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## **GMM**

# **EM** algorythm

$$\pi_k^{\text{new}} = \frac{N_k}{N}$$

$$\mu_k^{\text{new}} = \frac{1}{N_k} \sum_{n=1}^N \gamma_{nk} x_n$$

$$\Lambda_k^{-1\text{new}} = \frac{1}{N_k} \sum_{n=1}^N \gamma_{nk} x_n x_n^T - \mu_k^{\text{new}} \mu_k^{\text{newT}}$$

where,

$$N_{k} = \sum_{n=1}^{N} \gamma_{nk}$$

$$\gamma_{nk} = \frac{\pi_{k} N\left(x_{n} | \boldsymbol{\mu}_{k}, \boldsymbol{\Lambda}_{k}^{-1}\right)}{\sum_{k'=1}^{K} \pi_{k'} N\left(\boldsymbol{x}_{n} | \boldsymbol{\mu}_{k'}, \boldsymbol{\Lambda}_{k'}^{-1}\right)}$$

#### In [1]:

import matplotlib.pyplot as plt

- 2 3 4 import numpy as np
- import math
- from scipy.stats import multivariate\_normal as multi\_gauss
- from mpl\_toolkits.mplot3d import Axes3D

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In [2]:

```
1
          class EM_GMM:
  2
               def __init__(self,K):
   3
                    self.K=K
   4
   5
               def E_step(self,X,pi,mu,Sigma):
   6
                    gamma=np.zeros((self.N,self.K))
   7
  8
                    for n in range(self.N):
  9
                         for k in range(self.K):
10
                             gamma[n,k] = pi[k]*self.gauss(X[n].reshape(self.D, 1), mu[k].reshape(self.D, 1), Sigma[k]
11
12
13
                    gamma=gamma/np.sum(gamma, axis=1, keepdims=True)
14
15
                    return gamma
16
17
               def M_step(self,X,gamma):
18
                    Nk=np.sum(gamma,axis=0)
19
                    pi=Nk/self.N
                    mu=np.zeros((self.K,self.D))
20
21
                    Sigma=np.zeros((self.K,self.D,self.D))
22
                    temp=np.zeros((self.N,self.D,self.D))
23
                    for n in range(self.N):
24
                         temp[n]=np.dot(X[n].reshape(self.D,1),X[n].reshape(1,self.D))
25
                    for k in range(self.K):
26
                         mu[k]=np.average(X,axis=0,weights=gamma[:,k])
27
                         Sigma[k]=np.average(temp,axis=0,weights=gamma[:,k])-np.dot(mu[k].reshape(self.D,1),mi
28
29
                    return pi,mu,Sigma
30
31
               def gauss(self, x, mu, Sigma):
32
                         x=x.reshape(self.D,1)
33
                         mu=mu.reshape(self.D,1)
34
                         return np.exp(-0.5*(x-mu).T @ np.linalg.inv(Sigma)@(x-mu))/(np.linalg.det(Sigma) * np.sqr
35
36
               def loglikelihood(self, X,pi,mu,Sigma):
37
               # compute log likelohood
38
                    logL = 0
39
                    for n in range(self.N):
40
                        L = 0
41
                         for k in range(self.K):
42
                             L += pi[k] * self.gauss(X[n].reshape(self.D, 1), mu[k].reshape(self.D, 1), Sigma[k])
43
                         logL += np.log(L)
44
                    return logL
45
46
               def classify(self, X,pi,mu,Sigma):
47
                    gamma = np.zeros((self.N,self.K))
48
                    for n in range(self.N):
49
                         for k in range(self.K):
50
                              gamma[n, k] = pi[k] * self.gauss(X[n].reshape(self.D, 1), self.mu[k].reshape(self.D, 1), se
51
                    gamma=gamma/np.sum(gamma, axis=1, keepdims=True)
52
53
                    return gamma, np.argmax(gamma, axis=1)
54
55
               def fit(self,X,T=100):
56
                    #initialize
57
                    self.D = len(X[0])
58
                    self.N=X.shape[0]
59
                    pi=np.ones(self.K)/self.K
```

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```
60
         mu0 = np.mean(X,axis=0)
         mu=np.random.uniform(X.min(), X.max(), (self.K, self.D))
61
         Sigma=np.zeros((self.K,self.D,self.D))
62
63
         temp=np.dot(X.T,X)/self.N
         for k in range(self.K):
64
65
           Sigma[k]=temp
66
67
         #EM algorythm
68
         record=[]
69
         for step in range(T):
           qamma = self.E_step(X,pi,mu,Sigma)
70
71
           pi,mu,Sigma=self.M_step(X,gamma)
72
73
           logL = self.loglikelihood(X,pi,mu,Sigma)
74
           print("iter: %d, log likelihood: %f" % (step, logL))
75
           record.append([step, logL])
76
           if step == 0:
              oldL = logL
77
78
           else:
79
              if logL - oldL < 1e-5:
80
                print("breaked")
81
                break
82
              else:
83
                oldL = logL
84
85
         self.pi=pi
86
         self.mu=mu
87
         self.Sigma=Sigma
88
89
         return np.array(record)
```

### In [3]:

```
1 X = np.loadtxt("x.csv", delimiter=",")
2 gmm = EM_GMM(4)
3 record = gmm.fit(X, 100)
4 gamma, labels = gmm.classify(X,gmm.pi,gmm.mu,gmm.Sigma)

iter: 0, log likelihood: -89842.850601
iter: 1, log likelihood: -89100.863614
iter: 2, log likelihood: -84373.313521
iter: 3, log likelihood: -75787.685201
iter: 4 log likelihood: -70841.695423
```

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#### In [4]:

```
# save data
    np.savetxt("z.csv", gamma, delimiter=",")
 2
 3
    with open("params.dat", "w") as f:
 4
       f.write("pi:\n")
 5
       for k in range(gmm.K):
 6
         f.write("cluster %d: %f\n" % (k, gmm.pi[k]))
 7
       f.write("\nmeans:\n")
 8
       for k in range(gmm.K):
 9
         f.write("cluster %d: %s\n" % (k, gmm.mu[k]))
10
       f.write("\nprecison matrix:\n")
       for k in range(gmm.K):
11
12
         f.write("cluster %d\n" % k)
         f.write("%s\n" % np.linalg.inv(gmm.Sigma[k]))
13
    with open("em_likelihood.txt", "w") as f:
14
15
       f.write("step\tlog-likelihood\n")
16
       for i in range(len(record)):
         f.write("%d\t%f\n" % (record[i, 0], record[i, 1]))
17
18
     # plot
    colors = ["red", "lightblue", "lightgreen", "orange"]
19
20
    label_color = [colors[int(label)] for label in labels]
    fig = plt.figure()
21
22
    ax = Axes3D(fig)
23
    for i in range(X.shape[0]):
       ax.plot([X[i, 0]], [X[i, 1]], [X[i, 2]], "o", color=label_color[i])
24
25
    ax.set_xlim(-10, 10)
26
    ax.set_ylim(-10, 10)
    ax.set_zlim(-10, 10)
27
28
    plt.savefig("em.png")
29
    plt.show()
30
    plt.close()
```

