## Documentation for LabView vi's for QM Experiments

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These vi's were all specifically written to read data from the DE2 coincidence counting unit. Data streams from the DE2 counter at a rate of 10Hz over an RS-232 (COM) serial port.

Brief descriptions of the vi's:

## Appendix A -- Coincidence\_rs232.vi

Used to acquire data for several experiments: coincidence measurements, proving the existence of photons [ $g^{(2)}(0)$  measurements], and single photon interference.

## Appendix B - MCA.vi

Used to mimic the behavior of a multichannel analyzer (MCA) using an analog-to-digital converter; it saves you the money of buying a dedicated MCA. This is useful for measuring the arrival time of photons using a TAC.

## Appendix C - QSM\_rs232.vi

Used to measure the polarization state of a single photon.

#### Appendix D – Angle\_scan\_rs232.vi

Used to examine two photon polarization correlations (joint probabilities) as a function of angle.

## Appendix E - Hardy\_Bell\_rs232.vi

Used to acquire data for Hardy's test of local realism, or a Bell (CSHS) inequality test.

### Appendix F – Coincidence time res rs232.vi

Used to calibrate the coincidence time resolution.

## **Appendix G – NewStep Rotation Stage Configuration**

Instructions for configuring the NewStep rotation stages so that they will work properly with the programs described here.

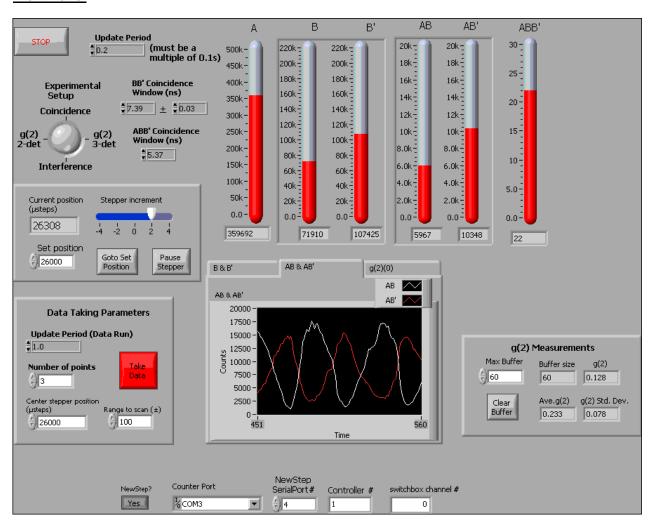
## Appendix A – Coincidence\_rs232.vi

This appendix describes the LabView vi used to acquire data for several experiments: coincidence measurements, proving the existence of photons, and single photon interference.

## **I. Starting Out**

The appearance of this vi will change depending on the experiment you are doing (as determined by the **Experimental Setup** knob on the vi.) The experiment with the most controls and indicators is the interference experiment, and the front panel for this experiment is shown below. If you are doing a different experiment, some of the objects may not be visible.

# Coincidence\_rs232.vi Front Panel



#### Description

This is the program you use to run one of 4 different experiments:

- 1) Simply measuring coincidences between two beams.
- 2) Measuring g(2)(0) for 2-beams using 3-detectors.
- 3) Measuring single photon interference patterns (and simultaneously g(2)(0) for 2-beams using 3-detectors).
- 4) Measuring g(2)(0) for 1-beam using 2-detectors.

Note that g(2) is calculated differently depending on whether you're making 3-detector or 2-detector measurements. See details in the description of the "g(2) Measurements" parameter.

This vi was specifically written for the Altera DE2 counter. Data streams to the computer from the DE2 over the RS232 serial port.

The program does not record data to a file right away, but displays the counters in real time so that you can align things.

Once everything is aligned and the parameters are set, you press the "Take Data" button. This transfers control to another program which records a data set and saves it to a file.

Note that there is one control: "NewStep?" that tells the computer what hardware you have present in your experiment. This control is not visible normally. It located below the "Data Taking Parameters", so you'll need to scroll the window down to access it. This control is only read once at the beginning of execution--so it must be properly set BEFORE you run the program. This control is useful so that the computer won't try to communicate with an instrument you don't have, causing a hang-up. By default "NewStep?" is set to "No"--if you do have a NewStep, you'll want to change the default to "Yes". For more info see the description of this control below.

For interference measurements, a Newport NewStep actuator (inexpensive stepper motor) is used to tilt a beam displacing polarizer to adjust the phase of a polarization interferometer. This actuator is controlled by a NewStep controller, connected to a serial port of the computer with an RS-485 to RS-232 converter. If you do not have this controller, set the "NewStep?" parameter to "No".

Signals that should be selected on the DE2 for the coincidence counters:

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A (Counter 0)

B (Counter 1)

A' (Counter 2) - unused by this vi

B' (Counter 3)

AB (Counter 4)

ABB' (Counter 5) – used for 3-detector g2 measurements (and interference)

AB' (Counter 6)

BB' (Counter 7) – used for 2-detector g2 measurements

Note that for the coincidence experiment, only 3 counters are used: A, B, and AB. For the other 3 experiments, 7 counters are used.

On startup, the program initializes the counters.

After initialization the program simply loops and displays the counts in a given time window (determined by the "Update Period" control in the upper left.) This is useful for tweaking the alignment and adjusting parameters.

Nothing is written to disk until the parameters are chosen and the "Take Data" button is pressed. This loads a second VI that records and saves data to disk. Parameters for this data acquisition phase are set in the "Data Taking Parameters" box.

When performing an interference experiment, the stepper motor will automatically adjust the tilt of the beam displacing prism, changing the phase.

Help for each of the controls and indicators can be obtained from the Contextual Help window <cntrl - H> by mousing over each control or indicator. Full documentation for each control and indicator can be obtained by printing using: File>Print>Custom, and then checking "All controls" and "Descriptions".

## **Coincidence Measurements**

## Experimental Setup

Which measurement to perform.

Coincidence: Measures A, B, and AB counts.

g(2) 3-det: Make g(2) measurements on 2 correlated beams using 3-detectors. This is the single photon measurement.

Interference: interference measurement [with simultaneous g(2) 3-detector measurement]

g(2) 2-det: Make g(2) measurements on a single beam using 2-detectors. This is the classical field measurement.

## TFF Stop

Use this to stop. If you stop some other way you'll probably need to quit LabView and restart; you may even need to reboot the computer.

#### **DBLI** Update Period

[Must be a multiple of 0.1s]

Time window (in s) for the counters during setup phase (i.e., before the "Take Data" button is pressed.) Readings update once each time window if "Status" reads "Reading Counters".

#### [U32] Counts A, B, B'

Singles counts in the time window specified by "Update Period" (upper left)

#### [U32] Counts AB, AB'

Coincidence counts in the time window specified by "Update Period" (upper left)

## Charts

Click on the tabs to display running plots of different measurements: B & B', AB & AB', or g(2).

## Update Period (Data Run) [Data Taking Parameter]

[Must be a multiple of 0.1s]

Time window (in s) for counters during data acquisition.

This applies after the "Take Data" button has been pressed.

### **1321** Number of points [Data Taking Parameter]

Number of measurements that are made during data acquisition.

Error measurements are essentially useless if this is less than 5. 10 is a better minimum number. For interference measurements, you will want to use many more than this so you can better see the pattern.

#### TIN Take Data [Data Taking Parameter]

Leave the setup "tweaking" mode and switch to data acquisition mode.

#### TFI NewStep?

Is the NewStep controller present?

If No, there is no attempt to communicate with the NewStep controller. Useful if you don't have a NewStep controller. In this case, the "Interference" experiment is unavailable. If you set "Experimental Setup" to "Interference", the program will act as though it's set to "g(2) 3-det".

If Yes, the NewStep functions normally.

This parameter is only read once, when the vi first starts to run. Therefore, it needs to be set BEFORE you run the program.

#### Counter Port

A string that identifies the serial communication port that the DE2 board is attached to: "COM1", "COM2", etc.

## NewStep SerialPort#

Number of the serial (COM) port that the NewStep controller is connected to.

## **□** Controller #

NewStep controller #

#### switchbox channel #

NewStep switchbox channel for motor. Set to 0 if there is no switchbox.

## 3-Detector g(2) Measurements

## All of the above parameters apply, plus the following:

#### **DBLI** ABB' Coincidence window

Coincidence window for ABB' measurements.

Used to determine expected g(2) for 3-detector (single-photon) measurements. Basically, this parameter determines the number of expected accidental ABB' counts.

#### [U32] Counts ABB'

Three-fold coincidence counts in the time window specified by "Update Period" (upper left)

## g(2) Measurements

The program calculates g(2) for every loop--and this value is displayed as g(2).

Calculated differently depending on which experiment you're doing.

Formulas:

T: update period (counting window, in S)

dt: BB' coincidence window (in nS)

3-detector, 2-beam experiment:

g(2)=(A\*ABB')/(AB\*AB')

2-detector, 1-beam experiment:

g(2)=(BB'/(B\*B'))\*(T/(dt\*1.0e-09))

These g(2) measurements are then stored in an array, which contains the most recent measurements.

g(2) Ave. and g(2) Std. Dev are the mean and standard deviation of these stored measurements.

**Max Buffer** is the maximum size of this array (i.e., the largest number of measurements that will be averaged).

Buffer size is the current length of the array that is being averaged.

Clear Buffer clears out the array, and new measurements begin repopulating it.

#### **U321** Center stepper position (µsteps) [Data Taking Parameter]

Center of the range for the stepper during data acquisition.

#### Range to scan (±) [Data Taking Parameter]

Range for the stepper during data acquisition.

At each point of data acquisition, the stepper moves evenly between ("Center stepper position" - "Range to scan") and ("Center stepper position" + "Range to scan")

# 2-Detector g(2) Measurements

## All of the above parameters apply, plus the following:

BB' Coincidence window

Coincidence window for BB' measurements. Needed to determine g(2) for 2-detector (classical) measurements.

DBL 2D window stdev

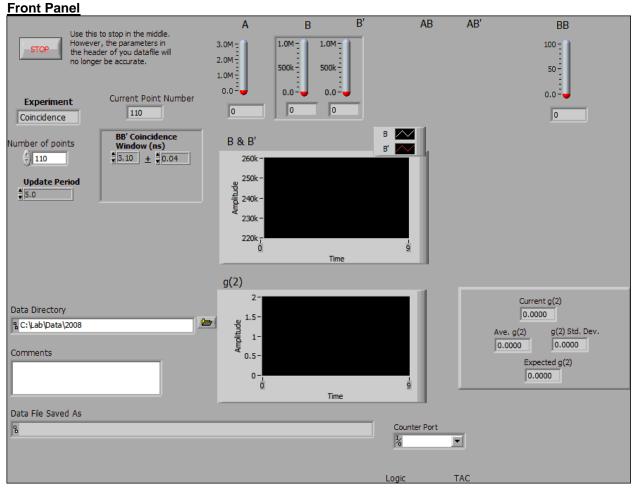
Standard deviation of coincidence window for BB' measurements. Needed to determine the error in g(2) for 2-detector (classical) measurements.

BB' BB' coincidences.
Only used for 2-detector g(2) measurements.

## II. Taking Data

When you move to data taking mode, the program you see will look something like that shown below. Again, the appearance of this vi will change depending on the experiment you are doing.

## Coincidence\_Recorder\_rs232.vi



#### **Description**

This VI should ONLY be called from the "Coincidence\_rs232" VI--necessary parameters are set there. This program records data (using parameters set in the "Coincidence\_rs232.vi" ) and saves the data to a file.

For a more detailed description of the parameters, see "Coincidence\_rs232.vi".

#### **Controls and Indicators**

**Ⅲ** Stop

Use this to stop in the middle of a data run. However, the parameters in the header of you datafile will no longer be accurate (e.g., you won't have as many points as the header says.)

Also, if you stop some other way you'll probably need to quit LabView and restart; you may even need to reboot the computer.

[132] Experiment

Displays which experiment is being performed: Coincidence, g(2), or Interference.

1321 Number of points

Number of measurements that are made during data acquisition.

Current Point Number

The data point that the computer is currently acquiring.

**DBLI** ABB' Coincidence window

Coincidence window for ABB' measurements.

Used to determine expected g(2) for 3-detector (single-photon) measurements. Basically, this parameter determines the number of expected accidental ABB' counts.

BB' Coincidence window

Coincidence window for BB' measurements.

Needed to determine g(2) for 2-detector (classical) measurements.

BB' 2D window stdev

Standard deviation of coincidence window for BB' measurements.

Needed to determine the error in g(2) for 2-detector (classical) measurements.

**DBL** Update Period

Time window (in s) for counters during data acquisition.

Data Directory

Path to directory where the data will be saved.

**Liber** Comments

A space where you can enter comments about the data run. These get saved in the header of the data file.

Once you've entered the text, note that you must hit "Enter" on the NUMERIC KEYPAD, not the "Enter" (or "Return") on the regular keyboard for this text to be saved.

Data File Saved As

Path to the data file. The data file is automatically named using the date and time.

[U32] Counts A, B, B'

Singles counts in the time window specified by "Update Period" (upper left)

[U32] Counts AB, AB'

Coincidence counts in the time window specified by "Update Period" (upper left)

[U32] Counts ABB'

Three-fold coincidence counts in the time window specified by "Update Period" (upper left)

**Graphs** 

Displays graphs of B and AB [Coincidence measurement], or **B & B'**, **AB & AB'**, and **g(2)**. [g(2) and Interference measurement.]

**DBL** Ave. AB [Coincidence measurement only]

Average value of AB coincidences. Updated when program ends.

- AB Std. Dev. [Coincidence measurement only]
- Standard deviation of AB coincidences. Updated when program ends.
- Counter Port
  A string that identifies the serial communication port that the DE2 board is attached to: "COM1", "COM2", etc.
  - g(2) Measurements (both 2-Detector and 3-Detector)
    All of the above parameters apply (except "Ave. AB" and "AB Std. Dev."), plus the following:
- Current g(2)

g(2) measurement for the current data point.

- Ave. g(2)
  Average of the g(2) measurements.
- **▶** g(2) Std. Dev.

For 3-detector measurements this is the standard Deviation of the g(2) measurements. For 2-detector measurements during data acquisition it is the standard deviation of the g(2) measurements. At the end this error is added in quadrature with the error in g(2) due to the uncertainty of the BB' coincidence time window ("BB' 2D window stdev").

Expected g(2)

Calculate the expected value of the parameter g^(2) (0). Based on number of expected accidental coincidences.

Calculated differently depending on which experiment you're doing.

For 2-detector, 1-beam measurements, this is assumed to be 1.0 (a classical beam).

For all other measurements, when the vi first starts running it is set to 0.0, and is updated with the expected g(2) at the very end.

Formula (from Appendix A of Thorn AJP)

- T: update period (counting window, in S)
- dt: ABB' coincidence window (in nS)

g(2)=(dt\*1.0e-09/T)\*A\*((B/AB)+(B'/AB'))

## **Interference Measurements**

Interference measurements assume a 3-detector setup for g(2) calculations.

All of the above parameters apply (except "Ave. AB" and "AB Std. Dev."), plus the following: Starting stepper position

## U32

Position of stepper motor at start of scan.

#### U32 **End stepper position**

Position of stepper motor at end of scan.

Over the course of a data run, the motor steps evenly between the starting and ending positions.

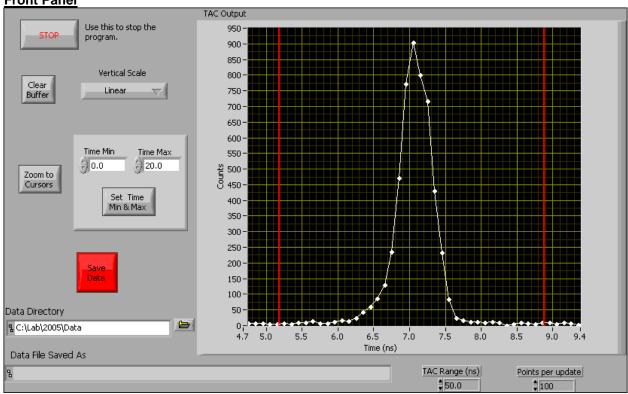
#### **Current Position** 132

Position of stepper motor for the current data point.

## Appendix B - MCA.vi

This appendix describes the LabView vi used to mimic the behavior of a multichannel analyzer (MCA). This is useful for measuring the arrival time of photons.





#### Description

This VI emulates a multi-channel-analyzer (MCA). An MCA essentially digitizes a series of voltage pulses, and creates a histogram of the pulse heights. The purpose of this VI is to analyze the voltage pulses from a Time-to-Amplitude Converter (TAC) [This VI was tested using the TAC in an ORTEC 567 TAC/SCA module].

The start and stop pulses going into the TAC come from photon counters, and the TAC output voltage is proportional to the time between the start and stop. Thus, the MCA is creating a histogram of the time interval between the arrivals of the two photons.

The main difference between this VI and a real MCA is that an MCA takes only one input-the voltage pulses. This VI also needs timing information about when the pulses are arriving. Fortunately, this can be obtained from the Valid Conversion output of the TAC. The Valid Conversion output is an approximately 3 microsecond long TTL pulse coincident with the TAC output pulse.

We have tested this VI with 2 different National Instruments multifunction cards: 6036E and 6052E. With these cards there are two clock signals that are needed to perform an A/D conversion: the trigger and the sample clock.

The trigger (input through PFI0) comes directly from the Valid Conversion output of the TAC. The program is configured to trigger on a low-to-high transition of the trigger -triggering arms the A/D, but does not actually cause an A/D conversion.

The program is configured to perform an A/D conversion on a high-to-low transition of the Sample Clock. The Sample Clock is obtained by generating a delayed pulse from the trigger. The delayed pulse is

generated by one of the counter/timers on the multifunction board: counter 0. The output of counter 0 is sent directly to the sample clock, so the user need only input the trigger pulse to PFI0, and the sample clock will take care of itself (the user can monitor the counter 0 output to observe the timing of the sample clock). The timing can be changed by adjusting the duration of the pulse (using the "High Time") parameter in the block diagram).

The TAC output to be digitized is input though Analog Input Channel 0.

Unlike many VI's you'll encounter, the screen updates after a specified number of data points are acquired (determined by the parameter "Points per update"), not after a specific time interval. Because of this, if the detectors are off, nothing will happen.

NOTE: The A/D boards we use are just barely fast enough to catch the 3 microsecond long TAC output (the width of the TAC output could also be increased for better results)--indeed, they're probably technically too slow. Because of this, the accuracy of the measurement of the TAC output is not very good (can be off by as much as 10 or 20%), which means that the time scale is poorly calibrated. However, the measurement is repeatable, so the time scale could be calibrated much more accurately. Despite this problem, the VI works quite well enough to accomplish its main goals-to display a bump in the histogram of arrival times between the photons from two detectors, and to allow one to set the SCA window to select coincidences (only needed if you're using the TAC/SCA for coincidence counting).

ALSO NOTE: This vi has only been seriously tested for START-STOP times ranging from a few up to about 30 ns. With much longer intervals than this the output pulses may be delayed, and the timing may change.

change.

Rough Timing diagram:

Trigger (PFI0)

Sample clock (counter 0)

A/D Ch 0

Help for each of the controls and indicators can be obtained from the Contextual Help window <cntrl - H> by mousing over each control or indicator. Full documentation for each control and indicator can be obtained by printing using: File>Print>Custom, and then checking "All controls" and "Descriptions"

FINAL NOTE: For whatever reason, the vi "aquire\_daqmx\_subvi.vi" does NOT get saved if you save the entire vi hierarchy. So, you explicitly need to copy this vi to the new library from the old one. After you copy it, LabView will STILL look for it in the old location, so you again need to explicitly find this vi for LabView.

#### **Controls and Indicators**

TFI Stop

Use this to stop.

Clear Buffer

Clears the histogram memory, and the accumulation starts over again.

**UB** Vertical Scale

Change the scaling of the vertical scale. Options are Linear and Logarithmic.

**III** Zoom to cursors

Horizontal scale will zoom in to the region specified by the cursor positions.

Time Min
Set minimum of horizontal axis to this value after pressing "Set Time Min & Max".

Time Max
Set maximum of horizontal axis to this value after pressing "Set Time Min & Max".

Set min & max

Set the minimum and maximum values of the horizontal axis to those specified.

Save Data

Save the current data to a file. Program exits after this is done.

Data Directory

Path to directory where the data will be saved.

Data File Saved As

Path to the data file. The data file is automatically named using the date and time.

**TAC Range (ns)** 

The full scale range of the TAC output. Used to scale the horizontal axis.

Points per update

Number of data points acquired before updating the screen. Remember, the screen updates after a specified number of data points are acquired, not after a specific time interval.

If you have very low count rates, you might want to decrease this from it's default value of 100.

TAC Output

Histogram of the time interval distribution.

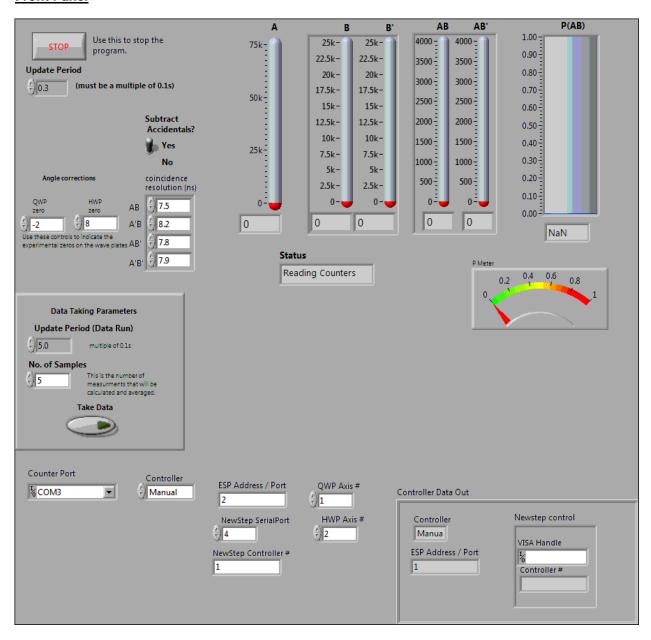
## Appendix C - QSM\_rs232.vi

This appendix describes the LabView vi used to perform a quantum state measurement. It measures the polarization state of a single photon.

## I. Starting Out

When you first run the vi, the program that you see is:

## QSM\_rs232.vi Front Panel



#### **Description**

This is the program you use to perform quantum state measurements of the polarization state of a single photon. It does not record data to a file right away, but displays the counters in real time so that you can align things. It also gives you interactive control over such things as the waveplate angles.

Once everything is aligned and the parameters are set, you press the "Take Data" button. This transfers control to another program which records a data set and saves it to a file.

This vi was specifically written for the Altera DE2 counter. Data streams to the computer from the DE2 over the RS232 serial port.

Waveplates (or polarizers) are controlled by either: i) a Newport ESP300 controller using, ii) a NewStep controller, or iii) can be manually controlled by following popup instructions if 'manual' is selected. [Note that the "Controller" parameter is only read once on initiallization, so it MUST be properly set BEFORE hitting run.] On program start, during initialization, the motors home themselves. The motors then set the waveplates to 0 (using the corrections in "QWP zero" and "HWP zero").

The DE2 board must be properly set to record the proper coincidences. The coincidences that should be mapped to a given counter are:

A (Counter 0)

B (Counter 1)

A' (Counter 2) (unused)

B' (Counter 3)

AB (Counter 4)

A'B (Counter 5) (unused)

AB' (Counter 6)

A'B' (Counter 7) (unused)

On startup, the program initializes the motors and the counters. During this time the "Status" indicator reads "Initializing". NOTE: occasionally when using the NewStep rotation stages, the program takes a LONG time to initialize (can be a minute or two). During this time the stages are finding their 0 positions (called the "Home" position).

After initialization the program simply loops and displays the counts in a given time window (determined by the "Update Period" control in the upper left.) Status reads "Reading Counters". This is useful for tweaking the alignment and adjusting parameters. Waveplates are moved by first setting the desired waveplate angles in the "QWP(HWP) Desired Position" controls, and then pressing the "Move Motors" button. Status changes to "Moving Motors" while the motors are in motion.

Nothing is written to disk until the parameters are chosen and the "Take Data" button is pressed. This loads a second VI that records and saves data to disk. Parameters for this data acquisition phase are set in the "Data Taking Parameters" box.

During data acquisition the motors will automatically set the waveplates to the correct angles. Three sets of measurements are performed, at angles (QWP, HWP): (0, 0), (45, 0), (45, 22.5). With these settings, the probability of an AB coincidence P(AB) corresponds to: P(H), P(L), P(+45).

Help for each of the controls and indicators can be obtained from the Contextual Help window <cntrl - H> by mousing over each control or indicator. Full documentation for each control and indicator can be obtained by printing using: File>Print>Custom, and then checking "All controls" and "Descriptions".

#### **Controls and Indicators**



**Stop** Use this to stop. It takes a little longer, but this way, the board gets reset. If you stop some other way you'll probably need to quit Labview and restart; you may even need to reboot the computer.

## Update Period

[Must be a multiple of 0.1s]

Time window (in s) for the counters during setup phase (i.e., before the "Take Data" button is pressed.) Readings update once each time window if "Status" reads "Reading Counters". Can behave irregularly if set to less than 0.3 s.

**DBLI** QWP zero

Motor angle at which quarter waveplate axis is 0.

**DBLI** HWP zero

Motor angle at which half waveplate axis is 0.

**TFI** Subtract Accidentals?

Determines whether or not accidental coincidences are subtracted. Controls data taking mode as well as tweaking mode.

[DBL] coincidence resolution (ns)

The coincidence time resolutions (used in subtraction of accidentals).

[U32] Counts A, B, B'

Singles counts in the time window specified by "Update Period" (upper left)

[U32] Counts AB, AB'

Coincidence counts in the time window specified by "Update Period" (upper left)

P(AB)

Probability of an AB coincidence.

P Meter

Probability of AB coincidence.

Status Program Status

Initializing: initializing the counters and motors.

Reading counters: Program is looping, reading the counters and updating the screen.

Moving Motors: Waveplates (polarizers) are rotating.

**QWP Desired Position** 

Angle to set quarter waveplate to.

Movement occurs after "Move Motors" button is pressed.

**IDBLY** HWP Desired Position

Angle to set half waveplate to.

Movement occurs after "Move Motors" button is pressed.

**TFI** Move Motors

Set the motors to the "Desired Positions"

**DBL** QWP Position

Current angle of the quarter wave plate.

HWP Position

Current angle of the hlaf waveplate.

**PDBL** QWP Motor Position

Actual position of the motor for the quarter waveplate.

Not the same as "QWP Position" because of the 0 position correction specified in "QWP zero".

HWP Motor Position

Actual position of the motor for the half waveplate.

Not the same as "HWP Position" because of the 0 position correction specified in "HWP zero".

#### **1701** Counter Port

A string that identifies the serial communication port that the DE2 board is attached to: "COM1", "COM2", etc. Note that you might need to scroll down to see this control.

#### **U15** Controller

Which rotation stage controller to use: NewStep or ESP or Manual Control. Note that this is only read once at initialization, so it MUST be set BEFORE hitting run.

#### ESP Address / Port

GPIB Address of ESP controller (if present)

#### NewStep SerialPort

# of COM port that NewStep controller is connected to (if present)

#### **■ NewStep Controller #**

Controller # of the NewStep (if present)

#### QWP Axis #

Axis # of QWP rotation stage. For NewStep this is the Switchbox channel #.

#### HWP Axis #

Axis # of HWP rotation stage. For NewStep this is the Switchbox channel #.

#### Controller Data Out

For Program use.

## **Data Taking Parameters**

## Update Period (Data Run)

[Must be a multiple of 0.1s]

Time window (in s) for counters during data acquisition.

This applies after the "Take Data" button has been pressed.

#### 1321 No. of Samples

Number of independent measurements (of H for Hardy measurements, or S for Bell Measurements) that are made during data acquisition. These are averaged to get the mean and error of the measurement.

Error measurements are essentially useless if this is less than 5. 10 is a good number for reasonable statistics.

#### Take Data

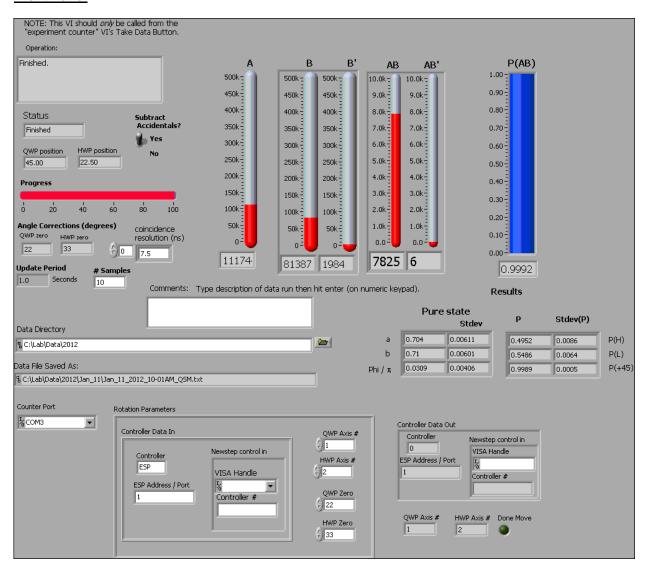
Leave the setup "tweaking" mode and switch to data acquisition mode.

## **II. Taking Data**

When you move to data taking mode, the program you see is:

## QSM-Recorder\_rs232(1\_7).vi

### **Front Panel**



#### **Description**

This VI should ONLY be called from a "QSM\_rs232" VI--necessary parameters are set there.

This program records data (using parameters set in the "QSM\_rs232" VI) and saves the data to a file.

## **Controls and Indicators**

## Deration 0

Displays what the program is trying to do. Normally this shows what the angles of the motors are.

There are 2 angles shown -- the waveplate angles are given first and the actual motor angles are in parentheses (they are different by the 0 offset displayed in "A zero" and "B zero".)

When the program is done this reads "Finished." Values for probabilities (expectations for Bell) and H (S for Bell) are not updated until this happens.

#### **Male** Status

Program Status:

Moving Motors: waveplate (polarizer) motors are in motion.

Waiting: Clearing out the counter buffers after motors move.

Taking Data: Data is being collected.

#### **DBL** QWP position

Current position of QWP motor.

#### HWP Position

Current position of HWP motor.

#### Subtract Accidentals?

Determines whether or not accidental coincidences are subtracted.

#### [DBL] coincidence resolution (ns)

Array of the coincidence time resolutions (used in subtraction of accidentals).

#### Progress

Rough indication of what percentage of the data run is complete.

#### **DBL** QWP zero

Motor angle at which quarter waveplate axis is 0.

#### HWP zero

Motor angle at which half waveplate axis is 0.

#### **IDBL** Update Period

Time window (in s) for counters.

#### FI32 # Samples

Number of independent measurements (of H for Hardy measurements, or S for Bell Measurements) that are made during data acquisition. These are averaged to get the mean and error of the measurement.

Error measurements are essentially useless if this is less than 5. 10 is a good number for reasonable statistics.

#### **Line Comments**

A space where you can enter comments about the data run. These get saved in the header of the data file.

Note that you must hit "Enter" on the NUMERIC KEYPAD, not the "Enter" (or "Return") on the regular keyboard for this text to be saved.

**Data Directory** 

Path to directory where the data will be saved.

Data File Saved As:

Path to the data file. The data file is automatically named using the date and time.

[DBL] Pure state

Parameters (and errors) that describe the measured state:

 $|\psi\rangle = a|H\rangle + be^{i\phi}|V\rangle$ 

[DBL] P Stdev(P)

Probabilities (and errors) of the indicated polarization.

Counter Port

A string that identifies the serial communication port that the DE2 board is attached to: "COM1", "COM2", etc.

Rotation Parameters

Inputs containing parameters describing rotation stages

QWP Axis #

Axis # of QWP rotation stage. For NewStep this is the Switchbox channel #.

**HWP Axis #**Axis # of HWP rotation stage. For NewStep this is the Switchbox channel #.

Done Move

I8

For program use.

## Appendix D - Angle\_scan\_rs232.vi

This appendix describes the LabView vi used to examine two photon polarization correlations (joint probabilities) as a function of angle.

## **I. Starting Out**

When you first run the vi, the program that you see is:

#### Angle\_scan\_rs232.vi **Front Panel** A' В' Α В AΒ A'B AB' A'B' Use this to stop the 2.5k-2.5k= 2.5k= 2.5k= 1.00 -50k = 50k = 45k-45k-2.3k= 2.3k-2.3k-0.90 -2.3k-**Update Period** 40k= 40k= 40k = 40k= 2k-2k= 2k-2k-0.80 -(must be a multiple of 0.1s) 35k-35k= 1.8k-1.8k= 35k-35k -1.8k= 1.8k= 0.70 30k-30k-30k -1.5k= 1.5k= 30k-1.5k= 1.5k= 0.60 € Subtract Accidentals? 25k-25k = 25k = 1.3k= 1.3k= 1.3k= 1.3k= 0.50 -20k-20k -20k-1k= 1k= 1k= 1k= 📗 Yes 15k= 15k= 15k= 15k= 750 -750 -750 -750 -10k= 10k= 10k= 10k= 500 coincidence 0.20 € 5k-5k-5k-250 -250 resolution (ns) 250 -250 -0.10 0-0-0-0-0-0-0-B zero 9.33 0.00 -89 10158 11969 8020 8182 721 -41 2 6 633 9.06 Use these controls to indicate the experimental zeros on the half-wave plates or polarizers 0.5294 7.7 Status A'B' 🗐 8.73 Reading Counters **Data Taking Parameters** B Desired Position A Desired Position 0.0 0.0 22.50 Move Motors Update Period (Data Run) B Position 1.0 multiple of 0.1s A Position -0.0 -0.0 No. of Samples B Motor Position measurments that will be calculated and averaged. A Motor Position -89.0 -41.0 Take Data Counter Port Controller I<sub>6</sub> COM3 NewStep Controller Data Out NewStep SerialPort Newstep control Controller NewSte VISA Handle NewStep Controller # ESP Address / Port ASRL4::INSTR Controller #

#### Description

This is the program you see first when you start to run the experiment. It requires a 4-detector setup. It does not record data to a file right away, but displays the counters in real time so that you can align things. It also gives you interactive control over such things as the waveplate angles.

Once everything is aligned and the parameters are set, you press the "Take Data" button. This transfers control to another program which records a data set and saves it to a file.

This vi was specifically written for the Altera DE2 counter. Data streams to the computer from the DE2 over the RS232 serial port.

Waveplates (or polarizers) are controlled by either: i) a Newport ESP300 controller using GPIB, or ii) a NewStep controller. On program start, during initialization, the motors home themselves. The motors then set the waveplates to 0 (using the corrections in "A zero" and "B zero").

The DE2 board must be properly set to record the proper coincidences. The coincidences that should be mapped to a given counter are:

A (Counter 0)

B (Counter 1)

A' (Counter 2)

B' (Counter 3)

AB (Counter 4)

A'B (Counter 5)

AB' (Counter 6)

A'B' (Counter 7)

On startup, the program initializes the motors and the counters. During this time the "Status" indicator reads "Initializing". NOTE: occasionally when using the NewStep rotation stages, the program takes a LONG time to initialize (can be a minute or two). During this time the stages are finding their 0 positions (called the "Home" position).

After initialization the program simply loops and displays the counts in a given time window (determined by the "update Period" control in the upper left.) Status reads "Reading Counters". This is useful for tweaking the alignment and adjusting parameters. Waveplates (or polarizers) are moved by first setting the desired waveplate angles in the " A(B) Desired Position" controls, and then pressing the "Move Motors" button. Status changes to "Moving Motors" while the motors are in motion.

Nothing is written to disk until the parameters are chosen and the "Take Data" button is pressed. This loads a second VI that records and saves data to disk. Parameters for this data acquisition phase are set in the "Data Taking Parameters" box.

During data acquisition the motors will automatically set the waveplates to the correct angles. The waveplate for the A beam is fixed by the Data Taking Parameter "A". The angle of waveplate B is scanned over 17 equally spaced values: 0, 5.625, 11.25, ... Remember that these are WAVEPLATE angles; since polarization rotates twice as fast as the waveplate, the corresponding polarization angles are twice as large. So, the A polarization angle is twice what is set by the A control, while the B polarization angles are 0, 11.25, 22.5, ... What gets recorded in the data file are waveplate angles, not polarization angles.

Help for each of the controls and indicators can be obtained from the Contextual Help window <cntrl - H> by mousing over each control or indicator. Full documentation for each control and indicator can be obtained by printing using: File>Print>Custom, and then checking "All controls" and "Descriptions".

#### **Controls and Indicators**



#### Stop

Use this to stop. If you stop some other way you'll probably need to quit Labview and restart; you may even need to reboot the computer.

#### DBL

#### **Update Period**

[Must be a multiple of 0.1s]

Time window (in s) for the counters during setup phase (i.e., before the "Take Data" button is pressed.) Readings update once each time window if "Status" reads "Reading Counters". Can behave irregularly if set to less than 0.3 s.

DBL A zero

Motor angle at which A waveplate axis is 0.

DBL B zero

Motor angle at which B waveplate axis is 0.

Subtract Accidentals?

Determines whether or not accidental coincidences are subtracted. Controls data taking mode as well as tweaking mode.

[DBL) coincidence resolution (ns)

The coincidence time resolutions (used in subtraction of accidentals).

**Pabe** Status

Program Status:

Initializing: initializing the counters and motors.

Reading Counters: Program is looping, reading the counters and updating the screen.

Moving Motors: Waveplates (polarizers) are rotating.

**DBLI** A Desired Position

Angle to set A waveplate to.

Movement occurs after "Move Motors" button is pressed.

B Desired Position

Angle to set B waveplate to.

Movement occurs after "Move Motors" button is pressed.

TFI Move Motors

Set the motors to the "Desired Positions"

▶**DBL** A Position

Current angle of the A waveplate.

B Position

Current angle of the B waveplate.

**MOTOR Position** 

Actual position of the motor for the A waveplate.

Not the same as "A Position" because of the 0 position correction specified in "A zero".

B Motor Position

Actual position of the motor for the B waveplate.

Not the same as "B Position" because of the 0 position correction specified in "B zero".

[U32] Counts A, A', B, B'

Singles counts in the time window specified by "Update Period" (upper left)

[U32] Counts AB, A'B, AB', A'B'

Coincidence counts in the time window specified by "Update Period" (upper left)

PDBL P

Probability of AB.

P Meter

Probability of AB

Counter Port

A string that identifies the serial communication port that the DE2 board is attached to: "COM1", "COM2", etc. Note that you might need to scroll down to see this control.

U15 Controller

Which rotation stage controller to use: NewStep or ESP

**ESP Address / Port** 

GPIB Address of ESP controller (if present)

NewStep SerialPort

# of COM port that NewStep controller is connected to (if present)

NewStep Controller #

Controller # of the NewStep (if present)

18 A Axis #

Axis # of A rotation stage. For NewStep this is the Switchbox channel #.

B Axis #

Axis # of B rotation stage. For NewStep this is the Switchbox channel #.

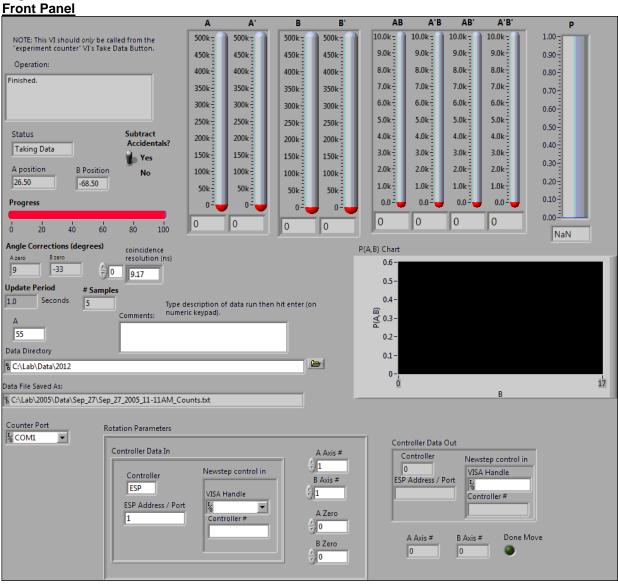
Controller Data Out

For Program use.

## **II. Taking Data**

When you move to data taking mode, the program you see is:

## $angle\_scan\_Recorder\_rs232.vi$



#### Description

This VI should ONLY be called from an "angle\_scan\_rs232" VI--necessary parameters are set there.

This program records data (using parameters set in the "angle\_scan\_rs232" VI) and saves the data to a file.

#### **Controls and Indicators**

## Deration

Displays what the program is trying to do. Normally this shows what the angles of the motors are

There are 2 angles shown -- the waveplate angles are given first and the actual motor angles are in parentheses (they are different by the 0 offset displayed in "A zero" and "B zero".)

When the program is done this reads "Finished." Values for probabilities (expectations for Bell) and H (S for Bell) are not updated until this happens.

### **Pabe** Status

Program Status:

Moving Motors: waveplate (polarizer) motors are in motion.

Waiting: Clearing out the counter buffers after motors move.

Taking Data: Data is being collected.

Finished: Program is done.

#### **PDBL** A position

Current position of A motor.

#### **B** Position

Current position of B motor.

#### Subtract Accidentals?

Determines whether or not accidental coincidences are subtracted.

## [DBL) coincidence resolution (ns)

Array of the coincidence time resolutions (used in subtraction of accidentals).

#### Progress

Rough indication of what percentage of the data run is complete.

#### **A zero** Motor angle at which A waveplate axis is 0.

**B** zero Motor angle at which B waveplate axis is 0.

## **IDBL** Update Period

Time window (in s) for counters.

#### FI32 # Samples

Number of independent measurements (of H for Hardy measurements, or S for Bell Measurements) that are made during data acquisition. These are averaged to get the mean and error of the measurement.

Error measurements are essentially useless if this is less than 5. 10 is a good number for reasonable statistics.

## DBL

Angle of A waveplate--fixed for duration of the data taking.

#### **Little Comments**

A space where you can enter comments about the data run. These get saved in the header of the data file.

Note that you must hit "Enter" on the NUMERIC KEYPAD, not the "Enter" (or "Return") on the regular keyboard for this text to be saved.

#### ■ Data Directory

Path to directory where the data will be saved.

#### Data File Saved As:

Path to the data file. The data file is automatically named using the date and time.

#### DBL

Probability of AB

#### P(A,B) Chart

Plot of the joint probability P(A,B) as the B waveplate is scanned.

#### Counter Port

A string that identifies the serial communication port that the DE2 board is attached to: "COM1", "COM2", etc.

#### Rotation Parameters

Inputs containing parameters describing rotation stages

#### A Axis #

Axis # of A rotation stage. For NewStep this is the Switchbox channel #.

#### B Axis #

Axis # of B rotation stage. For NewStep this is the Switchbox channel #.

#### Done Move

For program use.

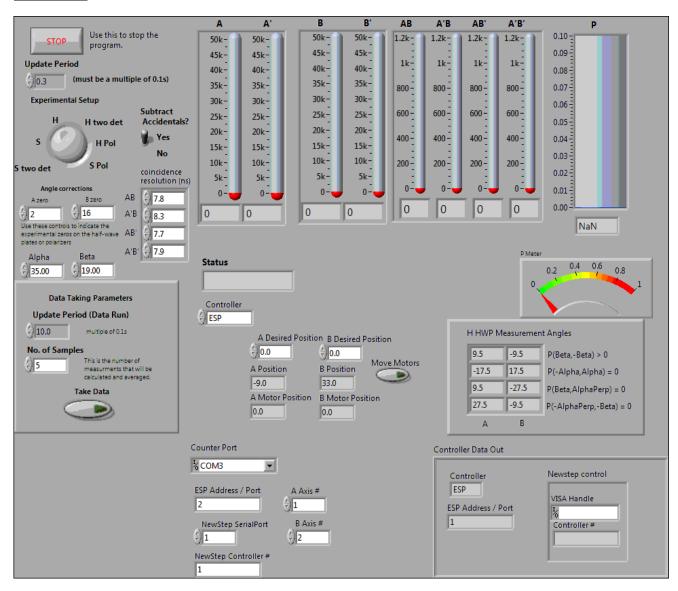
## Appendix E - Hardy\_Bell\_rs232.vi

This appendix describes the LabView vi used to acquire data for Hardy's test of local realism, or a Bell (CSHS) inequality test..

## **I. Starting Out**

When you first run the vi, the program that you see is:

## Hardy\_Bell\_rs232.vi Front Panel



#### Description

This is the program you see first when you start to run the experiment. It can be used for either Hardy-type or Bell-type measurements. It does not record data to a file right away, but displays the counters in real time so that you can align things. It also gives you interactive control over such things as the waveplate angles.

Once everything is aligned and the parameters are set, you press the "Take Data" button. This transfers control to another program which records a data set and saves it to a file.

This vi was specifically written for the Altera DE2 counter. Data streams to the computer from the DE2 over the RS232 serial port.

Waveplates (or polarizers) are controlled by either: i) a Newport ESP300 controller using, ii) a NewStep controller, or iii) can be manually controlled by following popup instructions if 'manual' is selected. [Note that the "Controller" parameter is only read once on initiallization, so it MUST be properly set BEFORE hitting run.] On program start, during initialization, the motors home themselves. On program start, during initialization, the motors home themselves. The motors then set the waveplates to 0 (using the corrections in "A zero" and "B zero").

The DE2 board must be properly set to record the proper coincidences. The coincidences that should be mapped to a given counter are:

A (Counter 0)

B (Counter 1)

A' (Counter 2)

B' (Counter 3)

AB (Counter 4)

A'B (Counter 5)

AB' (Counter 6)

A'B' (Counter 7)

On startup, the program initializes the motors and the counters. During this time the "Status" indicator reads "Initializing". NOTE: occasionally when using the NewStep rotation stages, the program takes a LONG time to initialize (can be a minute or two). During this time the stages are finding their 0 positions (called the "Home" position).

After initialization the program simply loops and displays the counts in a given time window (determined by the "update Period" control in the upper left.) Status reads "Reading Counters". This is useful for tweaking the alignment and adjusting parameters. Waveplates (or polarizers) are moved by first setting the desired waveplate angles in the "A(B) Desired Position" controls, and then pressing the "Move Motors" button. Status changes to "Moving Motors" while the motors are in motion.

Nothing is written to disk until the parameters are chosen and the "Take Data" button is pressed. This loads a second VI that records and saves data to disk. Parameters for this data acquisition phase are set in the "Data Taking Parameters" box.

During data acquisition the motors will automatically set the waveplates to the correct angles. Angles for a Bell measurement are fixed. Angles for a Hardy measurement are determined from the controls "Alpha" and "Beta".

Help for each of the controls and indicators can be obtained from the Contextual Help window <cntrl - H> by mousing over each control or indicator. Full documentation for each control and indicator can be obtained by printing using: File>Print>Custom, and then checking "All controls" and "Descriptions".

## Known bugs:

Very occasionally, the NewStep rotation stages will go to the wrong angle during data collection. However, they report that they have gone to the correct angle. This problem is intermittent and random, as far as I can tell. The result is that the recorded measurements are way off for one waveplate setting (typically the last setting). This results in an incorrect value of H or S. If you make many measurements of H or S, and one of them is very different from the others, this is the most likely cause.

## **Controls and Indicators**

**Ⅲ** Stop

Use this to stop. If you stop some other way you'll probably need to quit Labview and restart; you may even need to reboot the computer.

## **DBLI** Update Period

[Must be a multiple of 0.1s]

Time window (in s) for the counters during setup phase (i.e., before the "Take Data" button is pressed.) Readings update once each time window if "Status" reads "Reading Counters". Can behave irregularly if set to less than 0.3 s.

## Experimental Setup

Which Measurement to perform.

H: Hardy measurement (4 detectors)

H two det: Hardy measurement (2 detectors - waveplates)

H Pol: Hardy measurement (2 detectors - polarizers)

S: Bell measurement (4 detectors)

S two det: Bell measurement (2 detectors - waveplates)

S Pol: Bell measurement (2 detectors - polarizers)

#### DBLI A zero

Motor angle at which A waveplate axis is 0.

#### DBL B zero

Motor angle at which B waveplate axis is 0.

## Alpha (Hardy measurements only)

Angle Alpha used in the Hardy measurement.

## **Beta** (Hardy measurements only)

Angle Beta used in the Hardy measurement.

## Subtract Accidentals?

Determines whether or not accidental coincidences are subtracted. Controls data taking mode as well as tweaking mode.

## [DBL] coincidence resolution (ns)

The coincidence time resolutions (used in subtraction of accidentals).

#### **Pabe** Status

Program Status:

Initializing: initializing the counters and motors.

Reading Counters: Program is looping, reading the counters and updating the screen.

Moving Motors: Waveplates (polarizers) are rotating.

#### **P Meter** (4-detector Hardy measurements only)

Probability of AB

#### **DBL** A Desired Position

Angle to set A waveplate to.

Movement occurs after "Move Motors" button is pressed.

#### **DBLI** B Desired Position

Angle to set B waveplate to.

Movement occurs after "Move Motors" button is pressed.

#### **ITEL** Move Motors

Set the motors to the "Desired Positions"

A Position

Current angle of the A waveplate.

**B** Position

Current angle of the B waveplate.

**MOTOR Position** 

Actual position of the motor for the A waveplate.

Not the same as "A Position" because of the 0 position correction specified in "A zero".

**B** Motor Position

Actual position of the motor for the B waveplate.

Not the same as "B Position" because of the 0 position correction specified in "B zero".

Counter Port

A string that identifies the serial communication port that the DE2 board is attached to: "COM1", "COM2", etc. Note that you might need to scroll down to see this control.

U16 Controller

Which rotation stage controller to use: NewStep or ESP or Manual Control. Note that this is only read once at initialization, so it MUST be set BEFORE hitting run.

ESP Address / Port

GPIB Address of ESP controller (if present)

NewStep SerialPort

# of COM port that NewStep controller is connected to (if present)

NewStep Controller #

Controller # of the NewStep (if present)

A Axis #

Axis # of A rotation stage. For NewStep this is the Switchbox channel #.

B Axis #

Axis # of B rotation stage. For NewStep this is the Switchbox channel #.

Controller Data Out

For Program use.

## **Data Taking Parameters**

DBL

## **Update Period (Data Run)**

[Must be a multiple of 0.1s]

Time window (in s) for counters during data acquisition.

This applies after the "Take Data" button has been pressed.

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#### No. of Samples

Number of independent measurements (of H for Hardy measurements, or S for Bell Measurements) that are made during data acquisition. These are averaged to get the mean and error of the measurement.

Error measurements are essentially useless if this is less than 5. 10 is a good number for reasonable statistics.

TF

#### **Take Data**

Leave the setup "tweaking" mode and switch to data acquisition mode.

### **Bell Measurements**

DBL

E Meter (4-detector Bell measurement only)

**Expectation Value** 

DBL

**E** (4-detector Bell measurement only)

**Expectation Value** 

[DBL]

#### **S HWP Measurement Angles**

HWP angles at which probabilities that determine S will be measured.

Useful for 4 detector measurements so that you know which angles to set waveplates to when tweaking. Angles labeled + correspond to expectations you want to be as positive as possible, while those labeled - should be as negative as possible.

Not particularly useful for 2 detector measurements.

[DBL]

#### **S Pol Measurement Angles**

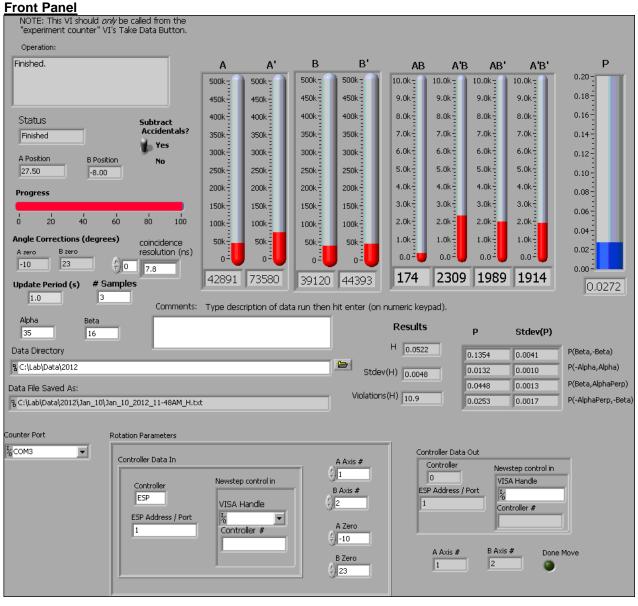
Polarizer angles at which probabilities that determine S will be measured.

Not a particularly useful parameter for 2 detector measurements.

## **II. Taking Data**

When you move to data taking mode, the program you see is:

## Hardy-Bell-Recorder\_rs232.vi



#### **Description**

This VI should ONLY be called from a "Hardy\_Bell\_rs232" VI--necessary parameters are set there.

This program records data (using parameters set in the "Hardy\_Bell\_rs232" VI) and saves the data to a file.

#### **Controls and Indicators**

## **Deration**

Displays what the program is trying to do. Normally this shows what the angles of the motors are.

There are 2 angles shown -- the waveplate angles are given first and the actual motor angles are in parentheses (they are different by the 0 offset displayed in "A zero" and "B zero".)

When the program is done this reads "Finished." Values for probabilities (expectations for Bell) and H (S for Bell) are not updated until this happens.

#### **Pabe** Status

Program Status:

Moving Motors: waveplate (polarizer) motors are in motion.

Waiting: Clearing out the counter buffers after motors move.

Taking Data: Data is being collected.

Finished: Program is done.

#### **▶ DBL** A position

Current position of A motor.

#### B Position

Current position of B motor.

#### **III** Subtract Accidentals?

Determines whether or not accidental coincidences are subtracted.

## [DBL) coincidence resolution (ns)

Array of the coincidence time resolutions (used in subtraction of accidentals).

#### **DBL** Progress

Rough indication of what percentage of the data run is complete.

#### PDBL A zero

Motor angle at which A waveplate axis is 0.

#### **PDBL** B zero

Motor angle at which B waveplate axis is 0.

#### **DBL** Update Period

Time window (in s) for counters.

### FI32 # Samples

Number of independent measurements (of H for Hardy measurements, or S for Bell Measurements) that are made during data acquisition. These are averaged to get the mean and error of the measurement.

Error measurements are essentially useless if this is less than 5. 10 is a good number for reasonable statistics.

#### **Line** Comments

A space where you can enter comments about the data run. These get saved in the header of the data file.

Note that you must hit "Enter" on the NUMERIC KEYPAD, not the "Enter" (or "Return") on the regular keyboard for this text to be saved.

## Data Directory

Path to directory where the data will be saved.

#### Data File Saved As:

Path to the data file. The data file is automatically named using the date and time.

## **DBLI** Alpha

Angle Alpha used in the Hardy measurement.

#### **DBL** Beta

Angle Beta used in the Hardy measurement.

#### **H** (Hardy measurement only)

Mean value of H. Updated when "operation" reads "Finished".

#### Stdev(H) (Hardy measurement only)

Standard Deviation of H. Updated when "operation" reads "Finished".

#### Violations(H) (Hardy measurement only)

Number of standard deviations that H is above 1. Updated when "operation" reads "Finished".

#### [DBL] P Stdev(P)

Probabilities and standard deviations of the probabilities for the indicated angles. Udated when "Operation" reads "Finished".

#### **P** (4 detector Hardy only)

Probability of AB

#### **I**Counter Port

A string that identifies the serial communication port that the DE2 board is attached to: "COM1", "COM2", etc.

#### Rotation Parameters

Inputs containing parameters describing rotation stages

#### IBI A Axis #

Axis # of A rotation stage. For NewStep this is the Switchbox channel #.

#### B Axis #

Axis # of B rotation stage. For NewStep this is the Switchbox channel #.

## Done Move

For program use.

## **Bell Measurements**

**S** (Bell measurement only)

Mean Value of S. Updated when "Operation" reads "Finished".

Stdev(S) (Bell measurement only)

Standard deviation of S. Updated when "Operation" reads "Finished".

Violations(S) (Bell measurement only)

Number of standard deviations that S is above 2. Updated when "Operation" reads "Finished".

**E** (4 detector Bell only)

Expectation value.

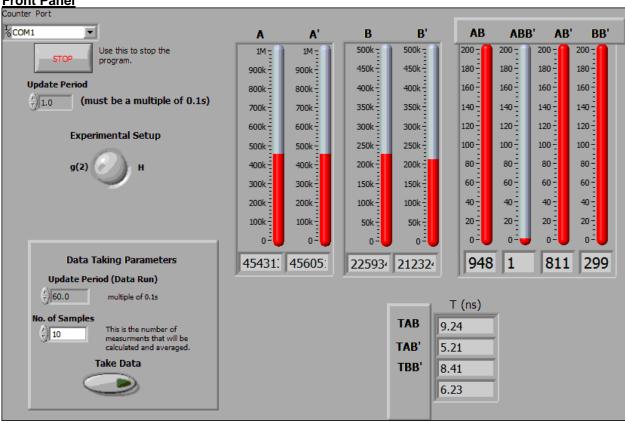
## Appendix F – Coincidence\_time\_res\_rs232.vi

This appendix describes the LabView vi used to calibrate the coincidence time resolution.

## I. Starting Out

The appearance of this vi will change slightly depending on the experiment you are doing (as determined by the **Experimental Setup** knob on the vi.)

# Coincidence\_time\_res\_rs232.vi Front Panel



## **Description**

This is the program you use to calibrate the coincidence time resolution of your coincidence circuit. It was specifically written for the Altera DE2 counter. Data streams to the computer from the DE2 over the RS232 serial port at 10 Hz.

In order to get accurate readings, the SPCMs must be illuminated by uncorrelated random streams of photons. One way to do this is to simply place a white card after the downconversion crystal to scatter blue pump light. There are plenty of scattered photons to get through the RG780 blocking filters. The intensity level can be adjusted somewhat by moving the card closer or further away from the exit face of the crystal. Adjusting iris diameters can help as well. 500k to 1M singles cps on each detector works well.

For example, with random photons the coincidence time resolution TAB for AB coincidences is  $TAB=(AB^*T)/(A^*B)$ , where T is the counting time, AB the number of coincidences, and A and B the number of singles.

There are 2 modes:

- 1) g(2)measures the resolution for AB, AB' and BB' coincidences. (random photons do not give an accurate measurement of the ABB' triple time because for those measurements you WANT at least one valid coincidence).
  - 2) H measures the time resolution for AB,. A'B, AB' and A'B' coincidences.

NOTE: The coincidence determination switches on the DE2 must be matched to the "Experimental Setup" switch here on the vi—appropriate switch settings are given below.

The program does not record data to a file right away, but displays the counters in real time so that you can align things.

Once everything is aligned and the parameters are set, you press the "Take Data" button. This transfers control to another program which records a data set and saves it to a file.

The DE2 board must be properly set to record the proper coincidences. The coincidences that should be mapped to a given counter are:

When set to g(2): A (Counter 0) B (Counter 1) A' (Counter 2) – unused for g(2) measurements B' (Counter 3) AB (Counter 4) ABB' (Counter 5) – used for g2 measurements, but not by this program AB' (Counter 6) BB' (Counter 7) When set to H: A (Counter 0) B (Counter 1) A' (Counter 2) B' (Counter 3) AB (Counter 4) A'B (Counter 5) AB' (Counter 6) A'B' (Counter 7)

On startup, the program initializes the com port.

After initialization the program simply loops and displays the counts in a given time window (determined by the "Update Period" control in the upper left.) This is useful for tweaking the alignment and adjusting parameters.

Nothing is written to disk until the parameters are chosen and the "Take Data" button is pressed. This loads a second VI that records and saves data to disk. Parameters for this data acquisition phase are set in the "Data Taking Parameters" box.

Help for each of the controls and indicators can be obtained from the Contextual Help window <cntrl - H> by mousing over each control or indicator. Full documentation for each control and indicator can be obtained by printing using: File>Print>Custom, and then checking "All controls" and "Descriptions".

## **Controls and Indicators**



#### **Counter Port**

A string that identifies the serial communication port that the DE2 board is attached to: "COM1", "COM2", etc.

#### I32

## **Experimental Setup**

Which calibration to perform.

- 1) g(2)measures the resolution for AB, AB' and BB' coincidences.
- 2) H measures the time resolution for AB, A'B, AB' and A'B' coincidences.

## **Update Period**

[Must be a multiple of 0.1s]

Time window (in s) for the counters during setup phase (i.e., before the "Take Data" button is pressed.)

## **□** Stop

Use this to stop. It takes a little longer, but this way, the board gets reset. If you stop some other way you'll probably need to quit Labview and restart; you may even need to reboot the computer.

#### [U32] Counts A, A', B & B'

Singles counts in the time window specified by "Update Period" (upper left)

## [U32] Coincidences

AB, A'B, AB', A'B' for H measurements

AB, ABB', AB', BB' for g2 measurements.

Coincidence counts (doubles or triples as indicated) in the time window specified by "Update Period" (upper left)

## [DBL] T (ns)

Values of coincidence time resolution (in ns) for the current iteration.

#### 1321 No. of Samples

Number of independent measurements that are made during data acquisition. These are averaged to get the mean and error of the measurement.

Error measurements are essentially useless if this is less than 5. 10 is a good number for reasonable statistics.

#### **DBLI** Update Period (Data Run)

Time window (in S) for counters during data acquisition.

This applies after the "Take Data" button has been pressed.

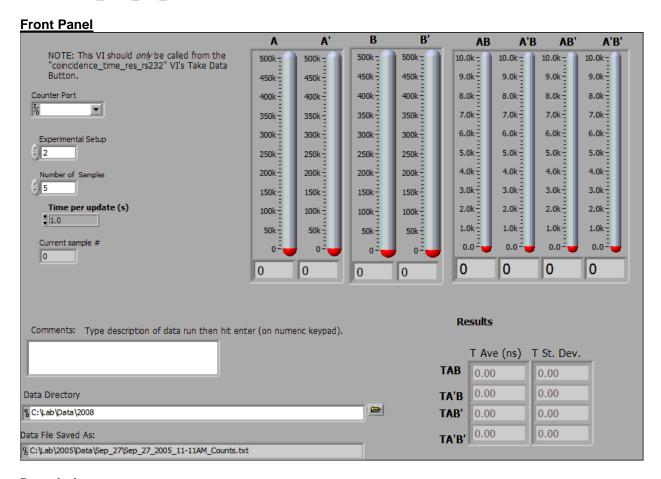
## Take Data

Leave the setup "tweaking" mode and switch to data acquisition mode.

## **II. Taking Data**

When you move to data taking mode, the program you see will look something like that shown below. Again, the appearance of this vi will change slightly depending on the calibration you are doing.

#### coincidence\_time\_res\_recorder.vi



## **Description**

This VI should ONLY be called from an "coincidence\_time\_res\_rs232" VI--necessary parameters are set there.

This program records data (using parameters set in the "coincidence\_time\_res\_rs232" VI) and saves the data to a file.

#### **Controls and Indicators**

Counter Port

A string that identifies the serial communication port that the DE2 board is attached to: "COM1", "COM2", etc.

**U321** Experimental Setup

Which calibration is being performed.

1: g2 calibration

2: H calibration

1321 Number of Samples

Number of independent measurements that are made during data acquisition. These are averaged to get the mean and error of the measurement.

**DBLI** Time per update (s)

Time window (in s) of counters during data acquisition.

**Li32** Current sample #

Which sample number is presently being measured.

[U32] Counts A, A', B & B'

Singles counts in the time window specified by "Time per update"

[U32] Coincidences

AB, A'B, AB', A'B' for H measurements

AB, ABB', AB', BB' for g2 measurements.

Coincidence counts (doubles or triples as indicated) in the time window specified by "Time per update"

**Label** Comments

A space where you can enter comments about the data run. These get saved in the header of the data file.

Note that you must hit "Enter" on the NUMERIC KEYPAD, not the "Enter" (or "Return") on the regular keyboard for this text to be saved.

Data Directory

Path to directory where the data will be saved.

Data File Saved As:

Path to the data file. The data file is automatically named using the date and time.

[DBL] T Ave (ns)

Measured average time resoltion in ns.

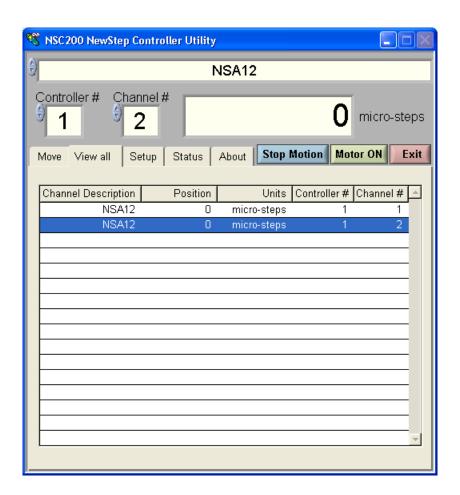
[DBL] T St. Dev.

Standard deviation of the measured time resolutions in ns.

## **Appendix G – NewStep Rotation Stage Configuration**

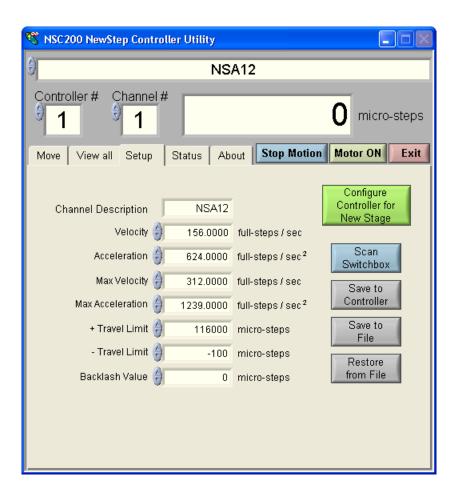
In order for the NewStep rotation stages to work properly, the controller must be configured to recognize them.

- 1. Setup the controller, switchbox and rotation stages according to the instructions.
- 2. Run NewStep Utility software, and follow the instructions to communicate with your controller.
- 3. Once the switchbox has been scanned, you should see the following:

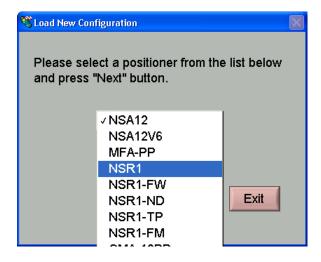


4. Note that the controller thinks you have NSA12 linear stages connected, and not NSR1 rotation stages.

5. Click on the "Setup" tab, and select the first channel number.



6. Click "Configure Controller for New Stage". A popup window opens; select "NSR1",:



- 7. Click "Next", then click "Next" again.
- 8. Repeat the above to configure the second channel.
- 9. Under the "Setup" tab, click "Save to Controller". This saves the setup information to non-volatile memory on the controller.
- 10. Exit the setup utility.