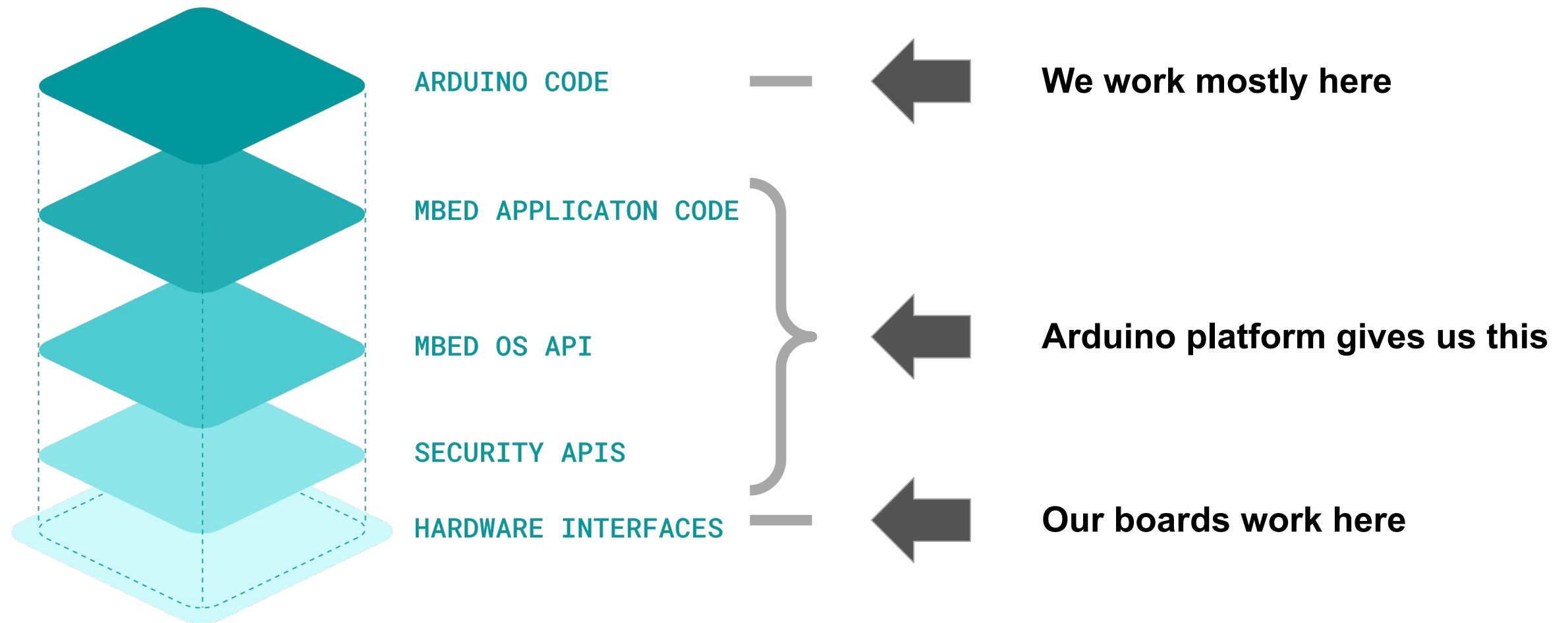


# Edge Computing in the IoT

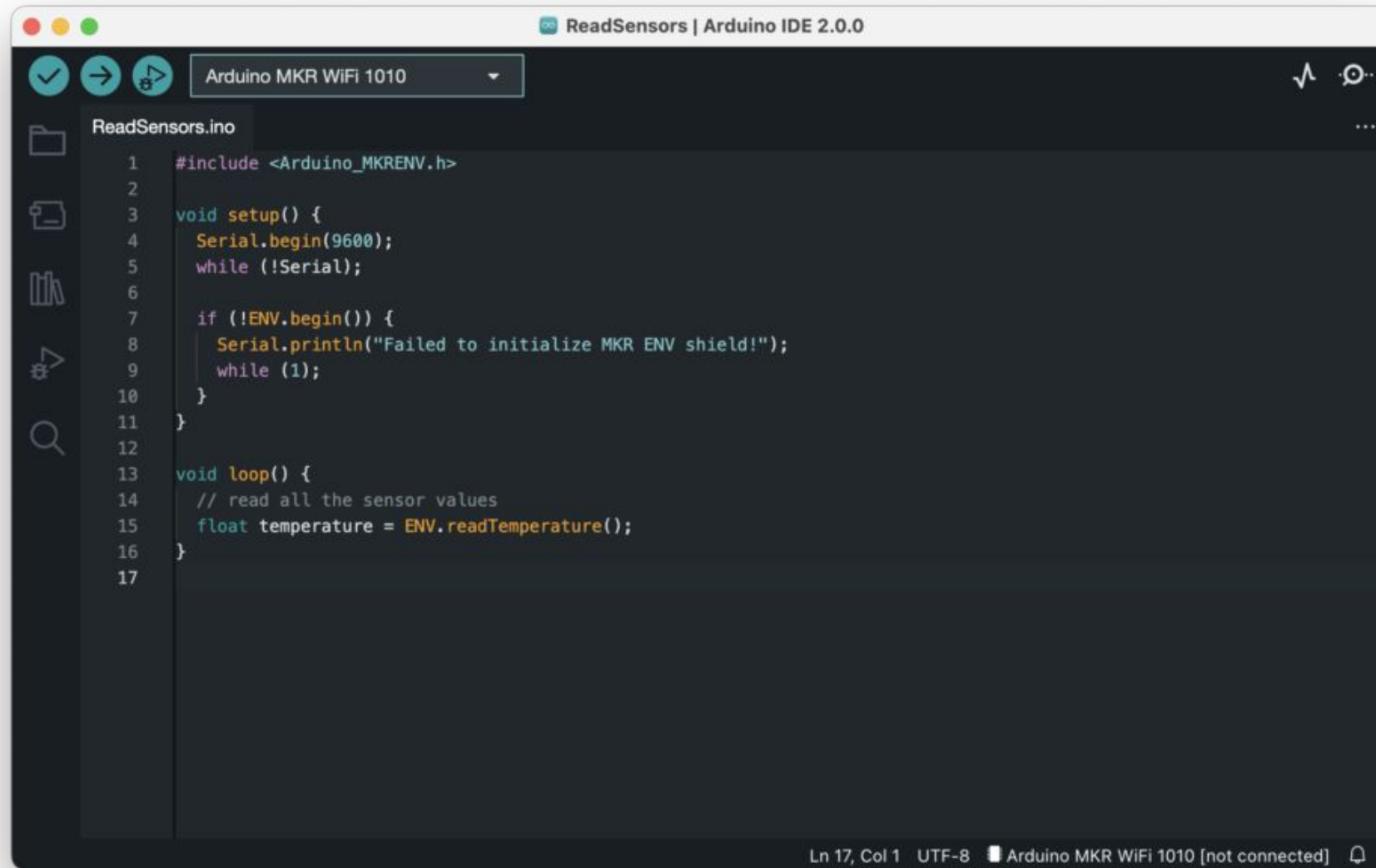
## Arduino Platform Hands-on

Alberto Ferrante  
TA: Luca Butera

# The Arduino abstraction



# The Arduino IDE 2.0



IDE 2.0 available for  
download at:  
[arduino.cc/en/software](https://arduino.cc/en/software)

Cloud IDE available at:  
[cloud.arduino.cc/home/](https://cloud.arduino.cc/home/)

# Blink LED

```
// the setup function runs once when you press reset or power the board
void setup() {
    // initialize digital pin LED_BUILTIN as an output.
    pinMode(LED_BUILTIN, OUTPUT);
}

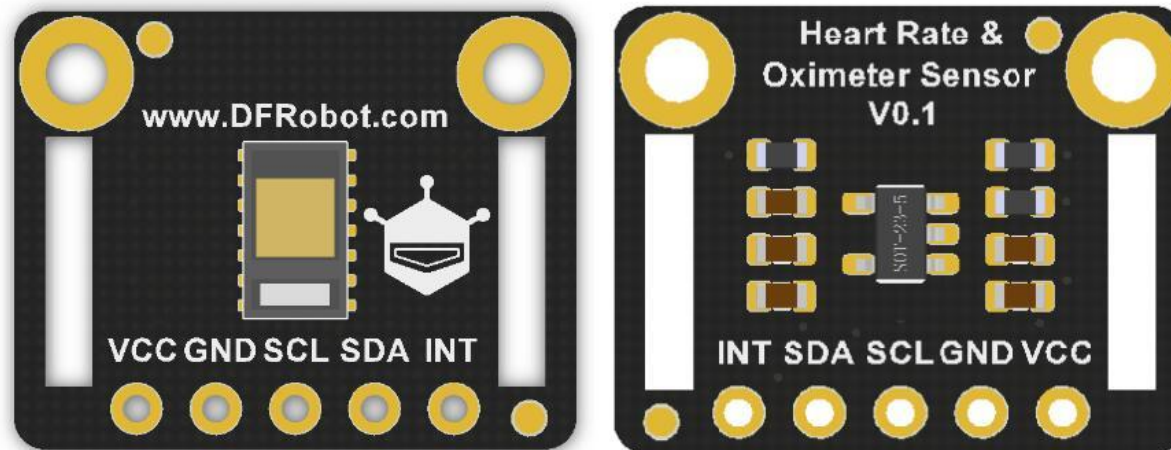
// the loop function runs over and over again forever
void loop() {
    digitalWrite(LED_BUILTIN, HIGH); // turn the LED on (HIGH is the voltage level)
    delay(1000);                      // wait for a second
    digitalWrite(LED_BUILTIN, LOW);  // turn the LED off by making the voltage LOW
    delay(1000);                      // wait for a second
}
```

This example code  
can be found in the  
**Arduino IDE 2.0**  
under:

**File -> Examples ->  
01.Basics -> Blink**

# Pulse Oximeter Sensor

## MAX30102



Sensor wiki:

[https://wiki.dfrobot.com/Heart\\_Rate\\_and\\_Oximeter\\_Sensor\\_SKU\\_SEN0344](https://wiki.dfrobot.com/Heart_Rate_and_Oximeter_Sensor_SKU_SEN0344)

Sensor library:

[https://github.com/DFRobot/DFRobot\\_MAX30102](https://github.com/DFRobot/DFRobot_MAX30102)

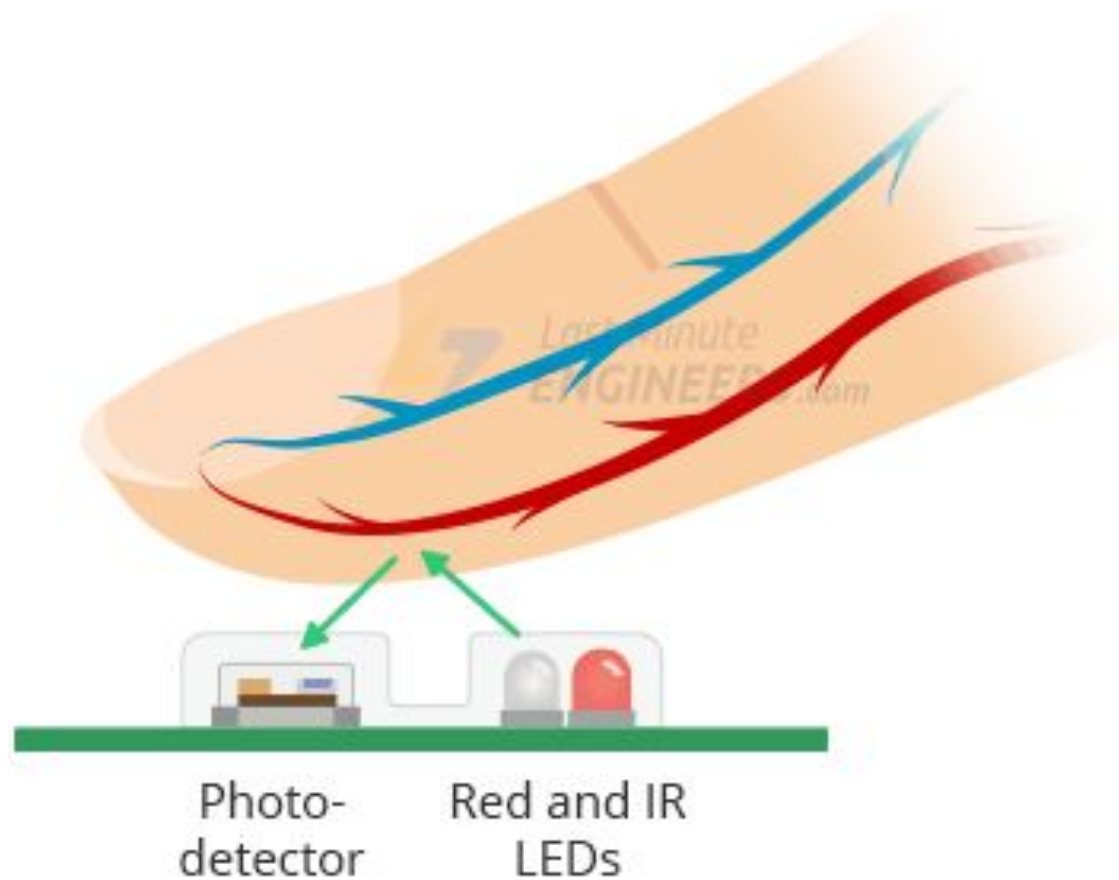
or

[https://github.com/sparkfun/SparkFun\\_MAX3010x\\_Sensor\\_Library](https://github.com/sparkfun/SparkFun_MAX3010x_Sensor_Library)

(directly available in the IDE)

Communicates through I2C.

## Working Principle

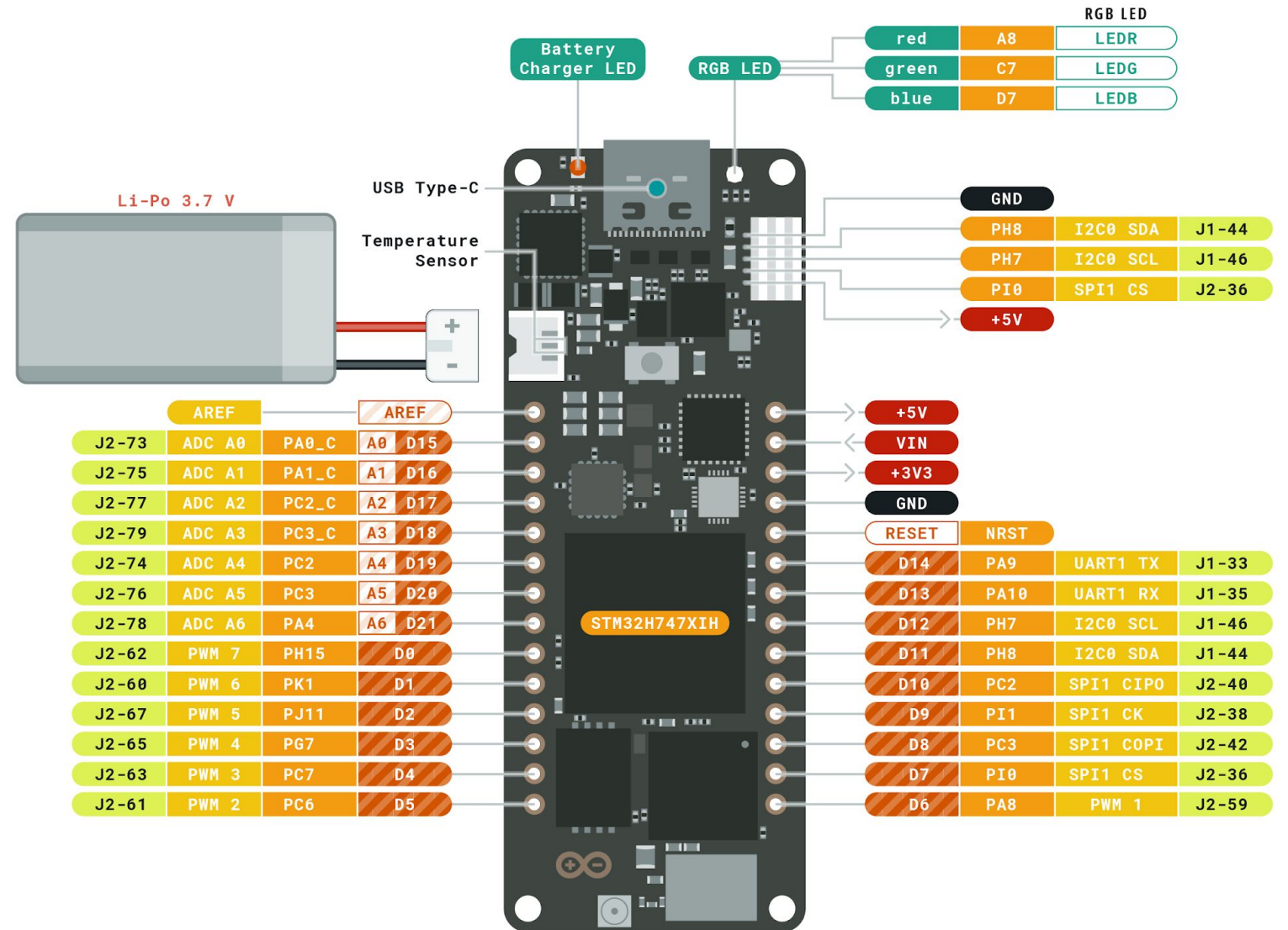


A RED and IR LEDs are shone through the skin and reflected onto a photo detector.

The amount of RED and IR light that is reflected depends on the bloodstream oxygen levels.

# Wiring Diagram

Sensor	Arduino	Role
VCC	+5V/+3V3	Power
GND	GND	Ground
SCL	D12	I2C Clock Line
SDA	D11	I2C Data Line
INT	D13	Interrupt Pin



## Debugging: code preparation

Add the following before your code and use the **Sketch -> Optimize for Debugging** option.

```
#include <ThreadDebug.h>
UsbDebugCommInterface debugComm(&SerialUSB);
ThreadDebug threadDebug(&debugComm, DEBUG_BREAK_IN_SETUP);

// Your code...
```

Execute **Sketch -> Export Compiled Binary**



# Debugging: running the debugger

Things we need:

- gdb debugger executable → `~/Library/Arduino15/packages/arduino/tools/arm-none-eabi-gcc/7-2017q4/bin/arm-none-eabi-gdb`
- arduino board port → `/dev/cu.usbmodem101`
- compiled sketch file → `~/Documenti/Arduino/blink/Blink/build/arduino.mbed_nano.nano33ble/Blink.ino.elf`

Populate the placeholders and run this command in your terminal.

```
<gdb> -ex "set pagination off" --baud <int> -ex "set target-charset ASCII" -ex "target remote <port>" <sketch>
```



```
~/Library/Arduino15/packages/arduino/tools/arm-none-eabi-gcc/7-2017q4/bin/arm-none-eabi-gdb -ex "set pagination off"  
--baud 230400 -ex "set target-charset ASCII" -ex "target remote /dev/cu.usbmodem101"  
~/Documenti/Arduino/blink/Blink/build/arduino.mbed_nano.nano33ble/Blink.ino.elf
```