THU-70250403, Convex Optimization (Fall 2020)

Homework: 5

Dual Problems and Classification

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Problem 1

Considering the following optimization problem

$$\min_{\boldsymbol{x},\boldsymbol{z}\in\mathbb{R}^n} \quad \frac{1}{2} |\boldsymbol{x}|_2^2 + \frac{1}{2} |A\boldsymbol{z} - \boldsymbol{b}|_2^2$$
 (1)

s.t.
$$x-z=c$$
 (2)

where $A \in \mathbb{R}^{m \times n}$ are known constant matrix with rank $(A) = n, b \in \mathbb{R}^m, c \in \mathbb{R}^n$ are known constant vectors.

Please derive the corresponding dual problem.

Solution

Let $\mathbf{y} = A\mathbf{z} - \mathbf{b}$, then the original problem becomes

$$\min_{\boldsymbol{x},\boldsymbol{y}} \quad \frac{1}{2}|\boldsymbol{x}|_2^2 + \frac{1}{2}|\boldsymbol{y}|_2^2
\text{s.t.} \quad \boldsymbol{y} = A\boldsymbol{z} - \boldsymbol{b} \tag{3}$$

s.t.
$$\mathbf{y} = A\mathbf{z} - \mathbf{b}$$
 (4)

$$\boldsymbol{x} - \boldsymbol{z} = \boldsymbol{c} \tag{5}$$

Now we introduce $v_1 \in \mathbb{R}^n, v_2 \in \mathbb{R}^m$ and formulate the lagrange function as follows:

$$L(v_1, v_2) = \frac{1}{2} |x|_2^2 + \frac{1}{2} |y|_2^2 + v_1^T (x - z - c) + v_2^T (Az - b - y)$$
(6)

$$= \frac{1}{2}\boldsymbol{x}^{T}\boldsymbol{x} + \boldsymbol{v_{1}}^{T}\boldsymbol{x} + \frac{1}{2}\boldsymbol{y}^{T}\boldsymbol{y} - \boldsymbol{v_{2}}^{T}\boldsymbol{y} + (\boldsymbol{v_{2}}^{T}\boldsymbol{A} - \boldsymbol{v_{1}})\boldsymbol{z} - \boldsymbol{v_{1}}^{T}\boldsymbol{c} - \boldsymbol{v_{2}}^{T}\boldsymbol{b}$$

$$(7)$$

$$\Rightarrow$$
 (8)

$$g(\mathbf{v_1}, \mathbf{v_2}) = \inf_{\mathbf{x}, \mathbf{y}} (\frac{1}{2} \mathbf{x}^T \mathbf{x} + \mathbf{v_1}^T \mathbf{x} + \frac{1}{2} \mathbf{y}^T \mathbf{y} - \mathbf{v_2}^T \mathbf{y} + (\mathbf{v_2}^T A - \mathbf{v_1}) \mathbf{z} - \mathbf{v_1}^T \mathbf{c} - \mathbf{v_2}^T \mathbf{b})$$
(9)

$$= -v_1^T c - v_2^T b + \inf_{x} (\frac{1}{2} x^T x + v_1^T x) + \inf_{y} (\frac{1}{2} y^T y - v_2^T y) + \inf_{z} ((v_2^T A - v_1^T) z)$$
(10)

Then we can get the following result,

$$g(\boldsymbol{v}) = \begin{cases} -\frac{1}{2} \boldsymbol{v_1}^T \boldsymbol{v_1} - \boldsymbol{v_1}^T \boldsymbol{c} - \frac{1}{2} \boldsymbol{v_2}^T \boldsymbol{v_2} - \boldsymbol{v_2}^T \boldsymbol{b} & \boldsymbol{v_2}^T A = \boldsymbol{v_1}^T \\ -\infty & \text{Otherwise} \end{cases}$$
(11)

Therefore, the dual problem of the original problem can be formulated as follows:

$$\max_{\boldsymbol{v_1}, \boldsymbol{v_2}} \quad -\frac{1}{2} \boldsymbol{v_1}^T \boldsymbol{v_1} - \boldsymbol{v_1}^T \boldsymbol{c} - \frac{1}{2} \boldsymbol{v_2}^T \boldsymbol{v_2} - \boldsymbol{v_2}^T \boldsymbol{b}$$
 (12)

s.t.
$$\mathbf{v_2}^T A = \mathbf{v_1}^T$$
 (13)

Also, we can use the subject condition to eliminate v_1 and get,

$$\max_{\boldsymbol{v_2}} \quad -\frac{1}{2}\boldsymbol{v_2}^T A A^T \boldsymbol{v_2} - \boldsymbol{v_2}^T A c - \frac{1}{2}v_2^T v_2 - \boldsymbol{v_2}^T \boldsymbol{b}$$
 (14)

Problem 2

The sum of the largest elements of a vector.

Define $f: \mathbb{R}^n \to \mathbb{R}$ as

$$f(\boldsymbol{x}) = \sum_{i=1}^{r} \boldsymbol{x}_{[i]},$$

where r is an integer between 1 and n, and $\boldsymbol{x}_{[1]} \geqslant \boldsymbol{x}_{[2]} \geqslant \cdots \geqslant \boldsymbol{x}_{[r]}$ are the components of x sorted in decreasing order. In other words, f(x) is the sum of the r largest elements of x. In this problem we study the constraint

$$f(\boldsymbol{x}) \leqslant \alpha.$$

This is a convex constraint, and equivalent to a set of n!/(r!(n-r)!) linear inequalities

$$\boldsymbol{x}_{i_1} + \cdots + \boldsymbol{x}_{i_r} \leqslant \alpha, \quad 1 \leqslant i_1 < i_2 < \cdots < i_r \leqslant n.$$

The purpose of this problem is to derive a more compact representation.

1. Given a vector $\boldsymbol{x} \in \mathbb{R}^n$, show that $f(\boldsymbol{x})$ is equal to the optimal value of the LP

with $\mathbf{y} \in \mathbb{R}^n$ as variable.

2. Derive the dual of the LP in part (a). Show that it can be written as

minimize
$$rt + \mathbf{1}^T \mathbf{u}$$

subject to $t\mathbf{1} + \mathbf{u} \succeq \mathbf{x}$
 $\mathbf{u} \succeq \mathbf{0}$.

where the variables are $t \in \mathbb{R}$, $\boldsymbol{u} \in \mathbb{R}^n$. By duality this LP has the same optimal value as the LP in (a), *i.e.*, f(x). We therefore have the following result: \boldsymbol{x} satisfies $f(\boldsymbol{x}) \leqslant \alpha$ if and only if there exist $t \in \mathbb{R}$, $\boldsymbol{u} \in \mathbb{R}^n$ such that

$$rt + \mathbf{1}^T \mathbf{u} \leqslant \alpha, \qquad t\mathbf{1} + \mathbf{u} \succ \mathbf{x}, \qquad \mathbf{u} \succ \mathbf{0}.$$

These conditions form a set of 2n+1 linear inequalities in the 2n+1 variables $\boldsymbol{x},\boldsymbol{u},t$.

Solution

1. Obviously, the optimal solution of the problem is to assign weight 1 to r largest elements of \boldsymbol{x} , which gives

$$\max_{\boldsymbol{y}} \quad \boldsymbol{x}^T \boldsymbol{y} = \sum_{i=1}^r \boldsymbol{x}_{[i]} \tag{15}$$

s.t.
$$\mathbf{0} \prec \mathbf{y} \prec \mathbf{1}$$
 (16)

$$\mathbf{1}^T \mathbf{y} = r \tag{17}$$

We can prove this by contradiction. Suppose an element $x_{[j]}$, j > r is assigned weight of a, 0 < a < 1. Assume this weight originally belongs to $x_{[k]}$, $1 \le k \le r$. Then the object value becomes $\sum_{i=1}^{r} x_{[i]} + a(x_{[j]} - x_{[k]}) < r$ $\sum_{i=1}^{r} \boldsymbol{x}_{[i]}$ since $\boldsymbol{x}_{[k]} > \boldsymbol{x}_{[j]}$ according to the sorting result. So the original assignment of weights is optimal as

2. The original problem is equivalent to:

$$\min_{\mathbf{y}} \quad -\mathbf{x}^{T}\mathbf{y} \tag{18}$$
s.t. $\mathbf{0} \leq \mathbf{y} \leq \mathbf{1} \tag{19}$

$$\mathbf{1}^{T}\mathbf{y} = r \tag{20}$$

s.t.
$$\mathbf{0} \leq \mathbf{y} \leq \mathbf{1}$$
 (19)

$$\mathbf{1}^T \mathbf{y} = r \tag{20}$$

Now we introduce $\lambda_1, \lambda_2 \in \mathbb{R}^n, v \in \mathbb{R}$ and formulate the lagrange function as follows:

$$L(\boldsymbol{y}, \boldsymbol{\lambda}_{1}, \boldsymbol{\lambda}_{2}, v) = -\boldsymbol{x}^{T} \boldsymbol{y} - \boldsymbol{\lambda}_{1}^{T} \boldsymbol{y} + \boldsymbol{\lambda}_{2}^{T} (\boldsymbol{y} - 1) + v(1^{T} \boldsymbol{y} - r)$$
(21)

$$= (-\boldsymbol{x}^{T} - \boldsymbol{\lambda_{1}}^{T} + \boldsymbol{\lambda_{2}}^{T} + v\boldsymbol{1}^{T})\boldsymbol{y} - \boldsymbol{\lambda_{2}}^{T}\boldsymbol{1} - vr$$
(22)

$$\Rightarrow$$
 (23)

Then we can get the following result,

$$g(\boldsymbol{v}) = \begin{cases} -\boldsymbol{\lambda_2}^T \mathbf{1} - vr & \boldsymbol{\lambda_2}^T + v \mathbf{1}^T = \boldsymbol{x}^T + \boldsymbol{\lambda_1}^T \\ -\infty & \text{Otherwise} \end{cases}$$
(25)

Therefore, the dual problem of the original problem can be formulated as follows:

$$\max_{\boldsymbol{\lambda}_{1}, \boldsymbol{\lambda}_{2}, v} - \boldsymbol{\lambda}_{2}^{T} \mathbf{1} - vr$$
s.t.
$$\boldsymbol{\lambda}_{2}^{T} + v \mathbf{1}^{T} = \boldsymbol{x}^{T} + \boldsymbol{\lambda}_{1}^{T}$$
(26)

s.t.
$$\boldsymbol{\lambda_2}^T + v \mathbf{1}^T = \boldsymbol{x}^T + \boldsymbol{\lambda_1}^T$$
 (27)

$$\lambda_1 \succeq 0 \tag{28}$$

$$\lambda_2 \succeq 0$$
 (29)

By eliminating λ_1 and substitute λ_2 , v with u, t respectively, we can get

$$\min_{\boldsymbol{u},t} \quad rt + \mathbf{1}^T \boldsymbol{u} \tag{30}$$

s.t.
$$t\mathbf{1}^T + \mathbf{u} \succeq \mathbf{x}$$
 (31)

$$\boldsymbol{u} \succeq \mathbf{0} \tag{32}$$

which is the same with the problem statement.

Problem 3

The so called Support Vector Data Description (SVDD) [1] is a one-class classification method. Given a set of data $(\boldsymbol{x}_i), i = 1, \dots, l, \boldsymbol{x}_i \in \mathbb{R}^n$, SVDD tries to find a closed boundary (indeed an hypersphere centered at $\boldsymbol{a} \in \mathbb{R}^n$ and has a radius $r \in \mathbb{R}$) around the data by solving the following problem

$$\min_{\boldsymbol{a},r} \quad r^2 + C \sum_{i=1}^{L} \xi_i \tag{33}$$

s.t.
$$|\mathbf{x}_i - \mathbf{a}|_2^2 \le r^2 + \xi_i, \ i = 1, \dots, L$$
 (34)

$$\xi_i \ge 0, \ i = 1, \dots, L \tag{35}$$

where C > 0 is a penalty parameter.

Please explain the geometry meaning of ξ_i above and derive the dual problem.

Solution

The existence of ξ_i makes the boundary of the hypersphere soft. That is, data points are allowed to have small disturbance from the boundary with tolerance equal to ξ_i in terms of square root of distance from \boldsymbol{a} . So the geometry meaning of ξ_i is that it makes the boundary from a 'line' to a 'circular ring'.

Now we introduce $\alpha \in \mathbb{R}^L$, $\beta \in \mathbb{R}^L$ and formulate the lagrange function as follows:

$$L(r, \boldsymbol{a}, \xi_i, \boldsymbol{\alpha}, \boldsymbol{\beta}) = r^2 + C \sum_{i=1}^{L} \xi_i + \sum_{i=1}^{L} \alpha_i (|\boldsymbol{x}_i - \boldsymbol{a}|_2^2 - r^2 - \xi_i) + \sum_{i=1}^{L} \beta_i (-\xi_i)$$
(36)

Letting its partial derivatives with respect to r, \boldsymbol{a}, ξ_i be zero, we have,

$$\frac{\partial L(r, \boldsymbol{a}, \xi_i, \boldsymbol{\alpha}, \boldsymbol{\beta})}{\partial r} = 2r(1 - \sum_{i=1}^{L} \alpha_i) = 0 \quad \Rightarrow \quad \sum_{i=1}^{L} \alpha_i = 1$$
 (37)

$$\frac{\partial L(r, \boldsymbol{a}, \xi_i, \boldsymbol{\alpha}, \boldsymbol{\beta})}{\partial \boldsymbol{a}} = \sum_{i=1}^{L} \alpha_i (\boldsymbol{a} - \boldsymbol{x}_i) = 0 \quad \Rightarrow \quad \boldsymbol{a} = \sum_{i=1}^{L} \alpha_i \boldsymbol{x}_i$$
(38)

$$\frac{\partial L(r, \boldsymbol{a}, \xi_i, \boldsymbol{\alpha}, \boldsymbol{\beta})}{\partial \xi_i} = C - \alpha_i - \beta_i = 0 \quad \Rightarrow \quad \alpha_i + \beta_i = C \tag{39}$$

Eliminating the partial decision variables r, a, ξ_i , we have the objective of the Lagrange dual problem as

$$g(\boldsymbol{\alpha}, \boldsymbol{\beta}) = \sum_{i=1}^{L} \alpha_i |\boldsymbol{x}_i - \sum_{j=1}^{L} \alpha_j \boldsymbol{x}_j|_2^2$$
(40)

Therefore, the dual problem of the original problem can be formulated as follows:

$$\max_{\boldsymbol{\alpha},\boldsymbol{\beta}} \quad \sum_{i=1}^{L} \alpha_i |\boldsymbol{x}_i - \sum_{j=1}^{L} \alpha_j \boldsymbol{x}_j|_2^2$$
 (41)

s.t.
$$\boldsymbol{\alpha} \succeq \mathbf{0}$$
 (42)

$$\beta \succeq \mathbf{0} \tag{43}$$

$$\alpha + \beta = C1 \tag{44}$$

$$\sum_{i=1}^{L} \alpha_i = 1 \tag{45}$$

Note that β is irrelevant to the objective funtion, so we can eliminate it from the subject conditions.

$$\max_{\boldsymbol{\alpha}} \quad \sum_{i=1}^{L} \alpha_i |\boldsymbol{x}_i - \sum_{j=1}^{L} \alpha_j \boldsymbol{x}_j|_2^2$$
 (46)

s.t.
$$C1 \succeq \alpha \succeq 0$$
 (47)

$$\sum_{i=1}^{L} \alpha_i = 1 \tag{48}$$

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References

[1] D. M. J. Tax, R. P. W. Duin, "Support Vector Data Description," *Machine Learning*, vol. 54, no. 1, pp. 45-66, 2004.