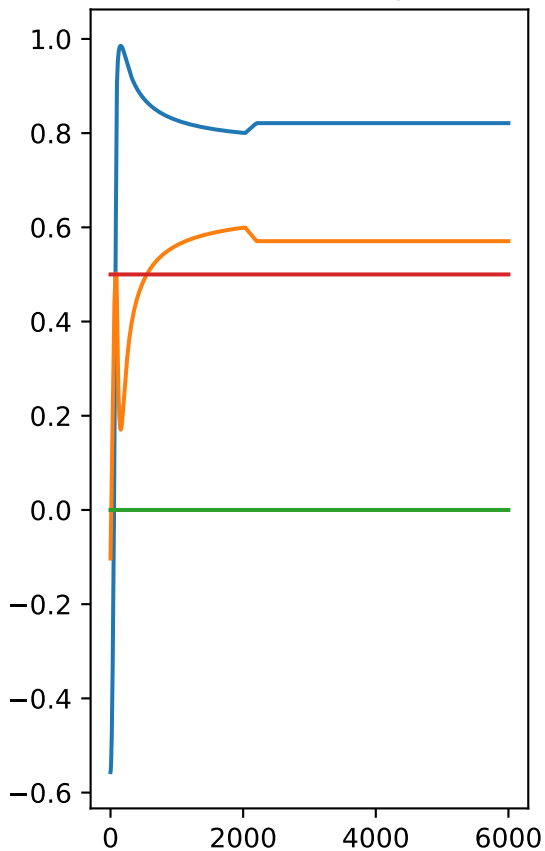
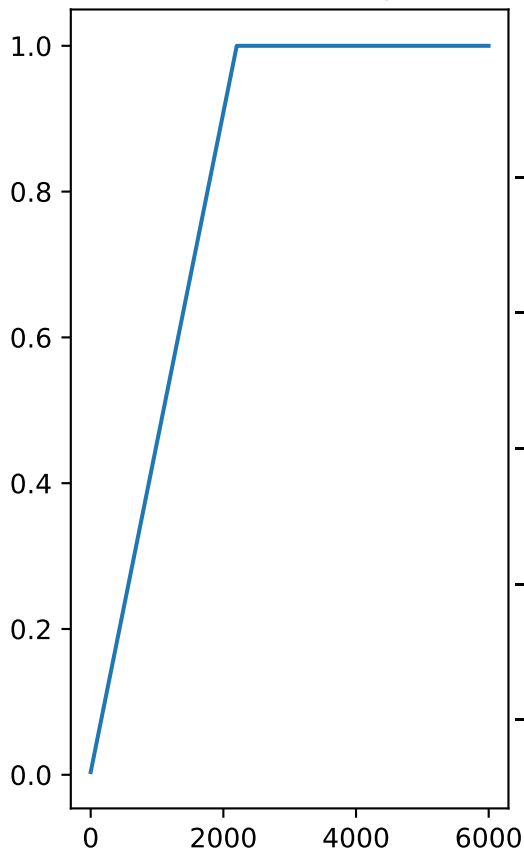


Reward: quadratic
Speed = 199.99999193158794 [rad/s]

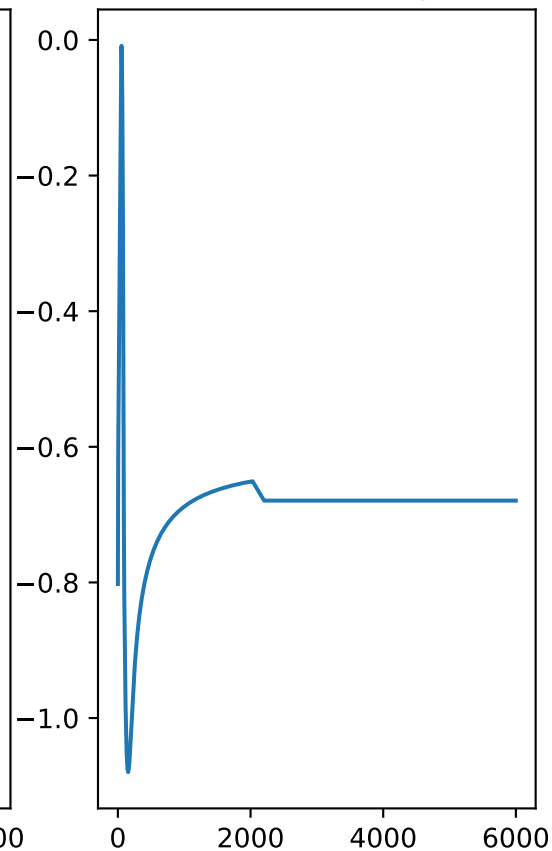
State vs step



Action vs step



Reward vs step



— Id — Idref
— Iq — Iqref

— ['Vd', 'Vq']