# Computer Vision Assignment

Problems attempted:

- Installing OpenCV :P
- Converting Video into individual frames
- Converting frames into video
- Capturing video from webcam
- Chroma Keying
- Face Detection

```
## Import Libraries
import cv2
import matplotlib.pyplot as plt
import numpy as np
import os
```

## Converting Video into individual frames

We start with writing a function to get a frame from the video specified in the file path, then storing it into a folder specified in the code.

```
video = "./GeoVision VD8700 Face Recognition IP Camera Demo Video.mp4"
cap = cv2.VideoCapture(video)
if not cap.isOpened():
    print("Error opening video stream or file")
def get_frame(sec):
    Gets a frame from the video at a given second
    :param sec: second to get frame from
    :return: frame at given second
    cap.set(cv2.CAP PROP POS MSEC, sec * 1000) # just cue to 20
sec. position
    hasFrames, image = cap.read()
    if hasFrames:
        cv2.imwrite("images/frame" + str(sec) + ".jpg", image)
# Common images folder for all images
    return hasFrames
sec = 0
```

```
frameRate = 0.5 # //it will capture image in each 0.5 second
count = 1

success = get_frame(sec)

while success: # Breaks when there are no more frames , compact way
of writing while True
    count = count + 1
    sec = sec + frameRate
    sec = round(sec, 2)
    success = get_frame(sec)

cap.release()
```

We read these images from the folder and now display them in two ways - OpenCV and Matplotlib.

```
# Read images from images folder
images = []
frames = 0
for filename in os.listdir("images"):
    if frames == 100:
        break
    frames += 1
    img = cv2.imread(os.path.join("images", filename))
    if img is not None:
        images.append(img)
        # print(filename + " read")
        print("Image " + str(frames) + " read")
# Display images OpenCV way
# cv2.imshow("Image", images[0])
# cv2.waitKey(0)
# cv2.destroyAllWindows()
## Using matplotlib
for i in range(len(images)):
    images[i] = cv2.cvtColor(images[i], cv2.COLOR BGR2RGB)
Convert to RGB for matplotlib
plt.imshow(images[0])
plt.show()
```



## Merge the frames into a video

```
for i in range(len(images)):
    images[i] = cv2.cvtColor(images[i], cv2.COLOR_RGB2BGR) #
Convert to RGB for matplotlib

# Merge images into a video
height, width, layers = images[0].shape
size = (width, height)

out = cv2.VideoWriter('project.mp4', cv2.VideoWriter_fourcc(*'MP4V'),
20.0, size)

for i in range(len(images)):
    out.write(images[i])

out.release()

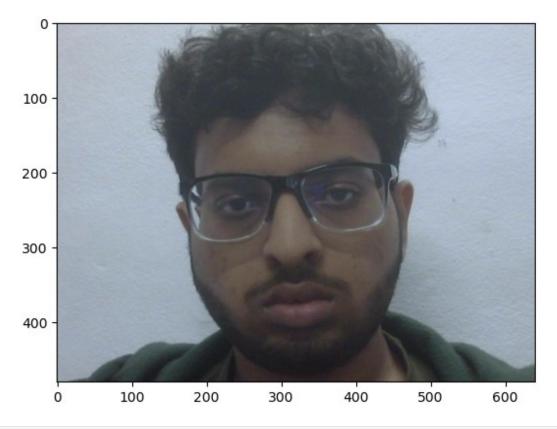
OpenCV: FFMPEG: tag 0x5634504d/'MP4V' is not supported with codec id
12 and format 'mp4 / MP4 (MPEG-4 Part 14)'
OpenCV: FFMPEG: fallback to use tag 0x7634706d/'mp4v'
```

The Only Challenge I really faced was to merge the frames back into a video in mp4 format, which I was able to solve using the documentation of OpenCV.

#### Capturing Video from Webcam and saving it

My Laptop does not have an Internal Webcam, so I used my Logitech C270 Webcam to capture the video and save it into a file.

```
## I don't have an in built webcam, so I will be using an external
webcam - a Logitech C270
cap = cv2.VideoCapture(0)
if not cap.isOpened():
    print("Error opening video stream or file")
frames = []
sec = 0
while True:
    ret, frame = cap.read()
    if ret:
        sec += 1
        frames.append(frame)
        print("Frame " + str(sec) + " read")
        cv2.imshow("Frame", frame)
        if cv2.waitKey(1) \& 0xFF == ord('q'):
            break
    else:
        break
cap.release()
cv2.destroyAllWindows()
for i in range(len(frames)):
    frames[i] = cv2.cvtColor(frames[i], cv2.COLOR BGR2RGB)
Convert to RGB for matplotlib
plt.imshow(frames[12])
<matplotlib.image.AxesImage at 0x7f7ab937b7c0>
```



#### Chroma Keying - Merging two videos into one

- We Do this by using the concept of masking, where we mask the green screen and replace it with the background video.
- We use the cv2.inRange function to mask the green screen, and get good results.

```
def chroma key frame(fg,bg):
    Replaces the background of a frame with a background image
    :param fg: foreground image
    :param bg: background image
    :return: frame with background replaced
    fg = cv2.cvtColor(fg, cv2.C0L0R BGR2RGB)
    bg = cv2.cvtColor(bg, cv2.COLOR BGR2RGB)
    fg = cv2.resize(fg, (bg.shape[1], bg.shape[0]))
    mask = np.zeros(fg.shape, dtype=np.uint8)
    lower color = np.array([0,30,0])
    upper color = np.array([75,255,75])
    mask = cv2.inRange(fg, lower color, upper color)
    # plt.imshow(mask, cmap="gray")
    masked image = np.copy(fg)
    masked image[mask != 0] = [0, 0, 0]
    bq new = np.copy(bq)
    bg new[mask == 0] = [0, 0, 0]
    return masked image + bg new
## Read video
green screen video = "./greenscreen.mp4"
wildlife video = "./wildlife.mp4"
cap = cv2.VideoCapture(green screen video)
if not cap.isOpened():
    print("Error opening video stream or file")
frames green = []
sec = 0
while True:
    ret, frame = cap.read()
    if ret:
        sec += 1
        frames green.append(frame)
        print("Frame " + str(sec) + " read")
```

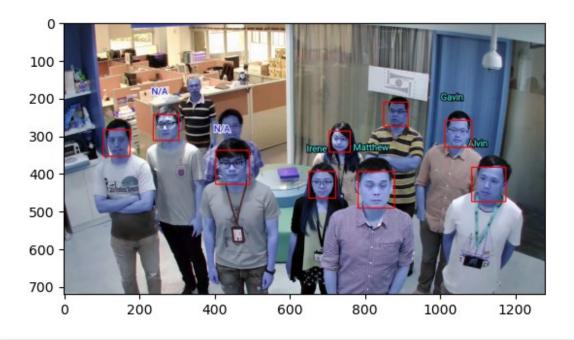
```
cv2.imshow("Frame", frame)
        if cv2.waitKey(1) \& 0xFF == ord('q'):
            break
    else:
        break
cap.release()
cv2.destroyAllWindows()
cap = cv2.VideoCapture(wildlife video)
if not cap.isOpened():
    print("Error opening video stream or file")
frames wildlife = []
sec = 0
while True:
    ret, frame = cap.read()
    if ret:
        sec += 1
        frames wildlife.append(frame)
        print("Frame " + str(sec) + " read")
        cv2.imshow("Frame", frame)
if cv2.waitKey(1) & 0xFF == ord('q'):
            break
    else:
        break
cap.release()
cv2.destroyAllWindows()
# Remove extra frames from wildlife video
frames wildlife = frames wildlife[:len(frames green)]
# Chroma keying
chroma keyed frames = []
for i in range(len(frames_green)):
chroma keyed frames.append(chroma key frame(frames green[i],frames wil
dlife[i]))
    chroma keyed frames[i] = cv2.cvtColor(chroma keyed frames[i],
cv2.COLOR_RGB2BGR) # Convert to RGB for matplotlib
## Merge frames into a video
```

```
height, width, layers = chroma_keyed_frames[0].shape
size = (width, height)
out = cv2.VideoWriter('chroma_keyed.mp4',
cv2.VideoWriter_fourcc(*'mp4v'), 20.0, size)
for i in range(len(chroma_keyed_frames)):
    out.write(chroma_keyed_frames[i])
out.release()
```

# Face Detection and Tracking

- Face detection using Haar Cascades
- We use the Haar Cascade for face detection, and then merge franes with bounding boxes on them to create a video.

```
# Read Images from /images folder
images = []
for filename in os.listdir("images"):
    img = cv2.imread(os.path.join("images", filename))
    if img is not None:
        images.append(img)
        print(filename + " read")
# Apply facial detection
# Load the cascade
face cascade =
cv2.CascadeClassifier('haarcascade frontalface default.xml')
# Read the input image
imq = images[55]
# Convert into grayscale
gray = cv2.cvtColor(img, cv2.COLOR BGR2GRAY)
# Detect faces
faces = face cascade.detectMultiScale(gray, 1.1, 9)
# Draw rectangle around the faces
for (x, y, w, h) in faces:
    cv2.rectangle(img, (x,y), (x+w, y+h), (255, 0, 0), 2)
# Display the output with faces detected
plt.imshow(img)
plt.show()
```



```
## Apply facial detection to all images
faces = []
for i in range(len(images)):
    img = images[i]
    gray = cv2.cvtColor(img, cv2.COLOR BGR2GRAY)
    faces.append(face cascade.detectMultiScale(gray, 1.1, 9))
# Create Video with faces detected
for i in range(len(images)):
    for (x, y, w, h) in faces[i]:
        cv2.rectangle(images[i], (x,y), (x+w, y+h), (255, 0, 0), 2)
    images[i] = cv2.cvtColor(images[i], cv2.COLOR BGR2RGB)
Convert to RGB for matplotlib
height, width, layers = images[0].shape
size = (width, height)
out = cv2.VideoWriter('faces detected.mp4',
cv2.VideoWriter fourcc(*'mp4v'), 20.0, size)
for i in range(len(images)):
    out.write(images[i])
out.release()
```