

Universität zu Lübeck

Institut für Medizinische Elektrotechnik



## Bachelorthesis

### Sensorfusion Design and Evaluation of Robot Motion Estimation in Uneven Terrain

Something

von  
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Submission Date: July 4, 2022  
Supervisor: Prof. Dr. Georg Schildbach

## **What to mention**

1. Design of software
2. Function of Sensorfusion
3. Kalman Filter
4. Hardware: How many degrees of freedom, Ackerman etc.
5. Analysis of results and data