HW5 Problem1

Let $\boldsymbol{y} = A\boldsymbol{z} - \boldsymbol{b}$, then the original problem becomes

$$\min_{\boldsymbol{x}, \boldsymbol{y}} \quad \frac{1}{2} |\boldsymbol{x}|_2^2 + \frac{1}{2} |\boldsymbol{y}|_2^2$$

s.t. $\boldsymbol{y} = A\boldsymbol{z} - \boldsymbol{b}$
 $\boldsymbol{x} - \boldsymbol{z} = \boldsymbol{c}$

Now we introduce $m{v}_1 \in \mathbb{R}^n, m{v}_2 \in \mathbb{R}^m$ and formulate the lagrange function as follows:

$$\begin{split} L\left(\boldsymbol{v_1}, \boldsymbol{v_2}\right) &= \frac{1}{2} |\boldsymbol{x}|_2^2 + \frac{1}{2} |\boldsymbol{y}|_2^2 + \boldsymbol{v_1}^T (\boldsymbol{x} - \boldsymbol{z} - \boldsymbol{c}) + \boldsymbol{v_2}^T (A \boldsymbol{z} - \boldsymbol{b} - \boldsymbol{y}) \\ &= \frac{1}{2} \boldsymbol{x}^T \boldsymbol{x} + \boldsymbol{v_1}^T \boldsymbol{x} + \frac{1}{2} \boldsymbol{y}^T \boldsymbol{y} - \boldsymbol{v_2}^T \boldsymbol{y} + \left(\boldsymbol{v_2}^T A - \boldsymbol{v_1}\right) \boldsymbol{z} - \boldsymbol{v_1}^T \boldsymbol{c} - \boldsymbol{v_2}^T \boldsymbol{b} \\ &\Rightarrow \\ g\left(\boldsymbol{v_1}, \boldsymbol{v_2}\right) &= \inf_{\boldsymbol{x}, \boldsymbol{y}} \left(\frac{1}{2} \boldsymbol{x}^T \boldsymbol{x} + \boldsymbol{v_1}^T \boldsymbol{x} + \frac{1}{2} \boldsymbol{y}^T \boldsymbol{y} - \boldsymbol{v_2}^T \boldsymbol{y} + \left(\boldsymbol{v_2}^T A - \boldsymbol{v_1}\right) \boldsymbol{z} - \boldsymbol{v_1}^T \boldsymbol{c} - \boldsymbol{v_2}^T \boldsymbol{b}\right) \\ &= -\boldsymbol{v_1}^T \boldsymbol{c} - \boldsymbol{v_2}^T \boldsymbol{b} + \inf_{\boldsymbol{x}} \left(\frac{1}{2} \boldsymbol{x}^T \boldsymbol{x} + \boldsymbol{v_1}^T \boldsymbol{x}\right) + \inf_{\boldsymbol{y}} \left(\frac{1}{2} \boldsymbol{y}^T \boldsymbol{y} - \boldsymbol{v_2}^T \boldsymbol{y}\right) + \inf_{\boldsymbol{z}} \left(\left(\boldsymbol{v_2}^T A - \boldsymbol{v_1}^T\right) \boldsymbol{z}\right) \end{split}$$

Then we can get the following result,

$$g(\boldsymbol{v}) = egin{cases} -rac{1}{2} oldsymbol{v_1}^T oldsymbol{v_1} - oldsymbol{v_1}^T oldsymbol{c} - rac{1}{2} oldsymbol{v_2}^T oldsymbol{v_2} - oldsymbol{v_2}^T oldsymbol{b} - oldsymbol{v_1}^T oldsymbol{c} - rac{1}{2} oldsymbol{v_2}^T oldsymbol{v_2} - oldsymbol{v_2}^T oldsymbol{b} - oldsymbol{v_1}^T oldsymbol{c} - oldsymbol{v_1} - oldsymbol{v_1}^T oldsymbol{v_2}^T oldsymbol{c} - oldsymbol{v_1}^T oldsymbol{c} - oldsymbol{v_1}^T oldsymbol{v_1} - oldsymbol{v_1}^T oldsymbol{c} - oldsymbol{v_1}^T oldsymbol{v_1} - oldsymbol{v_1}^T oldsymbol{v_2} - oldsymbol{v_2}^T oldsymbol{v_1} - oldsymbol{v_2}^T oldsymbol{v_1} - oldsymbol{v_2}^T oldsymbol{v_1} - oldsymbol{v_2}^T oldsymbol{v_1} - oldsymbol{v_2}^T oldsymbol{v_2} - oldsymbol{v_2}^T olds$$

Therefore, the dual problem of the original problem can be formulated as follows:

$$egin{array}{ll} \max_{oldsymbol{v_1,v_2}} & -rac{1}{2}oldsymbol{v_1}^Toldsymbol{v_1} - oldsymbol{v_1}^Toldsymbol{c} - rac{1}{2}oldsymbol{v_2}^Toldsymbol{v_2} - oldsymbol{v_2}^Toldsymbol{b} \ & ext{s.t.} & oldsymbol{v_2}^TA = oldsymbol{v_1}^T \end{array}$$

Also, we can use the subject condition to eliminate v_1 and get,

$$\max_{m{v_2}} - \frac{1}{2} m{v_2}^T A A^T m{v_2} - m{v_2}^T A c - \frac{1}{2} m{v_2}^T m{v_2} - m{v_2}^T m{b}$$