### Q 1

a.

By Amdahl's Law, Speedup:

$$S = \frac{1}{(1 - 0.8) + \frac{0.8}{2}} = \frac{5}{3}$$

Then frequency can be decrease:

$$F_{
m new} = rac{F_{
m old}}{S}$$

Therefore:

$$rac{F_{
m new}}{F_{
m old}} = rac{1}{S} = 0.6$$

b.

$$P_{dual} = 0.5 * C * (0.6V_{original})^2 \cdot (0.6f_{original}) = 0.216P_{original}$$

Thus, the dual-core system requires 21.6% of the dynamic power compared to the single-core system.

C.

We can know that

$$V_{new}=0.3V_{old}$$
  $S=rac{1}{(1-P)+rac{P}{2}}=rac{1}{rac{V_{new}}{V_{old}}}=3.3$ 

So that

$$P = 1.4$$

Since P cannot be greater than 1, this indicates that the voltage floor constraint is not feasible for this level of parallelization

d.

$$P_{Dual} = 0.5 * C * (0.3V_{origin}^2) * (0.3f_{origin}) = 0.3^3 P_{origin}$$

Thus the dual-core system with the voltage floor will require 2.7% of the dynamic power compared to the single-core system

**Q2** 

 For a large number of identical and independent components, the MTTF of the system can be approximated by:

$$MTTF_{system} pprox rac{MTTF_{ ext{computer}}}{Fraction~of~computers~failing} \ MTTF_{ ext{system}} pprox 90 ext{days}$$

#### Q3

The number of transistors on a microchip doubles approximately every two years, while the cost of computing power decreases.

#### Q4

Amdahl's Law is a formula used to predict the potential speedup of a task when a portion of it is parallelized. It states that the overall improvement gained by parallelizing part of a program is limited by the fraction of the task that remains sequential (cannot be parallelized).

The law is expressed as:

$$S = \frac{1}{(1-P) + \frac{P}{N}}$$

where:

- · S is the speedup,
- P is the proportion of the task that can be parallelized,
- N is the number of processors.

## Q 5

An Instruction Set Architecture (ISA) defines the set of instructions that a processor can execute and how it interacts with the system. It typically includes the following components:

Instructions, Registers, Addressing Modes, Data Types, Instruction Formats, Memory Architecture and Control Flow.

### **Q6**

We start by calculating the failure rate ( $\lambda$ ) for each component from its MTTF:

$$egin{align*} \lambda_{
m system} &= rac{10}{1000,000} + rac{1}{500,000} + rac{1}{200,000} + rac{1}{200,000} + rac{1}{1,000,000} \ \\ \lambda_{
m system} &= rac{10 + 2 + 5 + 5 + 1}{1,000,000} = rac{23}{1,000,000} \ \\ MTTF_{
m system} &= rac{1}{\lambda_{
m system}} pprox 43478 
m hours \end{aligned}$$

Q7

$$S = rac{1}{rac{0.5}{10} + 0.5} pprox 1.818$$

#### **Q8**

The overall baseline CPI is:

$$\begin{aligned} \text{CPI}_{\text{total}} &= f_{\text{FP}} \cdot \text{CPI}_{\text{FP}} + f_{\text{Non-FP}} \cdot \text{CPI}_{\text{Non-FP}} \\ \text{CPI}_{\text{total}} &= 0.25 \cdot 4.0 + 0.75 \cdot 1.33 = 1.0 + 0.9975 = 1.9975 \end{aligned}$$

#### a. alternative 1

$$ext{CPI}_{ ext{FP, new}} = f_{ ext{FSQRT}} \cdot ext{CPI}_{ ext{FSQRT, new}} + f_{ ext{Other FP}} \cdot ext{CPI}_{ ext{Other FP}} \$$
 $ext{CPI}_{ ext{FP, new}} = 0.02 \cdot 1.5 + 0.23 \cdot 4.0 = 0.03 + 0.92 = 0.95 \$ 
 $ext{CPI}_{ ext{total, new}} = f_{ ext{FP}} \cdot ext{CPI}_{ ext{FP, new}} + f_{ ext{Non-FP}} \cdot ext{CPI}_{ ext{Non-FP}} \$ 
 $ext{CPI}_{ ext{total, new}} = 0.25 \cdot 0.95 + 0.75 \cdot 1.33 = 0.2375 + 0.9975 = 1.235 \$ 

# b. alternative 2

$$ext{CPI}_{ ext{total, new}} = f_{ ext{FP}} \cdot ext{CPI}_{ ext{FP, new}} + f_{ ext{Non-FP}} \cdot ext{CPI}_{ ext{Non-FP}}$$
 $ext{CPI}_{ ext{total, new}} = 0.25 \cdot 2.0 + 0.75 \cdot 1.33 = 0.5 + 0.9975 = 1.4975$ 

Thus, alternative 1 (decreasing the CPI of FSQRT to 1.5) gives a better performance improvement, as it results in a lower overall CPI