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- Product use and build issues
- Questions regarding the technology employed in our products for learning and education
- Your input and opinions are always welcome
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- After use, always turn the power OFF and remove or unplug the batteries before storing.

### About Freenove

Freenove provides open source electronic products and services worldwide.

Freenove is committed to assist customers in their education of robotics, programming and electronic circuits so that they may transform their creative ideas into prototypes and new and innovative products. To this end, our services include but are not limited to:

- Educational and Entertaining Project Kits for Robots, Smart Cars and Drones
- Educational Kits to Learn Robotic Software Systems for Arduino, Raspberry Pi and micro: bit
- Electronic Component Assortments, Electronic Modules and Specialized Tools
- Product Development and Customization Services

You can find more about Freenove and get our latest news and updates through our website:

http://www.freenove.com

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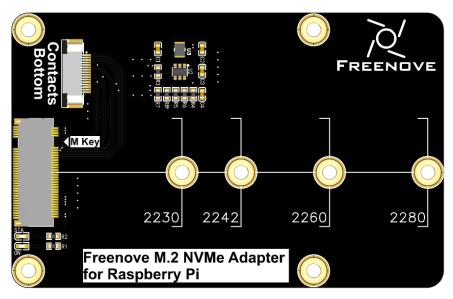
FREENOVE

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# Contents

We	elcome	
	Safety and Precautions	
	About Freenove	II
	Copyright	
Со	ontents	II
Pre	eface	1
Ov	verview	3
Ca	ution: Incompatible SSDs	4
Vic	deo Tutorial: https://youtu.be/Y3QnxM12_jo	5
1.	Flashing OS to SD Card or USB Drive	5
	Component List	5
	Optional Components	7
	Raspberry Pi OS	9
	Getting Started with Raspberry Pi	14
2.	Flashing OS to NVME SSD	23
	2.1 Assembly and Wiring	23
	2.2 Flashing the RPi OS to NVME SSD	26
3.	Booting from SSD	41
	3.1 Configuring the Boot Order	42
4.	Speed Test & PCIe Gen3.0	45
	4.1 Disk Speed Test	45
	4.2 PCle Gen 3.0	48
Wł	hat's Next?	50

### **Preface**



The Freenove M.2 NVMe Adapter for Raspberry Pi is a solid-state drives adapter designed specifically for the Raspberry Pi 5. Here are its key features:

• Interface Type: M.2 with M-Key

• Supported Protocol: NVMe

• Compatible Sizes: 2230, 2242, 2260, 2280

• **Power Supply**: 3.3V, up to 3A (maximum)

• Indicator Lights: Includes both power and SSD status LEDs.

The Raspberry Pi 5 includes a PCle x1 slot that is certified for PCle Gen 2.0, providing a theoretical maximum throughput of 5GT/sec, whichroughly translates to 500MB/sec for read and write operations. Although this slot is not officially certified for PCle Gen 3.0, it is possible to force the use of Gen 3.0 for potentially higher speeds.

The PCIe consortium states that the speed of PCIe Gen 3.0 x1 is up to 8GT/sec, which translates to approximately 985MB/sec; however, Raspberry Pi claims that their implementation can achieve a speed of 10GT/sec, equivalent to around 1231MB/sec.

https://en.wikipedia.org/wiki/PCI\_Express#Comparison\_table

https://www.raspberrypi.com/documentation/computers/raspberry-pi.html#pcie-gen-3-0

SSDs generally provide significantly faster read and write speeds compared to SD cards and USB drives, which can notably elevate the user experience when operating the Raspberry Pi 5.

Welcome to the Freenove M.2 NVMe Adapter for Raspberry Pi. This guide will walk you through the steps to effectively integrate and utilize this adapter on your Raspberry Pi 5.

Additionally, if you encounter any issues or have questions about this tutorial or the contents of kit, you can

support@freenove.com

always contact us for free technical support at:

# support@freenove.com

# Overview

To boot Raspberry Pi 5 from an NVMe SSD, two core tasks need to be accomplished:

- 1. Flash the Raspberry Pi's operating system image onto the NVMe SSD.
- 2. Configure the boot order of Raspberry Pi to give priority to SSD. (Optional)

#### **Analysis**

- First of all, make sure you can enter the Raspberry Pi os via SD card or U drive.
- After booting the Raspberry Pi, you can use it to flash the OS image directly onto the NVMe SSD. Alternatively, you can purchase an NVMe SSD to USB adapter and flash the image using USB on Windows or macOS, much like you would for an SD card or USB drive.
- With this analysis in mind, we can systematically carry out the necessary steps.

Raspberry Pi models manufactured at different times might not boot up in the same way as described, but that's okay; just follow our guide to proceed.

There are various ways to burn the Raspberry Pi OS to SSD, each requiring different hardware tools.

Ways	Ways of burning	Requirements
1	Use Raspberry Pi to burn the OS. This requires that you can successfully boot up the Raspberry Pi via SD card or U disk. (Recommended, described in this tutorial)	An SD card or a U disk that can access the Raspberry Pi OS.
2	Purchase an NVMe SSD to USB adapter and flash the image	NVME SSD to USB adapter (need
	just like you would with an SD card or USB drive.	to be bought separately)
3	If there are spare M.2 NVME interface on the motherboard of	PC with M.2 NVME interface
J	your PC, you can insert the SSD to it to flash the OS.	F C WITH IVI.2 INVIVIL IIITETIACE

# Caution: Incompatible SSDs

The recognition and reading/writing of the NVME SSD are handled by the drivers of the Raspberry Pi 5. The Freenove M.2 NVMe Adapter for Raspberry Pi (hereinafter referred to as the Adapter) serves to connect and power the SSD. If you find that your SSD is not recognized or readable/writeable by the Pi 5, please try to find the drivers suitable for your SSD and install them on the Raspberry Pi, or replace the SSD, or purchase our Adapter kit that comes with an SSD.

Currently, some SSDs are found incompatible, as shown below: <a href="https://docs.pineberrypi.com/nvme-compatibility-list">https://docs.pineberrypi.com/nvme-compatibility-list</a>

#### Not compatible drives

WD SN530 has been problematic for some users when it comes to NVMe boot, especially in the 2242 variant. Our test drive was a 2280 SKU and it worked OK but we generally recommend staying away from Western Digital drives completely.

- WD SN740
- WD SN350
- WD SN770
- WD SN850 possibly
- · Transcend TSXXXGMTE300S (submitted by our community)

However, with the update of Raspberry Pi drivers, the incompatible SSDs listed above may become compatible one day.

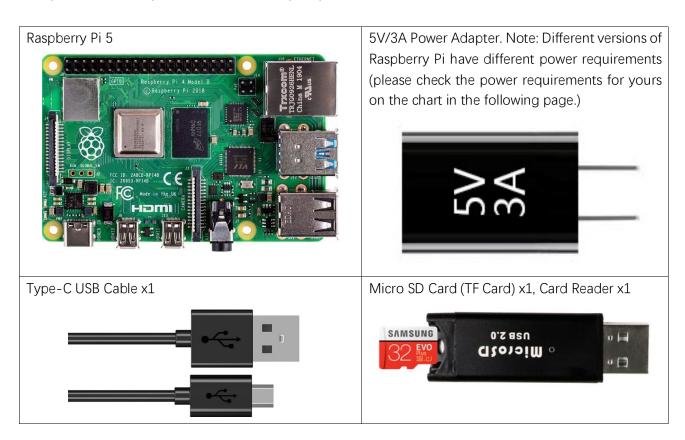
# Video Tutorial: <a href="https://youtu.be/JTJghC\_3c04">https://youtu.be/JTJghC\_3c04</a>

# 1. Flashing OS to SD Card or USB Drive

Based on the analysis above, our first step should be to install the Raspberry Pi operating system onto an SD card or USB drive, with a capacity of at least 16GB. If you are already able to boot the Raspberry Pi using an SD card or USB drive, you can skip this section and move on to the next chapter.

### Component List

### Required Components (self-prepared)



Power requirements of various versions of Raspberry Pi are shown in following table:

Product	Recommended PSU current capacity	Maximum total USB peripheral current draw	Typical bare-board active current consumption
Raspberry Pi Model A	700mA	500mA	200mA
Raspberry Pi Model B	1.2A	500mA	500mA
Raspberry Pi Model A+	700mA	500mA	180mA
Raspberry Pi Model B+	1.8A	600mA/1.2A (switchable)	330mA
Raspberry Pi 2 Model B	1.8A	600mA/1.2A (switchable)	350mA
Raspberry Pi 3 Model B	2.5A	1.2A	400mA
Raspberry Pi 3 Model A+	2.5A	Limited by PSU, board, and connector ratings only.	350mA
Raspberry Pi 3 Model B+	2.5A	1.2A	500mA
Raspberry Pi 4 Model B	3.0A	1.2A	600mA
Raspberry Pi 5 Model B	5.0A	1.6A (600mA if using a 3A power supply)	800mA
Raspberry Pi Zero W	1.2A	Limited by PSU, board, and connector ratings only.	150mA
Raspberry Pi Zero	1.2A	Limited by PSU, board, and connector ratings only	100mA

For more details, please refer to

https://www.raspberrypi.com/documentation/computers/raspberry-pi.html#power-supply

In addition, RPi also needs an Ethernet network cable used to connect it to a WAN (Wide Area Network).

All these components are necessary for any of your projects to work. Among them, the power supply of at least 5V/2.5A, because a lack of a sufficient power supply may lead to many functional issues and even damage your RPi, we STRONGLY RECOMMEND a 5V/2.5A power supply. We also recommend using a SD Micro Card with a capacity of 16GB or more (which, functions as the RPI's "hard drive") and is used to store the operating system and necessary operational files.

## **Optional Components**

Under normal circumstances, there are two ways to login to Raspberry Pi: 1) Using a stand-alone monitor. 2) Using a remote desktop or laptop computer monitor "sharing" the PC monitor with your RPi.

### Required Accessories for Monitor

If you choose to use an independent monitor, mouse and keyboard, you also need the following accessories:

- 1. A display with a HDMI interface
- 2. A Mouse and a Keyboard with an USB interface

As to Pi Zero and Pi Zero W, you also need the following accessories:

- 1. A Mini-HDMI to HDMI Adapter and Cable.
- 2. A Micro-USB to USB-A Adapter and Cable (Micro USB OTG Cable).
- 3. A USB HUB.
- 4. USB to Ethernet Interface or USB Wi-Fi receiver.

For different Raspberry Pi Modules, the optional items may vary slightly but they all aim to convert the interfaces to Raspberry Pi standards.

	Pi Zero	Pi A+	Pi Zero W	Pi 3A+	Pi B+/2B	Pi 3B/3B+	Pi 4B/5B
Monitor	Yes (AII)						
Mouse	Yes (All)						
Keyboard	Yes (All)						
Micro-HDMI to HDMI Adapter & Cable	Yes	No	Yes	No	No	No	No
Micro-HDMI to HDMI Adapter & Cable	No Yes						
Micro-USB to USB-A Adapter & Cable (Micro USB OTG Cable)	Yes	No	Yes	s No			
USB HUB	Yes	Yes	Yes	Yes	No	No	
USB to Ethernet select one from two or select two		optional		Internal Integration	Internal Integration		
USB Wi-Fi Receiver	from	two	Internal Integration		optional		

# Required Accessories for Remote Desktop

If you do not have an independent monitor, or if you want to use a remote desktop, you first need to login to Raspberry Pi through SSH, and then open the VNC or RDP service. This requires the following accessories.

	Pi Zero	Pi Zero W	Pi A+	Pi 3A+	Pi B+/2B	Pi 3B/3B+/4B/5B
Micro-USB to USB-A Adapter & Cable (Micro USB OTG Cable)	Yes	Yes	No		NO	
USB to Ethernet interface	Yes	Yes	Yes			

### Raspberry Pi OS

Without Screen - Use Raspberry Pi - under Windows PC: <a href="https://youtu.be/XpiT\_ezb\_7c">https://youtu.be/XpiT\_ezb\_7c</a> With Screen - Use Raspberry Pi - under Windows PC: https://youtu.be/HEywFsFrj3I

### **Automatically Method**

You can follow the official method to install the system for raspberry pi via visiting link below: https://projects.raspberrypi.org/en/projects/raspberry-pi-setting-up/2

In this way, the system will be downloaded automatically via the application.

### Manually Method

After installing the Imager Tool in the link above. You can also download the system manually first.

Visit https://www.raspberrypi.com/software/operating-systems/

### Operating system images

Many operating systems are available for Raspberry Pi, including Raspberry Pi OS, our official supported operating system, and operating systems from other organisations.

Raspberry Pi Imager is the quick and easy way to install an operating system to a microSD card ready to use with your Raspberry Pi. Alternatively, choose from the operating systems below, available to download and install manually.

Download: Raspberry Pi OS Raspberry Pi OS (64-bit) Raspberry Pi OS (Legacy) Raspberry Pi OS (Legacy, 64-Raspberry Pi Desktop

#### Raspberry Pi OS

Our recommended operating system for most users.

Compatible with:

All Raspberry Pi models

#### Raspberry Pi OS with desktop

Release date: March 15th 2024 System: 32-bit Kernel version: 6.6 Debian version: 12 (bookworm) Show SHA256 file integrity hash:

**Download** Download torrent

#### Raspberry Pi OS with desktop and recommended software

Release date: March 15th 2024 System: 32-bit Kernel version: 6.6 Debian version: 12 (bookworm) Size: 2,678MB Show SHA256 file integrity hash: Release notes

**Download** Download torrent

Archive

And then the zip file is downloaded.

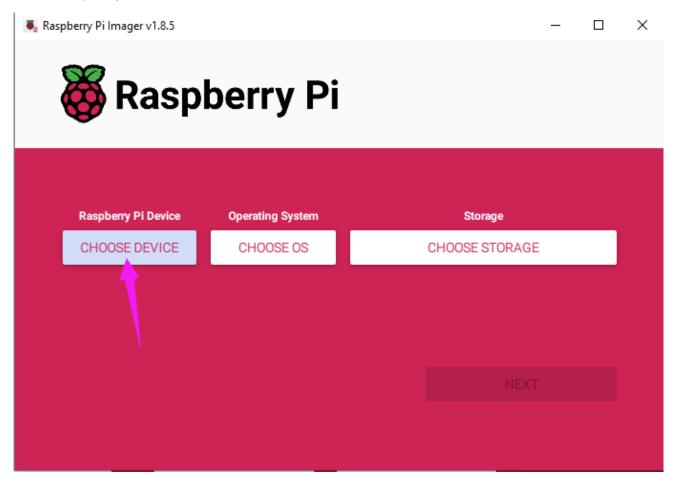
### Write System to Micro SD Card

First, put your Micro **SD card** into card reader and connect it to USB port of PC.

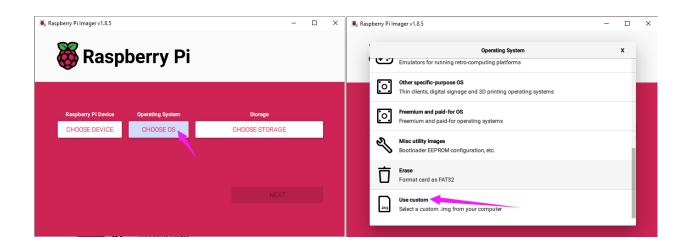


Open Raspberry Pi Imager.

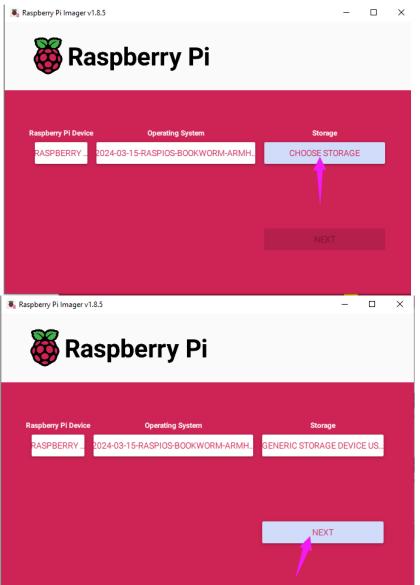
Choose Raspberry Pi 5 as the device.



Choose the system that you just downloaded in Use custom.



Choose the SD card and click on Next.

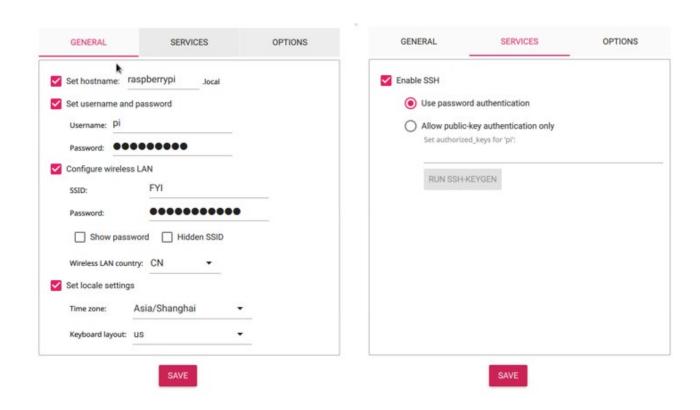


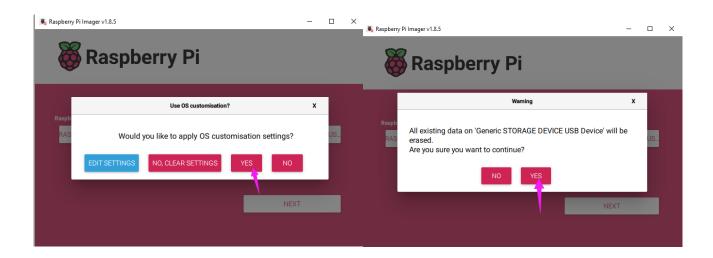
# Enable ssh and configure WiFi

### Click EDIT SETTINGS.



Configure wireless LAN, enable SSH and click Save.

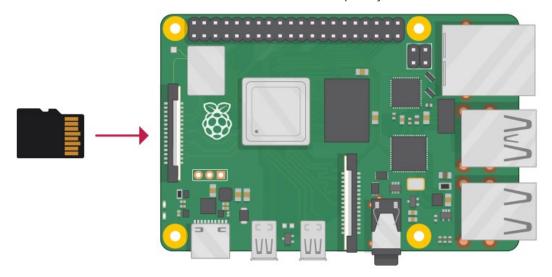




Wait for it to finish writing and verifying.

### Insert SD card

Then remove SD card from card reader and insert it into Raspberry Pi.



### Getting Started with Raspberry Pi

### Monitor desktop

If you do not have a spare monitor, please skip to next section Remote desktop & VNC. If you have a spare monitor, please follow the steps in this section.

After the system is written successfully, take out Micro SD Card and put it into the SD card slot of RPi. Then connect your RPi to the monitor through the HDMI port, attach your mouse and keyboard through the USB ports, attach a network cable to the network port and finally, connect your power supply (making sure that it meets the specifications required by your RPi Module Version. Your RPi should start (power up). Later, after setup, you will need to enter your user name and password to login. The default user name: pi; password: raspberry. After login, you should see the following screen.



Congratulations! You have successfully installed the RASPBERRY PI OS operating system on your RPi.

Raspberry Pi 4B, 3B+/3B integrates a Wi-Fi adaptor. You can use it to connect to your Wi-Fi. Then you can use the wireless remote desktop to control your RPi. This will be helpful for the following work. Raspberry Pi of other models can use wireless remote desktop through accessing an external USB wireless card.



### Remote desktop & VNC

#### If you have logged in Raspberry Pi via display, you can skip to **VNC Viewer**.

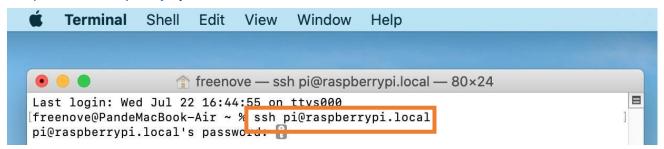
If you don't have a spare display, mouse and keyboard for your RPi, you can use a remote desktop to share a display, keyboard, and mouse with your PC. Below is how to use:

MAC OS remote desktop and Windows OS remote desktop.

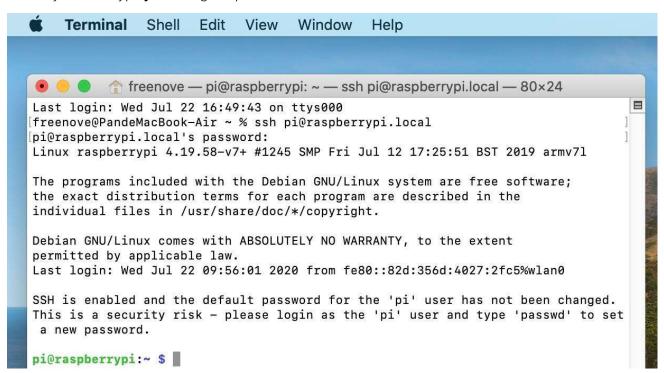
#### MAC OS Remote Desktop

Open the terminal and type following command. If this command doesn't work, please move to next page. ssh pi@raspberrypi.local

The password is **raspberry** by default, case sensitive.



You may need to type **yes** during the process.

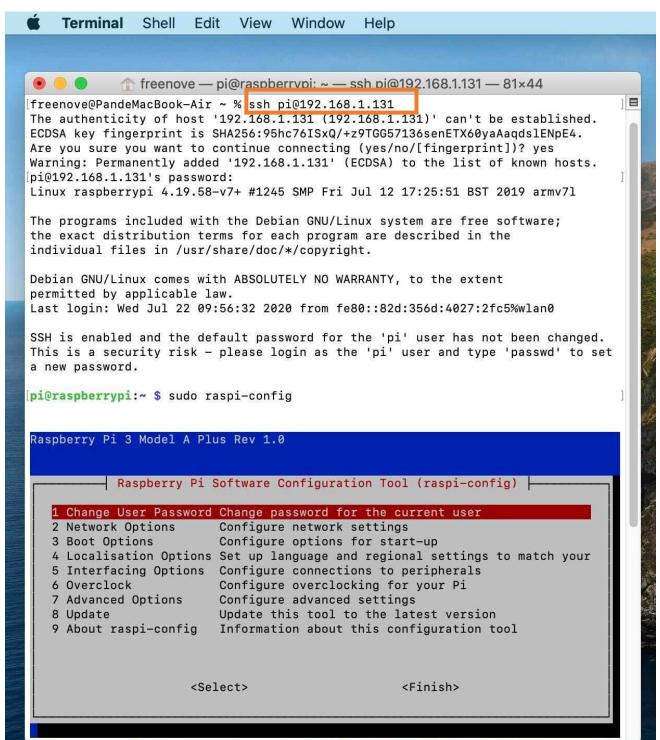


Enter router client to inquiry IP address named "raspberry pi". For example, I have inquired to my RPi IP address, and it is "192.168.1.131".

Open the terminal and type following command.

ssh pi@192.168.1.131

When you see pi@raspberrypi:~ \$, you have logged in Pi successfully. Then you can skip to next section.



Then you can skip to VNC Viewer.

#### Windows OS Remote Desktop

If you are using win10, you can use follow way to login Raspberry Pi without desktop.

Press Win+R. Enter cmd. Then use this command to check IP:

#### ping -4 raspberrypi.local

```
Command Prompt
Microsoft Windows [Version 10.0.19044.2130]
(c) Microsoft Corporation. All rights reserved.
C:\Users\Administrator>ping -4 raspberrypi.local
Pinging raspberrypi.local [192.168.1.147] with 32 bytes of data:
Reply from 192.168.1.147: bytes=32 time=10ms TTL=64
Reply from 192.168.1.147: bytes=32 time=4ms TTL=64
Reply from <u>192.168.1.147:</u> bytes=32 time=124ms TTL=64
Reply from 192.168.1.147 bytes=32 time=7ms TTL=64
Ping statistics for 192.168.1.147:
Packets: Sent = 4, Received = 4, Lost = 0 (0% loss),
Approximate round trip times in milli-seconds:
    Minimum = 4ms, Maximum = 124ms, Average = 36ms
```

Then 192.168.1.147 is my Raspberry Pi IP.

Or enter router client to inquiry IP address named "raspberrypi". For example, I have inquired to my RPi IP address, and it is "192.168.1.147".

#### ssh pi@xxxxxxxxxxx(IP address)

Enter the following command:

### ssh pi@192.168.1.147

```
C:\Users\Administrator>ssh pi@192.168.1.147
pi@192.168.1.147's password:
Linux raspberrypi 5.15.74-v7+ #1595 SMP Wed Oct 26 11:03:05 BST 2022 armv71
The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.
Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable 1aw.
Last login: Mon Nov 7 10:19:19 2022 from 192.168.1.127
SSH is enabled and the default password for the 'pi' user has not been changed.
This is a security risk - please login as the 'pi' user and type 'passwd' to set a new password.
```

#### **Enable VNC**

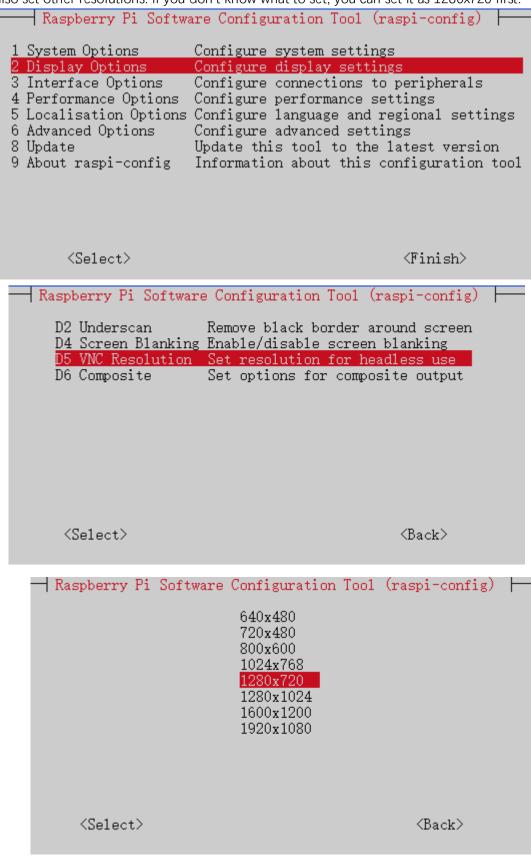
Type the following command. And select Interface Options→P3 VNC → Enter→Yes→OK. Here Raspberry Pi may need be restarted, and choose ok. Then open VNC interface.

sudo raspi-config

```
Raspberry Pi Software Configuration Tool (raspi-config)
Pl Camera
                                 Enable/Disable connection to the
P2 SSH
                                 Enable/Disable remote command lin
                                 Enable/Disable graphical remote a
P3 VNC
P4 SPI
                                 Enable/Disable automatic loading
P5 I2C
                                Enable/Disable automatic loading
P6 Serial
                                Enable/Disable shell and kernel m
P7 1-Wire
                                Enable/Disable one-wire interface
P8 Remote GPIO
                                Enable/Disable remote access to G
                 <Select>
                                              <Back>
```

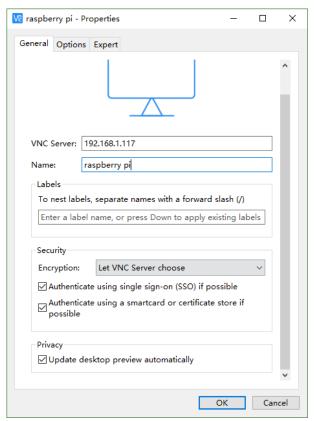
#### Set Resolution

You can also set other resolutions. If you don't know what to set, you can set it as 1280x720 first.



Then download and install VNC Viewer according to your computer system by click following link: https://www.realvnc.com/en/connect/download/viewer/

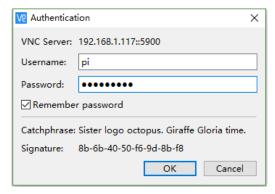
After installation is completed, open VNC Viewer. And click File  $\rightarrow$  New Connection. Then the interface is shown below.



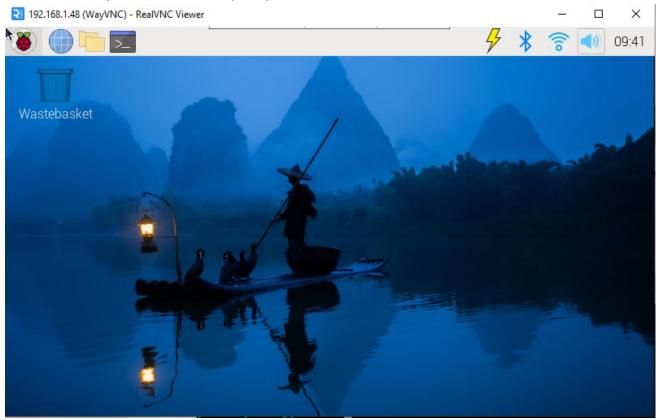
Enter ip address of your Raspberry Pi and fill in a name. Then click OK. Then on the VNC Viewer panel, double-click new connection you just created,



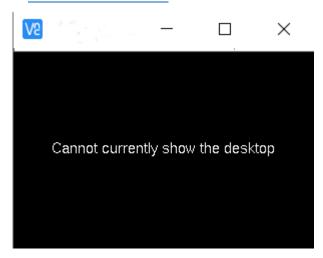
and the following dialog box pops up.



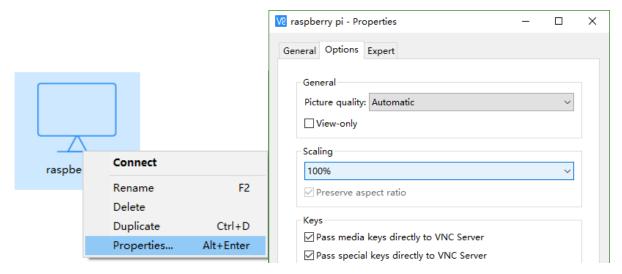
Enter username: pi and Password: raspberry. And click OK.



Here, you have logged in to Raspberry Pi successfully by using VNC Viewer. If there is black window, please set another resolution.



In addition, your VNC Viewer window may zoom your Raspberry Pi desktop. You can change it. On your VNC View control panel, click right key. And select Properties->Options label->Scaling. Then set proper scaling.



Here, you have logged in to Raspberry Pi successfully by using VNC Viewer and operated proper setting.

Raspberry Pi 4B/3B+/3B integrates a Wi-Fi adaptor. If you did not connect Pi to WiFi. You can connect it to wirelessly control the robot.

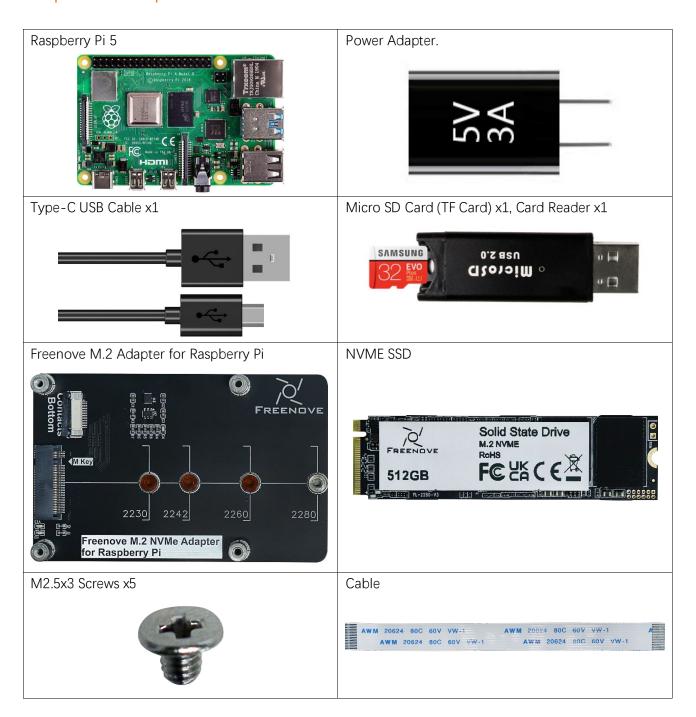


# 2. Flashing OS to NVME SSD

## 2.1 Assembly and Wiring

Assemble the Freenove M.2 Adapter for Raspberry Pi and NVME SSD to your Raspberry Pi.

### **Required Components**



## Assembly and Wiring

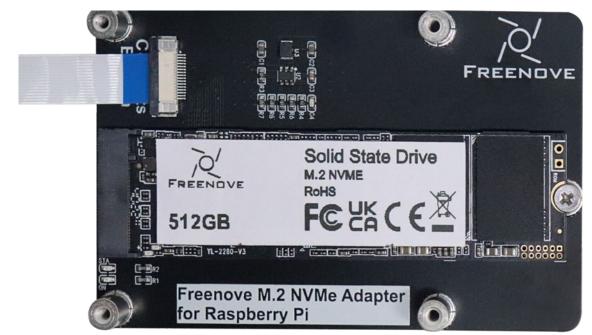
1. Connect the FPC cable to the FPC socket. Please note that the metal contacts of the ribbon cable should face downward, as shown in the figure below.



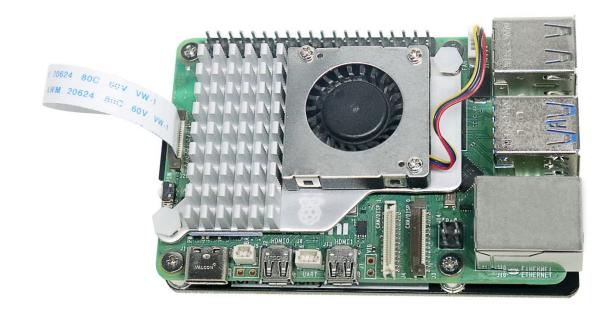
2. Insert the SSD to the adapter board. Please tilt it to insert.



3. Fix the SSD with a M2.5 screw..



4. Connect the other end of the cable to Raspberry Pi and fix the adapter to RPi with four M2.5 screws.



Once everything is set up, power on the Raspberry Pi and boot into the system. (In this case, we are using a brand new SSD with a 512GBits capacity that has not been partitioned yet.)

### 2.2.1 SSD Dectection

### ( Note: Not all SSDs are supported by Pi5. )

Run the following command in the Terminal to check whether SSD is detected.

Note that different SSDs display different content.

#### lspci

```
pi@raspberrypi:~ $ lspci
0000:00:00.0 PCI bridge: Broadcom Inc. and subsidiaries Device 2712 (rev 21)
0000:01:00.0 Non-Volatile memory controller: Silicon Motion, Inc. SM2263EN/SM2263XT SSD Controller (rev 03)
0001:00:00.0 PCI bridge: Broadcom Inc. and subsidiaries Device 2712 (rev 21)
0001:01:00.0 Ethernet controller: Device 1de4:0001
```

#### lsblk

```
pi@raspberrypi:~ $ lsblk
NAME
            MAJ:MIN RM
                          SIZE RO TYPE MOUNTPOINTS
mmcblk0
            179:0
                        29.8G
                     Θ
                               0 disk
 -mmcblk0p1 179:1
                     Θ
                          512M
                               0 part /boot/firmware
 -mmcblk0p2 179:2
                       29.3G
                     Θ
                                0 part /
nvme0n1
            259:0
                     0 476.9G
                                0 disk
pi@raspberrypi:~ 💲 📗
```

As shown in the figure above, the device 'nvme0n1' with a capacity of 476.9GBytes shows up, indicating that the SSD has been correctly recognized. The detected capacity will depend on the size of your SSD. If your drive has been previously partitioned, you may also see some partition information displayed.

Please note: Installing the system will format the SSD, erasing all data. If necessary, please back up any data on your SSD before proceeding.

### 2.2.2 Enable PCIE3.0 (on OS written into SD card)

If the SSD you received is with Phison controller, you may need to enable PCIE 3.0 .(This step is strongly recommended; without this step, the later process may fail.)

If it is not with Phison controller, you do not need to enable PCIE 3.0. You may skip this section.

Run the command **lspci** to check the controller.

```
pi@raspberrypi:~ $ lspci
0000:00:00.0 PCI bridge: Broadcom Inc. and subsidiaries BCM2712 PCIe Bridge (rev 21)
0000:01:00.0 Non-Volatile memory controller: Phison Electronics Corporation PS5021-E21
PCIe4 NVMe Controller (DRAM-less) (rev 01)
0001:00:00.0 PCI bridge: Broadcom Inc. and subsidiaries BCM2712 PCIe Bridge (rev 21)
0001:01:00.0 Ethernet controller: Raspberry Pi Ltd RP1 PCIe 2.0 South Bridge
```

(The above screenshot is the result of an 128GB SSD with Phison as main controller.)

#### Enable PCIe Gen3.0

Add the line dtparam=pciex1\_gen=3 to /boot/firmware/config.txt to enable PCle Gen3.0.

As shown below, enter the command to open the file.

```
sudo nano /boot/firmware/config.txt
```

Add the line dtparam=pciex1\_gen=3 to the end of the file, as shown below:

```
GNU nano 7.2
                              /boot/firmware/config.txt *
otg_mode∤1
[all]
dtparam=pciex1_gen=3
```

Press Ctrl-O to save the file, Enter to confirm, and Ctrl-X to exit.

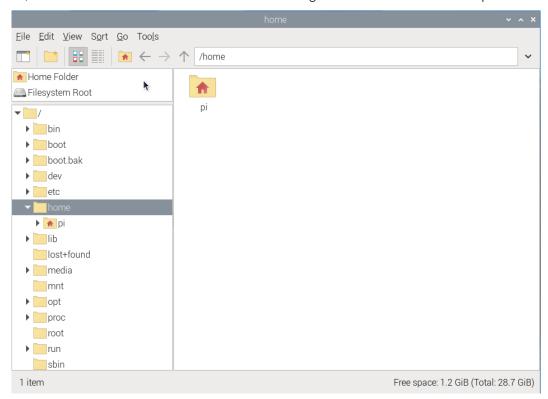
Reboot your Raspberry Pi.

sudo reboot

## 2.2.3 SSD Partitioning and Formatting

This step is not a must-do, but it can further test whether the SSD perform normally on Raspberry Pi to ensure smooth performance in later steps.

At this point, the hard drive cannot be seen in the file manager as the disk has not been partitioned yet.



Install a disk management tool with the following command:

### sudo apt-get install gparted

```
The following NEW packages will be installed:
    gparted gparted-common

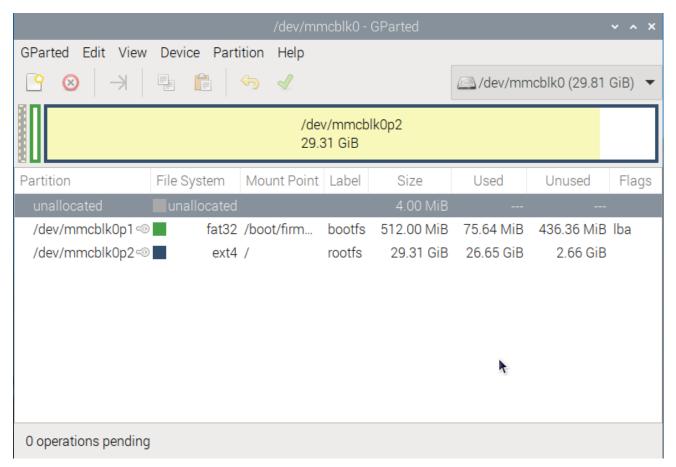
0 upgraded, 2 newly installed, 0 to remove and 164 not upgraded.
Need to get 772 kB/2,483 kB of archives.
After this operation, 8,638 kB of archives.
After this operation, 8,638 kB of additional disk space will be used.
Do you want to continue? [Y/n] y
Get:1 http://deb.debian.org/debian bookworm/main arm64 gparted arm64 1.3.1-1 [77
2 kB]
Fetched 772 kB in 0s (2,579 kB/s)
Selecting previously unselected package gparted-common.
(Reading database ... 222757 files and directories currently installed.)
Preparing to unpack .../gparted-common_1.3.1-1_all.deb ...
Unpacking gparted-common (1.3.1-1) ...
Selecting previously unselected package gparted.
Preparing to unpack .../gparted_1.3.1-1_arm64.deb ...
Unpacking gparted (1.3.1-1) ...
Setting up gparted-common (1.3.1-1) ...
Frocessing triggers for mailcap (3.70+nmu1) ...
Processing triggers for desktop-file-utils (0.26-1) ...
Processing triggers for desktop-file-utils (0.26-1) ...
Processing triggers for man-db (2.11.2-2) ...
pi@raspberrypi:~ $
```

Open gparted with the command:

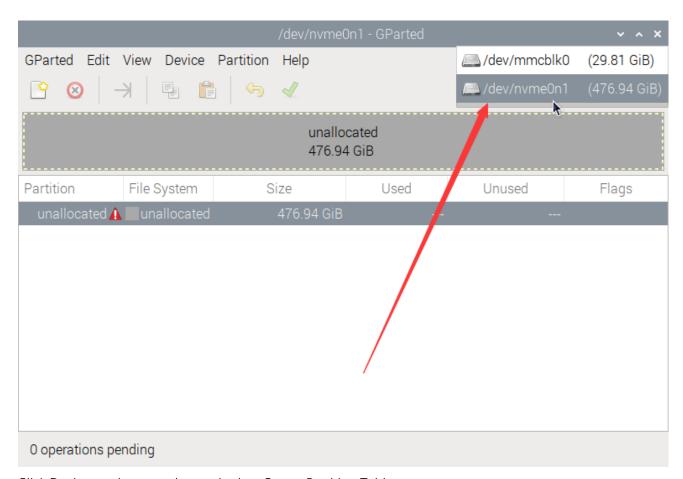
### sudo gparted



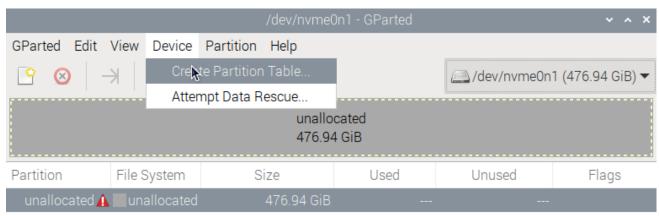
```
pi@raspberrypi:~ $ sudo gparted
error: XDG_RUNTIME_DIR is invalid or not set in the environment.
GParted 1.3.1
configuration --enable-libparted-dmraid --enable-online-resize
libparted 3.5
/dev/nvme0n1: unrecognised disk label
```



Click on the dropdown menu in the upper right corner and switch to NVME SSD.



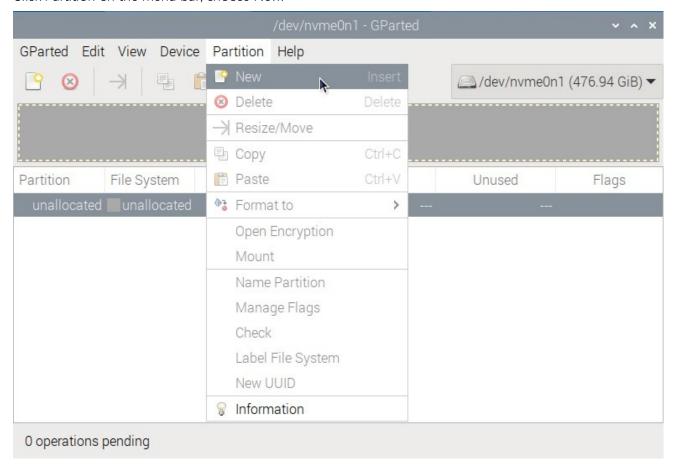
Click Device on the menu bar and select Create Partition Table.



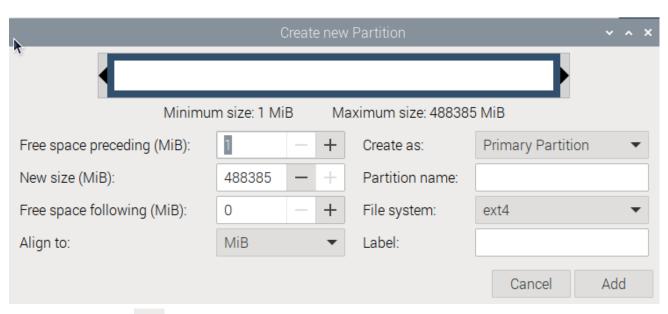
You will see the prompt that data will be erased. It is recommended to select gpt for partition table type. Click Apply.



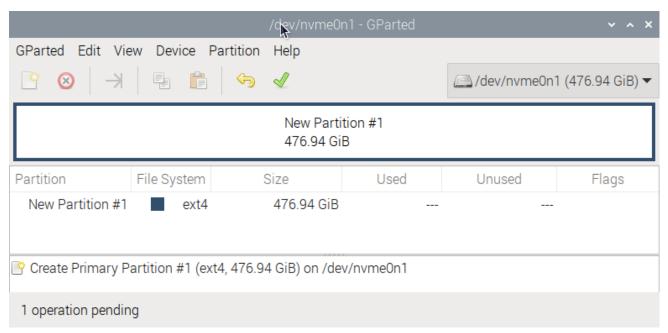
Click Partition on the menu bar, choose New.



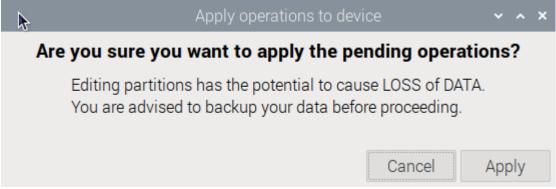
As shown in the figure below, the size of partition can be adjusted by dragging the mouse left and right, or by entering the size directly. The other options can be left as default setting. Here, we allocate all the capacity to a single partition. Click on Add.



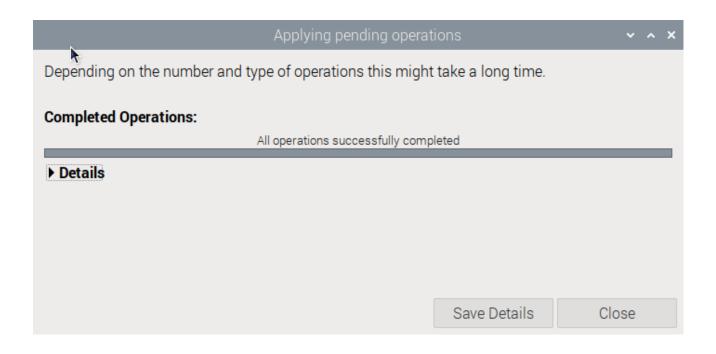
Click the check icon to save the partition just built, as illustrated below.



Click on Apply.



Wait for it to complete and click on Close.

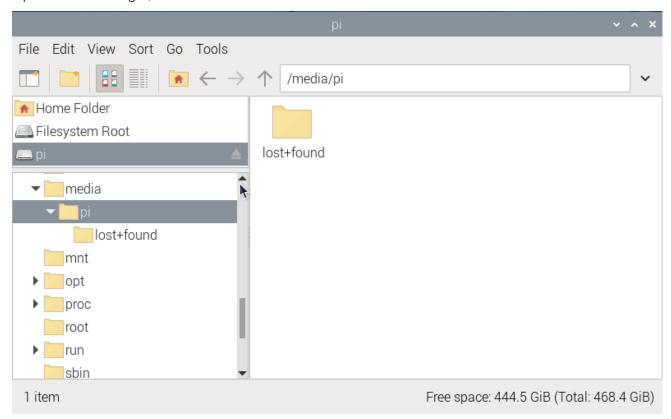


At this point, you can mount the disk using the mount command and then access the disk space through the file manager. Use the following command to mount the SSD:

```
mkdir pi
sudo mount /dev/nvme0n1p1 /media/pi

pi@raspberrypi:~ $ mkdir pi
pi@raspberrypi:~ $ sudo mount /dev/nvme0n1p1 /media/pi
```

Open the file manager, as shown below.



If you plan to use the SSD as a standard storage device, you can conclude the process here. However, if you want to further proceed with installing an operating system on the SSD, please read on.

### 2.2.4 Flashing the OS

Install the OS to SSD with the method similar to that in the previous section on installing a system onto an SD card. This time, operate on the Raspberry Pi.

Install rpi-imager with the following command:

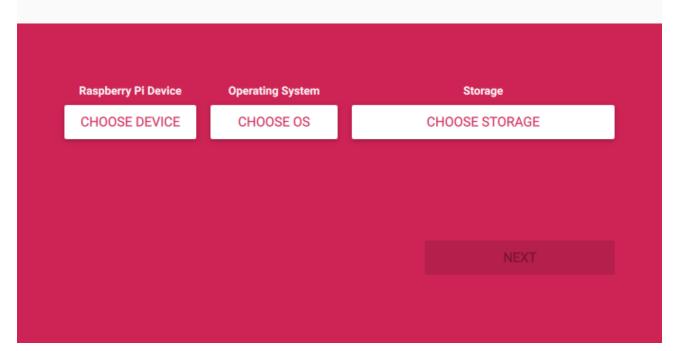
```
sudo apt install rpi-imager
pi@raspberrypi:~ $ sudo apt install rpi-imager
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
rpi-imager is already the newest version (1.8.5+rpt1).
0 upgraded, 0 newly installed, 0 to remove and 164 not upgraded.
pi@raspberrypi:~ $
```

Open rpi-imager:

sudo rpi-imager

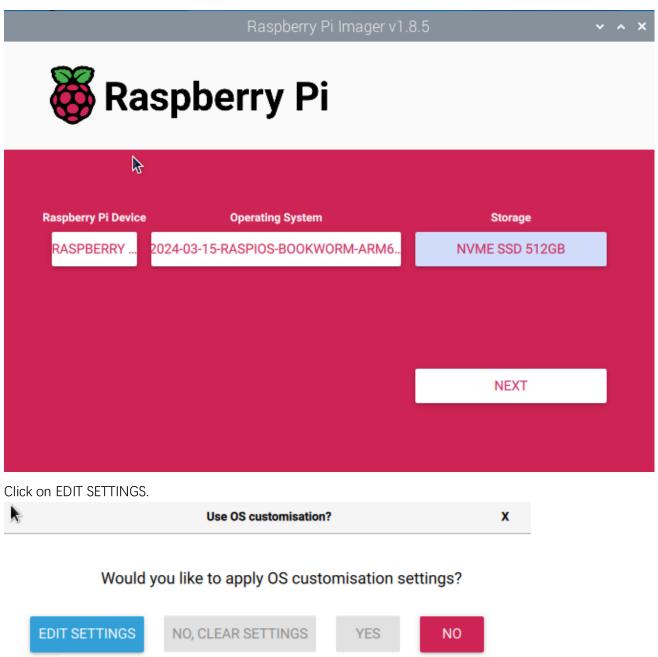
```
bi@raspberrypi:~ $ sudo rpi-imager
Q͡StandardPaths: XDG_RUNTIME_DIR not set, defaulting to '/tmp/runtime-root'
error: XDG_RUNTIME_DIR is invalid or not set in the environment.
```



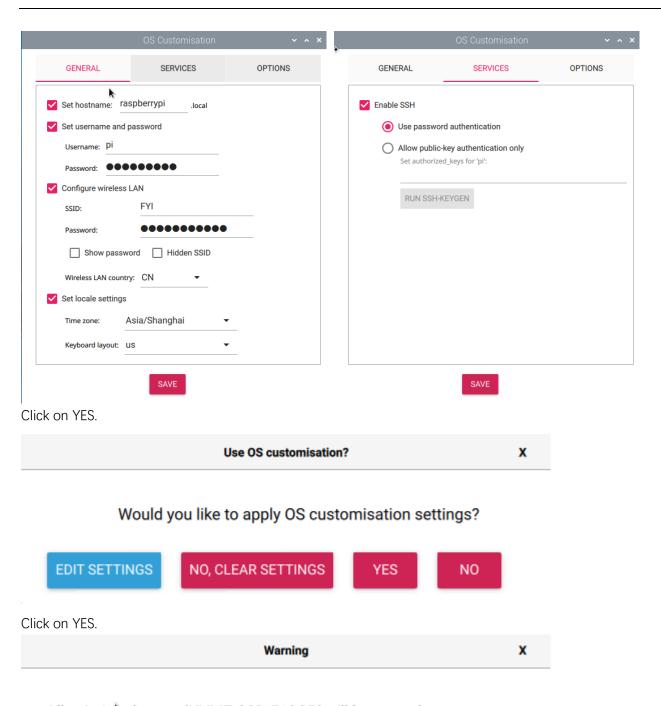


By this point, you should be quite familiar with the process.

Select the Raspberry Pi 5 as your device and choose either an online download or an offline file for the operating system; in this case, an offline file is selected. (It is recommended to use a 64-bit Raspberry Pi system with recommended software). Choose your NVME SSD as the storage device. Click NEXT.



Wireless LAN Country must be correctly set; otherwise, it may fail to search the WiFi. Enable SSH and click Save.



All existin data on 'NVME SSD 512GB' will be erased. Are you sure you want to continue?



Wait for it to finish.



Congratulations! You have done the most tricky and the time-comsuming part. Now that you have successfully installed the operating system onto the NVMe SSD, you are very close to achieving a triumph.

Next, boot into the system from SSD.

### 2.2.5 Enable PCIE3.0 (on system written into SSD)

If you have confirmed that SSD is with Phison controller in step 2, then you also need to enable PCIE3.0 on the system written into SSD.

If the controller of your SSD is not from Phison, you can skip this section.

The operation is as below:

1. Run the command lsblk to check the partitions of the SSD with Raspberry Pi OS written, as shown below:

```
pi@raspberrypi:~ $ lsblk
NAME
            MAJ:MIN RM
                         SIZE RO TYPE MOUNTPOINTS
mmcblk0
            179:0
                        29.3G
                     0
                               0 disk
 -mmcblk0p1 179:1
                     0
                         512M
                                0 part /boot/firmware
 -mmcblk0p2 179:2
                               0 part /
                     0 28.8G
nvme0n1
            259:0
                     0 119.2G
                                0 disk
 -nvme0n1p1 259:1
                         512M
                                0 part
 -nvme0n1p2 259:2
                     0 118.7G
                                0 part
pi@raspberrypi:~ $
```

(The above screenshot is the result of an 128GB SSD with Phison as main controller.)

Run the following commands one by one to mount partition 1 of the SSD to the directory of /media/pi.

```
sudo mkdir /media/pi
sudo mount /dev/nvme0n1p1 /media/pi
pi@raspberrypi:~ $ sudo mkdir /media/pi
pi@raspberrypi:~ $ sudo mount /dev/nvme0n1p1 /media/pi
```

If it mounts successfully, you'll see the following disk icon on the desktop.



Open and modify the config.txt file with the following command.

```
sudo nano /media/pi/config.txt
```

```
pi@raspberrypi:~ $ sudo nano /media/pi/config.txt
```

Add the line dtparam=pciex1\_gen=3 to the end of the file, as shown below:

Press Ctrl-O to save the file, Enter to confirm, and Ctrl-X to exit.

# 3. Booting from SSD

After finishing flashing the OS to SSD, shutdown Raspberry Pi, remove the power supply, and remove the SD card. Then connect the power, the Raspberry Pi will boot from SSD.

The default boot order of Raspberry Pi is SD card  $\Rightarrow$  SSD  $\Rightarrow$  USB, Therefore, when the SD card is removed, the Raspberry Pi cannot detect the SD card, it will boot from SSD. By far, the Raspberry Pi can boot successfully from NVME SSD.

```
B1 SD Card Boot Boot from SD Card before trying NVMe and then USB (RECOMMENDED)
B2 NVMe/USB Boot Boot from NVMe before trying USB and then SD Card
B3 Network Boot Boot from Network unless override by SD Card
```

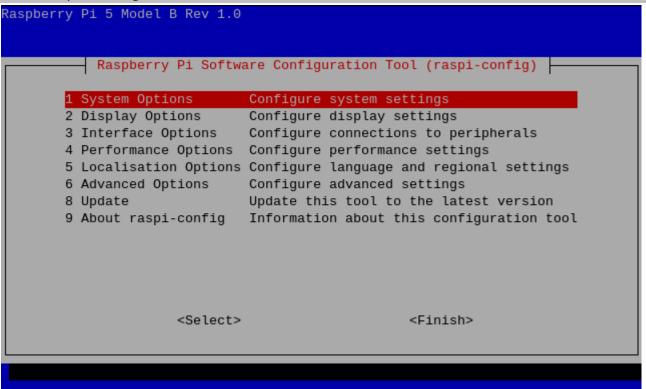
If you want the Raspberry Pi to boot from the SSD first, please continue with the following steps to modify the boot order. The boot order is saved in the Pi's EEPROM, so it does not matter whether you modify the boot order on SD card system or SSD system.

If you do not want to change the boot order, please skip this chapter.

### 3.1 Configuring the Boot Order

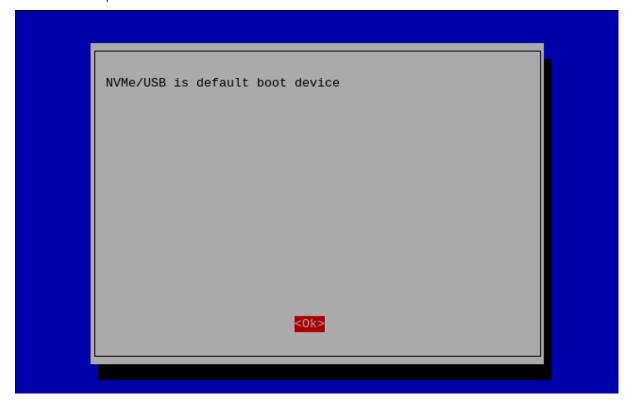
Type the following command in the Terminal.

#### sudo raspi-config



Using the keyboard's arrow keys and the Enter key, select the options in sequence.

"6 Advanced Options" → "A4 Boot Order" → "B2 NVME/USB Boot ···"



Select "OK"→"Finish"→"Yes", and reboot your Raspberry Pi.



At this point, upon restarting, the Raspberry Pi will boot from the NVME SSD first. If you are using an external monitor, you will see that the Raspberry Pi has booted up correctly. If your SD card is still inserted, you will also see an icon on the desktop as shown below.

With this, the process of booting the Raspberry Pi from the NVME SSD has been fully completed.



<Back>

If you use VNC viewer, you will need to repeat the previous steps to acitvate the VNC service as it is not yet enabled in the new system on the SSD. Here, we take Windows as an example.

Run the following command:

#### ssh pi@raspberrypi.local

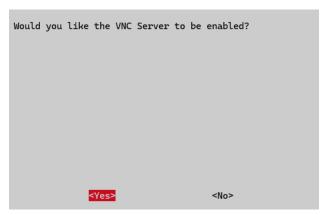
```
C:\Users\Administrator>ssh pi@raspberrypi.local
The authenticity of host 'raspberrypi.local (240e:3b4:3812:1fc0:954e:f55f:a772:fed5)' can't be established.
ECDSA key fingerprint is SHA256:hcx7u6H73nUsIc5WXA3HWa5GPSZEDroiz/mMbQx3ogc.
Are you sure you want to continue connecting (yes/no/[fingerprint])? yes
Warning: Permanently added 'raspberrypi.local,240e:3b4:3812:1fc0:954e:f55f:a772:fed5' (ECDSA) to the list of known hosts
pi@raspberrypi.local's password:
Linux raspberrypi 6.6.20+rpt-rpi-2712 #1 SMP PREEMPT Debian 1:6.6.20-1+rpt1 (2024-03-07) aarch64
The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.
Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
Last login: Mon Jun 3 16:50:25 2024
SSH is enabled and the default password for the 'pi' user has not been changed. This is a security risk - please login as the 'pi' user and type 'passwd' to set a new password.
```

Once successfully ssh into Raspberry Pi, run the following command to open the configuration and enable VNC.

#### sudo raspi-config

Select "3 Interface Options"→"I2 VNC"→"Yes"→"Finish".

```
I1 SSH
                                                                                                               Enable/disable remote command line access using SSH
                              Configure system settings
Configure display settings
1 System Options
2 Display Options
                                                                                                               Enable/disable graphical remote desktop access
Enable/disable automatic loading of SPI kernel module
                                                                                           I3 SPI
                                                                                           I4 I2C Enable/disable automatic loading of I2C kernel module
I5 Serial Port Enable/disable shell messages on the serial connection
4 Performance Options Configure performance settings
5 Localisation Options Configure language and regional settings
6 Advanced Options Configure advanced settings
                                                                                           I6 1-Wire
                                                                                                               Enable/disable one-wire interface
                                                                                           I7 Remote GPIO Enable/disable remote access to GPIO pins
                              Update this tool to the latest version
9 About raspi-config Information about this configuration tool
                                                                                                        <Select>
         <Select>
                                                                <Finish>
```



Now you should be able to access Raspberrry Pi via VNC.

# 4. Speed Test & PCle Gen 3.0

The Raspberry Pi 5 includes a PCle x1 slot that is certified for PCle Gen 2.0, providing a theoretical maximum throughput of 5GT/sec, whichroughly translates to 500MB/sec for read and write operations. Although this slot is not officially certified for PCle Gen 3.0, it is possible to force the use of Gen 3.0 for potentially higher speeds.

In actual tests, it is found that most SSDs can work stably at PCIE2.0, but are slightly unstable at PCIE3.0, while others are just the opposite. Therefore, please choose PCIE2.0 or PCIE3.0 according to your actual situation.

The PCle consortium states that the speed of PCle Gen 3.0 x1 is up to 8GT/sec, which translates to approximately 985MB/sec; however, Raspberry Pi claims that their implementation can achieve a speed of 10GT/sec, equivalent to around 1231MB/sec.

https://en.wikipedia.org/wiki/PCI\_Express#Comparison\_table

https://www.raspberrypi.com/documentation/computers/raspberry-pi.html#pcie-gen-3-0

## 4.1 Disk Speed Test

This is an additional chapter for those who wish to test the read and write speeds of their SSD.

Open the terminal and enter the following command:

#### git clone https://github.com/TheRemote/PiBenchmarks

```
pi@raspberrypi:~ $ git clone https://github.com/TheRemote/PiBenchmarks
Cloning into 'PiBenchmarks'...
remote: Enumerating objects: 652, done.
remote: Counting objects: 100% (112/112), done.
remote: Compressing objects: 100% (80/80), done.
remote: Total 652 (delta 69), reused 65 (delta 31), pack-reused 540
Receiving objects: 100% (652/652), 119.41 KiB | 417.00 KiB/s, done.
Resolving deltas: 100% (386/386), done.
pi@raspberrypi:~ $
```

Enter the directory:

#### cd PiBenchmarks/

Grant executable permissions to the script:

#### chmod +x Storage.sh

```
pi@raspberrypi:~ $ cd PiBenchmarks/
pi@raspberrypi:~/PiBenchmarks $ ls
CODE_OF_CONDUCT.ind CONTRIBUTING.md LICENSE README.md
                                                        Storage.sh
pi@raspberrypi:~/PiBenchmarks $ chmod +x Storage.sh
pi@raspberrypi:~/PiBenchmarks $
```

Start the speed test. Please be aware that the first execution will involve downloading the required dependencies, so the process could take a relatively long time.

#### sudo ./Storage.sh ~/

```
pi@raspberrypi:~/PiBenchmarks $ sudo ./Storage.sh ~/
 rimming and syncing drive
/mediap/pi/bootfs: 433.1 MiB (454152192 bytes) trimmed on /dev/mmcblk0p1
/media/pi/rootfs: 2.5 GiB (2681069568 bytes) trimmed on /dev/mmcblk0p2
/boot/firmware: 436.4 MiB (457588736 bytes) trimmed on /dev/nvme0n1p1
/: 457.4 GiB (491171225600 bytes) trimmed on /dev/nvme0n1p2
Install lshw
Hit:1 http://deb.debian.org/debian bookworm InRelease
Hit:2 http://deb.debian.org/debian-security bookworm-security InRelease
Hit:3 http://deb.debian.org/debian bookworm-updates InRelease
Hit:4 http://archive.raspberrypi.com/debian bookworm InRelease
Reading package lists... Done
Reading package lists... Done
Building dependency tree... Done
Reading state information... Done
pciutils is already the newest version (1:3.9.0-4).
            already the newest version
```

After the speed test is completed, follow the prompts to enter a description and a name for your SSD (you can use any arbitrary characters).

```
iozone test complete.

RandRead: 55044 - RandWrite: 169735 - Read: 194074 - Write: 159843

Enter a description of your storage and setup (Example: Kingston A400 SSD on Pi 4 using StarTech SATA to USB adapter)

Description: ssd1

(Optional) Enter alias to use on benchmark results. Leave blank for completely anonymous.

Alias (leave blank for Anonymous): ssd1

Result submitted successfully and will appear live on https://pibenchmarks.com within a couple of minutes.
```

#### Test result:

Category	Test	Result
HDParm	Disk Read	381.84 MB/sec
HDParm	Cached Disk Read	376.91 MB/sec
DD	Disk Write	312 MB/s
FI0	4k random read	93090 IOPS (372363 KB/s)
FI0	4k random write	70378 IOPS (281512 KB/s)
I0Zone	4k read	194074 KB/s
I0Zone	4k write	159843 KB/s
I0Zone	4k random read	55044 KB/s
I0Zone	4k random write	169735 KB/s
	Score: 36670	

The performance varies among different SSDs, and each test may also have cetain error, which is normal. The following image shows the speed test results for another SSD:

Category	Test	Result
HDParm	Disk Read	419.20 MB/sec
HDParm	Cached Disk Read	411.77 MB/sec
DD	Disk Write	253 MB/s
FIO	4k random read	105567 IOPS (422268 KB/s)
FIO	4k random write	58347 IOPS (233390 KB/s)
I0Zone	4k read	160588 KB/s
I0Zone	4k write	127044 KB/s
I0Zone	4k random read	55222 KB/s
I0Zone	4k random write	154445 KB/s
	Score: 33177	

This is a speed test result for a TF (microSD) card, and it shows a significant difference in speed compared to an SSD.

Category	Test	Result
HDParm	Disk Read	86.73 MB/sec
HDParm	Cached Disk Read	87.63 MB/sec
DD	Disk Write	13.1 MB/s
FIO	4k random read	4222 IOPS (16890 KB/s)
FIO	4k random write	191 IOPS (766 KB/s)
I0Zone	4k read	16691 KB/s
I0Zone	4k write	5123 KB/s
I0Zone	4k random read	16794 KB/s
I0Zone	4k random write	2455 KB/s
	Score: 1457	

## 4.2 PCle Gen 3.0

In the Preface, it is mentioned that the Raspberry Pi's PCle Gen 3.0 has not been officially certified. While it is functional, its performance is not as reliable as desired. This chapter is presented as an exploratory section for assessing the speed capabilities of SSDs when used with PCle Gen 3.0. For practical applications, it is advised to opt for PCle Gen 2.0 to ensure greater stability and dependability.

#### EnablePCle Gen3.0

Add the line dtparam=pciex1\_gen=3 to /boot/firmware/config.txt to enable PCle Gen3.0.

As shown below, enter the command to open the file.

```
sudo nano /boot/firmware/config.txt
```

Add the line dtparam=pciex1\_gen=3 to the end of the file, as shown below:

```
GNU nano 7.2 /boot/firmware/config.txt *
otg_mode {1

[all]

dtparam=pciex1_gen=3
```

Press Ctro-O to save the file, Enter to confirm, and Ctrl-X to exit.

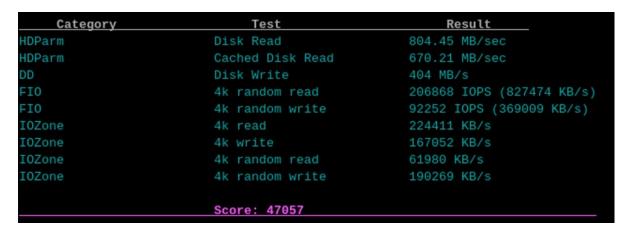
Reboot your Raspberry Pi.

#### sudo reboot

After rebooting, test the speed again.

Category	,	Test	Result
HDParm	Υ	Disk Read	755.51 MB/sec
HDParm	Υ.	Cached Disk Read	687.95 MB/sec
DD		Disk Write	487 MB/s
FI0		4k random read	93944 IOPS (375779 KB/s)
FI0		4k random write	89824 IOPS (359298 KB/s)
I0Zone		4k read	281334 KB/s
I0Zone		4k write	199418 KB/s
I0Zone		4k random read	60363 KB/s
I0Zone		4k random write	223924 KB/s
		Score: 47341	

The speed of another SSD.



#### Disable PCle Gen3.0

Delete the line added with the previous step to disable PCle Gen3.0. Delete the line **dtparam=pciex1\_gen=3** in the boot/firmware/config.txt file.

After the line is removed, it will change to PCle Gen2.0.

# What's Next?

THANK YOU for participating in this learning experience! If you have completed all of the projects successfully you can consider yourself a Raspberry Pi Master.

We have reached the end of this Tutorial. If you find errors, omissions or you have suggestions and/or questions about the Tutorial or component contents of this Kit, please feel free to contact us: <a href="mailto:support@freenove.com">support@freenove.com</a>

We will make every effort to make changes and correct errors as soon as feasibly possible and publish a revised version.

If you are interesting in processing, you can study the Processing.pdf in the unzipped folder.

If you want to learn more about Arduino, Raspberry Pi, Smart Cars, Robotics and other interesting products in science and technology, please continue to visit our website. We will continue to launch fun, cost-effective, innovative and exciting products.

http://www.freenove.com/

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