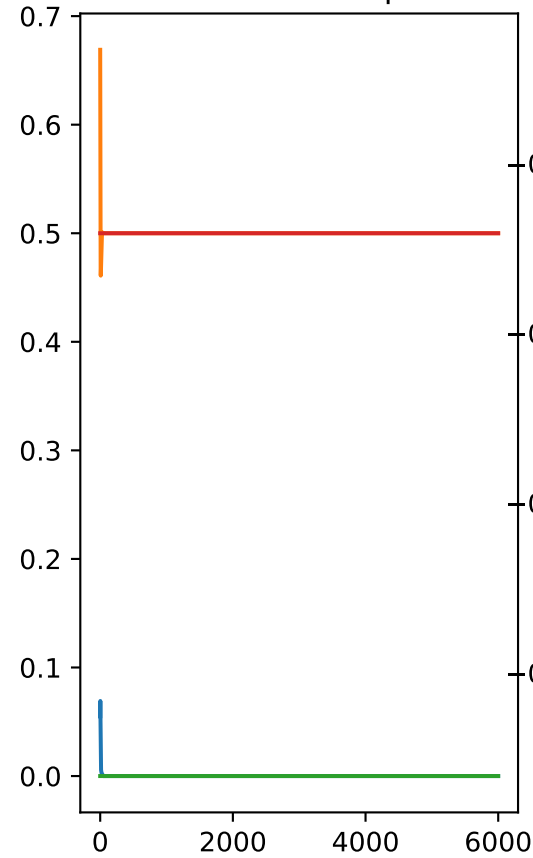
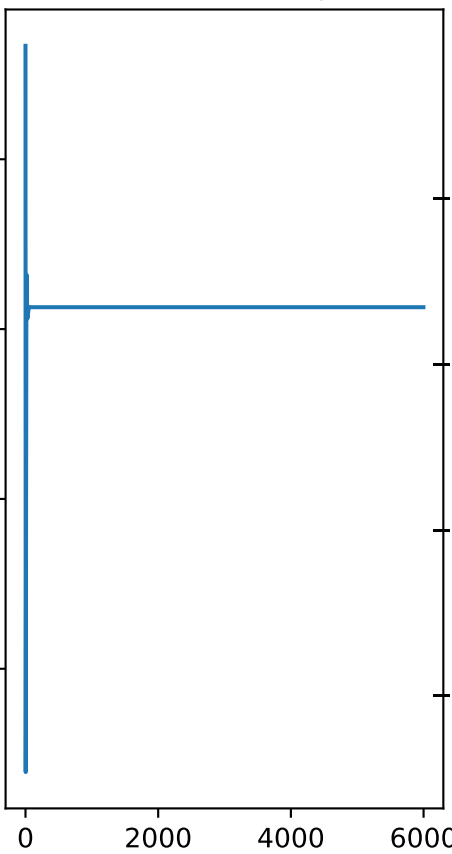


Reward: quadratic
Speed = 454.9277312803306 [rad/s]

State vs step



Action vs step



Reward vs step

