Tairan He

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Education

Carnegie Mellon University

Ph.D. IN ROBOTICS

Pittsburgh, USA

Aug. 2023 - Present

Shanghai Jiao Tong University

B.Eng. IN COMPUTER SCIENCE

Shanghai, China

Aug. 2018 - Jun. 2023

Publications (*equal contribution) _

CONFERENCE PROCEEDINGS

[C14] OmniH2O: Universal and Dexterous Human-to-Humanoid Whole-Body Teleoperation and Learning.

Tairan He*, Zhengyi Luo*, Xialin He*, Wenli Xiao, Chong Zhang, Kris Kitani, Weinan Zhang, Changliu Liu, Guanya Shi. *CoRL*, 2024 [Paper]

[C13] WoCoCo: Learning Whole-Body Humanoid Control with Sequential Contacts.

Chong Zhang*, Wenli Xiao*, **Tairan He**, Guanya Shi.

CoRL, 2024 [Paper]

[C12] Learning Human-to-Humanoid Real-Time Whole-Body Teleoperation.

Tairan He*, Zhengyi Luo*, Wenli Xiao, Chong Zhang, Kris Kitani, Changliu Liu, Guanya Shi. *IROS*, 2024 (Oral Presentation) [Paper]

[C11] Progressive Adaptive Chance-Constrained Safeguards for Reinforcement Learning.

Zhaorun Chen, Binhao Chen, **Tairan He**, Liang Gong, Chengliang Liu. *IROS*, 2024 (Oral Pitch) [Paper]

[C10] Agile But Safe: Learning Collision-Free High-Speed Legged Locomotion.

Tairan He*, Chong Zhang*, Wenli Xiao, Guanqi He, Changliu Liu, Guanya Shi.

RSS, 2024 (Outstanding Student Paper Award Finalist - Top 3) [Paper]

[C9] Safe Deep Policy Adaptation.

Wenli Xiao*, **Tairan He***, John Dolan, Guanya Shi.

ICRA, 2024 [Paper]

[C8] State-wise Safe Reinforcement Learning: A Survey.

Weiye Zhao, Tairan He, Rui Chen, Tianhao Wei, Changliu Liu.

IJCAI (Survey Track), 2023. [Paper]

[C7] Probabilistic Safeguard for Reinforcement Learning Using Safety Index Guided Gaussian Process Models.

Weiye Zhao*, **Tairan He***, Changliu Liu.

L4DC, 2023. [Paper]

[C6] Visual Imitation Learning with Patch Rewards.

Minghuan Liu, **Tairan He**, Weinan Zhang, Shuicheng Yan, Zhongwen Xu.

ICLR, 2023. [Paper]

[C5] Safety Index Synthesis via Sum-of-Squares Programming.

Weiye Zhao*, **Tairan He***, Tianhao Wei, Simin Liu, Changliu Liu.

ACC, 2023. [Paper]

[C4] AutoCost: Evolving Intrinsic Cost for Zero-violation Reinforcement Learning.

Tairan He, Weiye Zhao, Changliu Liu.

AAAI, 2023. [Paper]

[C3] Reinforcement Learning with Automated Auxiliary Loss Search.

Tairan He, Yuge Zhang, Kan Ren, Minghuan Liu, Che Wang, Weinan Zhang, Yuqing Yang, Dongsheng Li. *NeurIPS*, 2022. [Paper]

[C2] Model-free Safe Control for Zero-Violation Reinforcement Learning.

Weiye Zhao, Tairan He, Changliu Liu.

CoRL, 2021. [Paper]

[C1] Energy-Based Imitation Learning.

Minghuan Liu, Tairan He, Minkai Xu, Weinan Zhang.

AAMAS, 2021 (Oral) [Paper]

Professional Services

Reviewer International Conference on Machine Learning (ICML), 2024

Reviewer International Conference on Learning Representations (ICLR), 2024

Reviewer IEEE Conference on Decision and Control (CDC), 2023

Reviewer Conference on Neural Information Processing Systems (NeurIPS), 2023

Reviewer Learning for Dynamics & Control Conference (L4DC), 2023, 2024

Reviewer AAAI Conference on Artificial Intelligence (AAAI), 2022, 2023, 2024

Reviewer Conference on Robot Learning (CoRL), 2022, 2023, 2024

Reviewer IEEE-RAS International Conference on Humanoid Robots (Humanoids), 2024

Skills_

Programming C/C++, Python, TFX, JAVA, Node.js, Wolfram Language, SQL, Linux, MATLAB, PHP

Frameworks PyTorch, Tensorflow, NumPy, Flask, MySQL, Git, Anaconda, OpenCV.

Platforms Kinova, Rosbot. Unitree Go1

Research Experience _____

NVIDIA Research Santa Clara, USA

RESEARCH INTERN AT GEAR LAB, ADVISED BY JIM FAN AND YUKE ZHU

Jun. 2024 - Present

• Research Topics: humanoid whole-body control, dexterous bimanual manipulation.

Carnegie Mellon University

PHD STUDENT, ADVISED BY PROF. GUANYA SHI AND PROF. CHANGLIU LIU

Aug. 2023 - Present

• Research Topics: reinforcement learning, humanoid teleoperation, agile legged robots. Carnegie Mellon University

RESEARCH ASSISTANT AT INTELLIGENT CONTROL LAB, ADVISED BY PROF. CHANGLIU LIU

Research Topics: safe reinforcement learning, safe control, control theory.
 Microsoft Research

RESEARCH INTERN, ADVISED BY KAN REN AND YUGE ZHANG

• Research Topics: auto ML, reinforcement learning.

Shanghai Jiao Tong University

RESEARCH ASSISTANT AT APEX LAB, ADVISED BY PROF. WEINAN ZHANG

• Research Topics: reinforcement learning, imitation learning.

Shanghai, China Mar. 2021 - Dec. 2021

Jan. 2022 - Jan. 2023

Pittsburgh, USA

Pittsburgh, USA

Shanghai, China

Jul. 2019 - Jan. 2023

Project Portfolio (Selected) _

SJTU Anonymous Forum

Shanghai, China

FOUNDER & DEVELOPER. [ANDROID CODE] / [IOS CODE] / [FAREWELL VIDEO]

Feb. 2020 - Apr. 2021

- Develoed a care-free forum platform for SJTU students to share and talk using anonymous identities.
- More than **10000+** users used this app in the SJTU campus.

Honors and Awards (Selected) ___

- 2024 **Outstanding Student Paper Award Finalist Top 3**, Robotics: Science and Systems.
- 2021 **Microsoft Star of Tomorrow**, top-performing interns at Microsoft.
- 2020 **Shanghai Jiao Tong University Excellent Scholarship**, top 10% students in SJTU.
- 2019 **Zhiyuan Honorary Scholarship**, top 5% students in SJTU.