

JINJA JOINT EXAMINATIONS BOARD

MARKING GUIDE 2019

P425/2 FOR PAPER 2 MATHEMATICS

SECTION A (40 MARKS)

1.
$$P(2R, 1G) = p(RRG) + P(RGR) + p(GRR)$$

 $B1$ $B1$ $B1$ $B1$
 $= \frac{6}{10} \times \frac{5}{9} \times \frac{3}{8} + \frac{6}{10} \times \frac{3}{9} \times \frac{5}{8} + \frac{3}{10} \times \frac{6}{9} \times \frac{5}{8}M1$

$$=\frac{3}{8}$$

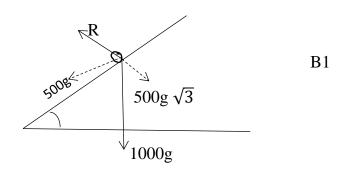
<u>A1</u>

05

2.
$$90 \text{kmh}^{-1} = 90 \text{ x} \frac{1000}{3600}$$

$$= 25 \text{ms}^{-1}$$

B1



 30^{0}

At maxm speed, tractive force = resistance

Resistance =
$$500g$$
 B1

But max speed =
$$\frac{\text{power}}{\text{tractive force}}$$

$$= \frac{\text{power}}{500g} \qquad \text{M1}$$

Power =
$$28 \times 500g$$

= 122500 warts $\underline{A1}$

B1

M1

A1

3.

	5.4	5.56	5.7	
	1.686	y	1.740	
•				
	5.7-5.	4	5.7-5	5.56
1.	740-1.	686	1.740) – y
	Y	=	1.7148	

$$\frac{5.2-5.0}{1.647-1.609} = \frac{5.0-x}{1.609-1.575}$$

$$X = 4.83$$

$$\frac{A1}{0.05}$$

4.
$$P = 0.25, \ q = 0.75, \ n = 80$$

$$= np \qquad = \sqrt{npq}$$

$$= 80 \times 0.025 \qquad = \sqrt{80 \times 0.25 \times 0.75}$$

$$= 20 \qquad = 3.873 \text{ or } \sqrt{15} \qquad B1$$

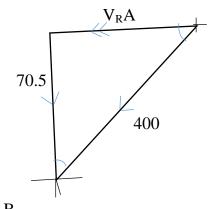
$$P(14 < x \le 18) \qquad = P\left(\frac{14.5 - 20}{\sqrt{15}} < Z < \frac{18.5 - 20}{\sqrt{15}}\right)$$

$$= P(-1.42 < Z < -0.516)$$

$$= 0.4222 - 0.1971$$

$$= 0.2251 \qquad \underline{A1}$$





B1

 80^{0}

B
$$V_R^2 = 70.5^2 + 400^2 - 2(70.5)(400)\cos 80^0$$

M1

$$V_R = 393.92 \text{ kmh}^{-1}$$

B1

$$\therefore \frac{\sin \theta}{70.5} = \frac{\sin 80}{393.92}$$

M1

$$\theta = 10.15^{\circ}$$

⇒direction is S90.15⁰ w

A1 05

6. But P =
$$\frac{0.38}{4.28} - \frac{0.30}{2.14}$$

$$Pmin = \frac{0.375}{4.285} - \frac{0.305}{2.135}$$

$$= -0.05534$$

M1

$$Pmax = \frac{0.385}{4.285} - \frac{0.295}{2.145}$$

$$= -0.04747$$

M1

Max possible error = ½ [-0.04747 + 0.05634] M1 = 0.003935 B1 ∴ $-0.0514 \le P \le -0.04354$ A1

<u>05</u>

7.

									I
Ry	7	9	2.5	8	5.5	4	2.5	1	5.5
Rx	8	7.5	7.5	1	5.5	5.5	3.5	3.5	2
d	1	1.5	-5	7	0	-1.5	-1	-2.5	3.5
d^2	1	2.25	25	49	0	2.25	1	6.25	12.25

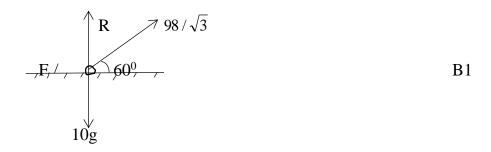
$$\sum d^2 = 99$$

$$\therefore \mathbf{r}_s = 1 - \frac{6 \times 99}{9 \times 80}$$
M1

= 0.175 A1

Comment: there is a positive partial correlation $\frac{A1}{05}$

8.



$$(\uparrow): R + \frac{98}{\sqrt{3}}.\sin 60^\circ = 10g$$
 M1

$$\Rightarrow$$
R = 49

$$(\rightarrow)$$
: F = $\frac{98}{\sqrt{3}}\cos 60^\circ = \frac{98}{2\sqrt{3}} = 49/\sqrt{3}$ M1

Since particle does not move; $F \le \mu R$

$$\therefore \frac{F}{R} = \frac{49/\sqrt{3}}{49} = \frac{1}{53} \Rightarrow \mu \ge \frac{1}{\sqrt{3}}$$
 M1

Minimum value of
$$\mu = 1/\sqrt{3}$$
 or $\frac{\sqrt{3}}{3}$

<u>A1</u>

<u>05</u>

SECTION B (60 MARKS)

9. (a)
$$\mu = 55$$
, $\sigma = 8$, $n = 1000$
 $P(x \ge 71) = P\left(Z \ge \frac{71 - 55}{8}\right)$ M1

$$P = (Z \ge 2)$$

$$= 0.5 - 0.4772$$
 M1

$$=0.0228$$
 B1

No of A - passes awarded =
$$0.0228 \times 1000$$
 M1
= 22.8 A1

(b) (i)
$$P(x < x) = 0.15$$

$$P(x < x) = P(Z < \frac{M1}{x-55}) = 0.15$$

But
$$Z0.35 = 1.03$$

$$\therefore \frac{x-55}{8} = -1.03$$
 M1

$$x = 46.76$$
 A1

(ii)
$$P = 0.85$$
, $q = 0.15$, $n = 2$

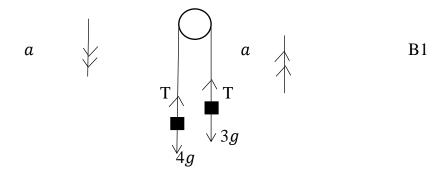
$$P(x = 2) = {2 \choose 2} (0.88)^2 (0.15)^0$$

$$= 0.7225$$
M1

A1

<u>12</u>

10. (a)



Pick
$$4kg : 4g - T = 4a$$
-----(i) M1
Pick $3kg : T - 3g = 3a$ -----(ii)

$$\underline{\text{(I)} + \text{(II)}} : g = 7a$$
 M1

(i)
$$a = 9.8/7$$

$$= 1.4 \text{ms}^{-2}$$
 A1

(ii)
$$\therefore T = 3 \times 9.8 + 3 \times 1.4$$

= 33.6N A1

(b) when 3kg picks up 2 kg, the total momentum of the whole system is conserved,

if V is the speed after total pick up

$$\Rightarrow 4V + 3V = (4+5) V_1$$
 M1

$$7 \times 9 = 9V_1$$

$$V_1 = 7ms^{-1}$$
 A1

(ii) let the 5kg mass rise a distance h from A

 $O^2 = 7^2 - 2x \underline{g} h$

9

 a_1a_1 $V_1 \downarrow \qquad \qquad \downarrow \qquad \downarrow \qquad \downarrow \qquad \downarrow \qquad \downarrow \qquad \downarrow \qquad \downarrow \qquad \qquad \qquad \downarrow \qquad \qquad \qquad$

h = 22.5m $\underline{A1}$ $\underline{12}$

M1

11.(b) Let
$$f(x) = x^{2} - \sin 2x$$

$$f(x) = 2x - 2\cos 2x$$

$$M1$$

$$x_{n+1} = x_{n} - \frac{(x_{n}^{2} - \sin 2x_{n})}{2x_{n} - 2\cos 2x_{n}}$$

$$x_{0} = 0.94$$

$$x_{1} = 0.94 - \frac{\left[(0.929)^{2} - \sin 2(0.99)\right]}{2(0.94) - 2\cos 2(0.94)}$$

$$= 0.922$$

$$x_{3} = 0.922 - \frac{\left[(0.922)^{2} - \sin 2(0.922)\right]}{2(0.922) - 2\cos 2(0.922)}$$

$$M1$$

$$x_{3} = 0.922 - \frac{\left[(0.922)^{2} - \sin 2(0.922)\right]}{2(0.922) - 2\cos 2(0.922)}$$

$$= 0.9175 \quad |e| = 0.0045$$

$$\therefore \text{ root} = 0.92$$

$$\frac{A1}{a} = \frac{B1}{a} = 0.0045$$

12.

$$P(x \le x) = F(x) = \begin{cases} 0 & ; & x < 2 \\ ax - bx & ; & 2 \le x \le 5 \\ 1 & ; & x > 5 \end{cases}$$

$$f(2) = 0;$$

$$\therefore 2a + \frac{b}{2} = 0 \Rightarrow b = 4a$$
 B1

<u>12</u>

$$f(5) = 1$$
 B1

$$\Rightarrow 5a - \frac{b}{5} = 1$$
 M1

$$a = \frac{5}{21}$$
 A1

$$\therefore b = \frac{20}{21}$$
 A1

$$f(x) = \begin{cases} 0 & ; & x < 2 \\ \frac{5}{21} (x - \frac{4}{x}) & ; & 2 \le x \le 5 \\ 1 & ; & x > 5 \end{cases}$$

(ii)
$$P(3 < x < 4) = F(4) - F(3)$$

$$=\frac{5}{21}\left(4-\frac{4}{4}\right)-\frac{5}{21}\left(3-\frac{4}{3}\right)$$
 M1

$$=\frac{20}{63}$$
 A1

(iii)
$$f(x) = F'(x) = \frac{5}{21} \left(1 + \frac{4}{x^2} \right) \text{ M1}$$

$$f(x) = \begin{cases} \frac{5}{21} \left(1 + \frac{4}{x^2} \right) & ; \quad 2 \le x \le 5 \\ 0 & ; \quad otherwise \end{cases}$$
 A1

(iv)
$$E(x) = \int_{2}^{5} \frac{5}{21} \left(x + \frac{4}{x} \right) dx$$

$$= \frac{5}{21} \left[\frac{x^2}{2} + 4Inx \right]_2^5$$
 M1

$$= \frac{5}{2} + \frac{20}{21} \ln \frac{5}{2}$$
 M1

$$= 3.3727$$
 $\underline{A1}$ 12

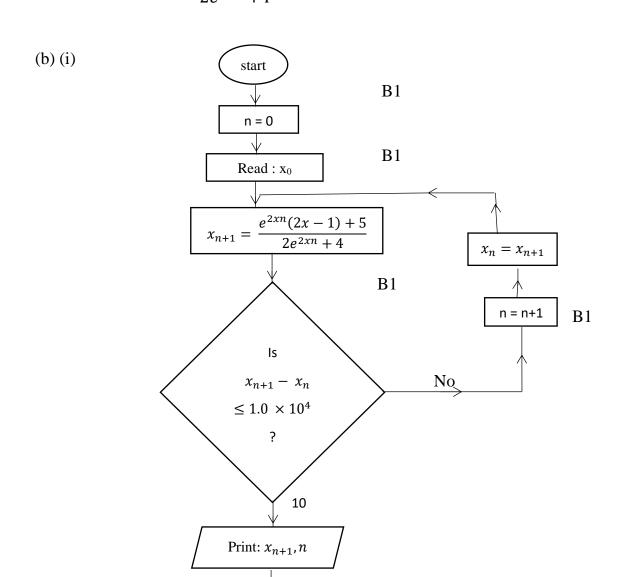
13. (a)
$$f(x) = e^{2x} + 4x - 5,$$

$$F'(x) = 2e^{2x} + 4$$

$$X_{n+1} = X_n - \frac{(e^{2xn} + 4x_n - 5}{2e^{2xn} + 4}$$

$$= \frac{2xn e^{2xn} + 4xn - e^{2xn} - 4xn \times 5}{2e^{2xn} + 4}$$

$$= \frac{2x_n e^{2xn} (2_{n+1} - 1) + 5}{2e^{2xn} + 4}$$
B1



B1

Yes

B1

(ii)

n	x_n	x_{n+1}	$(x_{n+1} - x_n)$
0	0.5	0.5299	0.0299
1	0.5299	0.5293	0.0006
2	0.5293	0.5293	0.0000

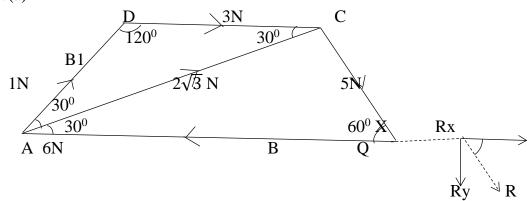
B1

B1

$$\therefore \text{ root} = 0.53$$

$$\underline{\underline{12}}$$

14. (a)



$$Rx = 1\cos 60^{0} + 3 + 5\cos 60^{0} - 6 + 2\sqrt{3}\cos 30^{0}$$
 M1

$$=$$
 3N B1

$$Ry = -1\cos 30^{0} + 5\cos 30^{0} - 2\sqrt{3}\sin 30^{0}$$
 M1

$$= \sqrt{3} N$$
 B1

$$R = \sqrt{3^2 + (\sqrt{3})^2} M1 \quad \text{and } \cos\theta = \frac{3}{2\sqrt{3}}$$

$$= 3.4641 N \quad A1 \quad \theta = 30^0$$
Resultant = 3.4641N at 30° with AB ie 30° to AB on opposite side to D

A1

(b)
$$M(A): 3 (1 \sin 60^{\circ}) + 5 \cos 30^{\circ} \times 2 = Ry AX$$
 M1 $3\frac{\sqrt{3}}{2} + 5\frac{\sqrt{3}}{2} \times 2 = \sqrt{3} AX$
$$AX = 6.5m \qquad \qquad \underline{A1} \ \underline{12}$$

15.

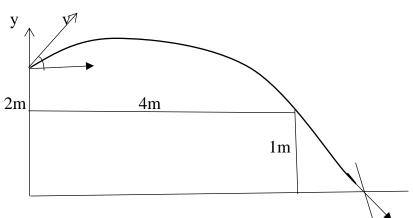
Distance	f	X	Xf	X^2F	F
31 - 40	10	35.5	355	12,602.5	10
41 - 45	15	43	645	27,735	25
46 - 50	20	48	960	46,080	45
51 - 55	70	53	3710	196,630	115
56 - 57	64	56.5	3616	204,304	179
58 - 60	24	59	1416	83,544	203
61 - 70	20	65.5	1310	85,805	223
71 - 90	10	80.5	805	64,802.5	233
sum	233		12817	721,503	
			B1	B1	B1

and C

(a) S.D =
$$\sqrt{\frac{721,503}{233}} - (55.0086)^2$$
 M1
= 8.4044 A1



 $45^{0}x$



$$x = vt\cos 45^{0}; y = vt\sin 45^{0} - \frac{1}{2}gt^{2}$$

$$= \frac{vt}{\sqrt{2}} \qquad = \frac{vt}{\sqrt{2}} - \frac{1}{2}gt^{2}$$
B1

$$\therefore y = x - \frac{gx^2}{v^2} - \cdots * t / = x \frac{\sqrt{2}}{v}$$

When x = 4, b = -1

$$\Rightarrow -1 = 4 - \frac{gx^2}{v^2}$$

$$\therefore v^2 = \frac{16g}{5}$$
 B1

From equation *

$$y = x - \frac{gx^2}{16g/5}$$
 M1

$$\Rightarrow 16y = 16x - 5x^2$$
 B1

(b) (i) when
$$y = -2$$

$$\Rightarrow 16(-2) = 16x - 5x^2$$

$$5x^{2} - 16x - 32 = 0$$

$$x = \frac{16 \pm 29.9332}{10}$$

$$= 4.5933 \text{ or } -1.39333$$
M1

 $\therefore x = 4.59333m$ hence ball strikes ground 0.59m beyond the wall

A1

(ii) using
$$v^2 = u^2 - 2gy$$

 $v^2 = 32 - 2g(-1)$
 $v = 8.5ms^{-1}$ B1

From equation $y = x - \frac{5x^2}{16}$

$$\frac{dy}{dx} = 1 - \frac{5}{8}x$$

$$= 1 - \frac{5}{8}(4.5933)$$
M1

$$\therefore \tan \theta = -1.8708$$

$$\theta = -61.87^{\circ}$$
 B1

∴ velocity = 8.5ms⁻¹, direction is 61.9^0 below the horizontal $\underline{A1}$

<u>12</u>