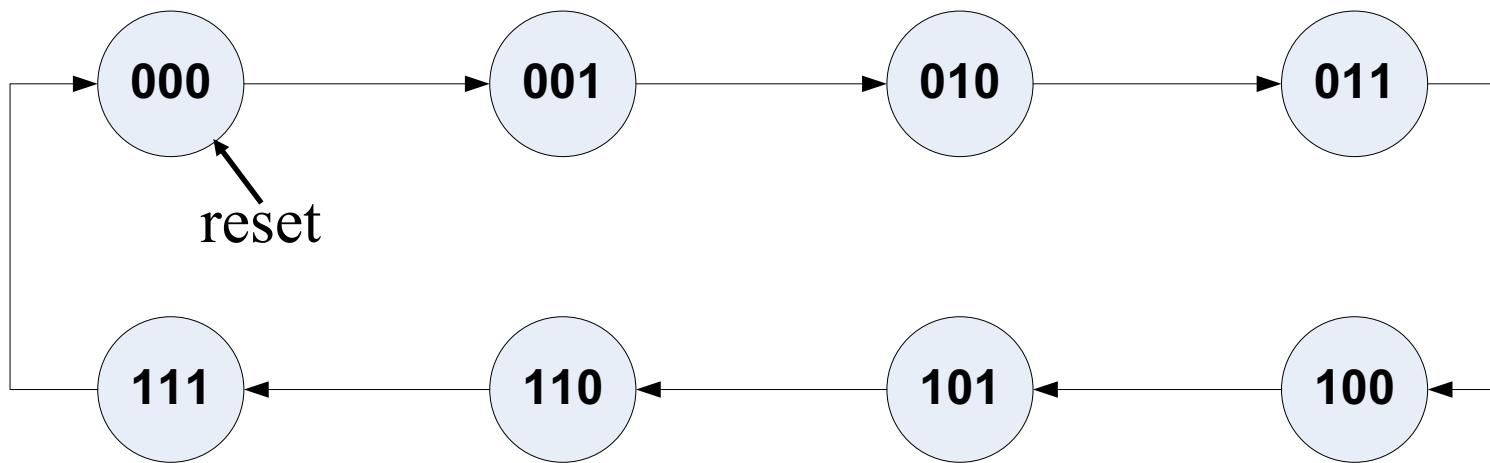


Topic 10

Finite State Machine

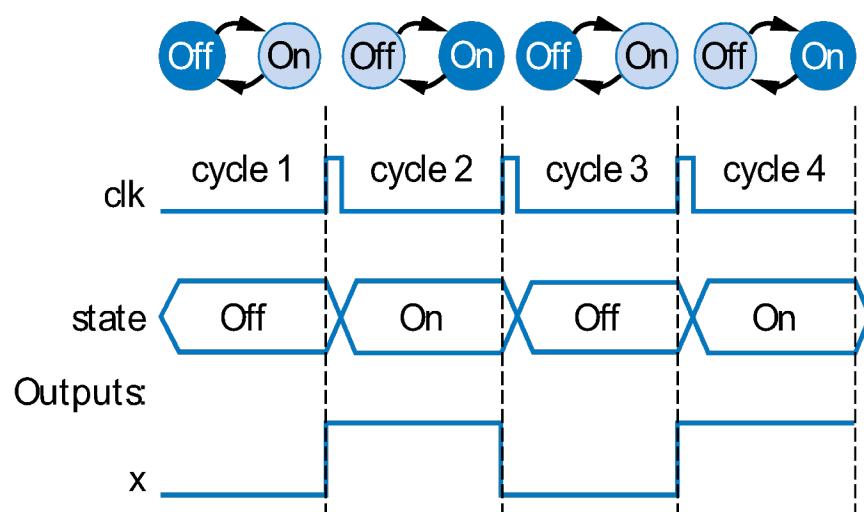
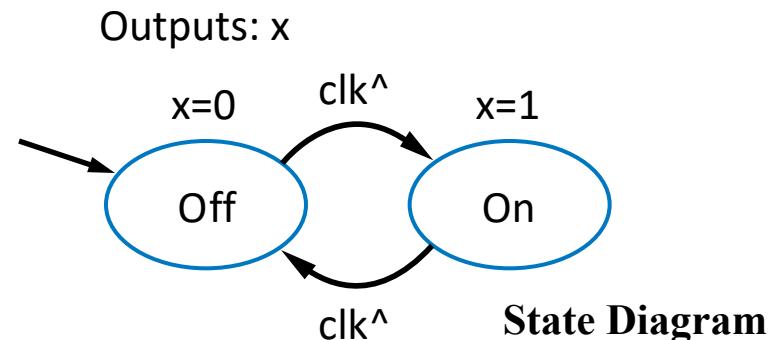
Recall Synchronous Binary Counter

- A circuit that changes its value (state) at every clock edge
- The counting sequence describes the behavior of the circuit



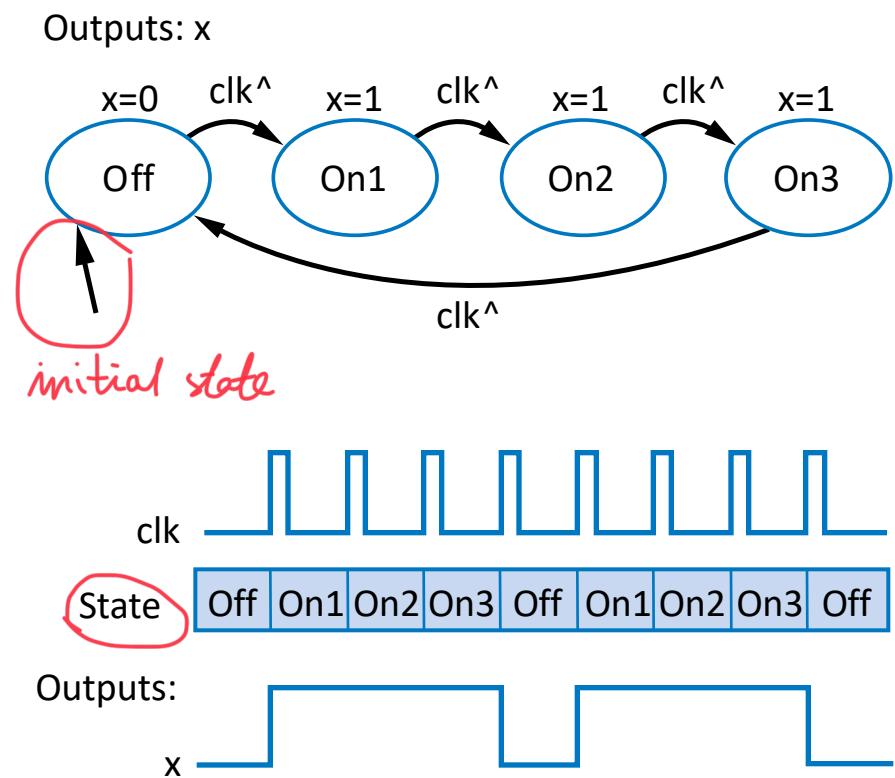
Describing Behavior of Sequential Circuit

- **Finite-State Machine (FSM)**
 - A way to describe **desired behavior** of a **sequential circuit**
 - Consists of a set of states, transitions between states, and maybe inputs and outputs
 - **present state**: currently happening
 - **next state**: next to happen
 - Example: Toggle output x every clock cycle
 - Two states: “Off” and “On”
 - Corresponding outputs: $x=0$ or 1
 - No input
 - Transition from Off to On, or On to Off, on **rising clock edge**
 - Arrow with **no starting state** points to **initial state**



Example: Output Special Pattern

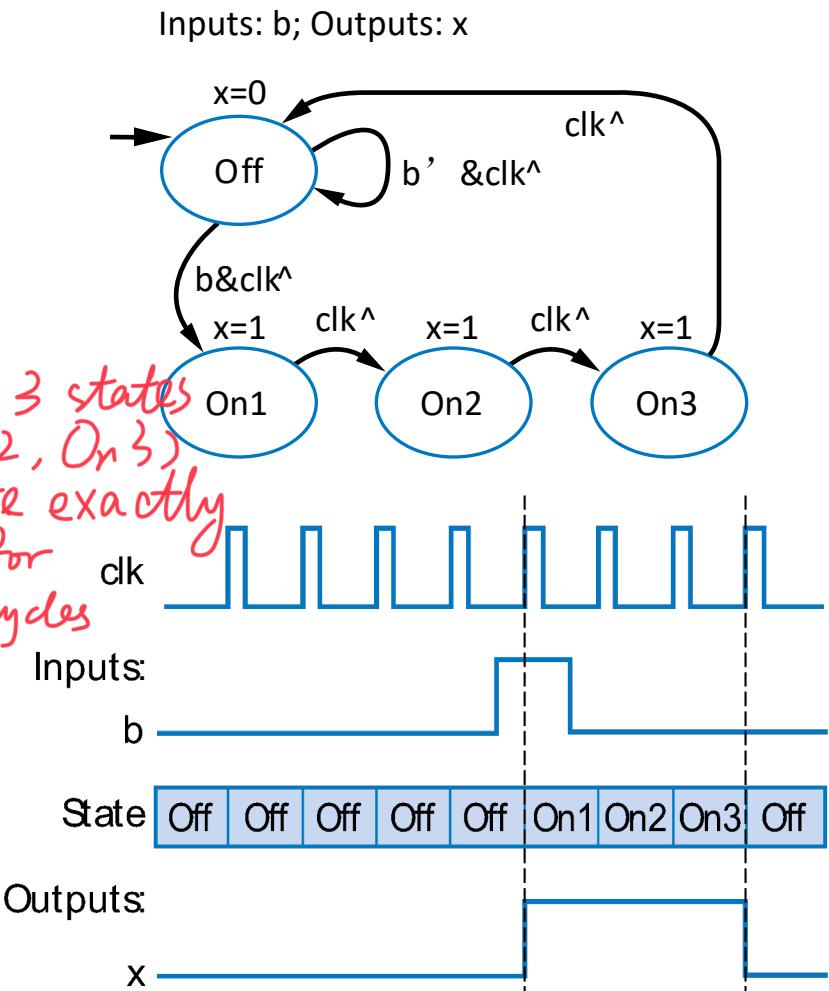
- Want a circuit to output
0, 1, 1, 1, 0, 1, 1, 1, ...
 - One bit at a time
 - Each bit for one clock cycle
- Can be described as FSM
 - Four states
 - Each state corresponds to an output, 0, 1, 1, 1
 - Then repeat
 - Transition on rising clock edge to next state



Example: FSM with Input

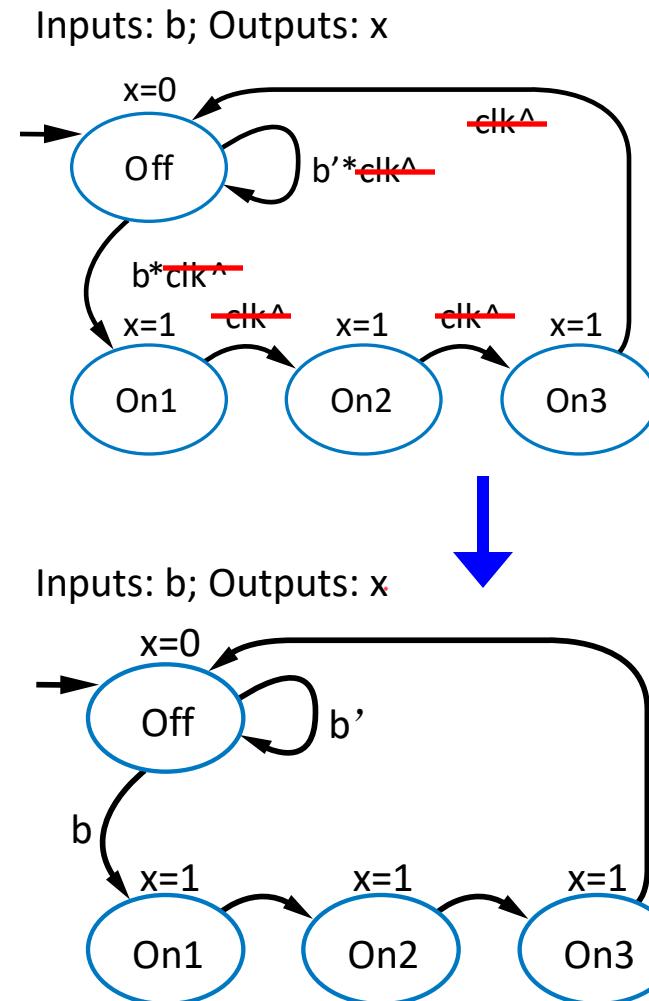
- b is a push button, output x to stay on for exactly 3 clock cycles no matter how long b is pushed
- Wait in “Off” state while b is 0 (b')
- When b is 1 (and rising clock edge), transition to On1
 - Sets $x=1$
 - On next two clock edges, transition to On2, then On3, which also set $x=1$
- So $x=1$ for three cycles after button pressed
- Potential issue: if button b stays on, what will happen?

Only “On” for 3 clk cycles



State Diagram Simplification: Clock Implicit

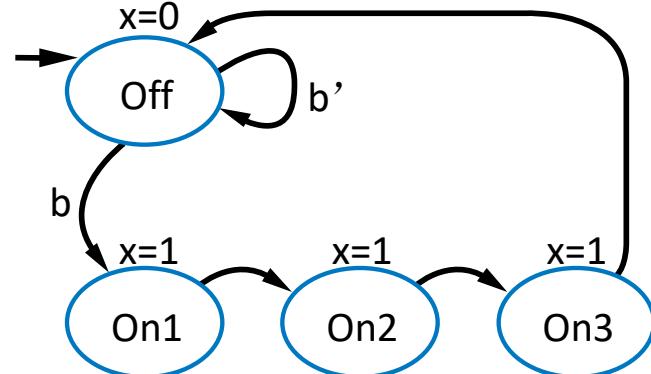
- **Synchronous** FSMs – FSM behaviors synchronized to active edge of clock
 - Asynchronous FSMs -- less common
- Make implicit – all state transitions are triggered by rising edge of clock
- Make implicit – Unlabeled path means transition is triggered **only by clock**, inputs don't matter



FSM Definition

- FSM consists of
 - Set of states
 - Ex: {Off, On1, On2, On3}
 - Set of inputs, set of outputs
 - Ex: Inputs: {b}, Outputs: {x}
 - Initial state
 - Ex: “Off”
 - Set of transitions
 - Describes next states
 - Ex: Has 5 transitions
 - Set of actions (outputs)
 - Sets outputs while in states
 - Ex: $x=0$, $x=1$, $x=1$, and $x=1$

Inputs: b; Outputs: x



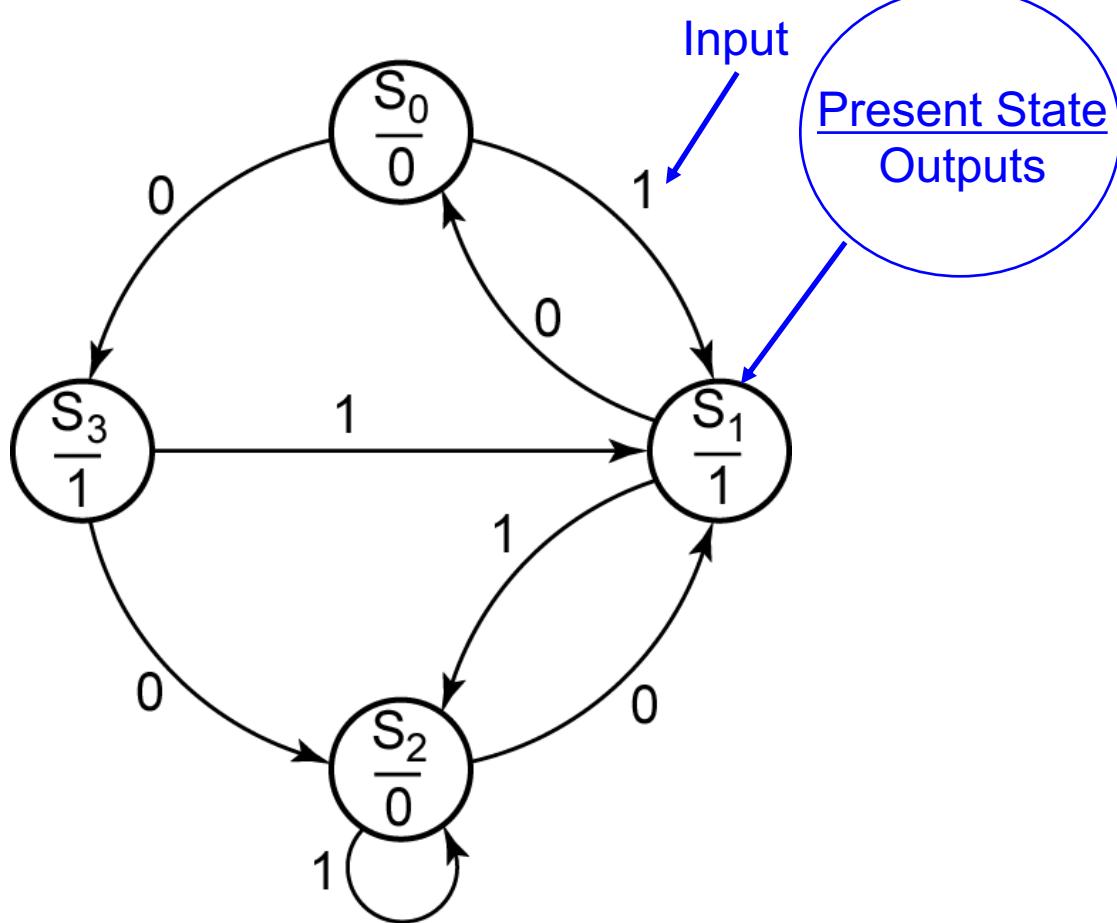
FSM can be represented graphically, known as **state diagram**

	Inputs			Outputs		
	s1	s0	b	x	n1	n0
Off	0	0	0	0	0	0
	0	0	1	0	0	1
On1	0	1	0	1	1	0
	0	1	1	1	1	0
On2	1	0	0	1	1	1
	1	0	1	1	1	1
On3	1	1	0	1	0	0
	1	1	1	1	0	0

FSM can also be represented in **tabular form**, known as **state table**

State Diagram and State Table

State Diagram



Outputs

Or

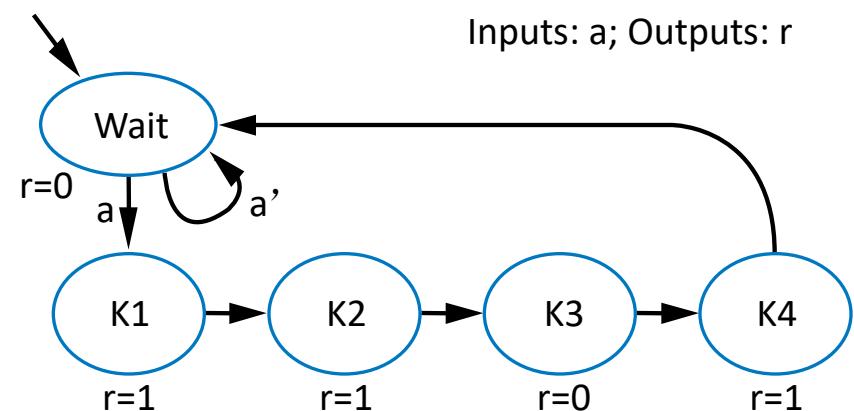
Present State

State Table

In	P.S.	N.S.	Out
0	S_0	S_3	0
1	S_0	S_1	0
0	S_1	S_0	1
1	S_1	S_2	1
0	S_2	S_1	0
1	S_2	S_2	0
0	S_3	S_2	1
1	S_3	S_1	1

Example: Secure Car Key

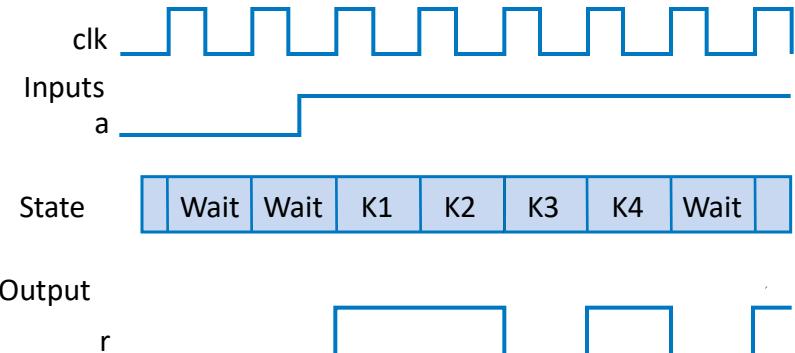
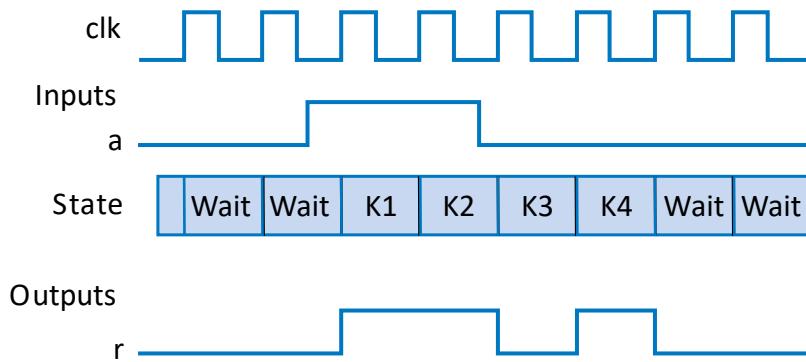
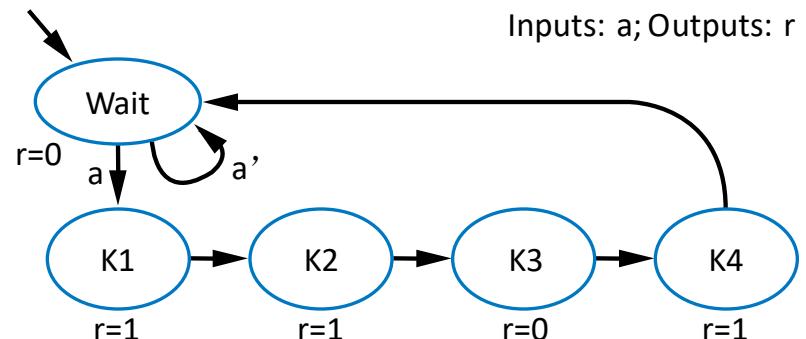
- All new car keys contain a tiny computer chip
 - When car starts, car's computer (under engine hood) requests identifier from key
 - Key transmits identifier
 - If not, computer shuts off car
- FSM
 - Wait until computer requests ID ($a=1$)
 - Transmit ID (in this case, 1101)



When there's a match, then turn on.

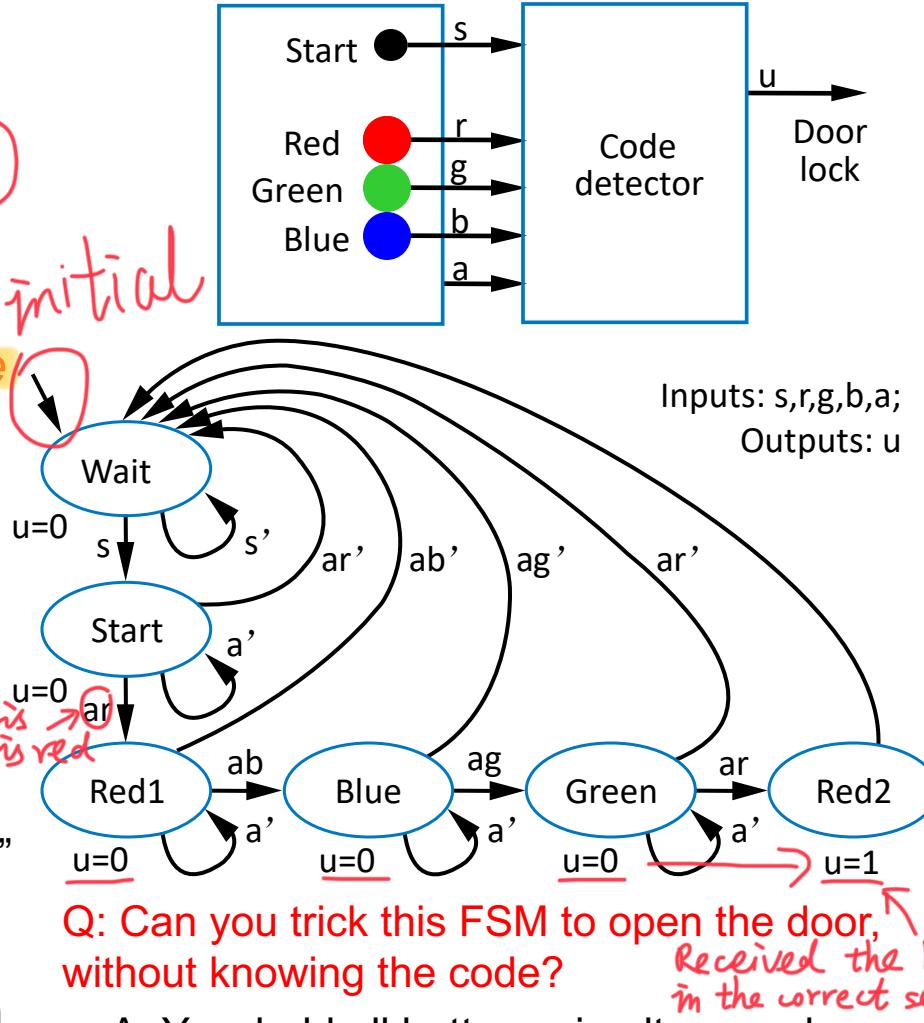
FSM Example: Secure Car Key (cont.)

- Timing diagrams show states and output values for different input waveforms



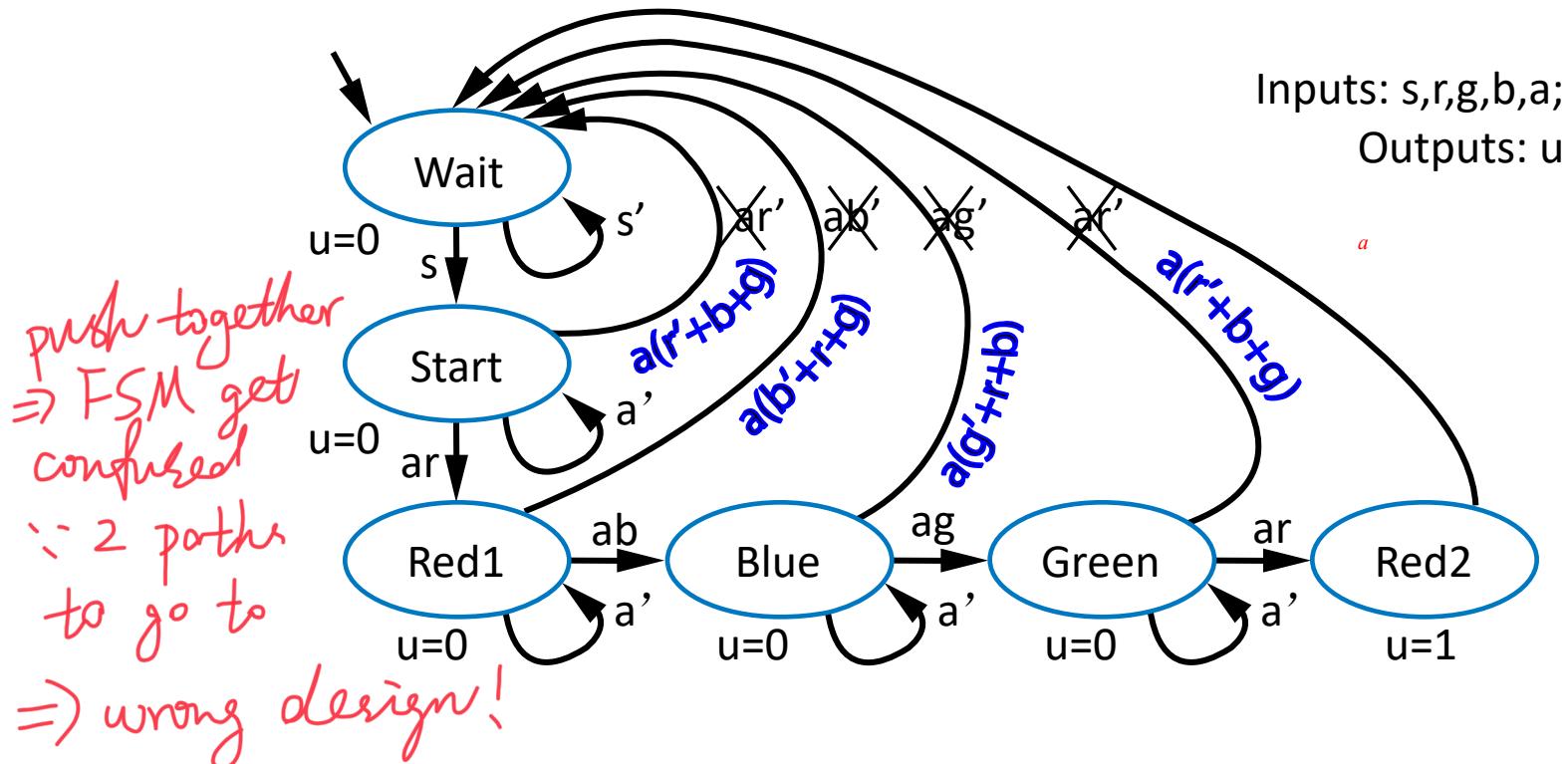
Example: Digital Lock

- Unlock door ($u=1$) only when buttons pressed **in sequence**:
 - start, then **red, blue, green, red**
- Input buttons: s, r, g, b
- Input a indicates that some color button pressed, **lasts for only one clock cycle with each button press**
- FSM
 - Wait for start ($s=1$) in “Wait”
 - Once started, go to “Start”, then
 - If see red, go to “Red1” **a button is pressed & is red**
 - Then, if see blue, go to “Blue”
 - Then, if see green, go to “Green”
 - Then, if see red, go to “Red2”, and $u=1$
 - Wrong button at any step, return to “Wait”, without opening door



A: Yes, hold all buttons simultaneously

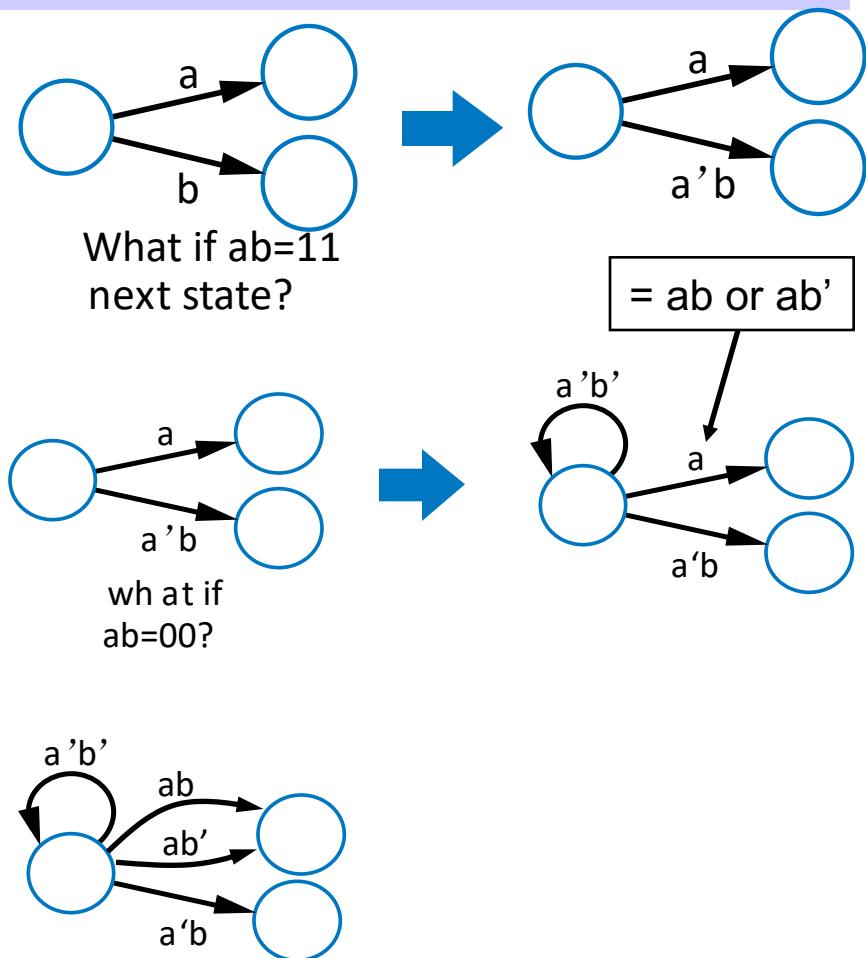
Improve FSM for Code Detector



- New transition conditions detect if wrong button pressed, returns to “Wait”

Common State Transition Property

- Only one condition **should** be true, among all transitions leaving a state
- One condition **must** be true
 - For any input combination
- All conditions **must** be considered when leaving a state



Pitfall is Common

- Recall code detector FSM

- Do the transitions obey the two required transition properties?

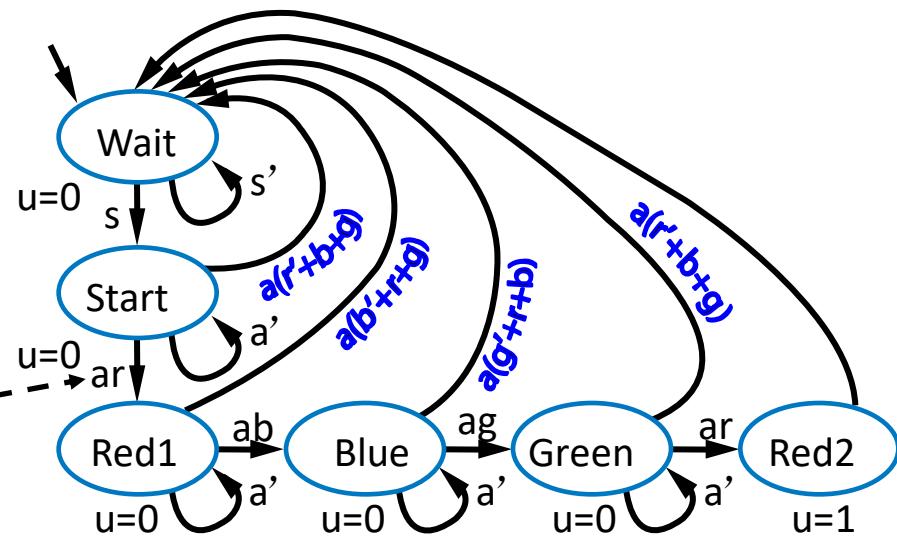
NO!

- How would it go wrong?

E.g. $arb\bar{g} = 1111$

How to solve?

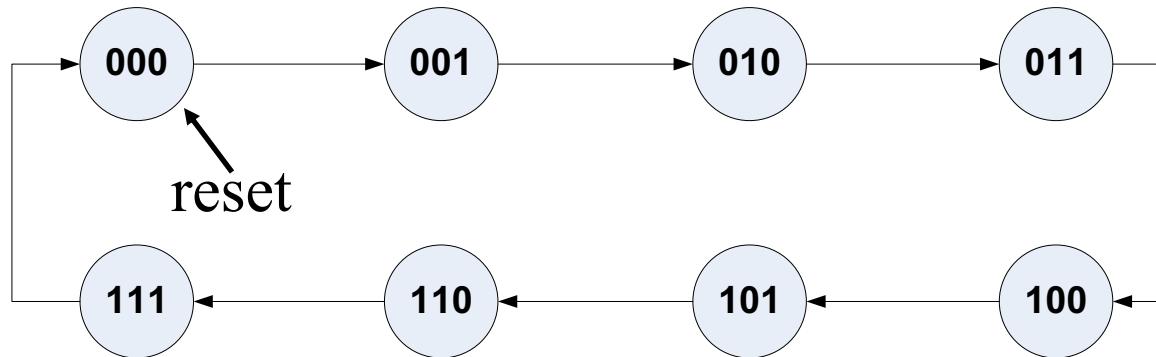
Answer: ar should be **$arb'g'$**
(likewise for ab, ag, ar)



Implementation of FSM

Example: Synchronous Binary Counter

- FSM that **counts binary numbers** – counter
- An n -bit binary counter can count in binary from 0 up to 2^n-1 and repeat
- An n -bit binary counter consists of n flip-flops
- All the flip-flops are synchronized to the same clock – synchronous counter
- May be implemented by different type of flip-flops
- Example: a 3-bit binary counter can count through this sequence



Synchronous Binary Counter Design

- An FSM (without external inputs)
 - State Table

Present State			Next State		
Q2	Q1	Q0	Q2 ⁺	Q1 ⁺	Q0 ⁺
0	0	0	0	0	1
0	0	1	0	1	0
0	1	0	0	1	1
0	1	1	1	0	0
1	0	0	1	0	1
1	0	1	1	1	0
1	1	0	1	1	1
1	1	1	0	0	0

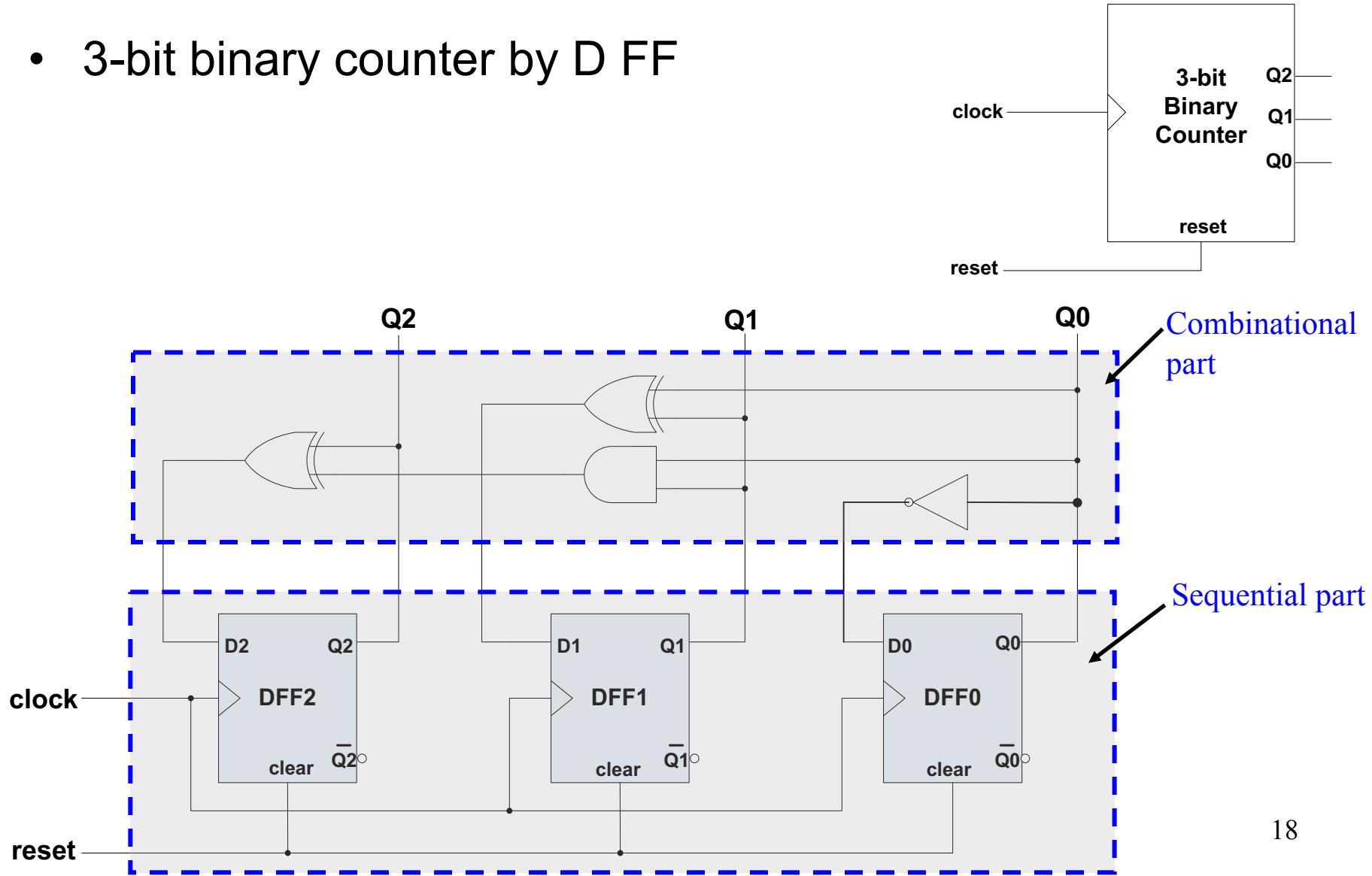
Counter Implemented with D Flip-Flop

- Use D flip flops to hold values: $Q^+ = D$ upon active edge
- Next state equations

Present State			Next State			D flip flop input		
Q2	Q1	Q0	Q2 ⁺	Q1 ⁺	Q0 ⁺	D2	D1	D0
0	0	0	0	0	1	0	0	1
0	0	1	0	1	0	0	1	0
0	1	0	0	1	1	0	1	1
0	1	1	1	0	0	1	0	0
1	0	0	1	0	1	1	0	1
1	0	1	1	1	0	1	1	0
1	1	0	1	1	1	1	1	1
1	1	1	0	0	0	0	0	0

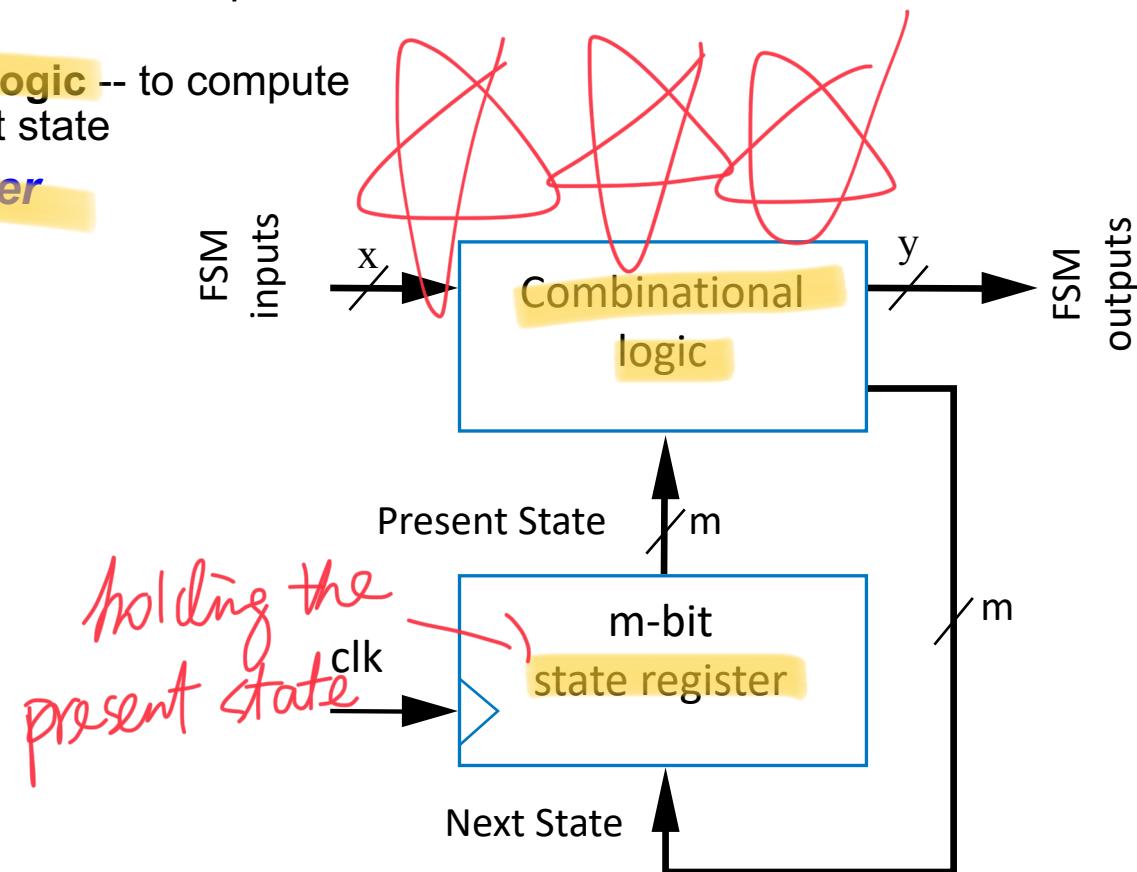
Synchronous Binary Counter with D Flip-Flop

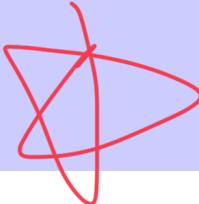
- 3-bit binary counter by D FF



Standard FSM Architecture

- How to design sequential circuit?
 - Design as FSM
 - Use standard architecture
 - **State register** -- to store the present state
 - **Combinational logic** -- to compute outputs, and next state
 - Known as *controller*





FSM (Controller) Design

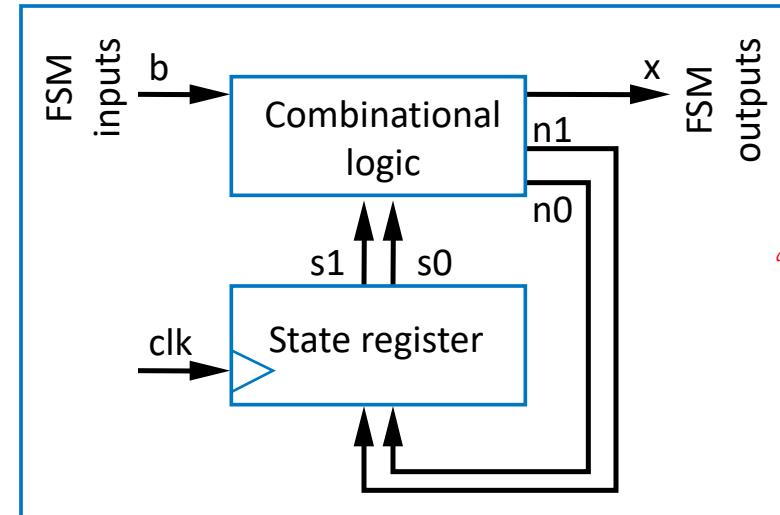
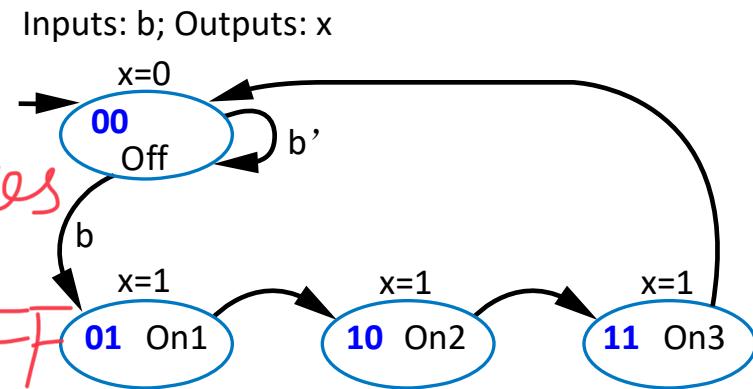
- Five step FSM design process

Step	Description
Step 1 <i>Capture the FSM</i>	Create an FSM that describes the desired behavior of the controller.
Step 2 <i>Create the architecture</i>	Create the standard architecture by using a state register of appropriate width, and combinational logic with inputs being the state register bits and the FSM inputs and outputs being the next state bits and the FSM outputs.
Step 3 <i>Encode the states</i>	Assign a unique binary number to each state. Each binary number representing a state is known as an <i>encoding</i> . Any encoding will do as long as each state has a unique encoding.
Step 4 <i>Create the state table</i>	Create a truth table for the combinational logic such that the logic will generate the correct FSM outputs and next state signals. Ordering the inputs with state bits first makes this truth table describe the state behavior, so the table is a state table.
Step 5 <i>Implement the combinational logic</i>	Implement the combinational logic using any method.

FSM Design Example: Push Button

- Step 1: Capture the FSM
 - Already done
- Step 2: Create architecture
 - 2-bit state register (for 4 states)
 - Input b, output x
 - Present state signals (s_1, s_0)
 - Next state signals (n_1, n_0)
- Step 3: Encode the states
 - Any encoding with unique representation for each state will work

$n \text{ bit} \rightarrow \leq 2^n \text{ states}$



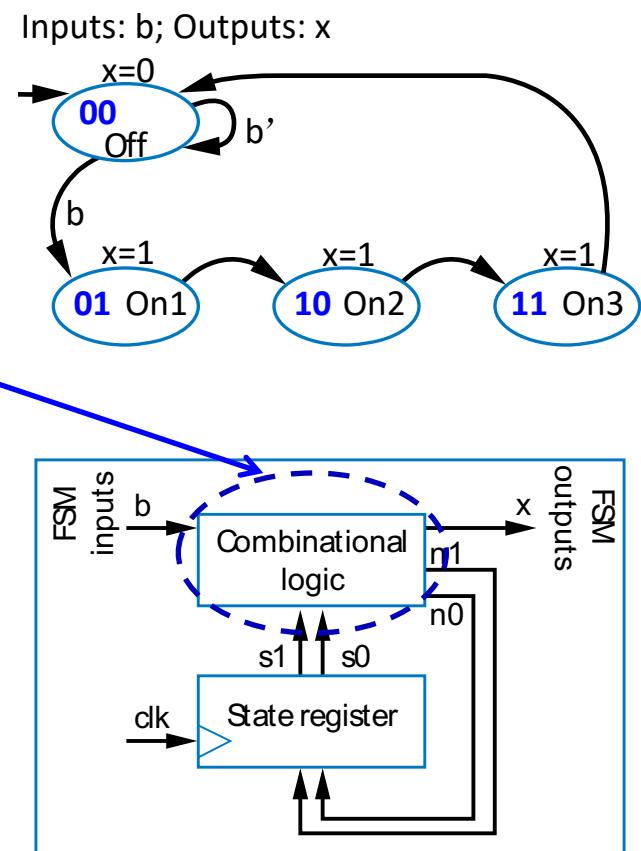
FSM Design Example: Push Button (cont.)

- Step 4: Create state table

just like truth table

Inputs			Outputs		
Present state			x	Next state	
Off	0	0	0	0	0
	0	0	1	0	1
On1	0	1	0	1	1
	0	1	1	1	0
On2	1	0	0	1	1
	1	0	1	1	1
On3	1	1	0	1	0
	1	1	1	1	0

Combinational Logic Inputs Combinational Logic Outputs

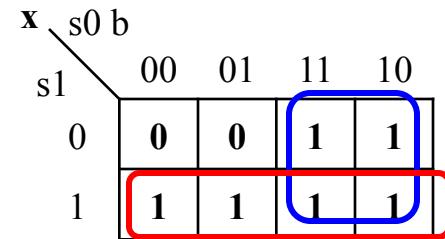


FSM Design Example: Push Button (cont.)

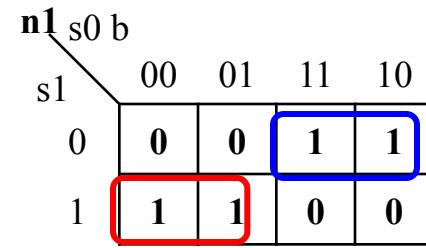
- Step 5: Implement combinational logic

	Inputs			Outputs		
	s1	s0	b	x	n1	n0
<i>Off</i>	0	0	0	0	0	0
	0	0	1	0	0	1
<i>On1</i>	0	1	0	1	1	0
	0	1	1	1	1	0
<i>On2</i>	1	0	0	1	1	1
	1	0	1	1	1	1
<i>On3</i>	1	1	0	1	0	0
	1	1	1	1	0	0

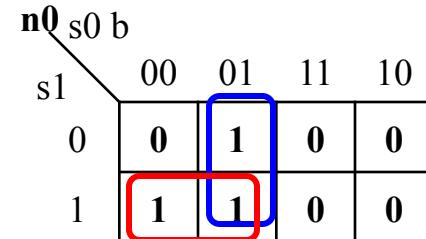
$$x = s_1 + s_0$$



$$n_1 = s_1's_0 + s_1s_0'$$

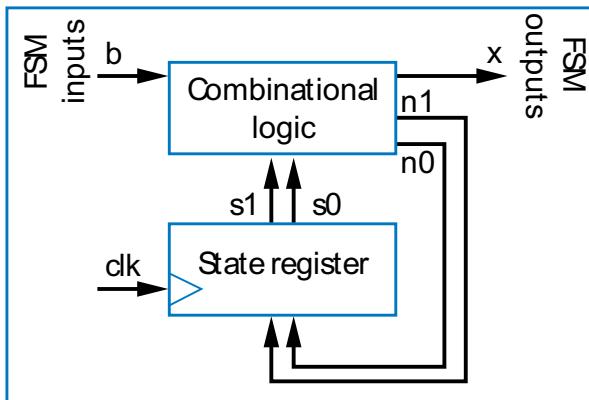


$$n_0 = s_0'b + s_1s_0'$$



FSM Design Example: Push Button (cont.)

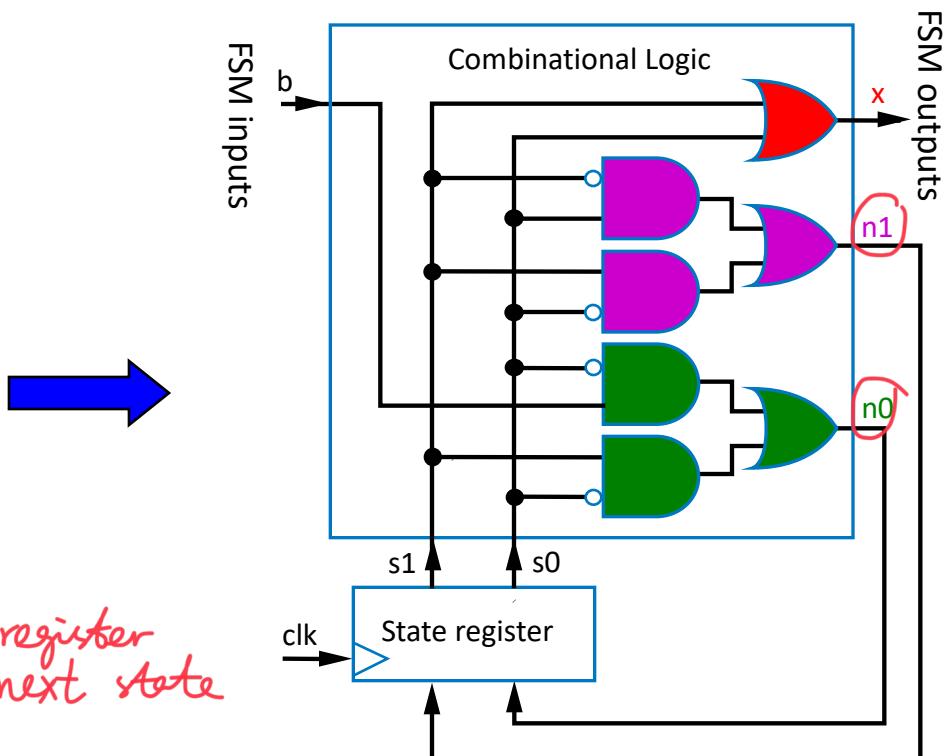
- Step 5: Implement combinational logic (cont)



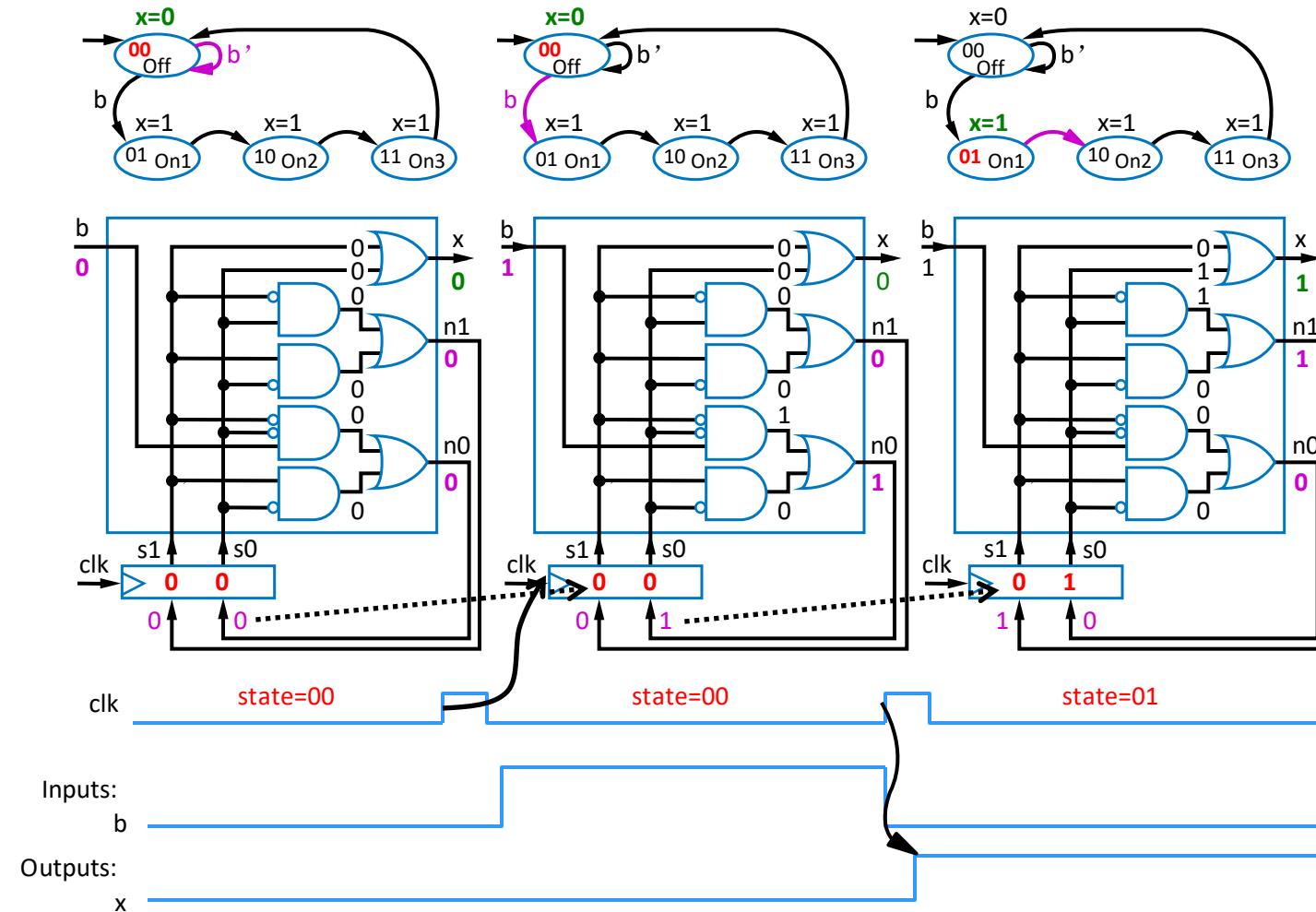
$$x = s_1 + s_0$$

$$\begin{aligned} n_1 &= s_1's_0 + s_1s_0' \\ n_0 &= s_0'b + s_1s_0' \end{aligned}$$

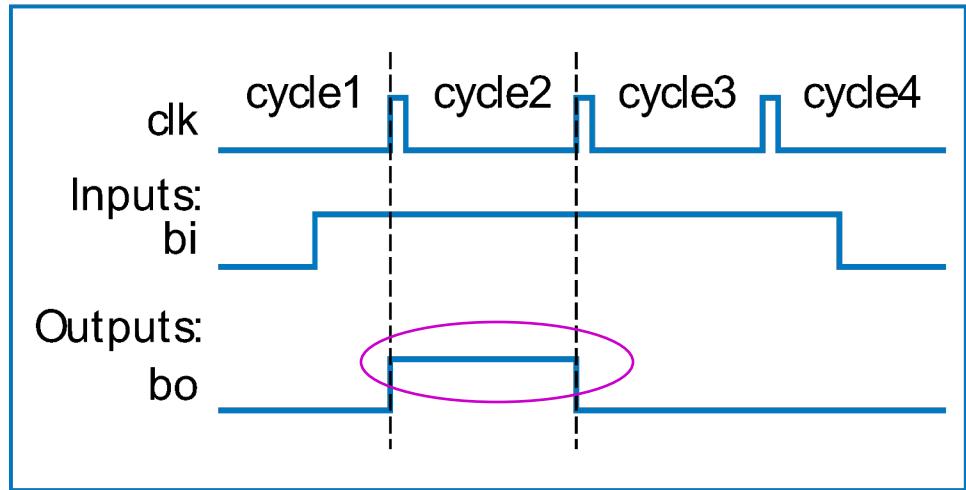
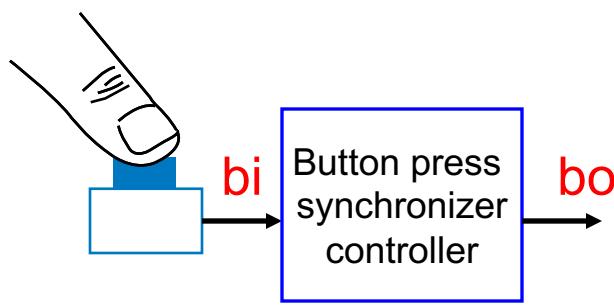
} provide to the register to serve as the next state



Understanding the Controller's Behavior

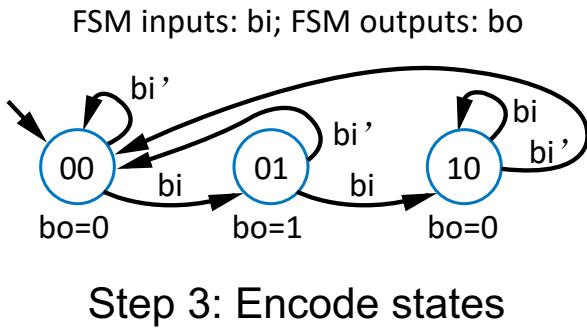
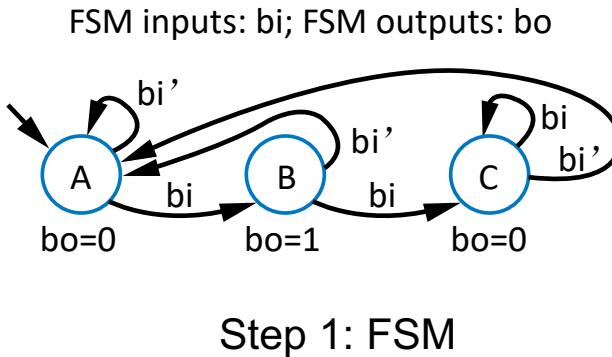


FSM Design Example: Button Press Synchronizer



- Want simple sequential circuit that converts button press to single clock cycle duration, regardless of length of time that button actually pressed
- Producing a signal like 'a' in the secure door example

FSM Design Example: Button Press Synchronizer (cont.)



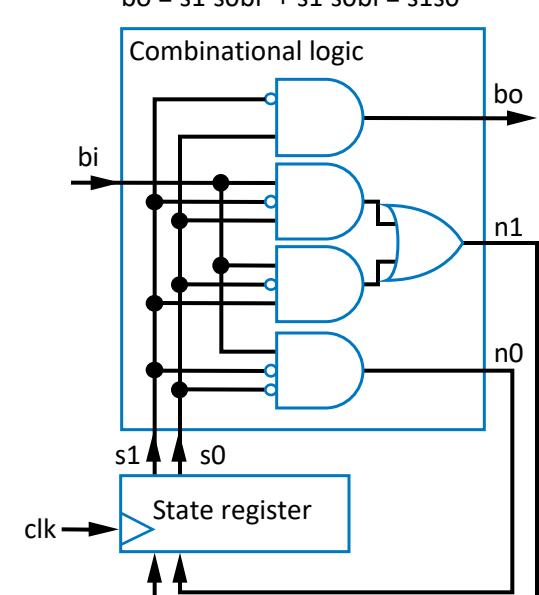
Step 4: State table

Combinational logic

Inputs			Outputs		
s1	s0	bi	n1	n0	bo
0	0	0	0	0	0
0	0	1	0	1	0
0	1	0	0	0	1
0	1	1	1	0	1
1	0	0	0	0	0
1	0	1	1	0	0
1	1	0	0	0	0
1	1	1	0	0	0

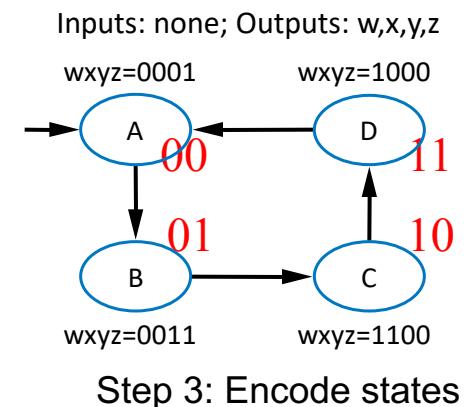
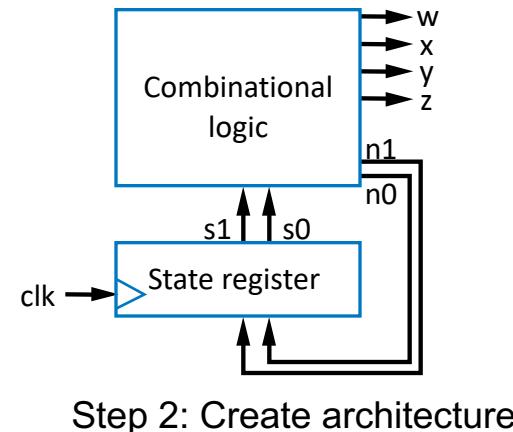
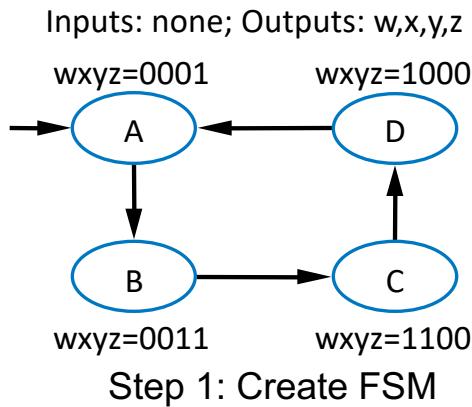
unused

may be 'x'



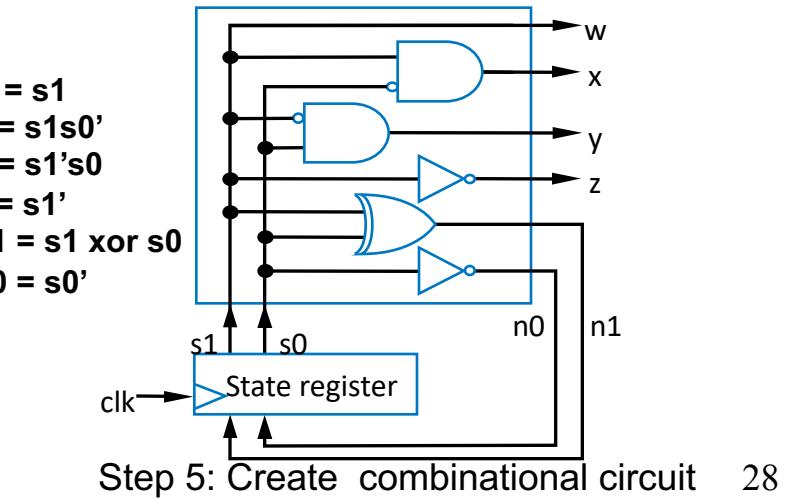
FSM Example: Sequence Generator

- Want generate sequence 0001, 0011, 1100, 1000, (repeat)
 - Each value for one clock cycle

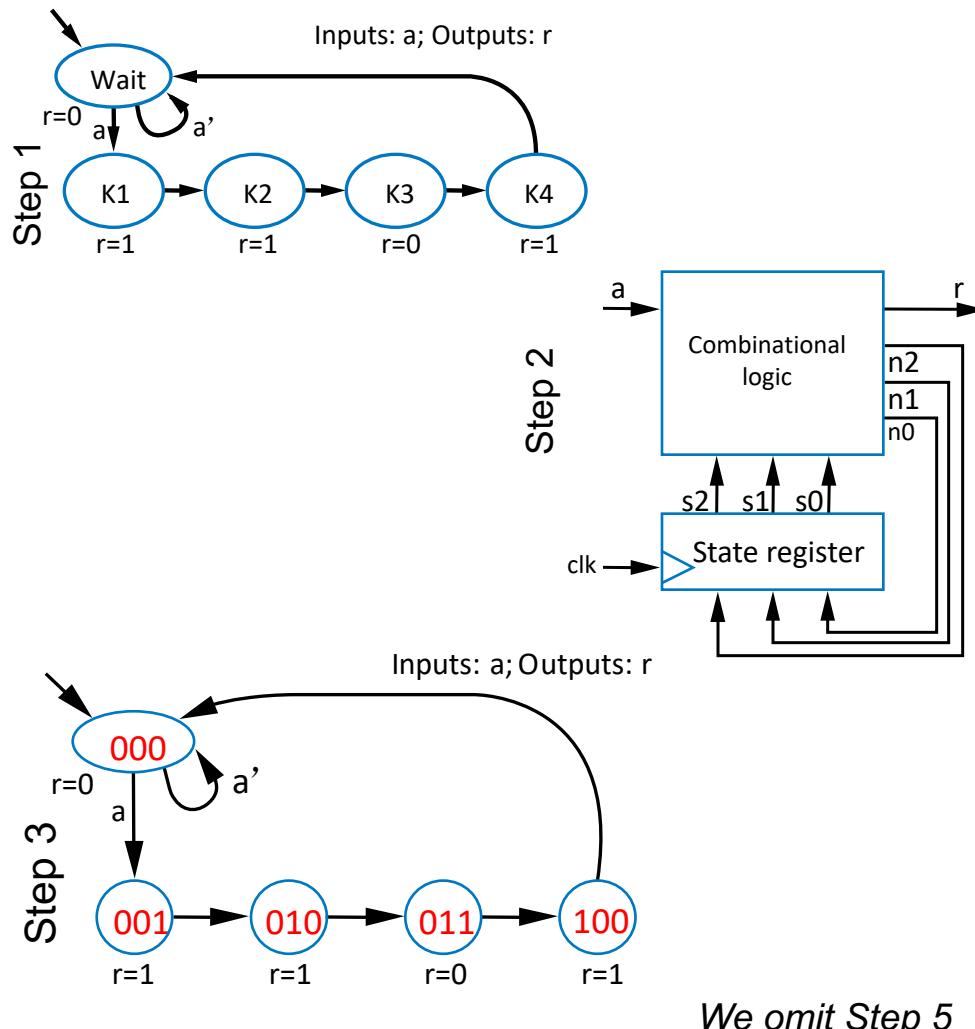


Step 4: Create state table

Inputs		Outputs					
s1	s0	w	x	y	z	n1	n0
A	0	0	0	0	1	0	1
B	0	1	0	0	1	1	0
C	1	0	1	1	0	0	1
D	1	1	1	0	0	0	0



FSM Example: Secure Car Key

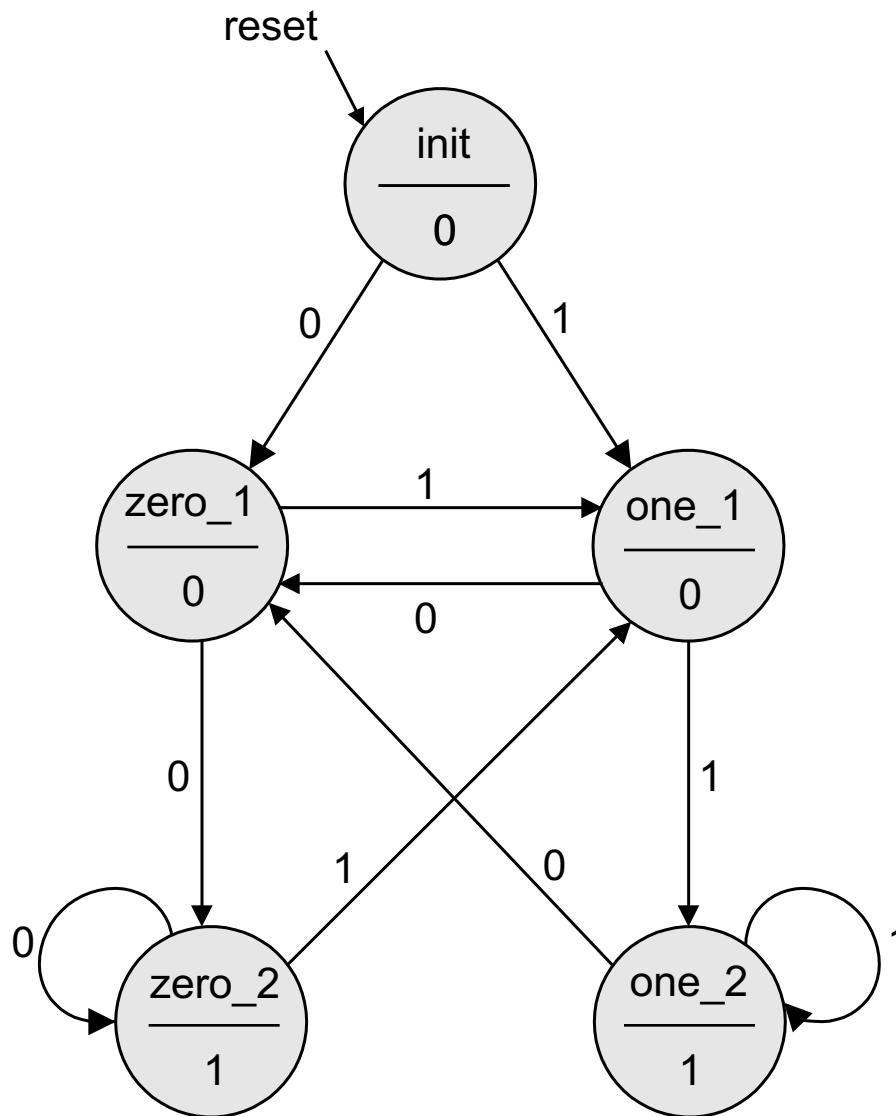


	Inputs				Outputs			
	s_2	s_1	s_0	a	r	n_2	n_1	n_0
<i>Wait</i>	0	0	0	0	0	0	0	0
	0	0	0	1	0	0	0	1
<i>K1</i>	0	0	1	0	1	0	1	0
	0	0	1	1	1	0	1	0
<i>K2</i>	0	1	0	0	1	0	1	1
	0	1	0	1	1	0	1	1
<i>K3</i>	0	1	1	0	0	1	0	0
	0	1	1	1	0	1	0	0
<i>K4</i>	1	0	0	0	1	0	0	0
	1	0	0	1	1	0	0	0
<i>Unused</i>	1	0	1	0	0	0	0	0
	1	0	1	1	0	0	0	0
	1	1	0	0	0	0	0	0
	1	1	0	1	0	0	0	0
	1	1	1	0	0	0	0	0
	1	1	1	1	0	0	0	0

Step 4

may be 'x'

Verilog Modeling of FSM



```

Module example_FSM (clock, reset, in_bit, out_bit);
  input          clock, reset, in_bit;
  output        out_bit;

  reg [2:0]      curr_state, next_state;

  parameter    init      = 3'b000;
  parameter    zero_1   = 3'b001;
  parameter    one_1    = 3'b010;
  parameter    zero_2   = 3'b011;
  parameter    one_2    = 3'b100;

  always @ (posedge clock or posedge reset) ← State register
    if (reset == 1) curr_state <= init;
    else           curr_state <= next_state;

  always @ (curr_state or in_bit) ← Combinational logic
    case (curr_state)
      init: if (in_bit == 0) next_state <= zero_1; else
            if (in_bit == 1) next_state <= one_1; else
              next_state <= init;

```

```

zero_1: if (in_bit == 0) next_state <= zero_2; else
        if (in_bit == 1) next_state <= one_1; else
                        next_state <= init;
zero_2: if (in_bit == 0) next_state <= zero_2; else
        if (in_bit == 1) next_state <= one_1; else
                        next_state <= init;
one_1:  if (in_bit == 0) next_state <= zero_1; else
        if (in_bit == 1) next_state <= one_2; else
                        next_state <= init;
one_2:  if (in_bit == 0) next_state <= zero_1; else
        if (in_bit == 1) next_state <= one_2; else
                        next_state <= init;
default:          next_state <= init;
endcase

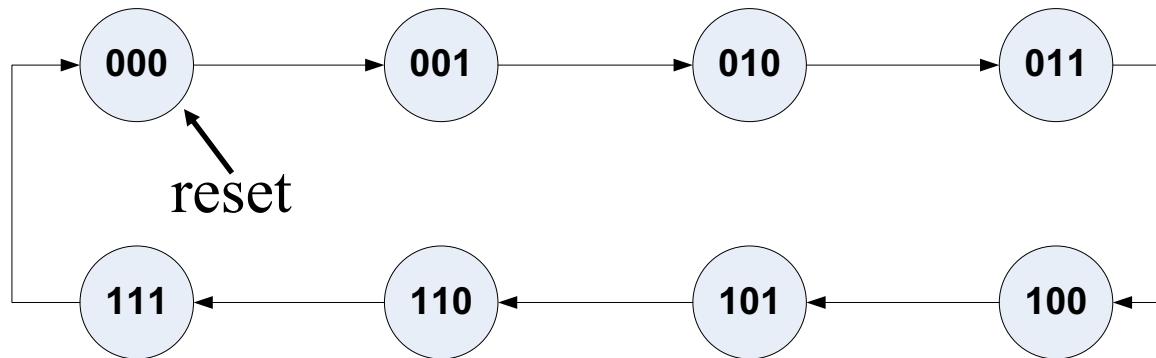
assign out_bit = ((curr_state==zero_2) || (curr_state==one_2))
endmodule

```

Combinational logic for FSM outputs

Revisit: Binary Counter as an FSM

- FSM that counts binary numbers – counter
- An n -bit binary counter can count in binary from 0 up to 2^n-1 and repeat
- An n -bit binary counter consists of n flip-flops
- All the flip-flops are synchronized to the same clock – synchronous counter
- May be implemented by different type of flip-flops
- Example: a 3-bit binary counter can count through this sequence



Implement FSM with T Flip-Flop

- Characteristic table and equation of T-FF

T	Q ⁺
0	Q No Change
1	Q' Complement

$$Q^+ = T \oplus Q$$

- Excitation table of T-FF

Q	Q ⁺		T
0	0	No Change	0
0	1	Toggle	1
1	0	Toggle	1
1	1	No Change	0



Q	Q ⁺		T
X	Q	No Change	0
X	Q'	Toggle	1

Implement FSM with T Flip-Flop

- State Table with T input

Intermediate columns

Present State			Next State			T Input		
Q2	Q1	Q0	Q2 ⁺	Q1 ⁺	Q0 ⁺	T2	T1	T0
0	0	0	0	0	1	0	0	1
0	0	1	0	1	0	0	1	1
0	1	0	0	1	1	0	0	1
0	1	1	1	0	0	1	1	1
1	0	0	1	0	1	0	0	1
1	0	1	1	1	0	0	1	1
1	1	0	1	1	1	0	0	1
1	1	1	0	0	0	1	1	1

Implement FSM with T Flip-Flop

- T input equations in terms of Qs can be found from the state table

		Q1Q0			
		00	01	11	10
T2	Q2	0	0	1	0
	1	0	0	1	0

$$T2 = Q1Q0$$

		Q1Q0			
		00	01	11	10
T1	Q2	0	1	1	0
	1	0	1	1	0

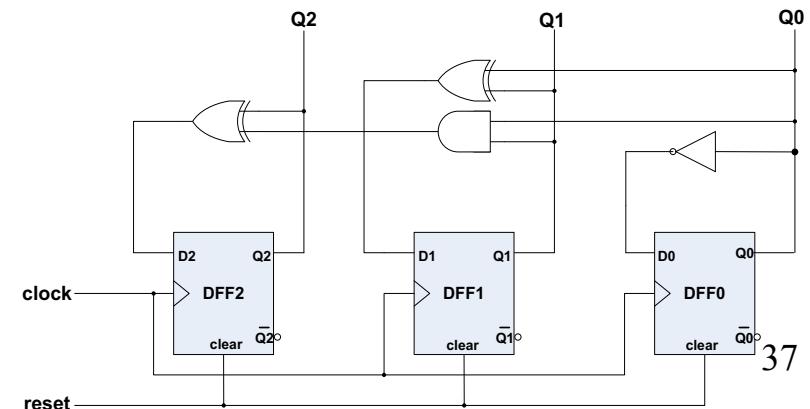
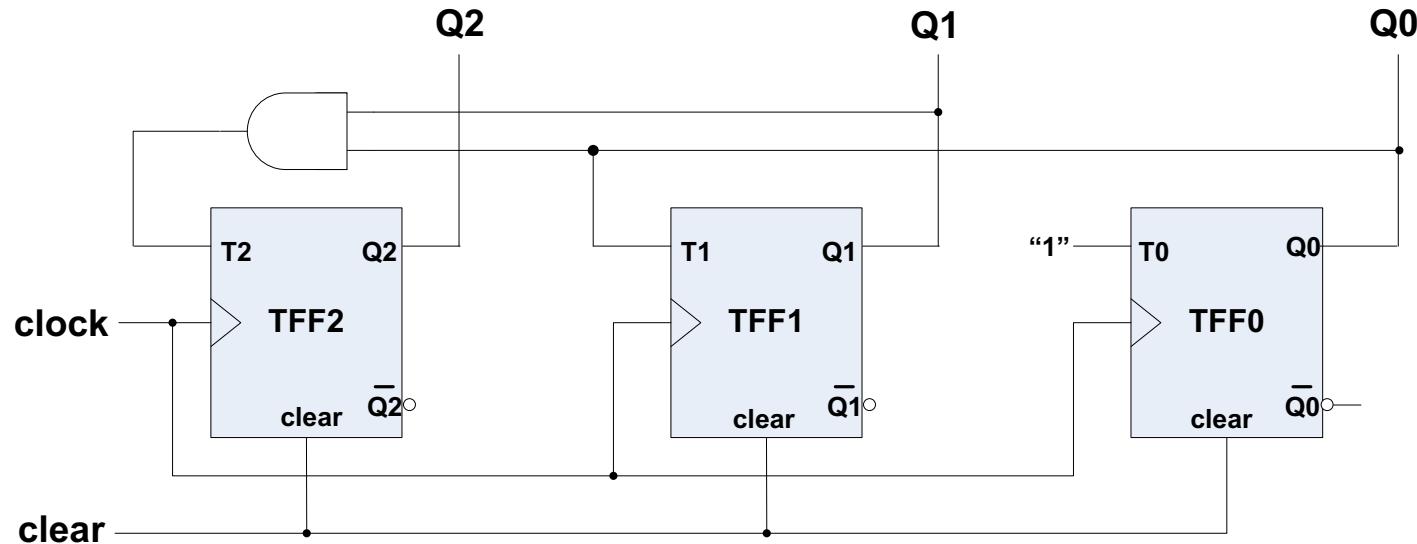
$$T1 = Q0$$

		Q1Q0			
		00	01	11	10
T0	Q2	0	1	1	1
	1	1	1	1	1

$$T0 = 1$$

Implement FSM with T Flip-Flop

- 3-bit binary counter by T FF



Implement FSM with JK Flip-Flop

- Characteristic table and equation of JK-FF

J	K	Q^+	Action
0	0	Q	Hold
0	1	0	Reset
1	0	1	Set
1	1	Q'	Toggle

$$Q^+ = JQ' + K'Q$$

- Excitation table of JK-FF

Q	Q^+	Action	J		K	
			0/0	1/0	0	X
0	0	Reset/Hold	0/0	1/0	0	X
0	1	Set/Toggle	1/1	0/1	1	X
1	0	Reset/Toggle	0/1	1/1	X	1
1	1	Set/Hold	1/0	0/0	X	0

Implement FSM with JK Flip-Flop

- State Table with JK input

Intermediate columns

Present State			Next State			JK Inputs					
Q2	Q1	Q0	Q_2^+	Q_1^+	Q_0^+	J2	K2	J1	K1	J0	K0
0	0	0	0	0	1	0	X	0	X	1	X
0	0	1	0	1	0	0	X	1	X	X	1
0	1	0	0	1	1	0	X	X	0	1	X
0	1	1	1	0	0	1	X	X	1	X	1
1	0	0	1	0	1	X	0	0	X	1	X
1	0	1	1	1	0	X	0	1	X	X	1
1	1	0	1	1	1	X	0	X	0	1	X
1	1	1	0	0	0	X	1	X	1	X	1

Implement FSM with JK Flip-Flop

- J-K Input equations

		Q1Q0				
		00	01	11	10	
J2	Q2	0	0	0	1	0
		1	X	X	X	X

$$J2 = Q1Q0$$

		Q1Q0				
		00	01	11	10	
J1	Q2	0	0	1	X	X
		1	0	1	X	X

$$J1 = Q0$$

		Q1Q0				
		00	01	11	10	
J0	Q2	0	1	X	X	1
		1	1	X	X	1

$$J0 = 1$$

		Q1Q0				
		00	01	11	10	
K2	Q2	0	X	X	X	X
		1	0	0	1	0

$$K2 = Q1Q0 = J2$$

		Q1Q0				
		00	01	11	10	
K1	Q2	0	X	X	1	0
		1	X	X	1	0

$$K1 = Q0 = J1$$

		Q1Q0				
		00	01	11	10	
K0	Q2	0	X	1	1	X
		1	X	1	1	X

$$K0 = 1 = J0$$

Implement FSM with JK Flip-Flop

- Circuit diagram

