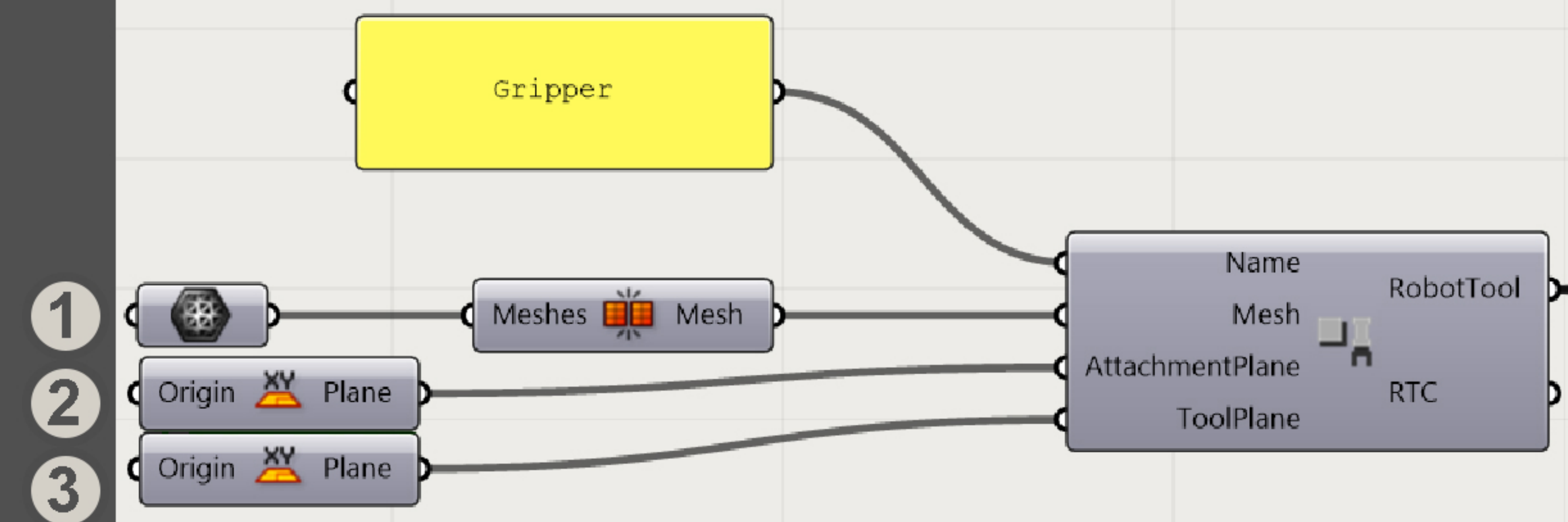
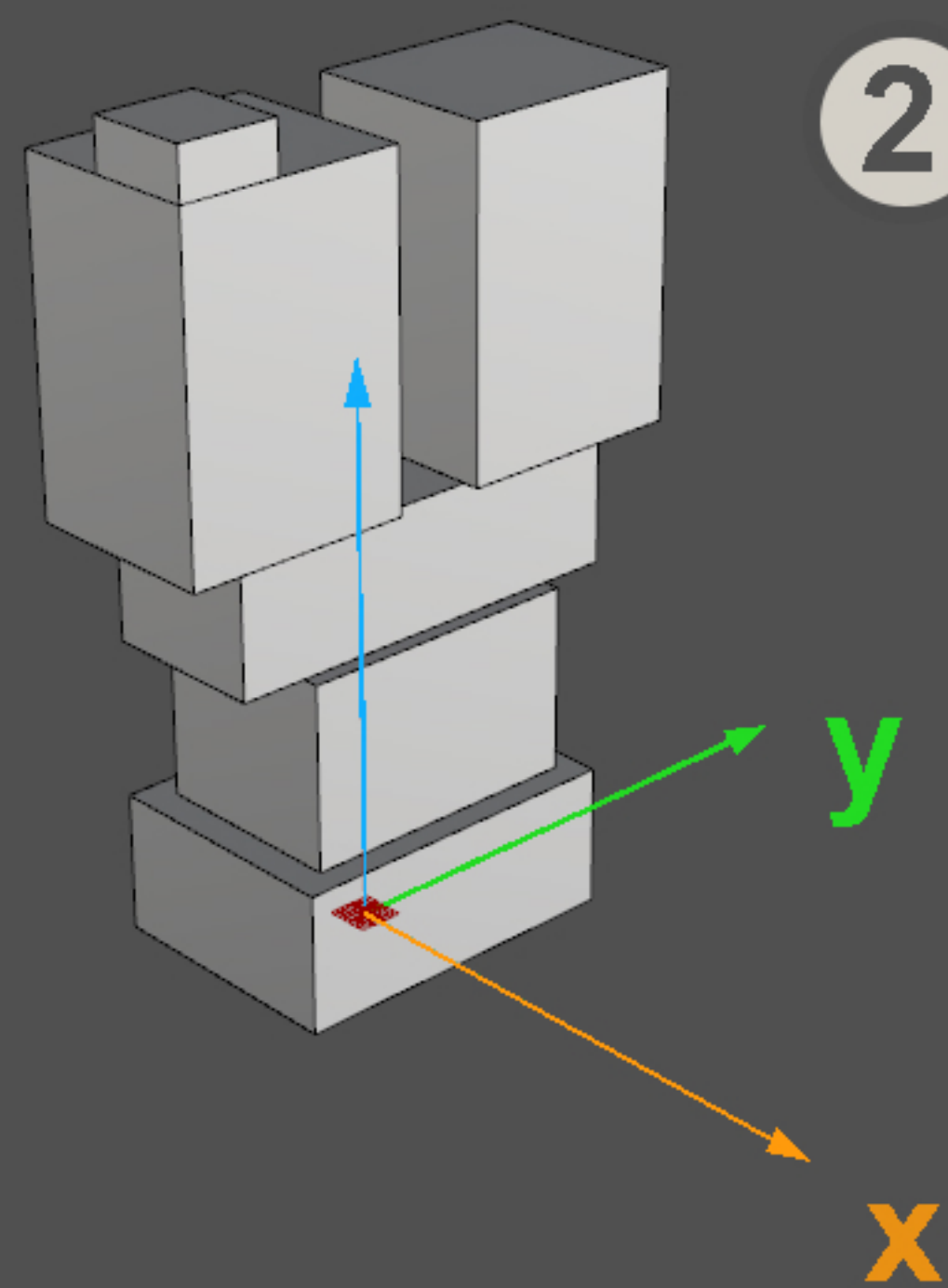


- 1 Place your tool vertically at the world center and import your geometry to grasshopper.

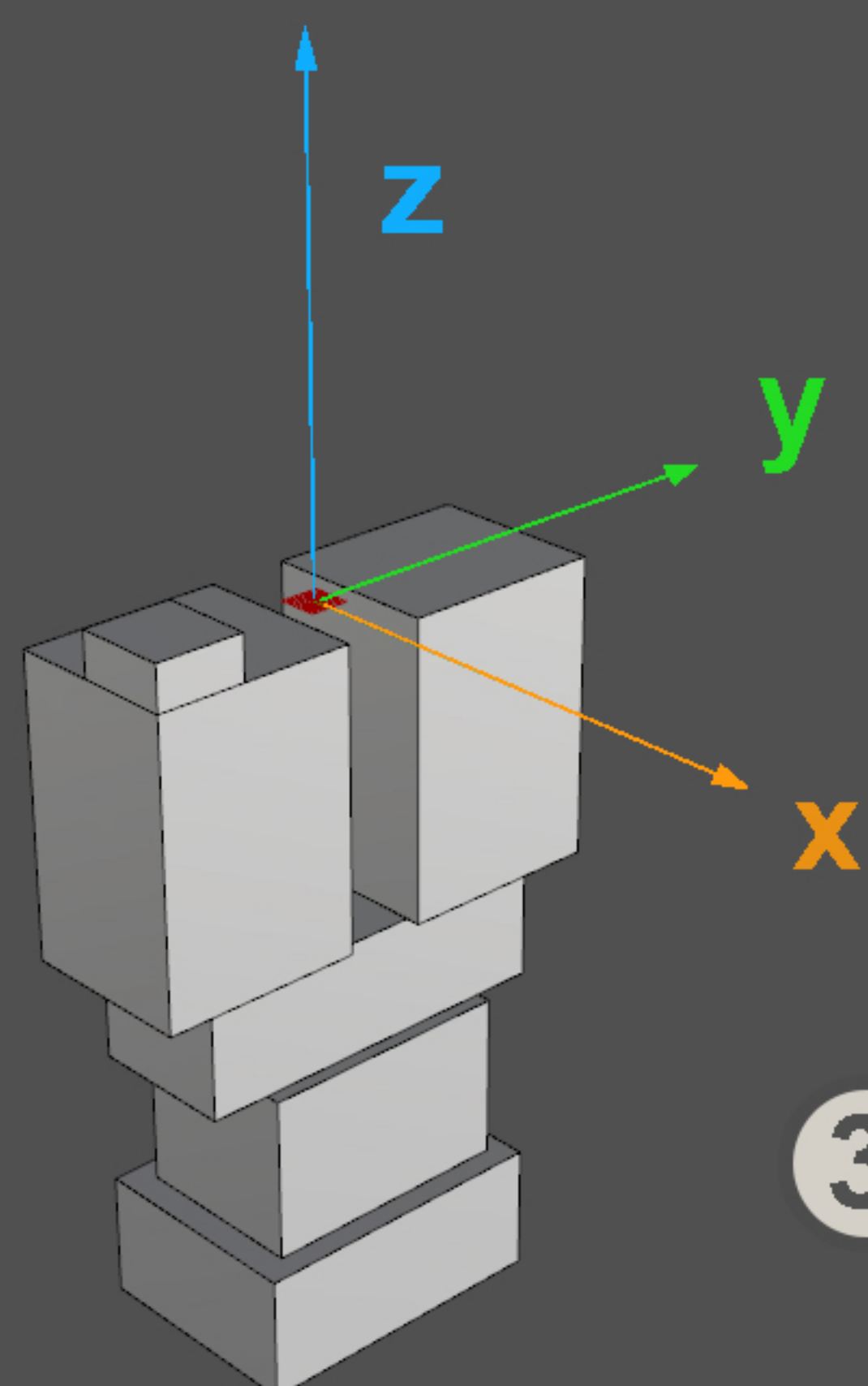
Definitions: Robot Tool



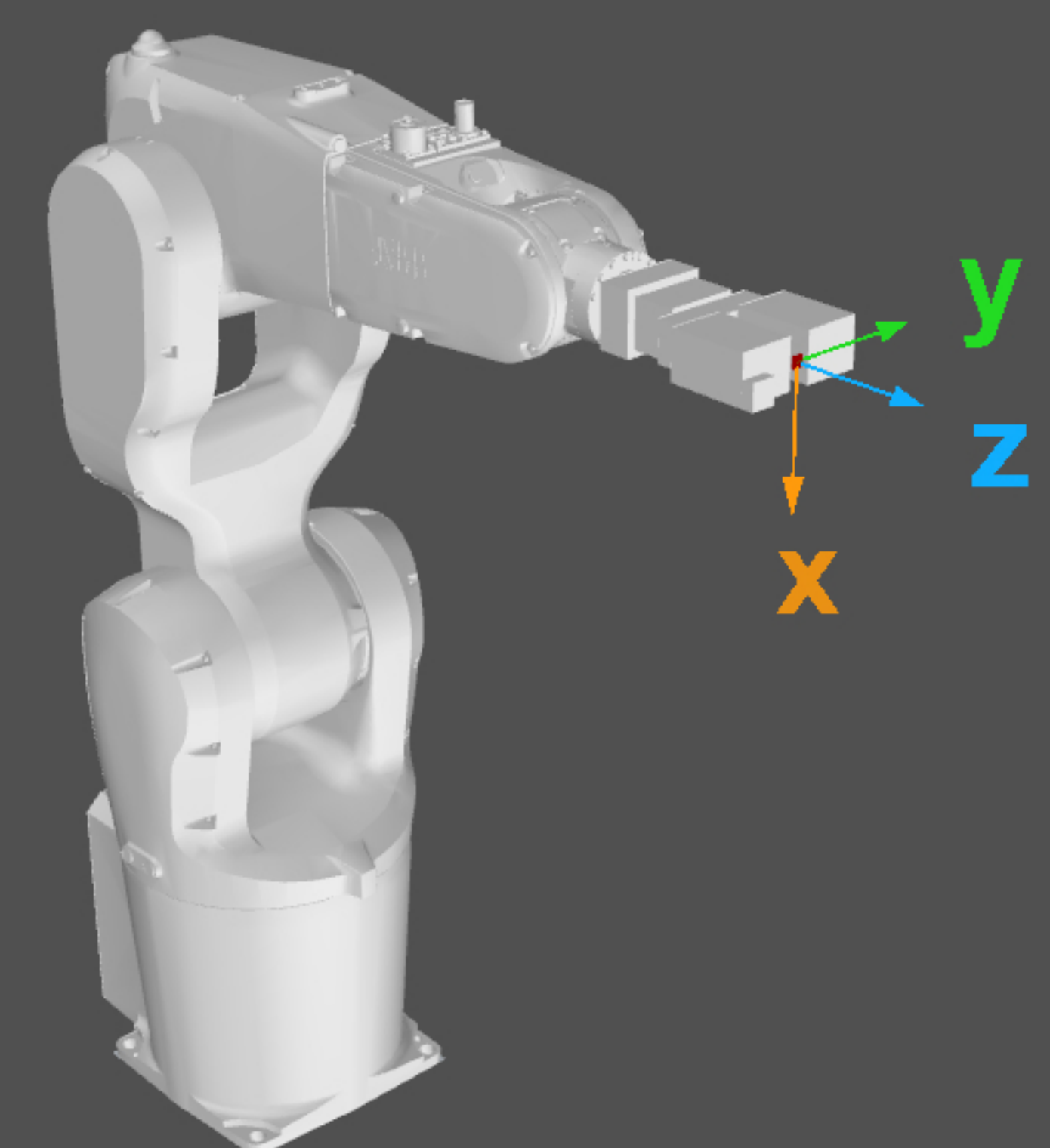
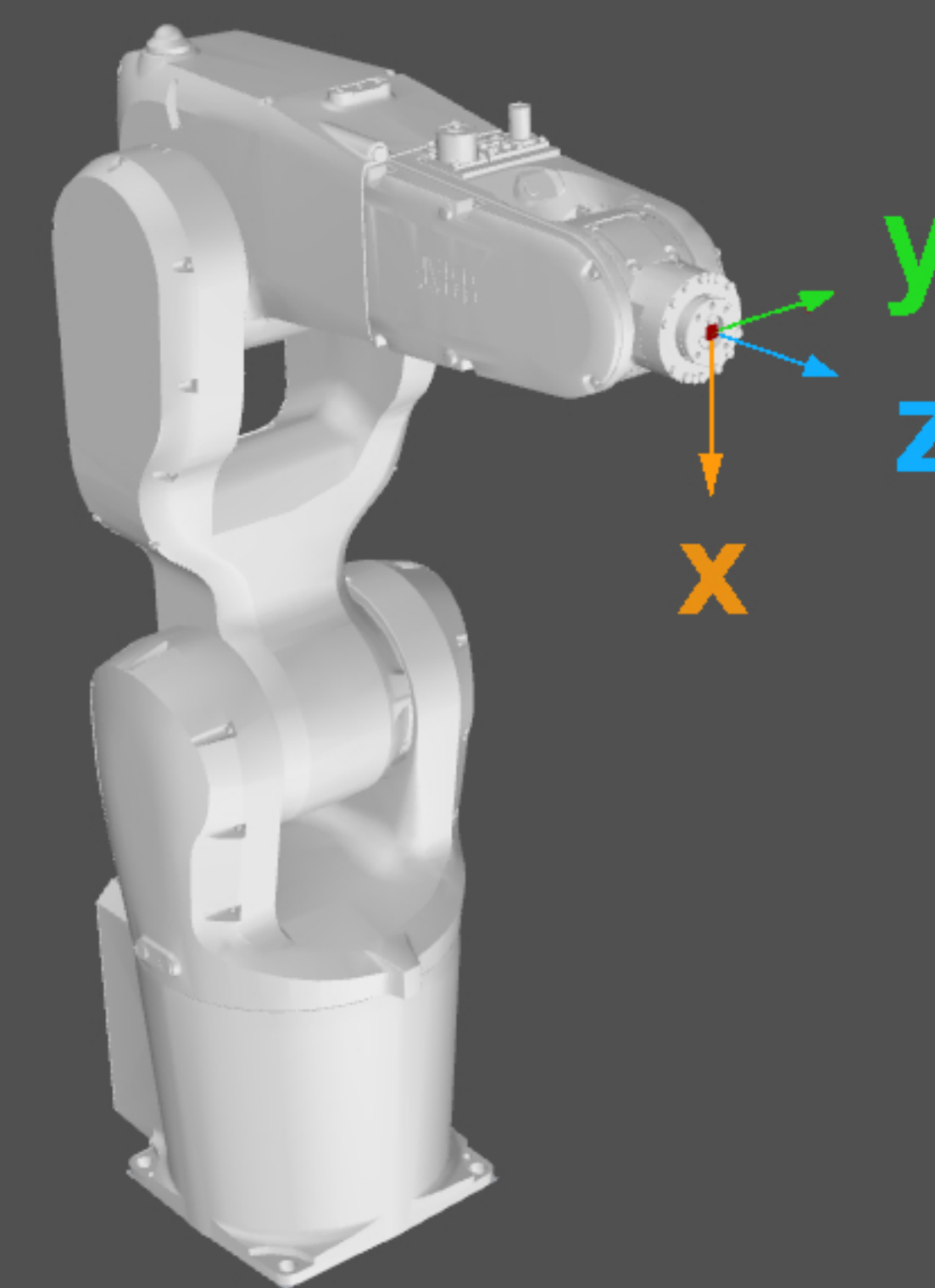
- 4 This is how your final setup should look inside of grasshopper.



- 2 Define the attachment plane of your tool with the XY Plane component of grasshopper. This will define how the tool will be attached to the mounting plane of the robot.



- 3 Define the tool plane of your tool with the XY Plane component of grasshopper.



- 5 If your setup is correct, the tool will be mounted to the robot by transforming it's position based on the attachment plane and a rotation of 90 degrees on the y axis.