



BABD

Masters in Business Analytics and Big Data

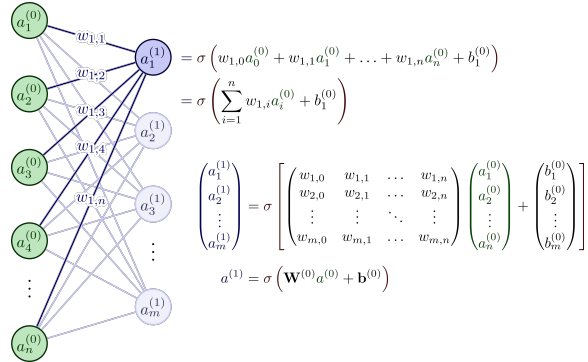
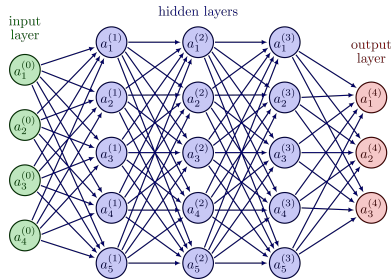
Introduction to NN Construction

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Contents

- ▶ Fast Forward
- ▶ Convolutional NN
- ▶ RNN - Long Short Term Memory networks (LSTM)

Fast Forward



Convolutional Neural Neural

Filters - Convolutional Layer

$$\begin{pmatrix}
 0 & 1 & 1 & 1 & 0 & 0 & 0 \\
 0 & 0 & 1 & 1 & 1 & 0 & 0 \\
 0 & 0 & 0 & 1 & 1 & 1 & 0 \\
 0 & 0 & 0 & 1 & 1 & 0 & 0 \\
 0 & 0 & 1 & 1 & 0 & 0 & 0 \\
 0 & 1 & 1 & 0 & 0 & 0 & 0 \\
 1 & 1 & 0 & 0 & 0 & 0 & 0
 \end{pmatrix}
 \begin{matrix}
 \times 1 \times 0 \times 1 \\
 \times 0 \times 1 \times 0 \\
 \times 0 \times 1 \times 0 \\
 \times 1 \times 0 \times 1
 \end{matrix}
 *
 \begin{pmatrix}
 1 & 0 & 1 \\
 0 & 1 & 0 \\
 1 & 0 & 1
 \end{pmatrix}
 =
 \begin{pmatrix}
 1 & 4 & 3 & 4 & 1 \\
 1 & 2 & 4 & 3 & 3 \\
 1 & 2 & 3 & 4 & 1 \\
 1 & 3 & 3 & 1 & 1 \\
 3 & 3 & 1 & 1 & 0
 \end{pmatrix}$$

I
 K
 $I * K$

Pooling Layer

Input

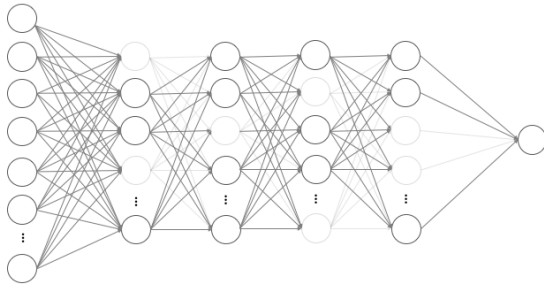
4	7	1	2
6	3	0	8
9	1	6	0
6	4	1	7

Max
pooling

Output

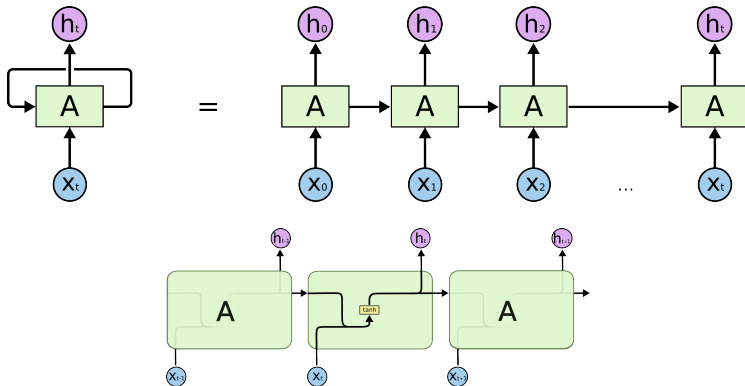
7	8
9	7

Dropout Layer



RNN: Recurrent Neural Networks

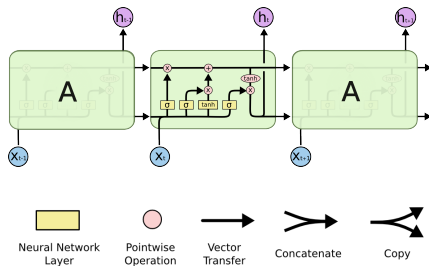
Given a sequence (of words): $x = x_1 x_2 \cdots x_t$



<https://colah.github.io/posts/2015-08-Understanding-LSTMs/>

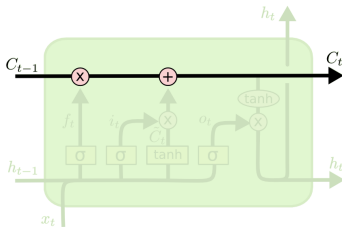
LSTM: Long Short Term Memory networks

1. We keep a cell state across the sequence C_t
2. After each step t we:
 - ▶ forget something: f_t
 - ▶ include something : i_t
 - ▶ update the cell state: C_t
 - ▶ output something to the next step: h_t



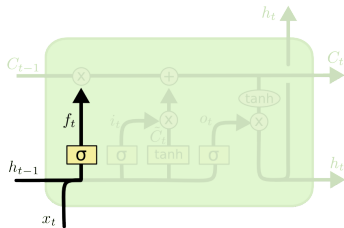
LSTM: Keep Global state

1. We keep a cell state across the sequence C_t
2. After each step t we:
 - ▶ forget something: f_t
 - ▶ include something : i_t
 - ▶ update the cell state: C_t
 - ▶ output something to the next step: h_t



LSTM: forget gate state

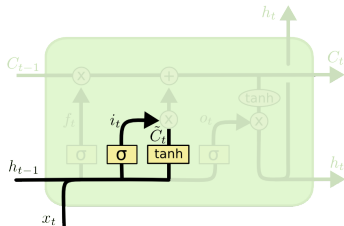
1. We keep a cell state across the sequence C_t
2. After each step t we:
 - ▶ **forget something:** f_t
 - ▶ include something : i_t
 - ▶ update the cell state: C_t
 - ▶ output something to the next step: h_t



$$f_t = \sigma(W_f \cdot [h_{t-1}, x_t] + b_f)$$

LSTM: input gate state

1. We keep a cell state across the sequence C_t
2. After each step t we:
 - ▶ forget something: f_t
 - ▶ **include something** : i_t
 - ▶ update the cell state: C_t
 - ▶ output something to the next step: h_t

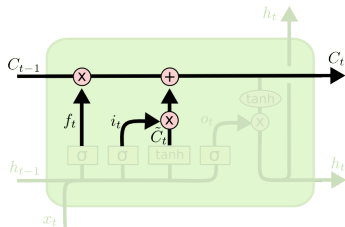


$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i)$$

$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

LSTM: update cell state

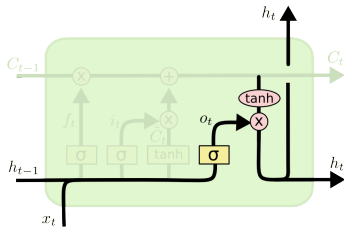
1. We keep a cell state across the sequence C_t
2. After each step t we:
 - ▶ forget something: f_t
 - ▶ include something : i_t
 - ▶ **update the cell state:** C_t
 - ▶ output something to the next step: h_t



$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

LSTM: cell output

1. We keep a cell state across the sequence C_t
2. After each step t we:
 - ▶ forget something: f_t
 - ▶ include something : i_t
 - ▶ update the cell state: C_t
 - ▶ **output something to the next step: h_t**



$$o_t = \sigma(W_o [h_{t-1}, x_t] + b_o)$$

$$h_t = o_t * \tanh(C_t)$$

Generating text

1. From the text, we create a training set form by couples $([x_1, \dots, x_t], y_t)$ where:
 - ▶ $[x_1, \dots, x_t]$ is a sequence of t elements (letters, words)
 - ▶ y_t is the element to be predicted
2. From a seed sequence we sequentially generate the text consider as input the last sequence.