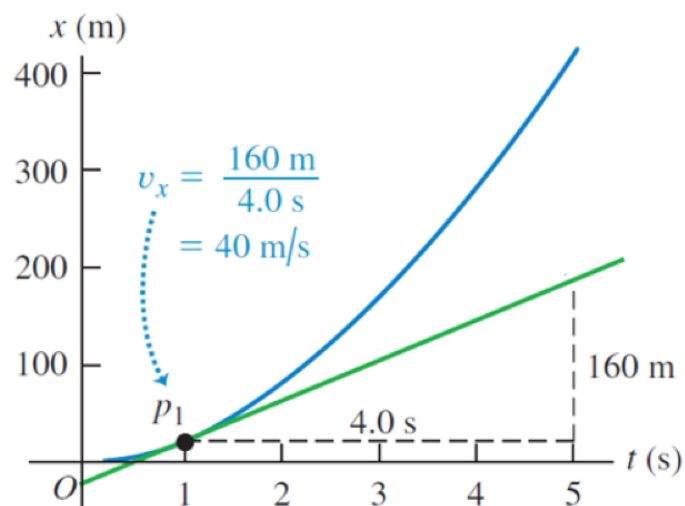


小结

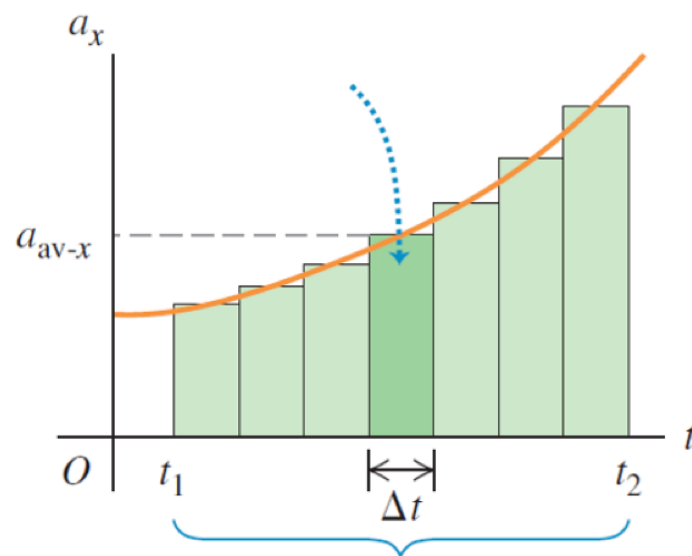
$$v_x = \frac{dx}{dt}$$

$$a_x = \frac{dv_x}{dt} = \frac{d^2x}{dt^2}$$



$$v_x = v_0 + \int_0^t a_x dt$$

$$x = x_0 + \int_0^t v_x dt$$



惯性导航系统



$$v_{2x} - v_{1x} = \int_{v_{1x}}^{v_{2x}} dv_x = \int_{t_1}^{t_2} a_x dt$$

$$x_2 - x_1 = \int_{x_1}^{x_2} dx = \int_{t_1}^{t_2} v_x dt$$

$$v_x = v_{0x} + \int_0^t a_x dt$$

$$x = x_0 + \int_0^t v_x dt$$

记录飞机的加速度，并根据起飞时初始的位置和速度，利用加速度的记录算出飞机在空中的位置和速度。

标量与矢量

标量(Scalar): 只有大小, 没有方向
温度(T), 质量(M), 体积(V)

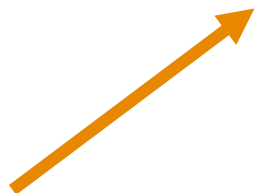
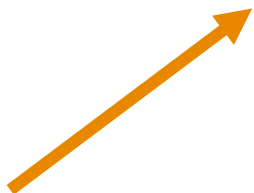


矢量(Vector): 既有大小, 也有方向

力 (\vec{f}), 位置矢量 (\vec{r}), 速度 (\vec{v}), 风速

\vec{A}

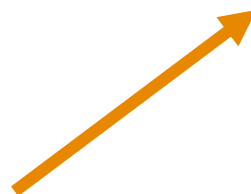
\vec{B}



$$\vec{A} = \vec{B}$$

\vec{A}

\vec{B}

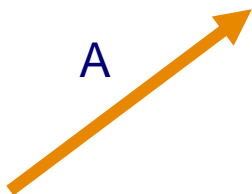


$$\vec{A} = -\vec{B}$$

矢量

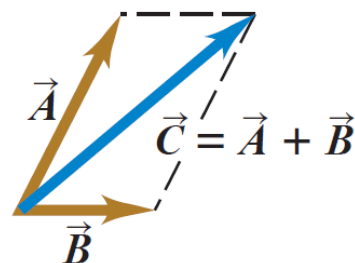
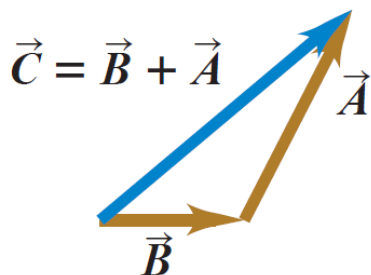
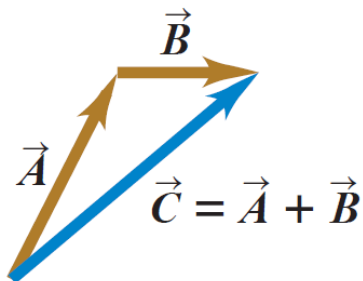
矢量长度

$$A = |\vec{A}|$$



矢量加法 $\vec{C} = \vec{A} + \vec{B}$

$$\vec{A} + \vec{B} = \vec{B} + \vec{A}$$



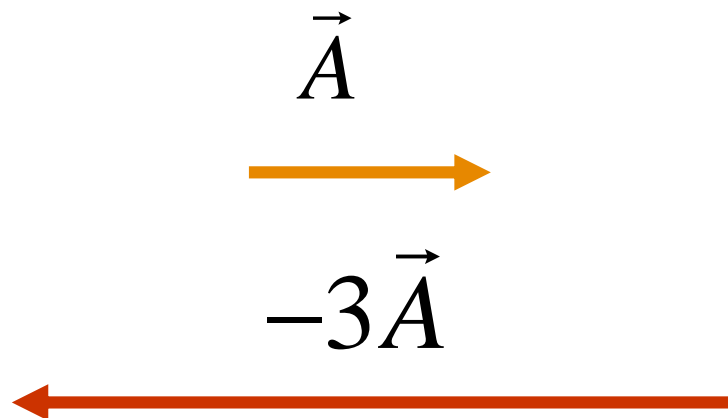
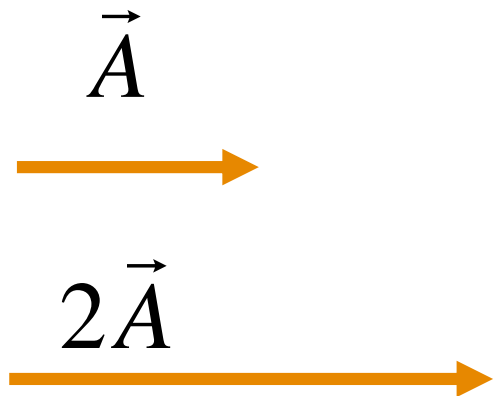
矢量减法

$$\vec{A} - \vec{B} = \vec{A} + (-\vec{B})$$

A diagram illustrating the subtraction of vector \vec{B} from vector \vec{A} . On the left, a horizontal vector \vec{A} pointing left is followed by a minus sign and a vector \vec{B} pointing down and to the left. This is set equal to a horizontal vector \vec{A} pointing left followed by a plus sign and a vector $-\vec{B}$ pointing up and to the right.

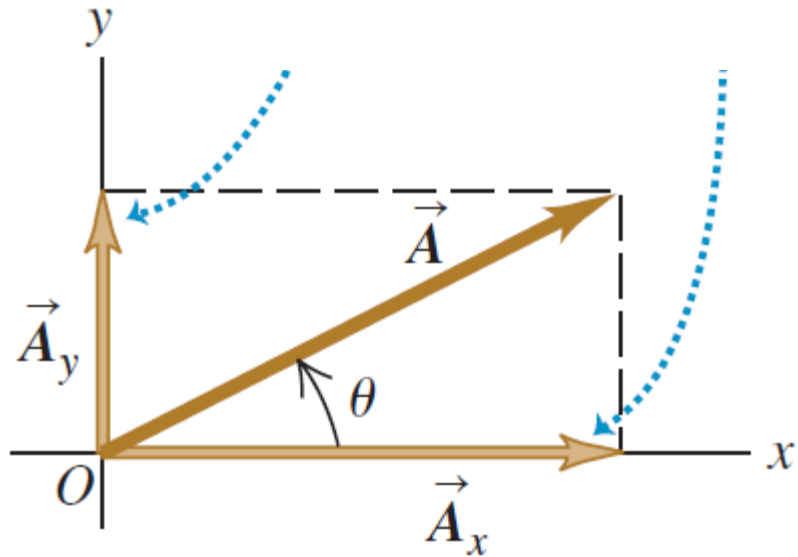
A diagram illustrating the triangle rule for vector subtraction. On the left, a triangle is formed by vector \vec{A} (bottom horizontal, pointing left), vector $-\vec{B}$ (left side, pointing up and right), and a blue vector $\vec{A} + (-\vec{B})$ (right side, pointing down and right). Below the triangle, the text $= \vec{A} - \vec{B}$ is written. This is set equal to another triangle on the right, which has vector \vec{A} (bottom horizontal, pointing left), vector \vec{B} (left side, pointing down and left), and a blue vector $\vec{A} - \vec{B}$ (right side, pointing down and right).

矢量与标量相乘



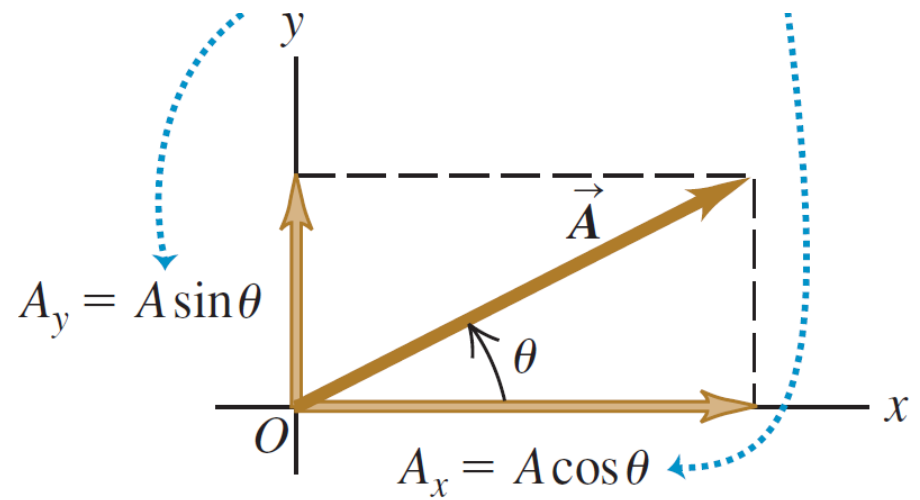
矢量分量

矢量 \vec{A} 的分量



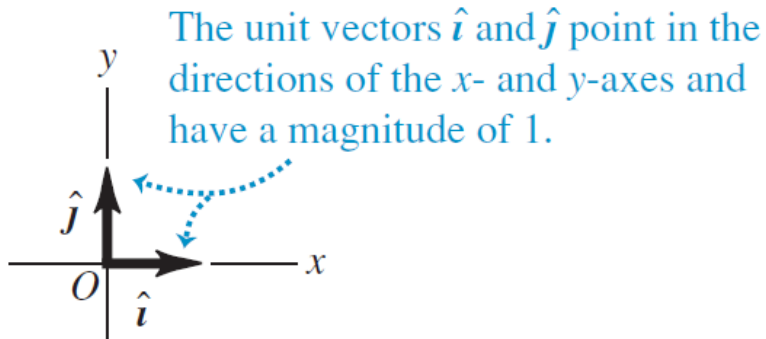
$$\vec{A} = \vec{A}_x + \vec{A}_y$$

矢量 \vec{A} 的分量



单位矢量

(a)

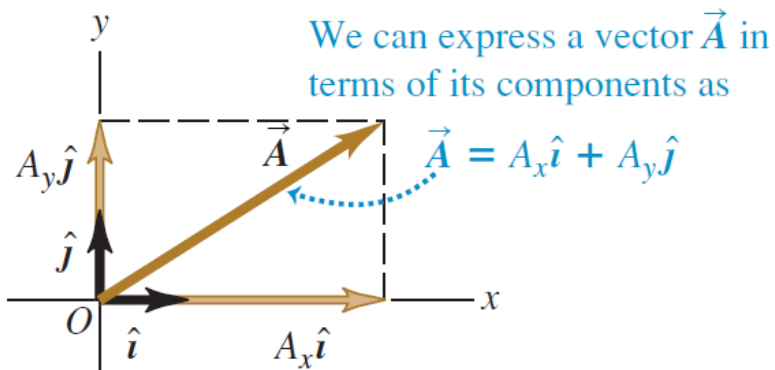


$$\vec{A}_x = A_x \hat{i}$$

$$\vec{A}_y = A_y \hat{j}$$

$$\vec{A} = A_x \hat{i} + A_y \hat{j}$$

(b)



单位矢量

矢量相加

$$\vec{A} = A_x \hat{i} + A_y \hat{j}$$

$$\vec{B} = B_x \hat{i} + B_y \hat{j}$$

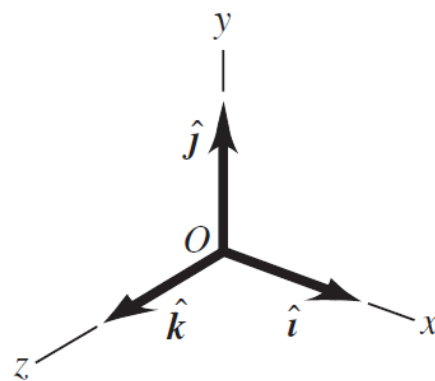
$$\vec{R} = \vec{A} + \vec{B}$$

$$= (A_x \hat{i} + A_y \hat{j}) + (B_x \hat{i} + B_y \hat{j})$$

$$= (A_x + B_x) \hat{i} + (A_y + B_y) \hat{j}$$

$$= R_x \hat{i} + R_y \hat{j}$$

三维单位矢量



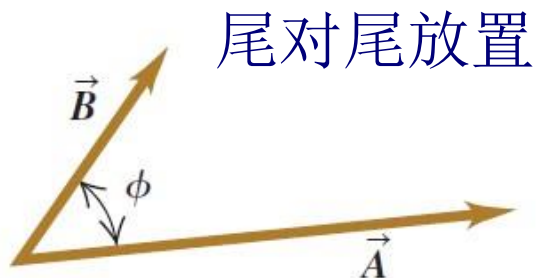
$$\vec{A} = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$

$$\vec{B} = B_x \hat{i} + B_y \hat{j} + B_z \hat{k}$$

$$\begin{aligned}\vec{R} &= (A_x + B_x) \hat{i} + (A_y + B_y) \hat{j} + (A_z + B_z) \hat{k} \\ &= R_x \hat{i} + R_y \hat{j} + R_z \hat{k}\end{aligned}$$

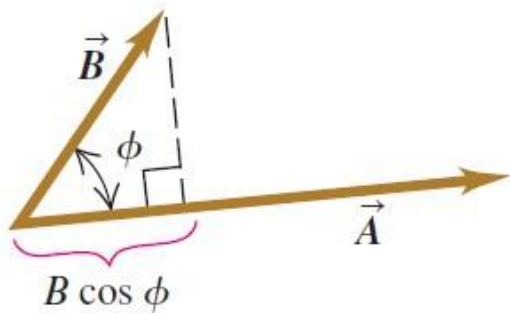
矢量点乘

(a)

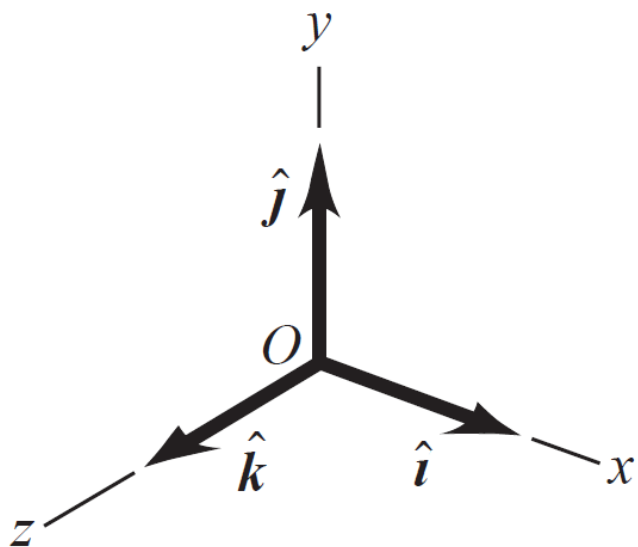


$$\vec{A} \cdot \vec{B} = AB \cos \phi = |\vec{A}| |\vec{B}| \cos \phi$$

(b)



矢量点乘



$$\hat{i} \cdot \hat{i} = \hat{j} \cdot \hat{j} = \hat{k} \cdot \hat{k} = (1)(1) \cos 0^\circ = 1$$

$$\hat{i} \cdot \hat{j} = \hat{i} \cdot \hat{k} = \hat{j} \cdot \hat{k} = (1)(1) \cos 90^\circ = 0$$

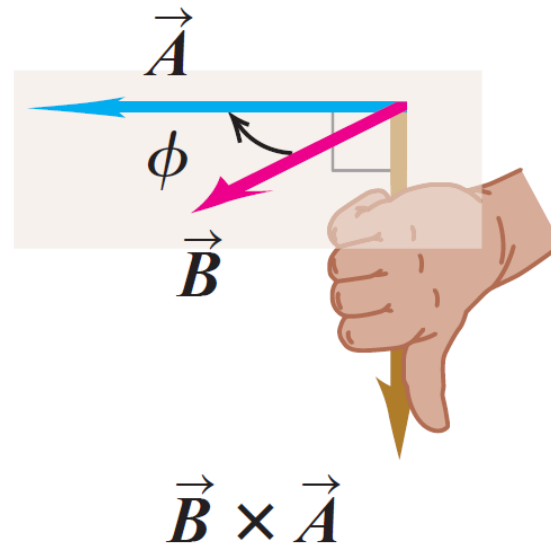
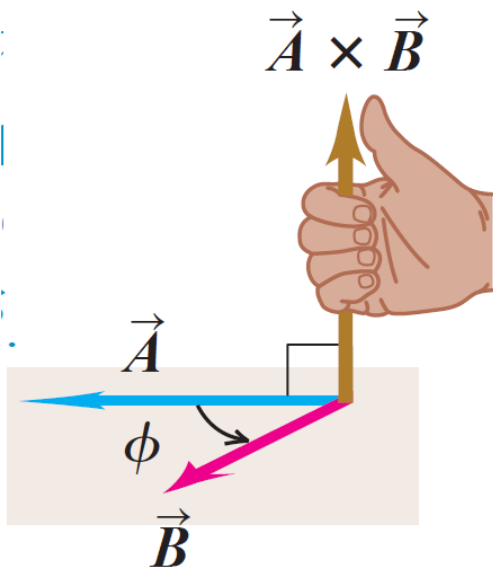
$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$

$$\begin{aligned}\vec{A} \cdot \vec{B} &= (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) \cdot (B_x \hat{i} + B_y \hat{j} + B_z \hat{k}) \\&= A_x \hat{i} \cdot B_x \hat{i} + A_x \hat{i} \cdot B_y \hat{j} + A_x \hat{i} \cdot B_z \hat{k} \\&\quad + A_y \hat{j} \cdot B_x \hat{i} + A_y \hat{j} \cdot B_y \hat{j} + A_y \hat{j} \cdot B_z \hat{k} \\&\quad + A_z \hat{k} \cdot B_x \hat{i} + A_z \hat{k} \cdot B_y \hat{j} + A_z \hat{k} \cdot B_z \hat{k} \\&= A_x B_x \hat{i} \cdot \hat{i} + A_x B_y \hat{i} \cdot \hat{j} + A_x B_z \hat{i} \cdot \hat{k} \\&\quad + A_y B_x \hat{j} \cdot \hat{i} + A_y B_y \hat{j} \cdot \hat{j} + A_y B_z \hat{j} \cdot \hat{k} \\&\quad + A_z B_x \hat{k} \cdot \hat{i} + A_z B_y \hat{k} \cdot \hat{j} + A_z B_z \hat{k} \cdot \hat{k}\end{aligned}$$

矢量叉乘

$$\vec{C} = \vec{A} \times \vec{B}$$

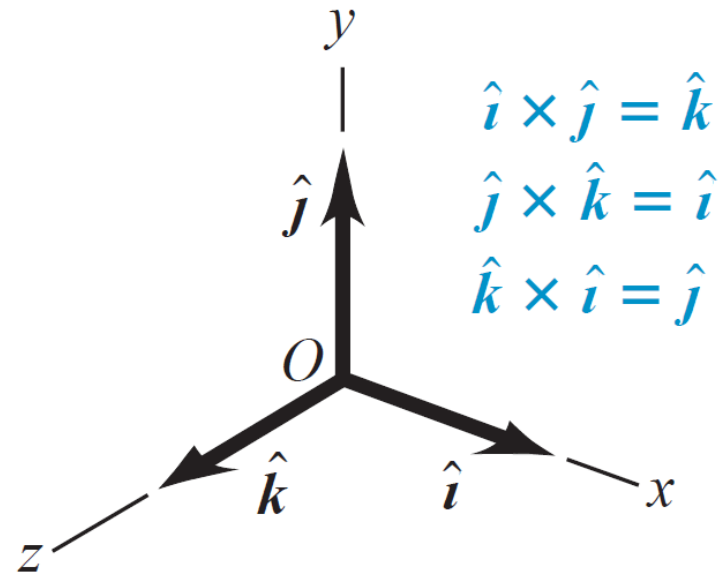
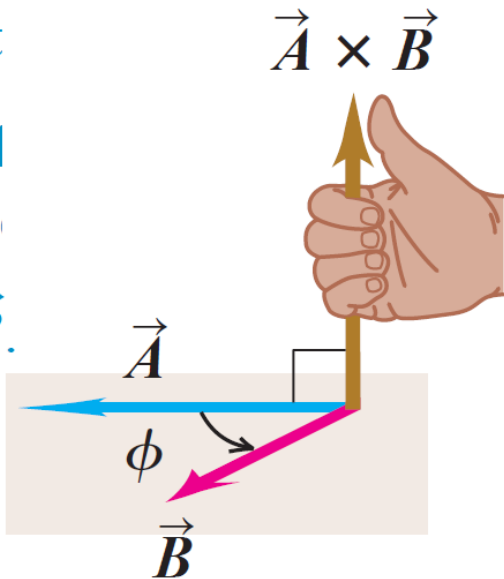
$$C = AB \sin \phi$$



$$\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$

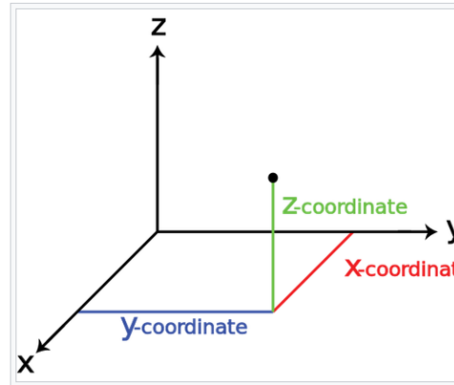
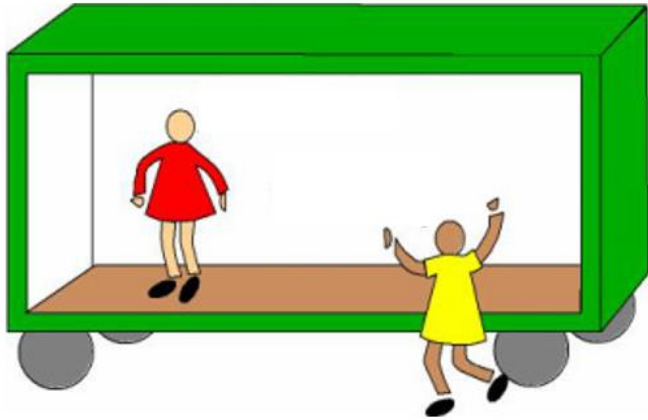
矢量叉乘

$$\vec{A} \times \vec{B} = (A_y B_z - A_z B_y) \hat{i} + (A_z B_x - A_x B_z) \hat{j} + (A_x B_y - A_y B_x) \hat{k}$$

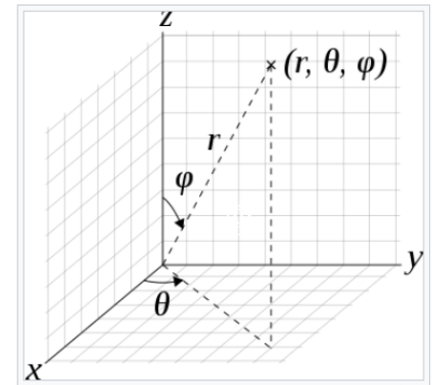


$$\vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$

参照系与坐标系



直角坐标系



球坐标系

车为参照系：车上人静止

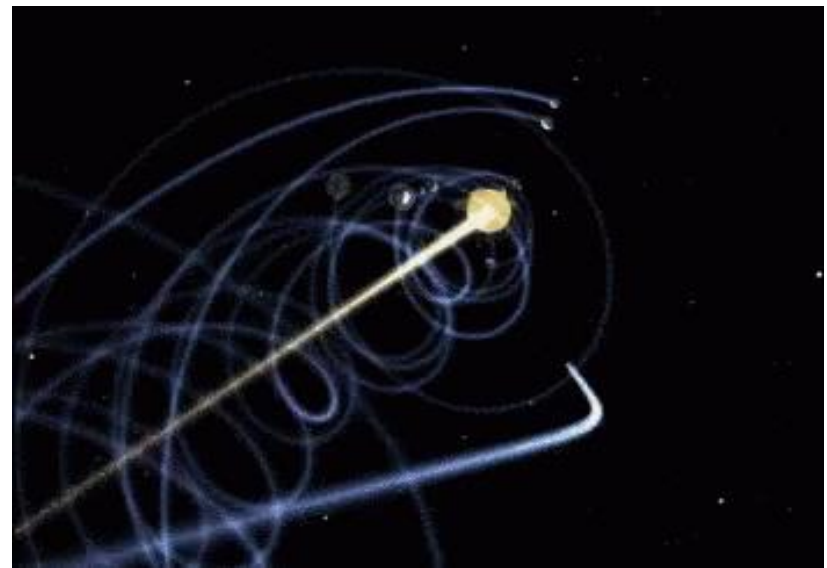
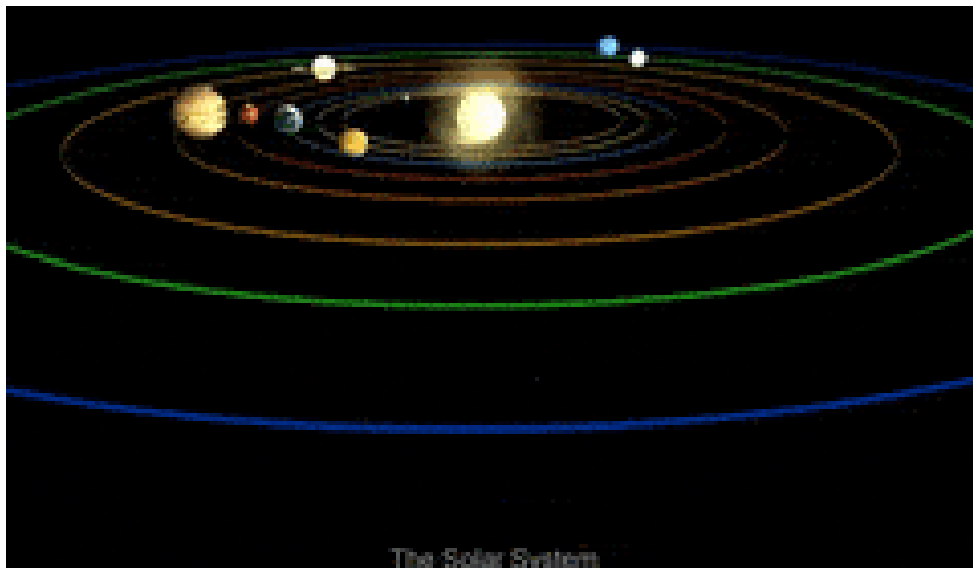
地面为参照系：车上人运动

坐标系：参考系中选择一点为原点，取通过原点并标有长度的线为坐标轴，用于定量确定物体在参考系中的位置。

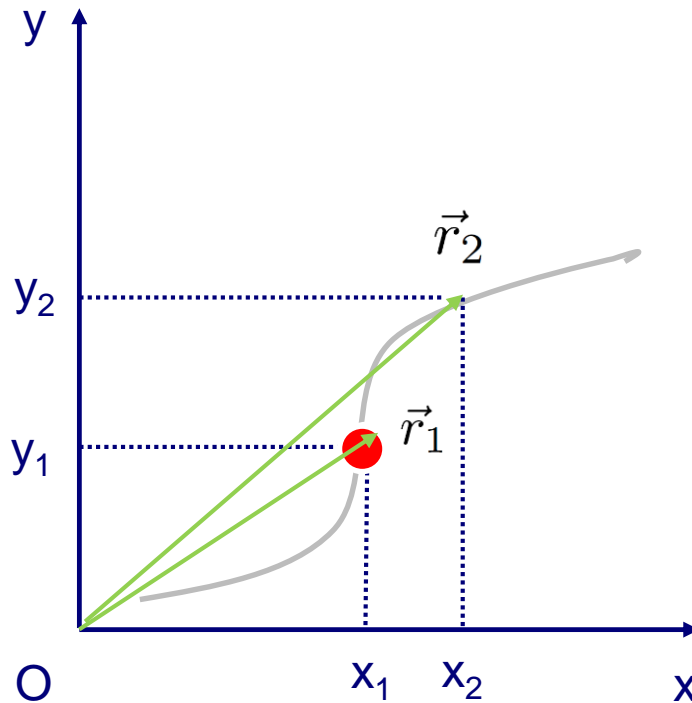
研究运动需要选择一定的**参照系**

不同参照系下，反映运动的关系不同

太阳系的运动



位置矢量



$$\vec{r}_1 = x_1 \hat{i} + y_1 \hat{j}$$

$$\vec{r} = x \hat{i} + y \hat{j}$$

位置1: (x_1, y_1)

位置2: (x_2, y_2)

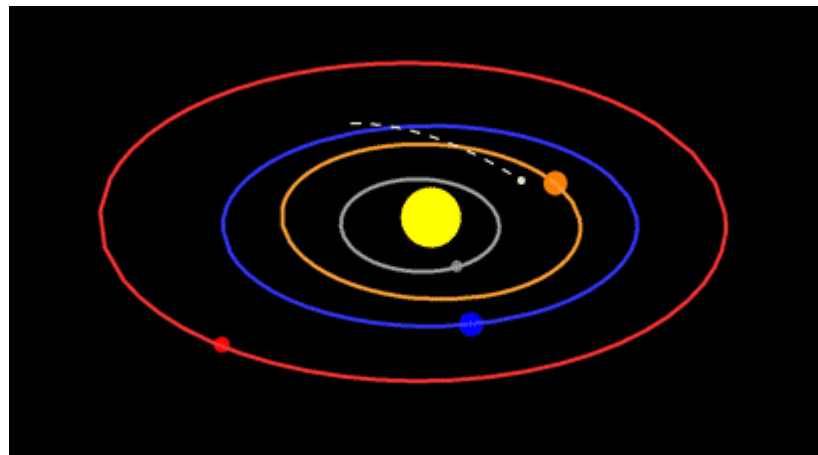
$$r = |\vec{r}| = \sqrt{(x^2 + y^2)}$$

运动: $\vec{r} = \vec{r}(t)$

轨道方程

$$\vec{r} = \vec{r}(t) = x(t)\hat{i} + y(t)\hat{j} + z(t)\hat{k}$$

$$\begin{cases} x = x(t) \\ y = y(t) \\ z = z(t) \end{cases}$$



消去时间 t 得到轨道方程:

x, y, z 变量之间的关系, 可以体现系统运动的特征

轨道方程

已知，在(x,y)平面内质点轨道方程为

$$x(t) = a \cos \omega t$$

$$y(t) = b \sin \omega t$$

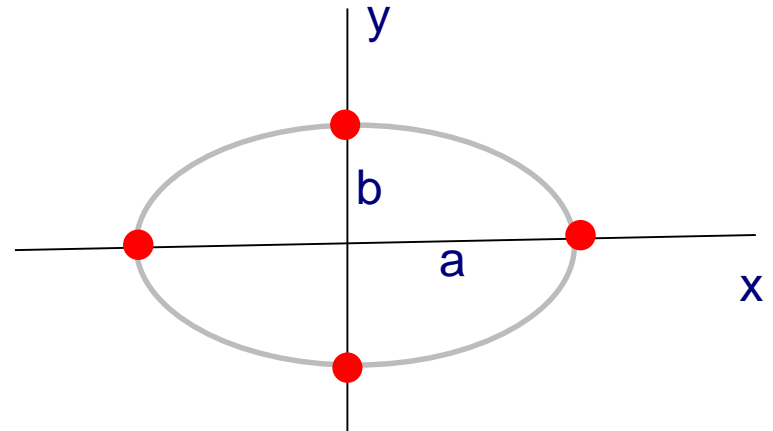
试求其轨道形态及特征。

$$t = 0, x = a, y = 0$$

$$t = \pi / 2\omega, x = 0, y = b$$

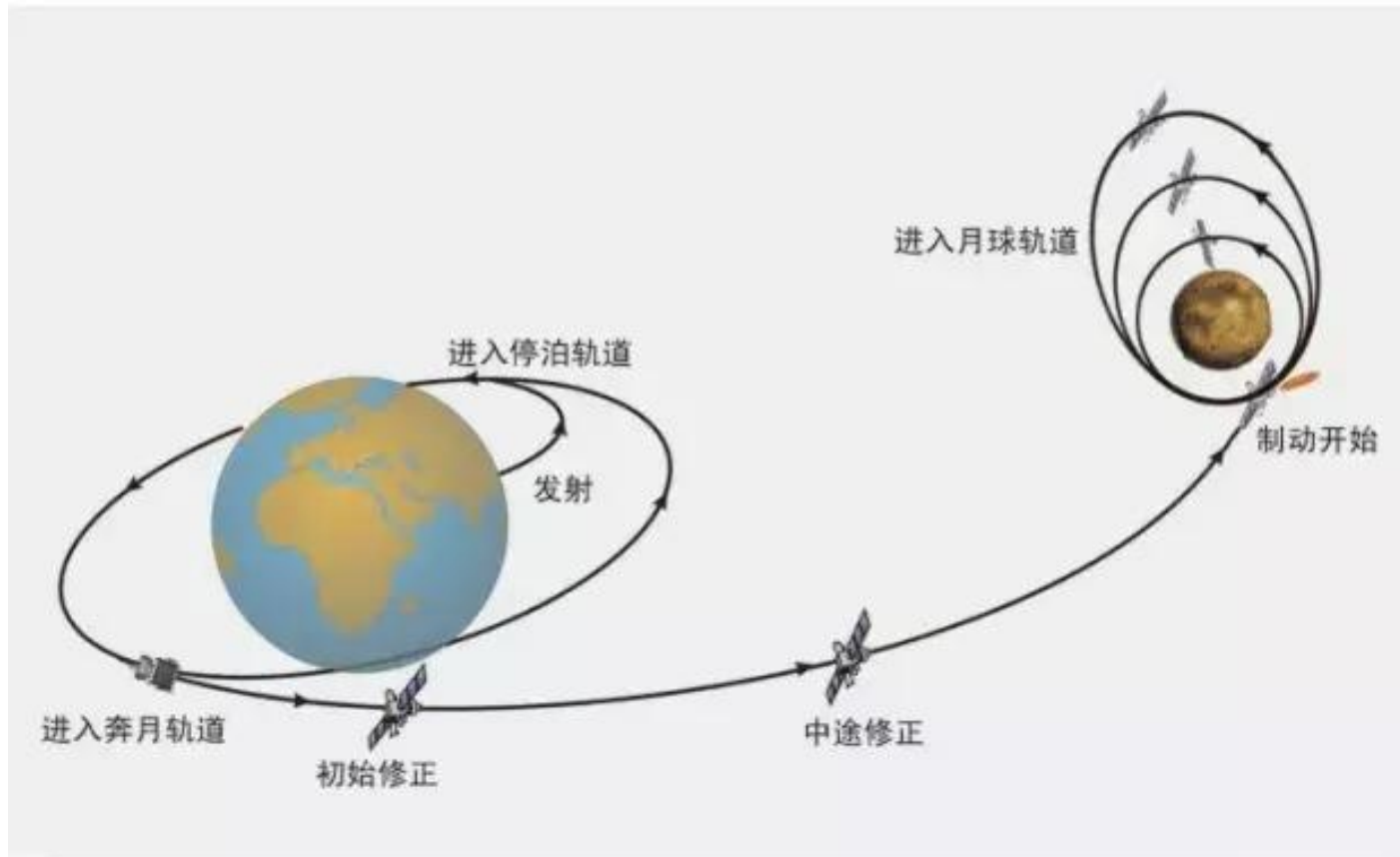
$$t = \pi / \omega, x = -a, y = 0$$

$$t = 3\pi / 2\omega, x = 0, y = -b$$

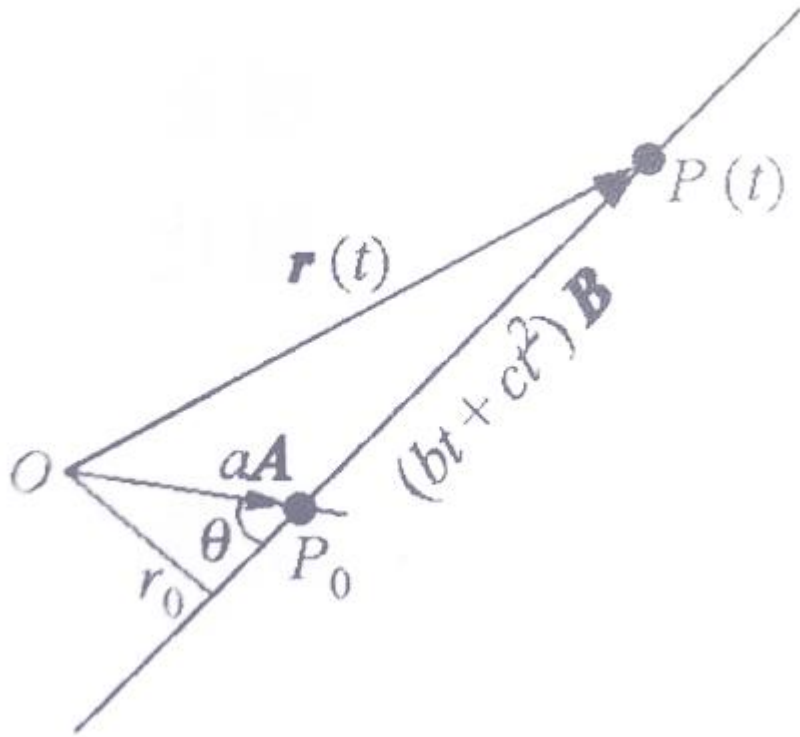


$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

嫦娥二号轨道



轨道方程

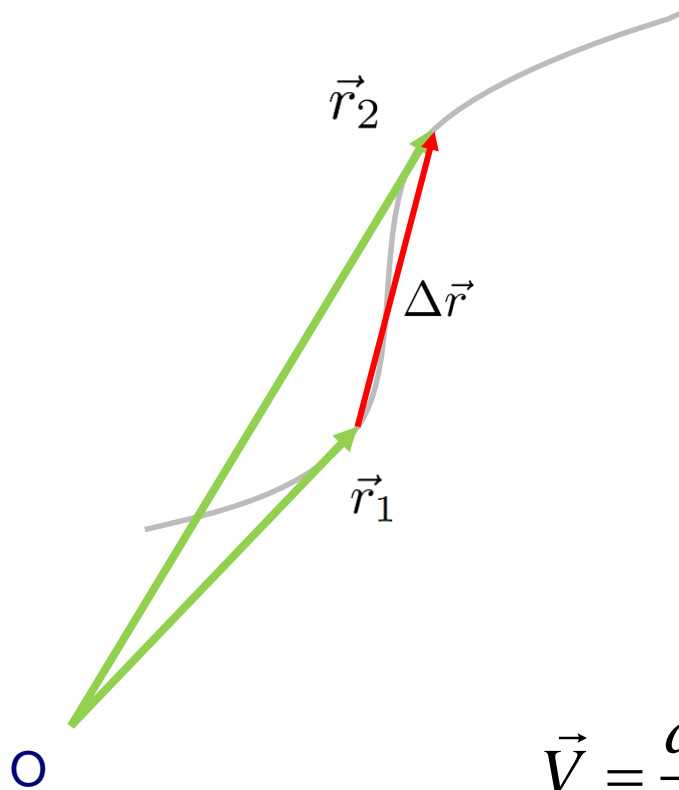


$$\vec{r}(t) = a\vec{A} + b(t + ct^2)\vec{B}$$

轨迹方程为一条直线

速度

速度也是矢量！



$$\vec{V} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{r}}{\Delta t} = \frac{d\vec{r}}{dt}$$

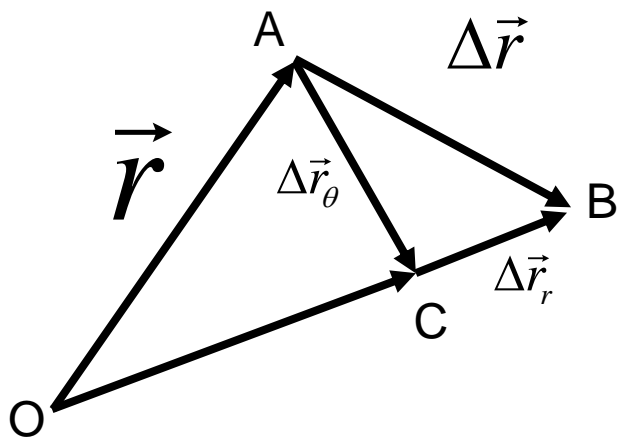
$$\Delta \vec{r} = \vec{r}_2 - \vec{r}_1$$

速度分量的形式

$$\vec{r} = x\vec{i} + y\vec{j}$$

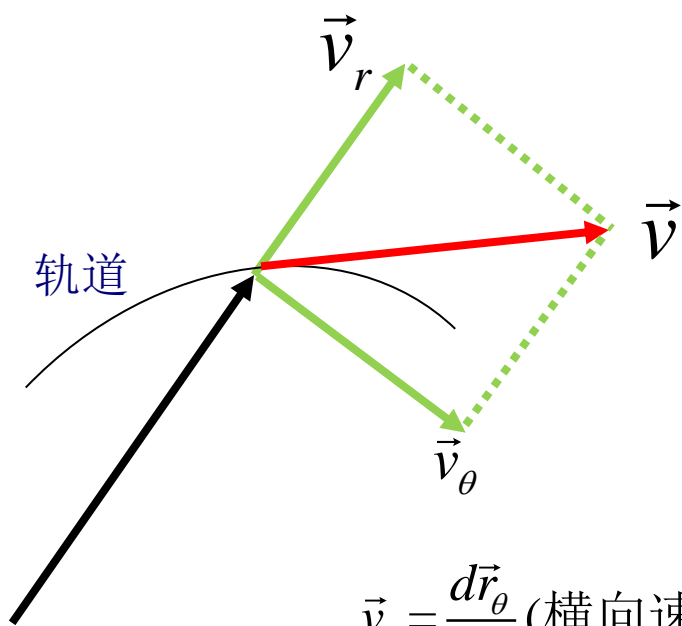
$$\vec{V} = \frac{d\vec{r}}{dt} = \frac{dx}{dt}\vec{i} + \frac{dy}{dt}\vec{j} = v_x\vec{i} + v_y\vec{j}$$

横向速度与径向速度



$$\Delta\vec{r} = \Delta\vec{r}_\theta + \Delta\vec{r}_r$$

横向位移 径向位移

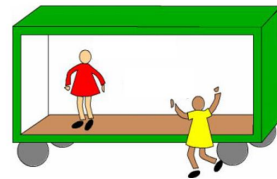


$$\vec{v} = \vec{v}_\theta + \vec{v}_r$$

$$\vec{v}_\theta = \frac{d\vec{r}_\theta}{dt} \text{ (横向速度)}$$

$$\vec{v}_r = \frac{d\vec{r}_r}{dt} \text{ (径向速度)}$$

牵连速度



参照系 K' 相对于参照系 K 以速度 u 移动
质点在 K' 参照系中以速度 v' 移动，求质点
在 K 参照系中的速度 v 。

在 K' 参照系中：质点的位置矢量与速度为

$$\vec{r}' \text{ 与 } \vec{v}' = \frac{d\vec{r}'}{dt'}$$

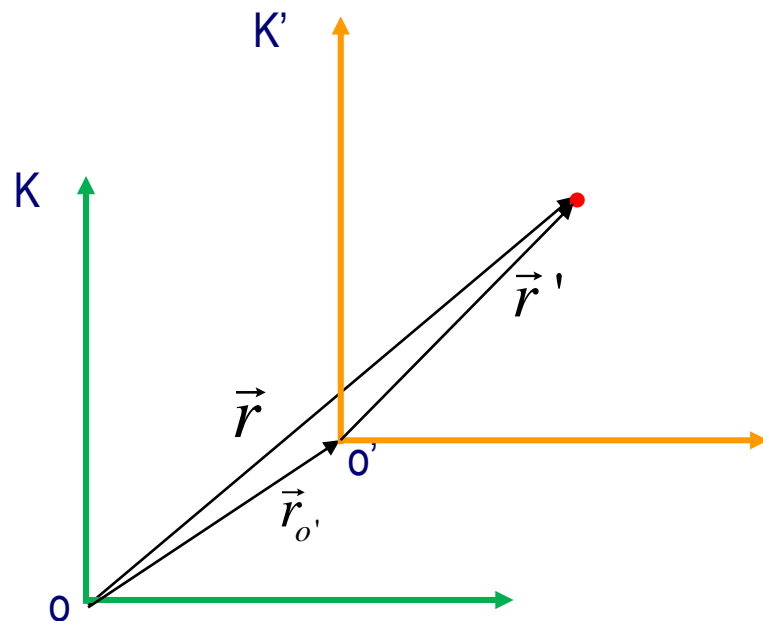
在 K 参照系中：质点的位置矢量与速度为

$$\vec{r} \text{ 与 } \vec{v} = \frac{d\vec{r}}{dt}$$

$$\vec{r} = \vec{r}_{o'} + \vec{r}'$$

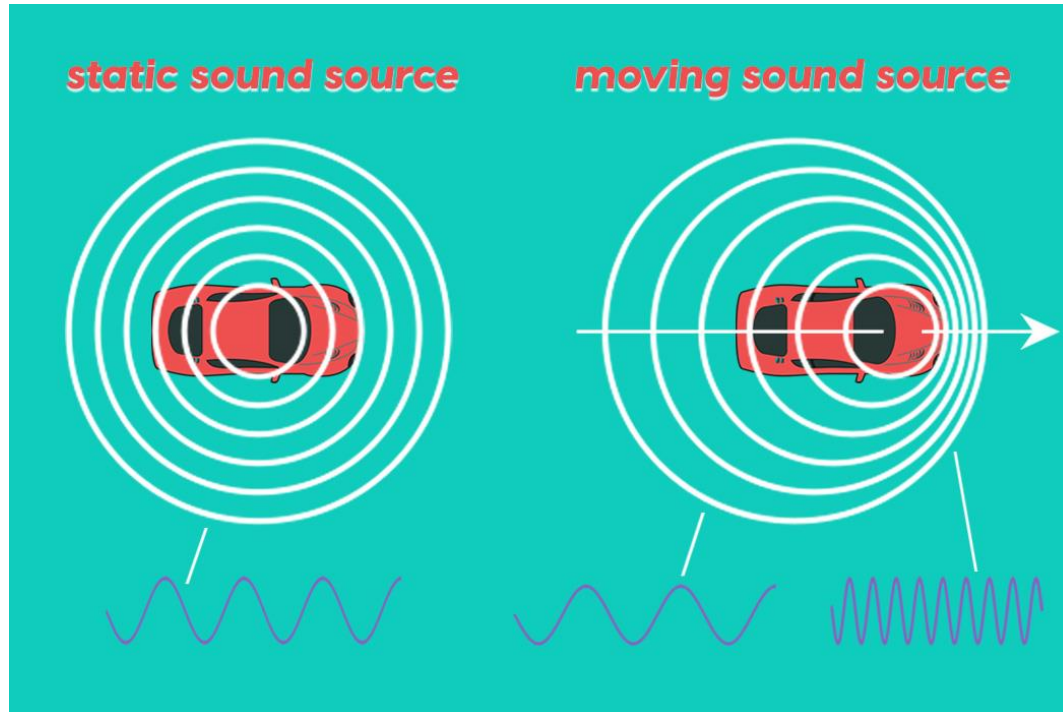
所以：

$$\vec{v}(t) = \frac{d\vec{r}}{dt} = \frac{d(\vec{r}_{o'} + \vec{r}')}{dt} = \vec{u}(t) + \vec{v}'(t)$$

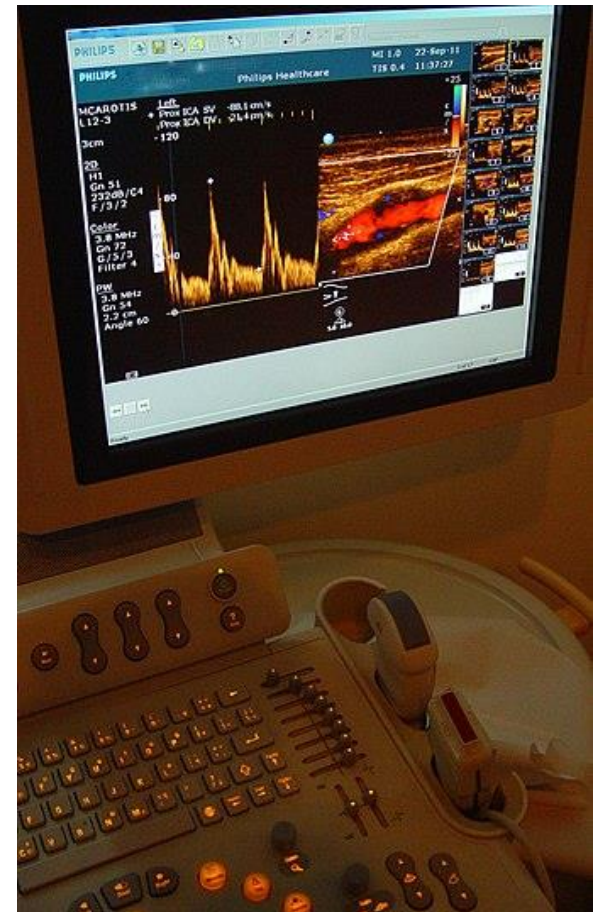


1. 仅适用于低速牛顿力学体系
2. 如果转动时， u 随参考点 o' 不同而变化

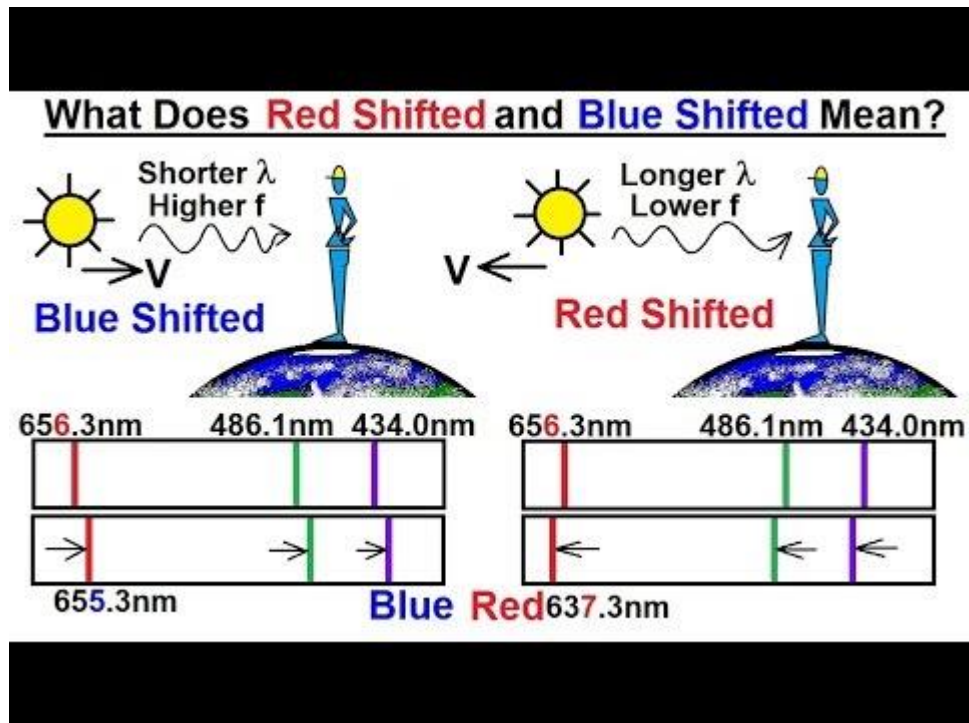
多普勒效应



源相对于接收器运动，频率变化



宇宙的红移



原子发射谱或吸收谱

谱线位置发生了移动

由多普勒效应：红移 恒星远离我们



(b)



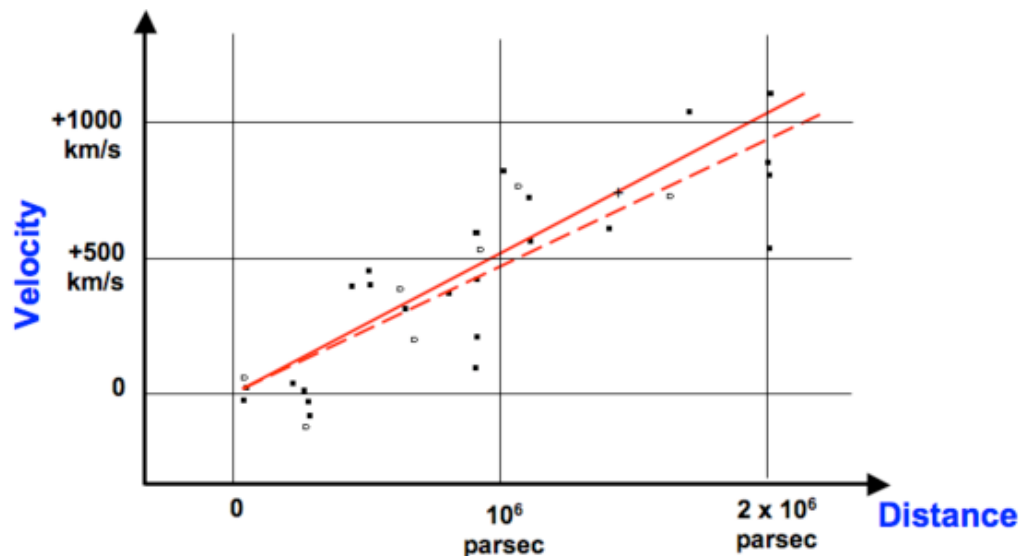
哈勃-勒梅特定律

$$v = H_0 r$$

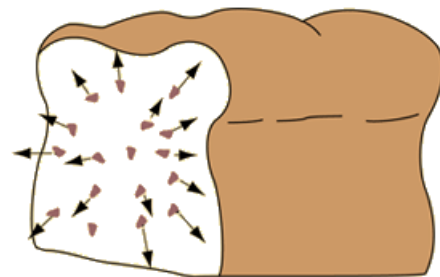
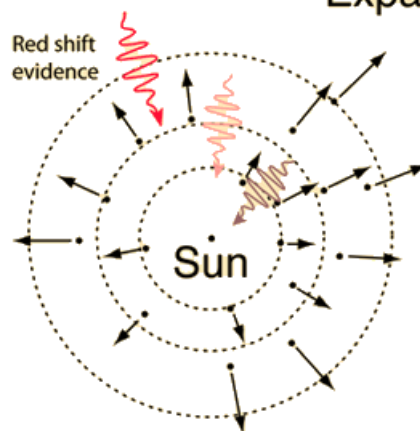
H_0 : 哈勃常数

v : 退行速度

r : 距离



Expanding universe

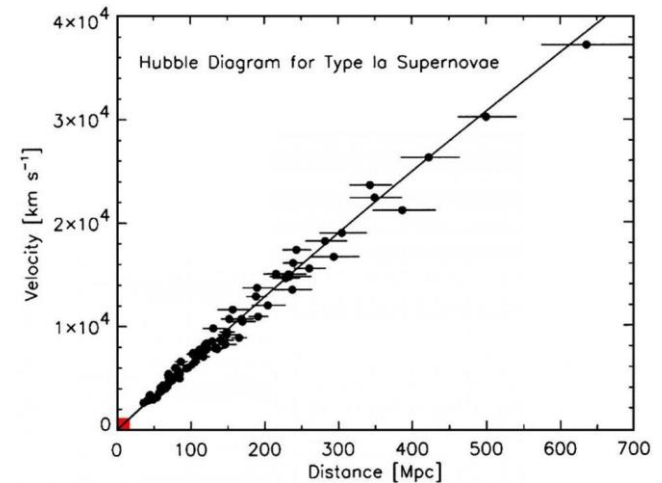
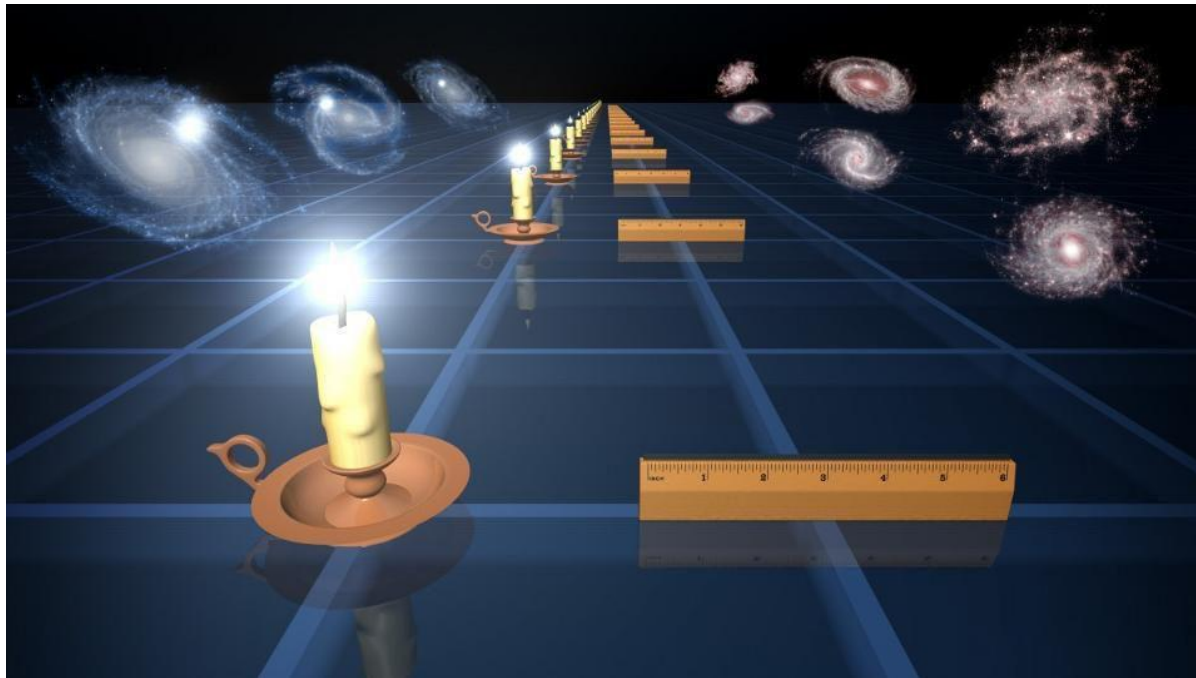


Every raisin in a rising loaf of raisin bread will see every other raisin expanding away from it.

$$H = 71 \text{ km/s/Mpc}$$

宇宙的年龄 $\sim \frac{1}{H_0}$

哈勃常数

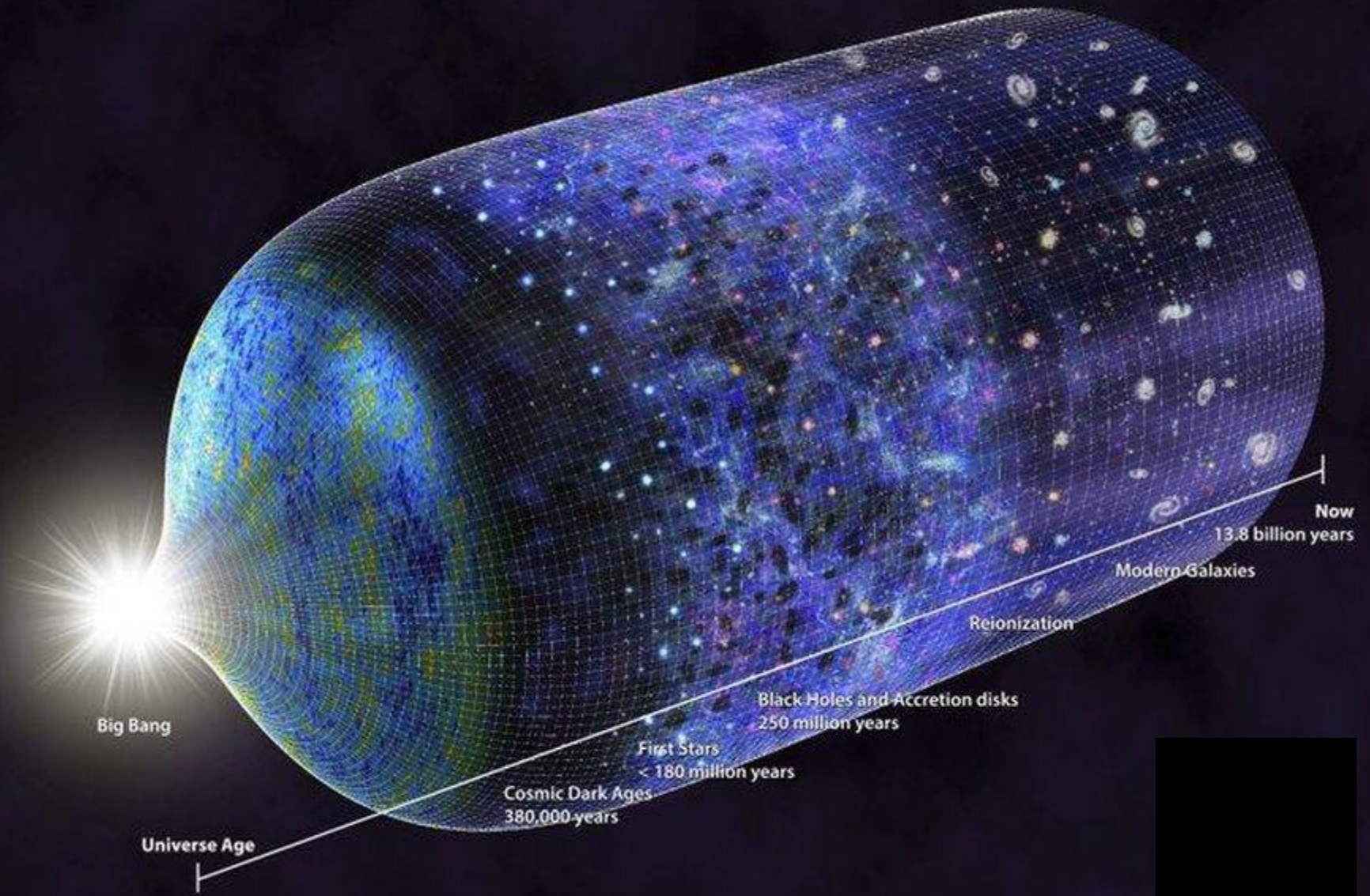


$$v = H_0 r$$

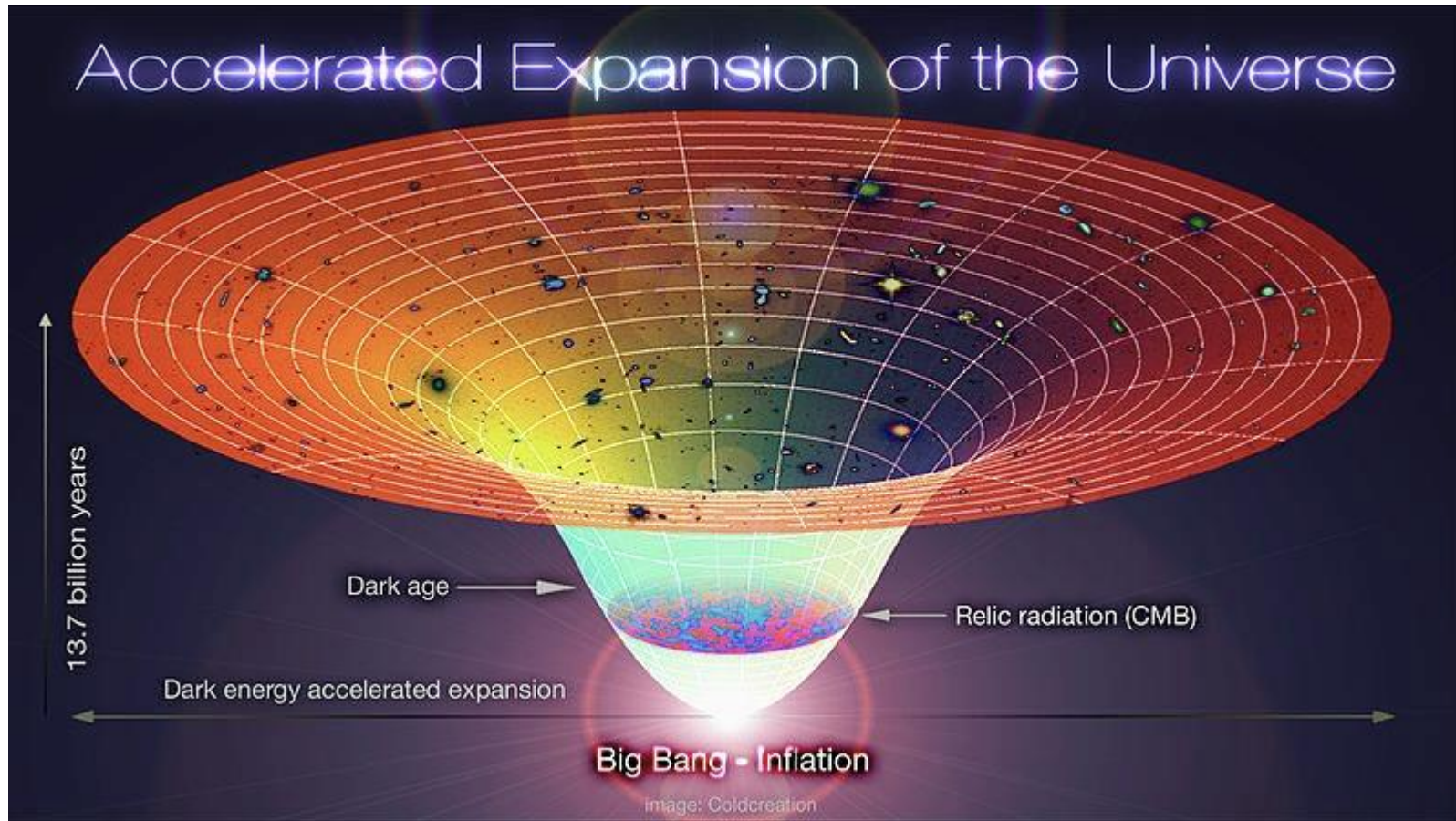
距离 r 的测量：标准烛光法。特定的星体发出的光的亮度是一定的，随距离衰减。

v ：根据红移测得

宇宙的演化

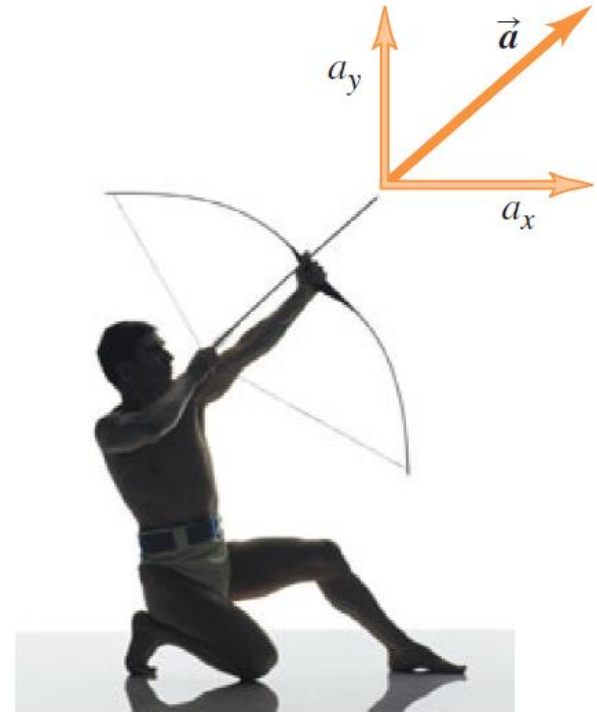


宇宙加速膨胀



加速度

$$\vec{a} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{v}}{\Delta t} = \frac{d\vec{v}}{dt} = \frac{d^2 \vec{r}}{dt^2}$$



$$\vec{F} = m\vec{a}$$

$$F_x = m(dv_x/dt) = m(d^2x/dt^2) = ma_x,$$

$$F_y = m(dv_y/dt) = m(d^2y/dt^2) = ma_y,$$

$$F_z = m(dv_z/dt) = m(d^2z/dt^2) = ma_z.$$