

9.1 Equation of a line in three dimensions

You need to know how to write the equation of a straight line in vector form.

Suppose a straight line passes through a given point A , with position vector \mathbf{a} , and is parallel to the given vector \mathbf{b} . Only one such line is possible. Let R be an arbitrary point on the line, with position vector \mathbf{r} .

Since \overrightarrow{AR} is parallel to \mathbf{b} , $\overrightarrow{AR} = \lambda\mathbf{b}$, where λ is a scalar.

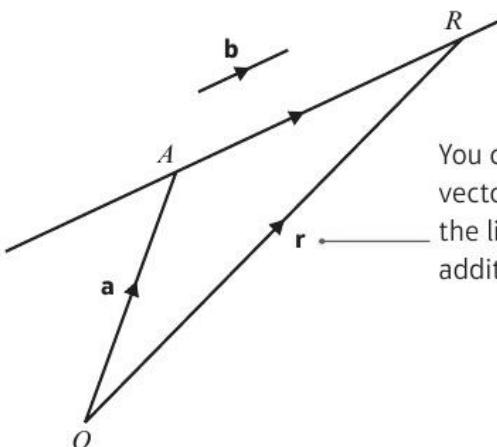
The vector \mathbf{b} is called the **direction vector** of the line.

So the position vector \mathbf{r} can be written as $\mathbf{a} + \lambda\mathbf{b}$.

- A vector equation of a straight line passing through the point A with position vector \mathbf{a} , and parallel to the vector \mathbf{b} is

$$\mathbf{r} = \mathbf{a} + \lambda\mathbf{b}$$

where λ is a scalar parameter.



You can find the position vector of any point R on the line by using vector addition ($\triangle OAR$):

$$\mathbf{r} = \mathbf{a} + \overrightarrow{AR}$$

By taking different values of the parameter λ , you can find the position vectors of different points that lie on the straight line.

Example

1

Find a vector equation of the straight line which passes through the point A , with position vector $3\mathbf{i} - 5\mathbf{j} + 4\mathbf{k}$, and is parallel to the vector $7\mathbf{i} - 3\mathbf{k}$.



Online Explore the vector equation of a line using GeoGebra.

Here $\mathbf{a} = \begin{pmatrix} 3 \\ -5 \\ 4 \end{pmatrix}$ and $\mathbf{b} = \begin{pmatrix} 7 \\ 0 \\ -3 \end{pmatrix}$.

\mathbf{b} is the direction vector.

An equation of the line is

$$\mathbf{r} = \begin{pmatrix} 3 \\ -5 \\ 4 \end{pmatrix} + \lambda \begin{pmatrix} 7 \\ 0 \\ -3 \end{pmatrix}$$

or $\mathbf{r} = (3\mathbf{i} - 5\mathbf{j} + 4\mathbf{k}) + \lambda(7\mathbf{i} - 3\mathbf{k})$

or $\mathbf{r} = (3 + 7\lambda)\mathbf{i} + (-5)\mathbf{j} + (4 - 3\lambda)\mathbf{k}$

or $\mathbf{r} = \begin{pmatrix} 3 + 7\lambda \\ -5 \\ 4 - 3\lambda \end{pmatrix}$

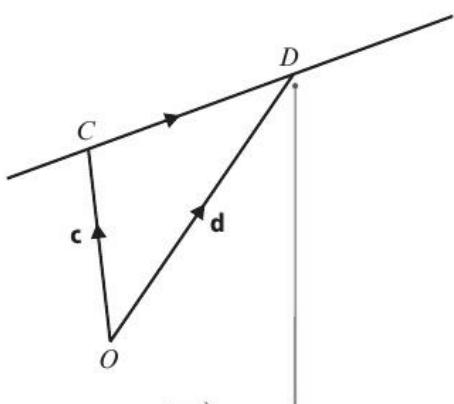
You sometimes need to show the separate x, y, z components in terms of λ .

You can represent a 3D vector using column

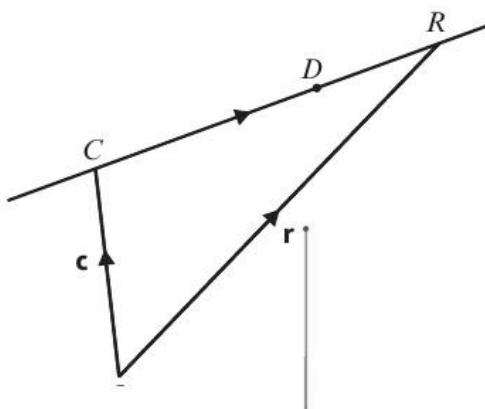
notation, $\begin{pmatrix} x \\ y \\ z \end{pmatrix}$, or using **ijk**-notation, $x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$.

← Pure Year 2, Chapter 12

Now suppose a straight line passes through two given points C and D , with position vectors \mathbf{c} and \mathbf{d} respectively. Again, only one such line is possible.



You can use \overrightarrow{CD} as a direction vector for the line:
 $\overrightarrow{CD} = \mathbf{d} - \mathbf{c}$.



You can now use one of the two given points and the direction vector to form an equation for the straight line.

- A vector equation of a straight line passing through the points C and D , with position vectors \mathbf{c} and \mathbf{d} respectively, is**

$$\mathbf{r} = \mathbf{c} + \lambda(\mathbf{d} - \mathbf{c})$$

where λ is a scalar parameter.

Note You can use any point on the straight line as the initial point in the vector equation. An alternative vector equation for this line would be $\mathbf{r} = \mathbf{d} + \lambda(\mathbf{d} - \mathbf{c})$.

Example 2

Find a vector equation of the straight line which passes through the points A and B , with coordinates $(4, 5, -1)$ and $(6, 3, 2)$ respectively.

$$\mathbf{a} = \begin{pmatrix} 4 \\ 5 \\ -1 \end{pmatrix}$$

$$\mathbf{b} = \begin{pmatrix} 6 \\ 3 \\ 2 \end{pmatrix}$$

Write down the position vectors of A and B .

$$\mathbf{b} - \mathbf{a} = \begin{pmatrix} 6 \\ 3 \\ 2 \end{pmatrix} - \begin{pmatrix} 4 \\ 5 \\ -1 \end{pmatrix} = \begin{pmatrix} 2 \\ -2 \\ 3 \end{pmatrix}$$

Find a direction vector for the line.

$$\mathbf{r} = \begin{pmatrix} 4 \\ 5 \\ -1 \end{pmatrix} + t \begin{pmatrix} 2 \\ -2 \\ 3 \end{pmatrix}$$

Use one of the given points to form the equation.

$$\text{or } \mathbf{r} = (4\mathbf{i} + 5\mathbf{j} - \mathbf{k}) + t(2\mathbf{i} - 2\mathbf{j} + 3\mathbf{k})$$

You don't have to use λ for the parameter. In this example, the parameter is represented by the letter t .

$$\text{or } \mathbf{r} = (4 + 2t)\mathbf{i} + (5 - 2t)\mathbf{j} + (-1 + 3t)\mathbf{k}$$

$$\text{or } \mathbf{r} = \begin{pmatrix} 4 + 2t \\ 5 - 2t \\ -1 + 3t \end{pmatrix}$$

You can give your answer in any of these forms.

Example 3

The straight line l has vector equation $\mathbf{r} = (3\mathbf{i} + 2\mathbf{j} - 5\mathbf{k}) + t(\mathbf{i} - 6\mathbf{j} - 2\mathbf{k})$.

Given that the point $(a, b, 0)$ lies on l , find the value of a and the value of b .

$$\begin{aligned}\mathbf{r} &= \begin{pmatrix} 3+t \\ 2-6t \\ -5-2t \end{pmatrix} \\ -5-2t &= 0 \\ t &= -\frac{5}{2} \\ a = 3+t &= \frac{1}{2} \\ b = 2-6t &= 17 \\ a = \frac{1}{2} \text{ and } b = 17 &\end{aligned}$$

You can write the equation in this form.

Use the z -coordinate (which is equal to zero) to find the value of t .

Find a and b using the value of t .

Example 4

The straight line l has vector equation $\mathbf{r} = (2\mathbf{i} + 5\mathbf{j} - 3\mathbf{k}) + \lambda(6\mathbf{i} - 2\mathbf{j} + 4\mathbf{k})$.

Show that another vector equation of l is $\mathbf{r} = (8\mathbf{i} + 3\mathbf{j} + \mathbf{k}) + \mu(3\mathbf{i} - \mathbf{j} + 2\mathbf{k})$.

Use the equation $\mathbf{r} = \begin{pmatrix} 2 \\ 5 \\ -3 \end{pmatrix} + \lambda \begin{pmatrix} 6 \\ -2 \\ 4 \end{pmatrix}$.

When $\lambda = 1$, $\mathbf{r} = \begin{pmatrix} 8 \\ 3 \\ 1 \end{pmatrix}$, so the point $(8, 3, 1)$ lies on l .

$\begin{pmatrix} 6 \\ -2 \\ 4 \end{pmatrix} = 2 \begin{pmatrix} 3 \\ -1 \\ 2 \end{pmatrix}$ so these two vectors are parallel.

So an alternative form of the equation is

$$\mathbf{r} = \begin{pmatrix} 8 \\ 3 \\ 1 \end{pmatrix} + \mu \begin{pmatrix} 3 \\ -1 \\ 2 \end{pmatrix}$$

To show that $(8\mathbf{i} + 3\mathbf{j} + \mathbf{k})$ lies on l , find a value of λ that gives this point. It is often easier to work in column vectors.

If one vector is a scalar multiple of another then the vectors are parallel.

Watch out Using the same value of the parameter in each equation will give **different** points on the line. You should use a different letter for the parameter of the second equation.

You also need to be able to write the equation of a line in three dimensions in **Cartesian form**.

This means that the equation is given in terms of coordinates relative to the x -, y - and z -axes.

- If $\mathbf{a} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$ and $\mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$ the equation of the line with vector equation $\mathbf{r} = \mathbf{a} + \lambda \mathbf{b}$ can be given

in **Cartesian form** as

$$\frac{x-a_1}{b_1} = \frac{y-a_2}{b_2} = \frac{z-a_3}{b_3} \quad \text{Each of the three expressions is equal to } \lambda.$$

Example 5

With respect to the fixed origin O , the line l is given by the equation

$$\mathbf{r} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} + \lambda \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$$

- a Prove that a Cartesian form of the equation of l is

$$\frac{x - a_1}{b_1} = \frac{y - a_2}{b_2} = \frac{z - a_3}{b_3}$$

- b Hence find a Cartesian equation of the line with equation $\mathbf{r} = \begin{pmatrix} 4 \\ 3 \\ -2 \end{pmatrix} + \lambda \begin{pmatrix} -1 \\ 2 \\ 5 \end{pmatrix}$.

a $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} a_1 + \lambda b_1 \\ a_2 + \lambda b_2 \\ a_3 + \lambda b_3 \end{pmatrix}$

$$x = a_1 + \lambda b_1, y = a_2 + \lambda b_2, z = a_3 + \lambda b_3$$

Rearranging,

$$\lambda = \frac{x - a_1}{b_1}, \lambda = \frac{y - a_2}{b_2}, \lambda = \frac{z - a_3}{b_3}$$

$$\text{So } \frac{x - a_1}{b_1} = \frac{y - a_2}{b_2} = \frac{z - a_3}{b_3}$$

b $\frac{x - 4}{-1} = \frac{y - 3}{2} = \frac{z + 2}{5}$

Write the position vector of the general point on the line as $\mathbf{r} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$.

Use the vector equation of the line to write expressions for x , y and z in terms of λ .

Make λ the subject of each equation.

For any point on the line, the value of λ is a constant, so equate the three different expressions for λ .

If you need to convert between vector and Cartesian forms you can quote this result without proof in your exam. Be careful with the signs on the top of each fraction.

Example 6

The line l has equation $\mathbf{r} = \begin{pmatrix} -2 \\ 1 \\ 4 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$, and the point P has position vector $\begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix}$.

- a Show that P does not lie on l .

Given that a circle, centre P , intersects l at points A and B , and that A has position vector $\begin{pmatrix} 0 \\ -3 \\ 6 \end{pmatrix}$,

- b find the position vector of B .

a $\mathbf{r} = \begin{pmatrix} -2 + \lambda \\ 1 - 2\lambda \\ 4 + \lambda \end{pmatrix}$

If $P(2, 1, 3)$ lies on the line then

$$2 = -2 + \lambda \Rightarrow \lambda = 4$$

$$1 = 1 - 2\lambda \Rightarrow \lambda = 0$$

$$3 = 4 + \lambda \Rightarrow \lambda = -1$$

so P does not lie on l .

b $\overrightarrow{AP} = \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix} - \begin{pmatrix} 0 \\ -3 \\ 6 \end{pmatrix} = \begin{pmatrix} 2 \\ 4 \\ -3 \end{pmatrix}$

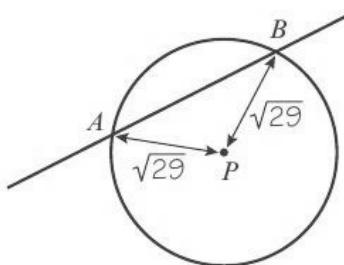
$$|\overrightarrow{AP}| = \sqrt{2^2 + 4^2 + (-3)^2} = \sqrt{29}$$

The position vector of B is $\begin{pmatrix} -2 + \lambda \\ 1 - 2\lambda \\ 4 + \lambda \end{pmatrix}$.

$$\overrightarrow{BP} = \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix} - \begin{pmatrix} -2 + \lambda \\ 1 - 2\lambda \\ 4 + \lambda \end{pmatrix} = \begin{pmatrix} 4 - \lambda \\ 2\lambda \\ -1 - \lambda \end{pmatrix}$$

$$(4 - \lambda)^2 + 4\lambda^2 + (-1 - \lambda)^2 = 29$$

$$16 - 8\lambda + \lambda^2 + 4\lambda^2 + 1 + 2\lambda + \lambda^2 = 29$$



$$6\lambda^2 - 6\lambda + 17 = 29$$

$$6\lambda^2 - 6\lambda - 12 = 0$$

$$\lambda^2 - \lambda - 2 = 0$$

$$(\lambda - 2)(\lambda + 1) = 0$$

So $\lambda = 2$ or $\lambda = -1$

$\lambda = 2$ gives $\begin{pmatrix} 0 \\ -3 \\ 6 \end{pmatrix}$. This is the position vector of point A .

$\lambda = -1$ gives $\begin{pmatrix} -3 \\ 3 \\ 3 \end{pmatrix}$. This is the position vector of point B .

Problem-solving

It is often useful to write the general point on a line as a single vector. You can write each component in the form $a + \lambda b$.

If P lies on l , there is one value of λ that satisfies all 3 equations. You only need to show that two of these equations are not consistent to show that P does not lie on l .

The distance between the points with position

vectors $\begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$ and $\begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$ is

$\sqrt{(b_1 - a_1)^2 + (b_2 - a_2)^2 + (b_3 - a_3)^2}$. As P is the centre of the circle and A lies on the circle, the radius of the circle is $\sqrt{29}$.

← Pure Year 2, Chapter 12

Use the general point on the line to represent the position vector of B .

B lies on the circle so the length $|\overrightarrow{BP}| = \sqrt{29}$.

Solve the resulting quadratic equation to find two possible values of λ . One will correspond to point A , and the other will correspond to point B .

Substitute values of λ into $\begin{pmatrix} -2 + \lambda \\ 1 - 2\lambda \\ 4 + \lambda \end{pmatrix}$. Check that one of the values gives the position vector of A . The other value must give the position vector for B .

Exercise 9A

- 1 For the following pairs of vectors, find a vector equation of the straight line which passes through the point, with position vector \mathbf{a} , and is parallel to the vector \mathbf{b} :

a $\mathbf{a} = 6\mathbf{i} + 5\mathbf{j} - \mathbf{k}$, $\mathbf{b} = 2\mathbf{i} - 3\mathbf{j} - \mathbf{k}$ b $\mathbf{a} = 2\mathbf{i} + 5\mathbf{j}$, $\mathbf{b} = \mathbf{i} + \mathbf{j} + \mathbf{k}$

c $\mathbf{a} = -7\mathbf{i} + 6\mathbf{j} + 2\mathbf{k}$, $\mathbf{b} = 3\mathbf{i} + \mathbf{j} + 2\mathbf{k}$ d $\mathbf{a} = \begin{pmatrix} 2 \\ 0 \\ 4 \end{pmatrix}$, $\mathbf{b} = \begin{pmatrix} -3 \\ 2 \\ 1 \end{pmatrix}$

e $\mathbf{a} = \begin{pmatrix} 6 \\ -11 \\ 2 \end{pmatrix}$, $\mathbf{b} = \begin{pmatrix} 0 \\ 5 \\ -2 \end{pmatrix}$

- 2 For the points P and Q with position vectors \mathbf{p} and \mathbf{q} respectively, find:

i the vector \overrightarrow{PQ}

ii a vector equation of the straight line that passes through P and Q

a $\mathbf{p} = 3\mathbf{i} - 4\mathbf{j} + 2\mathbf{k}$, $\mathbf{q} = 5\mathbf{i} + 3\mathbf{j} - \mathbf{k}$

b $\mathbf{p} = 2\mathbf{i} + \mathbf{j} - 3\mathbf{k}$, $\mathbf{q} = 4\mathbf{i} - 2\mathbf{j} + \mathbf{k}$

c $\mathbf{p} = \mathbf{i} - 2\mathbf{j} + 4\mathbf{k}$, $\mathbf{q} = -2\mathbf{i} - 3\mathbf{j} + 2\mathbf{k}$

d $\mathbf{p} = \begin{pmatrix} 3 \\ -1 \\ 4 \end{pmatrix}$, $\mathbf{q} = \begin{pmatrix} -2 \\ 3 \\ 1 \end{pmatrix}$

e $\mathbf{p} = \begin{pmatrix} 4 \\ -2 \\ 3 \end{pmatrix}$, $\mathbf{q} = \begin{pmatrix} -2 \\ 2 \\ 4 \end{pmatrix}$

- 3 Find a vector equation of the line which is parallel to the z -axis and passes through the point $(4, -3, 8)$.

- 4 a Find a vector equation of the line which passes through the points:

i $(2, 1, 9)$ and $(4, -1, 8)$ ii $(-3, 5, 0)$ and $(7, 2, 2)$

iii $(1, 11, -4)$ and $(5, 9, 2)$ iv $(-2, -3, -7)$ and $(12, 4, -3)$

b Write down a Cartesian equation in the form $\frac{x - a_1}{b_1} = \frac{y - a_2}{b_2} = \frac{z - a_3}{b_3}$ for each line in part a.

- (P) 5 The point $(1, p, q)$ lies on the line l . Find the values of p and q , given that the equation of l is:

a $\mathbf{r} = \begin{pmatrix} 2 \\ -3 \\ 1 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ -4 \\ -9 \end{pmatrix}$ b $\mathbf{r} = \begin{pmatrix} -4 \\ 6 \\ -1 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ -5 \\ -8 \end{pmatrix}$ c $\mathbf{r} = \begin{pmatrix} 16 \\ -9 \\ -10 \end{pmatrix} + \lambda \begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix}$

- (P) 6 The line l_1 has equation $\mathbf{r} = \begin{pmatrix} 2 \\ 1 \\ -3 \end{pmatrix} + \lambda \begin{pmatrix} -1 \\ 2 \\ 4 \end{pmatrix}$. The line l_2 has equation $\frac{x - 4}{2} = \frac{y + 1}{-4} = \frac{z - 3}{-8}$

Show that l_1 and l_2 are parallel.

- (P) 7 Show that the line l_1 with equation $\mathbf{r} = (3 + 2\lambda)\mathbf{i} + (2 - 3\lambda)\mathbf{j} + (-1 + 4\lambda)\mathbf{k}$ is parallel to the line l_2 which passes through the points $A(5, 4, -1)$ and $B(3, 7, -5)$.

- 8 Show that the points

$A(-3, -4, 5)$, $B(3, -1, 2)$ and $C(9, 2, -1)$ are collinear.

Hint Points are said to be **collinear** if they all lie on the same straight line.

- 9 Show that the points with position vectors $\begin{pmatrix} 1 \\ 7 \\ -2 \end{pmatrix}$, $\begin{pmatrix} 3 \\ -1 \\ 8 \end{pmatrix}$ and $\begin{pmatrix} 10 \\ 4 \\ 0 \end{pmatrix}$ do not lie on the same straight line.

- E/P** 10 The points $P(2, 0, 4)$, $Q(a, 5, 1)$ and $R(3, 10, b)$, where a and b are constants, are collinear. Find the values of a and b . (5 marks)

- E** 11 The line l_1 has equation

$$\mathbf{r} = (8\mathbf{i} - 5\mathbf{j} + 4\mathbf{k}) + \lambda(3\mathbf{i} + \mathbf{j} - 6\mathbf{k})$$

A is the point on l_1 such that $\lambda = -2$.

The line l_2 passes through A and is parallel to the line with equation

$$\mathbf{r} = (10\mathbf{i} + 3\mathbf{j} - 9\mathbf{k}) + \lambda(2\mathbf{i} - 4\mathbf{j} + \mathbf{k})$$

Find an equation for l_2 . (6 marks)

- E/P** 12 The point A with coordinates $(4, a, 0)$ lies on the line L with vector equation

$$\mathbf{r} = (10\mathbf{i} + 8\mathbf{j} - 12\mathbf{k}) + \lambda(\mathbf{i} - \mathbf{j} + b\mathbf{k})$$

where a and b are constants.

- a** Find the values of a and b . (3 marks)

The point X lies on L where $\lambda = -1$.

- b** Find the coordinates of X . (1 mark)

- E** 13 The line l has equation $\mathbf{r} = \begin{pmatrix} 3 \\ -5 \\ 9 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 2 \\ -2 \end{pmatrix}$.

A and B are the points on l with $\lambda = 5$ and $\lambda = 2$ respectively.

Find the distance AB . (4 marks)

- E** 14 The line l has equation $\mathbf{r} = \begin{pmatrix} 1 \\ -2 \\ 3 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix}$.

C and A are the points on l with $\lambda = 4$ and $\lambda = 3$ respectively.

A circle has centre C and intersects l at the points A and B .

Find the position vector of B . (3 marks)

- E/P** 15 The line l has equation $x - 5 = \frac{y + 1}{3} = \frac{z - 6}{-2}$

A circle C has centre $(4, -1, 2)$ and radius $3\sqrt{5}$.

Given that C intersects l at two distinct points, A and B , find the coordinates of A and B . (7 marks)

Problem-solving

Write $x - 5$ as $\frac{x - 5}{1}$ and convert the equation of the line into vector form.

- E/P** 16 The line l_1 has equation $\mathbf{r} = \begin{pmatrix} -4 \\ 6 \\ 5 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix}$. A and B are the points on l_1 with $\lambda = 2$ and $\lambda = 5$ respectively.

- a** Find the position vectors of A and B . (2 marks)

The point P has position vector $\begin{pmatrix} 0 \\ 2 \\ 3 \end{pmatrix}$.

The line l_2 passes through the point P and is parallel to the line l_1 .

- b** Find a vector equation of the line l_2 . (2 marks)

The points C and D both lie on line l_2 such that $AB = AC = AD$.

- c** Show that P is the midpoint of CD . (7 marks)

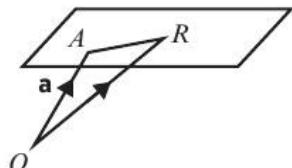
- E/P** 17 A tightrope is modelled as a line segment between points with coordinates $(2, 3, 8)$ and $(22, 18, 8)$, relative to a fixed origin O , where the units of distance are metres. Two support cables are anchored to a fixed point A on the wire. The other ends of the cables are anchored to points with coordinates $(14, 1, 0)$ and $(6, 17, 0)$ respectively.
- Given that the support cables are both 12 m long, find the coordinates of A . **(8 marks)**
 - Give one criticism of this model. **(1 mark)**

9.2 Equation of a plane in three dimensions

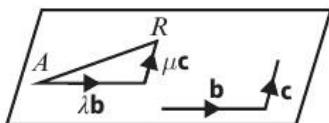
The equation of a plane can be written in vector form.

Suppose a plane passes through a given point A , with position vector \mathbf{a} . Let R be an arbitrary point on the plane, with position vector \mathbf{r} .

Then, using the triangle law, $\mathbf{r} = \mathbf{a} + \overrightarrow{AR}$.



Since \overrightarrow{AR} lies in the plane, it can be written as $\lambda\mathbf{b} + \mu\mathbf{c}$, where \mathbf{b} and \mathbf{c} are non-parallel vectors in the plane and where λ and μ are scalars.



So the position vector \mathbf{r} can be written as $\mathbf{r} = \mathbf{a} + \lambda\mathbf{b} + \mu\mathbf{c}$.

■ **The vector equation of a plane is $\mathbf{r} = \mathbf{a} + \lambda\mathbf{b} + \mu\mathbf{c}$, where:**

- **\mathbf{r} is the position vector of a general point in the plane**
- **\mathbf{a} is the position vector of a point in the plane**
- **\mathbf{b} and \mathbf{c} are non-parallel, non-zero vectors in the plane**
- **λ and μ are scalars**

Example 7

Find, in the form $\mathbf{r} = \mathbf{a} + \lambda\mathbf{b} + \mu\mathbf{c}$, an equation of the plane that passes through the points $A(2, 2, -1)$, $B(3, 2, -1)$ and $C(4, 3, 5)$.

\overrightarrow{AB} and \overrightarrow{AC} are vectors which lie in the plane.

$$\overrightarrow{AB} = \overrightarrow{OB} - \overrightarrow{OA} = \mathbf{i}$$

$$\overrightarrow{AC} = \overrightarrow{OC} - \overrightarrow{OA} = 2\mathbf{i} + \mathbf{j} + 6\mathbf{k}$$

So an equation of the plane is

$$\mathbf{r} = 2\mathbf{i} + 2\mathbf{j} - \mathbf{k} + \lambda\mathbf{i} + \mu(2\mathbf{i} + \mathbf{j} + 6\mathbf{k})$$

There are many other forms of this answer which are also correct. You could use $3\mathbf{i} + 2\mathbf{j} - \mathbf{k}$ or $4\mathbf{i} + 3\mathbf{j} + 5\mathbf{k}$ instead of $2\mathbf{i} + 2\mathbf{j} - \mathbf{k}$ in the equation.

You could write this equation as

$$\mathbf{r} = \begin{pmatrix} 2 \\ 2 \\ -1 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \mu \begin{pmatrix} 2 \\ 1 \\ 6 \end{pmatrix}$$

Example 8

Verify that the point P with position vector $\begin{pmatrix} 2 \\ 2 \\ -1 \end{pmatrix}$ lies in the plane with vector equation
 $\mathbf{r} = \begin{pmatrix} 3 \\ 4 \\ -2 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix}$

$$\mathbf{r} = \begin{pmatrix} 3 + 2\lambda + \mu \\ 4 + \lambda - \mu \\ -2 + \lambda + 2\mu \end{pmatrix}$$

If P lies on the plane,

$$\begin{pmatrix} 2 \\ 2 \\ -1 \end{pmatrix} = \begin{pmatrix} 3 + 2\lambda + \mu \\ 4 + \lambda - \mu \\ -2 + \lambda + 2\mu \end{pmatrix}$$

$$2 = 3 + 2\lambda + \mu \text{ so } 2\lambda + \mu = -1 \quad (1)$$

$$2 = 4 + \lambda - \mu \text{ so } \lambda - \mu = -2 \quad (2)$$

$$-1 = -2 + \lambda + 2\mu \text{ so } \lambda + 2\mu = 1 \quad (3)$$

Solving equations (2) and (3) simultaneously,

$$(3) - (2): \quad 3\mu = 3 \quad \text{so} \quad \mu = 1$$

$$\text{Sub in (2):} \quad \lambda - 1 = -2 \quad \text{so} \quad \lambda = -1$$

Check in equation (1):

$$2\lambda + \mu = -2 + 1 = -1 \text{ so } P \text{ lies in the plane.}$$

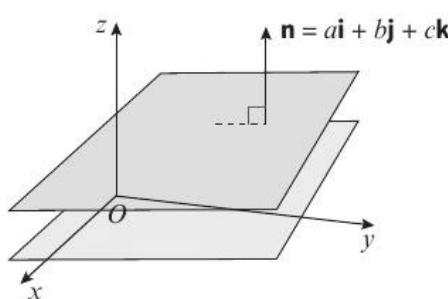
The position vector of any point on the plane can be written in this form.

Problem-solving

If the point P lies on the plane then there will be values of λ and μ that satisfy **all three** of these equations simultaneously. Solve one pair of equations simultaneously, then check that the solutions satisfy the third equation.

The direction of a plane can be described by giving a **normal vector**, \mathbf{n} . This is a vector that is perpendicular to the plane.

One normal vector can describe an infinite number of parallel planes, so the normal vector on its own is not enough information to define a plane uniquely.



- A **Cartesian equation of a plane in three dimensions can be written in the form $ax + by + cz = d$ where a, b, c and d are constants, and $\begin{pmatrix} a \\ b \\ c \end{pmatrix}$ is the normal vector to the plane.**

Note Compare this equation to the Cartesian equation of a line in two dimensions: $ax + by = c$.

Online Explore the vector and Cartesian equations of a plane using GeoGebra.



You can derive this result using the **scalar product**, which you will learn about later in this chapter.

Example 9

The plane Π is perpendicular to the normal vector $\mathbf{n} = 3\mathbf{i} - 2\mathbf{j} + \mathbf{k}$ and passes through the point P with position vector $8\mathbf{i} + 4\mathbf{j} - 7\mathbf{k}$.

Find a Cartesian equation of Π .

$$3x - 2y + z = d \quad \text{---} \\ 3 \times 8 - 2 \times 4 + 1 \times (-7) = 9 \quad \text{---}$$

So $d = 9$ and the Cartesian equation of Π is
 $3x - 2y + z = 9$.

Notation

Planes are often represented by the capital Greek letter pi, Π .

The general equation is $ax + by + cz = d$ where
the normal vector is $\begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix}$.

Substitute the values of x , y and z for point P into
this question to find the value of d .

Exercise 9B

1 Find, in the form $\mathbf{r} = \mathbf{a} + \lambda\mathbf{b} + \mu\mathbf{c}$, an equation of the plane that passes through the points:

- a $(1, 2, 0)$, $(3, 1, -1)$ and $(4, 3, 2)$
b $(3, 4, 1)$, $(-1, -2, 0)$ and $(2, 1, 4)$
c $(2, -1, -1)$, $(3, 1, 2)$ and $(4, 0, 1)$
d $(-1, 1, 3)$, $(-1, 2, 5)$ and $(0, 4, 4)$.

2 The plane Π is perpendicular to the normal vector $\begin{pmatrix} -1 \\ 3 \\ 2 \end{pmatrix}$ and passes through the point with
position vector $\begin{pmatrix} 4 \\ -2 \\ 6 \end{pmatrix}$. Find a Cartesian equation of Π .

(P) 3 Find the value of k , given that the plane Π with vector equation $\mathbf{r} = \begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix} + \lambda\begin{pmatrix} 3 \\ 2 \\ -2 \end{pmatrix} + \mu\begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix}$
passes through the points:

- a $(7, -1, k)$ b $(1, k, 11)$ c $(k, -4, 10)$ d $(10, k, -k)$

4 A Cartesian equation of the plane Π is $2x - 3y + 5z = 1$.

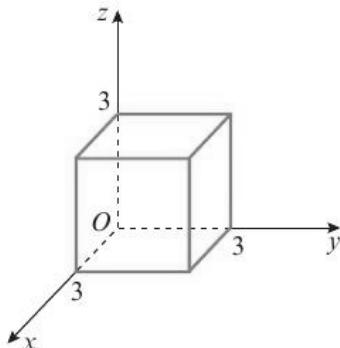
- a Verify that the plane passes through the point: i $(1, 2, 1)$ ii $(2, -4, -3)$
b Write down an equation of a normal vector to the plane.

5 The line l is normal to the plane Π with Cartesian equation $5x - 3y - 4z = 9$ and passes through the point $(2, 3, -2)$. Find:

- a a vector equation of l b a Cartesian equation of l

6 The diagram shows a cube with a vertex at the origin and sides of length 3.

Find a Cartesian equation for each face of the cube.



- E/P** 7 Show that the points $(2, 2, 3)$, $(1, 5, 3)$, $(4, 3, -1)$ and $(3, 6, -1)$ are coplanar. **(6 marks)**

Notation Points are said to be **coplanar** if they all lie on the same plane.

- E/P** 8 Show that the points $(2, 3, 4)$, $(2, -1, 3)$, $(5, 3, -2)$ and $(-1, -9, 8)$ are not coplanar. **(6 marks)**

- E/P** 9 The plane Π has vector equation $\mathbf{r} = 3\mathbf{i} - 2\mathbf{j} + \mathbf{k} + \lambda(-2\mathbf{i} + 3\mathbf{j} + 5\mathbf{k}) + \mu(4\mathbf{i} + 2\mathbf{j} - 3\mathbf{k})$. The point A lies on Π such that $\lambda = 1$ and $\mu = 2$.

- a Find the position vector of A . **(2 marks)**

Point B has position vector $(1, -7, 2)$.

- b Show that B lies on Π . **(2 marks)**

The line l passes through points A and B .

- c Find a vector equation of l . **(3 marks)**

The point C lies on l such that $|\overrightarrow{OA}| = |\overrightarrow{OC}|$.

- d Find the position vector of C . **(3 marks)**

Challenge

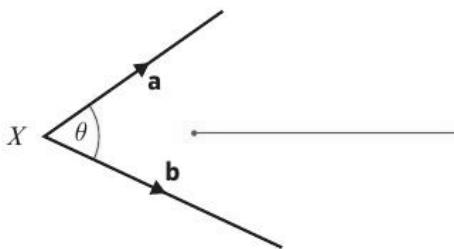
A plane has vector equation $\mathbf{r} = 2\mathbf{i} + 3\mathbf{j} + \lambda(\mathbf{i} - 2\mathbf{j} + \mathbf{k}) + \mu(2\mathbf{i} - \mathbf{j} + 3\mathbf{k})$.

A line has vector equation $\mathbf{r} = (2\mathbf{i} + 6\mathbf{j} + \mathbf{k}) + t(5\mathbf{i} - 7\mathbf{j} + 6\mathbf{k})$.

Show that the line lies entirely within the plane.

9.3 Scalar product

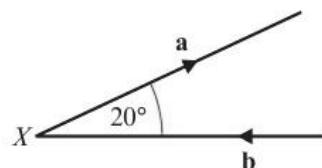
You need to know the definition of the scalar product of two vectors in either two or three dimensions, and how it can be used to find the angle between two vectors. To define the scalar product you need to know how to find the **angle between two vectors**.



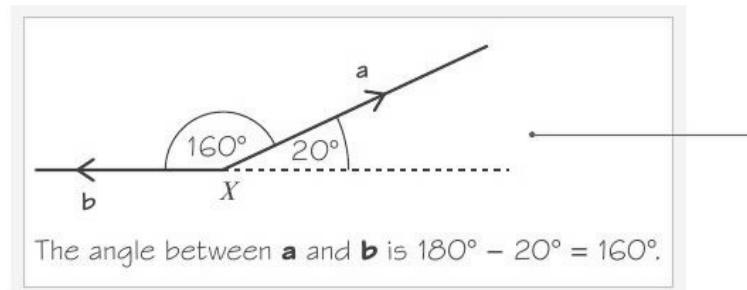
On the diagram, the angle between the vectors \mathbf{a} and \mathbf{b} is θ . Notice that \mathbf{a} and \mathbf{b} are both directed away from the point X .

Example 10

Find the angle between the vectors \mathbf{a} and \mathbf{b} on the diagram.



For the correct angle, \mathbf{a} and \mathbf{b} must both be pointing away from X , so re-draw to show this.

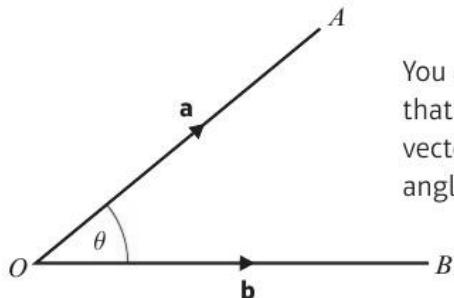


The angle between \mathbf{a} and \mathbf{b} is $180^\circ - 20^\circ = 160^\circ$.

- The scalar product of two vectors \mathbf{a} and \mathbf{b} is written as $\mathbf{a} \cdot \mathbf{b}$, and defined as

$$\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos \theta$$

where θ is the angle between \mathbf{a} and \mathbf{b} .



You can see from this diagram that if \mathbf{a} and \mathbf{b} are the position vectors of A and B , then the angle between \mathbf{a} and \mathbf{b} is $\angle AOB$.

Notation The scalar product is often called the **dot product**. You say 'a dot b'.

Online Use GeoGebra to consider the scalar product as the component of one vector in the direction of another.



- If \mathbf{a} and \mathbf{b} are the position vectors of the points A and B , then $\cos(\angle AOB) = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}| |\mathbf{b}|}$

If two vectors \mathbf{a} and \mathbf{b} are perpendicular, the angle between them is 90° .

Since $\cos 90^\circ = 0$, $\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos 90^\circ = 0$.

- The non-zero vectors \mathbf{a} and \mathbf{b} are perpendicular if and only if $\mathbf{a} \cdot \mathbf{b} = 0$.

If \mathbf{a} and \mathbf{b} are parallel, the angle between them is 0° .

- If \mathbf{a} and \mathbf{b} are parallel, $\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}|$. In particular, $\mathbf{a} \cdot \mathbf{a} = |\mathbf{a}|^2$.

Example 11

Find the values of

a $\mathbf{i} \cdot \mathbf{j}$

b $\mathbf{k} \cdot \mathbf{k}$

c $(4\mathbf{j}) \cdot \mathbf{k} + (3\mathbf{i}) \cdot (3\mathbf{i})$

a $\mathbf{i} \cdot \mathbf{j} = 1 \times 1 \times \cos 90^\circ = 0$

\mathbf{i} and \mathbf{j} are unit vectors (magnitude 1), and are perpendicular.

b $\mathbf{k} \cdot \mathbf{k} = 1 \times 1 \times \cos 0^\circ = 1$

\mathbf{k} is a unit vector (magnitude 1) and the angle between \mathbf{k} and itself is 0° .

c $(4\mathbf{j}) \cdot \mathbf{k} + (3\mathbf{i}) \cdot (3\mathbf{i})$
 $= (4 \times 1 \times \cos 90^\circ) + (3 \times 3 \times \cos 0^\circ)$
 $= 0 + 9 = 9$

Example 12

Given that $\mathbf{a} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$ and $\mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$, prove that $\mathbf{a} \cdot \mathbf{b} = a_1 b_1 + a_2 b_2 + a_3 b_3$.

$$\begin{aligned}
 \mathbf{a} \cdot \mathbf{b} &= (a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k}) \cdot (b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k}) \\
 &= a_1\mathbf{i} \cdot (b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k}) \\
 &\quad + a_2\mathbf{j} \cdot (b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k}) \\
 &\quad + a_3\mathbf{k} \cdot (b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k}) \\
 &= (a_1\mathbf{i}) \cdot (b_1\mathbf{i}) + (a_1\mathbf{i}) \cdot (b_2\mathbf{j}) + (a_1\mathbf{i}) \cdot (b_3\mathbf{k}) \\
 &\quad + (a_2\mathbf{j}) \cdot (b_1\mathbf{i}) + (a_2\mathbf{j}) \cdot (b_2\mathbf{j}) + (a_2\mathbf{j}) \cdot (b_3\mathbf{k}) \\
 &\quad + (a_3\mathbf{k}) \cdot (b_1\mathbf{i}) + (a_3\mathbf{k}) \cdot (b_2\mathbf{j}) + (a_3\mathbf{k}) \cdot (b_3\mathbf{k}) \\
 &= (a_1b_1)\mathbf{i} \cdot \mathbf{i} + (a_1b_2)\mathbf{i} \cdot \mathbf{j} + (a_1b_3)\mathbf{i} \cdot \mathbf{k} \\
 &\quad + (a_2b_1)\mathbf{j} \cdot \mathbf{i} + (a_2b_2)\mathbf{j} \cdot \mathbf{j} + (a_2b_3)\mathbf{j} \cdot \mathbf{k} \\
 &\quad + (a_3b_1)\mathbf{k} \cdot \mathbf{i} + (a_3b_2)\mathbf{k} \cdot \mathbf{j} + (a_3b_3)\mathbf{k} \cdot \mathbf{k} \\
 &= a_1b_1 + a_2b_2 + a_3b_3
 \end{aligned}$$

Use the results for parallel and perpendicular unit vectors:

$$\mathbf{i} \cdot \mathbf{i} = \mathbf{j} \cdot \mathbf{j} = \mathbf{k} \cdot \mathbf{k} = 1$$

$$\mathbf{i} \cdot \mathbf{j} = \mathbf{i} \cdot \mathbf{k} = \mathbf{j} \cdot \mathbf{i} = \mathbf{j} \cdot \mathbf{k} = \mathbf{k} \cdot \mathbf{i} = \mathbf{k} \cdot \mathbf{j} = 0$$

The above example leads to a simple formula for finding the scalar product of two vectors given in Cartesian component form:

■ If $\mathbf{a} = a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k}$ and $\mathbf{b} = b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k}$,

$$\mathbf{a} \cdot \mathbf{b} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \cdot \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = a_1b_1 + a_2b_2 + a_3b_3$$

You can use this result without proof in your exam.

Example 13

Given that $\mathbf{a} = 8\mathbf{i} - 5\mathbf{j} - 4\mathbf{k}$ and $\mathbf{b} = 5\mathbf{i} + 4\mathbf{j} - \mathbf{k}$,

- a Find $\mathbf{a} \cdot \mathbf{b}$.
- b Find the angle between \mathbf{a} and \mathbf{b} , giving your answer in degrees to 1 decimal place.

$$\begin{aligned}
 \mathbf{a} \cdot \mathbf{b} &= \begin{pmatrix} 8 \\ -5 \\ -4 \end{pmatrix} \cdot \begin{pmatrix} 5 \\ 4 \\ -1 \end{pmatrix} \\
 &= (8 \times 5) + (-5 \times 4) + (-4 \times -1)
 \end{aligned}$$

Write in column vector form.

$$\begin{aligned}
 &= 40 - 20 + 4 \\
 &= 24
 \end{aligned}$$

Use $\mathbf{a} \cdot \mathbf{b} = a_1b_1 + a_2b_2 + a_3b_3$.

$$\mathbf{b} \cdot \mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos \theta$$

Use the scalar product definition.

$$|\mathbf{a}| = \sqrt{8^2 + (-5)^2 + (-4)^2} = \sqrt{105}$$

Find the modulus of \mathbf{a} and of \mathbf{b} .

$$|\mathbf{b}| = \sqrt{5^2 + 4^2 + (-1)^2} = \sqrt{42}$$

$$\sqrt{105} \sqrt{42} \cos \theta = 24$$

Use $\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos \theta$.

$$\cos \theta = \frac{24}{\sqrt{105} \sqrt{42}}$$

$$\theta = 68.8^\circ \text{ (1 d.p.)}$$

Example 14

Given that $\mathbf{a} = -\mathbf{i} + \mathbf{j} + 3\mathbf{k}$ and $\mathbf{b} = 7\mathbf{i} - 2\mathbf{j} + 2\mathbf{k}$, find the angle between \mathbf{a} and \mathbf{b} , giving your answer in degrees to 1 decimal place.

$$\mathbf{a} \cdot \mathbf{b} = \begin{pmatrix} -1 \\ 1 \\ 3 \end{pmatrix} \cdot \begin{pmatrix} 7 \\ -2 \\ 2 \end{pmatrix} = -7 - 2 + 6 = -3$$

$$|\mathbf{a}| = \sqrt{(-1)^2 + 1^2 + 3^2} = \sqrt{11}$$

$$|\mathbf{b}| = \sqrt{7^2 + (-2)^2 + 2^2} = \sqrt{57}$$

$$\sqrt{11}\sqrt{57} \cos \theta = -3$$
$$\cos \theta = \frac{-3}{\sqrt{11}\sqrt{57}}$$
$$\theta = 96.9^\circ \text{ (1 d.p.)}$$

For the scalar product formula, you need to find $\mathbf{a} \cdot \mathbf{b}$, $|\mathbf{a}|$ and $|\mathbf{b}|$.

Use $\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}||\mathbf{b}| \cos \theta$.

The cosine is negative, so the angle is obtuse.

Example 15

Given that the vectors $\mathbf{a} = 2\mathbf{i} - 6\mathbf{j} + \mathbf{k}$ and $\mathbf{b} = 5\mathbf{i} + 2\mathbf{j} + \lambda\mathbf{k}$ are perpendicular, find the value of λ .

$$\mathbf{a} \cdot \mathbf{b} = \begin{pmatrix} 2 \\ -6 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 5 \\ 2 \\ \lambda \end{pmatrix}$$

$$= 10 - 12 + \lambda$$

$$= -2 + \lambda$$

$$-2 + \lambda = 0$$

$$\lambda = 2$$

Find the scalar product.

For perpendicular vectors, the scalar product is zero.

Example 16

Given that $\mathbf{a} = -2\mathbf{i} + 5\mathbf{j} - 4\mathbf{k}$ and $\mathbf{b} = 4\mathbf{i} - 8\mathbf{j} + 5\mathbf{k}$, find a vector which is perpendicular to both \mathbf{a} and \mathbf{b} .

$$\mathbf{a} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 0 \text{ and } \mathbf{b} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 0$$

$$\begin{pmatrix} -2 \\ 5 \\ -4 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 0 \text{ and } \begin{pmatrix} 4 \\ -8 \\ 5 \end{pmatrix} \cdot \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 0$$

$$-2x + 5y - 4z = 0 \quad (1)$$

$$4x - 8y + 5z = 0 \quad (2)$$

Both scalar products are zero.

Let $z = 1$ ←
 $-2x + 5y = 4$ (from 1)
 $4x - 8y = -5$ (from 2)
So $x = \frac{7}{4}$, $y = \frac{3}{2}$ and $z = 1$

A possible vector is $\frac{7}{4}\mathbf{i} + \frac{3}{2}\mathbf{j} + \mathbf{k}$. ←

Another possible vector is
 $4(\frac{7}{4}\mathbf{i} + \frac{3}{2}\mathbf{j} + \mathbf{k}) = 7\mathbf{i} + 6\mathbf{j} + 4\mathbf{k}$ ←

Choose a (non-zero) value for z (or for x , or for y).

Solving simultaneously gives
 $x = \frac{7}{4}$ and $y = \frac{3}{2}$

You can multiply by a scalar constant to find another vector which is also perpendicular to both \mathbf{a} and \mathbf{b} .

Example 17

The points A , B and C have coordinates $(2, -1, 1)$, $(5, 1, 7)$ and $(6, -3, 1)$ respectively.

- a Find $\overrightarrow{AB} \cdot \overrightarrow{AC}$
- b Hence, or otherwise, find the area of triangle ABC .

a $\overrightarrow{AB} = \begin{pmatrix} 3 \\ 2 \\ 6 \end{pmatrix}$ and $\overrightarrow{AC} = \begin{pmatrix} 4 \\ -2 \\ 0 \end{pmatrix}$

$$\overrightarrow{AB} \cdot \overrightarrow{AC} = 3 \times 4 + 2 \times (-2) + 6 \times 0 = 8$$

b $|\overrightarrow{AB}| = \sqrt{3^2 + 2^2 + 6^2} = 7$

$$|\overrightarrow{AC}| = \sqrt{4^2 + (-2)^2 + 0^2} = 2\sqrt{5}$$

$$\begin{aligned} \cos(\angle BAC) &= \frac{\overrightarrow{AB} \cdot \overrightarrow{AC}}{|\overrightarrow{AB}| |\overrightarrow{AC}|} \\ &= \frac{8}{7 \times 2\sqrt{5}} \\ &= 0.2555\dots \end{aligned}$$

$$\angle BAC = 75.1937\dots^\circ$$

$$\begin{aligned} \text{Area} &= \frac{1}{2} |\overrightarrow{AB}| |\overrightarrow{AC}| \sin(\angle BAC) \\ &= \frac{1}{2} \times 7 \times 2\sqrt{5} \sin(75.1937\dots^\circ) \\ &= 15.13 \text{ (2 d.p.)} \end{aligned}$$

Use the scalar product to find the angle between \overrightarrow{AB} and \overrightarrow{AC} . Then use $\text{area} = \frac{1}{2}ab \sin \theta$ to find the area of the triangle.

Problem-solving

You could find $\angle BAC$ by finding the lengths AB , BC and AC and using the cosine rule, but it is quicker to use a vector method.

Exercise 9C

- 1 The vectors \mathbf{a} and \mathbf{b} each have magnitude 3, and the angle between \mathbf{a} and \mathbf{b} is 60° . Find $\mathbf{a} \cdot \mathbf{b}$.
- 2 For each pair of vectors, find $\mathbf{a} \cdot \mathbf{b}$:
- a $\mathbf{a} = 5\mathbf{i} + 2\mathbf{j} + 3\mathbf{k}$, $\mathbf{b} = 2\mathbf{i} - \mathbf{j} - 2\mathbf{k}$
c $\mathbf{a} = \mathbf{i} + \mathbf{j} - \mathbf{k}$, $\mathbf{b} = -\mathbf{i} - \mathbf{j} + 4\mathbf{k}$
e $\mathbf{a} = 3\mathbf{j} + 9\mathbf{k}$, $\mathbf{b} = \mathbf{i} - 12\mathbf{j} + 4\mathbf{k}$
- b $\mathbf{a} = 10\mathbf{i} - 7\mathbf{j} + 4\mathbf{k}$, $\mathbf{b} = 3\mathbf{i} - 5\mathbf{j} - 12\mathbf{k}$
d $\mathbf{a} = 2\mathbf{i} - \mathbf{k}$, $\mathbf{b} = 6\mathbf{i} - 5\mathbf{j} - 8\mathbf{k}$
- 3 In each part, find the angle between \mathbf{a} and \mathbf{b} , giving your answer in degrees to 1 decimal place:
- a $\mathbf{a} = 3\mathbf{i} + 7\mathbf{j}$, $\mathbf{b} = 5\mathbf{i} + \mathbf{j}$
c $\mathbf{a} = \mathbf{i} - 7\mathbf{j} + 8\mathbf{k}$, $\mathbf{b} = 12\mathbf{i} + 2\mathbf{j} + \mathbf{k}$
e $\mathbf{a} = 6\mathbf{i} - 7\mathbf{j} + 12\mathbf{k}$, $\mathbf{b} = -2\mathbf{i} + \mathbf{j} + \mathbf{k}$
g $\mathbf{a} = -5\mathbf{i} + 2\mathbf{j} - 3\mathbf{k}$, $\mathbf{b} = 2\mathbf{i} - 2\mathbf{j} - 11\mathbf{k}$
- b $\mathbf{a} = 2\mathbf{i} - 5\mathbf{j}$, $\mathbf{b} = 6\mathbf{i} + 3\mathbf{j}$
d $\mathbf{a} = -\mathbf{i} - \mathbf{j} + 5\mathbf{k}$, $\mathbf{b} = 11\mathbf{i} - 3\mathbf{j} + 4\mathbf{k}$
f $\mathbf{a} = 4\mathbf{i} + 5\mathbf{k}$, $\mathbf{b} = 6\mathbf{i} - 2\mathbf{j}$
h $\mathbf{a} = \mathbf{i} + \mathbf{j} + \mathbf{k}$, $\mathbf{b} = \mathbf{i} - \mathbf{j} + \mathbf{k}$
- 4 Find the value, or values, of λ for which the given vectors are perpendicular:
- a $3\mathbf{i} + 5\mathbf{j}$ and $\lambda\mathbf{i} + 6\mathbf{j}$
c $3\mathbf{i} + \lambda\mathbf{j} - 8\mathbf{k}$ and $7\mathbf{i} - 5\mathbf{j} + \mathbf{k}$
e $\lambda\mathbf{j} + 3\mathbf{j} - 2\mathbf{k}$ and $\lambda\mathbf{i} + \lambda\mathbf{j} + 5\mathbf{k}$
- b $2\mathbf{i} + 6\mathbf{j} - \mathbf{k}$ and $\lambda\mathbf{i} - 4\mathbf{j} - 14\mathbf{k}$
d $9\mathbf{i} - 3\mathbf{j} + 5\mathbf{k}$ and $\lambda\mathbf{i} + \lambda\mathbf{j} + 3\mathbf{k}$
- 5 Find, to the nearest tenth of a degree, the angle that the vector $9\mathbf{i} - 5\mathbf{j} + 3\mathbf{k}$ makes with:
- a the positive x -axis
b the positive y -axis
- 6 Find, to the nearest tenth of a degree, the angle that the vector $\mathbf{i} + 11\mathbf{j} - 4\mathbf{k}$ makes with:
- a the positive y -axis
b the positive z -axis
- 7 The angle between the vectors $\mathbf{i} + \mathbf{j} + \mathbf{k}$ and $2\mathbf{i} + \mathbf{j} + \mathbf{k}$ is θ . Calculate the exact value of $\cos \theta$.
- 8 The angle between the vectors $\mathbf{i} + 3\mathbf{j}$ and $\mathbf{j} + \lambda\mathbf{k}$ is 60° . Show that $\lambda = \pm \sqrt{\frac{13}{5}}$
- 9 Find a vector which is perpendicular to both \mathbf{a} and \mathbf{b} , where:
- a $\mathbf{a} = \mathbf{i} + \mathbf{j} - 3\mathbf{k}$, $\mathbf{b} = 5\mathbf{i} - 2\mathbf{j} - \mathbf{k}$
c $\mathbf{a} = 4\mathbf{i} - 4\mathbf{j} - \mathbf{k}$, $\mathbf{b} = -2\mathbf{i} - 9\mathbf{j} + 6\mathbf{k}$
- b $\mathbf{a} = 2\mathbf{i} + 3\mathbf{j} - 4\mathbf{k}$, $\mathbf{b} = \mathbf{i} - 6\mathbf{j} + 3\mathbf{k}$
- 10 The points A and B have position vectors $2\mathbf{i} + 5\mathbf{j} + \mathbf{k}$ and $6\mathbf{i} + \mathbf{j} - 2\mathbf{k}$ respectively, and O is the origin. Calculate each of the angles in $\triangle OAB$, giving your answers in degrees to 1 decimal place.
- 11 The points A , B and C have coordinates $(1, 3, 1)$, $(2, 7, -3)$ and $(4, -5, 2)$ respectively.
- a Find the exact lengths of AB and BC .
b Calculate, to one decimal place, the size of $\angle ABC$.
- E/P 12 Given that the points A and B have coordinates $(7, 4, 4)$ and $(2, 2, 1)$ respectively,
- a find the value of $\cos \angle AOB$, where O is the origin (4 marks)
b show that the area of $\triangle AOB$ is $\frac{\sqrt{53}}{2}$ (3 marks)

- P** 13 AB is a diameter of a circle centred at the origin O , and P is a point on the circumference of the circle. By considering the position vectors of A , B and P , prove that AP is perpendicular to BP .

Problem-solving

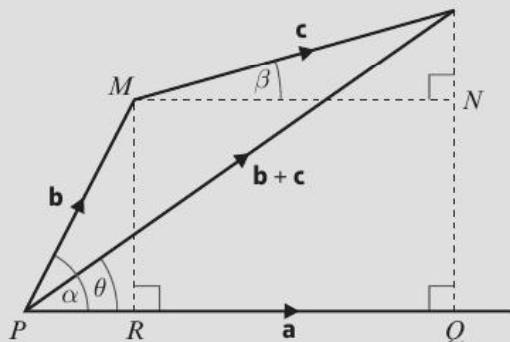
This is a vector proof of the fact that the angle in a semi-circle is 90° .

- E/P** 14 Points A , B and C have coordinates $(5, -1, 0)$, $(2, 4, 10)$ and $(6, -1, 4)$ respectively.
- Find the vectors \overrightarrow{CA} and \overrightarrow{CB} . (2 marks)
 - Find the area of the triangle ABC . (4 marks)
 - Point D is such that A , B , C and D are the vertices of a parallelogram. Find the coordinates of three possible positions of D . (3 marks)
 - Write down the area of the parallelogram. (1 mark)

- E/P** 15 The points P , Q and R have coordinates $(1, -1, 6)$, $(-2, 5, 4)$ and $(0, 3, -5)$ respectively.
- Show that PQ is perpendicular to QR . (3 marks)
 - Hence find the centre and radius of the circle that passes through points P , Q and R . (3 marks)

Challenge

- Using the definition $\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos \theta$, prove that $\mathbf{a} \cdot \mathbf{b} = \mathbf{b} \cdot \mathbf{a}$.
- The diagram shows arbitrary vectors \mathbf{a} , \mathbf{b} and \mathbf{c} , and the vector $\mathbf{b} + \mathbf{c}$.



- Show that:
 - $\mathbf{a} \cdot (\mathbf{b} + \mathbf{c}) = |\mathbf{a}| \times PQ$
 - $\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| \times PR$
 - $\mathbf{a} \cdot \mathbf{c} = |\mathbf{a}| \times RQ$
- Hence prove that $\mathbf{a} \cdot (\mathbf{b} + \mathbf{c}) = \mathbf{a} \cdot \mathbf{b} + \mathbf{a} \cdot \mathbf{c}$.

9.4 Calculating angles between lines and planes

If two straight lines in three dimensions intersect, then you can calculate the size of the angle between them using the scalar product.

- The acute angle θ between two intersecting straight lines is given by**

$$\cos \theta = \left| \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}| |\mathbf{b}|} \right|$$

where \mathbf{a} and \mathbf{b} are direction vectors of the lines.

Watch out The modulus signs around the whole expression ensure you get an acute angle. If you need to work out the size of an **obtuse** angle between two lines, use the formula then subtract the resulting acute angle from 180° .

Example 18

The lines l_1 and l_2 have vector equations $\mathbf{r} = (2\mathbf{i} + \mathbf{j} + \mathbf{k}) + t(3\mathbf{i} - 8\mathbf{j} - \mathbf{k})$ and $\mathbf{r} = (7\mathbf{i} + 4\mathbf{j} + \mathbf{k}) + s(2\mathbf{i} + 2\mathbf{j} + 3\mathbf{k})$ respectively.

Given that l_1 and l_2 intersect, find the size of the acute angle between the lines to one decimal place.

$$\mathbf{a} = \begin{pmatrix} 3 \\ -8 \\ -1 \end{pmatrix} \text{ and } \mathbf{b} = \begin{pmatrix} 2 \\ 2 \\ 3 \end{pmatrix}$$

$$\cos \theta = \left| \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}| |\mathbf{b}|} \right|$$

$$\mathbf{a} \cdot \mathbf{b} = \begin{pmatrix} 3 \\ -8 \\ -1 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 2 \\ 3 \end{pmatrix}$$

$$= 6 - 16 - 3 = -13$$

$$|\mathbf{a}| = \sqrt{3^2 + (-8)^2 + (-1)^2} = \sqrt{74}$$

$$|\mathbf{b}| = \sqrt{2^2 + 2^2 + 3^2} = \sqrt{17}$$

$$\cos \theta = \left| \frac{-13}{\sqrt{74} \sqrt{17}} \right|$$

$$\theta = 68.5^\circ \text{ (1 d.p.)}$$

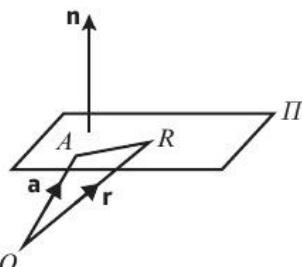
Use the direction vectors.

Use the formula. Be careful with the modulus signs. If $\cos \theta$ is positive then θ will be an acute angle, as required.

You can use the scalar product to write a vector equation of a plane efficiently.

Suppose a plane Π passes through a given point A , with position vector \mathbf{a} , and that the normal vector \mathbf{n} is perpendicular to the plane. Let R be an arbitrary point on the plane, with position vector \mathbf{r} .

Then, $\overrightarrow{AR} = \mathbf{r} - \mathbf{a}$



As \overrightarrow{AR} is a vector which lies in the plane, \overrightarrow{AR} is perpendicular to \mathbf{n} so $\overrightarrow{AR} \cdot \mathbf{n} = 0$.

This means $(\mathbf{r} - \mathbf{a}) \cdot \mathbf{n} = 0$

You can rewrite this as $\mathbf{r} \cdot \mathbf{n} = \mathbf{a} \cdot \mathbf{n}$

Since \mathbf{a} is a fixed point, $\mathbf{a} \cdot \mathbf{n}$ is a scalar constant, k , and the equation of the plane Π is $\mathbf{r} \cdot \mathbf{n} = k$.

■ The scalar product form of the equation of a plane is $\mathbf{r} \cdot \mathbf{n} = k$ where $k = \mathbf{a} \cdot \mathbf{n}$ for any point in the plane with position vector \mathbf{a} .

Example 19

The plane Π passes through the point A and is perpendicular to the vector \mathbf{n} .

Given that $\overrightarrow{OA} = \begin{pmatrix} 2 \\ 3 \\ -5 \end{pmatrix}$ and $\mathbf{n} = \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix}$ where O is the origin, find an equation of the plane:

a in scalar product form

b in Cartesian form

a $\mathbf{r} \cdot \mathbf{n} = k$, where $k = \mathbf{a} \cdot \mathbf{n}$.

$$\begin{aligned}\mathbf{a} \cdot \mathbf{n} &= \begin{pmatrix} 2 \\ 3 \\ -5 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix} \\ &= 2 \times 3 + 3 \times 1 + (-5) \times (-1) \\ &= 6 + 3 + 5 = 14\end{aligned}$$

So a scalar product form of the equation of Π is $\mathbf{r} \cdot \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix} = 14$.

b $\begin{pmatrix} x \\ y \\ z \end{pmatrix} \cdot \begin{pmatrix} 3 \\ 1 \\ -1 \end{pmatrix} = 14$

So a Cartesian form of equation of Π is $3x + y - z = 14$

Use $\mathbf{r} \cdot \mathbf{n} = k$ where $k = \mathbf{a} \cdot \mathbf{n}$ for any point in the plane with position vector \mathbf{a} .

Problem-solving

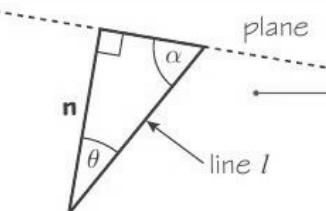
You can convert between scalar product form and Cartesian form quickly by writing the general position vector of a point in the plane as $\mathbf{r} = \begin{pmatrix} x \\ y \\ z \end{pmatrix}$.

You need to be able to calculate the angle between a line and a plane.

Example 20

Find the acute angle between the line l with equation $\mathbf{r} = 2\mathbf{i} + \mathbf{j} - 5\mathbf{k} + \lambda(3\mathbf{i} + 4\mathbf{j} - 12\mathbf{k})$ and the plane with equation $\mathbf{r} \cdot (2\mathbf{i} - 2\mathbf{j} - \mathbf{k}) = 2$.

Online Explore the angle between a line and a plane using GeoGebra.



The normal to the plane is in the direction

$$\mathbf{n} = 2\mathbf{i} - 2\mathbf{j} - \mathbf{k}$$

The angle between this normal and the line l is θ ,

$$\begin{aligned}\text{where } \cos \theta &= \frac{(3\mathbf{i} + 4\mathbf{j} - 12\mathbf{k}) \cdot (2\mathbf{i} - 2\mathbf{j} - \mathbf{k})}{\sqrt{3^2 + 4^2 + (-12)^2} \sqrt{2^2 + (-2)^2 + (-1)^2}} \\ &= \frac{10}{\sqrt{13} \times \sqrt{3}} = \frac{10}{39}\end{aligned}$$

So the angle between the plane and the line l is α where $\alpha + \theta = 90^\circ$.

$$\text{So } \sin \alpha = \frac{10}{39} \text{ and } \alpha = 14.9^\circ$$

Draw a diagram showing the line, the plane and the normal to the plane. Let the required angle be α and show α and θ in your diagram.

First find the angle between the given line and the normal to the plane.

Subtract the angle θ from 90° , to give angle α , or use the trigonometric connection that $\cos \theta = \sin \alpha$.

■ The acute angle θ between the line with equation $\mathbf{r} = \mathbf{a} + \lambda\mathbf{b}$ and the plane with equation $\mathbf{r} \cdot \mathbf{n} = k$ is given by the formula

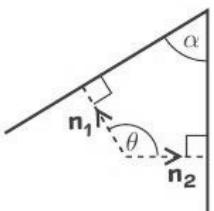
$$\sin \theta = \left| \frac{\mathbf{b} \cdot \mathbf{n}}{|\mathbf{b}| |\mathbf{n}|} \right|$$

You need to be able to calculate the angle between two planes.

Example 21

Find the acute angle between the planes with equations $\mathbf{r} \cdot (4\mathbf{i} + 4\mathbf{j} - 7\mathbf{k}) = 13$ and $\mathbf{r} \cdot (7\mathbf{i} - 4\mathbf{j} + 4\mathbf{k}) = 6$ respectively.

Online Visualise the angle between two planes using GeoGebra.



Draw a diagram showing the planes and the normals to the planes. Let the required angle be α and show α and θ in your diagram.

The normals to the planes are in the directions

$$\mathbf{n}_1 = 4\mathbf{i} + 4\mathbf{j} - 7\mathbf{k}, \text{ and } \mathbf{n}_2 = 7\mathbf{i} - 4\mathbf{j} + 4\mathbf{k}$$

The angle between these normals is θ , where

$$\begin{aligned}\cos \theta &= \frac{(4\mathbf{i} + 4\mathbf{j} - 7\mathbf{k}) \cdot (7\mathbf{i} - 4\mathbf{j} + 4\mathbf{k})}{\sqrt{4^2 + 4^2 + (-7)^2} \sqrt{7^2 + (-4)^2 + 4^2}} \\ &= \frac{28 - 16 - 28}{\sqrt{16 + 16 + 49} \sqrt{49 + 16 + 16}} \\ &= -\frac{16}{81}\end{aligned}$$

$$\text{So } \theta = 101.4^\circ$$

$$\begin{aligned}\text{So the angle between the planes is} \\ 180 - 101.4 = 78.6^\circ\end{aligned}$$

First find the angle between the normals to the planes.

Subtract the angle θ from 180° , to give angle α .

- The acute angle θ between the plane with equation $\mathbf{r} \cdot \mathbf{n}_1 = k_1$ and the plane with equation $\mathbf{r} \cdot \mathbf{n}_2 = k_2$ is given by the formula

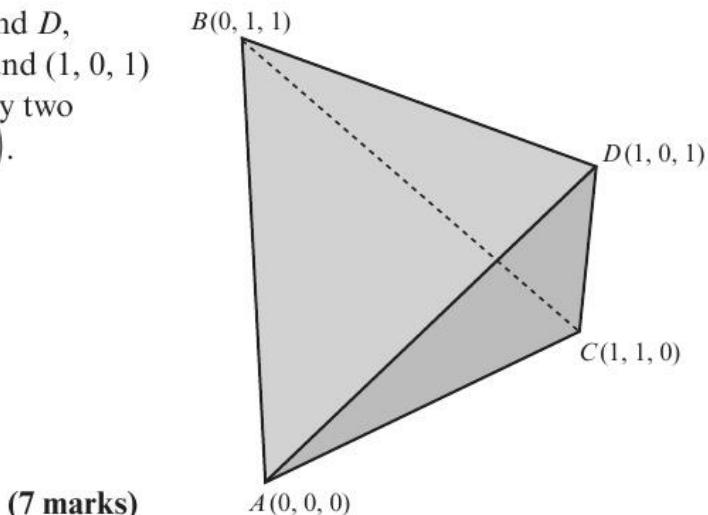
$$\cos \theta = \left| \frac{\mathbf{n}_1 \cdot \mathbf{n}_2}{|\mathbf{n}_1| |\mathbf{n}_2|} \right|$$

Exercise 9D

- 1 Given that each pair of lines intersect, find, to 1 decimal place, the acute angle between the lines with vector equations:
 - $\mathbf{r} = (2\mathbf{i} + \mathbf{j} + \mathbf{k}) + \lambda(3\mathbf{i} - 5\mathbf{j} - \mathbf{k})$ and $\mathbf{r} = (7\mathbf{i} + 4\mathbf{j} + \mathbf{k}) + \mu(2\mathbf{i} + \mathbf{j} - 9\mathbf{k})$
 - $\mathbf{r} = (\mathbf{i} - \mathbf{j} + 7\mathbf{k}) + \lambda(-2\mathbf{i} - \mathbf{j} + 3\mathbf{k})$ and $\mathbf{r} = (8\mathbf{i} + 5\mathbf{j} - \mathbf{k}) + \mu(-4\mathbf{i} - 2\mathbf{j} + \mathbf{k})$
 - $\mathbf{r} = (3\mathbf{i} + 5\mathbf{j} - \mathbf{k}) + \lambda(\mathbf{i} + \mathbf{j} + \mathbf{k})$ and $\mathbf{r} = (-\mathbf{i} + 11\mathbf{j} + 5\mathbf{k}) + \mu(2\mathbf{i} - 7\mathbf{j} + 3\mathbf{k})$
 - $\mathbf{r} = (\mathbf{i} + 6\mathbf{j} - \mathbf{k}) + \lambda(8\mathbf{i} - \mathbf{j} - 2\mathbf{k})$ and $\mathbf{r} = (6\mathbf{i} + 9\mathbf{j}) + \mu(\mathbf{i} + 3\mathbf{j} - 7\mathbf{k})$
 - $\mathbf{r} = (2\mathbf{i} + \mathbf{k}) + \lambda(11\mathbf{i} + 5\mathbf{j} - 3\mathbf{k})$ and $\mathbf{r} = (\mathbf{i} + \mathbf{j}) + \mu(-3\mathbf{i} + 5\mathbf{j} + 4\mathbf{k})$
- 2 Find, in the form $\mathbf{r} \cdot \mathbf{n} = k$, an equation of the plane that passes through the point with position vector \mathbf{a} and is perpendicular to the vector \mathbf{n} where:

a $\mathbf{a} = \mathbf{i} - \mathbf{j} - \mathbf{k}$ and $\mathbf{n} = 2\mathbf{i} + \mathbf{j} + \mathbf{k}$	b $\mathbf{a} = \mathbf{i} + 2\mathbf{j} + \mathbf{k}$ and $\mathbf{n} = 5\mathbf{i} - \mathbf{j} - 3\mathbf{k}$
c $\mathbf{a} = 2\mathbf{i} - 3\mathbf{k}$ and $\mathbf{n} = \mathbf{i} + 3\mathbf{j} + 4\mathbf{k}$	d $\mathbf{a} = 4\mathbf{i} - 2\mathbf{j} + \mathbf{k}$ and $\mathbf{n} = 4\mathbf{i} + \mathbf{j} - 5\mathbf{k}$
- 3 Find a Cartesian equation for each of the planes in question 2.

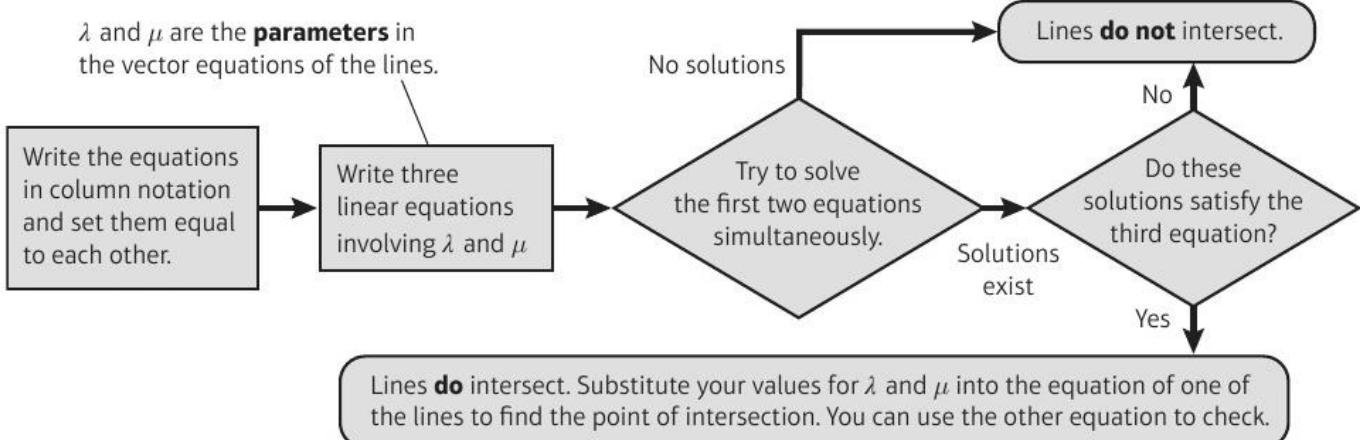
- 4 A plane has equation $\mathbf{r} \cdot \mathbf{n} = k$, where $\mathbf{n} = \begin{pmatrix} n_1 \\ n_2 \\ n_3 \end{pmatrix}$. Find a Cartesian equation of the plane.
- 5 Find the acute angle between the line with equation $\mathbf{r} = 2\mathbf{i} + \mathbf{j} - 5\mathbf{k} + \lambda(4\mathbf{i} + 4\mathbf{j} + 7\mathbf{k})$ and the plane with equation $\mathbf{r} \cdot (2\mathbf{i} + \mathbf{j} - 2\mathbf{k}) = 13$.
- 6 Find the acute angle between the line with equation $\mathbf{r} = -\mathbf{i} - 7\mathbf{j} + 13\mathbf{k} + \lambda(3\mathbf{i} + 4\mathbf{j} - 12\mathbf{k})$ and the plane with equation $\mathbf{r} \cdot (4\mathbf{i} - 4\mathbf{j} - 7\mathbf{k}) = 9$.
- 7 Find the acute angle between the planes with equations $\mathbf{r} \cdot (\mathbf{i} + 2\mathbf{j} - 2\mathbf{k}) = 1$ and $\mathbf{r} \cdot (-4\mathbf{i} + 4\mathbf{j} + 7\mathbf{k}) = 7$ respectively.
- 8 Find the acute angle between the planes with equations $\mathbf{r} \cdot (3\mathbf{i} - 4\mathbf{j} + 12\mathbf{k}) = 9$ and $\mathbf{r} \cdot (5\mathbf{i} - 12\mathbf{k}) = 7$ respectively.
- (P) 9 The straight lines l_1 and l_2 have vectors equations $\mathbf{r} = (\mathbf{i} + 4\mathbf{j} + 2\mathbf{k}) + \lambda(8\mathbf{i} + 5\mathbf{j} + \mathbf{k})$ and $\mathbf{r} = (\mathbf{i} + 4\mathbf{j} + 2\mathbf{k}) + \mu(3\mathbf{i} + \mathbf{j})$ respectively, and P is the point with coordinates $(1, 4, 2)$.
 - Show that the point $Q(9, 9, 3)$ lies on l_1 .
Given that l_1 and l_2 intersect, find:
 - the cosine of the acute angle between l_1 and l_2
 - the possible coordinates of the point R , such that R lies on l_2 and $PQ = PR$.
- (E/P) 10 The lines l_1 and l_2 have Cartesian equations $\frac{x-6}{-1} = \frac{y+3}{2} = \frac{z+2}{3}$ and $\frac{x+5}{2} = \frac{y-15}{-3} = \frac{z-3}{1}$ respectively.
 - Show that the point $A(3, 3, 7)$ lies on both l_1 and l_2 . (3 marks)
 - Find the size of the acute angle between the lines at A . (4 marks)
- (E) 11 The lines l_1 and l_2 have vector equations $\mathbf{r} = \begin{pmatrix} 1 \\ 3 \\ 3 \end{pmatrix} + \lambda \begin{pmatrix} 3 \\ 2 \\ -1 \end{pmatrix}$ and $\mathbf{r} = \begin{pmatrix} 3 \\ 5 \\ -2 \end{pmatrix} + \mu \begin{pmatrix} -4 \\ -3 \\ 1 \end{pmatrix}$.
The point A is on l_1 where $\lambda = 3$ and the point B is on l_2 where $\mu = -2$. Find the size of the acute angle between AB and l_1 . (6 marks)
- (E/P) 12 a Show that the points $A(3, 5, -1)$, $B(2, -2, 4)$, $C(4, 3, 0)$ and $D(1, 4, -3)$ are not coplanar.
b Find the angle between the plane containing A , B and C and the line segment AD . (4 marks)
- (E/P) 13 A regular tetrahedron has vertices A , B , C and D , with coordinates $(0, 0, 0)$, $(0, 1, 1)$, $(1, 1, 0)$ and $(1, 0, 1)$ respectively. Show that the angle between any two adjacent faces of the tetrahedron is $\arccos\left(\frac{1}{3}\right)$.



- E/P** 14 A flagpole is supported by 3 guide ropes which are attached at a point 20m above the base of the pole. The ends of the ropes are secured at points with position vectors $(0, 8, 2)$, $(12, -5, 3)$ and $(-2, 6, 5)$ relative to the base of the pole, where the units are metres. The flagpole will be stable if the angles between adjacent guide ropes are all greater than 15° . Determine whether the flagpole will be stable, showing your working clearly. **(7 marks)**

9.5 Points of intersection

You need to be able to determine whether two lines meet and, if so, to determine their point of intersection.



Example 22

The lines l_1 and l_2 have vector equations

$$\mathbf{r} = 3\mathbf{i} + \mathbf{j} + \mathbf{k} + \lambda(\mathbf{i} - 2\mathbf{j} - \mathbf{k}) \text{ and } \mathbf{r} = -2\mathbf{j} + 3\mathbf{k} + \mu(-5\mathbf{i} + \mathbf{j} + 4\mathbf{k}) \text{ respectively.}$$

Show that the two lines intersect, and find the position vector of the point of intersection.

$$\begin{pmatrix} 3 + \lambda \\ 1 - 2\lambda \\ 1 - \lambda \end{pmatrix} = \begin{pmatrix} -5\mu \\ -2 + \mu \\ 3 + 4\mu \end{pmatrix}$$

Use column vector notation for clarity, and to help to avoid errors.

Solve the simultaneous equations

$$3 + \lambda = -5\mu \quad (1)$$

$$\text{and } 1 - 2\lambda = 3 + 4\mu \quad (2)$$

Choose two of the three equations obtained by equating x -, y - and z -components and solve the resulting simultaneous equations.

Adding gives $4 = 3 - \mu$

and so $\mu = -1$.

Substituting back into equation (1) gives $\lambda = 2$.

Check $\mu = -1$, $\lambda = 2$ also satisfy the third equation.

If the lines intersect there is a pair of values of λ and μ that satisfy the 3 equations simultaneously.

$$1 - 2\lambda = -2 + \mu \text{ gives } -3 = -3$$

So the lines do intersect.

$$\text{Substituting } \lambda = 2 \text{ into } \begin{pmatrix} 3 + \lambda \\ 1 - 2\lambda \\ 1 - \lambda \end{pmatrix} \text{ gives } \begin{pmatrix} 5 \\ -3 \\ -1 \end{pmatrix}.$$

The point where the lines meet is $(5, -3, -1)$.

Check that the point which you obtain after substitution lies on both straight lines.

You also need to be able to find the coordinates of the point of intersection of a line with a plane.

Example 23

Find the coordinates of the point of intersection of the line l and the plane Π where l has equation $\mathbf{r} = -\mathbf{i} + \mathbf{j} - 5\mathbf{k} + \lambda(\mathbf{i} + \mathbf{j} + 2\mathbf{k})$ and Π has equation $\mathbf{r} \cdot (\mathbf{i} + 2\mathbf{j} + 3\mathbf{k}) = 4$.

The line meets the plane when

$$\begin{pmatrix} -1 + \lambda \\ 1 + \lambda \\ -5 + 2\lambda \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = 4$$

$$\begin{aligned} -1 + \lambda + 2(1 + \lambda) + 3(-5 + 2\lambda) &= 4 \\ 9\lambda - 14 &= 4 \\ 9\lambda &= 18 \\ \lambda &= 2 \end{aligned}$$

So the line meets the plane when $\lambda = 2$, at the point $(1, 3, -1)$.

Write the equation of the line in column vector

$$\text{form as } \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -1 + \lambda \\ 1 + \lambda \\ -5 + 2\lambda \end{pmatrix} \text{ and substitute into the equation of the plane } \begin{pmatrix} x \\ y \\ z \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = 4.$$

Solve to find λ and substitute its value into the equation of the line.

■ Two straight lines are skew if they are not parallel and they do not intersect.

Watch out If the line were parallel to the plane then this equation would produce either no solutions (if the line does not lie in the plane), or infinitely many (if it does).

Example 24

The lines l_1 and l_2 have equations $\frac{x-2}{4} = \frac{y+3}{2} = z-1$ and $\frac{x+1}{5} = \frac{y}{4} = \frac{z-4}{-2}$ respectively.

Prove that l_1 and l_2 are skew.

$$\begin{pmatrix} 2 + 4\lambda \\ -3 + 2\lambda \\ 1 + \lambda \end{pmatrix} = \begin{pmatrix} -1 + 5\mu \\ 4\mu \\ 4 - 2\mu \end{pmatrix}$$

$$2 + 4\lambda = -1 + 5\mu \quad (1)$$

$$-3 + 2\lambda = 4\mu \quad (2)$$

$$(1) - 2 \times (2): 8 = -1 - 3\mu \Rightarrow \mu = -3$$

$$\text{Substituting into (2): } -3 + 2\lambda = -12 \Rightarrow \lambda = -\frac{9}{2}$$

Check for consistency:

$$1 + \lambda = -\frac{7}{2} \text{ and } 4 - 2\mu = 10.$$

$1 + \lambda \neq 4 - 2\mu$ so equations not consistent and lines do not intersect.

Direction of l_1 is $\begin{pmatrix} 4 \\ 2 \\ 1 \end{pmatrix}$ or $\begin{pmatrix} 8 \\ 4 \\ 2 \end{pmatrix}$.

Direction of l_2 is $\begin{pmatrix} 5 \\ 4 \\ -2 \end{pmatrix}$.

Direction vectors are not scalar multiples of each other so lines are not parallel.

Hence l_1 and l_2 are skew.

Problem-solving

To show that two lines are skew you need to show that they do not intersect **and** that they are not parallel. Start by writing the general point on each line. Equate these general points and attempt to solve the three equations simultaneously.

Solve the first two equations simultaneously, then check to see whether the answer is consistent with the third equation.

If the lines are parallel the direction vectors will be scalar multiples of each other. Multiply the direction vector of l_1 by a scalar to make one component match the direction vector of l_2 , then compare the other components.

Exercise 9E

- 1** In each case establish whether lines l_1 and l_2 meet and, if they meet, find the coordinates of their point of intersection:
- l_1 has equation $\mathbf{r} = \mathbf{i} + 3\mathbf{j} + \lambda(\mathbf{i} - \mathbf{j} + 5\mathbf{k})$ and l_2 has equation $\mathbf{r} = -\mathbf{i} - 3\mathbf{j} + 2\mathbf{k} + \mu(\mathbf{i} + \mathbf{j} + 2\mathbf{k})$
 - l_1 has equation $\mathbf{r} = 3\mathbf{i} + 2\mathbf{j} + \mathbf{k} + \lambda(\mathbf{i} + \mathbf{j} + 2\mathbf{k})$ and l_2 has equation $\mathbf{r} = 4\mathbf{i} + 3\mathbf{j} + \mu(-\mathbf{i} + \mathbf{j} - \mathbf{k})$
 - l_1 has equation $\mathbf{r} = \mathbf{i} + 3\mathbf{j} + 5\mathbf{k} + \lambda(2\mathbf{i} + 3\mathbf{j} + \mathbf{k})$ and l_2 has equation $\mathbf{r} = \mathbf{i} + \frac{5}{2}\mathbf{j} + \frac{5}{2}\mathbf{k} + \mu(\mathbf{i} + \mathbf{j} - 2\mathbf{k})$
(In each of the above cases λ and μ are scalars.)
- E** **2** With respect to a fixed origin O , the lines l_1 and l_2 are given by the equations
- $$l_1: \mathbf{r} = (-6\mathbf{i} + 11\mathbf{k}) + \lambda(\mathbf{i} - \mathbf{j} + \mathbf{k})$$
- $$l_2: \mathbf{r} = (2\mathbf{i} - 2\mathbf{j} + 9\mathbf{k}) + \mu(2\mathbf{i} + \mathbf{j} - 3\mathbf{k})$$
- Show that l_1 and l_2 meet and find the position vector of their point of intersection. **(6 marks)**
- E** **3** The line l_1 has equation $\mathbf{r} = \begin{pmatrix} 3 \\ 1 \\ -2 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ 2 \\ 3 \end{pmatrix}$ and the line l_2 has equation $\mathbf{r} = \begin{pmatrix} 5 \\ 4 \\ 0 \end{pmatrix} + \mu \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix}$.
Show that l_1 and l_2 do not meet. **(4 marks)**
- 4** In each case, find the coordinates of the point of intersection of the line l with the plane Π .
- $l: \mathbf{r} = \mathbf{i} + \mathbf{j} + \mathbf{k} + \lambda(-2\mathbf{i} + \mathbf{j} - 4\mathbf{k})$
 $\Pi: \mathbf{r} \cdot (3\mathbf{i} - 4\mathbf{j} + 2\mathbf{k}) = 16$
 - $l: \mathbf{r} = \mathbf{i} + \mathbf{j} + \mathbf{k} + \lambda(2\mathbf{j} - 2\mathbf{k})$
 $\Pi: \mathbf{r} \cdot (3\mathbf{i} - \mathbf{j} - 6\mathbf{k}) = 1$
- E/P** **5** The line l has equation $\mathbf{r} = \begin{pmatrix} 2 \\ 3 \\ -2 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$.
- Show that l does not meet the plane with equation $\mathbf{r} \cdot \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix} = 1$. **(4 marks)**
 - Give a geometrical interpretation to your answer to part a. **(1 mark)**
- E/P** **6** The line with vector equation $\mathbf{r} = \begin{pmatrix} 5 \\ 4 \\ -1 \end{pmatrix} + \lambda \begin{pmatrix} 3 \\ -1 \\ 2 \end{pmatrix}$ is perpendicular to the line with vector equation $\mathbf{r} = \begin{pmatrix} 0 \\ 11 \\ 3 \end{pmatrix} + \mu \begin{pmatrix} -1 \\ p \\ p \end{pmatrix}$.
- Find the value of p . **(2 marks)**
 - Show that the two lines meet, and find the coordinates of the point of intersection. **(4 marks)**
- E** **7** The line l_1 has vector equation $\mathbf{r} = \begin{pmatrix} 5 \\ 2 \\ 1 \end{pmatrix} + \lambda \begin{pmatrix} -1 \\ 1 \\ 2 \end{pmatrix}$ and the line l_2 has vector equation $\mathbf{r} = \begin{pmatrix} 4 \\ 1 \\ 1 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$, where λ and μ are parameters.

The lines l_1 and l_2 intersect at the point A and the acute angle between l_1 and l_2 is θ .

- a Find the coordinates of A . (4 marks)
b Find the value of $\cos \theta$ giving your answer as a simplified fraction. (4 marks)

(E/P) 8 The lines l_1 and l_2 have equations $\frac{x}{-3} = \frac{y+1}{5} = \frac{z-2}{4}$ and $x = \frac{y-1}{-2} = \frac{z+5}{2}$ respectively.

Prove that l_1 and l_2 are skew.

(E/P) 9 With respect to a fixed origin O the lines l_1 and l_2 are given by the equations

$$l_1: \mathbf{r} = \begin{pmatrix} 8 \\ 2 \\ -12 \end{pmatrix} + \lambda \begin{pmatrix} -1 \\ 3 \\ 2 \end{pmatrix} \quad l_2: \mathbf{r} = \begin{pmatrix} -4 \\ 10 \\ p \end{pmatrix} + \mu \begin{pmatrix} q \\ 2 \\ -1 \end{pmatrix}$$

where λ and μ are parameters and p and q are constants. Given that l_1 and l_2 are perpendicular,

- a show that $q = 4$. (2 marks)

Given further that l_1 and l_2 intersect, find:

- b the value of p (6 marks)
c the coordinates of the point of intersection. (2 marks)

The point A lies on l_1 and has position vector $\begin{pmatrix} 9 \\ -1 \\ -14 \end{pmatrix}$. The point C lies on l_2 .

Given that a circle, with centre C , cuts the line l_1 at the points A and B ,

- d find the position vector of B . (3 marks) Problem-solving

Draw a diagram showing the lines l_1 and l_2 and the circle, and use circle properties.

(E/P) 10 The plane Π has equation $\mathbf{r} \cdot \begin{pmatrix} 2 \\ 3 \\ -1 \end{pmatrix} = k$ where k is a constant.

Given the point with position vector $\begin{pmatrix} 6 \\ -2 \\ 4 \end{pmatrix}$ lies on Π ,

- a find the value of k (3 marks)
b find a Cartesian equation for Π . (2 marks)

The point P has coordinates $(6, 4, 8)$. The line l passes through P and is perpendicular to Π .

The line l intersects Π at the point N .

- c Find the coordinates of N . (4 marks)

(E/P) 11 The line l has a Cartesian equation $\frac{x-3}{5} = \frac{y+2}{3} = \frac{4-z}{1}$

The plane Π has Cartesian equation $4x + 3y - 2z = -10$.

The line intersects the plane at the point P .

- a Find the position vector of P . (5 marks)
b Find the acute angle between the line and the plane at the point of intersection. (5 marks)

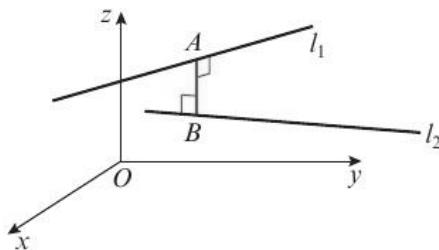
9.6 Finding perpendiculars

You need to be able to calculate the **perpendicular distance** between:

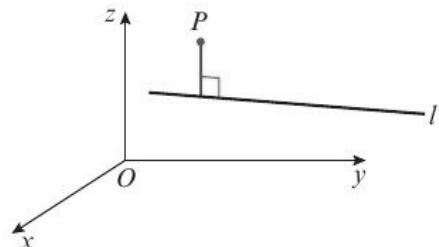
- two lines
- a point and a line
- a point and a plane

In each case, the perpendicular distance is the **shortest distance** between them.

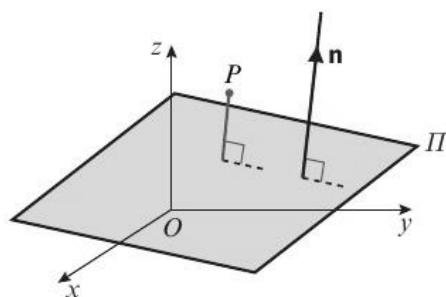
- For any two non-intersecting lines l_1 and l_2 there is a unique line segment AB such that A lies on l_1 , B lies on l_2 and AB is perpendicular to both lines.



- The perpendicular from a point P to a line l is a line through P which meets l at right angles.



- The perpendicular from a point P to a plane Π is a line through P which is parallel to the normal vector of the plane, \mathbf{n} .



Example 24

Show that the shortest distance between the parallel lines with equations

$$\mathbf{r} = \mathbf{i} + 2\mathbf{j} - \mathbf{k} + \lambda(5\mathbf{i} + 4\mathbf{j} + 3\mathbf{k}) \text{ and } \mathbf{r} = 2\mathbf{i} + \mathbf{k} + \mu(5\mathbf{i} + 4\mathbf{j} + 3\mathbf{k}),$$

where λ and μ are scalars, is $\frac{21\sqrt{2}}{10}$

Let A be a general point on the first line and B be a general point on the second line, then

$$\overrightarrow{AB} = \begin{pmatrix} 1 \\ -2 \\ 2 \end{pmatrix} + t \begin{pmatrix} 5 \\ 4 \\ 3 \end{pmatrix} \text{ where } t = \mu - \lambda.$$

$$\begin{pmatrix} 1+5t \\ -2+4t \\ 2+3t \end{pmatrix} \cdot \begin{pmatrix} 5 \\ 4 \\ 3 \end{pmatrix} = 0$$

$$5 + 25t - 8 + 16t + 6 + 9t = 0$$

$$50t = -3$$

$$t = -\frac{3}{50}$$

$$\begin{pmatrix} 1-5t \\ -2+4t \\ 2+3t \end{pmatrix} = \begin{pmatrix} 1-\frac{15}{50} \\ -2+\frac{12}{50} \\ 2-\frac{9}{50} \end{pmatrix} = \begin{pmatrix} \frac{35}{50} \\ \frac{112}{50} \\ \frac{91}{50} \end{pmatrix}$$

$$\begin{aligned} |\overrightarrow{AB}| &= \sqrt{\frac{35^2 + 112^2 + 91^2}{50^2}} \\ &= \frac{21\sqrt{2}}{10} \end{aligned}$$

So the shortest distance between the two

$$\text{lines is } \frac{21\sqrt{2}}{10}$$

$$\text{As } \begin{pmatrix} 1 \\ -2 \\ 2 \end{pmatrix} = \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}$$

You can set $t = \mu - \lambda$ so that there is only one independent variable.

As the direction of \overrightarrow{AB} is perpendicular to the direction vector for each line, the scalar product is zero.

Substitute $t = -\frac{3}{50}$ into the general form of \overrightarrow{AB} .

The shortest distance between two lines is the length of the line segment that is perpendicular to both lines.

Watch out Because the two lines are parallel, the line segment AB is not unique. There are infinitely many line segments that are perpendicular to both lines, but they will all have the same length.

Example 25

The lines l_1 and l_2 have equations $\mathbf{r} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix}$ and $\mathbf{r} = \begin{pmatrix} -1 \\ 3 \\ -1 \end{pmatrix} + \mu \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix}$ respectively, where λ and μ are scalars.

Find the shortest distance between these two lines.

Let A be the general point on l_1 with position vector $\begin{pmatrix} 1 \\ \lambda \\ \lambda \end{pmatrix}$ and let B be the general point on

l_2 with position vector $\begin{pmatrix} -1 + 2\mu \\ 3 - \mu \\ -1 - \mu \end{pmatrix}$

Online Explore the perpendicular distance between two lines using GeoGebra.



$$\overrightarrow{AB} = \begin{pmatrix} -1 + 2\mu \\ 3 - \mu \\ -1 - \mu \end{pmatrix} - \begin{pmatrix} 1 \\ \lambda \\ \lambda \end{pmatrix} = \begin{pmatrix} -2 + 2\mu \\ 3 - \mu - \lambda \\ -1 - \mu - \lambda \end{pmatrix}$$

Find position vectors of general points on l_1 and l_2 and use these to find \overrightarrow{AB} in terms of μ and λ .

\overrightarrow{AB} is perpendicular to l_1 , so:

$$\begin{pmatrix} -2 + 2\mu \\ 3 - \mu - \lambda \\ -1 - \mu - \lambda \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} = 0$$

$$3 - \mu - \lambda - 1 - \mu - \lambda = 0$$

$$2 - 2\mu - 2\lambda = 0 \quad (1)$$

\overrightarrow{AB} is perpendicular to l_2 so:

$$\begin{pmatrix} -2 + 2\mu \\ 3 - \mu - \lambda \\ -1 - \mu - \lambda \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix} = 0$$

$$-4 + 4\mu - 3 + \mu + \lambda + 1 + \mu + \lambda = 0$$

$$-6 + 6\mu + 2\lambda = 0 \quad (2)$$

$$\text{From (1), } \lambda = 1 - \mu$$

$$\text{From (2), } -3 + 3\mu + \lambda = 0$$

$$\text{So } -3 + 3\mu + 1 - \mu = 0 \Rightarrow \mu = 1$$

Substituting into (1) gives

$$2 - 2 - 2\lambda = 0 \Rightarrow \lambda = 0$$

$$\begin{aligned} \overrightarrow{AB} &= \begin{pmatrix} -2 + 2\mu \\ 3 - \mu - \lambda \\ -1 - \mu - \lambda \end{pmatrix} = \begin{pmatrix} -2 + 2 \\ 3 - 1 - 0 \\ -1 - 1 - 0 \end{pmatrix} \\ &= \begin{pmatrix} 0 \\ 2 \\ -2 \end{pmatrix} \end{aligned}$$

$$|\overrightarrow{AB}| = \sqrt{0^2 + 2^2 + (-2)^2} = \sqrt{8} = 2\sqrt{2}$$

So the shortest distance between the two lines is $2\sqrt{2}$.

Problem-solving

As \overrightarrow{AB} is perpendicular to l_1 and l_2 , the scalar product of the direction vectors of the lines is zero. You can use this fact to generate two linear equations in λ and μ .

The equations can be solved simultaneously to find λ and μ .

These two lines are **skew**, so in this case the line segment AB is unique.

Example 26

The line l has equation $\frac{x-1}{2} = \frac{y-1}{-2} = \frac{z+3}{-1}$, and the point A has coordinates $(1, 2, -1)$.

a Find the shortest distance between A and l .

b Find a Cartesian equation of the line that is perpendicular to l and passes through A .

a Vector equation of l is

$$\mathbf{r} = \begin{pmatrix} 1 \\ 1 \\ -3 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ -2 \\ -1 \end{pmatrix}$$

So a general point B , on the line has position vector $\begin{pmatrix} 1 + 2\lambda \\ 1 - 2\lambda \\ -3 - \lambda \end{pmatrix}$.

$$\text{Then } \overrightarrow{AB} = \begin{pmatrix} 1 + 2\lambda \\ 1 - 2\lambda \\ -3 - \lambda \end{pmatrix} - \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} = \begin{pmatrix} 2\lambda \\ -1 - 2\lambda \\ -2 - \lambda \end{pmatrix}$$

$$\begin{pmatrix} 2\lambda \\ -1 - 2\lambda \\ -2 - \lambda \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -2 \\ -1 \end{pmatrix} = 0$$

$$4\lambda + 2 + 4\lambda + 2 + \lambda = 0$$

$$4 + 9\lambda = 0$$

$$\lambda = -\frac{4}{9}$$

$$\overrightarrow{AB} = \begin{pmatrix} 2\lambda \\ -1 - 2\lambda \\ -2 - \lambda \end{pmatrix} = \begin{pmatrix} -\frac{8}{9} \\ -\frac{1}{9} \\ -\frac{14}{9} \end{pmatrix}$$

$$\begin{aligned} |\overrightarrow{AB}| &= \sqrt{\frac{(-8)^2 + (-1)^2 + (-14)^2}{9^2}} \\ &= \frac{\sqrt{29}}{3} = 1.80 \text{ (3 s.f.)} \end{aligned}$$

So the shortest distance between A and l

is $\frac{\sqrt{29}}{3}$ or 1.80 (3 s.f.).

b \overrightarrow{AB} is perpendicular to l , so direction of

$$\text{perpendicular is } \begin{pmatrix} -\frac{8}{9} \\ -\frac{1}{9} \\ -\frac{14}{9} \end{pmatrix} \text{ or } \begin{pmatrix} 8 \\ 1 \\ 14 \end{pmatrix}$$

A vector equation of the line through A

$$\text{perpendicular to } l \text{ is } \mathbf{r} = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} + \mu \begin{pmatrix} 8 \\ 1 \\ 14 \end{pmatrix}$$

So the Cartesian equation of the line is

$$\frac{x-1}{8} = \frac{y-2}{1} = \frac{z+1}{14}$$

$$\frac{x-1}{2} = \lambda, x = 1 + 2\lambda$$

$$\frac{y-1}{-2} = \lambda, y = 1 - 2\lambda$$

$$\frac{z+3}{-1} = \lambda, z = -3 - \lambda$$

Let B be the position vector of a general point on l .

Find \overrightarrow{AB} in terms of λ .

Since \overrightarrow{AB} is perpendicular to l the scalar product of \overrightarrow{AB} with the direction vector of the line is zero. This gives you an equation which you can solve to find λ .

Substitute the value of λ into your general expression for \overrightarrow{AB} .

The shortest distance is given by $|\overrightarrow{AB}|$.

Remember that you can multiply the direction vector by a scalar to find a simpler parallel vector.

A vector equation of the line through the point with position vector \mathbf{a} with direction \mathbf{b} is $\mathbf{r} = \mathbf{a} + \mu \mathbf{b}$ where μ is a scalar constant.

You can use the principles covered above to give meaning to the constant, k , in the scalar product form of the vector equation of a plane.

- **k is the length of the perpendicular from the origin to a plane Π , where the equation of plane Π is written in the form $\mathbf{r} \cdot \hat{\mathbf{n}} = k$, where $\hat{\mathbf{n}}$ is a unit vector perpendicular to Π .**
- **The perpendicular distance from the point with coordinates (α, β, γ) to the plane with equation $ax + by + cz = d$ is**

$$\frac{|a\alpha + b\beta + c\gamma - d|}{\sqrt{a^2 + b^2 + c^2}}$$

Note This formula is given in the formulae booklet and you can use it without proof in your exam.

Example 27

Find the perpendicular distance from the point with coordinates $(3, 2, -1)$ to the plane with equation $2x - 3y + z = 5$.

$$\begin{aligned}\text{Distance} &= \frac{|2 \times 3 - 3 \times 2 + 1 \times (-1) - 5|}{\sqrt{2^2 + (-3)^2 + 1^2}} \\ &= \frac{|-6|}{\sqrt{14}} \\ &= \frac{6}{\sqrt{14}}\end{aligned}$$

Substitute into the formula.

Remember to use the modulus of the numerator as distance is always positive.

Example 28

The plane Π has equation $\mathbf{r} \cdot (\mathbf{i} + 2\mathbf{j} + 2\mathbf{k}) = 5$. The point P has coordinates $(1, 3, -2)$.

- a Find the shortest distance between P and Π .

The point Q is the reflection of the point P in Π .

- b Find the coordinates of point Q .

a Cartesian equation of Π is $x + 2y + 2z = 5$.

$$\begin{aligned}\text{Distance} &= \frac{|1 \times 1 + 2 \times 3 + 2 \times (-2) - 5|}{\sqrt{1^2 + 2^2 + 2^2}} \\ &= \frac{|-2|}{\sqrt{9}} = \frac{2}{3}\end{aligned}$$

Use $\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$ and $\begin{pmatrix} x \\ y \\ z \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} = 5$.

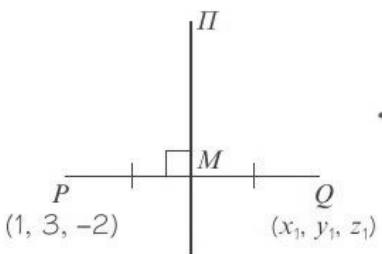
b A perpendicular vector to Π is

$$\mathbf{n} = \mathbf{i} + 2\mathbf{j} + 2\mathbf{k}$$

Let Q have coordinates (x_1, y_1, z_1) .
Let M be the midpoint of PQ .

Using the formula $\frac{|a\alpha + b\beta + c\gamma - d|}{\sqrt{a^2 + b^2 + c^2}}$ for the distance between a point with coordinates (α, β, γ) and the plane with Cartesian equation $ax + by + cz = d$.

A normal vector to the plane $ax + by + cz = d$ is $a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$.



A vector equation of the line through P , M

$$\text{and } Q \text{ is } \mathbf{r} = \begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}$$

M lies on this line so has position vector

$$\begin{pmatrix} 1 + \lambda \\ 3 + 2\lambda \\ -2 + 2\lambda \end{pmatrix}$$

$$M \text{ also lies on } II, \text{ so } \begin{pmatrix} 1 + \lambda \\ 3 + 2\lambda \\ -2 + 2\lambda \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} = 5$$

$$1 + \lambda + 2(3 + 2\lambda) + 2(-2 + 2\lambda) = 5$$

$$3 + 9\lambda = 5$$

$$\lambda = \frac{2}{9}$$

$$M \text{ has position vector } \begin{pmatrix} 1 + \frac{2}{9} \\ 3 + 2 \times \frac{2}{9} \\ -2 + 2 \times \frac{2}{9} \end{pmatrix} = \begin{pmatrix} \frac{11}{9} \\ \frac{31}{9} \\ -\frac{14}{9} \end{pmatrix}$$

P is the initial point in the equation of l ,

$$\text{so if } M \text{ has position vector } \begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix} + \frac{2}{9} \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}$$

then P has position vector

$$\begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix} + 2 \times \frac{2}{9} \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 + \frac{4}{9} \\ 3 + 2 \times \frac{4}{9} \\ -2 + 2 \times \frac{4}{9} \end{pmatrix} = \begin{pmatrix} \frac{13}{9} \\ \frac{35}{9} \\ -\frac{10}{9} \end{pmatrix}$$

Point Q has coordinates $(\frac{13}{9}, \frac{35}{9}, -\frac{10}{9})$.

The line joining P to its reflection Q will be perpendicular to the plane, and P and Q will be the same distance from the plane. Draw a diagram showing P , Q , and the midpoint of PQ . Represent the plane II using a vertical line.

Online Explore reflections in a plane using GeoGebra.



Use the fact that M lies on the line joining P and Q and on the plane to find M .

Problem-solving

$\begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix}$ is the position vector of point P , so if the point on the line $\mathbf{r} = \begin{pmatrix} 1 \\ 3 \\ -2 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix}$ with $\lambda = k$ is a distance x away from P , then the point with $\lambda = 2k$ will be a distance $2x$ away from P .

You could also use the fact that the midpoint of the line segment joining (x_1, y_1, z_1) to (x_2, y_2, z_2) is $\left(\frac{x_1 + x_2}{2}, \frac{y_1 + y_2}{2}, \frac{z_1 + z_2}{2}\right)$

Example 29

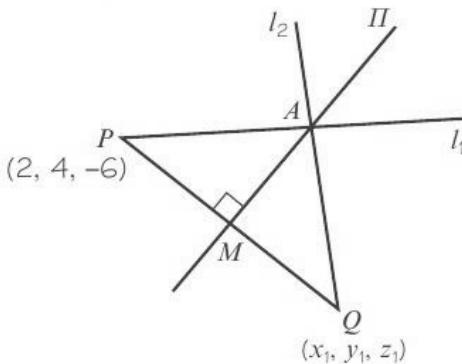
The line l_1 has equation $\frac{x-2}{2} = \frac{y-4}{-2} = \frac{z+6}{1}$. The plane Π has equation $2x - 3y + z = 8$.

The line l_2 is the reflection of line l_1 in the plane Π . Find a vector equation of the line l_2 .

A vector equation of l_1 is $\mathbf{r} = \begin{pmatrix} 2 \\ 4 \\ -6 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix}$.

So $P(2, 4, -6)$ is a point on line l_1 .

Let A be the point of intersection of l_1 and Π .



A lies on l_1 and on $2x - 3y + z = 8$.

A has position vector $\begin{pmatrix} 2 + 2\lambda \\ 4 - 2\lambda \\ -6 + \lambda \end{pmatrix}$ and satisfies

$$\begin{aligned} 2(2 + 2\lambda) - 3(4 - 2\lambda) - 6 + \lambda &= 8 \\ 4 + 4\lambda - 12 + 6\lambda - 6 + \lambda &= 8 \\ 11\lambda &= 22 \\ \lambda &= 2 \end{aligned}$$

So A has coordinates $(6, 0, -4)$.

A perpendicular direction vector to Π is $\mathbf{n} = 2\mathbf{i} - 3\mathbf{j} + \mathbf{k}$.

A vector equation of the line through P

perpendicular to Π is $\mathbf{r} = \begin{pmatrix} 2 \\ 4 \\ -6 \end{pmatrix} + \mu \begin{pmatrix} 2 \\ -3 \\ 1 \end{pmatrix}$.

Let $Q(x_1, y_1, z_1)$ be the point of intersection of this line and l_2 .

Let M be midpoint of PQ .

M lies on line and on $2x - 3y + z = 8$ so satisfies

$$\begin{aligned} 2(2 + 2\mu) - 3(4 - 3\mu) - 6 + \mu &= 8 \\ 4 + 4\mu - 12 + 9\mu - 6 + \mu &= 8 \\ 14\mu &= 22 \end{aligned}$$

$$\mu = \frac{11}{7}$$

So M has position vector $\begin{pmatrix} 2 \\ 4 \\ -6 \end{pmatrix} + \frac{11}{7} \begin{pmatrix} 2 \\ -3 \\ 1 \end{pmatrix}$

Problem-solving

You need to find **two points** on the reflected line, l_2 . One is the point of intersection of l_1 and Π .

To find another point on l_2 , choose any point on l_1 and reflect it in the plane.

Substitute the general position vector of a point on l_1 into the equation for Π to find the value of λ at A .

Substitute $\lambda = 2$ into the general position vector to find the coordinates of A .

Q is the reflection of the point $(6, 0, -4)$ in the plane.

The general point on the line PQ is $\begin{pmatrix} 2 + 2\mu \\ 4 - 3\mu \\ -6 + \mu \end{pmatrix}$.

and Q has position vector

$$\begin{pmatrix} 2 \\ 4 \\ -6 \end{pmatrix} + 2 \times \frac{11}{7} \begin{pmatrix} 2 \\ -3 \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{58}{7} \\ -\frac{38}{7} \\ -\frac{20}{7} \end{pmatrix}$$

Q is twice as far along the line from P as M .

So Q has coordinates $\left(\frac{58}{7}, -\frac{38}{7}, -\frac{20}{7}\right)$.

l_2 is the line through Q and A , so has direction:

$$\overrightarrow{AQ} = \begin{pmatrix} \frac{16}{7} \\ -\frac{38}{7} \\ \frac{8}{7} \end{pmatrix}$$

A vector equation of l_2 is $\mathbf{r} = \begin{pmatrix} 6 \\ 0 \\ -4 \end{pmatrix} + t \begin{pmatrix} 8 \\ -19 \\ 4 \end{pmatrix}$.

The direction of l_2 can be simplified to $\begin{pmatrix} 8 \\ -19 \\ 4 \end{pmatrix}$ by multiplying the expression for \overrightarrow{AQ} by $\frac{7}{2}$

Exercise 9F

- Find the shortest distance between the parallel lines with equations
 $\mathbf{r} = 2\mathbf{i} - \mathbf{j} + \mathbf{k} + \lambda(-3\mathbf{i} - 4\mathbf{j} + 5\mathbf{k})$ and $\mathbf{r} = \mathbf{j} + \mathbf{k} + \mu(-3\mathbf{i} - 4\mathbf{j} + 5\mathbf{k})$
where λ and μ are scalars.
- Find the shortest distance between the two skew lines with equations
 $\mathbf{r} = \mathbf{j} + \mathbf{k} + \lambda(-\mathbf{i} + \mathbf{j} - \mathbf{k})$ and $\mathbf{r} = 5\mathbf{i} - 2\mathbf{j} + 2\mathbf{k} + \mu(4\mathbf{i} - 2\mathbf{j} + 3\mathbf{k})$,
where λ and μ are scalars.
- Determine whether the lines l_1 and l_2 meet. If they do, find their point of intersection. If they do not, find the shortest distance between them. (In each of the following cases λ and μ are scalars.)
 - l_1 has equation $\mathbf{r} = 7\mathbf{i} + 3\mathbf{j} + \mathbf{k} + \lambda(6\mathbf{i} + 2\mathbf{j} - 4\mathbf{k})$ and l_2 has equation $\mathbf{r} = -\mathbf{i} + \mathbf{j} + 2\mathbf{k} - 2\mu\mathbf{j}$
 - l_1 has equation $\mathbf{r} = 2\mathbf{i} + \mathbf{j} - 2\mathbf{k} + \lambda(2\mathbf{i} - 2\mathbf{j} + 2\mathbf{k})$ and l_2 has equation $\mathbf{r} = \mathbf{i} - \mathbf{j} + 3\mathbf{k} + \mu(\mathbf{i} - \mathbf{j} + \mathbf{k})$
 - l_1 has equation $\mathbf{r} = \mathbf{i} + \mathbf{j} + 5\mathbf{k} + \lambda(2\mathbf{i} + \mathbf{j} - 2\mathbf{k})$ and l_2 has equation $\mathbf{r} = -\mathbf{i} - \mathbf{j} + 2\mathbf{k} + \mu(\mathbf{i} + \mathbf{j} + \mathbf{k})$
- Find the shortest distance between the point with coordinates $(4, 1, -1)$ and the line with equation $\mathbf{r} = 3\mathbf{i} - \mathbf{j} + 2\mathbf{k} + \mu(2\mathbf{i} - \mathbf{j} - \mathbf{k})$, where μ is a scalar.
- Find the shortest distance between the parallel planes.
 - $\mathbf{r} \cdot (6\mathbf{i} + 6\mathbf{j} - 7\mathbf{k}) = 55$ and $\mathbf{r} \cdot (6\mathbf{i} + 6\mathbf{j} - 7\mathbf{k}) = 22$
 - $\mathbf{r} = 3\mathbf{i} + 4\mathbf{j} + \mathbf{k} + \lambda(4\mathbf{i} + \mathbf{k}) + \mu(8\mathbf{i} + 3\mathbf{j} + 3\mathbf{k})$ and $\mathbf{r} = 14\mathbf{i} + 2\mathbf{j} + 2\mathbf{k} + \lambda(3\mathbf{j} + \mathbf{k}) + \mu(8\mathbf{i} - 9\mathbf{j} - \mathbf{k})$

6 The plane Π has equation $\mathbf{r} \cdot (10\mathbf{i} + 10\mathbf{j} + 23\mathbf{k}) = 81$.

- a Find the perpendicular distance from the origin to plane Π .
- b Find the perpendicular distance from the point $(-1, -1, 4)$ to the plane Π .
- c Find the perpendicular distance from the point $(2, 1, 3)$ to the plane Π .
- d Find the perpendicular distance from the point $(6, 12, -9)$ to the plane Π .

(E/P)

7 The line l has vector equation $\mathbf{r} = \begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}$.

The point P has coordinates $(3, 0, 2)$.

Problem-solving

Let M be the midpoint of the line segment joining P to its reflection in l . This segment must be perpendicular to l and pass through it.

Find the coordinates of the reflection of the point P in the line l .

(5 marks)

(E/P) 8 The plane Π has equation $-2x + y + z = 5$. The point P has coordinates $(1, 0, 3)$.

- a Find the shortest distance between P and Π .

(3 marks)

The point Q is the reflection of the point P in Π .

- b Find the coordinates of point Q .

(5 marks)

(E/P) 9 A birdwatcher is located on a hilltop. Relative to a fixed origin O , the position vector of the

birdwatcher is $\begin{pmatrix} 5 \\ 4 \\ 0.7 \end{pmatrix}$ km. The birdwatcher is able to spot any bird that

flies within 500 m of her position. A kestrel flies from point A to point B , where points A and B have position vectors $\begin{pmatrix} 3 \\ 5 \\ 0 \end{pmatrix}$ km and $\begin{pmatrix} 12 \\ 0 \\ 1.2 \end{pmatrix}$ km respectively. The kestrel is modelled as flying in a straight line.

- a Use the model to determine whether the birdwatcher is able to spot the kestrel.

(7 marks)

- b Give one criticism of the model.

(1 mark)

(E/P) 10 The plane Π_1 has equation $3x - 2y + 4z = 6$.

- a Find the perpendicular distance from the point $(4, -1, 8)$ to Π_1 .

(3 marks)

The plane Π_2 has vector equation $\mathbf{r} = \lambda(2\mathbf{i} - 2\mathbf{j} + 3\mathbf{k}) + \mu(-3\mathbf{i} + 3\mathbf{k})$ where λ and μ are scalar parameters.

- b Show that the vector $2\mathbf{i} + 5\mathbf{j} + 2\mathbf{k}$ is perpendicular to Π_2 .

(2 marks)

- c Find the acute angle between Π_1 and Π_2 .

(3 marks)

(E/P) 11 The line l_1 has equation $\frac{x+2}{2} = \frac{y-2}{-1} = \frac{z+1}{-2}$, and the point A has coordinates $(3, -1, 2)$.

- a Find the shortest distance between A and l_1 .

(5 marks)

- b Find a Cartesian equation of the line that is perpendicular to l_1 and passes through A .

(3 marks)

(E/P) 12 The line l_1 has vector equation $\mathbf{r} = \begin{pmatrix} 2 \\ -1 \\ 2 \end{pmatrix} + \lambda \begin{pmatrix} 4 \\ -3 \\ 4 \end{pmatrix}$. The plane Π has equation $\mathbf{r} \cdot \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix} = 4$.

The line l_2 is the reflection of line l_1 in the plane Π .

Find a vector equation of the line l_2 .

(7 marks)

Mixed exercise 9

- (E) 1 The line l passes through the points A and B with position vectors $\mathbf{i} - \mathbf{j} + 3\mathbf{k}$ and $\mathbf{i} + 2\mathbf{j} + 2\mathbf{k}$ respectively, relative to a fixed origin O .
- Find a vector equation of the line l . (4 marks)
 - Find the position vector of the point C which lies on the line segment AB such that $AC = 2CB$. (3 marks)
- (E) 2 Find a Cartesian equation of the straight line that passes through the points with coordinates $(7, -1, 2)$ and $(-1, 3, 8)$. (4 marks)
- (E) 3 Find a vector equation of the straight line which passes through the point A with position vector $2\mathbf{i} + 3\mathbf{j} - 4\mathbf{k}$, and is parallel to the vector $2\mathbf{j} + 3\mathbf{k}$. (3 marks)
- (E/P) 4 A straight line l has vector equation $\mathbf{r} = \begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix}$.
- Write down a Cartesian equation for l . (2 marks)
 - Given that the point $(0, a, b)$ lies on l , find the value of a and the value of b . (3 marks)
- 5 A straight line l has vector equation $\mathbf{r} = (\mathbf{i} + 2\mathbf{j} - \mathbf{k}) + \lambda(3\mathbf{i} + \mathbf{j} - 2\mathbf{k})$. Show that another vector equation of l is $\mathbf{r} = (7\mathbf{i} + 4\mathbf{j} - 5\mathbf{k}) + \lambda(9\mathbf{i} + 3\mathbf{j} - 6\mathbf{k})$.
- 6 A straight line l has Cartesian equation $\frac{x+2}{1} = \frac{y-2}{3} = \frac{z+3}{4}$.
- Find a vector form of the equation of l . b Verify that the point $(0, 8, 5)$ lies on l .
- 7 A plane passes through the points $A(2, -1, 2)$, $B(1, 3, -1)$ and $C(4, 2, 5)$.
- Find a vector form of the equation of the plane. (3 marks)
 - Find a Cartesian form of the equation of the plane. (3 marks)
- 8 A Cartesian form of the equation of a plane is $3x + 2y - 4z = 18$. Find a vector form of the equation of the plane.
- (E/P) 9 With respect to an origin O , the position vectors of the points L , M and N are $\begin{pmatrix} 4 \\ 7 \\ 7 \end{pmatrix}$, $\begin{pmatrix} 1 \\ 3 \\ 2 \end{pmatrix}$ and $\begin{pmatrix} 2 \\ 4 \\ 6 \end{pmatrix}$ respectively.
- Find the vectors \overrightarrow{ML} and \overrightarrow{MN} . (3 marks)
 - Prove that $\cos \angle LMN = \frac{9}{10}$ (3 marks)
- (E/P) 10 Referred to a fixed origin O , the points A , B and C have position vectors $9\mathbf{i} - 2\mathbf{j} + \mathbf{k}$, $6\mathbf{i} + 2\mathbf{j} + 6\mathbf{k}$ and $3\mathbf{i} + p\mathbf{j} + q\mathbf{k}$ respectively, where p and q are constants.
- Find, in vector form, an equation of the line l which passes through A and B . (2 marks)
- Given that C lies on l ,
- find the value of p and the value of q (2 marks)
 - calculate, in degrees, the acute angle between OC and AB . (3 marks)
- The point D lies on AB and is such that OD is perpendicular to AB .
- Find the position vector of D . (5 marks)

- (E) 11 Referred to a fixed origin O , the points A and B have position vectors $\begin{pmatrix} 1 \\ 2 \\ -3 \end{pmatrix}$ and $\begin{pmatrix} 5 \\ 0 \\ -3 \end{pmatrix}$ respectively.

a Find, in vector form, an equation of the line l_1 which passes through A and B . (3 marks)

The line l_2 has equation $\mathbf{r} = \begin{pmatrix} 4 \\ -4 \\ 3 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ -2 \\ 2 \end{pmatrix}$, where μ is a scalar parameter.

b Show that A lies on l_2 . (2 marks)

c Find, in degrees, the acute angle between the lines l_1 and l_2 . (4 marks)

The point C with position vector $\begin{pmatrix} 0 \\ 4 \\ -5 \end{pmatrix}$ lies on l_2 .

d Find the shortest distance from C to the line l_1 . (4 marks)

- (E) 12 Two submarines are travelling in straight lines through the ocean. Relative to a fixed origin, the vector equations of the two lines, l_1 and l_2 , along which they travel are

$$l_1: \mathbf{r} = 3\mathbf{i} + 4\mathbf{j} - 5\mathbf{k} + \lambda(\mathbf{i} - 2\mathbf{j} + 2\mathbf{k})$$

$$l_2: \mathbf{r} = 9\mathbf{i} + \mathbf{j} - 2\mathbf{k} + \mu(4\mathbf{i} + \mathbf{j} - \mathbf{k})$$

where λ and μ are scalars.

a Show that the submarines are moving in perpendicular directions. (2 marks)

b Given that l_1 and l_2 intersect at the point A , find the position vector of A . (4 marks)

The point B has position vector $10\mathbf{j} - 11\mathbf{k}$.

c Show that only one of the submarines passes through the point B . (3 marks)

d Given that 1 unit on each coordinate axis represents 100 m, find, in km, the distance AB . (2 marks)

- (E) 13 Find the shortest distance between the lines with vector equations

$$\mathbf{r} = 3\mathbf{i} + s\mathbf{j} - \mathbf{k} \quad \text{and} \quad \mathbf{r} = 9\mathbf{i} - 2\mathbf{j} - \mathbf{k} + t(\mathbf{i} - 2\mathbf{j} + \mathbf{k})$$

where s and t are scalars. (4 marks)

- (E) 14 Obtain the shortest distance between the lines with equations

$$\mathbf{r} = (3s - 3)\mathbf{i} - s\mathbf{j} + (s + 1)\mathbf{k} \quad \text{and} \quad \mathbf{r} = (3 + t)\mathbf{i} + (2t - 2)\mathbf{j} + \mathbf{k}$$

where s and t are parameters. (4 marks)

- 15 Find, in the form $\mathbf{r} \cdot \mathbf{n} = p$, an equation of the plane which contains the line l and the point with position vector \mathbf{a} where:

a l has equation $\mathbf{r} = \mathbf{i} + \mathbf{j} - 2\mathbf{k} + \lambda(2\mathbf{i} - \mathbf{k})$ and $\mathbf{a} = 4\mathbf{i} + 3\mathbf{j} + \mathbf{k}$

b l has equation $\mathbf{r} = \mathbf{i} + 2\mathbf{j} + 2\mathbf{k} + \lambda(2\mathbf{i} + \mathbf{j} - 3\mathbf{k})$ and $\mathbf{a} = 3\mathbf{i} + 5\mathbf{j} + \mathbf{k}$

c l has equation $\mathbf{r} = 2\mathbf{i} - \mathbf{j} + \mathbf{k} + \lambda(\mathbf{i} + 2\mathbf{j} + 2\mathbf{k})$ and $\mathbf{a} = 7\mathbf{i} + 8\mathbf{j} + 6\mathbf{k}$

- 16 Find a Cartesian equation of the plane which passes through the point $(1, 1, 1)$ and contains

$$\text{the line with equation } \frac{x-2}{3} = \frac{y+4}{1} = \frac{z-1}{2}$$

- (E) 17** A plane passes through the three points A , B and C , whose position vectors, referred to an origin O , are $\mathbf{i} + 3\mathbf{j} + 3\mathbf{k}$ and $3\mathbf{i} + \mathbf{j} + 4\mathbf{k}$, $2\mathbf{i} + 4\mathbf{j} + \mathbf{k}$ respectively.
- Find, in the form $l\mathbf{i} + m\mathbf{j} + n\mathbf{k}$, a unit vector normal to this plane. (4 marks)
 - Find also a Cartesian equation of the plane. (2 marks)
 - Find the perpendicular distance from the origin to this plane. (4 marks)
- (E) 18** a Show that the vector $\mathbf{i} + \mathbf{k}$ is perpendicular to the plane with vector equation

$$\mathbf{r} = \mathbf{i} + s\mathbf{j} + t(\mathbf{i} - \mathbf{k})$$
 (3 marks)
- Find the perpendicular distance from the origin to this plane. (4 marks)
 - Hence or otherwise obtain a Cartesian equation of the plane. (2 marks)
- (E) 19** The points A , B and C have position vectors $\mathbf{i} + \mathbf{j} + \mathbf{k}$, $5\mathbf{i} - 2\mathbf{j} + \mathbf{k}$ and $3\mathbf{i} + 2\mathbf{j} + 6\mathbf{k}$ respectively, referred to an origin O .
- Find a vector perpendicular to the plane containing the points A , B and C . (4 marks)
 - Hence, or otherwise, find an equation for the plane which contains the points A , B and C , in the form $ax + by + cz + d = 0$. (2 marks)
- (E/P) 20** Planes Π_1 and Π_2 have equations given by
- $$\Pi_1: \mathbf{r} \cdot (2\mathbf{i} - \mathbf{j} + \mathbf{k}) = 0,$$
- $$\Pi_2: \mathbf{r} \cdot (\mathbf{i} + 5\mathbf{j} + 3\mathbf{k}) = 1$$
- Show that the point $A(2, -2, 3)$ lies in Π_2 . (2 marks)
 - Show that Π_1 is perpendicular to Π_2 . (4 marks)
 - Find, in vector form, an equation of the straight line through A which is perpendicular to Π_1 . (2 marks)
 - Determine the coordinates of the point where this line meets Π_1 . (4 marks)
 - Find the perpendicular distance of A from Π_1 . (4 marks)
- (E/P) 21** With respect to a fixed origin O , the straight lines l_1 and l_2 are given by
- $$l_1: \mathbf{r} = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ 1 \\ -2 \end{pmatrix},$$
- $$l_2: \mathbf{r} = \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} + \mu \begin{pmatrix} -3 \\ 0 \\ 1 \end{pmatrix}$$
- where λ and μ are scalar parameters.
- Show that the lines intersect. (3 marks)
 - Find the position vector of their point of intersection. (1 mark)
 - Find the cosine of the acute angle between the lines. (4 marks)
- (E/P) 22** The line l_1 has vector equation $\mathbf{r} = 6\mathbf{i} + 8\mathbf{j} + 5\mathbf{k} + \lambda(\mathbf{i} - \mathbf{j} + \mathbf{k})$, where λ is a scalar parameter. The point A has coordinates $(3, a, 2)$, where a is a constant. The point B has coordinates $(8, 6, b)$, where b is a constant. Points A and B lie on the line l_1 .
- Find the values of a and b . (3 marks)
- Given that the point O is the origin, and that the point P lies on l_1 such that OP is perpendicular to l_1 ,

- b** find the coordinates of P . (5 marks)
- c** Hence find the distance OP , giving your answer in surd form. (2 marks)

- (E/P) 23** Relative to a fixed origin O , the point A has position vector $6\mathbf{i} + 3\mathbf{j} + 4\mathbf{k}$, and the point B has position vector $5\mathbf{i} + 2\mathbf{j} + 6\mathbf{k}$. The line l passes through the points A and B .
- a** Find the vector \overrightarrow{AB} . (2 marks)
- b** Find a vector equation for the line l . (2 marks)
- The point C has position vector $4\mathbf{i} + 10\mathbf{j} + 2\mathbf{k}$.
- The point P lies on l . Given that the vector \overrightarrow{CP} is perpendicular to l ,
- c** find the position vector of the point P . (6 marks)

- (E/P) 24** With respect to a fixed origin O , the lines l_1 and l_2 are given by the equations

$$l_1: \mathbf{r} = \begin{pmatrix} 3 \\ -2 \\ 4 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ 1 \\ -1 \end{pmatrix} \quad l_2: \mathbf{r} = \begin{pmatrix} 1 \\ 12 \\ 8 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ -2 \\ -1 \end{pmatrix}$$

where λ and μ are scalar parameters.

- a** Show that l_1 and l_2 meet and find the position vector of their point of intersection, A . (6 marks)
- b** Find, to the nearest 0.1° , the acute angle between l_1 and l_2 . (3 marks)

The point B has position vector $\begin{pmatrix} 5 \\ -1 \\ 3 \end{pmatrix}$.

- c** Show that B lies on l_1 . (1 mark)
- d** Find the shortest distance from B to the line l_2 , giving your answer to 3 significant figures. (4 marks)

- (E/P) 25** The plane P has equation $\mathbf{r} \cdot (2\mathbf{i} - 2\mathbf{j} + 3\mathbf{k}) = 1$.

The line l passes through the point $A (1, 2, 2)$ and meets P at $(4, 2, -1)$.

The acute angle between the plane P and the line l is α .

- a** Find α to the nearest degree. (4 marks)
- b** Find the perpendicular distance from A to the plane P . (4 marks)

- (E/P) 26** Two aeroplanes are modelled as travelling in straight lines. Aeroplane A travels from a point

with position vector $\begin{pmatrix} 120 \\ -80 \\ 13 \end{pmatrix}$ km to a point with position vector $\begin{pmatrix} 200 \\ 20 \\ 5 \end{pmatrix}$ km, relative to a fixed

origin O . Aeroplane B starts at a point with position vector $\begin{pmatrix} -20 \\ 35 \\ 5 \end{pmatrix}$ km relative to O , and flies in the direction of $\begin{pmatrix} 10 \\ -2 \\ 0.1 \end{pmatrix}$.

- a** Show that the flight paths of the two aeroplanes will intersect, and determine the position vector of the point of intersection. (7 marks)

An air traffic controller states that this means that the planes will collide.

- b** Explain why this conclusion is not necessarily correct. (2 marks)

Challenge

- 1 a Show that the equations $4x - 2y + 6z = 10$ and $-2x + y - 3z = -5$ represent the same plane.
- b Hence explain why the matrix $\begin{pmatrix} 4 & -2 & 6 \\ -2 & 1 & -3 \\ a & b & c \end{pmatrix}$ is singular for all possible values of a, b and c .
- c Find values of a, b and c such that the matrix equation $\begin{pmatrix} 4 & -2 & 6 \\ -2 & 1 & -3 \\ a & b & c \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 10 \\ -5 \\ 15 \end{pmatrix}$ has
- i no solutions
 - ii infinitely many solutions.
- 2 The points A, B and C have coordinates $(2, -9, 0)$, $(10, -3, 6)$ and $(8, -1, 2)$ respectively. Find the centre and radius of the circle that passes through all three points.

Summary of key points

- 1 A vector equation of a straight line passing through the point A with position vector \mathbf{a} , and parallel to the vector \mathbf{b} , is

$$\mathbf{r} = \mathbf{a} + \lambda\mathbf{b}$$

where λ is a scalar parameter.

- 2 A vector equation of a straight line passing through the points C and D , with position vectors \mathbf{c} and \mathbf{d} respectively, is

$$\mathbf{r} = \mathbf{c} + \lambda(\mathbf{d} - \mathbf{c})$$

where λ is a scalar parameter.

- 3 If $\mathbf{a} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix}$ and $\mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix}$, the equation of the line with vector equation $\mathbf{r} = \mathbf{a} + \lambda\mathbf{b}$ can be given

in Cartesian form as:

$$\frac{x - a_1}{b_1} = \frac{y - a_2}{b_2} = \frac{z - a_3}{b_3}$$

Each of these three expressions is equal to λ .

- 4 The vector equation of a plane is

$$\mathbf{r} = \mathbf{a} + \lambda\mathbf{b} + \mu\mathbf{c}, \text{ where:}$$

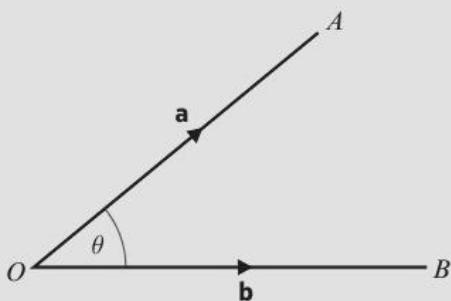
- \mathbf{r} is the position vector of a general point in the plane
- \mathbf{a} is the position vector of a point in the plane
- \mathbf{b} and \mathbf{c} are non-parallel, non-zero vectors in the plane
- λ and μ are scalars

5 A Cartesian equation of a plane in three dimensions can be written in the form $ax + by + cz = d$ where a, b, c and d are constants, and $\begin{pmatrix} a \\ b \\ c \end{pmatrix}$ is the normal vector to the plane.

6 The **scalar product** of two vectors \mathbf{a} and \mathbf{b} is written as $\mathbf{a} \cdot \mathbf{b}$ (say ‘ \mathbf{a} dot \mathbf{b} ’), and defined as

$$\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}| \cos \theta$$

where θ is the angle between \mathbf{a} and \mathbf{b} .



7 If \mathbf{a} and \mathbf{b} are the position vectors of the points A and B , then $\cos(\angle AOB) = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}| |\mathbf{b}|}$

8 The non-zero vectors \mathbf{a} and \mathbf{b} are perpendicular if and only if $\mathbf{a} \cdot \mathbf{b} = 0$.

9 If \mathbf{a} and \mathbf{b} are parallel, $\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| |\mathbf{b}|$. In particular, $\mathbf{a} \cdot \mathbf{a} = |\mathbf{a}|^2$.

10 If $\mathbf{a} = a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k}$ and $\mathbf{b} = b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k}$

$$\mathbf{a} \cdot \mathbf{b} = \begin{pmatrix} a_1 \\ a_2 \\ a_3 \end{pmatrix} \cdot \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} = a_1b_1 + a_2b_2 + a_3b_3$$

11 The acute angle θ between two intersecting straight lines is given by

$$\cos \theta = \left| \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}| |\mathbf{b}|} \right|$$

where \mathbf{a} and \mathbf{b} are direction vectors of the lines.

12 The scalar product form of the equation of a plane is $\mathbf{r} \cdot \mathbf{n} = k$ where $k = \mathbf{a} \cdot \mathbf{n}$ for any point in the plane with position vector \mathbf{a} .

13 The acute angle θ between the line with equation $\mathbf{r} = \mathbf{a} + \lambda\mathbf{b}$ and the plane with equation $\mathbf{r} \cdot \mathbf{n} = k$ is given by the formula

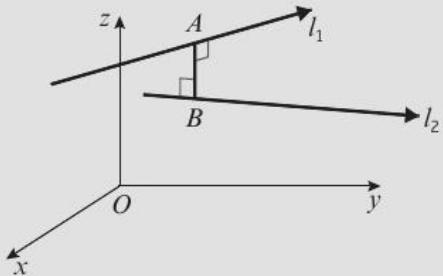
$$\sin \theta = \left| \frac{\mathbf{b} \cdot \mathbf{n}}{|\mathbf{b}| |\mathbf{n}|} \right|$$

14 The acute angle θ between the plane with equation $\mathbf{r} \cdot \mathbf{n}_1 = k_1$ and the plane with equation $\mathbf{r} \cdot \mathbf{n}_2 = k_2$ is given by the formula

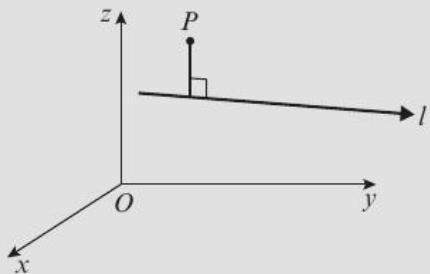
$$\cos \theta = \left| \frac{\mathbf{n}_1 \cdot \mathbf{n}_2}{|\mathbf{n}_1| |\mathbf{n}_2|} \right|$$

15 Two lines are **skew** if they are not parallel and they do not intersect.

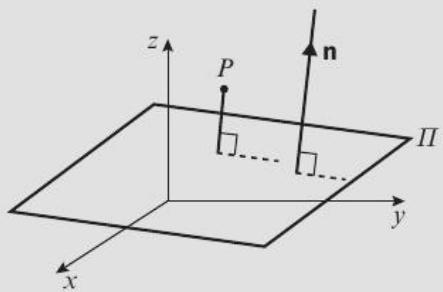
16 For any two non-intersecting lines l_1 and l_2 there is a unique line segment AB such that A lies on l_1 , B lies on l_2 and AB is perpendicular to both lines.



17 The perpendicular from a point P to a line l is a line drawn from P at right angles to l .



18 The perpendicular from a point P to a plane Π is a line drawn from P parallel to the normal vector \mathbf{n} .



19 k is the length of the perpendicular from the origin to a plane Π , where the equation of plane Π is written in the form $\mathbf{r} \cdot \hat{\mathbf{n}} = k$, where $\hat{\mathbf{n}}$ is a unit vector perpendicular to Π .

The perpendicular distance from the point with coordinates (α, β, γ) and the plane with equation $ax + by + cz = d$ is

$$\frac{|a\alpha + b\beta + c\gamma - d|}{\sqrt{a^2 + b^2 + c^2}}$$