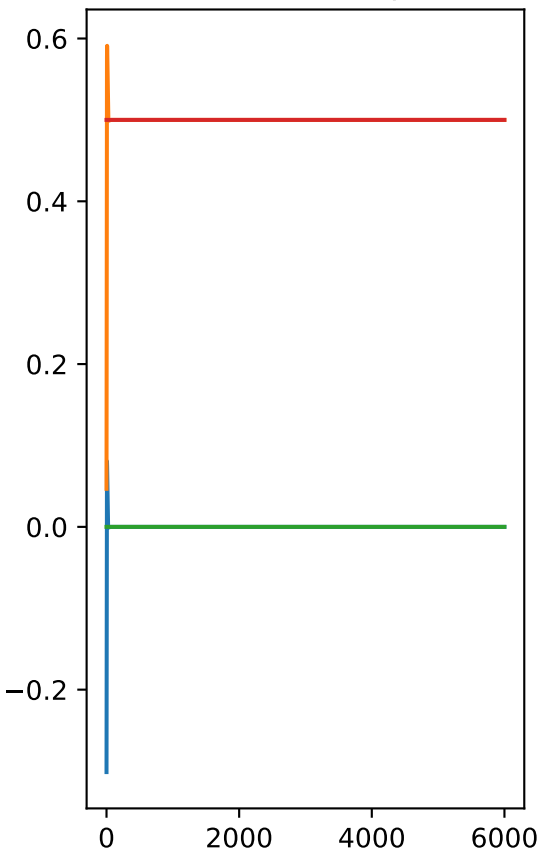
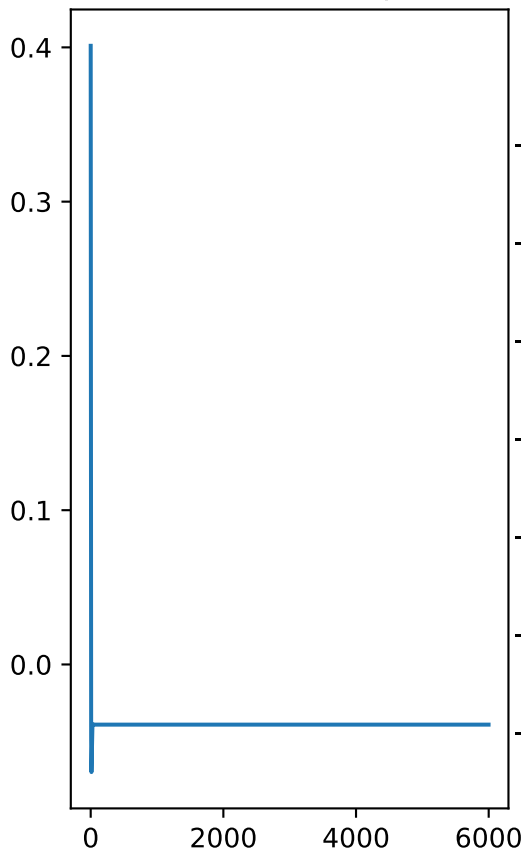


Reward: quadratic
Speed = 199.99999193158794 [rad/s]

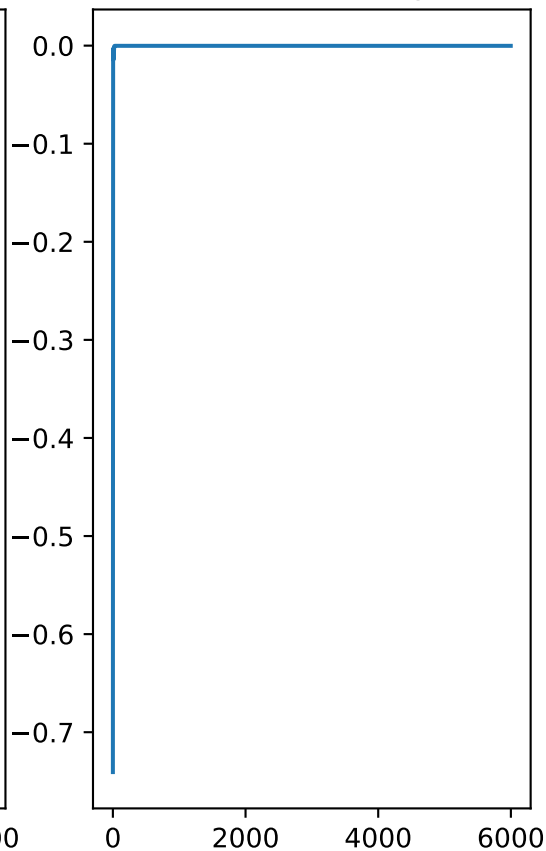
State vs step



Action vs step



Reward vs step



I_d I_{dref}
 I_q I_{qref}

$[V_d, V_q]$