





$$\mathcal{P}_G$$

cons	$\langle (x\ y), (\text{lambda } (k) \ (\text{if } k\ x\ y)), \mathcal{P}_G \rangle$
car	$\langle (p), (p\ \#t), \mathcal{P}_G \rangle$
cdr	$\langle (p), (p\ \#f), \mathcal{P}_G \rangle$
p	$\langle (k), (\text{if } k\ x\ y), \mathcal{P}_1 \rangle$

$$\mathcal{P}_1$$

x	1
y	2

$$\mathcal{P}_2$$

k	#t
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```
(define p (cons 1 2))
(car p)
```