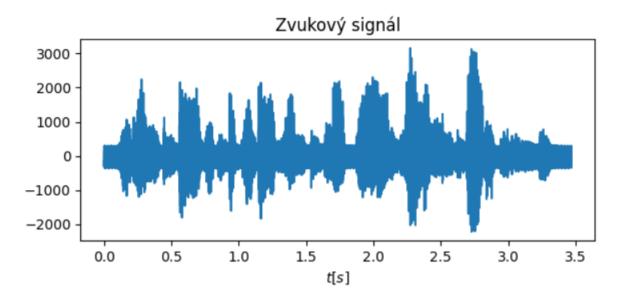
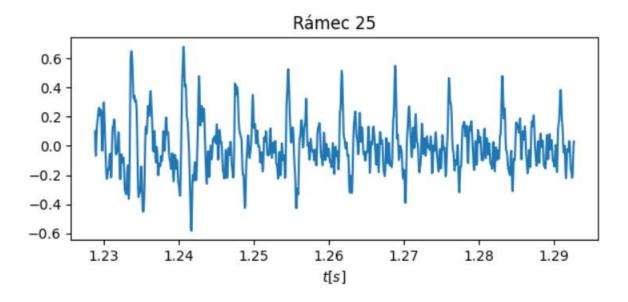
1. Základy

Vstupný z 55501 vzorkov a 3.4688125 sekundy, minimálna hodnota signálu je -2220 a maximálna hodnota signálu je 3156.



2. Předzpracování a rámce

Zobrazujem rámec 25 už ustredneného a znormalizovaného signálu.

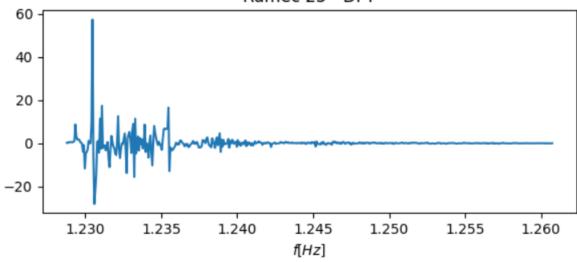


3. DFT

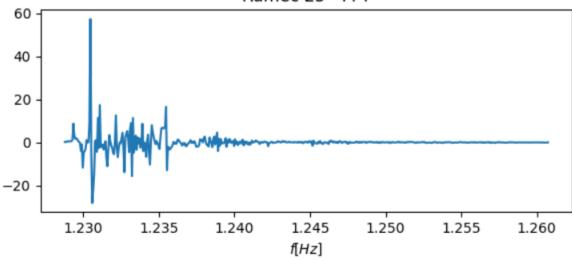
Implementácia DFT

```
def dft(x):
    dft = np.ndarray((1024))
    for j in range(0, 1024):
        temp = 0
        for k in range(0, 1024):
            temp += x[k] * np.exp(-1j * ((2 * np.pi) / 1024) * j * k)
        dft[j] = temp
    return dft
```

Rámec 25 - DFT

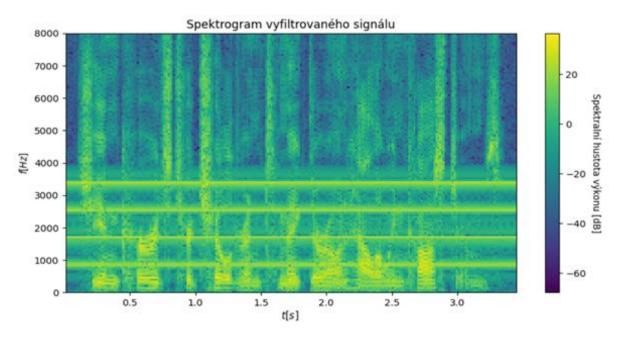


Rámec 25 - FFT



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4. Spektrogram



5. Určení rušivých frekvencí

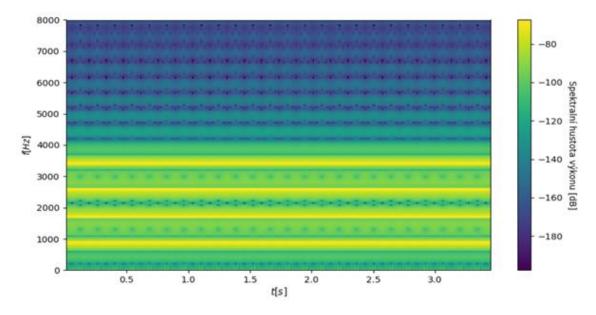
Rušivé frekvencie som určil odčítaním zo spektogramu. (f1 = 840Hz, f2 = 1680Hz, f3 = 2520Hz, f4 = 3360Hz). Rušivé cosínusovky sú harmonicky vztažené.

6. Generování signal

```
y1 = np.cos(np.arange(pocet_vzorkov) * f1 * np.pi * 2 / fs)
y2 = np.cos(np.arange(pocet_vzorkov) * f2 * np.pi * 2 / fs)
y3 = np.cos(np.arange(pocet_vzorkov) * f3 * np.pi * 2 / fs)
y4 = np.cos(np.arange(pocet_vzorkov) * f4 * np.pi * 2 / fs)
y = (y1 + y2 + y3 + y4) / 192
```

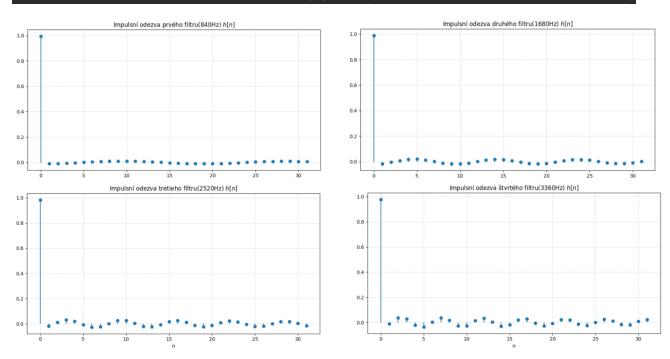
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7. Čisticí filtr

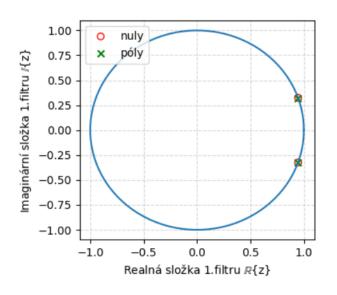
Použil som 4 filtre typu pásmová zádrž. (filter1 má koeficienty a1,b1; filter2 má koeficienty a2, b2; filter3 má koeficienty a3, b3; filter4 má koeficienty a4, b4)

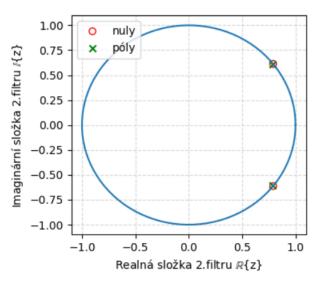


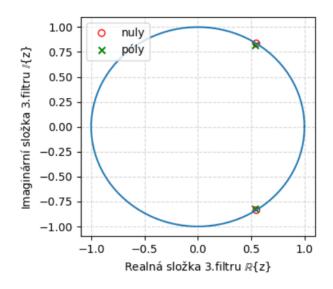
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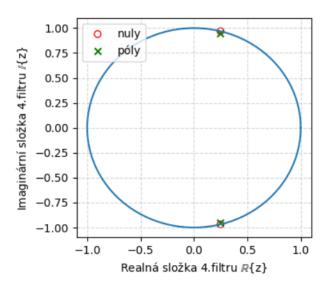
8. Nulové body a póly

Riešené podľa návodu v Jupyteri.







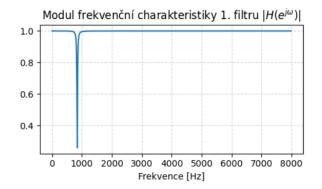


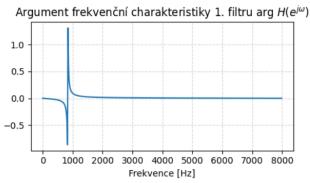
9. Frekvenční charakteristika

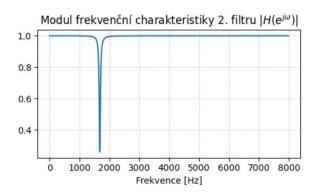
Riešené podľa návodu v Jupyteri.

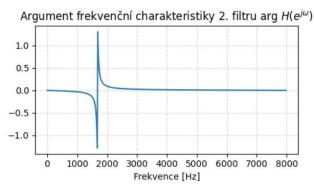
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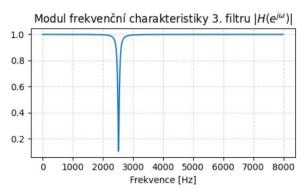
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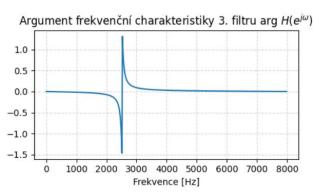


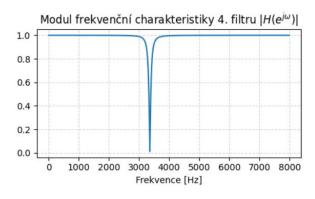


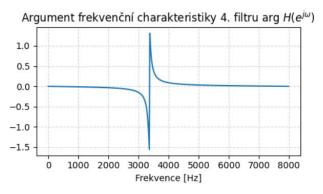




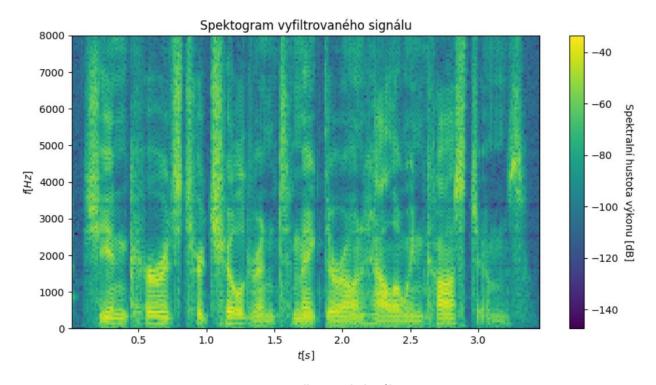


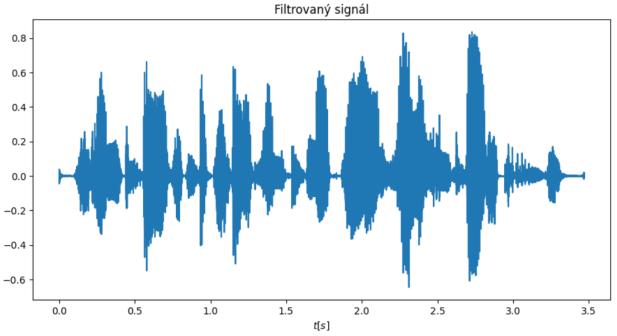






10. Filtrace





Na grafe možme vidieť, že sme sa filtrovaním zbavili rušivého signal a je to vidieť tak, že medzi slovami sa hodnota blíži k nule a nezostáva tam žiadne rušenie ako v grafe úlohy č.1.