# Welcome

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Freenove provides free and responsive product and technical support, including but not limited to:

- Product quality issues
- Product use and build issues
- Questions regarding the technology employed in our products for learning and education
- Your input and opinions are always welcome
- We also encourage your ideas and suggestions for new products and product improvements For any of the above, you may send us an email to:

# support@freenove.com

# Safety and Precautions

Please follow the following safety precautions when using or storing this product:

- Keep this product out of the reach of children under 6 years old.
- This product should be used only when there is adult supervision present as young children lack necessary judgment regarding safety and the consequences of product misuse.
- This product contains small parts and parts, which are sharp. This product contains electrically conductive parts. Use caution with electrically conductive parts near or around power supplies, batteries and powered (live) circuits.
- When the product is turned ON, activated or tested, some parts will move or rotate. To avoid injuries to hands and fingers, keep them away from any moving parts!
- It is possible that an improperly connected or shorted circuit may cause overheating. Should this happen, immediately disconnect the power supply or remove the batteries and do not touch anything until it cools down! When everything is safe and cool, review the product tutorial to identify the cause.
- Only operate the product in accordance with the instructions and guidelines of this tutorial, otherwise parts may be damaged or you could be injured.
- Store the product in a cool dry place and avoid exposing the product to direct sunlight.
- After use, always turn the power OFF and remove or unplug the batteries before storing.

# About Freenove

Freenove provides open source electronic products and services worldwide.

Freenove is committed to assist customers in their education of robotics, programming and electronic circuits so that they may transform their creative ideas into prototypes and new and innovative products. To this end, our services include but are not limited to:

- Educational and Entertaining Project Kits for Robots, Smart Cars and Drones
- Educational Kits to Learn Robotic Software Systems for Arduino, Raspberry Pi and micro: bit
- Electronic Component Assortments, Electronic Modules and Specialized Tools
- Product Development and Customization Services

You can find more about Freenove and get our latest news and updates through our website:

http://www.freenove.com

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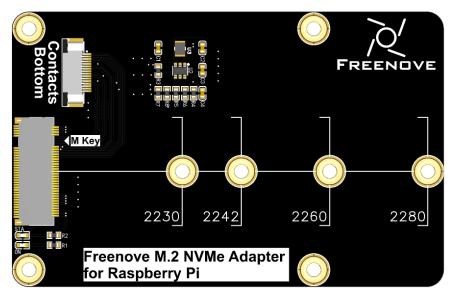
FREENOVE

Raspberry Pi® is a trademark of Raspberry Pi Foundation (https://www.raspberrypi.org/).

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# **Preface**



The Freenove M.2 NVMe Adapter for Raspberry Pi is a solid-state drives adapter designed specifically for the Raspberry Pi 5. Here are its key features:

• Interface Type: M.2 with M-Key

• Supported Protocol: NVMe

Compatible Sizes: 2230, 2242, 2260, 2280
 Power Supply: 3.3V, up to 3A (maximum)

• Indicator Lights: Includes both power and SSD status LEDs.

The Raspberry Pi 5 includes a PCle x1 slot that is certified for PCle Gen 2.0, providing a theoretical maximum throughput of 5GT/sec, whichroughly translates to 500MB/sec for read and write operations. Although this slot is not officially certified for PCle Gen 3.0, it is possible to force the use of Gen 3.0 for potentially higher speeds; however, doing so may lead to system instability and freezing. It is advised to stick with Gen 2.0 for reliability.

The PCle consortium states that the speed of PCle Gen 3.0 x1 is up to 8GT/sec, which translates to approximately 985MB/sec; however, Raspberry Pi claims that their implementation can achieve a speed of 10GT/sec, equivalent to around 1231MB/sec.

https://en.wikipedia.org/wiki/PCI\_Express#Comparison\_table https://www.raspberrypi.com/documentation/computers/raspberry-pi.html#pcie-gen-3-0

SSDs generally provide significantly faster read and write speeds compared to SD cards and USB drives, which can notably elevate the user experience when operating the Raspberry Pi 5.

Welcome to the Freenove M.2 NVMe Adapter for Raspberry Pi. This guide will walk you through the steps to effectively integrate and utilize this adapter on your Raspberry Pi 5.

support@freenove.com

Additionally, if you encounter any issues or have questions about this tutorial or the contents of kit, you can always contact us for free technical support at:

# support@freenove.com

# Overview

To boot Raspberry Pi 5 from an NVMe SSD, two core tasks need to be accomplished:

- 1. Configure the boot order of Raspberry Pi to give priority to SSD.
- 2. Flash the Raspberry Pi's operating system image onto the NVMe SSD.

## **Analysis**

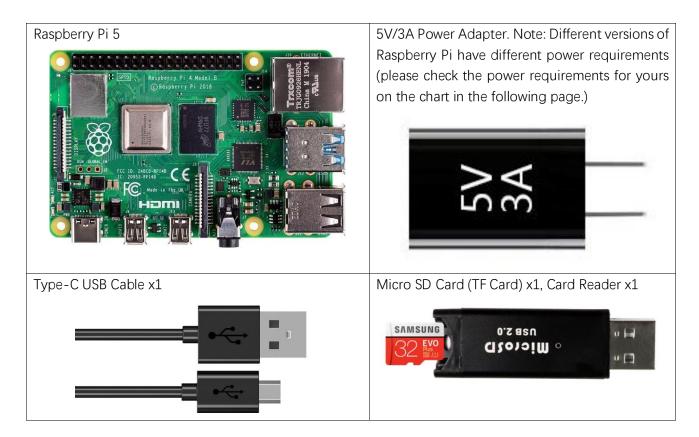
- 1. The default boot order of the Raspberry Pi is configured to prioritize booting from the SD card, followed by USB drives, while NVMe SSDs are not included in this predefined sequence. To alter the boot order, you must first boot the Raspberry Pi using an SD card or USB drive. This means that you should be able to start and operate the Raspberry Pi normally before integrating an NVMe SSD.
- 2. After booting the Raspberry Pi, you can use it to flash the OS image directly onto the NVMe SSD. Alternatively, you can purchase an NVMe SSD to USB adapter and flash the image using USB on Windows or macOS, much like you would for an SD card or USB drive.
- 3. With this analysis in mind, we can systematically carry out the necessary steps.

# 1. Flashing the RPi OS to SD Card or USB Drive

Based on the analysis above, our first step should be to install the Raspberry Pi operating system onto an SD card or USB drive, with a capacity of at least 16GB. If you are already able to boot the Raspberry Pi using an SD card or USB drive, you can skip this section and move on to the next chapter.

## Component List

## Required Components (provide yourselves)



Power requirements of various versions of Raspberry Pi are shown in following table:

Product	Recommended	Maximum total USB	Typical bare-board
	PSU current	peripheral current draw	active current
	capacity		consumption
Raspberry Pi Model A	700mA	500mA	200mA
Raspberry Pi Model B	1.2A	500mA	500mA
Raspberry Pi Model A+	700mA	500mA	180mA
Raspberry Pi Model B+	1.8A	600mA/1.2A (switchable)	330mA
Raspberry Pi 2 Model B	1.8A	600mA/1.2A (switchable)	350mA
Raspberry Pi 3 Model B	2.5A	1.2A	400mA
Raspberry Pi 3 Model A+	2.5A	Limited by PSU, board, and	350mA
		connector ratings only.	
Raspberry Pi 3 Model B+	2.5A	1.2A	500mA
Raspberry Pi 4 Model B	3.0A	1.2A	600mA
Raspberry Pi 5 Model B	5.0A	1.6A (600mA if using a 3A	800mA
		power supply)	
Raspberry Pi Zero W	1.2A	Limited by PSU, board, and	150mA
		connector ratings only.	
Raspberry Pi Zero	1.2A	Limited by PSU, board, and	100mA
		connector ratings only	

For more details, please refer to

https://www.raspberrypi.com/documentation/computers/raspberry-pi.html#power-supply

In addition, RPi also needs an Ethernet network cable used to connect it to a WAN (Wide Area Network).

All these components are necessary for any of your projects to work. Among them, the power supply of at least 5V/2.5A, because a lack of a sufficient power supply may lead to many functional issues and even damage your RPi, we STRONGLY RECOMMEND a 5V/2.5A power supply. We also recommend using a SD Micro Card with a capacity of 16GB or more (which, functions as the RPI's "hard drive") and is used to store the operating system and necessary operational files.

# **Optional Components**

Under normal circumstances, there are two ways to login to Raspberry Pi: 1) Using a stand-alone monitor. 2) Using a remote desktop or laptop computer monitor "sharing" the PC monitor with your RPi.

# Required Accessories for Monitor

If you choose to use an independent monitor, mouse and keyboard, you also need the following accessories:

- 1. A display with a HDMI interface
- 2. A Mouse and a Keyboard with an USB interface

As to Pi Zero and Pi Zero W, you also need the following accessories:

- 1. A Mini-HDMI to HDMI Adapter and Cable.
- 2. A Micro-USB to USB-A Adapter and Cable (Micro USB OTG Cable).
- 3. A USB HUB.
- 4. USB to Ethernet Interface or USB Wi-Fi receiver.

For different Raspberry Pi Modules, the optional items may vary slightly but they all aim to convert the interfaces to Raspberry Pi standards.

	Pi Zero	Pi A+	Pi Zero W	Pi 3A+	Pi B+/2B	Pi 3B/3B+	Pi 4B/5B
Monitor				Yes (Al	ll)		
Mouse		Yes (All)					
Keyboard				Yes (Al	ll)		
Micro-HDMI to HDMI Adapter & Cable	Yes	No	Yes	No	No	No	No
Micro-HDMI to HDMI Adapter & Cable				No			Yes
Micro-USB to USB-A Adapter & Cable (Micro USB OTG Cable)	Yes	No	Yes		Λ	lo	
USB HUB	Yes	Yes	Yes	Yes	No	No	
USB to Ethernet Interface	select o		opti	onal	Internal Integration	Internal I	ntegration
USB Wi-Fi Receiver	from	two	Internal Integratio		optional		

# Required Accessories for Remote Desktop

If you do not have an independent monitor, or if you want to use a remote desktop, you first need to login to Raspberry Pi through SSH, and then open the VNC or RDP service. This requires the following accessories.

	Pi Zero	Pi Zero W	Pi A+	Pi 3A+	Pi B+/2B	Pi 3B/3B+/4B/5B
Micro-USB to USB-A	Yes	Yes	No			
Adapter & Cable						
(Micro USB OTG						
Cable)					NO	
USB to Ethernet	Yes	Yes	Yes			
interface						

# Raspberry Pi OS

Without Screen - Use Raspberry Pi - under Windows PC: <a href="https://youtu.be/XpiT\_ezb\_7c">https://youtu.be/XpiT\_ezb\_7c</a> With Screen - Use Raspberry Pi - under Windows PC: <a href="https://youtu.be/HEywFsFrj3l">https://youtu.be/HEywFsFrj3l</a>

## **Automatically Method**

You can follow the official method to install the system for raspberry pi via visiting link below: <a href="https://projects.raspberrypi.org/en/projects/raspberry-pi-setting-up/2">https://projects.raspberrypi.org/en/projects/raspberry-pi-setting-up/2</a> In this way, the system will be downloaded **automatically** via the application.

# Manually Method

After installing the Imager Tool in the link above. You can also download the system manually first.

Visit https://www.raspberrypi.com/software/operating-systems/

## Operating system images

Many operating systems are available for Raspberry Pi, including Raspberry Pi OS, our official supported operating system, and operating systems from other organisations.

<u>Raspberry Pi Imager</u> is the quick and easy way to install an operating system to a microSD card ready to use with your Raspberry Pi. Alternatively, choose from the operating systems below, available to download and install manually.

Download:
Raspberry Pi OS
Raspberry Pi OS (64-bit)
Raspberry Pi OS (Legacy)
Raspberry Pi OS (Legacy, 64-bit)
Raspberry Pi Desktop

**Download** 

**Download** 

Download torrent

Archive

# Our recommended operating system for most users. Compatible with: Raspberry Pi OS with desktop Release date: March 15th 2024 System: 32-bit Kernel version: 12 (bookworm) Size: 1158MB Show SHA256 file integrity hash: Release notes Raspberry Pi OS with desktop and recommended software Release date: March 15th 2024 System: 32-bit Kernel version: 6.6 Debian version: 12 (bookworm)

Size: 2.678MB

Release notes

Show SHA256 file integrity hash:

And then the zip file is downloaded.



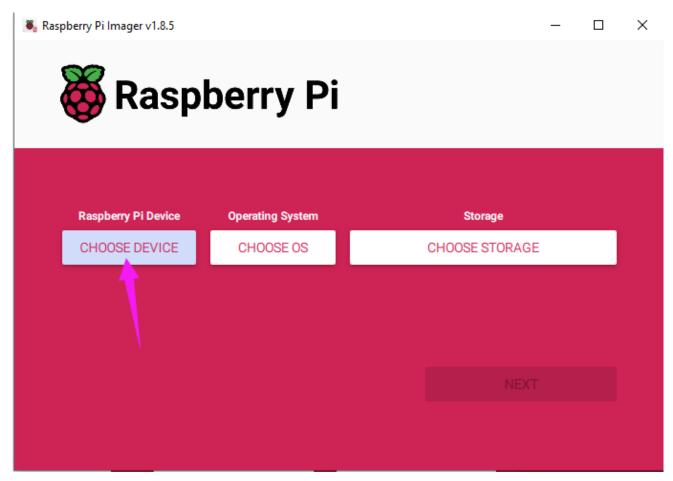
## Write System to Micro SD Card

First, put your Micro SD card into card reader and connect it to USB port of PC.

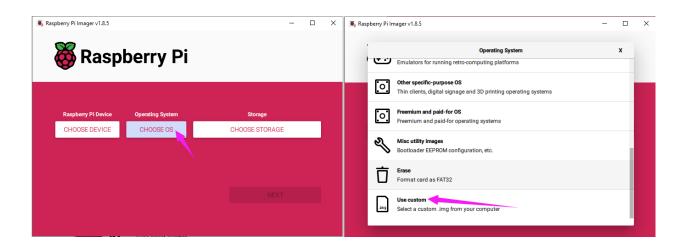


Open Raspberry Pi Imager.

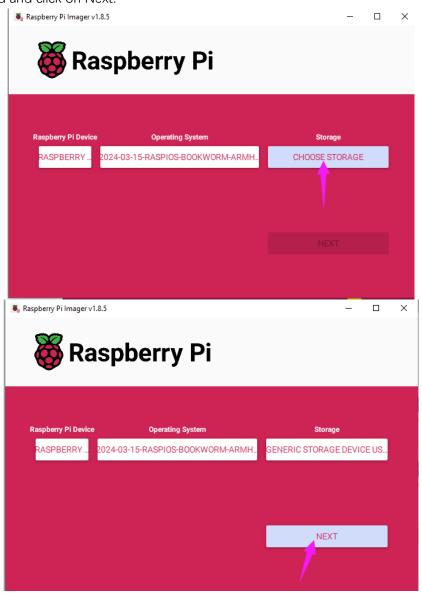
Choose Raspberry Pi 5 as the device.



Choose the system that you just downloaded in Use custom.

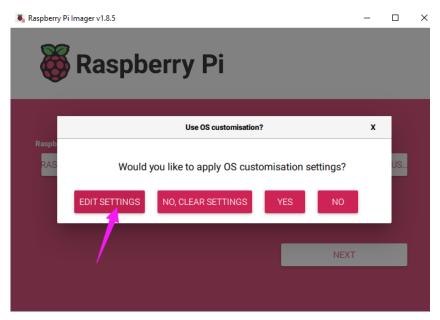


Choose the SD card and click on Next.

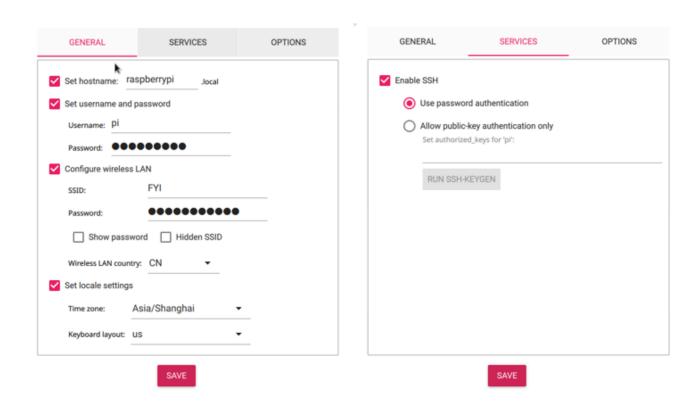


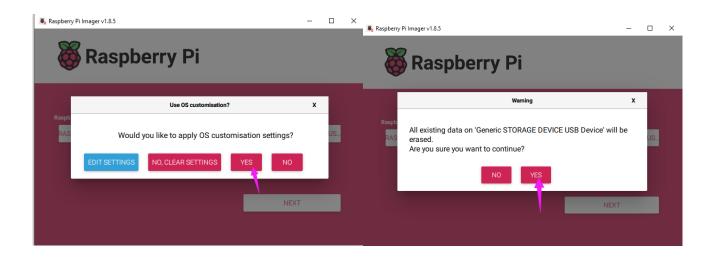
# Enable ssh and configure WiFi

### Click EDIT SETTINGS.



Configure wireless LAN, enable SSH and click Save.

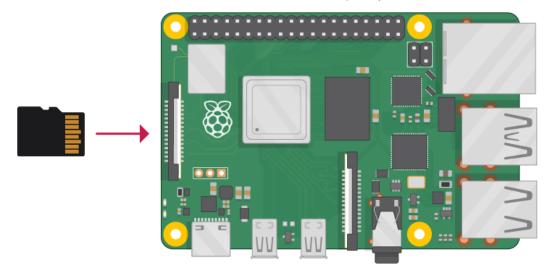




Wait for it to finish writing and verifying.

# Insert SD card

Then remove SD card from card reader and insert it into Raspberry Pi.



# Getting Started with Raspberry Pi

## Monitor desktop

If you do not have a spare monitor, please skip to next section Remote desktop & VNC. If you have a spare monitor, please follow the steps in this section.

After the system is written successfully, take out Micro SD Card and put it into the SD card slot of RPi. Then connect your RPi to the monitor through the HDMI port, attach your mouse and keyboard through the USB ports, attach a network cable to the network port and finally, connect your power supply (making sure that it meets the specifications required by your RPi Module Version. Your RPi should start (power up). Later, after setup, you will need to enter your user name and password to login. The default user name: pi; password: raspberry. After login, you should see the following screen.



Congratulations! You have successfully installed the RASPBERRY PI OS operating system on your RPi.

Raspberry Pi 4B, 3B+/3B integrates a Wi-Fi adaptor. You can use it to connect to your Wi-Fi. Then you can use the wireless remote desktop to control your RPi. This will be helpful for the following work. Raspberry Pi of other models can use wireless remote desktop through accessing an external USB wireless card.



## Remote desktop & VNC

If you have logged in Raspberry Pi via display, you can skip to **VNC Viewer**.

If you don't have a spare display, mouse and keyboard for your RPi, you can use a remote desktop to share a display, keyboard, and mouse with your PC. Below is how to use:

MAC OS remote desktop and Windows OS remote desktop.

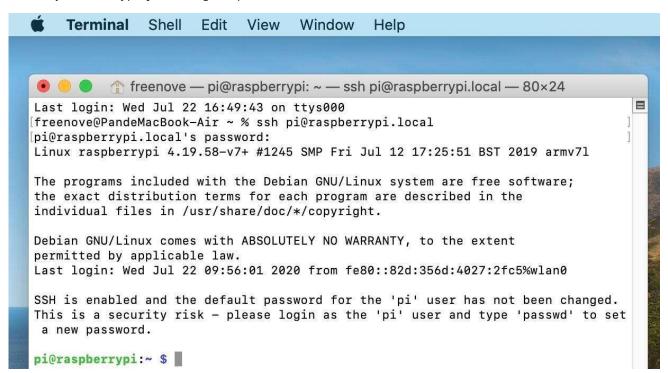
## **MAC OS Remote Desktop**

Open the terminal and type following command. If this command doesn't work, please move to next page. ssh pi@raspberrypi.local

The password is **raspberry** by default, case sensitive.



You may need to type **yes** during the process.



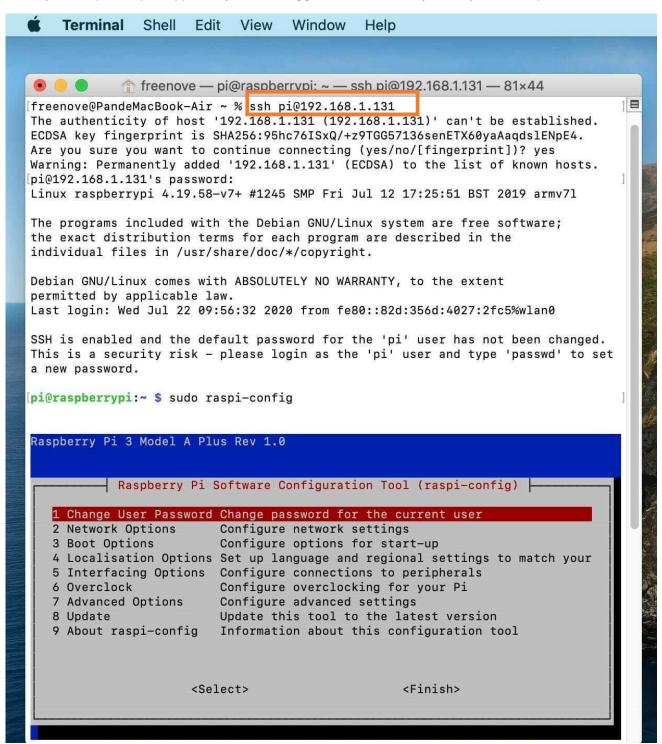
You can also use the IP address to log in Pi.

Enter **router** client to **inquiry IP address** named "raspberry pi". For example, I have inquired to **my RPi IP** address, and it is "192.168.1.131".

Open the terminal and type following command.

ssh pi@192.168.1.131

When you see pi@raspberrypi: ~ \$, you have logged in Pi successfully. Then you can skip to next section.



Then you can skip to VNC Viewer.

If you are using win10, you can use follow way to login Raspberry Pi without desktop.

Press Win+R. Enter cmd. Then use this command to check IP:

## ping -4 raspberrypi.local

```
Microsoft Windows [Version 10.0.19044.2130]
(c) Microsoft Corporation. All rights reserved.

C:\Users\Administrator>ping -4 raspberrypi.1ocal

Pinging raspberrypi.1ocal [192.168.1.147] with 32 bytes of data:
Reply from 192.168.1.147: bytes=32 time=10ms TTL=64
Reply from 192.168.1.147: bytes=32 time=4ms TTL=64
Reply from 192.168.1.147: bytes=32 time=124ms TTL=64
Reply from 192.168.1.147: bytes=32 time=7ms TTL=64

Ping statistics for 192.168.1.147

Packets: Sent = 4, Received = 4, Lost = 0 (0% loss),
Approximate round trip times in milli-seconds:
```

Minimum = 4ms, Maximum = 124ms, Average = 36ms

Then 192.168.1.147 is my Raspberry Pi IP.

Or enter router client to inquiry IP address named "raspberrypi". For example, I have inquired to my RPi IP address, and it is "192.168.1.147".

```
ssh pi@xxxxxxxxxxx(IP address)
```

Enter the following command:

```
ssh pi@192.168.1.147
```

### **VNC Viewer & VNC**

#### **Enable VNC**

Type the following command. And select Interface Options→P3 VNC → Enter→Yes→OK. Here Raspberry Pi may need be restarted, and choose ok. Then open VNC interface.

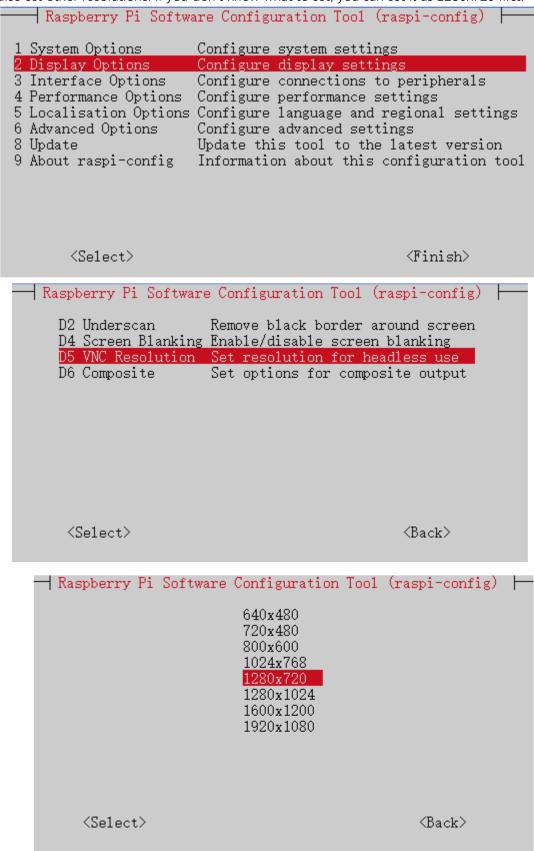
sudo raspi-config

```
— Raspberry Pi Software Configuration Tool (raspi-config)
1 System Options
                      Configure system settings
2 Display Options
                      Configure display settings
                      Configure connections to peripherals
3 Interface Options
4 Performance Options Configure performance settings
5 Localisation Options Configure language and regional settings
6 Advanced Options Configure advanced settings
8 Update
                      Update this tool to the latest version
9 About raspi-config Information about this configuration tool
             <Select>
                                          <Finish>
```

```
Raspberry Pi Software Configuration Tool (raspi-config)
Pl Camera
                                 Enable/Disable connection to the
P2 SSH
                                 Enable/Disable remote command lin
                                 Enable/Disable graphical remote a
P3 VNC
P4 SPI
                                 Enable/Disable automatic loading
P5 I2C
                                 Enable/Disable automatic loading
P6 Serial
                                 Enable/Disable shell and kernel m
P7 1-Wire
                                Enable/Disable one-wire interface
P8 Remote GPIO
                                 Enable/Disable remote access to G
                 <Select>
                                              <Back>
```

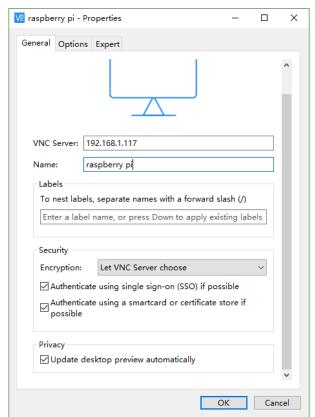
#### Set Resolution

You can also set other resolutions. If you don't know what to set, you can set it as 1280x720 first.



Then download and install VNC Viewer according to your computer system by click following link: <a href="https://www.realvnc.com/en/connect/download/viewer/">https://www.realvnc.com/en/connect/download/viewer/</a>

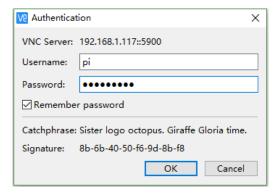
After installation is completed, open VNC Viewer. And click File → New Connection. Then the interface is shown below.



Enter ip address of your Raspberry Pi and fill in a name. Then click OK. Then on the VNC Viewer panel, double-click new connection you just created,



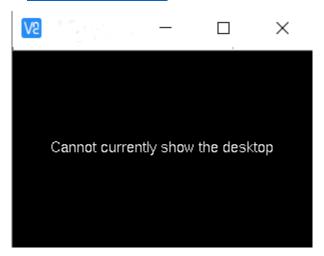
and the following dialog box pops up.



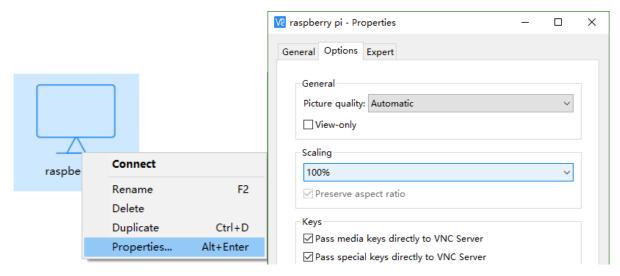
Enter username: **pi** and Password: **raspberry**. And click OK.



Here, you have logged in to Raspberry Pi successfully by using VNC Viewer. If there is black window, please **set another resolution**.



In addition, your VNC Viewer window may zoom your Raspberry Pi desktop. You can change it. On your VNC View control panel, click right key. And select Properties->Options label->Scaling. Then set proper scaling.



Here, you have logged in to Raspberry Pi successfully by using VNC Viewer and operated proper setting.

Raspberry Pi 4B/3B+/3B integrates a Wi-Fi adaptor. If you did not connect Pi to WiFi. You can connect it to wirelessly control the robot.

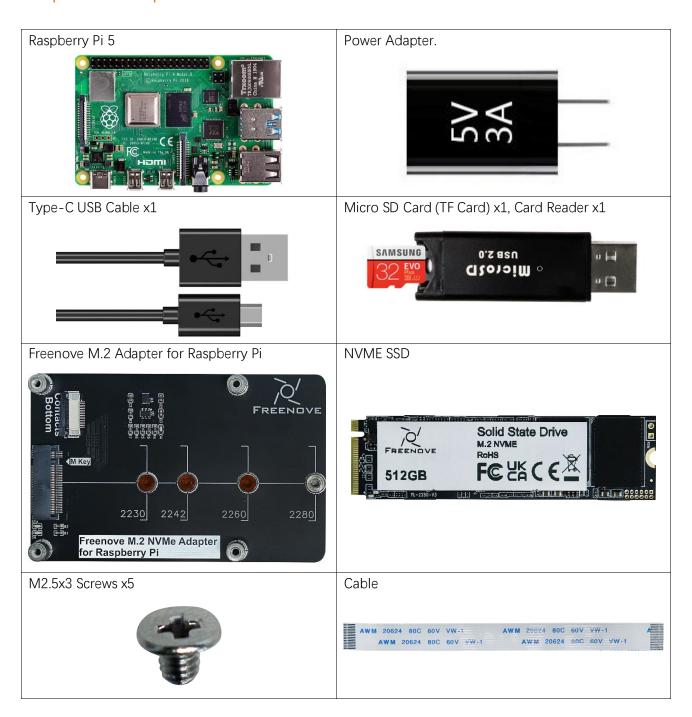


# 2. Flashing the RPi OS to NVME SSD

# 2.1 Assembly and Wiring

Mount the Freenove M.2 Adapter for Raspberry Pi and NVME SSD to your Raspberry Pi.

# **Required Components**



# Assembly and Wiring

1. Connect the FPC cable to the FPC socket. Please note that the metal contacts of the ribbon cable should face downward, as shown in the figure below.



2. Insert the SSD to the adapter board. Please tilt it to insert.





4. Connect the other end of the cable to Raspberry Pi and fix the adapter to RPi with four M2.5 screws.



## 2.2 Flashing the RPi OS to NVME SSD

Once everything is set up, power on the Raspberry Pi and boot into the system. (In this case, we are using a brand new SSD with a 512GBits capacity that has not been partitioned yet.)

#### 1. SSD Dectection

Run the following command in the Terminal to check whether SSD is detected.

### lsblk

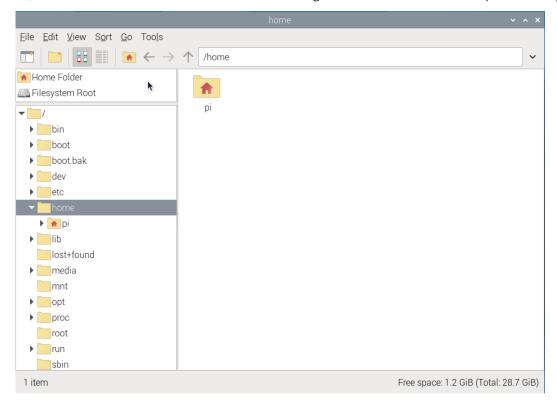
```
pi@raspberrypi:~ $ lsblk
NAME
            MAJ:MIN RM
                         SIZE RO TYPE MOUNTPOINTS
mmcblk0
            179:0
                        29.8G
                               0 disk
 -mmcblk0p1 179:1
                     0
                         512M
                               0 part /boot/firmware
 -mmcblk0p2 179:2
                     0 29.3G
                                0 part /
nvme0n1
            259:0
                     0 476.9G
                                0 disk
pi@raspberrypi:~ 💲 🗌
```

As shown in the figure above, the device `nvme0n1` with a capacity of 476.9GBytes shows up, indicating that the SSD has been correctly recognized. The detected capacity will depend on the size of your SSD. If your drive has been previously partitioned, you may also see some partition information displayed.

Please note: Installing the system will format the SSD, erasing all data. If necessary, please back up any data on your SSD before proceeding.

## 2. SSD Partitioning and Formatting

At this point, the hard drive cannot be seen in the file manager as the disk has not been partitioned yet.



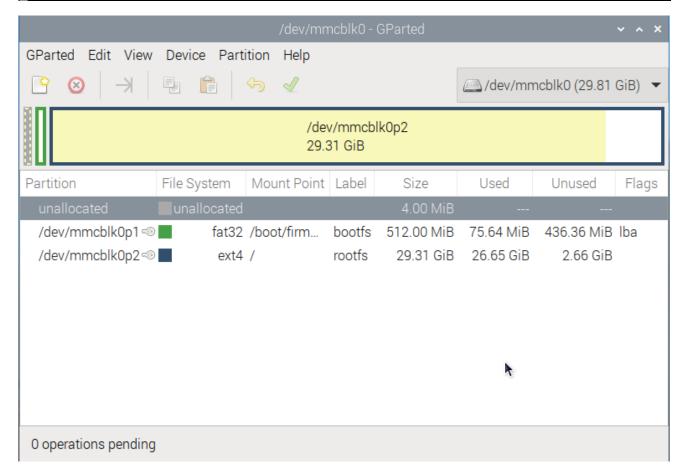
## sudo apt-get install gparted

```
The following NEW packages will be installed:
    gparted gparted-common
0 upgraded, 2 newly installed, 0 to remove and 164 not upgraded.
Need to get 772 kB/2,483 kB of archives.
After this operation, 8,638 kB of additional disk space will be used.
Do you want to continue? [Y/n] y
Get:1 http://deb.debian.org/debian bookworm/main arm64 gparted arm64 1.3.1-1 [77
2 kB]
Fetched 772 kB in 0s (2,579 kB/s)
Selecting previously unselected package gparted-common.
(Reading database ... 222757 files and directories currently installed.)
Preparing to unpack .../gparted-common_1.3.1-1_all.deb ...
Unpacking gparted-common (1.3.1-1) ...
Selecting previously unselected package gparted.
Preparing to unpack .../gparted_1.3.1-1_arm64.deb ...
Unpacking gparted (1.3.1-1) ...
Setting up gparted (3.3.1-1) ...
Setting up gparted (3.3.1-1) ...
Processing triggers for mailcap (3.70+nmu1) ...
Processing triggers for desktop-file-utils (0.26-1) ...
Processing triggers for floolor-icon-theme (0.17-2) ...
Processing triggers for man-db (2.11.2-2) ...
Processing triggers for man-db (2.11.2-2) ...
pi@raspberrypi:~ $
```

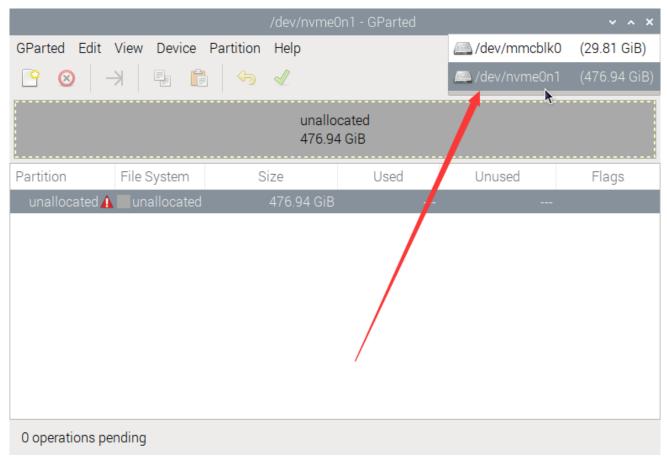
Open gparted with the command:

## sudo gparted

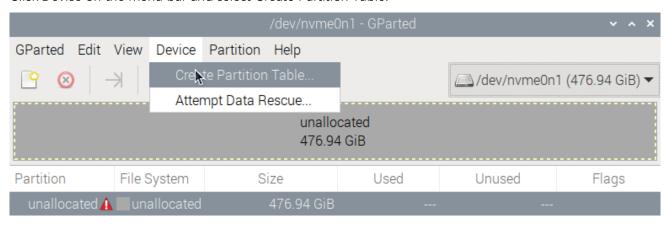
```
pi@raspberrypi:~ $ sudo gparted
error: XDG_RUNTIME_DIR is invalid or not set in the environment.
GParted 1.3.1
configuration --enable-libparted-dmraid --enable-online-resize
libparted 3.5
/dev/nvme0n1: unrecognised disk label
```



Click on the dropdown menu in the upper right corner and switch to NVME SSD.



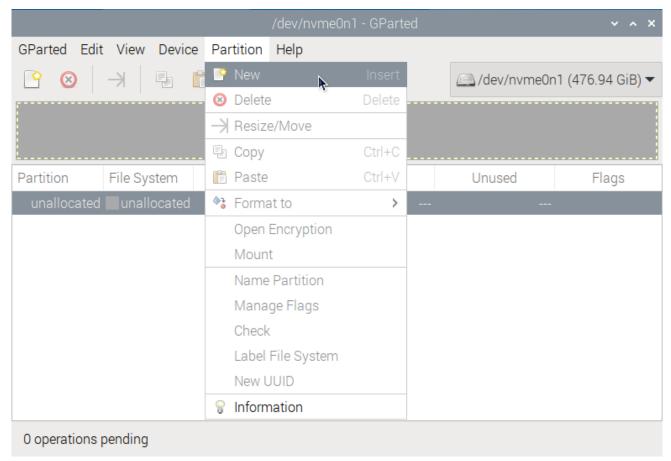
Click Device on the menu bar and select Create Partition Table.



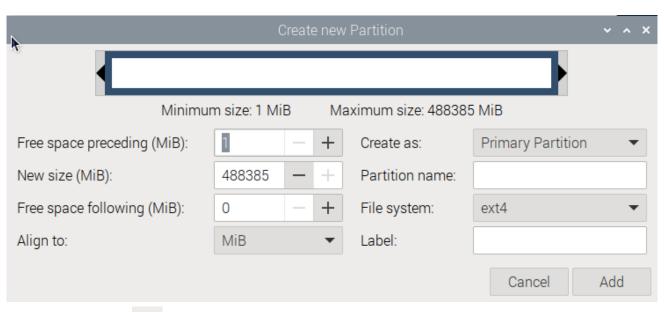
You will see the prompt that data will be erased. It is recommended to select gpt for partition table type. Click Apply.



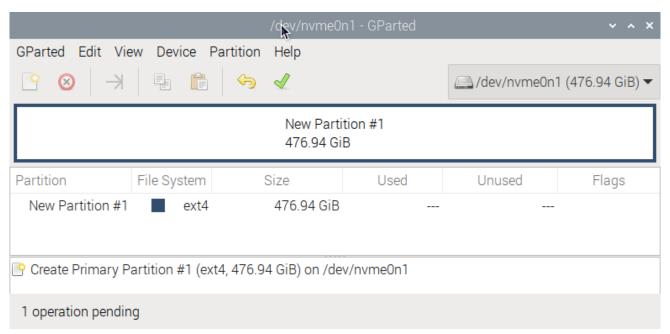
Click Partition on the menu bar, choose New.



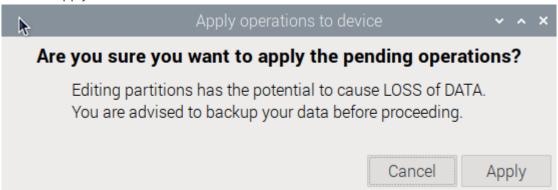
As shown in the figure below, the size of partition can be adjusted by dragging the mouse left and right, or by entering the size directly. The other options can be left as default setting. Here, we allocate all the capacity to a single partition. Click on Add.



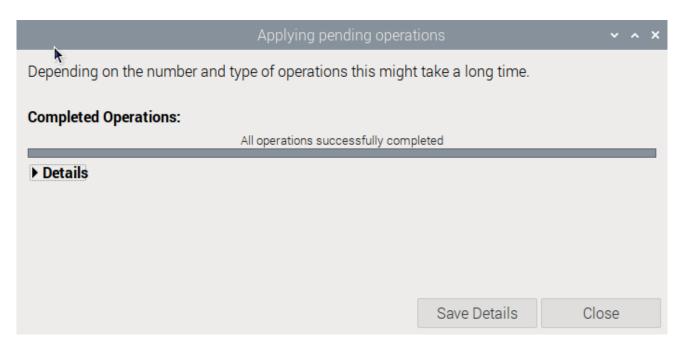
to save the partition just built, as illustrated below.



Click on Apply.



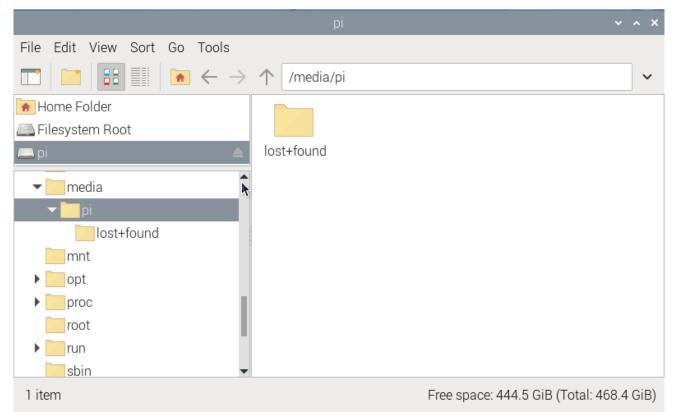
Wait for it to complete and click on Close.



At this point, you can mount the disk using the mount command and then access the disk space through the file manager. Use the following command to mount the SSD:

```
sudo mount /dev/nvme0n1p1 /media/pi
pi@raspberrypi:~ $ sudo mount /dev/nvme0n1p1 /media/pi
pi@raspberrypi:~ $
```

Open the file manager, as shown below.



If you plan to use the SSD as a standard storage device, you can conclude the process here. However, if you want to further proceed with installing an operating system on the SSD, please read on.

## 3. Flashing the OS

Install the OS to SSD with the method similar to that in the previous section on installing a system onto an SD card. This time, operate on the Raspberry Pi.

Install rpi-imager with the following command:

```
sudo apt install rpi-imager
```

```
pi@raspberrypi:~ $ sudo apt install rpi-imager
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
rpi-imager is already the newest version (1.8.5+rpt1).
0 upgraded, 0 newly installed, 0 to remove and 164 not upgraded.
pi@raspberrypi:~ $
```

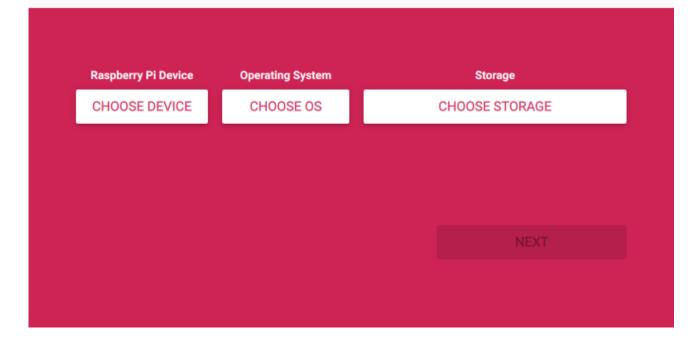
Open rpi-imager:

sudo rpi-imager

```
pi@raspberrypi:~ $ sudo rpi-imager
QStandardPaths: XDG_RUNTIME_DIR not set, defaulting to '/tmp/runtime-root'
error: XDG_RUNTIME_DIR is invalid or not set in the environment.
```

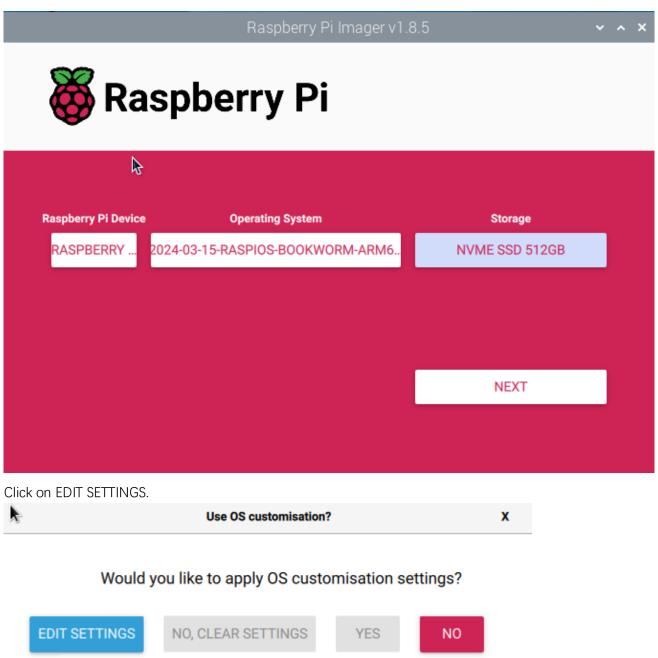




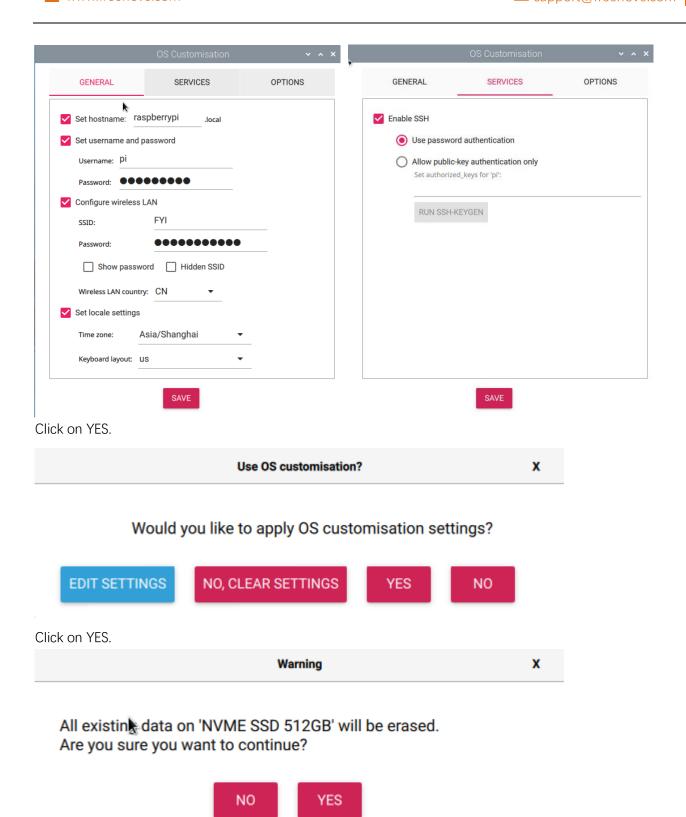


By this point, you should be quite familiar with the process.

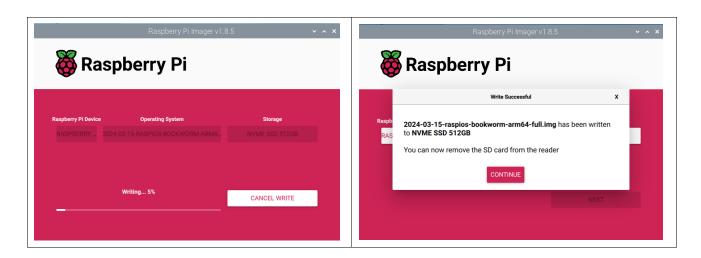
Select the Raspberry Pi 5 as your device and choose either an online download or an offline file for the operating system; in this case, an offline file is selected. (It is recommended to use a 64-bit Raspberry Pi system with recommended software). Choose your NVME SSD as the storage device. Click NEXT.



Wireless LAN Country must be correctly set; otherwise, it may fail to search the WiFi. Enable SSH and click Save.



Wait for it to finish.



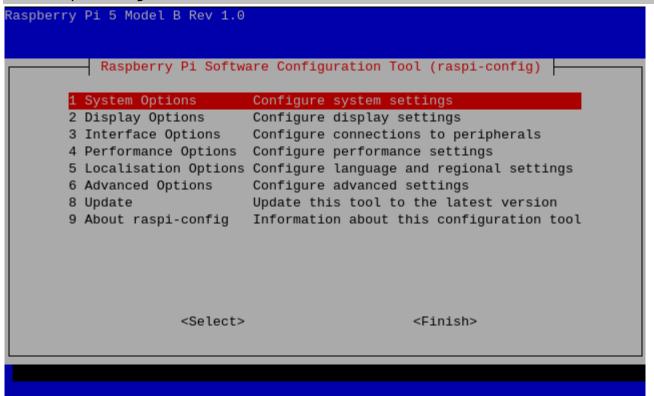
Congratulations! You have done the most tricky and the time-comsuming part. Now that you have successfully installed the operating system onto the NVMe SSD, you are very close to achieving a triumph. The subsequent step is to adjust the boot sequence on the Raspberry Pi, ensuring that it boots from the SSD by default.

# 3. RPi Boot Order Setting

# 3.1 Configuring the Boot Order

Type the following command in the Terminal.

## sudo raspi-config

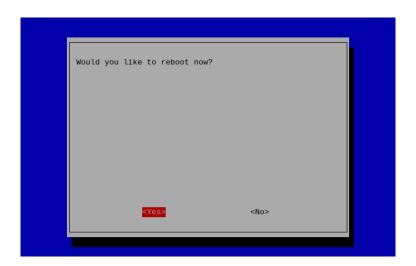


Using the keyboard's arrow keys and the Enter key, select the options in sequence.

"6 Advanced Options" →"A4 Boot Order" → "B2 NVME/USB Boot ..."



Select "OK"→"Finish"→"Yes", and reboot your Raspberry Pi.



At this point, upon restarting, the Raspberry Pi will boot from the NVME SSD. If you are using an external monitor, you will see that the Raspberry Pi has booted up correctly. If your SD card is still inserted, you will also see an icon on the desktop as shown below.

With this, the process of booting the Raspberry Pi from the NVME SSD has been fully completed.



If you use VNC viewer, you will need to repeat the previous steps to acitvate the VNC service as it is not yet enabled in the new system on the SSD. Here, we take Windows as an example.

Run the following command:

## ssh pi@raspberrypi.local

```
C:\Users\Administrator>ssh pi@raspberrypi.local
The authenticity of host 'raspberrypi.local (240e:3b4:3812:1fc0:954e:f55f:a772:fed5)' can't be established.
ECDSA key fingerprint is SHA256:hcx7u6H73nUsIc5WXA3HWa5GPSZEDroiz/mMbQx3ogc.
Are you sure you want to continue connecting (yes/no/[fingerprint])? yes
Warning: Permanently added 'raspberrypi.local,240e:3b4:3812:1fc0:954e:f55f:a772:fed5' (ECDSA) to the list of known hosts
.
pi@raspberrypi.local's password:
Linux raspberrypi 6.6.20+rpt-rpi-2712 #1 SMP PREEMPT Debian 1:6.6.20-1+rpt1 (2024-03-07) aarch64
The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.

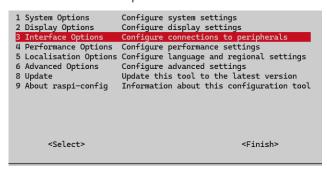
Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
Last login: Mon Jun 3 16:50:25 2024

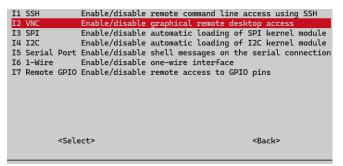
SSH is enabled and the default password for the 'pi' user has not been changed.
This is a security risk - please login as the 'pi' user and type 'passwd' to set a new password.
pi@raspberrypi:~ $
```

Once successfully ssh into Raspberry Pi, run the following command to open the configuration and enable VNC.

## sudo raspi-config

Select "3 Interface Options"→"I2 VNC"→"Yes"→"Finish".







Now you should be able to access Raspberrry Pi via VNC.

# 4. Speed Test & PCle Gen 3.0

The Raspberry Pi 5 includes a PCle x1 slot that is certified for PCle Gen 2.0, providing a theoretical maximum throughput of 5GT/sec, whichroughly translates to 500MB/sec for read and write operations. Although this slot is not officially certified for PCle Gen 3.0, it is possible to force the use of Gen 3.0 for potentially higher speeds; however, doing so may lead to system instability and freezing. It is advised to stick with Gen 2.0 for reliability.

The PCIe consortium states that the speed of PCIe Gen 3.0 x1 is up to 8GT/sec, which translates to approximately 985MB/sec; however, Raspberry Pi claims that their implementation can achieve a speed of 10GT/sec. equivalent to around 1231MB/sec.

https://en.wikipedia.org/wiki/PCI\_Express#Comparison\_table https://www.raspberrypi.com/documentation/computers/raspberry-pi.html#pcie-gen-3-0

## 4.1 Disk Speed Test

This is an additional chapter for those who wish to test the read and write speeds of their SSD.

Open the terminal and enter the following command:

## git clone https://github.com/TheRemote/PiBenchmarks

```
pi@raspberrypi:~ $ git clone https://github.com/TheRemote/PiBenchmarks
Cloning into 'PiBenchmarks'...
remote: Enumerating objects: 652, done.
remote: Counting objects: 100% (112/112), done.
remote: Compressing objects: 100% (80/80), done.
remote: Total 652 (delta 69), reused 65 (delta 31), pack-reused 540
Receiving objects: 100% (652/652), 119.41 KiB | 417.00 KiB/s, done.
Resolving deltas: 100% (386/386), done.
pi@raspberrypi:~ $
```

Enter the directory:

### cd PiBenchmarks/

Grant executable permissions to the script:

### chmod +x Storage.sh

```
pi@raspberrypi:~ $ cd PiBenchmarks/
pi@raspberrypi:~/PiBenchmarks $ ls
CODE_OF_CONDUCT.ind CONTRIBUTING.md LICENSE README.md Storage.sh
pi@raspberrypi:~/PiBenchmarks $ chmod +x Storage.sh
pi@raspberrypi:~/PiBenchmarks $
```

Start the speed test. Please be aware that the first execution will involve downloading the required dependencies, so the process could take a relatively long time.

## sudo ./Storage.sh ~/

```
pi@raspberrypi:~/PiBenchmarks $ sudo ./Storage.sh ~/
/mediap/pi/bootfs: 433.1 MiB (454152192 bytes) trimmed on /dev/mmcblk0p1
/media/pi/rootfs: 2.5 GiB (2681069568 bytes) trimmed on /dev/mmcblk0p2
/boot/firmware: 436.4 MiB (457588736 bytes) trimmed on /dev/nvme0n1p1
/: 457.4 GiB (491171225600 bytes) trimmed on /dev/nvme0n1p2
Install lshw
Hit:1 http://deb.debian.org/debian bookworm InRelease
Hit:2 http://deb.debian.org/debian-security bookworm-security InRelease
Hit:3 http://deb.debian.org/debian bookworm-updates InRelease
Hit:4 http://archive.raspberrypi.com/debian bookworm InRelease
Reading package lists... Done
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
pciutils is already the newest version (1:3.9.0-4).
            already the newest version
```

After the speed test is completed, follow the prompts to enter a description and a name for your SSD (you can use any arbitrary characters).

```
iozone test complete.
Description: ssd1
(Obtional) Enter alias to use on benchmark results. Leave blank for completely
Alias (leave blank for Anonymous): ssd1
Result submitted successfully and will appear live on https://pibenchmarks.com w
ithin a couple of minutes.
```

#### Test result:

Category	Test	Result
HDPamm	Disk Read	381.84 MB/sec
HDParm	Cached Disk Read	376.91 MB/sec
DD	Disk Write	312 MB/s
FI0	4k random read	93090 IOPS (372363 KB/s)
FI0	4k random write	70378 IOPS (281512 KB/s)
I0Zone	4k read	194074 KB/s
I0Zone	4k write	159843 KB/s
I0Zone	4k random read	55044 KB/s
I0Zone	4k random write	169735 KB/s
	Score: 36670	

The performance varies among different SSDs, and each test may also have cetain error, which is normal. The following image shows the speed test results for another SSD:

Category	Test	Result
HDParm	Disk Read	419.20 MB/sec
HDParm	Cached Disk Read	411.77 MB/sec
DD	Disk Write	253 MB/s
FI0	4k random read	105567 IOPS (422268 KB/s)
FI0	4k random write	58347 IOPS (233390 KB/s)
I0Zone	4k read	160588 KB/s
I0Zone	4k write	127044 KB/s
I0Zone	4k random read	55222 KB/s
I0Zone	4k random write	154445 KB/s
	Score: 33177	

This is a speed test result for a TF (microSD) card, and it shows a significant difference in speed compared to an SSD.

Category	Test	Result
HDParm	Disk Read	86.73 MB/sec
HDParm	Cached Disk Read	87.63 MB/sec
DD	Disk Write	13.1 MB/s
FI0	4k random read	4222 IOPS (16890 KB/s)
FI0	4k random write	191 IOPS (766 KB/s)
I0Zone	4k read	16691 KB/s
I0Zone	4k write	5123 KB/s
I0Zone	4k random read	16794 KB/s
I0Zone	4k random write	2455 KB/s
	Score: 1457	

# 4.2 PCle Gen 3.0

In the Preface, it is mentioned that the Raspberry Pi's PCle Gen 3.0 has not been officially certified. While it is functional, its performance is not as reliable as desired. This chapter is presented as an exploratory section for assessing the speed capabilities of SSDs when used with PCle Gen 3.0. For practical applications, it is advised to opt for PCle Gen 2.0 to ensure greater stability and dependability.

### EnablePCle Gen3.0

Add the line dtparam=pciex1\_gen=3 to /boot/firmware/config.txt to enable PCle Gen3.0.

As shown below, enter the command to open the file.

```
sudo nano /boot/firmware/config.txt
```

Add the line dtparam=pciex1\_gen=3 to the end of the file, as shown below:

```
GNU nano 7.2 /boot/firmware/config.txt *
otg_moder1

[all]
dtparam=pciex1_gen=3
```

Press Ctro-O to save the file, Enter to confirm, and Ctrl-X to exit.

Reboot your Raspberry Pi.

### sudo reboot

After rebooting, test the speed again.

Category		Test	Result
HDParm	Υ	Disk Read	755.51 MB/sec
HDParm	Y	Cached Disk Read	687.95 MB/sec
DD		Disk Write	487 MB/s
FI0		4k random read	93944 IOPS (375779 KB/s)
FI0		4k random write	89824 IOPS (359298 KB/s)
I0Zone		4k read	281334 KB/s
I0Zone		4k write	199418 KB/s
I0Zone		4k random read	60363 KB/s
I0Zone		4k random write	223924 KB/s
		Score: 47341	

The speed of another SSD.

Category	Test	Result
HDParm	Disk Read	804.45 MB/sec
HDParm	Cached Disk Read	670.21 MB/sec
DD	Disk Write	404 MB/s
FIO	4k random read	206868 IOPS (827474 KB/s)
FIO	4k random write	92252 IOPS (369009 KB/s)
I0Zone	4k read	224411 KB/s
I0Zone	4k write	167052 KB/s
I0Zone	4k random read	61980 KB/s
I0Zone	4k random write	190269 KB/s
	Score: 47057	

## Disable PCIe Gen3.0

Delete the line added with the previous step to disable PCIe Gen3.0.

Delete the line dtparam=pciex1\_gen=3 in the boot/firmware/config.txt file.

After the line is removed, it will change to PCle Gen2.0.

# What's Next?

THANK YOU for participating in this learning experience! If you have completed all of the projects successfully you can consider yourself a Raspberry Pi Master.

We have reached the end of this Tutorial. If you find errors, omissions or you have suggestions and/or questions about the Tutorial or component contents of this Kit, please feel free to contact us: <a href="mailto:support@freenove.com">support@freenove.com</a>

We will make every effort to make changes and correct errors as soon as feasibly possible and publish a revised version.

If you are interesting in processing, you can study the Processing.pdf in the unzipped folder.

If you want to learn more about Arduino, Raspberry Pi, Smart Cars, Robotics and other interesting products in science and technology, please continue to visit our website. We will continue to launch fun, cost-effective, innovative and exciting products.

http://www.freenove.com/

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