Yuming Jin

1009 Davis St. Apt.32, Evanston, IL 60201 ♦ C: (217) 904-9557 ♦ jinyumingtim@outlook.com ♦ Website: https://frogjin.github.io ♦ GitHub: https://github.com/frogjin ♦ LinkedIn: https://www.linkedin.com/in/yuming-jin-1509b7117/ Objective — Looking for Spring 2022 Full-Time Job & Winter/Summer Internship. Interested in Robotics related positions. Open to any positions. ———— Education -Computer Engineering, B.S. May 2020 University of Illinois at Urbana-Champaign - Urbana-Champaign, IL, US GPA: 3.33/4.00 2022, Current Robotics, M.S. Northwestern University, IL, US GPA: 3.475/4.00 Specialized Courses -Mobile Applications AI, ML & Computer Vision Robotics Manipulation Design of Elements VR Game Design Control Systems – Work History — Software Developer & Tester, Co-op at Nokia Small Cell Group 01/2019 - 05/2019, Full-time Co-op Nokia Corporation - 2000 W Lucent Ln, Naperville, IL 60563 ♦ Create an Android mobile app using Java that helps testers and customers to deploy/test Small Cells using BT \diamond Main software tester of the team that identify customers feedbacks and imporve the UI ♦ Write bug reports and manage Git repository ♦ Multinational team working and successfully demo the product beyond expectation Cloud Computing Developer, Intern at Vispractice 06/2017 - 08/2017, Full-time Internship Shenzhen Vispractice Technology Co., Ltd. - Nanshan Science and Technology Park, Shenzhen, China ♦ Trained for understanding Linux Virtual Machine, Filesystem & Amazon S3 API ♦ Learn to construct custom filesystem with FUSE, test and mount under VM environment ♦ Further study of **Python** web scraping & **MYSQL** database constructing ♦ Build Search Engine with **Haystack** & **Whoosh**, and design web page using **Django**. - Projects -Embedded Systems in Robotics Final Project, Connect-4 10/2020 - 12/2020♦ Codes the Sawyer robot to play connect 4 against a human player Mobile Manipulation Capstone Project, youBot CoppeliaSim Simulation 11/2020 - 12/2020 ♦ Plans a trajectory for the end-effector of the youBot mobile manipulator, performs odometry and feedback control to drive the youBot to pick up a block and drop it at a desired location. Theory of Machine Dynamics Final Project, Jack in Cup Simulation 10/2020 - 12/2020♦ Simulates the physical system of a "jack" in a "cup". Written in Python Mobile Computing and Applications Final Project, Walk Distance Tracking 04/2018 - 05/2018 ♦ Tracks the walking distance of a mobile device carrier by analysing the accelerometer, gyroscope and magnetic field data collected using MATLAB.

Personal Project, MOPO Forum

01/2015 - 12/2015

♦ An IOS App for MOPO (Mangrove Protection Organization) which allows the members to post and read threads. Written in **ObjectiveC** and used **MySQL** database.