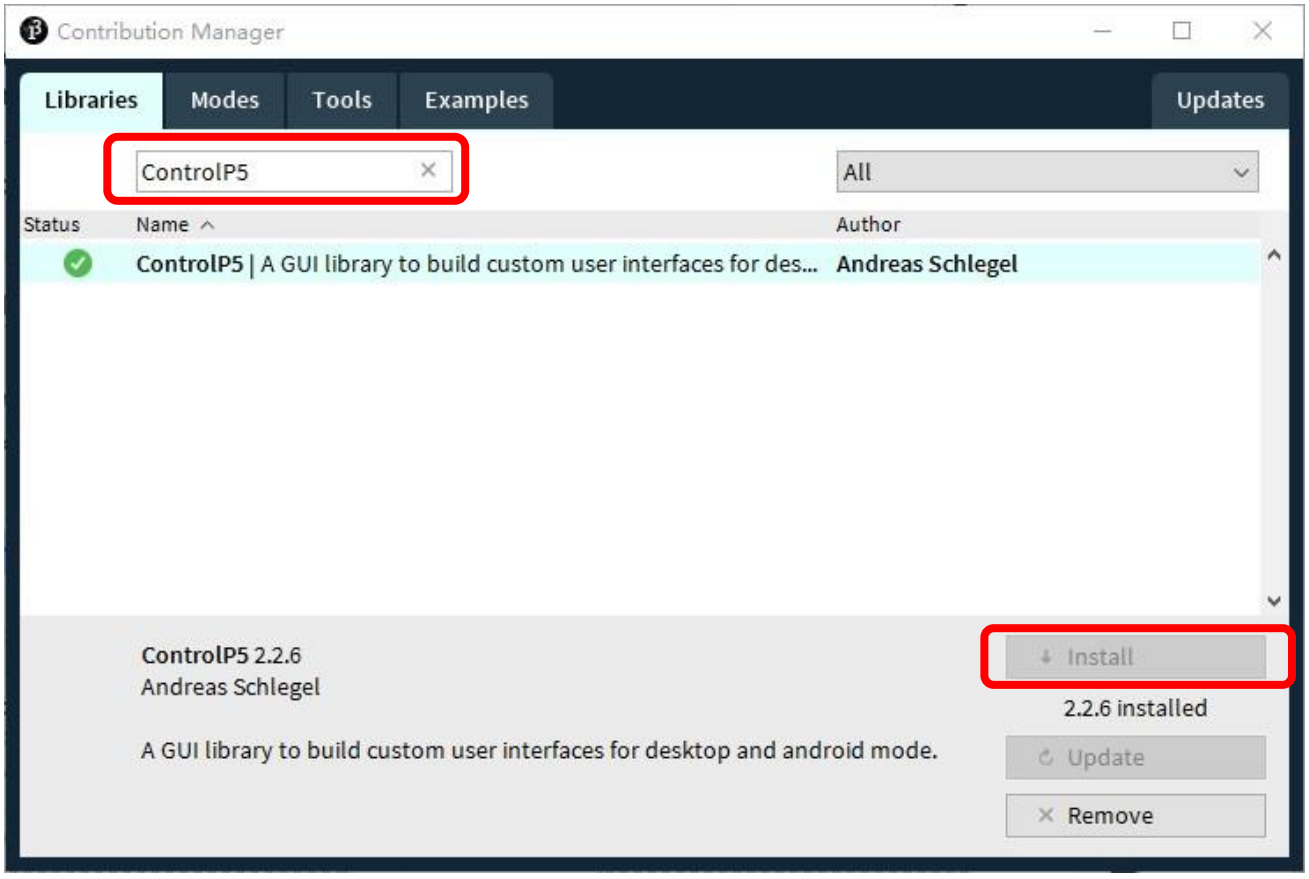
Select Libraries in the pop-up window.



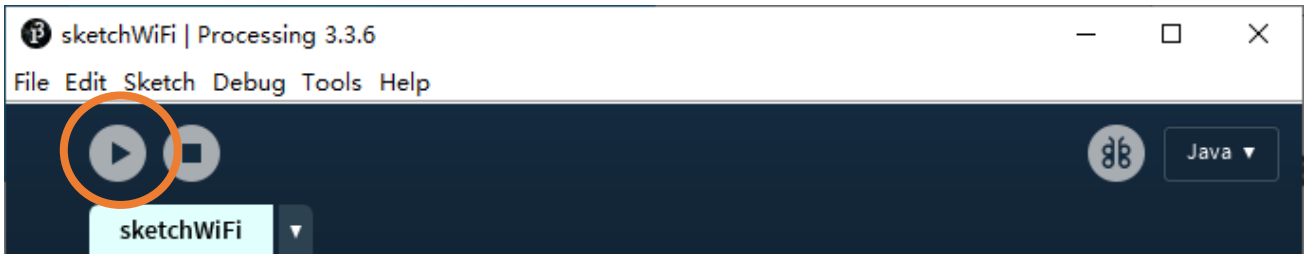
Input "ControlP5" in the searching box, and then select the option as below. Click "Install" and wait for the installation to finish.

You can also click Add Library under 'Import Library' under 'Sketch'.

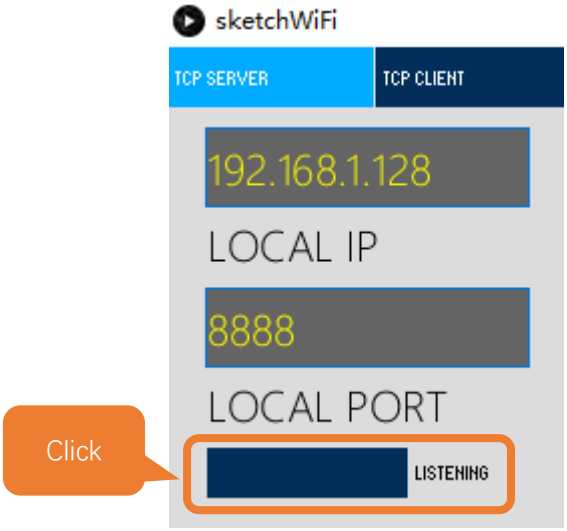

Oscilloscope | Processing 3.5.4
File Edit Sketch Debug Tools Help
Run Ctrl+R
Present Ctrl+Shift+R
Tweak Ctrl+Shift+T
Stop
Import Library...
Show Sketch Folder Ctrl+K
Add File...
Oscilloscope (Java)
Add Library...
DXF Export
Network
PDF Export
Serial
SVG Export
Contributed
ControlP5
Java


Contribution Manager
Libraries
Modes
Tools
Examples
Updates
ControlP5
All
Status
Name
Author
ControlP5 | A GUI library to build custom user interfaces for des...
Andreas Schlegel
ControlP5 2.2.6
Andreas Schlegel
A GUI library to build custom user interfaces for desktop and android mode.
Install
2.2.6 installed
Update
Remove

Before running the Code, please open "sketchWiFi.pde." first, and click "Run".



The newly pop up window will use the computer's IP address by default and open a data monitor port. Click "Listening"。

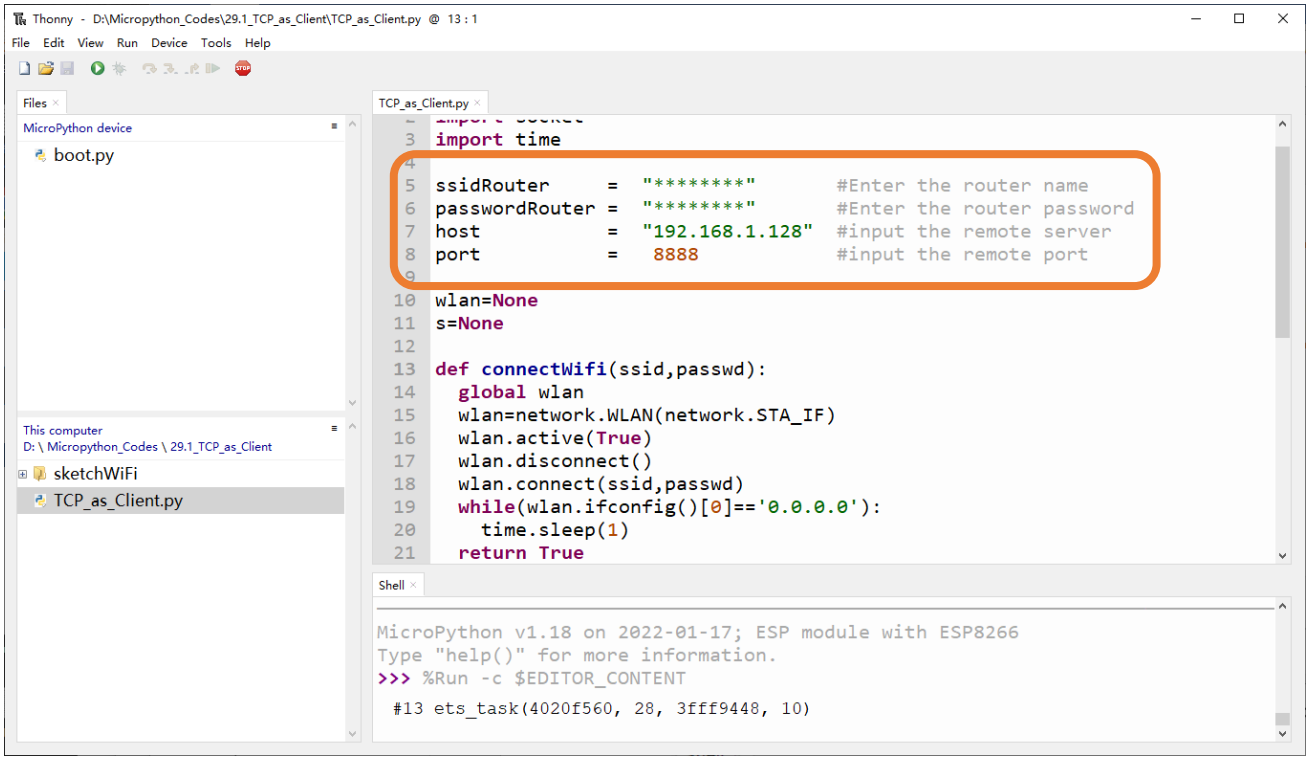


Move the program folder "**Freenove_ESP8266_Board/Python/Python_Codes**" to disk(D) in advance with the path of "**D:/Micropython_Codes**".

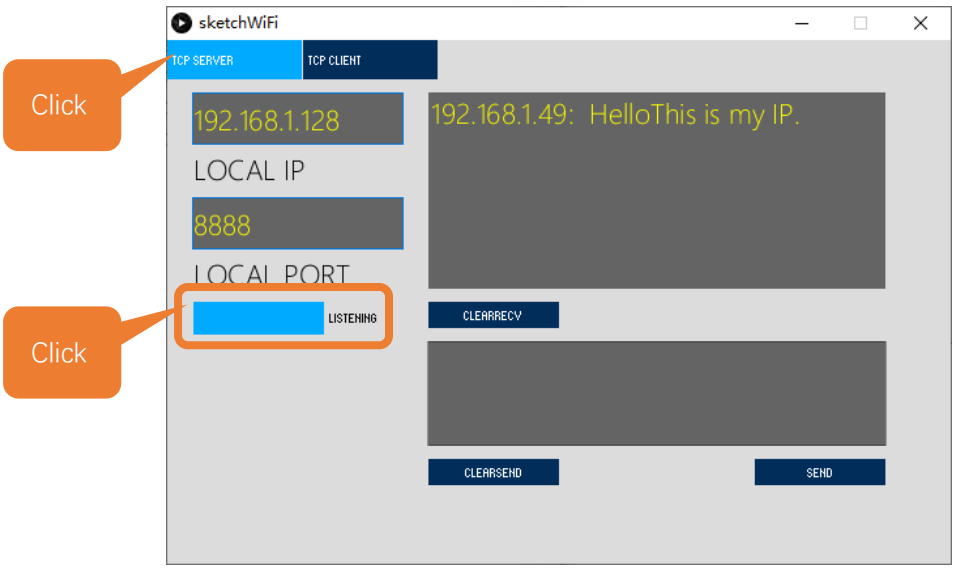
Open "Thonny", click "This computer" → "D:" → "Micropython_Codes" → "29.1_TCP_as_Client" and double click "TCP_as_Client.py".

Before clicking "Run current script", please modify the name and password of your router and fill in the "host" and "port" according to the **IP information in processing app** shown in the box below:

29.1_TCP_as_Client



Click "Run current script" and in "Shell", you can see ESP8266 automatically connects to sketchWiFi.

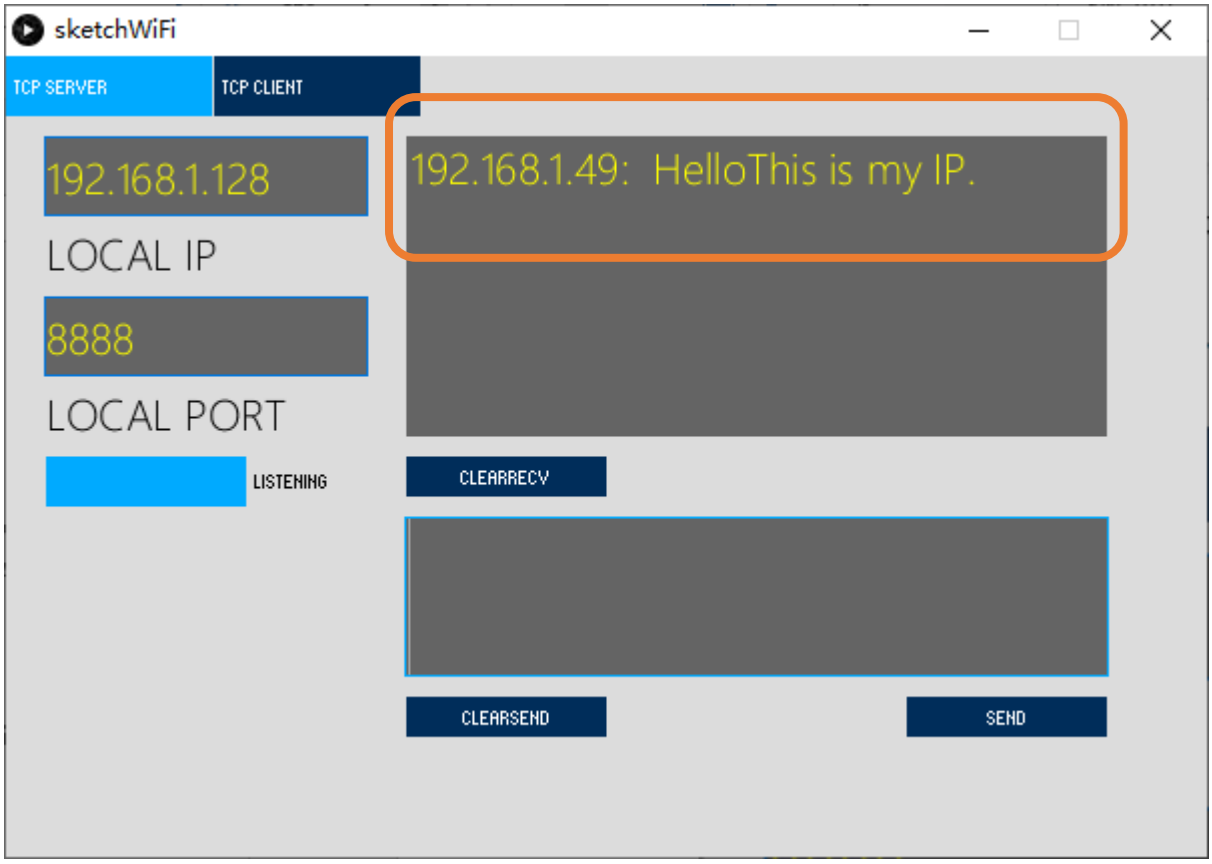


```
Shell
MicroPython v1.18 on 2022-01-17; ESP module with ESP8266
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT
  #5 ets_task(4020f560, 28, 3fff9ef0, 10)
TCP Connected to: 192.168.1.128 : 8888
```

If you don't click "Listening" for sketchWiFi, ESP8266 will fail to connect and will print information as follows:

```
Shell
  Close socket
>>> %Run -c $EDITOR_CONTENT
  TCP close, please reset!
>>>
```

ESP8266 connects with TCP SERVER, and TCP SERVER receives messages from ESP8266, as shown in the figure below.



The following is the program code:

```
1  import network
2  import socket
3  import time
```

```
4
5   ssidRouter     =  "********"    #Enter the router name
6   passwordRouter =  "********"    #Enter the router password
7   host           =  "********"    #input the remote server
8   port           =   8888         #input the remote port
9
10  wlan=None
11  s=None
12
13  def connectWifi(ssid,passwd):
14    global wlan
15    wlan= network.WLAN(network.STA_IF)
16    wlan.active(True)
17    wlan.disconnect()
18    wlan.connect(ssid,passwd)
19    while(wlan.ifconfig()[0]=='0.0.0.0'):
20      time.sleep(1)
21    return True
22  try:
23    connectWifi(ssidRouter,passwordRouter)
24    s = socket.socket()
25    s.setsockopt(socket.SOL_SOCKET, socket.SO_REUSEADDR, 1)
26    s.connect((host,port))
27    print("TCP Connected to:", host, ":", port)
28    s.send('Hello')
29    s.send('This is my IP.')
30    while True:
31      data = s.recv(1024)
32      if(len(data) == 0):
33        print("Close socket")
34        s.close()
35        break
36      print(data)
37      ret=s.send(data)
38  except:
39    print("TCP close, please reset!")
40    if (s):
41      s.close()
42    wlan.disconnect()
43    wlan.active(False)
```

Import network、socket、time modules.

```
1   import network
2   import socket
3   import time
```

Enter the actual router name, password, remote server IP address, and port number.

```
5  ssidRouter     = "********"   #Enter the router name
6  passwordRouter = "********"   #Enter the router password
7  host           = "********"   #input the remote server
8  port           =  8888        #input the remote port
```

Connect specified Router until it is successful.

```
13  def connectWifi(ssid,passwd):
14      global wlan
15      wlan= network.WLAN(network.STA_IF)
16      wlan.active(True)
17      wlan.disconnect()
18      wlan.connect(ssid,passwd)
19      while(wlan.ifconfig()[0]=='0.0.0.0'):
20          time.sleep(1)
21      return True
```

Connect router and then connect it to remote server.

```
23      connectWifi(ssidRouter,passwordRouter)
24      s = socket.socket()
25      s.setsockopt(socket.SOL_SOCKET, socket.SO_REUSEADDR, 1)
26      s.connect((host,port))
27      print("TCP Connected to:", host, ":", port)
```

Send messages to the remote server, receive the messages from it and print them out, and then send the messages back to the server.

```
28      s.send('Hello')
29      s.send('This is my IP.')
30      while True:
31          data = s.recv(1024)
32          if(len(data) == 0):
33              print("Close socket")
34              s.close()
35              break
36          print(data)
37          ret=s.send(data)
```

If an exception occurs in the program, for example, the remote server is shut down, execute the following program, turn off the socket function, and disconnect the WiFi.

```
39      print("TCP close, please reset!")
40      if (s):
41          s.close()
42      wlan.disconnect()
43      wlan.active(False)
```

Reference

Class socket

Before each use of **socket**, please add the statement "**import socket**" to the top of the python file.

socket([af, type, proto]): Create a socket.

af: address

socket.AF_INET: IPv4

socket.AF_INET6: IPv6

type: type

socket.SOCK_STREAM : TCP stream

socket.SOCK_DGRAM : UDP datagram

socket.SOCK_RAW : Original socket

socket.SO_REUSEADDR : socket reusable

proto: protocol number

socket.IPPROTO_TCP: TCPmode

socket.IPPROTO_UDP: UDPmode

socket.setsockopt(level, optname, value): Set the socket according to the options.

Level: Level of socket option

socket.SOL_SOCKET: Level of socket option. By default, it is 4095.

optname: Options of socket

socket.SO_REUSEADDR: Allowing a socket interface to be tied to an address that is already in use.

value: The value can be an integer or a bytes-like object representing a buffer.

socket.connect(address): To connect to server.

Address: Tuple or list of the server's address and port number

send(bytes): Send data and return the bytes sent.

recv(bufsize): Receive data and return a bytes object representing the data received.

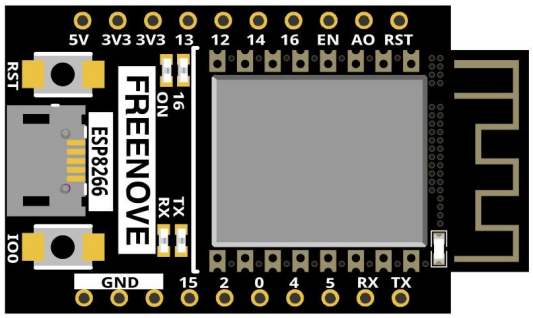
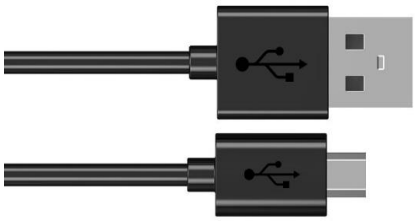
close(): Close socket.

To learn more please visit: http://docs.micropython.org/en/latest/

Project 4.2 As Server

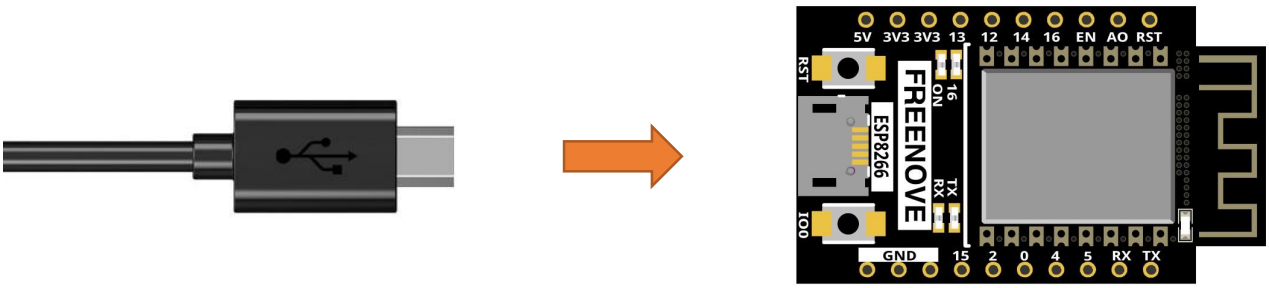
In this section, ESP8266 is used as a Server to wait for the connection and communication with Client on the same LAN.

Component List

ESP8266 x1 	USB cable 

Circuit

Connect Freenove ESP8266 to the computer using the USB cable.



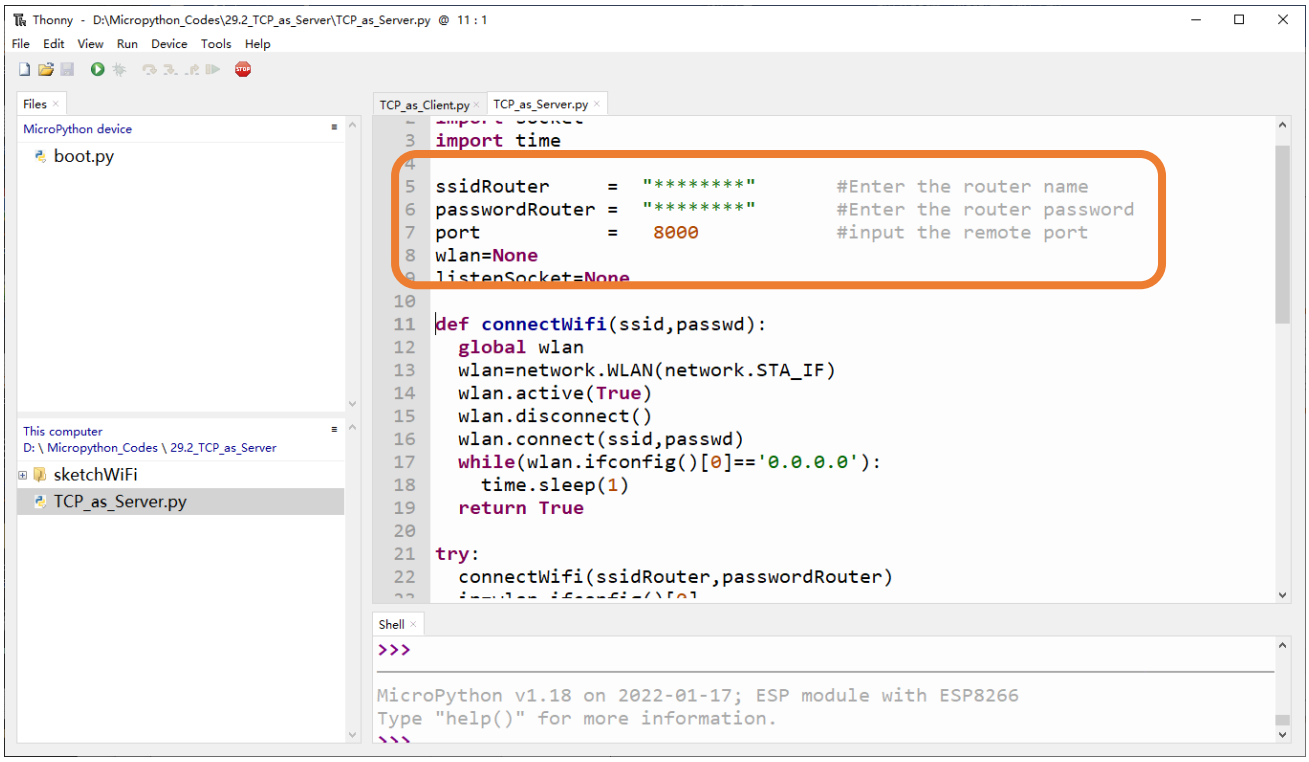
Code

Move the program folder "**Freenove_ESP8266_Board/Python/Python_Codes**" to disk(D) in advance with the path of "**D:/Micropython_Codes**".

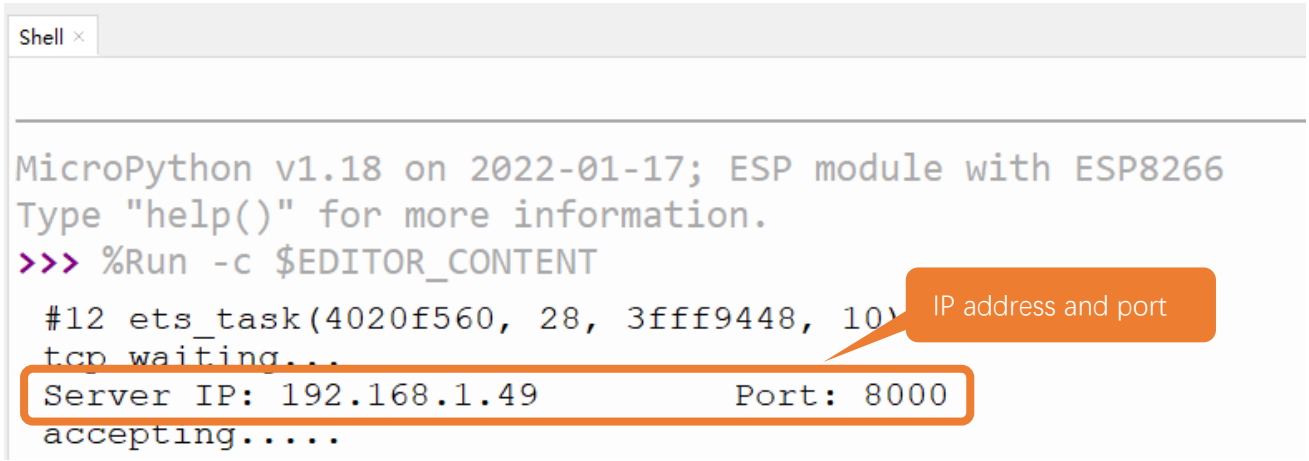
Open "Thonny", click "This computer" → "D:" → "Micropython_Codes" → "29.2_TCP_as_Server" and double click "TCP_as_Server.py".

Before clicking "Run current script", please modify the name and password of your router shown in the box below.

29.2_TCP_as_Server



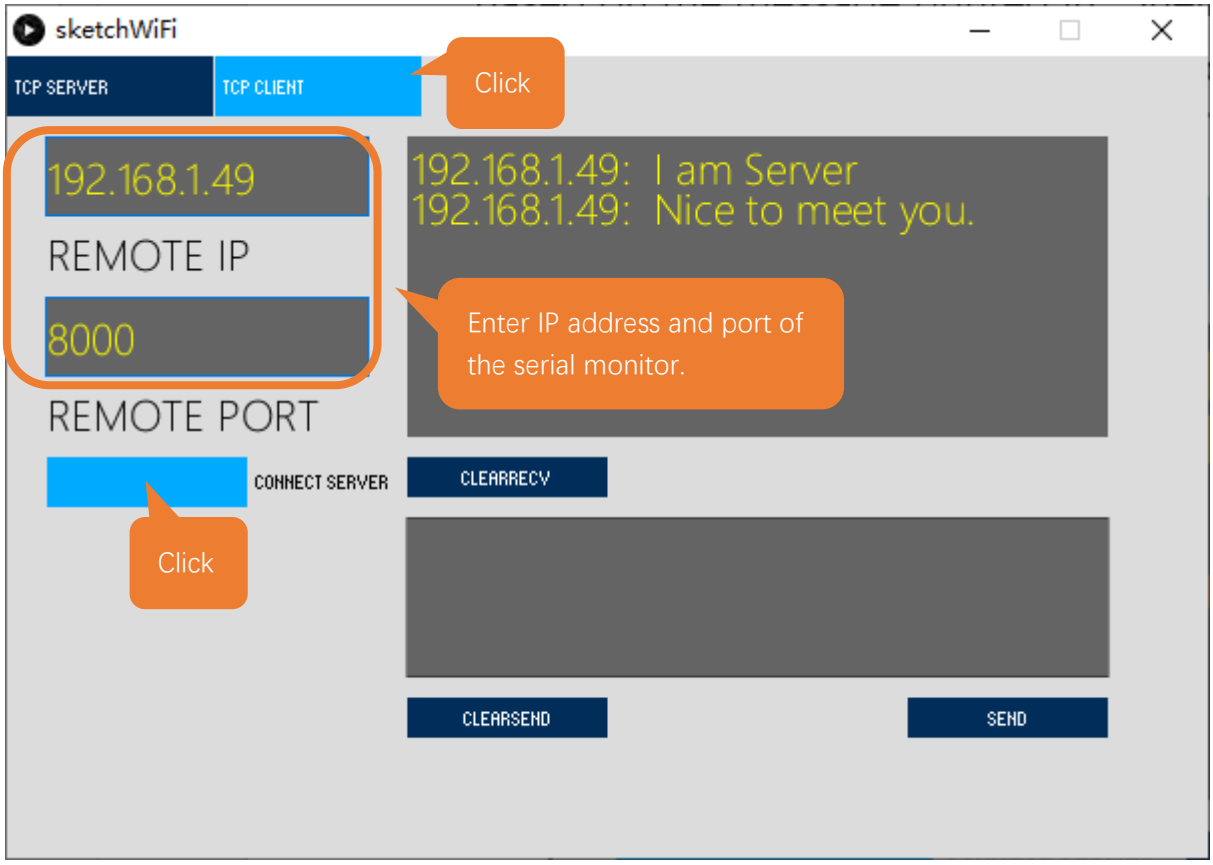
After making sure that the router's name and password are correct, click "Run current script" and in "Shell", you can see a server opened by the ESP8266 waiting to connecting to other network devices.



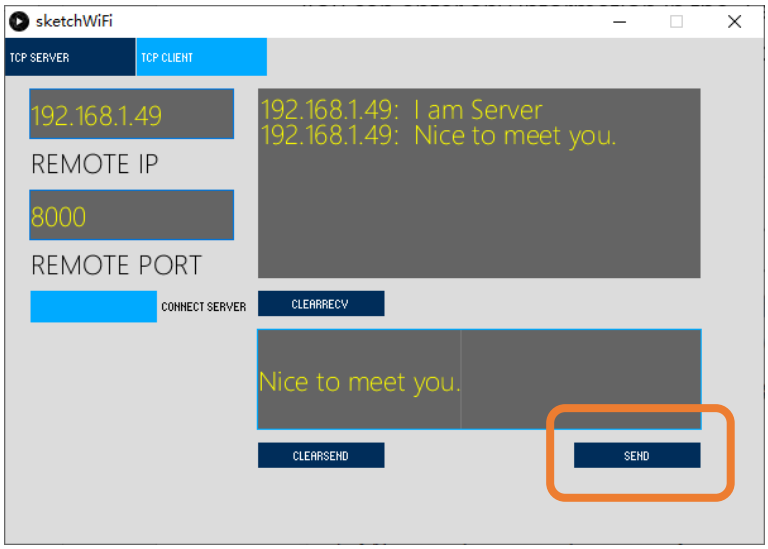
Processing:

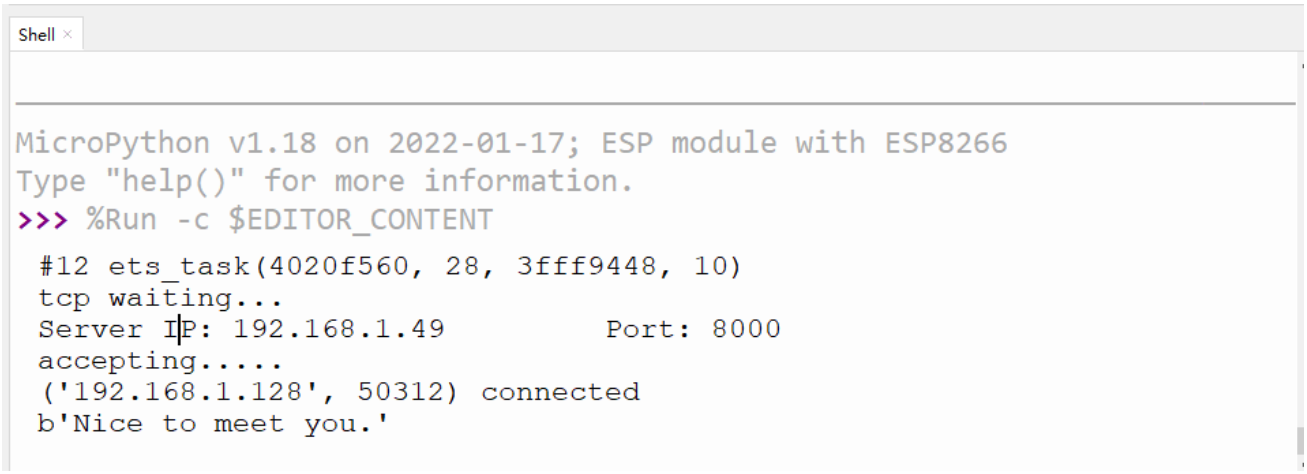
Open the "**Freenove_ESP8266_Board/Codes/MicroPython_Codes/29.2_TCP_as_Server/sketchWiFi/sketchWiFi.pde**".

Based on the message printed in "Shell", enter the correct IP address and port when processing, and click to establish a connection with ESP8266 to communicate.



You can enter any information in the "Send Box" of sketchWiFi. Click "Send" and ESP8266 will print the received messages to "Shell" and send them back to sketchWiFi.




Shell
MicroPython v1.18 on 2022-01-17; ESP module with ESP8266
Type "help()" for more information.
>>> %Run -c $EDITOR_CONTENT
#12 ets_task(4020f560, 28, 3fff9448, 10)
tcp waiting...
Server IP: 192.168.1.49 Port: 8000
accepting.....
('192.168.1.128', 50312) connected
b'Nice to meet you.'

The following is the program code:

```
import network
import socket
import time

ssidRouter     =  "********"       #Enter the router name
passwordRouter =  "********"       #Enter the router password
port           =   8000            #input the remote port
wlan           =  None
listenSocket   =  None

def connectWifi(ssid,passwd):
  global wlan
  wlan=network.WLAN(network.STA_IF)
  wlan.active(True)
  wlan.disconnect()
  wlan.connect(ssid,passwd)
  while(wlan.ifconfig()[0]=='0.0.0.0'):
    time.sleep(1)
  return True

try:
  connectWifi(ssidRouter,passwordRouter)
  ip=wlan.ifconfig()[0]
  listenSocket = socket.socket()
  listenSocket.bind((ip,port))
  listenSocket.listen(1)
  listenSocket.setsockopt(socket.SOL_SOCKET, socket.SO_REUSEADDR, 1)
  print('tcp waiting...')
  while True:
    print("Server IP:",ip,"\tPort:",port)
    print("accepting.....")
    conn,addr = listenSocket.accept()
    print(addr,"connected")
    break
  conn.send('I am Server')
  while True:
    data = conn.recv(1024)
    if(len(data) == 0):
      print("close socket")
      listenSocket.close()
      wlan.disconnect()
      wlan.active(False)
      break
```

```
    else:
      print(data)
      ret = conn.send(data)
except:
  print("Close TCP-Server, please reset.")
  if(listenSocket):
    listenSocket.close()
  wlan.disconnect()
  wlan.active(False)
```

Call function connectWifi() to connect to router and obtain the dynamic IP that it assigns to ESP8266.

```
  connectWifi(ssidRouter,passwordRouter)
  ip=wlan.ifconfig()[0]
```

Open the socket server, bind the server to the dynamic IP, and open a data monitoring port.

```
  listenSocket = socket.socket()
  listenSocket.bind((ip,port))
  listenSocket.listen(1)
  listenSocket.setsockopt(socket.SOL_SOCKET, socket.SO_REUSEADDR, 1)
```

Print the server's IP address and port, monitor the port and wait for the connection of other network devices.

```
  while True:
    print("Server IP:",ip,"\tPort:",port)
    print("accepting.....")
    conn,addr = listenSocket.accept()
    print(addr,"connected")
    break
```

Each time receiving data, print them in "Shell" and send them back to the client.

```
  while True:
    data = conn.recv(1024)
    if(len(data) == 0):
      print("close socket")
      listenSocket.close()
      wlan.disconnect()
      wlan.active(False)
      break
    else:
      print(data)
      ret = conn.send(data)
```

If the client is disconnected, close the server and disconnect WiFi.

```
except:
  print("Close TCP-Server, please reset.")
  if(listenSocket):
    listenSocket.close()
  wlan.disconnect()
  wlan.active(False)
```

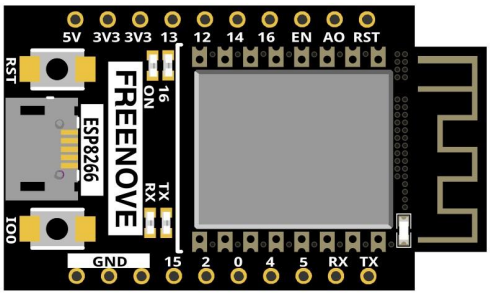
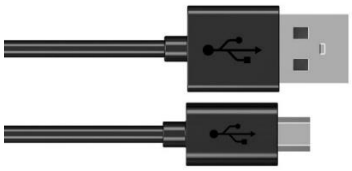
Chapter 5 Smart Home

In this chapter, we will use ESP8266 to make a simple smart home.We will learn how to control LED lights through web pages.

Project 5.1 Control_LED_through_Web

In this project, we need to build a Web Service and then use ESP8266 to control the LED through the Web browser of the PC.Through this example, you can remotely control the appliances in your home to achieve smart home.

Component List

ESP8266 x1 	Micro USB Wire x1 

Component knowledge

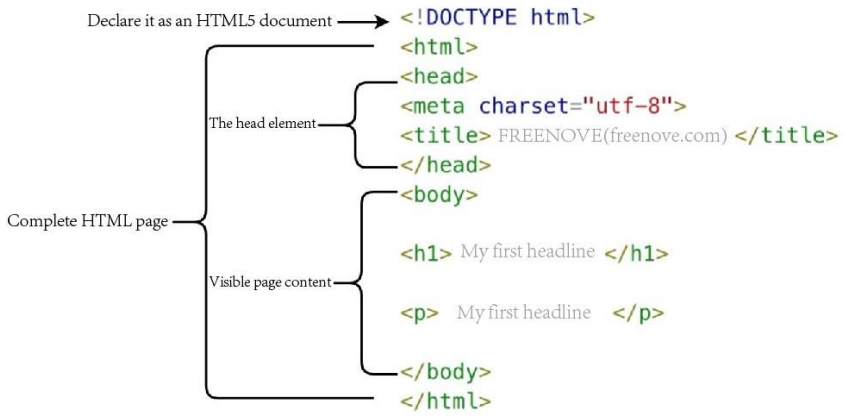
HTML

HyperText Markup Language (HTML) is a standard Markup Language for creating web pages.It includes a set of tags that unify documents on the network and connect disparate Internet resources into a logical whole.HTML text is descriptive text composed of HTML commands that describe text, graphics, animations, sounds, tables, links, etc.The extension of the HTML file is HTM or HTML.Hyper Text is a way to organize information.It uses hyperlinks to associate words and charts in Text with other information media.These related information media may be in the same Text, other files, or files located on a remote computer.This way of organizing information connects the information resources distributed in different places, which is convenient for people to search and retrieve information.

The nature of the Web is hypertext Markup Language (HTML), which can be combined with other Web technologies (e.g., scripting languages, common gateway interfaces, components, etc.) to create powerful Web pages. Thus, HYPERtext Markup Language (HTML) is the foundation of World Wide Web (Web) programming, that is, the World Wide Web is based on hypertext. Hypertext Markup Language is called hypertext Markup language because the text contains so-called "hyperlink" points.

You can build your own WEB site using HTML, which runs on the browser and is parsed by the browser.

Example analysis is shown in the figure below:



<!DOCTYPE html>: Declare it as an HTML5 document

<html>: Is the root element of an HTML page

<head>: Contains meta data for the document, such as < meta charset="utf-8"> Define the web page encoding format to UTF-8.

<title>: Notesthe title of the document

<body>: Contains visible page content

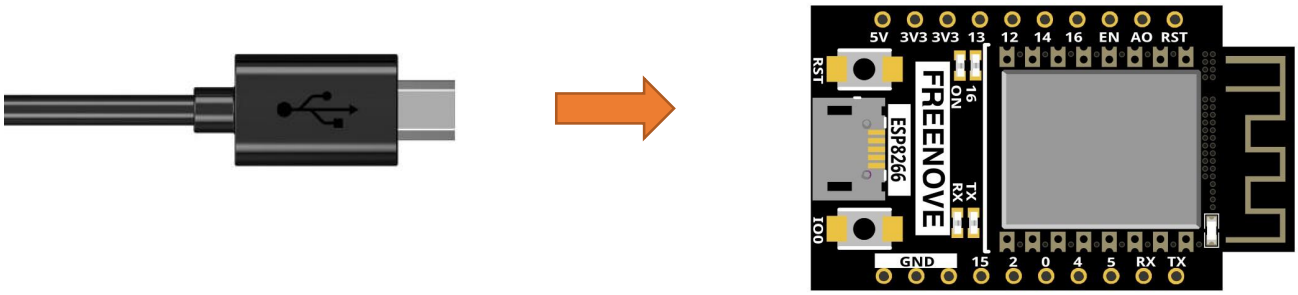
<h1>: Define a big heading

<p>: Define a paragraph

For more information, please visit: https://developer.mozilla.org/en-US/docs/Web/HTML

Circuit

Connect Freenove ESP8266 to the computer using a USB cable.

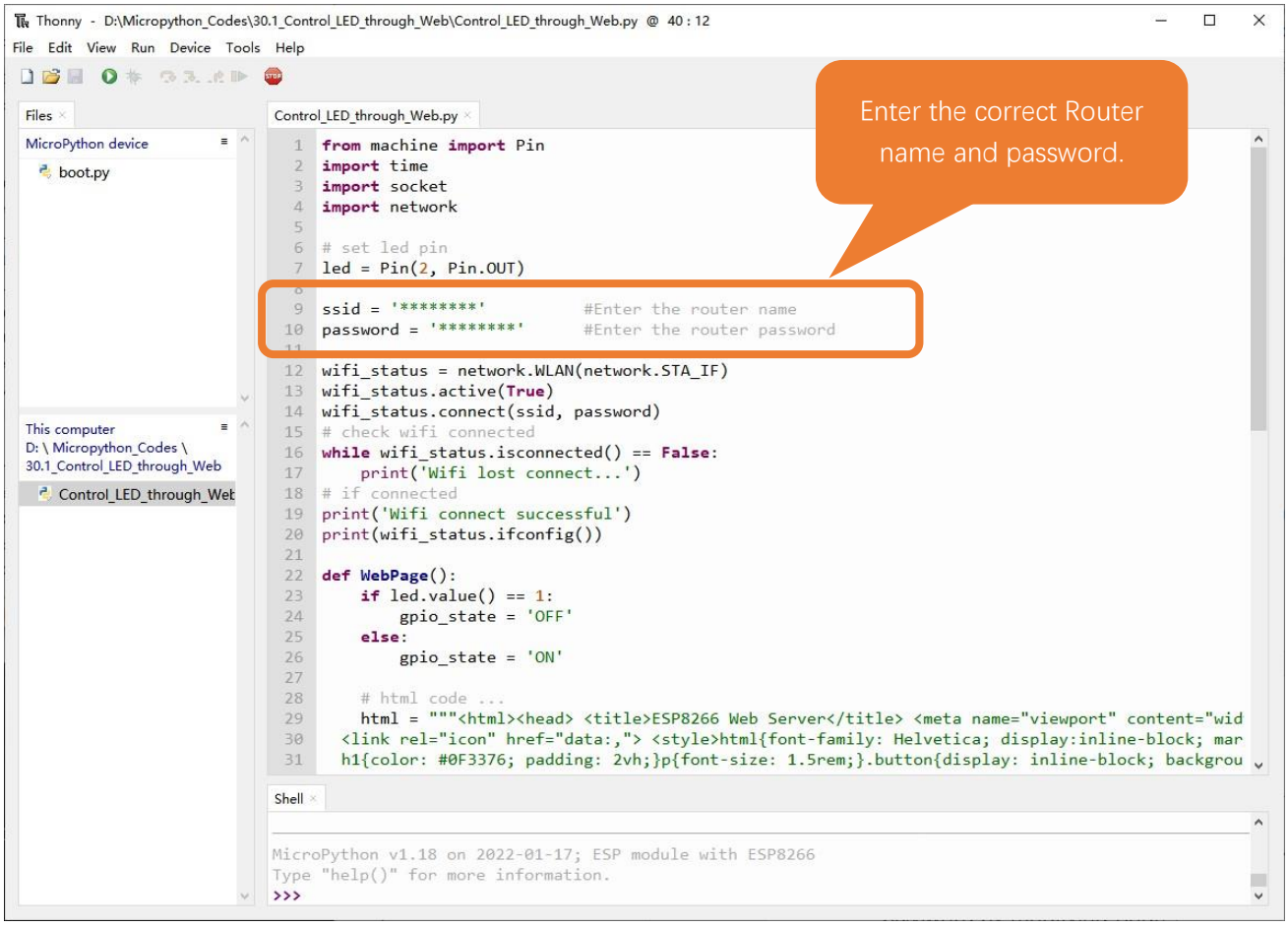


Code

Move the program folder "**Freenove_ESP8266_Board/Python/Python_Codes**" to disk(D) in advance with the path of "**D:/Micropython_Codes**".

Open "Thonny", click "This computer" → "D:" → "Micropython_Codes" → "30.1_Control_LED_through_Web". and double click "Control_LED_through_Web".

30.1_Control_LED_through_Web



Because the names and passwords of routers in various places are different, before the Code runs, users need to enter the correct router's name and password in the box as shown in the illustration above.
After making sure the router name and password are entered correctly, compile and upload codes to ESP8266, wait for ESP8266 to connect to your router and print the IP address assigned by the router to ESP8266 in "Shell".

```
Shell
Wifi lost connect...
Wifi lost connect...
Wifi lost connect...
Wifi lost connect...
Wifi lost connect...
Wifi lost connect...
Wifi lost connect...
Wifi lost connect...
Wifi lost connect...
Wifi connect successful
('192.168.1.45', '255.255.255.0', '192.168.1.1', '192.168.1.1')
```

When ESP8266 successfully connects to "ssid", "Shell" displays the IP address assigned to ESP8266 by the router. Access http://192.168.1.45 in a computer browser on the LAN. As shown in the following figure:

You can click the corresponding button to control the LED on and off.
The following is the program code:

```
1  from machine import Pin
2  import time
3  import socket
4  import network
5
6  # set led pin
7  led = Pin(2, Pin.OUT)
8
9  ssid = '********'          #Enter the router name
10 password = '********'      #Enter the router password
11
```

```
wifi_status = network.WLAN(network.STA_IF)
wifi_status.active(True)
wifi_status.connect(ssid, password)
# check wifi connected
while wifi_status.isconnected() == False:
    print('Wifi lost connect...')
# if connected
print('Wifi connect successful')
print(wifi_status.ifconfig())

def WebPage():
    if led.value() == 1:
        gpio_state = 'OFF'
    else:
        gpio_state = 'ON'

    # html code ...
    html = """
    <html>
        <head>
            <title>ESP8266 Web Server</title>
            <meta name="viewport" content="width=device-width, initial-scale=1">
            <link rel="icon" href="data:,">
            <style>
                html{font-family: Helvetica; display:inline-block; margin: 0px auto; text-
align: center;}
                h1{color: #0F3376; padding: 2vh;}
                p{font-size: 1.5rem;}
                button{display: inline-block; background-color: #4286f4; border: none;border-
radius: 4px; color: white; padding: 16px 40px; text-decoration: none; font-size: 30px; margin:
2px; cursor: pointer;}
                button2{background-color: #4286f4;}
            </style>
        </head>
        <body> <h1>ESP8266 Web Server</h1>
          <p>GPIO state: <strong>""" + gpio_state + """</strong></p>
          <p><a href="/?led=on"><button class="button">ON</button></a></p>
          <p><a href="/?led=off"><button class="button button2">OFF</button></a></p>
        </body>
    </html>
    """
    return html

s = socket.socket(socket.AF_INET, socket.SOCK_STREAM)
```

```
53  s.bind(('', 80))
54  s.listen(5)
55  try:
56      while True:
57          conn, addr = s.accept()
58          print('Connection: %s' % str(addr))
59          req = conn.recv(1024)
60          req = str(req)
61          print('Connect = %s' % req)
62          led_on = req.find('/?led=on')
63          led_off = req.find('/?led=off')
64          if led_on == 6:
65              print('LED ON')
66              led.value(0)
67          else:
68              print('LED OFF')
69              led.value(1)
70          if led.value() == 1:
71              gpio_state = 'OFF'
72          else:
73              gpio_state = 'ON'
74          response = WebPage()
75          conn.send('HTTP/1.1 200 OK\n')
76          conn.send('Content-Type: text/html\n')
77          conn.send('Connection: close\n\n')
78          conn.sendall(response)
79          conn.close()
80  except:
81      pass
```

Import socket module and Import network module.

```
3  import socket
4  import network
```

Enter correct AP name and password.

```
3  ssid = '********'            #Enter the router name
4  password = '********'        #Enter the router password
```

Set ESP8266 in Station mode and connect it to your router.

```
12  wifi_status = network.WLAN(network.STA_IF)
13  wifi_status.active(True)
14  wifi_status.connect(ssid, password)
```

"Shell" displays the IP address assigned to ESP8266.

```
20  print(wifi_status.ifconfig())
```

Click the button on the web page to control the LED light on and off.

```
55          if led_on == 6:
56              print('LED ON')
```

```
57                led.value(0)
58            else:
59                print('LED OFF')
60                led.value(1)
61            if led.value() == 1:
62                gpio_state = 'OFF'
63            else:
64                gpio_state = 'ON'
```

What's next?

Thanks for your reading. This tutorial is all over here. If you find any mistakes, omissions or you have other ideas and questions about contents of this tutorial or the kit and etc., please feel free to contact us:

support@freenove.com

We will check and correct it as soon as possible.

If you want learn more about ESP8266, you view our ultimate tutorial:
https://github.com/Freenove/Freenove_ESP8266_Board/archive/master.zip

If you want to learn more about Arduino, Raspberry Pi, smart cars, robots and other interesting products in science and technology, please continue to focus on our website. We will continue to launch cost-effective, innovative and exciting products.

http://www.freenove.com/

End of the Tutorial

Thank you again for choosing Freenove products.