



Developing a parsing algorithm for OpenCMISS to setup a generic simulation based on input file

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Road Map Of Presentation

- □State of the art.
- ☐ Motivation / Advantages.
- □Syntax and functionalities of the input file.
- □Different aspects of parsing algorithm.
- □Case studies
- ☐Future Work



State of the art

□Different binary for every case study.

☐ For each set of simulation parameters, one has to recompile the source code.

LaplaceBinary.out

UniaxialDisplacementBi nary.out

FluidFlowBinary.out

GenericBinary.out





Motivation/Advantages

The developed algorithm will allow user to,

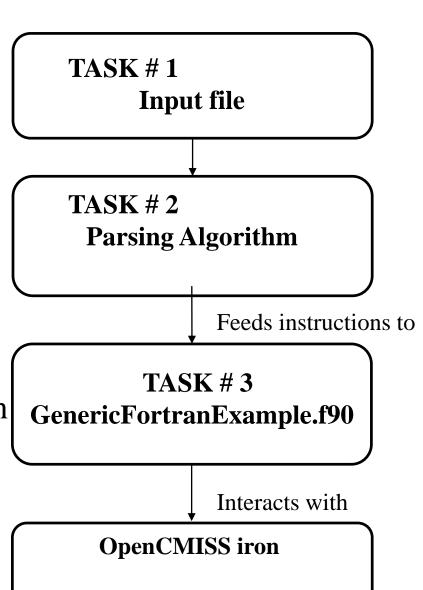
- Set up a generic simulation in OpenCMISS by providing instructions in an input file (just like .inp file in Abaqus or .ans file in Ansys).
- □ To change the simulation parameters (for instance in parametric analysis) without recompiling the code.
- Given a binary file (for instance *GenericCaseStudy.out*) and the input file (*for instance input.iron*), a simulation can be executed by,
- \$ < Absolute path to the binary file >/ Generic Case Study < Absolute path to the input file file >/ input.iron





Project overview

- 1- Develop layout/structure for the input file.
- 2- Develop a *GenericFortranExample.f90* file capable of setting up a generic simulation.
- 3- Develop a parsing algorithm that can pick input instructions from the input file and feeds them in the *GenericFortranExample.f90* file







1- Preliminary Concepts

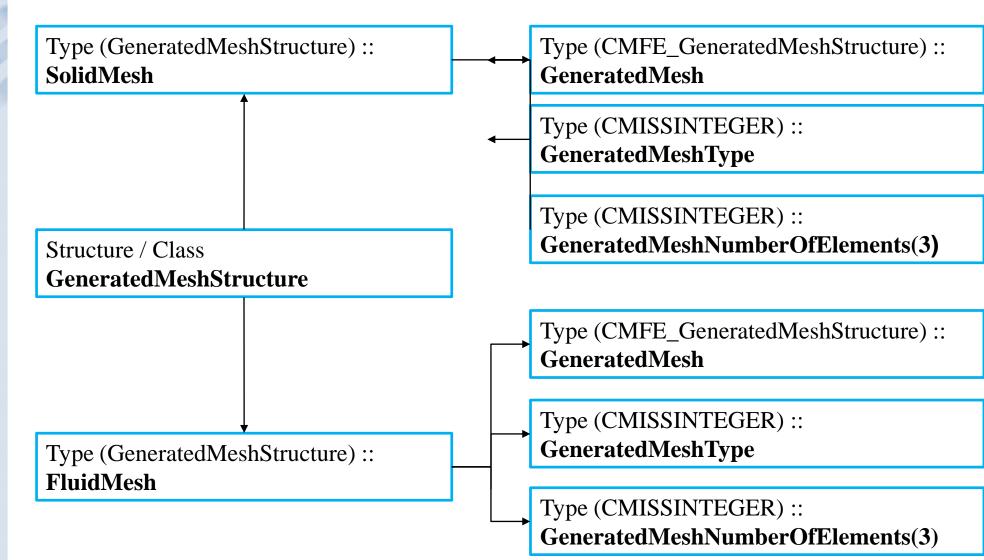
- ☐ Structure of OPENCMISS involves objects of different derived types. Each derived type object contains different simulation parameters. For instance:
- Objects of *CMFE_GeneratedMesh* Type contain information of mesh parameters such as mesh size, topology etc.
- Objects of *CMFE_BoundaryConditions* Type contains information of the boundary conditions such as location of BCs, prescribed values etc.
- □With instructions provided in the input file, these derived types objects are created and appropriate information is stored in them.







1- Preliminary Concepts (continued)





2- Syntax of the input file

☐ The input file is divided in 18 blocks and each block generates a derived type object and contains information which is later stored in different members of the object.

- •BASIS block
- •GENERATED_MESH Block
- •BOUNDARY_CONDITION Block
- •CONTROL_LOOP block
- •MATERIAL_FIELD block
- •DEPENDENT_FIELD block etc.

Note that each block corresponds to block of routines in FotranExample.f90 file







2 - Syntax of Input file (Continued)

- ☐ Each block starts and ends with the keywords START_<BLOCK NAME > and END_<BLOCK NAME> respectively.
- ☐ Each block encapsulate set of input arguments.

```
BASIS_ID
FLUID

NumberOfGaussXi ! For numerical integration 3 , 3

BASIS_INTERPOLATION_TYPE
LINEAR_LAGRANGE_INTERPOLATION

END BASIS
```





2 - Syntax of Input file (Continued)

☐ The syntax of input is case insensitive.	
□Comments should be started with exclamat	ion mark !
□Blank line can be introduced by the user in	the input file for
readability.	
☐ The input file should be finished with the ke	eyword
STOP_PARSING	
☐Please be careful with the spellings . As o	f now there is no
way to deal with typos.	







2 - Syntax of Input file (Continued) Example of an input file

Governing equation to be solved for domain with volume $1mx1m \times 1m$.

$$\Box$$
 Case a

$$abla^2arphi=0$$

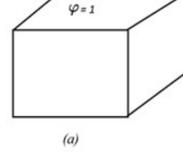
$$\varphi(x, y, 1) = 1$$

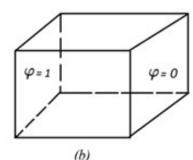
\Box Case b

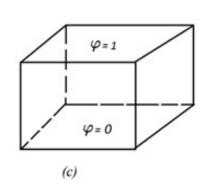
$$\varphi(0,y,z)=1 \quad \varphi(1,y,z)=0$$

 \Box Case c

$$\varphi(x, y, 1) = 1 \qquad \varphi(x, y, 0) = 0$$











3-Parsing Algorithm

3.1- Nomenclature of data structures

- □ The nomenclature of the data structures have been established with an aim to make them **self descriptive** and **clear in terms of readability.**
- □ For instance in all_GeneratedMesh(:)%GeneratedMeshInterpolationType
- > all_GeneratedMesh(:) is an array of objects of generated mesh.
- ➤ Size of the array = number of times the GENERATED_MESH block defined in the input file.
- For example for an FSI study there will be three GENERATED_MESH blocks i.e. for SOLID, FLUID and INTERFACE."





3.1- Nomenclature Of Data Structures (Conti.)

- □ Generated Mesh Interpolation Type is a string type member of object all_Generated Mesh(:).
- ☐ For instance, in an FSI study each domain (Solid, Fluid and Interface) can have a different Interpolation type
- *▶all_GeneratedMesh(1)%GeneratedMeshInterpolationType =*
- "QUADRATIC_LAGRANGE_INTERPOLATION"
- > all_GeneratedMesh(2)%GeneratedMeshInterpolationType =
- "QUADRATIC_LAGRANGE_INTERPOLATION"
- > all_GeneratedMesh(3)%GeneratedMeshInterpolationType =
- "LINEAR_LAGRANGE_INTERPOLATION"







3.1- Nomenclature Of Data Structures (Conti.)

- **Question:** In a multidomain problem how will the algorithm recognize which interpolation type belongs to which domain ?
- □Answer: Block Ids will help algorithm with that.
- >all_GeneratedMesh(1)%GeneratedMeshId = "SOLID"
- >all_GeneratedMesh(2)%GeneratedMeshId = "FLUID"
- >all_GeneratedMesh(3)%GeneratedMeshId = "INTERFACE"
- □Section 4 will explain this feature of the algorithm more in detail.

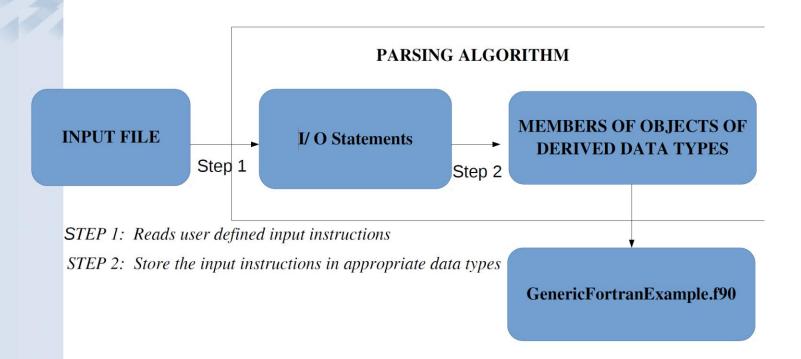






3.1- Nomenclature Of Data Structures (Conti.)

In a Nutshell







4- GenericFortranExampleFile.f90

This is the file where simulation is setup using the parameters define in the input file.

□ As of now, the *GenericFortranExampleFile.f90* is evolved enough to setup laplace, fluid and solid mechanics problems. □ Nevertheless, *GenericFortranExampleFile.f90* is quite amenable and modifiable for simulations of other classes.







4- GenericFortranExampleFile.f90 (Continued)

□Objects of different data type are linked here. For instance □Objects of $all_Region(:)\%Region$ and $all_CoordinateSystem(:)\%CoordinateSystem$ with similar data types are linked together i.e.

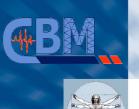
□CALL cmfe_Region_CoordinateSystemSet(all_Region(RegionIdx)%Region, & all_CoordinateSystem(CsysIdx)%CoordinateSystem,Err)

The Algorithm has to make sure in the subroutine above,

CoordinateSystemIdx and RegionIdx are such that

all_CoordinateSystem(CsysIdx)%CordinateSystemId = "SOLID"

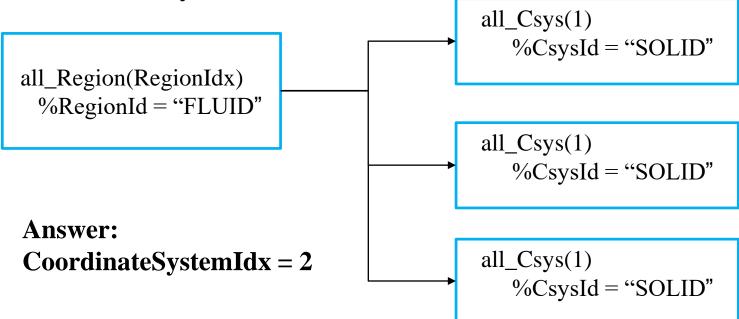
all_Region(RegionIdx)%RegionId = "SOLID"





4- GenericFortranExampleFile.f90

□Thats where the *MATCH_ID()* subroutine kicks in □call subroutine MATCH_ID(all_Region(RegionIdx)% RegionId, & □& all_CoordinateSystem(:)% CoordinateSystemId, □& CoordinateSystemIdx)









4- Case Studies 4.1 Laplace Problem

Governing equation to be solved for domain with volume $1mx1m \times 1m$.

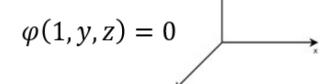
$$abla^2arphi=0$$

 \Box Case a

$$\varphi(x, y, 1) = 1$$

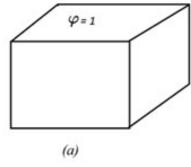
 \Box Case b

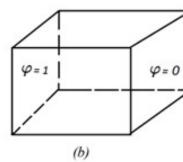
$$\varphi(0, y, z) = 1 \qquad \varphi(1, y, z) = 0$$

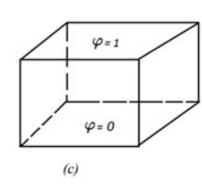


 \Box Case c

$$\varphi(x, y, 1) = 1 \qquad \varphi(x, y, 0) = 0$$









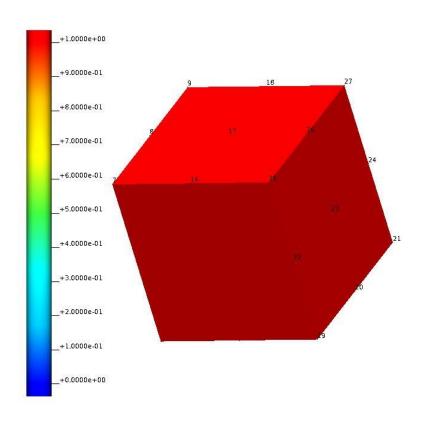


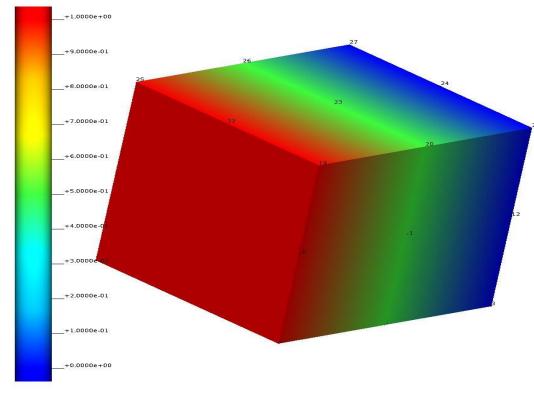


4.1- Laplace Problem (continued)

Case (a): $\varphi(x, y, 1) = 1$

Case (b): $\varphi(0, y, z) = 1$ $\varphi(1, y, z) = 0$





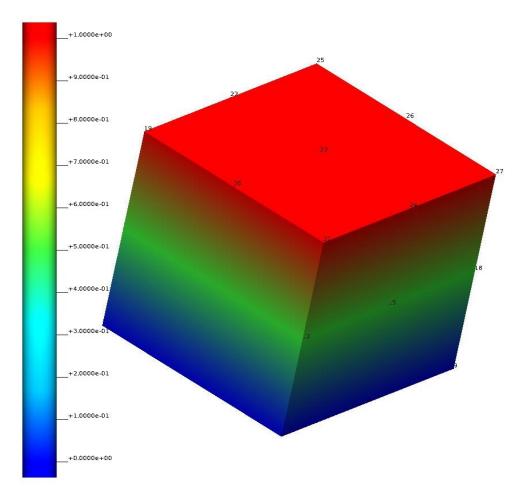






4.1- Laplace Problem (continued)

Case (c): $\varphi(x, y, 1) = 1$ $\varphi(x, y, 0) = 0$







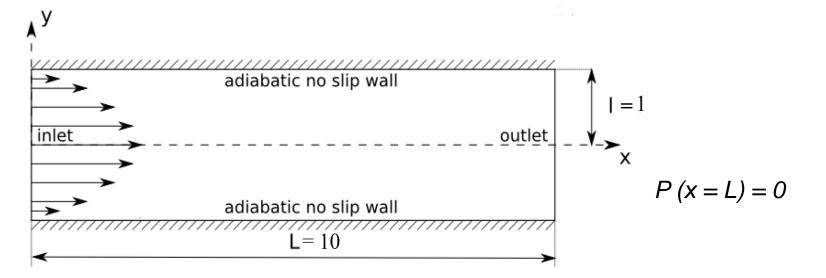


4.2 Case Study # 22D Fluid Flow Problem

Governing equation to be solved

$$\rho \underbrace{\left(\frac{\partial \overrightarrow{u}}{\partial t} + \overrightarrow{u} \cdot \nabla \overrightarrow{u}\right)}_{\text{Acceleration}} = \underbrace{-\nabla p}_{\text{Pressure}} + \underbrace{\nu \triangle \overrightarrow{u}}_{\text{Viscosity}}$$

$$Case(a) : V_x(0, y) = 4$$
 $Case(b) : V_x(0, y) = 4V_{max} \frac{y}{b} (\frac{y}{b} - 1)$





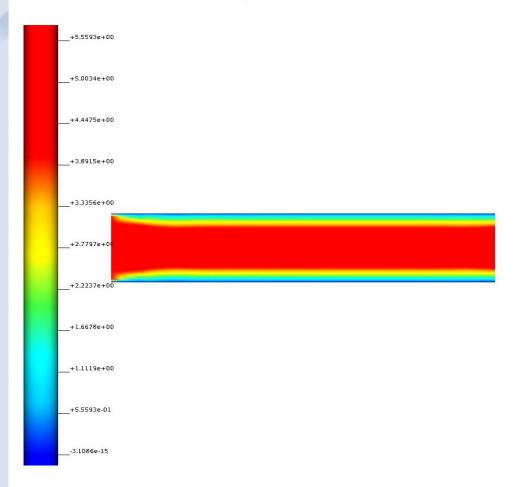




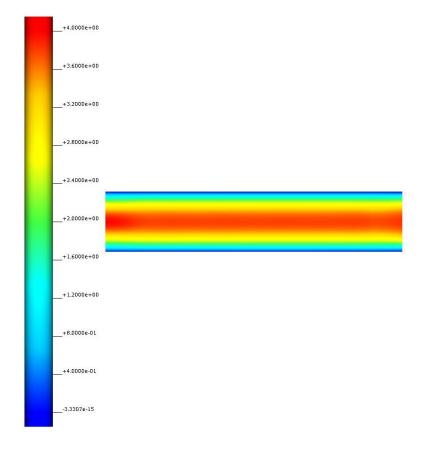


2d Fluid Flow Problem (Conti.)

$$Case(a): V_x(0,y) = 4$$



Case(b):
$$V_x(0,y) = 4V_{max} \frac{y}{h} (\frac{y}{h} - 1)$$









4.3 - Case study # 3 Cube subjected to uniaxial displacement

Governing equation to be solved

$$0 = rac{1}{
ho} \Delta \cdot \sigma + g$$

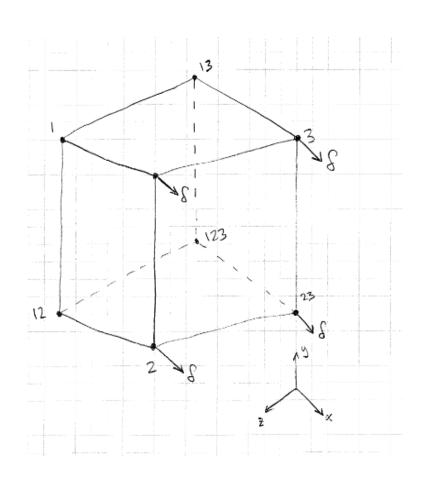
Boundary conditions

$$u(0, y, z) = 0$$

 $u(1, y, z) = 1$
 $u(x, y, 0) = 0$

Material model

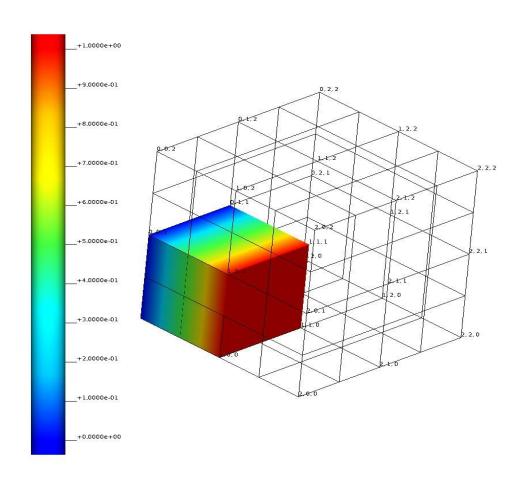
Transverse Isotropic Material model







4.3 Cube subjected to uniaxial displacement (Continued)







5- Conclusion and Future Research

- The developed parsing algorithm can ideally solve Fluid Mechanics , Solid Mechanics and Laplace problems.
- Over the course of following months, the algorithm will be further developed and tested to solve a **fluid solid interaction study**.
- Please talk to me if you want me to add any feature in my algorithm of your interest.







