

# Multi-view Scene Image Inpainting Based on Conditional Generative Adversarial Networks

Michael Shell<sup>1\*</sup>, John Doe<sup>2</sup>, and Jane Doe<sup>2\*\*</sup>

<sup>1</sup>Department of Electrical and Computer Engineering, Georgia Institute of Technology, Atlanta, GA, 30332, USA

<sup>2</sup>Indian Institute of Engineering Science and Technology, Shibpur, Howrah 711103, India

\* Member, IEEE

\*\* Senior Member, IEEE

Manuscript received June 7, 2017; revised June 21, 2017; accepted July 6, 2017. Date of publication July 12, 2017; date of current version July 12, 2017.

**Abstract**—Multi-views systems have been widely used in robots, ADAS(Advanced Driver Assistance Systems), monitor systems and so on, using multi-views, the machine can better perceive the surrounding scenes. The exposed lens and the camera are easily contaminated by the outside, resulting in abnormal images. Image inpainting technology can utilize the prior information of the image structure, texture and other information provided by the surrounding pixels of the abnormal area to recover the damaged image, which can reduce the loss of visual information. Provide as much information as possible for the machine's decisions. In order to achieve the above purposes, considering the characteristics of multi-vision system, a novel image inpainting method is proposed. The basic idea is that using conditional generative adversarial networks(CGAN) to amend defect images, in which the priori condition is the synchronization frame from other cameras in different viewpoints. The generator in the CGAN is a autoencoder which has skip connected from encoder to decoder. We also integrate spatial transform networks, group convolution and channel switching technology in our network structure to fusion the multi-views information. Experimental results show that our method can achieve high quality image inpainting.

**Index Terms**—Image inpainting, generative adversarial networks, convolutional neural network, deep learning.

## I. INTRODUCTION

This demo file is intended to serve as a “starter file” for *IEEE Sensors Letters* papers produced under L<sup>A</sup>T<sub>E</sub>X [1] using IEEE\_lsens.cls version 1.0 and later.

I wish you the best of success.

mds

July 12, 2017

### A. Subsection Heading Here

Subsection text here.

1) Subsubsection Heading Here: Subsubsection text here.

## II. CONCLUSION

The conclusion goes here.

## ACKNOWLEDGMENT

This work was supported by the IEEE. The authors would like to thank ... Note that the Acknowledgment section of *IEEE Sensors Letters* is rendered in scriptsize.

## REFERENCES

- [1] H. Kopka and P. W. Daly, *Guide to L<sup>A</sup>T<sub>E</sub>X*, 4th ed. Boston, MA: Addison-Wesley, 2004.

Corresponding author: M. Shell (e-mail: nospam@nospam.org).

(For the real e-mail address, see <http://www.michaelshell.org/contact.html>).

Associate Editor: Alan Smithee.

Digital Object Identifier 10.1109/LENS.2017.0000000