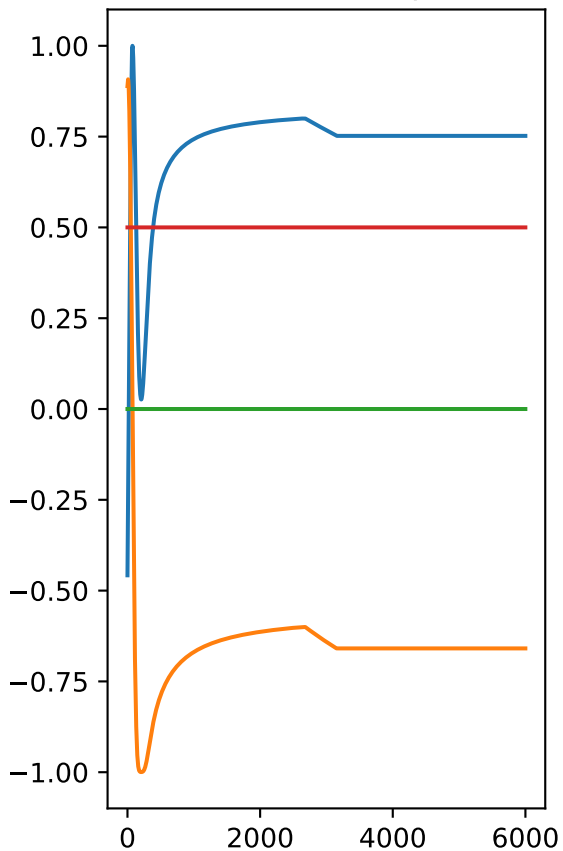
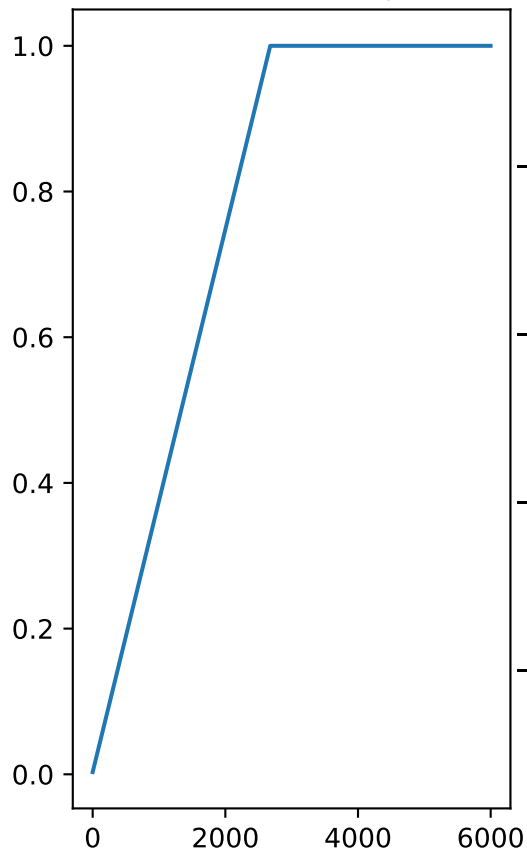


Reward: quadratic
Speed = 199.99999193158794 [rad/s]

State vs step



Action vs step



Reward vs step

