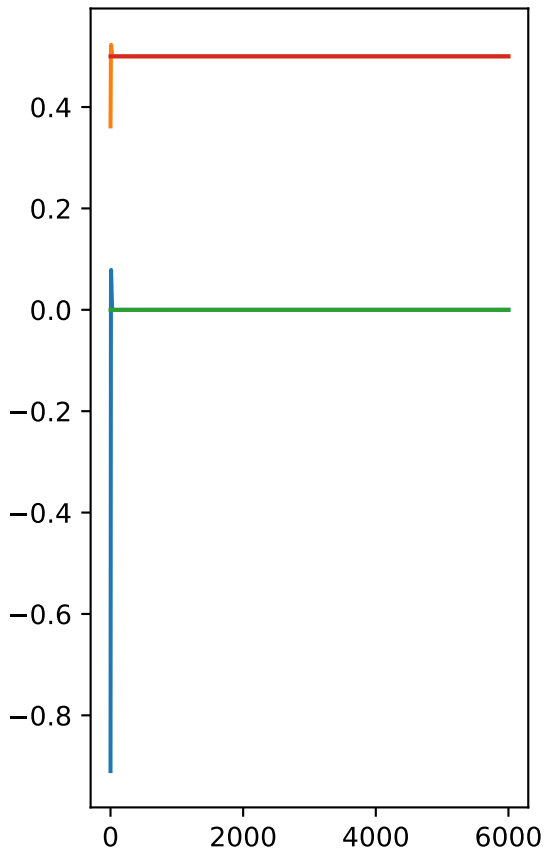
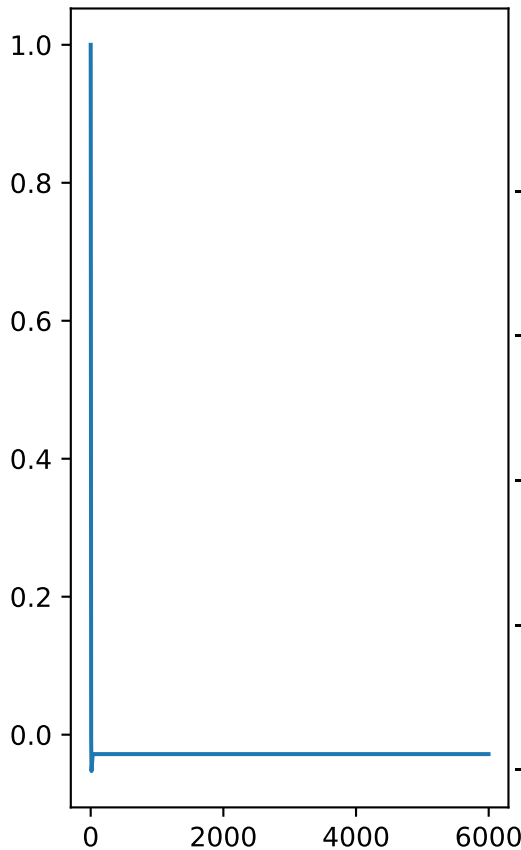


Reward: quadratic
Speed = 144.33733064746363 [rad/s]

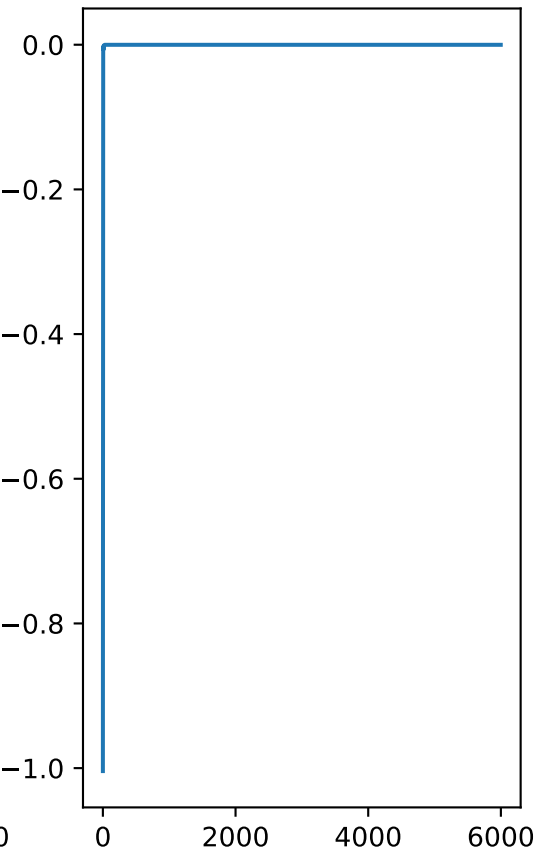
State vs step



Action vs step



Reward vs step



I_d I_d^{ref}
 I_q I_q^{ref}

$[V_d, V_q]$