Numerical simulation of a Penning trap

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I. INTRODUCTION

The purpose of this report is to present the study of the effects of a Penning trap through numerical simulations. The Penning trap is a device used to store or "trap" charged particles using static electric and magnetic fields as shown in figure 1. These particles can then be used for a variety of experiments. Examples of this are the ALPHA, AEgIS and BASE experiments at CERN, these use Penning traps to control antimatter. The electric field is generated by two end caps (a), at the top and bottom, and a ring (b) (figure 1 only shows the ring cross-section). This electric field restricts the particles' movement in the z direction and the additional homogenous magnetic field hiders particles escaping in the xy-plane (radial direction) if it is strong enough. The magnetic field is set by a cylinder magnet (c) (figure 1 again only shows the ring cross-section).

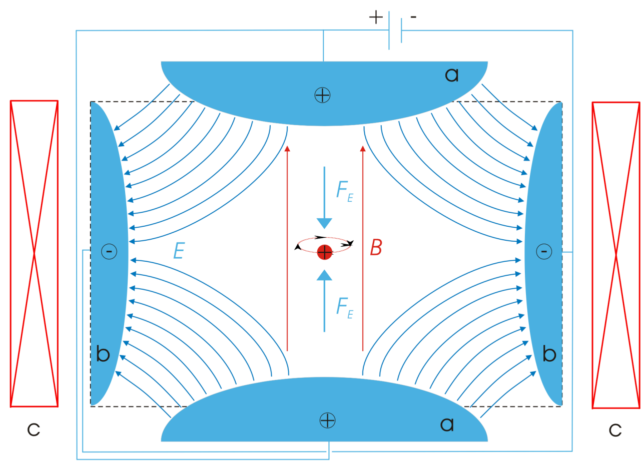

FIG. 1. This figure shows the idea of a Penning trap with a red positively charged particle in the center. Here blue lines represent the electric field generated by a quadrupole consisting of end caps (a) and a ring electrode (b). The red lines represent the magnetic field created by a surrounding cylinder magnet (c). Illustration by Arian Kriesch taken from Wikimedia Commons.

Materials to construct a physical Penning trap are very costly, we will therefore be using a numerical approach to simulate a Penning trap. To implement such a simulation we will be working with a system of coupled non-linear differential equations. These are very difficult and often impossible to solve analytically. An example some readers might be familiar with are the famous Navier-Stokes equations, the solving of which would be rewarded with a million dollar prize. In addition to the material cost, the complexity of the equations therefore also motivates the use of numerical methods.

Section II will describe the mathematical and physical background as well as concrete algorithms which in this case will be implemented in C++, but can be written in any programming language.

In section III we present...

A detailed discussion of the algorithms' and results is presented in section IV, followed by a summary and potential for further experiments in section V.

II. METHODS

The physical laws used to implement the Penning trap simulation will be from electrodynamics and classical mechanics, we will not take quantum aspects into account. The following equations will be used:

$$\mathbf{E} = -\nabla V \tag{1}$$

$\mathbf{E}$ is the electric field and V the electric potential.

$$\mathbf{E(r)} = k_e \sum_{j=1}^{n} q_j \frac{\mathbf{r} - \mathbf{r}_j}{|\mathbf{r} - \mathbf{r}_j|^3} \tag{2}$$

$\mathbf{E(r)}$ is the electric field at a point $\mathbf{r}$. This is set up by point charges $q_1, ..., q_n$ at points $\mathbf{r}_1, ..., \mathbf{r}_n$. This comes from **Coulomb's law**, stating the magnitude of force between to point charges. $k_e \approx 8.988 \cdot 10^9 Nm^2C^{-2}$ is the Coulomb constant.

$$\mathbf{F} = q\mathbf{E} + q\mathbf{v} \times \mathbf{B} \tag{3}$$

This is the **Lonretz force**, the force $\mathbf{F}$ on a particle with charge q, an electric field $\mathbf{E}$, magnetic field $\mathbf{B}$ and velocity of the particle $\mathbf{v}$.

$$m\ddot{\mathbf{r}} = \sum_i \mathbf{F}_i \tag{4}$$

Eq. 4 is Newton's second law. Here m is the mass of the particle and $\ddot{\mathbf{r}} \equiv \frac{d^2\mathbf{r}}{dt^2}$ (the acceleration). Famously expressing that the sum of forces equals mass times acceleration.

$$V(x,y,z) = \frac{V_0}{2d^2}(2z^2 - x^2 - y^2) \tag{5}$$

For this experiment we will be considering an ideal Penning trap for which the electric field $\mathbf{E}$ is given by the electric potential V. Here V_0 is the potential applied to the electrodes. $d = \sqrt{z_0^2 + r_0^2/2}$ is the *charachteristic dimension* representing the length scale for the region between electrodes. Here z_0 is distance from the center to the end caps (a) and r_0 is the distance from the center to the surrounding ring (b).

$$\mathbf{B} = B_0\hat{e}_z = (0, 0, B_0) \tag{6}$$

$\mathbf{B}$ is the homogenous magnetic field and is dictated by the field strength B_0. With $B_0 > 0$.

Now starting from Newton's second law and using the equations above we can express the time evolution of the particles motion. The sum of forces will be the Lonretz force, putting eq. 3 into eq. 4 leads to:

$$m\ddot{\mathbf{r}} = q\mathbf{E} + q\mathbf{v} \times \mathbf{B} \tag{7}$$

Here $\ddot{\mathbf{r}} = (\ddot{x}, \ddot{y}, \ddot{z})$ and $\mathbf{v} = (\dot{x}, \dot{y}, \dot{z})$. Putting eq. 5 into eq. 1 gives us:

$$\mathbf{E} = \left(x\frac{v_0}{d^2}, y\frac{v_0}{d^2}, -2z\frac{v_0}{d^2}\right) \tag{8}$$

Now looking at $q\mathbf{v} \times \mathbf{B}$ we have:

$$(q\dot{x}, q\dot{y}, q\dot{z}) \times (0, 0, B_0) = (B_0 q\dot{y}, -B_0 q\dot{x}, 0) \tag{9}$$

Finally substituting for $\mathbf{E}$ and $q\mathbf{v} \times \mathbf{B}$ in eq. 7 results in:

$$m\begin{pmatrix}\ddot{x}\\ \ddot{y}\\ \ddot{z}\end{pmatrix} = \begin{pmatrix}qx\frac{v_0}{d^2}\\ qy\frac{v_0}{d^2}\\ -2qz\frac{v_0}{d^2}\end{pmatrix} + \begin{pmatrix}B_0 q\dot{y}\\ -B_0 q\dot{x}\\ 0\end{pmatrix}$$

Rewriting this as a set of equations leaves us with:

$$\ddot{x} - w_0\dot{y} - \frac{1}{2}w_z^2 x = 0 \tag{10}$$

$$\ddot{y} + w_0\dot{x} - \frac{1}{2}w_z^2 y = 0 \tag{11}$$

$$\ddot{z} + w_z^2 z = 0 \tag{12}$$

Where $w_0 = \frac{qB_0}{m}$ and $w_z^2 = \frac{2qV_0}{md^2}$. Taking a closer look at eq. 12 we see that the general solution is:

$$z = A\cos\left(w_z^2 t\right) + B\sin\left(w_z^2 t\right) \tag{13}$$

eq. 10 and 11 are coupled, thus introducing a challenge. This can be resolved by introducing a complex function $f(t) = x(t) + iy(t)$ and rewriting them as a single differential equation. By introducing the complex function we have:

$$f(t) = x(t) + iy(t) \tag{14}$$

$$\dot{f}(t) = \dot{x}(t) + i\dot{y}(t) \tag{15}$$

$$\ddot{f}(t) = \ddot{x}(t) + i\ddot{y}(t) \tag{16}$$

Now multiplying eq. 11 by i gives:

$$i\ddot{y} + iw_0\dot{x} - i\frac{1}{2}w_z^2 y = 0 \tag{17}$$

eq. 10 and 17 can then be summed:

$$\ddot{x} + i\ddot{y} - w_0\dot{y} + iw_0\dot{x} - \frac{1}{2}w_z^2 x - i\frac{1}{2}w_z^2 y = 0 \tag{18}$$

Finally, substituting for $f(t)$, $\dot{f}(t)$ and $\ddot{f}(t)$ shows that eq. 10 and 11 can be rewritten as a single differential equation for f:

$$\ddot{f} + iw_0\dot{f} - \frac{1}{2}w_z^2 f = 0 \tag{19}$$

The general solution to eq. 19 is:

$$f(t) = A_+ e^{-i(w_+ t + \phi_+)} + A_- e^{-i(w_- t + \phi_-)} \tag{20}$$

where the amplitudes A_+ and A_- are positive, ϕ_+ and ϕ_- are constant phases, and

$$w_\pm = \frac{w_0 \pm \sqrt{w_0^2 - 2w_z^2}}{2} \tag{21}$$

To obtain a bounded solution for the radial movement (xy-plane) of the particle we need to introduce some constraints on w_0 and w_z. In other words we will introduce some constraints that will ensure that $|f(t)| < \infty$ as $t \to \infty$.

Studying eq. 20 one notices that $|f(t)| \to \infty$ only if $w_\pm$ is complex. To avoid this, we introduce the limitation $w_0^2 - 2w_z^2 \geq 0$, avoiding any negative values inside the square root and consequently limiting the result to real numbers. Rearranging this and remembering that $w_0 = \frac{qB_0}{m}$ and $w_z^2 = \frac{2qV_0}{md^2}$ leaves us with:

$$\frac{q}{m} \geq \frac{4V_0}{B_0^2 d^2} \tag{22}$$

A constraint, that if satisfied, keeps the particle within the Penning trap.

Now to express the upper and lower bounds of the particles' distance from the origin in the xy-plane we start with eq. 20. Through Taylor expansion of e^{ix} we arrive at Euler's formula:

$$e^{ix} = \cos(x) + i\sin(x)$$

Introducing $u = w_+ t + \phi_+$ and $v = w_- t + \phi_-$, and using Euler's formula, eq. 20 can be rewritten as:

$$f(t) = A_+ \left(\cos(u) - i\sin(u)\right) + A_- \left(\cos(v) - i\sin(v)\right)$$

The physical coordinates can then be found as $x(t) = \operatorname{Re} f(t)$ and $y(t) = \operatorname{Im} f(t)$. Giving us:

$$\begin{aligned} x(t) &= A_+ \cos(u) + A_- \cos(v) \\ y(t) &= -A_+ \sin(u) - A_- \sin(v) \end{aligned}$$

Since our xy-plane is a circle, the distance from the origin can be expressed as the radius $R = \sqrt{x^2 + y^2}$. Substituting for x and y we have:

$$R = \sqrt{(A_+ \cos(u) + A_- \cos(v))^2 + (-A_+ \sin(u) - A_- \sin(v))^2}$$

After expanding and rearranging we have:

$$R = \sqrt{A_+^2(\cos^2(u) + \sin^2(u)) + A_-^2(\cos^2(v) + \sin^2(v)) + 2A_+A_-(cos(u)\cos(v) + \sin(u)\sin(v))}$$

Recognizing that $cos^2(u) + \sin^2(u) = 1$ and $cos(u)\cos(v) + \sin(u)\sin(v) = \cos(u - v)$ this can be simplified to:

$$R = \sqrt{A_+^2 + A_-^2 + 2A_+A_- \cos(u - v)}$$

We know that cos is a function with an upper bound of 1 and lower bound of -1. The possible bounds for R are consequently:

$$\begin{aligned} R_+ &= \sqrt{A_+^2 + 2A_+A_- + A_-^2} = A_+ + A_- \\ R_- &= \sqrt{A_+^2 - 2A_+A_- + A_-^2} = |A_+ - A_-| \end{aligned}$$

The algorithms

Algorithm 1 Forward Euler method

```
procedure MIDPOINT RULE(f, a, b, n)
    I ← 0                            ▷ Initialize the integral variable
    h ← (b − a)/n                    ▷ Compute the interval length
    for i = 1, 2, . . . , n do
        x ← a + (i − 1/2)h           ▷ Assign x to the midpoint
        I ← I + f(x)                 ▷ Add contribution to integral
    I ← Ih                           ▷ Finalize the computation
```

Algorithm 2 Runge-Kutta fourth order method

```
procedure MIDPOINT RULE(f, a, b, n)
    I ← 0                            ▷ Initialize the integral variable
    h ← (b − a)/n                    ▷ Compute the interval length
    for i = 1, 2, . . . , n do
        x ← a + (i − 1/2)h           ▷ Assign x to the midpoint
        I ← I + f(x)                 ▷ Add contribution to integral
    I ← Ih                           ▷ Finalize the computation
```

III. RESULTS

IV. DISCUSSION

Note that you are free to merge the presentation and discussion of the results into a single section of your report. This can in many cases lead to a more fluid presentation. If you do this, we recommend you use "Results and discussion" or similar for the section title.

From table **??**, we note that our implementation reproduces the analytical results to four digits precision when the integration range is divided into $n = 10^4$ subintervals. This indicates that that our implementation of the algorithm is correct.

From figure **??**, we see that $\log_{10}(\epsilon)$ decreases linearly with $\log_2(n)$. From this, it should be possible to extract the convergence rate of our implementation of the midpoint rule. From a theoretical point of view we know that the midpoint rule should have a convergence rate of $\mathcal{O}(h^2)$. To properly verify our implementation, we should have estimated the convergence rate from our results and compared it to this theoretical rate. Without doing so, we cannot know that the our implementation of the algorithm is correct, even though we have seen that the numerical approximation converges to the correct answer in **??**.

Although this is a somewhat silly example, please note the following: We are to-the-point in our discussion of the results, and we only make strong claims about what we are actually certain about. In the discussion it is important to try to be as concise as possible — long paragraphs that only make very general points are typically of limited interest. Note that we also highlight aspects of our analysis that could have been improved and that might form a topic for future work.

V. CONCLUSION

In this section we state three things in a concise manner: what we have done, what we have found, and what should or could be done in the future.

We have investigated an implementation of the midpoint rule for numerical integration. As a first validation test we have checked that our implementation of the method reproduces the analytical result for the definite integral of $f(x) = x^3$ on $x \in [0, 1]$, achieving a four-digit precision when the integration range is divided into $n = 10^4$ subintervals. Furthermore, we have presented results for how the relative error of the method varies with the number of subintervals. To use these results to extract a precise estimate for the convergence rate of the method remains a topic for future work. As such, while our implementation of the midpoint rule has passed the initial validation tests, more work is needed to fully assess the validity of the implementation.