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# Neuro BackPropagation Lab

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# Chapter 1

# **Prolusion**

### 1.1 Goal

This report provides a comprehensive overview of a Python project whose goal is to develop and compare different adaptive backpropagation techniques involved in a machine learning process, as Rprop (Resilient BackPropagation). MNIST is the target of the learning model.

The project follows the "Empirical evaluation of the improved Rprop learning algorithms" article by Christian Igel and Michel Hüsken (2001).

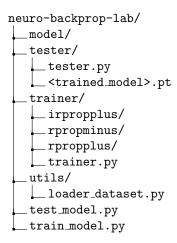
### 1.2 Software Stack

- Python 3.9.6
- $\bullet$  PyTorch 2.6.0

The project is equipped with a requirements.txt file which allows for seamless installation of dependencies, by executing pip install -r requirements.txt.

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## 1.3 Project Structure



- model includes the neural network model architecture.
- $\bullet$  tester handles the testing flow of the ready-to-use trained\_model>.pt.
- trainer handles the examined backpropagation techniques and the training flow of the model, saving it as <trained\_model>.pt.
- $\bullet$  utils offers utility functions designed to support the root project scripts.

# Chapter 2

# Module Overview

The part of the project which is shared across all the examined Rprop techniques is presented as follows.

## 2.1 Train Model

This script runs the training flow of the model and saves it for future testing phase.

#### Algorithm 1: train\_model.py

```
model \leftarrow newModel() \\ criterion, optimizer, epochs, train\_set, eval\_set \leftarrow get\_configuration() \\ Trainer.traineval(model, criterion, optimizer, train\_set, eval\_set, epochs) \\ savemodel(model)
```

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## 2.2 Test Model

This script runs the test flow of the model.

## Algorithm 2: test\_model.py

 $model, optimizer \leftarrow load\_model() \\ criterion, test\_set \leftarrow get\_configuration()$ 

 $Tester.test(model, criterion, test\_set)$ 

#### 2.3 Model

This class, model.py, represents the artificial neural network model architecture to be trained and tested.

It is a shallow network based on torch.nn.Module<sup>1</sup> class. Its three layers are fully connected using torch.nn.Linear(.) and they feed forward as follows:

- 1. the first layer flattens the input MNIST image, by transforming it from a multidimensional vector to a 784-sized (since a  $28 \times 28$ -sized image is manipulated) one-dimensional vector;
- the hidden layer receives the transformed vector and processes it into a 128-sized vector with a ReLU activation function to introduce non-linearity, a choice that was the result of empirical experiments;
- 3. the output layer extracts the final predictions by transforming the 128-sized vector into a 10-sized vector, which corresponds to the number of possible classes for classification.

<sup>&</sup>lt;sup>1</sup>https://pytorch.org/docs/stable/generated/torch.nn.Module.html (accessed 2025)

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## 2.4 Trainer

This class, trainer.py, is responsible for training the model and saving it for future testing phase. Data retrieval is addressed in subsection 2.6.1.

#### Algorithm 3: trainer.py

```
Function traineval (model, criterion, optimizer, train_set, eval_set, epochs):
    foreach epoch \in epochs do
         train\_loss\_avg, train\_accuracy \leftarrow
          train(model, criterion, optimizer, train\_set, train\_loss\_avgs, train\_accuracies)
         eval\_loss\_avq, eval\_accuracy \leftarrow eval(model, criterion, eval\_set, eval\_loss\_avqs, eval\_accuracies)
    end
    \textbf{return}\ train\_loss\_avgs, train\_accuracies, eval\_loss\_avgs, eval\_accuracies
return
Function train(model, criterion, optimizer, train_set, loss_averages, accuracies):
    foreach batch \in train\_set do
         labels, loss, outputs \leftarrow trainstep(model, criterion, optimizer, batch)
         total\_correct, total\_loss, total\_samples \leftarrow
          gather\_metrics(labels, loss, outputs, total\_correct, total\_loss, total\_samples)
    loss\_average, accuracy \gets
      compute\_metrics(total\_correct, total\_loss, total\_samples, loss\_averages, loss\_accuracies)
    return loss_average, accuracy
Function trainstep(model, criterion, optimizer, batch):
    inputs, labels \leftarrow batch
    outputs \leftarrow model(inputs)
    loss \leftarrow criterion(outputs, labels)
    loss.compute\_gradients()
    optimizer.step()
   return\ labels, loss, outputs
return
\textbf{Function}\ eval (model,\ criterion,\ eval\_set,\ loss\_averages,\ accuracies) :
    foreach batch \in eval\_set do
         labels, loss, outputs \leftarrow evalstep(model, criterion, batch)
         total\_correct, total\_loss, total\_samples \leftarrow
          gather\_metrics(labels, loss, outputs, total\_correct, total\_loss, total\_samples)
    end
    loss\_average, accuracy \leftarrow
      compute\_metrics(total\_correct, total\_loss, total\_samples, loss\_averages, accuracies)
    {f return}\ loss\_average,\ accuracy
Function evalstep(model, criterion, batch):
    inputs, labels \leftarrow batch
    outputs \leftarrow model(inputs)
    loss \gets criterion(outputs, labels)
    {\bf return}\ labels, loss, outputs
return
```

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#### 2.5 Tester

This class, tester.py, is responsible for loading and running a pre-trained model on unseen data.

#### 2.6 Utils

#### 2.6.1 Loader Dataset

This class, loader-dataset.py, is responsible for the methodology employed for data retrieval. It is the module that takes the most importance of the utils package, so it was worth describing it.

The method used to get the data is holdout, there is more than one function involved in this.

#### Algorithm 5: loader\_dataset.py

As planned, the learning data is completely separated from the testing data with the learn\_mode parameter.

The learning set is, in turn, split into the train set for the training phase and in the eval set for the evaluation phase. Finally, the train set undergoes a data shuffle, this should make the train phase more robust. The eval set comes in handy to avoid overfitting.

It is also important to note that the MNIST allocates 60,000 samples for training and 10,000 for testing.

# Chapter 3

# Resilient Backpropagation Techniques

Rprop algorithms differ from the classical back-propagation algorithms by the fact that they are independent of the magnitude of the gradient, but depend on its sign only.

### 3.1 Implementations

#### 3.1.1 Rprop-

This is Rprop-.

#### 3.1.2 Rprop+

This is Rprop+.

#### 3.1.3 Improved Rprop with Weight-Backtracking

This is IRprop+.

#### 3.1.4 Rprop+ by PyTorch

This is Rprop+ by PyTorch.<sup>1</sup>

### 3.2 Comparisons

Here I will show comparisons.

<sup>&</sup>lt;sup>1</sup> https://pytorch.org/docs/stable/generated/torch.optim.Rprop.html (accessed 2025)

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# Acronyms

 $\mathbf{MNIST}$  Modified National Institute of Standards and Technology database 1, 8, 12

 ${f ReLU}$  Rectified Linear Unit 8

**Rprop** Resilient BackPropagation 1, 5, 13