ECE 449 - Intelligent Systems Engineering

Lab 3: Neural Networks, Perceptrons and Hyperparameters

Lab date: Thursday, October 17, 2019 -- 2:00 - 4:50 PM

Room: ETLC E5-013

Lab report due: Wednesday, October 30, 2019 -- 3:50 PM

1. Objective:

The objective of this lab is to gain familiarity with the concepts of linear models and to gain a feeling for how changing hyperparameters affects the performance of the model. The exercises in the lab will help bring to light the weaknesses and strengths of linear models and how to work with them.

2. Expectation:

Complete the pre-lab, and hand it in before the lab starts. A formal lab report is required for this lab, which will be the completed version of this notebook. There is a marking guide at the end of the lab manual. If figures are required, label all the axies and provide a legend when appropriate. An abstract, introduction, and conclusion are required as well, for which cells are provided at the end of the notebook. The abstract should be a brief description of the topic, the introduction a description of the goals of the lab, and the conclusion a summary of what you learned, what you found difficult, and your own ideas and observations.

3. Pre lab:

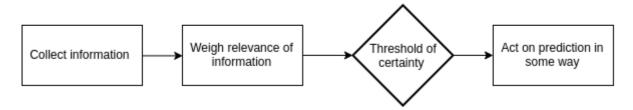
- 1. Read through the code. What kind of models will be used in this lab?
- 2. Explain why the differentiability of an activation function plays an important role in the learning of these neural networks. Why might the linear activation function be a poor choice in some cases?

4. Introduction:

During this lab, you will be performing a mix of 2 common machine learning tasks: regression and classification. Before defining these tasks mathematically, it is important to understand the core process behind the two tasks. Regression is defined as reasoning backwards. In the context of machine learning, regression is about predicting the future based on the past. Classification is defined as the act of arranging things based on their properties. These definitions give insight into how these problems are broken down.

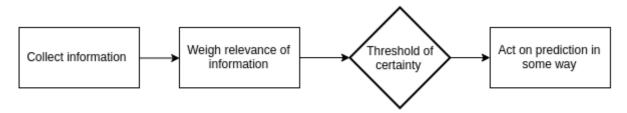
Suppose you, a human being, want to make a prediction. What are the steps that you take: You first collect data on the subject that you want to predict. Then you weigh the relevance of each piece of information that you get, attributing varying levels of importance to each piece of data. Once you have enough relevant data, you become certain of an outcome. Finally, you act on that certainty. This pipeline is shown in the figure below:

Prediction Pipeline:



Now the classification task, one usually begins this with a topic that they want to classify. This is usually accompanied by a list of candidate categories, one of which is the correct category for the topic in question. Since classification relies on properties of the topic, the next step is to list the notable features that may help in the discerning the correct category. Similarly to the prediction, the relevance of each piece of information is then weighed and a decision is made when you have enough data. Once this is done, the guess is compared to reality in order to judge if the classification was correct. This pipeline is shown in the figure below:

Prediction Pipeline:



The mathematical model that we will use in this lab to describe such behaviors are called linear models. The simplest linear model is the perceptron.

A perceptron is a simple type of neural network that uses supervised learning, where the expected values, or targets, are provided to the network in addition to the inputs. The network operates by first calculating the weighted sum of its inputs (and bias). These weights are typically randomly assigned. Then, the sum is processed with an activation function that "squashes" the summed total to a smaller range, such as (0, 1).

The perceptron's way of reasoning is formulated in the same way as a human's. It takes in input data in the form of the x vector. It then weighs the relevance of each input using the mathematical operation of multiplication. Following this, the total sum of all weighted inputs is passed through an activation function, analogous to the moment that you have enough data to confirm an outcome. Then they output a value, y, that is effectively the action that you take based on your prediction.

The math behind the perceptron's operations is described by the following formulae:

$$tot = \sum_{t=1}^n x_i w_i + heta = \sum_{t=0}^n x_i w_i \ o = f_{act}(tot)$$

Training a perceptron involves calculating the error by taking the difference between the targets and the actual outputs. This allows it to determine how to update its weights such that a closer output value to the target is obtained.

Perceptrons are commonly employed to solve two-class classification problems where the classes are linearly separable. However, the applications for this are evidently very limited. Therefore, a more practical extension of the perceptron is the multi-layer perceptron, which adds extra hidden layer(s) between the

inputs and outputs to yield more flexibility in what the MLP can classify.

The most common learning algorithm used is backpropagation (BP). It employs gradient descent in an attempt to minimize the squared error between the network outputs and the targets.

$$E = rac{1}{2} \sum_{k=1}^n \sum_{i=1}^q [t_i(k) - o_i(k)]^2$$

This error value is propagated backwards through the network, and small changes are made to the weights in each layer. Using a gradient descent approach, the weights in the network are updated as follows:

$$\Delta w^{(l)} = -\eta
abla w^{(l)} = -\eta rac{\partial E(k)}{\partial w^{(l)}}$$

where $\eta>0$ is the learning rate. The network is trained using the same data, multiple times in epochs. Typically, this continues until the network has reached a convergence point that is defined by the user through a tolerance value. For the case of this lab, the tolerance value is ignored and training will continue until the specified number of epochs is reached. More details of backpropagation can be found in the lecture notes.

Neural networks have two types of parameters that affect the performance of the network, parameters and hyperparameters. Parameters have to do with the characteristics that the model learns during the training process. Hyperparameters are values that are set before training begins. The parameters of linear models are the weights. The hyperparameters include:

- · Learning algorithm
- · Loss function
- · Learning rate
- · Activation function

Hyperparameter selection is very important in the field of AI in general. The performance of the learning systems that are deployed relies hevily on the selection of hyperparameters and some advances in the field have even been soley due to changes in hyperparametes. More on hyperparameters can be found in the lecture notes and in the literature.

Exercise 1: Perceptrons and their limitations

The objective of this exercise is to show how adding depth to the network makes it learn better. This exercise will involve running the following cells and examining the data. This exercise will showcase the classification task and it will be performed on the Iris dataset. Also, ensure that all files within "Lab 3 Resources" is placed in the same directory as this Jupyter notebook.

Run the following cell to import all the required libraries.

In [4]:

```
%matplotlib inline
                                                # General math operations
import numpy as np
import scipy. io as sio
                                               # Loads .mat variables
                                                 # Data visualization
import matplotlib.pyplot as plt
from sklearn.linear_model import Perceptron
                                                # Perceptron toolbox
from sklearn.neural network import MLPRegressor # MLP toolbox
import seaborn as sns
import pandas as pd
from sklearn. model selection import train test split
from sklearn import datasets
from sklearn.neural_network import MLPClassifier
from sklearn import preprocessing
                                               # Linear models
from sklearn import linear_model
from sklearn. tree import DecisionTreeRegressor
import warnings
warnings. filterwarnings ('ignore')
```

The Iris dataset: This dataset contains data points on three different species of Iris, a type of flower. The dataset has 50 entries for each of the species and has 4 different features:

- 1. Sepal Length
- 2. Sepal Width
- 3. Petal Length
- 4. Petal Width

This dataset has one obvious class that is separate from a cluster of the other two classes, making it a typical exercise in classification for machine learning. The next cell loads the dataset into 2 variables, one for the features and one for the classes.

In [5]:

```
# load the data
iris = datasets.load_iris()
Y = iris.target
X = iris.data

# set up the pandas dataframes
X_df = pd.DataFrame(X, columns = ['Sepal length', 'Sepal width', 'Petal length', 'Petal width'])
Y_df = pd.DataFrame(Y, columns = ['Iris class'])

# this code changes the class labels from numerical values to strings
Y_df = Y_df.replace({
0:'Setosa',
1:'Virginica',
2:'Versicolor'
})

# Joins the two dataframes into a single data frame for ease of use
Z_df = X_df.join(Y_df)
```

Visualizing the data is a important tool for data exploration. Visualizing the data will allow you to intuitively understand obvious relationships that are present in the data, even before you begin to analyse it. The next cell will plot all of the features against each other.

In [6]:

Sepal length

```
# show the data using seaborn
sns. set(style='dark', palette= 'deep')
pair = sns. pairplot(Z_df, hue = 'Iris class')
plt. show()
     8
  Sepal length
     6
   4.5
   4.0
Sepal width
   3.5
   3.0
   2.5
                                                                                                                  Setosa
                                                                                                                  Virginica
                                                                                                                  Versicolor
    6
  Petal length
   2.5
   2.0
Petal width
   1.5
   1.0
   0.5
   0.0
```

This type of plot is called a pairplot. It plots each feature against all other features including itself; this is done for all four features. This results in 2 different types of plots being present in the plot, scatter and histogram.

Petal length

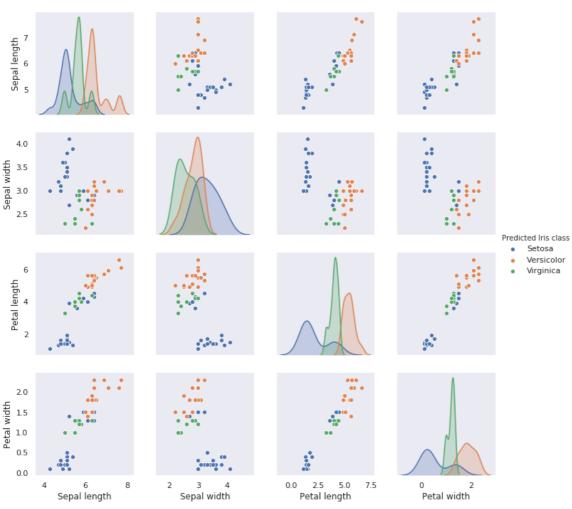
Petal width

The following cell will train a perceptron on the features and labels and display the result on the test set in a pairplot.

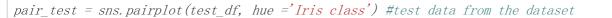
Sepal width

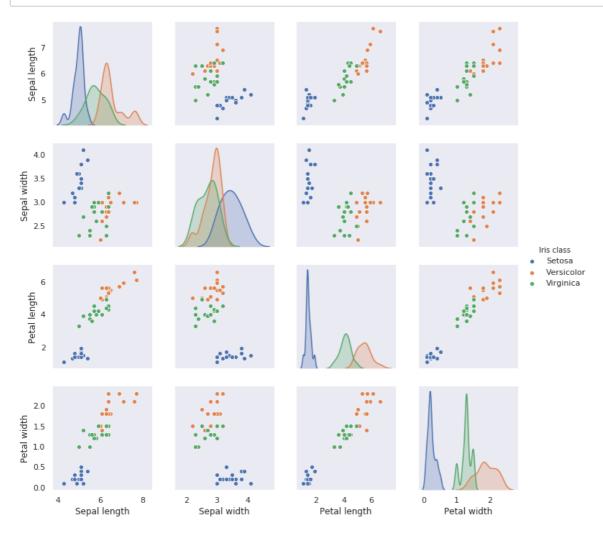
In [7]:

```
RANDOM SEED = 6
xTrain, xTest, yTrain, yTest = train_test_split(X_df, Y_df, test_size =0.3, |
                                                random state=RANDOM SEED)
#plot the testing data
test_df = xTest. join(yTest)
# print(test_df. head)
# perceptron training
percep = Perceptron(max_iter = 1000)
percep. fit (xTrain, yTrain)
prediction = percep. predict(xTest)
# print(prediction)
# display the classifiers performance
prediction_df = pd. DataFrame (prediction, columns=['Predicted Iris class'], index = test_df.index
# print (prediction df. head)
prediction_df_index_df = prediction_df. join(xTest)
# print(prediction_df_index_df.head)
pair = sns. pairplot(prediction_df_index_df, hue = 'Predicted Iris class')
#pair_test = sns. pairplot(test_df, hue ='Iris class')
plt. show()
```



In [8]:





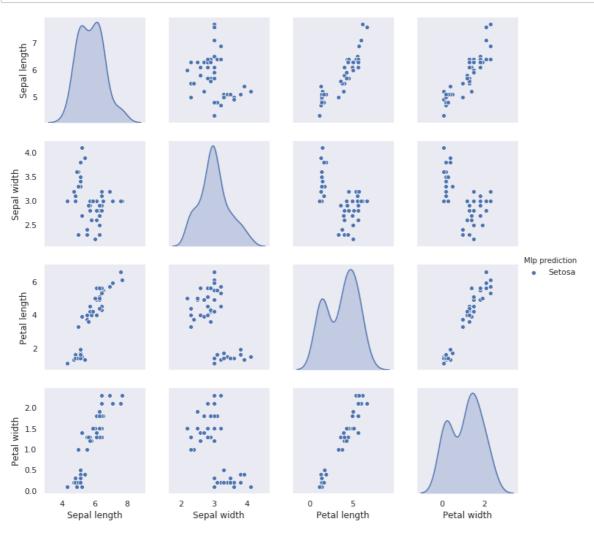
Question 1:

Comment on the performance of the perceptron, how well does it handle the task?

Visualizing the orginal data, we can tell the orange dots are close to the green dots while blue dots are isolated. The histogram also shows that green and orange are closely overlap and blue is separate. We expect computer will have hard time distinguishing blue and green near boundary(i.e. recognize green as blue when dots are very close to each other). When we split the data, for example, 70% of traing data and 30% of test data, using one neuron can do an "OK" job. After traing with training cace, it recognize all the blue dots and oranges which are isolated from the centre in the test case. However, with only one neuron which is not very powerful, the computer recognize some green dots as blue. These dots are all locate in the centre where dots are overlapping with each other. This is what we expect, and if we want to improve our computer, we can use more neurons and more layers.

The next cell will retrain the perceptron but with different parameters. This MLP consists of 2 hidden layers: one with 8 neurons and a second one with 3

In [9]:



Question 2:

Answer the following questions:

- How does the MIp compare to the perceptron in the classification task?
- · Did it do well
- · Was it able to classify the three classes?
- · What happens when you run it again?
- · Can you offer a explanation for what happened?

Fill the box below with your answer:

Mlp does an awesome job compare to the perceptron. The scatter and histogram plot is exactly the same as test case. With two hidden layer: one with 8 neurons and a second one with 3, 100000 time of traing, the computer is fully able to get good output. If we run again, there is a chance getter the plot with only blue color. It is because how we initialize and randomize the initial weight. Sometims the computer find the local minima of one type, and it interprete as one class. There is chance getter the other two color or two color mixing.

Exercise 2: Getting your hands dirty with regression

NOTE: The code in this exercise is computationally intensive and may require up to 5 minutes to finish running.

In order to improve the energy management of monitoring stations, a team of climatologists would like to implement a more robust strategy of predicting the solar energy available for the next day, based on the current day's atmospheric pressure. They plan to test this with a station situated in Moxee, and are designing a multi-layer perceptron that will be trained with the previous year's worth of Moxee data. They have access to the following values:

- Inputs: Pressure values for each hour, along with the absolute differences between them
- Targets: Recorded solar energy for the day after

The individual who was in charge of this project before had created a traditional machine learning approach to predict the solar energy availability of the next day. The individual recently retired and you have been brought on to the team to try to implement a more accurate system. You find some code that was left over that uses a MLP. The MLP is initially formed using one hidden layer of 50 neurons, a logistic sigmoid activation function, and a total of 500 iterations. Once it is trained, the MLP is used to predict the results of both the training cases and new test cases. As a measure of accuracy, the root mean square error (RMSE) is displayed after inputting data to the MLP.

First, read through the code to understand what results it produces, and then run the script.

Question 1:

Your objective is to play with the parameters of the regressor to see if you can beat the decision tree. There are parameters that you can change to try to beat it. You can change:

- Size of the Hidden Layers: between 1 and 50
- Activation Function:
 - Identity
 - Logistic
 - tanh
 - relu
- Number of Iterations, to different values (both lower and higher): Between 1 and 1000

Comment on how this affects the results. Include plots of your final results (using any one of your values for the parameters). Describe some of the tradeoffs associated with both lowering and raising the number of iterations. In order to determine the accuracy of the methods, you will be using RMSE

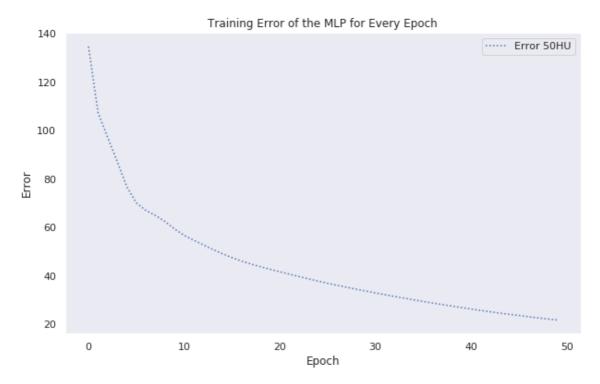
$$RMSE = \sqrt{rac{\sum{(Approximated - observed)}}{n}}$$

In [28]:

```
# Obtain training data
moxeeData = sio. loadmat('moxeetrainingdata.mat')  # Load variables from the Moxee dataset
trainingInputs = moxeeData['pressureData']  # Pressure values and differences for every
hour in a year
trainingTargets = moxeeData['dataEstimate']  # Estimate of incoming solar energy based on
observed data
```

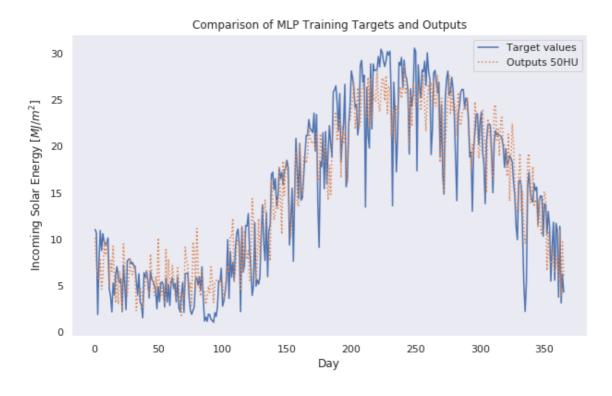
```
# Preprocess the training inputs and targets
iScaler = preprocessing. StandardScaler() # Scaler that removes the mean and scales to unit va
scaledTrainingInputs = iScaler.fit transform(trainingInputs) # Fit and scale the training inpu
tScaler = preprocessing. StandardScaler()
scaledTrainingTargets = tScaler.fit_transform(trainingTargets)
# Create the multilayer perceptron.
# This is where you will be modifying the regressor to try to beat the decision tree
mlp = MLPRegressor(
   hidden_layer_sizes = (20,),
                                # One hidden laver with 50 neurons
   activation = 'tanh', # Logistic sigmoid activation function
   solver = 'sgd',
                                 # Gradient descent
   learning_rate_init = 0.01 ,# Initial learning rate
dt reg = DecisionTreeRegressor(criterion='mse', max depth = 10)
dt reg. fit(scaledTrainingInputs, scaledTrainingTargets)
### MODIFY THE VALUE BELOW ###
noIterations = 50 # Number of iterations (epochs) for which the MLP trains
### MODIFY THE VALUE ABOVE ###
trainingError = np. zeros (noIterations) # Initialize array to hold training error values
# Train the MLP for the specified number of iterations
for i in range (noIterations):
   mlp.partial_fit(scaledTrainingInputs, np.ravel(scaledTrainingTargets)) # Partial fit is use
d to obtain the output values after each epoch
   currentOutputs = mlp.predict(scaledTrainingInputs) # Obtain the outputs for the current MLP
using the training inputs
   trainingError[i] = np. sum((scaledTrainingTargets.T - currentOutputs) ** 2) / 2 # Keep track
of the error throughout the number of epochs
# Plot the error curve
plt. figure (figsize=(10, 6))
ErrorHandle, = plt. plot (range (no Iterations), training Error, label = 'Error 50HU', linestyle =
'dotted')
plt. xlabel ('Epoch')
plt. ylabel ('Error')
plt. title('Training Error of the MLP for Every Epoch')
plt.legend(handles = [ErrorHandle])
plt. show()
# Obtain test data
testdataset = sio. loadmat('moxeetestdata.mat')
testInputs = testdataset['testInputs']
testTargets = testdataset['testTargets']
scaledTestInputs = iScaler.transform(testInputs) # Scale the test inputs
# Predict incoming solar energy from the training data and the test cases
scaledTrainingOutputs = mlp. predict(scaledTrainingInputs)
scaledTestOutputs = mlp. predict(scaledTestInputs)
scaledTreeTrainingOutputs = dt reg.predict(scaledTrainingInputs)
scaledTreeTestOutputs = dt_reg. predict(scaledTestInputs)
```

```
# Transform the outputs back to the original values
trainingOutputs = tScaler.inverse transform(scaledTrainingOutputs)
testOutputs = tScaler.inverse transform(scaledTestOutputs)
## DT outputs
treeTrainingOutputs = tScaler.inverse_transform(scaledTreeTrainingOutputs) # -- transform the tr
ee back to real data
treeTestingOutputs = tScaler.inverse_transform(scaledTreeTestOutputs)
# Calculate and display training and test root mean square error (RMSE)
trainingRMSE = np. sqrt(np. sum((trainingOutputs - trainingTargets[:, 0]) ** 2) / len(trainingOutputs
uts)) / 1000000 # Divide by 1e6 for MJ/m^2
testRMSE = np. sqrt(np. sum((testOutputs - testTargets[:, 0]) ** 2) / len(testOutputs)) / 1000000
## need to add this for the decision tree
trainingTreeRMSE = np. sqrt(np. sum((treeTrainingOutputs - trainingTargets[:, 0]) ** 2) / len(trai
ningOutputs)) / 1000000
testTreeRMSE = np. sqrt(np. sum((treeTestingOutputs - testTargets[:, 0]) ** 2) / 1en(testOutputs))
/ 1000000
print ("Training RMSE:", training RMSE, "MJ/m^2")
print("Test RMSE:", testRMSE, "M.J/m^2")
print ("Decision Tree training RMSE:", training TreeRMSE, 'MJ/m^2')
print("Decision Tree Test RMSE:", testTreeRMSE, 'MJ/m^2')
day = np. array(range(1, len(testTargets) + 1))
# Plot training targets vs. training outputs
plt. figure (figsize=(10, 6))
trainingTargetHandle , = plt. plot (day, trainingTargets / 1000000, label = 'Target values')
trainingOutputHandle , = plt. plot(day, trainingOutputs / 1000000, label = 'Outputs 50HU', linest
yle = 'dotted')
plt. xlabel ('Day')
plt. ylabel (r'Incoming Solar Energy [$M] / m^2$]')
plt. title ('Comparison of MLP Training Targets and Outputs')
plt.legend(handles = [trainingTargetHandle, trainingOutputHandle])
plt. show()
# Plot test targets vs. test outputs -- student
plt. figure (figsize=(10, 6))
testTargetHandle , = plt.plot(day, testTargets / 1000000, label = 'Target values')
testOutputHandle, = plt.plot(day, testOutputs / 1000000, label = 'Outputs 50HU', linestyle = 'd
otted')
plt. xlabel('Day')
plt.ylabel(r'Incoming Solar Energy [$MJ / m^2$]')
plt. title('Comparison of MLP Test Targets and Outputs')
plt. legend(handles = [testTargetHandle, testOutputHandle])
plt. show()
s. test outputs
plt. figure (figsize=(10, 6))
testTreeTargetHandle, = plt.plot(day, testTargets / 1000000, label = 'Target values')
testTreeOutputHandle, = plt.plot(day, treeTestingOutputs / 1000000, label = 'Decision tree', lin
estyle = 'dotted')
plt. xlabel('Day')
plt.ylabel(r'Incoming Solar Energy [$MJ / m^2$]')
plt. title ('Comparison of Decision Tree Test Targets and Outputs')
plt.legend(handles = [testTreeTargetHandle, testTreeOutputHandle])
plt. show()
```

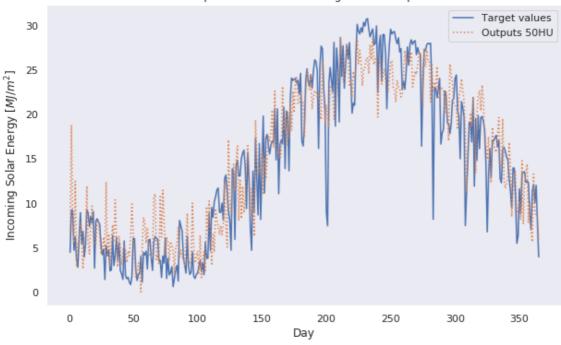


Training RMSE: 3.0583033199674907 MJ/m^2 Test RMSE: 3.644194128625708 MJ/m^2

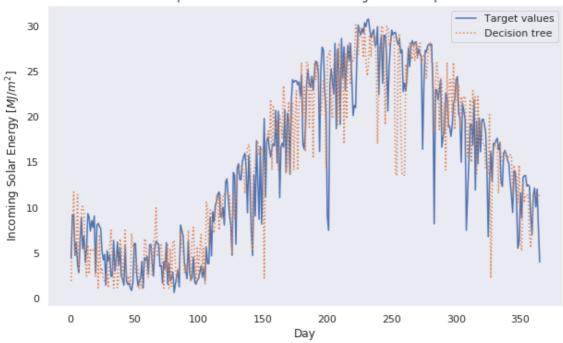
Decision Tree training RMSE: 0.18092649714730089 MJ/m^2 Decision Tree Test RMSE: 4.317150431861796 MJ/m^2











Fill the box below with your answer for question 1:

My first appraoch is try to use as many hidden layer as possible. With 50 hidden layer, 98 iteration and 'relu'function, I beat the decision tree(Test RMSE: 3.712982975809769 MJ/m^2 < Decision Tree Test RMSE: 4.329127514804251 MJ/m^2). The reason why I can't beat it in training case is because decision tree is very good at dealing with training data but having bad time with test data. Increasing number of iteration will sacrifice the time. Larger iteration require the program to run longer. With 30 iteration, the regression method can already

beat decision tree. When I set to 1000 times of iteration, the program run significant longer but the result is similar to only 30 iteration. Therefore, there is no need to use very large iteration. The 'tanh' function has overall best performance, the best result I get is $3.644 \, \text{MJ/m}^2 < 4.317 \, \text{MJ/m}^2$.

Repeat the same process but against this SVM:

During a coffee break, you get talking to one of your friends from a different department. He mentioned that at one point there was an intern that was also tasked with predicting the solar energy and they tried a Support Vector machine.

When you tell your superiors, they suggest that you try to beat this interns work as well since it seems to work better than the Decision tree that your predecessor left.

Question 2

Your objective again is to play with the parameters of the regressor to see if you can beat the Support Vector Machine. There are parameters that you can change to try to beat it. You can change:

- Size of the Hidden Layers: between 1 and 50
- · Activation Function:
 - Identity
 - Logistic
 - tanh
 - relu
- Number of Iterations, to different values (both lower and higher): Between 1 and 1000

Comment on how this affects the results. Include plots of your final results (using any one of your values for the parameters). Describe some of the tradeoffs associated with both lowering and raising the number of iterations.

In order to determine the accuracy of the methods, you will be using the RMSE again.

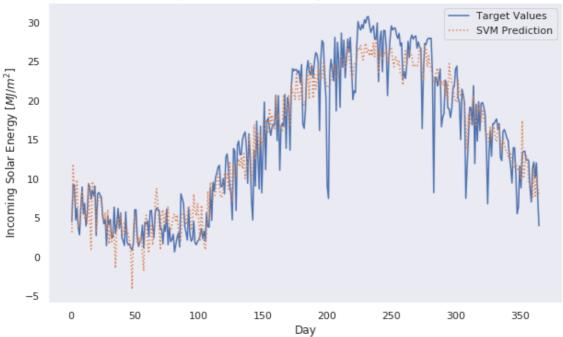
$$RMSE = \sqrt{rac{\sum{(Approximated - observed)}}{n}}$$

</0/>

In [52]:

```
#INITIALIZE
from sklearn.svm import LinearSVR
svm c1f = LinearSVR(C=0.6, loss='squared epsilon insensitive')
svm clf.fit(scaledTrainingInputs, np.ravel(scaledTrainingTargets))
# PREDICT the training outputs and the test outputs
scaledTrainingOutputs = svm clf.predict(scaledTrainingInputs)
scaledTestOutputs = svm_clf.predict(scaledTestInputs)
trainingOutputs = tScaler.inverse_transform(scaledTrainingOutputs)
testOutputs = tScaler.inverse transform(scaledTestOutputs)
 #Calculate and display training and test root mean square error (RMSE)
trainingsvmRMSE = np. sqrt(np. sum((trainingOutputs - trainingTargets[:, 0]) ** 2) / len(trainingO
utputs)) / 1000000 # Divide by 1e6 for MJ/m^2
testsvmRMSE = np. sqrt(np. sum((testOutputs - testTargets[:, 0]) ** 2) / 1en(testOutputs)) / 10000
#### PLOTTING
plt.rcParams["figure.figsize"] = (10, 6)
day = np. array(range(1, len(testTargets) + 1))
testTargetHandle, = plt.plot(day, testTargets / 1000000, label = 'Target Values')
testsvmOutputHandle, = plt.plot(day, testOutputs / 1000000, label = 'SVM Prediction', linestyle
= 'dotted')
plt. xlabel('Day')
plt. ylabel (r'Incoming Solar Energy [$M] / m^2$]')
plt. title ('Comparison of Prediction Targets and SVM Predictions')
plt.legend(handles = [testTargetHandle, testsvmOutputHandle])
plt. show()
print("Support Vector Machine RMSE values and Plots")
print("Training RMSE:", trainingsvmRMSE, "MJ/m^2")
print("Test RMSE:", testsvmRMSE, "MJ/m^2")
```

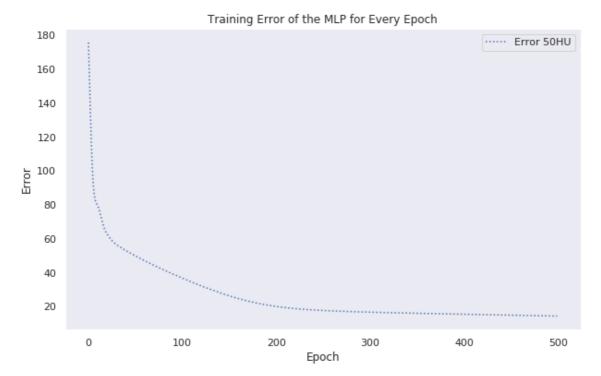
Comparison of Prediction Targets and SVM Predictions



Support Vector Machine RMSE values and Plots Training RMSE: 2.9838282802167466 MJ/m^2 Test RMSE: 3.0074990320858284 MJ/m^2

In [55]:

```
# Modify this neural network
mlp = MLPRegressor(
   hidden layer sizes = (50,),
                                 # One hidden layer with 50 neurons
    activation = 'logistic',
                                 # Logistic sigmoid activation function
    solver = 'sgd',
                                   # Gradient descent
    learning_rate_init = 0.01 ,# Initial learning rate
dt reg = DecisionTreeRegressor(criterion='mse', max depth = 10)
dt reg. fit(scaledTrainingInputs, scaledTrainingTargets)
### MODIFY THE VALUE BELOW ###
noIterations = 500 # Number of iterations (epochs) for which the MLP trains
### MODIFY THE VALUE ABOVE ###
trainingError = np. zeros (noIterations) # Initialize array to hold training error values
# Train the MLP for the specified number of iterations
for i in range(noIterations):
   mlp.partial fit(scaledTrainingInputs, np.ravel(scaledTrainingTargets)) # Partial fit is use
d to obtain the output values after each epoch
    currentOutputs = mlp.predict(scaledTrainingInputs) # Obtain the outputs for the current MLP
using the training inputs
    trainingError[i] = np. sum((scaledTrainingTargets. T - currentOutputs) ** 2) / 2 # Keep track
of the error throughout the number of epochs
scaledTrainingOutputs = mlp. predict(scaledTrainingInputs)
scaledTestOutputs = mlp. predict(scaledTestInputs)
#Training output conversion
trainingOutputs = tScaler.inverse_transform(scaledTrainingOutputs)
testOutputs = tScaler.inverse transform(scaledTestOutputs)
#RMSE calculation
trainingRMSE = np. sqrt(np. sum((trainingOutputs - trainingTargets[:, 0]) ** 2) / len(trainingOutp
uts)) / 1000000 # Divide by 1e6 for MJ/m^2
testRMSE = np. sqrt(np. sum((testOutputs - testTargets[:, 0]) ** 2) / len(testOutputs)) / 1000000
# Plot the error curve
plt. figure (figsize=(10, 6))
ErrorHandle, = plt. plot (range (noIterations), trainingError, label = 'Error 50HU', linestyle =
'dotted')
plt. xlabel ('Epoch')
plt. ylabel ('Error')
plt. title ('Training Error of the MLP for Every Epoch')
plt.legend(handles = [ErrorHandle])
plt. show()
print("MLP Training and test RMSE values:")
print("Training RMSE: ", trainingRMSE)
print("Test RMSE: ", testRMSE)
```



MLP Training and test RMSE values: Training RMSE: 2.490246812267675 Test RMSE: 2.940532605523648

Fill the box below with your answer for question 2:

The first time I beat SVM is using 'relu' function, 50 hidden layer and 1000 iteration. I get MLP Training RMSE: 0.3669547074921677 < SVM Training RMSE: 2.9713064871793726 MJ/m^2. After a lot of attempts, I use 'logistic' function, 50 hidden layer,500 iteration beat the SVM. The result is: MLP Training RMSE: 2.4886829322742723,mlp Test RMSE: 2.9836082497903815 < SVM Training RMSE: 2.9838282802167466 MJ/m^2 SVM Test RMSE: 3.0074990320858284 MJ/m^2. My conclusion is increasing iteration doesn't significantly improve the performance. Using right function and increase hidden layer is the key to get best performance.

Abstract

In this lab, I perform two machine learning task: regression and classification. Regression is good at predicting the future based on the past. Classification is defined as the act of arranging things based on their properties. Classification is used to identify three different species of Iris in 4 different feature. After doing the training, the result shows that MLP with 2 hidden layer(8 neurons in first layer and 3 neurons in second) did a much better job thant using perceptron which only have 1 neuron. Regression method is used to predict solar energy available for the next day base on current day's atmospheric pressure. The machine learning strategy is compared with Decision tree method and SVM. Since Decision tree is good at handle training data, the regression method is unable to beat it in training set. However, regression can beat decision tree easily in test set. SVM is another powerful machine learning method, it has good performance in both training and test set. After so many attempts with different parameters, regression barely beat the SVM. My conclusion is that there is no evidence showing which method is better.

Introduction

The objective of this lab is to gain familiarity with the concepts of linear models and to gain a feeling for how changing hyperparameters affects the performance of the model. During this lab, I performing a mix of 2 common machine learning tasks: regression and classification. Regression is defined as reasoning backwards. In the context of machine learning, regression is about predicting the future based on the past. Classification is defined as the act of arranging things based on their properties. In this lab, regression is used to predict future solar energy level and classification is used to identify different species of Iris.

Conclusion

Different machine learning technique is used to handle different task. Classification is good at arranging things based on their properties. The perceptron with only one neuron is not very powerful as it can not differentiate all the Iris. When we use MLP with more hidden layer and neurons, it is more effective than perceptron. In our task, it is fully able to recognize all the Iris. The MLP has a chance to recognize the three different Iris as one kind. It is because how we initialize and randomize the initial weight. Sometims the computer find the local minima of one type, and it interpretes as one class. There is chance getter the other two color or two color mixing.

Regression is used to compare with Decision tree and SVM. With 50 hidden layer, 98 iteration and 'relu'function, I beat the decision tree(Test RMSE: 3.712982975809769 MJ/m^2 < Decision Tree Test RMSE: 4.329127514804251 MJ/m^2). In the case of SVM, I use 'logistic' function, 50 hidden layer, 500 iteration beat the SVM. The result is: MLP Training RMSE: 2.4886829322742723, mlp Test RMSE: 2.9836082497903815 < SVM Training RMSE: 2.9838282802167466 MJ/m^2 SVM Test RMSE: 3.0074990320858284 MJ/m^2. My conclusion is increasing iteration doesn't significantly improve the performance. Using right function and increase hidden layer is the key to get best performance.

Lab 3 Marking Guide

Exercise	\mathbf{Item}	Total Marks	Earned Marks
	Pre-lab	3	
	Abstract	1	
	Introduction	1	
	Conclusion	2	
1	Classification	20	
2	Regression	20	
	TOTAL	47	