

Jump Type Cahn-Hilliard Equations with Fractional Noises****

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Abstract The authors explore a class of jump type Cahn-Hilliard equations with fractional noises. The jump component is described by a (pure jump) Lévy space-time white noise. A fixed point scheme is used to investigate the existence of a unique local mild solution under some appropriate assumptions on coefficients.

Keywords Cahn-Hilliard equations, Fractional noises, Lévy space-time white noise,
 Local mild solution

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1 Introduction

It is well-known that a classical model for the process of the spinodal decomposition can be described by a Cahn-Hilliard equation on the domain $[0, T] \times [0, \pi]^d$ (see [7, 16] and their references therein) as follows:

$$\frac{\partial u}{\partial t} + \Delta^2 u - \Delta f(u) = 0, \quad (1.1)$$

which describes the complicated phase separation and coarsening phenomena in a melted alloy. Here the mapping f is the derivative of the homogeneous free energy \tilde{F} , which contains a logarithmic term. In some cases, \tilde{F} can be approximated by an even-degree polynomial with positive dominant coefficient. A standard choice for f is a cubic polynomial such as $f(u) = u - u^3$.

This paper deals with the following jump type Cahn-Hilliard equations with fractional noise potentials:

$$\begin{cases} \square u(t, x) = \Delta b(u(t, x)) + \dot{B}^H(x, t) + a(u(t, x))\dot{F}(x, t), & \text{in } [0, T] \times D, \\ u(0) = \psi, \\ \frac{\partial u}{\partial n} = \frac{\partial \Delta u}{\partial n} = 0, & \text{on } [0, T] \times \partial D, \end{cases} \quad (1.2)$$

where the operator $\square := \frac{\partial}{\partial t} + \Delta^2$ with the Laplace operator Δ , and the domain $D = [0, \pi]^d$. In addition, \dot{B}^H denotes a fractional noise on $D \times [0, \infty)$ with Hurst parameter $H > \frac{1}{2}$, and \dot{F} is

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a (pure jump) Lévy space-time white noise on $D \times [0, \infty)$. The nonlinear drift $b : \mathbf{R} \rightarrow \mathbf{R}$ is a polynomial of degree 3 with positive dominant coefficients and $a : \mathbf{R} \rightarrow \mathbf{R}$ is a measurable map satisfying additional assumptions (see Section 4 below).

Second order heat equations with fractional noises have been investigated in the literature (see [9, 11, 14, 17, 21]). Among them, Duncan et al. [9] and Tindel et al. [21] investigated a class of parabolic equations with linear fractional noise terms, where the Hurst parameter H in [9] was restricted to $H > \frac{1}{2}$, and the later treats both cases $H > \frac{1}{2}$ and $H < \frac{1}{2}$. The heat equations with a multiplicative fractional noise of Hurst parameter $H = (h_0, \dots, h_d)$ on $[0, \infty) \times \mathbf{R}^d$ were proposed by Hu [11] and the author established the existence and uniqueness of mild solutions to the equation under some assumptions on H , through chaos expansion. For a nonlinear evolution equation in some Hilbert space, Maslowski and Nualart [14] proved the existence and uniqueness of mild solutions for the equation with a cylindrical fractional Brownian motion (FBM) under $H > \frac{1}{2}$. This leads one to define stochastic integrals with respect to FBM in a pathwise way (see also [18]). In [17], Nualart and Ouknine discussed a quasi-linear parabolic equation driven by an additive fractional noise on $[0, \infty) \times [0, 1]$.

Recently, a class of stochastic Cahn-Hilliard equations with Gaussian noise perturbations were introduced in [8, 5, 6], respectively. Furthermore, Bo and Wang [4] established a unique local solution to a stochastic Cahn-Hilliard equation driven by a Lévy space-time white noise, in which a new version of Burkholder-Davis-Gundy inequality (B-D-G inequality) played a key role (see also Proposition 3.2 below). In [2], Bo et al formulated a fourth-order Anderson model with double-parameter fractional noises on one-dimensional space by employing the Skorohod integral. In the present paper, we are going to develop several different versions of B-D-G inequalities for treating the jump component of (1.2). For the fractional noise term, we will limit our consideration on the linear additive fractional noises with Hurst parameter $H > \frac{1}{2}$ as proposed by Nualart and Ouknine [17]. Our aim is to establish the existence of a unique local mild solution to (1.2).

The outline of this paper is as follows. In the coming section, we will give the definitions of the fractional B^H and the pure jump Lévy noise F , respectively. In Section 3, several different B-D-G inequalities are presented. The statement of main result and its proof will be given in Section 4.

2 Fractional and Lévy Noises

In this section, we will present the definitions of the fractional noises, Lévy space-time white noises and stochastic integrals with respect to them in the respective subsections.

2.1 Fractional noises

Let $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \geq 0}, \mathbf{P})$ be a complete probability space with the filtration $(\mathcal{F}_t)_{t \geq 0}$ satisfying the usual conditions, on which $(B^H(A \times [0, t]))_{(t, A) \in [0, T] \times \mathcal{B}(D)}$ is a centered Gaussian family of random variables with the covariance, for $H \in (0, 1)$,

$$\mathbf{E}[B^H(A \times [0, t])B^H(B \times [0, s])] = |A \cap B|R_H(t, s), \quad s, t \in [0, T], \quad A, B \in \mathcal{B}(D),$$

with the covariance kernel

$$R_H(t, s) = \frac{1}{2}[t^{2H} + s^{2H} - |t - s|^{2H}].$$

Here $|A|$ denotes Lebesgue measure of the set $A \in \mathcal{B}(D)$.

We denote by ϵ the set of step functions on $D \times [0, T]$. Let \mathcal{H} be the Hilbert space defined as the closure of ϵ with respect to the scalar product

$$\langle \mathbf{1}_{[0,t] \times A}, \mathbf{1}_{[0,s] \times B} \rangle_{\mathcal{H}} = |A \cap B| R_H(t, s).$$

Thus the mapping $\mathbf{1}_{[0,t] \times A} \rightarrow B^H(A \times [0, t])$ is an isometry between \mathcal{E} and the linear space $\text{span}\{B^H(A \times [0, t]), A \in \mathcal{B}(D), t \in [0, T]\}$, a subspace of $L^2(\Omega)$. Moreover, the mapping can be extended to an isometry from \mathcal{H} to Gaussian space associated with B^H . This isometry will be denoted by $\varphi \rightarrow B^H(\varphi)$ for $\varphi \in \mathcal{H}$. Therefore, we can regard $B^H(\varphi)$ as the stochastic integral with respect to B^H . In general, we use the notation

$$\int_{[0,T] \times D} \varphi(y, s) B^H(dy, ds)$$

to represent $B^H(\varphi)$. On the other hand, it is known that the covariance kernel $R_H(t, s)$ satisfies

$$R_H(t, s) = \int_0^{t \wedge s} K_H(t, u) K_H(s, u) du,$$

where the kernel

$$K_H(t, s) = c_H(t-s)^{H-\frac{1}{2}} + c_H\left(\frac{1}{2} - H\right) \int_s^t (u-s)^{H-\frac{3}{2}} \left(1 - \left(\frac{s}{u}\right)^{\frac{1}{2}-H}\right) du$$

for some constant c_H . In particular, if $H > \frac{1}{2}$, then

$$R_H(t, s) = H(2H-1) \int_0^t \int_0^s |u-v|^{2H-2} du dv. \quad (2.1)$$

Define a linear operator $K_H^* : \mathcal{E} \rightarrow L^2([0, T])$ by

$$(K_H^* \psi)(s, x) = K_H(T, s) \psi(s, x) + \int_s^T (\psi(u, x) - \psi(s, x)) \frac{\partial K_H}{\partial u}(u, s) du. \quad (2.2)$$

Then the operator K_H^* gives an isometry from \mathcal{H} to $L^2([0, T] \times D)$ (see [17, 21]). Consequently,

$$W(t, A) := B^H((K_H^*)^{-1}(\mathbf{1}_{[0,t] \times A})), \quad (t, A) \in [0, T] \times \mathcal{B}(D)$$

defines a space-time white noise. Moreover we can regard B^H as

$$B^H(A \times [0, t]) = \int_0^t \int_D K_H(t, s) W(dy, ds).$$

2.2 Lévy space-time white noises

Let $(E_i, \mathcal{E}_i, \mu_i)$, $i = 1, 2$ be two σ -finite measurable spaces. We call $N : (E_1, \mathcal{E}_1, \mu_1) \times (E_2, \mathcal{E}_2, \mu_2) \times (\Omega, \mathcal{F}, \mathbf{P}) \rightarrow \mathbf{N} \cup \{0\} \cup \{\infty\}$ a Poisson noise on $(E_1, \mathcal{E}_1, \mu_1)$, if for all $A \in \mathcal{E}_1$, $B \in \mathcal{E}_2$ and $n \in \mathbf{N} \cup \{0\} \cup \{\infty\}$,

$$\mathbf{P}(\omega \in \Omega : N(A, B, \omega) = n) = \frac{e^{-\mu_1(A)\mu_2(B)} [\mu_1(A)\mu_2(B)]^n}{n!}. \quad (2.3)$$

In particular, when $(E_1, \mathcal{E}_1, \mu_1) = ([0, \infty) \times D, \mathcal{B}([0, \infty) \times D), dt \times dx)$, we can define the compensated random martingale measure

$$M(B, A, t) = N([0, t] \times A, B) - \mu_1([0, t] \times A)\mu_2(B) \quad (2.4)$$

by assuming that $\mu_1([0, t] \times A)\mu_2(B) < \infty$ for all $(t, A, B) \in [0, \infty) \times \mathcal{B}(D) \times \mathcal{E}_2$. Moreover, let $f : E_1 \times E_2 \times \Omega \rightarrow \mathbf{R}$ be an $(\mathcal{F}_t)_{t \geq 0}$ -predictable random process satisfying

$$\mathbf{E} \left[\int_0^t \int_A \int_B |f(s, x, y)|^2 \mu_2(dy) dx ds \right] < \infty \quad (2.5)$$

for all $t > 0$ and $(A, B) \in \mathcal{E}_1 \times \mathcal{E}_2$. Then the stochastic integral process

$$\left(R_t := \int_0^{t+} \int_A \int_B f(s, x, y) M(dy, dx, ds) \right)_{t \geq 0} \quad (2.6)$$

is a square integrable $(\mathcal{F}_t)_{t \geq 0}$ -martingale. It is well-known that a (pure jump) Lévy space-time white noise admits the following structure:

$$\dot{F}(x, t) = \int_{U_0} h_1(t, x, y) \dot{M}(dy, x, t) + \int_{E_2 \setminus U_0} h_2(t, x, y) \dot{N}(dy, x, t) \quad (2.7)$$

for some $U_0 \in \mathcal{E}_2$ such that $\mu_2(E_2 \setminus U_0) < \infty$. Here $h_1, h_2 : [0, \infty) \times D \times E_2 \rightarrow \mathbf{R}$ are measurable maps; \dot{M} and \dot{N} denote the Radon-Nikodym derivatives

$$\dot{M}(dy, x, t) := \frac{M(dy, dx, dt)}{dt \times dx}, \quad \dot{N}(dy, x, t) := \frac{N(dt \times dx, dy)}{dt \times dx} \quad (2.8)$$

with $(t, x, y) \in [0, \infty) \times D \times E_2$ (see [22]).

3 Burkholder-Davis-Gundy Inequalities

In order to estimate the higher order moments of mild solutions to (1.2), we need several different versions of Burkholder-Davis-Gundy inequalities. Those are quoted from [13, Theorem 4.1] and [10, Corollary 3.1], respectively. Let us first recall the usual Burkholder's inequality (see [19]).

Proposition 3.1 *Let $f : [0, \infty) \times D \times E_2 \times \Omega \rightarrow \mathbf{R}$ be an $(\mathcal{F}_t)_{t \geq 0}$ -predictable process satisfying (2.5). Denote by X the integral process*

$$\left(X_t := \int_0^{t+} \int_D \int_{E_2} f(s, y, z) M(dz, dy, ds) \right)_{t \geq 0}.$$

Then for $T > 0$ and $q \geq 1$, there exists a constant $C_1(q) > 0$ such that

$$\mathbf{E} \left[\sup_{t \in [0, T]} |X_t|^q \right] \leq C_1(q) \mathbf{E}[X, X]_T^{\frac{q}{2}}, \quad (3.1)$$

where $[X, X]_t = \int_0^t \int_D \int_{E_2} |f(s, y, z)|^2 N(ds \times dy, dz)$ is the quadratic variation process of X .

Remark 3.1 Note that, in Proposition 3.1,

$$\mathbf{E}[X, X]_t = \int_0^t \int_D \int_{E_2} |f(s, y, z)|^2 \mu_2(dz) dy ds.$$

Then Jensen's inequality yields, for $q \in [1, 2]$,

$$\mathbf{E} \left[\sup_{t \in [0, T]} |X_t|^q \right] \leq C_1(q) \left[\int_0^T \int_D \int_{E_2} \mathbf{E} |f(s, y, z)|^2 \mu_2(dz) dy ds \right]^{\frac{q}{2}}. \quad (3.2)$$

Proposition 3.2 Let $(X_t)_{t \geq 0}$ be defined as in Proposition 3.1. Then for $T > 0$ and $q \geq 2$, there exists a constant $C_2(q) > 0$ such that

$$\sup_{t \in [0, T]} \mathbf{E}[|X_t|^q] \leq C_2(q) \left[\int_0^T \int_D \int_{E_2} (\mathbf{E} |f(s, y, z)|^q)^{\frac{2}{q}} \mu_2(dz) dy ds \right]^{\frac{q}{2}}. \quad (3.3)$$

On the other hand, let $\mathcal{L}^{\text{sym}}(E_2, \mathcal{E}_2)$ denote the total of all symmetric Lévy measure on (E_2, \mathcal{E}_2) (see [10, Definition 2.2]). If the measure $\mu_2 \in \mathcal{L}^{\text{sym}}(E_2, \mathcal{E}_2)$ for the separable Banach space E_2 and if $q \in [2, 4]$, then there exists $C_3(q) > 0$ such that

$$\sup_{t \in [0, T]} \mathbf{E}[|X_t|^q] \leq C_3(q) \int_0^T \int_D \int_{E_2} \mathbf{E} |f(s, y, z)|^q \mu_2(dz) dy ds. \quad (3.4)$$

In particular, if $q = p^n$ for some $n \in \mathbf{N}$ and $1 \leq p \leq 2$, then there exists $C_4(q) > 0$ such that

$$\mathbf{E} \left[\sup_{t \in [0, T]} |X_t|^q \right] \leq C_4(q) \sum_{k=1}^n \left[\int_0^T \int_D \int_{E_2} \mathbf{E} |f(s, y, z)|^{p^k} \mu_2(dz) dy ds \right]^{p^{n-k}}. \quad (3.5)$$

In what follows, we turn to the definition of the solutions to (1.2). An $(\mathcal{F}_t)_{t \geq 0}$ -adapted random field $u = (u(t, x))_{(t, x) \in [0, T] \times D}$ is called a weak solution of (1.2), if for all $\varphi \in C_0^\infty([0, T] \times \mathbf{R}^d)$ with $\frac{\partial \varphi}{\partial n}|_{[0, T] \times \partial D} = \frac{\partial \Delta \varphi}{\partial n}|_{[0, T] \times \partial D} = 0$, it holds that

$$\begin{aligned} \langle u(t), \varphi(t) \rangle &= \langle \psi, \varphi(0) \rangle + \int_0^t \left\langle \left(\frac{\partial}{\partial t} - \Delta^2 \right) \varphi(s), u(s) \right\rangle ds \\ &\quad + \int_0^t \langle \Delta \varphi(s), b(u)(s) \rangle ds + \int_0^t \int_D \varphi(s, x) B^H(dx, ds) \\ &\quad + \int_0^t \int_D \varphi(s, x) a(u(s, x)) F(dx, ds), \end{aligned} \quad (3.6)$$

where $\langle \cdot, \cdot \rangle$ denotes the usual inner product of $L^2(D)$.

Let $G(t, x, y) : [0, t] \times D^2 \rightarrow \mathbf{R}$ be the Green kernel of the operator $\frac{\partial}{\partial t} + \Delta^2$ with the homogeneous Neumann boundary condition as in (1.2) (see Appendix). Then by virtue of the

proof of [20, Theorem 2.1] (or see [5, (1.9)–(1.10)]), (3.6) is equivalent to the following mild form in the sense of Walsh [23]. For $(t, x) \in [0, T] \times D$,

$$\begin{aligned} u(t, x) = & \int_D G(t, x, y) \psi(y) dy + \int_0^t \int_D b(u(s, y)) \Delta_y G(t - s, x, y) dy ds \\ & + \int_0^t \int_D G(t - s, x, y) a(u(s, y)) g(s, y) dy ds + \int_0^t \int_D G(t - s, x, y) B^H(dy, ds) \\ & + \int_0^{t+} \int_D \int_{E_2} G(t - s, x, y) a(u(s-, y)) h(s, y, z) M(dz, dy, ds), \end{aligned} \quad (3.7)$$

where the maps g, h are given respectively by

$$\begin{aligned} g(t, y) &= \int_{E_2 \setminus U_0} h_2(t, y, z) \mu_2(dz), \\ h(t, y, z) &= h_1(t, y, z) \mathbf{1}_{U_0}(z) + h_2(t, y, z) \mathbf{1}_{E_2 \setminus U_0}(z), \end{aligned}$$

with indicator $\mathbf{1}_A(\cdot)$ of the set $A \in \mathcal{E}_2$. On the other hand, as in Section 2, the fractional integral term in (3.7) can be represented as

$$\int_0^t \int_D G(t - s, x, y) B^H(dy, ds) = \int_0^t \int_D [K_H^* G(t - \cdot, x, \cdot)](s, y) W(dy, ds), \quad (3.8)$$

with the space-time white noise $(W(t, x))_{(t, x) \in [0, T] \times D}$ mentioned in Section 2. We mainly study the existence of a local mild solution of (3.7). To achieve it, let $\|\cdot\|_q$ denote the usual norm of $L^q(D)$ with $q \in [1, \infty)$. Given $n \in \mathbf{N}$, define a C^1 -function $\Psi_n : [0, \infty) \rightarrow [0, \infty)$ by

$$\Psi_n(x) = \begin{cases} 1, & \text{if } x < n, \\ 0, & \text{if } x \geq n + 1, \end{cases} \quad (3.9)$$

and $\|\Psi'_n\|_\infty := \sup_{x \geq 0} |\Psi'_n(x)| \leq 2$. Let the random field $(u_n(t, x))_{(t, x) \in [0, T] \times D}$ be a unique solution of the following:

$$\begin{aligned} u_n(t, x) = & \int_D G(t, x, y) \psi(y) dy + \int_0^t \int_D G(t - s, x, y) B^H(dy, ds) \\ & + \int_0^t \int_D b(u_n(s, y)) \Delta_y G(t - s, x, y) \Psi_n(\|u_n(s, \cdot)\|_q) dy ds \\ & + \int_0^t \int_D G(t - s, x, y) a(u_n(s, y)) g(s, y) \Psi_n(\|u_n(s, \cdot)\|_q) dy ds \\ & + \int_0^{t+} \int_D \int_{E_2} G(t - s, x, y) a(u_n(s-, y)) h(s, y, z) M(dz, dy, ds). \end{aligned} \quad (3.10)$$

Define $\tau_n = \inf\{t > 0; \|u_n(t, \cdot)\|_q \geq n\}$ with $n \in \mathbf{N}$. Then, on the event $\{t < \tau_n\}$, $u_1(t, x) = u_2(t, x) = \cdots = u_n(t, x)$ is a solution of (3.10). Let $\tau = \lim_{n \rightarrow \infty} \tau_n$, and define $u(t, \cdot) = u_n(t, \cdot)$, on the event $\{t < \tau_n < \tau\}$. Therefore $u(t, \cdot)$ is a solution of (3.10) on $\{t < \tau\}$. We call it a local mild solution of (1.2). In the following section, we will prove that such a local solution as in (3.10) exists and it is unique.

4 Main Results and Proofs

At the beginning, we state the main result of the paper as follows. Let the interval $(\alpha, \beta] = (\alpha, \beta]$ if $\alpha < \beta$, and \emptyset otherwise.

Theorem 4.1 *Let $H \in (\frac{1}{2}, 1)$ and $d < \frac{4H}{2-H}$ with $d \in \mathbf{N}$. Suppose that the following conditions are satisfied:*

- (i) *b is a polynomial of degree 3 with positive dominant coefficients.*
- (ii) *a is Lipschitzian and has linear growth on \mathbf{R} , i.e. there exists a constant $C > 0$ such that $|a(x)| \leq C(1 + |x|)$, for all $x \in \mathbf{R}$.*
- (iii) *For g, h and μ_2 ,*

$$\sup_{t \in [0, T]} \|g(t, \cdot)\|_q < \infty \quad \text{with } q > d + 2. \quad (4.1)$$

- (1) *For $q \in (d + 2, 4]$,*
 - (a) $V_q := \sup_{(s, y) \in [0, T] \times D} \|h(s, y, \cdot) s^{-\frac{d}{4}}\|_{L^q(E_2, \mu_2)}^q < \infty$;
 - (b) $\mu_2 \in \mathcal{L}^{\text{sym}}(E_2, \mathcal{E}_2)$ *with separable Banach space E_2 .*
- (2) *For $q > (d + 2) \vee 4$,*
 - (a') $G(t - s, x, y)h(s, y, z)$ *is $L^q([0, t] \times D^2 \times E_2, ds \times dx \times dy \times \mu_2(dz))$ integrable, for $0 \leq t \leq T$;*
 - (b') $\mu_2(E_2) < \infty$.

Then for every \mathcal{F}_0 -adapted initial process $\psi : D \times \Omega \rightarrow \mathbf{R}$ satisfying $\mathbf{E}\|\psi(\cdot)\|_q^q < \infty$, there exists a unique local solution $(u(t, x))_{(t, x) \in [0, T] \times D}$ for (3.7) and there exists a stopping time τ such that

$$\sup_{t \in [0, T]} \mathbf{E}\|u(t \wedge \tau, \cdot)\|_q^q < \infty \quad \text{for all } q > d + 2.$$

Let Λ_q be the space of all $L^q(D)$ -valued \mathcal{F}_t -adapted RCLL processes $u(t, \cdot)$. For fixed $\lambda > 0$ and $q \in [2, \infty)$, define a norm $\|\cdot\|_{\Lambda_q}$ (depending on (λ, q)) on Λ_q by

$$\|u\|_{\Lambda_q} = \left[\sup_{t \in [0, T]} e^{-\lambda t} \mathbf{E}\|u(t, \cdot)\|_q^q \right]^{\frac{1}{q}} < \infty, \quad (4.2)$$

with $\|\cdot\|_q$ the usual norm of $L^q(D)$. Then $(\Lambda_q, \|\cdot\|_{\Lambda_q})$ forms a Banach space. Let $\psi \in \Lambda_q$. Recall (1.2) or (3.10). For $(t, x) \in [0, T] \times D$,

$$\begin{aligned} u_n(t, x) &= \int_D G(t, x, y) \psi(y) dy + \int_0^t \int_D G(t - s, x, y) B^H(dy, ds) \\ &\quad + \int_0^t \int_D b(u_n(s, y)) \Delta_y G(t - s, x, y) \Psi_n(\|u_n(s, \cdot)\|_q) dy ds \\ &\quad + \int_0^t \int_D G(t - s, x, y) a(u_n(s, y)) g(s, y) \Psi_n(\|u_n(s, \cdot)\|_q) dy ds \\ &\quad + \int_0^{t+} \int_D \int_{E_2} G(t - s, x, y) a(u_n(s, y)) h(s, y, z) M(dz, dy, ds) \\ &:= \mathcal{A}_0(\phi)(t, x) + \sum_{i=1}^4 \mathcal{A}_i(u_n)(t, x). \end{aligned} \quad (4.3)$$

According to (4.3), we have

Proposition 4.1 *Under the assumptions of Theorem 4.1, for each $q > d + 2$ and $u \in \Lambda_q$, it holds that $\mathcal{A}_i(u) \in \Lambda_q$, $i = 0, \dots, 4$.*

Proof From (A.2), Minkovski's inequality and Young's inequality for $\frac{1}{q} = 1 + \frac{1}{q} - 1$, it follows that

$$\begin{aligned} \|\mathcal{A}_0(\phi)(t, \cdot)\|_q &\leq K t^{-\frac{d}{4}} \left\| \int_D \exp\left(-C \frac{|\cdot - y|^{\frac{4}{3}}}{t^{\frac{1}{3}}}\right) \psi(y) dy \right\|_q \\ &\leq K t^{-\frac{d}{4}} \left\| \left(\exp\left(-C \frac{|\cdot|^{\frac{4}{3}}}{t^{\frac{1}{3}}}\right) * \psi(\cdot) \right)(\cdot) \right\|_q \\ &\leq K t^{-\frac{d}{4}} \left\| \exp\left(-C \frac{|\cdot|^{\frac{4}{3}}}{t^{\frac{1}{3}}}\right) \right\|_1 \|\psi(\cdot)\|_q \\ &= C \|\psi(\cdot)\|_q. \end{aligned} \quad (4.4)$$

Therefore $\mathcal{A}_0(\phi) \in \Lambda_q$ if $\mathbf{E} \|\psi(\cdot)\|_q^q < \infty$. Next we turn to $\mathcal{A}_1(u)$. Let $\frac{1}{r_1} = \frac{1}{q} - \frac{1}{\rho} + 1 \in [0, 1]$. Applying (A.6), we conclude that

$$\|\mathcal{A}_1(u)(t, \cdot)\|_q \leq C \int_0^t (t-s)^{-\frac{d+2}{4} + \frac{d}{4r_1}} \|b(u(s, \cdot)) \Psi_n(\|u(s, \cdot)\|_q)\|_\rho ds. \quad (4.5)$$

In particular, let $\rho = \frac{q}{3}$. Then by the assumption (i) in Theorem 4.1,

$$\|b(u(s, \cdot))\|_\rho \leq C [\|u(s, \cdot)\|_q + \|u(s, \cdot)\|_q^2 + \|u(s, \cdot)\|_q^3].$$

Consequently,

$$\|\mathcal{A}_1(u)(t, \cdot)\|_q \leq C_n \int_0^t (t-s)^{-\frac{d+2}{4} + \frac{d}{4r_1}} ds, \quad (4.6)$$

which is finite if $\frac{d}{4r_1} - \frac{d+2}{4} > -1$. Since $\frac{1}{r_1} = \frac{q-2}{q}$, we have $\mathcal{A}_1(u) \in \Lambda_q$ for $q > d$. As for $\mathcal{A}_2(u)$, by virtue of (A.5), we have for $\frac{1}{r_2} = \frac{1}{q} - \frac{2}{q} + 1 = -\frac{1}{q} + 1 \in [0, 1]$,

$$\begin{aligned} \|\mathcal{A}_2(u)(t, \cdot)\|_q &\leq C \int_0^t (t-s)^{\frac{d}{4r_2} - \frac{d}{4}} \|g(s, \cdot) a(u(s, \cdot)) \Psi_n(\|u(s, \cdot)\|_q)\|_{\frac{q}{2}} ds \\ &\leq C \int_0^t (t-s)^{\frac{d}{4r_2} - \frac{d}{4}} \|g(s, \cdot) (1 + |u(s, \cdot)|) \Psi_n(\|u(s, \cdot)\|_q)\|_{\frac{q}{2}} ds \\ &\leq C \int_0^t (t-s)^{\frac{d}{4r_2} - \frac{d}{4}} [\|g(s, \cdot)\|_{\frac{q}{2}} + \|g(s, \cdot) u(s, \cdot)\|_{\frac{q}{2}}] \Psi_n(\|u(s, \cdot)\|_q) ds \\ &\leq C_q \int_0^t (t-s)^{\frac{d}{4r_2} - \frac{d}{4}} [\|g(s, \cdot)\|_q + \|g(s, \cdot)\|_q \|u(s, \cdot)\|_q] \Psi_n(\|u(s, \cdot)\|_q) ds \\ &\leq C_q \int_0^t (t-s)^{\frac{d}{4r_2} - \frac{d}{4}} [\|g(s, \cdot)\|_q + (n+1) \|g(s, \cdot)\|_q] ds \\ &\leq C_{n,q} \sup_{t \in [0, T]} \|g(t, \cdot)\|_q \int_0^t (t-s)^{\frac{d}{4r_2} - \frac{d}{4}} ds \\ &< \infty, \end{aligned} \quad (4.7)$$

provided $q > \frac{d}{4}$. Therefore $\mathcal{A}_2(u) \in \Lambda_q$ as $q > \frac{d}{4}$. In what follows, let us consider $\mathcal{A}_3(u)$. Applying the B-D-G inequality (3.1), we conclude that,

$$\begin{aligned}
\mathbf{E} \|\mathcal{A}_3(u)(t, \cdot)\|_q^q &= \int_D \mathbf{E} \left| \int_0^t \int_D G(t-s, x, y) B^H(dy, ds) \right|^q dx \\
&= \int_D \mathbf{E} \left| \int_0^t \int_D (K_H^* G(t-\cdot, x, \cdot))(s, y) W(dy, ds) \right|^q dx \\
&\leq C_q \int_D \mathbf{E} \left(\int_0^t \int_D (K_H^* G(t-\cdot, x, \cdot))^2(s, y) dy ds \right)^{\frac{q}{2}} dx \\
&= C_q \int_D \langle (K_H^* G(t-\cdot, x, \cdot))(\cdot, \cdot), (K_H^* G(t-\cdot, x, \cdot))(\cdot, \cdot) \rangle_{L^2([0, T] \times D)}^{\frac{q}{2}} dx \\
&= C_q \int_D \langle G(t-\cdot, x, \cdot), G(t-\cdot, x, \cdot) \rangle_{\mathcal{H}}^{\frac{q}{2}} dx \\
&\leq C_q \int_D \|G(t-\cdot, x, \cdot)\|_{L^{\frac{2}{H}}([0, T] \times D)}^q dx,
\end{aligned} \tag{4.8}$$

where we have used the fact that $L^{\frac{2}{H}}([0, T] \times D) \subset \mathcal{H}$ when $H > \frac{1}{2}$ (see [15, Theorem 1], but we need to modify their proof which is given in Appendix below). Note that

$$\begin{aligned}
\|G(t-\cdot, x, \cdot)\|_{L^{\frac{2}{H}}([0, T] \times D)}^q &= \left[\int_0^T \int_D |G(t-s, x, y)|^{\frac{2}{H}} dy ds \right]^{\frac{qH}{2}} \\
&= \left[\int_0^t \int_D |G(t-s, x, y)|^{\frac{2}{H}} dy ds \right]^{\frac{qH}{2}} \\
&\leq \left[\int_0^t (t-s)^{-\frac{d}{2H}} \int_D \exp\left(-C_H \frac{|x-y|^{\frac{4}{3}}}{(t-s)^{\frac{1}{3}}}\right) dy ds \right]^{\frac{qH}{2}} \\
&\leq C_H \left[\int_0^t (t-s)^{\frac{d}{4} - \frac{d}{2H}} ds \right]^{\frac{qH}{2}} \\
&\leq C_H T^{\frac{qH}{2}(1 + \frac{d}{4} - \frac{d}{2H})} \\
&< \infty,
\end{aligned} \tag{4.9}$$

under the assumption $d < \frac{4H}{2-H}$ of Theorem 4.1. So we have $\mathcal{A}_3(u) \in \Lambda_q$ for $q \geq 2$. Now we estimate $\mathcal{A}_4(u)$. In the case of $q \in (d+2, 4]$, the inequality (3.4) of Proposition 3.2 yields

$$\begin{aligned}
\|\mathcal{A}_4(u)\|_{\Lambda_q}^q &= \sup_{t \in [0, T]} e^{-\lambda t} \mathbf{E} \|\mathcal{A}_4(u)(t, \cdot)\|_q^q \\
&= \sup_{t \in [0, T]} e^{-\lambda t} \int_D \mathbf{E} \left(\left| \int_0^{t+} \int_D \int_{E_2} G(t-s, x, y) h(s, y, z) \right. \right. \\
&\quad \left. \left. \times a(u(s-, y)) M(dz, dy, ds) \right|^q \right) dx \\
&\leq C_q \sup_{t \in [0, T]} e^{-\lambda t} \int_D \left(\int_0^t \int_D \int_{E_2} |G(t-s, x, y) h(s, y, z)|^q \right. \\
&\quad \left. \times \mathbf{E}[|a(u(s, y))|^q] \mu_2(dz) dy ds \right) dx \\
&= C_q \sup_{t \in [0, T]} e^{-\lambda t} \int_0^t \int_D \left(\int_D \int_{E_2} |G(t-s, x, y) h(s, y, z)|^q \mu_2(dz) dx \right)
\end{aligned}$$

$$\begin{aligned}
& \times \mathbf{E}[|a(u(s, y))|^q] dy ds \\
& \leq C_q V_q \sup_{t \in [0, T]} e^{-\lambda t} \int_0^t |t-s|^{\frac{d}{4}} \mathbf{E} \left[\int_D |a(u(s, y))|^q dy \right] ds \\
& \leq C_q V_q \sup_{t \in [0, T]} e^{-\lambda t} \int_0^t |t-s|^{\frac{d}{4}} \mathbf{E}[\|a(u(s, \cdot))\|_q^q] ds \\
& \leq C_q V_q \sup_{t \in [0, T]} \int_0^t |t-s|^{\frac{d}{4}} e^{-\lambda(t-s)} (1 + e^{-\lambda s} \mathbf{E}[\|u(s, \cdot)\|_q^q]) ds \\
& \leq C_q V_q (1 + \|u\|_{\Lambda_q}^q) \int_0^T s^{\frac{d}{4}} e^{-\lambda s} ds \\
& \leq C_q V_q (1 + \|u\|_{\Lambda_q}^q) \frac{\Gamma(\frac{d}{4} + 1)}{\lambda^{\frac{d}{4} + 1}} \\
& < \infty,
\end{aligned} \tag{4.10}$$

where V_q is defined by Theorem 4.1(iii)(1)(a) and $\Gamma(\cdot)$ denotes the Gamma function.

As for $q > (d+2) \vee 4$, by the hypotheses Theorem 4.1(ii), (iii) and the inequality (3.3), it follows that

$$\begin{aligned}
\|\mathcal{A}_4(u)\|_{\Lambda_q}^q &= \sup_{t \in [0, T]} e^{-\lambda t} \mathbf{E} \|\mathcal{A}_4(u)(t, \cdot)\|_q^q \\
&= \sup_{t \in [0, T]} e^{-\lambda t} \int_D \mathbf{E} \left(\left| \int_0^t \int_D \int_{E_2} G(t-s, x, y) h(s, y, z) \right. \right. \\
&\quad \left. \left. \times a(u(s, y)) M(dz, dy, ds) \right|^q \right) dx \\
&\leq C_q \sup_{t \in [0, T]} e^{-\lambda t} \int_D \left(\int_0^t \int_D \int_{E_2} (\mathbf{E} |G(t-s, x, y) h(s, y, z) a(u(s, y))|^q)^{\frac{2}{q}} \right. \\
&\quad \left. \times \mu_2(dz) dy ds \right)^{\frac{q}{2}} dx \\
&\leq C_q \sup_{t \in [0, T]} e^{-\lambda t} \int_D \left(\int_0^t \int_D \int_{E_2} |G(t-s, x, y) h(s, y, z)|^2 e^{\frac{2\lambda s}{q}} \right. \\
&\quad \left. \times (e^{-\lambda s} \mathbf{E}(1 + |u(s, y)|^q)^{\frac{2}{q}} \mu_2(dz) dy ds) \right)^{\frac{q}{2}} dx \\
&\leq C_q \sup_{t \in [0, T]} \int_D \left(\int_0^t \int_D \int_{E_2} e^{-\lambda s} \mathbf{E}(1 + |u(s, y)|^q) \mu_2(dz) dy ds \right) \\
&\quad \times \left(\int_0^t \int_D \int_{E_2} |G(t-s, x, y) h(s, y, z)|^{\frac{2q}{q-2}} e^{-\frac{2\lambda(t-s)}{q-2}} \mu_2(dz) dy ds \right)^{\frac{q-2}{2}} dx \\
&\leq C_q \mu_2(E_2) \left(T|D| + \int_0^T e^{-\lambda s} \mathbf{E} \|u(s, \cdot)\|_q^q ds \right) \\
&\quad \times \sup_{t \in [0, T]} \int_D \left(\int_0^t \int_D \int_{E_2} |G(t-s, x, y) h(s, y, z)|^{\frac{2q}{q-2}} e^{-\frac{2\lambda(t-s)}{q-2}} \mu_2(dz) dy ds \right)^{\frac{q-2}{2}} dx \\
&\leq C_q \mu_2(E_2) (T|D| + T \cdot \|u\|_{\Lambda_q}^q) \\
&\quad \times \int_D \int_0^T \int_D \int_{E_2} |G(t-s, x, y) h(s, y, z)|^q e^{-\lambda(t-s)} \mu_2(dz) dy ds dx \\
&< \infty.
\end{aligned} \tag{4.11}$$

This shows that $\mathcal{A}_4(u) \in \Lambda_q$. Thus we complete the proof of the proposition.

We can now define an operator \mathcal{K} on Λ_q by

$$\mathcal{K}(u)(t, x) = \mathcal{A}_0(\phi)(t, x) + \sum_{i=1}^4 \mathcal{A}_i(u)(t, x), \quad (t, x) \in [0, T] \times D. \quad (4.12)$$

In what follows, we will prove that the operator $\mathcal{K} : \Lambda_q \rightarrow \Lambda_q$ is a contract mapping.

Theorem 4.2 *For $q > d + 2$, the operator \mathcal{K} defined by (4.12) is a contraction on Λ_q under the conditions of Theorem 4.1. In other words, there exists a constant $\varrho \in (0, 1)$ such that $\|\mathcal{K}(u) - \mathcal{K}(v)\|_{\Lambda_q} \leq \varrho \|u - v\|_{\Lambda_q}$ for $u, v \in \Lambda_q$.*

Proof Suppose that ψ_1, ψ_2 are initials of $(\mathcal{F}_t)_{t \geq 0}$ -adapted random fields $u, v \in \Lambda_q$ such that $\psi_1 = \psi_2$. Let us begin by considering \mathcal{A}_1 . Note that for $\rho = \frac{q}{3}$,

$$\|\Psi_n(\|u(s, \cdot)\|_q) b(u(s, \cdot)) - \Psi_n(\|v(s, \cdot)\|_q) b(v(s, \cdot))\|_\rho \leq C_n \|u(s, \cdot) - v(s, \cdot)\|_\rho. \quad (4.13)$$

By virtue of (A.6), we have for $\frac{1}{r} = \frac{1}{q} - \frac{1}{\rho} + 1 = -\frac{2}{q} + 1 \in [0, 1]$,

$$\begin{aligned} \|\mathcal{A}_1(u) - \mathcal{A}_1(v)\|_{\Lambda_q}^q &= \sup_{t \in [0, T]} e^{-\lambda t} \mathbf{E}(\|\mathcal{A}_1(u)(t, \cdot) - \mathcal{A}_1(v)(t, \cdot)\|_q^q) \\ &\leq \sup_{t \in [0, T]} e^{-\lambda t} \mathbf{E} \left(\int_0^t (t-s)^{\frac{d}{4r} - \frac{d+2}{4}} \right. \\ &\quad \times \|\Psi_n(\|u(s, \cdot)\|_q) b(u(s, \cdot)) - \Psi_n(\|v(s, \cdot)\|_q) b(v(s, \cdot))\|_\rho ds \Big)^q \\ &\leq C_n \sup_{t \in [0, T]} e^{-\lambda t} \mathbf{E} \left(\int_0^t (t-s)^{\frac{d}{4r} - \frac{d+2}{4}} \|u(s, \cdot) - v(s, \cdot)\|_q ds \right)^q \\ &\leq C_{n,q} \sup_{t \in [0, T]} \mathbf{E} \left(\int_0^t e^{\frac{-\lambda(t-s)}{q}} (t-s)^{\frac{d}{4r} - \frac{d+2}{4}} e^{\frac{-\lambda s}{q}} \|u(s, \cdot) - v(s, \cdot)\|_q ds \right)^q \\ &\leq C_{n,q} \sup_{t \in [0, T]} \mathbf{E} \left(\int_0^t e^{-\lambda s} \|u(s, \cdot) - v(s, \cdot)\|_q^q ds \right. \\ &\quad \times \left[\int_0^t (e^{\frac{-\lambda(t-s)}{q}} (t-s)^{\frac{d}{4r} - \frac{d+2}{4}})^{\frac{q}{q-1}} ds \right]^{q-1} \Big) \\ &\leq C_{n,q} \sup_{t \in [0, T]} \left(\int_0^t e^{-\lambda s} \mathbf{E} \|u(s, \cdot) - v(s, \cdot)\|_q^q ds \right. \\ &\quad \times \left[\int_0^t (e^{\frac{-\lambda(t-s)}{q-1}} (t-s)^{\frac{q}{q-1}(\frac{d}{4r} - \frac{d+2}{4})} ds \right]^{q-1} \Big) \\ &\leq C_{n,q} T \|u - v\|_{\Lambda_q}^q \Psi(d, q, T), \end{aligned} \quad (4.14)$$

where

$$\Psi(d, q, T) = \left[\int_0^T e^{\frac{-\lambda(t-s)}{q-1}} (t-s)^{\frac{q}{q-1}(\frac{d}{4r} - \frac{d+2}{4})} ds \right]^{q-1}.$$

Let

$$k = \frac{q}{q-1} \left(\frac{d}{4r} - \frac{d+2}{4} \right).$$

Then

$$\Psi(d, q, T) \leq \left[\frac{(q-1)^{k+1}}{\lambda^{k+1}} \int_0^\infty e^{-s} s^k ds \right]^{q-1} = \left[\frac{(q-1)^{k+1} \Gamma(k+1)}{\lambda^{k+1}} \right]^{q-1} < \infty, \quad (4.15)$$

when $q > d + 2$. Therefore,

$$\begin{aligned} \|\mathcal{A}_1(u) - \mathcal{A}_1(v)\|_{\Lambda_q} &\leq C(n, q) T^{\frac{1}{q}} \left[\frac{(q-1)^{\frac{k+1}{q}} \Gamma(k+1)^{\frac{1}{q}}}{\lambda^{\frac{k+1}{q}}} \right]^{q-1} \|u - v\|_{\Lambda_q} \\ &\leq \varrho_1 \|u - v\|_{\Lambda_q}, \end{aligned} \quad (4.16)$$

where $\varrho_1 \in (0, 1)$ by choosing λ large enough.

Next we consider $\mathcal{A}_4(u)$. In the case of $q \in (d + 2, 4]$, from a similar argument as in (4.10), it follows that

$$\begin{aligned} \|\mathcal{A}_4(u) - \mathcal{A}_4(v)\|_{\Lambda_q}^q &= \sup_{t \in [0, T]} e^{-\lambda t} \mathbf{E} \|\mathcal{A}_4(u)(t, \cdot) - \mathcal{A}_4(v)(t, \cdot)\|_q^q \\ &= \sup_{t \in [0, T]} e^{-\lambda t} \int_D \mathbf{E} \left[\left| \int_0^{t+} \int_D \int_{E_2} G(t-s, x, y) h(s, y, z) \right. \right. \\ &\quad \times (a(u(s-, y)) - a(v(s-, y))) M(dz, dy, ds) \Big|^q \Big] dx \\ &= C_q \sup_{t \in [0, T]} e^{-\lambda t} \int_0^t \int_D \left(\int_D \int_{E_2} |G(t-s, x, y) h(s, y, z)|^q \mu_2(dz) dx \right) \\ &\quad \times \mathbf{E} |u(s, y) - v(s, y)|^q dy ds \\ &\leq C_q V_q \|u - v\|_{\Lambda_q}^q \frac{\Gamma(\frac{d}{4} + 1)}{\lambda^{\frac{d}{4} + 1}} \\ &< \infty. \end{aligned} \quad (4.17)$$

For $q > (d + 2) \vee 4$, thanks to Proposition 3.1, we derive from the assumptions (ii) and (iii) of Theorem 4.1 that

$$\begin{aligned} &\|\mathcal{A}_4(u) - \mathcal{A}_4(v)\|_{\Lambda_q}^q \\ &= \sup_{t \in [0, T]} e^{-\lambda t} \mathbf{E} \|\mathcal{A}_4(u)(t, \cdot) - \mathcal{A}_4(v)(t, \cdot)\|_q^q \\ &= \sup_{t \in [0, T]} e^{-\lambda t} \int_D \mathbf{E} \left| \int_0^{t+} \int_D \int_{E_2} G(t-s, x, y) h(s, y, z) \right. \\ &\quad \times (a(u(s-, y)) - a(v(s-, y))) M(dz, dy, ds) \Big|^q dx \\ &\leq C_q \sup_{t \in [0, T]} e^{-\lambda t} \int_D \left(\int_0^t \int_D \int_{E_2} (\mathbf{E} |G(t-s, x, y) h(s, y, z)|^q \right. \\ &\quad \times (a(u(s, y)) - a(v(s, y)))^q)^{\frac{2}{q}} \mu_2(dz) dy ds \Big)^{\frac{q}{2}} dx \\ &\leq C_q \sup_{t \in [0, T]} e^{-\lambda t} \int_D \left(\int_0^t \int_D \int_{E_2} |G(t-s, x, y) h(s, y, z)|^2 \right. \\ &\quad \times (\mathbf{E} |u(s, y) - v(s, y)|^q)^{\frac{2}{q}} \mu_2(dz) dy ds \Big)^{\frac{q}{2}} dx \end{aligned}$$

$$\begin{aligned}
&= C_q \sup_{t \in [0, T]} e^{-\lambda t} \int_D \left(\int_0^t \int_D \int_{E_2} |G(t-s, x, y)h(s, y, z)|^2 e^{\frac{2\lambda s}{q}} \right. \\
&\quad \left. \times (e^{-\lambda s} \mathbf{E}|u(s, y) - v(s, y)|^q)^{\frac{2}{q}} \mu_2(dz) dy ds \right)^{\frac{q}{2}} dx \\
&\leq C_q \sup_{t \in [0, T]} \int_D \left(\int_0^t \int_D \int_{E_2} e^{-\lambda s} \mathbf{E}|u(s, y) - v(s, y)|^q \mu_2(dz) dy ds \right) \\
&\quad \times \left(\int_0^t \int_D \int_{E_2} |G(t-s, x, y)h(s, y, z)|^{\frac{2q}{q-2}} e^{-\frac{2\lambda(t-s)}{q-2}} \mu_2(dz) dy ds \right)^{\frac{q-2}{2}} dx \\
&\leq C_q T \mu_2(E_2) \|u - v\|_{\Lambda_q}^q \\
&\quad \times \sup_{t \in [0, T]} \int_D \int_0^t \int_D \int_{E_2} |G(t-s, x, y)h(s, y, z)|^q e^{-\lambda(t-s)} \mu_2(dz) dy ds dx. \tag{4.18}
\end{aligned}$$

Take into account

$$V_q \frac{\Gamma(\frac{d}{4} + 1)}{\lambda^{\frac{d}{4} + 1}} \rightarrow 0, \quad \text{as } \lambda \rightarrow \infty$$

and

$$\sup_{t \in [0, T]} \int_D \int_0^t \int_D \int_{E_2} |G(t-s, x, y)h(s, y, z)|^q e^{-\lambda(t-s)} \mu_2(dz) dy ds dx \rightarrow 0, \quad \text{as } \lambda \rightarrow \infty.$$

Then by (4.17) and (4.18), together with the assumption (iii) of Theorem 4.1, \mathcal{A}_4 is a contraction on Λ_q , for $\lambda > 0$ large enough.

For $q > d + 2$, a similar procedure as (4.14)–(4.16) yields that \mathcal{A}_2 is a contraction on Λ_q , by letting $\lambda > 0$ large enough. Therefore, it follows from (4.12) that $\mathcal{K}(\cdot)$ is a contraction on Λ_q if $\lambda > 0$ large enough. Thus the proof of Theorem 4.2 is completed.

We note that $h \rightarrow \frac{4h}{2-h}$ is an increasing function with the range $(\frac{4}{3}, 4)$ on $h \in (\frac{1}{2}, 1)$. Hence for $q > d + 2$, applying the fixed point principal on the set $\{u \in \Lambda_q : u(0) = \psi\}$, we conclude that (3.10) admits a unique solution $u \in \Lambda_q$. Thus the conclusion of Theorem 4.1 follows.

Appendix

Firstly, we will give a short proof for the assertion that $L^{\frac{2}{H}}([0, T] \times D) \subset \mathcal{H}$ if $H > \frac{1}{2}$.

Let

$$f \in L^{\frac{2}{H}}([0, T] \times D) \quad \text{and} \quad d_H = H(2H - 1).$$

Then Theorem 1 in [15] implies that there exists a positive constant $C(H, T, d)$ depending on H, T, d such that

$$\begin{aligned}
\|f\|_{\mathcal{H}}^2 &:= d_H \int_0^T \int_0^T \int_D f(u, x) f(v, x) |u - v|^{2H-2} dx du dv \\
&= d_H \int_D \left[\int_0^T \int_0^T f(u, x) f(v, x) |u - v|^{2H-2} du dv \right] dx
\end{aligned}$$

$$\begin{aligned}
&\leq C_H \int_D \left[\int_0^T |f(u, x)|^{\frac{1}{H}} du \right]^{2H} dx \\
&\leq C_{H,T} \int_D \left[\int_0^T |f(u, x)|^{\frac{2}{H}} du \right]^H dx \\
&\leq C_{H,T,d} \left[\int_D \int_0^T |f(u, x)|^{\frac{2}{H}} du dx \right]^H \\
&= C_{H,T,d} \left[\int_D \int_0^T |f(u, x)|^{\frac{2}{H}} du dx \right]^{\frac{H}{2} \times 2} \\
&= C_{H,T,d} \|f\|_{L^{\frac{2}{H}}([0,T] \times D)}^2,
\end{aligned} \tag{A.1}$$

where we have used Hölder inequality twice. This shows the continuity of the embedding.

In the following, we will give some estimates on the Green kernel $G(t, x, y)$ corresponding to the operator $\frac{\partial}{\partial t} + \Delta^2$ on the domain $[0, \infty) \times D$. As in [8], the Green function $G(t, x, y)$ admits the following expansion. Let $A = -\Delta$ be defined on $D(A) = \{u \in H^2(D) : \frac{\partial u}{\partial n}|_{\partial D} = 0\}$ and let $(\Theta_k)_{k \in \mathbf{N}^d}$ be the basis of eigenfunctions of A in $L^2(D)$, which can be written as

$$\Theta_k(x) = \prod_{i=1}^d \theta_{k_i}(x_i),$$

where $k = (k_1, \dots, k_d) \in \mathbf{N}^d$, $x = (x_1, \dots, x_d) \in D$. Moreover,

$$\begin{cases} \theta_{k_i}(x_i) = \sqrt{\frac{2}{\pi}} \cos(k_i x_i), & k_i \neq 0, \\ \theta_0(x_i) = \frac{1}{\sqrt{\pi}}, & k_i = 0 \end{cases}$$

with $i = 1, \dots, d$, and $(\lambda_k = \sum_{i=1}^d k_i^2)_{k \in \mathbf{N}^d}$ are the eigenvalues corresponding to the eigenfunctions. Therefore the Green function $G(t, x, y)$ on $[0, \infty) \times D^2$ can be expressed as

$$G(t, x, y) = \sum_{k \in \mathbf{N}^d} e^{-\lambda_k^2 t} \Theta_k(x) \Theta_k(y)$$

with $(t, x, y) \in [0, \infty) \times D^2$.

Lemma A.1 *There exist $K > 0$ and $C > 0$ such that for all $t \in (0, T]$, $x, y \in D$,*

$$|G(t, x, y)| \leq \frac{K}{t^{\frac{d}{4}}} \exp\left(-C \frac{|x-y|^{\frac{4}{3}}}{t^{\frac{1}{3}}}\right), \tag{A.2}$$

$$|\Delta_y G(t, x, y)| \leq \frac{K}{t^{\frac{d+2}{4}}} \exp\left(-C \frac{|x-y|^{\frac{4}{3}}}{t^{\frac{1}{3}}}\right), \tag{A.3}$$

$$\left| \frac{\partial G(t, x, y)}{\partial t} \right| \leq \frac{K}{t^{\frac{d+4}{4}}} \exp\left(-C \frac{|x-y|^{\frac{4}{3}}}{t^{\frac{1}{3}}}\right). \tag{A.4}$$

Lemma A.2 *For $v \in L^1([0, T], L^p(D))$, $0 \leq t_0 \leq t \leq T$ and $x \in D$, define*

$$J(v)(t_0, t, x) = \int_{t_0}^t \int_D H(t-s, x, y) v(s, y) dy ds.$$

Then for any $\rho \in [1, \infty)$, $\frac{1}{r} = \frac{1}{q} - \frac{1}{\rho} + 1 \in [0, 1]$. J is a bounded operator from $L^1([0, T], L^\rho(D))$ to $L^\infty([0, T], L^q(D))$. Furthermore,

(1) If $H(t - s, x, y) = G(t - s, x, y)$, there exists a constant $C > 0$ such that

$$\|J(v)(t_0, t, \cdot)\|_q \leq C \int_{t_0}^t (t - s)^{\frac{d}{4r} - \frac{d}{4}} \|v(s, \cdot)\|_\rho ds. \quad (\text{A.5})$$

(2) If $H(t - s, x, y) = \Delta_y G(t - s, x, y)$, there exists a constant $C > 0$ such that

$$\|J(v)(t_0, t, \cdot)\|_q \leq C \int_{t_0}^t (t - s)^{\frac{d}{4r} - \frac{d+2}{4}} \|v(s, \cdot)\|_\rho ds, \quad (\text{A.6})$$

where we assume that $r \neq \infty$ if $d = 2$, and $r < 3$, if $d = 3$.

(3) If $H(t - s, x, y) = G^2(t - s, x, y)$, there exists a constant $C > 0$ such that

$$\|J(v)(t_0, t, \cdot)\|_q \leq C \int_{t_0}^t (t - s)^{\frac{d}{4r} - \frac{d}{2}} \|v(s, \cdot)\|_\rho ds, \quad (\text{A.7})$$

where we assume that $r \neq \infty$ if $d = 2$, and $r < \frac{3}{2}$, if $d = 3$.

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